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A 3-variable PDE model for predicting fungal growth derived from microscopic mechanisms

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Abstract

In this work, we present a new PDE model of the growth of *Postia placenta*, a species of brown rot fungus. The formulation was derived mainly from the biological mechanisms embedded in our discrete model, validated against experimental data. In order to mimic the growth mechanisms, we propose a new reaction-diffusion formulation, based on three variables: the concentration of tips, the branch density and the total hyphal density. The evolution of tips obeys a reaction-diffusion model, with constant diffusivity, while the evolution of the two other variables results from time integrals. The numerical solution is in excellent agreement with the averaged radial tip/hyphal densities of the mycelial network obtained by the discrete model. Thanks to the efficient exponential Euler method with Krylov subspace approximation, the solution needs only 3.5 s of CPU time to simulate 104-day of mycelium growth, in comparison with 8 hours for the discrete model. The great reduction of the RAM memory and computing time gives the possibility to upscale the simulation. The novelty of the PDE system is that the spatial colonization is formulated as a diffusion mechanism, which is self-standing, contrary to models based on an advection term. The continuous model can also reproduce the radial densities when the growth parameters in the discrete model are varied to adapt to different growth conditions. The correlation constructed between the two models provides us a tool for mutual insights between local biological mechanisms to the global biomass distribution, especially when analyzing experimental data.

Keywords: Reaction-diffusion, continuum modeling, upscaling, fungus

1. Introduction

Wood and wood-based products have been popular constructive materials due to their excellent structural properties for many years. The good thermal performance and design of new manufacturing technology enable the reduction of energy consumption and emission, which addresses the

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5 present needs in building construction. This is why these materials became even more promoted
in construction. However, fungal decay in bio-based materials is of major concern in relation to
the service time of buildings and even to human safety, since it weakens the structural support of
wood enough to cause mechanical failure. Every year an enormous amount of wood and wood-
based products is destroyed by fungal decay, among which brown rot fungi are the most common
10 and destructive within buildings throughout Europe and North America due to their rapid decay
mechanisms [1]. Many researches have studied the growth and decay patterns of brown rot fungi
as well as the impact of environmental factors to their growth [2, 3, 4, 5, 6, 7, 8]. Nevertheless, the
laboratory observations are constrained by the scales of study and their cost. As a supplementary
tool, mathematical modeling in combination with laboratory experiments can realize a deeper and
15 wider insight in a more efficient way.

The modeling techniques to simulate the spatial distribution of fungi are classified into two
categories: discrete models and continuous models. The previous ones adapt well to model the
mycelial growth at a small scale in identifying individual hypha to form mycelial networks in differ-
20 ent environments. For example, Boswell *et al.* (2007) and Boswell (2008) respectively developed a
two-dimensional (2D) and a three-dimensional (3D) lattice-based model to simulate mycelial growth
in a soil-like environment [9, 10]. Fuhr *et al.* (2011) constructed a 3D lattice-free model of hyphal
growth in the heartwood of Norway spruce in simplifying the structure of wood [11]. These models
are generally constrained in a small scale by the necessary RAM memory and the computing time.
25 In contrast, the continuous models provide a potential of modeling the fungal growth from the
colony-scale to the macroscale, in which the density of fungal matter was viewed as averaged quan-
tities. The early models were extended from reaction-advection systems which included nutrients
and geometries of mycelial spread [12, 13, 14, 15]. However, the advection process requires the
development direction to be known at each point, which limits the prediction ability of the code
30 and/or augments the mathematical complexity especially in heterogeneous media. Thus, in the
recent models, the diffusion process has replaced the advection to model the movement of hyphal
biomass [16, 17, 18, 19, 20, 21] or combined with the advection process to model the movement
of tips and hyphae [22, 23]. However, in these models, some of the mechanisms were based on
assumptions and no precise validation process has been carried out.

35

The strategy of our work is to enlarge the spatio-temporal scale of the study of fungal growth
step by step in an accurate and efficient way. Thus, we started from the micro-scale experiment [24]
to observe the hyphal growth behaviors of a species of the brown rot fungi, *Postia placenta*. Then,
a discrete model [25], derived from the biological mechanisms of hyphal development, was precisely

40 validated with experimental data. Compared to the experiment, this model allows us to predict the mycelial growth at a larger spatial-scale in much shorter time. However, to reach the macroscale with an even a higher computational efficiency, a continuous model is needed.

In this work, we propose a PDE formulation mainly derived from the mechanisms of hyphal
45 growth at the microscopic level. A reaction-diffusion equation mimics the movement and proliferation of tips. Then, the evolution of hyphal biomass is related to the tip density following the tip elongation mechanism. Most of parameters of the continuous model were directly obtained from the discrete model, while three remaining parameters were determined by an inverse procedure: the model parameters were adjusted to minimize the objective function, i.e. the gap between the PDE
50 profiles and the radial profiles of hyphal density calculated by the validated discrete model. Thanks to the exponential Euler method with Krylov subspace approximation, the model was accurately solved in an efficient way. Then, the growth parameters in the discrete model have been varied to investigate their influences to the distributions of tips and hyphae. The good agreements between the numerical solutions and the profiles obtained in the discrete model verified the excellent pre-
55 diction capacity of the continuous model and its facility to adapt to different growth conditions. Additionally, thanks to the good correspondence of the two models, the local mechanisms of the mycelial network can also be estimated via the change of biomass distribution. Furthermore, due to the pure diffusion process, this model is simple enough to extend to study the fungal growth in multi-dimensional spaces and in porous media, and even provides a base to the multi-scale modeling
60 of the fungal development in wood.

2. Method and materials

2.1. Discrete mechanisms and radial profiles

In our discrete model [25], three main microscopic mechanisms (i.e., tip elongation, branching
65 and anastomosis) of hyphal growth were implemented in a regular square-lattice to simulate the development of a mycelial network. The two fundamental features of mycelial growth are tips and hyphae. Tips belong to two classes: active tips which extend at a certain, non-null, rate and dormant tips which do not elongate. A hypha elongates by the extension of an active tip, following its dominant direction. The elongation rate of each active tip follows a corrected gamma
70 distribution. Each site of the lattice can contain numerous hyphae and/or tips. Lateral and apical branching are considered as way to produce new tips. The rate of lateral branching depends on the lateral branching probability and the total number of tips and the lateral branches are uniformly distributed throughout the mycelium. The apical branching occurs to the active tips and its rate

is determined by the apical branching probability. The branching is inhibited in three special cases:

- (i) no lateral branches emerge in the proximity of an existed branch; (ii) the formation of a lateral branch around a hyphal tip is inhibited by apical dominance; (iii) the apical branching does not occur if its trailing hypha has not a certain length. Apart from the process of tip proliferation, tips can also disappear through anastomosis. The fusion of a tip with a hypha can occur when they contact each other to yield an interconnected mycelial network.

This model has been validated by a precise process using the experimental data of the growth of *P. Placenta* during 17 days. With the determined parameters, the spatio-temporal development of a mycelial network was generated from a spore during a longer timescale of 9×10^6 s (~ 104 days). We divided the mycelial network into a series of rings with a gap of $\Delta r = 1.5 \times 10^{-4}$ m, of which the radial densities of tips and hyphae were respectively calculated by averaging the discrete network over radius increments. The tip density is defined as the number of tips per unit volume, while the hyphal density denotes the length of hyphae per unit volume. Due to the numerous stochastic processes in the discrete model, a single realization contains fluctuations. Therefore, we repeated the simulations 20 times with the same parameters and averaged the two resulting densities for each ring: (i) the averaged tip density denoted by $\rho_{tip}(r, t)$ in the ring around the radius r and at time t and (ii) the averaged hyphal density denoted by $\rho_{hypha}(r, t)$. In the following, the temporal evolution of the tip and hyphal distributions, the two averaged densities, were calculated at nine instants from $t = 2.25 \times 10^5$ to $t = 9 \times 10^6$ s.

2.2. Continuous model

A continuous model was directly derived from the three microscopic mechanisms of mycelial growth of the above-presented discrete model. The fungal mycelium is represented by two components: tip density and hyphal density, which represent respectively the proliferation capacity of the mycelium and the total biomass quantity. The tip density, denoted by $C(\mathbf{x}, t)$, is the number of tips in a unit volume at the spatial position \mathbf{x} and time t , while $B(\mathbf{x}, t)$ is the hyphal density defined as the length of hyphae per unit volume.

The three main mechanisms of mycelial growth, tip elongation, branching and anastomosis, lead to respectively the migration, the proliferation and the elimination of tips. Thus, as shown in Eq. (1a), a reaction-diffusion equation was applied to describe the variation of the tip density. The diffusion term denotes the migration of tips with a diffusion coefficient D . The two reaction terms, S and P , represent the proliferation and the elimination of tips. As the hyphal extension is generated only by tip elongation, the amount of hyphae created in a unit volume over a short time

interval is linearly related to the actual quantity of tips by two factors, the averaged tip elongation
 110 rate R and the proportion of active tips P_{active} (Eq. (1b)).

$$\frac{\partial C}{\partial t} = \nabla(D\nabla C) + S(B, C) - P(B, C), \quad (1a)$$

$$\frac{\partial B}{\partial t} = RP_{active}C. \quad (1b)$$

As mentioned above, the term S denotes the production of tips by lateral and apical branching. According to the branching mechanisms in our discrete model, the number of lateral branches emerged per unit of time is the product of lateral branching probability P_{br}^{lat} by the total quantity
 115 of tips in the mycelium. The latter is obtained as the integral of the tip density over all the entire volume (i.e., $\int C d\mathbf{x}$). The lateral branches should be uniformly distributed in the mycelium. Thus, the amount of branches distributed into each unit volume depends on the proportion of hyphae containing in this volume over the whole mycelium (i.e., $B / \int B d\mathbf{x}$). In addition, the lateral branching is inhibited in two special cases related to the number of branches and tips per unit hyphal length.
 120 As shown in Eq. (2), we applied an exponential function to account for this inhibition, where β is defined as the inhibition coefficient and $Br(\mathbf{x}, t)$ denotes the number of branches per unit volume at position \mathbf{x} and time t . Since the branches do not move, Br is the accumulation of the term S over time, calculated by Eq. (3).

$$Y(\mathbf{x}, t) = \begin{cases} e^{-\beta(C(\mathbf{x}, t) + Br(\mathbf{x}, t)) / B(\mathbf{x}, t)} & B(\mathbf{x}, t) > 0, \\ 0 & B(\mathbf{x}, t) = 0. \end{cases} \quad (2)$$

$$\frac{\partial Br}{\partial t} = S. \quad (3)$$

For apical branching, each active tip possesses a probability P_{br}^{api} to form a new tip. The increase of tips due to the apical branching is hence given by $P_{br}^{api} P_{active} C$. Considering that the apical branching occurs when the hypha attains a certain length, we modified $C(\mathbf{x}, t)$ with a time-delayed term $C(\mathbf{x}, t - \tau)$ where τ is the necessary time for a tip to reach that given length with the average elongation rate. Together, the proliferation term S is modeled as:
 130

$$S(B, C) = P_{br}^{lat} \int C d\mathbf{x} \frac{B}{\int B d\mathbf{x}} Y + P_{br}^{api} P_{active} C(\mathbf{x}, t - \tau). \quad (4)$$

The disappearance of tips is caused by anastomosis. Such a fusion occurs when a hyphal tip contacts another hypha, which implies that the disappearance rate depends on the contact

probability between tips and hyphae. Since tips elongate at a low rate ($\sim 10^{-9} m \cdot s^{-1}$), they move a very short distance during a unit time interval. We focused on one tip and we took the volume
 135 formed by a unit surface and the short distance the tip passes through during a unit time interval. All the hyphae contained in this volume were projected on the bottom surface. The possibility of this tip contacting another hypha is equal to the proportion of the projected area, which is related to the hyphal length. In all, the elimination rate of tips is proportional to the tip density C , the tip elongation rate R , and the hyphal density B and can be expressed as follows:

$$P(B, C) = \gamma RBC. \quad (5)$$

140 The coefficient γ is named as the anastomosis coefficient for correlating the projected area with the hyphal density.

To summarize, the reaction-diffusion system takes the following form

$$\text{Tip density} \quad \frac{\partial C}{\partial t} = \nabla(D\nabla C) + S - P, \quad (6)$$

$$\text{Hyphal density} \quad \frac{\partial B}{\partial t} = RP_{active}C, \quad (7)$$

$$\text{Branch density} \quad \frac{\partial Br}{\partial t} = S. \quad (8)$$

where

$$S = \begin{cases} P_{br}^{lat} \int C d\mathbf{x} \frac{B}{\int B d\mathbf{x}} e^{-\beta(C+Br)/B} + P_{br}^{api} P_{active} C(\mathbf{x}, t - \tau) & B(\mathbf{x}, t) > 0, \\ P_{br}^{api} P_{active} C(\mathbf{x}, t - \tau) & B(\mathbf{x}, t) = 0, \end{cases} \quad (9a)$$

$$P = \gamma RBC. \quad (9b)$$

145 2.3. Numerical solution

The model was solved in a one-dimensional (1D) axisymmetric configuration to be compared with the radial profiles obtained with the discrete model. The 1D axisymmetric formulation reads as follows:

$$\begin{aligned} \frac{\partial C(r, t)}{\partial t} &= \frac{1}{r} \frac{\partial}{\partial r} \left(Dr \frac{\partial C(r, t)}{\partial r} \right) + S - P, \\ \frac{\partial B(r, t)}{\partial t} &= RP_{active}C, \\ \frac{\partial Br(r, t)}{\partial t} &= S. \end{aligned} \quad (10)$$

The term $C(\mathbf{x}, t - \tau)$ in Eq. (9a) is approximately transformed to an term able to be solved:

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$$C(t - \tau) \approx C(t) - \tau \frac{\partial C}{\partial t}(t). \quad (11)$$

The initial condition for this model was defined as the averaged density profiles of tips, hyphae and branches obtained with the discrete model at $t = 2.25 \times 10^5$ s.

The reaction-diffusion system was solved in cylindrical coordinates with a computational domain large enough to assume no-flux boundary conditions. A control-volume finite-element spatial discretization turned the PDEs system (Eq. (10)) into an initial value problem of the form

$$\frac{du}{dt} = g(u), \quad u(0) = u_0, \quad (12)$$

where $u = (C, B, Br) \in \mathbb{R}^{3N}$, $g: \mathbb{R}^{3N} \subset D \rightarrow \mathbb{R}^{3N}$ is a nonlinear function of u , and N is the size of the 1D mesh. The calculation domain was meshed uniformly with a spacing of 1.5×10^{-4} m which is equal to the spatial resolution of the profiles obtained in the discrete model.

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We performed the time integration process to get a linearized version of Eq. (12),

$$\frac{du}{dt} = g(u_n) + J_g(u_n)(u - u_n), \quad t > t_n, \quad (13)$$

whose exact solution is

$$u(t) = u_n + (t - t_n)\varphi((t - t_n)J_g(u_n))g(u_n), \quad t > t_n, \quad (14)$$

where $J_g \in \mathbb{R}^{3N \times 3N}$ is the Jacobian matrix of g and function φ is defined as $\varphi(z) = \frac{e^z - 1}{z}$.

Applying the exponential Euler method to Eq. (14) at time t_{n+1} , we get the approximate solution of Eq. (12)

$$u_{n+1} = u_n + dt_n \varphi(dt_n J_g(u_n))g(u_n), \quad (15)$$

with time step $dt_n = t_{n+1} - t_n$.

The exponential integrators method was first presented in 1960 by Certaine [26] and has been well-known since late of 1990s by works of M. Hochbruck and others [27, 28]. Thanks to the approximation of the Krylov subspace to the matrix-function vector product $\varphi(dt_n J_g(u_n))g(u_n)$, the exponential integrators method became very useful for large system of stiff equations [29, 30, 31].

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In this article, our work was inspired from the work of E. Carr, I. Turner and P. Perré [30] using the
 ”variable-stepsizes exponential Euler method” to solve the system of non-linear transport equations
 175 with great success.

The Krylov subspace methods compute a small $m \times m$ matrix H_m (the projection matrix) instead
 of the full Jacobian matrix J_g . The approximation of the matrix-vector product is as follows:

$$\varphi(dt_n J_g(u_n))g(u_n) \approx \beta_0 V_m \varphi(dt_n H_m) e_1. \quad (16)$$

Thanks to this, we can have a large time step dt_n without preconditioning techniques, which is very
 180 efficient in terms of computational time and RAM memory.

2.4. Parameter determination

The continuous model was calibrated for *P. Placenta* via the validated discrete model mentioned
 in Part 2.1. All parameters are summarized in table 1 using the international unit standard. Most
 185 of these parameters were defined directly from the discrete model [25]. For example, since the tip
 elongation rates follow a corrected gamma distribution, its mean was calculated as the averaged
 tip elongation rate R . With this averaged rate, we obtained $\tau \approx 1048 s$, which is the average time
 for a tip to extend by $5 \mu m$. The proportion of active tips, the lateral and the apical branching
 probability are simply those of the discrete model.

190 The determination of the three remaining, macroscopic parameters, the diffusion coefficient D ,
 the inhibition coefficient β and the anastomosis coefficient γ , were determined by inverse analysis.
 The objective function used for optimization compares, in the sense of mean squared difference,
 the radial profiles obtained with the discrete and continuous models. Since the tip and the hyphal
 195 density are tightly related and our final objective is to fit the latter one, we defined the relative
 error $E(B)$ of the hyphal density profiles:

$$E(B) = \sqrt{\frac{\sum_{t \in \{t_1, \dots, t_9\}} \sum_{k=1}^N (\rho_{hypha}[r(k), t] - B[r(k), t])^2}{\sum_{t \in \{t_1, \dots, t_9\}} \sum_{k=1}^N \rho_{hypha}^2[r(k), t]}}, \quad (17)$$

where the total number of radius increments is denoted by N (here $N = 299$) and $r(k)$ represents
 the radius of the k^{th} ring. This function was minimized using the Nelder-Mead method.

Table 1. Description of variables and parameter values in the continuous model.

Symbol	Description	Unit	Value
C	Tip density	m^{-3}	--
B	Hyphal density	$m \cdot m^{-3}$	--
Br	Branch density	m^{-3}	--
t	Time	s	--
R^*	Tip elongation rate	$m \cdot s^{-1}$	$4,77 \times 10^{-9}$
P_{active}^*	Proportion of active tips	--	0,7
P_{br}^{lat*}	Lateral branching probability	s^{-1}	1.11×10^{-5}
P_{br}^{api*}	Apical branching probability	s^{-1}	3.22×10^{-6}
τ^*	Lag time for apical branching	s	1048
D	Diffusion coefficient	$m^2 \cdot s^{-1}$	1.13×10^{-12}
β	Inhibition coefficient	--	7.78×10^{-5}
γ	Anastomosis coefficient	m	5.40×10^{-2}

* Parameter values come from [25].

3. Results

3.1. Radial profiles calculated from the discrete model

The spatial distribution of tips and the mycelial network were simulated during a long period ($9 \times 10^6 s$, ca. 100 days) by the discrete model. Fig. 1 shows the evolution of the tip distribution and the mycelial network at three elapsed times: $t = 1.8 \times 10^6$, 4.5×10^6 and $9 \times 10^6 s$. These profiles show very clearly how the tips proliferate and colonize the free space starting from the inoculum zone. After a long-term growth, the distribution of tips seems uniform throughout the mycelium except at the edge. Clearly, the area of the colony increases with time, but we can also see the increase of the hyphal density inside the colony from Fig. 1 (c) which shows the zoom of a tiny part of the mycelial network.

Then, nine profiles of the averaged radial density at different times were obtained from the discrete model (Fig. 2). The profiles confirm that, after a long-term growth, the tip density is almost uniformly distributed, even though it decreases slightly towards the center of the colony. The higher distribution of tips at the edge is a strategy that favors the exploitation of new space. The uniform distribution implies the existence of an equilibrium between the emergence of branches and the anastomosis. In spite of the wave-like shape of the tip density profiles, its higher value at the edge maintains a local gradient. It seems therefore reasonable to propose a diffusion process to simulate the tip movement in a continuum approach. One may note also that the tip density in the center increases first and then decreases at longer times. Indeed, when the mycelial network becomes dense, the anastomosis and the inhibition occur more frequently, leading to more elimina-

tion of tips. From Fig. 2 (b), we observed that the hyphal density profiles continuously increased in time keeping a negative gradient towards the edge. Note however that the hyphal density increases more and more slowly in the center due to the reduction of tip density, revealing the existence of an upper limit to the biomass even for the free growth of mycelia on a two-dimensional substrate.

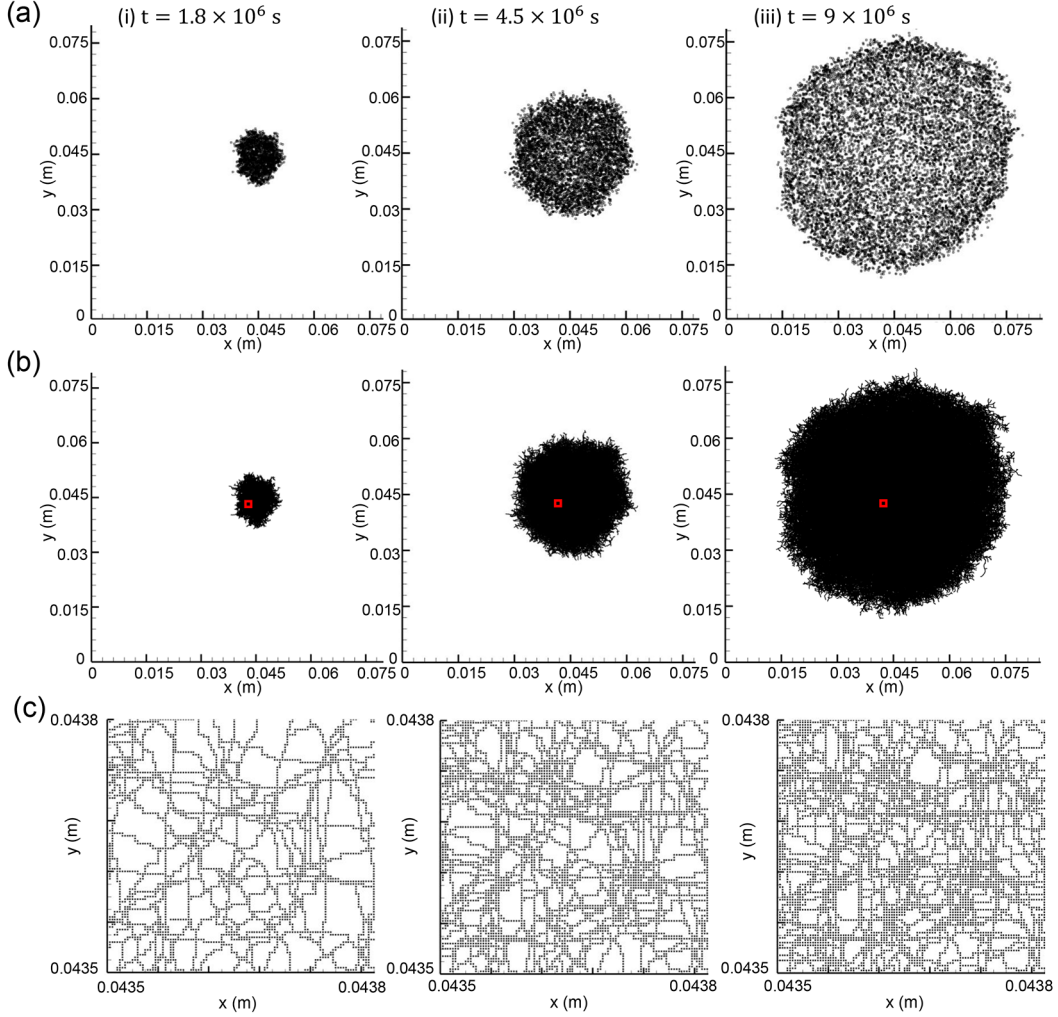


Fig. 1. Simulation of the discrete model: temporal evolution of (a) the distribution of tips, (b) the mycelial network and (c) the zoom of the red squared part in (b).

3.2. Validation of the PDE formulation

The profiles averaged over 20 realizations of the stochastic model (Fig. 2) were used to optimize the three macroscopic parameters of the continuous model. The optimized solution of Eq. (10) has a very small relative error ($E(B) = 2.70 \times 10^{-2}$), which proves the ability of the PDE formulation to represent the discrete mechanisms. The profiles, plotted at different times in Fig. 3, give another piece of information: even though the objective function considers only the hyphal density, both

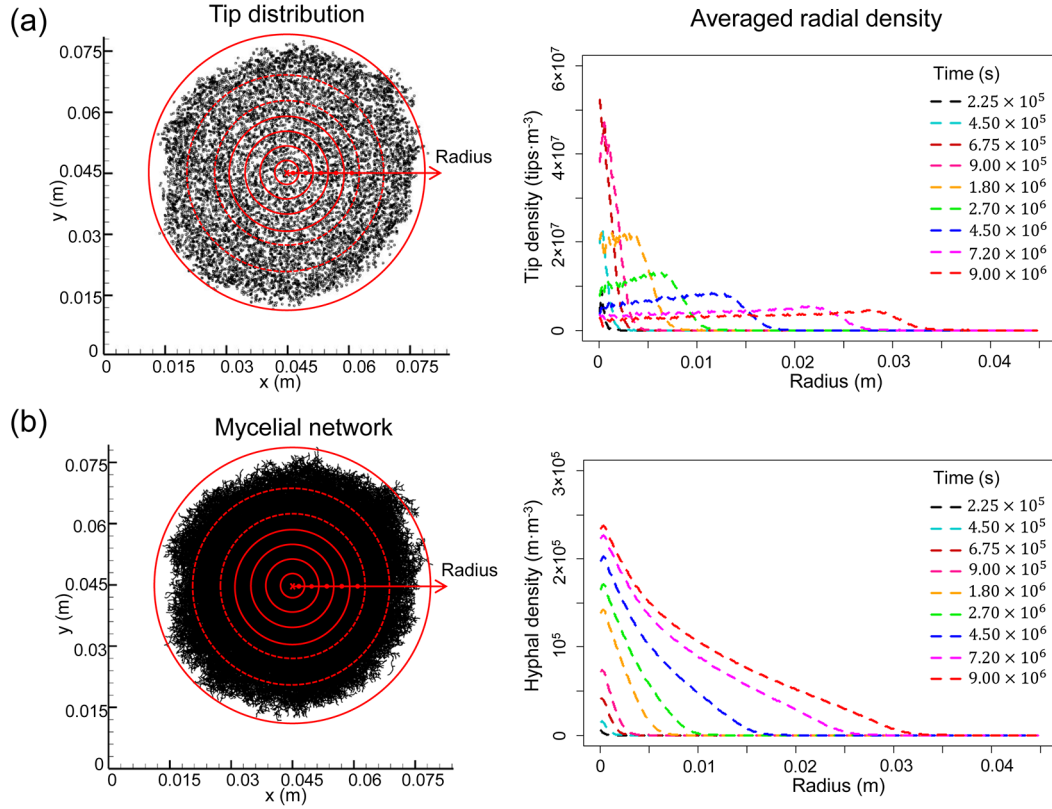


Fig. 2. Radial densities of tips and hyphae obtained by averaging respectively the tip distributions and the mycelial networks over radius increments at nine times. Profiles on the right are the average of 20 realizations of the stochastic discrete model.

the tip and the hyphal profiles of the PDE solution are in excellent agreement with the discrete model. This confirms that the two variables, tip density and hyphal density, are tightly related to each other. Moreover, the wave-shape of the tip profiles was well captured by the diffusion process, even though it resembles more a front-like progression than a diffusion phenomenon.

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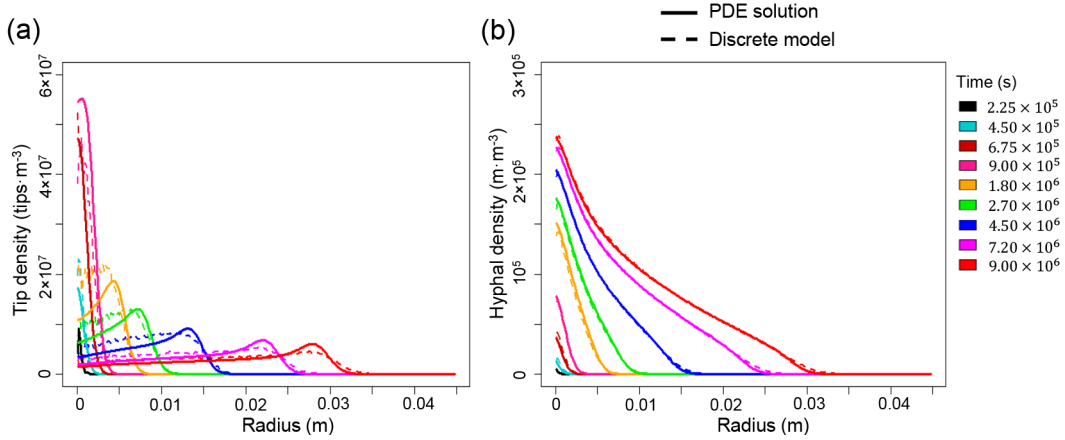


Fig. 3. Comparison of the numerical solutions (solid line) after optimization with the averaged radial profiles (dashed line) of the discrete model at eight times. The black solid lines depict the initial condition for the continuous model, which are the averaged profiles obtained with the discrete model at $t = 2.25 \times 10^5$ s.

Compared to the advection process, which requires the propagation direction to be known a priori, the diffusion process greatly facilitates multi-dimensional modeling. Indeed, as the propagation results are from a diffusion process, the propagation direction is defined locally from the actual gradient of the tip concentration. The other discrete mechanisms are also well described by the continuous terms, even the implicit ones. This is the case in particular for the anastomosis rate at the macroscale, assumed to be linearly related to the tip density, the tip elongation rate and the hyphal density, and for the branching inhibition expressed as an exponential function depending on the branching and tip density per unit length of hyphae. The value of the three parameters (i.e., D , β and γ) determined by inverse procedure are listed in Table 1.

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3.3. Ability of the PDE model to simulate different growth conditions

In the previous section, we proved that the continuous model perfectly reproduces, at the macroscopic scale, the growth of *P. Placenta* for the reference parameter set of the discrete model ([24, 25]). However, the change of the growth conditions, such as temperature, humidity or nutrient concentration, influences the behavior of hyphal growth, particularly branching and elongation rate [32, 33, 34, 35]. It is therefore very important to check whether the continuous model is able to predict the growth behaviour for different parameters of the discrete model. To that purpose, we

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altered the three key parameters of hyphal growth in the discrete model, (i.e., the apical branching probability P_{br}^{api} , the lateral branching probability P_{br}^{lat} and the tip extension rate R). The values of the three parameters listed in Table 1 were considered as reference. Then, for each parameter, we performed simulations with 0.5, 1.5 and 2 times the reference value. These factors were arbitrarily chosen to represent a quite significant change of growth conditions. This means that nine series of simulations (20 realizations per case study) have been carried out by changing one parameter of the discrete model at a time. The corresponding profiles were obtained in the same way as described in Part 2.1.

Obviously, these changes were reported when these discrete parameters are involved explicitly in the continuous formulation. The three macroscopic parameters identified in the previous section were used as initial guess. Then, for each series of profiles, we optimized four times the objective function $E(B)$ (Eq. (17)) by using different set of free parameters (D, γ, β) , (D, γ) , (D, β) and D . The relative errors of the hyphal density between the discrete and continuous solutions are presented in Fig. 4 before and after optimization. According to this bar chart, a good continuous-discrete match requires the value of D to be modified when the discrete parameter P_{br}^{api} changed, while both D and γ should be adjusted when parameters P_{br}^{lat} and R changed. Accordingly, parameter β can be kept unchanged in any case. The relative errors of the optimal solutions are all around 4.00×10^{-2} , which is low enough to ensure the capacity of the continuous model to replicate the mycelial growth under different conditions.

To better understand the impact of the three discrete parameters on the mycelial growth, we compared the profiles of the tip and the hyphal density obtained with different values of P_{br}^{api} , P_{br}^{lat} and R (respectively Fig. 5, 6 and 7) after optimization. In accordance with the results of Fig. 4, D was the unique adjusted parameter to match the changes of P_{br}^{api} while two parameters, D and γ , were adjusted when changing the value of P_{br}^{lat} or R . The numerical solutions agree well with the discrete results for all of the nine cases. With the increase of the apical and lateral branching probability, the local tip and hyphal density increase more rapidly since the proliferation rate of tips is higher. As a subtler effect, we may notice that the extension rate of the colony also augments with the increase of local tips. This result is from a statistical effect: with the increase of tips at the edge of the mycelium, the chance to have tips whose extension direction is close to the radial direction also increases, resulting in a more efficient spatial extension of the network. With the increase of the tip elongation rate, the extension rate of the colony rises but the local hyphal density reduces significantly. Since the tip proliferation rate does not change, the amount of tips produce by branching is similar, but, as the colony occupies a larger space, less tips will be distributed per unit volume.

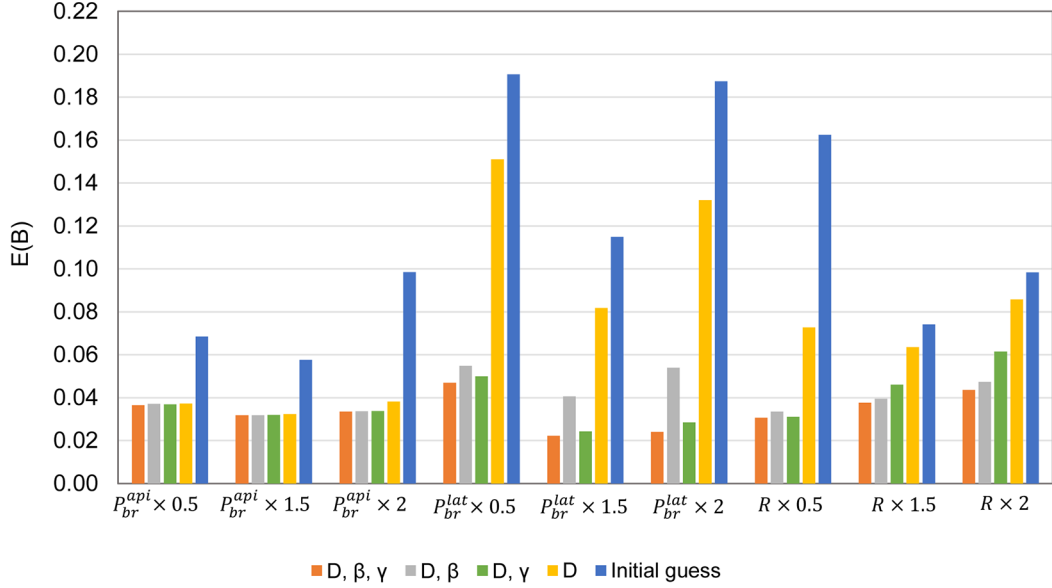


Fig. 4. Relative errors of the hyphal density ($E(B)$) between the discrete profiles and the numerical solutions in nine cases (in each case we varied one growth parameter in the discrete model). The five colors represent the numerical solutions before the optimization (blue) and after the optimization executed in specifying D , β and γ (orange), D and β (grey), D and γ (green), and D (yellow).

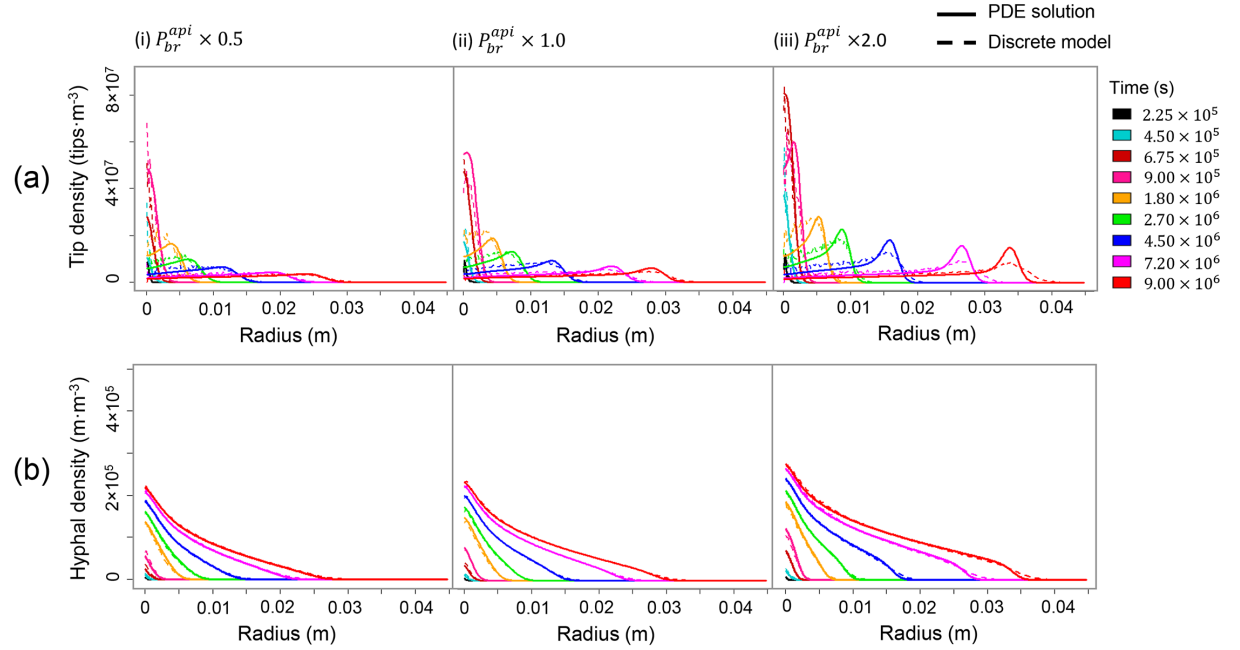


Fig. 5. Comparison of the numerical solutions after the optimization in identifying D and the radial profiles in the three cases of the variation of the apical branching probability P_{br}^{api} in the discrete model.

To summarize, even though the impact of P_{br}^{lat} and R is greater than that of P_{br}^{api} , the three parameters influence the morphology of the mycelial network by intricate effects. This necessarily

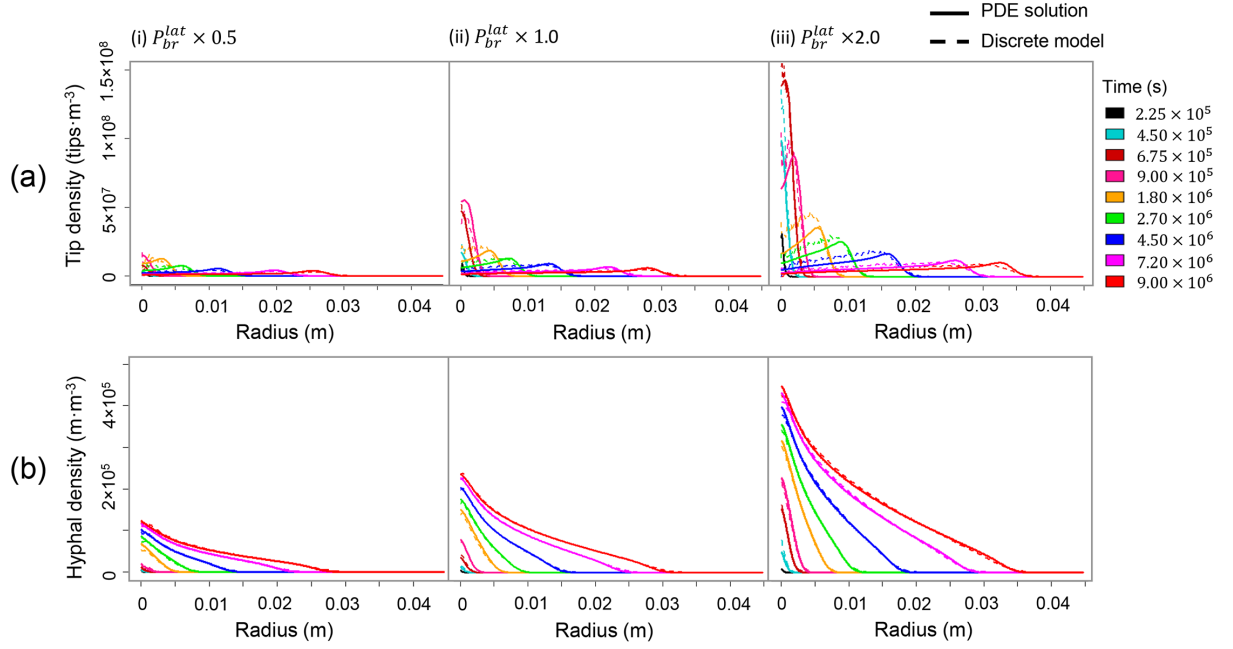


Fig. 6. Comparison of the numerical solutions after the optimization in identifying (D, γ) and the radial profiles in the three cases of the variation of the lateral branching probability P_{br}^{lat} in the discrete model.

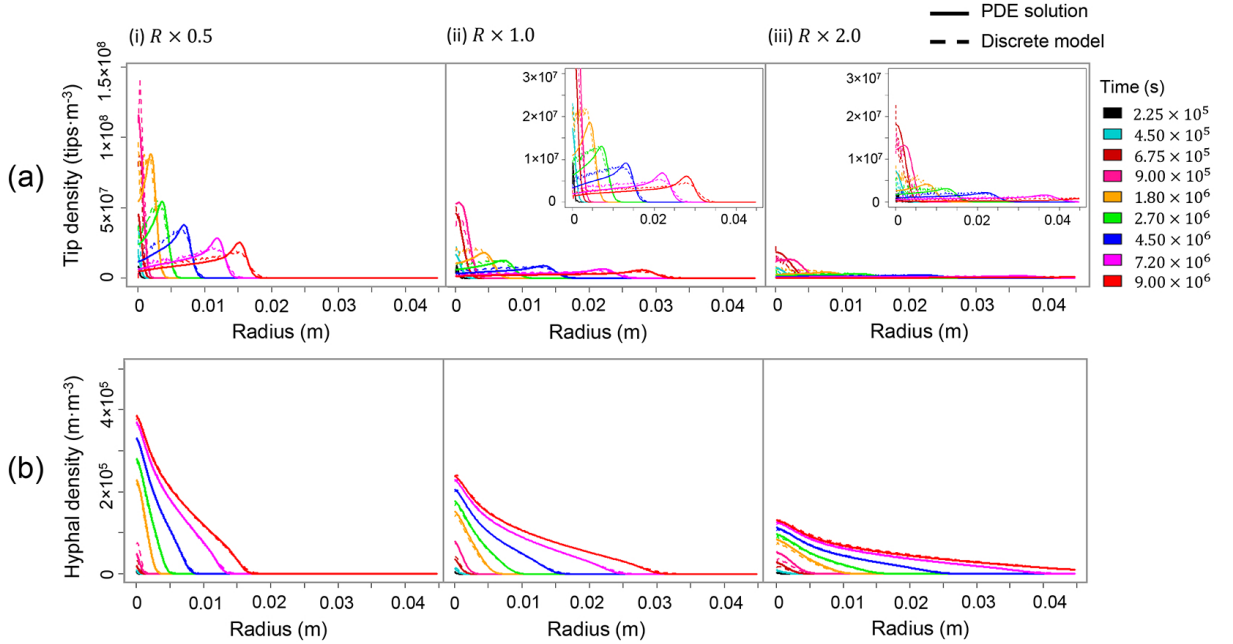


Fig. 7. Comparison of the numerical solutions after the optimization in identifying (D, γ) and the radial profiles in the three cases of the variation of tip elongation rate R in the discrete model.

modifies the colony size and the spatio-temporal distribution of biomass, which explains why the global parameters of the PDE model, the diffusion coefficient D and/or the anastomosis coefficient γ , need to be adjusted. The effect of the three growth parameters on the macroscopic coefficient D or γ are depicted in Fig. 8. The fitted expressions proposed in this figure have all a coefficient of determination r^2 close to the unit.

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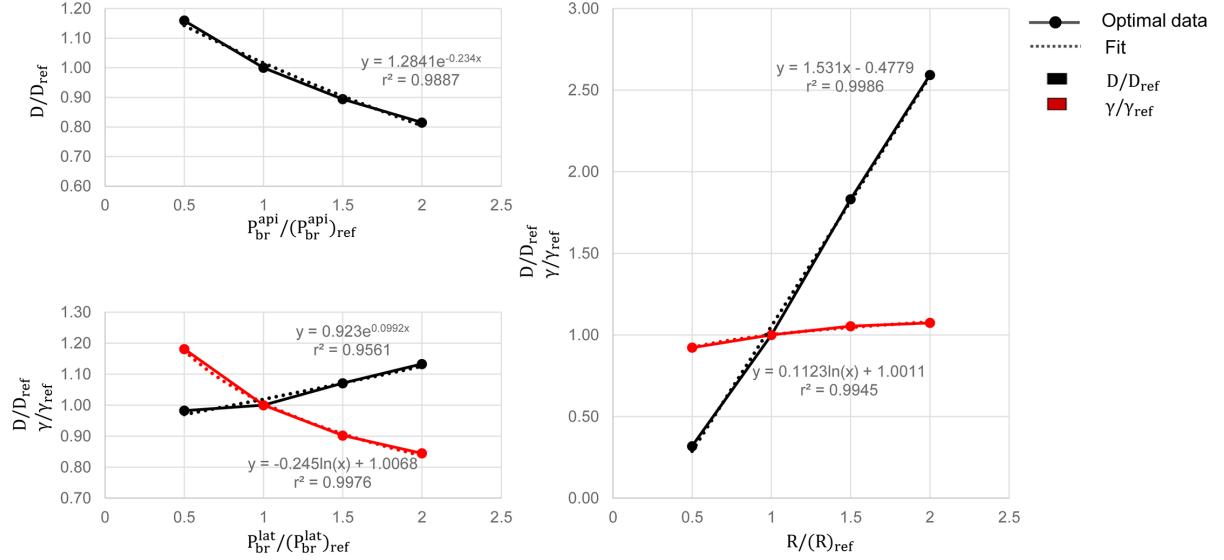


Fig. 8. Relationship between D or γ and the three growth parameters. X_{ref} represents the reference value of each parameter listed in Table 1. Dots are the optimal values of D or γ obtained for different growth parameters. Dash lines are the smoothing functions.

Consistently, the tip elongation rate R has a direct impact on D . The effect of R is almost linear with a slope equal to 1.5. The fact that D varies more rapidly than R , can be explained by the indirect effect of tip elongation rate on tip density.

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The effect of branching probabilities on D reveals more subtle mechanisms. Let's focus first on the negative correlation between apical branching probability P_{br}^{api} and D . We have to keep in mind that a higher value of P_{br}^{api} slightly increases the colony expansion rate, because the probability to have active tips right along the macroscopic radial direction increases with the tip density. Besides, the tip density at the colony edge is higher, giving rise to a larger tip gradient. Consequently, the diffusivity D must be smaller to obtain the right expansion rate.

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This coupled effect of tip gradient and diffusivity to build up the macroscopic extension rate is also likely to explain the positive correlation between lateral branching probability P_{br}^{lat} and D . Due to apical inhibition, a higher lateral branching probability increases the tip density everywhere

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except right at the colony edge. This non-uniform tip source term tends to decrease the tip gradient at the colony edge and should be compensated by a slightly larger diffusivity D .

Regarding the effect of growth condition on γ , equation 9b reminds us that this factor corrects the linear relation between biomass density B and anastomosis. Indeed, due to the statistical partition of biomass B in a volume, the projected area along tip extension is not simply proportional to B . In a certain volume, the proportion of overlapping hyphae increases with density. When P_{br}^{lat} increases or R decreases, the hyphal density increases and γ should be reduced to obtain the correct anastomosis term.

4. Discussion

As summary of this work, it is worth to come back to our global upscaling strategy of mycelial growth modeling. We first proposed a discrete model which mimics the mycelium development at the microscopic scale [25]. This model accounts for the fundamental mechanisms of network development (tip extension, lateral and apical branching, anastomosis). It has been calibrated and validated from experimental data by a rigorous procedure. For that purpose, the network development has been observed during 17 days by confocal microscopy, and the image were subsequently processed to extract relevant information [24]. In the discrete model, some parameters such as the lateral and apical branching probabilities, were determined by an inverse analysis. Without the discrete model, these parameters could not have been accurately determined from experimental data. Moreover, via the validation process, some underlying mechanisms have been discovered, such as the inhibition of branching which is almost impossible to observe directly from the mycelial morphology.

Acting as a bridge between the microscopic behaviors of hyphal growth and the mycelial development at the macroscale, the validated discrete model was used to simulate the mycelial growth during ~ 104 days. This is quite computationally intensive as one realization requires about 50 Go of RAM memory and a computational time of ca. 8 hours on a single core of a HPC cluster with the processor Intel Xeon CPU E5-2670 v3 @ 2.30 GHz. By this way, the spatial dimension was extended from $0.9\text{ cm} \times 0.9\text{ cm}$ (experiment) to $9\text{ cm} \times 9\text{ cm}$ (simulation). Therefore, the discrete model already allowed the spatio-temporal scale to be efficiently extended.

20 realizations of the discrete model, ca. 160 hours of CPU time, were averaged to obtain tip/hyphal density profiles. This piece of information served as input data for the continuous model proposed in the present work. Based on the hyphal growth mechanisms at the discrete

scale, a new reaction-diffusion system, involving three spatio-temporal variables (tip, mycelium and branch densities), has been derived. While most discrete parameters are involved explicitly in the continuous formulation, three macroscopic parameters had to be defined by inverse analysis. Once done, the discrete profiles are perfectly reproduced, in space and in time, by the PDE model. Thanks to the exponential Euler method with Krylov subspace approximation, the computational time to solve the continuous model was again greatly compressed to less than 4 s on a single core of the same cluster. In brief, by following the upscaling strategy, the continuous model realizes the prediction of the mycelial growth during 104 days in less than 4 s. In addition, since the memory required by the continuous model is much less than the discrete model, it is possible to further enlarge, by several orders of magnitude, the spatial and time scales.

Our continuous model is based on a reaction-diffusion formulation. Unlike advection models, it is not necessary for the diffusion process to know the development direction at each point a priori. This feature opens the door to multi-dimensional modeling and growth simulation in porous media. For the reaction part, we rigorously followed the mechanisms of the discrete model, which implies that all parameters have a physical meaning. In addition, thanks to the balance between diffusion and production (a global effect of branching), an almost constant gradient establishes at the edge of the network. This can be seen at the edge of the colony in Fig. 3(a): a tip density peak develops towards the free space. Therefore, an almost constant propagation rate arises from this diffusion-reaction mechanism. Consequently, a constant diffusivity is likely to simulate a given average tip elongation rate. The reaction-diffusion process is applied to the tip density, while the hyphal density is the accumulation of the tip density over time. Similarly, the branch density at any location is obtained as the time integration of the source terms of branches at that location. The 3-variable PDE model involves coupling between variables. For example, the tip density is connected to the hyphal density as the latter influences the lateral branching distribution and the anastomosis. Even so, the relation between the two main densities (tips and biomass) is nicely reproduced by the continuous model.

Apart from the reference simulation, additional series of profiles were produced by the discrete model with various parameter values, which are artificially set just to give us insight into the link between the possible microscopic mechanisms and the corresponding macroscopic behaviours. These configurations have been reproduced by the continuous model. Whether the branching rate or the elongation rate has great impact on the morphology of the mycelium by changing the colony extension rate and the local biomass distributions. They can also alter the maximal value of the tip density, revealing that they change the balance between branching and anastomosis. In addition,

380 due to the decrease of the tip density in the center at increasing hyphal density, it seems that
 there exists a limit for the biomass density on the 2D substrate. This last part told us that only
 two key parameters (the diffusion coefficient D and the anastomosis coefficient γ) out of the three
 macroscopic parameters, need to be adapted when the growth conditions change. It is certain that
 efforts should be made to figure out the quantitative change of the growth parameters depending
 385 on environmental factors, and this work is in progress in our team. However, the good quality of
 the continuous-discrete match proves the potential of the continuous model to describe the fungal
 growth under different conditions. It also provides a tool to realize the bidirectional transfer, from
 the local biological mechanisms to the global biomass distribution and vice-versa. For example,
 if the local mechanisms of hyphal growth change (different growing conditions or another species
 390 of interest), only their local growth characteristics are needed to be measured to obtain both the
 mycelial morphology and the biomass distribution. On the contrary, the variation of the local
 mechanism and the mycelial network can also be estimated via the experimental observation of the
 biomass distribution together with an inverse procedure. In this sense, the numerical efficiency of
 the continuous model is of particular interest.

5. Conclusion

This work proposes a new three-variable reaction-diffusion PDE model capable of simulating
 and predicting the mycelial growth under different environmental conditions. This model was
 calibrated using variable profiles predicted by the average over several realizations of a stochastic
 400 discrete model. For source and sink terms of tips, biomass production and branching density, the
 formulation rigorously follows the discrete mechanisms of mycelial development, which implies that
 all parameters have a physical meaning. Thanks to the discrete model, the ability of this new model
 to account for various growth conditions was successfully tested. Moreover, the correlation between
 the discrete and continuous model has been constructed, which provides us a tool to realize the
 405 bidirectional transfer, from the local biological mechanisms to the global biomass distribution and
 vice-versa.

As the mycelium network propagation is formulated as a diffusion process, this model has the
 potential to be easily extended in multi-dimensions and to heterogeneous media such as a Low Den-
 sity Fiberboard. In the future, additional features such as translocation and substrate-degradation
 410 mechanisms will be incorporated in the model to simulate the mycelial growth in the real morphol-
 ogy of bio-based materials as obtained by nano-tomography. Once combined with decomposition
 mechanisms, this model can also be applied to solid-state fermentation.

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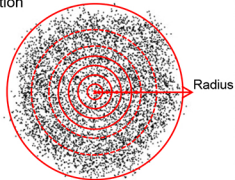
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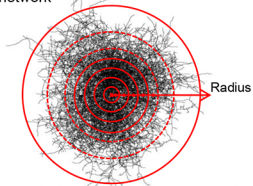
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Discrete model

Tip distribution



Mycelial network



Continuous model

— Numerical solution

- · - Radial profiles by averaging

