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Stochastic Metamodel for Probability of Detection Estimation of Eddy Current Testing Problem in Random Geometric Problem

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The calculation of the Probability Of Detection (POD) in Non Destructive Eddy Current Testing requires the solution of a stochastic model requiring numerous calls of a numerical model leading to a huge computation time. To reduce this computation time, we propose in this paper to combine either the use of a stochastic metamodel and a mapping which avoids the remeshing step. The stochastic metamodel is constructed using the Least Angle Regression Method. This approach is tested on a axisymmetric problem with 6 random input parameters which shows its efficiency and its accuracy.

Index Terms— Eddy Current Testing, Finite Volume Method, Stochastic Model, Least Angle Regression Method, Probability Of Detection.

I. INTRODUCTION

Nowadays, non-destructive testing (NDT) is an essential element of component quality qualification. For inspecting materials and components, several methods are developed. One of these methods is the Eddy Current Method (ECT). The qualification of this process is then required. The size of defects that can be detected should be determined. In practice, it appears that imperfections on the sensors or uncertainties on the material characteristics to be inspected modify the response of the NDT device. The measurement is not deterministic and varies around a targeted value. For this reason, a statistical study must be carried out to calculate the possibility of detecting (or not) defects under different operation conditions [1-2]. A Probability Of Detection (POD) can be estimated to quantify this capability of the NDT device to detect a defect.

The ECT system can be represented by electromagnetic equations such as Maxwell's equations. The difficulty of solving these equations analytically leads to use a numerical method to construct an accurate model. In this work, the Finite Volume (FV) method has been applied. As long as the input parameters are no longer nominal values, so the numerical model FV can be represented by a stochastic system [3] with input parameter which are random.

The response of ECT system is no longer deterministic and a sampling technic like the Monte Carlo Simulation Method can be used to characterize the output and particularly to calculate the POD. A high number of calls of the numerical model FV are required. So repeating the model FV for a fairly large number of realizations is time consuming, especially when the geometry is modified because the mesh should be modified. To avoid the remeshing (RM), a geometric transformation (GT) method [4] has been used which consists in changing the coordinates of the nodes without changing their connectivity. The GT method has been used to solve an electrokinetic problem [5] and more recently a magnetolectric problem [6]. To approximate the response of the stochastic system, a stochastic metamodel [2-3, 7] is

constructed based on a polynomial chaos expansion and the Least Angle Regression (LAR) method.

In this work the numerical POD of the defect depth is estimated using the Hit/Miss method in both methods GT and RM. To reduce the time calculation a stochastic metamodel is used in both methods (GT and RM) to approximate the responses. The two approaches are compared on a NDT stochastic example.

II. ECT AND FV MODEL

The ECT problem is modeled by the axisymmetric formulation of the magnetic vector potential "A" in the domain Ω is used as follows:

$$-\nabla \cdot \left(\frac{1}{\mu} \nabla A \right) + j \omega \sigma A = J_s, \quad \text{in } \Omega \quad (1)$$

with ω , J_s , σ , and μ are the angular frequency, source current density, electrical conductivity and magnetic permeability respectively.

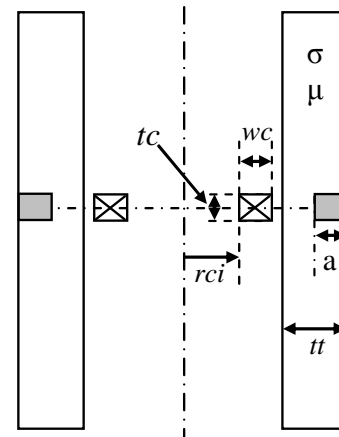


Fig. 1 Coil-tube geometry [8], with rci , wc , tc are the inner radius, the width, height of the coil, tt the thickness of the tube, and the defect a (shaded area).

This ECT problem consists of a coil located in a steam generator tube with an external circumferential defect. The geometry is shown in Fig. 1.

To solve Eq.1 with the FV model, we subdivide the domain into a large number of elements (triangle or quadrilateral). The integration of Eq.1 over each element (P) of the domain Ω is required as it is shows in Fig. 2.

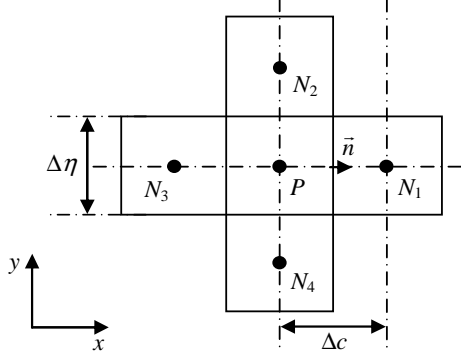


Fig. 2 Unknown elements representation.

The integration of first term of Eq.1 over the element P can be done by using the divergence theorem as in:

$$\begin{aligned} \iint_s \nabla \cdot \left(\frac{1}{\mu} \nabla A \right) \cdot ds &= \oint_{\Delta\eta_i} \left(\frac{1}{\mu} \nabla A \right) \cdot d\eta \cdot \vec{n}_i \\ &= \sum_{f_i} \frac{1}{\mu_i} \frac{A_{N_i} - A_P}{\Delta c_i} \Delta\eta_i, \end{aligned} \quad (2)$$

where A_{N_i} , A_P are the nodal magnetic vector potential of the nodes N_i ($i=1:4$), P respectively, f_i are the faces with \vec{n} its outward normal vector, Δc_i are the distances between the centres of N_i and P , $\Delta\eta_i$ are the lengths of the edges of the element. The non-orthogonal term is considered and interpolated as in [9]. We first solve the Eq.1 for the unknown potential A for all elements of the mesh and then we calculate the impedance of coil which is the quantity of interest to detect the defect. It can be calculated using Faraday's law and Stokes theorem [10] as follow:

$$Z = - \frac{j\omega \oint A \cdot dl}{\int_{\Omega} \mathbf{J}_s \cdot d\Omega}. \quad (3)$$

III. PROBABILITY OF DETECTION ESTIMATION

A. Empirical POD

The determination of the empirical POD requires considerable experimental measurements. A large number of samples are required to have a representative statistical population for signal of the defect. This method is time consuming and very expensive [11]. In this paper, we work with the numerical POD.

B. Numerical POD

• Monte Carlo Simulation Method (MCSM)

The Monte Carlo Simulation method [3, 12] consists in generating a sample of size which corresponds to M realizations of the input parameters, to solve M times the model and then in a postprocessing to give an estimation of the POD.

Its accuracy depends on sample size, and convergence is relatively low. Indeed, thousands of random realizations are often required to obtain a desired accuracy of the POD, which necessarily implies a high calculation time.

For the implementation of the MCSM, it is assumed that the input parameters are independent and have a uniform distribution.

• Stochastic model

As long as the calculated response of the ECT system is no longer nominal (deterministic), the notation of a random variable (Z) is used. So the stochastic model is given by the function:

$$Z = f(X, a). \quad (4)$$

where a is the depth of the defect (in the case without defect $a=0$ and Z is denoted Z_0) and X the vector a finite number of random input parameters. To alleviate the notations, we replace in the following $Z = f(X, a)$ by $Z(X)$ (or Z). X ($X = \{X_1, X_2, \dots, X_{N_X}\}$ with N_X the number of input parameters) gathers the input parameters which are: $\sigma \pm 10\%$, $\mu + 10\%$, rci , wc , $tc \pm 5\%$, and $tt \pm 5\%$. The depths of the defect are 0.05, 0.4970 and 0.9675 mm of the thickness tube with a width of 1.5 mm. The defect is circular and coaxial with the coil.

The model Z can be replaced by an approximate model (metamodel) $\hat{Z} = f_{LAR}(X, a)$ and is given in the following equation:

$$Z = f(X, a) \approx \hat{Z} = f_{LAR}(X, a). \quad (5)$$

The metamodel will be discussed in the next section. The Monte Carlo Simulation is applied to the model $Z(X)$ or $\hat{Z}(X)$ in order to estimate the POD.

• Stochastic Metamodel

It is necessary to find a model faster than the FV model in order to reduce the calculation time. In this case, it may be considered to propagate the uncertainties through a metamodel constructed from Truncated Polynomial Chaos Expansion [12]. In that case, the approximation $\hat{Z}(X)$ of the stochastic FV model $Z(X)$ can be written in the form [7]:

$$\hat{Z}(X) = \sum_{i=1}^{P_{out}} \alpha_i \Psi_i(\xi(X)), \quad (6)$$

with $\Psi = [\Psi_1, \Psi_2, \dots, \Psi_{P_{out}}]$ are the multidimensional polynomials of P_{out} terms, $\xi(X)$ is a vector of the input parameters distributed in the interval $[-1, 1]$, α_i are coefficients to be determined. The value of P_{out} depends on two quantities, N_X and the order of expansion of the polynomial p such as $P_{out} = \frac{(N_X + p)!}{N_X! p!}$, if the number of the input parameters is $N_X = 6$ and the polynomial order $p = 3$, thus the number of polynomial is equal to $P_{out} = 84$.

The coefficients of the polynomial can be estimated using a non-intrusive method such as the regression approximation [13]. The number of realisations desired is at least P_{out} , therefore, $N_X \geq P_{out}$. The unknown coefficients α_i can be calculated by the least square minimization, i.e. by minimizing the mean square of the residual reads:

$$\alpha = \arg \min E \left[\sum_{j=1}^{N_X} \left(Z(X_j) - \hat{Z}(X_j) \right)^2 \right], \quad (7)$$

with the mean operator $E[\cdot]$.

The LAR method is a regression method that reduces the computational cost by selecting the polynomial terms which are correlated the most with the output. The number of terms is therefore significantly reduced compared to the classical regression method. However, the number of polynomials increases exponentially with the dimension. So, in order to decrease the number, an improved LAR which consists in constructing iteratively with an increasing order of polynomials has been used [7].

- *Threshold Determination*

To determine the detection limit (s), the probability of False Alarm (PFA) has to be imposed at a very low value [14]. In our case, we put $PFA = 0.05$. Therefore the detection limit s is calculated by the following formula:

$$PFA = \mathcal{P}(Z_0 > s) = 0.05. \quad (8)$$

with Z_0 is the random impedance without any defect.

- *Probability of detection*

After the detection limit has been determined, the POD is estimated. The POD is the probability of the model response Z of a given defect ($a > 0$) that is above threshold s as shown in the following expression

$$POD = \mathcal{P}(Z > s) \approx \mathcal{P}(\hat{Z} > s). \quad (9)$$

The total number of realizations of the impedance in the presence of defect is denoted by M , we denote M_s the

number of realizations that exceeds the threshold s , therefore the POD can be estimated by $POD = M_s / M$.

IV. GEOMETRIC TRANSFORMATION (GT) METHOD

The dimensions of the sensor as well as the thickness of the tube are random input parameters. It means that during the sampling process the geometry is modified. Due to the large number of FV model calls, the remeshing of the geometry adds non negligible computational time. Moreover, the remeshing introduced an additional numerical noise due to the modification of the connectivities between nodes. The GT method is based on changing the position of the coordinates of the nodes without changing their connectivity. First of all an initial mesh is proposed and decomposed into different subdomains, if the coordinates are changed according to the random vector X_g (vector of geometric random parameters with $X_g \subset X$), then the new mesh is obtained by dilation, compression or translation. The main idea of the GT method is to determine the appropriate transformation. Fig. 3 represents an initial domain and a transformed domain knowing that the new coordinates of X_g .

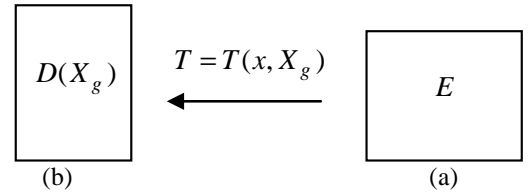


Fig. 3 Geometric domain; a) initial domain (E); b) transformed domain ($D(X_g)$).

The transformation T transforms the initial domain E into a random domain $D(X_g)$. For each realization of X , the nodes are repositioned. Fig. 4 gives the different steps to obtain with the two methods (GT and RM) the stochastic approximate model of the impedance by applying the LAR method.

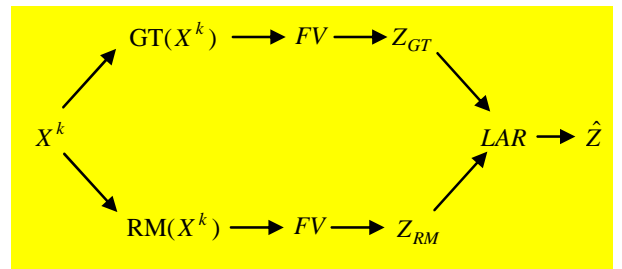


Fig. 4 Impedance calculation approximation with LAR in both methods: RM and GT.

V. NUMERICAL APPLICATION

A sample of M realizations of the input parameters is generated. With the RM method the geometry and the mesh are recalculated for each realization. Therefore, we estimate the POD for different meshes with a different size, denoted

POD_{RM}. The meshes used have S1=9102, S2= 14504, S3= 19836, S4= 25252 elements.

The second method used is the GT method, in which the mesh is fixed at the beginning (initial mesh) and the appropriate transformation is determined. Meshes of different size are also considered as in RM method (S1, S2, S3, and S4). The process of estimating the POD for the GT method denoted POD_{GT}. For each realization, the GT is used in order to relocate the nodes according to the modification of the geometry.

In the both methods (RM and GT), the POD_{RM} and POD_{GT} will be determined with defect sizes a_1 , a_2 , and a_3 equal to 0.05, 0.4970, and 0.9675mm respectively.

To estimate the POD with two methods, the approximate model is used. It is constructed with $N = 150$ realisations of the FV model obtained with GT or RM method, once the metamodel is constructed, the MCSM is applied with a sample of $M = 10000$ realisations for each value of defect size a_i . Repeating the same process with the RM and GT methods and all meshes. A linear metamodel is constructed and considered in this study; hence, the chaos coefficients are perfectly calculated.

To verify the accuracy of the approximate model, an error is calculated by the following expression:

$$\varepsilon = \frac{1}{M} \left(\sum_{j=1}^M \left\| Z(X_j) - \hat{Z}(X_j) \right\| \right) \quad (10)$$

The convergence of the metamodel is accurate with an error less than 10^{-4} which shows that the approximation is of good quality.

The Fig. 5 represents the POD for the S2 mesh, the POD_{Ref} is the reference POD of the GT method with $M = 10000$ and $POD_{Ref} = [0.06, 0.38, 0.95]$; it shows great agreement with the two methods (RM and GT) based on LAR and the reference.

The Table I represents the POD for different methods (RM and GT) and for different size meshes (S_i) where we can see also a good agreement between the different methods with changing of the defect size a_i . We can see that accurate results can be obtained with a coarse mesh and we can see also that the RM and GT methods give very similar results for this case meaning that the numerical has really few influence in the considered example.

TABLE I
POD FOR DIFFERENT METHODS

	order	POD _{RM}			POD _{GT}		
		a_1	a_2	a_3	a_1	a_2	a_3
S1	P=1	0.06	0.38	0.96	0.06	0.37	0.95
S2	P=1	0.06	0.38	0.95	0.06	0.37	0.95
S3	P=1	0.06	0.39	0.96	0.06	0.35	0.94
S4	P=1	0.06	0.39	0.96	0.06	0.38	0.95

VI. CONCLUSION

In this paper two approaches to estimate the POD of an eddy current testing problem of tube coil system (steam generator tubes) have been estimated. The modification of the geometry which is random has been handled by a geometric

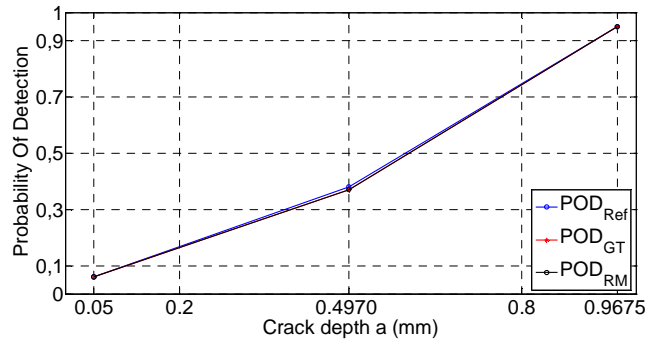


Fig. 5 Probability of Detection for different methods (RM and GT).

transformation. The geometric transformation (or mapping) is shown to give similar results to the remeshing technic but is less time consuming. The stochastic metamodel has been used in both methods to reduce the computation cost of the high number of realisation and showed a great precision.

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