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Generalized logarithmic Hardy-Littlewood-Sobolev inequality

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This paper is devoted to logarithmic Hardy-Littlewood-Sobolev inequalities in the two-dimensional Euclidean space, in presence of an external potential with logarithmic growth. The coupling with the potential introduces a new parameter, with two regimes. The attractive regime reflects the standard logarithmic Hardy-Littlewood-Sobolev inequality. The second regime corresponds to a reverse inequality, with the opposite sign in the convolution term, that allows us to bound the free energy of a drift-diffusion-Poisson system from below. Our method is based on an extension of an entropy method proposed by E. Carlen, J. Carrillo and M. Loss, and on a nonlinear diffusion equation.

1 Main result and motivation

On \mathbb{R}^2 , let us define the *density of probability* $\mu = e^{-V}$ and the *external potential* V by

$$\mu(x) := \frac{1}{\pi (1+|x|^2)^2} \quad \text{and} \quad V(x) := -\log \mu(x) = 2\log(1+|x|^2) + \log \pi \quad \forall x \in \mathbb{R}^2.$$

We shall denote by $L^1_+(\mathbb{R}^2)$ the set of a.e. nonnegative functions in $L^1(\mathbb{R}^2)$. Our main result is the following *generalized logarithmic Hardy-Littlewood-Sobolev inequality*.

Theorem 1.1. For any $\alpha \ge 0$, we have that

$$\int_{\mathbb{R}^2} f \log\left(\frac{f}{M}\right) dx + \alpha \int_{\mathbb{R}^2} V f \, dx + M(1-\alpha) \left(1 + \log \pi\right) \ge \frac{2}{M} \left(\alpha - 1\right) \iint_{\mathbb{R}^2 \times \mathbb{R}^2} f(x) f(y) \log|x - y| \, dx \, dy \quad (1)$$

for any function $f \in L^1_+(\mathbb{R}^2)$ with $M = \int_{\mathbb{R}^2} f \, dx > 0$. Moreover, the equality case is achieved by $f_* = M \mu$ and f_* is the unique optimal function for any $\alpha > 0$.

With $\alpha = 0$, the inequality is the classical *logarithmic Hardy-Littlewood-Sobolev inequality*

$$\int_{\mathbb{R}^2} f \log\left(\frac{f}{M}\right) dx + \frac{2}{M} \iint_{\mathbb{R}^2 \times \mathbb{R}^2} f(x) f(y) \log|x - y| \, dx \, dy + M \left(1 + \log \pi\right) \ge 0. \tag{2}$$

In that case f_{\star} is an optimal function as well as all functions generated by a translation and a scaling of f_{\star} . As long as the parameter α is in the range $0 \le \alpha < 1$, the coefficient of the right-hand side of (1)

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is negative and the inequality is essentially of the same nature as the one with $\alpha = 0$. It can indeed be written as

$$\int_{\mathbb{R}^2} f \log\left(\frac{f}{M}\right) dx + \alpha \int_{\mathbb{R}^2} V f \, dx + M \left(1 - \alpha\right) \left(1 + \log \pi\right) + \frac{2}{M} \left(1 - \alpha\right) \iint_{\mathbb{R}^2 \times \mathbb{R}^2} f(x) f(y) \log|x - y| \, dx \, dy \ge 0$$

For reasons that will be made clear below, we shall call this range the attractive range.

If $\alpha = 1$, the inequality is almost trivial since

$$\int_{\mathbb{R}^2} f \log\left(\frac{f}{M}\right) dx + \int_{\mathbb{R}^2} V f \, dx = \int_{\mathbb{R}^2} f \log\left(\frac{f}{f_\star}\right) dx \ge 0 \tag{3}$$

is a straightforward consequence of Jensen's inequality. Now it is clear that by adding (2) multiplied by $(1 - \alpha)$ and (3) multiplied by α , we recover (1) for any $\alpha \in [0, 1]$. As a consequence (1) is a straightforward interpolation between (2) and (3) in the *attractive range*.

Now, let us consider the *repulsive range* $\alpha > 1$. It is clear that the inequality is no more the consequence of a simple interpolation. We can also observe that the coefficient $(\alpha - 1)$ in the right-hand side of (1) is now positive. Since

$$G(x) = -\frac{1}{2\pi} \log|x|$$

is the Green function associated with $-\Delta$ on \mathbb{R}^2 , so that we can define

$$(-\Delta)^{-1} f(x) = (G * f)(x) = -\frac{1}{2\pi} \int_{\mathbb{R}^2} \log|x - y| f(y) \, dy,$$

it is interesting to write (1) as

$$\int_{\mathbb{R}^2} f \log\left(\frac{f}{M}\right) dx + \alpha \int_{\mathbb{R}^2} V f \, dx + \frac{4\pi}{M} \left(\alpha - 1\right) \int_{\mathbb{R}^2} f \left(-\Delta\right)^{-1} f \, dx \ge M \left(\alpha - 1\right) \left(1 + \log \pi\right). \tag{4}$$

If *f* has a sufficient decay as $|x| \to +\infty$, for instance if *f* is compactly supported, we know that $(-\Delta)^{-1} f(x) \sim -\frac{M}{2\pi} \log |x|$ for large values of |x| and as a consequence,

$$\alpha V + \frac{4\pi}{M} (\alpha - 1) (-\Delta)^{-1} f \sim 2(\alpha + 1) \log |x| \to +\infty \text{ as } |x| \to +\infty.$$

In a minimization scheme, this prevents the runaway of the left-hand side in (4). On the other hand, $\int_{\mathbb{R}^2} f \log f \, dx$ prevents any concentration, and this is why it can be heuristically expected that the left-hand side of (4) indeed admits a minimizer.

Inequality (2) was proved in [8] by E. Carlen and M. Loss (also see [2]). An alternative method based on nonlinear flows was given by E. Carlen, J. Carrillo and M. Loss in [7]: see Section 2 for a sketch of their proof. Our proof of Theorem 1.1 relies on an extension of this approach which takes into account the presence of the external potential *V*. A remarkable feature of this approach is that it is insensitive to the sign of $\alpha - 1$.

One of the key motivations for studying (4) arises from entropy methods applied to *drift-diffusion-Poisson* models which, after scaling out all physical parameters, are given by

$$\frac{\partial f}{\partial t} = \Delta f + \beta \nabla \cdot (f \nabla V) + \nabla \cdot (f \nabla \phi)$$
(5)

with a nonlinear coupling given by the Poisson equation

$$-\varepsilon \Delta \phi = f. \tag{6}$$

Here $V = -\log \mu$ is the external *confining potential* and we choose it as in the statement of Theorem 1.1, while $\beta \ge 0$ is a coupling parameter with V, which measures the strength of the external potential. We shall consider more general potentials at the end of this paper. The coefficient ε in (6) is either $\varepsilon = -1$, which corresponds to the *attractive* case, or $\varepsilon = +1$, which corresponds to the *repulsive* case. In terms of applications, when $\varepsilon = -1$, (6) is the equation for the mean field potential obtained from Newton's law of attraction in gravitation, for applications in astrophysics, or for the Keller-Segel concentration of chemo-attractant in chemotaxis. The case $\varepsilon = +1$ is used for repulsive electrostatic forces in semiconductor physics, electrolytes, plasmas and charged particle models.

In view of *entropy methods* applied to PDEs (see for instance [15]), it is natural to consider the *free energy functional*

$$\mathscr{F}_{\beta}[f] := \int_{\mathbb{R}^2} f \log f \, dx + \beta \int_{\mathbb{R}^2} V f \, dx + \frac{1}{2} \int_{\mathbb{R}^2} \phi f \, dx \tag{7}$$

because, if f > 0 solves (5)-(6) and is smooth enough, with sufficient decay properties at infinity, then

$$\frac{d}{dt}\mathscr{F}_{\beta}[f(t,\cdot)] = -\int_{\mathbb{R}^2} f \left| \nabla \log f + \beta \nabla V + \nabla \phi \right|^2 dx \tag{8}$$

so that \mathscr{F}_{β} is a Lyapunov functional. Of course, a preliminary question is to establish under which conditions \mathscr{F}_{β} is bounded from below. The answer is given by the following result.

Corollary 1.2. Let M > 0. The functional \mathscr{F}_{β} is bounded from below and admits a minimizer on the set of the functions $f \in L^1_+(\mathbb{R}^2)$ such that $\int_{\mathbb{R}^2} f \, dx = M$ if and only if either $\varepsilon = -1$ and $\beta \ge 1 + \frac{M}{8\pi}$, or $\varepsilon = +1$, $\beta \ge 0$ and $M \le 8\pi$. If $\varepsilon = -1$, the minimizer is unique.

As we shall see in Section 3.1, Corollary 1.2 is a simple consequence of Theorem 1.1. In the case of the parabolic-elliptic Keller-Segel model, that is, with $\varepsilon = -1$ and $\beta = 0$, this has been used in [12, 4] to provide a sharp range of existence of the solutions to the evolution problem. In [6], the case $\varepsilon = -1$ with a potential *V* with quadratic growth at infinity was also considered, in the study of intermediate asymptotics of the parabolic-elliptic Keller-Segel model.

Concerning the *drift-diffusion-Poisson* model (5)-(6) and considerations on the *free energy*, in the electrostatic case, we can quote, among many others, [14, 13] and subsequent papers. In the Euclidean space with confinig potentials, we shall refer to [10, 11, 3, 1]. However, as far as we know, these papers are primarily devoted to dimensions $d \ge 3$ and the sharp growth condition on V when d = 2 has not been studied so far. The goal of this paper is to fill this gap. The specific choice of V has been made to obtain explicit constants and optimal inequalities, but the confining potential plays a role only at infinity if we are interested in the boundedness from below of the free energy. In Section 3.3, we shall give a result for general potentials on \mathbb{R}^2 : see Theorem 3.4 for a statement.

2 **Proof of the main result**

As an introduction to the key method, we briefly sketch the proof of (2) given by E. Carlen, J. Carrillo and M. Loss in [7]. The main idea is to use the nonlinear diffusion equation

$$\frac{\partial f}{\partial t} = \Delta \sqrt{f}$$

with a nonnegative initial datum f_0 . The equation preserves the mass $M = \int_{\mathbb{R}^2} f \, dx$ and is such that

$$\frac{d}{dt} \left(\int_{\mathbb{R}^2} f \log f \, dx - \frac{4\pi}{M} \int_{\mathbb{R}^2} f\left((-\Delta)^{-1} f \right) dx \right) = -\frac{8}{M} \left(\int_{\mathbb{R}^2} \left| \nabla f^{1/4} \right|^2 dx \int_{\mathbb{R}^2} f \, dx - \pi \int_{\mathbb{R}^2} f^{3/2} \, dx \right)$$

According to [9], the Gagliardo-Nirenberg inequality

$$\left\|\nabla g\right\|_{2}^{2} \left\|g\right\|_{4}^{4} \ge \pi \left\|g\right\|_{6}^{6} \tag{9}$$

applied to $g = f^{1/4}$ guarantees that the right-hand side is nonpositive. By the general theory of fast diffusion equations (we refer for instance to [17]), we know that the solution behaves for large values of *t* like a self-similar solution, the so-called Barenblatt solution, which is given by $B(t, x) := t^{-2} f_{\star}(x/t)$. As a consequence, we find that

$$\begin{split} \int_{\mathbb{R}^2} f_0 \log f_0 \, dx &- \frac{4\pi}{M} \int_{\mathbb{R}^2} f_0 \left((-\Delta)^{-1} f_0 \right) dx \\ &\geq \lim_{t \to +\infty} \int_{\mathbb{R}^2} B \log B \, dx - \frac{4\pi}{M} \int_{\mathbb{R}^2} B \left((-\Delta)^{-1} B \right) dx = \int_{\mathbb{R}^2} f_\star \log f_\star \, dx - \frac{4\pi}{M} \int_{\mathbb{R}^2} f_\star \left((-\Delta)^{-1} f_\star \right) dx \end{split}$$

After an elementary computation, we observe that the above inequality is exactly (2) written for $f = f_0$.

The point is now to adapt this strategy to the case with an external potential. This justifies why we have to introduce a nonlinear diffusion equation with a drift. As we shall see below, the method is insensitive to α and applies when $\alpha > 1$ exactly as in the case $\alpha \in (0, 1)$. A natural question is whether solutions are regular enough to perform the computations below and in particular if they have a sufficient decay at infinity to allow all kinds of integrations by parts needed by the method. The answer is twofold. First, we can take an initial datum f_0 which is as smooth and decaying as $|x| \rightarrow +\infty$ as needed, prove the inequality and argue by density. Second, integrations by parts can be justified by an approximation scheme consisting in a truncation of the problem in larger and larger balls. We refer to [17] for regularity issues and to [15] for the truncation method. In the proof, we will therefore leave these issues apart, as they are purely technical.

Proof of Theorem 1.1. By homogeneity, we can assume that M = 1 without loss of generality and consider the evolution equation

$$\frac{\partial f}{\partial t} = \Delta \sqrt{f} + 2\sqrt{\pi} \,\nabla \cdot (x f) \,.$$

1) Using simple integrations by parts, we compute

$$\int_{\mathbb{R}^2} \left(1 + \log f\right) \Delta \sqrt{f} \, dx = -8 \int_{\mathbb{R}^2} \left|\nabla f^{1/4}\right|^2 dx$$

and

$$\int_{\mathbb{R}^2} \left(1 + \log f \right) \nabla \cdot (xf) \, dx = -\int_{\mathbb{R}^2} \frac{\nabla f}{f} \cdot (xf) \, dx = -\int_{\mathbb{R}^2} x \cdot \nabla f \, dx = 2 \int_{\mathbb{R}^2} f \, dx = 2$$

As a consequence, we obtain that

$$\frac{d}{dt} \int_{\mathbb{R}^2} f \log f \, dx = -8 \int_{\mathbb{R}^2} \left| \nabla f^{1/4} \right|^2 dx + 8\pi \int_{\mathbb{R}^2} \mu^{3/2} \, dx \tag{10}$$

using

$$\int_{\mathbb{R}^2} \mu^{3/2} \, dx = \frac{1}{2\sqrt{\pi}}$$

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2) By elementary considerations again, we find that

$$4\pi \int_{\mathbb{R}^2} f(-\Delta)^{-1} \left(\Delta \sqrt{f} \right) dx = -4\pi \int_{\mathbb{R}^2} f^{3/2} dx$$

and

$$\begin{split} 4\pi \int_{\mathbb{R}^2} \nabla \cdot (xf) (-\Delta)^{-1} f \, dx &= -4\pi \int_{\mathbb{R}^2} x f \cdot \nabla (-\Delta)^{-1} f \, dx \\ &= 2 \iint_{\mathbb{R}^2 \times \mathbb{R}^2} f(x) f(y) \, x \cdot \frac{x - y}{|x - y|^2} \, dx \, dy \\ &= \iint_{\mathbb{R}^2 \times \mathbb{R}^2} f(x) f(y) \, (x - y) \cdot \frac{x - y}{|x - y|^2} \, dx \, dy = 1 \end{split}$$

where, in the last line, we exchanged the variables *x* and *y* and took the half sum of the two expressions. This proves that

$$\frac{d}{dt} \left(4\pi \int_{\mathbb{R}^2} f\left((-\Delta)^{-1} f \right) dx \right) = -8\pi \int_{\mathbb{R}^2} \left(f^{3/2} - \mu^{3/2} \right) dx.$$
(11)

3) We observe that

$$\mu(x) = \frac{1}{\pi \left(1 + |x|^2\right)^2} = e^{-V(x)}$$

solves

$$\Delta V = -\Delta \log \mu = 8\pi\,\mu\tag{12}$$

and, as a consequence,

$$\int_{\mathbb{R}^2} V \Delta \sqrt{f} \, dx = \int_{\mathbb{R}^2} \Delta V \sqrt{f} \, dx = 8 \pi \int_{\mathbb{R}^2} \mu \sqrt{f} \, dx.$$

Since

$$2\sqrt{\pi} \int_{\mathbb{R}^2} V \nabla \cdot (xf) \, dx = -2\sqrt{\pi} \int_{\mathbb{R}^2} f \, x \cdot \nabla V \, dx = -8\sqrt{\pi} \int_{\mathbb{R}^2} \frac{|x|^2}{1+|x|^2} f \, dx$$
$$= -8\sqrt{\pi} + 8\sqrt{\pi} \int_{\mathbb{R}^2} \frac{f}{1+|x|^2} \, dx = -8\sqrt{\pi} + 8\pi \int_{\mathbb{R}^2} \sqrt{\mu} f \, dx,$$

we conclude that

$$\frac{d}{dt} \int_{\mathbb{R}^2} f V \, dx = 8\pi \int_{\mathbb{R}^2} \left(\mu \sqrt{f} + \sqrt{\mu} \, f - 2\,\mu^{3/2} \right) dx. \tag{13}$$

Let us define

$$\mathscr{F}[f] := \int_{\mathbb{R}^2} f \log f \, dx + \alpha \int_{\mathbb{R}^2} V f \, dx + (1-\alpha) \left(1 + \log \pi\right) + 2 \left(1 - \alpha\right) \iint_{\mathbb{R}^2 \times \mathbb{R}^2} f(x) f(y) \log |x - y| \, dx \, dy.$$

Collecting (10), (11) and (13), we find that

$$\frac{d}{dt}\mathscr{F}[f(t,\cdot)] = -8\left(\int_{\mathbb{R}^2} \left|\nabla f^{1/4}\right|^2 dx - \pi \int_{\mathbb{R}^2} f^{3/2} dx\right) - 8\pi \alpha \int_{\mathbb{R}^2} \left(f^{3/2} - \mu \sqrt{f} - \sqrt{\mu} f + \mu^{3/2}\right) dx.$$

Notice that

$$\int_{\mathbb{R}^2} \left(f^{3/2} - \mu \sqrt{f} - \sqrt{\mu} f + \mu^{3/2} \right) dx = \int_{\mathbb{R}^2} \varphi \left(\frac{f}{\mu} \right) \mu^{3/2} dx \quad \text{with} \quad \varphi(t) := t^{3/2} - t - \sqrt{t} + 1$$

and that φ is a strictly convex function on \mathbb{R}^+ such that $\varphi(1) = \varphi'(1) = 0$, so that φ is nonnegative. On the other hand, by (9), we know that

$$\int_{\mathbb{R}^2} |\nabla f^{1/4}|^2 \, dx - \pi \int_{\mathbb{R}^2} f^{3/2} \, dx \ge 0$$

as in the proof of [7]. Altogether, this proves that $t \mapsto \mathscr{F}[f(t, \cdot)]$ is monotone nonincreasing. Hence

$$\mathscr{F}[f_0] \ge \mathscr{F}[f(t,\cdot)] \ge \lim_{t \to +\infty} \mathscr{F}[f(t,\cdot)] = \mathscr{F}[f_\star] = 0.$$

This completes the proof of (1).

3 Consequences

3.1 Proof of Corollary 1.2

To prove the result of Corollary 1.2, we have to establish first that the *free energy* functional \mathscr{F}_{β} is bounded from below. Instead of using standard variational methods to prove that a minimizer is achieved, we can rely on the flow associated with (5)-(6).

• **Repulsive case.** Let us consider the *free energy* functional defined in (7) where ϕ is given by (6) with $\varepsilon = +1$, *i.e.*, $\phi = -\frac{1}{2\pi} \log |\cdot| * f$.

Lemma 3.1. Let M > 0 and $\varepsilon = +1$. Then \mathscr{F}_{β} is bounded from below on the set of the functions $f \in L^1_+(\mathbb{R}^2)$ such that $\int_{\mathbb{R}^2} f \, dx = M$ if and only if $\beta \ge 1 + \frac{M}{8\pi}$.

Proof. With $g = \frac{f}{M}$ and $\alpha = 1 + \frac{M}{8\pi}$, this means that

$$\frac{1}{M}\mathscr{F}_{\beta}[f] - \log M = \int_{\mathbb{R}^{2}} g \log g \, dx + \beta \int_{\mathbb{R}^{2}} V g \, dx - \frac{M}{4\pi} \iint_{\mathbb{R}^{2} \times \mathbb{R}^{2}} g(x) g(y) \log |x - y| \, dx \, dy$$
$$= (\beta - \alpha) \int_{\mathbb{R}^{2}} V g \, dx + \int_{\mathbb{R}^{2}} g \log g \, dx + \alpha \int_{\mathbb{R}^{2}} V g \, dx - 2 (\alpha - 1) \iint_{\mathbb{R}^{2} \times \mathbb{R}^{2}} g(x) g(y) \log |x - y| \, dx \, dy$$
$$\ge (\beta - \alpha) \int_{\mathbb{R}^{2}} V g \, dx - (1 - \alpha) \left(1 + \log \pi\right)$$

according to Theorem 1.1: the condition $\beta \ge \alpha$ is enough to prove that $\mathscr{F}_{\beta}[f]$ is bounded from below.

Reciprocally, let us assume that $\beta < 1 + \frac{M}{8\pi}$ and let $f_{\varepsilon}(x) := \varepsilon^2 f_{\star}(\varepsilon x)$. It is then straightforward to check that \mathscr{F}_{β} is not bounded from below because

$$\mathscr{F}_{\beta}[f_{\varepsilon}] \sim -4M(\beta-\alpha)\log\varepsilon \to -\infty \text{ as } \varepsilon \to 0_+.$$

Proof of Corollary 1.2 with $\varepsilon = +1$. Let us consider a smooth solution of (5)-(6). We refer to [16] for details and to [1] for similar arguments in dimension $d \ge 3$. According to (8), f converges as $t \to +\infty$ to a solution of

$$\nabla \log f + \beta \nabla V + \nabla \phi = 0.$$

Notice that this already proves the existence of a stationary solution. The equation can be solved as

$$f = M \frac{e^{-\beta V - \phi}}{\int_{\mathbb{R}^2} e^{-\beta V - \phi} \, dx}$$

after taking into account the conservation of the mass. With (6), the problem is reduced to solving

$$-\Delta \psi = M \left(\frac{e^{-\gamma V - \psi}}{\int_{\mathbb{R}^2} e^{-\gamma V - \psi} \, dx} - \mu \right), \quad \psi = (\beta - \gamma) \, V + \phi, \quad \gamma = \beta - \frac{M}{8\pi}$$

using (12). It is a critical point of the functional $\psi \mapsto \mathscr{J}_{M,\gamma}[\psi] := \frac{1}{2} \int_{\mathbb{R}^2} |\nabla \psi|^2 dx + M \int_{\mathbb{R}^2} \psi \mu dx + M \log (\int_{\mathbb{R}^2} e^{-\gamma V - \psi} dx)$. Such a functional is strictly convex as, for instance, in [10, 11]. We conclude that ψ is unique up to an additional constant.

• *Attractive case.* Let us consider the *free energy* functional (7) \mathscr{F}_{β} where ϕ is given by (6) with $\varepsilon = -1$, *i.e.*, $\phi = \frac{1}{2\pi} \log |\cdot| * f$. Inspired by [12], we have the following estimate.

Lemma 3.2. Let $\beta \ge 0$ and $\varepsilon = -1$. Then \mathscr{F}_{β} is bounded from below on the set of the functions $f \in L^{1}_{+}(\mathbb{R}^{2})$ such that $\int_{\mathbb{R}^{2}} f \, dx = M$ if and only if $M \le 8\pi$.

Proof. With $g = \frac{f}{M}$ and $\alpha = 1 - \frac{M}{8\pi}$, Theorem 1.1 applied to

$$\frac{1}{M} \mathscr{F}_{\beta}[f] - \log M$$

$$= (\beta - \alpha) \int_{\mathbb{R}^2} V g \, dx + \int_{\mathbb{R}^2} g \log g \, dx + \alpha \int_{\mathbb{R}^2} V g \, dx + 2 (1 - \alpha) \iint_{\mathbb{R}^2 \times \mathbb{R}^2} g(x) g(y) \log |x - y| \, dx \, dy$$

$$\geq (\beta - \alpha) \int_{\mathbb{R}^2} V g \, dx - (1 - \alpha) \left(1 + \log \pi\right)$$

proves that the free energy is bounded from below if $M \le 8\pi$. On the other hand, if $f_{\lambda}(x) := \lambda^2 f(\lambda x)$ and $M > 8\pi$, then

$$\mathscr{F}_{\beta}[f_{\lambda}] \sim -2M\left(\frac{M}{8\pi}-1\right)\log\lambda \to -\infty \quad \text{as} \quad \lambda \to +\infty,$$

which proves that \mathscr{F}_{β} is not bounded from below.

Proof of Corollary 1.2 with $\varepsilon = -1$. The proof goes as in the case $\beta = 0$. We refer to [4] and leave details to the reader.

Remark 3.3. Let us notice that \mathscr{F}_{β} is unbounded from below if $\beta < 0$. This follows from the observation that $\lim_{|y|\to\infty} \mathscr{F}_{\beta}[f_{y}] = -\infty$ where $f_{y}(x) = f(x + y)$ for any admissible f.

3.2 Duality

When $\alpha > 1$, we can write a first inequality by considering the *repulsive case* in the proof of Corollary 1.2 and observing that

$$\mathcal{J}_{M,\gamma}[\psi] \ge \min \mathcal{J}_{M,\gamma}$$

where $\psi \in W^{2,1}_{loc}(\mathbb{R}^2)$ is such that $\int_{\mathbb{R}^2} (\Delta \psi) dx = 0$ and the minimum is taken on the same set of functions.

When $\alpha \in [0, 1)$, it is possible to argue by duality as in [5, Section 2]. Since f_{\star} realizes the equality case in (1), we know that

$$\int_{\mathbb{R}^2} f_\star \log\left(\frac{f_\star}{M}\right) dx + \alpha \int_{\mathbb{R}^2} V f_\star \, dx + M(1-\alpha) \left(1 + \log \pi\right) = \frac{2}{M} \left(\alpha - 1\right) \iint_{\mathbb{R}^2 \times \mathbb{R}^2} f_\star(x) f_\star(y) \log|x-y| \, dx \, dy$$

and, using the fact that f_{\star} is a critical point of the difference of the two sides of (1), we also have that

$$\int_{\mathbb{R}^2} \log\left(\frac{f}{f_\star}\right) (f - f_\star) \, dx + \alpha \int_{\mathbb{R}^2} V\left(f - f_\star\right) \, dx = \frac{4}{M} \left(\alpha - 1\right) \iint_{\mathbb{R}^2 \times \mathbb{R}^2} \left(f(x) - f_\star(x)\right) f_\star(y) \log|x - y| \, dx \, dy.$$

By subtracting the first identity to (1) and adding the second identity, we can rephrase (1) as

$$\mathscr{F}_{(1)}[f] := \int_{\mathbb{R}^2} f \log\left(\frac{f}{f_{\star}}\right) dx \ge \frac{4\pi}{M} (1-\alpha) \int_{\mathbb{R}^2} (f-f_{\star}) (-\Delta)^{-1} (f-f_{\star}) dx := \mathscr{F}_{(2)}[f].$$

Let us consider the Legendre transform

$$\mathscr{F}^*_{(i)}[g] := \sup_f \left(\int_{\mathbb{R}^2} g f \, dx - \mathscr{F}_{(i)}[f] \right)$$

where the supremum is restricted to the set of the functions $f \in L^1_+(\mathbb{R}^2)$ such that $M = \int_{\mathbb{R}^2} f \, dx$. After taking into account the Lagrange multipliers associated with the mass constraint, we obtain that

$$M\log\left(\int_{\mathbb{R}^2} e^{g-V} \, dx\right) = \mathscr{F}_{(1)}^*[g] \le \frac{M}{16\pi (1-\alpha)} \int_{\mathbb{R}^2} |\nabla g|^2 \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \, dx + M \int_{\mathbb{R}^2} g \, e^{-V} \, dx = \mathscr{F}_{(2)}^*[g] \,$$

We can get rid of *M* by homogeneity and recover the standard Euclidean form of the Onofri inequality in the limit case as $\alpha \to 0_+$, which is clearly the sharpest one for all possible $\alpha \in [0, 1)$.

3.3 Extension to general confining potentials with critical asymptotic growth

As a concluding observation, let us consider a general potential W on \mathbb{R}^2 such that

$$W \in C(\mathbb{R}^2)$$
 and $\lim_{|x| \to +\infty} \frac{W(x)}{V(x)} = \beta$ (\mathcal{H}_W)

and the associated free energy functional

$$\mathscr{F}_{\beta,W}[f] := \int_{\mathbb{R}^2} f \log f \, dx + \beta \int_{\mathbb{R}^2} W f \, dx + \frac{1}{2} \int_{\mathbb{R}^2} \phi f \, dx$$

where ϕ is given in terms of f > 0 by (6). With previous notations, $\mathscr{F}_{\beta} = \mathscr{F}_{\beta,V}$. Our last result is that the asymptotic behaviour obtained from (\mathscr{H}_W) is enough to decide whether $\mathscr{F}_{\beta,W}$ is bounded from below or not. The precise result goes as follows.

Theorem 3.4. Under Assumption (\mathscr{H}_W) , $\mathscr{F}_{\beta,W}$ defined as above is bounded from below if either $\varepsilon = -1$ and $\beta > 1 + \frac{M}{8\pi}$, or $\varepsilon = +1$, $\beta > 0$ and $M \le 8\pi$. The result is also true in the limit case if $(W - \beta V) \in L^{\infty}(\mathbb{R}^2)$ and either $\varepsilon = -1$ and $\beta = 1 + \frac{M}{8\pi}$, or $\varepsilon = +1$, $\beta = 0$ and $M \le 8\pi$.

Proof. If $(W - \beta V) \in L^{\infty}(\mathbb{R}^2)$, we can write that

$$\mathscr{F}_{\beta,W}[f] \ge \mathscr{F}_{\beta}[f] - M \| W - \beta V \|_{\mathcal{L}^{\infty}(\mathbb{R}^2)}.$$

This completes the proof in the limit case. Otherwise, we redo the argument using $\tilde{\beta} V - (\tilde{\beta} V - W)_+$ for some $\tilde{\beta} \in (0, \beta)$ if $\varepsilon = +1$, and for some $\tilde{\beta} \in (1 + \frac{M}{8\pi}, \beta)$ if $\varepsilon = -1$.

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