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Reaction Networks to Boolean Networks: Exact Boolean Abstraction for Linear Equation Systems

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Abstract. We study the problem of how to convert reaction networks into boolean networks. We start from the sign abstraction of the ODE semantics of reaction network, and show that it can be captured by a quasi-boolean network, a generalization of boolean networks that we introduce. We then show that any quasi-boolean networks can be converted into a boolean networks by using John’s overapproximation. Our main technical contribution is a new rewrite algorithm that make linear equation systems exact with respect to the boolean abstraction. We apply our exact rewriting for improving the precision of the conversion of quasi-boolean to boolean networks, also in the general nonlinear case. Thereby we improve our compiler from reaction networks to boolean networks as well.

Keywords: Linear equation systems · abstract interpretation · sign abstraction · systems biology · reaction networks · boolean networks.

1 Introduction

Reaction networks [8,4,12,6] are the most prominent language for modeling the dynamics of biological system. We consider the deterministic semantics of reaction networks based on ordinary differential equations (ODEs). We propose to study the sign abstraction of dynamical states of the ODEs. The signs tell us whether a reaction rate at some time point is positive, negative or zero, and whether a species concentration is zero or not. The sign abstraction of a state always has a unique successor, yielding a finite sign graph for an ODE system. This sign graph can be used to prove properties of the dynamical behaviour of reaction networks. The question that we study in the present paper is how to compute the sign graph of an ODE system inferred from a reaction network. This is nontrivial even if the sign graph is always finite, since we cannot compute the infinite object from which it abstracts.

In the first step, we show how to overapproximate the sign graph of the ODE system of a reaction network by a boolean network. The idea is to see a system of ODEs as a system of arithmetic equations with the operators $+$ and $*$ that can be interpreted over positive reals. These equations can also be interpreted more abstractly over the booleans, mapping $+$ to disjunction and $*$ to conjunction. The soundness of this abstract interpretation can be derived from John’s theorem [1,17,13]. It implies that the set of boolean solutions of an arithmetic formula with $+$ and $*$ overapproximates the boolean abstraction of the set of its positive real solutions.

It turns out that the sign reinterpretation of the ODEs of the reaction network yields a boolean network, whose transition relation overapproximates the sign graph of the ODEs of the reaction network. While the real-valued states of the ODE have unique successors, this is not the case for their sign abstractions. Further nondeterminism is introduced by the overapproximation of the possible signs by abstract interpretation. Therefore we will have to deal with boolean networks with nondeterministic updates [18] rather than with their more classical deterministic counterparts.

We then study the question of whether or when the sign graph can be computed exactly. For this, we capture the sign graph of ODEs by the transition relation of quasi-boolean networks, a

generalization of boolean networks that we introduce. Whether the quasi-boolean network can be converted to a boolean network depends on whether the boolean abstraction of the \mathbb{R}_+ -solution sets of system of arithmetic equations with operators $+$ and $*$ can be described exactly by some boolean expressions.

We present a positive answer to question in the case of systems of linear homogeneous equations with integer coefficients. Our rewriting algorithm is based on the computation of elementary modes [16,10,11,22]. It yields first-order formulas, for which John’s overapproximation of the boolean abstraction of the \mathbb{R}_+ -solution set is exact. This rewriting algorithm also permits to compile a reaction network with linear ODEs into a boolean network by capturing exactly the sign graph of the ODEs.

We finally apply exact rewriting to general reaction networks with nonlinear kinetic expressions. For this we replace all nonlinear kinetic subexpressions by fresh variables, rewrite exactly the linear equation system obtained thereby, and then replace the fresh variables back by their nonlinear expressions. The boolean networks obtained in this manner may not always capture the sign graph exactly, but may still considerably reduce the overapproximation coming with abstract interpretation over signs.

The exact rewriting for linear equation systems with respect to boolean abstraction is also key for computing the difference abstraction of steady states of reaction networks [1]. We originally invented the exact rewriting in this context, but did not yet publish it. We discover the relevance of this result only recently, triggered by discussion with Jun Pang and Loïc Paulevé following the PhD defense of Emilie Allart.

Related Work. Classical boolean networks have deterministic updates specified by boolean functions. Their application for the modeling of biological systems is not new, and their generation from reaction networks has been discussed before. In [5] for instance, boolean networks are manually produced from ODE models based on bifurcation analysis.

More recent notions of boolean networks by Paulevé and Séné [18] permit nondeterministic updates by boolean relations. Nondeterministic updates are for instance useful to capture the most permissive semantics of a classical boolean network [20]. Recently, Paulevé also developed a most permissive semantics for well-structured reaction networks, that captures the sign graph of its ODEs [19].

The Boolean semantics of reaction networks from Fages and Soliman [7] is different in that it abstracts from the multiset rewriting semantics (see e.g. [15]). Multiset rewriting is asynchronous and discrete, in contrast to the ODEs, whose semantics is synchronous and continuous. Therefore, the Boolean semantics of reaction networks is not directly related to the sign abstraction its ODE semantics.

Another compiler from reaction networks to Boolean networks but with deterministic updates was presented recently by Sutavani et al. [21]. This translation is not intended to be correct with respect to the boolean abstraction of the ODE semantics of the reaction network. Therefore, they do not start from the usual ODEs inferred from the reaction network, but from simpler ODEs inferred differently, ignoring the kinetic expressions and the stoichiometry. Similarly to our approach, they then interpret multiplication as conjunction and addition as disjunction. But in contrast to us, they interpret unary subtraction as negation rather than eliminating subtraction beforehand.

2 Preliminaries

Let $\mathbb{B} = \{0, 1\}$ be the set of booleans, \mathbb{N} the set natural numbers including 0, \mathbb{Z} the set of integers, \mathbb{R} the set of real numbers, and \mathbb{R}_+ the set of positive real numbers including 0. Note that $\mathbb{B} \subseteq \mathbb{N} \subseteq \mathbb{R}_+ \subseteq \mathbb{R}$ and $\mathbb{N} \subseteq \mathbb{Z} \subseteq \mathbb{R}$.

Σ -Algebras. We next recall the usual notions of Σ -algebras and of homomorphism between Σ -algebras. Let $\Sigma = \cup_{n \geq 0} F^{(n)} \uplus C$ be a ranked signature. The elements of $f \in F^{(n)}$ are called the n -ary function symbols of Σ and the elements in $c \in C$ its constants.

Definition 1. A Σ -algebra $S = (dom(S), .^S)$ consists of a set $dom(S)$ and an interpretation $.^S$ such that $c^S \in dom(S)$ for all $c \in C$, and $f^S : dom(S)^n \rightarrow dom(S)$ for all $f \in F^{(n)}$.

Let $\Sigma_{arith} = \{+, *, 0, 1, -, /\}$ the arithmetic signature, where 0 and 1 are constants, and all other operator binary function symbols. Let $\Sigma_{bool} = \{+, *, 0, 1\}$ be the subset of boolean operators.

Example 2. The set of positive reals \mathbb{R} can be turned into a Σ_{arith} -algebra, in which the functions symbols are interpreted as addition of positive reals $+^{\mathbb{R}}$, and multiplication of positive reals $*^{\mathbb{R}}$. The constants are interpreted by themselves $0^{\mathbb{R}} = 0$ and $1^{\mathbb{R}} = 1$.

Example 3. The set of positive reals \mathbb{R}_+ can be turned into a Σ_{bool} -algebra, in which the functions symbols are interpreted as addition of positive reals $+^{\mathbb{R}_+}$, and multiplication of positive reals $*^{\mathbb{R}_+}$. The constants are interpreted by themselves $0^{\mathbb{R}_+} = 0$ and $1^{\mathbb{R}_+} = 1$.

Example 4. The set of Booleans $\mathbb{B} = \{0, 1\} \subseteq \mathbb{R}_+$ equally defines a Σ_{bool} -algebra. There, the function symbols are interpreted as a disjunction $+^{\mathbb{B}} = \vee^{\mathbb{B}}$ and conjunction $*^{\mathbb{B}} = \wedge^{\mathbb{B}}$ on Booleans. The constants are interpreted by themselves $0^{\mathbb{B}} = 0$ and $1^{\mathbb{B}} = 1$.

Example 5. The set of function of type $\mathbb{R}_+ \rightarrow \mathbb{R}$ can be turned into a Σ_{arith} -algebra. Function addition and multiplication are defined pointwise, that is $(f +^{\mathbb{R}_+ \rightarrow \mathbb{R}} f')(r) = f(r) +^{\mathbb{R}} f'(r)$ and $(f *^{\mathbb{R}_+ \rightarrow \mathbb{R}} f')(r) = f(r) *^{\mathbb{R}} f'(r)$. The interpretation $0^{\mathbb{R}_+ \rightarrow \mathbb{R}}$ is the constant-0 $^{\mathbb{R}}$ function, and similarly $1^{\mathbb{R}_+ \rightarrow \mathbb{R}}$ is the constant-1 $^{\mathbb{R}}$ function.

Σ -Structures. In order to generalize Σ -algebras to Σ -structures, we consider n -ary function symbols as $n+1$ -ary relation symbols.

Definition 6. A Σ -structure $\Delta = (dom(\Delta), .^\Delta)$ consists of a set $dom(\Delta)$ and an interpretation $.^\Delta$ such that $c^\Delta \in dom(\Delta)$ for all $c \in C$ and $f^\Delta \subseteq dom(\Delta)^{n+1}$ for all $f \in F^{(n)}$.

Clearly, any Σ -algebra is also a Σ -structure. Note also that symbols in $F^{(0)}$ are interpreted as monadic relations, i.e., as subsets of the domain, in contrast to constants in C that are interpreted as elements of the domain.

Example 7. The set of signs $\{-1, 0, 1\} \subseteq \mathbb{R}$ can be turned into a Σ_{bool} -structure $\mathbb{S} = (\{-1, 0, 1\}, .^{\mathbb{S}})$ with the interpretation $+^{\mathbb{S}}$ and $*^{\mathbb{S}}$ given in Fig. 3. The constants are interpreted by themselves $0^{\mathbb{S}} = 0$ and $1^{\mathbb{S}} = 1$. Note that all $+^{\mathbb{S}}$ contains $(-1, 1, -1)$, $(-1, 1, 1)$ and $(-1, 1, 0)$ meaning that the sum of a strictly negative and a strictly positive real has a sign in $-1 +^{\mathbb{S}} 1$, so it may either be strictly positive, strictly negative, or zero. For this reason, \mathbb{S} is a Σ -structure but not a Σ -algebra.

Definition 8. A homomorphism between two Σ -structures S and Δ is a function $h : dom(S) \rightarrow dom(\Delta)$ such that for $c \in C$, $n \in \mathbb{N}$, $f \in F^{(n)}$, and $s_1, \dots, s_{n+1} \in dom(S)$:

1. $h(c^S) = c^\Delta$, and
2. if $(s_1, \dots, s_{n+1}) \in f^S$ then $(h(s_1), \dots, h(s_{n+1})) \in f^\Delta$.

We can convert any $n + 1$ -ary relation to a n -ary set valued functions. In this way any n -function is converted to a n -ary set valued n -functions. In other words, functions of type $D^n \rightarrow D$ are converted to functions of type $D^n \rightarrow 2^D$ where $D = \text{dom}(\Delta)$. In set-valued notation, the second condition on homomorphism can then be rewritten equivalently as $h(f^S(s_1, \dots, s_n)) \subseteq f^\Delta(h(s_1), \dots, h(s_n))$. A homomorphism for Σ -algebras thus satisfies $h(c^S) = c^\Delta$ and for all function symbols $f \in F^{(n)}$ and $s_1, \dots, s_n \in \text{dom}(S)$ it satisfies $h(f^S(s_1, \dots, s_n)) = f^\Delta(h(s_1), \dots, h(s_n))$.

Expressions, Equations, ODEs. Let \mathcal{V} be a set of variables and $\Sigma = C \cup \bigcup_{n \geq 0} F^{(n)}$ a ranked signature with constants and function symbols. The set of Σ -expressions $e \in \mathcal{E}_\Sigma(\mathcal{V})$ is then given by the following abstract syntax:

$$e_1, \dots, e_n \in \mathcal{E}_\Sigma ::= x \mid c \mid f(e_1, \dots, e_n) \text{ where } c \in C, n \geq 0, f \in F^{(n)}, x \in \mathcal{V}$$

The semantics of an expression $e \in \mathcal{E}_\Sigma$ can be defined as usual for any Σ -structure S and variable assignment $\alpha : V \rightarrow \text{dom}(S)$ with $\mathcal{V}(e) \subseteq V \subseteq \mathcal{V}$: it is the subset of the domain $\llbracket e \rrbracket^{\alpha, S} \subseteq \text{dom}(S)$. Note that the semantics of expressions is set-valued in order to deal with Σ -structures. For Σ -algebras, it will always be a singleton.

A Σ -equation with variables in \mathcal{V} is a pair $e \stackrel{\circ}{=} e'$ where $e, e' \in \mathcal{E}_\Sigma(\mathcal{V})$. A system of Σ -equations is a conjunction of equations $\bigwedge_{i=1}^n e_i \stackrel{\circ}{=} e'_i$. In the case $n = 0$ the conjunction is $\text{true} \stackrel{\text{def}}{=} 1 \stackrel{\circ}{=} 1$. An equation system ϕ equal to $\bigwedge_{i=1}^n e_i \stackrel{\circ}{=} e'_i$ is true for a Σ -structure S and a variable assignment $\alpha : V \rightarrow \text{dom}(S)$ with $\mathcal{V}(\phi) \subseteq V$ if $\llbracket e_i \rrbracket^{\alpha, S} \cap \llbracket e'_i \rrbracket^{\alpha, S} \neq \emptyset$ for all $1 \leq i \leq n$. The equality symbol $\stackrel{\circ}{=}$ is interpreted as nondisjointness, i.e., $e \stackrel{\circ}{=} e'$ is true if and only if $\llbracket e \rrbracket^{\alpha, S} \cap \llbracket e' \rrbracket^{\alpha, S} \neq \emptyset$. In the case of Σ -algebras, the equality symbol $\stackrel{\circ}{=}$ is indeed interpreted as equality of singleton. In the case of more general Σ -structures, it will not be interpreted as set equality so.

Let \mathcal{S} be a finite set of species and $\dot{\mathcal{S}} = \{S, \dot{S} \mid S \in \mathcal{S}\}$. An ODE system is a conjunction of Σ_{arith} -equations with variables in $\dot{\mathcal{S}}$. We assume for all subexpressions e/e' that, the value of e' over \mathbb{R} is always different from 0. A solution of an ODE system is a function $\gamma : \dot{\mathcal{S}} \rightarrow \mathbb{R}_+ \rightarrow \mathbb{R}$ that makes all equations true over the structure $\mathbb{R}_+ \rightarrow \mathbb{R}$ such that $\frac{d\gamma(S)}{dt}(t) = \gamma(\dot{S})(t)$ for all $S \in \mathcal{S}$ and $t \in \mathbb{R}_+$.

Lemma 9 Positive Rewriting. *Any ODE system can be rewritten into an ODE system with boolean operators in Σ_{bool} while preserving the solutions in the Σ_{bool} -algebra \mathbb{R} .*

Proof Subtractions in Σ_{arith} -formulas $e - e' \stackrel{\circ}{=} e''$ can be eliminated by rewriting to $e \stackrel{\circ}{=} e'' + e'$. Division in Σ_{arith} -formula $e/e' \stackrel{\circ}{=} e''$ can be removed by rewriting to $e \stackrel{\circ}{=} e'' * e'$. The latter works since we assumed that the denominator e' can never become equal to 0. By exhaustive rewriting, we obtain an ODE system with only boolean operators in Σ_{bool} .

Reaction Networks. A reaction network with species in \mathcal{S} is a set of chemical reactions of the following form: $r : R \xrightarrow{e} P$ where r is a name, $R, P : \mathcal{S} \rightarrow \mathbb{N}$ are multisets of species called respectively the reactants and the products, and $e \in \mathcal{E}_{\Sigma_{arith}}(\mathcal{S})$ is the kinetic expression. The kinetic expression specifies the rate of the reaction at any time point, that is specified by the ODE semantics.

The ODEs of a reaction network N are inferred as follows. If a species $S \in \mathcal{S}$ is produced or consumed by reactions r_i with stoichiometry $z_i \in \mathbb{Z}$ – the number of S produced minus number of S consumed by r_i – and kinetic expression e_i then the ODE $\dot{S} = z_1 e_1 + \dots + z_n e_n$ is added to the ODEs of N . Consider for instance the acyclic reaction network N_{acyc} in Fig. 1. It has the molecular species is $\mathcal{S} = \{A, B, C, D\}$ and two reactions with mass-action kinetics $r_1 : A \xrightarrow{A} B$ and $r_2 : A + C \xrightarrow{A * C} D$. The deterministic semantics of N_{acyc} is the system of ODEs in Fig. 2. One numerical simulation of the ODEs, corresponding to one solution γ , is shown in Fig. 4.

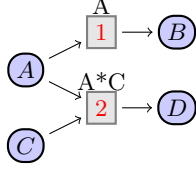


Fig. 1: The acyclic reaction network N_{acyc} .

$$\begin{aligned} \dot{A} &\stackrel{\circ}{=} -A - A * C & \wedge & \quad \dot{B} \stackrel{\circ}{=} A & \wedge \\ \dot{C} &\stackrel{\circ}{=} -A * C & \wedge & \quad \dot{D} \stackrel{\circ}{=} A * C \end{aligned}$$

Fig. 2: Deterministic semantics by ODEs.

d	d'	$d +^{\mathbb{S}} d'$	$d *^{\mathbb{S}} d'$	d	d'	$d +^{\mathbb{S}} d'$	$d *^{\mathbb{S}} d'$	d	d'	$d +^{\mathbb{S}} d'$	$d *^{\mathbb{S}} d'$
-1	1	{-1, 0, 1}	-1	0	1	1	0	1	1	1	1
-1	0	-1	0	0	0	0	0	1	0	1	0
-1	-1	-1	1	0	-1	-1	0	1	-1	{-1, 0, 1}	-1

Fig. 3: Interpretation of Σ -structure of signs \mathbb{S} .

Σ -Abstractions. The boolean abstraction is the function $h_{\mathbb{B}} : \mathbb{R}_+ \rightarrow \mathbb{B}$ with $h_{\mathbb{B}}(0) = 0$ and $h_{\mathbb{B}}(r) = 1$ if $r > 0$. The sign abstraction is the function $h_{\mathbb{S}} : \mathbb{R} \rightarrow \mathbb{S}$ with $h_{\mathbb{S}}(0) = 0$, $h_{\mathbb{S}}(r) = -1$ for all strictly negative reals $r < 0$ and $h_{\mathbb{S}}(r) = 1$ for all strictly positive reals $r > 0$. We can generalize the boolean abstraction and the sign abstraction as follows:

Definition 10. A Σ -abstraction is a homomorphism $h: S \rightarrow \Delta$ between Σ -structures such that $\text{dom}(\Delta) \subseteq \text{dom}(S)$.

Lemma 11. The boolean abstraction $h_{\mathbb{B}}$ is a Σ_{bool} -abstraction into a Σ_{bool} -algebra.

Lemma 12. The sign abstraction is $h_{\mathbb{S}}$ a Σ_{bool} -abstraction into a Σ_{bool} -structure.

First-Order Logic. We call the syntax and semantics of first-order logic. The set of first-order formulas $\mathcal{F}_{\Sigma}(\mathcal{V})$ is constructed from Σ -equations with variables in \mathcal{V} and the usual first-order connectives:

$$\phi \in \mathcal{F}_{\Sigma}(\mathcal{V}) ::= e \stackrel{\circ}{=} e' \mid \exists x. \phi \mid \phi \wedge \phi \mid \neg \phi \quad \text{where } e, e' \in \mathcal{E}_{\Sigma}(\mathcal{V}) \text{ and } x \in \mathcal{V}$$

The set of free variables $\mathcal{V}(\phi)$ are all those variables of ϕ that occur outside the scope of any quantifier. The semantics of first-order logic can be defined as usual for any Σ -structure S and variable assignment $\alpha : V \rightarrow \text{dom}(S)$. It yields a truth value $\llbracket \phi \rrbracket^{\alpha, S} \in \mathbb{B}$ for any formula $\phi \in \mathcal{F}_{\Sigma}(\mathcal{V})$ with $\mathcal{V}(\phi) \subseteq V$. See Fig. 11 of the appendix for the details. The set of solutions of a formula $\phi \in \mathcal{F}_{\Sigma}(\mathcal{V})$ over a Σ -algebra S with respect to a subset of variables $V \supseteq \mathcal{V}(\phi)$ is: $\text{sol}_V^S(\phi) = \{\alpha : V \rightarrow \text{dom}(S) \mid \llbracket \phi \rrbracket^{\alpha, S} = 1\}$. If $V = \mathcal{V}(\phi)$ we omit the index V , i.e., $\text{sol}^S(\phi) = \text{sol}_V^S(\phi)$. We can define the boolean abstraction by a first-order formula with signature Σ_{bool} :

$$y \stackrel{\circ}{=} h_{\mathbb{B}}(x) =_{\text{def}} (y = 0 \wedge x \stackrel{\circ}{=} 0) \vee (y \stackrel{\circ}{=} 1 \wedge \neg x \stackrel{\circ}{=} 0)$$

We need also to define applications of the boolean abstraction to the solution set of a first-order formula ϕ with signature Σ_{bool} . For this, let \mathbf{y} be vector of distinct variables such that $\{\mathbf{y}\} = \mathcal{V}(\phi)$. Let \mathbf{x} be a vector of fresh variables with the same arity than \mathbf{y} . We then define the application of $h_{\mathbb{B}}$ to the solution set of ϕ by the first-order formula $h_{\mathbb{B}}(\phi)$ as follows:

$$h_{\mathbb{B}}(\phi) =_{\text{def}} \exists \mathbf{x}. \phi[\mathbf{y}/\mathbf{x}] \wedge \bigwedge_i \mathbf{y}_i \stackrel{\circ}{=} h_{\mathbb{B}}(\mathbf{x}_i)$$

Abstract Interpretation. We recall John’s theorem [13] on how to overapproximate abstractions of solution sets of first-order formulas by abstract interpretation. Let $h : S \rightarrow \Delta$ be a Σ -abstraction and $V \subseteq \mathcal{V}$. For any subset of assignments R of type $V \rightarrow \text{dom}(S)$ we define $h \circ R = \{h \circ \alpha : V \rightarrow \text{dom}(\Delta) \mid \alpha \in R\}$.

Theorem 13 John’s Overapproximation [1,17,13]. *For any Σ -abstraction $h : S \rightarrow \Delta$ between Σ -structures and any negation-free formula $\phi \in \mathcal{F}_\Sigma(\mathcal{V})$: $h \circ \text{sol}^S(\phi) \subseteq \text{sol}^\Delta(\phi)$.*

We only give a sketch of the proof. Let $\alpha : V \rightarrow \text{dom}(S)$. For any expression $e \in \mathcal{E}_\Sigma(\mathcal{V})$ such that $\mathcal{V}(e) \subseteq V$ we can show that $h(\llbracket e \rrbracket^{\alpha,S}) = \llbracket e \rrbracket^{h \circ \alpha, \Delta}$ by induction on the structure of e . It then follows for any positive formula $\phi \in \mathcal{F}_\Sigma(\mathcal{V})$ with $\mathcal{V}(\phi) \subseteq V$ that $\llbracket \phi \rrbracket^{\alpha,S} \leq \llbracket \phi \rrbracket^{h \circ \alpha, \Delta}$. This is equivalent to that: $\{h \circ \alpha \mid \alpha \in \text{sol}_V^S(\phi)\} \subseteq \text{sol}_V^\Delta(\phi)$ and thus $h \circ \text{sol}_V^S(\phi) \subseteq \text{sol}_V^\Delta(\phi)$.

3 Sign Graphs of ODEs

Let \mathcal{S} be a set of species and $\dot{\mathcal{S}} = \{S, \dot{S} \mid S \in \mathcal{S}\}$. Note that the system of ODEs E of any reaction network with species in \mathcal{S} is a conjunction of Σ_{arith} -equations with variables in $\dot{\mathcal{S}}$, and thus a formula of $\mathcal{F}_{\Sigma_{arith}}(\dot{\mathcal{S}})$.

A state of a system of ODE equations is a function $\alpha : \dot{\mathcal{S}} \rightarrow \mathbb{R}$ that solves all its equations over the algebra \mathbb{R} . Note that $\alpha(\dot{S})$ may be negative, while $\alpha(S) \geq 0$ for all $S \in \mathcal{S}$ by assumption. Let E' be the formula $E \wedge \bigwedge_{S \in \mathcal{S}} S \geq 0$, where the formula $S \geq 0$ is defined by $\exists y. S = y * y$.

A real assignment $\alpha : \dot{\mathcal{S}} \rightarrow \mathbb{R}$ can be abstracted to a sign assignment $h_{\mathbb{S}} \circ \alpha : \dot{\mathcal{S}} \rightarrow \mathbb{S}$. Given an ODE system E we define a possibly nondeterministic successor relation on sign assignments $\beta, \beta' \in h_{\mathbb{S}} \circ \text{sol}^{\mathbb{R}}(E')$: we call β' a successor of β if

$$\forall S \in \mathcal{S}. \beta'(S) = \beta(S) +^{\mathbb{S}} \max(0, \beta(\dot{S}))$$

The sign graph of E has as node the elements of $h_{\mathbb{S}} \circ \text{sol}^{\mathbb{R}}(E')$, and as edges the elements of the successor relation. Due to the nondeterminism, some sign assignments may have multiple outgoing edges in the sign graph, as for instance in the sign graph in Fig. 8.

Example 14. *Reconsider the ODEs in Fig. 2 inferred from the reaction network N_{acyc} in Fig. 1. Let γ be the ODE solution in Fig. 4. We consider the following \mathbb{R} -solutions of the ODE equations:*

$$\begin{aligned} \alpha_1 = \gamma(0) &= [A/2, B/0, C/1, D/0, \dot{A}/-4, \dot{B}/2, \dot{C}/-2, \dot{D}/2] \\ \alpha_2 = \gamma(0.1) &= [A/0.7, B/0.1, C/0.3, D/0.9, \dot{A}/-0.2, \dot{B}/0.1, \dot{C}/-0.1, \dot{D}/0.1] \end{aligned}$$

The sign abstractions of these solutions are:

$$\begin{aligned} \beta_1 = h_{\mathbb{S}} \circ \alpha_1 &= [A/1, B/0, C/1, D/0, \dot{A}/-1, \dot{B}/1, \dot{C}/-1, \dot{D}/1] \\ \beta_2 = h_{\mathbb{S}} \circ \alpha_2 &= [A/1, B/1, C/1, D/1, \dot{A}/-1, \dot{B}/1, \dot{C}/-1, \dot{D}/1] \end{aligned}$$

We can now see that β_2 is a successor of β_1 . For species B , for instance, we have $\beta_2(B) = 1 = 0 + 1 = \beta_1(B) + \max(0, \beta_1(\dot{B}))$. The whole sign graph for the ODEs of N_{acyc} is given in Fig. 5.

4 Approximating Sign Graphs by Boolean Networks

We first give a syntax for the boolean networks with nondeterministic updates from [18] based on boolean formulas. We then present a compiler mapping the ODEs of a reaction network to a Boolean network based on boolean interpretation of the ODEs.

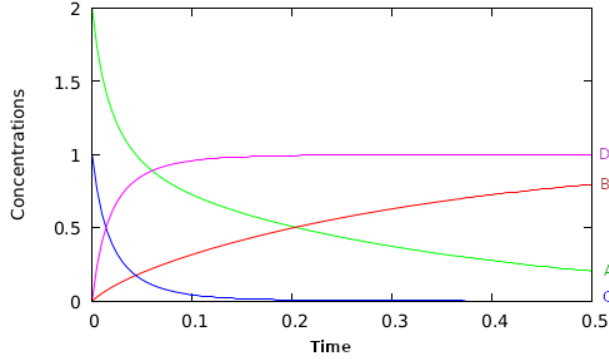


Fig. 4: Solution of ODEs of N_{acyc} with initial state $A(0) = 2$, $C(0) = 1$ and $B(0) = D(0) = 0$.

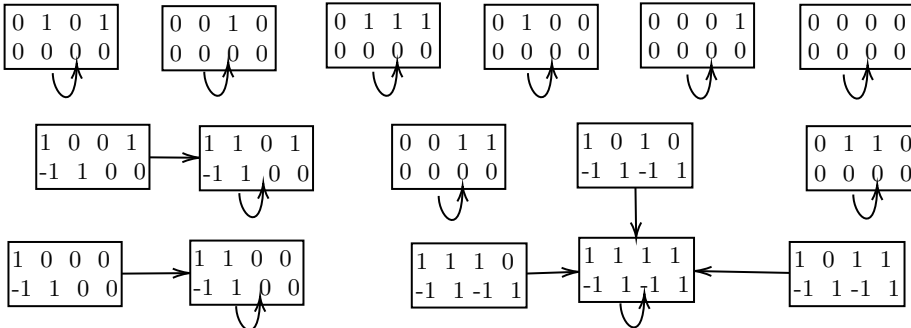


Fig. 5: Sign graph of ODEs for reaction network N_{acyc} .

The compiler will be done in such a way that the transition relation of the boolean network will overapproximate the sign graph of the ODEs. The overapproximation may introduce further nondeterminism to that of the sign graph, as we will see in the example in Fig. 10 of Section 5. In order to capture the nondeterminism, we need to admit nondeterministic updates for boolean networks too.

Let \mathcal{S} be a finite set of species. The set $\mathcal{S} \times \{1, 2\}$ provides two copies of \mathcal{S} . For any $S \in \mathcal{S}$, the first copy $S_1 = (S, 1)$ will denote the old boolean value of S before a transition, and $S_2 = (S, 2)$ the new boolean value of S after the transition. A boolean network with nondeterministic updates and species in \mathcal{S} is a formula $\phi \in \mathcal{F}_{\{+,*,0,1\}}(\mathcal{S} \times \{1, 2\})$. For illustration, the boolean network ϕ_{acyc}^{bool} is given in Fig. 6. With $\mathcal{S} = \{A, B, C, D\}$, the network has the set of species:

$$\dot{\mathcal{S}}^{+/-} = \{S, \dot{S}^+, \dot{S}^- \mid S \in \mathcal{S}\}$$

For each boolean network ϕ we define a transition relation $\rightarrow_{\phi}^{\mathbb{B}}$ on boolean assignments of species. Given two boolean assignments $\beta_1, \beta_2 : \mathcal{S} \rightarrow \mathbb{B}$, let $\beta : \mathcal{S} \times \{1, 2\}$ be such that $\beta(S_i) = \beta_i(S)$ for all $S \in \mathcal{S}$ and $i \in \{1, 2\}$. We can then define the transition relation $\rightarrow_{\phi}^{\mathbb{B}}$ such that:

$$\beta_1 \rightarrow_{\phi}^{\mathbb{B}} \beta_2 \text{ if and only if } \llbracket \phi \rrbracket^{\beta, \mathbb{B}} = 1$$

In this case, we say that β_2 is a successor of β_1 with respect to the boolean network ϕ . For the boolean network ϕ_{acyc}^{bool} in Fig. 6, the transition relation $\rightarrow_{\phi_{acyc}^{bool}}^{\mathbb{B}}$ corresponds exactly to the sign graph N_{acyc} when identifying the sign of \dot{S} by the equation $\dot{S} = \dot{S}^+ - \dot{S}^-$.

$$\begin{aligned}
& \bigwedge_{S \in \{A, B, C, D\}} S_2 \stackrel{\circ}{=} S_1 + \dot{S}_1^+ \wedge \dot{S}_2^- * \dot{S}_2^+ \stackrel{\circ}{=} 0 \\
& \wedge \dot{A}_2^+ + A_2 + A_2 * C_2 \stackrel{\circ}{=} \dot{A}_2^- \quad \wedge \dot{B}_2^+ \stackrel{\circ}{=} \dot{B}_2^- + A_2 \\
& \wedge \dot{C}_2^+ + A_2 * C_2 \stackrel{\circ}{=} \dot{C}_2^- \quad \wedge \dot{D}_2^+ \stackrel{\circ}{=} \dot{D}_2^- + A_2 * C_2
\end{aligned}$$

Fig. 6: Boolean network ϕ_{acycl}^{bool} obtained by boolean interpretation of ODEs of N_{acyc} .

We next present a compiler from reaction networks to boolean networks with nondeterministic updates. The objective is to overapproximate the sign graph of the ODEs of the reaction network by the transition relation of the boolean network. For instance, the reaction network N_{acyc} will be mapped to the boolean network $bn(N_{acyc}) = \phi_{acyc}^{bool}$.

Given a reaction network N , the compiler starts with the ODEs of N . As argued earlier, these can be rewritten positively to ODEs with operators in Σ_{bool} only. While the variables $S \in \mathcal{S}$ must have positive values at every time point, the variables \dot{S} may still have negative values. In order to get rid of all negative values, the idea is that every real number $r \in \mathbb{R}$ is equal to a difference of two positive real numbers $r^+ - r^-$, where $r^+ = \max(r, 0)$ and $r^- = -\min(r, 0)$. Hence, $r^+, r^- \in \mathbb{R}_+$ and the decomposition $r = r^+ - r^-$ is unique such that $r^+ \geq 0 \wedge r^- \geq 0 \wedge r^+ * r^- = 0$. Therefore, we replace each variable \dot{S} by a difference of two fresh variables $\dot{S}^+ - \dot{S}^-$ that are constrained by $\dot{S}^+ \geq 0 \wedge \dot{S}^- \geq 0 \wedge \dot{S}^+ * \dot{S}^- = 0$. We then apply Lemma 9 to rewrite the ODEs positively to a boolean formula with signature Σ_{bool} with variables in $\dot{\mathcal{S}}^{+/-}$, while eliminating the subtraction operator. For the example N_{acyc} we obtain the boolean formula $ode_{bf}(N_{acyc})$:

$$\dot{A}^+ + A + A * C = \dot{A}^- \wedge \dot{B}^+ = \dot{B}^- + A \wedge \dot{C}^+ + A * C = \dot{C}^- \wedge \dot{D}^+ = \dot{D}^- + A * C$$

The boolean formula $ode_{bf}(N)$ can be used to compile the reaction network N to a boolean network $bn(N)$. Suppose that the reaction network N has the species in \mathcal{S} . Then $ode_{bf}(N) \in \mathcal{F}_{\Sigma_{bool}}(\dot{\mathcal{S}}^{+/-})$. We define the boolean network $bn(N)$ with species in $\dot{\mathcal{S}}^{+/-}$ as follows:

$$bn(N) = ode_{bf}(N)[S/S_2 \mid S \in \mathcal{S}] \wedge \bigwedge_{S \in \mathcal{S}} S_2 \stackrel{\circ}{=} S_1 + \dot{S}_1^+ \wedge \dot{S}_2^- * \dot{S}_2^+ \stackrel{\circ}{=} 0$$

For any species $S \in \mathcal{S}$ the new value described by S_2 is determined by $S_2 \stackrel{\circ}{=} S_1 + \dot{S}_1^+$ when given the old values. Furthermore, the new values must satisfy the ODEs of N , that is the expression $ode_{be}(N)$ in which all S are replaced by S_2 . For illustration, the boolean network $bn(N_{acyc})$ is given in Fig. 6. Nicely, it captures precisely the sign graph of N_{acyc} .

5 Overapproximation Example

For general reaction networks N the boolean network $bn(N)$ may only overapproximate the sign graph of N . The overapproximation may be large as we illustrate next by example. For this we consider the cyclic reaction network N_{cyc} in Fig. 7. The sign graph of N_{cyc} is given in Fig. 8. The boolean network $bn(N_{cyc})$ inferred by boolean interpretation of $ode_{be}(N_{cyc})$ is given in Fig. 9. The approximation of the sign graph made by the boolean network $bn(N_{cyc})$ is shown in Fig. 10. Note that contains more sign assignments than the sign graph of N_{cyc} . The question is under how to capture the sign graphs of reaction networks more precisely or even exactly by boolean networks.

6 Capturing Sign Graphs by Quasi-Boolean Networks

We propose to generalize boolean networks to quasi-boolean networks. We then show how to compile reaction networks to quasi-boolean networks while capturing the sign graph exactly.

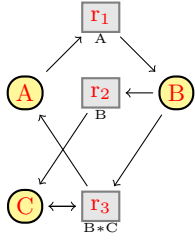


Fig. 7: The reaction network N_{cyc} .

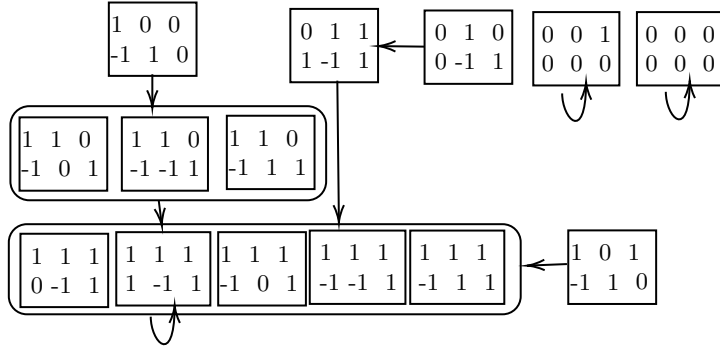


Fig. 8: The sign graph of N_{cyc} (ABC over $\dot{A}\dot{B}\dot{C}$).

$$\begin{aligned} \dot{A}_2^+ + A_2 &\stackrel{\circ}{=} \dot{A}_2^- + B_2 * C_2 \wedge \dot{B}_2^+ + B_2 + B_2 * C_2 \stackrel{\circ}{=} \dot{B}_2^- + A_2 \wedge \dot{C}_2^+ \stackrel{\circ}{=} \dot{C}_2^- + B_2 \\ \wedge \bigwedge_{S \in \{A, B, C\}} S_2 &\stackrel{\circ}{=} S_1 + \dot{S}_1^+ \wedge \dot{S}_2^- * \dot{S}_2^+ \stackrel{\circ}{=} 0 \end{aligned}$$

Fig. 9: The boolean network $bn(N_{cyc})$.

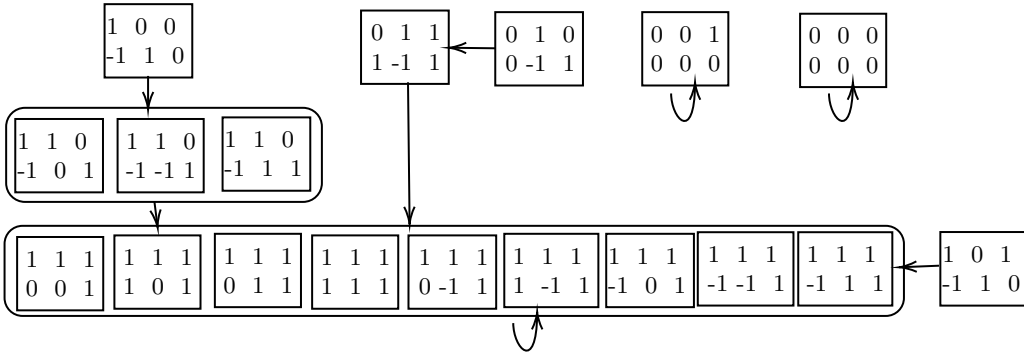


Fig. 10: Overapproximation of the sign graph by $bn(N_{cyc})$.

A quasi-boolean network with species in \mathcal{S} has the same syntax than a boolean network. But for the semantics, the formulas $\phi \in \mathcal{F}_{\Sigma_{bool}}(\mathcal{S} \times \{1, 2\})$ are interpreted over \mathbb{R}_+ rather than \mathbb{B} . The transition relation $\rightarrow_{\phi}^{\mathbb{R}_+}$ is defined such that:

$$\beta_1 \rightarrow_{\phi}^{\mathbb{R}_+} \beta_2 \text{ if and only if } \llbracket \phi \rrbracket^{\beta, \mathbb{R}_+} = 1$$

In this case we say that β_2 is a successor of β_1 with respect to the quasi-boolean network ϕ on \mathbb{R}_+ .

Given a reaction network N with species in \mathcal{S} , let $ode_{bf}(N)$ be the boolean formula that we obtained from its ODEs. This formula is a system of Σ_{bool} -equation with variables in $\dot{\mathcal{S}}^{+/-}$. We define the quasi-boolean network $qbn(N)$ with species in $\dot{\mathcal{S}}^{+/-}$ as follows:

$$qbn(N) = h_{\mathbb{B}}(qb(N))$$

Recall from Section 2 that $h_{\mathbb{B}}(\text{ode}_{bf}(N))$ is the first-order formula that defines the $h_{\mathbb{B}}$ -abstraction of the solutions of $\text{ode}_{bf}(N)$. In $h_{\mathbb{B}}(\text{ode}_{bf}(N))$, each variable S is to be replaced by S_2 , since the ODE equations are to be applied to the values after the transition step.

Proposition 15 Correctness of $qbn(N)$. *For any reaction network N , the sign graph of N is equal to the sign graph encoded by the transition relation of the quasi-boolean network $qbn(N)$.*

Proof This follows directly from the constructions.

Proposition 16 $bn(N)$ overapproximates $qbn(N)$. *The transition relation of the quasi-boolean network $qbn(N)$ is contained in the transition relation of the boolean network $bn(N)$.*

Proof By John's overapproximation (Theorem 13), we have $h_{\mathbb{B}} \circ \text{sol}^{\mathbb{R}^+}(\phi) \subseteq \text{sol}^{\mathbb{B}}(\phi)$ and thus $\text{sol}^{\mathbb{R}^+}(h_{\mathbb{B}}(\phi)) \subseteq \text{sol}^{\mathbb{B}}(\phi)$.

Theorem 17 $bn(N)$ overapproximates the sign graph of N . *The sign graph encoded by the transition relation of the boolean network $bn(N)$ subsumes the sign graph of N .*

Proof This is immediate from the correctness of the transition graph of $qbn(N)$ with respect to the sign graph of N in Proposition 15 and the overapproximation for the transition relation of $bn(N)$ relatively to $qbn(N)$ by Proposition 16.

Our next objective is to rewrite quasi-boolean networks to boolean networks while preserving the transition relation. For this, we propose to rewrite formulas $\phi \in \mathcal{F}_{\Sigma_{bool}}(\mathcal{V})$ to \mathbb{R}_+ -equivalent formulas $\phi' \in \mathcal{F}_{\Sigma_{bool}}(\mathcal{V})$ such that $\text{sol}^{\mathbb{B}}(\phi') = h_{\mathbb{B}} \circ \text{sol}^{\mathbb{R}^+}(\phi') = h_{\mathbb{B}} \circ \text{sol}^{\mathbb{R}^+}(\phi)$. The formula ϕ' can then be rewritten into a boolean expression $e \in \mathcal{E}_{\Sigma_{bool}}(\mathcal{V})$ that holds for the same boolean assignments, as we showed earlier. We provide a solution to the above problem only for the special case, where the formulas ϕ represent a linear homogenous equation system with integer coefficients. But the linear case can be used to obtain better Boolean networks for reaction networks with nonlinear ODEs, simply by replacing nonlinear subexpressions by variables, and putting nonlinear equations for these variables aside. This is the way we computed the sign graph for N_{acyc} in Fig. 8, even though its ODEs are nonlinear.

7 Linear Equation Systems and Elementary Modes

We are interested in systems of Σ_{bool} -equations. The base case is homogeneous linear equations systems with natural coefficients, which capture linear matrix integer equations $A\mathbf{x} = 0$ interpreted over \mathbb{R}_+ . We will show that elementary modes [16,10,11,22] can be used to transform linear integer matrix equations into equivalent systems which are *quasi-positive* and *strongly-triangular*, two key properties that we will show guarantee the exactness of their interpretation over the booleans. In order to extend our result to linear equation systems interpreted over \mathbb{R} , we also need systems of polynomial equations, with natural coefficients and no constant term, that are nonlinear.

In the following, let $e^n = \prod_{i=1}^n e$ and $ne =_{\text{def}} \sum_{i=1}^n e$.

Definition 18. *A Σ_{bool} -equation is called positive if it has the form $e \stackrel{\circ}{=} 0$ and quasi-positive if it has the form $e \stackrel{\circ}{=} ny$, where $n \in \mathbb{N}$, $y \in \mathcal{V}$, and $e \in \mathcal{E}_{\Sigma_{bool}}(\mathcal{V})$.*

This definition makes sense, since all constants in Σ_{bool} -expressions are positive and all operators of Σ_{bool} -expressions preserve positivity. Note also that any positive equation is quasi-positive since the constant 0 is equal to the polynomial $0y$. A *system of Σ_{bool} -equations* is a conjunctive

formula of the form $\bigwedge_{i=1}^n e_i \overset{\circ}{=} e'_i$ in \mathcal{F}_Σ . We call a system of Σ_{bool} -equations *positive* respectively *quasi-positive* if all its equations are.

A *polynomial (with natural coefficients)* is an expression of the form $\sum_{j=1}^l n_j \prod_{k=1}^{i_j} x_{j,k}^{m_{j,k}}$ where l and i_j are naturals, $x_{1,1}, \dots, x_{l,i_l}$ variables, all $n_j \neq 0$ naturals called the *coefficients*, and all $m_{j,k} \neq 0$ naturals called the *exponents*. The products $\prod_{k=1}^{i_j} x_{j,k}^{m_{j,k}}$ are called the *monomials* of the polynomial.

Definition 19. A polynomial $\sum_{j=1}^l n_j \prod_{k=1}^{i_j} x_{j,k}^{m_{j,k}}$ with natural coefficients $n_j \neq 0$ has no constant term if none of its monomials is equal to 1, i.e., $i_j \neq 0$ for all $1 \leq j \leq l$. It is linear if all its monomials are variables, i.e. $i_j = 1$ and $m^{j,1} = \dots = m^{j,i_j} = 1$ for all $1 \leq j \leq l$.

Note that any linear polynomial has the form $\sum_{j=1}^l n_j x_{j,1}$ where l and all $n_j \neq 0$ are naturals and all $x_{j,1}$ are variables. In particular, linear polynomials do not have a constant term. Furthermore, note that the constant 0 is equal to the linear polynomial with $l = 0$. A *polynomial equation* is a Σ_{bool} -equation $p \overset{\circ}{=} p'$ between polynomials. A (*homogeneous*) *linear equation* is a polynomial equation with linear polynomials, so without constant terms. A *linear equation system* is a system of linear equations.

A (*homogeneous*) *linear integer matrix equation* has the form $A\mathbf{y} \overset{\circ}{=} 0$ where A is a $n \times m$ matrix of integers for some naturals m, n such that $\mathbf{y} \in \mathcal{V}^m$. Any linear integer matrix equation can be turned into a linear equation system with natural coefficients, by bringing the negative coefficients on the right-hand side. For instance, the linear integer matrix equation on the right corresponds to the linear equation system with natural coefficients $3x \overset{\circ}{=} 0 \wedge 2x \overset{\circ}{=} 5y$.

$$\begin{pmatrix} 3 & 0 \\ 2 & -5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \overset{\circ}{=} 0$$

This system is quasi-positive, but not positive since $5y$ appears on a right-hand side. More generally, the linear equation system for an linear integer matrix equation $A\mathbf{y} \overset{\circ}{=} 0$ is positive if and only if all integers in A are positive, and quasi-positive, if each line of A contains at most one negative integer. Furthermore, the above linear equation system is triangular in the following sense, but not strongly triangular:

Definition 20. We call a quasi-positive system of Σ_{bool} -equations triangular if it has the form $\bigwedge_{l=1}^n e_l \overset{\circ}{=} n_l y_l$ such that the variables y_l are l -fresh for all $1 \leq l \leq n$, i.e., $y_l \notin \mathcal{V}(\bigwedge_{i=1}^{l-1} e_i \overset{\circ}{=} e'_i)$ and if $n_l \neq 0$ then $y_l \notin \mathcal{V}(e_l)$. We call the quasi-positive polynomial system strongly-triangular if it is triangular and satisfies $n_l \neq 0$ for all $1 \leq l \leq n$.

Consider a linear integer matrix equation $A\mathbf{y} \overset{\circ}{=} 0$. If A is positive and triangular, then the corresponding linear equation system is positive and triangular too. For being quasi-positive and strongly-triangular, the integers below the diagonal of A must be negative, those on the diagonal must be strictly negative, and those on the right of the diagonal must be positive.

Theorem 21 Elementary Modes. For any system of linear equations ϕ with natural coefficients, one can compute in at most exponential time a \mathbb{R}_+ -equivalent formula $\exists \mathbf{x}.\phi'$ such that ϕ' is a quasi-positive strongly-triangular system of linear equations with natural coefficients and \mathbf{x} the sequence of variables on the left hand sides of the equations.

The theorem applies in particular to the linear equation systems of integer matrix equations $A\mathbf{y} \overset{\circ}{=} 0$. It shows that there exists a matrix E of naturals, a vector of naturals \mathbf{n} , and a vector of fresh variables \mathbf{x} , such that $A\mathbf{y} \overset{\circ}{=} 0$ is \mathbb{R}_+ -equivalent to $\exists \mathbf{x}.\mathbf{E}\mathbf{x} \overset{\circ}{=} \mathbf{n}\mathbf{y}$.

8 Abstraction Exactness

John's overapproximation Theorem 13 shows that the set of solutions over the abstract domain $sol^\Delta(\phi)$ is an approximation by the abstraction of the concrete solution set $h(sol^S(\phi))$ for any abstraction $h : S \rightarrow \Delta$ from concrete to abstract structure and any positive first-order formula ϕ . We say that ϕ is h -exact if even equality holds.

Definition 22 Exactness. *Let $h : S \rightarrow \Delta$ be a Σ -abstraction, ϕ a Σ -formula and $V \supseteq \mathcal{V}(\phi)$. We call ϕ h -exact with respect to V if $h(sol_V^S(\phi)) = sol_V^\Delta(\phi)$. We call ϕ h -exact if ϕ is h -exact with respect to $\mathcal{V}(\phi)$.*

Our next objective is to study the preservation of h -exactness by logical operators. The main difficulty of this paper is the fact that h -exactness is not preserved by conjunction. Nevertheless, as we will show next, it is preserved by disjunction and existential quantification. For the case of disjunction, we need a basic property of union which fails for intersection.

Lemma 23. *Let V be a set of variables, R_1 and R_2 be subsets of assignments of type $V \rightarrow dom(S)$ and $h : S \rightarrow \Delta$ be a Σ -abstraction. $h \circ (R_1 \cup R_2) = h \circ R_1 \cup h \circ R_2$.*

Proposition 24. *The disjunction of h -exact formulas is h -exact.*

Lemma 25 Projection commutes with abstraction. *For any Σ -abstraction $h : S \rightarrow \Delta$, subset R of assignments of type $V \rightarrow S$, and variable $x \in \mathcal{V} : h \circ \pi_x(R) = \pi_x(h \circ R)$.*

Proposition 26 Quantification preserves exactness. *For any surjective Σ -abstraction $h : S \rightarrow \Delta$ and formula $\exists x.\phi \in \mathcal{F}_\Sigma$, if ϕ is h -exact then $\exists x.\phi$ is h -exact.*

We next study the h -exactness for strongly-triangular systems of Σ_{bool} -equations, under the condition that h is an abstraction between Σ -algebras with unique division.

Lemma 27 Singleton property. *If S is a Σ -algebra, $e \in \mathcal{E}_\Sigma$, and $\alpha : \mathcal{V}(e) \rightarrow S$ a variable assignment, then the set $\llbracket e \rrbracket^{\alpha, S}$ is a singleton.*

A Σ -algebra is a Σ -structure with the singleton property. Let ele be the function that maps any singleton to the element that it contains.

Definition 28. *We say that a Σ -structure S has unique division, if it satisfies the first-order formula $\forall x.\exists^{=1}y. ny \overset{\circ}{=} x$ for all nonzero natural number $n \in \mathbb{N}$.*

Clearly, the Σ -algebras \mathbb{R}_+ and \mathbb{B} have unique division. For any element s of the domain of a structure S with unique division and any nonzero natural number $n \in \mathbb{N}$, we denote by $\frac{s}{n}$ the unique element of $\{\alpha(y) \mid \alpha \in sol^S(ny \overset{\circ}{=} z), \alpha(z) = s\}$.

Lemma 29. *Let $\phi \in \mathcal{F}_\Sigma$ be a Σ -formula and S a Σ -algebra with unique division. For nonzero natural number n , variable $y \notin \mathcal{V}(\phi)$, and expression $e \in \mathcal{E}_\Sigma$ with $\mathcal{V}(e) \subseteq \mathcal{V}(\phi)$:*

$$sol^S(\phi \wedge ny \overset{\circ}{=} e) = \{\alpha[y / \frac{ele(\llbracket e \rrbracket^{\alpha, S})}{n}] \mid \alpha \in sol^S(\phi)\}$$

Proposition 30. *Let $\phi \in \mathcal{F}_\Sigma$ a Σ -formula, $n \neq 0$ a natural number, $e \in \mathcal{E}_\Sigma$ a Σ -expression with $\mathcal{V}(e) \subseteq \mathcal{V}(\phi)$ and $y \notin \mathcal{V}(\phi)$ and the Σ -abstraction $h : S \rightarrow \Delta$ with S and Δ two Σ -algebras with unique division. Then if ϕ is h -exact implies that $\phi \wedge e \overset{\circ}{=} ny$ is h -exact.*

Proposition 31. *Let $h : S \rightarrow \Delta$ be a Σ -abstraction between Σ -algebras with unique division. Then any strongly-triangular system of Σ -equations with natural coefficients is h -exact.*

We notice that Proposition 31 remains true for triangular systems that are not strongly-triangular. This will follow with further results from the next section (Theorem 43 and Proposition 37) requiring a different argument.

Theorem 32 Exactness. *Quasi-positive strongly-triangular polynomial system are $h_{\mathbb{B}}$ -exact.*

Proof The Σ -algebras \mathbb{R}_+ and \mathbb{B} have unique division, so we can apply Proposition 31.

The Elementary Modes Theorem 21 show that any integer matrix equation $A\mathbf{x} \stackrel{\circ}{=} 0$ is \mathbb{R}_+ -equivalent to some quasi-positive strongly-triangular linear equation system. We can thus apply Theorem 32 to obtain the following corollary.

Corollary 33. *Any matrix integer equation can be converted in at most exponential time to some \mathbb{R}_+ -equivalent $h_{\mathbb{B}}$ -exact Σ -formula.*

This corollary permits us to compute the $h_{\mathbb{B}}$ -abstraction of an integer matrix equation by computing the \mathbb{B} -solutions of the \mathbb{R}_+ -equivalent $h_{\mathbb{B}}$ -exact formula. For computing abstractions between structures without unique division we need to strengthen this result.

9 Abstraction Invariance

A problem that we need to overcome is that conjunctions of two h -exact formulas may not be h -exact. The situation changes when assuming the following notion of h -invariance for at least one of the two formulas.

Definition 34 Invariance. *Let $h : S \rightarrow \Delta$ be a Σ -abstraction and $V \subseteq \mathcal{V}$ a subset of variables. We call a subset R of variable assignments of type $V \rightarrow \text{dom}(S)$ h -invariant iff:*

$$\forall \alpha, \alpha' : V \rightarrow \text{dom}(S). (\alpha \in R \wedge h \circ \alpha = h \circ \alpha' \implies \alpha' \in R).$$

We call a Σ -formula ϕ h -invariant if its solution set $\text{sol}^S(\phi)$ is.

The relevance of the notion of invariance for exactness of conjunctions – that we will formalize in Proposition 37 – is due to the the following lemma:

Lemma 35. *If either R_1 or R_2 are h -invariant then: $h \circ (R_1 \cap R_2) = h \circ R_1 \cap h \circ R_2$.*

We continue with an algebraic characterization of h -invariance. Given a Σ -abstraction $h : S \rightarrow \Delta$, and a set R of variable assignments to $\text{dom}(\Delta)$, we define the left-decomposition of R with respect to h as the following set of variable assignments to $\text{dom}(S)$:

$$h \circ R =_{\text{def}} \{\alpha \mid h \circ \alpha \in R\}$$

Clearly, $R \subseteq h \circ (h \circ R)$. The inverse inclusion characterizes the h -invariance of R .

Lemma 36 Algebraic characterization. *A subset of R variables assignment of type $V \rightarrow \text{dom}(S)$ is h -invariant for a Σ -abstraction $h : S \rightarrow \Delta$ iff $h \circ (h \circ R) \subseteq R$.*

Proposition 37 Exactness is preserved by conjunction when assuming invariance.

Let h be a surjective Σ -abstraction. If ϕ_1 and ϕ_2 are h -exact Σ -formulas and ϕ_1 or ϕ_2 are h -invariant then the conjunction $\phi_1 \wedge \phi_2$ is h -exact.

Proof Let ϕ_1 and ϕ_2 be h -exact Σ -formulas. We assume without loss of generality that ϕ_1 is h -invariant. Let $V = \mathcal{V}(\phi_1 \wedge \phi_2)$. Since $\mathcal{V}(\phi_2) \subseteq V$ the set $\text{sol}_V^S(\phi_2)$ is h -invariant too by Lemma 56. We can now show that $\phi_1 \wedge \phi_2$ is h -exact as follows:

$$\begin{aligned} h \circ \text{sol}^S(\phi_1 \wedge \phi_2) &= h \circ (\text{sol}_V^S(\phi_1) \cap \text{sol}_V^S(\phi_2)) \\ &= h \circ \text{sol}_V^S(\phi_1) \cap h \circ \text{sol}_V^S(\phi_2) \text{ by Lemma 35} \\ &= \text{sol}_V^\Delta(\phi_1) \cap \text{sol}_V^\Delta(\phi_2) \text{ by } h\text{-exactness of } \phi_1 \text{ and } \phi_2 \text{ wrt } V \\ &= \text{sol}^\Delta(\phi_1 \wedge \phi_2) \end{aligned}$$

Our next objective is to show that h -invariant formulas are closed under conjunction, disjunction, and existential quantification. The two former closure properties rely on the following two algebraic properties of abstraction decomposition.

Lemma 38. *For any Σ -abstraction $h : S \rightarrow \Delta$, any subsets of assignments of type $V \rightarrow \text{dom}(S)$ R_1 and R_2 and V a subset of variables:*

- $h \circ (R_1 \cap R_2) = h \circ R_1 \cap h \circ R_2.$
- $h \circ (R_1 \cup R_2) = h \circ R_1 \cup h \circ R_2.$

Lemma 39 Intersection and union preserve invariance. *Let $h : S \rightarrow \Delta$ be a Σ -abstraction. Then the intersection and union of any two h -invariant subsets R_1 and R_2 of variables assignments of type $V \rightarrow \text{dom}(S)$ is h -invariant.*

Lemma 40 Projection commutes with left-decomposition. $h \circ \pi_x(R) = \pi_x(h \circ R).$

Proposition 41 Invariance is preserved by conjunction, disjunction, and quantification. *If h is a surjective abstraction then the class of h -invariant FO-formulas is closed under conjunction, disjunction, and existential quantification.*

We do not know whether negation preserves h -invariance in general, but for finite Δ it can be shown that if ϕ is h -exact and h -invariant, then $\neg\phi$ is h -exact and h -invariant too.

Proposition 42. *Let h be a surjective Σ -abstraction. Then the class of h -exact and h -invariant Σ -formulas is closed under conjunction, disjunction and existential quantification.*

Theorem 43 Invariance. *Any positive polynomial equation $p \stackrel{\circ}{=} 0$ such that p has no constant term is $h_{\mathbb{B}}$ -exact and $h_{\mathbb{B}}$ -invariant.*

Sketch of Proof. Any positive polynomial equation $p \stackrel{\circ}{=} 0$ such that p has no constant term and only positive coefficients has the form $\sum_{j=1}^l n_j \prod_{k=1}^{i_j} x_{j,k}^{m_{j,k}} \stackrel{\circ}{=} 0$ where $l \geq 0$, and $n_j, i_j, m_{j,k} > 0$. We can now show that for both algebras $S \in \{\mathbb{B}, \mathbb{R}_+\}$ that:

$$\text{sol}^S(p \stackrel{\circ}{=} 0) = \text{sol}^S\left(\bigwedge_{j=1}^l \bigvee_{k=1}^{i_j} x_{j,k} \stackrel{\circ}{=} 0\right)$$

Since the formulas $x_{j,k} \stackrel{\circ}{=} 0$ are $h_{\mathbb{B}}$ -exact and $h_{\mathbb{B}}$ -invariant, the theorem follows from the closure properties of Proposition 42.

10 Boolean Abstractions of Mixed Systems

In this section we prove our main result stating how to compute the $h_{\mathbb{B}}$ -abstraction of the \mathbb{R}_+ -solution set of a mixed system exactly.

Definition 44. *A mixed system is a formula in \mathcal{F}_{Σ} of the form $\exists \mathbf{z}. \phi \wedge \phi'$ where ϕ is a linear equation system and ϕ' a $h_{\mathbb{B}}$ -invariant and $h_{\mathbb{B}}$ -exact first-order formula.*

Note that linear equation systems $A\mathbf{y} \stackrel{\circ}{=} 0$, with A an integer matrix and \mathbf{y} a sequence of pairwise distinct variables, need not to be $h_{\mathbb{B}}$ -exact, if A is not positive. However, any linear equation systems of this shape is \mathbb{R}_+ -equivalent to some quasi-positive strongly-triangular polynomial system, as shown by the Elementary Modes Theorem 21. And quasi-positive strongly-triangular polynomial system were shown to be $h_{\mathbb{B}}$ -exact by Exactness Theorem 32.

Theorem 45 Main. *Any mixed system can be converted in exponential time to an \mathbb{R}_+ -equivalent Σ -formula that is $h_{\mathbb{B}}$ -exact.*

Proof Consider a mixed system $\exists \mathbf{x}. (\phi \wedge \phi')$ where ϕ is a linear equation system and ϕ' a first-order formula that is $h_{\mathbb{B}}$ -exact and $h_{\mathbb{B}}$ -invariant. Based on the Elementary Modes Theorem 21, the linear equation system ϕ can be transformed in exponential time to the form $\exists \mathbf{z}. \phi''$ where ϕ'' is a quasi-positive strongly-triangular system of linear equations. Such polynomial equation systems are $h_{\mathbb{B}}$ -exact by Theorem 32, and so is ϕ'' . The Invariance Proposition 37 shows that the conjunction $\phi'' \wedge \phi'$ is $h_{\mathbb{B}}$ -exact too, since ϕ' was assumed to be $h_{\mathbb{B}}$ -exact and $h_{\mathbb{B}}$ -invariant. Finally, $h_{\mathbb{B}}$ -exactness is preserved by existential quantification by Proposition 26, so the formula $\exists \mathbf{x}. \exists \mathbf{z}. \phi'' \wedge \phi'$ is $h_{\mathbb{B}}$ -exact too.

Corollary 46. *The $h_{\mathbb{B}}$ -abstraction of the \mathbb{R}_+ -solution set of a mixed system ϕ , that is $h_{\mathbb{B}} \circ \text{sol}^{\mathbb{R}_+}(\phi)$, can be computed in at most exponential time in the size of the system ϕ .*

The algorithm from the proof Corollary 46 can be improved so that it becomes sufficiently efficient for practical use. For this the two steps with exponential worst case complexity must be made polynomial for the particular instances. First note that the computation of the elementary modes (Theorem 21) is known to be computationally feasible. Various algorithms for this purpose were implemented [9,14,2,3] and applied successfully to problems in systems biology [11]. The second exponential step concerns the enumeration of all boolean variable assignments. This enumeration may be avoided by using constraint programming techniques for computing the solution set $\text{sol}^{\mathbb{B}}(\phi'')$. For those mixed systems for which both steps can be done in polynomial time, we can compute the boolean abstraction of the \mathbb{R}_+ -solution set in polynomial time too. The practical feasibility of this approach was demonstrated recently at an application to knockout prediction in systems biology [1], where previously only over-approximations could be computed.

11 Improving Boolean Networks for Sign Graphs

Let us now show how to obtain better boolean network for the sign graphs of reaction networks than by direct interpretation of ODEs over the booleans. We illustrate the approach for the example reaction network N_{cyc} . The formula $bn(N_{cyc})$ can be turned into a mixed-system by replacing the nonlinear kinetic expression $B_2 * C_2$ by some fresh variable v . The resulting mixed-system can then be rewritten by Theorem 45 to a $h_{\mathbb{B}}$ -exact formula that is \mathbb{R}_+ -equivalent. In the exact formula, we replace v back by $B_2 * C_2$ yielding the boolean network below. The network

indeed captures the sign graph of N_{cyc} in Fig. 8 exactly. The existentially bound variables x_1, \dots, x_n for boolean values are introduced by the elementary modes.

$$\begin{aligned}
A_2 &\stackrel{\circ}{=} A_1 + \dot{A}_1^+ \wedge B_2 \stackrel{\circ}{=} B_1 + \dot{B}_1^+ \wedge C_2 \stackrel{\circ}{=} C_1 + \dot{C}_1^+ \\
\wedge \dot{A}_2^+ * \dot{A}_2^- &\stackrel{\circ}{=} 0 \wedge \dot{B}_2^+ * \dot{B}_2^- \stackrel{\circ}{=} 0 \wedge \dot{C}_2^+ * \dot{C}_2^- \stackrel{\circ}{=} 0 \\
\wedge \exists x^0 \dots x^7. A_2 &\stackrel{\circ}{=} x^5 + x^6 + x^7 \wedge \dot{A}_2^- \stackrel{\circ}{=} x^4 + x^6 + x^7 \wedge \dot{A}_2^+ \stackrel{\circ}{=} x^3 + x^4 \wedge B_2 \stackrel{\circ}{=} x^2 + x^7 \\
\wedge \dot{B}_2^- &\stackrel{\circ}{=} x^1 + x^2 + x^3 \wedge \dot{B}_2^+ \stackrel{\circ}{=} x^1 + x^6 \wedge \dot{C}_2^- \stackrel{\circ}{=} x^0 \wedge \dot{C}_2^+ \stackrel{\circ}{=} x^0 + x^2 + x^7 \wedge B_2 * C_2 = x^3 + x^5
\end{aligned}$$

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Interpretation of expressions as sets of elements $\llbracket e \rrbracket^{\alpha, S} \subseteq \text{dom}(S)$, where S is a Σ -structure and $\alpha : V \rightarrow \text{dom}(S)$ where V contains all free variables.

$$\llbracket c \rrbracket^{\alpha, S} = c^S \quad \llbracket x \rrbracket^{\alpha, S} = \{\alpha(x)\} \quad \llbracket e \odot e' \rrbracket^{\alpha, S} = \cup \{s \odot^S s' \mid s \in \llbracket e \rrbracket^{\alpha, S}, s' \in \llbracket e' \rrbracket^{\alpha, S}\}$$

Interpretation of formulas as truth values $\llbracket \phi \rrbracket^{\alpha, S} \in \mathbb{B}$:

$$\begin{aligned} \llbracket e \overset{\circ}{=} e' \rrbracket^{\alpha, S} &= \begin{cases} 1 & \text{if } \llbracket e \rrbracket^{\alpha, S} \cap \llbracket e' \rrbracket^{\alpha, S} \neq \emptyset \\ 0 & \text{else} \end{cases} & \llbracket \phi \wedge \phi' \rrbracket^{\alpha, S} &= \llbracket \phi \rrbracket^{\alpha, S} \wedge^{\mathbb{B}} \llbracket \phi' \rrbracket^{\alpha, S} \\ \llbracket \neg \phi \rrbracket^{\alpha, S} &= \neg^{\mathbb{B}}(\llbracket \phi \rrbracket^{\alpha, S}) & \llbracket \exists x. \phi \rrbracket^{\alpha, S} &= \begin{cases} 1 & \text{if exists } s \in \text{dom}(S). \\ & \llbracket \phi \rrbracket^{\alpha[x/s], S} = 1 \\ 0 & \text{else} \end{cases} \end{aligned}$$

Fig. 11: Semantics of Σ -expressions and formulas over a Σ -structure S with respect to a variable assignment $\alpha : V \rightarrow \text{dom}(S)$.

A Proofs for Section 2 (Preliminaries)

For any set A and $n \in \mathbb{N}$, the set of n -tuples of elements in A is denoted by A^n . The i -th projection function on n -tuples of elements in A , where $1 \leq i \leq n$ is the function $\pi_i : A^n \rightarrow A$ such that $\pi_i(a_1, \dots, a_n) = a_i$ for all $a_1, \dots, a_n \in A$. If A is finite the number of elements of A is denote by $|A|$. *Projections and Pairs*. The projection $\pi_a(f)$ of a function $f : A \rightarrow B$ is its restriction $\alpha|_{A \setminus \{a\}}$. The projection of a set F of functions $f : A \rightarrow B$ is $\pi_a(F) = \{\pi_a(f) \mid f \in F\}$. Furthermore, we define the pair function $f^2 : A^2 \rightarrow B^2$ such that $f^2(a_1, a_2) = (f(a_1), f(a_2))$.

Lemma 11. *The boolean abstraction $h_{\mathbb{B}}$ is a Σ_{bool} -abstraction into a Σ_{bool} -algebra.*

Proof. For all $r, r' \in \mathbb{R}_+$ we have:

$$\begin{aligned} h_{\mathbb{B}}(r +^{\mathbb{R}_+} r') &= 1 \Leftrightarrow r +^{\mathbb{R}_+} r' \neq 0 \Leftrightarrow r \neq 0 \vee r' \neq 0 \Leftrightarrow h_{\mathbb{B}}(r) = 1 \vee h_{\mathbb{B}}(r') = 1 \\ h_{\mathbb{B}}(r *^{\mathbb{R}_+} r') &= 1 \Leftrightarrow r *^{\mathbb{R}_+} r' \neq 0 \Leftrightarrow r \neq 0 \wedge r' \neq 0 \Leftrightarrow h_{\mathbb{B}}(r) = 1 \wedge h_{\mathbb{B}}(r') = 1 \end{aligned}$$

Hence $h_{\mathbb{B}}(r +^{\mathbb{R}_+} r') = h_{\mathbb{B}}(r) +^{\mathbb{B}} h_{\mathbb{B}}(r')$ and $h_{\mathbb{B}}(r *^{\mathbb{R}_+} r') = h_{\mathbb{B}}(r) *^{\mathbb{B}} h_{\mathbb{B}}(r')$. Finally, for both constants $c \in C$ we have that $h_{\mathbb{B}}(c^{\mathbb{R}_+}) = h_{\mathbb{B}}(c) = c = c^{\mathbb{B}}$.

Lemma 12. *The sign abstraction is $h_{\mathbb{S}}$ a Σ_{bool} -abstraction into a Σ_{bool} -structure.*

Proof. For any $r, r' \in \mathbb{R}$ the second condition for homomorphism follows for all $\odot \in F^{(2)}$: $h_{\mathbb{S}}(r \odot r') \in h_{\mathbb{S}}(r) \odot^{\mathbb{S}} h_{\mathbb{S}}(r')$. And for all constants $c \in C$ we have by definition that $h_{\mathbb{S}}(c^{\mathbb{R}}) = c^{\mathbb{S}}$.

The following two lemmas are classical. Let R be a subset of assignments of type $V' \rightarrow \text{dom}(S)$ and $V \cap V' = \emptyset$ two subsets of \mathcal{V} . We define: $\text{ext}_V^S(R) = \{\alpha \cup \alpha' \mid \alpha' : V' \cup V \rightarrow \text{dom}(S), \alpha \in R\}$.

Lemma 47 Cylindrification. *If $V \cap \mathcal{V}(\phi) = \emptyset$ then: $\text{sol}_{V \cup \mathcal{V}(\phi)}^S(\phi) = \text{ext}_V^S(\text{sol}^S(\phi))$.*

Proof. We can show for all expressions $e \in \mathcal{E}_{\Sigma}$ with $\mathcal{V}(e)$ disjoint to V and any variables assignment $\alpha : \mathcal{V}(e) \cup V \rightarrow \text{dom}(S)$ that $\llbracket e \rrbracket^{\alpha, S} = \llbracket e \rrbracket^{\alpha|_{\mathcal{V}(e)}, S}$. This is by induction on the structure of expressions. It follows for all formulas $\phi \in \mathcal{F}_{\Sigma}(\mathcal{V})$ such that $\mathcal{V}(\phi)$ disjoint from V and $\alpha : \mathcal{V}(\phi) \cup V \rightarrow \text{dom}(S)$ that $\llbracket \phi \rrbracket^{\alpha, S} = \llbracket \phi \rrbracket^{\alpha|_{\mathcal{V}(\phi)}, S}$. This is by induction on the structure of formulas. It implies the lemma.

Lemma 48 Quantification is projection. $\text{sol}^S(\exists x. \phi) = \pi_x(\text{sol}^S(\phi))$.

Proof. This is straightforward from the semantics of existential quantifiers: $\text{sol}^S(\exists x. \phi) = \{\alpha|_{\mathcal{V}(\phi) \setminus \{x\}} \mid \alpha \in \text{sol}^S(\phi)\} = \pi_x(\text{sol}^S(\phi))$.

B Proofs for Section 7 (Linear Equation Systems and Elementary Modes)

Theorem 21 Elementary Modes. *For any system of linear equations ϕ with natural coefficients, one can compute in at most exponential time a \mathbb{R}_+ -equivalent formula $\exists \mathbf{x}.\phi'$ such that ϕ' is a quasi-positive strongly-triangular system of linear equations with natural coefficients and \mathbf{x} the sequence of variables on the left hand sides of the equations.*

Proof. Consider a system ϕ of linear equations with natural coefficients. Geometrically, the solution space of ϕ over the reals is a linear subspace of $\mathbb{R}^{\mathcal{V}(\phi)}$. When restricted to positive reals, as we do, this linear subspace is to be intersected with the positive cone $\mathbb{R}_+^{\mathcal{V}(\phi)}$. Therefore, $\text{sol}^{\mathbb{R}_+}(\phi)$ is a rational cone obtained by intersecting finitely many half-spaces: its H-representation is defined by the inequations $A\mathbf{y} \leq 0 \wedge A\mathbf{y} \geq 0 \wedge \mathbf{y} \geq 0$. The elementary modes of ϕ are the extreme rays of this cone and allow its V-representation. Up to normalization there are finitely many such extreme rays. Moreover, since the cone is rational and ϕ is homogeneous, the elementary modes can be normalised so that the V-representation contains only integer coefficients. The normalized elementary modes will be vectors of naturals in $\mathbb{N}^{\mathcal{V}(\phi)}$. Let e_1, \dots, e_n be the set of all normalized elementary modes in some arbitrary total order. Let E be the matrix with columns e_1, \dots, e_n . Let \mathbf{y} be the sequence of all variables of $\mathcal{V}(\phi)$ in some arbitrary total order. By construction, the variable in \mathbf{y} are pairwise distinct. According to the normalized V-representation of the system, every point of the cone is a positive linear combination of the elementary modes $\exists \mathbf{x}. E\mathbf{x} \overset{\circ}{=} \mathbf{ny}$, where \mathbf{n} contains the normalization factors. The linear system $E\mathbf{x} \overset{\circ}{=} \mathbf{ny}$ is quasi-positive, since E and \mathbf{n} are positive. The variables in \mathbf{x} can be chosen freshly, and thus pairwise distinct with \mathbf{y} . The linear system $E\mathbf{x} \overset{\circ}{=} \mathbf{ny}$ is strongly-triangular, since each variable of \mathbf{y} occurs in exactly one equation and never on the left. Therefore, we can define ϕ' as $E\mathbf{x} \overset{\circ}{=} \mathbf{ny}$. The computation of the elementary modes and thus of E can be done in at most exponential time in the size of ϕ by Motzkin's double description method [16,10,11].

C Proofs for Section 8 (Abstraction Exactness)

In order to do so we first show that h -exactness is preserved when adding variables. For this we have to assume that the abstraction h is surjective, which will be the case of all abstraction of interest.

Lemma 49 Variable extension preserves exactness. *Let $h : S \rightarrow \Delta$ be a Σ -abstraction that is surjective, $\phi \in \mathcal{F}_\Sigma$ a formula, and $V \supseteq \mathcal{V}(\phi)$. Then the h -exactness of ϕ implies the h -exactness of ϕ with respect to V .*

Proof. Essentially this follows from that solutions of formulas can be extended arbitrarily to variables that do not appear freely in the formula, as stated by the following claim.

Claim 50. *Any variable assignment $\sigma : V \rightarrow \Delta$ satisfies $\sigma \in h \circ \text{sol}_V^S(\phi)$ iff $\sigma|_{\mathcal{V}(\phi)} \in h \circ \text{sol}^S(\phi)$.*

For the one direction let $\sigma \in h \circ \text{sol}_V^S(\phi)$. Then there exists $\alpha \in \text{sol}_V^S(\phi)$ such that $\sigma = h \circ \alpha$. Since $V \supseteq \mathcal{V}(\phi)$ it follows that $\alpha|_{\mathcal{V}(\phi)} \in \text{sol}^S(\phi)$. Furthermore $\sigma|_{\mathcal{V}(\phi)} = h \circ \alpha|_{\mathcal{V}(\phi)}$ and thus $\sigma|_{\mathcal{V}(\phi)} \in h \circ \text{sol}^S(\phi)$.

For the other direction let $\sigma|_{\mathcal{V}(\phi)} \in h \circ \text{sol}^S(\phi)$. Then there exists $\alpha \in \text{sol}^S(\phi)$ such that $\sigma|_{\mathcal{V}(\phi)} = h \circ \alpha$. For any $y \in V \setminus \mathcal{V}(\phi)$ let $s_y \in \text{dom}(S)$ be such that $h(s_y) = \sigma(y)$. Such values exists since h is surjective. Now define $\alpha' = \alpha[y/s_y \mid y \in V \setminus \mathcal{V}(\phi)]$. Since $V \supseteq \mathcal{V}(\phi)$ it follows that $\alpha' \in \text{sol}_V^S(\phi)$. Furthermore, $\sigma = h \circ \alpha'$, so $\sigma \in h \circ \text{sol}_V^S(\phi)$.

Lemma 23. *Let V be a set of variables, R_1 and R_2 be subsets of assignments of type $V \rightarrow \text{dom}(S)$ and $h : S \rightarrow \Delta$ be a Σ -abstraction. $h \circ (R_1 \cup R_2) = h \circ R_1 \cup h \circ R_2$.*

Proof. This lemma follows from the following equivalences:

$$\begin{aligned} \beta \in h \circ (R_1 \cup R_2) &\Leftrightarrow \exists \alpha. \alpha \in R_1 \cup R_2 \wedge \beta = h \circ \alpha \\ &\Leftrightarrow \exists \alpha. (\alpha \in R_1 \vee \alpha \in R_2) \wedge \beta = h \circ \alpha \\ &\Leftrightarrow \exists \alpha. (\alpha \in R_1 \wedge \beta = h \circ \alpha) \vee (\alpha \in R_2 \wedge \beta = h \circ \alpha) \\ &\Leftrightarrow \beta \in h \circ R_1 \vee \beta \in h \circ R_2 \\ &\Leftrightarrow \beta \in h \circ R_1 \cup h \circ R_2 \end{aligned}$$

Proposition 24. *The disjunction of h -exact formulas is h -exact.*

Proof. Let ϕ_1 and ϕ_2 be negation free formulas that are h -exact. Let $V = \mathcal{V}(\phi_1) \cup \mathcal{V}(\phi_2)$. Lemma 49 shows that ϕ_1 and ϕ_2 are also h -exact with respect to the extended variable set V , i.e., for both $i \in \{1, 2\}$:

$$h \circ \text{sol}_V^S(\phi_i) = \text{sol}_V^\Delta(\phi_i)$$

The h -exactness of the disjunction $\phi_1 \vee \phi_2$ can now be shown as follows:

$$\begin{aligned} h \circ \text{sol}^S(\phi_1 \vee \phi_2) &= h \circ (\text{sol}_V^S(\phi_1) \cup \text{sol}_V^S(\phi_2)) \\ &= h \circ \text{sol}_V^S(\phi_1) \cup h \circ \text{sol}_V^S(\phi_2) \text{ by Lemma 23} \\ &= \text{sol}_V^\Delta(\phi_1) \cup \text{sol}_V^\Delta(\phi_2) \text{ by } h\text{-exactness of } \phi_1 \text{ and } \phi_2 \text{ wrt. } V \\ &= \text{sol}^\Delta(\phi_1 \vee \phi_2) \end{aligned}$$

Lemma 25 Projection commutes with abstraction. *For any Σ -abstraction $h : S \rightarrow \Delta$, subset R of assignments of type $V \rightarrow S$, and variable $x \in \mathcal{V}$: $h \circ \pi_x(R) = \pi_x(h \circ R)$.*

Proof. For all $\alpha : V \rightarrow \text{dom}(S)$ we have $h \circ \pi_x(\alpha) = h \circ \alpha|_{V \setminus \{x\}} = (h \circ \alpha)|_{V \setminus \{x\}} = \pi_x(h \circ \alpha)$.

Proposition 26 Quantification preserves exactness. *For any surjective Σ -abstraction $h : S \rightarrow \Delta$ and formula $\exists x. \phi \in \mathcal{F}_\Sigma$, if ϕ is h -exact then $\exists x. \phi$ is h -exact.*

Proof. Let ϕ be h -exact. By definition ϕ is h -exact with respect to V . Since h is assumed to be surjective, Lemma 49 implies that ϕ is h -exact with respect to $V \cup \{x\}$ (independently of whether x occurs freely in ϕ or not). Hence:

$$\begin{aligned} h(\text{sol}^S(\exists x. \phi)) &= h(\pi_x(\text{sol}^S(\phi))) \text{ by Lemma 48} \\ &= \pi_x(h(\text{sol}^S(\phi))) \text{ by Lemma 25} \\ &= \pi_x(\text{sol}^\Delta(\phi)) \text{ since } \phi \text{ is } h\text{-exact} \\ &= \text{sol}^\Delta(\exists x. \phi) \text{ by Lemma 48} \end{aligned}$$

Lemma 27 Singleton property. *If S is a Σ -algebra, $e \in \mathcal{E}_\Sigma$, and $\alpha : \mathcal{V}(e) \rightarrow S$ a variable assignment, then the set $\llbracket e \rrbracket^{\alpha, S}$ is a singleton.*

Proof. By induction on the structure of expressions $e \in \mathcal{E}$:

Case of constants $c \in \{0, 1\}$. The set $\llbracket c \rrbracket^{\alpha, S} = \{c^S\}$ is a singleton.

Case of variables $x \in \mathcal{V}$. The set $\llbracket x \rrbracket^{\alpha, S} = \{\alpha(x)\}$ is a singleton.

Case $e_1 \odot e_2$ where $e_1, e_2 \in \mathcal{E}_\Sigma$ and $\odot \in \{+, *\}$.

$$\llbracket e_1 \odot e_2 \rrbracket^{\alpha, S} = \{s \odot^S s' \mid s \in \llbracket e_1 \rrbracket^{\alpha, S}, s' \in \llbracket e_2 \rrbracket^{\alpha, S}\}$$

This set is a singleton since $\llbracket e_1 \rrbracket^{\alpha, S}$ and $\llbracket e_2 \rrbracket^{\alpha, S}$ are singletons by induction hypothesis, meaning that $s \odot^S s'$ is also a singleton since S is a Σ -algebra.

Lemma 29. *Let $\phi \in \mathcal{F}_\Sigma$ be a Σ -formula and S a Σ -algebra with unique division. For nonzero natural number n , variable $y \notin \mathcal{V}(\phi)$, and expression $e \in \mathcal{E}_\Sigma$ with $\mathcal{V}(e) \subseteq \mathcal{V}(\phi)$:*

$$\text{sol}^S(\phi \wedge ny \stackrel{\circ}{=} e) = \{\alpha[y/\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}] \mid \alpha \in \text{sol}^S(\phi)\}$$

Proof. We fix some $\alpha : \mathcal{V}(\phi) \rightarrow \text{dom}(S)$ arbitrarily. Since S is a Σ -algebra, $\llbracket e \rrbracket^{\alpha,S}$ is a singleton and $\mathcal{V}(e) \subseteq \mathcal{V}(\phi)$, $\text{ele}(\llbracket e \rrbracket^{\alpha,S})$ is defined uniquely. Furthermore S has unique division, so that $\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}$ is well defined element of $\text{dom}(S)$. Therefore and since $y \notin \mathcal{V}(\phi)$, $\alpha[y/\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}]$ is the unique solution of the equation $ny \stackrel{\circ}{=} e$ that extends on α .

First we prove the inclusion “ \supseteq ”. Let $\alpha \in \text{sol}^S(\phi)$, $y \notin \mathcal{V}(\phi)$, and $\alpha[y/\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}]$ is a solution of $ny \stackrel{\circ}{=} e$, it follows that $\alpha[y/\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}]$ is a solution of $\phi \wedge ny \stackrel{\circ}{=} e$.

Second, we prove the inverse inclusion “ \subseteq ”. Let $\alpha \in \text{sol}^S(\phi \wedge ny \stackrel{\circ}{=} e)$. Since $\alpha[y/\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}]$ is the unique solution of the equation $ny \stackrel{\circ}{=} e$ that extends on $\alpha' = \alpha|_{\mathcal{V}(\phi)}$ it follows that $\alpha(y) = \frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}$ so that $\alpha = \alpha'[y/\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}]$ while $\alpha' \in \text{sol}^S(\phi)$.

Proposition 30. *Let $\phi \in \mathcal{F}_\Sigma$ a Σ -formula, $n \neq 0$ a natural number, $e \in \mathcal{E}_\Sigma$ a Σ -expression with $\mathcal{V}(e) \subseteq \mathcal{V}(\phi)$ and $y \notin \mathcal{V}(\phi)$ and the Σ -abstraction $h : S \rightarrow \Delta$ with S and Δ two Σ -algebras with unique division. Then if ϕ is h -exact implies that $\phi \wedge e \stackrel{\circ}{=} ny$ is h -exact.*

Proof. Let $e \in \mathcal{E}_\Sigma$ a Σ -expression.

Claim 51. *For any $\alpha : V \rightarrow \mathbb{R}_+$ with $V \supseteq \mathcal{V}(e)$: $h(\text{ele}(\llbracket e \rrbracket^{\alpha,S})) = \text{ele}(\llbracket e \rrbracket^{h\circ\alpha,\Delta})$.*

This can be seen as follows. For any $\alpha : \mathcal{V}(\phi) \rightarrow S$ Theorem ?? on homomorphism yields $h(\llbracket e \rrbracket^{\alpha,S}) \subseteq \llbracket e \rrbracket^{h\circ\alpha,\Delta}$. Since S and Δ are both Σ -algebras, the sets $\llbracket e \rrbracket^{\alpha,S}$ and $\llbracket e \rrbracket^{h\circ\alpha,\Delta}$ are both singletons by Lemma 27, so that $h(\text{ele}(\llbracket e \rrbracket^{\alpha,S})) = \text{ele}(\llbracket e \rrbracket^{h\circ\alpha,\Delta})$.

Claim 52. *For any $s \in \text{dom}(S)$ and $n \neq 0$ a natural number: $h(\frac{s}{n}) = \frac{h(s)}{n}$.*

Since S is assumed to have unique division $s' = \frac{s}{n}$ is well-defined as the unique element of $\text{dom}(S)$ such that $\underbrace{s' +^S \dots +^S s'}_n = s$. Hence, $h(\underbrace{s' +^S \dots +^S s'}_n) = h(s)$ and since h is a homomorphism, it follows that $\underbrace{h(s') +^\Delta \dots +^\Delta h(s')}_n = h(s)$. Since Δ is assumed to have unique division, this implies that $h(s') = \frac{h(s)}{n}$.

The Proposition can now be shown based on these two claims. Let ϕ be h -exact, $y \notin \mathcal{V}(\phi)$, and $\mathcal{V}(e) \subseteq \mathcal{V}(\phi)$. We have to show that $\phi \wedge ny \stackrel{\circ}{=} e$ is h -exact too:

$$\begin{aligned} h \circ \text{sol}^S(\phi \wedge e \stackrel{\circ}{=} ny) &= h \circ \{\alpha[y/\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n}] \mid \alpha \in \text{sol}^S(\phi)\} && \text{by Lemma 29} \\ &= \{(h \circ \alpha)[y/h(\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n})] \mid \alpha \in \text{sol}^S(\phi)\} && \text{elementary} \\ &= \{\sigma[y/h(\frac{\text{ele}(\llbracket e \rrbracket^{\alpha,S})}{n})] \mid \sigma \in \text{sol}^\Delta(\phi)\} && \text{h-exactness of } \phi \\ &= \{\sigma[y/\frac{h(\text{ele}(\llbracket e \rrbracket^{\alpha,S}))}{n}] \mid \sigma \in \text{sol}^\Delta(\phi)\} && \text{by Claim 52} \\ &= \{\sigma[y/\frac{\text{ele}(\llbracket e \rrbracket^{h\circ\alpha,\Delta})}{n}] \mid \sigma \in \text{sol}^\Delta(\phi)\} && \text{by Claim 51} \\ &= \text{sol}^\Delta(\phi \wedge e \stackrel{\circ}{=} ny) && \text{by Lemma 29} \end{aligned}$$

Proposition 31. *Let $h : S \rightarrow \Delta$ be a Σ -abstraction between Σ -algebras with unique division. Then any strongly-triangular system of Σ -equations with natural coefficients is h -exact.*

Proof. Any strongly-triangular system of equations has the form $\bigwedge_{i=1}^n e_i \stackrel{\circ}{=} n_i y_i$ where n and $n_i \neq 0$ are naturals and y_i is i -fresh for all $1 \leq i \leq n$. The proof is by induction on n . In the case $n = 0$, the conjunction is equal to $true$ which is h -exact since $h(sol^S(true)) = h(\{\}) = sol^\Delta(true)$. In the case $n > 0$, we have by induction hypothesis that $\bigwedge_{j=1}^{i-1} e_j \stackrel{\circ}{=} n_j y_j$ is h -exact. Since $n_i \neq 0$ it follows from Proposition 30 that that $e_i \stackrel{\circ}{=} n_i y_i \wedge \bigwedge_{j=1}^{i-1} e_j \stackrel{\circ}{=} n_j y_j$ is h -exact.

D Proofs for Section 9 (Abstraction Invariance)

Lemma 35. *If either R_1 or R_2 are h -invariant then: $h \circ (R_1 \cap R_2) = h \circ R_1 \cap h \circ R_2$.*

Proof. The one inclusion is straightforward without invariance:

$$\begin{aligned} h \circ (R_1 \cap R_2) &= \{h \circ \alpha \mid \alpha \in R_1, \alpha \in R_2\} \\ &\subseteq \{h \circ \alpha \mid \alpha \in R_1\} \cap \{h \circ \alpha \mid \alpha \in R_2\} \\ &= h \circ R_1 \cap h \circ R_2 \end{aligned}$$

For the other inclusion, we can assume with loss of generality that R_1 is h -invariant. So let $\beta \in h \circ R_1 \cap h \circ R_2$. Then there exist $\alpha_1 \in R_1$ and $\alpha_2 \in R_2$ such that $\beta = h \circ \alpha_1 = h \circ \alpha_2$. By h -invariance of R_1 it follows that $\alpha_1 \in R_2$. So $\alpha_1 \in R_1 \cap R_2$, and hence, $\beta \in h \circ (R_1 \cap R_2)$.

Lemma 36 Algebraic characterization. *A subset of R variables assignment of type $V \rightarrow dom(S)$ is h -invariant for a Σ -abstraction $h : S \rightarrow \Delta$ iff $h \circ (h \circ R) \subseteq R$.*

Proof. “ \Rightarrow ”. Let R be h -invariant and $\alpha \in h \circ (h \circ R)$. Then there exists $\alpha' \in R$ such that $h \circ \alpha = h \circ \alpha'$. The h -invariance of R thus implies that $\alpha \in R$.

“ \Leftarrow ”. Suppose that $h \circ (h \circ R) \subseteq R$. Let $\alpha, \alpha' : V \rightarrow dom(S)$ such that $h \circ \alpha = h \circ \alpha'$ and $\alpha \in R$. We have to show that $\alpha' \in R$. From $h \circ \alpha = h \circ \alpha'$ and $\alpha \in R$ it follows that $\alpha' \in h \circ (h \circ R)$ and thus $\alpha' \in R$ as required.

Lemma 53 Variable extension preserves invariance. *Let h be a surjective abstraction and R a subset of functions of type $V' \rightarrow dom(S)$ and V a subset of variables disjoint from V' . If R is h -invariant then $ext_V^S(R)$ is h -invariant too.*

Proof. This will follow straightforwardly from the characterization of h -invariance in Lemma 36 and the following two claims:

Claim 54. *If h is surjective then $h \circ ext_V^S(R) = ext_V^\Delta(h \circ R)$.*

This follows from $h \circ ext_V^S(R) = \{h \circ \alpha \mid \alpha \in ext_V^S(R)\} = ext_V^\Delta(\{h \circ \alpha' \mid \alpha' \in R\})$ where we use the surjectivity of h in the last step.

Claim 55. *$h \circ ext_V^\Delta(R') = ext_V^S(h \circ R')$ for any subset R' of functions of type $V' \rightarrow dom(\Delta)$.*

$$\begin{aligned} h \circ ext_V^\Delta(R') &= \{\alpha : V \cup V' \rightarrow dom(S) \mid h \circ \alpha \in ext_V^\Delta(R')\} \\ &= \{\alpha : V \cup V' \rightarrow dom(S) \mid h \circ \alpha|_{V'} \in R'\} \\ &= ext_V^S(\{\alpha' : V' \rightarrow dom(S) \mid h \circ \alpha' \in R'\}) \\ &= ext_V^S(h \circ R') \end{aligned}$$

Lemma 56. *Let $h : S \rightarrow \Delta$ be a surjective Σ -abstraction, ϕ be a Σ -formula, and $V \supseteq \mathcal{V}(\phi)$. Then the h -invariance of ϕ implies the h -invariance of $sol_V^S(\phi)$.*

Proof. This follows from the cylindrification Lemma 47 and that extension preserves h -invariance as shown in Lemma 53.

Lemma 38. *For any Σ -abstraction $h : S \rightarrow \Delta$, any subsets of assignments of type $V \rightarrow \text{dom}(S)$ R_1 and R_2 and V a subset of variables:*

- $h \ominus (R_1 \cap R_2) = h \ominus R_1 \cap h \ominus R_2.$
- $h \ominus (R_1 \cup R_2) = h \ominus R_1 \cup h \ominus R_2.$

Proof. The case for unions follows straightforwardly from the definitions:

$$\begin{aligned} h \ominus (R_1 \cup R_2) &= \{\alpha \mid h \circ \alpha \in R_1 \cup R_2\} \\ &= \{\alpha \mid h \circ \alpha \in R_1 \vee h \circ \alpha \in R_2\} \\ &= \{\alpha \mid h \circ \alpha \in R_1\} \cup \{\alpha \mid h \circ \alpha \in R_2\} \\ &= h \ominus R_1 \cup h \ominus R_2 \end{aligned}$$

The case of intersection is symmetric:

$$\begin{aligned} h \ominus (R_1 \cap R_2) &= \{\alpha \mid h \circ \alpha \in R_1 \cap R_2\} \\ &= \{\alpha \mid h \circ \alpha \in R_1 \wedge h \circ \alpha \in R_2\} \\ &= \{\alpha \mid h \circ \alpha \in R_1\} \cap \{\alpha \mid h \circ \alpha \in R_2\} \\ &= h \ominus R_1 \cap h \ominus R_2 \end{aligned}$$

Lemma 39 Intersection and union preserve invariance. *Let $h : S \rightarrow \Delta$ be a Σ -abstraction. Then the intersection and union of any two h -invariant subsets R_1 and R_2 of variables assignments of type $V \rightarrow \text{dom}(S)$ is h -invariant.*

Proof. This follows from the algebraic characterization Lemma 36 for invariance, in combination with the algebraic properties of composition and decomposition given in Lemmas 23, 35, and 38.

Lemma 40 Projection commutes with left-decomposition. $h \ominus \pi_x(R) = \pi_x(h \ominus R).$

Proof. For all $\alpha : V \rightarrow \text{dom}(\Delta)$ we have $h \ominus \pi_x(\alpha) = h \ominus \alpha|_{V \setminus \{x\}} = (h \ominus \alpha)|_{V \setminus \{x\}} = \pi_x(h \ominus \alpha).$

Proposition 41 Invariance is preserved by conjunction, disjunction, and quantification. *If h is a surjective abstraction then the class of h -invariant FO-formulas is closed under conjunction, disjunction, and existential quantification.*

Proof. Let $h : S \rightarrow \Delta$ be a Σ -abstraction.

Case of conjunction: Let ϕ_1 and ϕ_2 be h -invariant and $V = \mathcal{V}(\phi_1 \wedge \phi_2)$. By Lemma 56 the sets $\text{sol}_V^S(\phi_1)$ and $\text{sol}_V^S(\phi_2)$ are both h -invariant, and so by Lemma 39 is their intersection. Hence:

$$\begin{aligned} h \ominus (h \circ \text{sol}^S(\phi_1 \wedge \phi_2)) &= h \ominus (h \circ (\text{sol}_V^S(\phi_1) \cap \text{sol}_V^S(\phi_2))) \\ &\subseteq \text{sol}_V^S(\phi_1) \cap \text{sol}_V^S(\phi_2) && \text{by } h\text{-invariance and Lemma 36} \\ &= \text{sol}^S(\phi_1 \wedge \phi_2) \end{aligned}$$

By Lemma 36 in the other direction, this implies that $\phi_1 \wedge \phi_2$ is h -invariant.

Case of disjunction: Analogous to the case of conjunction.

Case of existential quantification:

$$\begin{aligned} h \ominus (h \circ \text{sol}^S(\exists x. \phi_1)) &= h \ominus (h \circ \pi_x(\text{sol}^S(\phi_1))) \text{ by Lemma 48} \\ &= h \ominus (\pi_x(h \circ \text{sol}^S(\phi_1))) \text{ by Lemma 25} \\ &= \pi_x(h \ominus (h \circ \text{sol}^S(\phi_1))) \text{ by Lemma 40} \\ &\subseteq \pi_x(\text{sol}^S(\phi_1)) && \text{by } h\text{-invariance of } \phi_1 \text{ and Lemma 36} \\ &= \text{sol}^S(\exists x. \phi_1) && \text{by Lemma 48} \end{aligned}$$

By Lemma 36, this implies that $\exists x. \phi_1$ is h -invariant.

Proposition 42. *Let h be a surjective Σ -abstraction. Then the class of h -exact and h -invariant Σ -formulas is closed under conjunction, disjunction and existential quantification.*

Proof. Closure under conjunction follows from Propositions 37 and 41, closure under disjunction from Propositions 24 and 41, and closure under existential quantification by Propositions 26 and 41.

Theorem 43 Invariance. *Any positive polynomial equation $p \stackrel{\circ}{=} 0$ such that p has no constant term is $h_{\mathbb{B}}$ -exact and $h_{\mathbb{B}}$ -invariant.*

Proof. Consider a positive polynomial equation $p \stackrel{\circ}{=} 0$ such that p has no constant term and only positive coefficients. Thus p has the form $\sum_{j=1}^l n_j \prod_{k=1}^{i_j} x_{j,k}^{m_{j,k}} \stackrel{\circ}{=} 0$ where $l \geq 0$, and $n_j, i_j, m_{j,k} > 0$.

Claim 57. *For both algebras $S \in \{\mathbb{B}, \mathbb{R}_+\}$: $\text{sol}^S(p \stackrel{\circ}{=} 0) = \text{sol}^S(\bigwedge_{j=1}^l \bigvee_{k=1}^{i_j} x_{j,k} \stackrel{\circ}{=} 0)$.*

The polynomial has values zero if and only if all its monomials do, that is: $\prod_{k=1}^{i_j} x_{j,k}^{m_{j,k}} = 0$ for all $1 \leq j \leq l$. Since constant terms are ruled out, we have $i_j \neq 0$. Furthermore, we assumed for all polynomials that $m_{j,k} \neq 0$. So for all $1 \leq j \leq l$ there must exist $1 \leq k \leq i_j$ such that $x_{j,k} = 0$.

Claim 58. *The equation $x \stackrel{\circ}{=} 0$ is $h_{\mathbb{B}}$ -exact and $h_{\mathbb{B}}$ -invariant.*

This is straightforward from the definitions. With these two claims we are now in the position to prove the lemma. Since the class of $h_{\mathbb{B}}$ -exact and $h_{\mathbb{B}}$ -invariant formulas is closed under conjunction and disjunction by Proposition 42, it follows from Claim 58 that $\bigwedge_{j=1}^l \bigvee_{k=1}^{i_j} x_{j,k} \stackrel{\circ}{=} 0$ is both $h_{\mathbb{B}}$ -exact and $h_{\mathbb{B}}$ -invariant. Since this formula is equivalent over \mathbb{R}_+ to the polynomial equation by Claim 57, the $h_{\mathbb{B}}$ -invariance carries over to $p \stackrel{\circ}{=} 0$. The $h_{\mathbb{B}}$ -exactness also carries over based on the equivalence for both structures \mathbb{R}_+ and \mathbb{B} :

$$\begin{aligned} h_{\mathbb{B}} \circ \text{sol}^{\mathbb{R}_+}(p \stackrel{\circ}{=} 0) &= h_{\mathbb{B}} \circ \text{sol}_{V^+}^{\mathbb{R}_+}(\bigwedge_{j=1}^l \bigvee_{k=1}^{i_j} x_{j,k} \stackrel{\circ}{=} 0) && \text{by Claim 57 for } \mathbb{R}_+ \\ &= \text{sol}^{\mathbb{B}}(\bigwedge_{j=1}^l \bigvee_{k=1}^{i_j} x_{j,k} \stackrel{\circ}{=} 0) && \text{by } h_{\mathbb{B}} \text{ exactness} \\ &= \text{sol}^{\mathbb{B}}(p \stackrel{\circ}{=} 0) && \text{by Claim 57 for } \mathbb{B}. \end{aligned}$$

E Proofs for Section 10 (Boolean Abstractions of Mixed Systems)

Corollary 46. *The $h_{\mathbb{B}}$ -abstraction of the \mathbb{R}_+ -solution set of a mixed system ϕ , that is $h_{\mathbb{B}} \circ \text{sol}^{\mathbb{R}_+}(\phi)$, can be computed in at most exponential time in the size of the system ϕ .*

Proof. Given an mixed system ϕ , we can apply Theorem 45 to compute in at most exponential time an \mathbb{R}_+ -equivalent formula ϕ'' that is $h_{\mathbb{B}}$ -exact. It is then sufficient to compute $\text{sol}^{\mathbb{B}}(\phi'')$ in exponential time in the size of ϕ . This can be done in the naive manner, that is by evaluating the formula ϕ'' – which may be of exponential size – over all possible boolean variable assignments – of which there may be exponentially many. For each assignment the evaluation can be done in PSPACE and thus in exponential time. The overall time required is thus a product of two exponentials, which remains exponential.

F Proofs for Section 11 (References)