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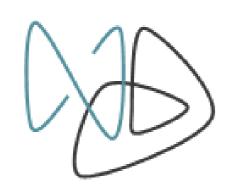
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SÃO PAULO SCHOOL OF ADVANCED SCIENCES ON

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SENSITIVITY ANALYSIS IN ZIKA VIRUS DYNAMICS AND A MODEL DISCREPANCY APPROACH

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Núcleo de **M**odelagem e **E**xpe**ri**mentação **Co**mputacional (NUMERICO)

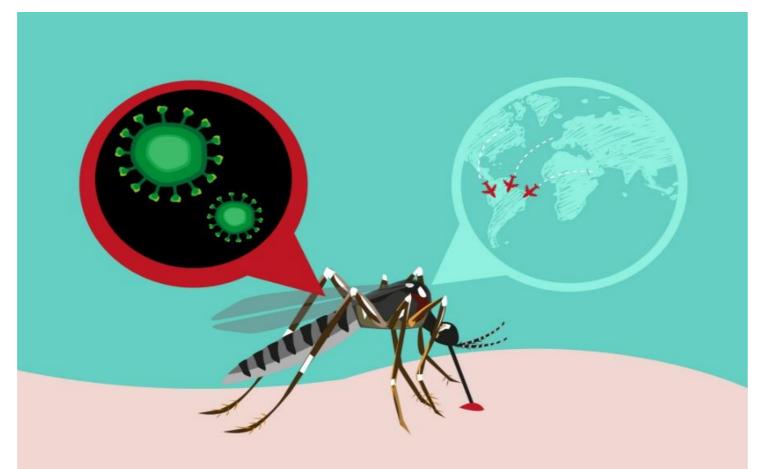




INTRODUCTION

- →Zika virus: global widespread and connection with congenital diseases;
- → 2016: Zika becomes a public health emergency of international concern;
- → Main vector: Aedes mosquitoes;
- → A validated model can reveal new characteristics of the disease;
- → Relations of model parameters are also of interest;

FIGURE 1 – Zika transmission representation.

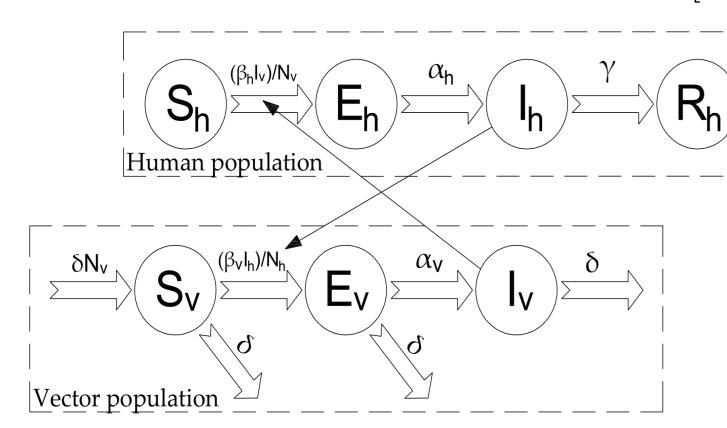


OBJECTIVE

- ◆Perform sensitivity analysis to compare the parameters' global effect under different scenarios;
- ◆ Develop a statistical framework using Bayesian Inference and Polynomial Chaos Expansion to quantify epidemic model discrepancies;

COMPUTATIONAL MODEL

FIGURE 2 - SEIR-SEI model schematic [1].



QUANTITIES OF INTEREST:

- Cumulative cases of infectious: $C(t) = \int_{\tau=0}^{t} \alpha_h E_h(\tau) d\tau$
- New cases per week: $\mathcal{N}_w = C_w - C_{w-1}, \ w = 1 \dots 52, \ \mathcal{N}_1 = C_1$

DYNAMICAL SYSTEM:

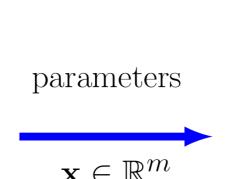
$$\frac{\mathrm{d}S_h}{\mathrm{d}t} = -\beta_h S_h \frac{I_v}{N_v} , \qquad \frac{\mathrm{d}S_v}{\mathrm{d}t} = \delta N_v - \beta_v S_v \frac{I_h}{N_h} - \delta S_v ,$$

$$\frac{\mathrm{d}E_h}{\mathrm{d}t} = \beta_h S_h \frac{I_v}{N_v} - \alpha_h E_h , \frac{\mathrm{d}E_v}{\mathrm{d}t} = \beta_v S_v \frac{I_h}{N_h} - (\alpha_v + \delta) E_v ,$$

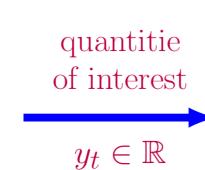
$$\frac{\mathrm{d}I_h}{\mathrm{d}t} = \alpha_h E_h - \gamma I_h , \qquad \frac{\mathrm{d}I_v}{\mathrm{d}t} = \alpha_v E_v - \delta I_v ,$$

 $\frac{\mathrm{d}R_h}{\mathrm{d}t} = \gamma I_h , \qquad \qquad \frac{\mathrm{d}C}{\mathrm{d}t} = \alpha_h E_h .$ + Initial Conditions

FIGURE 3 - Observation operator schematic [2].



mathematical model $y_t = \mathcal{M}(\mathbf{x}, t)$



gives

SENSITIVITY ANALYSIS

The Hoeffding-Sobol' decomposition [3] for n iid $X_i \sim \mathcal{U}(0,1)$

$$Y_t = \mathcal{M}_0 + \sum_{1 \le i \le n} \mathcal{M}_i(X_i) + \sum_{1 \le i < j \le n} \mathcal{M}_{ij}(X_i, X_j) + \dots + \mathcal{M}_{1 \dots n}(X_1 \dots X_n),$$

 $\mathcal{M}_0 = \mathbb{E}[Y_t], \ \mathcal{M}_i(X_i) = \mathbb{E}[Y_t|X_i] - \mathcal{M}_0, \ \mathcal{M}_{ij}(X_i, X_j) = \mathbb{E}[Y_t|X_i, X_j] - \mathcal{M}_0 - \mathcal{M}_i - \mathcal{M}_j.$

Sobol' Indices: interaction effect of inputs in u

 $S_{\mathbf{u}} = \operatorname{Var} \left[\mathcal{M}_{\mathbf{u}}(X_{\mathbf{u}}) \right] / \operatorname{Var} \left[\mathcal{M}(\mathbf{X}) \right]$

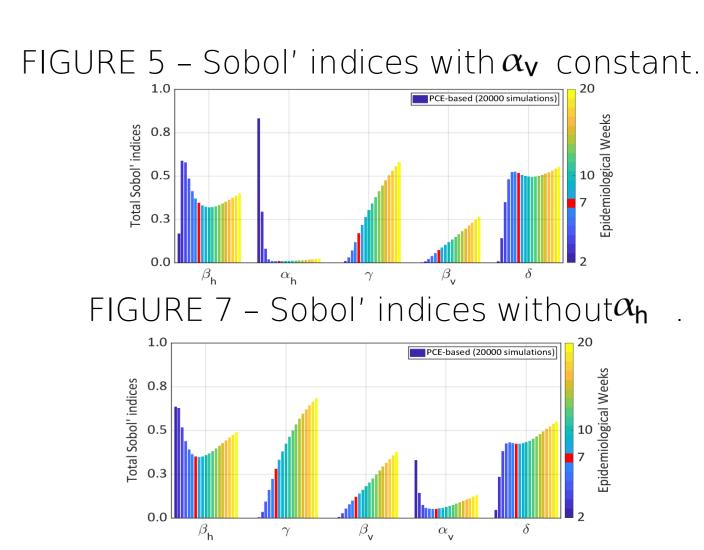
The Polynomial Chaos Expansion [2] of $m(Y = \mathcal{M}(\mathbf{X}))$, for a multivariate orthonormal polynomi $\Phi_{m{lpha}}$ amily with y_{α} efficients

$$Y_t = \sum_{\boldsymbol{\alpha} \in \mathbb{N}^k} y_{\boldsymbol{\alpha}}(t) \, \Phi_{\boldsymbol{\alpha}}(\mathbf{X}) \,,$$

enables analytic computation of Sobol Indices:

$$S_{\mathbf{u}} = \sum_{\alpha \in \mathcal{A}_{\mathbf{u}}} y_{\alpha}^2 / \sum_{\alpha \in \mathcal{A} \setminus 0} y_{\alpha}^2 , \quad \mathcal{A}_{\mathbf{u}} = \{ \alpha \in \mathcal{A} : i \in \mathbf{u} \iff \alpha_i \neq 0 \}$$

FIGURE 4 - Sobol' indices of the model. FIGURE 6 – Sobol' indices witho $lpha_{ m V}$



STATISTICAL INFERENCE (ONGOING RESEARCH)

DISCREPANCY CALCULATION:

Suppose a data se $\mathcal{D}=(t_1,y_1^{dat}),(t_2,y_2^{dat}),\ldots,(t_{N_d},y_{N_d}^{dat})$ of measur y_t of thi. The -th observation is given by

$$\underbrace{y_i^{dat}}_{reality} = \underbrace{\mathcal{M}(\mathbf{x}, t_i)}_{model} + \underbrace{\varepsilon_i}_{error}$$

Sargsyan, Najm and Ghanem's [4] novel approach to deal with the model discrepancies is to adopt a metamodel structure which lumps the error into the parameters

$$Y^{dat} \approx \mathcal{M}(\mathbf{X}_{\varepsilon}, t) , \quad \mathbf{X}_{\epsilon} = \sum_{\alpha \in \mathcal{I}} \mathbf{X}_{\alpha}(t) \Psi_{\alpha}(\boldsymbol{\xi}),$$

where \mathbf{X}_{α} coefficients are defined as random to be able to be identified by using Bayesian Inference.

BAYESIAN INFERENCE:

- Inference problem become use data information to update the prior probability
- From Bayes' rule,

$$\rho(\mathbf{X}_{\alpha}|\mathcal{D}) = \frac{\rho(\mathcal{D}|\mathbf{X}_{\alpha})\rho(\mathbf{X}_{\alpha})}{\rho(\mathcal{D})}.$$

 $\rightarrow \rho(\mathbf{X}_{\alpha}|\mathcal{D})$: posterior distribution

 $\rightarrow \rho(\mathbf{X}_{\alpha})$: prior distribution

 $\rightarrow \rho(\mathcal{D}|\mathbf{X}_{\alpha})$: likelihood function

 $\rightarrow \boldsymbol{\rho}(\mathcal{D})$: evidence

To define a good point of start, the Maximum Entropy Principle is applied to construct the most informative prior distribution.

FINAL REMARKS

- ✓ Comparative results of global Sobol' Indices show how the lack of some parameters can change the sensibility effect of the others;
- ✓ A framework for statistical inference exploring Polynomial Chaos to measure the model discrepancies was presented;
- ✓ In future works, the authors intend explore this new framework to quantify model discrepancy and then improve its predictions;

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