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Relative Fuzzy Connectedness on Directed Graphs and its Application in a Hybrid Method for Interactive Image Segmentation

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Abstract



Image segmentation consists of dividing an image into its composing regions or objects, for example, to isolate the pixels of a target object of a given application. In segmentation of medical images, the object of interest commonly presents transitions at its border predominantly from bright to dark or dark to bright. Traditional region-based methods of image segmentation, such as Relative Fuzzy Connectedness (**RFC**), do not distinguish well between similar boundaries with opposite orientations. The specification of the **boundary polarity** can help to alleviate this problem but this requires a mathematical formulation on **directed graphs**. A discussion on how to incorporate this property in the RFC framework is presented in this work. A theoretical proof of the optimality of the new algorithm, called Oriented Relative Fuzzy Connectedness (ORFC), in terms of an energy function on directed graphs subject to **seed constraints** is presented, and its application in powerful **hybrid** segmentation methods. The hybrid method proposed ORFC & Graph Cut preserves the robustness of ORFC respect to the seed choice, avoiding the shrinking problem of Graph Cut (GC), and keeps the strong control of the GC in the **contour delination** of irregular image boundaries. The proposed methods are evaluated using **medical** images of MRI and CT images of the human brain and thoracic studies.

Theorical definition of ORFC

ORFC as a directed cut in the digraph

ORFC is supported by a **graph cut optimality criterion**, which **encompasses RFC** as a particular case. In the case of directed graphs, we have two possible sets of **cuts (inner and outer)**. Let's consider the inner cut:

 $\mathcal{C}_{in}(x) = \{ \langle a, b \rangle \in E \colon x(a) = 0 \land x(b) = 1 \}$

So we have the following formulation for the **energy functional** of the ε_{∞} -minimizing problem.

$$\varepsilon_{\infty}^{in}(x) = \max_{\langle a,b\rangle \in \mathcal{C}_{in}} w(a,b)$$

Let $\varepsilon_{\infty\downarrow}^{in}$ be the **minimum value** of the energy $\varepsilon_{\infty}^{in}(x)$, that is:

Example of $A_{ORFC}^{in, \mathfrak{S}}(\mathcal{S}_o = \{s_i\}, \mathcal{S}_b)$



Results

In this work, we introduced the *ORFC* technique and showed that it can effectively exploit the boundary polarity improving the results in relation to its predecessor *RFC*. We also presented a powerful **hybrid approach**, which outperforms the previous works [KCC13, KCC12C]. A conference paper was published in SIBGRAPI [HHCB14], and

one **journal paper** was published in SIDGRAFT [IIIICD14], and Image and Video Processing [HHCB15].

$$\varepsilon_{\infty\downarrow}^{in} = \min\{\varepsilon_{\infty}^{in}(x) : x \in \mathcal{X}(\mathcal{S}_o, \mathcal{S}_b)\}$$

Therefore, we have the following **set of solutions**:

$$\mathcal{X}_{\infty}^{in}(\mathcal{S}_o, \mathcal{S}_b) = \{ x \in \mathcal{X}(\mathcal{S}_o, \mathcal{S}_b) : \varepsilon_{\infty}^{in}(x) = \varepsilon_{\infty\downarrow}^{in} \}$$

The ORFC algorithms on digraphs have the following definitions based on cut in graph: For the **inner cut** "*in*" with one internal seed s_1 ,

$$A_{ORFC}^{in, \mathcal{S}}(\{s_1\}, \mathcal{S}_b) = \chi_O \in \mathcal{X}_{\infty}^{in}(\{s_1\}, \mathcal{S}_b) : |O| = \min\{|P| : \chi_P \in \mathcal{X}_{\infty}^{in}(\{s_1\}, \mathcal{S}_b)\}$$

Hybrid segmentation: ORFC & GC



IRFC

1

ORFC+GC



1 Compute $P: \chi_P = A_{ORFC}^{out, \bigstar}(\mathcal{S}_o, \mathcal{S}_b).$ 2 Compute $Q: \chi_Q = A_{ORFC}^{in, \bigstar}(\mathcal{S}_b, \mathcal{S}_o).$ 3 Compute and return $A_{OGC}^{out}(P, Q).$



ORFC algorithm

Experimental Results



- Algorithm to compute $A_{ORFC}^{in, \mathfrak{S}}(\{s_i\}, \mathcal{S}_b)$:
- 1 Compute the value of the map $V_b(s_i)$ for the function $f_{min}^{\mathcal{S}_b}$.
- 2 Remove from the graph G all edges with weight $\leq \varepsilon_{\infty\downarrow}^{in} = V_b(s_i)$, obtaining a new graph G_{\leq} .
- Assign to the object the pixels that belong to the directed connected component of basepoint s_i in the transpose graph of G_{\leq} (i.e., $A_{ORFC}^{in, \mathfrak{S}}(\{s_i\}, \mathcal{S}_b) = \chi_O : O = DCC_{G_{\leq}^T}(s_i)$).
- Algorithm to compute $A_{ORFC}^{out, \mathfrak{S}}(\{s_i\}, \mathcal{S}_b)$: 1 Compute the value of the map $V_b^{\not|}(s_i)$ for the function $f_{min}^{\not|}\mathcal{S}_b$. 2 Remove from the graph G all edges with weight $\leq \varepsilon_{\infty\downarrow}^{out} = V_b^{\not|}(s_i)$, obtaining a new graph G_{\leq} . 3 Assign to the object the pixels that belong to the directed connected component of basepoint s_i in the graph G_{\leq} (i.e., $A_{ORFC}^{out,\mathfrak{S}}(\{s_i\}, \mathcal{S}_b) = \chi_O: O = DCC_{G_{\leq}}(s_i)$).

















