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Small eigenvalues of the Witten Laplacian with Dirichlet boundary conditions: the case with critical points on the boundary

Dorian Le Peutrec* and Boris Nectoux †

Abstract

In this work, we give sharp asymptotic equivalents in the limit $h \rightarrow 0$ of the small eigenvalues of the Witten Laplacian, that is the operator associated with the quadratic form

$$\psi \in H_0^1(\Omega) \mapsto h^2 \int_{\Omega} |\nabla(e^{\frac{1}{h}f}\psi)|^2 e^{-\frac{2}{h}f},$$

where $\bar{\Omega} = \Omega \cup \partial\Omega$ is an oriented C^∞ compact and connected Riemannian manifold with non empty boundary $\partial\Omega$ and $f : \bar{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function. The function f is allowed to admit critical points on $\partial\Omega$, which is the main novelty of this work in comparison with the existing literature.

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1 Introduction

1.1 Setting

Let $(\bar{\Omega}, g)$ be an oriented C^∞ compact and connected Riemannian manifold of dimension d with interior Ω and non empty boundary $\partial\Omega$, and let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ function. Let us moreover denote by d the exterior derivative acting on functions on $\bar{\Omega}$ and by d^* its formal adjoint (called the co-differential) acting on 1-forms (which are naturally identified with vector fields). For any $h > 0$, the semiclassical Witten Laplacian acting on functions on $\bar{\Omega}$ is then the Schrödinger operator defined by

$$\Delta_{f,h} := d_{f,h}^* d_{f,h} = h^2 \Delta_H + |\nabla f|^2 + h \Delta_H f,$$

where $\Delta_H = d^* d$ is the Hodge Laplacian acting on functions, that is the negative of the Laplace–Beltrami operator, and

$$d_{f,h} := h e^{-\frac{f}{h}} d e^{\frac{f}{h}} \quad \text{and} \quad d_{f,h}^* = h e^{\frac{f}{h}} d^* e^{-\frac{f}{h}}$$

are respectively the distorted exterior derivative and co-differential. This operator was originally introduced by Witten in [40] and acts more generally on the algebra of differential forms. Note also the relation

$$\Delta_{f,h} = h e^{-\frac{V}{2h}} (h \Delta_H + \nabla V \cdot \nabla) e^{\frac{V}{2h}} \quad \text{where} \quad V = 2f, \tag{1}$$

where the notation $\nabla V \cdot \nabla$ stands for $g(\nabla V, \nabla \cdot)$. It is then equivalent to study the Witten Laplacian $\Delta_{f,h}$ acting in the flat space $L^2(\Omega) = L^2(\Omega, d\text{Vol}_\Omega)$ or the weighted Laplacian

$$L_{V,h} := h \Delta_H + \nabla V \cdot \nabla = d_{V,h}^* d$$

acting in the weighted space $L^2(\Omega, e^{-\frac{V}{h}} d\text{Vol}_\Omega)$.

Let us now consider the usual self-adjoint Dirichlet realization $\Delta_{f,h}^D$ of the Witten Laplacian $\Delta_{f,h}$ on the Hilbert space $L^2(\Omega)$. Its domain is given by

$$D(\Delta_{f,h}^D) = H^2(\Omega) \cap H_0^1(\Omega),$$

where, for $p \in \mathbb{N}^*$, we denote by $H^p(\Omega)$ the usual Sobolev space with order p and by $H_0^1(\Omega)$ the set made of the functions in $H^1(\Omega)$ with vanishing trace on $\partial\Omega$. We refer for instance to [33] for more material about Sobolev spaces on manifolds with boundary. The operator $\Delta_{f,h}^D$ has a compact resolvent, and thus its spectrum $\sigma(\Delta_{f,h}^D)$ is discrete. This operator is moreover nonnegative since it satisfies:

$$\forall \psi \in D(\Delta_{f,h}^D), \quad \langle \Delta_{f,h}^D \psi, \psi \rangle_{L^2(\Omega)} = \|d_{f,h}\psi\|_{\Lambda^1 L^2(\Omega)}^2 = h^2 \int_{\Omega} |d(e^{\frac{f}{h}}\psi)|^2 e^{-\frac{2f}{h}}, \quad (2)$$

where $\Lambda^1 L^2(\Omega)$ denotes the space of 1-forms in $L^2(\Omega)$ and $\|d_{f,h}\psi\|_{\Lambda^1 L^2(\Omega)}^2 = \int_{\Omega} |d_{f,h}\psi|^2$. Let us also mention here that the (closed) quadratic form $Q_{f,h}$ associated with $\Delta_{f,h}^D$ has domain $H_0^1(\Omega)$ and satisfies, for every $\psi \in H_0^1(\Omega)$,

$$Q_{f,h}(\psi) := Q_{f,h}(\psi, \psi) = \|d_{f,h}\psi\|_{\Lambda^1 L^2(\Omega)}^2 = h^2 \int_{\Omega} |d\psi|^2 + \int_{\Omega} (|\nabla f|^2 + h\Delta_H f) |\psi|^2. \quad (3)$$

Remark 1. *From standard results on elliptic operators, the principal eigenvalue of $\Delta_{f,h}^D$, which is positive since $e^{-\frac{f}{h}} \notin H_0^1(\Omega)$ (see (2)), is moreover non degenerate and any associated eigenfunction has a sign on Ω (see for example [12, 15]).*

1.2 Spectral approach of metastability in statistical physics

The operator $L_{V,h} = \frac{1}{h} e^{\frac{f}{h}} \Delta_{f,h} e^{-\frac{f}{h}}$, where we recall that $V = 2f$ (see (1)), is the infinitesimal generator of the overdamped Langevin process

$$dX_t = -\nabla V(X_t)dt + \sqrt{2h} dB_t \quad (4)$$

which is for instance used to describe the motion of the atoms of a molecule or the diffusion of impurities in a crystal. When the temperature of the system is small, i.e. when $h \ll 1$, the process (4) is typically metastable: it is trapped during a long period of time in a neighborhood of a local minimum of V , called a metastable region, before reaching another metastable region.

When one looks at the process (4) on a metastable region Ω with absorbing boundary conditions, the evolution of observables is in particular given by the semigroup $e^{-tL_{V,h}^D}$, where $L_{V,h}^D := \frac{1}{h} e^{-\frac{f}{h}} \Delta_{f,h}^D e^{-\frac{f}{h}}$ is the Dirichlet realization of the weighted Laplacian $L_{V,h}$ in the weighted space $L^2(\Omega, e^{-\frac{V}{h}} d\text{Vol}_{\Omega})$, see (1). A first description of the metastability of the process (4) with absorbing boundary conditions is then given by the behaviour of the low spectrum of the Dirichlet realization $\Delta_{f,h}^D$ of the Witten Laplacian in the limit $h \rightarrow 0$. The metastable behaviour of the dynamics is more precisely characterized by the fact that the low spectrum of $\Delta_{f,h}^D$ contains exponentially small eigenvalues, i.e. eigenvalues of order $O(e^{-\frac{C}{h}})$ where $C > 0$. The first mathematical results in this direction probably go back to the works of Freidlin-Wentzell in the framework of their large deviation theory developed in the 70's and we refer in particular to their book [14] for an overview on this topic. In this context,

when λ_h is some exponentially small eigenvalue of $\Delta_{f,h}^D$, the limit of $h \ln \lambda_h$ has been investigated assuming that (see [14, Section 6.7])

$$|\nabla f| \neq 0 \text{ on } \partial\Omega. \quad (5)$$

The results of [14] imply in particular that, when $\partial_n f > 0$ on $\partial\Omega$ and Ω contains a unique critical point of f which is non degenerate and is hence the global minimum of f in $\bar{\Omega}$, the principal eigenvalue $\lambda_{1,h}$ of $\Delta_{f,h}^D$ satisfies

$$\lim_{h \rightarrow 0} h \ln \lambda_{1,h} = -2 \left(\min_{\partial\Omega} f - \min_{\bar{\Omega}} f \right).$$

The asymptotic logarithmic behaviour of the low spectrum of $\Delta_{f,h}^D$ has also been studied in [26] dropping the assumption (5). When f and $f|_{\partial\Omega}$ are smooth Morse functions and (5) holds, precise asymptotic formulas in the limit $h \rightarrow 0$ have been given by Helffer-Nier in [17] where they prove in particular that under additional generic hypotheses on the function f , any exponentially small eigenvalue λ_h of $\Delta_{f,h}^D$ satisfies the following Eyring-Kramers type formula when $h \rightarrow 0$:

$$\lambda_h = A h^\gamma e^{-\frac{2}{h}E} (1 + O(h)), \quad (6)$$

where $A > 0$, $E > 0$, and γ are explicit with moreover $\gamma \in \{\frac{1}{2}, 1\}$, and the error term $O(h)$ admits a full asymptotic expansion in h . The constants E 's involved in (6) are the depths of some characteristic wells of the potential f in Ω . The results of [17], obtained by a semiclassical approach, were following similar results obtained in the case without boundary in [5, 6, 20, 28] by a probabilistic approach and in [16] by a semiclassical approach. We also refer to [19, 27] for a generalization of the results obtained in [16] in the case without boundary (see also [2, 3, 21] for related results), to [11]¹ for a generalization of the results obtained in [17] in the case of Dirichlet boundary conditions (see also [4, 24, 25, 30] for related results), and to [23, 26] in the case of Neumann boundary conditions. Finally, we refer to [1] for a comprehensive review on this topic.

1.3 Motivation and results

Motivation. This past few years, several efficient algorithms have been designed to accelerate the sampling of the exit event from a metastable region Ω , such as for instance the Monte Carlo methods [7, 13, 31, 32, 38, 39] or the *accelerated dynamics* algorithms [35–37]. These algorithms rely on a very precise asymptotic understanding of the metastable behaviour of the process $(X_t)_{t \geq 0}$ in a metastable region Ω when $h \rightarrow 0$, and in particular on the validity of Eyring-Kramers type formulas of the type (6) in the limit $h \rightarrow 0$. Moreover, though the hypothesis (5) considered in [10, 17] is generic, in most applications of the accelerated algorithms mentioned above, the domain Ω is the basin of attraction of some local minimum of f for the dynamics $\dot{X} = -\nabla f(X)$ so that the function f admits critical points on the boundary of Ω .

¹This work corresponds to the first part of the preprint [10].

In this work, we precisely aim at giving a precise description of the low spectrum of $\Delta_{f,h}^D$ in the limit $h \rightarrow 0$ of the type (6) in a rather general geometric setting covering the latter case (though we assume Ω to have a smooth boundary). This establishes the first step to precisely describe the metastable behaviour of the overdamped Langevin process (4) with absorbing boundary conditions in Ω when $\partial\Omega$ admits critical points. Though the spectrum of $\Delta_{f,h}^D$ (or equivalently of $L_{V,h}^D$) has been widely studied this past few decades, up to our knowledge, this setting has not been treated in the mathematical literature. Let us point out that the existence of critical points of f on $\partial\Omega$ is a major obstacle to the use of the large deviation techniques, see for instance [14, Chapter 6] and references therein. In this work, we use techniques coming from semiclassical analysis and, in Section 1.4 below, we detail various difficulties arising when considering critical points of f on $\partial\Omega$ with such techniques.

Results. We recall that we assume that $\bar{\Omega}$ is a C^∞ oriented compact and connected Riemannian manifold of dimension d with interior Ω and boundary $\partial\Omega \neq \emptyset$, and that $f : \bar{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function. For $\mu \in \mathbb{R}$, we will use the notation

$$\{f \leq \mu\} = \{x \in \bar{\Omega}, f(x) \leq \mu\}, \quad \{f < \mu\} = \{x \in \bar{\Omega}, f(x) < \mu\},$$

and

$$\{f = \mu\} = \{x \in \bar{\Omega}, f(x) = \mu\}.$$

Moreover, for all $z \in \partial\Omega$, $n_\Omega(z)$ will denote the unit outward vector to $\partial\Omega$ at z . Finally, for $r > 0$ and $y \in \bar{\Omega}$, $B(y, r)$ will denote the open ball of radius r centered in y in $\bar{\Omega}$:

$$B(y, r) := \{z \in \bar{\Omega}, |y - z| < r\},$$

where, for $y \in \bar{\Omega}$, $|y - z|$ is the geodesic distance between y and z in $\bar{\Omega}$.

Since stating our main results, which are Theorems 2 and 3 (see Section 5.4), requires substantial additional material, we just give here simplified (and weaker) versions of these results. We first give a preliminary result stating that the number of small eigenvalues of a Morse function $f : \bar{\Omega} \rightarrow \mathbb{R}$ is the number of its local minima in Ω . This requires the following definition.

Definition 2. *Let us assume that $f : \bar{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function. The set of local minima of f in Ω is then denoted by U_0 and one defines*

$$m_0 := \text{Card}(U_0) \in \mathbb{N}.$$

Theorem 1. *Let us assume that $f : \bar{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function. Then, there exist $c_0 > 0$ and $h_0 > 0$ such that for all $h \in (0, h_0)$:*

$$\dim \text{Ran } \pi_{[0, c_0 h]}(\Delta_{f,h}^D) = \dim \text{Ran } \pi_{(0, e^{-\frac{c_0}{h}})}(\Delta_{f,h}^D) = m_0,$$

where, for a Borel set $E \subset \mathbb{R}$, $\pi_E(\Delta_{f,h}^D)$ denotes the spectral projector associated with $\Delta_{f,h}^D$ and E , and the nonnegative integer m_0 is defined in Definition 2.

Let us emphasize that according to Theorem 1, the potential local minima of f belonging to $\partial\Omega$ do not take part in the number of small eigenvalues of $\Delta_{f,h}^D$ in the limit $h \rightarrow 0$. This preliminary result is expected from works such as [17,18] but we did not find any such statement in the literature in our setting when the boundary admits critical points of f . Theorem 1 will be proven in Section 2.

In the sequel, when $\mathfrak{m}_0 > 0$, we will denote by

$$0 < \lambda_{1,h} < \lambda_{2,h} \leq \dots \leq \lambda_{\mathfrak{m}_0,h}$$

the \mathfrak{m}_0 exponentially small eigenvalues of $\Delta_{f,h}^D$ in the limit $h \rightarrow 0$ (see Theorem 1). The second main result of this paper is Theorem 2, which is stated and proven in Section 5.4. Here is a simplified version of this result, in a less general setting. The notation $\text{Hess } f(z)$ at a critical point z of f below stands for the endomorphism of the tangent space $T_z\bar{\Omega}$ canonically associated with the usual symmetric bilinear form $\text{Hess } f(z)$ on $T_z\bar{\Omega} \times T_z\bar{\Omega}$ via the metric g .

Theorem 2'. *Let us assume that the number of local minima \mathfrak{m}_0 of the Morse function f is positive, that $f|_{\partial\Omega}$ has only non degenerate local minima, and that at any saddle point (i.e. critical point of index 1) z of f which belongs to $\partial\Omega$, $\mathfrak{n}_\Omega(z)$ is an eigenvector of $\text{Hess } f(z)$ associated with its unique negative eigenvalue. Then, there exists $C > 0$ such that one has in the limit $h \rightarrow 0$:*

$$\forall j \in \{1, \dots, \mathfrak{m}_0\}, \quad \frac{1}{C} h^{\gamma_j} e^{-\frac{2}{h}E_j} \leq \lambda_{j,h} \leq C h^{\gamma_j} e^{-\frac{2}{h}E_j}, \quad (7)$$

where, for $j \in \{1, \dots, \mathfrak{m}_0\}$, $A_j > 0$, $E_j > 0$, and γ_j are explicit with moreover $\gamma_j \in \{\frac{1}{2}, 1\}$.

The above constants E_j 's are the depths of some characteristic wells of the potential f in Ω which are defined through the map \mathbf{j} constructed in Section 3. Note that they give the logarithmic equivalents of the small eigenvalues of $\Delta_{f,h}^D$ since the relation (8) obviously implies:

$$\forall j \in \{1, \dots, \mathfrak{m}_0\}, \quad \lim_{h \rightarrow 0} h \ln \lambda_{1,h} = -2E_j.$$

Note also that when Ω is the basin of attraction of some local minimum (or of some family of local minima) of some Morse function f for the flow of $\dot{X} = -\nabla f(X)$ and z is a saddle point of f which belongs to $\partial\Omega$, the following holds: $\partial\Omega$ is a smooth manifold of dimension $d-1$ near z and $\mathfrak{n}_\Omega(z)$ is an eigenvector of $\text{Hess } f(z)$ associated with its unique negative eigenvalue. More precisely, $\partial\Omega$ coincides with the stable manifold of z for the dynamics $\dot{X} = -\nabla f(X)$ near the saddle point z (see (9) in Section 2). The related hypothesis in the statement of Theorem 2' (and of Theorem 2) then just requires that the boundary $\partial\Omega$ of our actual domain Ω is, at z , tangent to the stable manifold of z .

Finally, the last main result of this work is Theorem 3, which is stated and proven in Section 5.4. It states that, under the hypotheses of Theorem 2, which, we recall,

are a little more general than the ones of Theorem 2', plus additional hypotheses on the separation of the characteristic wells of f which are defined through the map \mathbf{j} constructed in Section 3, one has in the limit $h \rightarrow 0$ sharp asymptotic estimates of the type (6) on all or part of the smallest eigenvalues of $\Delta_{f,h}^D$. To be more precise, we state below a simple consequence of Theorem 3 which can be stated with the material introduced in this section.

Theorem 3'. *Let us assume that f is a Morse function, that $\{f < \min_{\partial\Omega} f\}$ is non empty, connected, contains all the local minima of f in Ω , and that*

$$\partial\{f < \min_{\partial\Omega} f\} \cap \partial\Omega = \overline{\{f < \min_{\partial\Omega} f\}} \cap \partial\Omega = \{z_1, \dots, z_N\},$$

where $N \in \mathbb{N}^*$ and, for $k \in \{1, \dots, N\}$, z_k is a saddle point of f such that $\mathbf{n}_\Omega(z_k)$ is an eigenvector of $\text{Hess } f(z_k)$ associated with its unique negative eigenvalue $\lambda(z_k)$. The principal eigenvalue of $\Delta_{f,h}^D$ then satisfies the following Eyring-Kramers formula in the limit $h \rightarrow 0$:

$$\lambda_{1,h} = \frac{2}{\pi} \frac{\sum_{k=1}^N |\lambda(z_k)| |\det \text{Hess } f(z_k)|^{-\frac{1}{2}}}{\sum_{y \in \arg \min_{\Omega} f} (\det \text{Hess } f(y))^{-\frac{1}{2}}} h e^{-\frac{2}{h}(\min_{\partial\Omega} f - \min_{\Omega} f)} (1 + O(\sqrt{h})). \quad (8)$$

It follows moreover from our analysis that the error term $O(\sqrt{h})$ in (8) is optimal (see Remark 38 below) but we do not prove in this work the possible existence of a full asymptotic expansion of the low spectrum of $\Delta_{f,h}^D$. Let us also mention that adopting the 1-form approach (see the following subsection for details in this connection), one could obtain, as in [27] where the author treats the case of general Morse functions in the case without boundary, the existence of an Eyring-Kramers type formula for each small eigenvalue of $\Delta_{f,h}^D$ under the assumptions of Theorem 2'. This would however require a substantially finer analysis of the wells of the potential f in the spirit of [27] since in the general case, some tunneling effect between the characteristic wells of f mixes their corresponding pre-exponential factors. We refer to [27] for more details in this connection.

1.4 Strategy and organization of the paper

In works such as [10, 16, 17, 19, 23, 27], a part of the analysis relies on the construction of 0-forms (i.e. functions) quasi-modes supported in some characteristic wells of the potential f and of 1-forms quasi-modes supported near the saddle points of f , and, in [10, 17, 23], near its so-called generalized saddle points on the boundary. Very accurate WKB approximations of these local 1-forms quasi-modes then finally lead to the asymptotic expansions of the low spectrum of the Witten Laplacian acting on functions. This approach is based on the supersymmetric structure of the latter operator, once restricted to the interplay between 0- and 1-forms.

Near the generalized saddle points on the boundary as considered in [17, 23], where one recalls that $|\nabla f| \neq 0$ there and actually where the normal derivative $\partial_{\mathbf{n}_\Omega} f$ does not

vanish, this construction means solving non characteristic transport equations with prescribed initial boundary conditions, see in particular [17, 22, 23]. Near a usual saddle point z in Ω (i.e. a critical point z with index 1), this construction follows from the work [18] of Helffer-Sjöstrand and means solving transport equations which are degenerate at z (see in particular Section 2 there). In this case, the problem is well-posed only for prescribed initial condition at the single point z . In particular, when one drops the assumption (5) and z is a usual saddle point which belongs to $\partial\Omega$, the corresponding transport equations, which are the same as for interior saddle points, are uniquely solved as in [18], but the resulting WKB ansatz does not in general satisfy the required boundary conditions, except its leading term when the boundary $\partial\Omega$ has a specific shape near z . To be more precise, and to make the connection with the hypotheses of Theorems 2' and 3' (and Theorems 2 and 3), the leading term of this WKB ansatz satisfies the required boundary conditions if and only if $\partial\Omega$ coincides near z with the stable manifold of z for the dynamics $\dot{X} = -\nabla f(X)$ (see (9) in Section 2). This compatibility condition imposes in particular that $\mathfrak{n}_\Omega(z)$ spans the negative direction of $\text{Hess } f(z)$. Note in passing that this condition is natural regarding the accelerated dynamics algorithms [35–37]. The fact that the remaining part of the WKB ansatz does in general not satisfy the required boundary conditions for a compatible boundary $\partial\Omega$ arises from the curvature of this boundary.

The above considerations show that, when $z \in \partial\Omega$ is a saddle point of f and $\mathfrak{n}_\Omega(z)$ does not span the negative direction of $\text{Hess } f(z)$, the classical WKB ansatz constructed near z will not be an accurate approximation of the local 1-form quasi-mode associated with z . They also imply that the potential existence of full asymptotic expansions of the small eigenvalues of $\Delta_{f,h}^D$ will in general not follow from the existence of these WKB ansatz when f admits saddle points on the boundary. Moreover, we expect that the sharp asymptotic equivalents given by (8) are not valid in general when $\mathfrak{n}_\Omega(z)$ does not span the negative direction of $\text{Hess } f(z)$ at the relevant saddle points $z \in \partial\Omega$. In the latter case, we expect that the corresponding possible sharp asymptotic equivalents should also rely on the angle between $\mathfrak{n}_\Omega(z)$ and the negative direction of $\text{Hess } f(z)$.

In this work, we follow a different strategy based on the constructions of very accurate quasi-modes for $\Delta_{f,h}^D$. This approach, which is partly inspired by the quasi-modal construction made in [9] (see also [5, 21, 30]), means a careful construction of these functions quasi-modes around the relevant (possibly generalized) saddle points z of f , whereas these points were not in the supports of the corresponding quasi-modes constructed in [10, 16, 17, 19, 23, 27]. One advantage of this method is to avoid a careful study of the Witten Laplacian acting on 1-forms which would finally lead to slightly more stringent hypotheses on f and on $f|_{\partial\Omega}$, that is precisely to the hypotheses made in the statement of Theorem 2'. Nevertheless, when one does not work with the Witten Laplacian acting on 1-forms, one cannot hope in general proving a full asymptotic expansion of the low spectrum of $\Delta_{f,h}^D$ with the techniques used in this work.

The rest of the paper is organized as follows. In Section 2, we prove Theorem 1 about the number of small eigenvalues of $\Delta_{f,h}^D$. This is done using spectral and localization arguments. Then, in Section 3, we construct the map \mathbf{j} characterizing the relevant wells of the potential function f . This permits to construct our very accurate quasi-modes in Section 4 and then to state and prove our main results, namely Theorems 2 and 3, in Section 5. As in [10, 16, 17, 19, 23, 27], the analysis of the precise asymptotic behaviour of the low spectrum of $\Delta_{f,h}^D = d_{f,h}^{D,*} d_{f,h}^D$ is finally reduced to the computation of the small singular values of $d_{f,h}^D$.

2 On the number of small eigenvalues of $\Delta_{f,h}^D$

This section is dedicated to the proof of Theorem 1. Before going into its proof, we briefly recall basic facts about smooth (Morse) functions on a manifold with boundary $\bar{\Omega} = \Omega \cup \partial\Omega$.

Let $z \in \partial\Omega$. Let us consider a neighborhood V_z of z in $\bar{\Omega}$ and a coordinate system $p \in V_z \mapsto x = (x', x_d) \in \mathbb{R}_-^d = \mathbb{R}^{d-1} \times \mathbb{R}_-$ such that: $x(z) = 0$, $\{p \in V_z, x_d(p) < 0\} = \Omega \cap V_z$ and $\{p \in V_z, x_d(p) = 0\} = \partial\Omega \cap V_z$. By definition, the function f is C^∞ on V_z if, in the x -coordinates, the function $f : x(V_z) \rightarrow \mathbb{R}$ is the restriction of a C^∞ function defined on an open subset \mathcal{O} of \mathbb{R}^d containing $x(V_z)$. Moreover, $z \in \partial\Omega$ is a non degenerate critical point of $f : \bar{\Omega} \rightarrow \mathbb{R}$ of index $p \in \{0, \dots, d\}$ if it is a non degenerate critical point of index p for this extension. Notice that this definition is independent of the choice of the extension. A C^∞ function $f : \bar{\Omega} \rightarrow \mathbb{R}$ is then said to be a Morse function if all its critical points in $\bar{\Omega}$ are non degenerate. In the following, we will also say that $z \in \bar{\Omega}$ is a saddle point of the Morse function f if it is a critical point of f with index 1. Lastly, for a critical point $z \in \bar{\Omega}$ of the Morse function $f : \bar{\Omega} \rightarrow \mathbb{R}$, the sets $W^+(z)$ and $W^-(z)$ will respectively denote the stable and unstable manifold of z for the dynamics $\dot{X} = -\nabla f(X)$. In other words, denoting by $X_y(t)$ the solution to $\frac{d}{dt} X_y(t) = -\nabla f(X_y(t))$ with initial condition $X_y(0) = y$, one has:

$$W^\pm(z) = \{y \in \bar{\Omega}, \lim_{t \rightarrow \pm\infty} X_y(t) = z\}. \quad (9)$$

2.1 Preliminary results

In order to prove Theorem 1, one will make use of the following proposition which results from [18, Théorème 1.4].

Proposition 3. *Let $\bar{\mathcal{O}}$ be an oriented C^∞ compact and connected Riemannian manifold of dimension d with interior \mathcal{O} and non empty boundary $\partial\mathcal{O}$, let $\phi : \bar{\mathcal{O}} \rightarrow \mathbb{R}$ be a C^∞ Morse function, and let x_0 be a critical point of ϕ in \mathcal{O} with index $\ell \in \{0, \dots, d\}$ such that x_0 is the only critical point of ϕ in $\bar{\mathcal{O}}$. Then, the Dirichlet realization $\Delta_{\phi,h}^D(\mathcal{O})$ of the Witten Laplacian acting on functions on \mathcal{O} satisfies the following*

estimate: there exist $\eta_0 > 0$ and $h_0 > 0$ such that for all $h \in (0, h_0)$,

$$\text{Ran } \pi_{[0, \eta_0 h]}(\Delta_{f, h}^D(\mathbf{O})) = \delta_{\ell, 0}.$$

The following result is a direct consequence of Proposition 3.

Corollary 4. *Let $\bar{\mathbf{O}}$, ϕ , x_0 , and $\ell \in \{0, \dots, d\}$ be as in Proposition 3. Let us assume that $\ell = 0$, i.e. that x_0 is a local minimum of ϕ in \mathbf{O} , and that ϕ only attains its minimal value on $\bar{\mathbf{O}}$ at x_0 . Let moreover, for every h small enough, $\Psi \geq 0$ be the $L^2(\mathbf{O})$ -normalized eigenfunction of $\Delta_{f, h}^D(\mathbf{O})$ associated with its unique eigenvalue λ_h in $(0, \eta_0 h]$ (see Proposition 3 and Remark 1). Lastly, let $\xi \in C_c^\infty(\mathbf{O}, [0, 1])$ be a cut-off function such that $\xi = 1$ in a neighborhood of x_0 in \mathbf{O} . Then, defining $\chi := \frac{\xi e^{-\frac{1}{h}\phi}}{\|\xi e^{-\frac{1}{h}\phi}\|_{L^2(\mathbf{O})}}$, there exists $c > 0$ such that for every h small enough:*

$$\Psi = \chi + O(e^{-\frac{c}{h}}) \text{ in } L^2(\mathbf{O}) \quad \text{and} \quad 0 < \lambda_h \leq \|d_{\phi, h}\chi\|_{\Lambda^1 L^2(\mathbf{O})}^2 \leq e^{-\frac{c}{h}}. \quad (10)$$

Proof. The proof of (10) is standard but we give it for the sake of completeness. As in the statement of Corollary 4, let us define

$$\chi := \frac{\xi e^{-\frac{1}{h}\phi}}{\|\xi e^{-\frac{1}{h}\phi}\|_{L^2(\mathbf{O})}}.$$

From the definition of ξ and the Laplace method together with the fact that ϕ only attains its minimal value on $\bar{\mathbf{O}}$ at x_0 , it holds

$$\|\xi e^{-\frac{1}{h}\phi}\|_{L^2(\mathbf{O})}^2 = \frac{(\pi h)^{\frac{d}{2}}}{\sqrt{\det \text{Hess } \phi(x_0)}} e^{-\frac{2}{h}\phi(x_0)} (1 + O(h)).$$

According to Proposition 3, there exist $\eta_0 > 0$ and $h_0 > 0$ such that for all $h \in (0, h_0)$, $\pi_{[0, \eta_0 h]}(\Delta_{f, h}^D(\mathbf{O}))$ is the orthogonal projector on $\text{Span}\{\Psi\}$. Moreover, using the following spectral estimate, valid for any nonnegative self-adjoint operator $(T, D(T))$ on a Hilbert space $(\mathcal{H}, \|\cdot\|)$ with associated quadratic form $(q_T, Q(T))$,

$$\forall b > 0, \forall u \in Q(T), \|\pi_{[b, +\infty)}(T) u\|^2 \leq \frac{q_T(u)}{b}, \quad (11)$$

it holds (see (2) and (3))

$$\left\| \chi - \pi_{[0, \eta_0 h]}(\Delta_{\phi, h}^D(\mathbf{O}))\chi \right\|_{L^2(\mathbf{O})}^2 \leq \frac{\|d_{\phi, h}\chi\|_{\Lambda^1 L^2(\mathbf{O})}^2}{\eta_0 h} = \frac{h}{\eta_0} \frac{\int_{\mathbf{O}} |d\xi|^2 e^{-\frac{2}{h}\phi}}{\|\xi e^{-\frac{1}{h}\phi}\|_{L^2(\mathbf{O})}^2}.$$

Hence, since $\xi = 1$ in a neighborhood of x_0 and thus, for some $c > 0$, $\phi(y) \geq \phi(x_0) + c$ for every $y \in \text{supp } d\xi$, one has for every $h > 0$ small enough,

$$\|d_{\phi, h}\chi\|_{\Lambda^1 L^2(\mathbf{O})}^2 \leq e^{-\frac{c}{h}} \quad \text{and} \quad \left\| \chi - \pi_{[0, \eta_0 h]}(\Delta_{\phi, h}^D(\mathbf{O}))\chi \right\|_{L^2(\mathbf{O})}^2 \leq e^{-\frac{c}{h}}, \quad (12)$$

where $c > 0$ is independent of h . Since $\|\chi\|_{L^2(\mathcal{O})} = 1$, the first relation in (12) together with the Min-Max principle leads to (see (2))

$$\lambda_h \leq \langle \Delta_{\phi,h}^D(\mathcal{O})\chi, \chi \rangle_{L^2(\mathcal{O})} = \|d_{\phi,h}\chi\|_{\Lambda^1 L^2(\mathcal{O})}^2 \leq e^{-\frac{c}{h}}.$$

Moreover, using the second relation in (12) and the Pythagorean theorem, one obtains for every $h > 0$ small enough:

$$\|\pi_{[0,\eta_0 h]}(\Delta_{\phi,h}^D(\mathcal{O}))\chi\|_{L^2(\mathcal{O})} = 1 + O(e^{-\frac{c}{h}}). \quad (13)$$

In conclusion, from (12), (13), and since χ and Ψ are nonnegative, it holds, in $L^2(\mathcal{O})$, for some $c > 0$ and every $h > 0$ small enough:

$$\Psi = \frac{\pi_{[0,\eta_0 h]}(\Delta_{\phi,h}^D(\mathcal{O}))\chi}{\|\pi_{[0,\eta_0 h]}(\Delta_{\phi,h}^D(\mathcal{O}))\chi\|_{L^2(\mathcal{O})}} = \chi + O(e^{-\frac{c}{h}}).$$

This concludes the proof of (10) and then the proof of Corollary 4. ■

We are now in position to prove Theorem 1.

2.2 Proof of Theorem 1

Let $\{x_1, \dots, x_n\}$ be the set of the critical points of f in $\bar{\Omega}$, i.e.

$$\{x_1, \dots, x_n\} = \{x \in \bar{\Omega}, |\nabla f(x)| = 0\}.$$

From the preliminary discussion in the beginning of Section 2, there exist an oriented C^∞ compact and connected Riemannian manifold $\tilde{\Omega}$ of dimension d with interior $\tilde{\Omega}$ and boundary $\partial\tilde{\Omega}$, and a C^∞ Morse function $\tilde{f} : \tilde{\Omega} \rightarrow \mathbb{R}$ such that

$$\tilde{f}|_{\tilde{\Omega}} = f, \quad \bar{\Omega} \subset \tilde{\Omega} \quad \text{and} \quad \{x_1, \dots, x_n\} \subset \tilde{\Omega}.$$

We recall that m_0 denotes the number of local minima of f in Ω (see Definition 2), and thus that $0 \leq m_0 \leq n$. When $m_0 > 0$, the elements x_1, \dots, x_n are moreover ordered such that

$$\{x_1, \dots, x_{m_0}\} = \mathbf{U}_0.$$

In addition, one introduces for every $j \in \{1, \dots, m_0\}$ a smooth open neighborhood \mathcal{O}_j of x_j such that $\bar{\mathcal{O}}_j \subset \Omega$ and such that x_j is the only critical point of f in $\bar{\mathcal{O}}_j$ as well as the only point where f attains its minimal value in $\bar{\mathcal{O}}_j$. Similarly, when $x_j \in \Omega$ is not a local minimum of f , one introduces a smooth open neighborhood \mathcal{O}_j of x_j such that $\bar{\mathcal{O}}_j \subset \Omega$ and such that x_j is the only critical point of f in $\bar{\mathcal{O}}_j$. Lastly, when $x_j \in \partial\Omega$, one now introduces a smooth open neighborhood \mathcal{O}_j of x_j in $\tilde{\Omega}$ such that $\bar{\mathcal{O}}_j \subset \tilde{\Omega}$ and such that x_j is the only critical point of \tilde{f} in $\bar{\mathcal{O}}_j$. When such a x_j is a local minimum of f , the set \mathcal{O}_j is moreover chosen small enough such that the minimal value of f in $\bar{\mathcal{O}}_j$ is only attained at x_j . Let us also introduce a quadratic partition of unity $(\chi_j)_{j \in \{1, \dots, n+1\}}$ such that:

1. For all $j \in \{1, \dots, n+1\}$, $\chi_j \in C^\infty(\widetilde{\Omega}, [0, 1])$ and $\sum_{j=1}^{n+1} \chi_j^2 = 1$ on $\widetilde{\Omega}$.
2. For all $j \in \{1, \dots, n\}$, $\chi_j = 1$ near x_j and $\text{supp } \chi_j \subset \mathbf{O}_j$. In particular, $\text{supp } \chi_j \subset \Omega$ when $x_j \in \Omega$.
3. For all $(i, j) \in \{1, \dots, n\}^2$, $i \neq j$ implies $\text{supp } \chi_i \cap \text{supp } \chi_j = \emptyset$.

In the following, we will also use the so-called IMS localization formula (see for example [8]): for all $\psi \in H_0^1(\Omega)$, it holds

$$Q_{f,h}(\psi) = \sum_{j=1}^{n+1} Q_{f,h}(\chi_j \psi) - \sum_{j=1}^{n+1} h^2 \|\nabla \chi_j \psi\|_{L^2(\Omega)}^2, \quad (14)$$

where $Q_{f,h}$ is the quadratic form defined in (3).

Step 1. Let us first show that there exists $c_0 > 0$ such that for every h small enough, it holds

$$\dim \text{Ran } \pi_{(0, e^{-\frac{c_0}{h}})}(\Delta_{f,h}^D) \geq \mathbf{m}_0. \quad (15)$$

This relation is obvious when $\mathbf{m}_0 = 0$. When $\mathbf{m}_0 > 0$, the family $(\overline{\mathbf{O}}_j, f|_{\overline{\mathbf{O}}_j}, x_j)$ satisfies, for every $j \in \{1, \dots, \mathbf{m}_0\}$, the hypotheses of Corollary 4. Then, according to (10), the function

$$\psi_j := \frac{\chi_j e^{-\frac{f}{h}}}{\|\chi_j e^{-\frac{f}{h}}\|_{L^2(\mathbf{O}_j)}}$$

satisfies, for some $c_j > 0$ and every $h > 0$ small enough (see (3)),

$$Q_{f,h}(\psi_j) \leq e^{-\frac{c_j}{h}}.$$

Since the ψ_j 's, $j \in \{1, \dots, \mathbf{m}_0\}$, are unitary in $L^2(\Omega)$ and have disjoint supports, it follows from the Min-Max principle that $\Delta_{f,h}^D$ admits at least \mathbf{m}_0 exponentially small eigenvalues when $h \rightarrow 0$, which proves (15).

Step 2. Let us now show that there exists $c'_0 > 0$ such that for every h small enough, it holds

$$\dim \text{Ran } \pi_{[0, c'_0 h]}(\Delta_{f,h}^D) \leq \mathbf{m}_0. \quad (16)$$

According to the Min-Max principle, it is sufficient to show that there exist $h_0 > 0$ and $C > 0$ such that for every $h \in (0, h_0]$, there exist $u_1, \dots, u_{\mathbf{m}_0}$ in $L^2(\Omega)$ such that for any $\psi \in D(\Delta_{f,h}^D) = H_0^1(\Omega)$, it holds

$$Q_{f,h}(\psi) \geq Ch \|\psi\|_{L^2(\Omega)}^2 - \sum_{i=1}^{\mathbf{m}_0} \langle \psi, u_i \rangle_{L^2(\Omega)}^2. \quad (17)$$

Analysis on $\text{supp } \chi_{n+1}$.

Since $\text{supp } \chi_{n+1} \cap \overline{\Omega}$ does not meet $\{x_1, \dots, x_n\}$, there exists $C > 0$ such that $|\nabla f| \geq$

$3C$ on $\text{supp } \chi_{n+1} \cap \bar{\Omega}$. It then follows from (3) that there exists $C > 0$ such that for every h small enough and for every $\psi \in H_0^1(\Omega)$, it holds

$$\begin{aligned} Q_{f,h}(\chi_{n+1}\psi) &\geq \langle \chi_{n+1}\psi, (|\nabla f|^2 + h\Delta_H f)\chi_{n+1}\psi \rangle_{L^2(\Omega)} \\ &\geq 2C \|\chi_{n+1}\psi\|_{L^2(\Omega)}^2. \end{aligned} \quad (18)$$

Analysis on $\text{supp } \chi_j$, $j \in \{1, \dots, m_0\}$.

We assume here that $m_0 > 0$. We recall that for every $j \in \{1, \dots, m_0\}$, $(\bar{O}_j, f|_{\bar{O}_j}, x_j)$ satisfies the hypotheses of Corollary 4, and we denote, for $h > 0$, by $\Psi_j \geq 0$ the $L^2(O_j)$ -normalized eigenfunction of $\Delta_{f,h}^D(O_j)$ associated with its principal eigenvalue λ_h^j (which is positive, and exponentially small when $h \rightarrow 0$). It then follows from Proposition 3 and Corollary 4 that for some $C > 0$ and every $h > 0$ small enough, it holds, for every $j \in \{1, \dots, m_0\}$ and for every $\psi \in H_0^1(\Omega)$,

$$\begin{aligned} Q_{f,h}(\chi_j\psi) &\geq \lambda_h^j \langle \chi_j\psi, \Psi_j \rangle_{L^2(\Omega)}^2 + 2Ch \|\chi_j\psi - \langle \chi_j\psi, \Psi_j \rangle \Psi_j\|_{L^2(\Omega)}^2 \\ &\geq 2Ch \|\chi_j\psi\|_{L^2(\Omega)}^2 - 2Ch \langle \chi_j\psi, \Psi_j \rangle_{L^2(\Omega)}^2 \\ &= 2Ch \|\chi_j\psi\|_{L^2(\Omega)}^2 - \langle \psi, u_j \rangle_{L^2(\Omega)}^2, \end{aligned} \quad (19)$$

where one has defined $u_j := \sqrt{2Ch} \chi_j \Psi_j$.

Analysis on $\text{supp } \chi_j$, when $x_j \in \Omega$ is not a local minimum of f .

In this case, applying Proposition 3 with O_j and $\Delta_{f,h}^D(O_j)$, it follows that for some $C > 0$ and every $h > 0$ small enough, it holds, for every $\psi \in H_0^1(\Omega)$,

$$Q_{f,h}(\chi_j\psi) \geq 2Ch \|\chi_j\psi\|_{L^2(\Omega)}^2. \quad (20)$$

Analysis on $\text{supp } \chi_j$, when $x_j \in \partial\Omega$ is not a local minimum of f .

In this case, applying as previously Proposition 3 with O_j but here with $\Delta_{\tilde{f},h}^D(O_j)$ and denoting by $Q_{\tilde{f},h,O_j}$ its associated quadratic form, it follows that for some $C > 0$ and every $h > 0$ small enough, it holds, for every $\psi \in H_0^1(\tilde{\Omega})$,

$$Q_{\tilde{f},h,O_j}(\chi_j\psi) = \|d_{\tilde{f},h}\chi_j\psi\|_{\Lambda^1 L^2(O_j)}^2 \geq 2Ch \|\chi_j\psi\|_{L^2(\tilde{\Omega})}^2.$$

Let us now consider the application $\psi \in L^2(\Omega) \mapsto \tilde{\psi} \in L^2(\tilde{\Omega})$, where $\tilde{\psi}$ extends ψ on $\tilde{\Omega}$ by $\tilde{\psi}|_{\tilde{\Omega} \setminus \bar{\Omega}} = 0$. Since $\tilde{\psi}$ belongs to $H_0^1(\tilde{\Omega})$ for every $\psi \in H_0^1(\Omega)$ with moreover $(d\tilde{\psi})|_{\tilde{\Omega} \setminus \bar{\Omega}} = 0$, it holds, for every h small enough and for every $\psi \in H_0^1(\Omega)$,

$$\begin{aligned} Q_{f,h}(\chi_j\psi) &= \|d_{f,h}(\chi_j\psi)\|_{\Lambda^1 L^2(\Omega)}^2 = \|d_{\tilde{f},h}(\chi_j\tilde{\psi})\|_{\Lambda^1 L^2(O_j)}^2 \\ &\geq 2Ch \|\chi_j\tilde{\psi}\|_{L^2(\tilde{\Omega})}^2 = 2Ch \|\chi_j\psi\|_{L^2(\Omega)}^2. \end{aligned} \quad (21)$$

Analysis on $\text{supp } \chi_j$, when $x_j \in \partial\Omega$ is a local minimum of f .

Let us now consider, as previously, the extension map $\psi \in H_0^1(\Omega) \mapsto \tilde{\psi} \in H_0^1(\tilde{\Omega})$ by 0 outside $\bar{\Omega}$, and let $\Psi_j \geq 0$ be the $L^2(\mathcal{O}_j)$ -normalized eigenfunction of $\Delta_{\tilde{f},h}^D(\mathcal{O}_j)$ associated with its principal eigenvalue λ_h^j (see Remark 1). Then, according to Proposition 3, one has for some $C > 0$, for every h small enough, and for every $\psi \in H_0^1(\Omega)$,

$$\begin{aligned} Q_{f,h}(\chi_j \psi) &= Q_{\tilde{f},h,\mathcal{O}_j}(\chi_j \tilde{\psi}) \\ &\geq \lambda_h^j \langle \chi_j \tilde{\psi}, \Psi_j \rangle_{L^2(\mathcal{O}_j)}^2 + 6Ch \|\chi_j \tilde{\psi} - \langle \chi_j \tilde{\psi}, \Psi_j \rangle \Psi_j\|_{L^2(\mathcal{O}_j)}^2 \\ &\geq 6Ch \|\chi_j \tilde{\psi}\|_{L^2(\mathcal{O}_j)}^2 - 6Ch \langle \chi_j \tilde{\psi}, \Psi_j \rangle_{L^2(\mathcal{O}_j)}^2 \\ &= 6Ch \|\chi_j \psi\|_{L^2(\Omega)}^2 - 6Ch \langle \chi_j \psi, \Psi_j \rangle_{L^2(\Omega \cap \mathcal{O}_j)}^2. \end{aligned} \quad (22)$$

Moreover, applying Corollary 4 with $\mathcal{O} = \mathcal{O}_j$, $\phi = \tilde{f}|_{\overline{\mathcal{O}_j}}$, and $\xi = \chi_j$, it follows from (10) that for every h small enough, one has

$$\|\Psi_j\|_{L^2(\Omega \cap \mathcal{O}_j)}^2 = \frac{\|\chi_j e^{-\frac{1}{h}\tilde{f}}\|_{L^2(\Omega \cap \mathcal{O}_j)}^2}{\|\chi_j e^{-\frac{1}{h}\tilde{f}}\|_{L^2(\mathcal{O}_j)}^2} + O(e^{-\frac{c}{h}}).$$

From the Laplace method together with the fact that \tilde{f} only attains its minimal value on $\overline{\mathcal{O}_j}$ at x_j , it then holds in the limit $h \rightarrow 0$:

$$\|\Psi_j\|_{L^2(\Omega \cap \mathcal{O}_j)}^2 = \frac{1}{2} + o(1).$$

According to (22), this implies, using the Cauchy-Schwarz inequality

$$\langle \chi_j \psi, \Psi_j \rangle_{L^2(\Omega)}^2 \leq \|\chi_j \psi\|_{L^2(\Omega)}^2 \|\Psi_j\|_{L^2(\Omega \cap \mathcal{O}_j)}^2,$$

that for some $C > 0$, for every h small enough, and for every $\psi \in H_0^1(\Omega)$, it holds:

$$Q_{f,h}(\chi_j \psi) \geq 2Ch \|\chi_j \psi\|_{L^2(\Omega)}^2. \quad (23)$$

Conclusion.

Adding the estimates (18) to (21) and (23), we deduce from the IMS localization formula (14) that there exists $C > 0$ such that for every h small enough and for every $\psi \in H_0^1(\Omega)$, it holds

$$\begin{aligned} Q_{f,h}(\psi) &= \sum_{j=1}^{n+1} Q_{f,h}(\chi_j \psi) - \sum_{j=1}^{n+1} h^2 \|\nabla \chi_j \psi\|_{L^2(\Omega)}^2 \\ &\geq \sum_{j=1}^{n+1} 2Ch \|\chi_j \psi\|_{L^2(\Omega)}^2 - \sum_{j=1}^{m_0} \langle \psi, u_j \rangle_{L^2(\Omega)}^2 + O(h^2) \|\psi\|_{L^2(\Omega)}^2 \\ &\geq Ch \|\chi_j \psi\|_{L^2(\Omega)}^2 - \sum_{j=1}^{m_0} \langle \psi, u_j \rangle_{L^2(\Omega)}^2, \end{aligned}$$

where, for $j \in \{1, \dots, m_0\}$, we recall that $u_j = \sqrt{2Ch} \chi_j \Psi_j$. This implies the relation (17) and then (16), which concludes the proof of Theorem 1.

3 Study of the characteristic wells of the function f

In this section, one constructs two maps, \mathbf{j} and \mathbf{C}_j . The map \mathbf{j} associates each local minimum of f in Ω with a set of relevant saddle points, here called *separating saddle points*, of f in $\overline{\Omega}$, and the map \mathbf{C}_j associates each local minimum of f in Ω with a characteristic well, here called a *critical component*, of f in Ω (see Definition 16 below). Our construction is strongly inspired by a similar construction made in [19] in the case without boundary, where the notions of separating saddle point and of critical component were defined in this setting. The depths of the wells $\mathbf{C}_j(x)$, $x \in \mathbf{U}_0$, which can be expressed in terms of $\mathbf{j}(x)$, will finally give, up to some factor -2 , the logarithmic equivalents of the small eigenvalues of $\Delta_{f,h}^D$ (see indeed Theorems 2' and 2). The maps \mathbf{j} and \mathbf{C}_j will also be used in the next section to define accurate quasi-modes for $\Delta_{f,h}^D$.

This section is organised as follows. In Section 3.1, one defines the *principal (characteristic) wells* of the function f in Ω . Then, in Section 3.2, one defines the separating saddle points of f in $\overline{\Omega}$ and the critical components of f . Finally, Section 3.3 is dedicated to the constructions of the maps \mathbf{j} and \mathbf{C}_j .

3.1 Principal wells of f in Ω

Definition 5. Let $f : \overline{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function such that $\mathbf{U}_0 \neq \emptyset$. For all $x \in \mathbf{U}_0$ (see Definition 2) and $\lambda > f(x)$, one defines

$$\mathbf{C}(\lambda, x) \text{ as the connected component of } \{f < \lambda\} \text{ in } \overline{\Omega} \text{ containing } x.$$

Moreover, for every $x \in \mathbf{U}_0$, one defines

$$\lambda(x) := \sup\{\lambda > f(x) \text{ such that } \mathbf{C}(\lambda, x) \cap \partial\Omega = \emptyset\} \quad \text{and} \quad \mathbf{C}(x) := \mathbf{C}(\lambda(x), x).$$

Since for every $x \in \mathbf{U}_0$, x is a non degenerate local minimum of f in Ω , notice that the real value $\lambda(x)$ is well defined and belongs to $(f(x), +\infty)$. The *principal wells* of the function f in Ω are then defined as follows.

Definition 6. Let $f : \overline{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function such that $\mathbf{U}_0 \neq \emptyset$. The set

$$\mathcal{C} = \{\mathbf{C}(x), x \in \mathbf{U}_0\}$$

is called the set of *principal wells* of the function f in Ω . The number of *principal wells* is denoted by

$$\mathbf{N}_1 := \text{Card}(\mathcal{C}) \in \{1, \dots, \mathbf{m}_0\}.$$

Finally, the *principal wells* of f in Ω (i.e. the elements of \mathcal{C}) are denoted by:

$$\mathcal{C} = \{\mathbf{C}_{1,1}, \dots, \mathbf{C}_{1,\mathbf{N}_1}\}.$$

In Remark 18 below, one explains why the elements of \mathcal{C} are called the *principal wells* of f in Ω . Notice that they obviously satisfy $\partial\mathbf{C}(x) \subset \{f = \lambda(x)\}$ for every $x \in \mathbf{U}_0$. These wells satisfy moreover the following property.

Proposition 7. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function such that $U_0 \neq \emptyset$ and let $\mathcal{C} = \{C_{1,1}, \dots, C_{1,N_1}\}$ be the set of its principal wells defined in Definition 6. Then, for every $k \in \{1, \dots, N_1\}$, it holds:*

$$\begin{cases} C_{1,k} \text{ is an open subset of } \Omega, \text{ and} \\ \text{for all } \ell \in \{1, \dots, N_1\} \text{ with } \ell \neq k, C_{1,k} \cap C_{1,\ell} = \emptyset. \end{cases} \quad (24)$$

Proof. The proof of (24) is made in [10, Proposition 20]. Let us mention that in [10, Proposition 20], it is also assumed that $f|_{\partial\Omega}$ is a Morse function, but this assumption is not used in the proof of (24) there. \blacksquare

3.2 Separating saddle points

3.2.1 Separating saddle points of f in Ω

Before giving the definition of the separating saddle points of f in Ω , let us first recall the local structure of the sublevel sets of f near a point $z \in \Omega$.

Lemma 8. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function, let $z \in \Omega$, and let us recall that, for $r > 0$, $B(z, r) := \{x \in \bar{\Omega} \text{ s.t. } |x - z| < r\}$. For every $r > 0$ small enough, the following holds:*

1. *When $|\nabla f(z)| \neq 0$, the set $\{f < f(z)\} \cap B(z, r)$ is connected.*
2. *When z is a critical point of f with index $p \in \{0, \dots, d\}$, one has:*
 - (a) *if $p = 0$, i.e. if $z \in U_0$, then $\{f < f(z)\} \cap B(z, r) = \emptyset$,*
 - (b) *if $p = 1$, then $\{f < f(z)\} \cap B(z, r)$ has precisely two connected components,*
 - (c) *if $p \geq 2$, then $\{f < f(z)\} \cap B(z, r)$ is connected.*

The notion of separating saddle point of f in Ω was introduced in [19, Section 4.1] for a Morse function on a manifold without boundary.

Definition 9. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function. The point $z \in \Omega$ is a separating saddle point of f in Ω if it is a saddle point of f (i.e. a critical point of f of index 1) and if for every $r > 0$ small enough, the two connected components of $\{f < f(z)\} \cap B(z, r)$ are contained in different connected components of $\{f < f(z)\}$. The set of separating saddle points of f in Ω is denoted by $U_1^{\text{ssp}}(\Omega)$.*

With this definition, one has the following result which will be needed later to construct the maps \mathbf{j} and \mathbf{C}_j in Section 3.3.

Proposition 10. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function such that $U_0 \neq \emptyset$. Let us consider $C_{1,q}$ for $q \in \{1, \dots, N_1\}$. The set $C_{1,q}$ and its sublevel sets satisfy the following properties.*

1. *It holds,*

$$\text{if } \partial C_{1,q} \cap \partial\Omega = \emptyset \text{ (i.e. } \overline{C_{1,q}} \subset \Omega) \text{ then } \partial C_{1,q} \cap U_1^{\text{ssp}}(\Omega) \neq \emptyset. \quad (25)$$

2. Let λ_q be such that $C_{1,q}$ is a connected component of $\{f < \lambda_q\}$ (see Definitions 5 and 6). Let $\lambda \in (\min_{\overline{C_{1,q}}} f, \lambda_q]$ and C be a connected component of $C_{1,q} \cap \{f < \lambda\}$. Then,

$$(C \cap U_1^{\text{ssp}}(\Omega) \neq \emptyset) \quad \text{iff} \quad C \cap U_0 \text{ contains more than one point.}$$

Moreover, let us define

$$\sigma := \max_{y \in C \cap U_1^{\text{ssp}}(\Omega)} f(y)$$

with the convention $\sigma = \min_{\overline{C}} f$ when $C \cap U_1^{\text{ssp}}(\Omega) = \emptyset$. Then, the following assertions hold.

- For all $\mu \in (\sigma, \lambda]$, the set $C \cap \{f < \mu\}$ is a connected component of $\{f < \mu\}$.
- If $C \cap U_1^{\text{ssp}}(\Omega) \neq \emptyset$, one has $C \cap U_0 \subset \{f < \sigma\}$ and each of the boundary of the connected components of $C \cap \{f < \sigma\}$ contains a separating saddle point of f in Ω (i.e. a point in $U_1^{\text{ssp}}(\Omega)$).

Proof. The proof of Proposition 10 is the same as the proof of [10, Proposition 22] which follows from the study of the sublevel sets of a Morse function on a manifold without boundary (since the principal wells $C_{1,k}$'s are included in Ω). Again the assumption that $f|_{\partial\Omega}$ is a Morse function is not used in the proof of [10, Proposition 22].

■

3.2.2 Separating saddle points of f in $\overline{\Omega}$

In this section, we specify and extend Definition 9 in our setting by taking into account the boundary of Ω and the principal wells $\{C_1, \dots, C_{N_1}\}$ of f introduced in Definition 6. To this end, we first state the following result which describes the local structure of f near $\bigcup_{k \in \{1, \dots, N_1\}} \partial C_{1,k} \cap \partial\Omega$ and which will be used to state an additional assumption on f , assumption **(H1)** below, ensuring that the critical points of f in $\partial C_{1,k} \cap \partial\Omega$ are geometrical saddle points of f in $\overline{\Omega}$ (see Remark 14 below).

Proposition 11. *Let $f : \overline{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function such that $U_0 \neq \emptyset$. Let $k \in \{1, \dots, N_1\}$. Then, for $z \in \partial C_{1,k} \cap \partial\Omega$ (see Definition 6), one has:*

- If $|\nabla f(z)| \neq 0$, then z is a local minimum of $f|_{\partial\Omega}$ and $\partial_{n_\Omega} f(z) > 0$.
- If $|\nabla f(z)| = 0$, then z is saddle point of f . In addition, if the unit outward normal vector $n_\Omega(z)$ to Ω at z is an eigenvector of $\text{Hess } f(z)$ associated with its negative eigenvalue, then z is a non degenerate local minimum of $f|_{\partial\Omega}$ (where $\text{Hess } f(z)$ denotes the endomorphism of $T_z \overline{\Omega}$ canonically associated with the usual symmetric bilinear form $\text{Hess } f(z) : T_z \overline{\Omega} \times T_z \overline{\Omega} \rightarrow \mathbb{R}$ via the metric g).

Finally, it holds,

$$\text{for all } \ell \in \{1, \dots, N_1\} \text{ with } \ell \neq k, \quad \overline{C_{1,\ell}} \cap \overline{C_{1,k}} = \partial C_{1,k} \cap \partial C_{1,\ell} \subset U_1^{\text{ssp}}(\Omega). \quad (26)$$

Remark 12. As it will be clear from the proof of Proposition 11, the fact that $f : \overline{\Omega} \rightarrow \mathbb{R}$ is a Morse function is not needed in the proof of item (a) in Proposition 11.

Proof. Let $z \in \partial C_{1,k} \cap \partial \Omega$. Let V_z be a neighborhood of z in $\overline{\Omega}$ and let

$$p \in V_z \mapsto x = (x', x_d) \in \mathbb{R}^{d-1} \times \mathbb{R}_- \quad (27)$$

be a coordinate system such that $x(z) = 0$,

$$\{p \in V_z, x_d(p) < 0\} = \Omega \cap V_z \quad \text{and} \quad \{p \in V_z, x_d(p) = 0\} = \partial \Omega \cap V_z \quad (28)$$

and

$$\forall i, j \in \{1, \dots, d\}, \quad g_z\left(\frac{\partial}{\partial x_i}(z), \frac{\partial}{\partial x_j}(z)\right) = \delta_{ij} \quad \text{and} \quad \frac{\partial}{\partial x_d}(z) = \mathbf{n}_\Omega(z). \quad (29)$$

The set $x(V_z)$ is a neighborhood of 0 in $\mathbb{R}^{d-1} \times \mathbb{R}_-$. With a slight abuse of notation, the function f in the coordinates x is still denoted by f . The set $x(C_{1,k} \cap V_z)$ is included in $\{x_d < 0\}$ since $C_{1,k} \subset \Omega$ (see Proposition 11). For ease of notation, the set $x(C_{1,k} \cap V_z)$ will be denoted by $C_{1,k}$. Let us now introduce a C^∞ extension of $f : x(V_z) \subset \{x \in \mathbb{R}^d, x_d \leq 0\} \rightarrow \mathbb{R}$ to a neighborhood V_0 of 0 in \mathbb{R}^d such that $V_0 \cap \{x \in \mathbb{R}^d, x_d \leq 0\} \subset x(V_z)$. In the following this extension is still denoted by f . Note that according to (29), the matrix $\text{Hess } f(0)$ is then at the same time the matrix of the symmetric bilinear form $\text{Hess } f(z) : T_z \overline{\Omega} \times T_z \overline{\Omega} \rightarrow \mathbb{R}$ and of its canonically associated (via the metric g) endomorphism $\text{Hess } f(z) : T_z \overline{\Omega} \rightarrow T_z \overline{\Omega}$, in the basis $(\frac{\partial}{\partial x_1}(z), \dots, \frac{\partial}{\partial x_d}(z) = \mathbf{n}_\Omega(z))$ of $T_z \overline{\Omega}$.

Let $r_0 > 0$ be such that $\{x \in \mathbb{R}^d, |x| < r_0\} \subset V_0$ and let $r \in (0, r_0)$. To prove Proposition 11, one will both work with the initial function f and with the above associated function still denoted by f ,

$$f : x = (x', x_d) \in V_0 \subset \mathbb{R}^d \mapsto f(x) \in \mathbb{R}. \quad (30)$$

The proof of Proposition 11 is divided into several steps.

Step 1. Proof of item (a) in Proposition 11. Let us assume that $|\nabla f(z)| \neq 0$. According to Lemma 8, for all $r > 0$ small enough, the set $\{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\}$ is connected. Let us also notice that it clearly holds

$$\emptyset \neq C_{1,k} \cap \{x \in \mathbb{R}^d, |x| < r\} \subset \{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\}.$$

Let us now prove that

$$\{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\} \subset \{x_d < 0\}. \quad (31)$$

If it is not the case, there exists $y_2 \in \{x \in \mathbb{R}^d, |x| < r\}$ such that $x_d(y_2) \geq 0$ and $f(y_2) < f(0)$. The set $\{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\}$ is connected and thus, since it is locally path-connected, it is path-connected. Then, let $y_1 \in C_{1,k} \cap \{x \in \mathbb{R}^d, |x| < r\}$ and consider a continuous curve $\gamma : [0, 1] \rightarrow \{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\}$ such that $\gamma(0) = y_1$ and $\gamma(1) = y_2$. Let us define $t_0 := \inf\{t \geq 0, x_d(\gamma(t)) \geq 0\}$.

Since $x_d(\gamma(0)) < 0$ and $x_d(\gamma(1)) \geq 0$, it holds $t_0 > 0$. Then, for all $t \in [0, t_0]$, it holds $x_d(\gamma(t)) \leq 0$ (with equality if and only if $t = t_0$), $|\gamma(t)| < r$, and $f(\gamma(t)) < f(0)$. Therefore, since by definition $\mathbf{C}_{1,k}$ is a connected component of $\{q \in \bar{\Omega}, f(q) < f(z)\}$, it holds $\gamma(t_0) \in \mathbf{C}_{1,k} \subset \{x_d < 0\}$. This contradicts $x_d(\gamma(t_0)) = 0$ and proves (31). Hence, since $\mathbf{C}_{1,k}$ is a connected component of $\{f < f(z)\}$ in Ω which intersects the connected set $p(\{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\}) \subset \Omega$, it holds

$$\mathbf{C}_{1,k} \cap \{x \in \mathbb{R}^d, |x| < r\} = \{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\}. \quad (32)$$

Equations (28) and (31) imply that z is a local minimum of $f|_{\partial\Omega}$. Using in addition the fact that $|\nabla f(z)| \neq 0$, it holds $\partial_{n_\Omega} f(z) \neq 0$ and hence $\partial_{n_\Omega} f(z) > 0$, since $\partial_{n_\Omega} f(z) < 0$ would imply that z is a local minimum of f in $\bar{\Omega}$ which would thus not belong to $\overline{\mathbf{C}_{1,k}}$. This proves item (a) in Proposition 11. Let us mention that one can prove in addition that $\partial\Omega$ and $\partial\mathbf{C}_{1,k}$ are tangent at z .

Step 2. Proof of item (b) in Proposition 11. Let us now assume that $|\nabla f(z)| = 0$.

Step 2a. Let us prove that 0 is a saddle point of $f : \mathbf{V}_0 \rightarrow \mathbb{R}$. The point 0 is a non degenerate critical point of f . Moreover, because 0 is not a local minimum of f in $\{x_d \leq 0\}$ (since $0 \in \partial\mathbf{C}_{1,k}$), $\text{Hess } f(0)$ has at least one negative eigenvalue. To prove that 0 is a saddle point of f , let us argue by contradiction: assume that $\text{Hess } f(0)$ has at least two negative eigenvalues. Then, according to Lemma 8 (with $p \geq 2$ there), for all $r \in (0, r_0)$ small enough, the set $\{x \in \mathbb{R}^d, f(x) < f(0)\} \cap \{x \in \mathbb{R}^d, |x| < r\}$ is connected. In particular, the same arguments as those used to prove (31) and (32) imply that:

$$\mathbf{C}_{1,k} \cap \{x \in \mathbb{R}^d, |x| < r\} = \{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\} \subset \{x_d < 0\}. \quad (33)$$

To conclude, let us now prove that

$$\{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\} \cap \{x \in \mathbb{R}^d, x_d = 0\} \neq \emptyset, \quad (34)$$

which will contradict (33). To this end, let $(\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_d) \subset \mathbb{R}^d$ be an orthonormal basis of eigenvectors of $\text{Hess } f(0)$ associated with its eigenvalues (μ_1, \dots, μ_d) ordered such that $\mu_1 < 0$ and $\mu_2 < 0$. Since $\{x_d = 0\}$ is a $d-1$ dimensional vector space, there exists $\mathbf{v} \in \{x_d = 0\} \cap \text{Span}(\mathbf{e}_1, \mathbf{e}_2) \setminus \{0\}$. An order 2 Taylor expansion then shows that $f(t\mathbf{v}) < f(0)$ for every $t > 0$ small enough, which implies (34) since $t\mathbf{v} \in \{x_d = 0\}$. Thus, $\text{Hess } f(0)$ has only one negative eigenvalue, i.e. 0 is a saddle point of f .

Step 2b. Let us now end the proof of item (b) in Proposition 11. The point 0 is clearly a critical point of $f|_{\{x_d=0\}}$ since it is a critical point, and more precisely a saddle point by the above analysis, of $f : \mathbf{V}_0 \rightarrow \mathbb{R}$. Let us also emphasize here that without any additional assumption, 0 is not necessarily a non degenerate critical point of $f|_{\{x_d=0\}}$, nor a local minimum of $f|_{\{x_d=0\}}$ (see indeed Remark 15 below). Let us now make the following additional assumption: let us assume that the unit outward normal vector $\mathbf{n}_\Omega(z)$ is an eigenvector of $\text{Hess } f(z)$ associated with its negative eigenvalue. According to (28) and (29), this means that $\mathbf{e}_d = (0, \dots, 0, 1) \in \mathbb{R}^d$ is an eigenvector

of $\text{Hess } f(0)$ associated with its unique negative eigenvalue. Since in the Euclidean space \mathbb{R}^d , it holds $\{x_d = 0\} = \mathbf{e}_d^\perp$, it follows that $\text{Hess } f|_{\{x_d=0\}}(0)$ is positive definite and hence that 0 is a non degenerate local minimum of $f|_{\{x_d=0\}}$. This concludes the proof of item (b) in Proposition 11.

Step 3. Proof of the relation (26). Let us recall that for every k , the set $\mathbf{C}_{1,k}$ is an open subset of Ω such that for all $\ell \neq k$, it holds $\mathbf{C}_{1,\ell} \cap \mathbf{C}_{1,k} = \emptyset$ (see Proposition 7), and hence $\overline{\mathbf{C}_{1,\ell}} \cap \overline{\mathbf{C}_{1,k}} = \partial\mathbf{C}_{1,\ell} \cap \partial\mathbf{C}_{1,k}$. The proof of (26) is divided into two steps.

Step 3a. Let us prove that for all $\ell \in \{1, \dots, \mathbf{N}_1\}$, $\ell \neq k$, it holds

$$\partial\mathbf{C}_{1,\ell} \cap \partial\mathbf{C}_{1,k} \subset \Omega. \quad (35)$$

To this end, let us consider $z \in \partial\mathbf{C}_{1,k} \cap \partial\Omega$. Let us work again in the x -coordinates satisfying (27) and (28), and with the function

$$f : x = (x', x_d) \in \mathbf{V}_0 \subset \mathbb{R}^d \mapsto f(x) \in \mathbb{R}$$

which was introduced in (30).

Let us first consider the case when $|\nabla f(0)| \neq 0$. Let us recall that according to Lemma 8 and (32), for $r > 0$ small enough, $\{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\}$ is connected and equals $\mathbf{C}_{1,k} \cap \{x \in \mathbb{R}^d, |x| < r\}$. Let $\ell \in \{1, \dots, \mathbf{N}_1\}$, $\ell \neq k$. Since in addition $\mathbf{C}_{1,\ell} \cap \mathbf{C}_{1,k} = \emptyset$, one has $0 \notin \partial\mathbf{C}_{1,\ell}$. This concludes the proof of (35) when $|\nabla f(0)| \neq 0$.

Let us now consider the case when $|\nabla f(0)| = 0$. According to item (b), 0 is a saddle point of f . According to Lemma 8 and since 0 is a non degenerate saddle point of f , for $r > 0$ small enough, $\{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\}$ has two connected components which are denoted by \mathbf{A}_1 and \mathbf{A}_2 . To prove (35), let us argue by contradiction and let us assume that $0 \in \partial\mathbf{C}_{1,\ell} \cap \partial\mathbf{C}_{1,k}$ for some $\ell \in \{1, \dots, \mathbf{N}_1\}$ with $\ell \neq k$. Since both $\mathbf{C}_{1,k}$ and $\mathbf{C}_{1,\ell}$ meet $\mathbf{A}_1 \cup \mathbf{A}_2$, the same arguments as those used to prove (31) and (32) then lead, up to switching \mathbf{A}_1 and \mathbf{A}_2 , to

$$\mathbf{C}_{1,k} \cap \{x \in \mathbb{R}^d, |x| < r\} = \mathbf{A}_1 \quad \text{and} \quad \mathbf{C}_{1,\ell} \cap \{x \in \mathbb{R}^d, |x| < r\} = \mathbf{A}_2$$

and to

$$\{x \in \mathbb{R}^d, |x| < r \text{ and } f(x) < f(0)\} = \mathbf{A}_1 \cup \mathbf{A}_2 \subset \{x_d < 0\}. \quad (36)$$

This imposes that the eigenvector \mathbf{e}_d of $\text{Hess } f(0)$ associated with its negative eigenvalue satisfies

$$\mathbf{e}_d \in \{x_d = 0\}.$$

Indeed, if it was not the case, an order 2 Taylor expansion of $t \mapsto f(t\mathbf{e}_d)$ at $t = 0$ would imply that $f - f(0)$ admits negative values in $\{x_d > 0\} \cap \{|x| < r\}$ for every $r > 0$, contradicting (36). Thus, $\mathbf{e}_d \in \{x_d = 0\}$. Then, the order 2 Taylor expansion of $t \mapsto f(t\mathbf{e}_d)$ at $t = 0$ shows that $f - f(0)$ admits negative values in $\{x_d = 0\} \cap \{|x| < r\}$ for every $r > 0$, which also contradicts (36). This, concludes the proof of (35) when $|\nabla f(0)| = 0$.

Step 3b. Proof of (26). According to (35), for all $\ell \neq k$, it holds $\partial\mathbf{C}_{1,k} \cap \partial\mathbf{C}_{1,\ell} \subset \Omega$. Let us now consider $z \in \partial\mathbf{C}_{1,k} \cap \partial\mathbf{C}_{1,\ell}$ when the latter set is non empty, which implies that $\mathbf{C}_{1,k}$ and $\mathbf{C}_{1,\ell}$ are two connected components of $\{f < f(z)\}$. Then, for $r > 0$ small enough, $\{f < f(z)\} \cap B(z, r)$ has at least two connected components, respectively included in $\mathbf{C}_{1,k}$ and in $\mathbf{C}_{1,\ell}$. From Lemma 8, z is then a saddle point of f and, according to Definition 9, it thus belongs to $\mathbf{U}_1^{\text{ssp}}(\Omega)$. This concludes the proof of (26) and then the proof of Proposition 11. \blacksquare

We are now in position to state the following assumption which will be used to construct the maps \mathbf{j} and \mathbf{C}_j at the end of this section. Before stating it, let us recall that from item (b) in Proposition 11, any point z belonging to $\partial\mathbf{C}_{1,k} \cap \partial\Omega$ for some $k \in \{1, \dots, \mathbf{N}_1\}$ and such that $|\nabla f(z)| = 0$ is saddle point of f . Using moreover (26), such a z does not belong to $\overline{\mathbf{C}_{1,\ell}}$ when $\ell \in \{1, \dots, \mathbf{N}_1\} \setminus \{k\}$.

Assumption (H1). *The function $f : \overline{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function such that $\mathbf{U}_0 \neq \emptyset$ and whose principal wells $\mathbf{C}_{1,1}, \dots, \mathbf{C}_{1,\mathbf{N}_1}$ defined in Definition 6 satisfy the following property: for every $k \in \{1, \dots, \mathbf{N}_1\}$ and every $z \in \partial\mathbf{C}_{1,k} \cap \partial\Omega$ such that $|\nabla f(z)| = 0$, the unit outward normal vector $\mathbf{n}_\Omega(z)$ to Ω at z is an eigenvector of $\text{Hess } f(z)$ associated with its negative eigenvalue, where $\text{Hess } f(z)$ denotes the endomorphism of $T_z\overline{\Omega}$ canonically associated with the symmetric bilinear form $\text{Hess } f(z) : T_z\overline{\Omega} \times T_z\overline{\Omega} \rightarrow \mathbb{R}$ via the metric g .*

When (H1) is satisfied, according to Proposition 11, the sublevel sets $\{f < f(z)\}$ have the following local structure near the points $z \in \bigcup_{k=1}^{\mathbf{N}_1} \partial\mathbf{C}_{1,k} \cap \partial\Omega$.

Corollary 13. *Let $f : \overline{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function satisfying (H1). Then, for all $k \in \{1, \dots, \mathbf{N}_1\}$ and for all $z \in \partial\mathbf{C}_{1,k} \cap \partial\Omega$, one has:*

- (a) *If $|\nabla f(z)| \neq 0$, z is a local minimum of $f|_{\partial\Omega}$ and $\partial_{\mathbf{n}_\Omega} f(z) > 0$ (see Figure 1).*
- (b) *If $|\nabla f(z)| = 0$, z is a saddle point of f and the unit outward normal vector $\mathbf{n}_\Omega(z)$ to Ω at z is an eigenvector of $\text{Hess } f(z)$ associated with its negative eigenvalue. Moreover, the point z is a non degenerate local minimum of $f|_{\partial\Omega}$ (see Figure 2).*

Note that when (H1) is satisfied, it follows from Corollary 13 that the points $z \in \bigcup_{k=1}^{\mathbf{N}_1} \partial\mathbf{C}_{1,k} \cap \partial\Omega$ such that $|\nabla f(z)| = 0$ are isolated in $\bigcup_{k=1}^{\mathbf{N}_1} \partial\mathbf{C}_{1,k} \cap \partial\Omega$. Indeed, they are non degenerate critical points of $f|_{\partial\Omega}$ and $\bigcup_{k=1}^{\mathbf{N}_1} \partial\mathbf{C}_{1,k} \cap \partial\Omega$ is composed of critical points of $f|_{\partial\Omega}$. Note also that this is in general not the case for the points $z \in \bigcup_{k=1}^{\mathbf{N}_1} \partial\mathbf{C}_{1,k} \cap \partial\Omega$ such that $|\nabla f(z)| \neq 0$.

Remark 14. *When (H1) holds, it follows from items (a) and (b) in Corollary 13 that the elements of $\bigcup_{k=1}^{\mathbf{N}_1} (\partial\mathbf{C}_{1,k} \cap \partial\Omega)$ play geometrically the role of saddle points of f in $\overline{\Omega}$. Indeed, when f is extended by $-\infty$ outside $\overline{\Omega}$ (this extension is consistent with the Dirichlet boundary conditions used to define $\Delta_{f,h}^D$), the points $z \in \bigcup_{k=1}^{\mathbf{N}_1} \partial\mathbf{C}_{1,k} \cap \partial\Omega$ are local minima of $f|_{\partial\Omega}$ and local maxima of $f|_{D_z}$, where D_z is the straight line passing through z and orthogonal to $\partial\Omega$ at z . Note however that when $|\nabla f(z)| \neq 0$, z can*

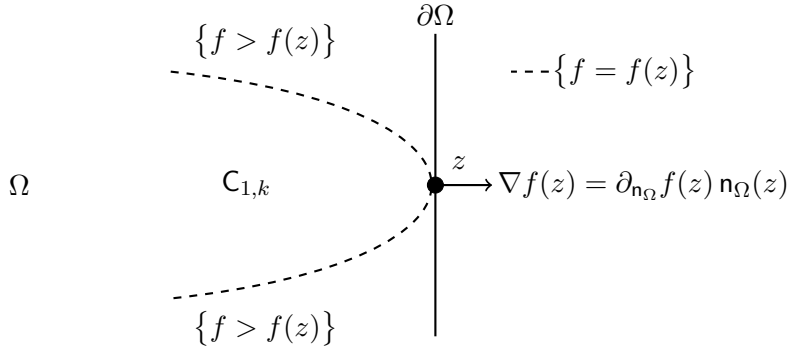


Figure 1: Behaviour of f in a neighborhood of $z \in \partial\mathbf{C}_{1,k} \cap \partial\Omega$ when $|\nabla f(z)| \neq 0$ and z is isolated in $\partial\mathbf{C}_{1,k} \cap \partial\Omega$.

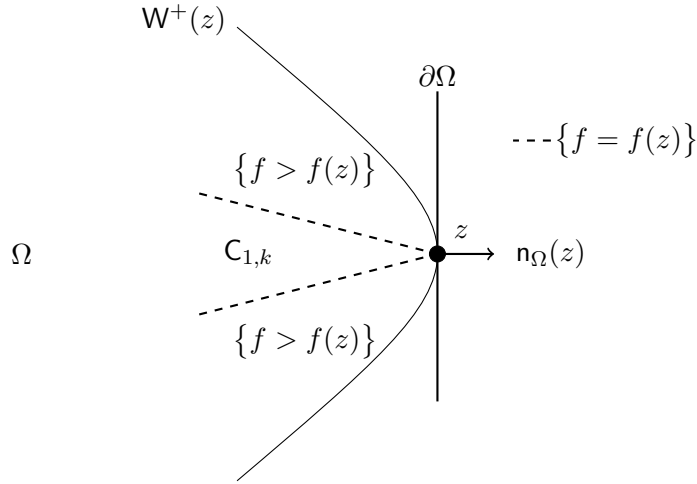


Figure 2: Behaviour of f in a neighborhood of $z \in \partial\mathbf{C}_{1,k} \cap \partial\Omega$ when $|\nabla f(z)| = 0$ and **(H1)** is satisfied. On this figure, $W^+(z)$ is the stable manifold of z for the dynamics $\dot{X} = -\nabla f(X)$.

be a degenerate local minimum of $f|_{\partial\Omega}$ (which can even be constant around z). This extends the definition of generalized saddle points of f in $\partial\Omega$ as introduced in [17, Definition 3.2.2] to the case when $f|_{\partial\Omega}$ is not a Morse function and f has critical point on $\partial\Omega$. Moreover, when **(H1)** does not hold, the points $z \in \bigcup_{k=1}^{N_1} \partial\mathbf{C}_{1,k} \cap \partial\Omega$ such that $|\nabla f(z)| = 0$, which are thus saddle points of f according to Proposition 11, do actually not necessarily play the role of saddle points of f in $\bar{\Omega}$ in the above sense, as explained in Remark 15 below.

Remark 15. Let $k \in \{1, \dots, N_1\}$ and $z \in \partial\mathbf{C}_{1,k} \cap \partial\Omega$ be such that $|\nabla f(z)| = 0$. We recall that, according to Proposition 11, z is a saddle point of f , and that, by Corollary 13, when $n_\Omega(z)$ is an eigenvector of $\text{Hess } f(z)$ associated with its negative eigenvalue, z is a local minimum of $f|_{\partial\Omega}$ and thus a geometrical saddle point of f in $\bar{\Omega}$ in the sense of Remark 14. We show below that the latter property fails to be

true in general when $z \in \partial C_{1,k} \cap \partial\Omega$ is only assumed to be a critical point, and is hence a saddle point, of f . To this end, let us consider, in the canonical basis $(\mathbf{e}_x, \mathbf{e}_y)$ of \mathbb{R}^2 , the Morse function

$$\psi(x, y) = y^2 - x^2,$$

whose only critical point in \mathbb{R}^2 is 0 and is a saddle point. Let us then introduce the two vectors

$$\mathbf{u} = \frac{1}{\sqrt{2}}(\mathbf{e}_x - \mathbf{e}_y) \text{ and } \mathbf{v} = \frac{1}{\sqrt{2}}(\mathbf{e}_x + \mathbf{e}_y).$$

In the orthonormal basis (\mathbf{u}, \mathbf{v}) , the function ψ writes $\psi(u, v) = -2uv$. Hence, defining the smooth curve

$$\Gamma := \{p = (u, u^2) \text{ in the basis } (\mathbf{u}, \mathbf{v}), u \in \mathbb{R}\} \text{ (see Figure 3),}$$

it holds $\psi|_{\Gamma} : p = (u, u^2) \in \Gamma \mapsto -2u^3$ and 0 is then not a local minimum of $f|_{\Gamma}$. In particular, if, in a neighborhood of 0 in \mathbb{R}^2 , $\partial\Omega$ coincides with Γ and Ω is chosen such that $\mathbf{n}_{\Omega}(0) = \mathbf{v}$, and if $f = \psi$, then, locally around 0 in $\bar{\Omega}$, $\{f < 0\} \cap \{x < 0\}$ is a connected component of $\{f < 0\}$ included in Ω such that $\overline{\{f < 0\} \cap \{x < 0\}} \cap \partial\Omega = \{0\}$ but 0 is not a local minimum of $f|_{\partial\Omega}$ (see Figure 3).

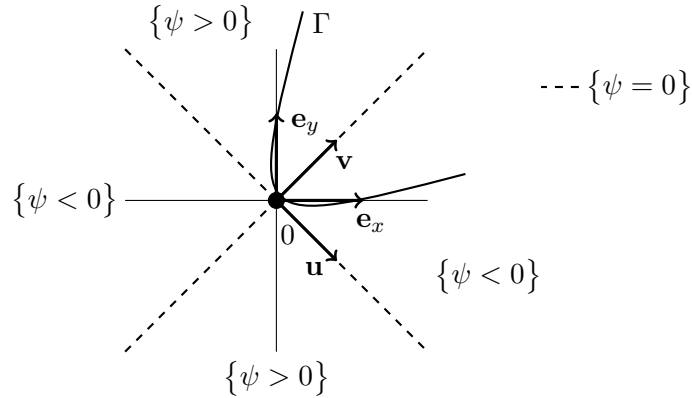


Figure 3: The function ψ and the curve Γ in a neighborhood of 0 in \mathbb{R}^2 .

When **(H1)** holds, one extends the definition of a separating saddle point of f in Ω given in Definition 9 to our setting by taking into account the points in $\bigcup_{i=1}^{N_1} \partial C_i \cap \partial\Omega$ which are, according to Remark 14, geometrical saddle points of f in $\bar{\Omega}$.

Definition 16. Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function satisfying **(H1)** and let $C_{1,1}, \dots, C_{1,N_1}$ be its principal wells defined in Definition 6.

1. A point $z \in \bar{\Omega}$ is a separating saddle point of f in $\bar{\Omega}$ if

$$\text{either } z \in \bigcup_{k=1}^{N_1} (\overline{C_{1,k}} \cap U_1^{\text{ssp}}(\Omega)), \text{ or } z \in \bigcup_{k=1}^{N_1} (\partial C_{1,k} \cap \partial\Omega).$$

Notice that in the first case $z \in \Omega$ whereas in second case $z \in \partial\Omega$. The set of separating saddle points of f in $\bar{\Omega}$ is denoted by $U_1^{\text{ssp}}(\bar{\Omega})$.

2. For any $\sigma \in \mathbb{R}$, a connected component C of the sublevel set $\{f < \sigma\}$ in $\overline{\Omega}$ is called a *critical connected component* of f if $\partial C \cap U_1^{\text{ssp}}(\overline{\Omega}) \neq \emptyset$. The family of critical connected components is denoted by $\mathcal{C}_{\text{crit}}$.

Equation (25) and item 1 in Definition 16 imply the following result which will be used in the first step of the construction of the maps \mathbf{j} and $C_{\mathbf{j}}$.

Corollary 17. *Let $f : \overline{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function satisfying **(H1)**. Then, it holds:*

$$\text{for all } \ell \in \{1, \dots, N_1\}, \quad \partial C_{1,\ell} \cap U_1^{\text{ssp}}(\overline{\Omega}) \neq \emptyset.$$

3.3 Construction of the maps \mathbf{j} and $C_{\mathbf{j}}$

Let us now construct the maps \mathbf{j} and $C_{\mathbf{j}}$, which respectively associate each local minimum of f in Ω with a set of $U_1^{\text{ssp}}(\overline{\Omega})$ and with an element of $\mathcal{C}_{\text{crit}}$ (see Definition 16). We closely follow the presentation of [10, Section 2.4] in the case when f does not have any critical point on the boundary and $f|_{\partial\Omega}$ is a Morse function and which was inspired by [19] in the case without boundary.

Let us assume that $f : \overline{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function satisfying **(H1)** (and thus such that $U_0 \neq \emptyset$.) The maps \mathbf{j} and $C_{\mathbf{j}}$ are then defined recursively as follows.

1. Initialization ($q = 1$). Let us consider the principal wells $C_{1,1}, \dots, C_{1,N_1}$ of f in Ω (see Definition 6).

For every $\ell \in \{1, \dots, N_1\}$, let us choose

$$x_{1,\ell} \in \arg \min_{C_{1,\ell}} f.$$

Then, for all $\ell \in \{1, \dots, N_1\}$, one defines

$$\kappa_{1,\ell} := \max_{C_{1,\ell}} f, \quad C_{\mathbf{j}}(x_{1,\ell}) := C_{1,\ell}, \quad \text{and} \quad \mathbf{j}(x_{1,\ell}) := \partial C_{1,\ell} \cap U_1^{\text{ssp}}(\overline{\Omega}). \quad (37)$$

From Definitions 5 and 6, $\partial C_{\mathbf{j}}(x_{1,\ell}) \subset \{f = \kappa_{1,\ell}\}$ for all $\ell \in \{1, \dots, N_1\}$. According moreover to Corollary 17, one has $\mathbf{j}(x_{1,\ell}) \neq \emptyset$ for all $\ell \in \{1, \dots, N_1\}$ and thus, $C_{\mathbf{j}}(x_{1,\ell}) \in \mathcal{C}_{\text{crit}}$ (see item 2 in Definition 16). Finally, it holds from (26),

$$\forall \ell \neq q \in \{1, \dots, N_1\}^2, \quad \partial C_{1,\ell} \cap \partial C_{1,q} \subset U_1^{\text{ssp}}(\Omega).$$

2. First step ($q = 2$).

From item 2 in Proposition 10, for each $\ell \in \{1, \dots, N_1\}$, $C_{1,\ell} \cap U_0 \neq \{x_{1,\ell}\}$ if and only if $U_1^{\text{ssp}}(\Omega) \cap C_{1,\ell} \neq \emptyset$. Consequently, one has:

$$U_1^{\text{ssp}}(\Omega) \cap \left(\bigcup_{\ell=1}^{N_1} C_{1,\ell} \right) \neq \emptyset \quad \text{iff} \quad \{x_{1,1}, \dots, x_{1,N_1}\} \neq U_0.$$

If $U_1^{\text{ssp}}(\Omega) \cap \left(\bigcup_{\ell=1}^{N_1} C_{1,\ell} \right) = \emptyset$ (or equivalently if $N_1 = m_0$), the constructions of the maps \mathbf{j} and $C_{\mathbf{j}}$ are finished and one goes to item 4 below. If $U_1^{\text{ssp}}(\Omega) \cap \left(\bigcup_{\ell=1}^{N_1} C_{1,\ell} \right) \neq \emptyset$, one defines

$$\kappa_2 := \max_{x \in U_1^{\text{ssp}}(\Omega) \cap \left(\bigcup_{\ell=1}^{N_1} C_{1,\ell} \right)} f(x) \in \left(\min_{\bigcup_{\ell=1}^{N_1} C_{1,\ell}} f, \max_{\ell \in \{1, \dots, N_1\}} \kappa_{1,\ell} \right).$$

The set

$$\bigcup_{\ell=1}^{N_1} \left(C_{1,\ell} \cap \{f < \kappa_2\} \right)$$

is then the union of finitely many connected components. We denote by $C_{2,1}, \dots, C_{2,N_2}$ (with $N_2 \geq 1$) the connected components of $\bigcup_{\ell=1}^{N_1} (C_{1,\ell} \cap \{f < \kappa_2\})$ which do not contain any of the minima $\{x_{1,1}, \dots, x_{1,N_1}\}$. From item 2 in Proposition 10 (applied for each $\ell \in \{1, \dots, N_1\}$ with $C = C_{1,\ell} \cap \{f < \kappa_2\}$ there) and item 2 in Definition 16,

$$\forall \ell \in \{1, \dots, N_2\}, C_{2,\ell} \in \mathcal{C}_{crit}.$$

Let us mention that the other connected components (i.e. those containing the points $\{x_{1,1}, \dots, x_{1,N_1}\}$) may be not critical. For each $1 \leq \ell \leq N_2$, one then considers an element $x_{2,\ell}$ arbitrarily chosen in $\arg \min_{\overline{C_{2,\ell}}} f = \arg \min_{C_{2,\ell}} f$ (the equality follows from $\partial C_{2,\ell} \subset \{f = \kappa_2\}$) and one defines:

$$C_{\mathbf{j}}(x_{2,\ell}) := C_{2,\ell} \text{ and } \mathbf{j}(x_{2,\ell}) := \partial C_{2,\ell} \cap U_1^{\text{ssp}}(\overline{\Omega}) (\neq \emptyset) \subset U_1^{\text{ssp}}(\Omega) \cap \{f = \kappa_2\}.$$

3. Recurrence ($q \geq 3$).

If all the local minima of f in Ω have been labeled at the end of the previous step, i.e. if $\bigcup_{j=1}^2 \{x_{j,1}, \dots, x_{j,N_j}\} = U_0$ (or equivalently if $N_1 + N_2 = m_0$), the constructions of the maps $C_{\mathbf{j}}$ and \mathbf{j} are finished, all the local minima of f have been labeled and one goes to item 4 below. If it is not the case, from item 2 in Proposition 10, there exists $m \in \mathbb{N}^*$ such that

$$\text{for all } q \in \{2, \dots, m+1\}, U_1^{\text{ssp}}(\Omega) \cap \bigcup_{\ell=1}^{N_1} (C_{1,\ell} \cap \{f < \kappa_q\}) \neq \emptyset, \quad (38)$$

where the decreasing sequence $(\kappa_q)_{q=3, \dots, m+2}$ is defined recursively by

$$\kappa_q := \max_{x \in U_1^{\text{ssp}}(\Omega) \cap \bigcup_{\ell=1}^{N_1} (C_{1,\ell} \cap \{f < \kappa_{q-1}\})} f(x) \in \left(\min_{\bigcup_{\ell=1}^{N_1} C_{1,\ell}} f, \kappa_{q-1} \right).$$

Let now $m^* \in \mathbb{N}^*$ be the largest $m \in \mathbb{N}^*$ such that (38) holds. Notice that m^* is well defined since the cardinal of U_0 is finite. By definition of m^* , one has moreover:

$$U_1^{\text{ssp}}(\Omega) \cap \bigcup_{\ell=1}^{N_1} (C_{1,\ell} \cap \{f < \kappa_{m^*+2}\}) = \emptyset. \quad (39)$$

Then, one repeats recursively m^* times the procedure described above defining $(C_{2,\ell}, \mathbf{j}(x_{2,\ell}), C_{\mathbf{j}}(x_{2,\ell}))_{1 \leq \ell \leq N_2}$: for $q \in \{2, \dots, m^*+1\}$, one defines $(C_{q+1,\ell})_{\ell \in \{1, \dots, N_{q+1}\}}$ as the set of the connected components of

$$\bigcup_{\ell=1}^{N_1} (C_{1,\ell} \cap \{f < \kappa_{q+1}\})$$

which do not contain any of the local minima $\cup_{j=1}^q \{x_{j,1}, \dots, x_{j,N_j}\}$ of f in Ω which have been previously labeled. From items 1 and 2 in Proposition 10 (applied for each $\ell \in \{1, \dots, N_1\}$ with $\mathbf{C} = \mathbf{C}_{1,\ell} \cap \{f < \kappa_{q+1}\}$ there),

$$\forall \ell \in \{1, \dots, N_{q+1}\}, \mathbf{C}_{q+1,\ell} \in \mathcal{C}_{crit}.$$

For $\ell \in \{1, \dots, N_{q+1}\}$, we then associate with each $\mathbf{C}_{q+1,\ell}$ one point $x_{q+1,\ell}$ arbitrarily chosen in $\arg \min_{\mathbf{C}_{q+1,\ell}} f$ and we define:

$$\mathbf{C}_{\mathbf{j}}(x_{q+1,\ell}) := \mathbf{C}_{q+1,\ell} \quad \text{and} \quad \mathbf{j}(x_{q+1,\ell}) := \partial \mathbf{C}_{q+1,\ell} \cap \mathbf{U}_1^{\text{ssp}}(\Omega) (\neq \emptyset) \subset \{f = \kappa_{q+1}\}.$$

From (39) and item 2 in Proposition 10, $\mathbf{U}_0 = \cup_{j=1}^{m^*+2} \{x_{j,1}, \dots, x_{j,N_j}\}$. Thus, all the local minima of f in Ω are labeled. This finishes the construction of maps \mathbf{j} and $\mathbf{C}_{\mathbf{j}}$.

4. Properties of the maps \mathbf{j} and $\mathbf{C}_{\mathbf{j}}$.

Let us now give important features of the map \mathbf{j} which follow directly from its construction and which will be used in the sequel. We have been defined two maps

$$\mathbf{C}_{\mathbf{j}} : \mathbf{U}_0 \longrightarrow \mathcal{C}_{crit} \quad \text{and} \quad \mathbf{j} : \mathbf{U}_0 \longrightarrow \mathcal{P}(\mathbf{U}_1^{\text{ssp}}(\overline{\Omega})) \quad (40)$$

which are clearly injective. For every $x \in \mathbf{U}_0$, the set $\mathbf{j}(x)$ is the set made of the separating saddle points of f in $\overline{\Omega}$ on $\partial \mathbf{C}_{\mathbf{j}}(x)$. Notice that the $\mathbf{j}(x)$, $x \in \mathbf{U}_0$, are not disjoint in general. For all $x \in \mathbf{U}_0$, the set $f(\mathbf{j}(x))$ contains exactly one value, which will be denoted by $f(\mathbf{j}(x))$. Moreover, for all $x \in \mathbf{U}_0$, it holds

$$f(\mathbf{j}(x)) - f(x) > 0. \quad (41)$$

Since $\cup_{\ell=1}^{N_1} \mathbf{C}_{1,\ell} \subset \Omega$ (see the first statement in (24)), one has $\mathbf{C}_{\mathbf{j}}(x) \subset \Omega$ for all $x \in \mathbf{U}_0$. Moreover, only the boundaries of the principal wells can contain separating saddle points of f on $\partial \Omega$, i.e.:

$$\forall x \in \mathbf{U}_0 \setminus \{x_{1,1}, \dots, x_{1,N_1}\}, \mathbf{j}(x) \subset \mathbf{U}_1^{\text{ssp}}(\Omega) \quad (\text{see Definition 9}). \quad (42)$$

In addition, for all $x, y \in \mathbf{U}_0$ such that $x \neq y$, since by construction $\mathbf{j}(y) \cap \mathbf{j}(x) = \partial \mathbf{C}_{\mathbf{j}}(y) \cap \partial \mathbf{C}_{\mathbf{j}}(x)$ (see (26)), one has two possible cases:

- (i) either $\mathbf{j}(x) \cap \mathbf{j}(y) = \emptyset$, in which case either $\overline{\mathbf{C}_{\mathbf{j}}(y)} \cap \overline{\mathbf{C}_{\mathbf{j}}(x)} = \emptyset$ or, up to interchanging x with y , $\overline{\mathbf{C}_{\mathbf{j}}(y)} \subset \mathbf{C}_{\mathbf{j}}(x)$,
- (ii) or $\mathbf{j}(x) \cap \mathbf{j}(y) \neq \emptyset$, in which case $f(\mathbf{j}(x)) = f(\mathbf{j}(y))$ and the sets $\mathbf{C}_{\mathbf{j}}(x)$ and $\mathbf{C}_{\mathbf{j}}(y)$ are two different connected components of $\{f < f(\mathbf{j}(x))\}$.

Finally, for all $\ell \in \{1, \dots, N_1\}$ and all $x \in \mathbf{U}_0 \cap \mathbf{C}_{\mathbf{j}}(x_{1,\ell}) \setminus \{x_{1,\ell}\}$, note that

$$f(x) \geq f(x_{1,\ell}), \quad f(\mathbf{j}(x)) < f(\mathbf{j}(x_{1,\ell})) \quad \text{and then} \quad f(\mathbf{j}(x)) - f(x) < f(\mathbf{j}(x_{1,\ell})) - f(x_{1,\ell}).$$

Let us also mention that the maps \mathbf{j} and $\mathbf{C}_{\mathbf{j}}$ are not uniquely defined as soon as there exists some $\mathbf{C}_{k,\ell}$, $k \geq 1$, $\ell \in \{1, \dots, N_k\}$, such that f has more than one global minimum in $\mathbf{C}_{k,\ell}$. However, this non-uniqueness has no influence on the results proven below (in particular Theorems 2 and 3).

Remark 18. For all $x \in \mathbf{U}_0$, the set $\mathbf{C}_j(x)$ has geometrically the shape of a potential well and the elements of \mathcal{C} (see Definition 6) are called the principal wells of f in Ω since they contain all the $\mathbf{C}_j(x)$, $x \in \mathbf{U}_0$.

Let us end this section with the following result which be used to prove the further Proposition 32.

Lemma 19. Let us assume that $f : \bar{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function which satisfies **(H1)**. Let $(\mathbf{C}_j(x))_{x \in \mathbf{U}_0}$ be as defined in (40) and let $k \geq 1$. Let us consider, for some $m \geq 1$, $\{\mathbf{C}^1, \dots, \mathbf{C}^m\} \subset \{\mathbf{C}_j(x_{k,1}), \dots, \mathbf{C}_j(x_{k, N_k})\}$ such that

$$\begin{cases} \bigcup_{\ell=1}^m \bar{\mathbf{C}}^\ell \text{ is connected, and} \\ \text{for all } \mathbf{C} \in \{\mathbf{C}_j(x_{k,1}), \dots, \mathbf{C}_j(x_{k, N_k})\} \setminus \{\mathbf{C}^1, \dots, \mathbf{C}^m\}, \quad \bar{\mathbf{C}} \cap \bigcup_{\ell=1}^m \bar{\mathbf{C}}^\ell = \emptyset. \end{cases}$$

Then, there exist $\ell_0 \in \{1, \dots, m\}$ and $z \in \mathbf{U}_1^{\text{ssp}}(\bar{\Omega})$ such that

$$z \in \partial \mathbf{C}^{\ell_0} \setminus \left(\bigcup_{\ell=1, \ell \neq \ell_0}^m \partial \mathbf{C}^\ell \right). \quad (43)$$

Proof. Let $\{\mathbf{C}^1, \dots, \mathbf{C}^m\}$ be as in Lemma 19.

When $k = 1$, the set $\{\mathbf{C}_j(x_{1,1}), \dots, \mathbf{C}_j(x_{1, N_1})\}$ is the set of the principal wells of f , i.e. the set \mathcal{C} of Definition 6, and the proof of Lemma 43 follows exactly the same lines as the proof of [10, Lemma 21].

Let us now consider the case when $k \geq 2$. Let us first notice that according to the construction of the maps \mathbf{j} and \mathbf{C}_j , for all $\ell \in \{1, \dots, m\}$, \mathbf{C}^ℓ is a connected component of $\{f < \kappa_k\}$ which has been labelled at the k -th iteration. Since $\bigcup_{\ell=1}^m \bar{\mathbf{C}}^\ell$ is connected, there exists $q \in \{1, \dots, N_1\}$ such that $\bigcup_{\ell=1}^m \bar{\mathbf{C}}^\ell \subset \mathbf{C}_{1,q} = \{f < \kappa_{1,q}\}$, where, since $k \geq 2$, $\kappa_k < \kappa_{1,q}$. Since, from Corollary 17, it holds $\emptyset \neq \partial \mathbf{C}_{1,q} \cap \mathbf{U}_1^{\text{ssp}}(\bar{\Omega}) \subset \{f = \kappa_{1,q}\}$, one can define $\kappa^* \in (\kappa_k, \kappa_{1,q}]$ as the minimum of the $\lambda \in (\kappa_k, \kappa_{1,q}]$ such that the connected component of $\{f < \lambda\} \cap \mathbf{C}_{1,q}$ containing $\bigcup_{\ell=1}^m \bar{\mathbf{C}}^\ell$ is critical (see Definition 16). We then define \mathbf{C}^* as the connected component of $\{f < \kappa^*\} \cap \mathbf{C}_{1,q}$ containing $\bigcup_{\ell=1}^m \bar{\mathbf{C}}^\ell$. By definition, \mathbf{C}^* is critical, and, from the construction of the maps \mathbf{j} and \mathbf{C}_j , it thus holds:

$$\mathbf{C}^* \cap \bigcup_{j=1}^{k-1} \{x_{j,1}, \dots, x_{j, N_j}\} \neq \emptyset. \quad (44)$$

Moreover, since all the \mathbf{C}^ℓ 's are critical, and thus $\mathbf{C}^* \cap \mathbf{U}_1^{\text{ssp}}(\Omega) \neq \emptyset$, the definitions of κ^* and \mathbf{C}^* together with item 2 in Proposition 10 applied to $\mathbf{C} = \mathbf{C}^*$ imply that

$$\kappa_k = \max_{y \in \mathbf{C}^* \cap \mathbf{U}_1^{\text{ssp}}(\Omega)} f(y) (< \kappa^*).$$

Therefore, using again item 2 in Proposition 10 with $\mathbf{C} = \mathbf{C}^*$,

$$\{f \leq \kappa_k\} \cap \mathbf{C}^* \text{ is connected} \quad \text{and} \quad \mathbf{C}^* \cap \mathbf{U}_0 \subset \{f < \kappa_k\}, \quad (45)$$

where the first affirmation follows from the fact that, for every $\lambda \in (\kappa_k, \kappa^*)$, $\mathbf{C}^* \cap \{f < \lambda\}$ is connected.

To prove (43), one argues by contradiction assuming that (43) is not satisfied. It then follows from the local structure of the sublevel sets of a Morse function given in Lemma 8 that there exists some open set $O \subset \Omega$ such that $O \cap \{f \leq \kappa_k\} = \bigcup_{\ell=1}^m \overline{C}^\ell$ (see, in [10], the arguments used to prove Equation (50) there for more details). In other words, the connected set $\bigcup_{\ell=1}^m \overline{C}^\ell$ is open in $\{f \leq \kappa_k\}$ and thus, since it is closed and then closed in $\{f \leq \kappa_k\}$, it is a connected component of $\{f \leq \kappa_k\}$. It thus follows from (45) that $\{f \leq \kappa_k\} \cap C^* = \bigcup_{\ell=1}^m \overline{C}^\ell$ contains all the local minima of f in C^* . According to (44), this implies, since $\bigcup_{\ell=1}^m \partial C^\ell$ does not contain any local minimum of f , that at least one of the C^ℓ 's, $\ell \in \{1, \dots, m\}$, does intersect $\bigcup_{j=1}^{k-1} \{x_{j,1}, \dots, x_{j,N_j}\}$. This leads to a contradiction since the C^ℓ 's ($\ell \in \{1, \dots, m\}$) are labelled at the k -th iteration ($k \geq 2$) and thus, each C^ℓ ($\ell \in \{1, \dots, m\}$) does not intersect $\bigcup_{j=1}^{k-1} \{x_{j,1}, \dots, x_{j,N_j}\}$. This concludes the proof of Lemma 19. \blacksquare

4 Quasi-modal construction

The aim of this section is to construct, for every $x \in U_0$, a quasi-mode ψ_x associated with x , or more exactly with $C_j(x)$, and whose energy in the limit $h \rightarrow 0$ will be shown to give the asymptotic behaviour of one of the m_0 first eigenvalues of $\Delta_{f,h}^D$ as exhibited in Theorems 2' and 2.

More precisely, our quasi-modes $(\psi_x)_{x \in U_0}$ are built as suitable normalisations of auxiliary functions $(\phi_x)_{x \in U_0}$, which are first explicitly constructed in a neighborhood of the elements of $\mathbf{j}(x) \subset \overline{\Omega}$, and then suitably extended to $\overline{\Omega}$. This construction is partly inspired by the construction made in [9] when $\Omega = \mathbb{R}^d$, see also [5, 21, 30]. We also refer to [11, 16, 17, 19, 23, 25, 27] for related constructions.

This section is organized as follows. In Section 4.1, one introduces adapted coordinate systems in a neighborhood of the elements of $\mathbf{j}(x)$, where $x \in U_0$, which then permit in Section 4.2 to construct the auxiliary functions ϕ_x in a neighborhood of $\mathbf{j}(x)$. The functions $(\phi_x)_{x \in U_0}$ and $(\psi_x)_{x \in U_0}$ are then defined in Section 4.3.

Before, let us introduce the following assumption which will be used throughout the rest of this work.

Assumption (H2). *The function $f : \overline{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function such that $U_0 \neq \emptyset$. Moreover, for all $z \in \bigcup_{k=1}^{N_1} \partial C_{1,k} \cap \partial \Omega$ (see Definition 6) such that $|\nabla f(z)| \neq 0$ (we recall that in this case, z is a local minimum of $f|_{\partial \Omega}$ by item (a) in Proposition 11),*

$$z \text{ is a non degenerate local minimum of } f|_{\partial \Omega} . \quad (46)$$

When f satisfies the assumptions (H1) and (H2), it holds

$$\text{Card}\left(\bigcup_{k=1}^{N_1} \partial C_{1,k} \cap \partial \Omega\right) < \infty \quad \text{and then} \quad \text{Card}\left(\bigcup_{x \in U_0} \mathbf{j}(x)\right) < \infty . \quad (47)$$

Indeed, $\text{Card}(\bigcup_{x \in \mathbf{U}_0} \mathbf{j}(x) \cap \Omega) < \infty$ since $\bigcup_{x \in \mathbf{U}_0} \mathbf{j}(x) \cap \Omega$ is composed of non degenerate saddle points of f in Ω (see the construction of the map \mathbf{j} in Section 3.3 and Definition 9) and, according to item (b) in Corollary 13 and to (46), the elements of

$$\bigcup_{x \in \mathbf{U}_0} \mathbf{j}(x) \cap \partial\Omega = \bigcup_{k=1}^{N_1} \partial\mathbf{C}_{1,k} \cap \partial\Omega \text{ are non degenerate local minima of } f|_{\partial\Omega}. \quad (48)$$

In the rest of this section, one assumes that $f : \bar{\Omega} \rightarrow \mathbb{R}$ is a C^∞ Morse function which satisfies the assumptions **(H1)** and **(H2)**.

4.1 Adapted coordinate systems

Let us recall that for any $x \in \mathbf{U}_0$, from the construction of the map \mathbf{j} made in Section 3.3 and from **(H1)**–**(H2)**, $\mathbf{j}(x)$ contains saddle points of f in $\bar{\Omega}$ (see Definition 16) which are in finite number and may be of two kinds: the elements $z \in \mathbf{j}(x) \cap \partial\Omega$, such that either $|\nabla f(z)| \neq 0$ or $|\nabla f(z)| = 0$, and the elements $z \in \mathbf{j}(x) \cap \Omega$, such that $|\nabla f(z)| = 0$.

For any $x \in \mathbf{U}_0$ and $z \in \mathbf{j}(x)$, we first construct a coordinate systems in a neighborhood of z as follows.

1.a) The case when $z \in \partial\Omega$ and $|\nabla f(z)| \neq 0$.

Let us recall that z is in this case a non degenerate local minimum of $f|_{\partial\Omega}$ and that $\mu := \partial_{\mathbf{n}_\Omega} f(z) > 0$. Then, according for example to [17, Section 3.4], there exists a neighbourhood \mathbf{V}_z of z in $\bar{\Omega}$ and a coordinate system

$$p \in \mathbf{V}_z \mapsto v = (v', v_d) = (v_1, \dots, v_{d-1}, v_d) \in \mathbb{R}^{d-1} \times \mathbb{R}_- \quad (49)$$

such that

$$v(z) = 0, \quad \{p \in \mathbf{V}_z, v_d(p) < 0\} = \Omega \cap \mathbf{V}_z, \quad \{p \in \mathbf{V}_z, v_d(p) = 0\} = \partial\Omega \cap \mathbf{V}_z, \quad (50)$$

and

$$\forall i, j \in \{1, \dots, d\}, \quad g_z\left(\frac{\partial}{\partial v_i}(z), \frac{\partial}{\partial v_j}(z)\right) = \delta_{ij} \quad \text{and} \quad \frac{\partial}{\partial v_d}(z) = \mathbf{n}_\Omega(z), \quad (51)$$

with moreover, in the v coordinates,

$$f(v', v_d) = f(0) + \mu v_d + \frac{1}{2}(v')^T \text{Hess } f|_{\{v_d=0\}}(0) v'. \quad (52)$$

For $\delta_1 > 0$ and $\delta_2 > 0$ small enough, one then defines the following neighborhood of z in $\partial\Omega$,

$$\mathbf{V}_{\partial\Omega}^{\delta_1, \delta_2}(z) := \{p \in \mathbf{V}_z, v_d(p) = 0 \text{ and } |v'(p)| \leq \delta_2\} \text{ (see (49)-(50))} \quad (53)$$

and the following neighbourhood of z in $\bar{\Omega}$,

$$\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z) = \{p \in \mathbf{V}_z, |v'(p)| \leq \delta_2 \text{ and } v_d(p) \in [-2\delta_1, 0]\}. \quad (54)$$

1.b) The case when $z \in \partial\Omega$ and $|\nabla f(z)| = 0$.

Let V_z be a neighborhood of z in $\bar{\Omega}$ and let

$$p \in V_z \mapsto v = (v', v_d) \in \mathbb{R}^{d-1} \times \mathbb{R}_- \quad (55)$$

be a coordinate system such that

$$v(z) = 0, \quad \{p \in V_z, v_d(p) < 0\} = \Omega \cap V_z, \quad \{p \in V_z, v_d(p) = 0\} = \partial\Omega \cap V_z, \quad (56)$$

and

$$\forall i, j \in \{1, \dots, d\}, \quad g_z\left(\frac{\partial}{\partial v_i}(z), \frac{\partial}{\partial v_j}(z)\right) = \delta_{ij} \quad \text{and} \quad \frac{\partial}{\partial v_d}(z) = \mathbf{n}_\Omega(z). \quad (57)$$

Let us also recall that z is a non degenerate saddle point of f in $\partial\Omega$ such that, according to **(H1)**, $\mathbf{n}_\Omega(z)$ is an eigenvector associated with the negative eigenvalue μ_d of $\text{Hess } f(z)$. Thus, denoting by μ_1, \dots, μ_{d-1} the positive eigenvalues of $\text{Hess } f(z)$, the coordinates $v' = (v_1, \dots, v_{d-1})$ can be chosen so that it holds, in the v coordinates,

$$f(v) = f(0) + \frac{1}{2} \sum_{j=1}^d \mu_j v_j^2 + O(|v|^3) = f(0) + \frac{1}{2} \sum_{j=1}^{d-1} |\mu_j| v_j^2 - \frac{1}{2} |\mu_d| v_d^2 + O(|v|^3). \quad (58)$$

Therefore, up to choosing V_z again smaller, one can assume that

$$\arg \min_{V_z} (f(v) + |\mu_d| v_d^2) = \{z\}. \quad (59)$$

For $\delta_1 > 0$ and $\delta_2 > 0$ small enough, one defines the following neighborhood of z in $\partial\Omega$,

$$V_{\partial\Omega}^{\delta_2}(z) := \{p \in V_z, v_d(p) = 0 \text{ and } |v'(p)| \leq \delta_2\} \quad (\text{see (55)-(56)}), \quad (60)$$

and the following neighbourhood of z in $\bar{\Omega}$,

$$V_{\bar{\Omega}}^{\delta_1, \delta_2}(z) = \{p \in V_z, |v'(p)| \leq \delta_2 \text{ and } v_d(p) \in [-2\delta_1, 0]\}. \quad (61)$$

2. The case when $z \in \Omega$.

Let us recall that in this case z is a non degenerate saddle point of f in Ω . Let $(\mathbf{e}_1, \dots, \mathbf{e}_d)$ be an orthonormal basis of eigenvectors of $\text{Hess } f(z)$ associated with its eigenvalues (μ_1, \dots, μ_d) with $\mu_d < 0$ and, for all $j \in \{1, \dots, d-1\}$, $\mu_j > 0$. Then, since \mathbf{e}_d is normal to $W_+(z)$, as in the case when $z \in \partial\Omega$ and $|\nabla f(z)| = 0$ and up to replacing \mathbf{e}_d by $-\mathbf{e}_d$, there exists a coordinate system

$$p \in V_z \mapsto v = (v', v_d) \in \mathbb{R}^{d-1} \times \mathbb{R} \quad (62)$$

such that

$$v(z) = 0, \quad C_j(x) \cap V_z \subset \{p \in V_z, v_d(p) < 0\}, \quad \{p \in V_z, v_d(p) = 0\} = W_+(z) \cap V_z, \quad (63)$$

and

$$\forall i, j \in \{1, \dots, d\}, \quad g_z\left(\frac{\partial}{\partial v_i}(z), \frac{\partial}{\partial v_j}(z)\right) = \delta_{ij} \quad \text{and} \quad \frac{\partial}{\partial v_d}(z) = \mathbf{e}_d, \quad (64)$$

with moreover, in the v coordinates,

$$f(v) = f(0) + \frac{1}{2} \sum_{j=1}^d \mu_j v_j^2 + O(|v|^3) = f(0) + \frac{1}{2} \sum_{j=1}^{d-1} |\mu_j| v_j^2 - \frac{1}{2} |\mu_d| v_d^2 + O(|v|^3). \quad (65)$$

Then, up to choosing V_z smaller, one can assume that

$$\arg \min_{V_z} (f(v) + |\mu_d| v_d^2) = \{z\}. \quad (66)$$

Then, for $\delta_1 > 0$ and $\delta_2 > 0$ small enough, one defines the following neighbourhood of z in $W^+(z)$ (see (62) and (63)),

$$V_{W^+}^{\delta_2}(z) := \{p \in V_z, v_d(p) = 0 \text{ and } |v'(p)| \leq \delta_2\} \subset W^+(z), \quad (67)$$

and the following neighbourhood of z in Ω ,

$$V_{\Omega}^{\delta_1, \delta_2}(z) = \{p \in V_z, |v'(p)| \leq \delta_2 \text{ and } v_d \in [-2\delta_1, 2\delta_1]\}. \quad (68)$$

Notice that one has:

$$\arg \min_{V_{W^+}^{\delta_2}(z)} f = \{z\}. \quad (69)$$

Some properties of these coordinate systems.

The sets defined in (54), (61), and (68) are cylinders centred at z in the respective system of coordinates. Up to choosing $\delta_1 > 0$ and $\delta_2 > 0$ smaller, one can assume that all these cylinders are two by two disjoint. Schematic representations of these sets introduced in (53)–(68) are given in Figures 4, 5 and 6.

Let us conclude this section by giving several properties of the sets previously introduced which will be needed for upcoming computations. Let us recall that, from (41), when $z \in \mathbf{j}(x)$ for some $x \in U_0$, it holds $f(z) > f(x)$. Moreover, by construction of the map \mathbf{j} in Section 3.3, it obviously holds $U_0 \cap \cup_{x \in U_0} \mathbf{j}(x) = \emptyset$. Therefore, up to choosing $\delta_1 > 0$ and $\delta_2 > 0$ small enough, the following properties are satisfied:

1. When $z \in \partial\Omega \cap \mathbf{j}(x)$ for some $x \in U_0$, it holds

$$\min_{V_{\Omega}^{\delta_1, \delta_2}(z)} f > f(x), \quad V_{\Omega}^{\delta_1, \delta_2}(z) \cap U_0 = \emptyset, \quad (70)$$

and

$$\arg \min_{V_{\partial\Omega}^{\delta_2}(z)} f = \{z\} \quad (\text{which follows from (48)}). \quad (71)$$

2. When $z \in \Omega \cap \mathbf{j}(x)$ for some $x \in U_0$, it holds:

$$\min_{V_{\Omega}^{\delta_1, \delta_2}(z)} f > f(x) \quad \text{and} \quad V_{\Omega}^{\delta_1, \delta_2}(z) \cap U_0 = \emptyset. \quad (72)$$

The parameter $\delta_2 > 0$ is now kept fixed. Finally, using (69), (71), and up to choosing $\delta_1 > 0$ smaller, there exists $r > 0$ such that (see Figures 4, 5 and 6):

1. For all $z \in \partial\Omega \cap \mathbf{j}(x)$ for some $x \in \mathbf{U}_0$,

$$\{p \in \mathbf{V}_z, |v'(p)| = \delta_2 \text{ and } v_d(p) \in [-2\delta_1, 0]\} \subset \{f \geq f(z) + r\}. \quad (73)$$

2. For all $z \in \Omega \cap \mathbf{j}(x)$ for some $x \in \mathbf{U}_0$,

$$\{p \in \mathbf{V}_z, |v'(p)| = \delta_2 \text{ and } v_d \in [-2\delta_1, 2\delta_1]\} \subset \{f \geq f(z) + r\}. \quad (74)$$

The parameter $\delta_1 > 0$ is now kept fixed.

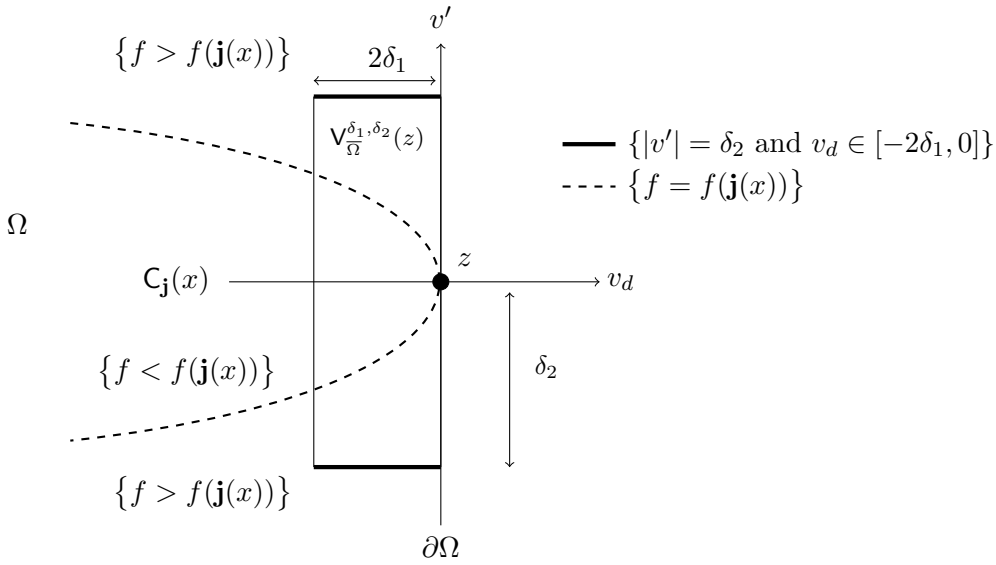


Figure 4: Schematic representation of the cylinder $\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)$ when $z \in \mathbf{j}(x) \cap \partial\Omega$ (for some $x \in \mathbf{U}_0$) is such that $|\nabla f(z)| \neq 0$. One recalls that $\mathbf{j}(x) \subset \partial\mathbf{C}_{\mathbf{j}(x)}$ and that, in this case, z is a non degenerate local minimum of $f|_{\partial\Omega}$ and $\partial_{n_{\Omega}}f(z) > 0$.

4.2 Quasi-modal construction near the elements of $\cup_{x \in \mathbf{U}_0} \mathbf{j}(x)$

Let us introduce an even cut-off function $\chi \in C^{\infty}(\mathbb{R}, [0, 1])$ such that

$$\text{supp } \chi \subset [-\delta_1, \delta_1] \text{ and } \chi = 1 \text{ on } \left[-\frac{\delta_1}{2}, \frac{\delta_1}{2}\right]. \quad (75)$$

Let $z \in \cup_{x \in \mathbf{U}_0} \mathbf{j}(x)$. Then, the function φ_z associated with z and x is defined as follows:

1. Let us assume that $z \in \partial\Omega$.

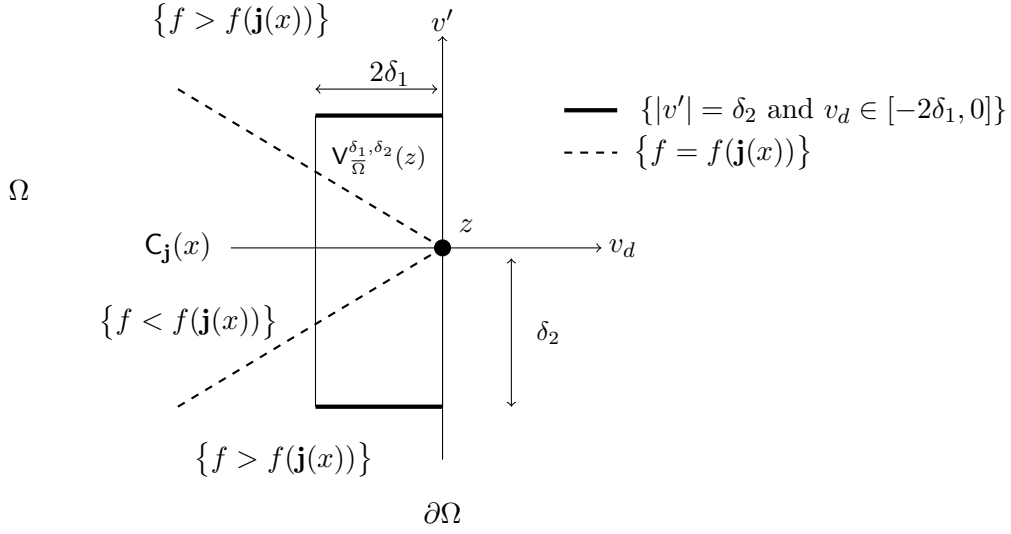


Figure 5: Schematic representation of the cylinder $V_{\Omega}^{\delta_1, \delta_2}(z)$ when $z \in \mathbf{j}(x) \cap \partial\Omega$ (for some $x \in U_0$) is such that $|\nabla f(z)| = 0$. One recalls that $\mathbf{j}(x) \subset \partial C_{\mathbf{j}}(x)$ and that, in this case, z is a non degenerate saddle point of f and a non degenerate local minimum of $f|_{\partial\Omega}$.

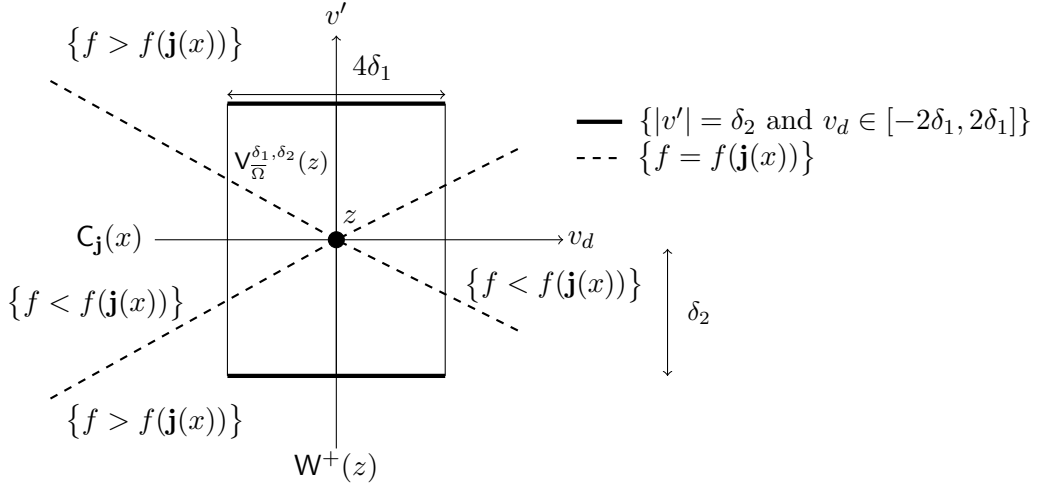


Figure 6: Schematic representation of the cylinder $V_{\Omega}^{\delta_1, \delta_2}(z)$ when $z \in \mathbf{j}(x) \cap \Omega$ for some $x \in U_0$. One recalls that $\mathbf{j}(x) \subset \partial C_{\mathbf{j}}(x)$ and that, in this case, z is a separating saddle point of f in Ω (see Definition 9).

(a) When $|\nabla f(z)| \neq 0$, one defines (see (49), (50), and (54)):

$$\forall v = (v', v_d) \in v(V_{\Omega}^{\delta_1, \delta_2}(z)), \quad \varphi_z(v', v_d) := \frac{\int_{v_d}^0 \chi(t) e^{\frac{2}{\hbar} \mu t} dt}{\int_{-2\delta_1}^0 \chi(t) e^{\frac{2}{\hbar} \mu t} dt}, \quad (76)$$

where we recall that $\mu = \partial_{n_{\Omega}} f(z) > 0$. Note that the function φ_z only

depends on the variable v_d . Moreover, it holds (see (75)),

$$\begin{cases} \varphi_z \in C^\infty(v(\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)), [0, 1]) \text{ and} \\ \forall (v', v_d) \in v(\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)), \varphi_z(v', v_d) = 1 \text{ if } v_d \in [-2\delta_1, -\delta_1]. \end{cases} \quad (77)$$

(b) When $|\nabla f(z)| = 0$, one defines (see (55), (56), and (61)):

$$\forall v = (v', v_d) \in v(\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)), \quad \varphi_z(v', v_d) := \frac{\int_{v_d}^0 \chi(t) e^{-\frac{1}{h}|\mu_d|t^2} dt}{\int_{-2\delta_1}^0 \chi(t) e^{-\frac{1}{h}|\mu_d|t^2} dt}, \quad (78)$$

where we recall that $\mu_d < 0$ is the negative eigenvalue of $\text{Hess}(f)(z)$. The function φ_z thus only depends on the variable v_d and it holds

$$\begin{cases} \varphi_z \in C^\infty(v(\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)), [0, 1]) \text{ and} \\ \forall (v', v_d) \in v(\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)), \varphi_z(v', v_d) = 1 \text{ if } v_d \in [-2\delta_1, -\delta_1]. \end{cases} \quad (79)$$

2. Let us assume that $z \in \Omega$. We recall that in this case, z is a separating saddle point of f in Ω (by construction of the map \mathbf{j} , see also Definition 9). Then, one defines the function (see (62), (63), and (68)):

$$\forall v = (v', v_d) \in v(\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)), \quad \varphi_z(v', v_d) := \frac{\int_{v_d}^{2\delta_1} \chi(t) e^{-\frac{1}{h}|\mu_d|t^2} dt}{\int_{-2\delta_1}^{2\delta_1} \chi(t) e^{-\frac{1}{h}|\mu_d|t^2} dt}, \quad (80)$$

where μ_d is the negative eigenvalues of $\text{Hess} f(z)$. Again, φ_z only depends on the variable v_d and it holds:

$$\varphi_z \in C^\infty\left(v(\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)), [0, 1]\right) \quad (81)$$

and for all $(v', v_d) \in v(\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z))$,

$$\varphi_z(v', v_d) = 1 \text{ if } v_d \in [-2\delta_1, -\delta_1] \text{ and } \varphi_z(v', v_d) = 0 \text{ if } v_d \in [\delta_1, 2\delta_1]. \quad (82)$$

4.3 Construction of m_0 quasi-modes for $\Delta_{f,h}^D$

In the following, one considers some arbitrary

$$x \in \mathbf{U}_0.$$

Let us recall the geometry of f near its critical component $\partial\mathbf{C}_{\mathbf{j}}(x)$. Let us consider a point $p \in \partial\mathbf{C}_{\mathbf{j}}(x) \setminus \mathbf{j}(x)$. Since $\mathbf{j}(x) = \partial\mathbf{C}_{\mathbf{j}}(x) \cap \mathbf{U}_1^{\text{ssp}}(\bar{\Omega})$ and $\partial\mathbf{C}_{\mathbf{j}}(x) \cap \partial\Omega \subset \mathbf{j}(x)$, $p \in \Omega \setminus \mathbf{U}_1^{\text{ssp}}(\Omega)$. Thus, there are two possible cases:

- Either p is saddle point of f in Ω . From Lemma 8, $\{f < f(\mathbf{j}(x))\} \cap B(p, r)$ has then, for $r > 0$ small enough, two connected components which are included in $\mathbf{C}_{\mathbf{j}}(x)$, since p is not separating (see Figure 8).
- Or p is not a saddle point of f in Ω . According to Lemma 8, $\{f < f(\mathbf{j}(x))\} \cap B(p, r)$ is then connected for $r > 0$ small enough and is thus included in $\mathbf{C}_{\mathbf{j}}(x)$.

In conclusion, when $p \in \partial\mathbf{C}_{\mathbf{j}}(x) \setminus \mathbf{j}(x)$, $\{f < f(\mathbf{j}(x))\} \cap B(p, r)$ is included in $\mathbf{C}_{\mathbf{j}}(x) \cap \Omega$ for $r > 0$ small enough. Moreover, one constructed in (54), (61), and (68), disjoint cylinders in neighborhoods of each $z \in \cup_{y \in \mathbf{U}_0} \mathbf{j}(y)$ which satisfy (70) and (72)–(74). This makes possible the construction used in the definition below.

Definition 20. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. Then $\mathbf{U}_0 \neq \emptyset$ and, for each $x \in \mathbf{U}_0$, there exist two C^∞ connected open sets $\Omega_1(x)$ and $\Omega_2(x)$ of Ω satisfying the following properties:*

1. For all $x \in \mathbf{U}_0$, it holds

$$\overline{\mathbf{C}_{\mathbf{j}}(x)} \subset \Omega_1(x) \quad \text{and} \quad \arg \min_{\overline{\Omega_1(x)}} f = \arg \min_{\overline{\mathbf{C}_{\mathbf{j}}(x)}} f.$$

2. For all $x \in \mathbf{U}_0$, $\overline{\Omega_2(x)} \subset \Omega_1(x)$ and the strip $\overline{\Omega_1(x)} \setminus \Omega_2(x)$ equal:

$$\overline{\Omega_1(x)} \setminus \Omega_2(x) = \bigcup_{z \in \mathbf{j}(x)} \mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z) \bigcup \mathbf{O}_1(x), \quad (83)$$

where there exists $c > 0$ such that:

$$\forall q \in \mathbf{O}_1(x), \quad f(q) \geq f(\mathbf{j}(x)) + c. \quad (84)$$

Notice that item 1, (83), (84), and the first statements in (70) and in (72) imply that $\arg \min_{\overline{\Omega_1(x)}} f = \arg \min_{\overline{\Omega_2(x)}} f = \arg \min_{\overline{\mathbf{C}_{\mathbf{j}}(x)}} f$.

3. For all $x, y \in \mathbf{U}_0$ such that $x \neq y$, it holds (depending on the two possible cases described in items 4.(i) and 4.(ii) in Section 3.3):

(i) If $\mathbf{j}(y) \cap \mathbf{j}(x) = \emptyset$:

$$\begin{cases} \text{either } \overline{\mathbf{C}_{\mathbf{j}}(y)} \cap \overline{\mathbf{C}_{\mathbf{j}}(x)} = \emptyset \text{ and } \overline{\Omega_1(x)} \cap \overline{\Omega_1(y)} = \emptyset, \\ \text{or, up to switching } x \text{ and } y, \overline{\mathbf{C}_{\mathbf{j}}(y)} \subset \overline{\mathbf{C}_{\mathbf{j}}(x)} \text{ and } \overline{\Omega_1(y)} \subset \overline{\Omega_2(x)}. \end{cases}$$

(ii) If $\mathbf{j}(y) \cap \mathbf{j}(x) \neq \emptyset$ (in this case, one recalls that $f(\mathbf{j}(y)) = f(\mathbf{j}(x))$ and thus, $\mathbf{C}_{\mathbf{j}}(y)$ and $\mathbf{C}_{\mathbf{j}}(x)$ are two connected components of $\{f < f(\mathbf{j}(x))\}$), then:

$$\overline{\Omega_1(x)} \cap \overline{\Omega_1(y)} = \bigcup_{z \in \mathbf{j}(y) \cap \mathbf{j}(x)} \mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z) \bigcup \mathbf{O}_2(x),$$

where $\mathbf{O}_2(x) \subset \mathbf{O}_1(x)$ and $\mathbf{O}_2(x) \cap \mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z) = \emptyset$ for all $z \in \mathbf{j}(y) \cup \mathbf{j}(x)$.

For $x \in \mathbf{U}_0$, schematic representations of $\Omega_1(x)$, $\Omega_2(x)$, and $\mathbf{O}_1(x)$ are given in Figures 7 and 8. With the help of the sets $\Omega_1(x)$ and $\Omega_2(x)$ introduced in Definition 20, one defines a smooth function $\phi_x : \bar{\Omega} \rightarrow [0, 1]$ associated with each $x \in \mathbf{U}_0$ as follows.

Definition 21. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. For each $x \in \mathbf{U}_0$, a function $\phi_x : \bar{\Omega} \rightarrow [0, 1]$ is constructed as follows:*

1. For every $z \in \mathbf{j}(x)$, ϕ_x is defined on the cylinder $V_{\bar{\Omega}}^{\delta_1, \delta_2}(z)$ (see (54), (61), and (68)) by

$$\forall p \in V_{\bar{\Omega}}^{\delta_1, \delta_2}(z), \phi_x(p) := \varphi_z(v(p)), \quad \text{see (76), (78), and (80)}. \quad (85)$$

2. From (77), (79), (81), (82), and the facts that $\overline{\Omega_2(x)} \subset \Omega_1(x)$ (see Definition 20) and (83) holds, ϕ_x can be extended to $\bar{\Omega}$ such that

$$\phi_x = 0 \text{ on } \bar{\Omega} \setminus \Omega_1(x), \quad \phi_x = 1 \text{ on } \Omega_2(x), \text{ and } \phi_x \in C^\infty(\bar{\Omega}, [0, 1]). \quad (86)$$

Notice that (86) implies that:

$$\text{supp } d\phi_x \subset \overline{\Omega_1(x)} \setminus \Omega_2(x). \quad (87)$$

Finally, in view of (76), (78), (80), and (83), ϕ_x can be chosen on O_1 such that for some $C > 0$ and for every h small enough (see indeed (96), (102), and (106) below):

$$\forall \alpha \in \mathbb{N}^d, |\alpha| \in \{1, 2\}, \|\partial_\alpha \phi_x\|_{L^\infty(O_1(x))} \leq \frac{C}{h^2}. \quad (88)$$

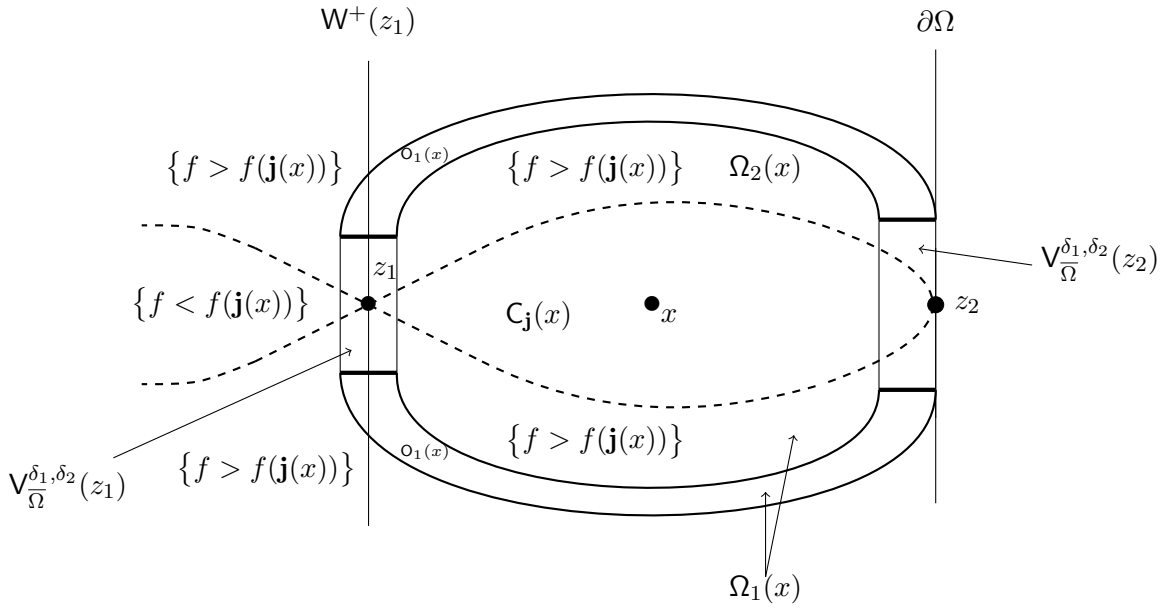


Figure 7: Schematic representation of $\Omega_2(x)$, $\Omega_1(x)$, and $O_1(x)$ (see Definition 20). On the figure, $\mathbf{j}(x) = \{z_1, z_2\}$ with $z_1 \in \Omega$ and $z_2 \in \partial\Omega$ ($|\nabla f(z_2)| = 0$).

Let us now define, for each $x \in U_0$, the quasi-mode $\psi_x : \bar{\Omega} \rightarrow \mathbb{R}^+$ of $\Delta_{f,h}^D$ as follows.

Definition 22. Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. For every $x \in U_0$, one defines

$$\psi_x := \frac{\phi_x e^{-\frac{f}{h}}}{Z_x} \quad \text{and} \quad Z_x := \|\phi_x e^{-\frac{f}{h}}\|_{L^2(\Omega)},$$

where ϕ_x is the function introduced in Definition 21.

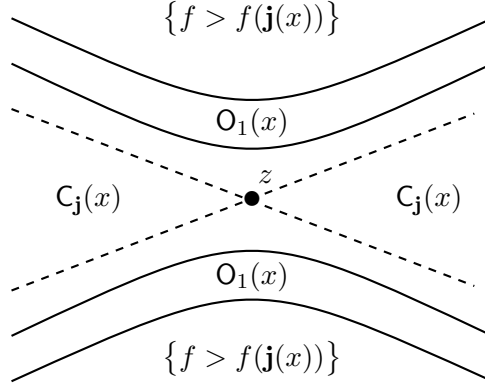


Figure 8: Schematic representation of $O_1(x)$ (see (84)) in a neighborhood of a non-separating saddle points z of f on $\partial C_j(x)$.

By construction of ϕ_x in Definition 21, $\psi_x \in C^\infty(\bar{\Omega}, \mathbb{R}^+)$ and $\psi_x = 0$ on $\partial\Omega$ (see indeed (86) together with the fact that $\Omega_1(x) \subset \Omega$, see Definition 20). In particular:

$$\psi_x \in D(\Delta_{f,h}^D) = H^2(\Omega) \cap H_0^1(\Omega). \quad (89)$$

5 Asymptotic equivalents of the small eigenvalues of $\Delta_{f,h}^D$

5.1 First quasi-modal estimates

Let us start with the following result which gives asymptotic estimates on the L^2 -norms of $d_{f,h}(\psi_x)$ and of $\Delta_{f,h}(\psi_x)$ around the points $z \in \mathbf{j}(x)$ in the limit $h \rightarrow 0$.

Proposition 23. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. Let $x \in \mathbf{U}_0$, ψ_x be as introduced in Definition 22, and $z \in \mathbf{j}(x)$.*

1. *Let us assume that $z \in \partial\Omega$.*

(a) *When $|\nabla f(z)| \neq 0$ (recall that in this case z is a non degenerate local minimum of $f|_{\partial\Omega}$ and $\partial_{n\Omega} f(z) > 0$, see item (a) in Corollary 13 and (46)), it holds in the limit $h \rightarrow 0$:*

$$\left\{ \begin{array}{l} \int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} |d_{f,h} \psi_x|^2 = c_{x,z} \sqrt{h} e^{-\frac{2}{h}(f(\mathbf{j}(x)) - f(x))} (1 + O(h)), \\ \text{where } c_{x,z} := \frac{2 \partial_{n\Omega} f(z)}{\sqrt{\pi}} \frac{(\det \text{Hess } f|_{\partial\Omega}(z))^{-\frac{1}{2}}}{\sum_{q \in \arg \min_{C_j(x)} f} (\det \text{Hess } f(q))^{-\frac{1}{2}}}. \end{array} \right. \quad (90)$$

Furthermore, one has when $h \rightarrow 0$:

$$\int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} |\Delta_{f,h} \psi_x|^2 = O(h^2) \int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} |d_{f,h} \psi_x|^2.$$

(b) When $|\nabla f(z)| = 0$ (recall that in this case z is a saddle point of f in $\partial\Omega$, see item (b) in Corollary 13), it holds in the limit $h \rightarrow 0$:

$$\left\{ \begin{array}{l} \int_{\sqrt{\delta_1, \delta_2}(z)} |d_{f,h} \psi_x|^2 = \mathbf{c}_{x,z} h e^{-\frac{2}{h}(f(\mathbf{j}(x)) - f(x))} (1 + O(\sqrt{h})), \\ \text{where } \mathbf{c}_{x,z} := \frac{2|\mu_d|}{\pi} \frac{|\det \text{Hess } f(z)|^{-\frac{1}{2}}}{\sum_{q \in \arg \min_{\mathbf{C}_j(x)} f} (\det \text{Hess } f(q))^{-\frac{1}{2}}}, \end{array} \right. \quad (91)$$

where we recall that $\mu_d < 0$ is the negative eigenvalue of $\text{Hess } f(z)$. Moreover, when $h \rightarrow 0$, one has:

$$\int_{\sqrt{\delta_1, \delta_2}(z)} |\Delta_{f,h} \psi_x|^2 = O(h^2) \int_{\sqrt{\delta_1, \delta_2}(z)} |d_{f,h} \psi_x|^2.$$

2. Let us assume that $z \in \Omega$ (recall that in this case z is a saddle point of f in Ω). Then, it holds in the limit $h \rightarrow 0$:

$$\left\{ \begin{array}{l} \int_{\sqrt{\delta_1, \delta_2}(z)} |d_{f,h} \psi_x|^2 = \mathbf{c}_{x,z} h e^{-\frac{2}{h}(f(\mathbf{j}(x)) - f(x))} (1 + O(h)), \\ \text{where } \mathbf{c}_{x,z} := \frac{|\mu_d|}{\pi} \frac{|\det \text{Hess } f(z)|^{-\frac{1}{2}}}{\sum_{q \in \arg \min_{\mathbf{C}_j(x)} f} (\det \text{Hess } f(q))^{-\frac{1}{2}}}, \end{array} \right. \quad (92)$$

where we recall that $\mu_d < 0$ is the negative eigenvalue of $\text{Hess } f(z)$. Finally, when $h \rightarrow 0$, one has:

$$\int_{\sqrt{\delta_1, \delta_2}(z)} |\Delta_{f,h} \psi_x|^2 = O(h^2) \int_{\sqrt{\delta_1, \delta_2}(z)} |d_{f,h} \psi_x|^2.$$

Remark 24. The remainder term $O(\sqrt{h})$ in (91) follows from the Laplace method applied to $\int_{\mathbb{R}^d \cap B(0,r)} \varphi_2 e^{-\frac{1}{h}\varphi_1}$ when $|\nabla \varphi_1(0)| = 0$, $\text{Hess } \varphi_1(0) > 0$, and 0 is the unique minimum of φ_1 on $\overline{B(0,r)}$, see (103) and the lines below (when $d = 1$, this is also known as Watson's lemma). On the other hand, the $O(h)$ in (92) arises from the standard Laplace method, i.e. when considering $\int_{B(0,r)} \varphi_2 e^{-\frac{1}{h}\varphi_1}$. In particular, these remainder terms are optimal.

Proof. Let $x \in \mathbf{U}_0$. Then, according to Definitions 22 and 21, one has

$$Z_x^2 = \int_{\Omega} \phi_x^2 e^{-\frac{2}{h}f} = \int_{\Omega_1(x)} \phi_x^2 e^{-\frac{2}{h}f} = \int_{\Omega_2(x)} \phi_x^2 e^{-\frac{2}{h}f} + \int_{\Omega_1(x) \setminus \Omega_2(x)} \phi_x^2 e^{-\frac{2}{h}f}.$$

Let us recall that by construction $0 \leq \phi_x \leq 1$ on Ω . Moreover, from the first statements in (70) and (72) together with (83) and (84), there exists $c > 0$ such that $f \geq f(x) + c$ on $\overline{\Omega_1(x)} \setminus \Omega_2(x)$. Thus, it holds, for some $C > 0$ independent of h :

$$\int_{\Omega_1(x) \setminus \Omega_2(x)} \phi_x^2 e^{-\frac{2}{h}f} \leq C e^{-\frac{2}{h}(f(x)+c)}.$$

In addition, since $\phi_x = 1$ on $\Omega_2(x)$ (see (86)) and

$$\arg \min_{\overline{\Omega_1(x)}} f = \arg \min_{\overline{\Omega_2(x)}} f = \arg \min_{\mathbf{C}_j(x)} f \quad (\text{see item 2 in Definition 20})$$

consists in a finite number of non degenerate local minima q of f in Ω such that $f(q) = f(x)$ (since by construction of \mathbf{C}_j , $x \in \arg \min_{\mathbf{C}_j(x)} f$), one has when $h \rightarrow 0$, using the Laplace method,

$$\int_{\Omega_2(x)} \phi_x^2 e^{-\frac{2}{h}f} = \sum_{q \in \arg \min_{\mathbf{C}_j(x)} f} \frac{(\pi h)^{\frac{d}{2}}}{\sqrt{\det \text{Hess } f(q)}} e^{-\frac{2}{h}f(x)} (1 + O(h)).$$

Therefore, when $h \rightarrow 0$,

$$Z_x = (\pi h)^{\frac{d}{4}} \left(\sum_{q \in \arg \min_{\mathbf{C}_j(x)} f} (\det \text{Hess } f(q))^{-\frac{1}{2}} \right)^{\frac{1}{2}} e^{-\frac{1}{h}f(x)} (1 + O(h)). \quad (93)$$

Let now z belong to $\mathbf{j}(x)$. The rest of the proof of Proposition 23 is divided into two steps, whether $z \in \partial\Omega$ or $z \in \Omega$.

Step 1.a) The case when $z \in \partial\Omega$ and $|\nabla f(z)| \neq 0$.

In this case, from Definition 22, one has

$$\int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} |d_{f,h} \psi_x|^2 = h^2 \frac{\int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} |d\phi_x|^2 e^{-\frac{2}{h}f}}{Z_x^2}. \quad (94)$$

Moreover, according to (85) and to (76), it holds:

$$\int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} |d\phi_x|^2 e^{-\frac{2}{h}f} = \frac{\int_{|v'| \leq \delta_2} \int_{v_d = -2\delta_1}^0 |dv_d|^2 \chi^2(v_d) e^{-\frac{2}{h}(f-2\mu v_d)} d_g v}{\left(\int_{-2\delta_1}^0 \chi(t) e^{\frac{2}{h}\mu t} dt \right)^2}, \quad (95)$$

where we recall that $\mu = \partial_{n_\Omega} f(z) > 0$, and $d_g v = \sqrt{\det g} dv$ denotes the Riemannian volume form. A straightforward computation (see (75)) implies that there exists $c > 0$ such that in the limit $h \rightarrow 0$,

$$N_z := \int_{-2\delta_1}^0 \chi(t) e^{\frac{2}{h}\mu t} dt = \frac{h}{2\mu} (1 + O(e^{-\frac{c}{h}})). \quad (96)$$

Moreover, from the Laplace method together with, (75), (52), and (51), one has when $h \rightarrow 0$:

$$\int_{|v'| \leq \delta_2} \int_{-2\delta_1}^0 |dv_d|^2 \chi^2(v_d) e^{-\frac{2}{h}(f-2\mu v_d)} d_g v = \frac{h}{2\mu} \frac{(\pi h)^{\frac{d-1}{2}} e^{-\frac{2}{h}f(0)}}{(\det \text{Hess } f|_{\{v_d=0\}}(0))^{\frac{1}{2}}} (1 + O(h)), \quad (97)$$

where we recall that with our notation, $f(0) = f(z) = f(\mathbf{j}(x))$ since $z \in \mathbf{j}(x)$ (see item 4 in Section 3.3). The relations (94)–(97) and (93) lead to the first statement

of item 1.(a) in Proposition 23. Let us now prove the second statement of item 1.(a). Since $\Delta_{f,h} = 2he^{-\frac{f}{h}} \left(\frac{h}{2} \Delta_H + \nabla f \cdot \nabla \right) e^{\frac{f}{h}}$, one has

$$\Delta_{f,h} \psi_x = \frac{2he^{-\frac{f}{h}}}{Z_x} \left(\frac{h}{2} \Delta_H + \nabla f \cdot \nabla \right) \phi_x = \frac{2he^{-\frac{f}{h}}}{Z_x} \left(\frac{h}{2} d^* d \phi_x + df(\nabla \phi_x) \right). \quad (98)$$

Thus, according to (76) and to (52), it holds on $V_{\Omega}^{\delta_1, \delta_2}(z)$,

$$\begin{aligned} \Delta_{f,h} \psi_x &= \frac{2he^{-\frac{f}{h}}}{Z_x} \left(\frac{h}{2} d^* d \varphi_z + df(\nabla \varphi_z) \right) \\ &= \frac{2he^{-\frac{f}{h}}}{Z_x N_z} \left(\frac{h}{2} d^* \left(-\chi(v_d) e^{\frac{2}{h} \mu v_d} dv_d \right) - \mu dv_d \left(\chi(v_d) e^{\frac{2}{h} \mu v_d} \nabla v_d \right) + O(|v|^2) \right) \\ &= \frac{2he^{-\frac{f}{h}} e^{\frac{2}{h} \mu v_d}}{Z_x N_z} \left(O(h) + \frac{h}{2} \chi(v_d) dv_d \left(\frac{2}{h} \mu \nabla v_d \right) - \mu dv_d \left(\chi(v_d) \nabla v_d \right) + O(|v|^2) \right) \\ &= \frac{h e^{-\frac{1}{h}(f-2\mu v_d)}}{Z_x N_z} \left(O(h) + O(|v|^2) \right), \end{aligned} \quad (99)$$

where N_z is defined by (96). It then follows from (93) that for every h small enough, it holds

$$\int_{V_{\Omega}^{\delta_1, \delta_2}(z)} |\Delta_{f,h} \psi_x|^2 = O(h^2) \sqrt{h} e^{-\frac{2}{h}(f(z)-f(x))} = O(h^2) \int_{V_{\Omega}^{\delta_1, \delta_2}(z)} |d_{f,h} \psi_x|^2,$$

which concludes the proof of item 1.(a) in Proposition 23.

Step 1.b) The case when $|\nabla f(z)| = 0$.

From Definition 22, it holds

$$\int_{V_{\Omega}^{\delta_1, \delta_2}(z)} |d_{f,h} \psi_x|^2 = h^2 \frac{\int_{V_{\Omega}^{\delta_1, \delta_2}(z)} |d\phi_x|^2 e^{-\frac{2}{h}f}}{Z_x}, \quad (100)$$

where, according to (85) and (78),

$$\int_{V_{\Omega}^{\delta_1, \delta_2}(z)} |d\phi_x|^2 e^{-\frac{2}{h}f} = \frac{\int_{|v'| \leq \delta_2} \int_{v_d = -2\delta_1}^0 |dv_d|^2 \chi^2(v_d) e^{-\frac{2}{h}(f+|\mu_d|v_d^2)} d_g v}{\left(\int_{-2\delta_1}^0 \chi(t) e^{-\frac{1}{h}|\mu_d|t^2} dt \right)^2}, \quad (101)$$

where we recall that μ_d is the negative eigenvalue of Hess $f(z)$ and a straightforward computation (see (75)) implies that there exists $c > 0$ such that in the limit $h \rightarrow 0$,

$$N_z := \int_{-2\delta_1}^0 \chi(t) e^{-\frac{1}{h}|\mu_d|t^2} dt = \frac{\sqrt{\pi h}}{2\sqrt{|\mu_d|}} (1 + O(e^{-\frac{c}{h}})). \quad (102)$$

Furthermore, from, (75), (57), (58), and (59) together with the Laplace method, one has in the limit $h \rightarrow 0$:

$$\int_{|v'| \leq \delta_2} \int_{-2\delta_1}^0 |dv_d|^2 \chi^2(v_d) e^{-\frac{2}{h}(f+|\mu_d|v_d^2)} d_g v = \frac{(\pi h)^{\frac{d}{2}} e^{-\frac{2}{h}f(0)}}{\sqrt{\mu_1 \cdots \mu_{d-1} |\mu_d|}} \left(\frac{1}{2} + O(\sqrt{h}) \right), \quad (103)$$

where μ_1, \dots, μ_{d-1} are the positive eigenvalues of $\text{Hess } f(z)$. Let us point out that the integral in (103) has the form $\int_{\mathbb{R}^d \cap B(0,r)} \varphi_2(v) e^{-\frac{1}{h} \varphi_1(v)} dv$. Hence, the terms of the type $\int_{\mathbb{R}^d \cap B(0,r)} v^\alpha e^{-\frac{1}{h} t v \text{Hess } \varphi_1(0) v} dv$ which appear when performing the Laplace method do not cancel (up to an exponentially small error term) when $|\alpha|$ is odd, contrary to the terms $\int_{B(0,r)} v^\alpha e^{-\frac{1}{h} t v \text{Hess } \varphi_1(0) v} dv$ appearing in the standard Laplace method (by a parity argument) as used to get (107). This justifies the optimality of the $O(\sqrt{h})$ in (103) (see Remark 24 above).

Equations (100)–(103) and (93) lead to the first statement in item 1.(b) of Proposition 23. Let us now prove the second statement in item 1.(b). Doing the same computations as to obtain (99), one deduces from (78), (57), and (58) that on $\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)$,

$$\begin{aligned} \Delta_{f,h} \psi_x &= \frac{2he^{-\frac{f}{h}}}{Z_x N_z} \left(\frac{h}{2} d^* \left(-\chi(v_d) e^{-\frac{1}{h} |\mu_d| v_d^2} dv_d \right) + |\mu_d| v_d dv_d \left(\chi(v_d) e^{-\frac{1}{h} |\mu_d| v_d^2} \nabla v_d \right) + O(|v|^2) \right) \\ &= \frac{2he^{-\frac{1}{h}(f+|\mu_d|v_d^2)}}{Z_x N_z} \left(O(h) - \frac{h}{2} \chi(v_d) dv_d \left(\frac{1}{h} |\mu_d| \nabla v_d^2 \right) + |\mu_d| v_d dv_d \left(\chi(v_d) \nabla v_d \right) + O(|v|^2) \right) \\ &= \frac{2he^{-\frac{1}{h}(f+|\mu_d|v_d^2)}}{Z_x N_z} \left(O(h) + O(|v|^2) \right), \end{aligned}$$

where N_z is defined by (102). It then follows from (102), (93), and (59) that in the limit $h \rightarrow 0$,

$$\int_{\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)} |\Delta_{f,h} \psi_x|^2 = O(h^3) e^{-\frac{2}{h}(f(z)-f(x))} = O(h^2) \int_{\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)} |d_{f,h} \psi_x|^2.$$

This proves the second statement of item 1.(b) in Proposition 23.

Step 2. The case when $z \in \Omega$.

According to Definition 22, one has

$$\int_{\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)} |d_{f,h} \psi_x|^2 = h^2 \frac{\int_{\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)} |d\phi_x|^2 e^{-\frac{2}{h} f}}{Z_x}, \quad (104)$$

where, from (85) and (80), one has:

$$\int_{\mathbf{V}_{\Omega}^{\delta_1, \delta_2}(z)} |d\phi_x|^2 e^{-\frac{2}{h} f} = \frac{\int_{|v'| \leq \delta_2} \int_{v_d = -2\delta_1}^{2\delta_1} |dv_d|^2 \chi^2(v_d) e^{-\frac{2}{h}(f+|\mu_d|v_d^2)} d_g v}{\left(\int_{-2\delta_1}^{2\delta_1} \chi(t) e^{-\frac{1}{h} |\mu_d| t^2} dt \right)^2}, \quad (105)$$

where μ_d is the negative eigenvalue of $\text{Hess } f(z)$ and a straightforward computation (see (75)) implies the existence of $c > 0$ such that in the limit $h \rightarrow 0$,

$$N_z := \int_{-2\delta_1}^{2\delta_1} \chi(t) e^{-\frac{1}{h} |\mu_d| t^2} dt = \frac{\sqrt{\pi h}}{\sqrt{|\mu_d|}} (1 + O(e^{-\frac{c}{h}})). \quad (106)$$

Moreover, from, (75), (64), (65), (66) and the Laplace method, one has in the limit $h \rightarrow 0$:

$$\int_{|v'| \leq \delta_2} \int_{v_d = -2\delta_1}^{2\delta_1} |dv_d|^2 \chi^2(v_d) e^{-\frac{2}{h}(f+|\mu_d|v_d^2)} d_g v = \frac{(\pi h)^{\frac{d}{2}} e^{-\frac{2}{h} f(0)}}{\sqrt{\mu_1 \cdots \mu_{d-1} |\mu_d|}} (1 + O(h)), \quad (107)$$

where μ_1, \dots, μ_{d-1} are the positive eigenvalues of $\text{Hess } f(z)$. The relations (104)–(107) and (93) imply the first statement of item 2 in Proposition 23. Let us lastly prove the second statement in item 2. From (80), (64), and (65), the same computations as those used to obtain (99) imply that on $V_{\bar{\Omega}}^{\delta_1, \delta_2}(z)$,

$$\Delta_{f,h}\psi_x = \frac{2h\chi e^{-\frac{1}{h}(f+|\mu_d|v_d^2)}}{Z_x N_z} \left(O(h) + O(|v|^2) \right)$$

and the relations (66), (106), and (93) then lead to

$$\int_{V_{\bar{\Omega}}^{\delta_1, \delta_2}(z)} |\Delta_{f,h}\psi_x|^2 = O(h^3) e^{-\frac{2}{h}(f(z)-f(x))} = O(h^2) \int_{V_{\bar{\Omega}}^{\delta_1, \delta_2}(z)} |d_{f,h}\psi_x|^2.$$

This concludes the proof of Proposition 23. \blacksquare

For every $x \in \mathbf{U}_0$, one defines the following constants:

$$\mathbf{K}_{1,x} := \sum_{\substack{z \in \mathbf{j}(x) \\ |\nabla f(z)| \neq 0}} \mathbf{c}_{x,z} \quad \text{and} \quad \mathbf{K}_{2,x} := \sum_{\substack{z \in \mathbf{j}(x) \\ |\nabla f(z)| = 0}} \mathbf{c}_{x,z}, \quad (108)$$

where the constants $\mathbf{c}_{x,z}$ are defined in (90), (91), and (92), with the convention $\sum_{\emptyset} = 0$. Let us recall that $\{z \in \mathbf{j}(x), |\nabla f(z)| \neq 0\} \subset \partial\Omega$. Finally, for $y \neq x \in \mathbf{U}_0$, one defines:

$$\mathbf{K}_{x,y} := \sum_{z \in \mathbf{j}(x) \cap \mathbf{j}(y)} \sqrt{\mathbf{c}_{x,z}} \sqrt{\mathbf{c}_{y,z}}, \quad \text{see (90)–(92)}. \quad (109)$$

Let us mention that since for all $x \in \mathbf{U}_0$, one has $\mathbf{j}(x) \neq \emptyset$, it holds $(\mathbf{K}_{1,x}, \mathbf{K}_{2,x}) \neq (0, 0)$. Proposition 25 has the following consequence.

Proposition 25. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. Let $x \in \mathbf{U}_0$ and ψ_x be as introduced in Definition 22.*

1. *In the limit $h \rightarrow 0$, one has:*

$$\|d_{f,h}\psi_x\|_{\Lambda^1 L^2(\Omega)}^2 = \left(\sqrt{h} \mathbf{K}_{1,x} (1 + O(h)) + h \mathbf{K}_{2,x} (1 + O(\sqrt{h})) \right) e^{-\frac{2}{h}(f(\mathbf{j}(x)) - f(x))},$$

where the constant $\mathbf{K}_{1,x}$ and $\mathbf{K}_{2,x}$ are defined in (108) and, when $\mathbf{j}(x) \cap \partial\Omega$ does not contain any critical point of f , the term $O(\sqrt{h})$ is actually of order $O(h)$. Moreover, it holds in the limit $h \rightarrow 0$:

$$\|\Delta_{f,h}\psi_x\|_{L^2(\Omega)}^2 = O(h^2) \|d_{f,h}\psi_x\|_{\Lambda^1 L^2(\Omega)}^2.$$

2. *Let $y \in \mathbf{U}_0$ be such that $y \neq x$. Then, for each of the two possible cases described in items 4.(i) and 4.(ii) in Section 3.3, it holds in the limit $h \rightarrow 0$:*

$$(i) \quad \text{When } \mathbf{j}(x) \cap \mathbf{j}(y) = \emptyset, \quad \langle d_{f,h}\psi_x, d_{f,h}\psi_y \rangle_{\Lambda^1 L^2(\Omega)} = 0.$$

(ii) When $\mathbf{j}(x) \cap \mathbf{j}(y) \neq \emptyset$,

$$\langle d_{f,h}\psi_x, d_{f,h}\psi_y \rangle_{\Lambda^1 L^2(\Omega)} = -h \mathsf{K}_{x,y} e^{-\frac{1}{h}(2f(\mathbf{j}(x)) - f(x) - f(y))} (1 + O(h)),$$

where $\mathsf{K}_{x,y}$ is defined in (109).

Proof. Let $x \in \mathsf{U}_0$.

Let us first prove item 1 in Proposition 25. From Definition 22 and (87),

$$d_{f,h}\psi_x = Z_x^{-1} h e^{-\frac{f}{h}} d\phi_x \text{ is supported in } \overline{\Omega_1(x)} \setminus \Omega_2(x). \quad (110)$$

Moreover, from (84), (88), and (93), there exists $c > 0$ such that for h small enough, $h^2 Z_x^{-2} \int_{\mathsf{O}_1(x)} |d\phi_x|^2 e^{-\frac{2}{h}f} = O(e^{-\frac{2}{h}(f(\mathbf{j}(x)) - f(x) + c)})$. Thus, using in addition (110) and (83), there exists $c > 0$ such that for h small enough,

$$\int_{\Omega} |d_{f,h}\psi_x|^2 = \sum_{z \in \mathbf{j}(x)} \int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} |d_{f,h}\psi_x|^2 + O(e^{-\frac{2}{h}(f(\mathbf{j}(x)) - f(x) + c)}).$$

The first statement in item 1 in Proposition 25 is then a direct consequence of Proposition 23. Let us now prove the second statement in Proposition 25. To this end, note first that according to (110),

$$\Delta_{f,h}\psi_x = d_{f,h}^* d_{f,h}\psi_x \text{ is supported in } \overline{\Omega_1(x)} \setminus \Omega_2(x).$$

Thus, from (83), (84), (88) together with (93), it holds for some $c > 0$ and every h small enough,

$$\int_{\Omega} |\Delta_{f,h}\psi_x|^2 = \sum_{z \in \mathbf{j}(x)} \int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} |\Delta_{f,h}\psi_x|^2 + O(e^{-\frac{2}{h}(f(\mathbf{j}(x)) - f(x) + c)}).$$

Together with Proposition 23, this proves item 1 in Proposition 25.

Let us now prove item 2 in Proposition 25. Let us consider $y \in \mathsf{U}_0$ such that $y \neq x$. According to (110) and (87),

$$d_{f,h}\psi_x \cdot d_{f,h}\psi_y = \frac{h^2 e^{-\frac{2}{h}f} d\phi_x \cdot d\phi_y}{Z_x Z_y} \text{ is supported in } \overline{\Omega_1(x)} \setminus \Omega_2(x) \cap \overline{\Omega_1(y)} \setminus \Omega_2(y).$$

Thus, using item 3 in Definition 20, it holds:

(i) When $\mathbf{j}(x) \cap \mathbf{j}(y) = \emptyset$, then, either $\overline{\Omega_1(x)} \cap \overline{\Omega_1(y)} = \emptyset$ or, up to switching x and y , $\overline{\Omega_1(y)} \subset \Omega_2(x)$. In any case, this implies $\int_{\Omega} d_{f,h}\psi_x \cdot d_{f,h}\psi_y = 0$.

(ii) When $\mathbf{j}(x) \cap \mathbf{j}(y) \neq \emptyset$, one has,

$$\begin{aligned} \int_{\Omega} d_{f,h}\psi_x \cdot d_{f,h}\psi_y &= \frac{h^2}{Z_x Z_y} \sum_{z \in \mathbf{j}(y) \cap \mathbf{j}(x)} \int_{\sqrt{\frac{\delta_1}{\Omega}}, \delta_2(z)} d\phi_x \cdot d\phi_y e^{-\frac{2}{h}f} \\ &+ \frac{h^2}{Z_x Z_y} \int_{\mathsf{O}_2(x)} d\phi_x \cdot d\phi_y e^{-\frac{2}{h}f}. \end{aligned} \quad (111)$$

Since $\mathbf{O}_2(x) \subset \mathbf{O}_1(x)$, from (84), (88), and (93), there exists $c > 0$ such that for h small enough:

$$\frac{h^2}{Z_x Z_y} \int_{\mathbf{O}_2(x)} d\phi_x \cdot d\phi_y e^{-\frac{2}{h}f} = O(e^{-\frac{1}{h}(2f(\mathbf{j}(x)) - f(x) - f(y) + c)}), \quad (112)$$

where we used $f(\mathbf{j}(y)) = f(\mathbf{j}(x))$. Moreover, using item 1 in Definition 21, for all $z \in \mathbf{j}(x) \cap \mathbf{j}(y) (\subset \Omega)$, $d\phi_x = -d\phi_y$ on $\mathbf{V}_{\frac{\delta_1, \delta_2}{\Omega}}(z)$. Thus, from (110), for all $z \in \mathbf{j}(x) \cap \mathbf{j}(y)$, it holds:

$$\frac{h^2}{Z_x Z_y} \int_{\mathbf{V}_{\frac{\delta_1, \delta_2}{\Omega}}(z)} d\phi_x \cdot d\phi_y e^{-\frac{2}{h}f} = -\frac{Z_x}{Z_y} \int_{\mathbf{V}_{\frac{\delta_1, \delta_2}{\Omega}}(z)} |d_{f,h} \psi_x|^2.$$

Then, item 2.(ii) in Proposition 25 is a consequence of (111) and (112) together with (93) and item 2 in Proposition 23.

This concludes the proof of Proposition 25. ■

5.2 Linear independence of the quasi-modes

Let us recall that according to Theorem 1, there exists $c_0 > 0$ such that for every h small enough:

$$\dim \text{Ran } \pi_{[0, c_0 h]}(\Delta_{f,h}^D) = \mathbf{m}_0.$$

In the following, for ease of notation, one denotes

$$\pi_h := \pi_{[0, c_0 h]}(\Delta_{f,h}^D). \quad (113)$$

In this section, one proves that for every h small enough, $(\pi_h \psi_x)_{x \in \mathbf{U}_0}$ is linearly independent, and hence a basis of $\text{Ran } \pi_h$, and that $(d_{f,h} \pi_h \psi_x)_{x \in \mathbf{U}_0}$ is linearly independent in $\Lambda^1 L^2(\Omega)$. Let us start with the following result.

Proposition 26. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. Let $x \in \mathbf{U}_0$ and ψ_x be as introduced in Definition 22. Then, there exists $C > 0$ such that for every h small enough:*

$$\|(1 - \pi_h) \psi_x\|_{L^2(\Omega)} \leq C \|d_{f,h} \psi_x\|_{L^2(\Omega)}$$

and

$$\|d_{f,h}(\pi_h \psi_x)\|_{\Lambda^1 L^2(\Omega)} = \|d_{f,h} \psi_x\|_{\Lambda^1 L^2(\Omega)} (1 + O(h)).$$

Proof. Let $c_0 > 0$ be the constant used to define π_h in (113). According to Theorem 1, for every h small enough, $\Delta_{f,h}^D$ has \mathbf{m}_0 eigenvalues smaller than $c_0 h$ which are moreover exponentially small. Let $C(\frac{c_0}{2}h) \subset \mathbb{C}$ be the circle centred at 0 of radius $\frac{c_0}{2}h$. Then, there exists $c > 0$ such that for every h small enough, all the points in $C(\frac{c_0}{2}h)$ are at a distance larger than ch of the spectrum of $\Delta_{f,h}^D$. Thus, by the spectral theorem, it holds:

$$\sup_{z \in C(\frac{c_0}{2}h)} \|(z - \Delta_{f,h}^D)^{-1}\|_{L^2(\Omega) \rightarrow L^2(\Omega)} \leq \frac{1}{ch}. \quad (114)$$

Moreover, since $\psi_x \in D(\Delta_{f,h}^D)$ for all $x \in \mathbf{U}_0$ (see (89)), it holds

$$\begin{aligned} (1 - \pi_h)\psi_x &= \frac{1}{2\pi i} \int_{C(\frac{c_0}{2}h)} (z^{-1} - (z - \Delta_{f,h}^D)^{-1})\psi_x dz \\ &= -\frac{1}{2\pi i} \int_{C(\frac{c_0}{2}h)} z^{-1}(z - \Delta_{f,h}^D)^{-1}\Delta_{f,h}^D\psi_x dz. \end{aligned}$$

Thus, using (114) and the second estimate in item 1 in Proposition 25, one obtains that $\|(1 - \pi_h)\psi_x\|_{L^2(\Omega)} \leq C\|d_{f,h}\psi_x\|_{\Lambda^1 L^2(\Omega)}$ for some $C > 0$ independent of h . Let us now prove the second asymptotic estimate of Proposition 26. Since the orthogonal projector π_h and $\Delta_{f,h}^D$ commute on $D(\Delta_{f,h}^D)$ and $\psi_x \in D(\Delta_{f,h}^D)$, one has

$$\begin{aligned} \|d_{f,h}(\pi_h\psi_x)\|_{\Lambda^1 L^2(\Omega)}^2 &= \langle \pi_h\psi_x, \Delta_{f,h}\psi_x \rangle_{\Lambda^1 L^2(\Omega)} \\ &= \langle \psi_x, \Delta_{f,h}\psi_x \rangle_{\Lambda^1 L^2(\Omega)} - \langle (1 - \pi_h)\psi_x, \Delta_{f,h}\psi_x \rangle_{\Lambda^1 L^2(\Omega)} \\ &= \|d_{f,h}\psi_x\|_{\Lambda^1 L^2(\Omega)}^2 + O(\|(1 - \pi_h)\psi_x\|_{L^2(\Omega)}\|\Delta_{f,h}\psi_x\|_{L^2(\Omega)}) \\ &= \|d_{f,h}\psi_x\|_{\Lambda^1 L^2(\Omega)}^2 + O(h)\|d_{f,h}\psi_x\|_{\Lambda^1 L^2(\Omega)}^2, \end{aligned}$$

where one used at the last line the second asymptotic estimate in item 1 in Proposition 25 and the first asymptotic estimate in Proposition 26. This concludes the proof of Proposition 26. \blacksquare

Remark 27. Note here that using the estimate (11) to obtain an upper bound on $\|(1 - \pi_h)\psi_x\|_{L^2(\Omega)}$, one would obtain $\|(1 - \pi_h)\psi_x\|_{L^2(\Omega)} \leq \frac{1}{\sqrt{c_0 h}}\|d_{f,h}\psi_x\|_{\Lambda^1 L^2(\Omega)}$. This would finally lead to a remainder term of order $O(\sqrt{h})$ instead of the $O(h)$ appearing in (131) in Theorem 3 below.

Definition 28. Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. Let $x \in \mathbf{U}_0$ and ψ_x be as introduced in Definition 22. Then, one defines the 1-form:

$$\Theta_x := \frac{d_{f,h}\psi_x}{\|d_{f,h}\psi_x\|_{\Lambda^1 L^2(\Omega)}},$$

which is C^∞ on $\bar{\Omega}$ and supported in $\overline{\Omega_1(x)} \setminus \Omega_2(x)$ (see (110)). Moreover, for every h small enough, one defines:

$$\psi_x^\pi := \frac{\pi_h\psi_x}{\|\pi_h\psi_x\|_{L^2(\Omega)}} \quad \text{and} \quad \Theta_x^\pi := \frac{d_{f,h}(\pi_h\psi_x)}{\|d_{f,h}(\pi_h\psi_x)\|_{\Lambda^1 L^2(\Omega)}},$$

which are well defined for every h small enough (see indeed Proposition 26) and where we recall that the orthogonal projector π_h on $L^2(\Omega)$ is defined by (113).

A consequence of Proposition 26 on the families $(\psi_x^\pi)_{x \in \mathbf{U}_0}$ and $(\Theta_x^\pi)_{x \in \mathbf{U}_0}$ introduced in Definition 28 is the following.

Proposition 29. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. Let $x, y \in \mathbf{U}_0$. Then, there exists $c > 0$ such that for every h small enough:*

$$\langle \psi_x^\pi, \psi_y^\pi \rangle_{L^2(\Omega)} = \langle \psi_x, \psi_y \rangle_{L^2(\Omega)} + O(e^{-\frac{c}{h}}),$$

and

$$\langle \Theta_x^\pi, \Theta_y^\pi \rangle_{\Lambda^1 L^2(\Omega)} = \langle \Theta_x, \Theta_y \rangle_{\Lambda^1 L^2(\Omega)} + O(h).$$

Proof. Let us recall that the orthogonal projector π_h and $\Delta_{f,h}^D$ commute on $D(\Delta_{f,h})$ and that $\psi_x \in D(\Delta_{f,h}^D)$. Then, for every $x, y \in \mathbf{U}_0$, it holds

$$\langle \pi_h \psi_x, \pi_h \psi_y \rangle_{\Lambda^1 L^2(\Omega)} = \langle \psi_x, \psi_y \rangle_{\Lambda^1 L^2(\Omega)} - \langle (1 - \pi_h) \psi_x, \psi_y \rangle_{\Lambda^1 L^2(\Omega)},$$

and

$$\langle d_{f,h}(\pi_h \psi_x), d_{f,h}(\pi_h \psi_y) \rangle_{\Lambda^1 L^2(\Omega)} = \langle d_{f,h} \psi_x, d_{f,h} \psi_y \rangle_{\Lambda^1 L^2(\Omega)} - \langle (1 - \pi_h) \psi_x, \Delta_{f,h} \psi_y \rangle_{\Lambda^1 L^2(\Omega)}.$$

Proposition 29 is then a direct consequence of these identities together with Propositions 25 and 26 (see also (41)). \blacksquare

The Gram matrices of the families $(\psi_x)_{x \in \mathbf{U}_0}$ and $(\Theta_x)_{x \in \mathbf{U}_0}$ are not necessarily quasi-unitary, i.e. of the form $\text{Id} + o(1)$, when $h \rightarrow 0$. For the family $(\psi_x)_{x \in \mathbf{U}_0}$, this follows from the fact that a global minimum of f in $\text{supp } \psi_x$ can also be a global minimum of f in $\text{supp } \psi_y$ (see item 4.(i) in Section 3.3). For the family $(\Theta_x)_{x \in \mathbf{U}_0}$, this follows from the fact that $\langle d_{f,h} \psi_x, d_{f,h} \psi_y \rangle_{\Lambda^1 L^2(\Omega)}$ can be of the same order as both $\|d_{f,h} \psi_x\|_{\Lambda^1 L^2(\Omega)}^2$ and $\|d_{f,h} \psi_y\|_{\Lambda^1 L^2(\Omega)}^2$ (see item 2.(ii) in Proposition 25). However, according to Proposition 32 below, these families are, in the limit $h \rightarrow 0$, uniformly linearly independent in the sense of the following definition (see [19]).

Definition 30. *Let \mathcal{H} be a Hilbert space, $n \geq 1$ be an integer smaller than $\dim \mathcal{H}$, and \mathcal{B}' be a family of n elements of \mathcal{H} depending on a parameter $h > 0$. The family \mathcal{B}' is said to be uniformly linearly independent in the limit $h \rightarrow 0$ if there exists $C > 0$ and $h_0 > 0$ such that for all $h \in (0, h_0)$, the family \mathcal{B}' is linearly independent and for some (and thus for any) orthonormal family \mathcal{B} of $\text{Span}(\mathcal{B}')$ and for some (and thus for any) matrix norm $\|\cdot\|$ on $\mathbb{R}^{n \times n}$, it holds*

$$\left\| \text{Mat}_{\mathcal{B}, \mathcal{B}'}(\text{Id}) \right\| \leq C \quad \text{and} \quad \left\| \text{Mat}_{\mathcal{B}', \mathcal{B}}(\text{Id}) \right\| \leq C.$$

Remark 31. *Since the Gram matrix $G^{\mathcal{B}'}$ of \mathcal{B}' writes $G^{\mathcal{B}'} = {}^t \text{Mat}_{\mathcal{B}', \mathcal{B}}(\text{Id}) \text{Mat}_{\mathcal{B}, \mathcal{B}'}(\text{Id})$, the family \mathcal{B}' is uniformly linearly independent in the limit $h \rightarrow 0$ if and only if there exists a constant $C > 0$ independent of h such that, for every h small enough, $\frac{1}{C} \leq G^{\mathcal{B}'} \leq C$ in the sense of quadratic forms.*

Proposition 32. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. Then, the family of functions $(\psi_x^\pi)_{x \in \mathbf{U}_0}$ (resp. the family of 1-forms $(\Theta_x^\pi)_{x \in \mathbf{U}_0}$) introduced in Definition 28 is uniformly linearly independent in $L^2(\Omega)$ (resp. in $\Lambda^1 L^2(\Omega)$) in the limit $h \rightarrow 0$ (see Definition 30). In particular, $(\psi_x^\pi)_{x \in \mathbf{U}_0}$ is a basis of $\text{Ran } \pi_h$ for every h small enough.*

The following lemma, which is a direct consequence of Proposition 23, item 1 in Proposition 25, and Definition 28, will be used in the proof of Proposition 32.

Lemma 33. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**, and $x \in \mathbf{U}_0$.*

1. *When there exists $z \in \mathbf{j}(x)$ such that $|\nabla f(z)| \neq 0$ (in this case $z \in \partial\Omega$), one has in the limit $h \rightarrow 0$,*

$$\|\Theta_x\|_{\Lambda^1 L^2(\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z))}^2 = \frac{c_{x,z}}{\sum_{p \in \mathbf{j}(x), |\nabla f(p)| \neq 0} c_{x,p}} (1 + o(1)),$$

where the constant $c_{x,z}$ is defined in (90) and $\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z)$ is defined in (54).

2. *When $|\nabla f(z)| = 0$ for every $z \in \mathbf{j}(x)$, one has in the limit $h \rightarrow 0$, for every $z \in \mathbf{j}(x)$,*

$$\|\Theta_x\|_{\Lambda^1 L^2(\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z))}^2 = \frac{c_{x,z}}{\sum_{p \in \mathbf{j}(x)} c_{x,p}} (1 + o(1)),$$

where the constants $c_{x,z}$ are defined in (91) and (92) and $\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z)$ in (61) and (68).

Proof of Proposition 32. In view of Proposition 29 and of Remark 31, Proposition 32 is equivalent to the fact that the family $(\psi_x)_{x \in \mathbf{U}_0}$ (resp. $(\Theta_x)_{x \in \mathbf{U}_0}$) is uniformly linearly independent in $L^2(\Omega)$ (resp. in $\Lambda^1 L^2(\Omega)$), in the limit $h \rightarrow 0$. Moreover, the proof of this property for $(\psi_x)_{x \in \mathbf{U}_0}$ is exactly the same as the one made in [19, Section 4.2]. Let us now prove that $(\Theta_x)_{x \in \mathbf{U}_0}$ is uniformly linearly independent in $\Lambda^1 L^2(\Omega)$ in the limit $h \rightarrow 0$. The following proof is inspired by the analysis done in [19, Section 4.2]. Let us recall that according to the construction of \mathbf{C}_j made in Section 3.3, one has:

$$(\mathbf{C}_j(x))_{x \in \mathbf{U}_0} = \bigcup_{k \geq 1} \{\mathbf{C}_j(x_{k,1}), \dots, \mathbf{C}_j(x_{k, \mathbf{N}_k})\},$$

where the sum over k is actually finite. For all $k \geq 1$, let us divide $\{\mathbf{C}_j(x_{k,1}), \dots, \mathbf{C}_j(x_{k, \mathbf{N}_k})\}$ into n_k groups ($n_k \leq \mathbf{N}_k$):

$$\{\mathbf{C}_j(x_{k,1}), \dots, \mathbf{C}_j(x_{k, \mathbf{N}_k})\} = \bigcup_{\ell=1}^{n_k} \{\mathbf{C}_{k,\ell}^1, \dots, \mathbf{C}_{k,\ell}^{m_\ell}\}$$

which are such that for all $\ell \in \{1, \dots, n_k\}$,

$$\begin{cases} \text{the set } \bigcup_{j=1}^{m_\ell} \overline{\mathbf{C}_{k,\ell}^j} \text{ is connected, and} \\ \forall \mathbf{C} \in \{\mathbf{C}_j(x_{k,1}), \dots, \mathbf{C}_j(x_{k, \mathbf{N}_k})\} \setminus \{\mathbf{C}_{k,\ell}^1, \dots, \mathbf{C}_{k,\ell}^{m_\ell}\}, \overline{\mathbf{C}} \cap \bigcup_{j=1}^{m_\ell} \overline{\mathbf{C}_{k,\ell}^j} = \emptyset. \end{cases} \quad (115)$$

Let $x, y \in \mathbf{U}_0$. Let k, k', ℓ , and ℓ' be such that $\mathbf{C}_j(x) \in \{\mathbf{C}_{k,\ell}^1, \dots, \mathbf{C}_{k,\ell}^{m_\ell}\}$ and $\mathbf{C}_j(y) \in \{\mathbf{C}_{k',\ell'}^1, \dots, \mathbf{C}_{k',\ell'}^{m_{\ell'}}\}$. Let us recall that $\mathbf{j}(x) \cap \mathbf{j}(y) \neq \emptyset$ is equivalent to $f(\mathbf{j}(x)) = f(\mathbf{j}(y))$ (which implies $k = k'$) and $\overline{\mathbf{C}_j(y)} \cap \overline{\mathbf{C}_j(x)} \neq \emptyset$ (which implies $\ell = \ell'$). Therefore,

when $\mathbf{C}_j(x)$ and $\mathbf{C}_j(y)$ belong to different groups, i.e. when $(k', \ell') \neq (k, \ell)$, it holds $\mathbf{j}(x) \cap \mathbf{j}(y) = \emptyset$. Thus, according to item 2.(i) in Proposition 25 and to Definition 28, it holds $\langle \Theta_x, \Theta_y \rangle_{\Lambda^1 L^2(\Omega)} = 0$. This implies that in $\Lambda^1 L^2(\Omega)$, it holds:

$$\text{Span}((\Theta_x)_{x \in U_0}) = \bigoplus_{k \geq 1}^{\perp} \left[\bigoplus_{\ell=1, \dots, n_k}^{\perp} \text{Span}(\Theta_x, x \text{ s.t. } \mathbf{C}_j(x) \in \{\mathbf{C}_{k,\ell}^1, \dots, \mathbf{C}_{k,\ell}^{m_\ell}\}) \right]. \quad (116)$$

According to Definition 30, in order to prove that $(\Theta_x)_{x \in U_0}$ is uniformly linearly independent in the limit $h \rightarrow 0$, it then suffices to prove that for all $k \geq 1$ and $\ell \in \{1, \dots, n_k\}$, the family $(\Theta_x, x \text{ s.t. } \mathbf{C}_j(x) \in \{\mathbf{C}_{k,\ell}^1, \dots, \mathbf{C}_{k,\ell}^{m_\ell}\})$ is uniformly linearly independent in the limit $h \rightarrow 0$. To this end, let $k \geq 1$ and $\ell \in \{1, \dots, n_k\}$. For ease of notation, we denote m_ℓ by m , $\{\mathbf{C}_{k,\ell}^1, \dots, \mathbf{C}_{k,\ell}^{m_\ell}\}$ by $\{\mathbf{C}^1, \dots, \mathbf{C}^m\}$, and $(\Theta_x, x \text{ s.t. } \mathbf{C}_j(x) \in \{\mathbf{C}_{k,\ell}^1, \dots, \mathbf{C}_{k,\ell}^{m_\ell}\})$ by $(\Theta_1, \dots, \Theta_m)$. For h small enough, let us then consider some $\varphi = \varphi(h) \in \text{Span}\{\Theta_1, \dots, \Theta_m\}$:

$$\varphi = \sum_{i=1}^m a_i(h) \Theta_i, \text{ where for all } i \in \{1, \dots, m\}, a_i(h) \in \mathbb{R}. \quad (117)$$

From (115) and using Lemma 19, up to reordering $\{\mathbf{C}^1, \dots, \mathbf{C}^m\}$, there exists $z_1 \in \mathbf{U}_1^{\text{ssp}}(\overline{\Omega})$ such that $z_1 \in \partial \mathbf{C}^1 \setminus (\cup_{i=2}^m \partial \mathbf{C}^i)$. Let us now choose such a point z_1 as follows:

- When $\{p \in \partial \mathbf{C}^1 \cap \mathbf{U}_1^{\text{ssp}}(\overline{\Omega}) \text{ s.t. } |\nabla f(p)| \neq 0\} = \emptyset$, one chooses any z_1 in $\mathbf{U}_1^{\text{ssp}}(\overline{\Omega}) \cap \partial \mathbf{C}^1 \setminus (\cup_{i=2}^m \partial \mathbf{C}^i)$ (and it holds $|\nabla f(z_1)| = 0$).
- When $\{p \in \partial \mathbf{C}^1 \cap \mathbf{U}_1^{\text{ssp}}(\overline{\Omega}) \text{ s.t. } |\nabla f(p)| \neq 0\} \neq \emptyset$, then \mathbf{C}^1 is a principal well of f (see (42)) and thus $\mathbf{C}^1, \dots, \mathbf{C}^m$ are principal wells of f . In this case, one chooses $z_1 \in \mathbf{U}_1^{\text{ssp}}(\overline{\Omega}) \cap \{p \in \partial \mathbf{C}^1 \text{ s.t. } |\nabla f(p)| \neq 0\} \subset \partial \Omega$ and from (26), it holds $p \notin \cup_{i=2}^m \partial \mathbf{C}^i$.

In both cases, according to Lemma 33, one has when $h \rightarrow 0$,

$$\|\Theta_1\|_{\Lambda^1 L^2(\mathbf{V}_{\overline{\Omega}}^{\delta_1, \delta_2}(z_1))} = c_1(1 + o(1)),$$

where $c_1 \in (0, 1)$ is independent of h . Since $z_1 \in \partial \mathbf{C}^1 \setminus (\cup_{i=2}^m \partial \mathbf{C}^i)$ and since all the cylinders defined by (54), (61), and (68) are two by two disjoint, the cylinder $\mathbf{V}_{\overline{\Omega}}^{\delta_1, \delta_2}(z_1)$ does not meet any of the cylinders associated with the $z \in \mathbf{U}_1^{\text{ssp}}(\overline{\Omega}) \cap \cup_{i=2}^m \partial \mathbf{C}^i$. Therefore, by definition of Θ_i (see Definition 28) and item 3 in Definition 20, it holds $\Theta_i \equiv 0$ on $\mathbf{V}_{\overline{\Omega}}^{\delta_1, \delta_2}(z_1)$ for all $i \in \{2, \dots, m\}$. Taking the $\Lambda^1 L^2$ -norm of (117) in $\mathbf{V}_{\overline{\Omega}}^{\delta_1, \delta_2}(z_1)$, one has for h small enough, $\|\varphi\|_{\Lambda^1 L^2(\Omega)} \geq \|\varphi\|_{\Lambda^1 L^2(\mathbf{V}_{\overline{\Omega}}^{\delta_1, \delta_2}(z_1))} \geq \frac{c_1}{2} |a_1(h)|$. Thus, for h small enough, it holds:

$$|a_1(h)| \leq \frac{2}{c_1} \|\varphi\|_{\Lambda^1 L^2(\Omega)}. \quad (118)$$

Let us now get a similar upper bound on $|a_2(h)|$. Since $\cup_{i=1}^m \overline{\mathbf{C}^i}$ is connected (see (115)), up to reordering $\{\mathbf{C}^2, \dots, \mathbf{C}^m\}$, it holds $\overline{\mathbf{C}^1} \cap \overline{\mathbf{C}^2} \neq \emptyset$, and one chooses $z_2 \in \mathbf{U}_1^{\text{ssp}}(\overline{\Omega}) \cap \partial \mathbf{C}^2$ as follows:

- When $\{p \in \partial\mathcal{C}^2 \cap \mathbf{U}_1^{\text{ssp}}(\bar{\Omega}) \text{ s.t. } |\nabla f(p)| \neq 0\} = \emptyset$, one chooses any $z_2 \in \partial\mathcal{C}^2 \cap \partial\mathcal{C}^1$.
- When $\{p \in \partial\mathcal{C}^2 \cap \mathbf{U}_1^{\text{ssp}}(\bar{\Omega}) \text{ s.t. } |\nabla f(p)| \neq 0\} \neq \emptyset$, one chooses $z_2 \in \{p \in \partial\mathcal{C}^2 \cap \mathbf{U}_1^{\text{ssp}}(\bar{\Omega}) \text{ s.t. } |\nabla f(p)| \neq 0\}$.

In both cases, $z_2 \in \mathbf{U}_1^{\text{ssp}}(\bar{\Omega}) \cap \partial\mathcal{C}^2 \setminus (\cup_{i=3}^m \partial\mathcal{C}^i)$. Therefore, it holds $\Theta_i \equiv 0$ on $\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z_2)$ for all $i \in \{3, \dots, m\}$ while, from Lemma 33, $\|\Theta_2\|_{\Lambda^1 L^2(\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z_2))} = c_2(1 + o(1))$ in the limit $h \rightarrow 0$ and for some $c_2 \in (0, 1)$ independent of h . Taking the $\Lambda^1 L^2$ -norm of (117) in $\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z_2)$ and using the fact that $\|\Theta_1\|_{\Lambda^1 L^2(\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z_2))} \leq 1$ lead to

$$\|\varphi\|_{\Lambda^1 L^2(\Omega)} \geq \|\varphi\|_{\Lambda^1 L^2(\mathbf{V}_{\bar{\Omega}}^{\delta_1, \delta_2}(z_2))} \geq -|a_1(h)| + \frac{c_2}{2}|a_2(h)|$$

for every h small enough. Using in addition (118), one obtains

$$|a_2(h)| \leq \frac{2}{c_2} \left(1 + \frac{2}{c_1}\right) \|\varphi\|_{\Lambda^1 L^2(\Omega)}.$$

Repeating this last procedure $m - 2$ times leads to the existence of some $C > 0$ such that for every h small enough, it holds $\sum_{i=1}^m |a_i(h)| \leq C \|\varphi\|_{\Lambda^1 L^2(\Omega)}$. Using (117), it follows that the family $(\Theta_1, \dots, \Theta_m)$ is uniformly linearly independent in the limit $h \rightarrow 0$, which concludes the proof of Proposition 32. \blacksquare

5.3 An accurate interaction matrix

Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. In the rest of this section, one chooses for ease of notation an arbitrary labeling of $\mathbf{U}_0 = \{x_1, \dots, x_{m_0}\}$ and one assumes that $(\psi_x)_{x \in \mathbf{U}_0} = (\psi_1, \dots, \psi_{m_0})$ and $(\Theta_x)_{x \in \mathbf{U}_0} = (\Theta_1, \dots, \Theta_{m_0})$ (see Definitions 22 and 28) are ordered according to this labeling.

Let us recall from Proposition 32 that for every h small enough, $(\psi_j^\pi)_{j \in \{1, \dots, m_0\}}$ and $(\Theta_i^\pi)_{i \in \{1, \dots, m_0\}}$ are uniformly linearly independent (see Definitions 28 and 30), which implies in particular, according to Theorem 1, that

$$\text{Span}(\psi_j^\pi)_{j \in \{1, \dots, m_0\}} = \text{Ran } \pi_h.$$

Let us now consider an orthonormal basis \mathcal{B}_0 of $\text{Ran}(\pi_h)$ in $L^2(\Omega)$ and an orthonormal basis \mathcal{B}_1 of $\text{Span}(\Theta_i^\pi)_{i \in \{1, \dots, m_0\}}$ in $\Lambda^1 L^2(\Omega)$. The eigenvalues of $\Delta_{f,h}^D$ which are smaller than $c_0 h$ for h small enough are then the eigenvalues of the matrix $M^{\mathcal{B}_0}$ of $\Delta_{f,h}^D$ in the basis \mathcal{B}_0 , and hence the singular values of the matrix $S^{\mathcal{B}_0, \mathcal{B}_1}$ defined by

$$S^{\mathcal{B}_0, \mathcal{B}_1} := \text{Mat}_{\mathcal{B}_0, \mathcal{B}_1}(d_{f,h}), \quad (119)$$

which follows from the relation $M^{\mathcal{B}_0} = {}^t S^{\mathcal{B}_0, \mathcal{B}_1} S^{\mathcal{B}_0, \mathcal{B}_1}$. This reduces the analysis of the asymptotic behaviour of the m_0 smallest eigenvalues of $\Delta_{f,h}^D$ in the limit $h \rightarrow 0$ to the study of the asymptotic behaviour of the singular values of the matrix $S^{\mathcal{B}_0, \mathcal{B}_1}$.

Note moreover that according to Definition 28, the matrix $S^{\mathcal{B}_0, \mathcal{B}_1}$ defined by (119) has the form

$$S^{\mathcal{B}_0, \mathcal{B}_1} = {}^t C_1^\pi S^\pi C_0^\pi, \quad (120)$$

where

$$C_1^\pi := \text{Mat}_{\mathcal{B}_1, (\Theta_i^\pi)_{i \in \{1, \dots, m_0\}}}(\text{Id}), \quad C_0^\pi := \text{Mat}_{\mathcal{B}_0, (\psi_j^\pi)_{j \in \{1, \dots, m_0\}}}(\text{Id}), \quad (121)$$

and

$$\begin{aligned} \text{for all } i, j \in \{1, \dots, m_0\}, \quad S_{i,j}^\pi &= \frac{\langle d_{f,h}\psi_j^\pi, d_{f,h}\psi_i^\pi \rangle_{\Lambda^1 L^2(\Omega)}}{\|d_{f,h}\psi_i^\pi\|_{\Lambda^1 L^2(\Omega)}} \\ &= \|d_{f,h}\psi_j^\pi\|_{\Lambda^1 L^2(\Omega)} \langle \Theta_j^\pi, \Theta_i^\pi \rangle_{\Lambda^1 L^2(\Omega)}. \end{aligned} \quad (122)$$

In order to give asymptotic estimates on the entries of the matrix S^π in the limit $h \rightarrow 0$, let us introduce the square matrix S defined by:

$$\begin{aligned} \text{for all } i, j \in \{1, \dots, m_0\}, \quad S_{i,j} &:= \frac{\langle d_{f,h}\psi_j, d_{f,h}\psi_i \rangle_{\Lambda^1 L^2(\Omega)}}{\|d_{f,h}\psi_i\|_{\Lambda^1 L^2(\Omega)}} \\ &= \|d_{f,h}\psi_j\|_{\Lambda^1 L^2(\Omega)} \langle \Theta_j, \Theta_i \rangle_{\Lambda^1 L^2(\Omega)}. \end{aligned} \quad (123)$$

From Propositions 25, 26, and 29, one has the following asymptotic result on the entries of the matrices S and S^π .

Proposition 34. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**, and $i, j \in \{1, \dots, m_0\}$. We then have the following estimates when $h \rightarrow 0$:*

1. When $\mathbf{j}(x_i) \cap \mathbf{j}(x_j) = \emptyset$, $S_{i,j} = 0$.
2. When $\mathbf{j}(x_i) \cap \mathbf{j}(x_j) \neq \emptyset$ and $i = j$,

$$S_{j,j} = h^{\frac{1}{4}} \left(\mathbf{K}_{1,x_j} (1 + O(h)) + h^{\frac{1}{2}} \mathbf{K}_{2,x_j} (1 + O(\sqrt{h})) \right)^{\frac{1}{2}} e^{-\frac{1}{h}(f(\mathbf{j}(x_j)) - f(x_j))}$$

and, when $\mathbf{j}(x_i) \cap \mathbf{j}(x_j) \neq \emptyset$ and $i \neq j$,

$$S_{i,j} = - \frac{h^{\frac{3}{4}} \mathbf{K}_{x_i, x_j}}{(\mathbf{K}_{1,x_i} (1 + O(h)) + h^{\frac{1}{2}} \mathbf{K}_{2,x_i} (1 + O(\sqrt{h})))^{\frac{1}{2}}} e^{-\frac{1}{h}(f(\mathbf{j}(x_j)) - f(x_j))},$$

where the constants \mathbf{K}_{1,x_j} , \mathbf{K}_{2,x_j} , and \mathbf{K}_{x_i, x_j} are defined in (108) and (109).

3. Finally, it holds in any case

$$S_{i,j}^\pi = S_{i,j} + O(h)S_{j,j}.$$

In order to suitably factorize the matrix S^π , let us first write $S = TD$, where D and T are the following $m_0 \times m_0$ matrices (defined for every h small enough):

- the matrix D is the diagonal matrix such that for all $j \in \{1, \dots, m_0\}$,

$$D_{j,j} := h^{p_j} e^{-\frac{1}{h}(f(j(x_j)) - f(x_j))}, \quad (124)$$

where

$$p_j := \frac{1}{4} \text{ when } K_{1,x_j} \neq 0 \text{ and } p_j := \frac{1}{2} \text{ when } K_{1,x_j} = 0, \quad (125)$$

- the matrix T is the matrix SD^{-1} , i.e.

$$\text{for all } i, j \in \{1, \dots, m_0\}, \quad T_{i,j} := \frac{S_{i,j}}{D_{j,j}}. \quad (126)$$

It then follows from (124)–(126) and Proposition 34 that in the limit $h \rightarrow 0$,

$$S^\pi = (T + R)D \quad \text{with} \quad R = S^\pi D^{-1} - T = (S^\pi - S)D^{-1} = O(h)$$

and $T = O(1)$. Moreover, according to Lemma 35 below, T is invertible and its inverse satisfies $T^{-1} = O(1)$. Thus, the matrix S^π factorizes as follows:

$$S^\pi = (T + O(h))D = (I_{m_0} + O(h)T^{-1})TD = (I_{m_0} + O(h))TD = (I_{m_0} + O(h))S. \quad (127)$$

We conclude this section by stating and proving Lemma 35 which led to (127).

Lemma 35. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**. Let $\|\cdot\|$ be a matrix norm on $\mathbb{R}^{m_0 \times m_0}$. Then, for every h small enough, the matrix T defined by (126) is invertible and there exists $C > 0$ independent of h such that*

$$\|T\| \leq C \text{ and } \|T^{-1}\| \leq C.$$

Proof. We already noticed the relation $\|T\| = O(1)$ in the limit $h \rightarrow 0$. To prove the relation $\|T^{-1}\| = O(1)$, let us first notice that from (123), (124), (126), and Definition 28, it holds

$$T = SD^{-1} = G^\Theta UD^{-1},$$

where

$$U = \text{Diag} \left(\|d_{f,h}\psi_1\|_{\Lambda^1 L^2(\Omega)}, \dots, \|d_{f,h}\psi_{m_0}\|_{\Lambda^1 L^2(\Omega)} \right) = \text{Diag} (S_{1,1}, \dots, S_{m_0,m_0})$$

and G^Θ is the Gram matrix of the family $(\Theta_1, \dots, \Theta_{m_0})$ in $\Lambda^1 L^2(\Omega)$. Moreover, according to (124), (125), and Proposition 34, there exist positive constants c_1, \dots, c_{m_0} such that $\lim_{h \rightarrow 0} UD^{-1} = \text{Diag} (c_1, \dots, c_{m_0})$ and thus $DU^{-1} = O(1)$. Lastly, let us recall from Proposition 32 that the family $(\Theta_1, \dots, \Theta_{m_0})$ is uniformly linearly independent in the limit $h \rightarrow 0$ and then, according to Remark 31, $(G^\Theta)^{-1} = O(1)$. It follows that $T^{-1} = DU^{-1}(G^\Theta)^{-1} = O(1)$, which concludes the proof of Lemma 35. ■

5.4 Asymptotic behaviour of the small eigenvalues of $\Delta_{f,h}^D$

In this section, one states and proves the main results of this work, Theorems 2 and 3 below, on the precise asymptotic behaviour of the small eigenvalues of $\Delta_{f,h}^D$ in the limit $h \rightarrow 0$.

The proofs of these results make both use of the weak form of the Fan inequalities stated in the following lemma (see for instance [34, Theorem 1.6]).

Lemma 36. *Let $A, B,$ and C be three $\mathfrak{m}_0 \times \mathfrak{m}_0$ matrices. It then holds:*

$$\forall j \in \{1, \dots, \mathfrak{m}_0\}, \eta_j(ABC) \leq \|A\| \|C\| \eta_j(B),$$

where, for any matrix $U \in \mathbb{R}^{\mathfrak{m}_0 \times \mathfrak{m}_0}$, $\eta_1(U) \geq \dots \geq \eta_{\mathfrak{m}_0}(U)$ denote the singular values of U and $\|U\| := \sqrt{\max \sigma({}^t U U)} = \eta_1(U)$ is the spectral norm of U .

In Theorem 2, one gives a precise lower and upper bound on every small eigenvalue of $\Delta_{f,h}^D$ in the limit $h \rightarrow 0$ under the sole assumptions **(H1)** and **(H2)**.

Theorem 2. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**, and thus such that $U_0 \neq \emptyset$. Let us order the set $U_0 = \{x_1, \dots, x_{\mathfrak{m}_0}\}$ such that*

- the sequence $(f(\mathbf{j}(x_j)) - f(x_j))_{j \in \{1, \dots, \mathfrak{m}_0\}}$ is decreasing,
- and, on any $\mathcal{J} \subset \{1, \dots, \mathfrak{m}_0\}$ such that $(f(\mathbf{j}(x_j)) - f(x_j))_{j \in \mathcal{J}}$ is constant, the sequence $(p_j)_{j \in \mathcal{J}}$ is decreasing (see (125)).

Finally, for $j \in \mathbb{N}^*$, let us denote by $\lambda_{j,h}$ the j -th eigenvalue of $\Delta_{f,h}^D$ counted with multiplicity. Then, there exist $C > 0$ and $h_0 > 0$ such that for every $j \in \{1, \dots, \mathfrak{m}_0\}$ and every $h \in (0, h_0)$, it holds

$$\frac{1}{C} h^{2p_j} e^{-\frac{2}{h}(f(\mathbf{j}(x_j)) - f(x_j))} \leq \lambda_{j,h} \leq C h^{2p_j} e^{-\frac{2}{h}(f(\mathbf{j}(x_j)) - f(x_j))}.$$

Proof. For any matrix $U \in \mathbb{R}^{\mathfrak{m}_0 \times \mathfrak{m}_0}$, we will denote by $\|U\|$ the spectral norm of U and by $\|U\| = \eta_1(U) \geq \dots \geq \eta_{\mathfrak{m}_0}(U)$ the singular values of U . Let us recall from Section 5.3 that the \mathfrak{m}_0 smallest eigenvalues of $\Delta_{f,h}^D$ are the singular values of the matrix $S^{\mathcal{B}_0, \mathcal{B}_1} = {}^t C_1^\pi S^\pi C_0^\pi \in \mathbb{R}^{\mathfrak{m}_0 \times \mathfrak{m}_0}$, where C_0^π , C_1^π , and S^π are defined in (121) and in (122). Moreover, using Proposition 32, there exists $c > 0$ such that for every h small enough, it holds

$$\max \left(\|C_0^\pi\|, \|(C_0^\pi)^{-1}\|, \|C_1^\pi\|, \|(C_1^\pi)^{-1}\| \right) \leq c. \quad (128)$$

Thus, using Lemma 36, there exists $c > 0$ such that for every h small enough, it holds

$$\forall j \in \{1, \dots, \mathfrak{m}_0\}, \frac{1}{c} \eta_j(S^\pi) \leq \eta_j(S^{\mathcal{B}_0, \mathcal{B}_1}) \leq c \eta_j(S^\pi). \quad (129)$$

Moreover, let us recall that $S^\pi = (I_{\mathfrak{m}_0} + O(h))TD$ according to (127) and then, using Lemmata 35 and 36, there exists $c > 0$ such that for every h small enough,

$$\forall j \in \{1, \dots, \mathfrak{m}_0\}, \frac{1}{c} \eta_j(D) \leq \eta_j(S^\pi) \leq c \eta_j(D). \quad (130)$$

Finally, according to the ordering of the elements of \mathbf{U}_0 considered in the statement of Theorem 2, the singular values of D satisfy (see indeed (124)),

$$\forall j \in \{1, \dots, m_0\}, \quad \eta_{m_0+1-j}(D) = D_{j,j} = h^{p_j} e^{-\frac{1}{h}(f(\mathbf{j}(x_j)) - f(x_j))}.$$

Together with (129) and (130), this implies the statement of Theorem 2. \blacksquare

Lastly, in the main result of this work stated below, one gives asymptotic equivalents of the smallest eigenvalues of $\Delta_{f,h}^D$ under additional assumptions on the maps \mathbf{j} and \mathbf{C}_j built in Section 3.3 which ensure that the wells $\mathbf{C}_j(x)$, $x \in \mathbf{U}_0$, are adequately separated.

Theorem 3. *Let $f : \bar{\Omega} \rightarrow \mathbb{R}$ be a C^∞ Morse function which satisfies **(H1)** and **(H2)**, and thus such that $\mathbf{U}_0 \neq \emptyset$. Let us assume that there exists $m^* \in \{1, \dots, m_0\}$ and a labeling of $\mathbf{U}_0 = \{x_1, \dots, x_{m_0}\}$ such that (see Section 3.3 for the constructions of the maps \mathbf{j} and \mathbf{C}_j):*

1. *It holds*

$$f(\mathbf{j}(x_1)) - f(x_1) \geq \dots \geq f(\mathbf{j}(x_{m^*})) - f(x_{m^*}) > \max_{i=m^*+1, \dots, m_0} f(\mathbf{j}(x_i)) - f(x_i),$$

$$\text{with the convention } \max_{i=m_0+1, m_0} f(\mathbf{j}(x_i)) - f(x_i) = 0.$$

2. *For all $j \in \{1, \dots, m^*\}$, $\mathbf{j}(x_j) \cap \bigcup_{i \in \{1, \dots, m_0\}, i \neq j} \mathbf{j}(x_i) = \emptyset$ (i.e. $\partial \mathbf{C}_j(x_j)$ does not contain any separating saddle point which belongs to another $\partial \mathbf{C}_j(x_i)$, $i \neq j$).*

3. *For all $k, \ell \in \{1, \dots, m^*\}$ such that $k \neq \ell$ and $\mathbf{C}_j(x_\ell) \subset \mathbf{C}_j(x_k)$ (notice that this implies $f(x_\ell) \geq f(x_k)$ by construction of \mathbf{C}_j), it holds $f(x_\ell) > f(x_k)$.*

For $j \in \mathbb{N}^*$, let us denote by $\lambda_{j,h}$ the j -th eigenvalue of $\Delta_{f,h}^D$ counted with multiplicity. Then, there exists $c > 0$ such that in the limit $h \rightarrow 0$, it holds

$$\lambda_{m^*+1,h} = O(e^{-\frac{c}{h}}) \lambda_{m^*,h}.$$

Moreover, there exists $h_0 > 0$ such that for every $h \in (0, h_0)$, there exists a bijection

$$\Lambda_h : \{x_1, \dots, x_{m^*}\} \longrightarrow \sigma(\Delta_{f,h}^D) \cap [0, \lambda_{m^*,h}],$$

where the spectrum is counted with multiplicity, such that, for every $j \in \{1, \dots, m^*\}$, it holds when $h \rightarrow 0$:

$$\begin{aligned} \Lambda_h(x_j) &= \left(\sqrt{h} \mathbf{K}_{1,x_j} (1 + O(h)) + h \mathbf{K}_{2,x_j} (1 + O(\sqrt{h})) \right) e^{-\frac{2}{h}(f(\mathbf{j}(x_j)) - f(x_j))} \quad (131) \\ &= \left(\frac{A_{j,1} + \sqrt{h} A_{j,2}}{B_j} + O(h) \right) \sqrt{\frac{h}{\pi}} e^{-\frac{2}{h}(f(\mathbf{j}(x_j)) - f(x_j))}, \end{aligned}$$

where K_{1,x_j} and K_{2,x_j} are defined in (108), $B_j := \sum_{q \in \arg \min_{C_j(x_j)} f} (\det \text{Hess } f(q))^{-\frac{1}{2}}$,

$$A_{j,1} = \sum_{\substack{z \in \mathbf{j}(x_j) \\ |\nabla f(z)| \neq 0}} \frac{2\partial_{n_\Omega} f(z)}{(\det \text{Hess } f|_{\partial\Omega}(z))^{\frac{1}{2}}} \quad \text{and} \quad A_{j,2} = \frac{1}{\sqrt{\pi}} \sum_{\substack{z \in \mathbf{j}(x_j) \\ |\nabla f(z)| = 0}} \frac{(1 + \mathbf{1}_{\partial\Omega}(z)) |\mu_d|}{|\det \text{Hess } f(z)|^{\frac{1}{2}}},$$

where $\mathbf{1}_{\partial\Omega}(z) = 1$ if $z \in \partial\Omega$ and $\mathbf{1}_{\partial\Omega}(z) = 0$ if not, and μ_d denotes the negative eigenvalue of $\text{Hess } f(z)$ when $z \in \mathbf{j}(x)$ and $|\nabla f(z)| = 0$.

Finally, when $\mathbf{j}(x_j) \cap \partial\Omega$ does not contain any critical point of f , the above error term $O(\sqrt{h})$ is actually of order $O(h)$ in (131).

Remark 37. The first statement of Theorem 3 is a simple consequence of its first item together with Theorem 2 (or even of Theorem 1 when $\mathbf{m}^* = \mathbf{m}_0$). Moreover, when in addition $f(\mathbf{j}(x_1)) - f(x_1) > \dots > f(\mathbf{j}(x_{\mathbf{m}^*})) - f(x_{\mathbf{m}^*})$, the eigenvalues $\lambda_{1,h}, \dots, \lambda_{\mathbf{m}^*,h}$ are respectively $\Lambda_h(x_1), \dots, \Lambda_h(\mathbf{m}^*)$. They are then simple and, for every $\ell \in \{1, \dots, \mathbf{m}^* - 1\}$, there exists $c > 0$ such that it holds $\lambda_{\ell+1,h} = O(e^{-\frac{c}{h}}) \lambda_{\ell,h}$ in the limit $h \rightarrow 0$. In general, the situation is slightly more involved and, when for example Theorem 3 applies with $\mathbf{m}^* = 2$ and $f(\mathbf{j}(x_1)) - f(x_1) = f(\mathbf{j}(x_2)) - f(x_2)$, Theorem 3 permits to discriminate which eigenvalue among $\Lambda_h(x_1)$ and $\Lambda_h(x_2)$ is $\lambda_{1,h}$ if and only if $(A_{1,1}/B_1, A_{1,2}/B_1) \neq (A_{2,1}/B_2, A_{2,2}/B_2)$, even though $\lambda_{1,h}$ is simple (see [24] in this connection when f is a double-well potential).

Remark 38. The term $O(\sqrt{h})$ in (131) is in general optimal, see Remark 24 and item 1 in Proposition 25.

Proof. Let us work with the labeling of $U_0 = \{x_1, \dots, x_{\mathbf{m}_0}\}$ considered in the statement of Theorem 3. Note in passing that the labeling of $\{x_{\mathbf{m}^*+1}, \dots, x_{\mathbf{m}_0}\}$ is actually arbitrary. Let us moreover order $(\psi_x)_{x \in U_0} = (\psi_1, \dots, \psi_{\mathbf{m}_0})$ and $(\Theta_x)_{x \in U_0} = (\Theta_1, \dots, \Theta_{\mathbf{m}_0})$ according to this labeling of U_0 . The proof of Theorem 3 is divided into several steps and is partly inspired by the analysis led in [19, Section 7.4] which generalizes the procedure made in [16, 17] (see also [29, Section C.3.1.2]).

Step 1. Let us first choose an adapted orthonormal basis \mathcal{B}_0 of $\text{Ran}(\pi_h)$ in $L^2(\Omega)$ and an adapted orthonormal basis \mathcal{B}_1 of $\text{Span}(\Theta_i^\pi)_{i \in \{1, \dots, \mathbf{m}_0\}}$ in $\Lambda^1 L^2(\Omega)$.

Step 1.a) Choice of the basis \mathcal{B}_0 .

Let us first prove that items 2 and 3 in Theorem 3 imply the existence of $c > 0$ such that for every h small enough,

$$\forall i, j \in \{1, \dots, \mathbf{m}^*\}, \quad \langle \psi_i, \psi_j \rangle_{L^2(\Omega)} = \delta_{i,j} + O(e^{-\frac{c}{h}}). \quad (132)$$

To this end, let us recall that from (86) and Definition 22, one has

$$\forall i \in \{1, \dots, \mathbf{m}_0\}, \quad \text{supp } \psi_i \subset \overline{\Omega_1(x_i)} \quad (133)$$

and let us consider $i, j \in \{1, \dots, \mathbf{m}^*\}$. According to item 2 in Theorem 3, it thus holds $\mathbf{j}(x_i) \cap \mathbf{j}(x_j) = \emptyset$ and, according to item 4.(i) in Section 3.3, there are two possible cases which finally lead to (132):

- either $\overline{\mathbf{C}_j(x_j)} \cap \overline{\mathbf{C}_j(x_i)} = \emptyset$, in which case, according to item 3.(i) in Definition 20 and to (133), the supports of ψ_i and ψ_j are disjoint and thus $\langle \psi_i, \psi_j \rangle_{L^2(\Omega)} = 0$,
- or, up to switching i and j , $\overline{\mathbf{C}_j(x_j)} \subset \mathbf{C}_j(x_i)$, in which case, according to item 3.(i) in Definition 20, $\overline{\Omega_1(x_j)} \subset \Omega_2(x_i) \subset \Omega_1(x_i)$. In this case, it then follows from Definition 22, (86), and (93), that

$$\langle \psi_i, \psi_j \rangle_{L^2(\Omega)} = \frac{\int_{\Omega_1(x_j)} \phi_i \phi_j e^{-\frac{2}{h}f}}{Z_{x_j} Z_{x_i}} \leq Ch^{-\frac{d}{2}} e^{-\frac{1}{h}(2f(x_j) - f(x_i) - f(x_j))},$$

where we also used the relation $\min_{\overline{\Omega_1(x_j)}} f = \min_{\overline{\mathbf{C}_j(x_j)}} f = f(x_j)$ arising from the construction of the map \mathbf{C}_j and item 1 in Definition 20. Moreover, using item 3 in Theorem 3, it holds $f(x_j) > f(x_i)$, and thus, there exists $c > 0$ such that when $h \rightarrow 0$:

$$\langle \psi_i, \psi_j \rangle_{L^2(\Omega)} = O(e^{-\frac{c}{h}}).$$

Then, according to (132) and to Proposition 29, there exists $c > 0$ such that for all $i, j \in \{1, \dots, m^*\}$, it holds in the limit $h \rightarrow 0$:

$$\langle \psi_i^\pi, \psi_j^\pi \rangle_{\Lambda^1 L^2(\Omega)} = \delta_{i,j} + O(e^{-\frac{c}{h}}). \quad (134)$$

Let us now consider the standard Gram-Schmidt orthonormalization $\mathcal{B}_0 := (e_1, \dots, e_{m_0})$ of the family $(\psi_1^\pi, \dots, \psi_{m_0}^\pi)$ in $L^2(\Omega)$. According to (134), it thus holds, for all $k \in \{1, \dots, m^*\}$,

$$e_k = (1 + O(e^{-\frac{c}{h}}))\psi_k^\pi + \sum_{q=1}^{k-1} O(e^{-\frac{c}{h}})\psi_q^\pi.$$

Thus, the matrix C_0^π defined by (121) has the block structure

$$C_0^\pi = \begin{bmatrix} I_{m^*} + O(e^{-\frac{c}{h}}) & [C_0^\pi]_2 \\ 0 & [C_0^\pi]_4 \end{bmatrix}, \quad (135)$$

where I_{m^*} is the identity matrix of $\mathbb{R}^{m^* \times m^*}$, $[C_0^\pi]_4 \in \mathbb{R}^{(m_0 - m^*) \times (m_0 - m^*)}$ is an invertible matrix (since, according to Proposition 32, C_0^π is invertible), and $[C_0^\pi]_2 \in \mathbb{R}^{m^* \times (m_0 - m^*)}$. One then defines the $m_0 \times m_0$ matrix C_0 by

$$C_0 := \begin{bmatrix} I_{m^*} & [C_0^\pi]_2 \\ 0 & [C_0^\pi]_4 \end{bmatrix}, \quad (136)$$

so that, according to Proposition 32, C_0 is invertible and

$$C_0 = O(1), \quad C_0^{-1} = \begin{bmatrix} I_{m^*} & -[C_0^\pi]_2 [C_0^\pi]_4^{-1} \\ 0 & [C_0^\pi]_4^{-1} \end{bmatrix} = O(1), \quad \text{and} \quad C_0^{-1} C_0^\pi = I_{m_0} + O(e^{-\frac{c}{h}}). \quad (137)$$

Step 1.b) Choice of the basis \mathcal{B}_1 .

According to Definition 28, item 2 in Theorem 3, and to item 2.(i) in Proposition 25, it holds, for every h small enough:

$$\forall j \in \{1, \dots, m^*\}, \quad \forall i \in \{1, \dots, m_0\}, \quad \langle \Theta_i, \Theta_j \rangle_{\Lambda^1 L^2(\Omega)} = \delta_{i,j}. \quad (138)$$

Thus, using in addition Proposition 29, it holds, for every h small enough:

$$\forall j \in \{1, \dots, m^*\}, \forall i \in \{1, \dots, m_0\}, \quad \langle \Theta_i^\pi, \Theta_j^\pi \rangle_{\Lambda^1 L^2(\Omega)} = \delta_{i,j} + O(h). \quad (139)$$

Let us now consider the standard Gram-Schmidt orthonormalization $\mathcal{B}_1 := (\Upsilon_1, \dots, \Upsilon_{m_0})$ of the family $(\Theta_1^\pi, \dots, \Theta_{m_0}^\pi)$ in $\Lambda^1 L^2(\Omega)$. It thus holds in the limit $h \rightarrow 0$,

$$\forall k \in \{1, \dots, m^*\}, \quad \Upsilon_k = (1 + O(h)) \Theta_k^\pi + \sum_{q=1}^{k-1} O(h) \Theta_q^\pi$$

and, for some real numbers $a_{k,q}(h)$, $k \in \{m^* + 1, \dots, m_0\}$ and $q \in \{m^* + 1, \dots, k\}$,

$$\forall k \in \{m^* + 1, \dots, m_0\}, \quad \Upsilon_k = \sum_{q=1}^{m^*} O(h) \Theta_q^\pi + \sum_{q=m^*+1}^k a_{k,q}(h) \Theta_q^\pi.$$

Hence, with this choice of \mathcal{B}_1 , the matrix C_1^π defined by (121) has the block structure

$$C_1^\pi = \begin{bmatrix} I_{m^*} + O(h) & O(h) \\ 0 & [C_1^\pi]_4 \end{bmatrix}, \quad (140)$$

where $[C_1^\pi]_4 \in \mathbb{R}^{(m_0 - m^*) \times (m_0 - m^*)}$ is an invertible matrix (since C_1^π is invertible, see indeed Proposition 32) and, according to (128), $[C_1^\pi]_4 = O(1)$ and $[C_1^\pi]_4^{-1} = O(1)$ in the limit $h \rightarrow 0$. Finally, let us define the $m_0 \times m_0$ matrix C_1 by

$$C_1 := \begin{bmatrix} I_{m^*} & 0 \\ 0 & [C_1^\pi]_4 \end{bmatrix}, \quad (141)$$

so that, in the limit $h \rightarrow 0$, it holds

$$C_1 = O(1) \quad \text{and} \quad C_1^{-1} = O(1) \quad (142)$$

and

$$\|C_1^{-1} (I_{m_0} + O(h)) C_1^\pi\| = 1 + O(h) \quad \text{and} \quad \|(C_1^\pi)^{-1} (I_{m_0} + O(h)) C_1\| = 1 + O(h). \quad (143)$$

Step 2. Let us recall that in the limit $h \rightarrow 0$, the m_0 smallest eigenvalues of $\Delta_{f,h}^D$ are the singular values of the matrix $S^{\mathcal{B}_0, \mathcal{B}_1} = {}^t C_1^\pi S^\pi C_0^\pi \in \mathbb{R}^{m_0 \times m_0}$, where C_0^π , C_1^π , and S^π are defined in (121) and in (122). Moreover, the relation (127) leads to the factorization (see (123) for the definition of the matrix S)

$$S^{\mathcal{B}_0, \mathcal{B}_1} = {}^t (C_1^{-1} (I_{m_0} + O(h)) C_1^\pi) {}^t C_1 S C_0 (C_0^{-1} C_0^\pi).$$

Using (137), (143), and Lemma 36, it follows that

$$\forall j \in \{1, \dots, m_0\}, \quad \eta_j(S^{\mathcal{B}_0, \mathcal{B}_1}) = \eta_j({}^t C_1 S C_0) (1 + O(h)). \quad (144)$$

Hence, the m_0 smallest eigenvalues of $\Delta_{f,h}^D$ are, up to a multiplicative term of order $(1 + O(h))$, the squares of the singular values of the matrix ${}^t C_1 S C_0$.

In order to prepare the precise computation of these singular values made in the following step, let us first suitably decompose the matrices taking part into ${}^t C_1 S C_0$. To this end, let us introduce

$$k^* \in \{1, \dots, m^*\}$$

and write the diagonal matrix D defined by (124) and (125) as follows:

$$D = \begin{bmatrix} D_1 & 0 \\ 0 & D_2 \end{bmatrix}, \quad (145)$$

where D_1 is the square diagonal matrix of size k^* defined by

$$D_1 := \text{Diag}(h^{p_1} e^{-\frac{1}{h}(f(j(x_1)) - f(x_1))}, \dots, h^{p_{k^*}} e^{-\frac{1}{h}(f(j(x_{k^*})) - f(x_{k^*}))}) \quad (146)$$

and D_2 is the square diagonal matrix of size $m_0 - k^*$ defined by

$$D_2 := \text{Diag}(h^{p_{k^*+1}} e^{-\frac{1}{h}(f(j(x_{k^*+1})) - f(x_{k^*+1}))}, \dots, h^{p_{m_0}} e^{-\frac{1}{h}(f(j(x_{m_0})) - f(x_{m_0}))}). \quad (147)$$

Moreover, according to (138), the matrices $S = (\|d_{f,h}\psi_j\|_{\Lambda^1 L^2(\Omega)} \langle \Theta_i, \Theta_j \rangle_{\Lambda^1 L^2(\Omega)})_{i,j}$ and $T = S D^{-1}$ defined in (123) and in (126) have the block structure

$$S = \begin{bmatrix} S_1 & 0 \\ 0 & S_2 \end{bmatrix} \quad \text{and} \quad T = \begin{bmatrix} T_1 & 0 \\ 0 & T_2 \end{bmatrix}, \quad (148)$$

where:

- T_1 and S_1 are square diagonal matrices of size k^* defined by

$$S_1 := \text{Diag}(S_{1,1}, \dots, S_{k^*,k^*}) \quad \text{and} \quad T_1 := S_1 D_1^{-1}, \quad (149)$$

- $T_2, S_2 \in \mathbb{R}^{(m_0 - k^*) \times (m_0 - k^*)}$ and, according to Lemma 35,

$$T_2 = S_2 D_2^{-1} \text{ is invertible and } T_2^{-1} = O(1). \quad (150)$$

Using in addition (136) and (141), the matrices C_0 , C_1 and thus ${}^t C_1 S C_0$ have the block structures

$$C_0 = \begin{bmatrix} I_{k^*} & U \\ 0 & V \end{bmatrix}, \quad C_1 = \begin{bmatrix} I_{k^*} & 0 \\ 0 & W \end{bmatrix}, \quad \text{and thus} \quad {}^t C_1 S C_0 = \begin{bmatrix} S_1 & S_1 U \\ 0 & {}^t W S_2 V \end{bmatrix}, \quad (151)$$

where, according to (137) and (142), it holds in the limit $h \rightarrow 0$:

$$U, V = O(1), \quad V^{-1} = O(1) \quad \text{and} \quad W, W^{-1} = O(1). \quad (152)$$

Note lastly that when $k^* = m^*$, one has $U = [C_0^\pi]_2$, $V = [C_0^\pi]_4$, and $W = [C_1^\pi]_4$.

Step 3. We are now in position to prove Theorem 3. To this end, we will compute the smallest singular values of the matrix ${}^t C_1 S C_0$ that we have seen to be, up to a multiplicative error term of order $1 + O(h)$, the square roots of the smallest eigenvalues of $\Delta_{f,h}^D$ (see indeed (144)).

In the following, one uses the block decompositions exhibited in (145)–(151) and, for $\ell \in \mathbb{N}$, one denotes by $\|\cdot\|_2$ the Euclidean norm on \mathbb{R}^ℓ . Moreover, for every h small enough, one chooses the ordering of the set $\{x_1, \dots, x_{m^*}\}$, depending on h , such that

the sequence $(S_{j,j})_{j \in \{1, \dots, m^*\}}$ is increasing.

According to (144), (149), and to Proposition 34, it then suffices to show that there exists $c > 0$ such that it holds in the limit $h \rightarrow 0$,

$$\forall \ell \in \{1, \dots, m^*\}, \quad \eta_{m_0-\ell+1}({}^t C_1 S C_0) = S_{\ell, \ell} (1 + O(e^{-\frac{c}{h}})). \quad (153)$$

To this end, we recall that by the Max-Min principle, one has for every $\ell \in \{1, \dots, m_0\}$,

$$\eta_{m_0-\ell+1}({}^t C_1 S C_0) = \max_{E \subset \mathbb{R}^{m_0}, \dim E = \ell-1} \min_{y \in E^\perp; \|y\|_2=1} \left\| {}^t C_1 S C_0 y \right\|_2 \quad (154)$$

$$= \min_{E \subset \mathbb{R}^{m_0}, \dim E = \ell} \max_{y \in E; \|y\|_2=1} \left\| {}^t C_1 S C_0 y \right\|_2. \quad (155)$$

To obtain the upper bound in (153) for some arbitrary $\ell \in \{1, \dots, m^*\}$, we apply (155) which gives, according to (151) applied with $k^* = \ell$ and to (149):

$$\begin{aligned} \eta_{m_0-\ell+1}({}^t C_1 S C_0) &\leq \max_{y \in \mathbb{R}^\ell; \|y\|_2=1} \left\| {}^t C_1 S C_0 (y, 0, \dots, 0) \right\|_2 = \max_{y \in \mathbb{R}^\ell; \|y\|_2=1} \left\| S_1 y \right\|_2 \\ &= S_{\ell, \ell}. \end{aligned} \quad (156)$$

Let us now prove the lower bound in (153) for some arbitrary $\ell \in \{1, \dots, m^*\}$. For that purpose, let us introduce $y^* \in \mathbb{R}^{m_0}$ such that $\|y^*\|_2 = 1$, $y^* \in (\mathbb{R}^{\ell-1} \times \{0, \dots, 0\})^\perp$, and

$$\left\| {}^t C_1 S C_0 y^* \right\|_2 = \min_{y \in (\mathbb{R}^{\ell-1} \times \{0, \dots, 0\})^\perp; \|y\|_2=1} \left\| {}^t C_1 S C_0 y \right\|_2.$$

Note that according to (154), it holds in particular

$$\eta_{m_0-\ell+1}({}^t C_1 S C_0) \geq \left\| {}^t C_1 S C_0 y^* \right\|_2. \quad (157)$$

Let us also introduce $k^* \in \{\ell, \dots, m^*\}$ such that

$$f(\mathbf{j}(x_\ell)) - f(x_\ell) = f(\mathbf{j}(x_{k^*})) - f(x_{k^*}) > \max_{i=k^*+1, \dots, m_0} f(\mathbf{j}(x_j)) - f(x_j). \quad (158)$$

Note that this is indeed possible by the first item of Theorem 3. Let us then write $y^* = (y_a^*, y_b^*)$, where $y_a^* \in \mathbb{R}^{k^*}$ and $y_b^* \in \mathbb{R}^{m_0-k^*}$, and let us prove that there exists $c > 0$ such that when $h \rightarrow 0$,

$$\|y_b^*\|_2 = O(e^{-\frac{c}{h}}). \quad (159)$$

According to (157), (151) applied with k^* , and to the triangular inequality, one has

$$\begin{aligned} \eta_{m_0-\ell+1}({}^t C_1 S C_0) &\geq \left\| {}^t C_1 S C_0 (y_a^*, y_b^*) \right\|_2 \geq \left\| {}^t C_1 S C_0 (0, y_b^*) \right\|_2 - \left\| {}^t C_1 S C_0 (y_a^*, 0) \right\|_2 \\ &= \left\| {}^t C_1 S C_0 (0, y_b^*) \right\|_2 - \left\| S_1 y_a^* \right\|_2. \end{aligned}$$

Using in addition (156) and (149) with k^* , it follows that in the limit $h \rightarrow 0$:

$$\left\| {}^t C_1 S C_0 (0, y_b^*) \right\|_2 \leq S_{\ell, \ell} + \|S_1\| \|y_a^*\|_2 \leq 2S_{k^*, k^*}. \quad (160)$$

Moreover, according to (151), one has

$$\|{}^t C_1 S C_0(0, y_b^*)\|_2 = \left(\|S_1 U y_b^*\|_2^2 + \|{}^t W S_2 V y_b^*\|_2^2 \right)^{\frac{1}{2}} \geq \|{}^t W S_2 V y_b^*\|_2,$$

where, using (150) and (152), it holds for some $C > 0$ in the limit $h \rightarrow 0$,

$$\|{}^t W S_2 V y_b^*\|_2 = \|{}^t W T_2 D_2 V y_b^*\|_2 \geq \frac{1}{C} \|D_2^{-1}\|^{-1} \|y_b^*\|_2.$$

It then follows from (160) that in the limit $h \rightarrow 0$, it holds

$$\|y_b^*\|_2 \leq 2C \|D_2^{-1}\| S_{k^*, k^*},$$

which leads to (159) according to item 2 in Proposition 34, (147), and to (158).

Then, using (157), (151) with k^* , and (159) together with the fact that $U = O(1)$ (see (152)), we obtain the existence of $c > 0$ such that it holds in the limit $h \rightarrow 0$,

$$\begin{aligned} \eta_{m_0-\ell+1}({}^t C_1 S C_0) &\geq \|{}^t C_1 S C_0 y^*\|_2 \geq \|S_1 y_a^*\|_2 - \|S_1 U y_b^*\|_2 \\ &= \|S_1 y_a^*\|_2 - \|S_1\| O(e^{-\frac{c}{h}}). \end{aligned}$$

Hence, using in addition $\|y_a^*\|_2 = 1 + O(e^{-\frac{c}{h}})$ (which follows from (159) and $\|y^*\|_2 = 1$), $y_{a,1}^* = \dots = y_{a,\ell-1}^* = 0$ (since $y^* \in (\mathbb{R}^{\ell-1} \times \{0, \dots, 0\})^\perp$), (149), item 2 in Proposition 34, and (158), it holds in the limit $h \rightarrow 0$,

$$\eta_{m_0-\ell+1}({}^t C_1 S C_0) \geq S_{\ell,\ell}(1 + O(e^{-\frac{c}{h}})) - S_{k^*, k^*} O(e^{-\frac{c}{h}}) \geq S_{\ell,\ell}(1 + O(e^{-\frac{c}{2h}})),$$

which concludes the proof of (153). The proof of Theorem 3 is thus complete. \blacksquare

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