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▶ To cite this version:

Farouk Yahaya, Matthieu Puigt, Gilles Delmaire, Gilles Roussel. NMF for Big Data with Missing Entries: A Random Projection Based Approach. 6ème Journée Régionale des Doctorants en Automatique et Traitement du Signal (JRDA), Jul 2019, Lille, France. hal-02166582

HAL Id: hal-02166582

https://hal.science/hal-02166582

Submitted on 1 Jun 2021

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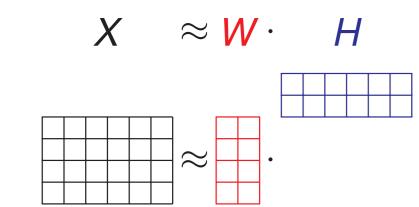
NMF for Big Data with Missing Entries: A Random Projection Based Approach

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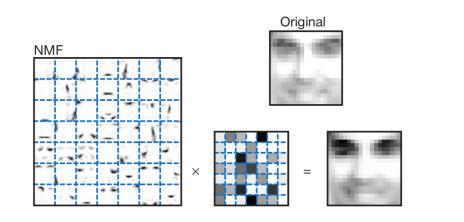
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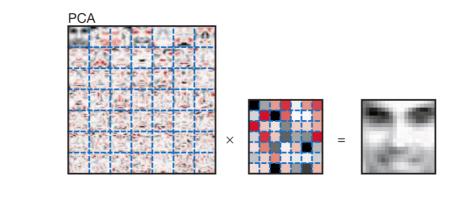
Context and problem statement



Nonnegative Matrix Factorization (NMF) is a popular tool in Signal/Image Processing and Machine Learning

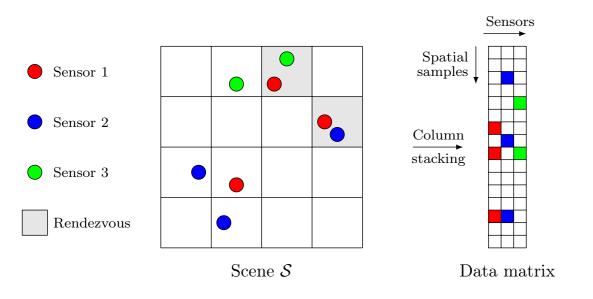
- ▶ Goal: estimate two nonnegative $n \times p$ and $p \times m$ matrices W and H such that an observed low-rank nonnegative $n \times m$ matrix X can be written as $X \approx W \cdot H$
- Some applications:
- ► Source separation, dictionary learning, graph analysis, topic modelling, hyperspectral unmixing...
- Why is NMF so popular? Better interpretability than no-sign-constrained approaches

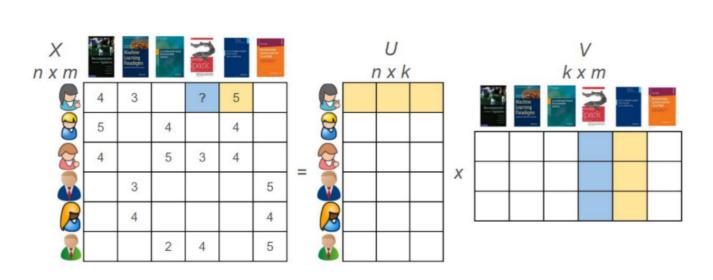




NMF and PCA applied to face dataset (source: [1])

- How is NMF working?
- ▶ Iterative procedure where W and H are alternatingly updated
- ► Historical techniques known to be slow (multiplicative updates, projected gradients, nonnegative least squares, etc)
- ► NMF and Big Data: How to face the data deluge?
- ► Distributed computing (e.g., [2])
- ► Online factorization (e.g., [3])
- ► Fast solver (e.g., [4])
- ► Randomized strategies (e.g., [5, 6, 7])
- ▶ In many problems, observed data matrix *X* with **missing entries or confidence measures** associated to each entry
 - ► Some applications: collaborative filtering, source apportionment, low-rank nonnegative matrix completion, mobile sensor calibration (aim of the Ph.D. thesis)





mobile sensor calibration (source: [8]).

recommender systems (source: [9])

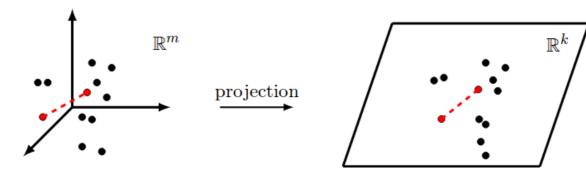
Weighted NMF (WNMF):

$$\min_{\boldsymbol{W},\boldsymbol{H}\geq 0}\|\boldsymbol{Q}\circ\boldsymbol{X}-\boldsymbol{Q}\circ(\boldsymbol{W}\cdot\boldsymbol{H})\|_{\mathcal{F}}$$

- ► WNMF and Big Data:
- 1. Most techniques are based on slow solvers
- 2. A few with the fastening strategies for unweighted NMF
- 3. No existing approach with random projections
- ⇒ How to use random projections in WNMF?

Principle of random projections applied to NMF

- ▶ Random projections is a popular tool in machine learning to speed-up computations while preserving pairwise structure
- Mathematical foundations based on the Johnson-Lindenstrauss Lemma



Principles of the random projections (source: [10])

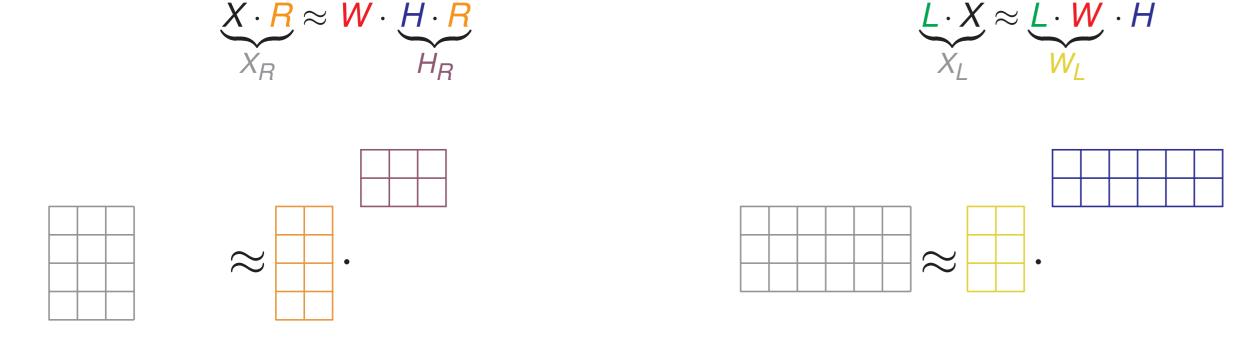
- Gaussian random matrices as projection matrices [5]
- Structured random projections [6, 7]
- Randomized Power Iterations (RPIs) or Randomized Subspace Iterations (RSIs)

Require: a target rank ν (with $p \le \nu \ll \min(n, m)$) and an integer qDraw Gaussian random matrices $\Omega_L \in \mathbb{R}^{m \times \nu}$ and $\Omega_R \in \mathbb{R}^{\nu \times n}$

Define $B_L \triangleq (XX^T)^q \cdot X \cdot \Omega_L$ and $B_R \triangleq \Omega_R \cdot X \cdot (X^TX)^q$ Derive $L \in \mathbb{R}^{\nu \times n}$ and $R \in \mathbb{R}^{m \times \nu}$ by QR decompositions of B_I and B_R , respectively.

- ► RSIs are similar but add intermediate QR decompositions in the computations ⇒ less sensitive to round-off errors than RPIs
- ♦ Why we have designed "compressions matrices" R and L?

Dimensionality reduction of X by right (resp. left) multiplication with R (resp. L)



NMF with weights

Weighted Extensions of NMF aim to solve:

$$\min_{W,H>0} \|Q \circ X - Q \circ (W \cdot H)\|_{\mathcal{F}}$$

- 1. Direct computations (Ho, 2008):
 - ► Incorporating the matrix *Q* in the update rules
- 2. EM-based strategy (Zhang et al., 2006)
 - ► E-step: Estimate the unknown entries of *X*

$$X^{\text{comp}} = Q \circ X + (\mathbb{1}_{n,m} - Q) \circ (W \cdot H), \tag{1}$$

where $\mathbb{1}_{n,m}$ is the $n \times m$ matrix of ones.

▶ M-step: Apply any standard NMF technique to X^{comp} Direct incorportation of random projections is not trivial...

Proposed Method

Require: initial matrices *W* and *H* repeat {Compression makes E-step 3 times slower in our experiments} {E-step} Compute X^{comp} as in (1) Apply RSIs or RPIs to X^{comp} to compute L and R Define $X_{I}^{\text{comp}} \triangleq L \cdot X^{\text{comp}}$ and $X_{R}^{\text{comp}} \triangleq X^{\text{comp}} \cdot R$ {M-step} {10-100 times faster than SotA EM-W-NMF methods in our experiments} for compt=1 to Max_{Outlter} do Define $H_R \triangleq H \cdot R$ Solve $\min_{W>0} \|X_{R}^{\text{comp}} - WH_{R}\|_{\mathcal{F}}$ Define $W_I \triangleq L \cdot W$ Solve $\min_{H>0} \|X_l^{\text{comp}} - W_L H\|_{\mathcal{F}}$ end for until a stopping criterion

Experiments and Results

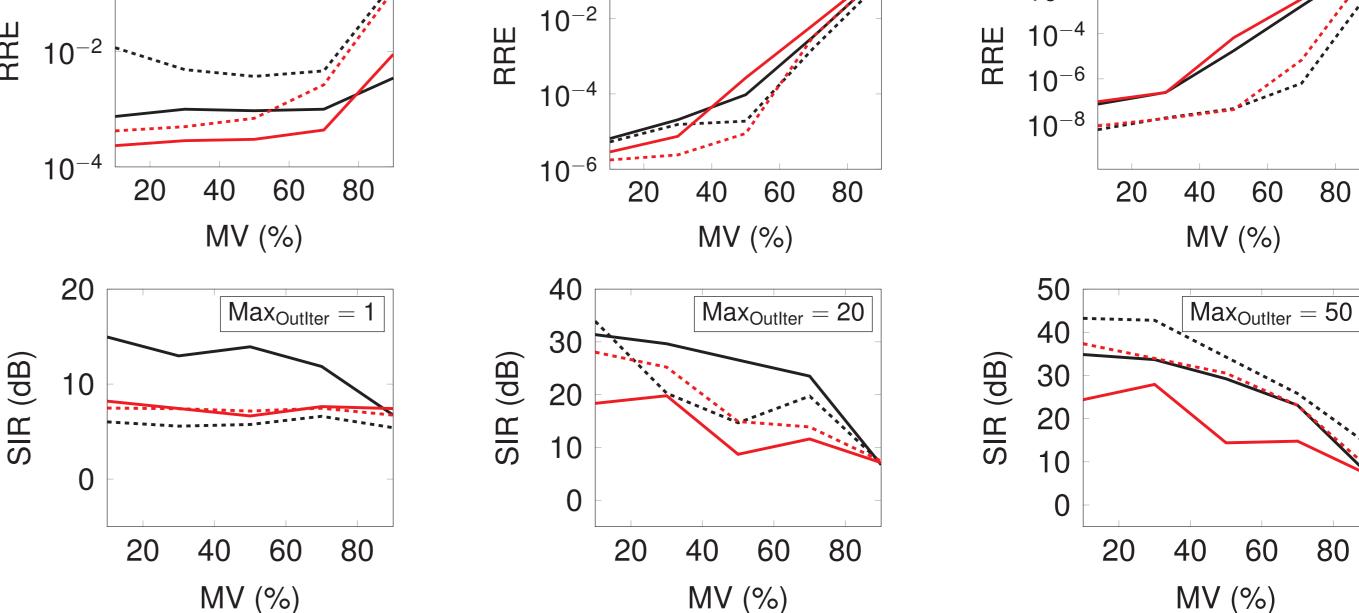
To test our method we run each test for 60 seconds and repeat 15 times the following:

- we randomly generate nonnegative factor matrices W^{theo} and H^{theo} , with n=m=10000and p = 5.
- \blacktriangleright we randomly suppress data to generate X, with a sampling rate varying from 10 to 90% (with a step-size of 20%)
- ▶ We compare the proposed REM-W-NMF strategy to the EM-W-NMF with several solvers,
- i.e., MU, PG, ALS & Nesterov iterations ▶ measure the accuracy of reconstruction of X Relative Reconstruction Error (RRE) and the

accuracy of estimation of *H* (Signal-to-Interference Ratio—SIR)

$$RRE \triangleq \left| \left| X^{\text{theo}} - W \cdot H \right| \right|_{\mathcal{F}}^{2} / \left| \left| X^{\text{theo}} \right| \right|_{\mathcal{F}}^{2} \quad (2) \qquad SIR = \sum_{j=1}^{p} 10 \log_{10} \left(\left| \left| \hat{h}_{j}^{\text{coll}} \right| \right|^{2} / \left| \left| \hat{h}_{j}^{\text{orth}} \right| \right|^{2} \right) \quad (3)$$

$$10^{0} \qquad 10^{0} \qquad 10^{0} \qquad 10^{-2} \qquad 10^{-2} \qquad 10^{-2} \qquad 10^{-2} \qquad 10^{-4} \qquad 10^{-4} \qquad 10^{-4} \qquad 10^{-6} \qquad$$



REM-W-NMF-ALS — EM-W-NeNMF ... EM-W-NMF-ALS ... **REM-W-NeNMF**

Conclusion and perspectives

- ► Novel framework to combine random projections and weighted matrix factorization.
- ▶ Based on an EM scheme
- ► The proposed strategy outperforms non-randomized state-of-the-art EM techniques
- ▶ In future work, we aim to apply the proposed strategy to informed and structured NMF techniques applied to mobile sensor calibration

References and acknowledgments

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F. Yahaya gratefully acknowledges the Région Hauts-de-France to partly fund his PhD fellowship.