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NMF for Big Data with Missing Entries: **A Random Projection Based Approach**

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Context and problem statement



- Nonnegative Matrix Factorization (NMF) is a popular tool in Signal/Image Processing and Machine Learning
- Goal: estimate two nonnegative $n \times p$ and $p \times m$ matrices *W* and *H* such that an observed low-rank nonnegative $n \times m$ matrix X can be written as $X \approx W \cdot H$
- Some applications:
 - **Source separation**, dictionary learning, graph analysis, topic modelling, hyperspectral unmixing...
- Why is NMF so popular? Better interpretability than no-sign-constrained approaches





Proposed Method

```
Require: initial matrices W and H
   repeat
                                              {Compression makes E-step 3 times slower in our experiments}
    {E-step}
    Compute X^{\text{comp}} as in (1)
    Apply RSIs or RPIs to X^{\text{comp}} to compute L and R
Define X_{L}^{\text{comp}} \triangleq L \cdot X^{\text{comp}} and X_{R}^{\text{comp}} \triangleq X^{\text{comp}}.
    {M-step}
                                 {10-100 times faster than SotA EM-W-NMF methods in our experiments}
    for compt=1 to Max<sub>OutIter</sub> do
     Define H_R \triangleq H \cdot R
      Solve \min_{W>0} \|X_B^{comp} - WH_B\|_{\mathcal{F}}
      Define W_{I} \triangleq L \cdot W
      Solve min<sub>H>0</sub> <math>||X_{L}^{comp} - W_{L}H||_{\mathcal{F}}</sub>
    end for
   until a stopping criterion
```

NMF and PCA applied to face dataset (source: [1])

- How is NMF working?
 - Iterative procedure where W and H are alternatingly updated
 - Historical techniques known to be slow (multiplicative updates, projected gradients, nonnegative least squares, etc)
- NMF and Big Data: How to face the data deluge?
 - Distributed computing (e.g., [2])
 - Online factorization (e.g., [3])
- ► Fast solver (e.g., [4])
- ► Randomized strategies (e.g., [5, 6, 7])
- ► In many problems, observed data matrix X with **missing entries or confidence measures** associated to each entry
- ► Some applications: collaborative filtering, source apportionment, low-rank nonnegative matrix completion, mobile sensor calibration (aim of the Ph.D. thesis)



mobile sensor calibration (source: [8]).



recommender systems (source: [9])

➡ Weighted NMF (WNMF):

$$\min_{\boldsymbol{W},\boldsymbol{H}\geq 0} \|\boldsymbol{Q}\circ\boldsymbol{X}-\boldsymbol{Q}\circ(\boldsymbol{W}\cdot\boldsymbol{H})\|_{\mathcal{F}}$$

- ► WNMF and Big Data:
- 1. Most techniques are based on slow solvers
- 2. A few with the fastening strategies for unweighted NMF
- 3. No existing approach with random projections

⇒ How to use random projections in WNMF?

Experiments and Results

To test our method we run each test for 60 seconds and repeat 15 times the following:

- we randomly generate nonnegative factor matrices W^{theo} and H^{theo} , with n = m = 10000and p = 5.
- we randomly suppress data to generate X, with a sampling rate varying from 10 to 90% (with a step-size of 20%)
- ► We compare the proposed REM-W-NMF strategy to the EM-W-NMF with several solvers, i.e., MU, PG, ALS & Nesterov iterations
- measure the accuracy of reconstruction of X Relative Reconstruction Error (RRE) and the accuracy of estimation of *H* (Signal-to-Interference Ratio—SIR)

$$\mathsf{RRE} \triangleq \left| \left| X^{\mathsf{theo}} - \mathbf{W} \cdot \mathbf{H} \right| \right|_{\mathcal{F}}^{2} / \left| \left| X^{\mathsf{theo}} \right| \right|_{\mathcal{F}}^{2} \quad (2) \qquad \mathsf{SIR} = \sum_{j=1}^{p} 10 \log_{10} \left(\left| \left| \hat{h}_{j}^{\mathsf{coll}} \right| \right|^{2} / \left| \left| \hat{h}_{j}^{\mathsf{orth}} \right| \right|^{2} \right) \quad (3)$$







 $Max_{OutIter} = 50$

50

40

30

20

10

Ω

SIR (dB)



Principle of random projections applied to NMF

- Random projections is a popular tool in machine learning to speed-up computations while preserving pairwise structure
- Mathematical foundations based on the Johnson-Lindenstrauss Lemma



Principles of the random projections (source: [10])

- Gaussian random matrices as projection matrices [5]
- Structured random projections [6, 7]
- Randomized Power Iterations (RPIs) or Randomized Subspace Iterations (RSIs)

Require: a target rank ν (with $p \le \nu \ll \min(n, m)$) and an integer qDraw Gaussian random matrices $\Omega_L \in \mathbb{R}^{m \times \nu}$ and $\Omega_B \in \mathbb{R}^{\nu \times n}$ Define $B_L \triangleq (XX^T)^q \cdot X \cdot \Omega_L$ and $B_R \triangleq \Omega_R \cdot X \cdot (X^T X)^q$ Derive $L \in \mathbb{R}^{\nu \times n}$ and $R \in \mathbb{R}^{m \times \nu}$ by QR decompositions of B_I and B_R , respectively.

► RSIs are similar but add intermediate QR decompositions in the computations less sensitive to round-off errors than RPIs

▷ Why we have designed "compressions matrices" R and L ?

Dimensionality reduction of X by right (resp. left) multiplication with R (resp. L)





EM-W-NMF-ALS ···· REM-W-NMF-ALS — EM-W-NeNMF … **REM-W-NeNMF**

Conclusion and perspectives

- Novel framework to combine random projections and weighted matrix factorization.
- Based on an EM scheme
- ► The proposed strategy outperforms non-randomized state-of-the-art EM techniques
- ► In future work, we aim to apply the proposed strategy to informed and structured NMF techniques applied to mobile sensor calibration

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NMF with weights

Weighted Extensions of NMF aim to solve:

 $\min_{\boldsymbol{W},\boldsymbol{H}>0} \|\boldsymbol{Q}\circ\boldsymbol{X}-\boldsymbol{Q}\circ(\boldsymbol{W}\cdot\boldsymbol{H})\|_{\mathcal{F}}$

1. Direct computations (Ho, 2008): ► Incorporating the matrix *Q* in the update rules 2. EM-based strategy (Zhang *et al.*, 2006) ► E-step: Estimate the unknown entries of X

$X^{\operatorname{comp}} = Q \circ X + (\mathbb{1}_{n.m} - Q) \circ (W \cdot H),$

where $\mathbb{1}_{n,m}$ is the $n \times m$ matrix of ones.

M-step: Apply any standard NMF technique to X^{comp}

Direct incorportation of random projections is not trivial...

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