

```

> des := {delta(t) = 0.01*t, delta(t0) = delta0, diff(phi(t), t) =
tan(delta(t))/l, diff(x(t), t) = V*cos(phi(t)), diff(y(t), t) =
V*sin(phi(t)), phi(t0) = phi0, x(t0) = x0, y(t0) = y0};
> desSol := dsolve(des, numeric, parameters = [V, l, t0, x0, y0,
phi0, delta0]);
> desSol(parameters = [109, 5, 0, 0, 0, 0, 0]);
> desSol(90);
> with(plots);
> odeplot(desSol, [[t, x(t)], [t, y(t)], [t, phi(t)]], 0 .. 300,
labels = ["t", "Trajectory"], legend = ["x(t) - Position in x",
"y(t) - Position in y", "phi(t) - Heading Angle"]);
> odeplot(desSol, [t, x(t), y(t)], 0 .. 300);
> odeplot(desSol, [x(t), y(t), phi(t)], 0 .. 150, labels = ["x -
Position", "y - Position", "phi - Heading Angle"]);

des :=  $\left\{ \begin{array}{l} \delta(t) = 0.01 t, \delta(t0) = \delta0, \frac{d}{dt} \phi(t) = \frac{\tan(\delta(t))}{l}, \frac{d}{dt} x(t) = V \cos(\phi(t)), \frac{d}{dt} y(t) \\ = V \sin(\phi(t)), \phi(t0) = \phi0, x(t0) = x0, y(t0) = y0 \end{array} \right\}$ 

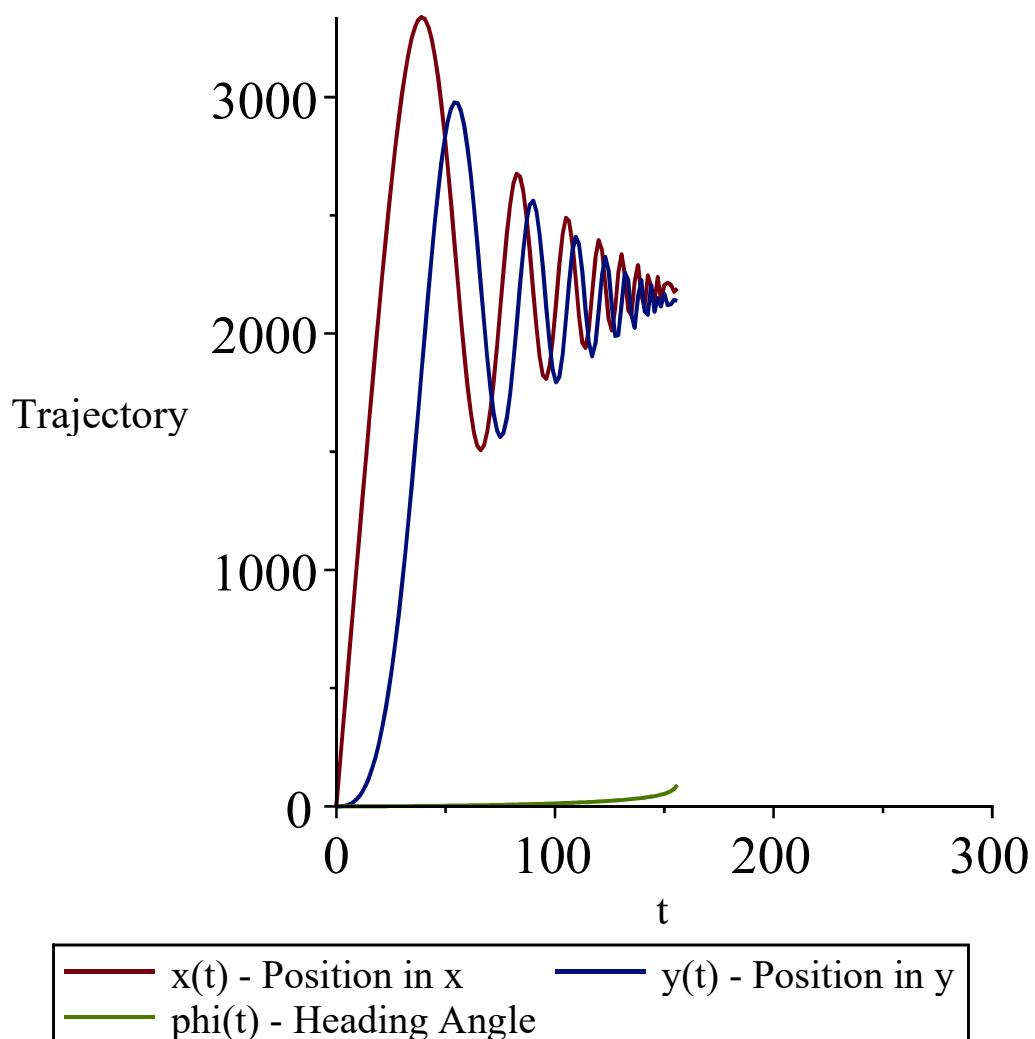
desSol := proc(x_rkf45_dae) ... end proc
[ V=109., l=5., t0=0., x0=0., y0=0., phi0=0., delta0=0. ]

[ t=90., delta(t)=0.900000000000000, phi(t)=9.50884887136091, x(t)=2184.94156683081, y(t)
= 2561.96008935270 ]

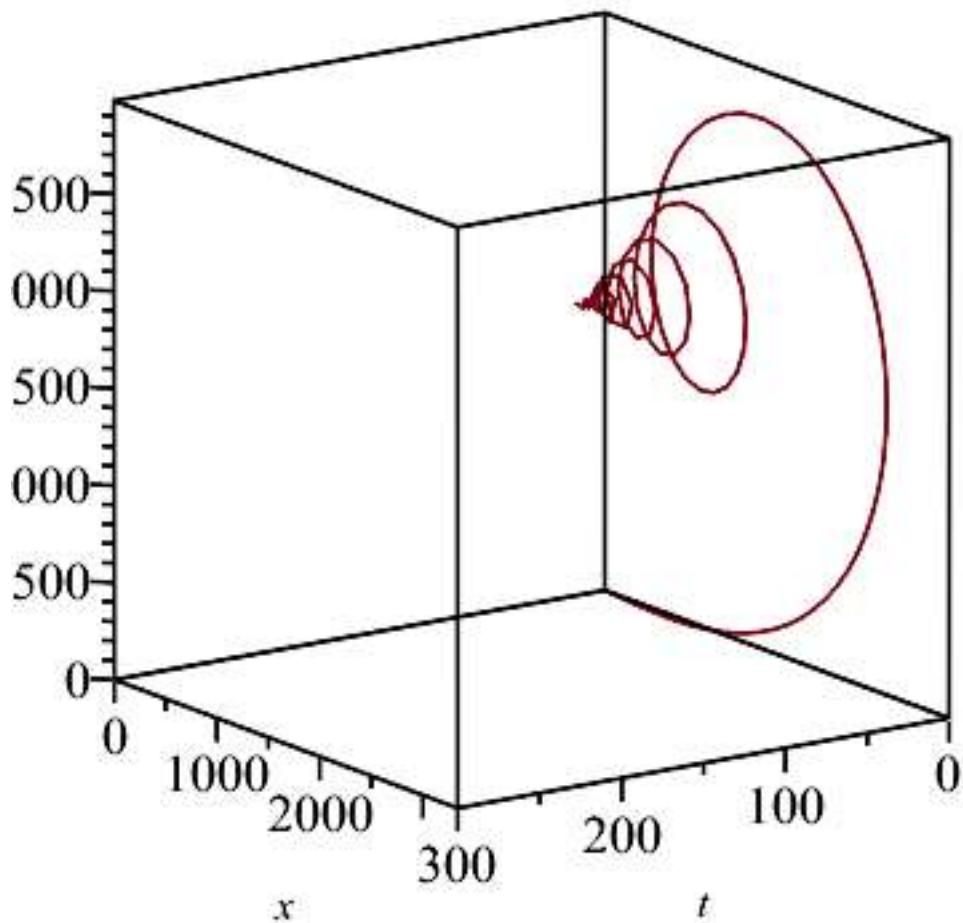
[animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d,
conformal, conformal3d, contourplot, contourplot3d, coordplot, coordplot3d, densityplot,
display, dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d, implicitplot,
implicitplot3d, inequal, interactive, interactiveparams, intersectplot, listcontplot,
listcontplot3d, listdensityplot, listplot, listplot3d, loglogplot, logplot, matrixplot, multiple,
odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot, polygonplot, polygonplot3d,
polyhedra_supported, polyhedraplot, rootlocus, semilogplot, setcolors, setoptions,
setoptions3d, shadebetween, spacecurve, sparsematrixplot, surldata, textplot, textplot3d,
tubeplot]

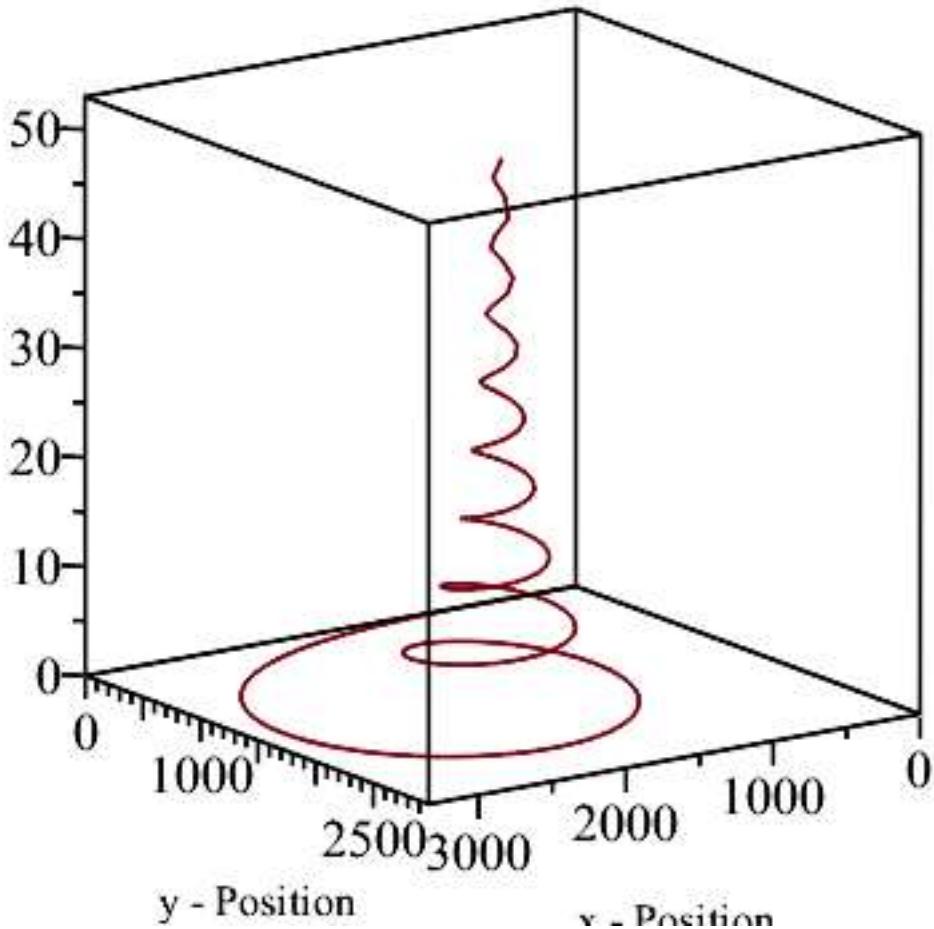
Warning, cannot evaluate the solution further right of
157.07963, probably a singularity

```



Warning, cannot evaluate the solution further right of 157.07963, probably a singularity





> `fsolve(des)`

$$fsolve\left(\left\{\delta(t) = 0.01, t, \delta(t0) = \delta0, \frac{d}{dt} \phi(t) = \frac{\tan(\delta(t))}{l}, \frac{d}{dt} x(t) = V \cos(\phi(t)), \frac{d}{dt} y(t) = V \sin(\phi(t)), \phi(t0) = \phi0, x(t0) = x0, y(t0) = y0\right\}, \{V, \delta0, l, \phi0, t, t0, x0, y0\}\right) \quad (1)$$

> `singularities(des, t)`

`singularities(des, t)` (2)

> `singularities(desSol, [[t, x(t)], [t, y(t)], [t, phi(t)]])`

`singularities(desSol, [[t, x(t)], [t, y(t)], [t, phi(t)]])` (3)

>

with

(DEtools,

singularities, hyperode, convertAlg, dpolyform)

with (DEtools, singularities, hyperode, convertAlg, dpolyform) (4)

> `singularities(des)`

`singularities(des)` (5)

> `singularities(desSol)`

(6)

> $\text{singularities}(\text{desSol})$

(7)

> $\text{singularities}(\text{des}, \text{x}(t), \text{y}(t))$

(8)

> des

(9)

> $\text{singularities}(\{\delta(t) = 0.01 * t, \text{delta}(t0) = \text{delta0}, \text{diff}(\phi(t), t) = \tan(\delta(t)) / l, \text{diff}(x(t), t) = V * \cos(\phi(t)), \text{diff}(y(t), t) = V * \sin(\phi(t)), \phi(t0) = \phi0, x(t0) = x0, y(t0) = y0\}, t, \text{x}(t), \text{y}(t))$

(9)

$\text{singularities}\left(\left\{\delta(t) = 0.01 t, \delta(t0) = \delta0, \frac{d}{dt} \phi(t) = \frac{\tan(\delta(t))}{l}, \frac{d}{dt} x(t) = V \cos(\phi(t)), \frac{d}{dt} y(t) = V \sin(\phi(t)), \phi(t0) = \phi0, x(t0) = x0, y(t0) = y0\right\}, t, \text{x}(t), \text{y}(t)\right)$

(10)

> $\text{singularities}(\{\delta(t) = 0.01 * t, \text{delta}(t0) = \text{delta0}, \text{diff}(\phi(t), t) = \tan(\delta(t)) / l, \text{diff}(x(t), t) = V * \cos(\phi(t)), \text{diff}(y(t), t) = V * \sin(\phi(t)), \phi(t0) = \phi0, x(t0) = x0, y(t0) = y0\}, t, \text{x}(t), \text{y}(t), \phi(t))$

(10)

$\text{singularities}\left(\left\{\delta(t) = 0.01 t, \delta(t0) = \delta0, \frac{d}{dt} \phi(t) = \frac{\tan(\delta(t))}{l}, \frac{d}{dt} x(t) = V \cos(\phi(t)), \frac{d}{dt} y(t) = V \sin(\phi(t)), \phi(t0) = \phi0, x(t0) = x0, y(t0) = y0\right\}, t, \text{x}(t), \text{y}(t), \phi(t)\right)$

>