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Challenges to global solutions in Horndeski's theory

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We explore the question of obtaining global solutions in Horndeski's theories of gravity. Toward this end, we study a relevant set of the theory and, by employing the Einstein frame we simplify the analysis by exploiting known results on global solutions of wave equations. We identify conditions for achieving global solutions as well as obstacles that can arise to spoil such goal. We illustrate such problems via numerical simulations.

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I. INTRODUCTION

In the context of extensions to general relativity, Horndeski's theories [1] stand out since they constitute the most general four-dimensional, diffeomorphism covariant theories leading to second order equations of motion [2,3]. These theories, where the gravitational degrees of freedom are expressed in terms of a metric tensor together with a scalar field, have a particularly distinct feature. Namely, the equations of motion they define are of *second order type*. This property ensures the absence of Ostrogradski ghosts (e.g., [2]), which is arguably a necessary condition for any physical theory. The freedom allowed by this family of theories has been exploited in many fronts, for instance, with goals to address dark energy (see e.g., [4–7] and references therein) and incipient explorations of extensions of GR in binary mergers (e.g., [8–15]). In the former front, particular examples include quintessence [16,17], kinetic quintessence or *k*-essence [18,19], and chameleon/galileon [20,21] theories.

Typically, applications have been analyzed in the context of linearized studies over specific backgrounds endowed with special symmetries, and consistency with observations in different regimes is addressed. In particular, the subset of Horndeski's theories allowed by observation have been severely constrained by the gravitational wave event GW170817 [22–24], with constraints derived from linearized studies. In spite of certainly relevant discussions and consequences derived in this context, it is important however to understand the fully nonlinear behavior of allowed theories within this family. For instance, a successful observation derived at the linear level which is not derivable from the nonlinear system would arguably call into question the original

action as providing a true model for nature¹ or the extent to which a linear analysis yields comprehensive/sensible constraints. Consistency of solutions to the linear problem with those of the full problem in the linear regime is not always a given as nonlinear solutions might give rise to phenomenology completely absent at the linear level—even when initial conditions are chosen within the linear regime. In the case of general relativity and its application in cosmology, requirements for this being the case have been discussed in [25].

Naturally, the extent to which a linear solution can be trusted—with respect to the original action—depends on one's understanding of the nonlinear regime. To gain such understanding, which in turn can help decide which subset within the theory can be considered physical, a stricter and certainly natural condition must be satisfied. Namely, *well posedness* [26]. This condition, implies a given problem has a unique solution that depends continuously on initial and boundary data.² From a natural point of view, the satisfaction of these properties is crucial for the physical understanding of the problem under consideration.

Consequently, insisting a valid theory must yield well-posed initial boundary value problems is a general powerful requirement to restrict potential options and identify possible alternatives to general relativity. The analysis of this condition in specific theories is typically complex, which has hindered drawing straightforward conclusions for Horndeski's theories in the past. Recent works however have begun to explore this issue and, in particular, have

¹In the former case, the linear system should instead be regarded as the fundamental building block.

²The absence of Ostrogradski ghosts is necessary but certainly not sufficient for well posedness.

uncovered significant restrictions [27–29] even locally. We stress the importance of this condition cannot be underestimated even in linearized regimes. Failure to satisfy it implies it would be impossible to trust possible solutions let alone seek them in the first place—regardless of the method employed to seek for such solutions.

In this paper, both strongly motivated by and building from these recent works, we revisit the problem from a slightly different angle by performing our analysis in a different frame—the so called Einstein frame. As a result, a simpler system is obtained where the complexity of the analysis lies primarily in understanding the equation of motion for the scalar field. In such frame it is arguably easier to elucidate the degree to which these theories display a more involved behavior when contrasted with general relativity and the obstacles that might arise to obtain global solutions.

We recall that much has been discussed on the issue of frames in scalar-tensor gravity theories such as Horndeski's (e.g., [30,31]). Whether the Ricci scalar appears “clean” in such action or not is often signaled as being a description in the Einstein (former) or Jordan frame. Here we explore (a subset of) Horndeski's theories from the initial value problem (IVP) point of view in the Einstein frame, discuss the existence of delicate issues, and illustrate their consequences via numerical simulations. As well, and for concreteness, we do not concern ourselves at this time with the “nonvacuum case,” i.e., scenarios which include matter. Here further issues come into play that in and of themselves raise further concerns for the theory to remain viable—from observational points of view. This, in turn, requires invoking mechanisms like “Vainshtein screening” which bring about further mathematical difficulties; see e.g., [32].

This work is organized as follows. In Sec. II we revisit the special case of Horndeski's theories that has been identified as well posed and reanalyze it in the Einstein frame drawing general conclusions about such case and discuss issues related to well posedness in the nonlinear regime. In Secs. III and IV we illustrate our discussion both analytically and numerically in a couple of special cases.

II. HORNDESKI'S THEORY, SPECIAL CASE ANALYZED

Horndeski's theories describe gravitational interactions in terms of a metric tensor g_{ab} and a scalar field ϕ . Their equations of motion are determined from the action

$$S = \frac{1}{16\pi G} \int d^4x \sqrt{-g} (\Sigma_{i=1}^5 \mathcal{L}_i) \quad (1)$$

where

$$\mathcal{L}_1 = R + X - V(\phi), \quad (2)$$

$$\mathcal{L}_2 = \mathcal{G}_2(\phi, X), \quad (3)$$

$$\mathcal{L}_3 = \mathcal{G}_3(\phi, X) \square \phi, \quad (4)$$

$$\mathcal{L}_4 = \mathcal{G}_4(\phi, X) R + \partial_X \mathcal{G}_4(\phi, X) \delta_{bd}^{ac} \nabla_a \nabla^b \phi \nabla_c \nabla^d \phi, \quad (5)$$

$$\begin{aligned} \mathcal{L}_5 = & \mathcal{G}_5(\phi, X) G_{ab} \nabla^a \nabla^b \phi \\ & - \frac{1}{6} \partial_X \mathcal{G}_5(\phi, X) \delta_{bdf}^{ace} \nabla_a \nabla^b \phi \nabla_c \nabla^d \phi \nabla_e \nabla^f \phi. \end{aligned} \quad (6)$$

with $X = -1/2 \nabla_a \phi \nabla^a \phi$, G_{ab} the Einstein tensor, \mathcal{G}_i are functions of the scalars $\{\phi, X\}$, V is a potential, and $\delta_{a_1 \dots a_n}^{b_1 \dots b_n}$ is the generalized Kronecker delta symbol.

A thorough analysis of hyperbolicity properties of the resulting equations of motion, given the complexity of the PDE system, is naturally a difficult task. One such study has been presented recently in [27] (see also [28]). Here, following steps taken to establish local well posedness of Einstein equations [33]—whereby the introduction of harmonic coordinates renders Einstein equations manifestly symmetric hyperbolic—a judicious coordinate choice is found to guarantee strong hyperbolicity. Within this context, it is shown that only a special subset of Horndeski's theories leads to strong hyperbolicity in harmonic gauge in the nonlinear regime. This subset is given by the action

$$S = \frac{1}{16\pi} \int d^4x \sqrt{-g} [(1 + \mathcal{G}_4(\phi)) R + X - V(\phi) + \mathcal{G}_2(\phi, X)]. \quad (7)$$

Notice the action above corresponds to the so-called Jordan frame (as the Ricci scalar appears multiplied by a nontrivial function of ϕ). The equations of motion obtained from this action can be found in [27]. A conformal transformation, of the form $\tilde{g}_{ab} = \Omega^2 g_{ab}$ with $\Omega = \sqrt{1 + \mathcal{G}_4(\phi)}$, can be exploited to obtain the equations in the Einstein frame. We assume that the conformal factor Ω never vanishes, which ensures that the transformation is well defined and the two formulations of the theory are equivalent. It allows one to rewrite the above action as

$$\begin{aligned} S = & \frac{1}{16\pi} \int d^4x \sqrt{-\tilde{g}} \left\{ \tilde{R} + \frac{1}{(1 + \mathcal{G}_4(\phi))^2} \right. \\ & \times [(3[\mathcal{G}'_4(\phi)]^2 + 1 + \mathcal{G}_4(\phi)) \tilde{X} - V(\phi) \\ & \left. + \mathcal{G}_2(\phi, (1 + \mathcal{G}_4(\phi)) \tilde{X}) \right\}, \end{aligned} \quad (8)$$

where $\tilde{X} = -1/2 \tilde{\nabla}_c \phi \tilde{\nabla}^c \phi$. From this action, the equations of motion are

$$\begin{aligned} \tilde{G}_{ab} = & \left[\frac{3[\mathcal{G}'_4(\phi)]^2 + 1 + \mathcal{G}_4(\phi)}{2(1 + \mathcal{G}_4(\phi))^2} \tilde{X} + \frac{-V(\phi) + \mathcal{G}_2(\phi, X)}{2(1 + \mathcal{G}_4(\phi))^2} \right] \tilde{g}_{ab} \\ & + \left[\frac{3[\mathcal{G}'_4(\phi)]^2}{2(1 + \mathcal{G}_4(\phi))^2} + \frac{1 + \partial_X \mathcal{G}_2(\phi, X)}{2(1 + \mathcal{G}_4(\phi))} \right] \tilde{\nabla}_a \phi \tilde{\nabla}_b \phi, \end{aligned} \quad (9)$$

$$\begin{aligned}
& \left[\tilde{g}^{ab} - \frac{(1 + \mathcal{G}_4(\phi))^2 \partial_{XX}^2 \mathcal{G}_2(\phi, X)}{3[\mathcal{G}'_4(\phi)]^2 + (1 + \mathcal{G}_4(\phi))(1 + \partial_X \mathcal{G}_2(\phi, X))} \tilde{\nabla}^a \phi \tilde{\nabla}^b \phi \right] \tilde{\nabla}_a \tilde{\nabla}_b \phi \\
&= \frac{1}{3[\mathcal{G}'_4(\phi)]^2 + (1 + \mathcal{G}_4(\phi))(1 + \partial_X \mathcal{G}_2(\phi, X))} \left\{ V'(\phi) - \partial_\phi \mathcal{G}_2(\phi, X) - 2\mathcal{G}'_4(\phi) \frac{V(\phi) - \mathcal{G}_2(\phi, X)}{1 + \mathcal{G}_4(\phi)} \right. \\
&\quad + \left[2(1 + \mathcal{G}_4(\phi)) \partial_{\phi X}^2 \mathcal{G}_2(\phi, X) + \mathcal{G}'_4(\phi) \left(6\mathcal{G}''_4(\phi) - 1 - 3\partial_X \mathcal{G}_2(\phi, X) - 6 \frac{[\mathcal{G}'_4(\phi)]^2}{1 + \mathcal{G}_4(\phi)} \right) \right] \tilde{X} \\
&\quad \left. + 2\mathcal{G}'_4(\phi)(1 + \mathcal{G}_4(\phi)) \partial_{XX}^2 \mathcal{G}_2(\phi, X) \tilde{X}^2 \right\}. \tag{10}
\end{aligned}$$

In order to write the scalar field equation in the convenient form (10), we have divided it by the overall factor $3[\mathcal{G}'_4(\phi)]^2 + (1 + \mathcal{G}_4(\phi))(1 + \partial_X \mathcal{G}_2(\phi, X))(1 + \mathcal{G}_4(\phi))^{-2}$. In the following, we will assume that this factor is nonzero. Notice that neither of the right-hand sides in Eqs. (9) and (10) involve second order derivatives of the relevant fields (metric or scalar), and, the hyperbolic properties of the system can be assessed independently for g_{ab} and ϕ . In the case of the metric tensor, such properties only depend on the metric tensor itself and we can draw from the vast knowledge about properties of Einstein equations (see e.g., [34]). In particular, we recall that they can be straightforwardly rendered into symmetric hyperbolic form. Indeed, following again [33], one can introduce harmonic coordinates ($\tilde{\Gamma}_a = 0$), and Eq. (9) becomes symmetric hyperbolic. Further, we recall the speed of propagation of perturbations is *independent of the metric tensor itself* (thus the equation is linearly degenerate and no shocks can arise from smooth initial data). Importantly, the observations above with regards to well posedness (at least locally) and linear degeneracy are certainly valid for other gauges. As we shall discuss below, regardless of the gauge choice, the scalar field equation has particular “worrisome” properties.

The principal part of the scalar field equation depends on $\{g_{ab}, \phi, \partial_a \phi\}$. Indeed, the principal part of the equation for ϕ , Eq. (10), is given by a wave equation of a modified metric

$$\gamma^{ab} = \tilde{g}^{ab} - \frac{(1 + \mathcal{G}_4(\phi))^2 \partial_{XX}^2 \mathcal{G}_2(\phi, X)}{3[\mathcal{G}'_4(\phi)]^2 + (1 + \mathcal{G}_4(\phi))(1 + \partial_X \mathcal{G}_2(\phi, X))} \times \tilde{\nabla}^a \phi \tilde{\nabla}^b \phi. \tag{11}$$

Thus, propagation speeds of scalar field perturbations depend on the state of the field and its gradient. As a consequence, shocks can develop from smooth initial data, at which point uniqueness of the solution is lost and with it, well posedness.³ Another potential problem is that the equation itself might change character pointwise in the

³To recover it, further conditions would need to be imposed; see discussions in [35,36].

spacetime. Indeed the character of this equation, i.e., hyperbolic, elliptic, or parabolic, is determined by the eigenvalues of γ^{ab} . Namely, if no eigenvalue is zero, and the sign of only one of them is opposite to the others the equation is hyperbolic⁴ (with + signature it would be one negative). If all signs are the same the equation is elliptic and if at least one eigenvalue is zero parabolic. For a well-defined initial value problem describing a small departure from general relativity, the equation would be hyperbolic. Notice that at the linear level, Eq. (10) is symmetric hyperbolic, linearly degenerate, and the scalar field perturbations propagate at the speed of light of the metric \tilde{g}_{ab} . However, at the nonlinear level—even with smooth initial data—if dispersion does not win and gradients grow (assuming $\partial_{XX} \mathcal{G}_2 \neq 0$) the character of the equation can change and, by continuity, it would do so by turning—locally—to parabolic and then elliptic. Thus either through a change of character, or by loss of uniqueness due to shocks well posedness could be lost.

Interestingly, a change in character in spherically symmetric nonlinear studies in subclasses of Horndeski's theories has been identified, for instance in k -essence [37] and Einstein-Dilaton-Gauss-Bonnet theories [38]. The theories studied in these references are seemingly different from Eq. (7), but they can be linked to a Horndeski theory through the following mappings. In the former case, only the kinetic term $\mathcal{G}_2(X)$ is present, while in the latter we only have $\mathcal{G}_5(\phi, X) = -\lambda \ln |X|$ where λ is the coupling constant.⁵

Notice however that the potential change in character or the development of shocks might be absent in special cases. To assess this, consider the following transformation for the scalar field:

$$\tilde{\phi} = \int \frac{3[\mathcal{G}'_4(\phi)]^2 + (1 + \mathcal{G}_4(\phi))(1 + \partial_X \mathcal{G}_2(\phi, X))}{(1 + \mathcal{G}_4(\phi))^2} d\phi. \tag{12}$$

⁴If more than one is of opposite sign, the equation would be ultrahyperbolic in character.

⁵Although such a function \mathcal{G}_5 is not smooth at $X = 0$, the equations of motion are well defined everywhere [39].

The scalar equation of motion becomes

$$\tilde{g}^{ab}\tilde{\nabla}_a\tilde{\nabla}_b\tilde{\phi} = \frac{1}{(1+\mathcal{G}_4(\phi))^2} \left\{ V'(\phi) - \partial_\phi \mathcal{G}_2(\phi, X) - 2\mathcal{G}'_4(\phi) \frac{V(\phi) - \mathcal{G}_2(\phi, X)}{1+\mathcal{G}_4(\phi)} \right. \\ \left. - \mathcal{G}'_4(\phi) \left[6\mathcal{G}_4''(\phi) - 1 + \partial_X \mathcal{G}_2(\phi, X) - 6 \frac{[\mathcal{G}'_4(\phi)]^2}{1+\mathcal{G}_4(\phi)} \right] \tilde{X} \right\}, \quad (13)$$

where ϕ is to be understood as a function of $\tilde{\phi}$: $\phi(\tilde{\phi})$, provided the relation (12) is invertible. Then, the scalar field $\tilde{\phi}$ obeys a wave equation of the original metric \tilde{g}_{ab} , and no pathologies would arise (unless \tilde{g}^{ab} itself becomes singular). However, the equivalence between the new scalar field and the old one is a nontrivial question, as the transformation (12) may not always be well defined. In particular, the requirement that the newly defined scalar field should verify $\tilde{\nabla}_{[\mu}\tilde{\nabla}_{\nu]}\tilde{\phi} = 0$ further implies that $\tilde{\nabla}_{[\mu}(\tilde{X}\partial_{\nu]}\phi) = 0$, thus $\tilde{X}\partial_a\phi$ is twist free. Such condition could be regarded as an external constraint to ensure well posedness. In the simple example of Sec. III A, we perform a similar redefinition of the scalar field which is always well defined as it does not depend on X . As an illustration, we show in the nonlinear example of Sec. III B how the twist evolves for several representative cases.

Notice that by working in the Einstein frame, we have straightforwardly recovered the conclusions from [27], i.e., *local well posedness* of this class of Horndeski's theories by virtue of the equations of motion for g_{ab} and ϕ being symmetric hyperbolic. The question of global solutions to this theory is, naturally, far more involved which is not unexpected as this is already a complex question in general relativity. Nevertheless, some relevant conclusions can be drawn:

- (i) At the nonlinear level for *weak data*, the equation satisfies Klainerman's *null condition* [40] if \mathcal{G} is at least order X ($\propto \tilde{X}$). Consequently, together with stability of Minkowski results [41] or the weak null energy condition satisfaction by Einstein equations [42], together with contributions of ϕ satisfying Strauss's conjecture [43] would imply the (subclass) of Horndeski's theories considered has a global solution in the small data case. Beyond the weak case, however, little is known; although, as mentioned, the propagation speed dependence on the field and its gradient implies a high likelihood of shocks arising and/or a change in character. Would such issues arise and be "invisible" to far observers? It would depend on whether they generically form *inside* a black hole. In such case, pathological issues might be shielded from problematic consequences at the classical level. *A priori* this seems far from guaranteed; indeed, in the context of Ref. [38], a change in character of the equations is encountered prior to a black hole being formed. We will also illustrate such a behavior in Sec. III B.

- (ii) Since the speed of propagation of (perturbations of) metric tensor and scalar field can be different, black holes are defined by the fastest outward propagation speeds. Additionally, gravitational Cherenkov radiation would be possible and high energy cosmic rays can help to draw constraints on this process (e.g., [44]).

Last, we can also check what we can draw from adopting the harmonic gauge in the Einstein frame and its implication in the Jordan frame. For starters, it is trivial to determine that $\tilde{\Gamma}^a = \Omega^{-2}(\Gamma^a - 2\nabla^a \ln \Omega)$. Thus, in the Jordan frame the harmonic condition from the Einstein frame calls for adopting coordinates that satisfy instead $\Gamma^a = 2\nabla^a \ln \Omega$, which implies

$$\Gamma^a = \frac{\mathcal{G}'_4}{1+\mathcal{G}_4} \nabla^a \phi \quad (14)$$

which is precisely the condition derived in [27] in the Jordan frame to obtain a strongly hyperbolic system of equations and establish local well posedness.

III. ILLUSTRATION IN SPECIFIC CASES

A. Jordan and Einstein frames equations of motion. Hyperbolicity and implications

Within the class of Horndeski's theories, one of the simplest ones is given by

$$S = \frac{1}{16\pi} \int d^4x \sqrt{-g} \left[\phi R - \frac{\omega}{\phi} g^{\alpha\beta} \nabla_\alpha \phi \nabla_\beta \phi \right], \quad (15)$$

where ω is a function of ϕ only. A comparison with Horndeski's Lagrangian implies

$$\mathcal{G}_2 = \frac{(2\omega - \phi)}{\phi} X, \quad \mathcal{G}_4 = \phi - 1;$$

with all the other functions (including the potential) set to zero. From our previous discussion, since $\partial_{XX}\mathcal{G}_2 = 0$, it is clear that in the Einstein frame characteristics of both metric tensor and scalar field are determined by the metric. This theory has recently been the subject of fully nonlinear studies in the context of binary black neutron star mergers [9,45,46]. In such scenarios global solutions describing several orbits, merger, and aftermath have been successfully achieved. This suggests an underlying robustness of

the equations of motion which can be understood at the analytical level rather simply. To fix ideas, let us consider the vacuum case. The field equations derived from the (Jordan frame) action (15) are

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R = \frac{\omega}{\phi^2} \left(\nabla_\mu \phi \nabla_\nu \phi - \frac{1}{2}g_{\mu\nu} \nabla^\alpha \phi \nabla_\alpha \phi \right) + \frac{1}{\phi} (\nabla_\mu \nabla_\nu \phi - g_{\mu\nu} \square \phi), \quad (16)$$

$$\square \phi = -\frac{\phi R}{2\omega} + \left(\frac{1}{2\phi} - \frac{\omega'}{2\omega} \right) (\nabla \phi)^2. \quad (17)$$

Upon replacing the Ricci scalar one reexpresses Eq. (17) as

$$\square \phi = -\frac{\omega'}{3 + 2\omega} (\nabla \phi)^2, \quad (18)$$

which satisfies the null condition in the weak case. However, a nontrivial coupling—at the level of the principal part—is present in Eq. (16). Furthermore, notice the right-hand side of this equation contains second derivatives of the scalar field—thus such terms do belong to the principal part of the system. As well, because of such terms, the right-hand side does not seemingly satisfy the null energy condition. Both these observations indicate it is not *a priori* clear that solutions obtained from this system are well behaved.

However, through the conformal transformation [47],

$$g_{\mu\nu} \rightarrow \tilde{g}_{\mu\nu} = \phi g_{\mu\nu}, \quad (19)$$

and the scalar field redefinition

$$\phi \rightarrow \tilde{\phi} = \int \frac{(3 + 2\omega)^{1/2}}{\phi} d\phi, \quad (20)$$

one recasts the theory in the Einstein frame. In this frame, the theory is defined by the standard Einstein-Hilbert action with an extra field,

$$S = \int d^4x \sqrt{-\tilde{g}} \left[\frac{\tilde{R}}{16\pi} - \frac{1}{2} \tilde{g}^{\mu\nu} \tilde{\nabla}_\mu \tilde{\phi} \tilde{\nabla}_\nu \tilde{\phi} \right]. \quad (21)$$

The field equations are the usual Einstein equations with the scalar field as a source together with a rather trivial equation for the scalar field itself,

$$\tilde{R}_{\mu\nu} - \frac{1}{2} \tilde{g}_{\mu\nu} \tilde{R} = 8\pi \left(\tilde{\nabla}_\mu \tilde{\phi} \tilde{\nabla}_\nu \tilde{\phi} - \frac{1}{2} \tilde{g}_{\mu\nu} \tilde{\nabla}^\alpha \tilde{\phi} \tilde{\nabla}_\alpha \tilde{\phi} \right), \quad (22)$$

$$\tilde{\square} \tilde{\phi} = 0. \quad (23)$$

The equation for the (conformal) metric \tilde{g}_{ab} is amenable to the standard analysis of well posedness in Einstein

equations (e.g., [34]). In particular, adopting *harmonic coordinates* ($\tilde{\Gamma}_a = 0$) the principal part of Eq. (21) becomes just ten wave equations. Further, the right-hand side now obeys the null energy condition. Thus, in the Einstein frame it follows that at least a local in time solution will exist and standard geometrical arguments can be exploited to assess general features of the spacetime behavior.

What does this imply in the Jordan frame? Here, since, $\tilde{\Gamma}_a = \phi^{-2}(\phi \Gamma_a - \nabla_a \phi)$, the discussion above suggests adopting coordinates satisfying $\Gamma_a = \phi^{-1} \nabla_a \phi$. With this choice, the equations of motion in the Jordan frame can be reexpressed in the following way. Beginning with

$$R_{ab} = \frac{\omega}{\phi^2} \nabla_a \phi \nabla_b \phi + \frac{1}{2\phi} g_{ab} \square \phi + \frac{1}{\phi} \nabla_a \nabla_b \phi, \quad (24)$$

we then define $\hat{R}_{ab} + \nabla_{(a} \Gamma_{b)} \equiv R_{ab}$ (i.e., taking out the covariant derivative of the trace of the Christoffels). Now, replacing in such a term the condition on the coordinates, we obtain

$$\hat{R}_{ab} = \frac{\omega + 1}{\phi^2} \nabla_a \phi \nabla_b \phi + \frac{1}{2} g_{ab} \phi^{-1} \square \phi. \quad (25)$$

A priori we still have second order derivatives in the right-hand side of the above equation, but—on shell—we can use the equation for the field ϕ still. Recall,

$$\square \phi = -\frac{\omega'}{(3 + 2\omega)} (\nabla \phi)^2. \quad (26)$$

Thus, the metric equation results in

$$\hat{R}_{ab} = \frac{(1 + \omega)}{\phi^2} \nabla_a \phi \nabla_b \phi - \frac{\omega'}{2\phi(3 + 2\omega)} g_{ab} (\nabla \phi)^2. \quad (27)$$

And it is evident the right-hand side can satisfy the null energy condition for $w \geq 1$.

B. Exploring the nonlinear behavior.

Case with $\partial_{XX} \mathcal{G}_2 \neq 0$

We now turn our attention to Horndeski's theories with a nonlinear kinetic term $\mathcal{G}_2(\phi, X) = -gX^2$, with all other functions, as well as the potential, set to zero for simplicity. This choice, similar to those adopted in [37], can be thought of as the first nonlinear term in a Taylor expansion of the kinetic term in a *k*-essence theory,

$$S = \int d^4x \sqrt{-g} [R + X - gX^2]. \quad (28)$$

Our goal is to study the nonlinear behavior of the theory and explore the possible phenomenology that can arise. While we are restricting our discussion to a rather special case, as we shall see, a number of possible pitfalls can

appear which are likely to manifest in more general cases. To simplify the treatment and presentation, we concentrate on spherically symmetric scenarios and present several cases defined by different initial conditions as well as the value of the coupling g . For simplicity we adopt Schwarzschild coordinates where the metric can be written as

$$ds^2 = -\alpha^2 dt^2 + a^2 dr^2 + r^2 d\Omega^2. \quad (29)$$

Thus the only dynamical metric functions are the lapse function $\alpha(t, r)$ and $a(t, r)$. Recall that these coordinates become singular when a horizon forms. Such scenario takes place when $l^\mu \nabla_\mu r = 0$, where l^μ is a null vector [37]. In the gauge (29), this is simply $\alpha = 0$. Consequently, with our current implementation we can explore up to black hole formation. Despite this limitation, as we shall see below, one can identify several problematic scenarios arising either outside the black hole or even prior to its formation. Thus, severe restrictions to well posedness arise which are not cloaked by a horizon for asymptotic observers.

To simplify the discussion and the numerical implementation, we introduce standard first order variables as used in [48],

$$\Phi \equiv \phi', \quad \Pi \equiv \frac{a}{\alpha} \dot{\phi}, \quad (30)$$

using the notation $\dot{f} = \partial_t f$ and $f' = \partial_r f$. In the special case of $\mathcal{G}_2(\phi, X) = \mathcal{G}_2(X)$, as in (28), Eqs. (9) and (10), respectively, take the form

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = \left[\frac{X + \mathcal{G}_2(X)}{2} \right] g_{\mu\nu} + \left[\frac{1 + \partial_X \mathcal{G}_2(X)}{2} \right] \nabla_\mu \phi \nabla_\nu \phi, \quad (31)$$

$$\left[g^{\mu\nu} - \frac{\partial_{XX}^2 \mathcal{G}_2(X)}{1 + \partial_X \mathcal{G}_2(X)} \nabla^\mu \phi \nabla^\nu \phi \right] \nabla_\mu \nabla_\nu \phi = 0 \quad (32)$$

where the effective inverse metric $\gamma^{\mu\nu}$, as in Eq. (11), is given by

$$\gamma^{\mu\nu} = g^{\mu\nu} - \frac{\partial_{XX}^2 \mathcal{G}_2(X)}{1 + \partial_X \mathcal{G}_2(X)} \nabla^\mu \phi \nabla^\nu \phi. \quad (33)$$

Now, in order to monitor the character of the equation of motion for the scalar field (32), the eigenvalues of the effective inverse metric must be computed. In particular we extract at any given time the two eigenvalues, here labeled as λ_\pm for every spatial point. Since we are mainly interested in one of the eigenvalues going to zero, the relevant quantities will be $\min(\lambda_+)$ and $\max(\lambda_-)$, where $\min(\cdot)$ and $\max(\cdot)$ refer to the minimum and maximum in the spatial (radial) direction, at any given time. It is important

to keep in mind that although $\lambda_+ > 0$ and $\lambda_- < 0$ for $\phi = 0$, this is not necessarily the case for arbitrary configurations. In fact, the equations will change character when these conditions cease to be satisfied. The two eigenvalues can be expressed as

$$\begin{aligned} \lambda_\pm &= \frac{\gamma^{tt} + \gamma^{rr}}{2} \pm \sqrt{\left(\frac{\gamma^{tt} + \gamma^{rr}}{2} \right)^2 - \gamma^{tt} \gamma^{rr} + (\gamma^{tr})^2} \\ &= \frac{\gamma^{tt} + \gamma^{rr}}{2} \pm \sqrt{\left(\frac{\gamma^{tt} + \gamma^{rr}}{2} \right)^2 - \det(\gamma^{\mu\nu})}. \end{aligned} \quad (34)$$

It is evident that the system will become parabolic when $\det(\gamma^{\mu\nu}) = 0$, as expected. Additionally, it is important to keep track of the characteristic speeds, or propagation velocities, of the scalar field. This can be done by extracting the eigenvalues, here labeled as V_\pm , of the principal part of the (first order) equations of motion for Φ and Π . These eigenvalues determine the shape of the light cones for the scalar field, and can be used to identify features such as sound horizons (horizons for the scalar field [37]). With our conventions, asymptotically $V_+ \rightarrow 1$ while $V_- \rightarrow -1$ describing, respectively, the incoming and outgoing modes of the field. A sound horizon—with respect to asymptotic observers—will appear⁶ when $V_- = 0$, $V_+ \geq 0$. Again, as in the case of the effective metric, we are interested in $\min(V_+)$ and $\max(V_-)$,

$$V_\pm = -\frac{\gamma^{tr}}{\gamma^{tt}} \pm \sqrt{\left(\frac{\gamma^{tr}}{\gamma^{tt}} \right)^2 - \frac{\gamma^{rr}}{\gamma^{tt}}} = -\frac{\gamma^{tr}}{\gamma^{tt}} \pm \sqrt{-\frac{\det(\gamma^{\mu\nu})}{(\gamma^{tt})^2}}. \quad (35)$$

As mentioned, when $\det(\gamma^{\mu\nu}) = 0$ the equation changes character. However, the rate at which $(\gamma^{tt})^2 \rightarrow 0$ distinguishes two important cases with respect of the *type* of change. Recall that mixed character equations can often be classified in comparison to two standard equations [49]. These are the Tricomi equation

$$\partial_y^2 u(x, y) + y \partial_x^2 u(x, y) = 0, \quad (36)$$

where the characteristic speeds, $\pm y^{1/2}$, go to zero at the character transition line $y = 0$, and the Keldysh equation

$$\partial_y^2 u(x, y) + \frac{1}{y} \partial_x^2 u(x, y) = 0, \quad (37)$$

where the speed $\pm y^{-1/2}$ diverges at the transition line.

Notice that the discriminant between the two characteristic speeds (35) turns out to be proportional to $-\det(\gamma^{\mu\nu})$.

⁶Naturally the opposite condition still defines a local sound horizon, cloaking some local region from being reached by scalar field perturbations.

Therefore, as long as $(\gamma^{tt})^2 \rightarrow 0$ slower than $\det(\gamma^{\mu\nu}) \rightarrow 0$, the characteristic speeds V_+, V_- will coincide and the scalar field light cone becomes degenerate. Thus, there must exist some instant of time, before the system becomes—at least locally—parabolic, when either V_+ or V_- is zero (the latter case implying a sound horizon) indicative of a Tricomi-type transition. On the other hand, if $(\gamma^{tt})^2 \rightarrow 0$ faster than $\det(\gamma^{\mu\nu}) \rightarrow 0$ the characteristic speeds diverge indicating a transition of Keldysh type. This case is more delicate to tract numerically as the diverging speeds imply the time step should be adjusted to decrease inversely with the maximum speed with an explicit integration algorithm. (Note: an implicit update could be implemented to bypass this issue, but at the expense of missing physics taking place at smaller scales than the time step adopted.)

Interestingly, in [49], only a Tricomi-type behavior is observed. Anticipating our results, we observe both cases depending on the value of the coupling g : Tricomi-like for $g < 0$ and Keldysh-type transitions $g > 0$. The well posedness of Tricomi equation has been explored in [50,51] and, as discussed in [49] the initial/boundary conditions to ensure well posedness would be rather unnatural from a time-development point of view.

1. Implementation details

In the first order variables (30) we can extract from the rr and tt components of Eq. (31), respectively, the first order constraint equations

$$\alpha' = \frac{\alpha}{8r} [4(a^2 - 1) + r^2(\Phi^2 + \Pi^2)] - g \frac{r\alpha}{16a^2} [(\Phi^2 + \Pi^2)^2 - 4\Phi^4], \quad (38)$$

$$a' = \frac{a}{8r} [4(1 - a^2) + r^2(\Phi^2 + \Pi^2)] + g \frac{r}{16a} [(\Phi^2 + \Pi^2)^2 - 4\Pi^4]. \quad (39)$$

Equation (32), in terms of the first order variables, is given by

$$\begin{aligned} \dot{\Pi} = & \frac{1}{r^2} \left(r^2 \frac{\alpha}{a} \Phi \right)' + \frac{2g}{a^2 + g(\Phi^2 - 3\Pi^2)} \frac{\alpha}{a} \\ & \times \left[(\Phi^2 + \Pi^2)\Phi' - 2\Phi\Pi\Pi' \right. \\ & + \left(\frac{r}{4}\Pi^2 - \frac{a'}{a} \right) (\Phi^2 - \Pi^2)\Phi \\ & \left. + \frac{gr}{4a^2} (\Phi^2 - \Pi^2)^2\Phi\Pi^2 + \frac{2}{r}\Phi\Pi^2 \right], \end{aligned} \quad (40)$$

together with the condition that $\partial_t \partial_r \phi = \partial_r \partial_t \phi$, namely

$$\dot{\Phi} = \left(\frac{\alpha}{a} \Pi \right)'. \quad (41)$$

The effective inverse metric from Eq. (33) reads

$$\begin{aligned} \gamma^{tt} &= -\frac{1}{\alpha^2} \left(1 - g \frac{2\Pi^2}{a^2 + g(\Phi^2 - \Pi^2)} \right), \\ \gamma^{rr} &= \frac{1}{a^2} \left(1 + g \frac{2\Phi^2}{a^2 + g(\Phi^2 - \Pi^2)} \right), \end{aligned} \quad (42)$$

$$\gamma^{tr} = -g \frac{2\Pi\Phi}{a\alpha(a^2 + g(\Phi^2 - \Pi^2))}, \quad (43)$$

and the matrix defining the principal part of Eqs. (40) and (41) is

$$\begin{aligned} M &= \begin{pmatrix} 0 & \frac{\alpha}{a} \\ -\frac{a\gamma^{rr}}{\alpha\gamma^{tt}} & -2\frac{\gamma^{tr}}{\gamma^{tt}} \end{pmatrix} \\ &= \frac{\alpha}{a} \begin{pmatrix} 0 & 1 \\ 1 + 2g \frac{\Phi^2 + \Pi^2}{a^2 + g(\Phi^2 - 3\Pi^2)} & -4g \frac{\Pi\Phi}{a^2 + g(\Phi^2 - 3\Pi^2)} \end{pmatrix}. \end{aligned} \quad (44)$$

The equations of motion are solved in a constrained evolution scheme. Both $\alpha(t, r)$ and $a(t, r)$ are obtained through a spatial integration while the scalar field is integrated in time through a Runge Kutta fourth order time integrator. At each time step (intermediate or full), given a spatial profile for the fields Φ and Π , the constraint Eqs. (38) and (39) are integrated in space using also a Runge-Kutta fourth order method (RK4). First, a is integrated radially outwards from $r = 0$ to $r = r_{\max}$ with the initial condition $a(r = 0) = 1$. This condition ensures regularity at $(\alpha' = a' = 0)$ at the origin. Then, α is integrated radially inwards with the condition $\alpha(r_{\max}) = 1/a(r_{\max})$. Notice that, as these integrations are carried out, the fields Φ and Π which are needed at “virtual radial points” in between grid points are obtained through fourth order (second order near the spatial boundaries) spatial interpolations at any given time step.

Evolution of Φ and Π forward in time is carried out via the method of lines with a RK4 integration using Eqs. (40) and (41). Spatial derivatives are computed with second order (first order near the boundaries) finite-difference operators satisfying summation by parts. Regularity at the origin is addressed by using l'Hôpital's rule at $r = 0$ to regularize the equation, and we defined totally outgoing boundary conditions at the outer radial boundary. A small amount of fourth order (second order near the boundaries) artificial dissipation is added for convenience as described. For further details see [52–54].

The numerical results displayed in this paper are performed in a spatial domain ranging from $r = 0$ to $r = r_{\max} = 100$, and a spatial resolution of $\Delta r = 1/80$ (though convergence and consistency of the solutions obtained is checked with resolutions of $\Delta r = 1/20$ and $\Delta r = 1/40$). The Courant number is initially taken to

be $C = 1/10$, and therefore $\Delta t = C\Delta r = 1/800$. Numerical output is produced every 40 time steps. For cases displaying very fast changes, or a high speed of propagation of the scalar field, we switch to a Courant parameter of $C = 1/100$ ($\Delta t = 1/8000$) in the last part of the simulation, and we produce output of the solution every 4 time steps. For reference, the times when these refinements are initiated are listed in the Appendix.

2. Initial conditions and coupling parameters

As mentioned, our goal is to explore the possible phenomenology that can arise in this theory. We have performed extensive studies to try and isolate different scenarios and, for concreteness in our presentation, we present three representative cases for positive and negative coupling values. In particular, we adopt initial data for the (first order variables of the) scalar field given by

$$\begin{aligned}\Phi(t=0, r) &= A \exp\left(-\frac{(r-r_0)^2}{\sigma^2}\right) \cos\left(\frac{\pi}{10}r\right), \\ \Pi(t=0, r) &= 0,\end{aligned}\quad (45)$$

with $r_0 = 55$. The three cases, labeled A, B, and C, are defined by the following parameters:

- (i) Case A: $A = 0.02$, $\sigma = 15.0$.
- (ii) Case B: $A = 0.14$, $\sigma = 1.5$.
- (iii) Case C: $A = 0.045$, $\sigma = 15.0$.

For each of these parameter sets, we have obtained solutions for $g = +1$ (labeled A+, B+ and C+) and for $g = -1$ (A-, B- and C-). Naturally, the scale over which a nontrivial physical behavior occurs depends on (i) the initial location and amplitude of the pulse—as it travels

towards the origin in spherical symmetry, his associated energy density naturally grows—and (ii) the strength of the coupling parameter g .

C. Negative coupling constant: $g = -1$

Setting $g = -1$, we observe three different outcomes depending on the initial conditions of the wave pulse as illustrated in Fig. 1. If the data is weak enough, case A-, the ingoing pulse reaches the origin, bounces off it, and disperses as it propagates to infinity. For configuration B-, the eigenvalue λ_+ of the effective inverse metric crosses zero at $t \approx 56.63$, $r \approx 1.75$ while the lapse remains bounded from below by $\alpha \approx 0.62$. This indicates the system has become parabolic before a light horizon forms. Further, as predicted by Eq. (35), the characteristic speeds of the scalar field merge together as $\lambda_+ \rightarrow 0$ and acquire an imaginary part after that. Before the transition point, the eigenvalue V_- crosses zero at $t \approx 56.52$, $r \approx 1.90$, and therefore a sound horizon is indeed produced. However, since the lapse function α is positive everywhere, there is no light horizon and perturbations of the metric tensor can still propagate through the sound horizon, thus the transition point is not disconnected from outside observers. This is not the only possible outcome for strong enough initial data, as in configuration C- a light horizon does form, together with a sound horizon at $r \approx 6.5$, without any change in character of the scalar field equation. In Fig. 1 C-, the final state at and outside this region is described by a black hole with an outwards propagating field. As mentioned, we cannot comment on what takes place inside the horizon. Interestingly, case B- displays characteristic speeds going to zero before going imaginary where the equation changes

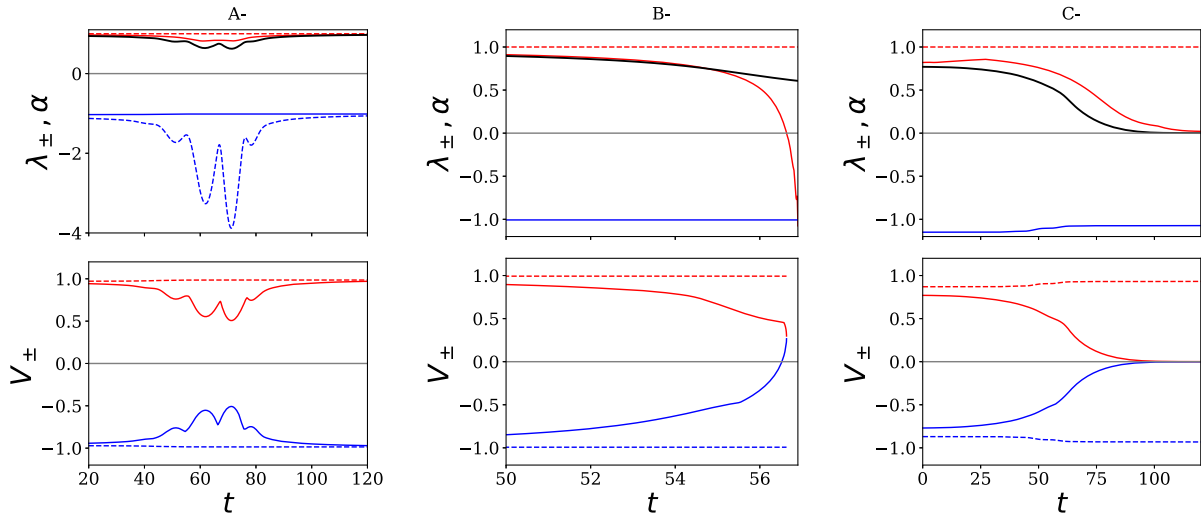


FIG. 1. Eigenvalues for $g = -1$, in cases A- (left), B- (center), and C- (right). The upper three plots show the (max/min) of eigenvalues λ_{\pm} of the effective inverse metric $\gamma^{\mu\nu}$ and the minimum of α . The lower three plots show the eigenvalues V_{\pm} of the principal part of the scalar field equations, corresponding to the characteristic speeds of propagation of the scalar. In each plot, the upper red curves correspond to the spatial maximum (red dashed) and minimum (red solid) values of the λ_+ and V_+ , while the lower blue curves depict the spatial maximum (blue solid) and minimum (blue dashed) of λ_- and V_- . The thick black solid line is the lapse function α , used to identify the formation of a black hole. A gray line at 0 is added as a guide to the eye.

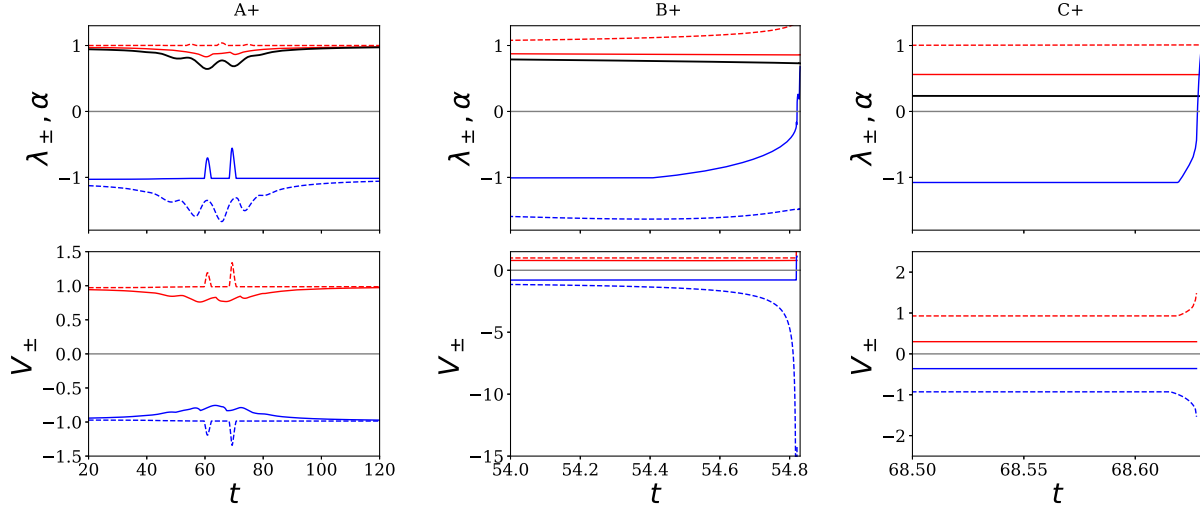


FIG. 2. Eigenvalues for $g = +1$, in cases A+ (left), B+ (center) and C+ (right). The upper three plots show the (max/min of) eigenvalues λ_{\pm} of the effective inverse metric $\gamma^{\mu\nu}$ and the minimum of α . The lower three plots show the eigenvalues V_{\pm} of the principal part of the scalar field equations, corresponding to the characteristic speeds of propagation of the scalar. In each plot, the upper red curves correspond to the spatial maximum (red dashed) and minimum (red solid) values of the λ_{+} and V_{+} , while the lower blue curves depict the spatial maximum (blue solid) and minimum (blue dashed) of λ_{-} and V_{-} . The thick black solid line is the lapse function α , used to identify the formation of a black hole. A gray line at 0 is added as a guide to the eye.

character to parabolic. This, as discussed in [49], is an indication that the equation is of Tricomi type.

D. Positive coupling constant: $g = +1$

For $g = +1$, delicate features in the solution for the same initial conditions developed in a more marked way and, arguably, more violently. The obtained behavior is illustrated in Fig. 2. Naturally, there is not much qualitative difference in A+ configuration. This is to be expected since for weak enough data, the impact of the scalar field is considerably suppressed. In cases B+ and C+, however, λ_{-} crosses zero and the system becomes parabolic in a rather sharp, abrupt way. The transition occurs at $t \approx 54.82$, $r \approx 1.70$ for case B+, and at $t \approx 68.63$, $r \approx 0$ for case C+.

In contrast to the previous case, cases B+, C+ display fastly growing characteristic speeds right before becoming imaginary where the equation changes character to parabolic. This, as discussed in [49], is an indication that the

equation is of Keldysh type. Moreover, this implies these regimes have a natural causal horizon significantly larger than that of light (e.g., [55]). Nevertheless, the change of character in the equation signals well-behaved solutions can only be obtained within a finite range of time. Furthermore, this change of character—for both values of coupling—takes place *prior to a shock being formed*.

Finally, we illustrate the behavior of the (only nontrivial) component, τ_{tr} , of the twist

$$\tau_{\mu\nu} = \nabla_{[\mu}(X\partial_{\nu]}\phi) \quad (46)$$

in Figs. 3 and 4 for the negative and positive couplings adopted. As is evident in the figures, in the weak cases (A−, A+), the twist remains bounded and relatively small throughout the evolution. In contrast, in all but the C− cases the twist grows without bound. In case C−, however, the twist remains bounded since the large value of a at the horizon causes $X = a^{-2}(\Pi^2 - \Phi^2)/2$ to approach zero.

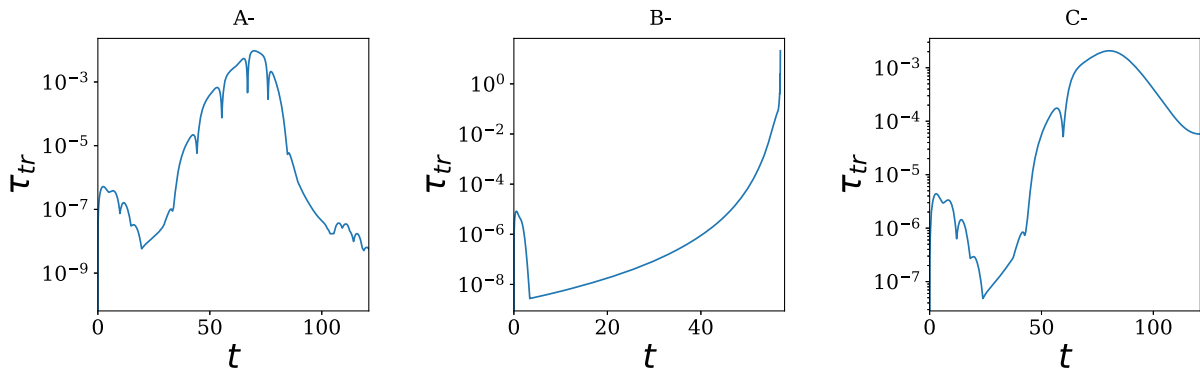
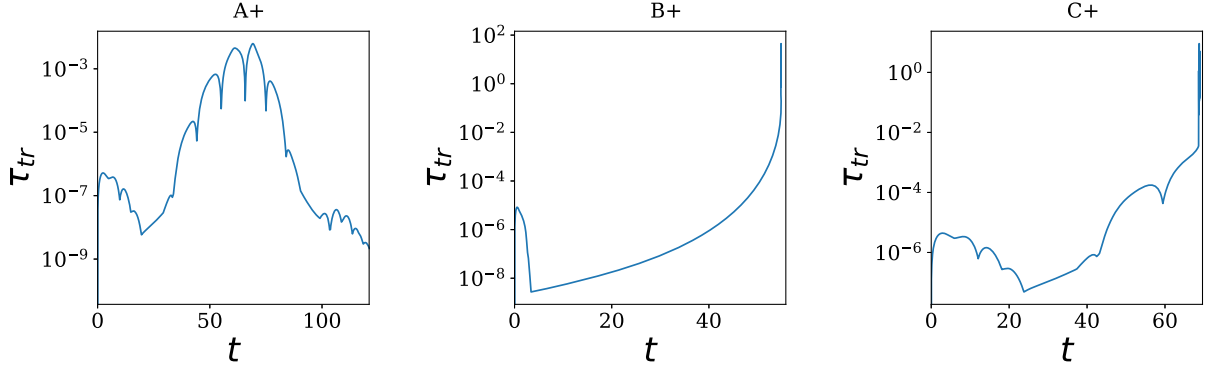


FIG. 3. $\text{Max}|\tau_{tr}|$ for cases A− (left), B− (center), and C− (right).

FIG. 4. $\text{Max}|\tau_{tr}|$ for cases A+ (left), B+ (center), and C+ (right).

IV. FINAL COMMENTS

In this work we explored the subset of Horndeski's theories identified as being able to define locally well posed problems. The analysis we build upon, described in [27,28], relied on identifying and exploiting a specific gauge. Such a choice might *a priori* be regarded as restrictive; however, when seen from the Einstein frame point of view, it can be argued as being quite natural. Further, note the discussion—and problems identified that can arise—for the dynamics of the scalar field holds regardless of the gauge chosen to consider the evolution for the metric sector. In particular, one can argue for the existence of global well-behaved solutions in the weak data case. Beyond this regime, however, the truly nonlinear character of the equations can induce phenomenology which present serious roadblocks. Avoiding such issues requires satisfying a twist-free condition, but such a case might be too restrictive depending on the application and context of interest. In the general case, the strong possibility of a change in character of the equation—from hyperbolic to elliptic through a parabolic stage—as well as the loss of uniqueness through the appearance of shocks further question the ability to define well-posed problems with these theories. (In simplified settings, similar deficiencies have been identified [32,56,57]). We mention in passing that since the effective metric depends on the gradient of the scalar field, the transition to parabolic/elliptic regimes is likely to take prior to the formation of shocks in generic situations (also highlighted in [38]). Hence, considering Horndeski's theories as the leading order in a gradient expansion, problems might arise still within the *a priori* assumed regime of applicability. The timescale for the identified pathologies to arise depends, naturally, on the coupling value considered and the initial data adopted. Due to these difficulties, the extent to which global solutions obtained within the linearized regime and the information one can draw from them with respect to the original action can be regarded as suspect.

This observation, which is arguably in tension with interesting observations drawn at linearized levels in the cosmological context, perhaps calls for a different

philosophy with respect to Horndeski's theories. For instance, to use the linearized equations of motion as a starting point to build a new one free of the (many) problems identified at the nonlinear level through the addition of further suitable operators (for a related discussion, see [58]). However, it might come at the expense of higher derivatives being introduced. A complementary or alternative approach would be to identify the set of behaviors which can be considered physical and, armed with a suitable justification, modify the nonlinear equations of motion to control unphysical pathologies (e.g., [36,59]).

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APPENDIX: NUMERICAL DETAILS

In order to have a better time resolution in the last stages of the simulations, the Courant parameter is reduced from 1/10 to 1/100, and the output is produced every 4 time steps. The instants of time where this happens are listed in Table I.

TABLE I. Instants in time where resolution is increased.

Parameter set	A−	B−	C−	A+	B+	C+
Refinement time	Never	$t = 56.5$	Never	Never	$t = 54.0$	$t = 68.0$

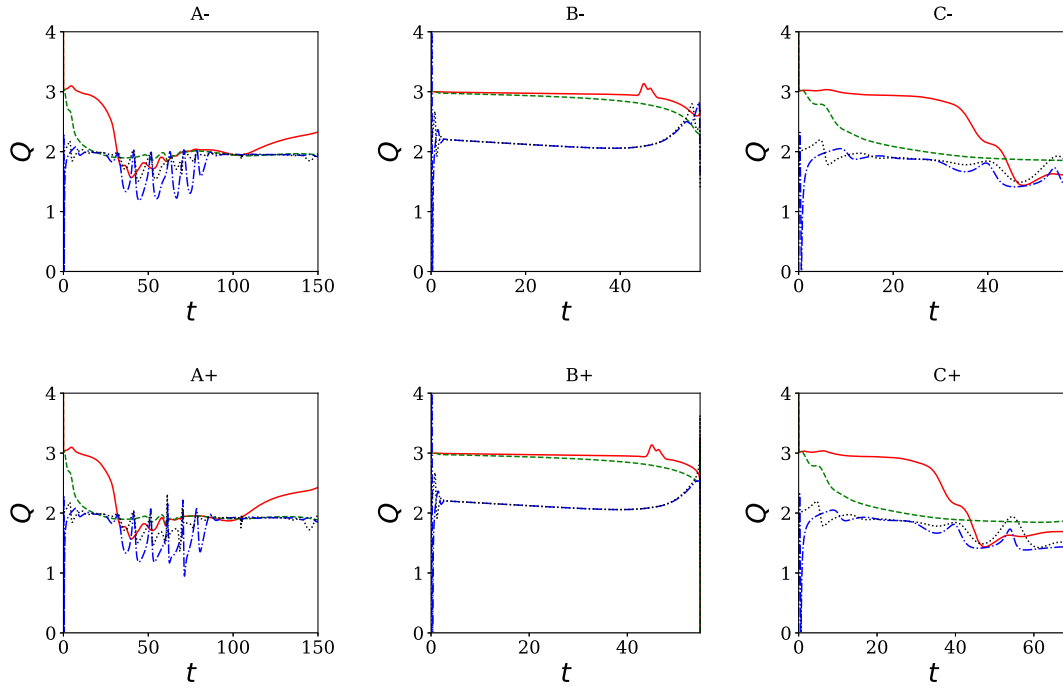


FIG. 5. Order of convergence Q for the four grid functions α (red solid), a (green dashed), Φ (blue, dash-dotted), and Π (black dotted).

Further, we compute the order of convergence of solutions Q as

$$2^Q = \frac{|S_{\Delta/2} - S_{\Delta}|}{|S_{\Delta/4} - S_{\Delta/2}|}. \quad (\text{A1})$$

In Fig. 5 the order of convergence is shown as a function of time for the four grid functions, indicating convergence with the expected rate.

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