

## MARMIT: A multilayer radiative transfer model of soil reflectance to estimate surface soil moisture content in the solar domain (400–2500 nm)

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### **Highlights:**

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- A multilayer radiative transfer model of soil reflectance as a function of surface water content is . developed
- A new method of SMC retrieval is developed
- SMC retrieval combines good accuracy and efficiency after a soil classification •
- The new method is compared to other SMC retrieval methods
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#### 35 Abstract

Surface soil moisture content (SMC) is known to impact soil reflectance at all wavelengths of the 36 37 solar spectrum. As a consequence, many semi-empirical methods aim at inferring SMC from soil reflectance, but very few rely on physically-based models. This article presents a multilayer radiative 38 transfer model of soil reflectance called MARMIT (multilayer radiative transfer model of soil 39 40 reflectance) as a function of SMC given on a mass basis and a method called MARMITforSMC to estimate it from soil reflectance spectra. This model depicts a wet soil as a dry soil covered with a thin 41 42 film of water. It is used to assess SMC over seven independent laboratory datasets gathered from the 43 literature. A learning phase is required to link the thickness of the water film with the SMC. For that 44 purpose, a sigmoid function, the parameters of which are related to soil physical and chemical properties such as porosity, grain size and mineralogy composition, is fitted. SMC can be inferred 45 with good accuracy (RMSE  $\approx$  3%) if the learning step is applied soil by soil. The link between SMC 46

and water thickness actually depends on soil texture and chemical composition. If the soils are divided
into classes and if the learning phase is applied to a class, the RMSE slightly increases up to 5%.
Finally, MARMITforSMC provides lower RMSE than any other existing semi-empirical or
physically-based method.

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### 52 1. Introduction

53 Soil water content (or soil moisture content, SMC) assessment is critical in agriculture, hydrology, micrometeorology, defense, civil engineering, and other environmental fields (e.g., Gardner, 2000; 54 Robinson et al., 2008; Vereecken et al., 2008; Wang and Qu, 2009; Ochsner et al., 2013). In 55 56 agriculture, SMC is an indicator of soil sensitivity to wind erosion; it also provides information about water infiltration, runoff and storage that helps monitor soil-water-plant conditions and manage 57 irrigation (Glenn et al., 2009; Yang et al., 2012). Therefore, it is highly correlated with crop yield 58 estimation. In hydrology and meteorology, SMC plays an important role in flood prevention 59 (Haubrock et al., 2008), incident radiation distribution and, indirectly, temperature and evaporation 60 (Khanna et al., 2007: Patel et al., 2009): thus it contributes to mass conservation and energy balance 61 calculation. In defense or homeland security, trafficability depends on surface characteristics 62 including SMC and can be key in succeeding military or humanitarian operations. Vehicle traffic is 63 easier on dry clay paths and, conversely, on wet sand paths. SMC is also increasingly examined in 64 planetary sciences: for instance, the reflectance of some Martian surfaces in the near-infrared presents 65 66 strong absorption features attributed to the presence of water in the regolith or in the minerals that compose it (e.g., Milliken and Mustard, 2005, 2007a,b; Pommerol et al., 2009, 2013). Last but not 67 least, water alters the background reflectance of a bare soil and the apparent mineral absorption depths 68 69 in the spectrum, therefore it affects classification accuracy. Determining soil moisture content from 70 reflectance measurements may be useful to quantify other information of interest such as mineralogy, salinity, texture, organic matter content or roughness (e.g., Ben Dor et al., 2002; Whiting, 2004; 71 Bogrekci and Lee, 2006; Minasny et al., 2011; Rienzi et al., 2014; Rodionov et al., 2014; Zu et al., 72 73 2016; Marion and Carrère, 2018).

There are three main types of soil water: (1) hydration (absorbed) water incorporated into the lattice of minerals; (2) hygroscopic (adsorbed) water bound to soil particles, including soil organic matter, due to the attraction between surface electrical charges and water molecules; (3) free water covering the minerals, occupying the pores and moving through the soil by gravity and capillary forces.

79 Soil water content generally refers to mass or volumetric water content, both expressed as a 80 fraction. As stated by Stafford (1988) or Petropoulos et al. (2013), there is no conventional method to determine SMC. It is measured either in the laboratory with gravimetric and thermogravimetric 81 82 methods or in the field using, for example, portable neutron probes, time domain reflectometry (TDR) or capacitance probes. Such measurements are reliable, but their footprint is limited to a few square 83 84 meters at most. Moreover, soil water content abruptly varies both in space and time due to the spatial variability of soil physical properties and to the discontinuous nature of rainfall. All these methods 85 may be expensive and laborious to implement, especially at a fine spatial sampling interval, when a 86 87 large number of measurements are required.

Remote sensing can provide data at different spatial resolutions at reasonable costs. Moreover, it is 88 a non-destructive and non-invasive method. Most researches have focused on the measurement of the 89 backscattering coefficient and the brightness temperature in the microwave domain (Njoku and 90 Entekhabi, 1996; Das et al., 2008; Mladenova et al., 2014) that allow determining the volumetric 91 92 water content in the first centimeters, especially at lower frequencies (Tabatabaeenejad et al., 2015). But it often requires extra information about the soil dielectric constant or the surface roughness. In 93 94 the solar domain (400-2500 nm), light penetration in soil varies from a few micrometers to a few 95 millimeters depending on the wavelength and the soil type. Remote sensing offers the possibility to determine moisture of the topmost layer of the soil with much higher spatial resolution (Sadeghi et al., 96 2017) and may be an indicator of moisture below in some unique profiles. 97

98 Water spectroscopy is well known but still complex: the main absorption features of liquid water 99 occurring in the infrared result from vibrational transitions involving various overtones and 100 combinations of three fundamental vibrational transitions at 2870 nm (asymmetric O–H stretching), 101 3050 nm (symmetric O-H stretching), and 6080 nm (O-H bending). In the shortwave infrared, two 102 major water absorption peaks centered at 1470 nm and 1900 nm, and two minor absorption peaks 103 centered at 970 nm and 1200 nm, are observed. Smaller peaks and shoulders can be found in the 104 visible-near infrared at 514 nm, 606 nm, 660 nm, 739 nm, and 836 nm (Eisenberg and Kauzmann, 2005; Wozniak and Dera, 2007). The dominant effect of water on soil optical properties is an overall 105 106 decrease in spectral reflectance with increasing soil moisture. Idso et al. (1975) provided empirical 107 evidence that soil albedo decreased linearly with soil moisture, but subsequent studies have 108 challenged this view (Bowers and Hanks, 1965; Bedidi et al., 1992; Muller and Décamps, 2001). 109 Indeed, as is common in optics, nonlinear phenomena induce more pronounced absorption features in 110 the absorption bands of water than any others. For high SMC, soil reflectance may even increase with moisture due to specular reflection (Neema et al., 1987; Liu et al., 2002). That critical point, which 111 112 seems to correspond to the field capacity, strongly depends on soil type (Liu et al., 2002). Soil 113 reflectance is controlled by many other factors such as texture, mineralogy, organic matter, and 114 surface roughness (e.g., Clark and Roush, 1984; Baumgardner et al., 1985; Okin and Painter, 2004; 115 Stenberg et al., 2010; Ben-Dor, 2011).

116 Numerous experiments have measured soil reflectance variation as a function of soil moisture in the visible (VIS, 0.4-0.7 µm), in the near-infrared (NIR, 0.7-1.0 µm), in the shortwave-infrared 117 (SWIR, 1.0-3.0 µm) (e.g., Bowers and Hanks, 1965; Skidmore et al., 1968; Planet, 1970; Idso et al., 118 1975; Twomey et al., 1986; Ishida et al., 1991; Liu et al., 2002; Haubrock et al., 2008), and more 119 120 recently, in the midwave-infrared (MWIR, 3.0-8.0 µm) and longwave-infrared (LWIR, 8.0-12.0 µm) 121 (e.g., Van Bavel et al., 1976; Narayanan et al., 1993; Bishop et al., 1994; Mira et al., 2007; 122 Lesaignoux et al., 2013). Many empirical methods link SMC and reflectance. They include spectral indices (e.g., Levitt et al., 1990; Bryant et al., 2003; Khanna et al., 2007; Haubrock et al., 2008; Gao et 123 124 al., 2013), statistical relationships (e.g., Lesaignoux et al., 2013; Yin et al., 2013), multivariate analysis (Mouazen et al., 2006), wavelet analysis (Peng et al., 2013) and exponential functions 125 126 (Muller and Décamps, 2001; Liu et al., 2002; Lobell and Asner, 2002; Whiting et al., 2004; Kaleita et al., 2005; Sun et al., 2007; Somers et al., 2010; Verpoorter et al., 2014; Zhang et al., 2014). Such 127

methods have been applied to reflectance spectra and their successive derivatives, and to continuumremoved spectra. However, most of them are not universal because they have been calibrated over a limited range of soil types and knowledge of parameters such as soil density or porosity may be required.

132 Very few methods relying on physically-based models have been developed. In the 1920s, 133 Ångström (1925) proposed a simple model where a wet soil is regarded as a dry soil covered with a 134 thin film of liquid water. This model derives the albedo of a wet soil by calculating the multiple 135 reflections between the two media based on Snell's law. Lekner and Dorf (1988) improved the 136 Ångström model by using the Fresnel coefficients instead of Snell's law. Bach and Mauser (1994) 137 introduced the Beer-Lambert-Bouguer law to account for light absorption in the water layer and extended the model to the VIS-SWIR. More recently, Kimmel and Baranoski (2007) published a ray 138 139 tracing model called SPLITS (spectral light transport model for sand) and Sadeghi et al (2015) 140 proposed a model based on the Kubelka-Munk two-flux radiative transfer model. However, SPLITS 141 requires information on the soil that is somewhat difficult to access, high computing resources, and it 142 does not allow retrieving the SMC. As for the Sadeghi model, it only works at some wavelengths, 143 which reduces its field of application (see Section 4.3).

In this article, we improve the Bach model (Bach and Mauser, 1994) which appears to efficiently estimate the surface SMC ( $r^2 = 0.88$ ) but which has not been validated or improved in the literature for the past twenty years. The equations underlying the multilayer radiative transfer model of soil reflectance (MARMIT) are detailed, and the validation datasets are presented. Then, a method to retrieve SMC called MARMITforSMC and based on a logistic function is introduced and compared to other statistical or semi-empirical methods.

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### 151 **2. Model and datasets**

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### **2.1 Description of MARMIT**

MARMIT mimics a wet soil as a dry soil covered with a thin film of water (Fig. 1). Such an 154 approach is naturally a simplified version of reality, as the geometry of water films within soils is 155 156 much more complex (Tuller et al., 1999). A fraction of light is transmitted from the air (medium 1) to 157 the water layer (medium 2) with a transmissivity  $t_{12}$ . Another fraction is reflected to the air. The 158 reflectivity at the interface is  $r_{12} = 1 - t_{12}$ . Then light is diffusely scattered through internal multiple reflections between the liquid-soil interface  $(R_d)$  and the liquid-air interface  $(r_{21})$ . These multiple 159 reflections increase the probability of light absorption by soil particles and explain why a wet soil 160 appears darker than a dry soil. The fraction of light that is not reflected back to the soil is transmitted 161 162 from the water to the air  $(t_{12})$ .

163



Fig. 1. Thin liquid water layer over a rough surface. Medium 1 is air and medium 2 is water.  $r_{ij}$  and  $t_{ij}$  are the reflectivity and transmissivity at the interface between the media *i* and *j*,  $T_w$  is the transmittance of the water layer,  $R_d$  the reflectance of the dry soil.  $n_w$  is the refractive index of water, that of air being assumed to be 1. All these physical quantities are wavelength dependent.

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MARMIT results from a series of improvements of an approach initiated by Ångström (1925), continued by Lekner and Dorf (1988) half a century later, and by Bach and Mauser (1994) a few years later. In the first two papers, water absorption is assumed to be negligible in the VIS-NIR and the total absorptance of a wet soil is calculated as

169

$$A_{wsL} = \frac{t_{12}A_d}{1 - r_{21}R_d} \tag{1}$$

where  $A_d = 1 - R_d$  is the absorptance of the dry soil,  $t_{12}$  the transmissivity at the air-water interface 171 172 and  $r_{21}$  the reflection coefficient at the water-air interface. Both are calculated by the Fresnel equations for unpolarized light.  $t_{12}$  depends on the incidence angle  $\theta_i$  formed between the normal and 173 174 the incident ray and on the relative refractive index n defined as the ratio of the refractive index of pure liquid water  $(n_w)$  to the refractive index of the air  $(n_a = 1)$ :  $n = n_w/n_a = n_w$ . Angström 175 176 (1925) assumes that light exiting the water layer lies within a cone of a given angle while Lekner and Dorf (1988) consider a diffuse light. The latter consequently calculate  $r_{21}$  by integrating the 177 reflectivity over the entire hemisphere (Stern, 1964): 178

$$r_{21} = 1 - \frac{1}{n^2} (1 - r_{12}') \tag{2}$$

180

181 with

$$r_{12}' = \frac{3n^2 + 2n + 1}{3(n+1)^2} - \frac{2n^3(n^2 + 2n - 1)}{(n^2 + 1)^2(n^2 - 1)} + \frac{n^2(n^2 + 1)}{(n^2 - 1)^2}\log n - \frac{n^2(n^2 - 1)^2}{(n^2 + 1)^2}\log \frac{n(n+1)}{n-1}$$
(3)  
183

The hypothesis of a nonabsorbing water layer is invalid in the SWIR. Bach and Mauser (1994) calculate its transmittance  $T_w$  with the Beer-Lambert law:  $T_w = \exp(-\alpha_B L)$  with  $\alpha_B$  the specific absorption coefficient of *in situ* water determined empirically  $[m^{-1}]$  and *L* the thickness of the water layer [m]. Therefore, the reflectance of a wet soil is written in the form

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189

 $R_{wsB} = (1 - A_{wsL})\exp(-2\alpha_B L) \tag{4}$ 

# 190 with $A_{wsL}$ the total absorptance of a wet soil defined in Eq. (1). The factor 2 is because the light ray 191 crosses twice the water layer. Considering that the soil surface may be a patchwork of wet and dry 192 areas, Bach (1995) introduced an efficiency term $\varepsilon$ that accounts for the fraction of wet soil:

193

$$R_{modB} = \varepsilon \times R_{wsB} + (1 - \varepsilon) \times R_d \tag{5}$$

194

195  $\varepsilon = 0$  means that the soil is dry and  $\varepsilon = 1$  that it is covered with a film of water over its whole 196 surface. 197 In MARMIT the transmittance of light through the water layer is taking into account along the path 198 of the ray (Fig. 1). The expression for the total reflectance of the water/soil system can be derived by 199 summing the amplitudes of successive reflections and refractions at the top of the water layer:

200

201

$$R_{ws} = r_{12} + t_{12} T_w^2 R_d t_{21} + t_{12} T_w^4 R_d^2 t_{21} r_{21} + \cdots$$
(6)

202 Eq. (6) can be easily factorized in

203

204

 $R_{ws} = r_{12} + t_{12}t_{21}R_dT_w^2(1 + r_{21}R_dT_w^2 + r_{21}^2R_d^2T_w^4 + \cdots)$ (7)

The expression in brackets is a geometric series of general term  $x = r_{21}R_dT_w^2$  that converges to  $\frac{1}{1-x}$ 206 if |x| < 1. So we obtain

207

$$R_{ws} = r_{12} + \frac{t_{12}t_{21}R_d T_w^2}{1 - r_{21}R_d T_w^2} \tag{8}$$

208

with  $T_w = \exp(-\alpha L)$ ,  $\alpha$  the absorption coefficient of pure liquid water provided by Palmer and Williams (1974). If the soil is dry, the transmission-related parameters  $t_{12}$ ,  $t_{21}$  and  $T_w$  are 1 and the reflections  $r_{12}$  and  $r_{21}$  are 0, then  $R_{ws} = R_d$ . MARMIT also introduces an efficiency term  $\varepsilon$  like in Eq. (5),

- 213
- 214

$$R_{mod} = \varepsilon \times R_{ws} + (1 - \varepsilon) \times R_d \tag{9}$$

In the following, the term  $r_{12}$  is ignored because the diffuse radiation is negligible for our laboratory measurements and none of the measurements described hereafter have been acquired in the specular direction while the water layer is assumed to be flat. In conclusion, MARMIT is physically more consistent than the previous models because the coupling between the multiple reflections and the absorption of light in the water layer is more realistic. The differences between the models presented above are summarized in Table 1.

Author	Lekner and Dorf (1988)	Bach (1995)	MARMIT
Physical variable	absorptance	reflectance	reflectance
Expression	$A_{wsL}$	$R_{wsB}$	$R_{ws}$

Equation	$\frac{t_{12}A_d}{1-r_{21}R_d}$	$(1 - A_{wsL})\exp(-2\alpha_B L)$	$\frac{t_{12}t_{21}R_dT_w^2}{1-r_{21}R_dT_w^2}$
Remark	Summation of the absorptances above the water layer; no light absorption in the water layer	Transmittance of light in the water layer accounted for and multiplied by $1 - A_{wLD}$ ; empirical absorption coefficient of water	Transmittance of light in the water layer directly added in the path of the ray; absorption coefficient of pure liquid water

### 223 **2.2 Datasets**

224 MARMIT was tested on a database gathering six datasets published in the literature, plus a new one generated in the frame of this study (Table 2). They are, in order of publication year, Liu02 (Liu 225 226 et al., 2002, 2003), Lob02 (Lobell and Asner, 2002), Whit04 (Whiting, 2004; Whiting et al., 2004), Les08 (Lesaignoux, 2010; Lesaignoux et al., 2013; Fabre et al., 2015), Mar12 (Marcq, 2012), Phil14 227 (Tian and Philpot, 2015a,b), and Bab16 (this article). They represent a total of 217 soil samples. 228 229 Ideally the number of SMC levels would cover the full range of soil moisture variation and textural 230 information about the soil samples would be available. The incompleteness of the datasets does not 231 allow completely validating MARMIT, analyzing its performance, and explaining the results. For 232 instance, Whit04, Lob02 and Mar12 have many SMC levels but little textural information about the soil samples. The latter is available in Liu02 but there are only four SMC levels. The new Bab16 233 234 dataset includes enough SMC levels with relevant information on soils.

#### 235

Dataset	N	SMC		Drying protocol	Sieving	$\theta_i$	Bulk density
	-	Number of levels	range				
Liu02	92	4	0-83 %	Oven-dried	2 mm	15°	0.98-1.88
Lob02	4	9 to 15	0-118 %	Oven-dried	2 mm	15°	0.64-1.54
Whit04	60	10 to 12	0-45 %	Air-dried	2 mm		0.88-1.36
Les08	32	6	0-87 %	Oven-dried	no	15°	
Mar12	9	25 to 30	0-50 %	Humidification	no	25°	
Phil14	3	97 to 205	0-45 %	Air-dried	2 mm	30°	0.95-1.53
Bab16	17	6 to 8	0-40 %	Oven-dried	2 mm	15°	

**Table 2**. Summary of the main information on the datasets. *N* is the number of soil samples, *SMC* is the soil moisture content,  $\theta_i$  is the angle of the incident light.

236

The soil samples in Whit04 originate from two locations: fifteen come from Tomelloso (Castilla-La Mancha, Spain) and as many from Lemoore (California, USA). Whiting et al. (2004) made two replicates of each soil so that the dataset gathers sixty samples. The soils sampled in Lemoore belong

to three textural soil classes: clay loam, sandy clay loam, and silty clay loam; those sampled in 240 Tomelloso also include three soil classes: loam, sandy loam, and silt loam. Organic matter content is 241 low in both regions (< 2%). Soil mineralogy (CaCO<sub>3</sub> and SiO<sub>2</sub> contents) is provided for four soils 242 243 from Tomelloso and five soils from Lemoore. Whiting et al. (2004) removed the reflectance between 244 760 nm and 950 nm because of detector artifacts in that region. The textural information is available for the 92 soils of Liu02, the 32 soils of Les08, and 10 out of 17 soils of Bab16 (Fig. 2). Lob02 245 includes four soils displaying various mineralogical compositions, amounts of organic matter, and 246 247 porosities. Mar12 includes six different soils collected in the region of Reims (France). Three of them (soils 1, 2 and 4) have one replicate. 248

249



**Fig. 2**. Soil texture triangle showing the 12 major textural classes and particle size scales as defined by the USDA, for 134 soils of three datasets (Liu02, Les08, and Bab16).

250

251 Soil moisture content was most of the time expressed as a weight percent (SMC<sub>g</sub>):

252

$$SMC_g = \frac{M_{ws} - M_{ds}}{M_{ds}} = \frac{M_{H_2O}}{M_{ds}}$$
(10)

253

with  $M_{ws}$  [g] the mass of wet sample,  $M_{ds}$  [g] the mass of dry sample, and  $M_{H_2O}$  [g] the mass of

255 water. Sometimes it was expressed as a volumetric percent (SMC<sub>v</sub>):

$$SMC_{\nu} = \frac{V_{ws} - V_{ds}}{V_{ds}} = \frac{V_{H_2O}}{V_{ds}}$$
(11)

with  $V_{ws}$  [cm<sup>3</sup>] the volume of wet sample (dry soil and water-filled pores),  $V_{ds}$  [cm<sup>3</sup>] the volume of dry sample, and  $V_{H_2O}$  [cm<sup>3</sup>] the volume of water. SMC<sub>g</sub> and SMC<sub>v</sub> are related by the dry bulk density of the sample (Lobell and Asner, 2002):

261

$$SMC_{v} = \frac{V_{H_{2}O}}{V_{ds}} = \frac{M_{H_{2}O} \times d_{ds}}{M_{ds} \times d_{H_{2}O}} = SMC_{g} \times \frac{d_{ds}}{d_{H_{2}O}}$$
(12)

262

with  $d_{H_2O}$  [g.cm<sup>-3</sup>] the density of water (~1) and  $d_{ds}$  [g.cm<sup>-3</sup>] the dry bulk density of the sample. 263 Because densities of the soils were not available for every dataset, SMCg has been used in this study 264 instead of SMC<sub>v</sub>. In the following, if nothing is specified, the SMC will refer to the definition of SMC<sub>g</sub>. 265 The experiments vary somewhat so we refer the reader to the original articles for spectrometer 266 setup and moisture measurement protocol. Most of the data were acquired with an ASD FieldSpec 267 spectroradiometer (Analytical Spectral Devices, Inc.) except for Whit04 where a Cary 5E 268 spectrophotometer (SpectraLab Scientific, Inc.) was used. All the datasets but Mar12 were acquired 269 according to the same protocol: the soil sample is sieved, put into a Petri dish with a radius of about 5 270 cm, moistened up to saturation (except for Liu02 where the saturation stage is exceeded) and then 271 dried. At regular intervals during drying, the soil samples are weighed in order to assess SMC and 272 273 their reflectance spectrum is recorded. Mar12 was obtained in a somewhat different way since the soil 274 samples were not sieved and moistened after drying. Moreover, they were put into pie plates with a 275 radius around 25 cm.

All the datasets associate a reflectance spectrum with a water content value measured concomitantly. Since reflectance varies with the angle of the incident light  $\theta_i$ , precautions will be taken when comparing Mar12 and Phil 14 to the other datasets. Fig. 3 shows the evolution, as a function of water content, of the reflectance of a clay soil, a loamy soil, and a sandy soil picked at the vertices of the texture triangle.



**Fig. 3**. Reflectance spectra and their associated SMC<sub>g</sub> (g/g). (top) Clay soil 724 Lebna57 in Bab16, (middle) loamy soil Luvisol 208Te in Bab16 and (bottom) sandy soil 76 in Liu02.

The clay soil made of very fine particles holds greater amounts of water and has greater porosity than coarser soils, so the SMC at saturation is higher (Fig. 3, top). Conversely, the sandy soil made of large particles has a lower porosity; it rapidly reaches saturation (Fig. 3, bottom). Finally, the SMC of the loamy soil at saturation is in-between (Fig. 3, middle).

288

### 2.3 The MARMITforSMC approach

The method for retrieving soil moisture content with MARMIT called MARMITforSMC involvesthree steps (Fig. 4):

- 291 (1) Inversion step: the water thickness *L* and the efficiency  $\varepsilon$  are estimated by model inversion 292 (Eq. (14)). One can note that the reflectance of the dry soil is needed to infer the reflectance of 293 a wet soil.
- 294 (2) Calibration step: a statistical relationship is established between the mean water thickness 295 (mean light path) defined as  $\varphi = L \times \varepsilon$  and the measured SMC. Here we use  $\varphi$  instead of *L* 296 because, for very small SMC,  $\varepsilon$  changes slowly in comparison to *L* which can vary very 297 quickly.
- (3) Assessment step: SMC is retrieved by applying the relation found in the calibration step andcompared with the measured values.
- 300



Fig. 4. Flowchart representing the overall MARMITforSMC method used in this study.

### 301

### **302 3. Results**

303 The root-mean-square error (RMSE) that measures the difference between the measured and 304 estimated values of SMC was chosen to compare the efficiency of the various regressions and models: 305

$$RMSE = \sqrt{\frac{\sum_{i=1}^{N} (SMC_i^{meas} - SMC_i^{est})^2}{N}}$$
(13)

306

307 where  $SMC_i^{est}$  is the estimated SMC for the soil sample *i*,  $SMC_i^{meas}$  is the measured SMC, and *N* is 308 the number of SMC.

### 310 **3.1 Inversion step**

311 The inversion step is applied to all the samples. Model fitting is achieved by searching the best 312 values of *L* and  $\varepsilon$  that minimize the merit function  $\chi^2$  thanks to the bounded simplex search algorithm, 313 implemented in MATLAB (Nelder and Mead, 1965):

314

$$\chi^{2}(L,\varepsilon) = \sqrt{\frac{\sum_{\lambda_{1}}^{\lambda_{2}}(R_{meas}(\lambda) - R_{mod}(\lambda, L, \varepsilon))^{2}}{n_{\lambda}}}$$
(14)

315

with  $R_{meas}$  the measured reflectance at wavelength  $\lambda$ ,  $R_{mod}$  the modeled reflectance described in Eq. (9) at wavelength  $\lambda$ , and  $n_{\lambda}$  the number of wavelengths. In our case,  $\lambda_1 = 400$  nm and  $\lambda_2 = 2400$  nm. The fit is good for most of the soils ( $r^2 > 0.95$ , Fig. 5, top) but, when SMC is higher than 20%, the reflectance of some soils is overestimated by the model outside the water absorption bands and underestimated within these bands ( $r^2 < 0.90$ , Fig. 5, bottom). This misfit decreases if  $\varepsilon$  is unconstrained but we bounded it between 0 and 1 to keep a physical meaning.





Fig. 5. Measured (solid line) and modeled (dashed line) reflectance spectra of two soils at various levels of soil water content: (top) *30PrairieB* in Les08 with SMC in weight percent ( $g.g^{-1} \times 100$ ) and (bottom) *Entisol* in Lob02 with SMC in volumetric percent ( $cm^3.cm^{-3} \times 100$ ). The retrieved parameters of the model are provided to the right of the curves ( $L, \varepsilon$ ). L is in mm.

324 The RMSE between the measured and the modeled reflectance spectra of all soils of all dataset is 325 generally lower than 2% except at 1900 nm, a major water absorption band (Fig. 6). Philpot (2010) 326 suspects that part of this discrepancy is due to a change in the optical properties of the liquid phase of 327 soil when water, that already contains dissolved organic matter and ions, is mixed with suspended 328 mineral particles. Bach (1995), who empirically derived a specific absorption coefficient of water 329 bound with soil, obtained a better fit with her model in the water absorption band at 1900 nm but applying this coefficient to every kind of soil is difficult to justify so we decided to use the specific 330 331 absorption coefficient of pure liquid water (Fig. 6).





Fig. 6. Root-mean-square error (RMSE) between the soil spectra and two soil reflectance models, calculated for all the datasets.

### 334

### **3.2** Calibration and prediction steps

The calibration step consists in finding a mathematical expression relating the mean water 335 336 thickness ( $\varphi$ ) to the soil moisture content (SMC). It is not possible to determine a unique relationship 337 valid for all soils of all datasets because the points are widely scattered (Fig. 7). The relationship 338 seems to depend on soil characteristics and measurement protocols: as an example the two white quartz sands in Phil14 and Bab16, which are very bright, are distinct from the other soils. One also 339 340 notes that the soil samples of Mar12, which were wetted instead of being dried, display a relationship 341 shifted by about 0.1 mm on the right compared to the other soils. Tian et al. (2015b) mention that 342 water tends to stagnate on the surface of the soil during humidification so that a small amount of water induces a significant change in reflectance. Conversely during drying, water and air are distributed 343 344 throughout the sample for most of the drying period, so that soil reflectance does not change much 345 when the sample is almost dry.

346



**Fig. 7**. Relationship between SMC<sub>g</sub> and  $\varphi$  for all soils of all datasets.

347

348 Because no general relationship could be found, the soils were first studied separately and then 349 gathered into classes based on textural, mineralogical, and spectral properties.

350

### **351 3.2.1 Soil-by-soil calibration and prediction steps**

352 Several models such as polynomials of degree one (Bach and Mauser, 1994; Bach, 1995), two or

353 three, as well as power functions have been tested to adjust the points relating SMC to  $\varphi$ . The S-shape 354 curvatures observed for almost every soil suggest using a logistic function:

355

$$SMC = \frac{K}{1 + ae^{-\psi\varphi}} \tag{15}$$

356

with *K* the maximum value of the curve,  $\psi$  the steepness of the curve, and *a* a translation factor that moves the whole curve along the x-axis. A simple one-factor-at-a-time sensitivity analysis of the logistic function illustrates the effect of each parameter on the curve shape (Fig. 8). An increase in *K* induces an increase in the asymptote of the curve; an increase in *a* shifts the whole curve to the right; an increase in  $\psi$  increases the slope of the curve and shifts the inflexion point towards the smallest values of  $\varphi$ .





**Fig. 8**. Schematic trends of a logistic function. (top) *K* is variable,  $\psi$  and *a* are constant; (middle)  $\psi$  is variable, *K* and *a* are constant; and (bottom) *a* is variable, *K* and  $\psi$  are constant.

Fig. 9 shows that the logistic function explains very well the evolution of the SMC with  $\varphi$  for every soil. The relationship is not constrained:  $\varphi = 0$  does not mean that the soil sample is dry but that there is no detectable water on the soil surface. Moreover a logistic function is strictly positive when the parameters *K*,  $\psi$  and *a* are positives. The function is then called a sigmoid function.





Fig. 9. Calibration step for six soils of six different datasets. Name of the soil in title and dataset in bracket.

Note that when K is at the maximum value of SMC, i.e., saturation, the soil pores are filled with 371 372 water and the volumetric water content is nearly equal to the porosity. Since the volumetric and the gravimetric water contents can be calculated by Eq. (12), K may be related to the porosity of the soil. 373 374 To validate this assumption, we plotted the maximum soil water content, i.e., the water content at 375 saturation (SMCs), as a function of K (Fig. 10). In most cases, there is a correspondence between the 376 two but K sometimes diverges from the bisector because of the limited range of soil moistures available in some datasets. If now we remove the soil samples containing less than six data points 377 (twice the number of parameters in the sigmoid function), these two parameters are almost equivalent. 378





**Fig. 10**. Link between *K* and SMCs (left) for every soil of every dataset and (right) for the soils with more than six moisture content measurements.

381 If the values of  $\varphi$  determined during the inversion step are reinjected into the relationship found 382 between SMC and  $\varphi$ , and if the measured and estimated soil moisture contents are compared, then 383 excellent results are obtained (*RMSE* < 3%). It proves that the soil-by-soil calibration is very





Fig. 11. Estimated vs measured SMC for the six soil samples used in the calibration step in the Fig. 9.

We used the replicates of the Whit04 dataset to test the soil-by-soil calibration and to validate the method. A relationship has been adjusted between  $\varphi$  and SMC for thirty soil samples, leading to as many calibration equations that have been applied to the replicates. The estimation error is generally less than 5% and the RMSE 2.8% (Fig. 12). In comparison, the errors associated with field TDR measurements are approximately 2.5% in volume percent of water (Walker et al., 2004).



Fig. 12. Estimated vs measured SMC for the soils of the Whith04 dataset.

One of the advantages of remote sensing is a large spatial coverage, but detailed knowledge of the nature of the investigated soils is barely available because they may change quickly in terms of texture and structure from one spot to another. Therefore, an approach requiring a calibration relation between SMC and  $\varphi$  for each soil hardly applies since there is no unique relation as shown in Fig. 7. In order to fulfill operational requirements, we attempted classifying soils into groups. Several techniques were used, based on soil physical, chemical and spectral characteristics.

400

### 401 **3.2.2** Class-by-class calibration and assessment steps: physical and chemical properties

402 First, the effects of mineralogy and texture in the estimation of the relationship between SMC and 403  $\varphi$  were investigated. To this end, we took advantage of the mineralogical information of the Whit04 404 dataset. The amount of calcium carbonate  $(CaCO_3)$  and silicon dioxide  $(SiO_2)$  in the Tomelloso soils is quite variable, while there is no CaCO<sub>3</sub> and a constant amount of SiO<sub>2</sub> (~29%) in the Lemoore soils. 405 The relationship between SMC and  $\varphi$  is consequently more scattered for the first ( $r^2 = 0.93$ ) (Fig. 406 13a) than for the second  $(r^2 = 0.97)$  (Fig. 13b). While the modification of the spectral properties of a 407 408 soil when moistened depends upon its mineralogical composition (Bedidi et al., 1992), it may influence the parameters  $\psi$  and a of the sigmoid function. The soils of Les08 and Bab16 that contain 409 410 textural information were also investigated. We divided them into two groups: sandy soils for which 411 50% of the grain size is sand (larger than 0.05 mm and less than 2 mm) and clay soils for which 50% 412 of the grain size is clay (less than 2  $\mu$ m). The relationship between SMC and  $\varphi$  is well fitted by the 413 sigmoid function in both cases, with high coefficients of determination (Figs. 13c and 13d). 414 Furthermore, the parameter K is lower for the sandy soils (46.2%) than for the clay and silt soils 415 (59.1%) in accordance with the fact that the porosity of the former is lower than that of the latter. This 416 is consistent with the hypothesis that the parameter K is related to this soil property. These results 417 show that our method can be generalized by making a preliminary soil texture and mineralogical 418 composition classification. Unfortunately, such information is seldom available.



**Fig. 13**. Calibration phase for (a) four soils from Tomelloso and (b) five soils from Lemoore (Whit04 dataset). Calibration phase for (c) six sandy soils and (d) nine non-sandy soils of the Les08 (blue crosses) and Bab16 (brown squares) datasets.

### 421 **3.2.3** Class-by-class calibration and prediction: spectral signatures

We investigated the classification method proposed by Lesaignoux et al. (2013) where the soils are 422 423 grouped together on the basis of the shape of the dry soil reflectance spectrum in four wavelength ranges (VIS, NIR-SWIR, MWIR, and LWIR). The 32 soils were initially divided into nine groups but, 424 in this study, groups 1 and 2 and groups 4 and 5 were merged together because the shape of their dry 425 soil is identical in the VIS and NIR-SWIR and because our study is restricted to these domains. 426 Moreover groups 3, 7, 8 and 9 which contain less than two soils were discarded. Finally we 427 maintained three classes: class I (groups 1 and 2), class II (groups 4 and 5), and class III (group 6). 428 429 Figs. 14a-d compare the sigmoid functions obtained on these three classes and on the whole dataset. Note that because some soils of Les08 are excluded from the three classes, some points of Fig. 14a do 430 431 not appear in Figs. 14b-d. The  $r^2$  values of 0.71, 0.84 and 0.98 for class I, II and III, respectively, are globally better than that of the whole dataset ( $r^2 = 0.75$ ). The calibration equation of class III 432 433 displays a very high coefficient of determination probably because all the samples have been collected 434 in the same area (Camargue, France). The soils of class II that contain a maximum number of samples

have been divided into two sub-classes: one for the calibration and one for the validation (Figs. 14e-f).
Soil moisture content is very well inferred thanks to that classification (RMSE = 5.1%) although the
accuracy is worse compared to the soil-by-soil calibration, as expected. Nevertheless, the
classification was based upon a visual method: it may introduce some mistakes and it is not suited for
large datasets, so it cannot be applied to the whole database.





Fig. 14. Calibration phase for the different *a priori* classes of the Les08 dataset: (a) the thirty-two soils of the whole dataset, (b) the five soils of class I, (c) the sixteen soils of class II and (d) the three soils of class III. (e) Link between SMC and  $\varphi$  obtained with five soils of the class II and (f) estimated SMC thanks to the equation of calibration of (e) compared to measured SMC for the five soils of the validation dataset of class II.



442 Another classification method has been tested: Lacerda et al (2016) compare the reflectance of dry 443 soils in Landsat-TM 5 band 5 (1650 nm) and band 7 (2215 nm). When one plots the second as a

function of the first, clayey soils and sandy soils are respectively located at the bottom and the top of 444 the plot. The reflectance of sandy soils is often higher because they are often made of quartz (e.g., 445 446 Stoner and Baumgardner, 1981; Demattê, 2002; Lacerda et al., 2016). The Whit04 dataset that contains two different kinds of soils is well suited to test this method. Fig. 15a shows that the 447 Tomelloso soils are located at the top of the plot and are scattered, while the Lemoore soils are located 448 449 at the bottom and are concentrated. The calibration performed on the whole dataset globally led to a lower coefficient of determination ( $r^2 = 0.94$ ) than that performed on the Lemoore and Tomelloso 450 soils ( $r^2 = 0.96$  and  $r^2 = 0.94$ , respectively) (Figs. 15c-d). Therefore, by using the same method of 451 classification, we divided the Tomelloso soils into two subsets (Fig. 15b). The fit is slightly better 452 453 with coefficients of determination higher than 0.95 and the two classes are clearly separated (Fig. 454 15e). Once again the parameters of the sigmoid function,  $\psi$  and a, seem to be related to the mineralogy of the soils, which corroborates the result of Figs. 13a-b. 455







**Fig. 15**. Classification of the sixty soils of Whit04 after Lacerda et al. (2016). (a) Lemoore and Tomelloso separately and (b) Lemoore and Tomelloso when separated into two datasets. Calibration phase of the Whit04 dataset for (c) all the sample, (d) the thirty soil samples from Tomolleso and the thirty soil samples from Lemoore and (e) the thirty soil samples from Tomelloso soils divided into two datasets.

To validate this method of classification, a cross validation was performed on the Whit04 dataset by dividing the Lemoore soils into two subsets randomly chosen and equally sized, one for the calibration step (Fig. 16a) and one for the validation step (Fig. 16b). The soil moisture retrieval is very good (RMSE = 3.6%).





Fig. 16. (a) Calibration phase on eight soils from Lemoore and (b) prediction step on seven other soils of this same area.



470 is 0.75 (Figs. 17b-e). So it will allow assessing the SMC of a soil of one of these groups with a good
471 accuracy. Moreover, the coefficient *K* of the group III, which is made of sandy soils, is lower than that
472 of the group I which is a mixture of sandy and clayey soils.





Fig. 17. (a) Lacerda classification method applied to ninety-seven soils of Lob02, Whit04, Les08 and Bab16, black dots are the unclassified samples. Calibration step on (b) all the soils of the datasets Lob02, Whit04, Les08 and Bab16, (c) fifty-three soils of group I, (d) twenty-two soils of group II and (e) the twenty-five soils of group III.

474

This method of classification seems to be adequate to build calibration equations that are strong enough to use MARMITforSMC globally. The next step is to use it outdoor, i.e., to see to what extent the atmospheric absorption bands affect the SMC retrieval.

### 479 3.3 MARMIT and MARMITforSMC without atmospheric absorption bands

In real conditions, part of the solar spectrum is not available because of atmospheric absorption bands. We removed the two main bands located between 1300 nm and 1500 nm and between 1800 nm and 2100 nm, and inverted MARMIT again. Fig. 18 shows a good fit of the data, which is not surprising since Bach and Mauser (1994) came to the same conclusion with their model.

484



Fig. 18. Measured (solid line) and modeled (dashed line) reflectance spectra, excluding data in the main atmospheric absorption bands of one soil at various levels of soil water content: soil from Ithaca in Phil14. The retrieved parameters of the model are provided to the right of the curves  $(L, \varepsilon)$ . *L* is in mm.

485

486 The RMSE obtained without the atmospheric absorption bands is even better (Fig. 19). The mean
487 water thickness estimated by inversion of MARMIT is very similar.

488



Fig. 19. RMSE obtained with MARMIT with and without reflectance data in the main atmospheric absorption bands (AAB) for all the soils of all the database.

489

### 490 **4.** Comparison with other methods

In this section, the MARMITforSMC method described in Section 3.2 is compared to other methods published in the literature for soil moisture content estimation. As they require calibration, we performed the calibration step and the assessment step on the same dataset as in Sadeghi et al. (2015).

495

### 496 **4.2 Semi-empirical methods**

Five spectral indices and two semi-empirical approaches, that are the Soil Moisture Gaussian Model (SMGM) (Whiting et al., 2004) and the relative absorption depth (RAD) through Continuum Removal method, were investigated. A spectral index is a combination of reflectances at two or more wavelengths: generally one chooses wavelengths where photons are not or little absorbed and wavelengths where, contrariwise, they are strongly absorbed. Most of the spectral indices listed in Table 3 are typically used to determine soil water content. They perform quite well and are easy to use.

504

Index	Formula	Source
Normalized Soil Moisture Index (NSMI)	$\frac{R_{1800} - R_{2119}}{R_{1800} + R_{2119}}$	Haubrock et al. (2008)
Normalized Index of NSWIR domain for SMC estimation from Linear regression (NINSOL)	$\frac{R_{2076} - R_{2230}}{R_{2076} + R_{2230}}$	Fabre et al. (2015)
Normalized Index of NSWIR domain for SMC estimation from Non-linear regression (NINSON)	$\frac{R_{2122} - R_{2230}}{R_{2122} + R_{2230}}$	Oltra-Carrió et al. (2015)
Normalized Difference Water Index (NDWI)	$\frac{R_{860} - R_{1240}}{R_{860} + R_{1240}}$	Gao (1996)
Water Index SOIL (WISOIL)	$\frac{R_{1450}}{R_{1300}}$	Whalley et al. (1991)

505

Table 3. Some spectral indices found in the literature. Wavelengths are expressed in nm.

The SMGM and RAD methods are based on the continuum of the spectrum. Indeed, absorption features in the reflectance spectrum can be isolated by a mathematical function called apparent continuum (Clark and Roush, 1984). In the SMGM, Whiting et al. (2004) fit an inverted Gaussian function to the continuum and they calibrate the area below the curve to SMC. Yin et al. (2013) calculate the relative absorption depth as  $R = 1 - R_b/R_c$  (where  $R_b$  is the normalized reflectance at 511 1940 nm and  $R_c$  the one at 1800 nm) and they regress it against SMC. In order to have a reliable 512 calibration, the results provided by these methods are compared to MARMITforSMC for datasets 513 containing more than five soil samples (Fig. 20). The worst results are obtained with the Liu02 and 514 Bab16 datasets, due to the nature of the soils described above. Let's now analyze the methods 515 individually:

1) The indices NSMI, NINSOL and NINSON which are known to perform well (Fabre et al., 2015)
provide the best results contrary to NDWI index which is mainly used for the detection of water in
vegetation (Gao, 1996; Khanna et al., 2007). NSMI, which performs best with Liu02, a dataset
containing oversaturated samples, seems to be the most appropriate index for saturated soils and
WISOIL also gives good results. But none of these both indices can be used in remote sensing
because one of the wavelength used is located in a broad atmospheric absorption band.

522 2) SMGM works well on Whit04 and Mar12 because the efficiency of this method depends on the
523 spectral shape of soil reflectance, which is very similar in these two datasets. The main
524 disadvantage of this method is that it is limited to soil below saturation with water content less than
525 0.32 g/g (Whiting et al., 2004).

3) The RAD method always leads to acceptable errors but never performs the best. It means that it
is robust but less efficient than NSMI, WISOIL and MARMITforSMC. Moreover, it has only been
tested on samples in laboratory conditions and it uses a wavelength located in one of the main
atmospheric absorption band (1940 nm).

4) MARMITforSMC performs very well and is the most robust method except for the Liu02dataset for reasons already discussed.

532



**Fig. 20**. Comparison of RMSE obtained with the spectral indices of Table 3, the SMGM and RAD methods, and MARMITforSMC using the datasets: (a) Liu02, (b) Whit04, (c) Les08, (d) Mar12 and (e) Bab16. NDWI cannot be applied to Whit04 because the reflectance at 860 nm is not available.

### 534 **4.3 Physical models**

### 535 4.3.1 The Sadeghi model

Sadeghi et al. (2015) developed a model based on the Kubelka-Munk theory. They provide two models, a complete one and a simplified one (Eq. (16)), which both link the SMC to the transformed reflectance of the wet soil (r), the dry soil ( $r_d$ ), the saturated soil ( $r_s$ ) and to the saturated SMC (SMCs):

540

$$SMC = \frac{r - r_d}{r_s - r_d} SMC_s \tag{16}$$

The transformed reflectance r is linked to soil reflectance R at 2210 nm (center of the Landsat-TM and MODIS bands) by the relation  $r = (1 - R)^2/2R$ . Sadeghi et al. (2015) tested the efficiency of the simplified model for SMC retrieval on two datasets: Lob02 and Whit04. For Lob02 they tested it soilby-soil and for Whit04 they separated the Lemoore soils from Tomelleso soils. They first performed a calibration step: SMCs are measured and they obtain  $r_d$  and  $r_s$  thanks to a least square optimization. Then they used this calibration equation to assess SMC. Table 4 provides the RMSE of SMC retrieved using the Sadeghi model and using MARMITforSMC.

549

Deteget	Soil -	RN	<b>RMSE (%)</b>		
Dataset		Sadeghi	MARMITforSMC		
	Andisol	3.6	2.4		
Lab02	Entisol	1.2	2.4		
L0002	Aridosol	0.5	1.1		
	Mollisol	3.0	2.8		
W/L:+04	Lemoore	6.7	2.7		
w mt04	tu4 Tomelloso	7.7	3.3		

**Table 4.** Comparison of SMC assessment with MARMIT compared to the one with the Sadeghi model. In bold the best results.

551 MARMITforSMC performs much better than the Sadeghi model for the Whit04 dataset while the 552 results are similar for the Lob02 dataset, depending on the soil. The RMSE are divided by more than 553 two because, in the calibration phase of the Sadeghi model, only one transformed reflectance 554 spectrum of dry and wet soil can be obtained by inversion even if different soils are studied. In 555 MARMIT the reflectance spectrum of the dry soil is used for each soil.

556

550

### **4.3.2 The Bach model**

As mentioned in Section 2.1, MARMIT derives from the Bach model (Eq. (5)). Bach (1995) also performs a calibration of her model but she relates SMC with *L* using a linear regression. We decided to apply the same calibration phase as in MARMITforSMC and to link  $\varphi$  and SMC with a sigmoid function. The entire dataset Whit04 and the three classes of Les08 have been compared. MARMIT leads to a better RMSE (Table 5), even if the Bach model better fits the measured reflectance spectra (Fig. 6) due to an adapted water absorption coefficient.

Dataset -		<b>RMSE (%)</b>		
		Bach	MARMITforSMC	
Whit04		4.8	3.4	
	Whole dataset	7.1	6.7	
L ac/09	Class I	7.0	6.7	
Lesua	Class II	4.8	4.3	
	Class III	2.9	2.1	

Table 5. Comparison between MARMIT and the Bach model. In bold the best RMSE.

565

### 566 5. Conclusion

A simple physically-based model called MARMIT was developed and used for SMC retrieval on 567 seven independent datasets gathering 217 soil samples collected in China, France, Spain, Tunisia and 568 569 the U.S.A. The model estimates SMC in three key steps which constitutes the MARMITforSMC method: (1) inversion, (2) calibration, and (3) (cross-)validation. Step (1) works better for low SMC 570 571 values. Sometimes it is difficult to fit the reflectance in the visible probably because some phenomena 572 are not taken into account: for instance, it is likely that the soil particles and the water film mix as suggested by Philpot (2010). This leads to an overestimation of the reflectance outside the water 573 574 absorption bands and an underestimation in the water absorption bands. Despites this issue, step (2) explains very well the evolution of SMC with  $\varphi$  when soils are considered individually ( $r^2 \ge 0.95$ ). 575 The variation of soil moisture content as a function of the mean water thickness is well described by a 576 577 sigmoid function, some parameters of which are related to soil chemical and physical properties. The 578 parameter K (maximum value of the function) seems to be linked with the SMC at saturation; a (the place of the curve on the x-axis) and  $\psi$  (the slope between the two horizontal asymptotes) may be 579 related to mineralogy. Unfortunately, we lack metadata to support this hypothesis. As the goal of the 580 581 method is to infer the SMC using remote sensing data regardless of the soil type, a soil-by-soil 582 calibration is not desirable. We successfully grouped the soils together into general classes to infer 583 accurate global calibration equations. The most operational way of classification proposed by Lacerda 584 et al. (2016) has been successfully tested on the thirty Lemoore soils of the Whit04 dataset (RMSE =585 3.62%) and more generally on the soils of the datasets Lob02, Whit04, Les08 and Bab16 together.

Indeed, we found three groups with coefficients of determination of the relationship between SMC 586 587 and  $\varphi$  greater than 0.74. Finally, MARMIT for SMC has been compared to existing methods for SMC retrieval: the method performs as well or better than other methods, especially the one relying on the 588 589 Bach model. Moreover, we proved that SMC could be retrieved with the same accuracy as TDR 590 measurements thanks to an appropriate classification (RMSE  $\sim 3\%$ ). The new method clearly led to 591 an improvement in the SMC retrieval. The main advantage of this model is that it is easy to 592 understand and fast to compute, and there is room for progress. The drawback of MARMITforSMC is 593 that it requires a calibration step, which is soil dependent, and the reflectance spectrum of the dry soil. 594 The first issue can be overcome with a soil classification based on spectral signatures and the second one by multi-data imagery. We also showed that MARMIT was not suitable for oversaturated soils in 595 596 water. The model may be improved by taking into account specular reflectance. The measurement protocol, e.g., water distribution within the sample, probably influences the results of 597 598 MARMIT for SMC given that the SMC in the sample is variable vertically and horizontally. Future research in SMC retrieval using MARMIT with soils of known textural and mineralogical properties 599 600 will help extend and improve the model for porosity or grain size.

601

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612

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