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# Temporal Dynamics of action perception: Differences on ERP evoked by Object-Related and Non-Object-Related Actions

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## ABSTRACT:

While neuropsychological dissociations suggest that distinct processes are involved in execution or perception of transitive (object-related) and intransitive (non-object-related) actions, the few neuroimaging studies that directly contrasted the brain activations underlying transitive and intransitive gesture perception failed to find substantial differences between the two action types. However, the distinction could be visible on brain activity timing within the fronto-parietal network. In this study, we used Event-Related Potential (ERP) method to assess the temporal dynamics of object-related and non-object-related action processing. Although both meaningful, only object-related actions involve object motor features. Accordingly, perception of the two action types would show distinct neural correlates. Participants were presented with four movie types (ORA, Object-Related Action, NORA: Non-Object-Related Action and 2 control movies) and were instructed to perform tasks that required explicit or implicit action recognition (specific action recognition or color change detection). Movies were presented as Point-Light Display (PLD) and thus provided only information about gesture kinematics regardless of action type. ERP were computed during movie visual perception and analyzed as a function of movie type and task. The main result revealed a difference between ORA and NORA on the amplitude of the P3a component in the fronto-parietal region. The difference observed around 250 ms after movie onset do not likely origin from variation in low-level visual features or attention resource allocation. Instead, we suggest that it reflects incidental recruitment of object attributes during object-related action perception. The exact nature of these attributes is discussed.

**KEYWORDS:** EEG; Action perception; Object Knowledge; Point Light Display; Transitive and Intransitive Action

1           **1. INTRODUCTION**  
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5           Several influential models of gesture production suggest that distinct cognitive  
6 mechanisms are devoted to the execution of different gesture types. Based on the  
7 observation of apraxic patients, such models typically propose two distinct routes for  
8 action, a semantic route and a non-semantic route (Buxbaum, 2001; Cubelli,  
9 Marchetti, Boscolo, & Della Sala, 2000; Gonzalez Rothi, Ochipa, & Heilman, 1991).  
10 The two routes would be differentially involved in the production of meaningless,  
11 transitive, and intransitive gestures. While imitation of meaningless gestures can only  
12 rely on the direct, non-semantic route for action, execution of both transitive (i.e.  
13 object-related) and intransitive (i.e. non-object-related) gestures can tap onto the  
14 semantic or non-semantic route. In other words, executing intransitive actions as well  
15 as pantomimes of object use may involve semantic representations. However, it is still  
16 unclear whether transitive and intransitive gestures rely on distinct cognitive and  
17 neural mechanisms.  
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36           Distinction between production of transitive and intransitive gestures has been  
37 first documented in the neuropsychological literature. Patients with strongly impaired  
38 transitive gesture production and relatively preserved intransitive gesture execution  
39 have been reported many times following left hemisphere lesions (Dumont, Ska, &  
40 Schiavetto, 1999; Foundas et al., 1995; Haaland, Harrington, & Knight, 2000;  
41 Rapcsak, Ochipa, Beeson, & Rubens, 1993; Roy, Square-Storer, Hogg, & Adams,  
42 1991). Based on these observations, it has been suggested that transitive and  
43 intransitive gesture execution rely on distinct cognitive networks. However, transitive  
44 gestures could be simply more difficult to perform than intransitive gestures. Several  
45 behavioral results are consistent with this alternative interpretation. Using more  
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1 refined measures of gesture production accuracy, Carmo & Rumiati (2009) revealed  
2 that healthy participants imitated intransitive gestures better than transitive gestures  
3 (see also Mozaz, Rothi, Anderson, Crucian, & Heilman, 2002, for similar results).  
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5 Thus, differences in gesture execution complexity could account for the greater  
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7 deficits in transitive gesture production frequently reported in apraxic patients.  
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11 In this context, neuroimaging studies have tried to identify the neural  
12 substrates that would be specific to transitive action planning and execution  
13 (Bohlhalter et al., 2009; Culham, 2004; Fridman et al., 2006; Johnson-frey, Newman-  
14 norlund, & Grafton, 2005; Króliczak & Frey, 2009). Although both gesture types  
15 recruit a left-lateralized fronto-parietal network (but see Bohlhalter et al., 2008 for a  
16 right hemispheric dominance for intransitive gestures), some areas of this network  
17 have been shown to be more active during preparation and/or execution of transitive  
18 compared to intransitive actions (Buxbaum, Kyle, Grossman, & Coslett, 2007;  
19 Culham et al., 2003; Fridman et al., 2006; Haaland, Harrington, & Knight, 2000;  
20 Króliczak & Frey, 2009; Wheaton & Hallett, 2007). As suggested by Króliczak and  
21 collaborators in their interpretation (Króliczak & Frey, 2009), the differences  
22 observed may also depend on movement complexity since sensory-motor cortex  
23 activity and movement complexity are closely linked (Gut et al., 2007). Thus,  
24 findings from neuroimaging studies corroborate neuropsychological observations and  
25 suggest that the stronger fronto-parietal involvement observed during production of  
26 transitive compared to intransitive gestures is probably caused by greater difficulty of  
27 transitive gesture execution.  
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54 Recently, the pattern of apraxic deficits presented by an autistic child re-  
55 fuelled the debate on the transitive-intransitive gesture distinction. Ham, Bartolo,  
56 Corley, Swanson & Rajendran (2010) reported the case of JK, who exhibited a  
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1 selective impairment in producing intransitive gestures with normal scores in  
2 transitive gesture production. The existence of a double dissociation between the  
3 deficits presented by this child and the impairments of apraxic patients showing the  
4 opposite pattern suggests that the difference between transitive and intransitive  
5 gesture execution goes beyond difficulty.  
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13 In the present study, we aimed at investigating the neural correlates of  
14 transitive (object-related) and intransitive (non-object-related) action processing in  
15 perceptual tasks. We used perceptual tasks for two reasons. First, neuroimaging  
16 studies using production tasks lack appropriate baseline conditions for transitive and  
17 intransitive gesture comparison (Króliczak & Frey, 2009). Since gesture complexity is  
18 not matched between action types, it is tricky to draw conclusions about the specific  
19 neural substrates of object-related and non-object-related actions from production  
20 data. This limit is less difficult to overcome in perception. Accordingly, we designed  
21 perceptual control stimuli that were equivalent to the perceived transitive and  
22 intransitive actions in term of visual complexity. Second, in order to keep transitive  
23 and intransitive gestures equivalent, objects could not be presented. Moreover, we  
24 wanted to avoid pantomime tasks, since there is evidence of partially distinct neural  
25 circuits for real and pantomimed gesture execution (Króliczak, Cavina-Pratesi,  
26 Goodman, & Culham, 2007; Senkfor, 2008). Thus, the use of a perceptual paradigm  
27 allowed the assessment of object-related actions without involving objects or  
28 pantomimes.  
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52 On the one hand, the two routes of action models (Buxbaum, 2001; Cubelli et  
53 al., 2000; Gonzalez Rothi et al., 1991) suggest that both object-related and non-  
54 object-related actions could involve some kind of semantic representations. On the  
55 other hand, it has been argued that in many situations, object-related actions require  
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1 accessing both action and object representations (Buxbaum, 2001; Frey, 2007). This  
2 characteristic can obviously not apply to non-object-related actions, suggesting that  
3 additional semantic processes are involved in visual perception of object-related  
4 actions. Thus, perception of object-related actions, but not non-object-related actions,  
5 would involve the recruitment of object knowledge and in particular object motor  
6 features (Buxbaum et al., 2007; Chao & Martin, 2000; Martin, 2007). Based on this  
7 idea and on the double dissociation observed in production (Dumont et al., 1999;  
8 Foundas et al., 1999; Haaland et al., 2000; Ham et al., 2009; Rapcsak et al., 1993;  
9 Roy et al., 1991), differences in cerebral activity during observation and recognition  
10 of object-related and non-object-related actions should be expected. In perceptual  
11 tasks, neuroanatomical and neuroimaging studies that directly compared object-  
12 related and non-object-related actions are even more limited (Agnew, Wise, & Leech,  
13 2012; Pazzaglia, Smania, Corato, & Aglioti, 2008; Villarreal et al., 2008). Villarreal et  
14 al. (2008) have reported some differences in the inferior frontal gyrus (IFG) between  
15 the action types. However, they have been related to extra-processing demands for  
16 non-object-related gesture perception, probably because of the symbolic nature of the  
17 gestures presented (e.g. stop, salute, hitch hike, crazy, victory). Recently, Agnew et  
18 collaborators (2012) showed different fMRI responses in frontal and parietal cortices  
19 during observation of object-related compared to meaningless non-object-related  
20 actions, but results could be due to the use of meaningless actions in the non-related  
21 action condition. Indeed, fronto-parietal areas may be more strongly recruited when  
22 action processing follows the semantic route, regardless of the type of semantic  
23 representation involved. Taken together, patient and fMRI studies have not provided a  
24 coherent pattern of data in support of a clear distinction between object-related and  
25 non-object-related gesture processing during action production or perception.  
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On possible reason for the inconsistencies reported may be that the distinction between object-related and non-object-related actions is relatively fine-grained and more visible on the timing of brain activity within the fronto-parietal network. Accordingly, fMRI paradigms would not be best suited to investigate this issue. Thus, we used EEG measurement and particularly Event-Related Potential method (ERP) to assess the temporal dynamics of object-related and non-object-related action processing during perceptual tasks. With EEG, we could determine the specific moment in processing when differences between action types emerged. It was thus possible to discriminate between effects related to visual complexity occurring at early processing stages and semantic effects occurring at later processing stages. Although the neural correlates of action observation have been importantly studied using EEG techniques (e.g. Silas, Levy, Nielsen, Slade, & Holmes, 2010 using whole-body movements, Perry & Bentin, 2009 using hand grasps or Urgen, Plank, Ishiguro, Poizner, & Saygin, 2013 for comparison between human and non-human motion), to our knowledge no EEG paradigm has explicitly contrasted object-related and non-object-related actions before.

In light of previous studies, it was critical for our EEG paradigm to control for differences in stimulus complexity between the two action types. Thus, we used point-light display (PLD) stimuli (Johansson, 1973) in order to control for physical differences between stimuli. Indeed, baseline control PLD stimuli were created for each action type, in which the general movement characteristics (duration, number of points and kinematic of points) were equal to the original action but movement information was meaningless. Moreover, PLD stimuli provided biological movement information only – without giving any object visual information in the case of object-related action- and minimized context effects. Thus, we are able to test the distinction

1 between temporal dynamics of object-related and non-object-related action processing  
2 with strictly equivalent stimuli, while controlling for potential differences in stimulus  
3 complexity.  
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7 Although time-frequency analysis, and in particular mu rhythm modulation,  
8 has been successfully used to highlight motor system involvement during observation  
9 of PLD of biological movements (Perry & Bentin, 2011; Perry, Troje, & Bentin,  
10 2010), mu rhythm modulation would not be expected to be sensitive to semantic  
11 differences during action observation. Since the objective of the present study was to  
12 distinguish between the semantic processes at play during observation of two types of  
13 biological movements, we focused our analysis on ERP components.  
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24 Several ERP components have been shown to be sensitive to the observation  
25 of PLD presenting whole-body intransitive movements (Hirai, Fukushima, & Hiraki,  
26 2003; Hirai, Senju, Fukushima, & Hiraki, 2005; Jokisch, Daum, Suchan, & Troje,  
27 2005; Krakowski et al., 2011), starting around 200 ms after stimuli onset. We  
28 predicted ERP differences between action types at two stages of PLD visual  
29 processing. First, on early visual components (P100 and N170) known to reflect  
30 analysis of stimuli physical features (Hirai et al., 2003, 2005; Jokisch et al., 2005), we  
31 expected to find differences related to inhomogeneity in stimuli complexity. Second  
32 and most critically, differences during perception of the two gesture types were  
33 expected on late ERPs components known to be related to object semantic processing.  
34 Perception of object-related actions, but not non-object-related actions, would involve  
35 the recruitment of some parts of object knowledge, perhaps related to object motor  
36 features (Buxbaum et al., 2007; Chao & Martin, 2000; Martin, 2007). Traditionally,  
37 semantic processing has been associated with brain responses occurring around 350-  
38 400 ms after stimulus onset, often identified as N400 component (for instance,  
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1 Balconi & Caldiroli, 2011; Proverbio & Riva, 2009; van Elk, van Schie, & Bekkering,  
2 2010). However, recent studies evidenced that stimulus semantic processing could  
3 start earlier. For instance, brain responses associated with semantic tasks (e.g.,  
4 meaningful/meaningless decision, semantic incongruence detection) on action verbs  
5 (Moseley, Pulvermüller, & Shtyrov, 2013; Pulvermüller, Härle, & Hummel, 2001),  
6 action pictures (Meyer, Harrison, & Wuerger, 2013) or object pictures (Lloyd-Jones,  
7 Roberts, Leek, Fouquet, & Truchanowicz, 2012; Lu et al., 2010; Proverbio, Adorni, &  
8 D’Aniello, 2011) have been reported as early as 250 ms after stimulus onset. Thus,  
9 ERP components occurring from 250 ms after stimuli onset were all possible  
10 candidates for distinguishing between object-related and non-object-related action  
11 processing. In other words, differences during action observation were expected on  
12 P3a and/or P3b and/or N400 components.  
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29 Finally, we aimed at testing the incidental character of object motor feature  
30 selective activation during object-related action processing. To this aim, participants  
31 were proposed two distinct tasks. They were instructed either to recognize one given  
32 action (specific action recognition task), or to detect the presence of a red point during  
33 PLD visual presentation (red point detection task). If object motor feature activation  
34 were incidental, ERP differences between object-related and non-related actions  
35 would be independent of the requirements of the task.  
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## 48 **2. METHODS**

### 49 **2.1. Participants**

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54 Twenty adults (mean age 24.3; age range 19–32; 13 women) participated in  
55 the experiment. Data from one participant were removed from the final statistical  
56 analysis due to head motion artifacts. The final sample included 19 participants. All  
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1 participants were right-handed (handedness quotients 60–100%; mean 90%; Oldfield  
2 1971) and had normal or corrected-to-normal visual acuity. None of the participants  
3 reported history of dyslexia or any neurological diseases. The experimental procedure  
4 was approved by the local ethical committee in accordance with the Helsinki  
5 declaration. All participants signed an informed consent form prior to their  
6 participation.

## 14 **2.2. Stimuli & materials**

17 A Qualysis motion capture system was used in order to capture the motion of  
18 one actor in 30 different actions, classified into 2 Action Types: 15 Object-Related  
19 Actions (ORA) and 15 Non-Object-Related Actions (NORA). An additional ORA  
20 [hammering (a nail)] was recorded in order to serve as the action target in the Specific  
21 Action Recognition Task. Action list is presented in Appendix 1. Eighteen reflective  
22 markers were attached to the major joints of the actor's body (shoulder, elbow, wrist,  
23 thumb, index finger, hip, knee, foot, head and plexus). Motion of these markers was  
24 then recorded to create movies of 'point-light' displays (PLD) against a dark  
25 background.

27 It is critical to note that ORA movies resembled pantomimes in the sense that  
28 they did not contain objects. However, object-related gestures were actual use actions  
29 that were performed by the actor with the object in hand while the motion of the  
30 markers positioned on the joints of her body were recorded. Thus, both ORA and  
31 NORA movies only presented movements of body in action. Nevertheless, the  
32 amount of movement information between the two stimuli categories could have  
33 differed (e.g., movements in NORA movies might be of greater amplitude overall).  
34 Therefore, control conditions of ORA and NORA stimuli were designed by applying  
35 a random transformation on the x coordinate of each marker before applying a 180°  
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1 spatial rotation to the movie. Thanks to this procedure, each transformed video had  
2 the exact same general movement characteristics (duration, number of point and  
3 kinematic of point) as the original video but did not convey any signification. Thus,  
4 there were 4 stimulus conditions, 2 Action Types [ORA and NORA] × 2 Display  
5 Types [Normal and Transformed], and 15 videos in each condition. Examples of  
6 stimuli are presented in Figure 1. Movie duration was set to 1 second. Movies were  
7 displayed within a 500 × 500 pixels area in the middle of a black screen. Stimulus  
8 presentation was controlled by Eprime software version 2.0 run on a PC.

19 To assess potential behavioral variations in PLD semantic processing, a  
20 normative experiment was conducted. Seventeen additional participants viewed the  
21 60 videos and performed a task in which they had to determine as exactly and quickly  
22 as possible if the action presented was meaningful or meaningless (for more details  
23 about the procedure, see Appendix 2). On the basis of response time (RT) results, 2  
24 items were considered outliers and were excluded from the EEG experiment analysis  
25 (1 from each category ORA and NORA: respectively “Opening a tap” and “running”)  
26 because RT for these items were beyond 2.5 Median Absolute Deviation (MAD) from  
27 median RT in their respective condition (Leys et al., 2013). Moreover, on the 28  
29 remaining actions, statistical analyses did not revealed any RT differences between  
30 the two Action Types (ORA vs. NORA;  $t_{1,15} = 0.962$  ;  $p = 0.351$ ). This measure was  
31 taken as an index of action subjective semantic processing difficulty (i.e. the more  
32 time participants require to decide that a given action is meaningful, the more difficult  
33 it is to access some kind of semantic representation of the action). Thus, the two final  
34 PLD categories were considered equivalent in terms of semantic processing difficulty.

58 -----< Insert Figure 1 about here >-----  
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### 2.3. Procedure

After a brief presentation of EEG materials and of the general goal of the study, participants were informed that they had to perform two distinct tasks implying the same stimuli: A Red Point Detection task and a Specific Action Recognition task. Task order was counterbalanced between participants. Specific instructions were recalled before each task. During the whole experiment, participants were seated in front of a computer screen (1600 × 900, 60 Hz) in a dimly illuminated room. They were instructed to keep their gaze fixated on the center of the screen and to answer by pressing on the -space- key of the keyboard.

Prior to the EEG experiment, a familiarization session was administered. The goal of the familiarization session was to clarify the impoverished stimuli that would be presented during the whole EEG experiment. Indeed, videos were simple points in motion, and we wanted to be sure that participants perceived the same actions as those realized by our actor. Thus, each PLD in normal orientation (15+1 ORA and 15 NORA) was presented twice during the familiarization session, preceded by the name of the corresponding action (e.g. sawing). Participants had to answer two questions: (1) Are you able to see the person in this video [sawing]? (first presentation) (2) Could you mime the action presented (second presentation)? The same procedure was realized for the 31 actions with signification presented in pseudo-random order. Finally, recognition of the 31 critical PLD was checked right before starting the experimental session. Videos were presented a last time and participants had to name them one at a time. After familiarization, errors were very rare (2%). Since the goal of the familiarization session was to ensure agreement on PLD identity before the EEG experiment, participants' responses were systematically corrected. Behavioral

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variability in PLD semantic processing was assessed in a separate normative experiment in which reaction times to PLD semantic categorization were recorded (see 2.2 and Appendix 2).

### 2.3.1. Task involving implicit semantic processing: Red-Point Detection

Specific instructions for the Red-point detection task were: “On each trial, a video of a schematized action will be briefly presented (1 s). On some trials, one of the white points that compose the schematized action will turn to red. When you detect it, press on the -space- key of the keyboard placed in front of you”. This task was called “implicit” because the participant did not need to recognize the action to perform the task. A fixation cross was presented in the center of the screen before and after video presentation. Participants were instructed to fix it in order to minimize blink artifact generated by gaze motion. Inter-trial presentation was set between 3 s and 4 s by step of 250 ms. The trial procedure was the same for the 420 trials (3 sessions × 2 repetitions × 2 action types × 2 display types × 15 actions + 24 trials without video presentation + 36 trials in which the red point was presented: 8,6% of total number of trials). Duration of inter-trials and filler trials (without video presentation) was varied in order to minimize stimuli onset predictability. Trials requiring a behavioral response were used to ensure that participants maintained their attention on the stimuli presented. On those trials, a point-light turned to red during 200 ms in a random manner between 300 and 700 ms after video onset. The position of the red point was also randomly determined. Only trials without behavioral response were used for EEG analyses. The duration of the task was about 24 minutes, leading to a total of about 30 minutes including breaks.

### 2.3.2. Task involving explicit semantic processing: Specific Action

#### Recognition

The Specific Action Recognition task used the exact same procedure as the Red-Point Detection task except that the instructions explicitly required action semantic processing: “On each trial, a video of a schematized action will be briefly presented (1 s). On some trials, the action of “hammering [a nail]” will be shown. When you detect it, press on the -space- key of the keyboard placed in front of you ”.

With a total of 420 trials (3 sessions  $\times$  2 repetitions  $\times$  2 action types  $\times$  2 display types  $\times$  15 actions + 24 trials without video presentation + 36 trials in which the action “hammering [a nail]” was presented: 8,6% of total number of trials), the duration of the task was about 24 minutes, leading to a total of about 30 minutes including breaks.

## **2.4. Data Acquisition**

EEG was recorded continuously during the two sessions from 128 active electrodes mounted on an elastic cap (10-20 International system Electro-Cap Inc) with an Active Two Biosemi system (Biosemi, Amsterdam, the Netherlands. According to constructor guidelines, all electrode offsets were kept below 20 mV. Two additional electrodes were used to monitor eye movements and blinks (one placed at lateral canthi and one below the eyes). Continuous EEG was digitized at 512 Hz and filtered offline (1-20 Hz) using EEGLAB software (Delorme & Makeig, 2004) and recalculated to linked mastoid reference. ICA-based artifact correction was used in order to correct blink artifacts (Delorme, Sejnowski, & Makeig, 2007)<sup>1</sup>.

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<sup>1</sup> A relatively restrictive bandpass filter of 1-20Hz was applied with regard to the ICA-based artifact correction used. While the ICA procedure allows saving trials

1 Epochs consisting of 200 ms pre-stimulus and 800 ms post stimulus were processed  
2 separately for each stimulus condition in the two tasks. Epochs contaminated by  
3 muscular contractions or an excessive deflection ( $\pm 75 \mu\text{V}$ ) were detected by a visual  
4 inspection of the data, and excluded from the averaged ERP waveforms (i.e., on  
5 average 5.1% of trials). Individual subject ERPs were computed on all remaining  
6 trials for each condition (about 80 trials), using the 200 ms pre-stimulus as baseline.  
7 In order to generalize results to the items used, a secondary averaging was performed  
8 by computing individual item ERPs for each condition (about 110 trials). Based on  
9 visual inspection of the scalp map distribution averaged for the 4 conditions (2 Action  
10 Types  $\times$  2 Display Types) in the 2 tasks, we collapsed ERPs across 8, 11 and 12  
11 electrodes to represent maximal left and right posterior activity respectively for P100,  
12 N170 and P3b. A similar procedure was adopted for P3a and N400, where maximal  
13 anterior activity was represented by the average signal across 12 and 25 electrodes,  
14 respectively (see Figure 2 for more detail about ROI definition).  
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41 Mean Peak Amplitude for each component was computed by averaging the  
42 signal according to a window centered on the maximum peak. Maximum peak was  
43 determined using the mean signal (irrespective of task, subject, region and stimuli  
44 presentation). In order to adapt mean amplitude computation to the shape of each  
45 component, window size was 20 ms (10 ms on both sides of the maximum peak) for  
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54 contaminated by blink artifacts (and thus computing ERPs based on a maximum of  
55 trials), it is very sensitive to linear drifts and results in poor decomposition when  
56 linear drifts are present in the raw data (Debener, Thorne, Schneider, & Campos  
57 Viola, 2010). Thus, a 1Hz filter was required to remove linear drifts before applying  
58 the ICA procedure.  
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1 P100 and N170 components, 60 ms for P3a component and 100 ms for P3b and N400  
2 components. The percentage of individual peaks contained in each time window was  
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4 74% for P100, 42% for N170, 74% for P3a, and 68% for P3b.  
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7 In order to localize the regions specifically involved in the generation of each  
8 component, we performed a Low-Resolution Electromagnetic Tomography  
9 (sLORETA; Pascual-Marqui, 2002) on the ERP waveforms at each time window. In  
10 this study, an improved version of this algorithm was used (called sLORETA) on the  
11 group data independently for each of the 4 stimuli conditions (2 Action Types  $\times$  2  
12 Display Types). Images of electric neuronal activity were derived from the surface  
13 electrodes using a three-shell spherical head model. Current source densities were  
14 estimated from these images for each of the 6,430 voxels in the MNI space (Montreal  
15 Neurological Institute), each voxel representing 5 mm<sup>3</sup> of brain tissue. The procedure  
16 was used to provide additional information about the possible sources of the ERP  
17 differences observed. Thus, source localization maps will be presented only for ERPs  
18 that exhibit differences between action types, after controlling for their respective  
19 baseline.  
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## 41 **2.5. Data Analysis**

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44 First, although task order was counterbalanced during the experiment and was  
45 not a factor of interest, we verified that it did not have any major effect on EEG data  
46 (as witnessed by either a main effect of order or an interaction between order and  
47 task) before removing this factor from the analyses.  
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### 54 **2.5.1. Main Analysis**

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57 In order to directly highlight the components that differ in the visual  
58 processing of the two Action Types while controlling for potential differences in  
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1 motion quantity between stimuli, we conducted analyses on the signal difference  
2 between Normal and Transformed Display Types for each ERP component. With this  
3 procedure, the variables Action Types (ORA and NORA) and Display Types (Normal  
4 and Transformed) were replaced by a single variable: Action Type Corrected  
5 (ORAc = ORA Normal – ORA Transformed, and NORAc = NORA Normal – NORA  
6 Transformed). Thus, a Task (Explicit vs. Implicit) × ROI (Right vs. Left) × Action  
7 Type Corrected (NORAc vs. ORAc) Analysis of Variance (ANOVA) was computed  
8 on the Mean Peak Amplitude of P100, N170 and P3b components. Similarly, a Task  
9 (Explicit vs. Implicit) × Action Type Corrected (NORAc vs. ORAc) ANOVA was  
10 computed on the Mean Peak Amplitude of P3a and N400 components. Finally,  
11 planned comparisons were used to directly contrast the effect of the two action types  
12 (NORAc vs. ORAc) on response amplitude in each task and/or region of interest.  
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29 If differences in visual processing of object-related and non-object-related  
30 actions do exist, we should observe a main effect of Action Type Corrected, or an  
31 interaction between Action Type Corrected and Task and/or ROI, on the Mean Peak  
32 Amplitude of at least one ERP component. In particular, we expected differences on  
33 relatively late ERPs components (after 250 ms) devoted to higher-level visuo-  
34 semantic processing.  
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### 43 **2.5.2. Complementary Analysis**

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Secondarily, we ran analyses on Mean Peak Amplitude of P100, N170, P3a, P3b, and N400 components while keeping Action Type and Display Type variables separated. This was done in order to evaluate potential effects that were not of primary interest, but that could provide further information for the interpretation of effects tested in the main analysis. In particular, effects of Action Type (Object-Related vs. Non-Object-Related) regardless of Display Type (both Normal and

1 Transformed) could inform about low-level visual differences between object-related  
2 and non-object-related actions.  
3

4 Thus, a Task (Explicit vs. Implicit)  $\times$  ROI (Right vs. Left)  $\times$  Action Type  
5 (NORA vs. ORA)  $\times$  Display Type (Normal vs. Transformed) ANOVA was conducted  
6 on the Mean Peak Amplitude of P100, N170 and P3b components. Similarly, a Task  
7 (Explicit vs. Implicit)  $\times$  Action Type (NORA vs. ORA)  $\times$  Display Type (Normal vs.  
8 Transformed) ANOVA was computed on the Mean Peak Amplitude of P3a and N400  
9 components. Finally, response amplitudes for the two action types were directly  
10 contrasted using planned comparisons.  
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### 24 **3. RESULTS**

25 Main results are presented in Figure 3. Below are presented the results of the analyses  
26 on the individual subject ERPs (variability between subjects). Note that the same  
27 pattern of results is visible in the analysis on individual item ERPs (variability  
28 between items, all significant p-values < .05).  
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#### 39 **3.1. Main results**

##### 40 *3.1.1. P100 and N170 component (20ms)*

41 The ANOVA did not show any main effect of Action Type Corrected on  
42 Mean Peak Amplitude of the P100 and N170 components (all  $F < 1$ ). Furthermore,  
43 Action Type Corrected did not interact with Task on Mean Peak Amplitude of the  
44 P100 component, alone or combined with Region (respectively  $F_{1,18} = 1.371$ ;  $p =$   
45  $0.257$  and  $F_{1,18} = 1.295$ ;  $p = 0.27$ ). Similarly, results were non-significant on Mean  
46 Peak Amplitude of the N170 component (respectively  $F_{1,18} = 2.594$ ;  $p = 0.125$  and  
47  $F_{1,18} = 2.01$ ;  $p = 0.173$  for interaction with Task alone or with Task and Region)  
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### 3.1.2. P3a component (60ms)

The ANOVA revealed a significant main effect of Action Type Corrected on Mean Peak Amplitude of the P3a component ( $F_{1,18} = 10.63; p < 0.01$ ). Specifically, P3a amplitude was greater when participants perceived Object-Related Actions compared to Non-Object-Related Actions, and this difference could not be attributed to low-level differences between stimuli (Figure 3a and 3b). Besides, Action Type Corrected did not interact with Task on Mean Peak Amplitude of the P3a component ( $F < 1$ ).

-----< Insert Figure 3 about here >-----

### 3.1.3. P3b (100 ms)

The ANOVA showed a marginal Region  $\times$  Action Type Corrected interaction on Mean Peak Amplitude of the P3b component ( $F_{1,18} = 4.18; p = 0.056$ ). However, pairwise comparisons did not reveal any significant difference between ORAc and NORAc stimuli in the left ( $t_{18} = -0.32, p = 0.75$ ) or in the right posterior ROI ( $t_{18} = 0.84, p = 0.41$ ). Furthermore, Action Type Corrected did not interact with Task on Mean Peak Amplitude of the P3b component, alone or combined with Region (respectively  $F_{1,18} = 0.23; p = 0.64$  and  $F_{1,18} = 0.588; p = 0.453$ ).

### 3.1.4. N400 (100 ms)

The ANOVA did not highlight any main effect of Action Type Corrected on Mean Peak Amplitude of the N400 component ( $F < 1$ ). Furthermore, Action Type Corrected did not interact with Task on Mean Peak Amplitude of the N400

component ( $F_{1,18} = 2.75$ ;  $p = 0.115$ ).

## 3.2. Complementary Results

### 3.2.1. Action Type effects

When Action Type and Display Type were considered separately, a main effect of Action Type was observed on Mean Peak Amplitude of the N170 and P3a components (respectively  $F_{1,18} = 7.032$ ;  $p < 0.05$  and  $F_{1,18} = 16.88$ ;  $p < 0.001$ ). Mean Peak Amplitude of the N170 component was significantly greater when participants perceived Object-Related Actions compared to Non-Object-Related Actions, independently of Display Type (both Normal and Transformed), Region or Task.

In a similar line, there was a significant Region  $\times$  Action Type interaction on Mean Peak Amplitude of the P100 and P3b components (respectively  $F_{1,18} = 11.82$ ;  $p < 0.01$  and  $F_{1,18} = 6.59$ ;  $p < 0.05$ ). For the P100 component, planned comparisons showed that ORA P100 amplitude was greater than NORA P100 amplitude in the right ( $t_{18} = 2.58$ ,  $p < 0.05$ ), but not in the left posterior ROI ( $t_{18} = -0.18$ ,  $p = 0.85$ ). For P3b, the reverse pattern of results was observed: ORA P3b amplitude was smaller than NORA P3b amplitude in the left ( $t_{18} = -2.53$ ,  $p < 0.05$ ), but not in the right posterior ROI ( $t_{18} = -0.92$ ,  $p = 0.37$ ).

### 3.2.2. Task effects

A main effect of Task was visible on the Mean Peak Amplitude of the P3a and N400 components ( $F_{(1,18)} = 10.42$ ;  $p < 0.05$  and  $F_{(1,18)} = 6.39$ ;  $p < 0.05$ , respectively). Results showed that Mean Peak Amplitude of the P3a component was greater when the task involved an implicit semantic processing compared to an explicit one. Inversely, Mean Peak Amplitude of the N400 component was greater when the task involved an explicit semantic processing compared to an implicit one.

### 3.3. Source Visualization

Probable sources of the P3a component in the different conditions using sLORETA are displayed in Figure 3c. As shown by Figure 3c, P3a probable source generator computed with sLORETA software was identified within a large fronto-temporo-parietal network. However, visual inspection of the probable sources for the two action types and their respective control baselines suggests relative fine differences between P3a sources across conditions. Indeed, the most probable source for non-object related actions is observed in the left inferior frontal cortex (around BA 44), whereas the most probable source for object-related actions is situated in the left parietal cortex (around BA 40).

### 4. DISCUSSION

The main goal of the present work was to investigate whether transitive (object-related) and intransitive (non-object-related) gestures relied on distinct cognitive and neural mechanisms. Based on the assumption that regardless of gesture type, action execution and observation neural circuits largely overlap in several regions of the fronto-parietal cortex (for review, see Caspers et al., 2010; Rizzolatti & Craighero, 2004 but see Hickok & Hauser, 2010; Kalénine et al., 2010; Mahon & Caramazza, 2008 for nuances), we evaluated to what extent object-related or non-object-related actions involved distinct processes within this network using perceptual tasks. Thanks to the high temporal resolution of EEG/ERP recordings, we were able to identify temporal differences in the perception of the two action types at the neural level. The main results revealed a significant difference between object-related and non-object-related action perception on the amplitude of the P3a component. Perception of point-light displays depicting object-related actions lead to a greater P3a

1 response than perception of point-light displays depicting non-object-related actions.  
2 In the following section, we will argue that the differences observed between the two  
3 action types do not only reflect differences in low-level visual features or attentional  
4 processes, but rather suggest that object-related actions involved the additional  
5 mobilization of some object features. The exact nature of the features recruited will be  
6 debated, and additional arguments from source localization results will be presented.  
7 Finally, the incidental character of object motor feature activation will be discussed  
8 according to the pattern of task-related effects observed.  
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#### 22 **4.1. Differences between Object-Related and Non-Object-Related Action** 23 **perception cannot be explained by low-level visual features**

24 The main difference between Object-Related and Non-Object-Related Actions  
25 was observed after comparison with baseline conditions that controlled for low-level  
26 visual differences between stimuli, such as the amount of movement information.  
27 Thus, we are fairly confident that the neural difference observed during action  
28 processing does not simply reflect potential differences in visual complexity between  
29 object-related and non-object-related actions, an alternative hypothesis that could not  
30 have been ruled out in previous studies (Agnew et al., 2012; Villarreal et al., 2008).  
31 Discrepancies between studies are probably due to differences in the stimuli used.  
32 Indeed, in our study object-related and non-object related actions only differed on the  
33 existence of a relation between action kinematics and object use. Conversely, the  
34 contrast between object-related and non-object-related actions overlapped with the  
35 distinction between meaningful and meaningless gestures in Agnew et al. (2012), and  
36 with the difference between symbolic and non-symbolic gestures in Villarreal et al.  
37 (2008). Yet, our results are in line with theoretical developments arguing that object-  
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1 related and non-object-related actions are supported by distinct processes (Haaland et  
2 al., 2000; Ham et al., 2010; Rapcsak et al., 1993; Roy et al., 1991).  
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4 Additional results highlighted direct differences between the two action types  
5 (before subtraction with baseline) on several ERP components (P100, N170, P3a and  
6 P3b). Direct differences between action types were expected in the case of low-level  
7 physical differences between stimuli. Indeed, our data showed that the mean peak  
8 amplitude of the N170 component evoked by object-related actions was significantly  
9 greater than the one evoked by non-object-related actions. A similar pattern of results  
10 was also present for the P100 component, but only in the right posterior region.  
11 Sensitivity of early ERP components to whole-body movements has already been  
12 investigated (Hirai et al., 2003, 2005; Hirai & Hiraki, 2006; Jokisch et al., 2005; Virji-  
13 Babul, Cheung, Weeks, Kerns, & Shiffrar, 2007). Classically, the positive component  
14 observed at occipital sites around 100-130 ms after stimulus presentation (P100) is  
15 associated with form-processing mechanisms (Bach & Ullrich, 1997; Jokisch et al.,  
16 2005), whereas the negativity occurring closely after around 150-300 ms after  
17 stimulus presentation (called N170 or N200) is supposed to represent motion  
18 processing (Hirai et al., 2003; 2005, 2006; Jokisch et al., 2005). Thus, the effect  
19 observed on the P100 could reflect physical differences in our stimuli, in particular in  
20 the number of points presented and/or their spatial configuration in the first frame.  
21 The effect observed on the later components (N170 and P3b) could be related to  
22 motion quantity differences between the two action types. Overall, point-light  
23 displays representing non-object-related actions involved more body segments than  
24 object-related actions, implying difference in quantity of points in motion. Even if all  
25 stimuli depicted biological kinematics, subtle motion quantity differences likely  
26 impacted components involved in motion processing occurring between 150 and  
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300 ms (Hirai et al., 2003; 2005, 2006; Jokisch et al., 2005).

In sum, by contrasting action types before and after subtraction with the appropriate baseline, it was possible to disentangle the effects related to low-level stimulus differences between the two action types (observed on P100 and N170) from the effects related to differences in early semantic processing (observed on P3a).

#### **4.2. Differences between Object-Related and Non-Object-Related Action perception are not driven by the sample of intransitive actions used**

The goal of the present study was to contrast ORA and NORA as a whole, without further clustering of non-object-related actions. Therefore, a wide range of NORA was selected, irrespective of the limb(s) involved, the symbolic aspect, the action valence, etc. (see stimulus list in Appendix 1). Nonetheless, one could object that differences between ORA and NORA are driven by a subtype of NORA exemplars. In order to verify that this is not the case, we conducted a complementary by-item analysis, i.e. averaging the ERPs over participants and considering variability between items. The same results were visible in the by-item analysis, confirming that the results can be generalized to all NORA and ORA items. Future studies may further evaluate the existence of ERP differences on P3a component between various ORA and NORA subtypes.

#### **4.3. Differences between Object-Related and Non-Object-Related Actions are not likely related to variations in attentional resource allocation**

In the attentional literature, the P3a component is classically related to the “oddball” effect (Kok, 2001; Picton, 1992; Polich, 2007). In the oddball paradigm, a deviant stimulus presented in a homogeneous series causes an important increase of

1 P3a amplitude around 300 ms after stimulus onset. Deviance can apply to a wide  
2 range of stimulus characteristics such as novelty, salience, semantic incongruence,  
3 etc. In our study, the only potentially deviant stimuli were the target stimuli to be  
4 detected (i.e. red-point PLD or hammering [a nail] action) for which manual  
5 responses were recorded, and data excluded. In addition, PLD in the two action type  
6 conditions were submitted to the same number of repetitions, leading to equally  
7 homogeneous series. Thus, P3a differences do not reasonably reflect variations in  
8 deviance detection here.  
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19 More generally, P300 has been associated to resource allocation, processing  
20 capacity and task difficulty (Kok, 2001; Picton, 1992; Polich, 2007). One could argue  
21 that object-related actions are more complex to identify at the basic level (e.g. sawing,  
22 drinking from a cup, etc.) than non-object-related actions and consequently, that their  
23 recognition require more processing capacities, as reflected by stronger P3a  
24 involvement. Even if our normative experiment showed that semantic categorization  
25 was equivalent between the two action types in terms of difficulty, action naming was  
26 not involved, like in the EEG experiment. Thus, basic-level action identification was  
27 not directly tested. Moreover, although participants named all actions before the EEG  
28 experiment, we cannot exclude the possibility that basic-level identification remained  
29 easier for one category compared to the other after familiarization. During the EEG  
30 experiment, participants might have engaged in such basic-level identification when  
31 performing the specific action recognition task (“detecting the hammering [a nail]  
32 action”), which may have put more load on the attentional system. Yet similar P3a  
33 differences between action types were observed in the Red Point Detection Task,  
34 where semantic processing was not required at all. It is always possible that  
35 participants implicitly performed basic-level action identification while detecting the  
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1 color change in the stimuli, but this hypothesis remains relatively unlikely,  
2 considering its additional cognitive cost.  
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#### 7 **4.4. Differences between action types on the P3a component possibly** 8 **reflect mobilization of object motor features** 9

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11 Activation of object motor features during perception of static object pictures  
12 was the focus of a recent EEG study (Proverbio, Adorni, & D’Aniello, 2011).  
13 Proverbio and collaborators reported differences in brain activity during perception of  
14 manipulable and non-manipulable objects starting from 210-270 ms after stimulus  
15 onset (component referred to as “anterior negativity”) and continuing at 550-600 ms  
16 (component referred to as “P300”). In both time windows, they observed a larger  
17 response, particularly in the left hemisphere, when participants perceived objects  
18 associated with a specific action manipulation (e.g. hammer, screwdriver or keyboard  
19 for instance), as compared to less manipulable objects (e.g. carpet or piece of pottery).  
20 Interestingly, the difference we observed during perception of object-related and non-  
21 object-related actions became visible in the 200-300 ms time window. Thus, object  
22 manipulability and action transitivity seem to influence brain activity with a similar  
23 timing, suggesting that both situations involve the recruitment of additional object  
24 motor features.  
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45 The findings reported here strongly suggest that object-related and non object-  
46 related action processing differs at the neural level. However, the difference was  
47 observed during action observation and any generalization to action performance  
48 must be cautious. Although there is important evidence that regardless of gesture  
49 type, action execution and observation neural circuits largely overlap in several  
50 regions of the fronto-parietal cortex (for review, see Caspers, Zilles, Laird, &  
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1 Eickhoff, 2010; Rizzolatti & Sinigaglia, 2010), neural circuits are not fully equivalent  
2 and we might not observe the same exact processes at play when executing object-  
3 related and non-object related actions (Hickok & Hauser, 2010; Kalénine, Buxbaum,  
4 & Coslett, 2010; Mahon & Caramazza, 2008). As mentioned earlier, one challenge to  
5 assess this hypothesis is to find a way to execute object-related actions without  
6 involving objects or pantomimes.  
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14 Another remaining issue concerns the nature of the specific knowledge  
15 recruited. While the result pattern strongly suggests that the neural difference  
16 observed between the two action types reflects the additional involvement of object  
17 features, it is also possible that they activate different body-part representations.  
18 Indeed, NORA may involve whole-body representations more frequently, whereas  
19 ORA are tool-use actions that are tied to hand representations. Several studies suggest  
20 that action and body representations (and in particular tool-use gestures and hand  
21 representations) recruit very similar brain areas within the motor system (Buxbaum  
22 & Saffran, 2002; Carota, Moseley, & Pulvermüller, 2012; Hauk, Johnsrude, &  
23 Pulvermüller, 2004; Tettamanti et al., 2005). Our paradigm does not allow  
24 distinguishing between body-related and gesture-related representations. Thus, ORA  
25 may involve both object-related and hand-related representations to a greater extent  
26 than NORA. Moreover, motor features may not be the only part of object knowledge  
27 activated during ORA observation. Other object features, such as object shape or  
28 object function, may also be recruited. The difference in the probable source of the  
29 EEG response to the two action types might provide additional discussion elements to  
30 this issue.  
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#### 58 **4.5. Probable sources of EEG responses suggest differences between** 59 60 61 62 63 64 65

## **object-and non-object-related-action processing within the fronto-parietal network**

As shown by Figure 3c, a large fronto-temporo-parietal network seems to be recruited during action observation independently from action characteristics. However, a subset of probable sources would be specific to the action type considered. Qualitatively, comparing the probable sources of the two action types with their respective controls suggests that the left inferior frontal cortex (around BA 44) is the most probable source for non-object related actions, whereas the left parietal cortex (around BA 40) would be the most probable source for object-related actions. These two regions are considered important parts of the visuo-motor system and have already been highlighted as critically involved in action recognition (Kalénine et al., 2010; Pazzaglia et al., 2008). In our study, activation of the visuo-motor system during visual perception of actions was expected, even if actions were summarized by point lights in motion (Perry, Troje, & Bentin, 2010; Saygin, Wilson, Hagler, Bates, & Sereno, 2004; Ulloa & Pineda, 2007). As suggested by Saygin and collaborators, the recruitment of the visuo-motor system during perception of simplified stimuli such as PLD allowed participants to “fill in” or to reconstruct the meaning of the impoverished visual input.

The presence of a left parietal source in the case of object-related action processing, which was not visible during non-object related action processing, is particularly interesting. The left parietal cortex is an important region of the visuo-motor system and a critical part of the dorsal stream (Milner & Goodale, 1995; Ungerleider & Mishkin, 1982). Within the dorsal stream, a specific pathway has been recently identified for planning actions based on conceptual representations, i.e. the dorso-ventral stream (Buxbaum & Kalénine, 2010; Pisella, Binkofski, Lasek, Toni, &

1 Rossetti, 2006; Rizzolatti & Matelli, 2003). The probable source of the P3a response  
2 for object-related actions seems to cover most part of the left inferior parietal cortex, a  
3 key area of the dorso-ventral pathway that would support gesture representations.  
4 Thus, results from the source localization are compatible with the hypothesis that  
5 object-related action perception involves additional activation of object motor  
6 features, alone or in combination with other parts of object knowledge.  
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#### 17 **4.6. Object knowledge recruitment during object-related action** 18 **processing is incidental** 19

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21 Another important result is the fact that we observed a difference between  
22 action types on the P3a component independently from the implicit or explicit  
23 character of the semantic processing induced by the task. Nevertheless, we observed a  
24 main effect of Task on the P3a and N400 components indicating that overall, the  
25 amplitude of these components significantly differed between implicit and explicit  
26 semantic processing. The influence of the type of task on these late components – and  
27 not on earlier components– reinforces the idea that P3a and N400 components reflect  
28 high-level (semantic) action processing.  
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41 There was no interaction between Task and Action Type Corrected factors on  
42 the mean amplitude of the P3a component. Thus, it seems that the recruitment of  
43 object knowledge during PLD action processing is incidental and does not require  
44 explicit action recognition. Based on lesion studies, Pisella and colleagues (2006)  
45 have already suggested that activation of the distributed network likely supporting  
46 tool knowledge (concentrated in the left hemisphere) should be observed  
47 independently from the modality of stimulus presentation (image, word presented  
48 visually or auditory) and/or to task (object naming, object-action matching task,  
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1 passive object perception). All happens as if independently of the task required,  
2 object-related actions automatically activated associated object knowledge.  
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#### 8 **4.7. Conclusion** 9

10 The present study highlights neural activity differences between perception of  
11 object-related and non-object-related actions. Using the high temporal resolution of  
12 EEG recordings, we could identify that the difference occurred around 250 ms after  
13 onset of action visual processing, and that it was probably related to a differential  
14 recruitment of fronto-parietal regions. This result cannot be explained by low-level  
15 visual feature differences between action types and is not likely related to variations  
16 in attentional resource allocation. Instead, the ERP difference possibly reflects  
17 incidental activation of object knowledge in the case of object-related actions.  
18 Although results are compatible with the activation of object motor features during  
19 action perception, the issue of the exact nature of the attributes recruited remains for  
20 further research.  
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44 program FEDER SCV-IrDIVE. Authors thank the 37 volunteers for their participation  
45 in the study and Yann Coello for precious comments on the experiment design.  
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## 7. APPENDICES

### Appendix 1: Complete List of the actions used

Object-Related Action (ORA)	Non-Object-Related Actions (NORA)
Putting a hat on	Walking
Turning on the light	Running
Opening the tap	Jumping
Fishing with fishing rod	Hopping
Pulling a suitcase	Jumping with legs apart
Using a pan	Walking on all fours
Color with coloured pencil	Sitting
Sawing	Standing up
Screwing	Crouching down
Drinking from a cup	Kneeling down
Applying toothpaste	Climbing on a step
Putting a necklace on	Dancing
Playing with a ball	Praying
Drinking from a bowl	Saying hello
Watering with watering can	Beckoning by waving arms
Hammering [a nail]	

## Appendix 2:

### Normative experiment:

As briefly presented in the Method section, a normative experiment was used in order to collect a behavioral measure of processing difficulty for each point-light-display (PLD) stimulus. Seventeen participants (who did not take part in the EEG experiment) were submitted to the same familiarization session as in the EEG experiment. One ambidextrous participant was removed from the final analysis. Then, participants performed a meaningful/meaningless discrimination task on the 30 critical Object-Related and Non-Object-Related actions mixed with the 15 transformed meaningless actions. Each action was presented once or twice (counterbalanced between participants) to minimize strategies based on action identity predictability since participants were familiarized with PLD movies beforehand. However, only data obtained from PLD first occurrence were analyzed. The ratio between meaningful and meaningless expected responses was 3/1.

On each trial, the PLD was presented during 1 second and participants had to decide whether the action presented had signification or not. Participants responded by pressing with their finger on two distinct response keys (mapping between response keys and meaningful/meaningless decisions was counterbalanced between participants). Accuracy and reaction times to identify whether the action conveyed meaning or not were assumed to reflect item relative semantic processing difficulty. These measures were used to detect potential outlier items in each condition. The duration of the task was about 4 minutes.

## 8. FIGURE CAPTIONS

**Figure 1:** Static frame examples of the movies used in the 4 conditions (2 Action Types  $\times$  2 Display Types): Object-related actions in normal orientation (in the left upper part of the table: here sawing), its equivalent without signification (left lower part); Non-object-related actions in normal orientation (in the right upper part of the table: Beckoning by waving arms) and its equivalent without signification (right lower part).

**Figure 2:** Regions of Interest (ROI) defined on basis of the scalp map distribution for each ERP component. Thus, two ROIs were considered for P100, N170 and P3b analyses and only one for P3a and N400.

**Figure 3:** (a) Event-Related Potentials evoked by the visual presentation of the 4 movie types (2 Action Types [ORA vs NORA]  $\times$  2 Display Types [Normal vs Transformed]) under anterior ROI (A1/D1/D2/C1/C2/C11/C12/C21/C22/C23/C24 and C25 electrodes); (b) Amplitude of P3a components for object and non-object related actions computed on a 60 ms time window centered on the averaged P3a peak, after subtraction with their corresponding baseline (ORAc, NORAc); (c) sLORETA inverse solution applied to P3a activity (60ms time window centered on the averaged P3a peak) for each movie type.

Figure1

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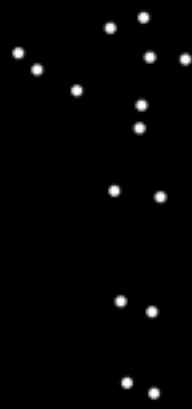

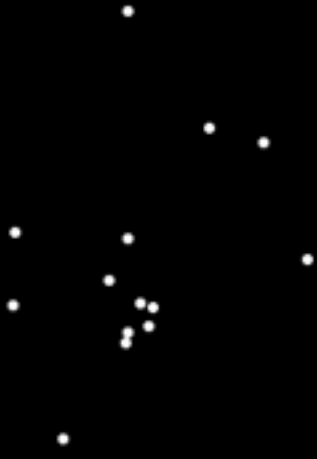
	Object-Related Action	Non-Object-Related Action
Experimental conditions (ORA, NORA)		
Control conditions (ORAt, NORAt)		

Figure2

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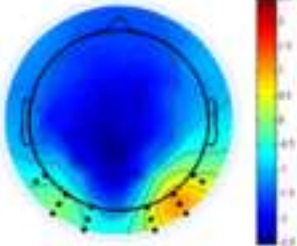
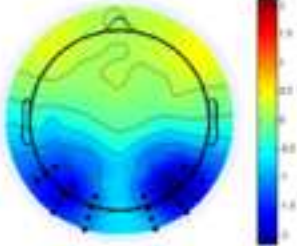
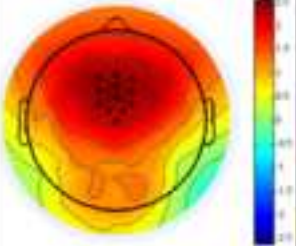
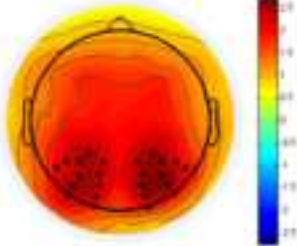
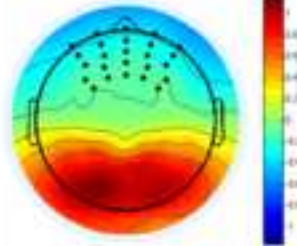
Component	P100	N170	P3a	P3b	N400
Latency	120-150ms	180-220ms	200-300ms	275-400ms	400-600ms
Scalp map distribution					
Electrodes collapsed for each ROI	<p>Left: D31-D32-A10-A11 A12-A13-A14-A15</p> <p>Right: A26-A27-A28-B7 B8-B9-B10-B11</p>	<p>Left: D30-D31-D32-A9 A10-A11-A12-A13 A14-A15-A16</p> <p>Right: A26-A27-A28-A29 B6-B7-B8-B9-B10 B11-B12</p>	<p>Anterior: A1-D1-D2-C1-C2 C11-C12-C21-C22 C23-C24-C25</p>	<p>Left: A5-A6-A7-A8-A9 A10-A15-A16-A17 A18-D29-D30</p> <p>Right: A28-A29-A30-A31 A32-B3-B4-B5-B6 B7-B11-B12</p>	<p>Anterior: C2-C4-C8-C9-C10 C12-C13-C14-C15 C16-C17-C18-C19 C20-C21-C25-C26 C27-C28-C29-C30 C31-C32-D3-D4</p>

Figure3  
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