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On a Monotone Dynamic Approach to Optimal Stopping Problems for Continuous-Time Markov Chains

Laurent Miclo* and Stéphane Villeneuve†

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Abstract

This paper is concerned with the solution of the optimal stopping problem associated to the valuation of Perpetual American options driven by continuous time Markov chains. We introduce a new dynamic approach for the numerical pricing of this type of American options where the main idea is to build a monotone sequence of almost excessive functions that are associated to hitting times of explicit sets. Under minimal assumptions about the payoff and the Markov chain, we prove that the value function of an American option is characterized by the limit of this monotone sequence.

Keywords: Markov chains, Optimal Stopping, American option pricing

1 Introduction

Optimal stopping problems have received a lot of attention in the literature on stochastic control since the seminal work of Wald [16] about sequential analysis while the most recent application of optimal stopping problems have emerged from mathematical finance with the valuation of American options and the theory of real options, see e.g. [12] and [5]. The first general result of optimal stopping theory for stochastic processes was obtained in discrete time by Snell [14] who characterized the value function of an optimal stopping problem as the least excessive function that is a majorant of the reward. For a survey of optimal stopping theory for Markov processes, see the book by Shiryaev [13]. Theoretical and numerical aspects of the valuation of American options have been the subject of numerous articles in many different models including discrete-time Markov chains (see e.g. [3],[10]), time-homogenous diffusions (see e.g. [4]) and Lévy processes (see e.g. [11]) . Following the recent study by Eriksson and Pistorius [?], this paper is concerned with optimal stopping problems in the setting of a continuous-time Markov chain. This class of processes, which contains the classic birth-death process, have recently been introduced in finance to model the state of the order book, see [1]. Assuming a uniform integrability condition for the payoff function, Eriksson and Pistorius [7] have shown that the value of an optimal stopping problem for a continuous-time Markov chain can be characterized as the unique solution to a system of variational inequalities. Furthermore, when the state space of the underlying Markov chain is a subset of \mathbb{R} and when the stopping region is assumed to be an interval, their paper provides an algorithm to compute the value

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function.

Our approach is different and relies on a monotone recursive construction of both the value function and the stopping region along a sequence of almost excessive functions build along the hitting times of explicit sets. Using the Snell characterization of the value function as the smallest excessive majorant of the payoff function has been already the idea of the two papers [9] and [2] in the one-dimensional diffusion case where upper bounds of the value function are build using linear programming. The main advantage of the monotone approach developed here, is that it converges to the value with minimal assumptions about the continuous-time Markov chain and the payoff function. In particular, we abandon the uniform integrability condition while the state space is not necessary a subset of the set of real numbers. Such an approach gives a constructive method of finding the value function and seems to be designed for computational methods. It is fair to notice however, that this procedure may give the exact value of the value function only after infinite number of steps. A practical exception is given when considering the case of Markov chains with finite number of states where the resulting algorithm resembles the elimination algorithm proposed in [15] and thus converges in a finite number of steps.

2 Formulation of the problem

On a countable state space V endowed with the discrete topology, we consider a Markov generator $\mathcal{L} := (L(x, y))_{x, y \in V}$, that is an infinite matrix whose entries are real numbers satisfying

$$\begin{aligned} \forall x \neq y \in V, \quad L(x, y) &\geq 0 \\ \forall x \in V, \quad L(x, x) &= - \sum_{y \neq x} L(x, y) \end{aligned}$$

We define $L(x) = -L(x, x)$ and assume that $L(x) < +\infty$ for every $x \in V$.

For any probability measure m on V , let us associate to L a Markov process $X := (X_t)_{t \geq 0}$ defined on some probability space $(\Omega, \mathcal{G}, \mathbb{P})$ whose initial distribution is m . First we set $\sigma_0 := 0$ and X_0 is sampled according to m . Then we consider an exponential random variable σ_1 of parameter $L(X_0) := -L(X_0, X_0)$. If $L(X_0) = 0$, we have a.s. $\sigma_1 = +\infty$ and we take $X_t := X_0$ for all $t > 0$, as well as $\sigma_n := +\infty$ for all $n \in \mathbb{N}, n \geq 2$. If $L(X_0) > 0$, we take $X_t := X_0$ for all $t \in (0, \sigma_1)$ and we sample X_{σ_1} on $V \setminus \{X_0\}$ according to the probability distribution $L(X_0, \cdot) / L(X_0)$. Next, still in the case where $\sigma_1 < +\infty$, we sample an inter-time $\sigma_2 - \sigma_1$ as an exponential distribution of parameter $L(X_{\sigma_1})$. If $L(X_{\sigma_1}) = 0$, we have a.s. $\sigma_2 = +\infty$ and we take $X_t := X_{\sigma_1}$ for all $t \in [\sigma_1, +\infty)$, as well as $\sigma_n := +\infty$ for all $n \in \mathbb{N}, n \geq 3$. If $L(X_{\sigma_1}) > 0$, we take $X_t := X_{\sigma_1}$ for all $t \in [\sigma_1, \sigma_2)$ and we sample X_{σ_2} on $V \setminus \{X_{\sigma_1}\}$ according to the probability distribution $(L(X_{\sigma_1}, \cdot) / L(X_{\sigma_1}))_{x \in V \setminus \{X_{\sigma_1}\}}$. We keep on following the same procedure, where all the ingredients are independent, except for the explicitly mentioned dependences.

In particular, we get a non-decreasing family $(\sigma_n)_{n \in \mathbb{Z}_+}$ of jump times taking values in $\bar{\mathbb{R}}_+ := \mathbb{R}_+ \sqcup \{+\infty\}$. Denote the corresponding exploding time

$$\sigma_\infty := \lim_{n \rightarrow \infty} \sigma_n \in \bar{\mathbb{R}}_+$$

When $\sigma_\infty < +\infty$, we must still define X_t for $t \geq \sigma_\infty$. So introduce Δ a cemetery point not belonging to V and denote $\bar{V} := V \sqcup \{\Delta\}$. \bar{V} is seen as the Alexandrov compactification of V . We take $X_t := \Delta$ for all $t \geq \sigma_\infty$ to get a \bar{V} -valued Markov process X . Let $(\mathcal{G}_t)_{t \geq 0}$ be the completed right-continuous filtration

generated by $X := (X_t)_{t \geq 0}$ and let \mathcal{F} (resp. $\bar{\mathcal{F}}_+$) be the set of functions defined on V taking values in \mathbb{R}_+ (resp. $\bar{\mathbb{R}}_+ := \mathbb{R}_+ \sqcup \{+\infty\}$). The generator L acts on \mathcal{F} via

$$\begin{aligned} \forall f \in \mathcal{F}, \forall x \in V, \quad \mathcal{L}[f](x) &:= \sum_{y \in V} L(x, y) f(y) \\ &= \sum_{y \in V \setminus \{x\}} L(x, y) (f(y) - f(x)). \end{aligned}$$

We would like to extend this action on $\bar{\mathcal{F}}_+$, but since its elements are allowed to take the value $+\infty$, it leads to artificial conventions such as $(+\infty) - (+\infty) = 0$. The only reasonable convention is $0 \times (+\infty) = 0$, so let us introduce \mathcal{K} , the infinite matrix whose diagonal entries are zero and which is coinciding with \mathcal{L} outside the diagonal. Its interest is that \mathcal{K} acts obviously on $\bar{\mathcal{F}}_+$ through

$$\forall f \in \bar{\mathcal{F}}_+, \forall x \in V, \quad \mathcal{K}[f](x) := \sum_{y \in V \setminus \{x\}} L(x, y) f(y) \in \bar{\mathbb{R}}_+. \quad (2.1)$$

In this paper, we will consider an optimal stopping problem with payoff $e^{-rt} \phi(X_t)$, where $\phi \in \bar{\mathcal{F}}_+$ and $r > 0$, given by

$$u(x) := \sup_{\tau \in \mathcal{T}} \mathbb{E}_x[e^{-r\tau} \phi(X_\tau)], \quad (2.2)$$

where \mathcal{T} is a set of \mathcal{G}_t -adapted stopping times and where the x in index of the expectation indicates that X starts from $x \in V$. A stopping time τ^* is said to be optimal for u if

$$u(x) = \mathbb{E}_x(e^{-r\tau^*} \phi(X_{\tau^*})).$$

Observe that with our convention, we have $e^{-r\tau} \phi(X_\tau) = 0$ on the set $\{\tau = +\infty\}$.

There are two questions to be solved in connection with Definition (2.2). The first question is to value the function u while the second is to find an optimal stopping time τ^* . Note that optimal stopping times may not exist (see [13] Example 5 p.61). According to the general optimal stopping theory, an optimal stopping time, if it exists, is related to the set

$$D = \{x \in V : u(x) = \phi(x)\} \quad (2.3)$$

called the stopping region. In particular, when ϕ satisfies the uniform integrability condition

$$\mathbb{E}_x \left[\sup_{t \geq 0} e^{-rt} \phi(X_t) \right] < \infty,$$

the stopping time $\tau_D = \inf\{t \geq 0, X_t \in D\}$ is optimal if for all $x \in V, \mathbb{P}_x(\tau_D < \infty) = 1$ (see Shiryaev [13] Theorem 4 p.52).

The main objective of this paper is to provide a recursive construction of both the value function u and the stopping region D without assuming the uniform integrability condition. However, to present the idea of the monotone dynamic approach developed in this paper, Section 3 first consider the case of a finite state space V for which the uniform integrability condition is obviously satisfied. Section 4 is devoted to the general case. Section 5 revisits an example of optimal stopping with random intervention times.

3 Finite state space

On a finite set V , the payoff function is bounded and thus the value function u defined by (2.2) is well-defined for every $x \in V$. Moreover, it is well-known (see [13], Theorem 3) that the value function u is the minimal r -excessive function which dominates ϕ . Recall that a function f is r -excessive if $0 \geq \mathcal{L}[f] - rf$. Moreover, on the set $\{u > \phi\}$, u satisfies $\mathcal{L}[u](x) - ru(x) = 0$. Because of the finiteness of V , the process

$$e^{-rt}f(X_t) - f(x) - \int_0^t e^{-rs} (\mathcal{L}[f] - rf)(X_s) ds$$

is a \mathcal{G}_t -martingale under \mathbb{P}_x for every function f defined on V and every $x \in V$ which yields by taking expectations, the so-called Dynkin's formula.

We first establish some properties of the stopping region \mathcal{D} . Let us introduce the set

$$\mathcal{D}_1 := \{x \in V, \mathcal{L}[\phi](x) - r\phi(x) \leq 0\}$$

and assume that $\phi(x_0) > 0$ for some $x_0 \in V$. We recall that a Markov process X is said to be irreducible if for all $x, y \in V \times V$, $\mathbb{P}_x(T_y < +\infty) > 0$ where

$$T_y := \inf\{t \geq 0, X_t = y\}.$$

Lemma 1. *We have the inclusion $\mathcal{D} \subset \mathcal{D}_1$ and when we assume furthermore that X is irreducible, we have $\mathcal{D} \subset \{x \in V, \phi(x) > 0\}$.*

Proof. Because u is r -excessive, we have for all $x \in \mathcal{D}$,

$$\begin{aligned} 0 &\geq \mathcal{L}[u](x) - ru(x) \\ &= \sum_{y \neq x} L(x, y)u(y) - (r + L(x))\phi(x) \quad \text{because } x \in \mathcal{D} \\ &\geq \sum_{y \neq x} L(x, y)\phi(y) - (r + L(x))\phi(x) \quad \text{because } u \geq \phi \\ &= \mathcal{L}[\phi](x) - r\phi(x). \end{aligned}$$

Therefore, $x \in \mathcal{D}_1$.

For the second inclusion, let T_{x_0} be the first time X hits x_0 . We have for all $x \in V$, and every $t \geq 0$,

$$\begin{aligned} u(x) &\geq \mathbb{E}_x[e^{-r(T_{x_0} \wedge t)} \phi(X_{T_{x_0} \wedge t})] \\ &= \phi(x_0) \mathbb{E}_x[e^{-rT_{x_0}} \mathbb{1}_{T_{x_0} \leq t}] + \mathbb{E}_x[e^{-rt} \phi(X_t) \mathbb{1}_{T_{x_0} \geq t}] \end{aligned}$$

Letting t tend to $+\infty$, we obtain because ϕ is bounded on the finite state space V

$$u(x) \geq \phi(x_0) \mathbb{E}_x[e^{-rT_{x_0}} \mathbb{1}_{T_{x_0} < +\infty}] > 0$$

where the last strict inequality follows from the fact that X is irreducible. □

Now, we introduce u_1 as the value associated to the stopping strategy *Stop the first time X enters in \mathcal{D}_1* . Formally, let us define

$$\tau_1 := \inf\{t \geq 0 : X_t \in \mathcal{D}_1\}$$

and

$$u_1(x) := \mathbb{E}_x[e^{-r\tau_1}\phi(X_{\tau_1})\mathbb{1}_{\tau_1 < +\infty}]$$

Clearly $u \geq u_1$ by Definition (2.2). Moreover, we have $u_1 = \phi$ on \mathcal{D}_1 .

Lemma 2. *We have*

- $\forall x \notin \mathcal{D}_1, u_1(x) > \phi(x)$ and $\mathcal{L}[u_1](x) - ru_1(x) = 0$.
- $\forall x \in \mathcal{D}, \mathcal{L}[u_1](x) - ru_1(x) \leq 0$.

Proof. Let $x \notin \mathcal{D}_1$. Applying the Optional Sampling theorem to the bounded martingale

$$M_t = e^{-rt}\phi(X_t) - \phi(x) - \int_0^t e^{-rs}(\mathcal{L}[\phi] - r\phi)(X_s) ds,$$

we have,

$$\begin{aligned} u_1(x) &= \mathbb{E}_x[e^{-r\tau_1}\phi(X_{\tau_1})] \\ &= \phi(x) + \mathbb{E}_x \left[\int_0^{\tau_1} e^{-rs}(L[\phi](X_s) - r\phi(X_s)) ds \right] \\ &> \phi(x), \end{aligned}$$

because $L[\phi](y) - r\phi(y) > 0$ for $y \notin \mathcal{D}_1$. Moreover, for $x \notin \mathcal{D}_1$, $\tau_1 \geq \sigma_1$ almost surely. Thus, the Strong Markov property yields

$$\begin{aligned} u_1(x) &= \mathbb{E}_x[e^{-r\tau_1}\phi(X_{\tau_1})] \\ &= \mathbb{E}_x[e^{-r\sigma_1}u_1(X_{\sigma_1})] \\ &= \frac{\mathcal{L}[u_1](x) + L(x)u_1(x)}{r + L(x)}, \end{aligned}$$

from which we deduce $\mathcal{L}[u_1](x) - ru_1(x) = 0$.

Because u is r -excessive, we have for all $x \in \mathcal{D}$,

$$\begin{aligned} 0 &\geq \mathcal{L}[u](x) - ru(x) \\ &= \sum_{y \in V} L(x, y)u(y) - r\phi(x) \quad \text{because } x \in \mathcal{D} \\ &\geq \sum_{y \neq x} L(x, y)u_1(y) - (r + L(x))\phi(x) \\ &= \mathcal{L}[u_1](x) - ru_1(x) \quad \text{because } \mathcal{D} \subset \mathcal{D}_1. \end{aligned}$$

□

To start the recursive construction, we introduce the set

$$\mathcal{D}_2 := \{x \in \mathcal{D}_1, \mathcal{L}[u_1](x) - ru_1(x) \leq 0\}$$

and the function

$$u_2(x) := \mathbb{E}_x[e^{-r\tau_2}\phi(X_{\tau_2})\mathbb{1}_{\tau_2 < +\infty}]$$

where

$$\tau_2 := \inf\{t \geq 0 : X_t \in \mathcal{D}_2\}$$

Observe that if $\mathcal{D}_2 = \mathcal{D}_1$, u_1 is a r -excessive majorant of ϕ and therefore $u_1 \geq u$. Because the reverse inequality holds by definition, the procedure stops.

By induction, we shall define a sequence (u_n, \mathcal{D}_n) for $n \in \mathbb{Z}_+$ starting from (u_1, \mathcal{D}_1) by

$$\mathcal{D}_{n+1} := \{x \in \mathcal{D}_n, \mathcal{L}[u_n](x) - ru_n(x) \leq 0\}$$

and

$$u_{n+1}(x) := \mathbb{E}_x[e^{-r\tau_{n+1}}\phi(X_{\tau_{n+1}})\mathbb{1}_{\tau_{n+1} < +\infty}]$$

where

$$\tau_{n+1} := \inf\{t \geq 0 : X_t \in \mathcal{D}_{n+1}\}.$$

Next lemma proves a key monotonicity result.

Lemma 3. *We have $u_{n+1} \geq u_n$ and $\forall x \notin \mathcal{D}_{n+1}, u_{n+1}(x) > \phi(x)$.*

Proof. To start the induction, we assume using Lemma 2 that u_n satisfies

$$\forall x \in V \setminus \mathcal{D}_n, \mathcal{L}[u_n](x) - ru_n(x) = 0 \text{ and } u_n(x) > \phi(x) \quad (3.1)$$

$$\forall x \in \mathcal{D}_n, u_n(x) = \phi(x). \quad (3.2)$$

For $x \in \mathcal{D}_{n+1} \subset \mathcal{D}_n$, we have $u_{n+1}(x) = \phi(x) = u_n(x)$. On the other hand, for $x \notin \mathcal{D}_{n+1}$, we have

$$\begin{aligned} u_{n+1}(x) &= \mathbb{E}_x[e^{-r\tau_{n+1}}\phi(X_{\tau_{n+1}})\mathbb{1}_{\tau_{n+1} < +\infty}] \\ &= \mathbb{E}_x[e^{-r\tau_{n+1}}u_n(X_{\tau_{n+1}})\mathbb{1}_{\tau_{n+1} < +\infty}] \quad \text{because } \mathcal{D}_{n+1} \subset \mathcal{D}_n \\ &= u_n(x) + \mathbb{E}_x \left[\int_0^{\tau_{n+1}} e^{-rs} (\mathcal{L}[u_n](X_s) - ru_n(X_s)) ds \right] \\ &\geq u_n(x), \end{aligned}$$

because $\mathcal{L}[u_n] - u_n \geq 0$ outside \mathcal{D}_{n+1} .

Let $x \notin \mathcal{D}_{n+1}$. If $x \notin \mathcal{D}_n$, we have $u_n(x) > \phi(x)$ and thus $u_{n+1}(x) > \phi(x)$. Now, let $x \in \mathcal{D}_n \cap \mathcal{D}_{n+1}^c$ and let us define

$$\hat{\tau} := \inf\{t \geq 0, X_t \notin \mathcal{D}_n \cap \mathcal{D}_{n+1}^c\}.$$

Clearly, $\hat{\tau} \leq \tau_{n+1}$. Therefore by the Strong Markov property,

$$\begin{aligned} u_{n+1}(x) &= \mathbb{E}_x[e^{-r\hat{\tau}}u_{n+1}(X_{\hat{\tau}})\mathbb{1}_{\hat{\tau} < +\infty}] \\ &\geq \mathbb{E}_x[e^{-r\hat{\tau}}u_n(X_{\hat{\tau}})\mathbb{1}_{\hat{\tau} < +\infty}] \\ &> u_n(x), \end{aligned}$$

because $\mathcal{L}[u_n] - u_n > 0$ on the set $\mathcal{D}_n \cap \mathcal{D}_{n+1}^c$. □

According to Lemma 3, the sequence $(u_n)_n$ is increasing and satisfies $u_n \geq \phi$ with strict inequality outside \mathcal{D}_n , while by construction, the sequence $(\mathcal{D}_n)_n$ is decreasing. It follows that we can define a function u_∞ on V by

$$u_\infty(x) = \lim_{n \rightarrow \infty} u_n(x)$$

and a set by

$$\mathcal{D}_\infty := \bigcap_{n \in \mathbb{Z}_+} \mathcal{D}_n.$$

We are in a position to state our first result.

Theorem 4. *We have $u_\infty = u$ and $\mathcal{D}_\infty = D$.*

Proof. By definition, $u \geq u_n$ for every $n \in \mathbb{Z}_+$ and thus passing to the limit, we have $u \geq u_\infty$. To show the reverse inequality, we first notice that for every $n \in \mathbb{Z}_+$, we have $u_n \geq \phi$ and thus $u_\infty \geq \phi$.

If $x \in \mathcal{D}_\infty$ then $x \in \mathcal{D}_{n+1}$ for every $n \in \mathbb{Z}_+$ and thus $\mathcal{L}[u_n](x) - ru_n(x) \leq 0$ for every $n \in \mathbb{Z}_+$. Passing to the limit, we obtain

$$\mathcal{L}[u_\infty](x) - ru_\infty(x) \leq 0 \quad \forall x \in \mathcal{D}_\infty.$$

If $x \notin \mathcal{D}_\infty$ then there is some n_0 such that $x \notin \mathcal{D}_n$ for $n \geq n_0$. Thus, for such a $n \geq n_0$, we have

$$\mathcal{L}[u_n](x) - ru_n(x) = 0.$$

Passing to the limit, we obtain

$$\mathcal{L}[u_\infty](x) - ru_\infty(x) = 0 \quad \forall x \notin \mathcal{D}_\infty.$$

To conclude, we observe that because for every $x \in V$, we have $\mathcal{L}[u_\infty](x) - ru_\infty(x) \leq 0$, we have for every stopping time τ

$$u_\infty(x) \geq \mathbb{E}[e^{-r\tau} u_\infty(X_\tau)],$$

from which we deduce that

$$u_\infty(x) \geq \mathbb{E}[e^{-r\tau} \phi(X_\tau)], \tag{3.3}$$

because $u_\infty \geq \phi$. Taking the supremum over τ at the right-hand side of (3.3), we obtain $u_\infty \geq u$.

Equality $u = u_\infty$ implies that $\mathcal{D}_\infty \subset \mathcal{D}$. To show the reverse inclusion, let $x \notin \mathcal{D}_\infty$ which means that $x \notin \mathcal{D}_n$ for n larger than some n_0 . Lemma 3 yields that $u_n(x) > \phi(x)$ for $n \geq n_0$ and because u_n is increasing, we deduce that $u_\infty(x) > \phi(x)$ for $x \notin \mathcal{D}_\infty$ which concludes the proof. \square

Remark 5. *Because V is finite, the sequence $(u_n)_n$ is constant after some $n_0 \leq \text{card}(V)$ and therefore the procedure stops after at most $\text{card}(V)$ steps.*

Example 6. *Let $(X_t)_{t \geq 0}$ be a birth-death process on the set of integers $V_N = \{-N, \dots, N\}$ stopped the first time it hits $-N$ or N . We define for $x \in V_N \setminus \{-N, N\}$,*

$$\begin{cases} L(x, x+1) &= \lambda \geq 0, \\ L(x, x-1) &= \mu \geq 0, \\ L(x) &= \lambda + \mu, \end{cases}$$

and $L(-N) = L(N) = 0$. We define $\phi(x) = \max(x, 0)$ as the reward function.

Clearly, $u(-N) = 0 = \phi(-N)$ and $u(N) = N = \phi(N)$ thus the stopping region contains the extreme points $\{-N, N\}$. We define

$$\mathcal{D}_1 := \{x \in V_N, \mathcal{L}[\phi](x) - r\phi(x) \leq 0\}.$$

A direct computation shows that $\mathcal{L}[\phi](x) - r\phi(x) = 0$ for $-N + 1 \leq x \leq -1$, $\mathcal{L}[\phi](0) - r\phi(0) = \lambda$ and $\mathcal{L}[\phi](x) - r\phi(x) = \lambda - \mu - rx$ for $1 \leq x \leq N - 1$. Therefore,

$$\mathcal{D}_1 = \{-N, -N + 1, \dots, -1\} \cup \{x_1, \dots, N\},$$

with $x_1 = \lceil \frac{\lambda - \mu}{r} \rceil$, where $\lceil x \rceil$ is the least integer greater than or equal to x . In particular, when $\lambda \leq \mu$, we have $x_1 = 0$ and thus $\mathcal{D}_1 = V_N = \mathcal{D}$. Assume now that $\lambda > \mu$. To start the induction, we define

$$\tau_1 := \inf\{t \geq 0 : X_t \in \mathcal{D}_1\}$$

and

$$u_1(x) := \mathbb{E}_x[e^{-r\tau_1}\phi(X_{\tau_1})\mathbb{1}_{\tau_1 < +\infty}]$$

and we construct u_1 by solving for $0 \leq x \leq x_1 - 1$, the linear equation

$$\lambda u_1(x + 1) + \mu u_1(x - 1) - (r + \lambda + \mu)u_1(x) = 0 \text{ with } u_1(-1) = 0 \text{ and } u_1(x_1) = x_1.$$

The function u_1 is thus explicit and denoting

$$\Delta := (r + \lambda + \mu)^2 - 4\lambda\mu > 0,$$

$$\theta_1 = \frac{r + \lambda + \mu - \sqrt{\Delta}}{2\lambda} \text{ and } \theta_2 = \frac{r + \lambda + \mu + \sqrt{\Delta}}{2\lambda},$$

we have

$$u_1(x) = x_1 \frac{\theta_2^{x+1} - \theta_1^{x+1}}{\theta_2^{x_1+1} - \theta_1^{x_1+1}}.$$

Observe that $\theta_2 + \theta_1 > 0$ and thus $\mathcal{L}[u_1](-1) - ru_1(-1) = \lambda u_1(0) > 0$. As a consequence, -1 does not belong to the set

$$\mathcal{D}_2 = \{x \in \mathcal{D}_1, \mathcal{L}[u_1](x) - ru_1(x) \leq 0\}.$$

Therefore, if $\mathcal{L}[u_1](x_1) - ru_1(x_1) = \mu u_1(x_1 - 1) + \lambda - (r + \mu)x_1 \leq 0$, we have

$$\mathcal{D}_2 = \{-N, -N + 1, \dots, -2\} \cup \{x_1, \dots, N\},$$

or, if $\mathcal{L}[u_1](x_1) - ru_1(x_1) = \mu u_1(x_1 - 1) + \lambda - (r + \mu)x_1 > 0$

$$\mathcal{D}_2 = \{-N, -N + 1, \dots, -2\} \cup \{x_1 + 1, \dots, N\}.$$

Following our recursive procedure, after N steps, we shall have eliminated the negative integers and thus obtain

$$\mathcal{D}_N = \{-N\} \cup \{x_N, \dots, N\}$$

for some $x_1 \leq x_N \leq N$. Note that for $-N \leq x \leq x_N$, we have

$$u_N(x) = x_N \frac{\theta_2^{x+N} - \theta_1^{x+N}}{\theta_2^{x_N+N} - \theta_1^{x_N+N}}.$$

If $\lambda u_N(x_n + 1) + \mu u_N(x_N - 1) - (r + \lambda + \mu)u_N(x_N) = \lambda - (r + \mu)x_N + \mu x_N \frac{\theta_2^{x_N-1+N} - \theta_1^{x_N-1+N}}{\theta_2^{x_N+N} - \theta_1^{x_N+N}} \leq 0$, the stopping region coincides with \mathcal{D}_N , else we define

$$\mathcal{D}_{N+1} = \{-N\} \cup \{x_{N+1}, \dots, N\}, \text{ with } x_{N+1} = x_N + 1$$

and

$$u_{N+1}(x) = x_{N+1} \frac{\theta_2^{x+N} - \theta_1^{x+N}}{\theta_2^{x_{N+1}+N} - \theta_1^{x_{N+1}+N}}$$

and we repeat the procedure.

4 General state space

4.1 Countable State Space

When considering countable finite state space, Dynkin's formula that has been used in the proofs of Lemma 2 and 3 is not directly available, because nothing prevents the payoff to take arbitrarily large values. Nevertheless, we will adapt the strategy used in the case of a finite state space to build a monotone dynamic approach of the value function in the case of a countable finite state space.

Hereafter, we set some payoff function $\phi \in \bar{\mathcal{F}}_+ \setminus \{0\}$ and $r > 0$. We will construct a subset $D_\infty \subset V$ and a function $u_\infty \in \bar{\mathcal{F}}_+$ by the following recursive algorithm.

We begin by taking $D_0 := V$ and $u_0 := \phi$. Next, let us assume that $D_n \subset V$ and $u_n \in \bar{\mathcal{F}}_+$ have been built for some $n \in \mathbb{Z}_+$ such that

$$\forall x \in V \setminus D_n, \quad (r + L(x))u_n(x) = \mathcal{K}[u_n](x) \tag{4.1}$$

$$\forall x \in D_n, \quad u_n(x) = \phi(x). \tag{4.2}$$

Observe that it is trivially true for $n = 0$. Then, we define the subset D_{n+1} as follows

$$D_{n+1} := \{x \in D_n : \mathcal{K}[u_n](x) \leq (r + L(x))u_n(x)\} \tag{4.3}$$

where the inequality is understood in $\bar{\mathbb{R}}_+$.

Next, we consider the stopping time

$$\tau_{n+1} := \inf\{t \geq 0 : X_t \in D_{n+1}\}$$

with the usual convention that $\inf \emptyset = +\infty$. For $m \in \mathbb{Z}_+$, define furthermore the stopping time

$$\tau_{n+1}^{(m)} := \sigma_m \wedge \tau_{n+1}$$

and the function $u_{n+1}^{(m)} \in \bar{\mathcal{F}}_+$ given by

$$\forall x \in V, \quad u_{n+1}^{(m)}(x) := \mathbb{E}_x[\exp(-r\tau_{n+1}^{(m)})u_n(X_{\tau_{n+1}^{(m)}})]. \quad (4.4)$$

Remark 7. *The non-negative random variable $\exp(-r\tau_{n+1}^{(m)})u_n(X_{\tau_{n+1}^{(m)}})$ is well-defined, even if $\tau_{n+1}^{(m)} = +\infty$, since the convention $0 \times (+\infty) = 0$ imposes that $\exp(-r\tau_{n+1}^{(m)})u_n(X_{\tau_{n+1}^{(m)}}) = 0$ whatever would be $X_{\tau_{n+1}^{(m)}}$, which is not defined in this case. The occurrence of $\tau_{n+1}^{(m)} = +\infty$ should be quite exceptional: we have*

$$\{\tau_{n+1}^{(m)} = +\infty\} = \{\tau_{n+1} = +\infty \text{ and } L(X_{\tau_{n+1}}) = 0\}$$

in particular it never happens if $L(x) > 0$ for all $x \in V$, i.e. when Δ is the only possible absorbing point for X .

Our first result shows that the sequence $(u_{n+1}^{(m)})_{m \in \mathbb{Z}_+}$ is non-decreasing.

Lemma 8. *We have*

$$\forall m \in \mathbb{Z}_+, \forall x \in V, \quad u_{n+1}^{(m)}(x) \leq u_{n+1}^{(m+1)}(x)$$

Proof. We first compute

$$\begin{aligned} u_{n+1}^{(m+1)}(x) &:= \mathbb{E}_x[\exp(-r\tau_{n+1}^{(m+1)})u_n(X_{\tau_{n+1}^{(m+1)}})] \\ &= \mathbb{E}_x[\mathbf{1}_{\tau_{n+1} \leq \sigma_m} \exp(-r\tau_{n+1}^{(m+1)})u_n(X_{\tau_{n+1}^{(m+1)}})] + \mathbb{E}_x[\mathbf{1}_{\tau_{n+1} > \sigma_m} \exp(-r\tau_{n+1}^{(m+1)})u_n(X_{\tau_{n+1}^{(m+1)}})] \end{aligned}$$

Note that on the event $\{\tau_{n+1} \leq \sigma_m\}$, we have that $\tau_{n+1}^{(m+1)} = \tau_{n+1} = \tau_{n+1}^{(m)}$, so the first term in the above r.h.s. is equal to

$$\mathbb{E}_x[\mathbf{1}_{\tau_{n+1} \leq \sigma_m} \exp(-r\tau_{n+1}^{(m+1)})u_n(X_{\tau_{n+1}^{(m+1)}})] = \mathbb{E}_x[\mathbf{1}_{\tau_{n+1} \leq \sigma_m} \exp(-r\tau_{n+1}^{(m)})u_n(X_{\tau_{n+1}^{(m)}})] \quad (4.5)$$

On the event $\{\tau_{n+1} > \sigma_m\}$, we have that $\tau_{n+1}^{(m+1)} = \tau_{n+1}^{(m)} + \sigma_1 \circ \theta_{\tau_{n+1}^{(m)}}$, where θ_t , for $t \geq 0$, is the shift operator by time $t \geq 0$ on the underlying canonical probability space $\mathbb{D}(\mathbb{R}_+, \bar{V})$ of c \tilde{A} dl \tilde{A} g trajectories. Using the Strong Markov property of X , we get that

$$\mathbb{E}_x[\mathbf{1}_{\tau_{n+1} > \sigma_m} \exp(-r\tau_{n+1}^{(m+1)})u_n(X_{\tau_{n+1}^{(m+1)}})] = \mathbb{E}_x \left[\mathbf{1}_{\tau_{n+1} > \sigma_m} \exp(-r\tau_{n+1}^{(m)}) \mathbb{E}_{X_{\tau_{n+1}^{(m)}}} [\exp(-r\sigma_1)u_n(X_{\sigma_1})] \right] \quad (4.6)$$

For $y \in V$, consider two situations:

- if $L(y) = 0$, we have a.s. $\sigma_1 = +\infty$ and as in Remark 7, we get

$$\mathbb{E}_y[\exp(-r\sigma_1)u_n(X_{\sigma_1})] = 0$$

- if $L(y) > 0$, we compute, in $\bar{\mathbb{R}}_+$,

$$\begin{aligned}
\mathbb{E}_y[\exp(-r\sigma_1)u_n(X_{\sigma_1})] &= \int_0^{+\infty} \exp(-rs)L(y) \exp(-L(y)s) \sum_{z \in V \setminus \{y\}} \frac{L(y,z)}{L(y)} u_n(z) \\
&= \int_0^{+\infty} \exp(-rs) \exp(-L(y)s) \sum_{z \in V \setminus \{y\}} L(y,z) u_n(z) \\
&= \frac{1}{r + L(y)} \mathcal{K}[u_n](y)
\end{aligned}$$

By our conventions, the equality

$$\mathbb{E}_y[\exp(-r\sigma_1)u_n(X_{\sigma_1})] = \frac{1}{r + L(y)} \mathcal{K}[u_n](y) \quad (4.7)$$

is then true for all $y \in V$.

For $y \in D_n$, due to (4.1), the r.h.s. is equal to $u_n(y)$. For $y \in D_n \setminus D_{n+1}$, by definition of D_{n+1} in (4.3), the r.h.s. of (4.7) is bounded below by $u_n(y)$. It follows that for any $y \notin D_{n+1}$,

$$\mathbb{E}_y[\exp(-r\sigma_1)u_n(X_{\sigma_1})] \geq u_n(y)$$

On the event $\{\tau_{n+1} > \sigma_m\}$, we have $X_{\tau_{n+1}}^{(m)} \notin D_{n+1}$ and thus

$$\mathbb{E}_{X_{\tau_{n+1}}^{(m)}}[\exp(-r\sigma_1)u_n(X_{\sigma_1})] \geq u_n(X_{\tau_{n+1}}^{(m)})$$

Coming back to (4.6), we deduce that

$$\mathbb{E}_x[\mathbf{1}_{\tau_{n+1} > \sigma_m} \exp(-r\tau_{n+1}^{(m+1)})u_n(X_{\tau_{n+1}^{(m+1)}})] \geq \mathbb{E}_x[\mathbf{1}_{\tau_{n+1} > \sigma_m} \exp(-r\tau_{n+1}^{(m)})u_n(X_{\tau_{n+1}^{(m)}})]$$

and taking into account (4.5), we conclude that

$$\begin{aligned}
u_{n+1}^{(m+1)}(x) &\geq \mathbb{E}_x[\mathbf{1}_{\tau_{n+1} \leq \sigma_m} \exp(-r\tau_{n+1}^{(m)})u_n(X_{\tau_{n+1}^{(m)}})] + \mathbb{E}_x[\mathbf{1}_{\tau_{n+1} > \sigma_m} \exp(-r\tau_{n+1}^{(m)})u_n(X_{\tau_{n+1}^{(m)}})] \\
&= \mathbb{E}_x[\exp(-r\tau_{n+1}^{(m)})u_n(X_{\tau_{n+1}^{(m)}})] \\
&= u_{n+1}^{(m)}(x)
\end{aligned}$$

□

The monotonicity property of Lemma 8 enables us to define the function $u_{n+1} \in \bar{\mathcal{F}}_+$ via

$$\forall x \in V, \quad u_{n+1}(x) := \lim_{m \rightarrow \infty} u_{n+1}^{(m)}(x)$$

ending the iterative construction of the pair (D_{n+1}, u_{n+1}) from (D_n, u_n) . It remains to check that:

Lemma 9. *The assertion (4.1) is satisfied with n replaced by $n + 1$.*

Proof. Consider $x \in V \setminus D_{n+1}$ for which $\tau_{n+1}^{(m+1)} \geq \sigma_1$, \mathbb{P}_x a. s.. For the Markov process X starting from x , we have for any $m \in \mathbb{Z}_+$,

$$\tau_{n+1}^{(m+1)} = \sigma_1 + \tau_{n+1}^{(m)} \circ \sigma_1$$

The Strong Markov property of X then implies that

$$\begin{aligned} u_{n+1}^{(m+1)}(x) &= \mathbb{E}_x \left[\exp(-r\sigma_1) \mathbb{E}_{X_{\sigma_1}} [\exp(-r\tau_{n+1}^{(m)}) u_n(X_{\tau_{n+1}^{(m)}})] \right] \\ &= \mathbb{E}_x \left[\exp(-r\sigma_1) u_{n+1}^{(m)}(X_{\sigma_1}) \right] \\ &= \frac{1}{r + L(x)} \mathcal{K}[u_{n+1}^{(m)}](x) \end{aligned}$$

by resorting again to the computations of the proof of Lemma 8. Monotone convergence insures that

$$\lim_{m \rightarrow \infty} \mathcal{K}[u_{n+1}^{(m)}](x) = \mathcal{K}[u_{n+1}](x)$$

so we get that for $x \in V \setminus D_{n+1}$,

$$(r + L(x))u_{n+1}(x) = \mathcal{K}[u_{n+1}](x)$$

as wanted. □

The sequence $(D_n)_{n \in \mathbb{Z}_+}$ is non-increasing by definition, as a consequence we can define

$$D_\infty := \bigcap_{n \in \mathbb{Z}_+} D_n$$

From Lemma 8, we deduce that for any $n \in \mathbb{Z}_+$,

$$\begin{aligned} \forall x \in V, \quad u_{n+1}(x) &\geq u_{n+1}^{(0)}(x) \\ &= u_n(x) \end{aligned}$$

It follows that we can define the function $u_\infty \in \bar{\mathcal{F}}_+$ as the non-decreasing limit

$$\forall x \in V, \quad u_\infty(x) = \lim_{n \rightarrow \infty} u_n(x) \in \bar{\mathbb{R}}_+$$

The next two propositions establish noticeable properties of the pair (D_∞, u_∞) :

Proposition 10. *We have:*

$$\begin{aligned} \forall x \in D_\infty, \quad &\begin{cases} u_\infty(x) = \phi(x) \\ \mathcal{K}[u_\infty](x) \leq (r + L(x))u_\infty(x) \end{cases} \\ \forall x \in V \setminus D_\infty, \quad &\begin{cases} u_\infty(x) \geq \phi(x) \\ \mathcal{K}[u_\infty](x) = (r + L(x))u_\infty(x) \end{cases} \end{aligned}$$

Proof. Since $u_0 = \phi$, the fact that $(u_n)_{n \in \mathbb{Z}_+}$ is a non-decreasing sequence implies that $u_\infty \geq \phi$. To show there is an equality on D_∞ , it is sufficient to show that

$$\forall n \in \mathbb{Z}_+, \forall x \in D_n, \quad u_n(x) = \phi(x)$$

This is proven by an iterative argument on $n \in \mathbb{Z}_+$. For $n = 0$, it corresponds to the equality $u_0 = \phi$. Assume that $u_n = \phi$ on D_n , for some $n \in \mathbb{Z}_+$. For $x \in D_{n+1}$, we have $\tau_{n+1} = 0$ and thus for any $m \in \mathbb{Z}_+$, we get $\tau_{n+1}^{(m)} = 0$. From (4.4), we deduce that

$$\forall x \in D_{n+1}, \quad u_{n+1}^{(m)} = u_n(x) = \phi(x)$$

Letting m go to infinity, it yields that $u_{n+1} = \phi$ on D_{n+1} .

Consider $x \in V \setminus D_\infty$. There exists $N(x) \in \mathbb{Z}_+$ such that for any $n \geq N(x)$, we have $x \in V \setminus D_n$. Then passing at the limit for large n in (4.1), we get, via another use of monotone convergence, that

$$\forall x \in V \setminus D_\infty, \quad (r + L(x))u_\infty(x) = \mathcal{K}[u_\infty](x)$$

For $x \in D_\infty$, we have $x \in D_{n+1}$ for any $n \in \mathbb{Z}_+$ and thus from (4.3), we have $\mathcal{K}[u_n](x) \leq (r + L(x))u_n(x)$. Letting n go to infinity, we deduce that

$$\forall x \in D_\infty, \quad \mathcal{K}[u_\infty](x) \leq (r + L(x))u_\infty(x)$$

□

In fact, u_∞ is a strict majorant of ϕ on $V \setminus D_\infty$ as proved in the following

Proposition 11. *We have*

$$\forall x \in V \setminus D_\infty, \quad u_\infty(x) > \phi(x)$$

It follows that

$$D_\infty = \{x \in V : u_\infty(x) = \phi(x)\}$$

Proof. Consider $x \in V \setminus D_\infty$, there exists a first integer $n \in \mathbb{Z}_+$ such that $x \in D_n$ and $x \notin D_{n+1}$. From (4.1) and $x \in V \setminus D_{n+1}$, we deduce that

$$\mathcal{K}[u_{n+1}](x) = (r + L(x))u_{n+1}(x)$$

From (4.3) and $x \in V \setminus D_{n+1}$, we get

$$\mathcal{K}[u_n](x) > (r + L(x))u_n(x)$$

Putting together these two inequalities and the fact that $\mathcal{K}[u_{n+1}] \geq \mathcal{K}[u_n]$, we end up with

$$(r + L(x))u_{n+1}(x) > (r + L(x))u_n(x)$$

which implies that

$$\begin{aligned} \phi(x) &\leq u_n(x) \\ &< u_{n+1}(x) \\ &\leq u_\infty(x) \end{aligned}$$

namely $\phi(x) < u_\infty(x)$.

This argument shows that

$$\{x \in V : u_\infty(x) = \phi(x)\} \subset D_\infty$$

The reverse inclusion is deduced from Proposition 10. \square

Another formulation of the functions u_n , for $n \in \mathbb{N}$, will be very useful for the characterization of their limit u_∞ . For $n, m \in \mathbb{Z}_+$, let us modify Definition (4.4) to define a function $\tilde{u}_{n+1}^{(m)}$ as

$$\forall x \in V, \quad \tilde{u}_{n+1}^{(m)}(x) := \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m)}) \phi(X_{\tau_{n+1}^{(m)}}) \right] \quad (4.8)$$

A priori there is no monotonicity with respect to m , so we define

$$\forall x \in V, \quad \tilde{u}_{n+1}(x) := \liminf_{m \rightarrow \infty} \tilde{u}_{n+1}^{(m)}(x)$$

A key observation is:

Lemma 12. *For any $n \in \mathbb{N}$, we have $\tilde{u}_n = u_n$.*

Proof. Since for any $n \in \mathbb{Z}_+$, we have $u_n \geq \phi$, we get from a direct comparison between (4.4) and (4.8) that for any $m \in \mathbb{Z}_+$, $\tilde{u}_{n+1}^{(m)} \leq u_{n+1}^{(m)}$, so letting m go to infinity, we deduce that

$$\tilde{u}_{n+1} \leq u_{n+1} \quad (4.9)$$

The reverse inequality is proven by an iteration over n .

More precisely, since $u_0 = \phi$, we get by definition that $\tilde{u}_1 = u_1$.

Assume that the equality $\tilde{u}_n = u_n$ is true for some $n \in \mathbb{N}$, and let us show that $\tilde{u}_{n+1} = u_{n+1}$. For any $m \in \mathbb{Z}_+$, we have

$$\begin{aligned} \forall x \in V, \quad u_{n+1}^{(m)}(x) &= \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m)}) u_n(X_{\tau_{n+1}^{(m)}}) \right] \\ &= \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m)}) \tilde{u}_n(X_{\tau_{n+1}^{(m)}}) \right] \\ &= \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m)}) \liminf_{l \rightarrow \infty} \tilde{u}_n^{(l)}(X_{\tau_{n+1}^{(m)}}) \right] \\ &\leq \liminf_{l \rightarrow \infty} \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m)}) \tilde{u}_n^{(l)}(X_{\tau_{n+1}^{(m)}}) \right] \end{aligned}$$

where we used Fatou's lemma. From (4.8) and the Strong Markov property, we deduce that

$$\begin{aligned} \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m)}) \tilde{u}_n^{(l)}(X_{\tau_{n+1}^{(m)}}) \right] &= \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m)}) \mathbb{E}_{X_{\tau_{n+1}^{(m)}}} \left[\exp(-r\tau_{n+1}^{(l)}) \phi(X_{\tau_{n+1}^{(l)}}) \right] \right] \\ &= \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m+l)}) \phi(X_{\tau_{n+1}^{(m+l)}}) \right] \end{aligned}$$

It follows that

$$\begin{aligned} u_{n+1}^{(m)}(x) &\leq \liminf_{l \rightarrow \infty} \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m+l)}) \phi(X_{\tau_{n+1}^{(m+l)}}) \right] \\ &= \tilde{u}_{n+1}(x) \end{aligned}$$

It remains to let m go to infinity to get $u_{n+1} \leq \tilde{u}_{n+1}$ and $u_{n+1} = \tilde{u}_{n+1}$, taking into account (4.9). \square

Let \mathcal{T} be the set of $\bar{\mathbb{R}}_+$ -valued stopping times with respect to the filtration generated by X . For $\tau \in \mathcal{T}$ and $m \in \mathbb{Z}_+$, we define

$$\tau^{(m)} := \sigma_m \wedge \tau$$

Extending the observation of Remark 7, it appears that for any $m \in \mathbb{Z}_+$, the quantity

$$\forall x \in V, \quad u^{(m)}(x) := \sup_{\tau \in \mathcal{T}} \mathbb{E}_x [\exp(-r\tau^{(m)})\phi(X_{\tau^{(m)}})] \quad (4.10)$$

is well-defined in $\bar{\mathbb{R}}_+$. It is non-decreasing with respect to $m \in \mathbb{Z}_+$, since for any $\tau \in \mathcal{T}$ and any $m \in \mathbb{Z}_+$, $\tau^{(m)}$ can be written as $\tilde{\tau}^{(m+1)}$, with $\tilde{\tau} := \tau^{(m)} \in \mathcal{T}$. Thus we can define a function \hat{u} by

$$\forall x \in V, \quad \hat{u}(x) := \lim_{m \rightarrow \infty} u^{(m)}(x)$$

By definition of the value function u given by (2.2), we have $u^{(m)}(x) \leq u(x)$ for every $m \in \mathbb{Z}_+$ and thus $\hat{u}(x) \leq u(x)$ for every $x \in V$. To show the reverse inequality, consider any stopping time $\tau \in \mathcal{T}$ and apply Fatou Lemma to get

$$\begin{aligned} \mathbb{E}_x [\exp(-r\tau)\phi(X_\tau)] &= \mathbb{E}_x \left[\liminf_{m \rightarrow \infty} \exp(-r\tau^{(m)})\phi(X_{\tau^{(m)}}) \right] \\ &\leq \liminf_{m \rightarrow \infty} \mathbb{E}_x [\exp(-r\tau^{(m)})\phi(X_{\tau^{(m)}})] \\ &\leq \liminf_{m \rightarrow \infty} u^{(m)}(x) \\ &\leq \hat{u}(x). \end{aligned}$$

Therefore, the value function u coincides with the limit of the sequence $(u^{(m)})_{m \in \mathbb{Z}_+}$. At this stage, we recall the definition of the stopping region

$$D := \{x \in V : u(x) = \phi(x)\} \quad (4.11)$$

We are in a position to state our main result

Theorem 13. *We have*

$$\begin{aligned} u_\infty &= u \\ D_\infty &= D. \end{aligned}$$

Proof. It is sufficient to show that $u_\infty = u$, since $D_\infty = D$ will then follow from Proposition 11 and (4.11). We begin by proving the inequality $u_\infty \leq u$. Fix some $x \in V$. By considering in (4.10) the stopping time $\tau := \tau_{n+1}$ defined in (4.4), we get for any given $m \in \mathbb{Z}_+$,

$$\begin{aligned} u^{(m)}(x) &\geq \mathbb{E}_x \left[\exp(-r\tau_{n+1}^{(m)})\phi(X_{\tau_{n+1}^{(m)}}) \right] \\ &= \tilde{u}_{n+1}^{(m)}(x) \end{aligned}$$

considered in (4.8). Taking Lemma 12 into account, we deduce that

$$u^{(m)}(x) \geq u_{n+1}^{(m)}(x)$$

and letting m go to infinity, we get $u(x) \geq u_{n+1}(x)$. It remains to let n go to infinity to show that $u(x) \geq u_\infty(x)$.

To prove the reverse inequality $u_\infty \geq u$, we will show by induction that for every $x \in V$, every $m \in \mathbb{Z}_+$ and every $\tau \in \mathcal{T}$, we have

$$\mathbb{E}_x [\exp(-r(\sigma_m \wedge \tau)u_\infty(X_{\sigma_m \wedge \tau})] \leq u_\infty(x). \quad (4.12)$$

For $m = 1$, we have, because $u_\infty(X_\tau) = u_\infty(x)$ on the set $\{\tau < \sigma_1\}$,

$$\begin{aligned} \mathbb{E}_x [\exp(-r(\sigma_1 \wedge \tau)u_\infty(X_{\sigma_1 \wedge \tau})] &= \mathbb{E}_x [\exp(-r\sigma_1)u_\infty(X_{\sigma_1})\mathbb{1}_{\sigma_1 \leq \tau}] + \mathbb{E}_x [\exp(-r\tau)u_\infty(X_\tau)\mathbb{1}_{\tau < \sigma_1}] \\ &= \mathbb{E}_x [\exp(-r\sigma_1)u_\infty(X_{\sigma_1})\mathbb{1}_{\sigma_1 \leq \tau}] + u_\infty(x)\mathbb{E}_x [\exp(-r\tau)\mathbb{1}_{\tau < \sigma_1}] \\ &= \mathbb{E}_x [\exp(-r\sigma_1)u_\infty(X_{\sigma_1})] + u_\infty(x)\mathbb{E} [\exp(-r\tau)\mathbb{1}_{\sigma_1 > \tau}] \\ &\quad - \mathbb{E} [\exp(-r\sigma_1)u_\infty(X_{\sigma_1})\mathbb{1}_{\sigma_1 > \tau}]. \end{aligned}$$

Focusing on the third term, we observe, that on the set $\{\tau < \sigma_1\}$, we have $\sigma_1 = \tau + \hat{\sigma}_1 \circ \theta_\tau$ where $\hat{\sigma}_1$ is an exponential random variable with parameter $L(x)$ independent of τ . Therefore, the Strong Markov property yields

$$\begin{aligned} \mathbb{E} [\exp(-r\sigma_1)u_\infty(X_{\sigma_1})\mathbb{1}_{\sigma_1 > \tau}] &= \mathbb{E}_x [\exp(-r\tau)\mathbb{E}_x [\exp(-r\hat{\sigma}_1)u_\infty(X_{\hat{\sigma}_1})] \mathbb{1}_{\sigma_1 > \tau}] \\ &= \frac{\mathcal{K}[u_\infty](x)}{r + L(x)} \mathbb{E}_x [\exp(-r\tau)\mathbb{1}_{\sigma_1 > \tau}]. \end{aligned}$$

Hence,

$$\begin{aligned} \mathbb{E}_x [\exp(-r(\sigma_1 \wedge \tau)u_\infty(X_{\sigma_1 \wedge \tau})] &= \frac{\mathcal{K}[u_\infty](x)}{r + L(x)} (1 - \mathbb{E}_x [\exp(-r\tau)\mathbb{1}_{\sigma_1 > \tau}]) + u_\infty(x)\mathbb{E}_x [\exp(-r\tau)\mathbb{1}_{\sigma_1 > \tau}] \\ &\leq u_\infty(x) \end{aligned}$$

where the last inequality follows from Proposition 10. This proves the assertion for $m = 1$. Assume now that for every $x \in V$ and every $\tau \in \mathcal{T}$, we have

$$\mathbb{E}_x [\exp(-r(\sigma_m \wedge \tau)u_\infty(X_{\sigma_m \wedge \tau})] \leq u_\infty(x).$$

Observing that $\sigma_{m+1} \wedge \tau = \sigma_m \wedge \tau + (\sigma_1 \wedge \tau) \circ \theta_{\sigma_m \wedge \tau}$, we get

$$\begin{aligned} \mathbb{E}_x [\exp(-r(\sigma_{m+1} \wedge \tau)u_\infty(X_{\sigma_{m+1} \wedge \tau})] &= \mathbb{E}_x [\exp(-r(\sigma_m \wedge \tau))\mathbb{E}_{X_{\sigma_m \wedge \tau}} (\exp(-r(\sigma_1 \wedge \tau)u_\infty(X_{\sigma_1 \wedge \tau})))] \\ &\leq \mathbb{E}_x [\exp(-r(\sigma_m \wedge \tau)u_\infty(X_{\sigma_m \wedge \tau})] \\ &\leq u_\infty(x), \end{aligned}$$

which ends the argument by induction. To conclude, we take the limit at the right-hand side of inequality (4.12) to obtain $u(x) \leq u_\infty(x)$ for every $x \in V$. \square

Remark 14. *Because we have financial applications in mind, we choose to work directly with payoffs of the form $e^{-rt}\phi(X_t)$. Observe, however, that our methodology applies when $r = 0$ pending the assumption $\phi(X_\tau) = 0$ on the set $\{\tau = +\infty\}$.*

We close this section by giving a very simple example on the countable state space \mathbb{Z} with a bounded reward function ϕ such that the recursive algorithm does not stop in finite time because it eliminates only one point at each step.

Example 15. Let $(X_t)_{t \geq 0}$ be a birth-death process with the generator on \mathbb{Z}

$$\begin{cases} L(x, x+1) &= \lambda \geq 0, \\ L(x, x-1) &= \mu \geq 0, \\ L(x) &= \lambda + \mu, \end{cases}$$

We define the reward function as

$$\phi(x) = \begin{cases} 0 & \text{for } x \leq 0 \\ 1 & \text{for } x = 1 \\ 2 & \text{for } x \geq 2. \end{cases}$$

We assume $r = 0$ and $\lambda \geq \mu$. Therefore, $\mathcal{D}_1 = \mathbb{Z} \setminus \{1\}$. It is easy to show that

$$u_1(1) = \frac{2\lambda}{\lambda + \mu}, \text{ and thus } \mathcal{L}[u_1](0) = \lambda u_1(1) > 0.$$

Therefore, $\mathcal{D}_2 = \mathbb{Z} \setminus \{1, 0\}$. At each step $n \in \mathbb{Z}_+$, because $u_n(1-n) > 0$, the algorithm will remove only the integer $1-n$ in the set \mathcal{D}_n . Therefore, it will not reach the stopping region $\mathcal{D} = \{2, 3, \dots\}$ in finite time.

4.2 Measurable state space

Up to now, we have only considered continuous-time Markov chains with a discrete state space. But, it is not difficult to see that the results of the previous section can be extended to the case where the state space of the Markov chain is a measurable space. More formally, we consider on a measurable state space (V, \mathcal{V}) , a non-negative finite kernel K . It is a mapping

$$K : V \times \mathcal{V} \ni (x, S) \mapsto K(x, S) \in \mathbb{R}_+$$

such that

- for any $x \in V$, $K(x, \cdot)$ is a non-negative finite measure on (V, \mathcal{V}) (because $K(x, V) \in \mathbb{R}_+$),
- for any $S \in \mathcal{V}$, $K(\cdot, S)$ is a non-negative measurable function on (V, \mathcal{V}) .

For any probability measure m on V , let us associate to K a continuous-time Markov process $X := (X_t)_{t \geq 0}$ whose initial distribution is m . First we set $\sigma_0 := 0$ and X_0 is sampled according to m . Then we consider an exponential random variable σ_1 of parameter $K(X_0) := K(X_0, V)$. If $K(X_0) = 0$, we have a.s. $\sigma_1 = +\infty$ and we take $X_t := X_0$ for all $t > 0$, as well as $\sigma_n := +\infty$ for all $n \in \mathbb{N}, n \geq 2$. If $K(X_0) > 0$, we take $X_t := X_0$ for all $t \in (0, \sigma_1)$ and we sample X_{σ_1} on $V \setminus \{X_0\}$ according to the probability distribution $K(X_0, \cdot)/K(X_0)$. Next, still in the case where $\sigma_1 < +\infty$, we sample an inter-time $\sigma_2 - \sigma_1$ as an exponential distribution of parameter $K(X_{\sigma_1})$. If $K(X_{\sigma_1}) = 0$, we have a.s. $\sigma_2 = +\infty$ and we take $X_t := X_{\sigma_1}$ for all $t \in (\sigma_1, +\infty)$, as well as $\sigma_n := +\infty$ for all $n \in \mathbb{N}, n \geq 3$. If $K(X_{\sigma_1}) > 0$, we take $X_t := X_{\sigma_1}$ for all $t \in (\sigma_1, \sigma_2)$ and we sample X_{σ_2} on $V \setminus \{X_{\sigma_1}\}$ according to the probability distribution $(K(X_{\sigma_1}, x)/K(X_{\sigma_1}))_{x \in V \setminus \{X_{\sigma_1}\}}$. We keep on following the same procedure, where all the ingredients are independent, except for the explicitly mentioned dependences.

In particular, we get a non-decreasing family $(\sigma_n)_{n \in \mathbb{Z}_+}$ of jump times taking values in $\bar{\mathbb{R}}_+ := \mathbb{R}_+ \sqcup \{+\infty\}$. Denote the corresponding exploding time

$$\sigma_\infty := \lim_{n \rightarrow \infty} \sigma_n \in \bar{\mathbb{R}}_+$$

When $\sigma_\infty < +\infty$, we must still define X_t for $t \geq \sigma_\infty$. So introduce Δ a cemetery point not belonging to V and denote $\bar{V} := V \sqcup \{\Delta\}$. We take $X_t := \Delta$ for all $t \geq \sigma_\infty$ to get a \bar{V} -valued process X . Let \mathcal{B} be the space of bounded and measurable functions from V to \mathbb{R} . For $f \in \mathcal{B}$, the infinitesimal generator of $X = (X_t)_{t \geq 0}$ is given by

$$\mathcal{L}[f](x) = \int_V f(y)K(x, dy) - K(x)f(x) := \mathcal{K}[f](x) - K(x)f(x).$$

As in Section 4.1, we set some payoff function $\phi \in \bar{\mathcal{F}}_+ \setminus \{0\}$ and $r > 0$. We will construct a subset $D_\infty \subset V$ and a function $u_\infty \in \bar{\mathcal{F}}_+$ by our recursive algorithm as follows:

We begin by taking $D_0 := V$ and $u_0 := \phi$. Next, let us assume that $D_n \subset V$ and $u_n \in \bar{\mathcal{F}}_+$ have been built for some $n \in \mathbb{Z}_+$ such that

$$\begin{aligned} \forall x \in V \setminus D_n, \quad (r + L(x))u_n(x) &= \mathcal{K}[u_n](x) \\ \forall x \in D_n, \quad u_n(x) &= \phi(x). \end{aligned}$$

Observe that it is trivially true for $n = 0$. Then, we define the subset D_{n+1} as follows

$$D_{n+1} := \{x \in D_n : \mathcal{K}[u_n](x) \leq (r + K(x))u_n(x)\}$$

where the inequality is understood in $\bar{\mathbb{R}}_+$.

Next, we consider the stopping time

$$\tau_{n+1} := \inf\{t \geq 0 : X_t \in D_{n+1}\}$$

with the usual convention that $\inf \emptyset = +\infty$. It is easy to check that the proofs of Section 4.1. are directly deduced.

Remark 16. *Our methodology also applies for discrete Markov chains according to the Poissonization technique that we recall briefly. Consider a Poisson process $N = (N_t)_t$ of intensity λ and a discrete Markov chain $(X_n)_{n \in \mathbb{Z}_+}$ with transition matrix or kernel P . Assume that $(X_n)_{n \in \mathbb{Z}_+}$ and $N = (N_t)_t$ are independent. Then, the process*

$$X_t = \sum_{n=0}^{N_t} X_n$$

is a continuous-time Markov chain with generator $\mathcal{L} := \lambda(P - \text{Id})$.

5 Application: optimal stopping with random intervention times

We revisit the paper by Dupuis and Wang [6] where they consider a class of optimal stopping problems that can be only stopped at Poisson jump times. Consider a probability space $(\Omega, \mathcal{F} := (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ satisfying

the usual conditions. For $x > 0$, let $(S_t^x)_{t \geq 0}$ be a geometric Brownian motion solving the stochastic differential equation

$$\frac{dS_t^x}{S_t^x} = b dt + \sigma dW_t, \quad S_0^x = x,$$

where $W = (W_t)_{t \geq 0}$ is a standard \mathcal{F} -Brownian motion and b and $\sigma > 0$ are constants. When $x = 0$, we take $S_t^0 = 0$ for all times $t \geq 0$. The probability space is rich enough to carry a \mathcal{F} -Poisson process $N = (N_t)_{t \geq 0}$ with intensity $\lambda > 0$ that is assumed to be independent from W . The jump times of the Poisson process are denoted by T_n with $T_0 = 0$

In [6], the following optimal stopping problem is considered

$$u(0, x) = \sup_{\tau \in \mathcal{S}_0} \mathbb{E} [e^{-r\tau} (S_\tau^x - K)_+],$$

where $r > b$ and \mathcal{S}_0 is the set of \mathcal{F} -adapted stopping time τ for which $\tau(\omega) = T_n(\omega)$ for some $n \in \mathbb{Z}_+$. Similarly to [6], let us define $\mathcal{G}_n = \mathcal{F}_{T_n}$ and the \mathcal{G}_n -Markov chain $Z_n = (T_n, S_{T_n}^x)$ to have

$$u(0, x) = \sup_{N \in \mathcal{N}_0} \mathbb{E} [\psi(Z_N) | Z_0 = (0, x)], \text{ where } \psi(t, x) = e^{-rt} (x - K)_+$$

and \mathcal{N}_0 is the set of \mathcal{G} -stopping time with values in \mathbb{Z}_+ . To enter the continuous-time framework of the previous sections, we use Remark 16 with an independent Poisson process $\tilde{N} = (\tilde{N}_t)_t$ with intensity 1. To start our recursive approach, we need to compute the infinitesimal generator $\tilde{\mathcal{L}}$ of the continuous Markov chain $(\tilde{Z}_t = \sum_{i=0}^{\tilde{N}_t} Z_n)_{t \geq 0}$ with state space $V = \mathbb{R}_+ \times \mathbb{R}_+$ in order to define

$$\tilde{\mathcal{D}}_1 := \{(t, x) \in V; \tilde{\mathcal{L}}[\psi](t, x) \leq 0\}.$$

Let f be a bounded and measurable function on V . According to Remark 16, we have,

$$\tilde{\mathcal{L}}[f](t, x) = \lambda \int_0^{+\infty} \mathbb{E}[f(t+u, S_u^x)] e^{-\lambda u} du - f(t, x).$$

Because $\psi(t, x) = e^{-rt} \phi(x)$ with $\phi(x) = (x - K)_+$, we have

$$\tilde{\mathcal{L}}[\psi](t, x) = e^{-rt} (\lambda R_{r+\lambda}[\phi](x) - \phi(x)),$$

where

$$R_{r+\lambda}[\phi](x) = \int_0^{+\infty} \mathbb{E}[\phi(S_u^x)] e^{-(r+\lambda)u} du$$

is the resolvent of the continuous Markov process $S^x = (S_t^x)_{t \geq 0}$. Therefore, we have $\tilde{\mathcal{D}}_1 = \mathbb{R}_+ \times \mathcal{D}_1$ with

$$\mathcal{D}_1 := \{x \in \mathbb{R}_+, \lambda R_{r+\lambda}[\phi](x) - \phi(x) \leq 0\}.$$

First, we observe that \mathcal{D}_1 is an interval $[x_1, +\infty[$. Indeed, let us define

$$\eta(x) := \lambda R_{r+\lambda}[\phi](x) - \phi(x).$$

Clearly, $\eta(x) > 0$ for $x \leq K$. Moreover, for $x > K$,

$$\eta'(x) = \left(\lambda \int_0^{+\infty} \partial_x \mathbb{E}[\phi(S_u^x)] e^{-(r+\lambda)u} du \right) - \phi'(x).$$

It is well-known that $\partial_x \mathbb{E}[\phi(S_u^x)] \leq e^{bu}$ for any $x \geq 0$ and thus, because $r > b$,

$$\eta'(x) \leq \frac{\lambda}{r-b+\lambda} - 1 < 0,$$

which gives that η is a decreasing function on $[K, +\infty)$. It follows that if \mathcal{D}_1 is not empty, then it will be an interval of the form $[x_1, +\infty)$. Now,

$$\eta(x) = x \left(\lambda \int_0^{+\infty} \frac{\mathbb{E}[\phi(S_u^x)]}{x} e^{-(r+\lambda)u} du \right) - \phi(x).$$

Because $\frac{\mathbb{E}[\phi(S_u^x)]}{x} \leq e^{bu}$, we have $\eta(x) \leq \left(\frac{\lambda}{r-b+\lambda} - 1\right)x + K$ and therefore, $\eta(x) \leq 0$ for $x \geq \left(1 + \frac{\lambda}{r-b}\right)K$ which proves that \mathcal{D}_1 is not empty.

We will now prove by induction that for every $n \in \mathbb{N}$, $\tilde{\mathcal{D}}_n = \mathbb{R}_+ \times \mathcal{D}_n$ with $\mathcal{D}_n = [x_n, +\infty)$ and $x_n > K$. Assume that it is true for some $n \in \mathbb{N}$. Following our monotone procedure with Remark 14, we define the solution $u_{n+1} : \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}$ of the equation

$$\begin{cases} \tilde{\mathcal{L}}[u_{n+1}] = 0 & , \text{ on } \tilde{\mathcal{D}}_n^c \\ u_{n+1} = \psi & , \text{ on } \tilde{\mathcal{D}}_n \end{cases}$$

and define

$$\tilde{\mathcal{D}}_{n+1} := \{(t, x) \in \tilde{\mathcal{D}}_n, \tilde{\mathcal{L}}[u_{n+1}] \leq 0\}.$$

Let us check that $\tilde{\mathcal{D}}_{n+1} = \mathbb{R}_+ \times \mathcal{D}_{n+1}$ with $\mathcal{D}_{n+1} = [x_{n+1}, +\infty)$ and $x_{n+1} \geq x_n$.

To do this, we look for a function of the form

$$\forall (t, x) \in \mathbb{R}_+ \times \mathbb{R}_+, \quad u_{n+1}(t, x) = \exp(-rt)v_{n+1}(x) \tag{5.1}$$

We end up with the following equation on v_{n+1} :

$$\begin{cases} \lambda R_{r+\lambda}[v_{n+1}] - v_{n+1} = 0 & , \text{ on } \mathcal{D}_n^c \\ v_{n+1} = \phi & , \text{ on } \mathcal{D}_n \end{cases} \tag{5.2}$$

or equivalently, (see [8], Proposition 2.1 page 10)

$$\begin{cases} \mathcal{L}^S[v_{n+1}] - rv_{n+1} = 0 & , \text{ on } \mathcal{D}_n^c \\ v_{n+1} = \phi & , \text{ on } \mathcal{D}_n \end{cases}$$

where \mathcal{L}^S is the infinitesimal generator of $S^x = (S_t^x)_{t \geq 0}$, that is, acting on any $f \in \mathcal{C}^2(\mathbb{R}_+)$ via

$$\mathcal{L}^S[f](x) = \frac{\sigma^2 x^2}{2} f''(x) + bx f'(x),$$

With this formulation we see that v_{n+1} is given by

$$\forall x \in \mathbb{R}_+, \quad v_{n+1}(x) = \mathbb{E}_x[\exp(-r\tau_{x_n}^x)\phi(S_{\tau_{x_n}^x}^x)]$$

where τ_{x_n} is the first hitting time of $\mathcal{D}_n = [x_n, +\infty[$ by our induction hypothesis. By definition, we have

$$\begin{aligned} \tilde{\mathcal{D}}_{n+1} &:= \{(t, x) \in \tilde{\mathcal{D}}_n : \tilde{\mathcal{L}}[u_{n+1}](t, x) \leq 0\} \\ &= \mathbb{R}_+ \times \{x \in \mathcal{D}_n : \lambda R_{r+\lambda}[v_{n+1}](x) - v_{n+1}(x) \leq 0\} \\ &= \mathbb{R}_+ \times \{x \in \mathcal{D}_n : \lambda R_{r+\lambda}[v_{n+1}](x) - \phi(x) \leq 0\} \end{aligned}$$

thus $\tilde{\mathcal{D}}_{n+1} = \mathbb{R}_+ \times \mathcal{D}_{n+1}$ where

$$\mathcal{D}_{n+1} := \{x \in \mathcal{D}_n : \zeta_{n+1}(x) \leq 0\}$$

with

$$\forall x \geq 0, \quad \zeta_{n+1}(x) := \lambda R_{r+\lambda}[v_{n+1}](x) - \phi(x)$$

To prove that \mathcal{D}_{n+1} is of the form $[x_{n+1}, +\infty)$, we begin by showing that

$$\forall y \geq x \geq x_n, \quad \zeta_{n+1}(x) = 0 \Rightarrow \zeta_{n+1}(y) \leq 0 \quad (5.3)$$

To do so, introduce the hitting time

$$\tau_x^y := \inf\{t \geq 0 : S_t^y = x\}$$

Recall that the solution of (5.1) is given by

$$\forall x \in \mathbb{R}_+, \forall t \geq 0, \quad S_t^x = x \exp\left(\sigma W_t - \frac{\sigma^2}{2}t + bt\right)$$

It follows that

$$\tau_x^y = \inf\{t \geq 0 : W_t - \frac{\sigma^2}{2}t + bt = \ln(x/y)\}$$

In particular τ_x^y takes the value $+\infty$ with positive probability when $b > \sigma^2/2$, but otherwise τ_x^y is a.s. finite. Nevertheless, taking into account that for any $z \geq x_n$, we have $v_{n+1}(z) = \phi(z)$, we can always write for $y \geq x \geq x_n$:

$$\begin{aligned} &R_{r+\lambda}[v_{n+1}](y) \\ &= \mathbb{E}\left[\int_0^\infty v_{n+1}(S_u^y) \exp(-(r+\lambda)u) du\right] \\ &= \mathbb{E}\left[\int_0^{\tau_x^y} v_{n+1}(S_u^y) \exp(-(r+\lambda)u) du + \int_{\tau_x^y}^\infty v_{n+1}(S_u^y) \exp(-(r+\lambda)u) du\right] \\ &= \mathbb{E}\left[\int_0^{\tau_x^y} \phi(S_u^y) \exp(-(r+\lambda)u) du\right] + \mathbb{E}\left[\exp(-(r+\lambda)\tau_x^y) \int_0^\infty v_{n+1}(S_{\tau_x^y+u}^y) \exp(-(r+\lambda)u) du\right] \\ &= \mathbb{E}\left[\int_0^{\tau_x^y} \phi(S_u^y) \exp(-(r+\lambda)u) du\right] + \mathbb{E}[\exp(-(r+\lambda)\tau_x^y)] R_{r+\lambda}[v_{n+1}](x) \end{aligned}$$

where we use the strong Markov property with the stopping time τ_x^y . Reversing the same argument, with v_{n+1} replaced by ϕ , we deduce that

$$\begin{aligned} R_{r+\lambda}[v_{n+1}](y) &= \mathbb{E} \left[\int_0^{\tau_x^y} \phi(S_u^y) \exp(-(r+\lambda)u) du \right] + \mathbb{E} [\exp(-(r+\lambda)\tau_x^y)] R_{r+\lambda}[\phi](x) \\ &\quad + \mathbb{E} [\exp(-(r+\lambda)\tau_x^y)] (R_{r+\lambda}[v_{n+1}](x) - R_{r+\lambda}[\phi](x)) \\ &= R_{r+\lambda}[\phi](y) + \mathbb{E} [\exp(-(r+\lambda)\tau_x^y)] (R_{r+\lambda}[v_{n+1}](x) - R_{r+\lambda}[\phi](x)) \end{aligned}$$

Thus, we have

$$\zeta_{n+1}(y) = \lambda R_{r+\lambda}[\phi](y) - \phi(y) + \lambda \mathbb{E} [\exp(-(r+\lambda)\tau_x^y)] (R_{r+\lambda}[v_{n+1}](x) - R_{r+\lambda}[\phi](x))$$

In the first part of the above proof, to get the existence of x_1 , we have shown that the mapping $\zeta_1 := R_{r+\lambda}[\phi] - \phi$ is non-increasing on $[x_1, +\infty) \supset [x_n, +\infty)$, and in particular

$$\begin{aligned} \lambda R_{r+\lambda}[\phi](y) - \phi(y) &\leq \lambda R_{r+\lambda}[\phi](x) - \phi(x) \\ &= \zeta_1(x) \end{aligned}$$

so we get

$$\zeta_{n+1}(y) \leq \zeta_1(x) \mathbb{E} [\exp(-(r+\lambda)\tau_x^y)] (\lambda R_{r+\lambda}[v_{n+1}](x) - \lambda R_{r+\lambda}[\phi](x))$$

Assume now that $\zeta_{n+1}(x) = 0$. It means that

$$\lambda R_{r+\lambda}[v_{n+1}](x) = \phi(x)$$

implying that

$$\begin{aligned} \zeta_{n+1}(y) &\leq \zeta_1(x) + \mathbb{E} [\exp(-(r+\lambda)\tau_x^y)] (\phi(x) - \lambda R_{r+\lambda}[\phi](x)) \\ &\leq (1 - \mathbb{E} [\exp(-(r+\lambda)\tau_x^y)]) \zeta_1(x) \\ &\leq 0 \end{aligned}$$

since $x \geq x_n \geq x_1$ so that $\zeta_1(x) \leq 0$.

This proves (5.3) and ends the induction argument.

According to Proposition 10 and Theorem 13 (more precisely its extension given in Subsection 4.2), the value function u and the stopping set $\mathcal{D} = \{x \in \mathbb{R}_+, u(x) = \phi(x)\}$ satisfy $u(t, x) = e^{-rt}v(x)$, where

$$v(x) = \lambda R_{r+\lambda}[v](x) \text{ on } \mathbb{R}_+ \setminus \mathcal{D},$$

$$v = \phi \text{ on } \mathcal{D}$$

and

$$\mathcal{D} = \bigcap_{n \in \mathbb{N}} [x_n, +\infty[.$$

The stopping set is an interval $[x^*, +\infty[$ that may be empty if x^* is not finite. Using again [8], Proposition 2.1, we obtain

$$\mathcal{L}^S[v](x) - rv(x) = 0 \quad \forall x \in \mathbb{R}_+ \setminus \mathcal{D}.$$

Therefore, the function w given by $w(x) := \lambda R_{r+\lambda}[v](x)$ for any $x \in (0, +\infty)$ also satisfies

$$\mathcal{L}^S[w](x) - rw(x) = 0 \quad \forall x \in \mathbb{R}_+ \setminus \mathcal{D}.$$

Moreover,

$$(-\mathcal{L}^S + (r + \lambda))[w](x) = \lambda v(x) = \lambda \phi(x) \quad \forall x \in \mathcal{D},$$

which yields

$$\mathcal{L}^S[w](x) - rw(x) + \lambda(\phi(x) - w(x)) = 0 \quad \forall x \in \mathcal{D}.$$

This corresponds to the variational inequality (3.4)-(3-9) page 6 solved in [6], establishing that \mathcal{D} is non-empty.

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