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A new formulation for two-wave Riemann solver accurate at contact interfaces.

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This study proposes a new formulation for Harten, Lax and van Leer (HLL) type Riemann solver which is capable of solving contact discontinuities accurately but with robustness for strong shock. It is well known that the original HLL, which has incomplete wave structures, is too dissipative to capture contact discontinuities accurately. On the other side, contact-capturing approximate Riemann solvers such as Harten, Lax and van Leer with Contact (HLLC) usually suffer from spurious solutions, also called carbuncle phenomenon, for strong shock. In this work a new accurate and robust HLL-type formulation, so-called HLL-BVD (HLL Riemann solver with BVD) is proposed by modifying the original HLL with BVD (boundary variation diminishing) algorithm. Instead of explicitly recovering the complete wave structures like the way of HLLC, the proposed method restores the missing contact with a jump-like function. The capability of solving contact discontinuities is further improved by minimizing the inherent dissipation term in HLL. Without modifying the original incomplete wave structures of HLL, the robustness for strong shock has been reserved. Thus the proposed method is free from shock instability problem. The accuracy and robustness of the new method are demonstrated through solving several one- and two-dimensional tests. Results indicate that the new formulation based on two-wave HLL-type Riemann solver is not only capable of capturing contact waves more accurately than the original HLL or HLLC but, most importantly, is free from carbuncle instability for strong shock.

I. INTRODUCTION

The modern finite volume method (FVM) for hyperbolic systems is developed based on Godunov scheme¹ which assumes that (1) the flow variables within each computing elements are constant and (2) numerical fluxes are calculated from the solution of the Riemann problem. Owing to its robustness and flexibility, Godunov approach has been further developed for decades, and is popularly applied to solve Euler equations for high speed compressible flows. One branch in the development is the construction of approximate Riemann solvers, or in another word, upwind fluxes. Different from the exact Riemann solver, the approximate algorithms are non-iterative and hence less expensive. Over the years, several upwind fluxes have been proposed, which can be generally categorized into flux vector splitting (FVS) and flux difference splitting (FDS) methods².

The FVS methods split flux vectors into upstream and downstream travelling informations. These methods are generally less complicated and more easily compatible with implicit methods. However, they are not effective in capturing the discontinuities represented by linear waves. Thus they are prone to intensively smear out contact surfaces and shear waves. Schemes such as the Steger-Warming³ and the FVS scheme of van Leer⁴ belong to

this approach.

On the other hand, the FDS methods are constructed from approximate solution of local Riemann problem between two adjacent states. The FDS methods can be further divided into two groups as complete or incomplete Riemann solvers. The complete solvers have the same wave structures as the exact Riemann solver. For Euler equations, the wave structures comprise a contact discontinuity and two nonlinear waves which corresponds to either a shock or a rarefaction wave. By virtue of comprising all wave components, the complete FDS methods are capable of capturing linear as well as non-linear waves. This attractive quality makes complete Riemann solvers such as the Roe solver⁵, the Osher solver⁶ and Harten, Lax and van Leer with Contact (HLLC) solver widely used. Incomplete Riemann solvers, however, employ coarser wave structures which do not include the contact discontinuity. Thus, they generally bring excessive dissipation across contact. The incomplete solvers include the HLL⁷, the Harten Lax van Leerinfeldt (HLLC)⁸ and the Rusanov solver⁹.

Among these approximated Riemann solvers introduced above, HLLC method, which is less dissipative, is considered to be one of the most preferred FDS method because it can capture contact very accurately. Unfortunately, it may encounter a problem of numerical instability known as the carbuncle phenomenon. In fact, it has been known that Riemann solvers, which can resolve the contact and shear waves exactly, usually suffer from numerical instability in the vicinity of strong shock waves¹⁰. On the other side, HLL, which is more dissipative due to its incomplete wave structures, is very robust.

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It has an entropy satisfaction property, exactly resolves isolated shock and preserves positivity^{7,11,12} although it is notorious that it cannot resolve contact discontinuities exactly.

Consequently, there have been several attempts to construct Riemann solvers which can overcome the problem of either shock instability or exactly resolving contact discontinuities. Among these attempts, the most popular methodology is a hybrid method proposed in¹³. It is suggested that using a dissipative scheme in shock region while a less dissipative one elsewhere may tackle this problem. From then, several successful approaches^{10,14–16} have been proposed by relying on hybridization. However, the choice and design of switching parameters required in the hybrid methods usually have some arbitrariness. This arbitrariness in parameters may lead to failures for complex flow cases¹⁷. Moreover, the hybridization of complementary solvers may break the strict Rankine-Hugoniot jump conditions, which will result in smearing contact discontinuities¹⁵. Realizing the drawbacks of hybrid methods, other ideas have been tried to modify the HLL-type approximate Riemann solver. For example, in the work of¹⁸ Euler equations are split into convective and pressure parts before formulating the HLL in order to recover the contact in HLL. Through modifying the dissipation term in HLL flux, the ability to resolve the contact is further enhanced. In¹⁷, new HLL-type and HLLC-type Riemann solvers are constructed by modifying the shear viscosity of the original HLL and HLLC methods respectively. Although these modifications give good results in two dimensional problems, the performance has not been evaluated in one dimensional cases. Recently, several methods have been proposed to reduce shock instability for complete wave Riemann solvers through controlling numerical dissipation. In the work¹⁹, artificial viscosity has been introduced in the control equations to cure the carbuncle phenomenon. Shock-stable items or shear viscosity are introduced into numerical flux in^{20,21} to stabilize strong shock. A method named normal reconstruction procedure is proposed in²² to add dissipation to transverse velocity which tends to cause propagation of shock anomalies. In^{23,24}, shock stability is realized by effective controlling dissipation term. Based on the fact that different reconstruction processes have different dissipation properties, the work²⁵ alleviates shock anomalies through combing with reconstruction schemes.

Despite these efforts, there is still no consensus on how to construct an accurate and robust approximate Riemann solver. In the present work, a simple novel method, so-called HLL-BVD (HLL Riemann solver with boundary variation diminishing algorithm), is proposed to solve contact discontinuities accurately without suffering from numerical shock instability problems. By realizing that the dissipation term in HLL flux leads to the failure of accurately resolving contact, the current method makes an attempt to minimize this dissipation term through introduction of a jump-like function. In

line with²⁶, which uses Tangent of Hyperbola for Interface Capturing (THINC) function^{27,28} with boundary variation diminishing (BVD) algorithm to effectively control numerical dissipation, the current work employs a jump-like THINC function to represent the information of contact discontinuities and derives a consistent BVD algorithm to minimize the dissipation term. This leads to significant improvements in the resolution of contact discontinuities. Since the new method restores the contact with an implicit algebraic way, the incomplete wave structure of HLL is preserved. Thus, unlike other methods which retrieve contact by modifying the wave structures of HLL, the robustness of HLL for strong shocks can be kept. Examined through several benchmark tests, the proposed HLL-BVD approach is shown to better represent contact interfaces and be free from shock instability problems.

The outline of the paper is as follows. In Section 2, after a brief review of HLL-type Riemann solvers, details of our HLL-BVD method are presented. In Section 3, numerical results of benchmark tests are presented and systematically compared with conventional HLL and HLLC methods. Some concluding remarks are given in Section 4.

II. NUMERICAL METHODS

A. Governing equations

The one-dimensional Euler equations can be expressed as

$$\frac{\partial \mathbf{U}}{\partial t} + \frac{\partial \mathbf{F}(\mathbf{U})}{\partial x} = 0 \quad (1)$$

under conservative form, where the physical variables vector \mathbf{U} and flux vectors $\mathbf{F}(\mathbf{U})$ read

$$\mathbf{U} = \begin{bmatrix} \rho \\ \rho u \\ \rho v \\ E \end{bmatrix} \quad \text{and} \quad \mathbf{F}(\mathbf{U}) = \begin{bmatrix} \rho u \\ \rho u^2 + p \\ \rho uv \\ u(E + p) \end{bmatrix}.$$

Following the conventional notation, ρ denotes the density, p the pressure and E the total energy per unit volume. u is the fluid velocity in the x direction and v is the transverse velocity. System (1) is closed through introduction of the perfect gas equation of state

$$p = (\gamma - 1)(E - \frac{1}{2}\rho(u^2 + v^2)), \quad (2)$$

where γ is the specific heat ratio.

Within the finite volume framework, System (1) in semi-discrete form reads

$$\frac{\partial \bar{\mathbf{U}}_i}{\partial t} = -\frac{1}{\Delta x}(\mathbf{F}_{i+\frac{1}{2}} - \mathbf{F}_{i-\frac{1}{2}}), \quad (3)$$

where the volume-integrated average value $\bar{\mathbf{U}}_i$ in cell \mathcal{I}_i is defined as

$$\bar{\mathbf{U}}_i \approx \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} \mathbf{U}(x, t) dx. \quad (4)$$

The numerical fluxes $\mathbf{F}_{i \pm \frac{1}{2}}$ at cell boundaries can be computed by a Riemann solver. In the following, let the subscripts **L** and **R** identify the left and right values of a given quantity on either side of the cell interface.

B. HLL Riemann solvers

Within the HLL framework, each cell boundary is regarded as a two-wave system. The system, illustrated in Fig. 1, then consists of two waves travelling at (S_L, S_R) .

In that context, writing the conservation equations (1) in weak form

$$\oint \mathbf{U} \cdot d\mathbf{x} - \mathbf{F} \cdot d\mathbf{t} = 0, \quad (5)$$

and assuming \mathbf{U} to be constant on each branch of the integration path illustrated in Fig.1 directly leads to

$$\mathbf{U}^* = \frac{S_R \mathbf{U}_R - S_L \mathbf{U}_L + \mathbf{F}_L - \mathbf{F}_R}{S_R - S_L}, \quad (6)$$

where the * superscript denotes the middle state. The corresponding flux can be found as

$$\mathbf{F}^* = \frac{S_R \mathbf{F}_L - S_L \mathbf{F}_R + S_L S_R (\mathbf{U}_R - \mathbf{U}_L)}{S_R - S_L}. \quad (7)$$

The final flux $\mathbf{F}_{i+\frac{1}{2}}$, required to solve (3), then read

$$\mathbf{F}_{i+\frac{1}{2}}^{hll} = \begin{cases} \mathbf{F}_L & \text{if } 0 \leq S_L, \\ \mathbf{F}^* & \text{if } S_L \leq 0 \leq S_R, \\ \mathbf{F}_R & \text{if } 0 \geq S_R. \end{cases} \quad (8)$$

Following²⁹, the right and left wave velocities are approximated as

$$S_L = \min(u_L - c_L, u_R - c_R), \quad S_R = \max(u_L + c_L, u_R + c_R), \quad (9)$$

where $c_{L/R}$ is the sound speed on either side of the interface.

As with most shock capturing schemes, robustness is assured by inclusion of diffusion at the shock. This can

be easily seen by separating the flux (7) into two contributions

$$\mathbf{F}^{hll} = \frac{1}{2}(\mathbf{F}_L + \mathbf{F}_R) + \varepsilon_{hll}, \quad (10)$$

where the first term corresponds to the classical central difference flux, and ε_{hll} can be interpreted as a numerical diffusion term

$$\varepsilon_{hll} = \underbrace{\frac{S_R + S_L}{2(S_R - S_L)}(\mathbf{F}_L - \mathbf{F}_R)}_{\varepsilon_1} - \underbrace{\frac{S_L S_R}{S_R - S_L}(\mathbf{U}_L - \mathbf{U}_R)}_{\varepsilon_2}. \quad (11)$$

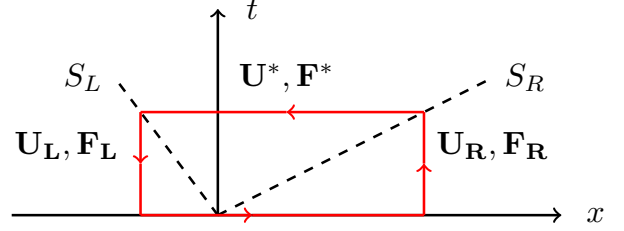


FIG. 1. The wave structure in HLL Riemann solvers. In red, the integration contour leading to Eq. (6)

When the flow presents density discontinuities, the density (and therefore \mathbf{U}) is not constant between the S_L and S_R waves. This leads to excessive numerical diffusion and the failure of HLL Riemann solver to accurately solve contact discontinuities¹⁸.

C. Towards the reduction of numerical diffusion

There are several strategies to cope with these deficiencies. One strategy, proposed in¹⁸ is to assume local isentropy, as to replace the density jump terms in the second term of the HLL diffusion ε_{hll} (11)

$$\varepsilon_2 = \frac{S_L S_R}{S_R - S_L} \begin{pmatrix} \rho_L - \rho_R \\ (\rho u)_L - (\rho u)_R \\ (\rho v)_L - (\rho v)_R \\ E_L - E_R \end{pmatrix}, \quad (12)$$

into pressure jump terms

$$\varepsilon_2^{isen} = \frac{S_L S_R}{\bar{c}^2(S_R - S_L)} \begin{pmatrix} p_L - p_R \\ (pu)_L - (pu)_R \\ (pv)_L - (pv)_R \\ \frac{\bar{c}^2}{\gamma - 1}(p_L - p_R) + \frac{1}{2}((p(u^2 + v^2))_L - (p(u^2 + v^2))_R) \end{pmatrix}, \quad (13)$$

through introduction of an interface sound speed $\bar{c} = \frac{c_L + c_R}{2}$. This method can improve the resolution across contact waves and keep shock stable. However, the isentropic hypothesis may not always hold.

A second strategy is the introduction of an anti-diffusive term in (11). In that direction, the HLLEM solver⁸ is a possible alternative, with the diffusive term now reading

$$\varepsilon_{hllem} = \frac{S_R + S_L}{2(S_R - S_L)}(\mathbf{F}_L - \mathbf{F}_R) - \frac{S_L S_R}{S_R - S_L}(\mathbf{U}_L - \mathbf{U}_R) + \phi \frac{S_L S_R}{S_R - S_L} M(\mathbf{U})(\mathbf{U}_L - \mathbf{U}_R), \quad (14)$$

where the scalar $\phi \in [0, 1]$ is a free parameter, and $M(\mathbf{U})$ arises from the eigen-structure of Jacobi matrix of hyperbolic system^{30,31}.

Clearly, the HLLEM Riemann solver reduces to the HLL solver for $\phi = 0$. Just as the HLLC solver, the HLLEM solver is flexible and able to resolve contact waves with accuracy. Unfortunately, HLLC and HLLEM solvers share similar shock instability problems, believed to be caused by perturbation transverse to the shock waves³². These comments are compatible with the observation³³ that Riemann solvers explicitly dealing with the contact surface display clear evidence of carbuncle phenomenon.

This motivates the derivation of an implicit algebraic method to capture the missing contact waves in HLL Riemann solver without modifying the original two-wave

system.

D. HLL-BVD: A new formulation for HLL accurate at contact

As stated in the previous section, the failure of HLL Riemann solver to resolve contact waves is caused by the numerical dissipation term ε_{hll} (11). Assuming constant flow variables in each cell, in particular, leads to excessive numerical dissipation due to the density jump $|\rho_L - \rho_R|$.

In this work, we then suggest a procedure to minimize that contribution to the numerical dissipation ε_{hll} . Inspired by^{26,34,35}, we use the THINC function^{27,28} to reconstruct density jumps

$$\tilde{\rho}_i(x) = \bar{\rho}_{min} + \frac{\Delta\rho}{2} \left(1 + \theta \tanh \left(\beta \left(\frac{x - x_{i-1/2}}{x_{i+1/2} - x_{i-1/2}} - \tilde{x}_i \right) \right) \right), \quad (15)$$

where $\bar{\rho}_{min} = \min(\bar{\rho}_{i-1}, \bar{\rho}_{i+1})$, $\Delta\rho = |\bar{\rho}_{i+1} - \bar{\rho}_{i-1}|$, and $\theta = \text{sgn}(\bar{\rho}_{i+1} - \bar{\rho}_{i-1})$. The jump “thickness” is controlled by parameter β , set to 1.6 throughout the validation section. It is noted that from our numerical experiments, the parameter β valued from 1.4 to 2.0 is also able to give good or acceptable results. A smaller β will results in more diffusive solutions while a larger one tends to introduce extra anti-diffusion effect. \tilde{x}_i represents the position of jumps, computed as to satisfy $\bar{\rho}_i = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} \tilde{\rho}_i(x) dx$. Having reconstructed the THINC function in every cell, it becomes straightforward to retrieve the corresponding density values $\rho_{L/R}^T$ on either side of the face (note the T superscript for THINC reconstruction).

On the other hand, we have at our disposal the interface values $\rho_{L/R}^P$, coming from the Polynomial reconstruction, which may vary depending on the numerical scheme. In the present work, we use MUSCL (Monotone Upstream-centered Schemes for Conservation Law) scheme³⁶ as the polynomial reconstruction.

In order to minimize the dissipation term, a BVD algorithm which is originally proposed in²⁶ is devised to minimize the density jumps on each cell boundaries. Final values for $\rho_{L/R}$ are picked from $\rho_{L/R}^P$ and $\rho_{L/R}^T$ values, as to minimize the density jump. In other words,

$$|\rho_L - \rho_R| = \min(|\rho_L^T - \rho_R^T|, |\rho_L^P - \rho_R^P|, |\rho_L^P - \rho_R^T|, |\rho_L^T - \rho_R^P|), \quad (16)$$

leading to a minimal density jump in the dissipative term in ε_{hll} (11), now reading

$$\varepsilon_{new} = \frac{S_R + S_L}{2(S_R - S_L)}(\mathbf{F}_L - \mathbf{F}_R) - \frac{S_L S_R}{S_R - S_L} \left(\begin{array}{c} \rho_L - \rho_R \\ \rho_L u_L - \rho_R u_R \\ \rho_L v_L - \rho_R v_R \\ (\frac{p_L}{\gamma - 1} + \frac{1}{2} \rho_L (u_L^2 + v_L^2)) - (\frac{p_R}{\gamma - 1} + \frac{1}{2} \rho_R (u_R^2 + v_R^2)) \end{array} \right). \quad (17)$$

To summarize, the numerical diffusion term of the new formulation for HLL-type Riemann solver is calculated by following steps:

1. Prepare the density values $\rho_{L/R}^P$ at cell interfaces by using classical Godunov scheme or high order schemes;
2. Retrieve the discontinuous density field in the intermediate state with THINC function of (15) to get $\rho_{L/R}^T$;
3. Determine the intermediate density value ρ_L and ρ_R from $\rho_{L/R}^T$ and $\rho_{L/R}^P$ with BVD algorithm in (16) to minimize the density jump $|\rho_L - \rho_R|$ at cell boundaries;
4. The final flux is then computed through (10) and (17).

Since the contact waves are restored through an algebraic way without modifying the wave structures explicitly like HLLC or HLLEM, the numerical tests in following section will show that the new HLL-type solver can accurately solve sharp contact whilst preserving shock stability.

III. NUMERICAL RESULTS

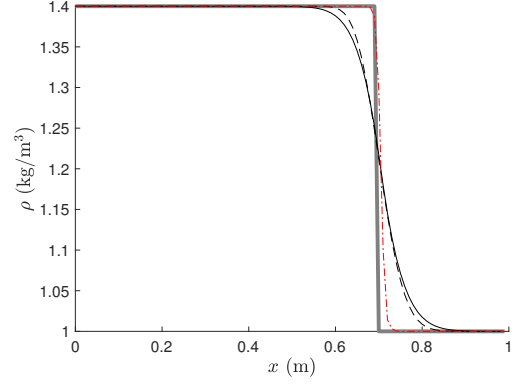
This section presents a series of numerical tests conducted to evaluate the performance of the proposed new HLL-BVD Riemann solver and systematic comparison with the HLL and HLLC solvers are presented. Throughout this section, the specific heat ratio is set as $\gamma = 1.4$. The CFL number is set to 0.4 unless specifically noted.

A. Isolated contact

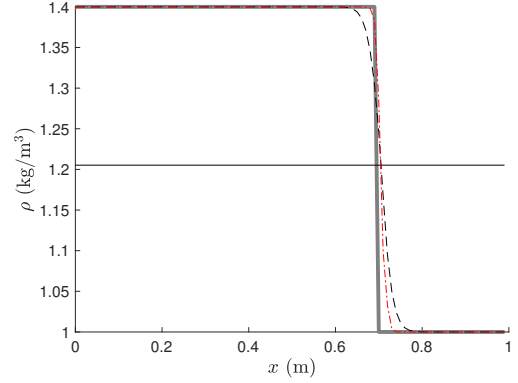
Let us first consider contact wave propagation at low Mach numbers. A one-dimensional domain is initialized as

$$(\rho_0, u_0, p_0) = \begin{cases} (1.4, 0.1, 1.0) & 0 \leq x \leq 0.5 \\ (1.0, 0.1, 1.0) & \text{otherwise} \end{cases}, \quad (18)$$

corresponding to a contact discontinuity moving at $Ma = 0.1$. The computation is carried out with 100 uniform cells and with time integrated up to $t = 2.0$. Figure 2.a presents the density profile as obtained through integration with the classical HLL and HLLC solvers, as well as the present HLL-BVD solver. It can be seen that the moving contact wave resolved by the original HLL Riemann solver is the most diffusive. Although HLLC can resolve the moving contact wave better than HLL, it still poorly represents the contact wave as a sharp discontinuity. However, the proposed HLL-BVD has the ability to capture the sharp jump of density field across the contact. The test shows that the proposed HLL-BVD is superior



(a) Mach=0.1



(b) Mach=10⁻⁵

FIG. 2. Density profiles for an isolated right-moving contact wave travelling at Mach=0.1 (a) and Mach=10⁻⁵ (b), as obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. The reference solution is represented by the thick line.

to original HLL and HLLC regarding to represent sharp contact discontinuities.

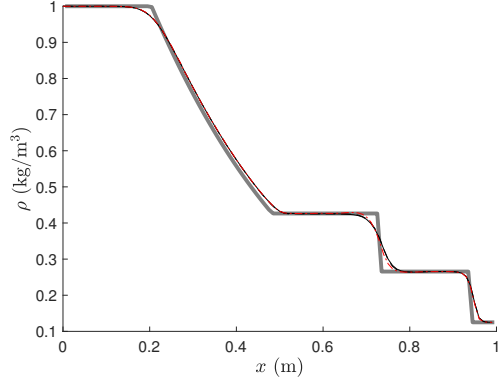
To further examine the performance of the proposed formulation, the same test case is carried out at a very low Mach Number, $Ma = 10^{-5}$. The results, reported in Fig. 2.b, exhibit the failure of the HLL solver, consistently with previous reports³⁷⁻³⁹. Our HLL-BVD proposal, however, successfully capture the contact discontinuity, even at very low Mach number.

B. Sod's problem

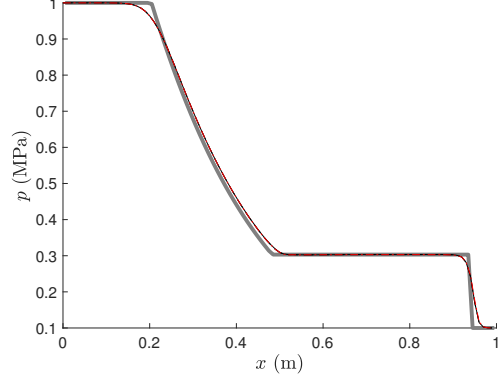
Our second test case is the Sod problem, with initial conditions set as⁴⁰

$$(\rho_0, u_0, p_0) = \begin{cases} (1, 0, 1) & 0 \leq x \leq 0.5 \\ (0.125, 0, 0.1) & \text{otherwise} \end{cases}. \quad (19)$$

This initial condition will result in a right running shock, a right running contact wave and a left running rarefaction wave. With the same number of cells as in previous



(a) Density



(b) Pressure

FIG. 3. Density (a) and pressure (b) profiles for Sod problem with 100 cell elements, as obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. The reference solution is represented by the thick line.

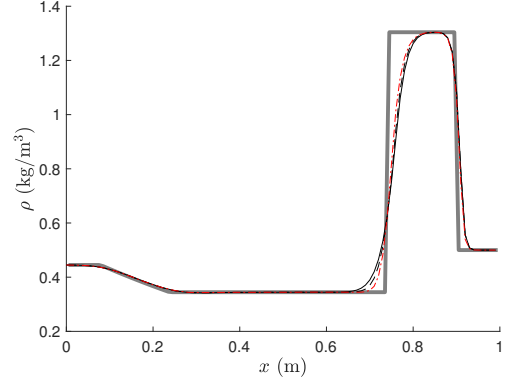
case, the computation lasts until time $t = 0.25$. The density and pressure profiles, displayed in Fig 3, are very similar whether the HLL, HLLC or HLL-BVD solver is used, with the exception of the contact discontinuity, slightly thinner in the HLL-BVD case.

C. Lax's problem

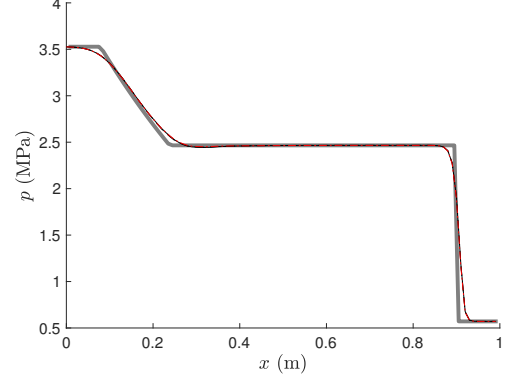
The Lax problem is employed here to check the performance of the proposed numerical scheme to capture relatively strong shock⁴¹. The initial condition is

$$(\rho_0, u_0, p_0) = \begin{cases} (0.445, 0.698, 3.528) & 0 \leq x \leq 0.5 \\ (0.5, 0, 0.571) & \text{otherwise} \end{cases} \quad (20)$$

A relatively strong right running shock, a right running contact discontinuity and a left running expansion wave will evolve with this initial condition. Numerical solutions for density and pressure field are presented in Fig. 4. Again, solutions for expansion fan and shock are almost identical for all three types of HLL Riemann solvers.



(a) Density



(b) Pressure

FIG. 4. Density (a) and pressure (b) profiles for Lax problem with 100 cell elements, as obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. The reference solution is represented by the thick line.

Again, HLL-BVD solves the contact discontinuity with slightly less numerical diffusion.

1. Strong Lax problem

In this test, a numerical test involving a strong shock is considered here to examine the ability of numerical methods to capture contact discontinuities as well as strong shock waves. The initial condition is set as following:

$$(\rho_0, u_0, p_0) = \begin{cases} (1.0, -19.59745, 1000.0) & 0 \leq x \leq 0.8 \\ (1.0, -19.59745, 0.01) & \text{otherwise} \end{cases} \quad (21)$$

The solution consists of a strong shock, a stationary contact and a left running expansion wave. The numerical results at $t = 0.012$ from different Riemann solvers are presented in Fig. 5 for density field and Fig. 6 for pressure field. For this case, it seems that the HLLC Riemann solver can resolve stationary contact with the least amount of numerical diffusion. However, it produces the largest overshoot values across the shock waves as shown

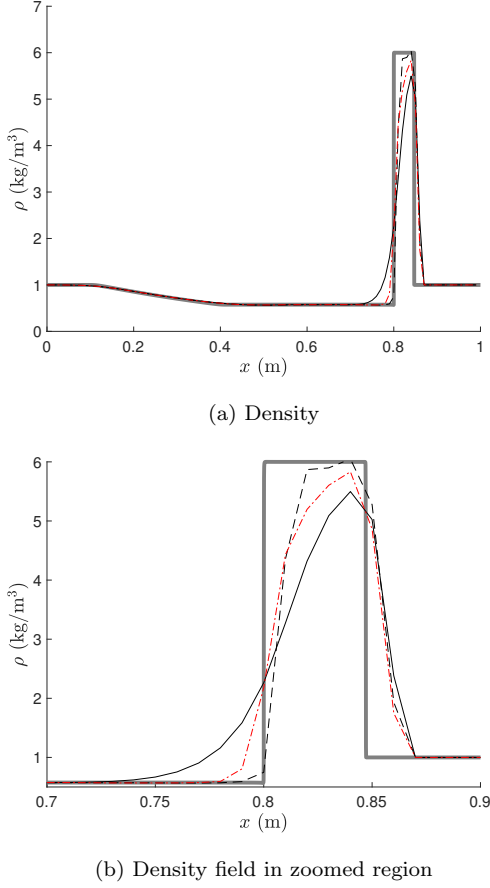


FIG. 5. Global (a) and magnified (b) density profiles for strong Lax problem, as obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. The reference solution is represented by the thick line.

in zoomed region of Fig. 5 and Fig. 6, which may lead unstable solutions for strong shock. However, the proposed one has the ability to represent stationary contact with much less numerical diffusion than the original HLL but also capture strong shock waves without overshooting.

D. Slow moving shock

To further investigate the abilities of different HLL-type Riemann solvers to capture shock waves stably, the slowly moving shock problem is considered here. The computational domain is still one unit long, but now consists of 1000 elements. The initial condition of slowly right moving shock is set as follows

$$(\rho_0, u_0, p_0) = \begin{cases} (1.0, -3.44, 1.0) & 0 \leq x \leq 0.5 \\ (3.86, -0.81, 10.33) & \text{otherwise} \end{cases} \quad (22)$$

The post-shock condition is set at the left boundary while the pre-shock condition is set at the right side. The numerical solutions are obtained at $t = 1.5$ and shown in

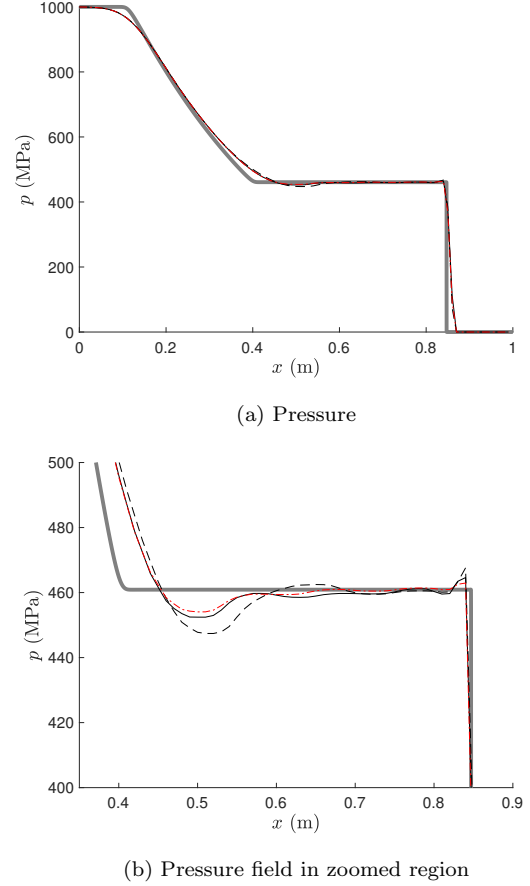


FIG. 6. Global (a) and magnified (b) pressure profiles for strong Lax problem, as obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. The reference solution is represented by the thick line.

Fig. 7. Among the three solvers, HLLC leads to the maximum oscillation amplitude in the post-shock state, while HLL-BVD clearly leads to the most stable solution. As shown in two-dimensional tests later, the unstable shock waves from HLLC may result in unacceptable solutions.

E. 2D Riemann problems

Let us consider two-dimensional problem, starting with the two-dimensional Riemann problem proposed and extensively studied in^{42,43}. It has been reported in⁴⁴ that sharp capturing of discontinuities as well as shear waves is critical to capture the small-scale structures created by the Kelvin-Helmholtz instability.

The computational domain is $[-0.5, 0.5] \times [-0.5, 0.5]$. Two different configurations are studied in the present work. The initial conditions are set as follows,

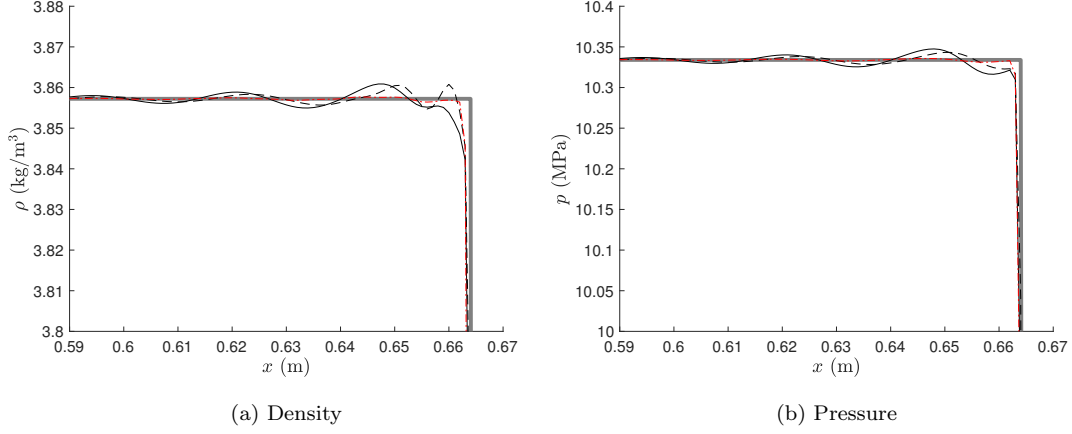


FIG. 7. Density (a) and pressure (b) profiles for the slow moving shock problem, as obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. The reference solution is represented by the thick line.

$$\text{Case 1: } (\rho_0, u_0, v_0, p_0) = \begin{cases} (2.0, 0.75, 0.5, 1.0) & x \leq 0.0, y \geq 0.0 \\ (1.0, -0.75, 0.5, 1.0) & x < 0.0, y < 0.0 \\ (1.0, 0.75, -0.5, 1.0) & x > 0.0, y > 0.0 \\ (3.0, -0.75, -0.5, 1.0) & x > 0.0, y < 0.0 \end{cases} \quad (23)$$

$$\text{Case 2: } (\rho_0, u_0, v_0, p_0) = \begin{cases} (2.0, -0.75, 0.5, 1.0) & x \leq 0.0, y \geq 0.0 \\ (1.0, 0.75, 0.5, 1.0) & x < 0.0, y < 0.0 \\ (1.0, -0.75, -0.5, 1.0) & x > 0.0, y > 0.0 \\ (3.0, 0.75, -0.5, 1.0) & x > 0.0, y < 0.0 \end{cases} \quad (24)$$

Uniform grids of 600×600 are employed in our calculation. The numerical results calculated from different HLL-type Riemann solvers are presented in Fig. 8-9. These results clearly indicate the superiority of our HLL-BVD solver over the classical HLL and HLLC options in capturing contact and shear waves. The solutions produced by the original HLL Riemann solver are the most diffusive, which will lead to failure of resolving Kelvin-Helmholtz instability. The tests in this subsection demonstrate that the proposed HLL-BVD can work well in two dimensional problems whilst significantly improving the capability to solve contact discontinuities and associated fine flow structures.

F. Odd-even perturbation problem

It is well known that Riemann solvers which can accurately capture contact discontinuities usually suffer from spurious solutions, called carbuncle instabilities, in the vicinity of strong shock. Solving strong shock is especially important for problems involving reaction and heat

release⁴⁵⁻⁴⁸. In this case, the odd-even decoupling test originally proposed in¹³ is employed to examine the ability of the proposed HLL-BVD to obtain the stability of strong shocks. The computational domain consists of 51×26 elements. Initially, a steady normal shock of Mach=20 is set in the domain with initial conditions for left ($i \leq 39$) and right ($i \geq 41$) sides following Rankine-Hugoniot conditions. An intermediate state is prescribed at $i = 40$ where the internal shock conditions are given as $\rho_M = \lambda \rho_L + (1 - \lambda) \rho_R$ with other variables calculated based on ρ_M . A perturbation of shock along y-direction is produced by assigning different λ as

$$\lambda = \begin{cases} 0.2 & \text{if } j \text{ is odd} \\ 0.4 & \text{if } j \text{ is even} \end{cases} \quad (25)$$

The initial density contour of odd-even perturbation is presented in the first plot of Fig. 10. The CFL=0.5 is used. We examine the solutions from different Riemann solvers. The contour plots after 1×10^4 time steps and 4×10^4 time steps are presented in Fig. 10. The density distributions along x-direction in the middle of domain are also plotted in the Fig. 11. From these results, odd-even decoupling is clearly visible with HLLC, with which

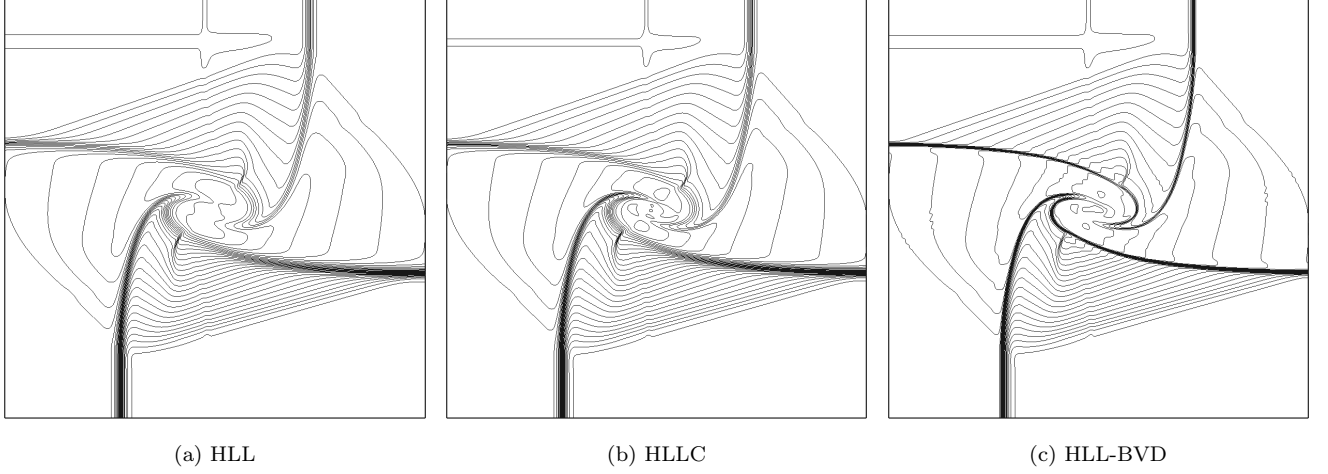


FIG. 8. Density contour for 2D Riemann problems with Case 1 initial condition. Solutions using uniform grids of 600×600 from different formulation for HLL-type Riemann solvers are presented.

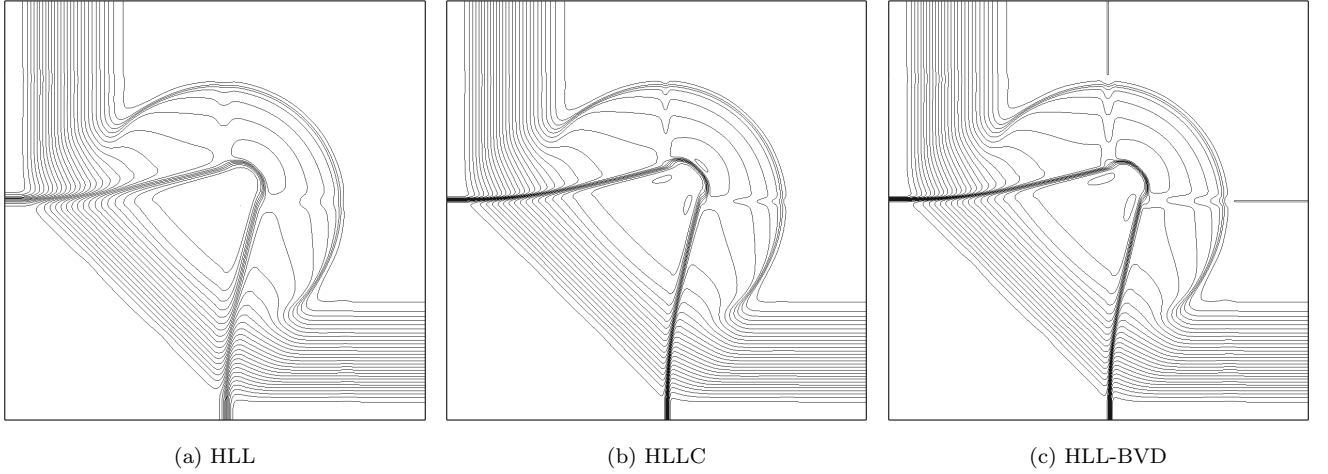


FIG. 9. Density contour for 2D Riemann problems with Case 2 initial condition. Solutions using uniform grids of 600×600 from different HLL-type Riemann solvers are presented.

original steady shock suffers from instabilities and dies out after 4×10^4 time steps. Whereas, HLL and proposed one are free from carbuncle instability. The test shows that the proposed formulation is more robust than HLLC when solving strong shocks.

G. Sedov blast wave problem

A spherically symmetric explosion, known as Sedov blast wave problem, is considered here. The computational domain is $[-1.1, 1.1] \times [-1.1, 1.1]$ with 160 grid elements in each direction. The initial conditions are given by $(\rho_0, u_0, v_0, p_0) = (1.0, 0.0, 0.0, 10^{-6})$ except in the central cell where an initial delta-function energy source was

set in terms of pressure as

$$p_c = (\gamma - 1)\rho_0 \frac{\epsilon_0}{V_c} \quad (26)$$

in which V_c denotes the volume of the cell containing the origin energy source and ϵ_0 is the total amount of released energy. In our numerical tests, the released energy is $\epsilon_0 = 0.244816$. The simulations are carried out up to time $t = 1.0$ at which the shock front reaches a radius of $R = 1$. Fig. 12 shows the numerical results obtained by the HLL, HLLC and the proposed method. As one can see, the results from the HLLC exhibit carbuncle instability across the shock front. Whereas, both HLL and the proposed method are capable of solving stable shock front. To make a quantitative comparison, we plot numerical solutions with different solvers and exact solution^{49–51} in Fig. 13. It is obvious that HLLC produces the largest numerical errors due to carbuncle

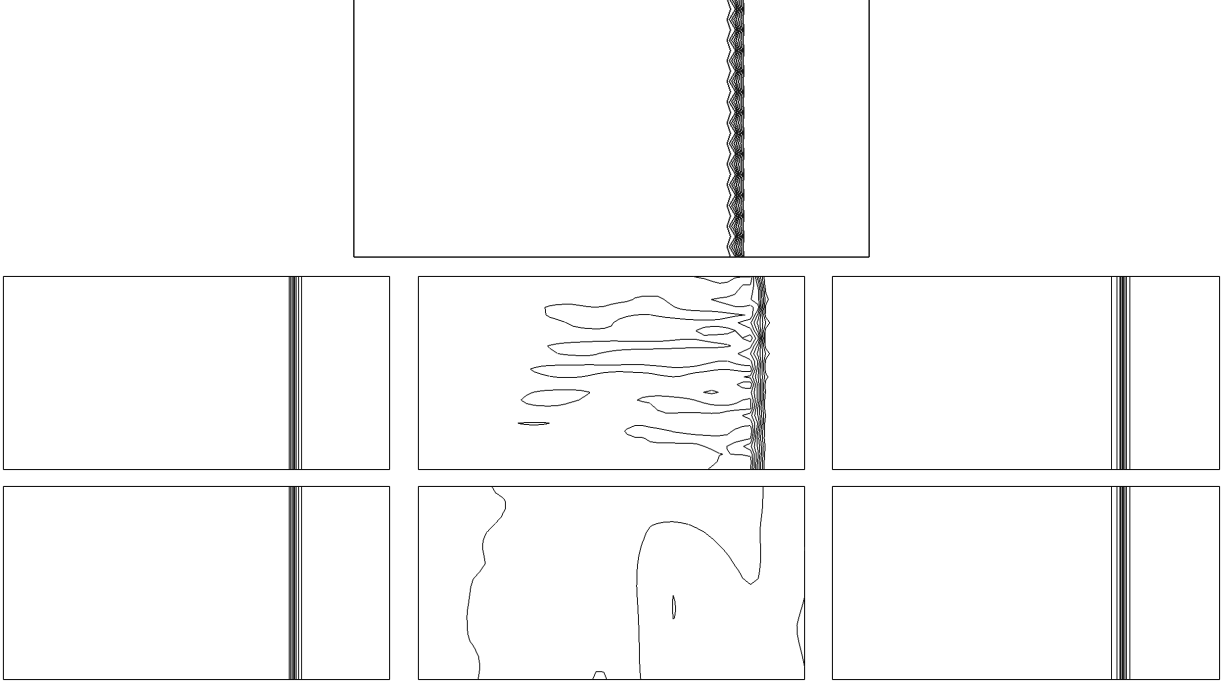


FIG. 10. Density contours for the odd-even perturbation problem as obtained with the HLL (left), HLLC (middle) and HLL-BVD (right) solvers. Initial condition (top), after 10000 (middle) and 40000 time steps.

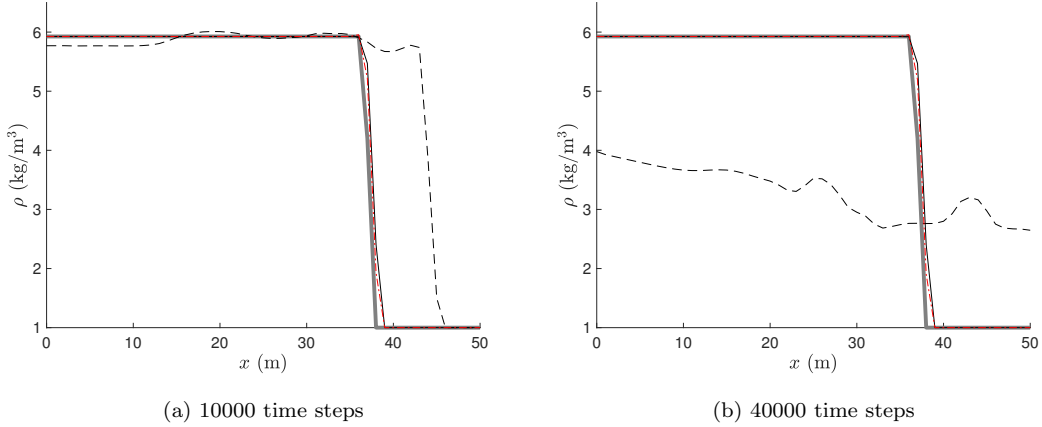


FIG. 11. Density distribution along x -direction in the middle of domain for the odd-even perturbation problem (Fig. 10), as obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. The reference solution is represented by the thick line. Numerical solutions after 10000 time steps are shown in (a), while after 40000 time steps are presented in (b).

issue.

H. Double Mach reflection

To further examine that the proposed HLL-type Riemann solver is free from carbuncle phenomenon, a $Ma = 10$ hypersonic propagating planar shock reflected by 30° ramp is simulated in this case. It is well known that the kinked Mach stem may occur due to carbuncle instability from Riemann solvers. This problem is proposed

in⁵². The computational domain is $[0, 3.2] \times [0, 1]$. A right-moving Mach 10 shock is imposed with 60° angle relative to x -axis. At the right boundary of the computational domain, the boundary condition is given by setting all gradients to be zero. The solution is computed up to $t = 0.2$ with different Riemann solvers. The results are displayed in Fig. 14. It is clearly visible that kinked Mach stem occurs in case of HLLC, which gives rise to spurious triple point and polluted region after shock. Whereas the spurious kinked Mach stem is completely eliminated with HLL or the proposed one. Moreover, the roll-up region

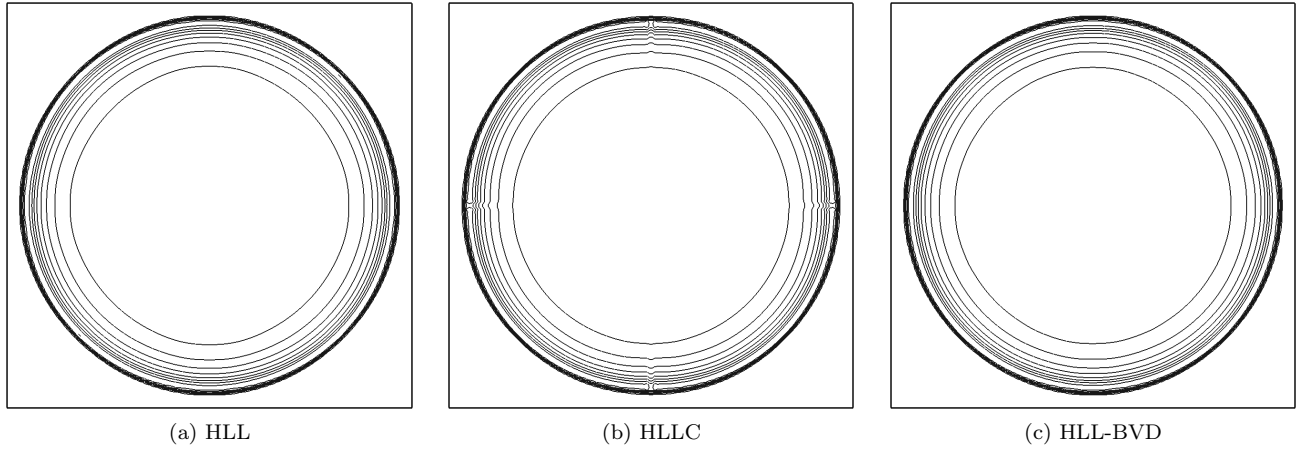


FIG. 12. Density contour calculated by different Riemann solvers until $t = 1.0$ for the Sedov blast wave problem. It is noted that in the x- and y-direction, some numerical oscillations caused by the carbuncle instability can be observed for HLLC.

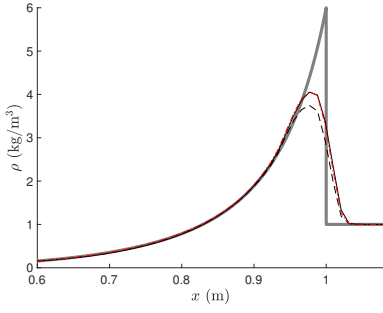


FIG. 13. The radial distribution of the density field for the Sedov blast wave problem, as obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. The reference solution is represented by the thick line.

around slip line is solved with less numerical diffusion by the new formulation compared with the original HLL.

I. Rayleigh-Taylor instability

Let us conclude the validation section with a simulation of the Rayleigh-Taylor instability problem^{53,54}. Initially, a single contact discontinuity separating two fluids with different densities is set at $y = 0.0$. A small perturbation is given to the velocity. Due to the density difference, the heavy fluid will accelerate into the light one. The Rayleigh-Taylor instability will develop as the spike of the heavy fluid falls into the light one and the bubble of the light fluid rises into the ambient heavy fluid. The computation domain is $[0, 0.25] \times [0, 1]$. The initial condition is given by

$$(\rho_0, u_0, v_0, p_0) = \begin{cases} (2, 0, -\tau \cos(8\pi x), 1 + 2y) & 0 \leq y \leq 0.5 \\ (1, 0, -\tau \cos(8\pi x), 1.5 + y) & \text{otherwise} \end{cases} \quad (27)$$

where $\tau = 0.025\sqrt{\gamma p/\rho}$, and the specific heat is chosen to be $\gamma = 5/3$ in this case. To model the effect of density difference, a source term ρ is added to the right hand of the momentum equations in the y-direction and a source term ρv is added to the energy equation. The computation is carried out up to the $t = 1.95s$ with 60×240 cell elements. As studied in^{34,53}, low-dissipation methods are essential to resolve the sharp contact and associated small scale structures due to Rayleigh-Taylor instability. We plot the density contour calculated by different Riemann solvers in the left panel of Fig. 15. Clearly HLL is the most diffusive solver and can not resolve sharp contact. Both HLLC and proposed HLL-BVD methods produce high resolution results. The proposed HLL-BVD method obtains sharper material interfaces compared with HLLC. To evaluate the numerical solution quantitatively, we plot the temporal evolution of the spike and bubble tip in the right panel of Fig. 15. As studied in⁵⁴, numerical solvers with excessive errors are not able to correctly predict the temporal evolution of instability. In our results, we find that HLL underestimates the evolution of bubble and spike characteristics due to excessive numerical dissipation errors. And the HLL and HLL-BVD produce very similar prediction.

IV. CONCLUDING REMARKS

This work proposes a novel formulation called HLL-BVD which is simultaneously capable of solving contact discontinuities accurately and of being free from shock instability. The missing contact in original HLL is restored with a jump-like THINC function. The resolution of contact wave is further improved by minimizing the dissipation term in HLL. Without modifying the waves structure explicitly, the robustness of original HLL has been preserved, as shown through one-dimensional and two-dimensional benchmark test cases. The new formulation significantly improves the resolution of contact wave

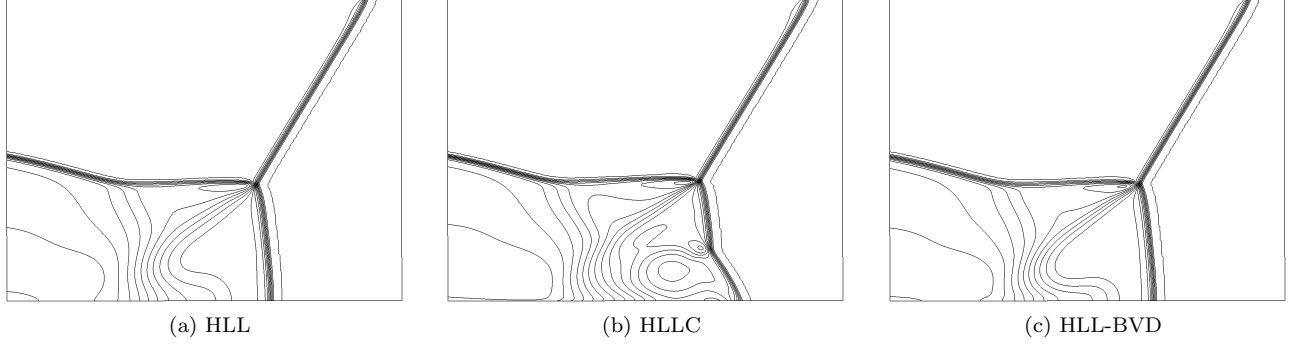


FIG. 14. Density contours for double Mach reflection at $t = 0.2$ with different Riemann solvers.

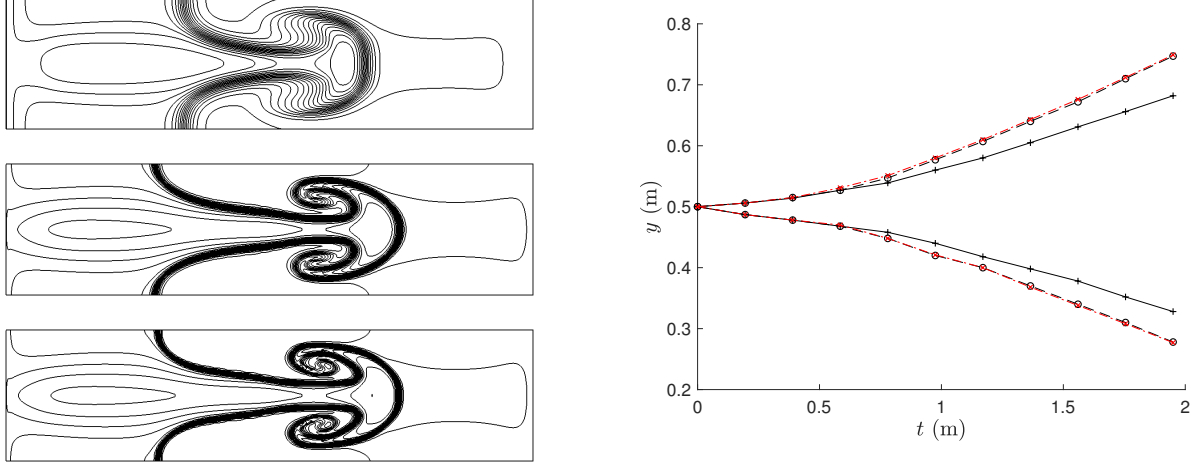


FIG. 15. Density contours for the Rayleigh-Taylor instability problem at $t = 1.95s$ with different Riemann solvers are shown in the left panel (HLL, HLLC and HLL-BVD from top to bottom). In the right panel, we show the temporal variation of bubble and spike tip positions for the Rayleigh-Taylor instability problems obtained with the HLL (solid), HLLC (dashed) and present (dot-dashed) solvers. Results from the HLLC and HLL-BVD solvers are practically indistinguishable.

and, most importantly, is free from carbuncle instability for strong shock.

Future work will investigate whether the reduced dissipation across the contact interface also improves the behavior of the HLL solver for the description of viscous flow, often penalized by excessive dissipation across the shear wave^{16,20}.

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