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A STOCHASTIC PDE MODEL FOR LIMIT ORDER BOOK DYNAMICS

RAMA CONT AND MARVIN S. MÜLLER

ABSTRACT. We propose an analytically tractable class of models for the dynamics of a limit order book, described as the solution of a stochastic partial differential equation (SPDE) with multiplicative noise. We provide conditions under which the model admits a finite dimensional realization driven by a (low-dimensional) Markov process, leading to efficient methods for estimation and computation. We study two examples of parsimonious models in this class: a two-factor model and a model in which the order book depth is mean-reverting. For each model we perform a detailed analysis of the role of different parameters, study the dynamics of the price, order book depth, volume and order imbalance, provide an intuitive financial interpretation of the variables involved and show how the model reproduces statistical properties of price changes, market depth and order flow in limit order markets.

MSC Classification: 35R60 60H15 91B26 91G80

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Financial instruments such as stocks and futures are increasingly traded in electronic, order-driven markets, in which orders to buy and sell are centralized in a *limit order book* and market orders are executed against the best available offers in the limit order book. The dynamics of prices in such markets are not only interesting from the viewpoint of market participants –for trading and order execution– but also from a fundamental perspective, since they provide a detailed view of the dynamics of supply and demand and their role in price formation.

The availability of a large amount of high frequency data on order flow, transactions and price dynamics on these markets has instigated a line of research which, in contrast to traditional market microstructure models which make assumptions on the behavior and preferences of various types of agents, focuses on the *statistical modeling* of aggregate order flow and its relation with price dynamics, in a quest to understand the interplay between price dynamics and order flow of various market participants (Cont, 2011).

A fruitful line of approach to these questions has been to model the stochastic dynamics of the *limit order book*, which centralizes all buy and sell orders, either as a queueing system (Lukock, 2003; Smith et al., 2003; Cont et al., 2010; Cont and De Larrard, 2012; Cont and de Larrard, 2013; Kelly and Yudovina, 2018) or, at a coarse-grained level, through a (stochastic) partial differential equation describing the evolution of the distribution of buy and sell orders (Lasry and Lions, 2007; Caffarelli et al., 2011; Burger et al., 2013; Carmona and Webster, 2013; Markowich et al., 2016; Hambly et al., 2018; Horst and Kreher, 2018). These PDE models may be viewed as scaling limits of discrete point process models (Cont and De Larrard, 2012; Hambly et al., 2018; Horst and Kreher, 2018).

Although joint modeling of order flow at all price levels in the limit order book is more appealing, (S)PDE models have lacked the analytical and computational tractability needed for applications; as a result, most analytical results have been derived using reduced-form models of the best bid-ask queues (Cont and De Larrard, 2012; Cont and de Larrard, 2013; Chavez-Casillas and Figueroa-Lopez, 2017; Huang et al., 2017).

We propose a class of stochastic models for the dynamics of the limit order book which represent the dynamics of the entire order book while retaining at the same time the analytical and computational tractability of low-dimensional Markovian models. Our model may be viewed as a stochastic –and analytically tractable– extension of the Lasry-Lions model adapted to the description of intraday dynamics of limit order books, with realistic dynamics for the market price and order book depth. Starting with a description of the dynamics of the limit order book via a stochastic partial differential equation (SPDE) with multiplicative noise, we show that in many cases, the solutions of this equation may be parameterized in terms of a low-dimensional diffusion process, which then makes the model computationally tractable. In particular, we are able to derive analytical relations between model parameters and various observable quantities. This feature may be used for calibrating model parameters to match statistical features of the order flow and leads to empirically testable predictions, which we proceed to test using high frequency time series of order flow in electronic equity markets.

Outline Section 1 introduces a description of the dynamics of a limit order book through a stochastic partial differential equation (SPDE). We describe the various terms in the equation, their interpretation and discuss the implications for price dynamics (Section 1.3). This class of models is part of a more general family of SPDEs driven by semimartingales, introduced in Sec. 1.5 and studied in Sec. 2.

We then focus on two analytically tractable examples: a two-factor model (Section 3) and a model with mean-reverting depth and imbalance (Section 4). For

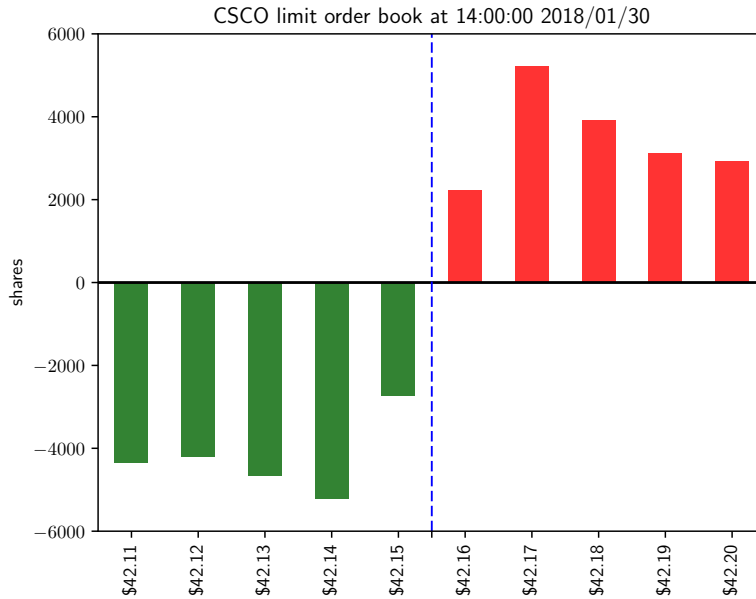


FIGURE 1. Snapshot of the NASDAQ limit order book for CISCO shares (Jan 30, 2018), displaying outstanding buy orders (green) and sell orders (red) awaiting execution at different prices. The highest buying price (\$ 42.15 in this example) is the *bid* and the lowest selling price (\$ 42.16) is the *ask*.

each model we perform a detailed analysis of the role of different parameters and study the dynamics of the price, order book depth, volume and order imbalance, provide an intuitive financial interpretation of the variables involved and show how the model may be estimated from financial time series of price, volume and order flow.

1. A STOCHASTIC PDE MODEL FOR LIMIT ORDER BOOK DYNAMICS

We consider a market for a financial asset (stock, futures contract, etc.) in which buyers and sellers may submit *limit orders* to buy or sell a certain quantity of the asset at a certain price, and *market orders* for immediate execution against the best available price.¹ Limit orders awaiting execution are collected in the *limit order book*, an example of which is shown in Figure 1: at any time t , the state of the limit order book is summarized by the volume $V(t, p)$ of orders awaiting execution at price levels p on a grid with mesh size given by the minimum price increment or *tick* size θ . By convention we associate negative volumes with buy orders and positive volumes with sell orders, as shown in Figure 1. An admissible order book configuration is then represented by a function $p \mapsto V(p)$ such that

$$0 < s^b(V) := \sup\{p > 0, \quad V(p) < 0\} \leq s^a(V) := \inf\{p > 0, \quad V(p) > 0\} < \infty.$$

$s^b(V)$ (resp. $s^a(V)$) is called the *bid* (resp. *ask*) price and represents the price associated with the best buy (resp. sell) offer. The quantity

$$S = \frac{s^a(V) + s^b(V)}{2}$$

¹In the following we do not distinguish market orders and marketable limit orders i.e. limit orders with a price better than the best price on the opposite side.

is called the *mid-price* and the difference $s^a(V) - s^b(V)$ is called the bid-ask spread. In the example shown in Figure 1, $s^b(V) = 42.15$, $s^a(V) = 42.16$ and the bid-ask spread is equal in this case to the tick size, which is 1 cent.

One modelling approach has been to represent the dynamics of $V(t, p)$ as a spatial (marked) point process (Luckock, 2003; Cont et al., 2010; Cont and de Larrard, 2013; Kelly and Yudovina, 2018). These models preserve the discrete nature of the dynamics at high frequencies but can become computationally challenging as one tries to incorporate realistic dynamics. In particular, price dynamics, which is endogenous in such models, is difficult to study, even when the order flow is a Poisson point process.

When the bid-ask spread and tick size θ are much smaller than the price level, as is often the case, another modelling approach is to use a continuum approximation for the order book, describing it through its *density* $v(t, p)$ representing the volume of orders per unit price:

$$V(t, p) \simeq v(t, p)\theta.$$

The evolution of the density of buy and sell orders is then described through a partial differential equation (PDE). A deterministic model of this type was proposed by (Lasry and Lions, 2007) and studied in detail by (Chayes et al., 2009; Caffarelli et al., 2011; Burger et al., 2013). In the Lasry-Lions model, the evolution of the density of buy and sell orders is described by a pair of diffusion equations coupled through the dynamics of the price, which represents the (free) boundary between prices of buy and sell orders. This model is appealing in many respects, especially in terms of analytical tractability, but leads to a deterministic price process so does not provide any insight into the relation between liquidity, depth, order flow and price volatility. (Markowich et al., 2016) explore some stochastic extensions of this model but show that these extensions do not provide realistic price dynamics.

We adopt here this continuum approach for the description of the limit order book, but describe instead its dynamics through a *stochastic* partial differential equation, paying close attention to price dynamics and its relation with order flow. The model we propose may be viewed as a stochastic extension of the Lasry-Lions model adapted to the description of intraday dynamics of limit order books, with realistic dynamics for the market price and order book depth. It relates to the classes of models studied in (Horst and Kreher, 2018; Hambly et al., 2018) as scaling limits of discrete queueing systems.

We now describe our model in some detail.

1.1. State variables and scaling transformations. We focus on the case where the tick size θ and the bid-ask spread are small compared to the typical price level and consider a limit order book described in terms of a mid-price S_t and the density $v(t, p)$ of orders at each price level p , representing buy orders for $p < S_t$, and sell orders for $p > S_t$. We use the convention, shown in Figure 1, of representing buy orders with a negative sign and sell orders with a positive sign, so

$$v(t, p) \leq 0 \quad \text{for } p < S_t \quad \text{and} \quad v(t, p) \geq 0 \quad \text{for } p > S_t$$

Limit orders are executed against market orders according to price priority and their position in the queue; execution of a limit order only occurs if they are located at the best (buy/sell) prices. This means that price dynamics is determined by the interaction of market orders with limit orders of opposite type at or near the *interface* defined by the best price (Cont et al., 2010). Due to this fact, most limit orders flow are submitted close to the the best price levels: the frequency of limit order submissions is highly inhomogeneous as a function of distance to the best price and concentrated near the best price. As shown in previous empirical studies, order flow intensity at a given distance from the best price can be considered as

a stationary variable in a first approximation (Bouchaud et al., 2009; Cont et al., 2010). For this reason, in a stochastic description it is more convenient to model the dynamics of order flow in the reference frame of the (mid-)price S_t . We define

$$u_t(x) = v(t, S_t + x)$$

where x represents a distance from the mid-price. We refer to u_t as the *centered* order book density.

The simplest way of centering is to set $x(p) = p - S_t$ but other, nonlinear, scalings may be of interest. Although limit orders may be placed at any distance from the bid/ask prices, price dynamics is dominated by the behavior of the order book a few levels above and below the mid price (Cont and De Larrard, 2012). This region becomes infinitesimal if the tick size θ is naively scaled to zero, suggesting that the correct scaling limit is instead one in which we choose as coordinate a scaled version $(p - S_t)$, as classically done in boundary layer analysis of PDEs (Schlichting and Gersten, 2017), in order to zoom into the relevant region:

$$(1.1) \quad x(p) := -(S_t - p)^a, \quad p < S_t, \quad x(p) = (p - S_t)^a, \quad p > S_t, \quad a > 0$$

for bid and ask side, respectively. We will consider examples of such nonlinear scalings when discussing applications to high-frequency data in Sections 3 and 4.

These arguments also justify limiting the range of the argument x to a bounded interval $[-L, +L]$, setting $u_t(x) = 0$ for $x \notin (-L, L)$. This amounts to assuming that no orders are submitted at price levels at distances $|x| \geq L$ from the mid-price and that orders previously submitted at some price p are cancelled as soon as $|S_t - p| \geq L$ i.e. when the mid-price S_t moves away from p by more than L .

1.2. Dynamics of the centered limit order book. Empirical studies on intraday order flow in electronic markets reveal the coexistence of two, very different types of order flow operating at different frequencies (Lehalle and Laruelle, 2018).

On one hand, we observe the submission (and cancellation) of orders queuing at various price levels on both sides of the market price by regular market participants. Cancellation may occur in several ways: we distinguish *outright* cancellations, which we model as proportional to current queue size, from cancellations with replacement ('order modifications'), in which an order is cancelled and immediately replaced by another one of the same type, usually at a neighboring price limit. The former results in a net decrease in the volume of the order book whereas the latter is *conservative* and simply shifts orders across neighboring levels of the book. Further decomposing this conservative flow into a symmetric and antisymmetric part leads to two terms in the dynamics of u_t : a *diffusion* term representing the cancellation of orders and their (symmetric) replacement by orders at neighboring price levels and a *convection* (or transport) term representing the cancellation of orders and their replacement by orders closer to the mid-price. The net effect of this order flow on the order book may thus be described as a superposition of

- ▶ a term $f^b(x)$ (resp. $f^a(x)$) representing the rate of buy (resp. sell) order submissions at a distance x from the best price;
- ▶ a term $\alpha^b u_t$ (resp. $\alpha^a u_t$) representing (outright) proportional cancellation of limit buy (resp. sell) orders at a distance x from the mid-price. (where $\alpha^a, \alpha^b \leq 0$).
- ▶ a convection term $-\beta^b \nabla u_t(x)$ (resp. $+\beta^a \nabla u_t(x)$) with $\beta^a, \beta^b > 0$ which models the replacement of buy (resp. sell) orders by orders closer to the mid-price (which corresponds to $x = 0$, hence the signs in these terms).
- ▶ a diffusion term $\eta^b \Delta u_t(x)$ (resp. $\eta^a \Delta u_t(x)$) which represents the cancellation and symmetric replacement of orders at a distance x from the mid-price.

Another component of order flow is the one generated by high-frequency traders (HFT). These market participants buy and sell at very high frequency and under tight inventory constraints, submitting and cancelling large volumes of limit orders near the mid-price and resulting in an order flow whose net contribution to total order book volume is zero on average over longer time intervals but whose sign over small time intervals fluctuates at high frequency. At the coarse-grained time scale of the average (non-HF) market participants, these features may be modeled as a multiplicative noise term of the form

► $\sigma^b u_t(x) dW^b$ for buy orders ($x < 0$) and $\sigma^a u_t(x) dW^a$ for sell orders ($x > 0$) where (W^a, W^b) is a two-dimensional Wiener process (with possibly correlated components). The multiplicative nature of the noise accounts for the high-frequency cancellations associated with HFT orders.

The impact of these different order flow components may be summarized by the following stochastic partial differential equation for the centered order book density u :

$$\begin{aligned} du_t(x) &= [\eta^a \Delta u_t(x) + \beta^a \nabla u_t(x) + \alpha^a u_t(x) + f^a(x)] dt + \sigma^a u_t(x) dW_t^a, & x \in (0, L), \\ du_t(x) &= [\eta^b \Delta u_t(x) - \beta^b \nabla u_t(x) + \alpha^b u_t(x) - f^b(x)] dt + \sigma^b u_t(x) dW_t^b, & x \in (-L, 0) \\ &u_t(x) \leq 0, \quad x < 0, & u_t(x) \geq 0, \quad x > 0, \\ (1.2) \quad &u_t(0+) = u_t(0-) = 0, & u_t(-L) = u_t(L) = 0 \end{aligned}$$

Here $\eta^a, \eta^b, \beta^b, \beta^a, \sigma^a, \sigma^b \in (0, \infty)$, $\alpha^a, \alpha^b \leq 0$ and $f^a, f^b: I \rightarrow [0, \infty)$ although the equation may be equally considered without these sign restrictions.

Note that, unlike the Lasry-Lions model, there is no ‘smooth pasting’ condition at $x = 0$: in general $\nabla u_t(0+) \neq \nabla u_t(0-)$: the difference $\nabla u_t(0+) - \nabla u_t(0-)$ is in fact random and represents an imbalance in the flow of buy and sell orders, which drives price dynamics. This important feature is discussed in Section 1.3 below.

The existence of a solution satisfying the boundary and sign constraints is not obvious but we will see in Section 2 that (1.2) is well-posed: it follows from (Da Prato and Zabczyk, 2014, Theorem 6.7) and (Milian, 2002, Theorem 3) that, when $f_a, f_b \in L^2(I)$, then for all $u_0 \in L^2(I)$ there exists a unique weak solution of (1.2) (see Definition 2.2 below) and, when $u_0|_{(0,L)} \geq 0$ and $u_0|_{(-L,0)} \leq 0$ this solution satisfies

$$(1.3) \quad u_t|_{(0,L)} \leq 0, \quad u_t|_{(-L,0)} \geq 0.$$

We will study the mathematical properties of the solution in more detail below.

1.3. Endogenous price dynamics. The dynamics of the limit order book determines the dynamics of the bid and ask price, which corresponds to the location of the best (buy and sell) orders. The dynamics of the price should thus be endogenous and determined by the arrival and execution of orders in the order book.

To derive the relation between price dynamics and order flow, consider first an order book with k (price) levels, multiples of a tick size θ , D^b orders per level on the bid side and D^a orders per level on the ask side. An order flow imbalance of $OFI(t, t + \Delta t) > 0$ accumulated over a short time interval $[t, t + \Delta t]$ represents an excess of buy orders, which will then be executed against limit sell orders sitting on the ask side and move the ask price by $OFI(t, t + \Delta t)/D^a$ ticks (see Figure 2), resulting in a price move of $\theta OFI(t, t + \Delta t)/D^a$. This leads to the following dynamics for the price:

$$(1.4) \quad \begin{aligned} \Delta s_t^a &= \theta \frac{OFI(t, t + \Delta t)}{D_t^a} & \text{if } OFI(t, t + \Delta t) > 0 \\ \Delta s_t^b &= \theta \frac{OFI(t, t + \Delta t)}{D_t^b} & \text{if } OFI(t, t + \Delta t) < 0 \end{aligned}$$

where D_t^b, D_t^a represent the (bid,ask) depth (number of shares per level) at the top of the book and θ is the tick size. The dynamics of the mid price $S_t = (s_t^b + s_t^a)/2$ is then given by

$$(1.5) \quad \Delta S_t = \frac{\theta}{2} \left(\frac{\Delta D_t^b}{D_t^b} - \frac{\Delta D_t^a}{D_t^a} \right).$$

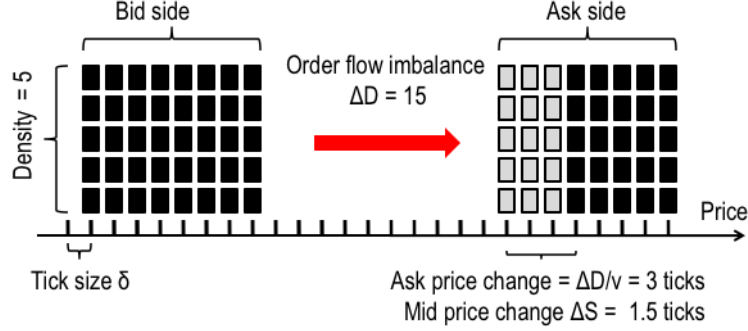


FIGURE 2. Impact of order flow imbalance on the order book and the price.

Let us now see how the relation (1.5) translates in terms of the variables in our model. Denoting by D_t^b (resp. D_t^a) the volume of buy (resp. sell) limit orders at the top of the book (i.e. the first or average of the first few levels) the order flow imbalance is given by

$$\text{OFI}(t, t + dt) = dD_t^b - dD_t^a.$$

Assume that the spread is constant and equal to the tick size $\theta > 0$, as is the case most of the times for ‘large tick’ assets (Cont, 2011). Given a mid-price $S \in \mathbb{R}$, we define a scaling transformation $x: [S, S + L] \rightarrow [0, \infty)$ as discussed in Section 1.1, with continuously differentiable inverse and such that $x(s) = 0$. The volumes in the best bid and ask queue D^b and D^a are then given by

$$(1.6) \quad D^a = \int_s^{s+\theta} u(x(p)) dp = \int_0^{x(s+\theta)} u(y)(x^{-1})'(y) dy.$$

This quantity represents the depth at the top of the book; we will refer to them as ‘market depth’. We will see later that the depth can be computed explicitly in many cases. In the special case of linear scaling i.e. when $x(p) = p - s$, using $u(0) = 0$ a second order expansion in $\theta > 0$ yields

$$(1.7) \quad D^a = \int_0^\theta u(x) dx \approx \theta u(0+) + \frac{\theta^2}{2} \nabla u(0+) = \frac{\theta^2}{2} \nabla u(0+).$$

Similarly, for the bid side

$$(1.8) \quad D^b \approx \frac{\theta^2}{2} \nabla u(0-).$$

Substituting these expressions in (1.5), we obtain the following equation for the dynamics of the mid-price:

$$(1.9) \quad dS_t = c_s \theta \left(\frac{dD_t^b}{D_t^b} - \frac{dD_t^a}{D_t^a} \right) = c_s \theta \left(\frac{d\nabla u_t(0-)}{\nabla u_t(0-)} - \frac{d\nabla u_t(0+)}{\nabla u_t(0+)} \right).$$

We observe that price dynamics is entirely determined by the order flow at the top of the book and the depth of the limit order book around the mid-price.

Remark 1.1. Equation (1.9) requires left and right-differentiability of u at the origin. This can be guaranteed whenever u_t takes values in the Sobolev space $H^{2\gamma}(I)$, for some $\gamma > 3/4$ which will be the case in our model. However, note that in general $\nabla u(0+) \neq \nabla u(0-)$.

1.4. Dynamics in price coordinates. The model above describes dynamics of the order book in *relative* price coordinates, i.e. as a function of the (scaled) distance from the mid-price. The density of the limit order book parameterized by the (absolute) price level $p \in \mathbb{R}$ is given by

$$(1.10) \quad v_t(p) = u_t(p - S_t), \quad x \in \mathbb{R},$$

where we extend u_t to \mathbb{R} by setting $u_t(y) = 0$ for $y \in \mathbb{R} \setminus [-L, L]$. Using a (generalized) Ito-Wentzell formula, (see Appendix A), we can show that v may be described as the solution of a *stochastic moving boundary problem* (Mueller, 2016)

$$(1.11) \quad \begin{aligned} dv_t(p) = & \left[(\eta_a + \frac{1}{2}\sigma_s^2) \Delta v_t(p) \right. \\ & + (\nu_b - \nu_a + \beta_a - c_s \theta (\varrho_{a,b} \sigma_b \sigma_a - \sigma_a^2)) \nabla v_t(p) + \alpha_a v_t(p) \left. \right] dt \\ & + (\sigma_a v_t(p) + c_s \theta \sigma_a \nabla v_t(p)) dW_t^a - c_s \theta \sigma_b \nabla v_t(p) dW_t^b, \end{aligned}$$

for $p \in (S_t, S_t + L)$, and

$$(1.12) \quad \begin{aligned} dv_t(p) = & \left[(\eta_b + \frac{1}{2}\sigma_s^2) \Delta v_t(p) \right. \\ & + (\nu_b - \nu_a - \beta_b - c_s \theta (\sigma_b^2 - \varrho_{a,b} \sigma_b \sigma_a)) \nabla v_t(x) + \alpha_b v_t(p) \left. \right] dt \\ & + c_s \theta \sigma_a \nabla v_t(p) dW_t^a + (\sigma_b v_t(p) - c_s \theta \sigma_b \nabla v_t(p)) dW_t^b \end{aligned}$$

for $x \in (S_t - L, S_t)$ with the moving boundary conditions

$$(1.13) \quad v_t(S_t) = 0, \quad v_t(y) = 0, \quad \forall y \in \mathbb{R} \setminus (S_t - L, S_t + L),$$

Note that (3.36) is a *stochastic boundary condition* at S_t .

A more detailed discussion of this result is given in Appendix A, using Krylov's extended Ito-Wentzell formula (Krylov, 2011, Theorem 1.1).

1.5. Linear evolution models for order book dynamics. We will now describe a more general class of linear models for order book dynamics, rich enough to cover the examples we discussed so far, but also covering all level-1 models where the best bid and ask queue are modeled by positive semimartingales. Generally, the densities of orders in the bid and ask side will take values in some function spaces H^b and H^a , respectively. We assume that orders at relative price level x for $|x| \geq L \in (0, \infty]$ will be cancelled. The relative price levels are on the bid side $I^b := (-L, 0)$, and on the ask side $I^a := (0, L)$. Then, in order to preserve the interpretation of a density it will be reasonable to ask $H^b \subset L_{loc}^1(I^b)$ and $H^a \subset L_{loc}^1(I^a)$. From mathematical side, we will assume that H^a and H^b are real separable Hilbert spaces. For notational convenience we now also set $I := I^b \cup I^a$.

The density of limit orders at relative price level x and time t is given by $u: I \times [0, \infty) \times \Omega \rightarrow \mathbb{R}$, such that $u^* := u|_{I^*}$ is an H^* -valued adapted process. The initial state is described by $h: I \rightarrow \mathbb{R}$, such that $h^* := h|_{I^*}$ is an element in H^* . The (averaged) intra-book dynamics are modeled by linear operators $A_*: \text{dom}(A_*) \subset H^* \rightarrow H^*$, for $\star \in \{a, b\}$, which we assume to be densely defined and such that for $\star \in \{a, b\}$ there exist weak solutions in H^* of the equations

$$(1.14) \quad \frac{\partial}{\partial t} g_t^*(h^*) = A_* g_t^*(h^*), \quad t > 0, \quad g_0^*(h^*) = h^*,$$

for each initial state $h^* \in H^*$.

The random order arrivals and cancellations are assumed to be proportional and are modelled by cadlag semimartingales X^b and X^a , which we assume to have

jumps greater than -1 almost surely. We assume the initial order book state is denoted by $h \in H$ and we write $h^a := h|_{I^a}$, $h^b := h|_{I^b}$.

Model 1.2 (Linear Homogeneous Evolution). The general form of the linear homogeneous model is

$$(1.15) \quad \begin{cases} du_t^b = A_b u_{t-}^b dt + u_{t-}^b dX_t^b, & \text{on } I^b, \\ du_t^a = A_a u_{t-}^a dt + u_{t-}^a dX_t^a, & \text{on } I^a, \end{cases}$$

for $t \geq 0$, and $u_0 = h$. u can be alternatively expressed as

$$(1.16) \quad u_t = g_t^b(h^*)\mathcal{E}_t(X^b)\mathbf{1}_{I^b} + g_t^a(h^*)\mathcal{E}_t(X^a)\mathbf{1}_{I^a},$$

where g^b and g^a are solutions of (1.14), see Theorem 2.5 below. If, in addition, $t \mapsto \nabla g_t^b(0-)$ and $t \mapsto \nabla g_t^a(0+)$ are of bounded variation, then we obtain the price dynamics (1.9).

Corollary 1.3. *Assume the setting of Model 1.2 and, in addition, that h^* is an eigenfunction of $-A_*$ with eigenvalue $\nu_* \in \mathbb{R}$, for $\star = b$ and $\star = a$. Then, (1.14) can be solved explicitly and*

$$(1.17) \quad u_t = h^b e^{-\nu_b t} \mathcal{E}_t(X^b)\mathbf{1}_{I^b} + h^a e^{-\nu_a t} \mathcal{E}_t(X^a)\mathbf{1}_{I^a}.$$

Remark 1.4. In case that X^b and X^a are (local) martingales, the eigenvalues $-\nu_b$ and $-\nu_a$ play the role of net order arrival rates on bid and ask side, respectively.

Model 1.5 (Linear models with source terms). A more realistic setting assumes in addition an influx/outflow of orders at a rate $f^a(x), f^b(x)$ which depends on the distance x to the mid price (Cont et al., 2010). The equation then becomes:

$$(1.18) \quad \begin{cases} du_t^b = (A_b u_t^b + f^b) dt + u_t^b dX_t^b, & \text{on } I^b, \\ du_t^a = (A_a u_t^a + f^a) dt + u_t^a dX_t^a, & \text{on } I^a, \end{cases}$$

for $t \geq 0$, with initial condition $u_0 = h$.

As we will discuss in Section 4, an interesting case is when f^b (resp. f^a) is an eigenfunction of $-A^b$ (resp. $-A^a$) associated with some eigenvalue ν_b (resp. ν_a). Then by Theorem 2.10 we obtain

$$(1.19) \quad u_t = (g_t^b(h^b - f^a)\mathcal{E}_t(X^b) + f^b Z_t^b)\mathbf{1}_{I^b} + (g_t^a(h^a - f^a) + f^a Z_t^a)\mathbf{1}_{I^a},$$

where, for $\star \in \{a, b\}$, Z_t^* is the solution of

$$(1.20) \quad dZ_t^* = (1 - \nu_* Z_{t-}^*) dt + Z_{t-}^* dX_t^*, \quad t \geq 0, \quad Z_0^* = 1.$$

Remark 1.6. If $\nu_b, \nu_a > 0$ the state of the order book is mean reverting to the state $f^b \mathbf{1}_{[-L, 0)} + f^a \mathbf{1}_{(0, L]}$. We will give an example of such a mean-reverting order book model in Section 4.

Example 1.7 (Reduced form order book models). Reduced form order book models (Cont and De Larrard, 2012; Cont and de Larrard, 2013; Chavez-Casillas and Figueroa-Lopez, 2017; Huang et al., 2017) focus on the dynamics of best bid/ask queues. We can recover this class of models as a special case of our framework by choosing $L := \theta$ to be the tick size, $H^a := L^2(0, L)$, $H^b := L^2(-L, 0)$, $A_a := 0$, $A_b := 0$. Let $V_0^a, V_0^b > 0$ be the initial volume in the best ask and bid queue and Z_t^a, Z_t^b be positive real-valued semimartingales with $Z_0^a = Z_0^b = 1$. We thus obtain a general class of reduced form models as a subclass of 1.2:

$$(1.21) \quad u_t = \mathbf{1}_{(0, L)} V_0^a Z_t^a - \mathbf{1}_{(-L, 0)} V_0^b Z_t^b.$$

Remark 1.8. Any model for the dynamics of the order book implies a model for price dynamics via (1.9). In particular this implies a relation between price volatility and parameters describing order flow, in the spirit of (Cont and de Larrard, 2013).

We will derive this relation for the examples studied in the sequel and use it to construct a model-based intraday volatility estimator.

In the next section, we will study this class of models from a mathematical point of view. We will then continue with the analysis of the two examples mentioned above in Sections 3 and 4.

2. LINEAR SPDE MODELS WITH MULTIPLICATIVE NOISE

In order to further study the properties of the SPDE model (1.2), we require a more explicit characterization of the solution, in order to compute various quantities of interest and estimate model coefficients from observations. A useful approach is to look for a finite dimensional realization of the infinite-dimensional process u :

Definition 2.1 (Finite dimensional realizations). A process $u = (u_t)_{t \geq 0}$ taking values in an (infinite-dimensional) function space E is said to admit a *finite dimensional realization* of dimension $d \in \mathbb{N}$ if there exists an \mathbb{R}^d -valued stochastic process $Z = (Z^1, \dots, Z^d)$ and a map

$$\phi : \mathbb{R}^d \rightarrow E \quad \text{such that} \quad \forall t \geq 0, \quad u_t = \phi(Z_t).$$

Availability of a finite dimensional realization for the SPDE (1.2) makes simulation, computation and estimation problems more tractable, especially if the process Z is a low-dimensional Markov process. Existence of such finite-dimensional realizations for stochastic PDEs have been investigated for SPDEs arising in filtering (Lévine, 1991) and interest rate modelling (Filipovic and Teichmann, 2003; Gaspar, 2006).

We will now show that finite dimensional realizations may indeed be constructed for a class of SPDEs which includes (1.2), and use this representation to perform an analytical study of these models.

2.1. Homogeneous equations. We now consider a more general class of linear homogeneous evolution equations with multiplicative noise taking values in a real separable Hilbert space $(H, \langle \cdot, \cdot \rangle_H)$. Typically, H will be a function space such as $L^2(I)$ for some interval $I \subset \mathbb{R}$. We consider the following class of evolution equations:

$$(2.1) \quad \begin{aligned} du_t &= Au_{t-} dt + u_{t-} dX_t, & t > 0, \\ u_0 &= h_0 \in H. \end{aligned}$$

where X is a real càdlàg semimartingale whose jumps satisfy $\Delta X_t > -1$ a. s. and $A: \text{dom}(A) \subset H \rightarrow H$ a linear operator on H whose adjoint we denote A^* . We assume that $\text{dom}(A) \subset H$ is dense, and A is closed. Since A is closed we have that also $\text{dom}(A^*) \subset H$ is dense and that $A^{**} = A$ (Yosida, 1995, Theorem VII.2.3).

Definition 2.2. An adapted H -valued stochastic process (u_t) is an (*analytical*) *weak solution* of (2.1) with initial condition h_0 if, for all $\varphi \in \text{dom}(A^*)$, $[0, \infty) \ni t \mapsto \langle u_t, \varphi \rangle_H \in \mathbb{R}$ is càdlàg a. s. and for each $t \geq 0$, a. s.

$$\langle u_t, \varphi \rangle_H - \langle h_0, \varphi \rangle_H = \int_0^t \langle u_{s-}, A^* \varphi \rangle_H ds + \int_0^t \langle u_{s-}, \varphi \rangle_H dX_s.$$

The case $X \equiv 0$ corresponds to a notion of weak solution for the PDE:

$$(2.2) \quad \forall t > 0, \quad \frac{\partial}{\partial t} g_t = Ag_t \quad g_0 = h_0.$$

That is, for all $\varphi \in \text{dom}(A^*)$,

$$(2.3) \quad \langle g_t, \varphi \rangle_H - \langle h_0, \varphi \rangle_H = \int_0^t \langle g_s, A^* \varphi \rangle_H ds,$$

where the integral on the right hand side is assumed to exist.² In particular, this yields that $[0, \infty) \ni t \mapsto \langle g_t, \varphi \rangle_H \in \mathbb{R}$ is continuous.

Remark 2.3. By considering bid and ask side separately, we can bring (1.2) into the form of (2.1), where X is a Brownian motion and A is given by $A := \eta \Delta \pm \beta \nabla + \alpha \text{Id}$ on $H := L^2(I)$, $I := (0, L)$ or $I := (-L, 0)$, with domain

$$\text{dom}(A) := H^2(I) \cap H_0^1(I),$$

where $H_0^1(I)$ is the closure in $H^1(I)$ of test functions with compact support in I .

Denote by $Z_t = \mathcal{E}_t(X)$ the stochastic exponential of X . We recall the following useful lemma:

Lemma 2.4. *Let*

$$(2.4) \quad Y_t := -X_t + [X, X]_t^c + \sum_{s \leq t} \frac{(\Delta X_s)^2}{1 + \Delta X_s}, \quad t \geq 0,$$

Then, $\mathcal{E}_t(X)\mathcal{E}_t(Y) = 1$ almost surely, for all $t \geq 0$. Moreover,

$$(2.5) \quad [X, Y] = -[X, X]^c - \sum_{s \leq \cdot} \frac{(\Delta X_s)^2}{1 + \Delta X_s}.$$

Proof. The first part is shown e. g. in (Karatzas and Kardaras, 2007, Lemma 3.4). Recall that $[X, X]_t = [X, X]_t^c + \sum_{s \leq t} (\Delta X_s)^2$ so

$$\begin{aligned} [X, Y]_t &= -[X, X]_t^c - \sum_{s \leq t} \frac{(\Delta X_s)^2 + (\Delta X_s)^3}{1 + \Delta X_s} + \sum_{s \leq t} \frac{(\Delta X_s)^3}{1 + \Delta X_s} \\ &= -[X, X]_t^c - \sum_{s \leq t} \frac{(\Delta X_s)^2}{1 + \Delta X_s}. \quad \square \end{aligned}$$

Theorem 2.5. *Let $Z := \mathcal{E}(X)$, $h_0 \in H$. Then every weak solution of (2.1) is of the form*

$$u_t := Z_t g_t, \quad t \geq 0$$

where g is a weak solution of (2.2).

Remark 2.6. In particular, the SPDE (2.1) admits a two dimensional realization in the sense of Definition 2.1 with factor process $(t, \mathcal{E}_t(X))$ and $\phi(t, y) := yg_t$.

Proof. Set $u_t := g_t Z_t$, $t \geq 0$, and for $\varphi \in D(A^*)$ write $B_t^\varphi := \langle g_t, \varphi \rangle_H$, $C_t^\varphi := B_t^\varphi Z_t = \langle u_t, \varphi \rangle_H$. Since $t \mapsto \langle g_t, \varphi \rangle_H$ is continuous and Z is scalar and càdlàg, we get that $t \mapsto \langle u_t, \varphi \rangle_H$ is càdlàg. Note that B^φ is of finite variation and Z is a semimartingale, so that also C^φ is a semimartingale. Moreover, by Itô product rule and since B^φ is of finite variation and continuous,

$$(2.6) \quad dC_t^\varphi = B_t^\varphi dZ_t + Z_{t-} dB_t^\varphi = B_{t-}^\varphi Z_{t-} dX_t + \langle u_{t-}, A^* \varphi \rangle_H dt,$$

which is (2.1). Now, let u be a solution of (2.1) and set

$$Y := -X + [X, X]^c + J, \quad J := \sum_{s \leq \cdot} \frac{(\Delta X_s)^2}{1 + \Delta X_s},$$

and $Z_t := \mathcal{E}_t(Y)$, $t \geq 0$. Recall that by Lemma 2.4 we have $Z_t \mathcal{E}_t(X) = 1$ for all $t \geq 0$. Set $g_t := Z_t u_t$, and, as above, fix $\varphi \in \text{dom}(A^*)$ and write $B_t^\varphi := \langle u_t Z_t, \varphi \rangle_H =$

²Note that this slightly differs from the classical formulation of weak solutions for PDEs.

$\langle g_t, \varphi \rangle_H$ and $C_t^\varphi := \langle u_t, \varphi \rangle_H$. By Ito's product rule and Lemma 2.4,

$$\begin{aligned} dB_t^\varphi &= C_{t-}^\varphi dZ_t + Z_{t-} dC_t^\varphi + d[C^\varphi, Z]_t \\ &= C_{t-}^\varphi Z_{t-} dY_t + Z_{t-} \langle u_{t-}, A^* \varphi \rangle_H dt + C_{t-}^\varphi Z_{t-} dX_t + C_{t-}^\varphi Z_{t-} d[X, Y]_t \\ &= \langle g_{t-}, A^* \varphi \rangle_H dt + B_{t-}^\varphi (d[X, X]_t^c + dJ_t) - B_{t-}^\varphi (d[X, X]_t^c + dJ_t) \\ &= \langle g_{t-}, A^* \varphi \rangle_H dt. \end{aligned}$$

Thus, g is a weak solution of (2.2). \square

Example 2.7. Let A be the generator of a strongly continuous semigroup $(S_t)_{t \geq 0}$. Then, for $h_0 \in H$ define

$$g_t := S_t h_0, \quad t \geq 0,$$

which is a weak solution of (2.2). By Theorem 2.5.

$$u_t := \mathcal{E}_t(X) S_t h_0, \quad t \geq 0,$$

is a weak solution of (2.1).

Remark 2.8. If h_0 is an eigenfunction of A with eigenvalue ν , then, $g_t = e^{\nu t} h_0$ is the unique locally H -integrable solution of (2.2), and the unique solution of (2.1) is given by

$$u_t := h_0 e^{\nu t} \mathcal{E}_t(X).$$

2.2. Inhomogeneous equations. We keep the assumptions on A , h_0 and X from the previous section and let $f \in H$. We now consider the inhomogeneous linear evolution equations

$$(2.7) \quad \begin{aligned} du_t &= [Au_t + \alpha f] dt + u_{t-} dX_t, \quad t \geq 0, \\ u_0 &= h_0. \end{aligned}$$

Definition 2.9. A weak solution of (2.7) is an adapted H -valued stochastic process u such that for all $\varphi \in \text{dom}(A^*)$ the mapping $[0, \infty) \ni t \mapsto \langle u_t, \varphi \rangle_H$ is càdlàg and

$$\langle u_t, \varphi \rangle_H - \langle h_0, \varphi \rangle_H = \int_0^t \langle u_{s-}, A^* \varphi \rangle_H ds + \int_0^t \langle u_{s-}, \varphi \rangle_H dX_s + t\alpha \langle f, \varphi \rangle_H, \quad t \geq 0,$$

almost surely. In particular, all the integrals are assumed to exist.

We exclude the cases $\alpha = 0$ or $f \equiv 0$ which correspond to the homogeneous case discussed above. Let us first consider the case where A admits at least one eigenfunction.

Theorem 2.10. *Suppose that $f \in \text{dom}(A)$ is an eigenfunction for A with eigenvalue $\lambda \in \mathbb{R}$, let $z_0 > 0$ and Z be the solution of*

$$(2.8) \quad dZ_t = (\lambda Z_{t-} + \alpha) dt + Z_{t-} dX_t, \quad t \geq 0, \quad Z_0 = z_0.$$

Then:

- (i) *The stochastic process defined by $u_t = Z_t f$, $t \geq 0$, is a solution of (2.7) with initial condition $h_0 := z_0 f$.*
- (ii) *Let, in addition, $h_0 \in H$ be such that there exists a weak solution $g = (g_t)_{t \geq 0}$ of the deterministic equation*

$$(2.9) \quad \frac{\partial}{\partial t} g_t = Ag_t, \quad t \geq 0 \quad g_0 = h_0 - z_0 f.$$

Then, $u_t := g_t \mathcal{E}_t(X) + f Z_t$ is a solution of (2.7) with initial condition h_0 .

- (iii) *Let $h_0 \in H$ be such that there exists a weak solution $u = (u_t)_{t \geq 0}$ of (2.7) with initial condition h_0 . Then, $g := (u - fZ) \mathcal{E}(X)^{-1}$, is a weak solution of (2.9).*

Remark 2.11. Let $(Z_t^1)_{t \geq 0}$ and $(Z_t^2)_{t \geq 0}$ be given by (2.8) with respective initial data $z_1, z_2 > 0, z_1 \neq z_2$. Then, in fact $Z_t^2 - Z_t^1 = (z_2 - z_1)\mathcal{E}_t(X)$, which is consistent with choosing different values for z_0 in (ii).

Proof. Part (i) follows by direct a computation: Let $\varphi \in H$, then for $t \geq 0$,

$$(2.10) \quad \begin{aligned} d \langle u_t, \varphi \rangle_H &= \langle f, \varphi \rangle_H dZ_t = \\ &= \langle f, \varphi \rangle_H (\lambda Z_{t-} + \alpha) dt + \langle f, \varphi \rangle_H Z_{t-} dX_t \\ &= [\langle u_{t-}, A^* \varphi \rangle_H + \alpha \langle f, \varphi \rangle_H] dt + \langle u_{t-}, \phi \rangle_H dX_t. \end{aligned}$$

Similarly, we obtain that any solution u of (2.7) with initial data $h_0 \in H$ can be written as

$$u = u^{\circ, (h_0 - z_0 f)} + u^{(z_0 f)}$$

where $u^{\circ, (h_0 - z_0 f)}$ is the solution of the homogeneous problem (2.1) with initial data $h_0 - z_0 f$ and $u^{(z_0 f)}$ is a solution of (2.7) with initial data $z_0 f$. Then, part (i) and Theorem 2.5 finish the proof of (ii) and (iii). \square

The following result shows that Z is known explicitly and extends (Kallenberg, 2002, Proposition 21.2) which covers linear SDEs driven by continuous semimartingales.

Proposition 2.12. *Let*

$$Y_t := -X_t + [X, X]_t^c + \sum_{s \leq t} \frac{\Delta X_s^2}{1 + \Delta X_s}, \quad t \geq 0.$$

Then, the unique solution of (2.8) is given by

$$(2.11) \quad Z_t := \mathcal{E}_t(X) e^{\lambda t} \left(Z_0 + \alpha \int_0^t e^{-\lambda s} \mathcal{E}_{s-}(Y) ds \right), \quad t \geq 0.$$

Proof. First recall from Lemma 2.4 that $\mathcal{E}_t(Y)\mathcal{E}_t(X) = 1$ and define

$$\begin{aligned} A_t &:= Z_0 + \alpha \int_0^t e^{-\lambda s} \mathcal{E}_{s-}(Y) ds, \\ B_t &:= \mathcal{E}_t(X) e^{\lambda t}, \quad t \geq 0. \end{aligned}$$

Let Z be given by (2.11), then $Z_t = A_t B_t$ and by Ito product rule

$$\begin{aligned} dZ_t &= A_{t-} dB_t + B_{t-} dA_t + d[A, B]_t \\ &= \lambda A_{t-} B_{t-} dt + A_{t-} B_{t-} dX_t + \alpha e^{-\lambda t} \mathcal{E}_{t-}(Y) B_{t-} dt \\ &= (\lambda Z_t + \alpha) dt + Z_{t-} dX_t. \end{aligned} \quad \square$$

To analyze the assumption that f is an eigenfunction of A in more detail we now focus on the case $X = \sigma W$ for a real Brownian motion W and a constant $\sigma > 0$. Then, we will consider *regular* two-dimensional realizations of the form $u_t = \Phi(t, Y_t)$, where

- (a) Y is a diffusion process with state space $J \subseteq \mathbb{R}$, satisfying

$$dY_t = b(Y_t) dt + a(Y_t) dW_t,$$

for Borel measurable functions $b, a: J \rightarrow \mathbb{R}$, where J has non-empty interior, $a(y) > 0$ for all $y \in J$ and $1/a$ is locally integrable on J .

- (b) $\Phi: [0, \infty) \times J \rightarrow \text{dom}(A)$ such that for all $\varphi \in \text{dom}(A^*)$, the maps defined by $\Phi^\varphi(t, y) := \langle \Phi(t, y), \varphi \rangle$, $t \geq 0, y \in J$, are in $C^{1,2}(\mathbb{R}_{\geq 0} \times J; \mathbb{R})$.

Examples of such regular two-dimensional realizations are given by Theorem 2.10.(i).

Theorem 2.13. *Let $X_t = \sigma W_t$, $t \geq 0$, for $\sigma > 0$ and a real Brownian motion W , and assume that (2.7) admits a regular finite-dimensional realization $u_t = \Phi(t, Y_t)$, $t \geq 0$. Then f is an eigenfunction of A for some eigenvalue $\lambda \in \mathbb{R}$, and there exists an invertible transformation $h: J \rightarrow \mathbb{R}_+$ such that for $t \geq 0$, almost surely*

$$Z_t = h(Y_t), \quad u_t = \Phi(t, h^{-1}(Z_t)) = fZ_t,$$

where Z is given by (2.8).

Proof. Let $\varphi \in \text{dom}(A^*)$, and

$$(2.12) \quad \Phi^\varphi(t, Y_t) := \langle \Phi(t, Y_t), \varphi \rangle.$$

Then, Ito formula yields

$$(2.13) \quad d\langle u_t, \varphi \rangle = d\Phi^\varphi(t, Y_t) = \left(\partial_t \Phi^\varphi(t, Y_t) + \partial_y b(Y_t) \Phi^\varphi(t, Y_t) + \frac{1}{2} a^2(Y_t) \partial_{yy} \Phi^\varphi(t, Y_t) \right) dt + a(Y_t) \partial_y \Phi^\varphi(t, Y_t) dW_t.$$

Comparing the martingale term with (2.7), we see that Φ^φ satisfies the ODE

$$\partial_y \Phi^\varphi(t, Y_t) = \frac{\sigma \Phi^\varphi(t, Y_t)}{a(Y_t)},$$

$dt \otimes d\mathbb{P}$ -a. e. and hence, Φ^φ must be of the form

$$\Phi^\varphi(t, y) = g^\varphi(t) h(y) = g^\varphi(t) \exp\left(\int_{y_0}^y \frac{\sigma d\eta}{a(\eta)}\right), \quad t \geq 0, y \in J,$$

for some $g^\varphi \in C^1(\mathbb{R}_{\geq 0})$ and y_0 in the interior of J . The regularity property of the representation guarantees that h is well-defined and strictly monotone increasing. We stress that h is in fact independent of $\varphi \in \text{dom}(A^*)$. Setting $Z_t = h(Y_t)$, we see that Z satisfies

$$dZ_t = m(Z_t) dt + \sigma Z_t dW_t$$

for the drift function $m = (bh') \circ h^{-1} + \frac{1}{2}(a^2 h'') \circ h^{-1}$.

Note that for each $t \geq 0$, the mapping $\varphi \mapsto g^\varphi(t)$ is linear continuous from $\text{dom}(A^*) \subset H$ into \mathbb{R} . Since $\text{dom}(A^*) \subset H$ is dense, by Riesz representation theorem for each $t \geq 0$ there exists $g(t) \in H$ such that

$$(2.14) \quad \langle g(t), \varphi \rangle = g^\varphi(t).$$

Since $\Phi^\varphi(t, y) = g^\varphi(t) h(y)$, g^φ is differentiable and (2.13) becomes, for $\varphi \in \text{dom}(A^*)$,

$$d\langle u_t, \varphi \rangle = (Z_t \partial_t g^\varphi(t) + g^\varphi(t) m(Z_t)) dt + g^\varphi(t) Z_t dW_t.$$

Comparing the drift terms with (2.7) yields for $t \geq 0$, $\varphi \in \text{dom}(A^*)$ and $z \in h(J)$,

$$(2.15) \quad z(\langle g(t), A^* \varphi \rangle - \partial_t g^\varphi(t)) + \alpha \langle f, \varphi \rangle = m(z) g^\varphi(t).$$

Evaluating at two different points $z_0, z_1 \in h(J)$ and subtracting we obtain that

$$(\langle g(t), A^* \varphi \rangle - \partial_t \langle g(t), \varphi \rangle) \cdot (z_1 - z_0) = \langle g(t), \varphi \rangle \cdot (m(z_1) - m(z_0)),$$

for all $t \in \mathbb{R}_{\geq 0}$, $\varphi \in \text{dom}(A^*)$ and $z_0, z_1 \in h(J)$. We conclude that there exists a constant $\lambda \in \mathbb{R}$ such that

$$(2.16) \quad \langle g(t), A^* \varphi \rangle - \partial_t \langle g(t), \varphi \rangle = \lambda \langle g(t), \varphi \rangle$$

and

$$(2.17) \quad m(z_1) - m(z_0) = \lambda(z_1 - z_0).$$

Thus m must be of the form $m(z) = \lambda z + c$ for $c := m(0)$. Inserting into (2.15) we obtain that

$$\alpha \langle f, \varphi \rangle = c \langle g(t), \varphi \rangle, \quad \forall \varphi \in \text{dom}(A^*).$$

Since $\text{dom}(A^*) \subset H$ is dense the equation holds for all $\varphi \in H$. Due to the assumption that $\alpha \neq 0$ and f is non-zero, also $c \neq 0$ and we get $g(t) = \frac{\alpha}{c}f$. In particular $g(t)$ is independent of t and (2.16) yields

$$\langle f, A^*\varphi \rangle = \langle \frac{\lambda\alpha}{c}f, \varphi \rangle \quad \forall \varphi \in \text{dom}(A^*).$$

This means that $f \in \text{dom}(A^{**})$. Since $A = A^{**}$, see e.g. (Yosida, 1995, Theorem VII.2.3), we have $f \in \text{dom}(A)$ and

$$\langle f, A^*\varphi \rangle = \langle Af, \varphi \rangle = \lambda \langle f, \varphi \rangle, \quad \forall \varphi \in \text{dom}(A^*).$$

By density of $\text{dom}(A^*)$ in H this yields that $Af = \lambda f$, i.e. f must be an eigenfunction of A with eigenvalue λ .

Putting everything together, we have shown that $u_t = \frac{\alpha}{c}fZ_t$ where

$$dZ_t = (\lambda Z_t + c) dt + \sigma Z_t dW_t.$$

Rescaling Z by $\frac{\alpha}{c}$ concludes the proof. \square

2.3. Linear SDEs & Pearson Diffusions. Let again $X_t = \sigma W_t$ for some $\sigma > 0$ and a real Brownian motion W . The factor processes Z appearing above are then special cases of the linear SDE

$$(2.18) \quad dZ_t = (aZ_t + c)dt + (bZ_t + d)dW_t, \quad t \geq 0, \quad Z_0 = z_0,$$

studied e.g. in (Kloeden and Platen, 1992, Ch. 4) or (Kallenberg, 2002, Prop. 21.2). Well-known special cases are the geometric Brownian motion ($c = d = 0$) and the Ornstein-Uhlenbeck-process ($b = 0$). Relevant in our context is the less common case $d = 0$, on which we focus now. Also in this case, recall from Proposition 2.12, the SDE is explicitly solvable, with solution given by

$$(2.19) \quad Z_t = X_t \left(Z_0 + c \int_0^t X_s^{-1} ds \right), \quad t \geq 0,$$

where

$$(2.20) \quad X_t = \exp \left(\left(a - \frac{b^2}{2} \right) t + bW_t \right), \quad t \geq 0.$$

Solutions of (2.18) have also been studied in the context of reciprocal gamma diffusions (see e.g. the ‘Case 4’ in (Forman and Sørensen, 2008)) or also Pearson diffusions. These are generalizations of (2.18) that allow for a square-root term in the diffusion coefficient.

Proposition 2.14. *Assume that $z_0 > 0$, $a < 0$ and $c > 0$. Then, Z has unique invariant distribution ϖ , which is an Inverse Gamma distribution with shape parameter $1 - \frac{2a}{b^2}$ and scale parameter $\frac{b^2}{2c}$ and, for any bounded measurable function $\phi: (0, \infty) \rightarrow \mathbb{R}$,*

$$\lim_{t \rightarrow \infty} \mathbb{E}[\phi(Z_t)] = \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t \phi(Z_s) ds = \int_0^\infty \phi(x) \varpi(dx).$$

Proof. First, note that

$$s'(x) := x^{\frac{c}{b^2}} e^{2\frac{c}{b^2}x}, \quad m(dx) := x^{-2(1+\frac{c}{b^2})} e^{-2\frac{c}{b^2}x} dx, \quad x \in (0, \infty)$$

define a scale density and speed measure for Z . Then, one can easily verify that Z is strictly positive and recurrent on $(0, \infty)$, see e.g. (Karatzas and Shreve, 1987, Prop. 5.5.22). Moreover, $m((0, \infty)) < \infty$ and so the unique invariant distribution of Z is

$$(2.21) \quad \varpi(A) := \frac{m(A)}{m((0, \infty))}.$$

The remaining results then follow from e.g. (Borodin and Salminen, 2012, II.35) or (Revuz and Yor, 1999, X.3.12). \square

$\mu(t) := \mathbb{E}Z_t$, $t \geq 0$, satisfies the ODE

$$\frac{\partial}{\partial t} \mu(t) = a\mu(t) + c, \quad t > 0, \quad \mu(0) = Z_0.$$

Thus,

$$(2.22) \quad \mu(t) = \left(Z_0 + \frac{c}{a} \right) e^{at} - \frac{c}{a}.$$

Remark 2.15. Let $a < 0$, $c > 0$ and (Z_t) be the stationary solution of

$$dZ_t = (aZ_t + c) dt + bZ_t dW_t,$$

that is, Z_0 is chosen distributed according to inverse gamma distribution with shape parameter $1 - \frac{2a}{b^2}$ and scale parameter $\frac{b^2}{2c}$. Then, as shown in (Bibby et al., 2005), the autocorrelation function of (Z_t) is given by

$$(2.23) \quad r(t) := \text{Corr}(Z_{s+t}, Z_s) = e^{at}, \quad s, t \geq 0.$$

To study price dynamics it is also useful to examine the reciprocal process $Y = 1/Z$:

Proposition 2.16. *Let Z be the stochastic process given by (2.18) with $d = 0$. Then, $Y_t := Z_t^{-1}$ is the unique solution of the stochastic differential equation*

$$(2.24) \quad dY_t = -Y_t(a - b^2 + cY_t) dt - bY_t dW_t, \quad Y_0 = z_0^{-1}.$$

In particular, with X given in (2.20),

$$(2.25) \quad Y_t = \mathcal{E}_t(-bW \cdot - a(\cdot)) \left(Z_0 + c \int_0^t X_s^{-1} ds \right)^{-1}, \quad t \geq 0.$$

Proof. In fact, Itô's formula yields

$$(2.26) \quad dZ_t^{-1} = -Z_t^{-2}(c + aZ_t) dt - Z_t^{-2}bZ_t^1 dW_t + Z_t^{-3}b^2Z_t^2 dt \\ = -Z_t^{-1}(a - b^2 + cZ_t^{-1}) dt - bZ_t^{-1} dW_t. \quad \square$$

When $a < b^2$, (2.24) is called the stochastic logistic differential equation.

2.4. Positivity, Stationarity and Martingale Property. Let us first come back to the linear homogeneous situation. On average, market makers do not accumulate inventory, which suggests to consider the baseline case in which the order arrival and cancellation process X is a (local) martingale.

Corollary 2.17. *Let M be a local martingale with $\Delta M > -1$ a.s., and let u_t be a weak solution of the homogeneous equation (2.1) with $X = M$.*

- (i) *The solution u_t of (2.1) is a local martingale, if and only if the initial condition h_0 is A -harmonic: $h_0 \in \text{dom}(A)$ and $Ah_0 = 0$.*
- (ii) *If $\mathcal{E}(M)$ is a martingale and $Ah_0 = 0$, then $(u_t)_{t \geq 0}$ is a martingale.*

Proof. If $h_0 \in \text{dom}(A)$ and $Ah_0 = 0$, then clearly $u_t = h_0 \mathcal{E}_t(M)$ is a local martingale. Conversely, assume that u_t is a local martingale. Thus, for all $\varphi \in \text{dom}(A^*)$, $(\langle z_t, A^* \varphi \rangle)_{t \geq 0}$ is a local martingale. Write $u_t = g_t \mathcal{E}_t(M)$, where g solves (2.2), then

$$d\langle u_t, \varphi \rangle = \langle g_t, A^* \varphi \rangle \mathcal{E}_t(M) dt + \langle u_{t-}, \varphi \rangle dM_t.$$

Since $\mathcal{E}_t(M) > 0$ almost surely, this means that $\langle g_t, A^* \varphi \rangle = 0$ for all $t \geq 0$. Hence, the mapping

$$\text{dom}(A^*) \ni \varphi \mapsto \langle g_t, A^* \varphi \rangle = 0,$$

is continuous, and thus $g_t \in \text{dom}(A^{**}) = \text{dom}(A)$. Since $\text{dom}(A^*) \subset H$ is dense, we get that $Ag_t = 0$ and $g_t = h_0$ for all $t \geq 0$. The second part is immediate. \square

For the long time behavior we again switch to the Brownian motion case. From the discussion in the previous subsection we directly obtain:

Corollary 2.18. *Let $X = \sigma W$ for a Brownian motion W and $\sigma > 0$, and let u be the solution of the inhomogeneous equation (2.7), where f is an eigenfunction of $-A$ with eigenvalue ν and $h_0 = z_0 f$, for some $z_0 > 0$. If $\nu > 0$ and $\alpha > 0$, then*

$$u_t \xrightarrow{t \rightarrow \infty} f Z_\infty$$

where Z_∞ has an Inverse Gamma distribution with shape parameter $1 + 2\frac{\nu}{\sigma^2}$ and scale parameter $\frac{\sigma^2}{2\alpha}$.

Remark 2.19. The Inverse Gamma distribution has a regularly varying right tail with tail index $1 + 2\nu$ in this case: the k -th moment of $\mathbb{E}(Z_\infty^k) < \infty$ if and only if $k < 1 + 2\nu$.

So far, we have set aside the requirement that the positivity constraint for u . By Theorem 2.5 this reduces to analysis of the deterministic equation. We now return to the case of second-order elliptic operators:

Assumption 2.20. Let $I \subset \mathbb{R}$ be an interval and suppose that A is a uniformly elliptic operator of the form

$$Au(x) = \eta(x)\Delta u(x) + \beta(x)\nabla u(x) + \alpha(x)u(x), \quad x \in I,$$

with Dirichlet boundary conditions, and where η, β and α are smooth and bounded coefficients, and in particular $\eta(x) \geq \underline{\eta} > 0$ for all $x \in I$.

For this class of operators, the strong parabolic maximum principle (cf. (Evans, 2010, Sec. 7.1)) implies that the solution $g_t(x)$ of (2.2) remains positive, whenever the initial condition h_0 is positive. In addition, it is known that there exists a real simple eigenvalue λ_1 , the principal eigenvalue of A , such that all other eigenvalues satisfy $\text{Re}(\lambda) \leq \lambda_1$ and such that the eigenfunction f associated to λ_1 is positive on I (cf. (Evans, 2010, Sec. 6.5)). Note that the factor process Z_t has state space $(0, \infty)$ both in Theorem 2.5 and 2.5. Thus, we obtain the following corollary.

Corollary 2.21 (Positivity). *Under Assumption 2.20 the following holds:*

- (i) *If h_0 is positive on I , then also the solution g_t of (2.2) and the solution u_t of (2.1) are a.s. positive on I .*
- (ii) *If f is the principal eigenfunction of A , then the finite-dimensional realization $u_t = f Z_t$ of (2.7) is a.s. positive on I .*

This simple result thus guarantees the existence of a solution with the correct sign, thereby avoiding recourse to ‘reflected’ solutions as in (Hambly et al., 2018) and considerably simplifying the analysis of our model.

3. A TWO-FACTOR MODEL

We now study the simplest example of model satisfying Assumption 2.20, namely the case of constant coefficients $\eta_a, \eta_b, \sigma_a, \sigma_b > 0$, $\beta_a, \beta_b \geq 0$, $\alpha_a, \alpha_b \in \mathbb{R}$;

$$(3.1) \quad \begin{aligned} du_t(x) &= [\eta_a \Delta u_t(x) + \beta_a \nabla u_t(x) + \alpha_a u_t(x)] dt + \sigma_a u_t(x) dW_t^a, \quad x \in (0, L), \\ du_t(x) &= [\eta_b \Delta u_t(x) - \beta_b \nabla u_t(x) + \alpha_b u_t(x)] dt + \sigma_b u_t(x) dW_t^b, \quad x \in (-L, 0), \\ u_t(x) &= 0, \quad x \in \{-L, 0, L\}, \quad u_0 \in L^2(-L, L). \end{aligned}$$

together with the sign condition:

$$(3.2) \quad u_t(x) \leq 0, \quad x \in (-L, 0), \quad \text{and} \quad u_t(x) \geq 0, \quad x \in (0, L), \quad t \geq 0.$$

In the following, we will write $u_0^b := u_0|_{[-L, 0]}$ and $u_0^a := u_0|_{[0, L]}$.

3.1. Spectral representation of solutions. A spectral representation of the operator may be used to obtain an analytical solution to this model.

Proposition 3.1. *Let $I = (-L, 0)$ or $I = (0, L)$ and $\eta > 0$, $\beta, \alpha \in \mathbb{R}$, and consider the linear operator*

$$(3.3) \quad A := \eta\Delta + \beta\nabla + \alpha\text{Id}$$

on $L^2(I)$, with $\text{dom}(A) := \{u \in H^2(I) \mid u|_{\partial I} = 0\} = H^2(I) \cap H_0^1(I)$. The eigenvalues of $-A$ are real and given by

$$(3.4) \quad \nu_k = -\alpha + \frac{\eta k^2 \pi^2}{L^2} + \frac{\beta^2}{4\eta}, \quad k = 1, 2, \dots$$

with corresponding eigenfunctions

$$h_k(x) := e^{-\frac{\beta}{2\eta}x} \sin\left(\frac{k\pi}{L}x\right), \quad x \in I.$$

In particular the only positive eigenfunction is h_1 .

Proof. First we note that that ϕ is an eigenfunction of A with eigenvalue ν , if and only if

$$x \mapsto e^{\frac{\beta}{2\eta}x} \phi(x)$$

is an eigenfunction of $A_0 := \eta\Delta + \alpha\text{Id}$ with zero Dirichlet boundary conditions, for eigenvalue $\nu + \frac{\beta^2}{4\eta}$. Details of calculations are given in (Cont, 2005). The operator A_0 with domain $\text{dom}(A_0) := \text{dom}(A)$ is self-adjoint, has compact resolvent (Cont, 2005) and eigenvalues

$$(3.5) \quad \alpha - \frac{\eta k^2 \pi^2}{L^2}, \quad k \in \mathbb{N}.$$

Eigenfunctions of A_0 with eigenvalue for $\nu \in \mathbb{R}$ are solutions of the Sturm-Liouville problem

$$(3.6) \quad \eta g''(x) + (\alpha - \nu)g(x) = 0, \quad x \in I,$$

with zero boundary conditions, which yields that g must be of the form

$$(3.7) \quad g(x) = ce^{-\gamma_1 x} \sin(\gamma_2 x)$$

where $\gamma_1, \gamma_2 \in \mathbb{R}$ are roots of the corresponding characteristic equation :

$$\gamma_1 = 0, \quad \gamma_2 = \frac{\nu - \alpha}{\eta}.$$

The zero boundary conditions at 0 and $\pm L$ further imply that $\gamma_2 = \frac{k}{L}\pi$ for some $k \in \mathbb{N}$ which implies

$$(3.8) \quad \nu = \alpha - \frac{\eta k^2 \pi^2}{L^2}.$$

Translating this from A_0 to A as mentioned in the beginning of this proof yields the result. \square

Define the following bilinear forms:

$$(3.9) \quad L^2(-L, 0) \times L^2(-L, 0) \ni (f, g) \mapsto \langle f, g \rangle_{-\gamma} := \frac{2}{L} \int_{-L}^0 f(x)g(x)e^{-2\gamma x} dx$$

and

$$(3.10) \quad L^2(0, L) \times L^2(0, L) \ni (f, g) \mapsto \langle f, g \rangle_{\gamma} := \frac{2}{L} \int_0^L f(x)g(x)e^{2\gamma x} dx$$

which define equivalent inner products, respectively for $L^2(-L, 0)$ and $L^2(0, L)$. For $\gamma > 0$, and $k \in \mathbb{N}$, define

$$(3.11) \quad \nu_k^a := -\alpha_a + \frac{\eta_a k^2 \pi^2}{L^2} + \frac{\beta_a^2}{4\eta_a}, \quad \nu_k^b := -\alpha_b + \frac{\eta_b k^2 \pi^2}{L^2} + \frac{\beta_b^2}{4\eta_b},$$

$$(3.12) \quad h_k^a(x) := e^{\frac{-\beta_a}{2\eta_a} x} \sin\left(\frac{k\pi}{L} x\right), \quad x \in (0, L),$$

$$(3.13) \quad h_k^b(x) := e^{\frac{\beta_b}{2\eta_b} x} \sin\left(\frac{k\pi}{L} x\right), \quad x \in (-L, 0).$$

Let

$$(3.14) \quad \gamma_a := \frac{\beta_a}{2\eta_a}, \quad \gamma_b := \frac{\beta_b}{2\eta_b}.$$

Then $(h_k^b)_{k \in \mathbb{N}}$ is an orthonormal basis of $(L^2(-L, 0), \langle \cdot, \cdot \rangle_{-\gamma_b})$ and $(h_k^a)_{k \in \mathbb{N}}$ is an orthonormal basis for $(L^2(0, L), \langle \cdot, \cdot \rangle_{\gamma_a})$ and solutions for the SPDE may be constructed using an expansion along these bases:

Proposition 3.2. *Let $u_0 \in L^2(-L, L)$, $u_0^a := u_0|_{[0, L]}$, $u_0^b := u_0|_{[-L, 0]}$. Then $(u_t)_{t \geq 0}$ defined by*

$$(3.15) \quad u_t(x) := \begin{cases} \mathcal{E}_t(\sigma_b W^b) \sum_{k=1}^{\infty} e^{-\nu_k^b t} \langle u_0^b, h_k^b \rangle_{-\gamma_b} h_k^b(x), & x \in (-L, 0), \\ \mathcal{E}_t(\sigma_a W^a) \sum_{k=1}^{\infty} e^{-\nu_k^a t} \langle u_0^a, h_k^a \rangle_{\gamma_a} h_k^a(x), & x \in (0, L), \\ 0, & x \in \{-L, 0, L\}. \end{cases}$$

is the unique continuous weak solution of (3.1) in the sense of Definition 2.2.

Proof. The unique continuous solutions of the respective deterministic equations are given by $(S_t^b u_0^b)_{t \geq 0}$ and $(S_t^a u_0^a)_{t \geq 0}$, where $(S_t^b)_{t \geq 0}$ and $(S_t^a)_{t \geq 0}$ are the Dirichlet semigroups generated by

$$(3.16) \quad A_b = \eta_b \Delta u_t - \beta_b \nabla + \alpha_b \quad \text{and} \quad A_a = \eta_a \Delta + \beta_a \nabla + \alpha_a$$

on $(-L, 0)$ and $(0, L)$, respectively. Thus, from Theorem 2.5 we get

$$(3.17) \quad u_t(x) = \begin{cases} \mathcal{E}_t(\sigma_b W^b) S_t^b u_0^b(x), & x \in (-L, 0), \\ \mathcal{E}_t(\sigma_a W^a) S_t^a u_0^a(x), & x \in (0, L). \end{cases}$$

(S_t^a) and (S_t^b) are linear continuous so that for each $h^a \in L^2(0, L)$, $h^b \in L^2(-L, 0)$,

$$S_t^a h^a = \sum_{k \in \mathbb{N}} \langle u_0^a, h_k^a \rangle_{\gamma_a} S_t^a h_k^a, \quad \text{and} \quad S_t^b h^b = \sum_{k \in \mathbb{N}} \langle u_0^b, h_k^b \rangle_{-\gamma_b} S_t^b h_k^b.$$

By Proposition 3.1 h_k^a (resp. h_k^b) are eigenfunctions of A_a (resp. A_b) and thus also of S^a (resp. S^b). This yields the desired representation, where the series converge in L^2 . To obtain pointwise convergence, we note that for $x \in [0, L]$ and $t > 0$, by Cauchy-Schwarz inequality, Parseval's identity and integral criterion for sequences, for $\star \in \{a, b\}$,

$$\begin{aligned} \sum_{k=1}^{\infty} \left| e^{-\nu_k^{\star} t} \langle u_0|_{(0, L)}, h_k^{\star} \rangle_{\frac{\beta_{\star}}{\eta_{\star}}} h_k^{\star}(x) \right| &\leq \|h|_{(0, L)}\|_{L^2(0, L)} \sqrt{\sum_{k=1}^{\infty} e^{-2\nu_k^{\star} t}} \\ &\leq \|u_0|_{(0, L)}\|_{L^2(0, L)}^2 e^{t(\alpha_{\star} - \frac{\beta_{\star}^2}{4\eta_{\star}})} \sqrt{\int_0^{\infty} e^{-2t \frac{\eta_{\star} \pi^2}{L^2} y^2} dy}. \square \end{aligned}$$

When $\eta > 0$, then the weights $e^{-\nu_k t}$ of the spectral decomposition decay exponentially in k^2 for large k . This justifies approximating the solution by the first few terms. Note also that the only positive eigenfunctions are the principal eigenfunctions h_1^a and $-h_1^b$ so the sign constraints (3.2) only if the projection of the solution along the principal eigenfunctions dominates the other terms in the expansion. This motivates us to focus on solutions which live in the the first eigenspace. This occurs if the initial condition is a (positive) linear combination of h_1^a and h_1^b . We will later show that this assumption is supported by market data. This leads to a finite-dimensional realization which satisfies the sign constraints (3.2):

Corollary 3.3. *Let $V_0^a > 0$ resp. $V_0^b > 0$ and define*

$$(3.18) \quad H_1^a(x) = \frac{h_1^a(x)\mathbf{1}_{(0,L)}(x)}{\int_0^L |h_1^a|} \geq 0 \quad \text{and} \quad H_1^b(x) = \frac{h_1^b(x)\mathbf{1}_{(-L,0)}(x)}{\int_{-L}^0 |h_1^b|} \leq 0.$$

The unique solution of (3.1)–(3.2) with initial condition $u_0 = V_0^a H_1^a + V_0^b H_1^b$ is given by

$$(3.19) \quad u_t(x) = H_1^b(x)V_t^b + H_1^a(x)V_t^a, \quad t \geq 0, x \in [-L, L], \quad \text{where}$$

$$(3.20) \quad \nu^a = -\alpha_a + \frac{\eta_a \pi^2}{L^2} + \frac{(\beta_a)^2}{4\eta_a}, \quad \nu^b = -\alpha_b + \frac{\eta_b \pi^2}{L^2} + \frac{(\beta_b)^2}{4\eta_b} \quad \text{and}$$

$$(3.21) \quad dV_t^a = -\nu^a V_t^a dt + \sigma_a V_t^a dW_t^a, \quad dV_t^b = -\nu^b V_t^b dt + \sigma_b V_t^b dW_t^b$$

In particular, $u_t|_{[-L,0]} \leq 0$, $u_t|_{[0,L]} \geq 0$ and

$$\nabla u_t(0+) = \frac{\pi}{L} V_t^a, \quad \nabla u_t(0-) = \frac{\pi}{L} V_t^b.$$

The L^1 normalization (3.18) allows to interpret the variables in terms of order book volume and depth: $\int_0^L |u_t| = V_t^a$ (resp. $\int_{-L}^0 |u_t| = V_t^b$) represents the volume of sell (resp. buy) orders, while $\nabla u_t(0+)\theta = \frac{\theta\pi}{L} V_t^a$ (resp. $\nabla u_t(0-).\theta = \frac{\theta\pi}{L} V_t^b$) represents the depth at the top of the book. In this simple two-factor model, these two are proportional to each other: they may be decoupled by considering multifactor specifications involving higher-order eigenfunctions.

The drift parameter $-\nu^a$ (resp. $-\nu^b$) thus represents the net growth rate of decrease of the volume of sell (resp. buy) orders. As shown in (3.20), this net growth rate results from the superposition of several effects:

- ▶ submission/ cancellation of limit sell (resp. buy) orders by directional sellers (resp. buyers) at rate α_a (resp. α_b); this may be interpreted as the ‘low frequency’ component of the order flow;
- ▶ replacement of limit orders by new ones closer to the mid-price, at rate $\frac{\beta_a^2}{4\eta_a}$ (resp. $\frac{\beta_b^2}{4\eta_b}$);
- ▶ cancellation of limit orders as the mid-price moves away (i.e. at distance $\pm L$ from the mid-price), at rate $\frac{\eta_a \pi^2}{L^2}$ (resp. $\frac{\eta_b \pi^2}{L^2}$).

In the case of a *balanced* order flow for which there is no systematic accumulation or depletion of limit orders away from the mid-price, these terms compensate each other and the volume of limit orders in any interval $[S_t + x_1, S_t + x_2]$ is a (local) martingale. The following result is a consequence of Corollary 2.17:

Corollary 3.4 (Balanced order flow). *The order book density u is a local martingale (in L^2), if and only if*

$$u_0(x) = V_0^b H_1^b(x)\mathbf{1}_{(-L,0)}(x) + V_0^a H_1^a(x)\mathbf{1}_{(0,L)}(x),$$

for some $V_0^b \geq 0, V_0^a \geq 0$ and

$$(3.22) \quad \alpha_a = \frac{\eta_a \pi^2}{L^2} + \frac{\beta_a^2}{4\eta_s}, \quad \alpha_b = \frac{\eta_b \pi^2}{L^2} + \frac{\beta_b^2}{4\eta_b}.$$

Remark 3.5 (Balance between high- and low-frequency order flow). The balance condition (3.22) expresses a balance between the slow arrival of directional orders, represented by the terms α_a and α_b , and the fast replacement of orders inside the book, represented by the terms $\frac{\beta_a^2}{4\eta_b}$ and $\frac{\beta_b^2}{4\eta_b}$, and finally the cancellation of limit orders deep inside the book, at rate $\eta_a \pi^2 / L^2$.

This balance between order flow at various frequencies may be seen as a mathematical counterpart of the observations made by (Kirilenko et al., 2017) on the nature of intraday order flow.

3.2. Shape of the order book. An implication of the above results is that the average profile of the order book is given, up to a constant, by the principal eigenfunctions H_1^a, H_1^b :

$$(3.23) \quad \mathbb{E}(u_t(x)) = \mathbb{E}(V_t^b) H_1^b(x) + \mathbb{E}(V_t^a) H_1^a(x)$$

Dropping the indices a, b , the normalized profile of the order book has the form:

$$H_1(x) := c_1 e^{-\frac{\beta}{2\eta}x} \sin\left(\frac{\pi}{L}x\right), \quad x \in [0, L],$$

where c_1 is such that $\int_0^L |H_1| = 1$:

$$\frac{1}{c_1} = \int_0^L e^{-\frac{\beta}{2\eta}x} \sin\left(\frac{\pi}{L}x\right) dx = \frac{4\pi L \eta^2}{L^2 \beta^2 + \pi^2 4\eta^2} \left(e^{-\frac{\beta}{2\eta}L} + 1 \right),$$

Figure 3 shows this function for different values of β : H_1 has a unique maximum at

$$(3.24) \quad \hat{x} := \frac{L}{\pi} \arctan\left(\frac{2\eta\pi}{L\beta}\right).$$

The position of the maximum moves closer to the origin as β/η is increased. For $\beta = 0$ we have $\hat{x} = \frac{L}{2}$, and, on the other hand $\hat{x} \searrow 0$ as $\beta/\eta \rightarrow \infty$. Typically, the order book profile for liquid large-tick securities a few ticks from the mid price. Figure 4 shows the average order book profile for QQQ; similar results were found in (Bouchaud et al., 2009; Cont et al., 2010). This suggests \hat{x} is of the order of a few ticks, so we are interested in the parameter range for which β/η is large.

The value at the maximum is

$$(3.25) \quad \max_{x \in [0, L]} H_1(x) = \sqrt{\frac{\beta^2}{4\eta^2} + \frac{\pi^2}{L^2}} \exp\left(-\frac{\beta L}{2\eta\pi} \arctan\left(\frac{2\eta\pi}{L\beta}\right)\right) \left(e^{-\frac{\beta L}{2\eta}} + 1\right)^{-1}.$$

which grows linearly as $\beta/2\eta \rightarrow \infty$, as shown in Figure 3, where we have plotted h , normalized by its L^1 -norm, for various values of β with $L := 3\pi$ and $\eta = 1$.

The above results are valuable for calibrating the model parameters $\frac{\beta}{2\eta}$, α and σ to reproduce the average profile (for each side) of the order book.

$\frac{\beta}{2\eta}$ can be estimated from the position \hat{x} of the maximum using (3.24). Note that, when L is large then

$$\hat{x} \approx \frac{2\eta}{\beta}.$$

The height of this maximum gives a further constraint on parameters, using (3.25).

We will use this result for parameter estimation in Section 3.6.

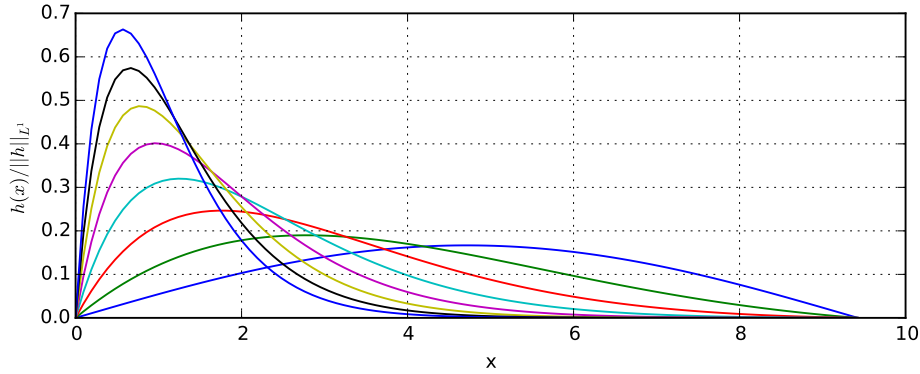


FIGURE 3. Shape of the normalized principal eigenfunction H_1 , which corresponds to the average profile of the normalized order book, for $L := 3\pi$, $\eta := 1$ and different values of $\beta \in \{0, 0.5, \dots, 3.5\}$.

3.3. Dynamics of order book volume. As noted in Corollary 3.3, V_t^a and V_t^b may be identified as the volume of sell (resp. buy) limit orders: they follow (correlated) geometric Brownian motions:

$$V_t^a = \int_0^L |u_t(x)| dx = V_0^a \exp(\sigma_a W^a - \nu_a t - \frac{\sigma_a^2 t}{2})$$

$$V_t^b = \int_{-L}^0 |u_t(x)| dx = V_0^b \exp(\sigma_b W^b - \nu_b t - \frac{\sigma_b^2 t}{2})$$

where $[W^a, W^b]_t = \rho_{a,b} t$. The average volume of the order book $V_t = V_t^a + V_t^b$ satisfies

$$\mathbb{E}(V_t) = V_0 - \int_0^t V_0^a \nu_a e^{-\nu_a s} - V_0^b \nu_b e^{-\nu_b s} ds = V_0 + V_0^a e^{-\nu_a t} + V_0^b e^{-\nu_b t}.$$

Intraday studies of order book volume show it to be stable away from the open and close. Here $\mathbb{E}V_t = V_a + V_b$ if and only if V is a martingale, i.e. $\nu_a = \nu_b = 0$.

3.4. Dynamics of price and market depth. Recall from the discussion in Section 1.3 that the order book dynamics yield the price process

$$dS_t = c_s \theta \left(\frac{dD_t^b}{D_t^b} - \frac{dD_t^a}{D_t^a} \right),$$

where $c_s \approx \frac{1}{2}$ is a dimensionless constant, θ is the tick size and D_t^b and D_t^a represent the depth at the top of the order book (Cont et al., 2014):

$$(3.26) \quad D_t^a := \int_0^\theta u_t(x) dx \approx \frac{1}{2} \theta^2 \nabla u_t(0+), \quad D_t^b := \int_{-\theta}^0 |u_t(x)| dx \approx \frac{1}{2} \theta^2 \nabla u_t(0-).$$

Using the results in Corollary 3.3, we obtain the following price dynamics:

$$(3.27) \quad dS_t = c_s \theta \left(\frac{dV_t^b}{V_t^b} - \frac{dV_t^a}{V_t^a} \right),$$

where

$$(3.28) \quad dV_t^b = -\nu_b V_t^b dt + \sigma_b V_t^b dW_t^b, \quad dV_t^a = -\nu_a V_t^a dt + \sigma_a V_t^a dW_t^a.$$

The price dynamics can thus be written as

$$\begin{aligned} S_t &= S_0 - c_s \theta t (\nu_b - \nu_a) + c_s \theta \sigma_b W_t^b - c_s \theta \sigma_a W_t^a \\ &= S_0 - c_s \theta t (\nu_b - \nu_a) + \sigma_S B_t \end{aligned}$$

where B is a Brownian motion and σ_S is the mid price volatility, which may be expressed in terms of parameters describing the order flow:

$$(3.29) \quad \sigma_S := c_s \theta \sqrt{\sigma_b^2 + \sigma_a^2 - 2\sigma_a \sigma_b \varrho_{a,b}}.$$

The implied price dynamics thus corresponds to the Bachelier model:

- ▶ The drift term $\nu_a - \nu_b$ only depends on the rate of relative increase of the bid/ask depth, not the actual depths D_t^b and D_t^a .
- ▶ The quadratic variation of the mid price is $\sigma_S^2 t$ decreases with the correlation between the buy and sell order flow. This correlation, generated by market makers, reduces price volatility.

Remark 3.6. Replacing $\sigma_a W^a$ and $\sigma_b W^b$ by arbitrary semimartingales X^a and X^b with jumps bounded from below by -1 , yields the following price dynamics:

$$(3.30) \quad S_t = S_0 - c_s \theta t (\nu_b - \nu_a) + c_s \theta (X_t^b - X_t^a).$$

In particular, this relation links price jumps to large changes ('jumps') in order flow imbalance:

$$(3.31) \quad \frac{\Delta S_t}{\theta} = c_s \Delta(X_t^b - X_t^a).$$

3.5. Order book as solution to a stochastic moving boundary problem.

The model above describes dynamics of the order book in relative price coordinates, i.e. as a function of the (scaled) distance x from the mid-price. The density of the limit order book parameterized by the (absolute) price level $p \in \mathbb{R}$ is given (in the case of linear scaling) by

$$(3.32) \quad v_t(p) = u_t(p - S_t), \quad x \in \mathbb{R},$$

where we extend u_t to \mathbb{R} by setting $u_t(y) = 0$ for $y \in \mathbb{R} \setminus [-L, L]$. As observed in Section 3.4, the mid-price dynamics is given by

$$(3.33) \quad dS_t = -c_s \theta (\nu_b - \nu_a) dt + c_s \theta \sigma_b dW_t^b - c_s \theta \sigma_a dW_t^a.$$

The dynamics of v may then be described, via an application of the Ito-Wentzell formula, as the solution of a *stochastic moving boundary problem* (Mueller, 2016):

Theorem 3.7 (Stochastic moving boundary problem). *The order book density $v_t(p)$, as a function of the price level p is a solution, in the sense of distributions, of the stochastic moving boundary problem*

$$(3.34) \quad \begin{aligned} dv_t(p) &= \left[(\eta_a + \frac{1}{2} \sigma_s^2) \Delta v_t(p) \right. \\ &\quad \left. + (\nu_b - \nu_a + \beta_a - c_s \theta (\varrho_{a,b} \sigma_b \sigma_a - \sigma_a^2)) \nabla v_t(p) + \alpha_a v_t(p) \right] dt \\ &\quad + (\sigma_a v_t(p) + c_s \theta \sigma_a \nabla v_t(p)) dW_t^a - c_s \theta \sigma_b \nabla v_t(p) dW_t^b, \end{aligned}$$

for $p \in (S_t, S_t + L)$, and

$$(3.35) \quad \begin{aligned} dv_t(p) &= \left[(\eta_b + \frac{1}{2} \sigma_s^2) \Delta v_t(p) \right. \\ &\quad \left. + (\nu_b - \nu_a - \beta_b - c_s \theta (\sigma_b^2 - \varrho_{a,b} \sigma_b \sigma_a)) \nabla v_t(x) + \alpha_b v_t(p) \right] dt \\ &\quad + c_s \theta \sigma_a \nabla v_t(p) dW_t^a + (\sigma_b v_t(p) - c_s \theta \sigma_b \nabla v_t(p)) dW_t^b \end{aligned}$$

for $x \in (S_t - L, S_t)$ with the moving boundary conditions

$$(3.36) \quad v_t(S_t) = 0, \quad v_t(y) = 0, \quad \forall y \in \mathbb{R} \setminus (S_t - L, S_t + L),$$

in the following sense: $(v_t)_{t \geq 0}$ is an continuous $L^2(\mathbb{R})$ -valued stochastic process and for all $\varphi \in C_0^\infty(\mathbb{R})$ and $t \geq 0$,

$$(3.37) \quad \langle v_t, \varphi \rangle - \langle v_0, \varphi \rangle = \int_0^t \langle m(x - S_t, \Delta v_r, \nabla v_r, v_r), \varphi \rangle dr + \\ \frac{1}{2} \int_0^t (\nabla v_r(S_r-) - \nabla v_r(S_r+)) \varphi(S_r) - \nabla v_r(S_r - L+) \varphi(S_r - L) + \nabla v_r(S_r + L-) \varphi(S_r + L) d\langle S \rangle_r \\ + \int_0^t \langle \mathbf{1}_{(S, S_r+L)} \sigma_a v_r, \varphi \rangle dW_r^a + \int_0^t \langle \mathbf{1}_{(S_r-L, S_r)} \sigma_b v_r, \varphi \rangle dW_r^b \\ + c_s \theta \sigma_a \int_0^t \langle \nabla v_r, \varphi \rangle dW_r^a - c_s \theta \sigma_b \int_0^t \langle \nabla v_r, \varphi \rangle dW_r^b,$$

where we denote, for $S \in \mathbb{R}$, $V \in H_0^1((-L, L) \setminus \{0\}) \cap H^2((-L, L) \setminus \{0\})$,

$$m(x, y'', y', y) = \begin{cases} (\eta_a + \frac{1}{2} \sigma_s^2) y'' \\ + (\nu_b - \nu_a + \beta_a - c_s \theta (\varrho_{a,b} \sigma_b \sigma_a - \sigma_a^2)) y' + \alpha_a y, & x \in (0, L), \\ (\eta_b + c_s \theta \sigma_s^2) y'' \\ + (\nu_b - \nu_a - \beta_b - c_s \theta (\sigma_b^2 - \varrho_{a,b} \sigma_b \sigma_a)) y' + \alpha_b y, & x \in (-L, 0) \\ 0, & \text{else,} \end{cases}$$

for $x, y'', y', y \in \mathbb{R}$.

Remark 3.8. Note that (3.36) is a stochastic boundary condition at S_t .

The proof, given in Appendix A, is based on Krylov's extended Ito-Wentzell formula (Krylov, 2011, Theorem 1.1).

3.6. Parameter estimation. We now describe a method for estimating model parameters. We use time series of order books for NASDAQ stocks and ETFs, from the LOBSTER database.

Given that we do not observe separately the various components of the order flow as in (3.1), we use the relations discussed in Sec. 3.2 to calibrate the parameters σ , ν and the shape parameter

$$(3.38) \quad \gamma := \frac{\beta}{2\eta}.$$

for each side of the order book. We set L to the largest value in our data set, ($L := 1000$). Parameters may be calibrated either through

- (a) a least squares fit of (3.23) to the average order book profile, or
- (b) calibrating parameters to reproduce the position \hat{x} and height of the maximum of the order book profile.

Remark 3.9. The estimator based on the maximum position of the peak is fast in computation but the fixed price level grid in the data restricts the set possible values for estimation of γ . In particular, changes of one tick of the maximum position have large impact on this estimator.

We show results for a set of NASDAQ stocks and ETFs. Figure 4 shows how the model reproduces the average book profile for QQQ at NASDAQ on 17th November 2017. In Figure 5 we see the coefficient γ estimated across various 30-min windows during the trading day. The one-factor model based on the principal eigenfunction yields a reasonable approximation for the average order book profile, which justifies our assumptions on the dynamics in Section 1.2.

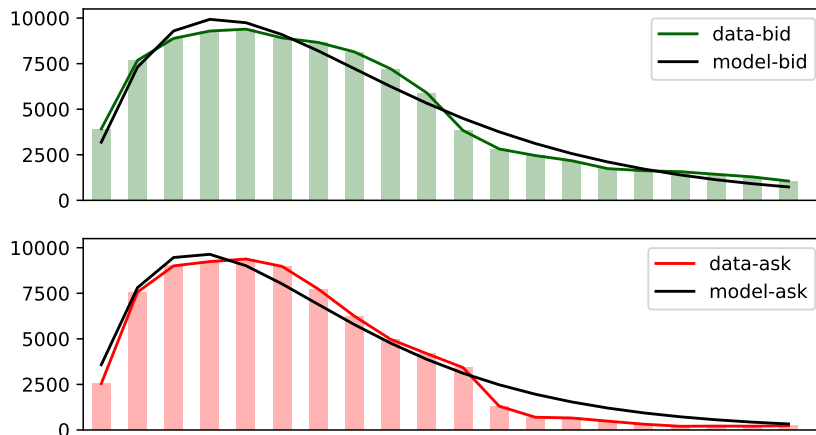


FIGURE 4. Average profile of QQQ order book (first 20 levels), 17 Nov 2016 (Top: bid, Bottom: ask).

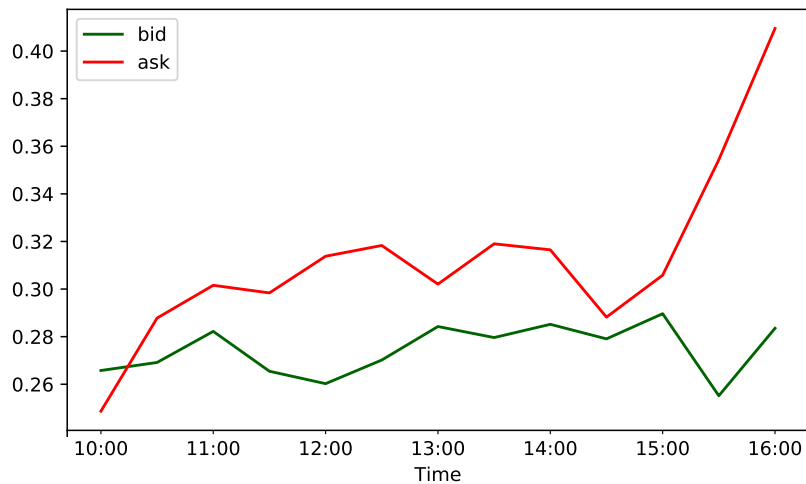


FIGURE 5. Values of parameter γ_a, γ_b estimated from 30 min average profile of QQQ order book (first 20 levels), 17 Nov 2016.

For low-price stocks, the average order book profiles may differ from the exponential-sine shape. For such stocks, we use the nonlinear scaling described in Section 1.1, leading to an average order book profile:

$$(3.39) \quad U(p) = V \exp(-\gamma((p - S_t)/\theta)^a) \sin(((p - S_t)/\theta)^a \pi/L),$$

where S_t is the best price. Figure 6 shows such a nonlinear fit for the average order book profile of SIRI.

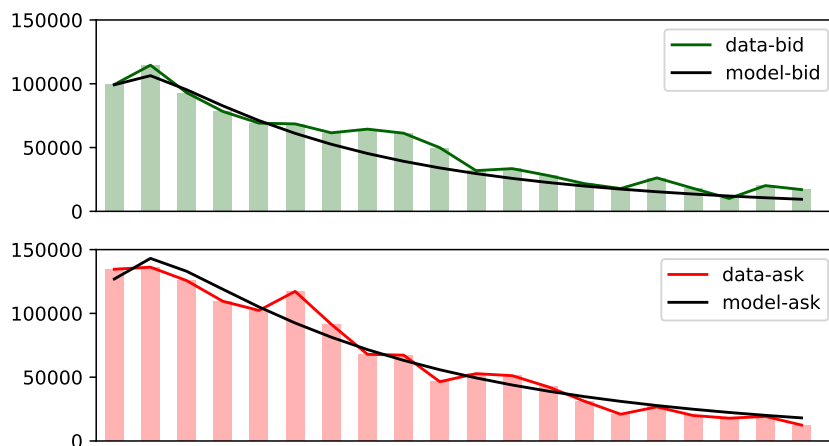


FIGURE 6. Average profile of QQQ order book (first 20 levels, 17th November 2016)(Top: bid, Bottom: ask) $\gamma_b = 0.95$, $\gamma_a = 0.86$, $a_b = 0.52$, $a_a = 0.56$.

4. MEAN REVERTING MODELS

4.1. A class of models with mean-reversion. We now return to the full model (1.2) with non-zero source terms $f^a(x)$, $f^b(x)$ representing the rate of arrival of new limit orders at a distance x from the best price:

$$\begin{aligned} du_t(x) &= [\eta^a \Delta u_t(x) + \beta^a \nabla u_t(x) + \alpha^a u_t(x) + f^a(x)] dt + \sigma^a u_t(x) dW_t^a, & x \in (0, L), \\ du_t(x) &= [\eta^b \Delta u_t(x) - \beta^b \nabla u_t(x) + \alpha^b u_t(x) + f^b(x)] dt + \sigma^b u_t(x) dW_t^b, & x \in (-L, 0), \\ u_t(0+) &= u_t(0-) = 0, & u_t(-L) = u_t(L) = 0, & t > 0, \end{aligned}$$

with the sign condition

$$u_t(x) \leq 0, \quad x \in (-L, 0), \quad \text{and} \quad u_t(x) \geq 0, \quad x \in (0, L), \quad t \geq 0,$$

where, as above $\eta_a, \eta_b, \sigma_a, \sigma_b > 0$, $\beta_a, \beta_b \geq 0$, $\alpha_a, \alpha_b \in \mathbb{R}$ are constants and $u_0 \in L^2((-L, L))$. As above, we denote $u_0^b := u_0|_{[-L, 0]}$ and $u_0^a := u_0|_{[0, L]}$. We will show that, when α^a and α^b are negative and $f^a(x), f^b(x) > 0$, this class of models leads to mean reverting dynamics for the order book profile, consistent with the observation that intraday dynamics of order book volume and queue size over intermediate time scales (hours, day) typically exhibit mean reversion rather than a trend.

Projecting the equation on the eigenfunctions h_k^a, h_k^b , as in Section 3, we see that, due to the fast increase in the eigenvalues (3.4), solutions starting from a generic initial condition may be approximated by their projection on the principal eigenfunctions h_1^a, h_1^b (we will justify this below in Proposition 4.2) and the main contribution of heterogeneous order arrivals arises from the projection of f^a (resp. f^b) on h_1^a (resp. h_1^b).

This motivates the following specification, which leads to a tractable class of models:

$$(4.1) \quad f^a(x) := \bar{V}_a H_1^a(x), \quad f^b(x) := \bar{V}_b H_1^b(x), \quad \bar{V}_a > 0, \quad \bar{V}_b > 0$$

Theorem 2.10 then gives explicit solutions to (1.2). Recall the notations (3.10) and (3.9) and define V_t^b and V_t^a by

$$(4.2) \quad dV_t^a = (\bar{V}_a - \nu_a V_t^a) dt + \sigma_a V_t^a dW_t^a, \quad dV_t^b = (\bar{V}_b - \nu_b V_t^b) dt + \sigma_b V_t^b dW_t^b$$

where $\nu_i := \frac{\eta_i \pi^2}{L^2} + \frac{\beta_i^2}{4\eta_i} - \alpha_i$, $i \in \{a, b\}$. The solution of the SPDE may then be obtained as follows:

Proposition 4.1. (i) *The unique L^2 -continuous solution of (1.2) – (4.1) for a general initial condition u_0 is given by*

$$u_t(x) = \begin{cases} V_t^b H_1^b(x) + \mathcal{E}_t(\sigma_b W^b) \sum_{k=1}^{\infty} e^{-\nu_k^b t} \langle u_0^b - V_0^b H_1^b, h_k^b \rangle_{(-\frac{\beta_b}{2\eta_b})} h_k^b(x), & x \in (-L, 0), \\ V_t^a H_1^a(x) + \mathcal{E}_t(\sigma_a W^a) \sum_{k=1}^{\infty} e^{-\nu_k^a t} \langle u_0^a - V_0^a H_1^a, h_k^a \rangle_{\frac{\beta_a}{2\eta_a}} h_k^a(x), & x \in (0, L), \\ 0, & x \notin (-L, 0) \cup (0, L). \end{cases}$$

(ii) *For an initial condition of the form*

$$u_0(x) = V_0^a H_1^a(x) \mathbf{1}_{[0, L]} + V_0^b H_1^b(x) \mathbf{1}_{[-L, 0]}$$

the unique L^2 -continuous solution of (1.2) – (4.1) is given by

$$(4.3) \quad u_t(x) = (V_t^a H_1^a(x) \mathbf{1}_{(0, L)}(x) + V_t^b H_1^b(x) \mathbf{1}_{(-L, 0)}(x)), \quad x \in [-L, L].$$

Proof. We obtain the general solution of the linear homogeneous equation from Proposition 3.2. The series representation of u results from the spectral decomposition, Proposition 3.1 and Theorem 2.10. \square

4.2. Long time asymptotics and stationary solutions. An important question is to describe the order book has an ergodic behavior and describe stationary solutions. This relates to the convergence of time-averaged statistics such as the average order book profile.

The following result describes the long-term dynamics and shows that this dynamics is well approximated by projecting the initial condition on the principal eigenfunctions as done in (4.3):

Proposition 4.2. *Let u_t be the unique solution of (1.2) – (4.1) for a general initial condition $u_0 \in L^2(-L, L)$ and define:*

$$(4.4) \quad \check{u}_t(x) := V_t^b H_1^b(x) \mathbf{1}_{(-L,0)}(x) + V_t^a H_1^a(x) \mathbf{1}_{(0,L)}(x), \quad t > 0.$$

If $\nu_1^b > 0$ and $\nu_1^a > 0$, then:

- (i) *The long-term dynamics of the order book is well approximated by the dynamics (4.4) projected along the principal eigenfunctions:*

$$(4.5) \quad \mathbb{P} \left(\lim_{t \rightarrow \infty} \|u_t - \check{u}_t\|_\infty = 0 \right) = 1.$$

- (ii) *u_t has a unique stationary distribution and*

$$(4.6) \quad u_t(x) \xrightarrow[t \rightarrow \infty]{} f^b(x) Z^b, \quad x < 0, \quad u_t(x) \xrightarrow[t \rightarrow \infty]{} f^a(x) Z^a, \quad x > 0,$$

where f^a, f^b are given by (4.1) and Z^a (resp. Z^b) is an Inverse Gamma random variable with shape parameter $1 + 2\frac{\nu_a}{\sigma_a^2}$ (resp. $1 + 2\frac{\nu_b}{\sigma_b^2}$) and scale parameter $\frac{\sigma_a^2}{2V_a}$ (resp. $\frac{\sigma_b^2}{2V_b}$).

- (iii) *If furthermore $\nu_1^b > \frac{\sigma_b^2}{2}$ and $\nu_1^a > \frac{\sigma_a^2}{2}$, then*

$$(4.7) \quad \lim_{t \rightarrow \infty} \mathbb{E} \left[\|u_t - \check{u}_t\|_{L^2(-L,L)}^2 \right] = 0.$$

Proof. For $t_0 > 0$, let

$$K_{t_0} := \sqrt{\sum_{k=1}^{\infty} e^{-2(\nu_k^a - \nu_1^a)t_0}} < \infty.$$

This term is indeed finite by integral criterion for series, see e. g. proof of Proposition 3.2. Denote $u_t^\circ(\cdot; h)$ the unique solution of the linear homogeneous equation (3.1) for an initial condition h . Recall from Theorem 2.10 that

$$u_t(x) - \check{u}_t(x) = u_t^\circ(x; u_0 - \check{u}_0).$$

It suffices now to prove the results for the ask side and note that the calculations will be analogous for the bid side. Using the representation of u_t° from Proposition 3.2 we get for all $t > t_0$ and all $h \in L^2(0, L)$,

$$\begin{aligned} \|u_t^\circ(\cdot; h)\|_{(0,L)} &\leq e^{-\nu_1^a t} \mathcal{E}_t(\sigma_a W^a) \sqrt{\sum_{k=1}^{\infty} e^{-2(\nu_k^a - \nu_1^a)t_0}} \sqrt{\sum_{k=1}^{\infty} \left| \langle h, h_k^a \rangle_{\frac{\beta_a}{2\eta_a}} \right|^2} \\ &= K_{t_0} \|h\|_{\frac{\beta_a}{2\eta_a}} \exp\left(\sigma_a W_t^a - \left(\nu_1^a + \frac{\sigma_a^2}{2}\right)t\right), \end{aligned}$$

which, as $t \rightarrow \infty$, converges to 0 provided that $\nu_1^a > 0$. This proves (i).

To show (iii), a similar calculation but using the orthogonality of the decomposition in Proposition 3.2 yields

$$\begin{aligned}\mathbb{E} \left[\left\| u_t^\circ(\cdot; h) \Big|_{(0,L)} \right\|_{\frac{\beta_a}{2\eta_a}}^2 \right] &= \sum_{k=1}^{\infty} e^{-2\nu_k^a t} \left| \langle h, h_k^a \rangle_{\frac{\beta_a}{2\eta_a}} \right|^2 \mathbb{E} \left[|\mathcal{E}_t(\sigma_a W^a)|^2 \right] \\ &\leq e^{-2\nu_1^a t} \|h\|_{\frac{\beta_a}{2\eta_a}}^2 \mathbb{E} \left[\exp(2\sigma_a W_t^a - \sigma_a^2 t) \right] \\ &= e^{(-2\nu_1^a + \sigma_a^2)t} \|h\|_{\frac{\beta_a}{2\eta_a}}^2.\end{aligned}$$

If $\sigma_a^2 < 2\nu_1^a$, then this converges to 0 as $t \rightarrow \infty$. Since $\|\cdot\|_{\frac{\beta_a}{2\eta_a}}$ defines an equivalent norm on $L^2(0, L)$, this finishes the proof of (iii).

Assertion (ii) follows from Proposition 2.14. Indeed, recall that $V^i, i \in \{a, b\}$ are ergodic processes whose unique invariant distribution is given by an Inverse Gamma distribution with shape parameter $1 + \frac{2\nu_i}{\sigma_i^2}$ and scale parameters $\frac{\sigma_i^2}{(\bar{V}_i)^2}$, $i \in \{a, b\}$. Denote by Z^b and Z^a random variables with these distribution. For any $x \in [-L, L]$, we have the convergence in distribution

$$(4.8) \quad \check{u}_t|_{(-L,0)} \Longrightarrow Z^b f_1^b(\cdot), \quad \check{u}_t|_{(0,L)} \Longrightarrow Z^a f^a(\cdot).$$

Since almost sure convergence yields convergence in distribution, by part (i) this yields that (4.8) holds also for u_t with arbitrary initial data $u_0 \in L^2(-L, L)$. \square

4.3. Dynamics of Order Book Volume. Consider now the ‘projected’ dynamics as in the setting of Proposition 4.1(ii). The dynamics of the order book volume V_t is then given by

$$(4.9) \quad V_t := \int_{-L}^L |u_t(x)| dx = V_t^b + V_t^a, \quad t \geq 0,$$

where V^b and V^a , defined in (4.2), represent the volume of buy (resp. sell) orders in the order book.

Since $[W^a, W^b]_t = \varrho_{a,b} t$ we can write

$$W^a =: W, \quad W^b := \varrho_{a,b} W + \sqrt{1 - \varrho_{a,b}^2} \widehat{W},$$

for some Brownian motion \widehat{W} , independent of W . Then,

$$(4.10) \quad \begin{aligned}dV_t &= (\bar{V}_a + \bar{V}_b - (\nu_a V_t^a + \nu_b V_t^b)) dt \\ &\quad + (\sigma_a V_t^a + \varrho_{a,b} \sigma_b V_t^b) dW_t + \sqrt{1 - \varrho_{a,b}^2} \sigma_b V_t^b d\widehat{W}_t.\end{aligned}$$

In particular, the quadratic variation (‘realized variance’) of the order book volume is given by

$$(4.11) \quad d\langle V \rangle_t = (\sigma_a^2 (V_t^a)^2 + 2\varrho_{a,b} \sigma_b \sigma_a V_t^a V_t^b + \sigma_b^2 (V_t^b)^2) dt$$

For the symmetric and perfectly correlated case, V is itself a reciprocal gamma diffusion:

Corollary 4.3. *Assume the setting of Proposition 4.1(ii) and, in addition, that $\nu_a = \nu_b =: \nu$, $\sigma_a = \sigma_b =: \sigma$ and $\varrho_{a,b} = 1$. Then, V is the unique solution of*

$$(4.12) \quad dV_t = ((\bar{V}_b + \bar{V}_a) - \nu V_t) dt + \sigma V_t dW_t,$$

with $V_0 = V_0^b + V_0^a$.

In all cases, we get from (2.22) that for $i \in \{a, b\}$, $t \geq 0$,

$$(4.13) \quad \mathbb{E} V_t^i = \left(V_0^i - \frac{\nu_i}{\bar{V}_i} \right) e^{-\nu_i t} + \frac{\nu_i}{\bar{V}_i}$$

and

$$(4.14) \quad \mathbb{E}V_t^i = \left(V_0^b - \frac{\bar{V}_b}{\nu_b} \right) e^{-\nu_b t} + \left(V_0^a - \frac{\bar{V}_a}{\nu_a} \right) e^{-\nu_a t} + \frac{\bar{V}_b}{\nu_b} + \frac{\bar{V}_a}{\nu_a}.$$

4.4. Dynamics of price and market depth. We now consider the mid price and market depths dynamics in the situation of Proposition 4.1.(ii). As discussed in Sections 1.3 and Section 3.4 for the linear homogeneous models, the dynamics of the mid-price is given by

$$dS_t = c_s \theta \left(\frac{dD_t^b}{D_t^b} - \frac{dD_t^a}{D_t^a} \right),$$

where θ is the tick size and $c_s \approx \frac{1}{2}$ is a constant, while the bid/ask market depths follow

$$D_t^a := \int_0^\theta u_t(x) dx \approx \frac{1}{2} \theta^2 \nabla u_t(0+) = \frac{\pi}{2L} \theta^2 V_t^a,$$

$$D_t^b := - \int_{-\theta}^0 u_t(x) dx \approx \frac{1}{2} \theta^2 \nabla u_t(0-) = \frac{\pi}{2L} \theta^2 V_t^a.$$

Thus, the dynamics of the market depths are given by

$$dD_t^b = \nu_b (\bar{D}_b - D_t^b) dt + \sigma_b D_t^b dW_t^b,$$

$$dD_t^a = \nu_a (\bar{D}_a - D_t^a) dt + \sigma_a D_t^a dW_t^a.$$

for some mean reversion levels $\bar{D}_b, \bar{D}_a > 0$. We thus obtain the joint dynamics of price and market depth:

$$(4.15) \quad d \begin{pmatrix} D_t^b \\ D_t^a \\ S_t \end{pmatrix} = \begin{pmatrix} \nu_b (\bar{D}_b - D_t^b) \\ \nu_a (\bar{D}_a - D_t^a) \\ c_s \theta \left(\frac{\nu_b \bar{D}_b}{D_t^b} - \frac{\nu_a \bar{D}_a}{D_t^a} - (\nu_b - \nu_a) \right) \end{pmatrix} dt$$

$$+ \begin{pmatrix} \sigma_b D_t^b & 0 \\ \varrho_{a,b} \sigma_a D_t^a & \sqrt{1 - \varrho_{a,b}^2} \sigma_a D_t^a \\ c_s \theta (\sigma_b - \varrho_{a,b} \sigma_a) & -c_s \theta \sqrt{1 - \varrho_{a,b}^2} \sigma_a \end{pmatrix} d \begin{pmatrix} W_t^1 \\ W_t^2 \end{pmatrix},$$

where W^1 and W^2 are independent Brownian motions. The mid-price itself has quadratic variation $\langle S \rangle_t = \sigma_S^2 t$, where

$$(4.16) \quad \sigma_S := c_s \theta \sqrt{\sigma_b^2 + \sigma_a^2 - 2\sigma_a \sigma_b \varrho_{a,b}}.$$

Over a small time interval Δt ,

$$S_{\Delta t} = S_0 + c_s \theta \int_0^{\Delta t} \frac{\nu_b (\bar{D}_b - D_s^b)}{D_s^b} - \frac{\nu_a (\bar{D}_a - D_s^a)}{2D^a(s)} ds + c_s \theta \sigma_b W_{\Delta t}^b - c_s \theta \sigma_a W_{\Delta t}^a$$

$$\approx S_0 + \Delta t \frac{\theta}{2} \left(\frac{\nu_b (\bar{D}_b - D_0^b)}{D_0^b} - \frac{\nu_a (\bar{D}_a - D_0^a)}{D_0^a} \right) + \sigma_S \sqrt{\Delta t} N_{0,1}$$

where $N_{0,1}$ is a standard Gaussian variable. In particular the conditional probability of an upward mid-price move of size y is given by

$$(4.17) \quad \mathbb{P}[S_{\Delta t} \geq S_0 + y] \simeq N \left(\frac{c_s \theta \sqrt{\Delta t}}{\sigma_S} \left(\frac{\nu_b (\bar{D}_b - D_0^b)}{D_0^b} - \frac{\nu_a (\bar{D}_a - D_0^a)}{D_0^a} \right) - \frac{y}{\sigma_S \sqrt{\Delta t}} \right),$$

where N denotes the cumulative distribution function of the standard normal distribution.

Remark 4.4. Using (2.22), the expected order flow over a small time interval $[0, t]$ on each side of the book is given by for $\star \in \{a, b\}$,

$$(4.18) \quad \mathbb{E}[D_t^\star - D_0^\star] = t\nu_\star(\bar{D}_\star - D_0^\star) + o(t).$$

Remark 4.5 (Mean-reverting order book imbalance). The imbalance between buy and sell depth is a frequently used indicator for predicting short term price moves (Cartea et al., 2018; Cont and de Larrard, 2013; Lipton et al., 2014). In this model, the depth imbalance has the following dynamics:

$$d(D_t^b - D_t^a) = \left(\nu^b \bar{D}^b - \nu^a \bar{D}^a - (\nu^b D_t^b - \nu^a D_t^a) \right) dt + \sigma^b D_t^b dW_t^b - \sigma^a D_t^a dW_t^a.$$

In the symmetric case, when $\bar{D} = \bar{D}_a = \bar{D}_b$, $\nu = \nu_a = \nu_b$, (4.17) becomes

$$(4.19) \quad N \left(\frac{\nu \bar{D} c_s \theta \sqrt{t} (D_0^a - D_0^b)}{\sigma_S} - \frac{y}{\sigma_S \sqrt{t}} \right).$$

This quantity is *decreasing* in the depth imbalance $D_0^b - D_0^a$: this is a consequence of the mean reversion in order book depth. In the symmetric case

$$(4.20) \quad d(D_t^b - D_t^a) = -\nu (D_t^b - D_t^a) dt + \sigma^b D_t^b dW_t^b - \sigma^a D_t^a dW_t^a,$$

so the model reproduces the empirical observation that order book imbalance is mean reverting (Cartea et al., 2018).

Note that the model predicts mean reversion of market depths on the scale of $1/\nu$ which corresponds to seconds for the ETFs QQQ and SPY and around 10 seconds for large tick stocks such as MSFT and INTC (see Table 1). For time scales smaller than $1/\nu$, the direction of price moves is highly correlated with order flow imbalance, as shown in empirical studies of equity markets (Cont et al., 2014).

4.5. Parameter estimation. We now discuss estimation of model parameters from a discrete set of observations $(V_n^a, V_n^b)_{n=0, \dots, N}$ of the bid/ask volumes V_t^a, V_t^b on a uniform time grid $\{k\Delta t : k = 0, \dots, N\}$. Let us rewrite the dynamics of V_t^a and V_t^b in the form of reciprocal Gamma diffusions:

$$(4.21) \quad dV_t^\star = \nu_\star (\bar{D}_\star - V_t^\star) + \sqrt{2 \frac{\nu_\star}{c_\star} (V_t^\star)^2} dW_t^\star, \quad t \geq 0, \quad V_0^\star \in (0, \infty), \star \in \{a, b\}$$

with $\nu_\star, \bar{D}_\star, c_\star > 0$. We use method of moments estimators as in (Leonenko and Šuvak, 2010) for \bar{D}_\star and c_\star and a martingale estimation function (Bibby and Sørensen, 1995) for the autocorrelation parameters $\nu_\star, \star \in \{a, b\}$: we define

$$\widehat{\bar{D}}_\star := \frac{1}{N} \sum_{k=1}^N \hat{V}_k, \quad \text{and} \quad \hat{c}_\star := \frac{\sum_{n=1}^N (\hat{V}_n)^2}{\sum_{n=1}^N (\hat{V}_n)^2 - \widehat{\bar{D}}_\star^2} = 1 + \frac{\widehat{\bar{D}}_\star^2}{\sum_{n=1}^N |\hat{V}_n|^2 - \widehat{\bar{D}}_\star^2}.$$

Combining Proposition 2.14 and Remark 2.19 with (Leonenko and Šuvak, 2010, Theorem 6.3) we obtain that if $\bar{D}_\star > 0$ and $c_\star > 5$, then V^\star has finite 4th moment and the estimators are consistent and asymptotically normal.

For the autocorrelation parameters ν_a and ν_b we use the martingale estimation function (Bibby and Sørensen, 1995, Section 2):

$$(4.22) \quad G_\star(\nu; \bar{D}, c) := \frac{c}{\nu} \sum_{n=1}^N \frac{(\bar{D}_\star - \hat{V}_{n-1}^\star)}{(\hat{V}_{n-1}^\star)^2} \left(\hat{V}_n - F(\hat{V}_{n-1}; \nu, \bar{D}) \right),$$

where

$$(4.23) \quad F(z; \nu, \bar{D}) := (z - \bar{D})e^{-\nu \Delta t} + \bar{D}.$$

Given \bar{D}_* , this yields the estimators

$$(4.24) \quad \hat{\nu}_* := \frac{1}{\Delta t} \log \left(- \frac{\sum_{n=1}^N \frac{(\bar{D}_* - \hat{V}_{n-1})^2}{(\hat{V}_{n-1})^2}}{\sum_{n=1}^N \frac{(\bar{D}_* - \hat{V}_{n-1})}{(\hat{V}_{n-1})^2} (V_n - \bar{D}_*)} \right), \quad * \in \{a, b\}.$$

Convergence of this estimator is discussed in (Bibby and Sørensen, 1995, Theorem 3.2).

We apply these estimators to high-frequency limit order book time series for NASDAQ stocks and ETFs, obtained from the LOBSTER database, arranged into equally spaced observations over time intervals of size $\Delta t = 10ms$ and $dt = 50ms$. For each observation we use as market depth the average volume in the first two levels over the previous 50 ms time window.³ Below we show sample results for ETFs (SPY and QQQ) and liquid stocks, (MSFT and INTC).

Figure Table 1 shows estimated parameter values across different days for INTC, MSFT, QQQ and SPY. We observe negative values of correlation $\varrho_{a,b}$ across bid and ask order flows which is consistent with observations in (Carmona and Webster, 2013). Figure 7 shows intraday variation of estimators for $\nu_a, \nu_b, \sigma_a, \sigma_b$ and $\varrho_{a,b}$

Ticker	Date	μ_b	μ_a	ν_b	ν_a	σ_b	σ_a	$\varrho_{a,b}$
INTC	2016-11-15	5179.0	5641.7	0.151	0.156	0.133	0.134	-0.077
	2016-11-16	5565.0	5672.5	0.082	0.118	0.111	0.124	-0.070
	2016-11-17	5776.5	7363.2	0.144	0.109	0.118	0.116	-0.019
MSFT	2016-11-15	3035.6	3855.9	0.522	0.426	0.292	0.292	-0.092
	2016-11-16	2839.9	3562.1	0.409	0.395	0.239	0.240	-0.071
	2016-11-17	4149.0	5762.5	0.300	0.239	0.202	0.208	-0.146
QQQ	2016-11-15	4686.9	5489.2	2.467	1.972	0.724	0.639	-0.177
	2016-11-16	4801.0	5142.6	2.041	1.845	0.632	0.677	-0.177
	2016-11-17	6414.0	6226.4	1.428	1.281	0.510	0.506	-0.224
SPY	2016-11-15	3903.4	4877.9	1.949	1.689	0.737	0.666	-0.176
	2016-11-16	3773.4	4486.4	1.324	1.763	0.578	0.657	-0.156
	2016-11-17	3693.0	4115.4	1.355	1.405	0.597	0.543	-0.181

TABLE 1. Averaged estimators for model parameters; ν and σ are given per second.

computed over 30-minute windows.

There are various estimators for intraday price volatility in this model, which allows to test the model. Recall that in (4.16) we expressed price volatility in terms of the parameters describing the order flow:

$$(4.25) \quad \hat{\sigma}_S := \frac{\theta}{2} \sqrt{\sigma_b^2 + \sigma_a^2 - 2\sigma_b\sigma_a\varrho_{a,b}}$$

where θ is the tick size. Importantly, in Equation (4.25) the right hand side does *not* require price observations and may be computed from the realized variance/covariance of the order flow. We call this the RV estimator.

Another estimator is obtained by first estimating σ_b and σ_a using the martingale estimation function (4.22) then computing the price volatility using Equation (4.25). We label this the RCG estimator.

³The source code for the implementation is available online (LOBPY, 2017).

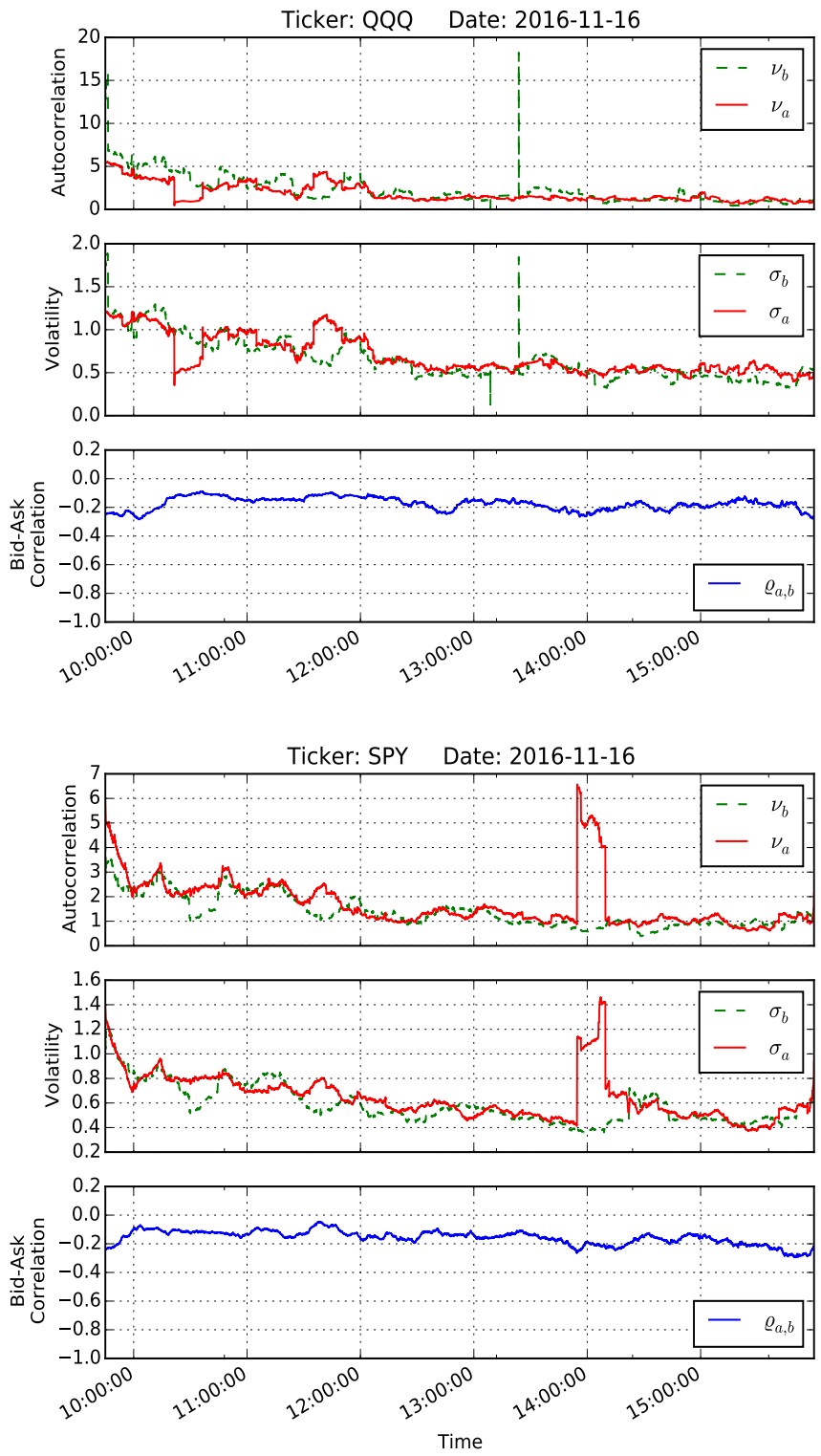


FIGURE 7. Autocorrelation ($\nu_{a/b}$), standard deviation ($\sigma_{a/b}$) and bid-ask correlation ($\rho_{a,b}$) of order book depth in first 2 levels for two liquid ETFs (QQQ and SPY).

Finally, one can compute the realized variance of the price over a 30 min. time window using price changes over 10 ms intervals. Comparing these different estimators is a qualitative test of the model.

Figure 9 compares these estimators, computed over 30 minute time windows: we observe that the model-based estimators are of the same order and closely track the intraday realized price volatility, which shows that the model captures correctly the qualitative relation between order flow and volatility.

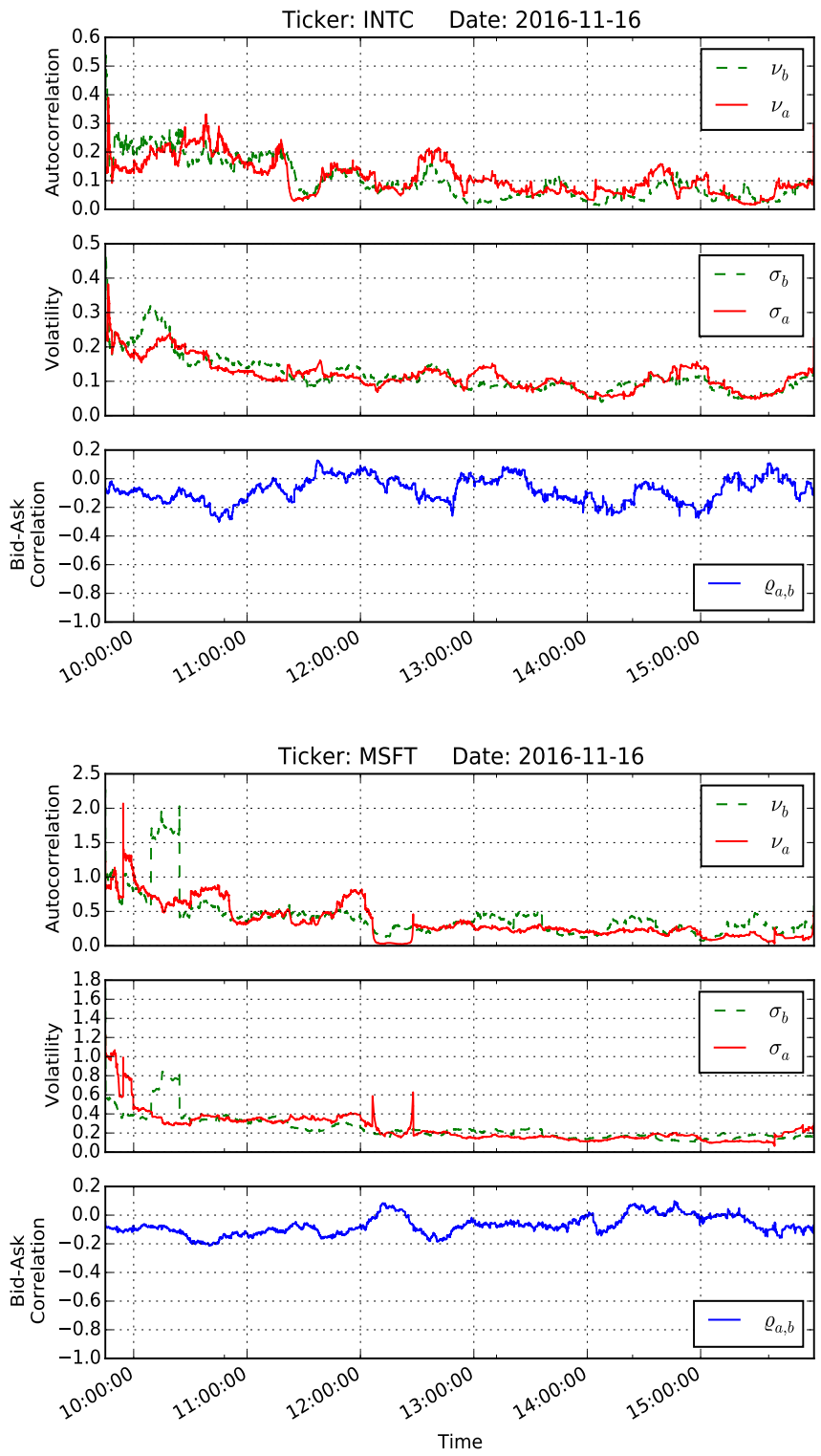


FIGURE 8. Autorcorrelation ($\nu_{a/b}$), standard deviation ($\sigma_{a/b}$) and bid-ask correlation ($\varrho_{a,b}$) of order book depth in first 2 levels for two liquid stocks (INTC and MSFT).

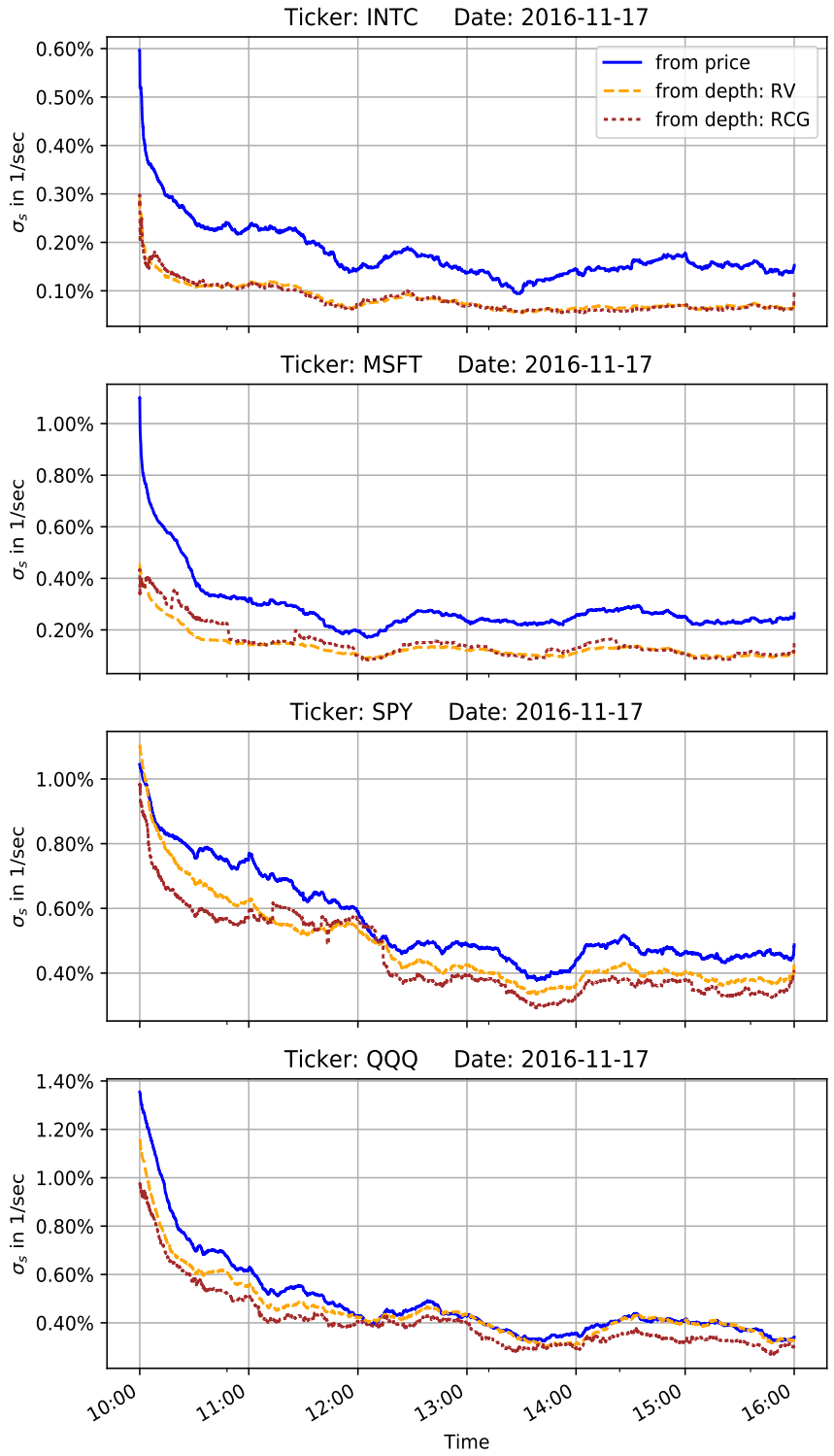


FIGURE 9. Comparison of various estimators for intraday price volatility σ_S : standard deviation of price changes (blue), estimator based on realized variance/covariance of bid/ask depth (red), and estimator based on martingale estimation function (orange).

APPENDIX A. DYNAMICS IN ABSOLUTE PRICE COORDINATES

We now discuss in more detail the generalized Ito-Wentzell formula for distribution-valued processes, which is used in Section 3.5 to derive the dynamics of the (non-centered) order book density $v_t(p)$. Let $C_0^\infty := C_0^\infty(\mathbb{R})$ be the space of smooth compactly supported functions on \mathbb{R} , \mathbb{D} its dual, the space of generalized functions. We denote by $\frac{\partial}{\partial x}$ and $\frac{\partial^2}{\partial x^2}$ the first two derivatives in the sense of distributions and by $\langle \cdot, \cdot \rangle$ the duality product on $\mathbb{D} \times C_0^\infty$.

A \mathbb{D} -valued stochastic process $u = (u_t)_{t \geq 0}$ on a filtered probability space $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$ is called \mathbb{F} -predictable if for all $\phi \in C_0^\infty(\mathbb{R})$ the real valued process $(\langle u_t, \phi \rangle)_{t \geq 0}$ is predictable.

Let $N \in \mathbb{N}$ and $(b_t)_{t \geq 0}$ and $(c_t^k)_{t \geq 0}$, $k \in \{1, \dots, N\}$ be predictable \mathbb{D} valued processes. We assume that for all $T, R \in (0, \infty)$ and all $\phi \in C_0^\infty(\mathbb{R})$, almost surely

$$(A.1) \quad \int_0^T \sup_{|x| \leq R} |\langle b_t, \phi(\cdot - x) \rangle| + \sum_{k=1}^N |\langle c_t^k, \phi(\cdot - x) \rangle|^2 dt < \infty.$$

Let $(W_t^k, k = 1, \dots, N)_{t \geq 0}$ be independent scalar Brownian motions. We consider an equation of the form

$$(A.2) \quad du_t = b_t dt + \sum_{k=1}^N c_t^k dW_t^k,$$

Definition A.1. A \mathbb{D} -valued stochastic process $(u_t)_{t \geq 0}$ is called a solution of (A.2) in the sense of distributions with initial condition u_0 if for $t \in (0, \infty)$ and $\phi \in C_0^\infty$

$$(A.3) \quad \langle u_t, \phi \rangle - \langle u_0, \phi \rangle = \int_0^t \langle b_s, \phi \rangle ds + \sum_{k=1}^N \int_0^t \langle c_s^k, \phi \rangle dW_s^k.$$

holds almost surely.

The following change of variable formula is a special case of a result by Krylov (Krylov, 2011, Theorem 1.1):

Theorem A.2 (Generalized Ito-Wentzell formula). *Let $(u_t)_{t \geq 0}$ be a solution of (A.2) in the sense of distributions and let $(x_t)_{t \geq 0}$ be a locally integrable process with representation*

$$dx_t = \mu_t dt + \sum_{k=1}^N \sigma_t^k dW_t^k, \quad t \geq 0.$$

where $(\mu_t)_{t \geq 0}$ and $(\sigma_t^k, k = 1..N)_{t \geq 0}$ are real-valued predictable processes. Define the \mathbb{D} -valued process $(v_t)_{t \geq 0}$ by $v_t(x) := u_t(x + x_t)$, for $x \in \mathbb{R}$, $t \in [0, \infty)$. Then $(v_t)_{t \geq 0}$ is a solution of

$$dv_t = \left[b_t(\cdot + x_t) + \frac{1}{2} \left(\sum_{k=1}^N |\sigma_t^k|^2 \right) \frac{\partial^2}{\partial x^2} v_t + \mu_t \frac{\partial}{\partial x} v_t + \sum_{k=1}^N \left(\sigma_t^k \frac{\partial}{\partial x} c_t^k(\cdot + x_t) \right) \right] dt + \sum_{k=1}^N [c_t^k(\cdot + x_t) + \sigma_t^k \frac{\partial}{\partial x} v_t] dW_t^k$$

in the sense of distributions.

Remark A.3. It is worth noting that the correlation of (u_t) and (x_t) contributes the term

$$\sum_{k=1}^N \left(\sigma_t^k \frac{\partial}{\partial x} c_t^k(\cdot + x_t) \right).$$

We now apply the above Ito-Wentzell formula in order to derive the dynamics of the order book density v , in non-centered coordinates, in the setting considered in Sections 3 and 4.

Let $L \in (0, \infty]$ and $I := (-L, 0) \cup (0, L)$. For $h, f \in H^2(I) \cap H_0^1(I)$. Then, (1.2) with initial condition $u_0 = h$ admits a unique (analytically) strong solution denoted by $(u_t)_{t \geq 0}$. Let \tilde{u}_t be the trivial extension of u_t to \mathbb{R} , i. e.

$$(A.4) \quad \tilde{u}_t(x) := \begin{cases} u_t(x), & x \in I, \\ 0, & \text{otherwise.} \end{cases}$$

Note that $\tilde{u} \in H^2(\mathbb{R} \setminus \{-L, 0, L\}) \cap H^1(\mathbb{R})$. Recall that Δ and ∇ in the previous discussions denoted the weak derivatives on $\mathbb{R} \setminus \{-L, 0, L\}$, and we get that $\frac{\partial}{\partial x} \tilde{u} = \nabla \tilde{u}$ and

$$(A.5) \quad \begin{aligned} \frac{\partial^2}{\partial x^2} \tilde{u} - \Delta \tilde{u} &= \frac{\partial}{\partial x} \nabla \tilde{u} - \nabla \nabla \tilde{u} \\ &= (\nabla \tilde{u}(-L+) - \nabla \tilde{u}(-L-)) \delta_{-L} \\ &\quad + (\nabla \tilde{u}(0+) - \nabla \tilde{u}(0-)) \delta_0 + (\nabla \tilde{u}(L+) - \nabla \tilde{u}(L-)) \delta_L, \end{aligned}$$

where δ_x denotes a point mass at $x \in \mathbb{R}$. Define

$$(A.6) \quad b_t(x) := \begin{cases} \eta_a \Delta u_t(x) + \beta_a \nabla u_t(x) + \alpha_a u_t(x) + f_a(x), & x \in (0, L), \\ \eta_b \Delta u_t(x) - \beta_b \nabla u_t(x) + \alpha_b u_t(x) + f_b(x), & x \in (-L, 0), \\ 0, & \text{otherwise,} \end{cases}$$

$$(A.7) \quad c_t^1(x) := \begin{cases} \sigma_a \varrho_{a,b} u_t(x), & x \in (0, L), \\ \sigma_b u_t(x), & x \in (-L, 0), \\ 0, & \text{otherwise,} \end{cases}$$

$$(A.8) \quad c_t^2(x) := \begin{cases} \sigma_a \sqrt{1 - \varrho_{a,b}^2} u_t(x), & x \in (0, L), \\ 0, & \text{otherwise,} \end{cases}$$

so that

$$(A.9) \quad d\tilde{u}_t = b_t dt + c_t^1 dW_t^1 + c_t^2 dW_t^2.$$

The Cauchy-Schwartz inequality shows that (A.1) is satisfied. Assume now that the mid price $(S_t)_{t \geq 0}$ follows the dynamics

$$(A.10) \quad dS_t = c_s \theta \mu_t dt + c_s \theta (\sigma_b - \sigma_a \varrho_{a,b}) dW_t^1 - c_s \theta \sigma_a \sqrt{1 - \varrho_{a,b}^2} dW_t^2.$$

for some integrable predictable process μ . Define

$$(A.11) \quad \sigma_s := c_s \theta \sqrt{\sigma_b^2 + \sigma_a^2 - 2\varrho_{a,b} \sigma_b \sigma_a}.$$

Then, Theorem A.2 yields that for $v_t(x) := \tilde{u}_t(x - S_t)$ we get

$$(A.12) \quad \begin{aligned} dv_t &= \left[b_t(\cdot - S_t) + \frac{1}{2} \sigma_s^2 \frac{\partial^2}{\partial x^2} v_t - c_s \theta \mu_t \frac{\partial}{\partial x} v_t \right. \\ &\quad \left. - \left(c_s \theta (\sigma_b - \varrho_{a,b} \sigma_a) \frac{\partial}{\partial x} c_t^1(\cdot - S_t) + c_s \theta \sqrt{1 - \varrho_{a,b}^2} \sigma_a \frac{\partial}{\partial x} c_t^2(\cdot - S_t) \right) \right] dt \\ &\quad + \left(c_t^1(\cdot - S_t) - c_s \theta (\sigma_b - \varrho_{a,b} \sigma_a) \frac{\partial}{\partial x} v_t \right) dW_t^1 \\ &\quad + \left(c_t^2(\cdot - S_t) + c_s \theta \sqrt{1 - \varrho_{a,b}^2} \sigma_a \frac{\partial}{\partial x} v_t \right) dW_t^2 \end{aligned}$$

i. e. v is a solution of the stochastic moving boundary problem,

$$\begin{aligned}
dv_t &= \left[\left(\eta_a + \frac{1}{2} \sigma_s^2 \right) \Delta v_t + \left(\beta_a - c_s \theta \mu_t - c_s \theta (\varrho_{a,b} \sigma_b \sigma_a - \sigma_a^2) \right) \nabla v_t \right. \\
&\quad \left. + \alpha_a v_t + f_a(\cdot - S_t) \right] dt \\
&\quad + \left(\sigma_a \varrho_{a,b} v_t - c_s \theta (\sigma_b - \varrho_{a,b} \sigma_a) \nabla v_t \right) dW_t^1 \\
&\quad + \sigma_a \sqrt{1 - \varrho_{a,b}^2} (v_t + c_s \theta \nabla v_t) dW_t^2, \quad \text{on } (S_t, S_t + L), \\
(A.13) \quad dv_t &= \left[\left(\eta_b + \frac{1}{2} \sigma_s^2 \right) \Delta v_t - \left(\beta_b + c_s \theta \mu_t + c_s \theta (\sigma_b^2 - \varrho_{a,b} \sigma_b \sigma_a) \right) \nabla v_t \right. \\
&\quad \left. + \alpha_b v_t + f_b(\cdot - S_t) \right] dt \\
&\quad + \left(\sigma_b v_t - c_s \theta (\sigma_b - \varrho_{a,b} \sigma_a) \nabla v_t \right) dW_t^1 \\
&\quad + c_s \theta \sqrt{1 - \varrho_{a,b}^2} \sigma_a \nabla v_t dW_t^2 \quad \text{on } (S_t - L, S_t), \\
v_t &= 0 \quad \text{otherwise;} \\
dS_t &= c_s \theta \mu_t dt + c_s \theta (\sigma_b - \varrho_{a,b} \sigma_a) dW_t^1 - c_s \theta \sqrt{1 - \varrho_{a,b}^2} \sigma_a dW_t^2,
\end{aligned}$$

To define what we mean by solution in this context we introduce the mappings

$$\begin{aligned}
\mathbb{L}: \bigcup_{x \in \mathbb{R}} \left[(H^2(\mathbb{R} \setminus \{x - L, x, x + L\}) \cap H_0^1(\mathbb{R} \setminus \{x - L, x, x + L\})) \times \{x\} \right] &\rightarrow \mathbb{D}, \\
(v, s) &\mapsto (\nabla(v(s - L+) - \nabla v(s - L-))) \delta_{s-L} \\
&\quad + (\nabla(v(s+) - \nabla v(s-))) \delta_s \\
&\quad + (\nabla(v(s + L+) - \nabla v(s + L-))) \delta_{s+L}.
\end{aligned}$$

Define now the functions $\bar{\mu}: \mathbb{R}^5 \rightarrow \mathbb{R}$, $\bar{\sigma}_1, \bar{\sigma}_2: \mathbb{R}^4 \rightarrow \mathbb{R}$ as

$$\begin{aligned}
\bar{\mu}(x, y'', y', y, s) &:= \begin{cases} \left(\eta_a + \frac{1}{2} \sigma_s^2 \right) y'' + \left(\beta_a - c_s \theta (\varrho_{a,b} \sigma_b \sigma_a - \sigma_a^2) \right) y' \\ \quad + \alpha_a y + f_a(x), & x \in (0, L) \\ \left(\eta_b + \frac{1}{2} \sigma_s^2 \right) y'' - \left(\beta_b + c_s \theta (\sigma_b^2 - \varrho_{a,b} \sigma_b \sigma_a) \right) y' \\ \quad + \alpha_b y + f_b(x), & x \in (-L, 0), \\ 0, & \text{otherwise,} \end{cases} \\
\bar{\sigma}_1(x, y', y, s) &:= \begin{cases} \sigma_a \varrho_{a,b} y, & x \in (0, L), \\ \sigma_b y, & x \in (-L, 0), \\ 0, & \text{otherwise,} \end{cases} \\
\bar{\sigma}_2(x, y', y, s) &:= \begin{cases} \sigma_a \sqrt{1 - \varrho_{a,b}^2} y, & x \in (0, L) \\ 0, & \text{otherwise} \end{cases}
\end{aligned}$$

for $x, y'', y', y, s \in \mathbb{R}$.

Following (Mueller, 2016, Definition 1.11), a solution of (A.13) is an $L^2(\mathbb{R}) \times \mathbb{R}$ -continuous stochastic process (v_t, S_t) , taking values in

$$\bigcup_{x \in \mathbb{R}} \left[(H^2(\mathbb{R} \setminus \{x - L, x, x + L\}) \cap H_0^1(\mathbb{R} \setminus \{x - L, x, x + L\})) \times \{x\} \right],$$

such that (S_t) is given by (A.10) and, in the sense of distributions,

$$\begin{aligned}
(A.14) \quad dv_t &= (\bar{\mu}(\cdot - S_t, \Delta v_t, \nabla v_t, v_t, S_t)) dt - \nabla v_t dS_t + \frac{1}{2} \mathbb{L}(v_t, S_t) d\langle S \rangle_t \\
&\quad + \bar{\sigma}_1(\cdot - S_t, \nabla v_t, v_t, S_t) dW_t^1 + \bar{\sigma}_2(\cdot - S_t, \nabla v_t, v_t, S_t) dW_t^2.
\end{aligned}$$

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