# A Theoretic Approach of Classical Operations in Clifford Algebras 

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# A Theoretic Approach of Classical Operations in Clifford Algebra 

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## Chapter 1

## Introduction

Clifford algebra concepts have a limited theoretical interest. Their properties are presented in the literature of applied mathematics by considering their existence for granted.
We find in the mathematical literature a rigorous definition of Clifford algebras but that omits to define certain concepts that have a limited theoretical interest. Similarly, works of applied mathematics that present the Clifford algebras make a list of their properties by considering their existence for granted. This report presents a definition of Clifford algebra with other interpretations and demonstrations based on [1], [2], [6] and [3] with practical notions used in [5] and [4].

## Chapter 2

## Inner Product

### 2.1 Introduction

We will define the inner product due to Hestenes [5] from an asymmetric product called contraction which is useful in computer science [4].
We first present a definition of Clifford algebra and the universal property and secondly the Clifford algebra dimension. We then present $\dagger$ and $\alpha$ operators to finally propose a definition of the geometric algebra.

### 2.2 Definition and universal property

In this paper, $V$ is a vector space on a field $\mathbb{K}=\mathbb{R}$ or $\mathbb{C}, Q$ is a quadratic form on $V$ and $B$ its polar form:

$$
B(x, y)=\frac{Q(x+y)-Q(x)-Q(y)}{2}, \quad \forall x, y \in V .
$$

The tensor algebra of $V$ noted $\otimes(V)$ is the unitary graded algebra:

$$
\mathbb{K} \oplus V \oplus(V \otimes V) \oplus(V \otimes V \otimes V) \oplus \cdots
$$

The product is induced by the tensor product and the identity element is noted $1_{\otimes}$. The linear subspace of elements of degree $h$ is noted $\otimes^{h}(V)$.

Definition 1. A Clifford algebra on $V$ with respect to $Q$, noted $C(V, Q)$ is the quotient of tensor algebra $\otimes(V)$ by the two-sided ideal $I_{Q}$ spanned by elements of the form:

$$
x \otimes x-Q(x), \quad x \in V \subset \otimes(V) .
$$

The canonical projection of $\otimes(V)$ onto the Clifford algebra $C(V, Q)$ is called $i_{Q}$. We set $\bar{x}=i_{Q}(x)$ for $x \in \otimes(V)$. The quotient $C(V, Q)$ is an associative unitary algebra which contains the identity element $\overline{1}_{\otimes}$. As $V$ generates $\otimes(V), i_{Q}(V)$ generates $C(V, Q)$. Using the definition, we have the fundamental relationship:

$$
\begin{equation*}
\bar{x}^{2}=Q(x) \quad \forall x \in V, \tag{2.1}
\end{equation*}
$$

By developing the expression: $(\bar{x}+\bar{y})^{2}=Q(x+y)$ with $x, y \in V$ :

$$
\begin{equation*}
\bar{x} \bar{y}+\bar{y} \bar{x}=2 B(x, y) . \tag{2.2}
\end{equation*}
$$

This relationship allows us to characterize orthogonal vectors.

Property 1 (Universal property). Let $A$ be $a \mathbb{K}$-algebra and $f: V \rightarrow A$ a morphism of $\mathbb{K}$-vector space such that:

$$
\forall x \in V, \quad f(x)^{2}=Q(x) 1 .
$$

Then there exists a unique $g$ such that the following diagram is commutive:


### 2.3 Dimension of $C(V, Q)$

Lemma 1. If $u_{1}, \ldots, u_{n}$ span the vector space $V$, then

$$
\overline{1_{\otimes}}, \quad \bar{u}_{i_{1}} \bar{u}_{i_{2}} \cdots \bar{u}_{i_{r}}, \text { where } 1 \leqslant i_{1}<i_{2}<\cdots<i_{r} \leqslant n \text { and } 1 \leqslant r \leqslant n \text {, }
$$

span the vector space $C(V, Q)$.
Proof. Let $u_{1}, \ldots, u_{n}$ be vectors generating the vector space $V$. All elements of $C(V, Q)$ are also linear combination of monomial in the $\bar{u}_{i}, 1 \leqslant i \leqslant n$, because $i_{Q}(V)$ spans $C(V, Q)$. On the other hand,

$$
\begin{gather*}
\bar{u}_{i} \bar{u}_{j}+\bar{u}_{j} \bar{u}_{i}=2 B\left(u_{i}, u_{j}\right),  \tag{2.4}\\
\left(\bar{u}_{i}\right)^{2}=Q\left(u_{i}\right) . \tag{2.5}
\end{gather*}
$$

If we reorder these monomials using the relationship (2.4) then lowering the degree with (2.5), we can assume that all element of $C(V, Q)$ is a linear combination of elements of the form:

$$
\overline{1_{\otimes}}, \quad \bar{u}_{i_{1}} \bar{u}_{i_{2}} \cdots \bar{u}_{i_{r}}, \text { where } 1 \leqslant i_{1}<i_{2}<\cdots<i_{r} \leqslant n \text { and } 1 \leqslant r \leqslant n \text {. }
$$

Definition 2. Let $F$ and $G$ be two graded algebras. The tensor product $F \times G$ can be endowed with an associative algebra structure by defining:

$$
\left(a_{1} \otimes a_{2}\right)\left(b_{1} \otimes b_{2}\right)=(-1)^{p_{2} q_{1}} a_{1} b_{1} \otimes a_{2} b_{2}
$$

where $a_{2}$ is of degree $p_{2}$ and $b_{1}$ is of degree $q_{1}$ and then extend to $F \times G$ by linearity.
Lemma 1. Let $Q$ and $Q^{\prime}$ be two quadratic forms on vector spaces of finite dimension $V$ and $V^{\prime}$ respectively. Then there exists a surjective morphism of algebra of $C\left(V \oplus V^{\prime}, Q \oplus\right.$ $\left.Q^{\prime}\right)$ onto $C(V, Q) \otimes C\left(V^{\prime}, Q^{\prime}\right)$.

Proof. Let $u: V \oplus V^{\prime} \longrightarrow C(V, Q) \otimes C\left(V^{\prime}, Q^{\prime}\right)$ be defined by

$$
u\left(x, x^{\prime}\right)=i_{Q}(x) \otimes 1+1 \otimes i_{Q^{\prime}}\left(x^{\prime}\right)
$$

for $x \in V$ and $x^{\prime} \in V^{\prime}$. We have:

$$
\begin{aligned}
\left(u\left(x, x^{\prime}\right)\right)^{2} & =\left(i_{Q}(x) \otimes 1+1 \otimes i_{Q^{\prime}}\left(x^{\prime}\right)\right)^{2} \\
& =\left(i_{Q}(x)\right)^{2} \otimes 1+1 \otimes\left(i_{Q^{\prime}}(x)\right)^{2}+i_{Q}(x) \otimes i_{Q^{\prime}}\left(x^{\prime}\right)-i_{Q^{\prime}}(x) \otimes i_{Q}(x) \\
& =Q(x)+Q^{\prime}\left(x^{\prime}\right)=\left(Q \oplus Q^{\prime}\right)\left(x, x^{\prime}\right)
\end{aligned}
$$

Using the universal property, there exists a unique $\psi$ such that:

is commutative. On the other hand, as $i_{Q}(V)$ spans $C(V, Q)$ and $i_{Q^{\prime}}\left(V^{\prime}\right)$ spans $C\left(V^{\prime}, Q^{\prime}\right)$, $C(V, Q) \otimes C\left(V^{\prime}, Q^{\prime}\right)$ is spanned by elements of form $1 \otimes i_{Q^{\prime}}\left(x^{\prime}\right)=u\left(0, x^{\prime}\right)$ and $i_{Q}(x) \otimes 1=$ $u(x, 0)$ for $x \in V$ and $x^{\prime} \in V^{\prime}$. The map $\psi$ is then surjective.

Theorem 1. We have the following structure theorem:
i) $\operatorname{dim} C(V, Q)=2^{n}$ and for all basis $\left(u_{1}, \ldots, u_{n}\right)$ of $V$, the following elements

$$
\begin{equation*}
\overline{1_{\otimes}}, \quad \bar{u}_{i_{1}} \bar{u}_{i_{2}} \cdots \bar{u}_{i_{r}}, \text { where } 1 \leqslant i_{1}<i_{2}<\cdots<i_{r} \leqslant n \text { and } 1 \leqslant r \leqslant n, \tag{2.6}
\end{equation*}
$$

form a basis for $C(V, Q)$.
ii) The morphism $i_{Q}: V \longrightarrow C(V, Q)$ is injective.

## $2.4 \dagger$ and $\alpha$ operators

### 2.4.1 $\alpha$ operator

Property 2. There exists a unique endomorphism of algebra of $C(V, Q)$ denoted $\alpha$ such that:

$$
\alpha(v)=-v, \quad \forall v \in V
$$

This endomorphism is an involution called the main involution of the Clifford algebra $C(V, Q)$.

We note the set of even elements $C^{+}(V, Q)=\{x \in C(V, Q), \alpha(x)=x\}$ and the set of odd elements $C^{-}(V, Q)=\{x \in C(V, Q), \alpha(x)=-x\}$. We have $C(V, Q)=C^{+}(V, Q) \oplus$ $C^{-}(V, Q)$ and $C^{+}(V, Q)$ is a subalgebra of $C(V, Q)$.

### 2.4.2 † operator

Property 3. There exists a unique anti-automorphism of $C(V, Q)$, noted $\dagger$ such that:

$$
v^{\dagger}=v \quad \forall v \in V
$$

This anti-automorphism is an involution.

### 2.5 Geometric Algebra

### 2.5.1 Canonical Isomorphism between $\wedge(V)$ and $C(V, Q)$

Vector subspace representation using the exterior product in the Grassmann algebra allows for example to express the belonging relation to a point in a space or the character of a linearly dependent vector subset by simple algebraic relations. We would like to equip a Clifford algebra with such a product. It is sufficient to exhibit an isomorphism between the two spaces and transport the product of an algebra on the other. The question is which isomorphism to choose so that both products perform well with respect to the other. A solution would be to choose a $Q$-orthogonal base $\left(e_{1}, \ldots, e_{n}\right)$ of $V$ and to send the element $e_{1} \wedge \cdots \wedge e_{n}$ on $e_{1} \cdots e_{n}$. We can then prove that an isomorphism between vector spaces is defined. We consider here an independent definition of any choice of a base inspired by [1] and [3].

Definition 3. Let $x \in V$, we define a creation operator for all $a \in \otimes(V)$ by $e_{x}(a)=x \otimes a$.
Definition 4. Let $h$ and $j$ be integers $>0$ such that $j \leqslant h,\left(e_{1}, \ldots, e_{n}\right)$ a base of $V$ and $\varphi$ an element of $V^{*}$. We define the contraction operator $C_{\varphi}^{j}$ of $\otimes^{h}(V)$ in $\otimes^{h-1}(V)$ by:

$$
C_{\varphi}^{j}\left(e_{i_{1}} \otimes \cdots \otimes e_{i_{h}}\right)=\varphi\left(e_{i_{j}}\right)\left(e_{i_{1}} \otimes \cdots \otimes \widehat{e_{j}} \otimes \cdots \otimes e_{i_{h}}\right) .
$$

Property 4. Let $\varphi \in E^{*}$, there exists a unique vector space morphism $i_{\varphi}: \otimes(V) \longrightarrow$ $\otimes(V)$ such that:

$$
\begin{gather*}
i_{\varphi}(1)=0,  \tag{2.7}\\
\forall x \in V, \quad i_{\varphi} \circ e_{x}+e_{x} \circ i_{\varphi}=\varphi(x) \mathrm{Id} . \tag{2.8}
\end{gather*}
$$

Proof. $i_{\varphi}$ is already defined on $\mathbb{K}$. It is defined on $\otimes^{i}(V)$ by induction.
Property 5. We have $i_{\varphi}=\sum_{j=1}^{h}(-1)^{j+1} C_{\varphi}^{j}$ on $\otimes^{h}(V)$.
Proof. The proof can be found by induction on $h$. By linearity, it is sufficient to prove the equality for a term $x \otimes a$ with $x \in V$ and $a \in \otimes^{h}(V)$.

Property 6. Let $\varphi, \psi \in V^{*}$, we have the following equalities:

$$
\left(i_{\varphi}\right)^{2}=0 \quad \text { and } \quad i_{\varphi} \circ i_{\psi}+i_{\psi} \circ i_{\varphi}=0 .
$$

Proof. We first remark that $\left(i_{\varphi}\right)^{2}$ and $e_{x}$ commute using (2.8). We then prove by induction on $h$ that $\left(i_{\varphi}\right)^{2}=0$ on $\otimes^{h}(V)$. On the other hand,

$$
\begin{aligned}
i_{\varphi} \circ i_{\psi}+i_{\psi} \circ i_{\varphi} & =\left(i_{\varphi+\psi}\right)^{2}-\left(i_{\varphi}\right)^{2}-\left(i_{\psi}\right)^{2} \\
& =0
\end{aligned}
$$

Property 7. Let $a \in \otimes^{h}(V)$ and $b \in \otimes(V)$, we have the following equality:

$$
\begin{equation*}
i_{\varphi}(a \otimes b)=i_{\varphi}(a) \otimes b+(-1)^{h} a \otimes i_{\varphi}(b) \tag{2.9}
\end{equation*}
$$

Proof. By linearity, we can suppose that $b \in \otimes^{k}(V)$. We have successively:

$$
\begin{aligned}
i_{\varphi}(a \otimes b) & =\sum_{j=1}^{h+k}(-1)^{j-1} C_{\varphi}^{j}(a \otimes b) \\
& =\left(\sum_{j=1}^{h}(-1)^{j-1} C_{\varphi}^{j}(a)\right) \otimes b+a \otimes\left(\sum_{j=h+1}^{h+k}(-1)^{j-1} C_{\varphi}^{j-h}(b)\right) \\
& =i_{\varphi}(a) \otimes b+(-1)^{h} a \otimes i_{\varphi}(b)
\end{aligned}
$$

Property 8. The map $i_{\varphi}$ descends to $\wedge(V)$ by:

$$
i_{\varphi}\left(x_{1} \wedge x_{2} \wedge \cdots \wedge x_{h}\right)=\sum_{j=1}^{h}(-1)^{j+1} \varphi\left(x_{j}\right)\left(x_{1} \wedge \cdots \wedge \widehat{x_{j}} \wedge \cdots \wedge x_{h}\right)
$$

Proof. It is sufficient to prove that ideal $I$ is stable by $i_{\varphi}$. By linearity, it is sufficient to prove that for all $a \in \otimes^{h}(V), x \in V$ and $b \in \otimes(V)$, we have: $i_{\varphi}(a \otimes x \otimes x \otimes b) \in I$. By applying (2.9) twice and given that $i_{\varphi}(x \otimes x)=0$, we find:

$$
i_{\varphi}(a \otimes x \otimes x \otimes b)=i_{\varphi}(a) \otimes x \otimes x \otimes b+(-1)^{h} a \otimes x \otimes x \otimes i_{\varphi}(b) \in I
$$

Lemma 2. Let $F$ be a bilinear form on $V$, there exists a unique linear endomorphism $\lambda_{F}$ on $\otimes(V)$ such that:

$$
\begin{align*}
\lambda_{F}(1) & =1,  \tag{2.10}\\
\lambda_{F} \circ e_{x} & =\left(e_{x}+i_{x}^{F}\right) \circ \lambda_{F} \tag{2.11}
\end{align*}
$$

where $i_{x}^{F}=i_{x^{*}}$ and $x^{*}(y)=F(x, y)$.

Proof. $\lambda_{F}$ is defined on $\mathbb{K}$ by (2.10). Moreover, for all $x \in V$ and $a \in \otimes^{h}(V)$, we necessarily have:

$$
\begin{equation*}
\lambda_{F}(x \otimes a)=\left(e_{x}+i_{x}^{F}(x)\right) \circ \lambda_{F}(a)=x \otimes \lambda_{F}(a)+i_{x}^{F}\left(\lambda_{F}(a)\right) \tag{2.12}
\end{equation*}
$$

This defines $\lambda_{F}$ on $\otimes^{h+1}(V)$.
Lemma 3. For all $\varphi \in E^{*}, \lambda_{F}$ and $i_{\varphi}$ commute.
Proof. By linearity, it is sufficient to prove that $\lambda_{F}$ and $i_{\varphi}$ commute on $\otimes^{h}(V) \forall h \geqslant 0$ and by induction on $h$. It is obvious for $h=0$ because $\lambda_{F}(1)=1$. Let $h \geqslant 0, a \in \otimes^{h}(V)$ and $x \in V$, we have:

$$
\begin{aligned}
\lambda_{F}\left(i_{\varphi}(x \otimes a)\right) & =\lambda_{F}\left(i_{\varphi}(x) \otimes a-x \otimes i_{\varphi}(a)\right) \\
& =\varphi(x) \lambda_{F}(a)-\left(e_{x}+i_{x}^{F}\right)\left(i_{\varphi}\left(\lambda_{F}(a)\right)\right) \\
& =i_{\varphi}\left(\lambda_{F}(x \otimes a)\right) .
\end{aligned}
$$

Lemma 4. Let $F$ and $F^{\prime}$ be two bilinear form on $E$, we have the relationship $\lambda_{F} \circ \lambda_{F^{\prime}}=$ $\lambda_{F+F^{\prime}}$. In particular, $\lambda_{F}$ is an isomorphism of $\otimes(V)$.
Proof. By linearity, it is sufficient to prove that $\lambda_{F} \circ \lambda_{F^{\prime}}=\lambda_{F+F^{\prime}}$ on $\otimes^{h}(V)$ for all $h \geqslant 0$. We prove this by induction on $h$.
The case $h=0$ is obvious because $\lambda_{F}(1)=\lambda_{F^{\prime}}(1)=1$. Let $h \geqslant 0, a \in \otimes^{h}(V)$ and $x \in V$, we have:

$$
\begin{aligned}
\lambda_{F}\left(\lambda_{F^{\prime}}(x \otimes a)\right) & =\lambda_{F}\left(\lambda_{F^{\prime}}\left(e_{x}(a)\right)\right) \\
& =\left(e_{x}+i_{x}^{F}\right)\left(\lambda_{F}\left(\lambda_{F^{\prime}}(a)\right)\right)+i_{x}^{F^{\prime}}\left(\lambda_{F}\left(\lambda_{F^{\prime}}(a)\right)\right) \\
& =\lambda_{F+F^{\prime}}(x \otimes a)
\end{aligned}
$$

This proves the relationship on $\otimes^{h+1}(V)$.
In particular $\lambda_{F} \circ \lambda_{-F}=\lambda_{0}$ and it is not difficult to show that $\lambda_{0}=$ Id. Hence $\lambda_{F} \circ \lambda_{-F}=$ $\lambda_{-F} \circ \lambda_{F}=\mathrm{Id}$ and $\lambda_{F}$ is an isomorphism of $\otimes(V)$.

Property 9. Let $I_{Q}$ be the two-sided ideal of $\otimes(V)$ spanned by $x \otimes x-Q(x)$ for $x \in V$. We set $I=I_{0}$. The $\lambda_{B}$ operator sends the ideal $I_{Q}$ in the ideal $I$ and defines an isomorphism of vector space between $C(V, Q)$ and $\wedge(V)$.

Proof. It is sufficient to prove that $\lambda_{B}\left(I_{Q}\right) \subset I$. Indeed the induced morphism will be surjective and $C(V, Q)$ and $\wedge(V)$ have the same dimension. This is done by induction.

We obtain by passing to the quotient in (2.11) the relationship $\lambda_{B}(x u)=x \wedge \lambda_{B}(u)+$ $i_{x^{*}}\left(\lambda_{B}(u)\right)$. Then by identifying an element of $C(V, Q)$ and its image by $\lambda_{B}$, we find:

$$
\begin{equation*}
x u=x \wedge u+i_{x^{*}}(u) \tag{2.13}
\end{equation*}
$$

An exterior product on $C(V, Q)$ compatible with the geometric product in the sense of $(2.13)$ is then defined.

Remark 1. By applying the $\dagger$ operator to the relationship (2.13) and by assuming that $u$ is a $k$-vector, we can establish the similar equality:

$$
\begin{equation*}
u x=u \wedge x-(-1)^{k} i_{x^{*}}(u) . \tag{2.14}
\end{equation*}
$$

### 2.5.2 Definition of an inner product.

We consider the extension of $B$ on the whole Clifford algebra $C(V, Q)$. We first observe that for all $x, y \in V, i_{x^{*}}(y)=B(x, y)$. The map $i_{x^{*}}$ extends the scalar product to $V \times C(V, Q)$. It exists many possible extensions: the left contraction is an asymmetric product which is useful in computer science[4]. We will define the inner product due to Hestenes [5] from the contraction rather than from property (19).

Definition 5. Let $k>0, x=v_{1} \wedge \cdots \wedge v_{k}$ be a decomposable $k$-vector and $y \in C(V, Q)$. We fix $l_{x}=i_{v_{1}^{*}} \circ \cdots \circ i_{v_{k}^{*}}$. We call left contraction of $x$ and $y$ and we note it $x$ y the element $l_{x}(y)$. We then extend this contraction by linearity by fixing $\left.\lambda\right\rfloor y=\lambda y$.

Definition 6. Let $x$ be a r-vector and $y$ a s-vector. We define the inner product of $x$ and $y$ and we note it $x \cdot y$ the element:

$$
x \cdot y= \begin{cases}0 & \text { if } r=0 \text { or } s=0 \\ x\rfloor y & \text { if } r \leqslant s \\ \left.(-1)^{s(r-1)} y\right\rfloor x & \text { if } r>s .\end{cases}
$$

We then extend this product by linearity.
Remark 2. In fact, if $r=s$ we have $x\rfloor y=y\rfloor x$. The last case in previous definition need not be strict.

Property 10. Let $x$ be a r-vector, y a s-vector, z a t-vector. We have:
i) $x \cdot y=(-1)^{r(s-1)} y \cdot x \quad$ for $r \leqslant s$.
ii) $x \cdot(y \cdot z)=(x \wedge y) \cdot z \quad$ for $r+s \leqslant t$ and $r, s>0$.
iii) $(x \cdot y) \cdot z=x \cdot(y \wedge z) \quad$ for $s+t \leqslant r$ and $s, t>0$.
iv) $x \cdot(y \cdot z)=(x \cdot y) \cdot z \quad$ for $r+t \leqslant s$.

Proof. i). It comes directly from the definition.
ii). By inner product bilinearity, we can suppose that $x$ and $y$ are decomposable, i-e $x=x_{1} \wedge \cdots \wedge x_{r}$ and $y=y_{1} \wedge \cdots \wedge y_{s}$. By using the notations of the definition 5 , as $r \leqslant t$ and $s \leqslant t$, we have:

$$
\begin{aligned}
x \cdot(y \cdot z) & =x\rfloor(y\rfloor z) \quad \text { because } r, s>0 \\
& =l_{x}\left(l_{y}(z)=l_{x \wedge y}(z)=(x \wedge y) \cdot z \quad \text { because } r+s \leqslant t .\right.
\end{aligned}
$$

iii). It comes from (i) by exchanging the roles of $x$ and $z$ in (ii).
iv). For $r=0$ or $t=0$, the relationship is obvious. We thus suppose $r, t>0$. By using (i) and (ii), we successively have:

$$
\begin{aligned}
x \cdot(y \cdot z) & =(-1)^{s(t-1)} x \cdot(z \cdot y)=(-1)^{t(s-1)}(x \wedge z) \cdot y \\
& =(-1)^{t(s-1)}(-1)^{r t}(z \wedge x) \cdot y=(-1)^{t(s-1)}(-1)^{r t} z \cdot(x \cdot y) \\
& =(-1)^{t(s-1)}(-1)^{r t}(-1)^{t(s-r-1)}(x \cdot y) \cdot z=(x \cdot y) \cdot z .
\end{aligned}
$$

### 2.5.3 Geometric Algebra

The Clifford algebra is now equipped with an exterior product. We can use concepts introduced in Grassmann algebras. We say that an element of $C(V, Q)$ is decomposable if it can be written as the exterior product of any number of element of $V$. We call the set of $k$-vecteurs the set $C^{k}(V, Q)=\operatorname{Vect}\left\{x_{1} \wedge \cdots \wedge x_{k}, x_{1}, \ldots, x_{k} \in V\right\}$. By convention $C^{0}(V, Q)=\mathbb{K}$. The $C^{k}(V, Q)$ spaces are in direct $\operatorname{sum} C(V, Q)=\bigoplus_{i=0}^{n} C^{i}(V, Q)$ and we have the equality $\operatorname{dim} C^{r}(V, Q)=\binom{n}{k}$.
We note $\langle\cdot\rangle_{i}$ the projection of $C(V, Q)$ onto $C^{i}(V, Q)$, so that:

$$
\begin{equation*}
x=\sum_{i=1}^{n}\langle x\rangle_{i} . \tag{2.15}
\end{equation*}
$$

We call degree of element $x$ of $C(V, Q)$ the integer $\max _{0 \leqslant i \leqslant n}\{0\} \cup\left\{i,\langle x\rangle_{i} \neq 0\right\}$. A nonnull $k$-vector is this of degree $k$.
We now establish two useful lemmas relying vector product and geometric product.
Lemma 2. If $x_{1}, \ldots, x_{r}$ is an orthogonal family of element of $V$, then

$$
x_{1} \cdots x_{r}=x_{1} \wedge \cdots \wedge x_{r}
$$

Proof. By induction on $r$. The case $r=1$ is obvious. We suppose $x_{1} \cdots x_{r}=x_{1} \wedge \cdots \wedge x_{r}$ for all $1 \leqslant r<n$. Let $x_{r+1} \in V$ such that the family $\left(x_{1}, \ldots, x_{r+1}\right)$ is orthogonal. We fix $u=x_{2} \cdots x_{r+1}$. According to (2.13) we have $x_{1} \cdots x_{r+1}=x_{1} u=x_{1} \wedge u+i_{x^{*}}(u)$. Yet $i_{x^{*}}(u)=\sum_{j=2}^{r+1}(-1)^{j} B\left(x_{1}, x_{j}\right)\left(x_{2} \wedge \cdots \wedge \widehat{x_{j}} \wedge \cdots \wedge x_{r+1}\right)=0$, because $B\left(x_{1}, x_{j}\right)=0$ for all $j=2, \ldots, r+1$. We thus have the equality $x_{1} \cdots x_{r}=x_{1} \wedge \cdots \wedge x_{r}$.

Lemma 3. Let $F$ be a vector subspace of $V,\left(v_{1}, \ldots, v_{r}\right)$ a base of $F$ and $\left(u_{1}, \ldots, u_{r}\right)$ an orthogonal base of $F$. If $A$ denotes the transfer matrix of the base $\left(u_{1}, \ldots, u_{r}\right)$ to the base $\left(v_{1}, \ldots, v_{r}\right)$, we have the equality:

$$
\begin{equation*}
v_{1} \wedge \cdots \wedge v_{r}=\operatorname{det}(A) u_{1} \cdots u_{r} . \tag{2.16}
\end{equation*}
$$

Proof. We have $v_{i}=\sum_{k=1}^{r} a_{k i} u_{k}, \forall 1 \leqslant i \leqslant r$. We can then write:

$$
\begin{aligned}
v_{1} \wedge \cdots \wedge v_{k} & =\left(\sum_{i=0}^{r} a_{i 1} u_{i}\right) \wedge \cdots \wedge\left(\sum_{i=0}^{r} a_{i r} u_{i}\right) \\
& =\sum_{\sigma \in \mathcal{S}_{r}} a_{\sigma(1) 1} \cdots a_{\sigma(r) r} u_{\sigma(1)} \wedge \cdots \wedge u_{\sigma(r)} \\
& =\operatorname{det}(A) u_{1} \wedge \cdots \wedge u_{r}=\operatorname{det}(A) u_{1} \cdots u_{r},
\end{aligned}
$$

Property 11. Let $v_{1}, \ldots v_{r}$ be vectors, $x$ a $k$-vector and $y \in C(V, Q)$. Also:
i) $\left(v_{1} \wedge \cdots \wedge v_{r}\right)^{\dagger}=v_{r} \wedge \cdots \wedge v_{1}=(-1)^{\frac{r(r-1)}{2}}\left(v_{1} \wedge \cdots \wedge v_{r}\right)$.
ii) $x^{\dagger}=(-1)^{\frac{k(k-1)}{2}} x$.
iii) $y^{\dagger}=\sum_{i=0}^{n}(-1)^{\frac{i(i-1)}{2}}\langle y\rangle_{i}$.

Property 12. Let $x$ be $k$-vector and $y, z \in C(V, Q)$. We have the following equalities:
i) $\alpha(x)=(-1)^{k} x$.
ii) $\alpha(y \wedge z)=\alpha(y) \wedge \alpha(z)$.
iii) $\alpha(y)=\sum_{i=0}^{n}(-1)^{i}\langle y\rangle_{i}$.
iv) $C^{+}(V, Q)=\bigoplus_{\substack{0 \leqslant i \leqslant n \\ i \text { pair }}} C^{i}(V, Q)$.
v) $C^{-}(V, Q)=\bigoplus_{\substack{0 \leqslant i \leq n \\ i \text { impair }}} C^{i}(V, Q)$.

Lemma 5. Let $x \in V$ and $\wedge_{x}: C(V, Q) \longrightarrow C(V, Q)$ such that $\wedge_{x}(u)=x \wedge u$ for all $u \in C(V, Q)$. Then:

$$
\begin{equation*}
\langle\cdot\rangle_{i+1} \circ \wedge_{x}=\wedge_{x} \circ\langle\cdot\rangle_{i} \quad \forall i \text { such that } 0 \leqslant i \leqslant n-1 . \tag{2.17}
\end{equation*}
$$

Proof. $\langle\cdot\rangle_{i}$ and $\wedge_{x}$ are indeed linear operators, it is sufficient to check (2.17) on each space $C^{k}(V, Q)$ where $0 \leqslant k \leqslant n$. Let $u \in C^{k}(V, Q)$ and $i$ such as $0 \leqslant i \leqslant n-1$.
If $k \neq i,\langle\cdot\rangle_{i+1} \circ \wedge_{x}(u)=\langle x \wedge u\rangle_{i+1}=0$ and $\wedge_{x} \circ\langle\cdot\rangle_{i}(u)=\wedge_{x}\left(\langle u\rangle_{i}\right)=0$.
If $k=r,\langle\cdot\rangle_{i+1} \circ \wedge_{x}(u)=\langle x \wedge u\rangle_{i+1}=x \wedge u$ and $\wedge_{x} \circ\langle\cdot\rangle_{i}(u)=\wedge_{x}\left(\langle u\rangle_{i}\right)=x \wedge u$.
Property 13. Let $x$ be a r-vector and $y$ a s-vector. If $r \neq 0$ or $s \neq 0$, we have $x \wedge y=\langle x y\rangle_{r+s}$.

Proof. If $r=0$ or $s=0$, the equality is obvious. We now suppose $r, s>0$. We proceed by induction on $n=r+s$. The case $r=s=1$ for $n=2$ is obvious. We suppose $n>2$ and $r+s=n$. By linearity, we can suppose that $x$ is decomposable, we thus have $x=x_{1} \wedge x^{\prime}$ and then:

$$
\begin{aligned}
x \wedge y & =x_{1} \wedge x^{\prime} \wedge y \\
& =x_{1} \wedge\left\langle x^{\prime} y\right\rangle_{r+s-1}, \quad \text { by recurrence hypothesis }, \\
& =\wedge_{x_{1}} \circ\langle\cdot\rangle_{r+s-1}\left(x^{\prime} y\right)=\langle\cdot\rangle_{r+s} \circ \wedge_{x_{1}}\left(x^{\prime} y\right), \quad \text { according lemma } 5 \\
& =\left\langle x_{1} \wedge\left(x^{\prime} y\right)\right\rangle_{r+s}=\left\langle x_{1} x^{\prime} y-i_{x_{1}^{*}}\left(x^{\prime} y\right)\right\rangle_{r+s}=\left\langle x_{1} x^{\prime} y\right\rangle_{r+s} \\
& =\left\langle\left(x_{1} \wedge x^{\prime}\right) y+i_{x_{1}^{*}}\left(x^{\prime}\right) y\right\rangle_{r+s}=\langle x y\rangle_{r+s},
\end{aligned}
$$

Hence the relationship at rank $n$.
Property 14. Let $x$ be a r-vector and $y$ a s-vector. If $r \neq 0$ and $s \neq 0$, we have $x \cdot y=\langle x y\rangle_{|r-s|}$.

Proof. By linearity, we can suppose that $x$ and $y$ are decomposable. We use induction on $r$.

1. If $r=1$, by using (2.13) we have:

$$
\begin{aligned}
x \cdot y & =i_{x^{*}}(y)=i_{x^{*}}(y)+\langle x \wedge y\rangle_{|s-1|}=\left\langle i_{x^{*}}(y)\right\rangle_{s-1}+\langle x \wedge y\rangle_{|s-1|} \\
& =\left\langle i_{x^{*}}(y)+x \wedge y\right\rangle_{|s-1|}=\langle x y\rangle_{|s-1|}
\end{aligned}
$$

2. We suppose $r>1$, there are two cases:
a) If $r \leqslant s$, we fix $x=x_{1} \wedge \cdots \wedge x_{r}$ with orthogonal vectors $x_{1}, \ldots x_{r}$. By using (2.13), we have:

$$
\begin{aligned}
x \cdot y & =\left(x_{1} \wedge \cdots \wedge x_{r}\right) \cdot y=\left(x_{1} \wedge \cdots \wedge x_{r-1}\right) \cdot\left(x_{r} \cdot y\right) \\
& =\left(x_{1} \cdots x_{r-1}\right) \cdot\left(x_{r} \cdot y\right)=\left\langle\left(x_{1} \cdots x_{r-1}\right)\left(x_{r} \cdot y\right)\right\rangle_{|r-1-(s-1)|} \\
& =\left\langle\left(x_{1} \cdots x_{r-1}\right)\left(x_{r} y-x_{r} \wedge y\right)\right\rangle_{|r-s|} \\
& =\left\langle x_{1} \cdots x_{r} y\right\rangle_{|r-s|}-\left\langle\left(x_{1} \wedge \cdots \wedge x_{r} \wedge y\right)\right\rangle_{|r-s|}=\langle x y\rangle_{|r-s|}
\end{aligned}
$$

b) If $r \geqslant s$, we fix $y=y_{1} \wedge \cdots \wedge y_{s}$ with orthogonal vectors $y_{1}, \ldots, y_{s}$. By using (2.14), we have:

$$
\begin{aligned}
x \cdot y & =x \cdot\left(y_{1} \wedge \cdots \wedge y_{s}\right)=\left(x \cdot y_{1}\right) \cdot\left(y_{2} \wedge \cdots \wedge y_{s}\right) \\
& =\left\langle\left(x \cdot y_{1}\right) y_{2} \cdots y_{s}\right\rangle_{|r-1-(s-1)|}=\left\langle\left(x y_{1}-x \wedge y_{1}\right) y_{2} \cdots y_{s}\right\rangle_{|r-s|} \\
& =\left\langle x y_{1} \cdots y_{s}\right\rangle_{|r-s|}-\left\langle x \wedge y_{1} \wedge \cdots \wedge y_{s}\right\rangle_{|r-s|}=\langle x y\rangle_{|r-s|},
\end{aligned}
$$

Hence the relationship at rank $r$.

### 2.6 Conclusion

We have presented a definition of the Clifford Algebra with a theoretical viewpoint. Defined products will then allow us to write linear transformations of the space $V$. We had to be interested in the case where $\mathbb{K}=\mathbb{R}$.

## Chapter 3

## Geometric Transformations

### 3.1 Introduction

We are interested in the case where $\mathbb{K}=\mathbb{R}$. We assume that the quadratic form $Q$ is nondegenerated and has the signature $(p, q)$. For simplicity we also note $\mathbb{R}_{p, q}$ the Clifford algebra $C(V, Q)$ and $\mathbb{R}_{p, q}^{k}$ the $k$-vectors of this algebra. 0 -vectors, 1 -vectors, 2 -vectors and 3 -vectors are also called respectively scalars, vectors, bivectors and trivectors. We will introduce the concept of pseudo-vectors and the operation of duality that allows to algebrize the transition to the orthogonal of a subspace of $V$. Products defined in the part I will then allow us to write linear transformations of the space $V$.
In a first time we define the invertibility then the duality. We secondly present the orthogonal projection onto a subspace, the orthogonal symmetry and the rotation.

### 3.2 Inversibility

An interest of Clifford algebras is that you can take the inverse of a non-isotropic vector. Indeed, let $v$ be a non-isotropic vector. We have $v^{2}=Q(v)$ then $v \frac{v}{Q(v)}=\frac{v}{Q(v)} v=1$ and $v^{-1}=\frac{v}{Q(v)}$.

You can also notice that every $k$-decomposable nonzero vector $u$ being a regular vector subspace is invertible. Such a vector can be written $\lambda v_{1} \cdots v_{k}$ where the $v_{i}$ anticommute, $Q\left(v_{i}\right)=\epsilon_{i}, \epsilon_{i}= \pm 1$ and $\lambda \in \mathbb{R}^{*}$. We have:

$$
u u^{\dagger}=u^{\dagger} u=\lambda^{2} Q\left(v_{1}\right) \cdots Q\left(v_{k}\right)=\lambda^{2} \epsilon,
$$

with $\epsilon=\epsilon_{1} \cdots \epsilon_{k}$ and thus

$$
u^{-1}=\frac{\epsilon}{\lambda^{2}} u^{\dagger} .
$$

### 3.3 Duality

We choose an orthonormal base $\left(e_{1}, \ldots, e_{n}\right)$ of $V$. We call pseudo-vector relative to the base $\left(e_{1}, \ldots, e_{n}\right)$ the element:

$$
I=e_{1} \cdots e_{n}
$$

We have the following relationships:

$$
I^{-1}=I^{\dagger}=(-1)^{\frac{n(n-1)}{2}} I,
$$

and if $u$ is $k$-vector,

$$
u I=(-1)^{k(n-1)} I u
$$

Definition 7. We call dual of an element $u \in C(V, Q)$ the element $\tilde{u}$ such that:

$$
\widetilde{u}=u I^{-1} .
$$

Remark 3. We remark that we have $\widetilde{u}=u \cdot I^{-1}$ for all non scalar $u$. In fact the pseudovector can be defined with the inner product which in this case, is a left contraction.

Lemma 1. Let $E$ be a subspace of $V$ and $E_{0}$ its kernel. Let $\left(e_{1}, \ldots, e_{p}\right)$ an orthogonal base of $E_{0}$ and $U$ a space such that $U \perp E_{0}=E$. There exists $f_{1}, \ldots, f_{p}$ such that $P_{i}=\mathbb{R} e_{i}+\mathbb{R} f_{i}$ is an hyperbolic plane and such that:

$$
F^{\prime}=P_{1} \perp \cdots \perp P_{p} \perp U
$$

is an orthogonal sum in $E$.
Proof. By induction on $p$. The case $p=0$ is obvious. We suppose the lemma true at rank $p-1, p \geqslant 1$. We fix $E_{1}=U+\operatorname{Vect}\left(e_{1}, \ldots, e_{p-1}\right)$. We have $E_{1} \subsetneq E$. Let $f_{p} \in E_{1}^{\perp} / E^{\perp}$, we then have $f_{p} \cdot e_{p} \neq 0$ and $e_{1} \cdot f_{p}=\cdots=e_{p-1} \cdot f_{p}=0$. By replacing $f_{p}$ by $f_{p}+\lambda e_{p}$ with a well chosen $\lambda$ we can suppose that $f_{p}$ is isotropic and that $e_{p} \cdot f_{p}=1$. The plane $P_{p}=\operatorname{Vect}\left(e_{p}, f_{p}\right)$ is then hyperbolic. We apply the induction hypothesis to the subspace $E_{1} \perp P_{p}$ whose kernel is $\operatorname{Vect}\left(e_{1}, \ldots, e_{p-1}\right)$. There exists then $p-1$ element $f_{1}, \ldots, f_{p-1}$ such that:

$$
F^{\prime}=P_{1} \perp \cdots \perp P_{p-1} \perp P_{p} \perp U
$$

hence the relationship at rank $p$.
Property 15. Let $E$ be a non zero subspace of $V$ and $E^{\perp}$ its orthogonal. If u represents $E$ then $\widetilde{u}$ represents $E^{\perp}$.

Proof. i) We suppose $E$ regular. Let $e_{n-k+1}, \ldots, e_{n}$ an orthogonal base of $E$ which is completed in an orthogonal base $e_{1}, \ldots, e_{n}$ of $V$. The subspace $E$ id represented by $u=e_{n-k+1} \wedge \cdots \wedge e_{n}=e_{n-k+1} \cdots e_{n}$. We have then:

$$
\begin{aligned}
\widetilde{u} & =e_{n-k+1} \cdots e_{n} I^{-1} \\
& =e_{n-k+1} \cdots e_{n} e_{n} \cdots e_{1} \\
& =e_{n-k} \cdots e_{1} \\
& =e_{n-k} \wedge \cdots \wedge e_{1},
\end{aligned}
$$

which represents the orthogonal of $E$.
ii) If $E$ is not regular. Let $E_{0}=E \cap E^{\perp}, A$ such that $E=E_{0} \oplus A,\left(a_{1}, \ldots, a_{q}\right)$ an orthogonal base of $A$ and $\left(e_{1}, \ldots, e_{p}\right)$ an orthogonal base of $E_{0}$. By applying lemma 1 , let $f_{1}, \ldots, f_{p}$ be elements such that $P_{i}=\operatorname{Vect}\left(e_{i}, f_{i}\right)$ is an hyperbolic
plane and $E^{\prime}=P_{1} \perp \ldots \perp P_{p} \perp U$ is regular. Let $G$ such that $G \perp E^{\prime}$ and $\left(g_{1}, \ldots, g_{k}\right)$ a base of $G$. We remark that the family:

$$
g_{1}, \ldots, g_{k}, \frac{e_{1}-f_{1}}{\sqrt{2}}, \ldots, \frac{e_{p}-f_{p}}{\sqrt{2}}, \frac{e_{1}+f_{1}}{\sqrt{2}}, \ldots, \frac{e_{p}+f_{p}}{\sqrt{2}}, a_{1}, \ldots, a_{q}
$$

is an orthonormal base of $V$. A pseudo-scalar is thus written:

$$
I=g_{1} \cdots g_{k} \cdot \frac{e_{1}-f_{1}}{\sqrt{2}} \cdots \frac{e_{p}-f_{p}}{\sqrt{2}} \cdot \frac{e_{1}+f_{1}}{\sqrt{2}} \cdots \frac{e_{p}+f_{p}}{\sqrt{2}} \cdot a_{1} \cdots a_{q}
$$

From which:

$$
\begin{aligned}
I^{-1} & =a_{q} \cdots a_{1} \cdot \frac{e_{p}+f_{p}}{\sqrt{2}} \cdots \frac{e_{1}+f_{1}}{\sqrt{2}} \cdot \frac{e_{p}-f_{p}}{\sqrt{2}} \cdots \frac{e_{1}-f_{1}}{\sqrt{2}} \cdot g_{k} \cdots g_{1} \\
& =a_{q} \cdots a_{1} \cdot \frac{f_{p} e_{p}-e_{p} f_{p}}{2} \cdots \frac{f_{1} e_{1}-e_{1} f_{1}}{2} \cdot g_{k} \cdots g_{1} .
\end{aligned}
$$

If $u=e_{1} \cdots e_{p} \cdot a_{1} \cdots a_{q}$ represents $E$, we also have:

$$
\begin{aligned}
\widetilde{u} & =u I^{-1} \\
& =e_{1} \cdots e_{p} \cdot a_{1} \cdots a_{q} \cdot a_{q} \cdots a_{1} \cdot \frac{f_{p} e_{p}-e_{p} f_{p}}{2} \cdots \frac{f_{1} e_{1}-e_{1} f_{1}}{2} \cdot g_{k} \cdots g_{1} \\
& =e_{1} \cdots e_{p} \cdot \frac{f_{p} e_{p}-e_{p} f_{p}}{2} \cdots \frac{f_{1} e_{1}-e_{1} f_{1}}{2} \cdot g_{k} \cdots g_{1} \\
& =e_{1} \cdots e_{p} \cdot \frac{f_{p} e_{p}}{2} \cdots \frac{f_{1} e_{1}}{2} \cdot g_{k} \cdots g_{1} \\
& =\frac{e_{p} f_{p} e_{p}}{2} \cdots \frac{e_{1} f_{1} e_{1}}{2} \cdot g_{k} \cdots g_{1} \\
& =e_{p} \cdots e_{1} \cdot g_{k} \cdots g_{1}
\end{aligned}
$$

which represents $E^{\perp}=E_{0} \oplus G$.

Lemma 6. Let $x$ be an element of $C(V, Q)$ and $d$ an integer such as $0 \leqslant d \leqslant n$. We also have:

$$
\widetilde{\langle x\rangle_{d}}=\langle\widetilde{x}\rangle_{n-d}
$$

Proof. By linearity, it is sufficient to check that the duality operator sends a $k$-vector on a $(n-k)$-vector. We can convince oneself by taking an orthogonal base $\left(e_{1}, \ldots, e_{n}\right)$ of $V$.

Property 16. Let a be a vector and $M$ a multivector. We have the following relationship of duality:

$$
\begin{equation*}
\widetilde{a \wedge M}=a \cdot \widetilde{M} \tag{3.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\widetilde{a \cdot M}=a \wedge \widetilde{M} \tag{3.2}
\end{equation*}
$$

Proof. By linearity, we can suppose that $M$ is a $k$-vector. if $k=n$, the equality is obvious. Otherwise we have successively with lemma 6 and properties 18 and 19 (appendices 3.7).

$$
\begin{aligned}
\widetilde{a \wedge M} & =\left\langle\widetilde{a M\rangle_{k+1}}\right. \\
& =\langle\widetilde{a M}\rangle_{n-(k+1)} \\
& =\langle a \widetilde{M}\rangle_{n-k-1} \\
& =a \cdot \widetilde{M}
\end{aligned}
$$

The relationship (3.2) is deduced from (3.1) by replacing $M$ by $\widetilde{M}$ and by taking the dual of obtained relationship.

### 3.4 Orthogonal projection onto a subspace

Property 17. Let $E$ be a regular subspace of $V$ of dimension $k$ such as $1 \leqslant k \leqslant n$ and let $p_{E}$ be the orthogonal projection onto $E$. Let $u$ be a decomposable $k$-vector which represents $E$. We have the following relationship:

$$
\begin{equation*}
p_{E}(v)=(v \cdot u) u^{-1} \tag{3.3}
\end{equation*}
$$

Proof. As all elements representing a given subspace are the same up to a positive factor, it is sufficient to prove (3.3) for example for $u=e_{1} \wedge \ldots \wedge e_{k}$ with $\left(e_{1}, \ldots, e_{k}\right)$ an orthonormal base of $E$ because $E$ is regular. We complete with an orthonormal base $\mathcal{B}=\left(e_{1}, \ldots, e_{n}\right)$ of $V$. Let $v \in V$ and $\left(\lambda_{1}, \ldots, \lambda_{n}\right) \in \mathbb{R}^{n}$ its coordinates in the base $\mathcal{B}$. We have:

$$
v=\sum_{i=1}^{n} \lambda_{i} e_{i}
$$

and

$$
p_{E}(v)=\sum_{i=1}^{k} \lambda_{i} e_{i}
$$

We remark that for $1 \leqslant i \leqslant n$ :

$$
i_{e_{i}^{*}}(u)= \begin{cases}e_{1} \wedge \cdots \wedge \check{e}_{i} \wedge \cdots \wedge e_{k} & \text { if } 1 \leqslant i \leqslant k \\ 0 & \text { if } k<i \leqslant n\end{cases}
$$

By linearity, we thus find:

$$
i_{v^{*}}(u)=\sum_{i=1}^{k}(-1)^{i-1} \lambda_{i} e_{1} \wedge \cdots \wedge \check{e}_{i} \wedge \cdots \wedge e_{k}
$$

It is sufficient to remark that:

$$
e_{1} \wedge \cdots \wedge \check{e}_{i} \wedge \cdots \wedge e_{k}=e_{1} \cdots \check{e}_{i} \cdots e_{k}
$$

and

$$
\left(e_{1} \cdots \check{e}_{i} \cdots e_{n}\right)\left(e_{1} \cdots e_{n}\right)^{-1}=(-1)^{i-1} e_{i}
$$

To conclude:

$$
p_{E}(v)=(v \cdot u) u^{-1}
$$

### 3.5 Orthogonal symmetry

Let $E$ be a regular subspace of $V$ and let $s_{E}$ be the orthogonal symmetry with respect to $E$. It is connected to the orthogonal projection $p_{E}$ by the formula:

$$
s_{E}=2 p_{E}-\mathrm{Id}
$$

We thus find, for all $v \in V$ :

$$
\begin{aligned}
s_{E}(v) & =2 p_{E}(v)-v \\
& =2(v \cdot u) u^{-1}-v \\
& =(2 v \cdot u-v u) u^{-1} \\
& =(v \cdot u-v \wedge u) u^{-1}
\end{aligned}
$$

Where $u$ is a vector, we have $u \wedge v=-v \wedge u$, we thus find:

$$
s_{E}(v)=u v u^{-1}
$$

Where $u$ represents a hyperplan, we have $u=\widetilde{n}$ with $n$ a non-isotropic vector. We also have:

$$
\begin{aligned}
s_{E}(v) & =(v \cdot \widetilde{n}-v \wedge \widetilde{n}) \widetilde{n}^{-1} \\
& =(\widetilde{v \wedge n}-\widetilde{v \cdot n}) \widetilde{n}^{-1} \\
& =-\widetilde{n v} \widetilde{n}^{-1} \\
& =-n v I^{-1} I n^{-1} \\
& =-n v n^{-1} .
\end{aligned}
$$

In this two cases and up to the sign we obtain a rotation of angle $\pi$ around an axis and a symmetry with respect to a hyperplane by conjugating the vector $v$ by an invertible element of the Clifford algebra. This motivates the definition of the Clifford group in the next section.

### 3.6 Rotation

### 3.6.1 Clifford group

Let $G$ be the set of invertible elements $g \in C(V, Q)$ such that:

$$
\varphi_{g}(x)=g x g^{-1} \in V, \quad \forall x \in V
$$

Then $G$ is a group and $\varphi_{g} \in \operatorname{GL}(V)$.

Definition 8. The multiplicative group $G$ of invertible elements $g \in C(V, Q)$ such that:

$$
g x g^{-1} \in V, \quad \forall x \in V
$$

is called the Clifford group.
The intersection $G \cap C^{+}(V, Q)$ is called the even Clifford group noted $G^{+}$.
Theorem 2. i) $\varphi$ is a representation of $G$ in $\mathrm{O}(Q)$ whose kernel is the set of invertible elements of the center of $C(V, Q)$.
ii) $V \cap G$ is the set of non-isotropic vectors of $V$ and if $g \in V \cap G,-\varphi_{g}$ is the orthogonal symmetry with respect to the hyperplane $g^{\perp}$.
iii) If $\operatorname{dim} V=2 r, \varphi(G)=\mathrm{O}(Q), \varphi\left(G^{+}\right)=\mathrm{SO}(Q)$.
iv) If $\operatorname{dim} V=2 r+1, \varphi(G)=\varphi\left(G^{+}\right)=\mathrm{SO}(Q)$.

Proof. (i). The application $\varphi_{g}=\varphi(g)$ is an isometry because:

$$
\begin{aligned}
Q\left(\varphi_{g}(x)\right) & =Q\left(g x g^{-1}\right) \\
& =\left(g x g^{-1}\right)^{2} \\
& =g x^{2} g^{-1} \\
& =Q(x)
\end{aligned}
$$

The application $\varphi$ is thus a morphism of $G$ in $\mathrm{O}(Q)$. Then let $g \in \operatorname{ker} \varphi, g$ is invertible and we have $g x g^{-1}=x$ for all $x \in V$ i.e. $g \in Z \cap G$ because $V$ spans $C(V, Q)$. Reciprocally, let $g$ an invertible element of the center of $C(V, Q)$, we have $\varphi_{g}=\operatorname{Id}_{V}$ thus $g \in \operatorname{ker} \varphi$. (ii). Let $g \in V \cap G, g$ be invertible, thus $g^{2}=Q(v) \neq 0$. Reciprocally let $g$ be a non-isotropic vector of $V$. Then $g$ has for invertible $g(Q(v))^{-1}$ and we have:

$$
\begin{aligned}
\varphi_{g}(x) & =\frac{g x g}{Q(v)} \\
& =\frac{a(2 B(x, a)-a x)}{Q(a)} \\
& =-x+\frac{2 B(x, a)}{Q(a)} a
\end{aligned}
$$

Thus $g \in V \cap G$ and $-\varphi_{g}$ is the orthogonal symmetry of hyperplane $g^{\perp}$.
(iii). Let $u \in \mathrm{O}(Q)$. By the theorem of Cartan-Dieudonné, $u$ is written as reflection product i.e. $u=u_{1} \circ \cdots \circ u_{h}$ with $u_{i}=-\varphi\left(x_{i}\right)$ and $x_{i}$ is a non-isotropic vector, $1 \leqslant i \leqslant h$. Finally $u=(-1)^{h} \varphi(g)$ with $g=x_{1} \cdots x_{h}$. We deduce $\operatorname{SO}(Q) \subset \varphi\left(G^{+}\right)$.
In other hand, as $n$ is even we remark that $\varphi(I)=-\operatorname{Id}_{V}$ thus if $h$ is odd $u=\varphi(I g)$. We have thus:

$$
\varphi(G)=\mathrm{O}(Q)
$$

It remains to prove that $\varphi\left(G^{+}\right) \subset \mathrm{SO}(Q)$. Suppose by contradiction that $\varphi(t)=u$ with $t \in G^{+}$et $u \in \mathrm{O}(Q) \backslash \mathrm{SO}(Q)$. According to the above, we can also write $u=\varphi(I g)$.

We have thus $I g t^{-1} \in \operatorname{ker} \varphi$ then $\operatorname{Igt}^{-1} \in \mathbb{K}$ because $n$ is even which is a contradiction because $\alpha\left(I g t^{-1}\right)=-1$.
(iv). If $n$ is odd, using the same reasoning we find:

$$
\mathrm{SO}(Q) \subset \varphi\left(G^{+}\right)
$$

Suppose by contradiction that $-\operatorname{Id}_{V} \in \mathrm{O}(Q) \backslash \mathrm{SO}(Q)$ be an element of $\varphi(G)$. Let $t \in G$ such as $t x t^{-1}=-t$ for all $x \in V$. We have $t I t^{-1}=-I$ but $I \in Z$ because $n$ is odd which is a contradiction. We have also $\varphi(G) \subset \mathrm{SO}(Q)$ because $-\mathrm{Id}_{V}$ and $\mathrm{SO}(Q)$ span $\mathrm{O}(Q)$. Thus we have the following inclusions:

$$
\mathrm{SO}(Q) \subset \varphi\left(G^{+}\right) \subset \varphi(G) \subset \mathrm{SO}(Q),
$$

From which we conclude:

$$
\varphi(G)=\varphi\left(G^{+}\right)=\mathrm{SO}(Q) .
$$

### 3.6.2 Reduced Clifford group

According to the previous theorem in all cases we have $\varphi\left(G^{+}\right)=S O(Q)$. We search to reduce $G^{+}$while maintaining the surjectivity of $\varphi$.

Lemma 7. For all $g \in G^{+}, g^{\dagger} g \in \mathbb{R}^{*}$ and $N: g \mapsto g^{\dagger} g$ is a homomorphism of $G^{+}$in $\mathbb{R}^{*}$.
Proof. We prove that $G$ is stable by $\dagger$ operator.
Let $g \in G$ and $x \in V$. Fix $x^{\prime}=\varphi_{g}(x)$. We have:

$$
x^{\prime}=g x g^{-1},
$$

From which, by applying $\dagger$ operator:

$$
\begin{equation*}
x^{\prime}=\left(g^{\dagger}\right)^{-1} x g^{\dagger} . \tag{3.4}
\end{equation*}
$$

Also $\varphi_{\left(g^{\dagger}\right)^{-1}}(x) \in V$ thus $\left(g^{\dagger}\right)^{-1} \in G$ from which $g^{\dagger} \in G$. And moreover:

$$
\begin{aligned}
\varphi_{g^{\dagger} g}(x) & =g^{\dagger} g x\left(g^{\dagger} g\right)^{-1} \\
& =g^{\dagger} x^{\prime}\left(g^{\dagger}\right)^{-1} \\
& =x, \quad \text { according to (3.4). }
\end{aligned}
$$

Also $g^{\dagger} g$ belongs to the center $Z$ of the Clifford algebra.
If moreover $g \in G^{+}$we have $g^{\dagger} g \in G^{+} \cap Z=\mathbb{R}^{*}$.
It remains to prove that $N$ is an homomorphism. Let $g, h \in G^{+}$we have:

$$
\begin{aligned}
N(g h) & =(g h)^{\dagger} g h \\
& =h^{\dagger} N(g) h \\
& =N(g) N(h) .
\end{aligned}
$$

Definition 9. The subgroup of elements $g \in G^{+}$such that $|N(g)|=1$ is called spinor group of Clifford algebra $\mathbb{R}_{p, q}$ and it is noted $\operatorname{Spin}(Q)$.

Thus we remark that transformations induced by a metric $Q$ on a vector space $V$ can be express as simple algebraic operations in Clifford algebra of $V$ associated to $Q$.

### 3.7 Conclusion

We have presented Clifford Algebra with a theoretical viewpoint and their properties and certain concepts that have a theoretical interest for their applications in physics and computer science.

## Appendice

The proofs of the property of the wedge product and the one of the inner product can be found in the part I " A Theoretic Approach of Classical Operations in Clifford Algebra (I): the Inner Product".

Property 18. Let $x$ be a r-vector and $y$ a s-vector. If $r \neq 0$ or $s \neq 0$, we have $x \wedge y=\langle x y\rangle_{r+s}$.

Property 19. Let $x$ be a r-vector and $y$ a s-vector. If $r \neq 0$ and $s \neq 0$, we have $x \cdot y=\langle x y\rangle_{|r-s|}$.

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