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Title: Contributions of MIR to Soundscape Ecology. Part 2: Spectral timbral analysis for discriminating soundscape components Running Title: Spectral timbral analysis

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Contributions of MIR to Soundscape Ecology. Part 2: Spectral timbral analysis for

discrimination of soundscape components

by Kristen M. Bellisario, Jack VanSchaik, Zhao Zhao, Amandine Gasc, Hichem Omrani, and Bryan C. Pijanowski

Abstract

Soundscape ecology evaluates biodiversity and environmental disturbances by investigating the interaction among soundscape components (biological, geophysical, and humanproduced sounds) using data collected with autonomous recording units. Current analyses consider the acoustic properties of frequency and amplitude resulting in varied metrics, but rarely focus on the discrimination of soundscape components. Computational musicologists analyze similar data but consider a third acoustic property, timbre.

Here, we investigated the effectiveness of spectral timbral analysis to distinguish among dominant soundscape components. This process included manually labeling and extracting spectral timbral features for each recording. Then, we tested classification accuracy with linear and quadratic discriminant analyses on combinations of spectral timbral features.

Different spectral timbral feature groups distinguished between biological, geophysical, and manmade sounds in a single field recording. Furthermore, as we tested different combinations of spectral timbral features that resulted in both high and very low accuracy results, we found that they could be ordered to "sift" out field recordings by individual dominant soundscape component.

By using timbre as a new acoustic property in soundscape analyses, we could classify dominant soundscape components effectively. We propose further investigation into a sifting scheme that may allow researchers to focus on more specific research questions such as understanding changes in biodiversity, discriminating by taxonomic class, or to inspect weatherrelated events.

1. Introduction

Soundscape ecology is an emerging science that provides a new paradigm to address a variety of global environmental change issues (Pijanowski, Farina, Gage, Dumyahn, & Krause, 2011a; Pijanowski, Villanueva-Rivera, Dumyahn, Farina, Krause, Napoletano, ... & Pieretti, 2011b; *in sensu* Vitousek, Mooney, Lubchenco, & Melillo 1997). Soundscapes — defined as the combination of biological (e.g., animal vocalizations), geophysical (e.g., thunder, rain) and anthropogenic (e.g., transportation) sounds in a landscape (Pijanowski et al., 2011b) — contain information that can be used to study environmental patterns and processes. Soundscape analyses have been successfully applied to evaluate patterns of biodiversity in the context of environmental disturbances (e.g., Gasc et al., 2018; Farina & Pieretti, 2014; Sueur, Aubin, & Simonis, 2008).

Autonomous recording units (ARUs) are widely used survey instruments deployed to collect sound in the field for large temporal and/or spatial scale ecological research projects. As audio files contain a vast amount of data per unit, long-term landscape level studies tend to amass large volumes of recordings that are challenging to analyze with traditional "listen and tag" approaches (Towsey, Parsons, & Sueur, 2014; Zhao, Zhang, Xu, Bellisario, Dai, Omrani, & Pijanowski, 2017). Thus, researchers need efficient, automated analysis methods for conducting a majority of soundscape ecological research.

Two classes of approaches are currently being used by soundscape ecologists using automated techniques. This first approach is applied to species presence-absence surveys; these methods use segmentation of a sound file into species calls which are then matched to a known template of spectral characteristics using machine learning algorithms (e.g., Keen, Ross, Griffiths, Lanzone, & Farnsworth, 2014; Zhao et al., 2017). Automating these tools has been successfully demonstrated by a variety of researchers and is useful for studies designed to determine if a rare species is present at a location.

The second approach includes the application of metrics of broad spectral features in a recording (Villanueva et al., 2011; Sueur et al., 2014). These acoustic indices calculate the sonic complexity across a recording, integrating frequency and amplitude properties through such features as the entropy, evenness and dominance of frequencies, frequency band ratios, the number of frequency peaks, or the complexity of all signals across temporal and spectral ranges of the recordings. In one comparison of indices in varying landscapes, the acoustic complexity index (ACI) (Pieretti & Farina, 2013) and bioacoustics index (Boelman, Asner, Hart, & Martin, 2007) were linked to bird acoustic activity while the acoustic diversity index (ADI) (Villanueva-Rivera, Pijanowski, Doucette & Pekin, 2011) was sensitive to nocturnal activity (Fuller, Axel, Tucker, & Gage, 2015). Pekin et al. (2014) also showed that specific frequency bands as well as the ADI were positively correlated with the structural complexity of vegetation in a Neotropical rainforest that varied from old growth to young, secondary forests.

However, both current approaches to developing measures of acoustic patterns across space and time have their shortcomings. For the first approach, automated species detection requires the knowledge of the calls of every species present in a recording. Although much is known of bird

calls, species specific sounds of other animal calls such as amphibians, insects, fish and aquatic invertebrates are widely unknown. The call of many terrestrial mammals are extremely complex (e.g., primates) and species detection methods applied to those species have been limited (Aide, Corrada-Bravo, Campos-Cerqueira, Milan, Vega & Alvarez, 2013). The second approach, although widely used currently, make numerous assumptions about the nature of sound and their sound sources limiting their use in natural resource management. For instance, the Normalized Difference Soundscape Index (NDSI) (Kasten, Gage, Fox, & Joo, 2012) provides a ratio of animal and human soundscape contribution but its anthrophony frequency boundaries may include animal species that vocalize within the anthrophony frequency range (Eldridge, Casey, Moscoso, & Peck, 2016; Towsey et al., 2014). Thus, the reliability of acoustic indices is influenced by several factors that require substantial interpretation and may affect the quality of the result (Fairbrass, Rennett, Williams, Titheridge, & Jones, 2017; Mammides, Goodale, Dayananda, Kang, & Chen, 2017). Often, reliability of these indices is affected by geophonic and anthropogenic sounds captured in soundscape field recordings. As many researchers focus exclusively on the analysis of biophonic sounds, a filtering method of these competing sounds might aid researchers who are limited in the ability to interpret the biophony component and potentially improve index reliability.

In this paper, we present a novel approach for classifying the dominant soundscape composition of biophony, geophony, and/or anthrophony using a method classically used in musicology, spectral timbral analysis. Musicians have recognized "timbre" as a significant property of a sound signal influenced by composition (e.g., wood versus metal), shape (e.g., bell size), and sound production mechanism (e.g., string versus reed). The Acoustical Society of America defines timbre as the "attribute of auditory sensation which enables a listener to judge that two non-identical sounds, similarly presented and having the same loudness and pitch, are dissimilar" (Kitamura 1988). Recently, a group of computational musicologists has developed approaches that quantify timbral qualities, for instance using spectral features, to classify musical instruments (Peeters, Giordano, Susini, Misdariis, & McAdams, 2011). This group refers to this approach as Music Information Retrieval (MIR), a system that relies on models to solve audio classification problems using temporal and spectral features (Downie, 2003).

Spectral timbral analysis has been applied to tonal and noise-like signals in controlled tests using labeled samples (e.g., bird, cow, thunder, specific music instrument) and effective classification results have been obtained (e.g., Mitrovic, Zeppelzauer, & Eidenberger, 2007). As sound production mechanisms of terrestrial species (Marler, 1967; Wiley & Richards, 1978) are similar to those of idiophone (e.g. stringed) and aerophone (e.g., air) instruments (von Hornbostel & Sachs, 1914), we propose that MIR classification methods (Herrera, Amatriain, Batlle, & Serra, 2000) may be an adaptable analysis for soundscape ecologists. For instance, some birds and most insects may be considered idiophones, while more melodic birds and many amphibians may be aerophones.

Limited research has been conducted on how spectral timbral features classify field recordings that contain biological and non-biological sound sources (Bormpoudakis, Sueur, & Pantis, 2013) and to date, MIR methods have not been applied to soundscape ecology research (see Bellisario and Pijanowski, in review, for additional information). Considering that musical sound production properties are similar to those in the ecology domain, we were interested in whether these features

could distinguish between soundscape classes of anthrophony, geophony, and biophony, or in what capacity this is possible. Methods that could assist in further deconstructing sound sources to major animal taxonomic classes (e.g., taxonomic groups of birds, insects, amphibians, etc.) would be a great improvement over the approaches that employ acoustic metrics. We argue that spectral timbral features have the potential to characterize soundscape field recordings by dominant soundscape composition group (biophony, geophony, and anthrophony) and should complement current analysis approaches. The use of timbral features in bioacoustics and soundscape analyses has benefited previous research. For instance, spectral centroid was a favorable feature in the classification of anurans (Han et al, 2011). And, Sueur et al (2008) used spectral evenness as the basis for the H(f) entropy index. Another timbral feature used in current bioacoustic classification analyses is MFCC (Mel-frequency cepstral coefficients). This timbral feature has measurable success at classification of anurans (Noda et al 2016) but is less robust in classifying birds with urban noise (Ricard and Glotin, 2016).

Here, we use MIR methods to demonstrate the efficacy of using a spectral timbral analysis approach to the field of soundscape ecology. Recordings from three contrasting ecosystems: tropical forest, an arid grassland, and an open field in an estuary system, were analyzed and the performance of spectral timbral features in classifying sound samples to ecologically meaningful classes was evaluated. In the rest of this paper, Section 2 briefly describes timbre as an acoustic feature from the perspective of the musicology field. Section 3 describes field recordings and spectral timbral analysis process. Experimental results and discussion are provided in Section 4 and 5.



Figure 1: Timbre Description

The pitch 440 Hz (1) is played by three different sound sources (2a, 2b, and 2c) at the same loudness, or amplitude. Even though pitch and amplitude are the same for each sound source, the resulting temporal envelope (3a) and spectral envelope (3b) are different. These differences are features of timbre and can help discern between a played tuning fork, guitar, or recorder. Ultimately, these features provide unique patterns that can be used in machine learning applications.

2. Background: timbre as an acoustic feature

One of the first musicologists to quantify timbre was Schouten (1968) who suggested that timbre has several acoustic dimensions including temporal and spectral envelopes (Figure 1). The temporal envelope describes the waveform by overall shape of the signal (attack, sustain, decay, and release) over time while the characteristics of the spectral envelope are determined by the size of its sound source and the composition of its resonator, e.g., wood or metal. In this example, a single pitch (440 Hz) (1) is notated by three different sound sources, a tuning fork (2a), guitar (2b), and recorder (2c) that results in a waveform. The temporal envelope (3a) is the shape of this waveform and described as the amplitude of the pitch over time. The shape of the recorder's envelope differs from the guitar because of amplitude variation caused by vibrato and air pressure to produce sound. The differences between these sounds are evident in the spectral envelope (3b). The pure tone emitted from the tuning fork has a single harmonic peak at 440 Hz, while the recorder and guitar have a harmonic peak at 440 Hz but also harmonic peaks at different simultaneous frequencies that resonate when the single pitch is played by the instrument. It is this type of difference between the spectral envelopes of the tuning fork, guitar, and recorder that provide a unique set of descriptors that can identify one instrument from another instrument. Ultimately, the full set of timbral features exhibited in temporal and spectral envelopes can be quantified.

Instrument timbral profiles result in unique patterns including those generated by a vibration from hitting, shaking, and/or scraping (idiophone), and by the modulation of vibrations of air or other mediums (aerophone). These sound-production mechanisms are similar to those of sources in soundscapes. Although MIR models are not expressly designed to analyze soundscape recordings, some non-musical sounds have been identified in MIR analysis that share similar features with soundscape ecology recordings, such as a dog bark or rain (Mitrovic, 2006).

In particular, one MIR feature set used for instrument classification consists of spectral timbral features, a type of frequency-domain measurement resulting in unique spectral envelopes. More specifically, *spectral centroid* describes the brightness of sound and is also known to detect the difference among sounds, for instance those produced by various techniques of a violin bow; and *spectral slope* indicates how the sound tapers off toward high frequencies, with higher values indicating a stronger low frequency component (Bullock & Conservatoire, 2007). Both spectral centroid and spectral slope are highly correlated for harmonic instruments (r=0.96), but may be unique classifiers in a soundscape. Three other spectral features measure differences in the bandwidth and include *spectral skewness* — relationship to the mean and spread of the spectrum; *spectral spread* — the distribution of energy among frequencies; and *spectral variance* – a weighted version of spectral spread. These measurements are influenced by the beginning of a sound, or articulation features, and offer unique characteristics that MIR technologists (Agostini, Longari, & Pollastri, 2003; Gutierrez, 2006; Peeters et al., 2011; Tzanetakis & Cook, 2002) and audiologists (Krimphoff, McAdams, Winsberg, Petit, Bakchine, Dubois, … & Vellas, 1994) have successfully used for sound classification tasks. Soundscape recordings often include overlapping,

or polyphonic, sounds. Recent MIR work has shown that instrument families (e.g., flute, violin, french horn) can be classified with the correct complimentary set of features even within a polyphonic texture (Muller, Ellis, Klapuri, & Richard, 2011). Based on the aforementioned studies, spectral centroid, spectral slope, spectral skewness, spectral spread, and spectral variance, as well as their different combinations, were investigated in this paper.

TIMBRAL ANALYSIS PROCESS



Figure 2: Block diagram of the proposed timbral analysis process.

3. Materials and methods

The overall workflow of our proposed spectral timbral analysis procedure consists of three main phases: 1) soundscape bank selection, 2) feature extraction, and 3) validation (Figure 2). The stratified random samples of sound recordings used in this work, i.e. the soundscape bank, are field recordings collected from three different ecosystems. The feature extraction step is a crucial step that computes spectral timbral measurements for each recording in the sound bank. Validation focused on identifying ecologically meaningful classes using an adapted sensory evaluation method (SEM) after an observation window length was determined. Then, based on five individual spectral timbral features, feature groups were assessed in terms of soundscape composition classification accuracy using discriminant analysis (DA).

3.1 Soundscape bank selection

We selected soundscape recordings from the Center for Global Soundscapes (CGS) soundscape library located at Purdue University (West Lafayette, Indiana, USA). These stereo recordings were collected in the field with ARU SM2+ (Wildlife Acoustics Inc., Maynard, MA, USA). All field recordings had a duration of ten minutes and a sampling rate of 44,100 Hz with 16-bit depth. We considered field recordings for four discrete time periods (dawn – 6-8:30 am, midday – 11am-1:30 pm, dusk – 6-8:30 pm, and late evening – 11 pm-1:30 am) and from three different ecosystems: a tropical forest located in La Selva Biological Station (Costa Rica; n = 239), an arid grassland located in the Chiricahua National Monument located in the Sonoran desert (Arizona, USA; n = 241), and an estuarine open field located in the Wells Marine Reserve (Maine, USA; n = 241). The samples from the La Selva Biological Station were collected from the old growth and mature secondary forest dominated by sounds from over 700 species of mammals, birds, amphibians and insects (Pekin et al, 2012). Most common sounds are from rain, howler monkeys (Alouatta

species), toucans (Ramphastidae), tinamous (Tinamidae), cicadas (Cicadidae), and a variety of tropical frog species (Anura). The samples from the study in Chiricahua National Monument focused on arid environments with soundscapes of insects, birds, and wind. Samples from the Wells Estuary Reserve study focused on anthropogenic influences on a coastline reserve that serves as a fragile interface between the land and ocean systems. Common sounds in the terrestrial estuary were comprised of shorebirds and forest breeding passerine birds, along with those sounds from human activities (motors), rain, wind, and insects (Appendix A). The testing dataset used in this work consisted of the first 60s of 180 recordings with 60 recordings per site that were randomly selected via stratified sampling per site and time period from the 721 soundscape bank recordings.

3.2 Spectral timbral feature extraction

Spectral timbral features were extracted using a short-time Fourier Transform (STFT) that was computed with a window size of 1024. As the sample rate of the recordings were 44100 Hz, this resulted in a discrete frame length of 23ms. We used a Blackman-Harris window for the transform because it minimizes side-lobe levels, or undesired artifacts (spectral components that are present during the transform process), and is also a preferred window in polyphonic pitch detection (Harris, 1978; Herrera, Amatriain, Batlle, & Serra 2000; Masri & Bateman, 1995). Five spectral timbral features—spectral centroid, spectral spread, spectral skewness, spectral slope, and spectral variance—were extracted per frame of 23 ms from each recording in the dataset using Sonic Annotator (Cannam, Landone, & Sandler, 2010) with libxtract algorithms (Bullock & Conservatoire, 2007). A brief description of the spectral timbral features selected for this experiment is presented in Appendix B.

3.3 Validation

The validation phase aimed to determine how ecologically meaningful classes, identified using an adapted sensory evaluation method (SEM), match different combinations of the spectral timbral features. This phase included 1) determining the best window length of spectral timbral features for the DA; 2) describing the soundscape composition class for each recording using SEM by expert coders with assistance of visually inspecting the corresponding spectrogram (full bandwidth) or melodic-range spectrogram (a type of zoomed spectrogram used to inspect information in the 1.2 kHz bandwidth range) (Cannam et al., 2010); and 3) evaluating how the timbral features classify soundscape classes using DA. All analyses of this section were computed in the R program (initially Rx86_64 3.0.2; 2014 and optimized for Rx86_64 3.5.0, R Core Team, 2018) using packages 'vegan' (Oksanen et al, 2018), 'MASS' (Venables and Ripley, 2002), 'pROC' (Robin et al, 2011) and 'caret' (Kuhn, 2016). Visualizations used packages 'ggplot2' (Wickham, 2016), 'gplot'(Wasserman & Faustm 1994), 'dplyr' (Wickham & Francois, 2016) , 'colorspace' (Ihaka et al, 2016), and 'alluvial' (Bojanowski & Edwards, 2016), here on after referred to by the package name ("package name," R package).

3.3.1 Observation window segment inspection

Spectral timbral features were first extracted on a randomly selected subsample from the testing database in a frame-by-frame manner. However, considering the acoustic interpretation of a sound by humans for SEM labeling requires a longer duration, we calculated the centered mean of different window segment durations (1s, 3s, 10s, and 60s) for each feature and compared the

resulting mean value with those single frame counterparts using the absolute value of a Pearson correlation (mean value is the sum of all discrete 23ms for a length duration divided by the number of frames centered around the compared 23ms frame). The window length that had the high and consistent Pearson correlation values across features was considered the best performing choice, in our case (3s). Then, this window length segment inspection was used to establish the duration of the recordings used in the SEM (subsection 3.3.2) as well as to compute each mean feature value in our analysis (subsection 3.3.3) for each recording. Thus, we trimmed the testing dataset recordings from 60s to 3s segments (1s to 4s) for all further phases of this experiment.

3.3.2 Sensory evaluation method (SEM)

SEM is a method whereby humans use a sensory response and rate results according to that sense (Lokki, Pätynen, Kuusinen, & Tervo, 2012; Meilgaard, Carr, & Civille, 2006). In our adaptation of this method, we used both sight and hearing to label soundscape recordings in the dataset (n=180). First, KB and JV listened to 1s-4s of each recording in the testing dataset and coded it as containing biophony, geophony, and/or anthrophony. We assigned a single label to each recording using a hierarchical approach when two or more classes were present in a single sound file (Appendix A). Here, a class means anthrophony, geophony, or biophony. Any sound file that did not result in agreement was reviewed using a spectrogram and/or melodic-range spectrogram by KB and ZZ. The final label of the soundscape was determined in a single-label manner using the following coding rule: a recording was considered anthrophony if any motor sound (vehicle, motor boat, airplane) or coastal noise (n=12) (identified using a melodic-range spectrum as a constant band of low frequency with or without harmonic structure) was present (Pieretti & Farina 2013); then, geophony if any geophysical sounds of rain, wind or wind-like noise (identified using a melodic-range spectrum as different than anthrophony or coastal noise by fluctuations in the low frequency bands) were present (Digby, Towsey, Bell, & Teal, 2013; Hofmann, Wolff, Buck, Haulick, & Kellermann, 2012; Soares & Cherneva, 2005); and, then biophony when the soundscape consisted exclusively of biological sounds (unless minimal rain drops) from insects, amphibians, and/or some birds. This coding rule was developed using an exploratory data analysis of a random sample (n=60, 23ms frame) drawn from the original dataset to see how spectral timbral features measure sound characteristics of the soundscape composition classes (Borcard, Gillet, & Legendre, 2011).

Furthermore, considering that the alluvial diagram is a powerful visualization tool that compares categorical data within groups (Liu, Derudder, & Taylor, 2013), we used an alluvial diagram to compare the distribution of the SEM-derived classes within and between sites and time of the day ('alluvial', R package).

3.3.3 Discriminant analysis (DA)

Discriminant analyses searches feature combinations that best separate classes (Legendre and Legendre 1998). The soundscape recordings from the testing dataset were classified using a combinatorial computation of all possible feature combinations excluding single spectral timbral feature. We did not evaluate single features, as our preliminary work found that the individual features were not suitable for discrimination tasks. Additionally, considering that the unbalanced conditions of the SEM-derived classes could bias the DA results, the use of our small sample size

per class reduced potential bias when working with an unbalanced dataset (Blagus & Lusa, 2010; Xue & Titterington, 2008).

Table 1: Feature Groups

Listing of possible feature groups [FG] combinations of spectral timbral features used in the discrimination analysis.

Feature Group	Spectral Timbral Features
FG1	centroid, skewness, slope, spread, variance
FG2	centroid, skewness, slope, spread
FG3	centroid, skewness, slope
FG4	centroid, skewness
FG5	centroid, skewness, spread
FG6	centroid, skewness, variance
FG7	centroid, skewness, slope, variance
FG8	centroid, skewness, spread, variance
FG9	centroid, slope, spread, variance
FG10	centroid, slope, variance
FG11	centroid, slope, spread
FG12	centroid, slope
FG13	centroid, spread, variance
FG14	centroid, spread
FG15	centroid, variance
FG16	skewness, slope, spread, variance
FG17	skewness, slope, spread
FG18	skewness, slope, variance
FG19	skewness, slope
FG20	skewness, variance
FG21	skewness, spread, variance
FG22	skewness, spread
FG23	slope, spread, variance
FG24	slope, spread
FG25	slope, variance
FG26	spread, variance

We assessed conformance of the data to assumptions of multivariate normality, homogeneity of variance, and non-collinearity (Anderson, 2006). We tested multivariate normality using a Bonferroni-corrected permutational ANOVA (permutations=10,000) (Oksanen, 2016; Team,

2013; Venables & Ripley, 2002) which assessed if mean distances from group centroids in the multivariate space were similar among each group (Anderson, 2006; McArdle & Anderson, 2001), examined resulting covariance matrices for homogeneity of variance ('vegan,' R package), and checked collinearity (' MASS,' R package). Specifically, we tested the 26 possible combinations of the five features (Table 1), i.e. 26 different feature groups (FG), with two discriminant analysis classification algorithms: linear (LDA) and quadratic discriminant analysis (QDA) ('MASS,' R package).

These classifications were validated by comparing them to SEM results using a jackknife cross-validation (Oksanen, 2016; Venables & Ripley, 2002), which produced a confusion matrix ('vegan,' R package). This confusion matrix was used to compute performance metrics, i.e. accuracy, sensitivity (true positive rate, TPR) specificity (1-specificity is false positive rate, FPR) ('caret,' R package), and a multi-class area under the curve (AUC) (using TPR and TFR) ('pROC,' R package). AUC was the ultimate factor in deciding the highest performing feature groups if sensitivity / specificity was similar as it validates performance metrics with the lowest occurrence of misclassification (Hand & Till 2001). Overall, we considered high precision for a single feature group to be TPR > 70% and AUC>70% following Powers (2011).

4. Results

First, the suitable window length duration was determined. Then, the recordings labeled by SEM were provided and the corresponding alluvial diagram was depicted. Finally, the performance comparison among different feature groups using two DA algorithms: LDA and QDA, was illustrated. In the following subsections, we present each experimental result in detail.



Figure 3: Observation Window Length Inspection Results

The absolute value of Pearson correlation (r) values of the discrete spectral feature (23 ms frame) compared with mean values of window lengths (1s, 3s, 10s, 60s) of individual spectral timbral features.

4.1 Observation window length inspection

The plot of Pearson correlation coefficients (r) of the mean feature values for each window length duration (1s, 3s, 10s, and 60s) is compared with corresponding single frame counterparts (Figure

3). The r values were similar for all window lengths for the spectral timbral features centroid, skew, and variance. However, the r values for slope and spread were not similar across window lengths. This plot indicated that slope and spread were measurements that are influenced by quick timbral changes in the sound event while the other features were more stable over longer durations. Due to this variation, as both slope and spread had highest r value at the 3s window, we selected a 3s window as the most suitable for all tested features.

4.2 Sensory evaluation method

Our observations, those dataset recordings labeled by SEM, were organized by class composition of biophony (n=59), geophony (n=74), and anthrophony (n=47). Figure 4 shows the resulting soundscape composition classes from SEM. More specifically, the alluvial diagram shows the density of class membership and its distribution across daily time periods (1-dawn: 6-8:30 am), 2-midday: 11am-1:30pm; 3-dusk: 6-8:30pm, and 4-late evening: 11pm-1:30am), and sites (Arizona, Costa Rica, and Maine). Each class was color coded with ribbons extending from the time period node to the site node. Here, we interpret the results of the alluvial diagram with respect to SEM class. Geophony had the greatest presence in the midday as represented by the width of the blue ribbon. From here, we can see that the geophony presence in midday is comprised of sounds from each site, with the widest band present in Arizona. Biophony had the greatest presence in the dawn, dusk, and late evening time periods as represented by the width of the greatest band present in Costa Rica. Anthrophony had the greatest presence in the dawn, midday, and dusk time periods as represented by the width of the red ribbon with the widest band present in Maine. Overall, the soundscape component classes, biophony, geophony, and anthrophony confirmed that SEM classes were distributed across each time period and the three sites.





The alluvial diagram displays the SEM class by density (ribbon width) and distribution across time period and site. The ribbon color is associated with the specific soundscape composition glass (e.g., geophony is blue, biophony is green, and anthrophony is red). This alluvial diagram displays non-correlation between each node (class, time, site) representing an unbiased sample.

4.3 Discriminant analysis

To begin our comparison of DA results, we used a confusion matrix to calculate accuracy, sensitivity, and specificity using the observations (SEM-derived classes) and the DA-classified classes (Table 2 and 3). A performance measure of 0-100% is calculated using multiple algorithms (resulting in accuracy, sensitivity, specificity, or AUC) that use the number of correctly identified DA-classified classes as compared to the labeled observation, with 50% or less performance relative to low performance or a null hypothesis, and 70% or higher performance relative to high performance (Powers, 2011). We assessed different combinations of feature groups and DA algorithms that had the lowest and highest performances in terms of accuracy. As this analysis was exploratory in nature, different feature groups yielded a wide range of classification performance, suggesting that certain feature groups were better at classifying sonic characteristics for a particular soundscape class – and thus, have discriminatory value. For instance, when considering the metric accuracy, the lowest performing feature group for anthrophony had 0% (LDA) while the highest performing feature group was 86.7% (QDA). The performance range for geophony was similar having a range of 0% (QDA) to 75.3% (LDA). After comparing

all the results, though, we found there was not a single feature group that could classify the three classes with accuracy metrics all higher than 70%.

In this context, considering that those feature groups with the best performance on predicting a certain single class might be further utilized in a synergistic way, we selected a separate feature group to classify each soundscape class. Specifically, according to Tables 3 and 4, we determined the best performing feature groups for each class considering the complementary set of sensitivity, R^2 value, and AUC as listed below (complete set of metrics on Tables 3 and 4).

 Biophony [FG12-plus-QDA]: sensitivity = 86.7%, R²=0.21, AUC=75.5%
Geophony [FG4-plus-LDA]:

sensitivity = 74%, R²=0.07, AUC=71.4%

3) Anthrophony [FG11-plus-QDA]: sensitivity = 87.2%, R²=0.21, AUC=71.8%

Table 2: Results of Linear Discriminant Analysis

LDA: Featur e Group Comb inatio n	Permut ational Anova Result s	AU C	Biop hony : accu racy	Geop hony : accu racy	Anthro phony : accura cy	Biop hony : sens itivit y	Biop hony : spec ificit y	Geop hony : sensi tivity	Geop hony : speci ficity	Anthro phony : sensiti vity	Anthro phony : specifi city
FG1	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	79. 87 %	55%	57.5 %	83%	55%	86.7 %	56.2 %	73.8 %	83%	83%
FG2	F(2,179)=6.45, R ² =0.0	70. 1%	13.3 %	64.4 %	78.7%	13.3 %	89.2 %	64.4 %	54.2 %	78.7%	80.5%

	1								1		· · · · · · · · · · · · · · · · · · ·
	7, p<0.00 1										
FG3	F(2,179)=6.45, R ² =0.0 7, p<0.00 1	70. 03 %	8.3%	67.1 %	78.7%	8.3%	90.8 %	67.1 %	50.5 %	78.7%	81.2%
FG4	F(2,179)=6.45, R ² =0.0 7, p<0.00 1	71. 8%	0%	74%	78.7%	0%	97.5 %	74%	43%	78.7%	81.2%
FG5	F(2,179)=6.45, R ² =0.0 7, p<0.00 1	72. 2%	0%	72.6 %	78.7%	0%	99.2 %	71.2 %	41.1 %	78.7%	80.0%
FG6	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	80. 02 %	56.7 %	54.8 %	80.9%	56.7 %	86.7 %	55%	73%	80.9%	82.7%
FG7	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	80. 07 %	53.3 %	60.3 %	83%	53.3 %	88.3 %	58.9 %	73%	83%	82.7%
FG8	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	79. 69 %	56.7 %	53.4 %	80.9%	56.7 %	85.8 %	52.1 %	72.9 %	80.9%	82%
FG9	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	78. 75 %	58.3 %	38.4 %	83%	58.3 %	81.7 %	38.4 %	74.8 %	83%	78.2%
FG10	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	79. 21 %	56.7 %	38.4 %	83%	56.7 %	80.8 %	37%	72.9 %	83%	79%
FG11	F(2,179)=24.03 , R ² =0.2	70. 07 %	0%	71.2 %	70.2%	0%	99.2 %	72.6 %	36.4 %	70.2%	81.2%

	1, p<0.00 1										
FG12	F(2,179)=24.03 , R ² =0.2 1, p<0.00 1	69. 23 %	0%	72.6 %	68.1%	0%	99.2 %	72.6 %	35.5 %	68.1%	81.2%
FG13	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	79. 25 %	58.3 %	42.5 %	80.9%	58.3 %	80.8 %	42.5 %	72.9 %	80.9%	82%
FG14	F(2,179)=24.03 , R ² =0.2 1, p<0.00 1	68. 68 %	0%	71.2 %	66%	0%	97.5 %	69.8 %	33.6 %	66%	82%
FG15	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	78. 99 %	56.7 %	41.1 %	80.9%	56.7 %	80.0 %	41.1 %	72%	80.9%	82%
FG16	F(2,179)=9.27, R ² =0.9 4, p<0.00 1	79. 55 %	55%	57.5 %	80.9%	55%	88.3 %	57.5 %	72.9 %	80.9%	82%
FG17	*F(2,17 9)=1.95 , R ² =0.0 2, p=0.15	70. 03 %	8.3%	68.5 %	78.7%	8.3%	90.8 %	67.1 %	50.4 %	78.7%	81.2%
FG18	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	79. 61 %	53.3 %	60.3 %	80.9%	53.3 %	89.2 %	60.3 %	72%	80.9%	82.7%
FG19	*F(2,17 9)=1.95 , R ² =0.0 2, p=0.13	70. 03 %	8.3%	68.5 %	78.7%	8.3%	91.7 %	68.5 %	50.5 %	78.7%	81.2%

FG20	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	66. 78 %	61.7 %	65.8 %	0%	61.7 %	79.2 %	65.7 %	39.3 %	0%	96.2%
FG21	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	67. 33 %	63.3 %	64.4 %	0%	63.3 %	79.2 %	65.8 %	40.2 %	0%	96.2%
FG22	*F(2,17 9)=1.95 , R ² =0.0 2, p=0.12	50. 0%	0%	98.7 %	0%	0%	99.2 %	98.6 %	0%	0%	100%
FG23	F(2,179)=9.27, R ² =0.9 4, p<0.00 1	79. 26 %	58.3 %	42.5 %	83%	58.3 %	80.8 %	42.5 %	74.8 %	83%	81.2%
FG24	*F(2,17 9)=1.17 , R ² =0.0 1, p=0.32	69. 36 %	0%	74%	68.1%	0%	99.2 %	74%	35.5 %	68.1%	82%
FG25	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	79. 2%	56.7 %	42.5 %	80.9%	56.7 %	81.7 %	42.5 %	72%	80.9%	81.2%
FG26	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	59. 92 %	46.7 %	75.3 %	0%	46.7 %	81.7 %	74%	33.6 %	0%	96.2%

Results for linear discriminant analysis show feature groups with high geophony classification accuracy. Performance measures include a permutational ANOVA, area under the curve, and sensitivity for the class. Feature groups with an "*" indicate a p-value greater than the Bonferroni-corrected significance of p<0.002 and were not considered for the "sifting" workflow (gray) (Figure 5). Feature group 4 [FG4] had the overall highest performance for classification of geophony (black).

Table 3: Results for	Quadratic	Discriminant	Analysis
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QDA: Featur	Permut ational	AU C	Biop hony	Geop hony	Anthro phony	Biop hony	Biop hony	Geop hony	Geop hony	Anthro phony	Anthro phony
e Group Combi nation s	Anova Result s		: accu racy	: accu racy	accura cy	: sens itivit y	: spec ificit y	: sensi tivity	: speci ficity	sensiti vity	specifi city
FG1	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	75. 17 %	81.2 0%	8.30 %	87.20 %	81.7 0%	58.0 0%	8.30 %	97.20 %	87.20 %	77.30 %
FG2	F(2,179)=6.45, R ² =0.0 7, p<0.00 1	74. 38 %	80.0 0%	8.30 %	87.20 %	80.0 0%	57.1 0%	8.30 %	97.20 %	87.20 %	77.30 %
FG3	F(2,179)=6.45, R ² =0.0 7, p<0.00 1	75. 91 %	83.3 0%	9.70 %	87.20 %	83.0 0%	54.6 0%	9.70 %	97.20 %	87.20 %	81.80 %
FG4	F(2,179)=6.45, R ² =0.0 7, p<0.00 1	73. 93 %	80.0 0%	11.00 %	83.00 %	80.0 0%	56.7 0%	11.00 %	96.30 %	83.00 %	78.20 %
FG5	F(2,179)=6.45, R ² =0.0 7, p<0.00 1	74. 28 %	78.3 0%	11.00 %	85.10 %	78.3 0%	60.8 0%	11.00 %	95.30 %	85.10 %	75.20 %
FG6	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	74. 81 %	78.3 0%	12.30 %	87.20 %	78.3 0%	58.3 0%	12.30 %	96.30 %	87.20 %	78.20 %
FG7	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	76. 91 %	86.7 0%	0.00 %	78.70 %	85.0 0%	58.0 0%	9.70 %	98.10 %	89.40 %	79.50 %
FG8	F(2,179)=9.27, R ² =0.0 9,	74. 85 %	80.0 0%	11.00 %	85.10 %	80.0 0%	59.2 0%	11.00 %	95.30 %	85.10 %	77.40 %

	p<0.00 1										
FG9	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	74. 75 %	81.7 0%	0.00 %	91.50 %	81.7 0%	60.5 0%	0.00 %	99.10 %	91.50 %	70.50 %
FG10	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	75. 50 %	85.0 0%	0.00 %	91.50 %	85.0 0%	58.8 0%	0.00 %	100.0 0%	91.50 %	72.70 %
FG11	F(2,179)=24.03 , R ² =0.2 1, p<0.00 1	72. 21 %	78.3 0%	0.00 %	87.20 %	78.3 0%	58.8 0%	0.00 %	99.10 %	87.20 %	68.90 %
FG12	F(2,179)=24.03 , R ² =0.2 1, p<0.00	71. 80 %	86.7 0%	0.00 %	78.70 %	86.7 0%	51.3 0%	0.00 %	100.0 0%	78.70 %	75.80 %
FG13	1 F(2,179)=9.27, R ² =0.0 9, p<0.00 1	74. 17 %	81.7 0%	4.10 %	87.20 %	81.7 0%	60.8 0%	4.10 %	98.10 %	87.20 %	71.40 %
FG14	F(2,179)=24.03 , R ² =0.2 1, p<0.00 1	73. 59 %	80.0 0%	4.10 %	87.20 %	80.0 0%	60.0 0%	4.10 %	98.10 %	87.20 %	71.40 %
FG15	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	79. 07 %	56.7 0%	58.90 %	83.00 %	56.7 0%	92.5 0%	58.90 %	77.60 %	83.00 %	76.70 %
FG16	F(2,179)=9.27, R ² =0.9 4, p<0.00 1	74. 70 %	80.0 0%	9.60 %	85.10 %	80.0 0%	59.2 0%	9.60 %	95.30 %	85.10 %	76.70 %

FG17	*F(2,17 9)=1.95 , R ² =0.0 2, p=0.15	74. 12 %	78.3 0%	9.60 %	85.10 %	78.3 0%	60.0 0%	9.60 %	95.30 %	85.10 %	75.20 %
FG18	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	74. 65 %	78.3 0%	11.00 %	87.20 %	78.3 0%	58.3 0%	11.00 %	96.30 %	87.20 %	77.40 %
FG19	*F(2,17 9)=1.95 , R ² =0.0 2, p=0.13	73. 77 %	80.0 0%	9.60 %	83.00 %	80.0 0%	55.8 0%	9.60 %	96.30 %	83.00 %	78.20 %
FG20	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	71. 51 %	75.0 0%	9.60 %	78.70 %	75.0 0%	59.2 0%	9.60 %	94.40 %	78.70 %	72.90 %
FG21	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	75. 14 %	76.7 0%	9.60 %	89.40 %	76.7 0%	67.5 0%	9.60 %	95.30 %	89.40 %	69.20 %
FG22	*F(2,17 9)=1.95 , R ² =0.0 2, p=0.12	63. 66 %	48.3 0%	9.60 %	85.10 %	48.3 0%	92.5 0%	9.60 %	95.30 %	85.10 %	32.30 %
FG23	F(2,179)=9.27, R ² =0.9 4, p<0.00 1	74. 01 %	81.7 0%	2.70 %	87.20 %	81.7 0%	60.8 0%	2.70 %	98.10 %	87.20 %	70.70 %
FG24	*F(2,17 9)=1.17 , R ² =0.0 1, p=0.32	73. 44 %	80.0 0%	2.70 %	87.20 %	80.0 0%	60.0 0%	2.70 %	98.10 %	87.10 %	70.70 %
FG25	F(2,179)=9.27, R ² =0.0 9, p<0.00 1	78. 87 %	55.0 0%	58.90 %	83.00 %	55.0 0%	93. 3 0%	58.90 %	76.60 %	83.00 %	75.90 %

FG26	F(2,179	65.	58.3	1.40	83.00	58.3	83.3	1.37	97.20	83.00	38.30
)=9.27,	07	0%	%	%	0%	3%	%	%	%	%
	R ² =0.0	%									
	9,										
	p<0.00										
	1										

Results for quadratic discriminant analysis show feature groups with high biophony and anthrophony classification accuracy. Performance measures include a permutational ANOVA, area under the curve, and sensitivity for the class. Feature groups with an "*" indicate a p-value greater than the Bonferroni-corrected significance of p<0.002 and were not considered for the "sifting" workflow (gray) (Figure 5). Feature group 11 had the overall highest performance for classification of anthrophony while feature group 12 had the overall highest performance for classification of biophony (black).

QDA: Feature Group Combinations	Permutational Anova Results	AUC	Biophony: accuracy	Geophony: accuracy	Anthrophony: accuracy	Biophony: sensitivity	Biophony: specificity	Geophony: sensitivity	Geophony: specificity	Anthrophony: sensitivity	Anthrophony: specificity
FG1	F(2,179)=9.27, R ² =0.09, p<0.001	75.17%	81.20%	8.30%	87.20%	81.70%	58.00%	8.30%	97.20%	87.20%	77.30%
FG2	F(2,179)=6.45, R²=0.07, p<0.001	74.38%	80.00%	8.30%	87.20%	80.00%	57.10%	8.30%	97.20%	87.20%	77.30%
FG3	F(2,179)=6.45, R²=0.07, p<0.001	75.91%	83.30%	9.70%	87.20%	83.00%	54.60%	9.70%	97.20%	87.20%	81.80%
FG4	F(2,179)=6.45, R²=0.07, p<0.001	73.93%	80.00%	11.00%	83.00%	80.00%	56.70%	11.00%	96.30%	83.00%	78.20%
FG5	F(2,179)=6.45, R²=0.07, p<0.001	74.28%	78.30%	11.00%	85.10%	78.30%	60.80%	11.00%	95.30%	85.10%	75.20%
FG6	F(2,179)=9.27, R²=0.09, p<0.001	74.81%	78.30%	12.30%	87.20%	78.30%	58.30%	12.30%	96.30%	87.20%	78.20%
FG7	F(2,179)=9.27, R²=0.09, p<0.001	76.91%	86.70%	0.00%	78.70%	85.00%	58.00%	6.70%	98.10%	89.40%	79.50%
FG8	F(2,179)=9.27, R²=0.09, p<0.001	74.85%	80.00%	11.00%	85.10%	80.00%	59.20%	11.00%	95.30%	85.10%	77.40%
FG9	F(2,179)=9.27, R²=0.09, p<0.001	74.75%	81.70%	0.00%	91.50%	81.70%	60.50%	%00.0	99.10%	91.50%	70.50%
FG10	F(2,179)=9.27, R²=0.09, p<0.001	75.50%	85.00%	0.00%	91.50%	85.00%	58.80%	%00.0	100.00%	91.50%	72.70%
FG11	F(2,179)=24.03, R ² =0.21, p<0.001	72.21%	78.30%	0.00%	87 <u>.</u> 20%	78.30%	58.80%	0:00%	99.10%	87.20%	68.90%
FG12	F(2,179)=24.03, R²=0.21, p<0.001	71-80%	86.70%	%00'0	78.70%	86.70%	51.30%	%00'0	100.00%	78.70%	75.80%
FG13	F(2,179)=9.27, R ² =0.09, p<0.001	74.17%	81.70%	4 10%	87.20%	81.70%	60.80%	4.10%	98.10%	87.20%	71.40%
FG14	F(2,179)=24 03, R²=0.21, p<0.001	73.59%	80.00%	4.10%	87.20%	80.00%	60.00%	4.10%	98.10%	87.20%	71.40%
FG15	F(2,179)=9.27, R²=0.09, p<0.001	79.07%	56.70%	58.90%	83.00%	56.70%	92.50%	58.90%	77.60%	83.00%	76.70%
FG16	F(2,179)=9.27, R²=0.94, p<0.001	74.70%	80.00%	%09.6	85.10%	80.00%	59.20%	%09.6	95.30%	85.10%	76.70%
FG17	*F(2,179)=1.95, R ² =0.02, p=0.15	74.12%	78.30%	9.60%	85.10%	78.30%	60.00%	60%	95.30%	85.10%	75.20%
FG18	F(2,179)=9.27, R²=0.09, p<0.001	74.65%	78.30%	11.00%	87.20%	78.30%	58.30%	11.00%	96.30%	87.20%	77.40%
FG19	*F(2,179)=1.95, R ² =0.02, p=0.13	73.77%	80.00%	9.60%	83.00%	80.00%	55.80%	%09.6	96.30%	83.00%	78.20%
FG20	F(2,179)=9.27, R ² =0.09, p<0.001	71.51%	75.00%	9.60%	78.70%	75.00%	59.20%	%09.6	94.40%	78.70%	72.90%
FG21	F(2,179)=9.27, R²=0.09, p<0.001	75.14%	76.70%	9.60%	89.40%	76.70%	67.50%	%09.6	95.30%	89.40%	69.20%
FG22	*F(2,179)=1.95, R ² =0.02, p=0.12	63.66%	48.30%	9.60%	85.10%	48.30%	92.50%	9.60%	95.30%	85.10%	32.30%
FG23	F(2,179)=9.27, R²=0.94, p<0.001	74.01%	81.70%	2.70%	87.20%	81.70%	60.80%	2.70%	98.10%	87.20%	70.70%
FG24	*F(2,179)=1.17, R ² =0.01, p=0.32	73.44%	80.00%	2.70%	87.20%	80.00%	60.00%	2.70%	98.10%	87.10%	70.70%
FG25	F(2,179)=9.27, R²=0.09, p<0.001	78.87%	55.00%	58.90%	83.00%	55.00%	93.30%	58.90%	76.60%	83.00%	75.90%
FG26	F(2,179)=9.27, R²=0.09, p<0.001	65.07%	58.30%	1.40%	83.00%	58.30%	83.33%	1.37%	97.20%	83.00%	38.30%

5. Discussion

The classification of soundscape composition classes using field recordings is challenging due to the inherent diversity of sounds within a class. As soundscape ecologists often consider biological events in relation to other sound events, the biophony class needs to include acoustically different sounds (e.g., a howler monkey vocalization and a cricket stridulation), while separating them from geophony or anthrophony. Furthermore, the identification of characteristics that group these sounds within the boundaries of each soundscape class has not been widely studied or implemented.

We investigated spectral timbral feature analysis to address this fundamental problem in soundscape ecology due to its high performance capabilities in classifying musical instruments. We found in preliminary work that, although in musical instruments centroid and slope are highly correlated, in field recordings this was rarely the case. This could be due to the nature of an instrument's harmonic qualities whereby a fundamental frequency is present unlike most sounds found in a soundscape bank (Agostini et al., 2003; Beauchamp, 2007; Marozeau, de Cheveigné, McAdams, & Winsberg, 2003). In fact, the slope and spread were more sensitive to immediate changes in our soundscape bank and responsive to nuances in sound such as wind pitch rising slightly, while the other features were relatively stable over a span of time. Evaluating feature groups in timbral space was not dependent on template matching or species identification, but evaluated a recording using the full spectrum in three-second windows. This approach is useful as template matching and species-identification of sounds within a large collection of soundscapes is challenging due to unknown species and competing signals (Towsey et al., 2014; Zhao et al., 2017).

The set of tested feature groups had a range of classification accuracy performance for each class. We had suspected that one feature group might be able to classify the three classes. However, there was not one feature group that had strong performance for all soundscape composition classes. The most difficult soundscape class to classify was geophony. Upon listening to the entire group of geophonic sounds, several consisted of thunder and heavy rain, a natural ecological process that is often present in unfiltered soundscape banks. One possible improvement for geophonic classification is a pre-filtering method that removes extreme weather events and inclusion of a new class for inconclusive sounds.

Another interesting result from this experiment is that certain feature groups resulted in a single class with low accuracy. For instance, the classification result for [FG10-plus-QDA] was 0% accuracy for the geophony class. We can infer that this combination does not measure the timbral qualities present in that feature group and could be used to potentially "sift" out sounds that do not have geophony, a typical source of noise that is difficult to determine without manually searching sound files. Additionally, there were several high performing feature groups for an individual soundscape class with accuracy and AUC higher than 70%. Indeed, many feature groups had high performance for biophony and anthrophony, especially using the QDA algorithm. As for [FG14-plus-QDA], this option had a higher R^2 value (R^2 = 0.21) from the permutational ANOVA and resulted in 80% accuracy for biophony, 87.2% accuracy for anthrophony, with 0% for geophony. So, although we did not include this feature group for inclusion in the proposed "sifting" workflow,

this single workflow may be useful for ecologists with questions regarding biological and anthropogenic sounds without influence by weather-related occurrences.



Figure 5: Proposed Sifting Workflow

A "sifting" workflow for soundscape ecology composition classification. FG refers to feature group, LDA is linear discriminant analysis, and QDA is quadratic discriminant analysis.

Many relationships exist amongst the feature groups, but those feature groups with higher F statistics and R² values, as well as sensitivity and multi-class AUC, should be considered for deeper analysis. In this study, utilizing this criterion, we compiled a list of potential "sifting" feature groups, geophony [FG-4 plus-LDA], biophony [FG12-plus-QDA], and anthrophony [FG11-plus-QDA], that could benefit soundscape analyses (Figure 5). In this proposed method, we demonstrate a series of steps that can output a single soundscape composition class. In Figure 5, we illustrate a proposed "sifting" process to output all biophonic sounds could benefit research studies that relate to an underlying theme in soundscape analysis, such as the acoustic niche hypothesis, whereby species are thought to have evolved to produce sound in their own acoustic bandwidth to avoid masking (Brumm & Slabbekorn, 2005). This "sifting" process could be expanded to include ecological "genres" that become more specialized resulting in a species community profile. This paper explored only one type of MIR feature, but other features may offer novel solutions such as algorithms that utilize tempos of a location (tempograms), concentration of frequencies (chromagrams), and other temporal and spectral timbral features (timbregrams) (Grosche, Müller, & Kurth, 2010). As we have investigated one type of feature analyses, a low-level audio descriptor in MIR, ecologists might consider using analyses of other audio descriptor scales. Certainly, the gamut of computational musicological analyses is a useful exploratory tool for the soundscape ecologist.

Overall, this work demonstrates that we can use different spectral timbral feature groups to classify sounds into soundscape composition classes, and offers the potential for a "sifting" process that may retrieve recordings that contain or do not contain a soundscape class. It is worth remarking that this hierarchical scheme has been recently suggested by soundscape researchers as a needed tool to reduce analysis time (Towsey et al., 2014). A similar multi-step "sifting" approach has been used in recent visualization problems (Lahoulou, Larabi, Beghdadi, Viennet, & Bouridane, 2016) and as a tool on the progress of classifying musical genres (Li & Ogihara, 2006).

Our method worked in a single-label manner, which allowed discrimination of a single, dominant soundscape composition class. Additionally, since determining the SEM class was difficult due to interpreting the difference between distant noise and wind, visual cues were involved in the inspection of the sound. Further improvements to this experiment include the use of multi-label concepts (Omrani, Abdallah, Charif, & Longford, 2015; Omrani, Tayyebi, & Pijanowski, 2017; Zhang et al., 2016) and a larger sample size.

6. Appendix A

Spectral Timbral Feature Definitions (Bullock & Conservatoire, 2007; Cannam et al., 2010; Krimphoff et al., 1994; Peeters et al., 2011)

Spectral Centroid

Measures spectral center of gravity of the magnitude spectrum at time window t, defined as

$$\mu(t) = \sum_{n=1}^{N} f_n p(t, n)$$

Where *n* is the spectral index resultant from the Fourier transform and f_n is the *n*th frequency. And

$$p(t,n) = \frac{v(t,n)}{\sum_{n=1}^{N} v(t,n)}$$

Where v(t,n) is the amplitude spectrum at frequency index *n* and time window *t*.

Spectral Spread

Measures the spread of the spectrum around it's mean value at time window t, defined as

$$\sigma^{2}(t) = \sum_{n=1}^{N} (f_{n} - \mu(t))^{2} p(t, n)$$

Spectral Skewness

Measures the asymmetry of the spectrum by using the frequency distribution around its main value at time window *t*. A value of $??_3$ indicates a symmetric distribution, $??_3 < 0$ indicates more spectral

energy at frequencies lower than the mean value, and $??_3 > 0$ indicates more energy at higher frequencies, defined as

$$\gamma_3(t) = \frac{m_3(t)}{\sigma^3(t)}$$

where

$$m_3(t) = \sum_{n=1}^{N} (f_n - \mu(t))^3 p(t, n)$$

Spectral Slope

Measures the amount of decrease of spectral amplitude with respect to frequency at time window *t*. It is calculated using the slope coefficient of a simple linear regression, defined as

$$\frac{1}{\sum_{n=1}^{N} v(t,n)} * \frac{N \sum_{n=1}^{N} f_n v(t,n) - (\sum_{n=1}^{N} f_n) (\sum_{n=1}^{N} v(t,n))}{N \sum_{n=1}^{N} f_n^2 - (\sum_{n=1}^{N} f_n)^2}$$

Spectral Variance

Measures spectral spread weighted by the inverse total amplitude.

$$v(t) = \frac{1}{\sum_{n=1}^{N} p(t,n)} \sum_{n=1}^{N} [(f_n - \mu(t))^2 p(t,n)]$$

7. Appendix B

This is the master list for soundscape recordings used in this experiment where B represents biophony, G represents geophony, A represents anthrophony, C represents observation code, SEM class represents the class assignment using the sensory evaluation method (SEM), Time represents the time period of the random sample draw, and Site is the location where the recording occurred.

No.	File Name	В	G	А	С	SEM class	Time	Site
1	Arizona_H1_U_T1_H1-NO-R3_20140313_060000	1	1	0	6	geophony	1-dawn	Arizona
2	Arizona_H1_U_T1_H1-NO-R3_20140316_080000	1	1	0	6	geophony	1-dawn	Arizona
3	Arizona_H1_U_T1_H1-NO-R3_20140320_063000	1	1	0	6	geophony	1-dawn	Arizona
4	Arizona_H1_U_T1_H1-NO-R3_20140421_080000	1	1	0	6	geophony	1-dawn	Arizona
5	Arizona_H1_U_T1_H1-NO-R3_20140422_060000	1	1	0	6	geophony	1-dawn	Arizona
6	Arizona_H1_U_T1_H1-NO-R3_20140427_060000	1	1	0	6	geophony	1-dawn	Arizona
7	Arizona_H1_U_T1_H1-NO-R3_20140430_060000	1	1	0	6	geophony	1-dawn	Arizona
8	Arizona_H1_U_T1_H1-NO-R3_20140430_080000	1	1	0	6	geophony	1-dawn	Arizona
9	Arizona_H1_U_T1_H1-NO-R3_20140502_060000	0	1	0	7	anthrophony	1-dawn	Arizona
10	Arizona_H1_U_T1_H1-NO-R3_20140502_063000	1	1	0	6	geophony	1-dawn	Arizona
11	Arizona_H1_U_T1_H1-NO-R3_20140506_070000	1	1	0	6	geophony	1-dawn	Arizona

12	Arizona_H1_U_T1_H1-NO-R3_20140603_060000
13	Arizona_H1_U_T1_H1-NO-R3_20140603_063000
14	Arizona_H1_U_T1_H1-NO-R3_20140606_080000
15	Arizona_H1_U_T1_H1-NO-R3_20140608_060000
16	Arizona_H1_U_T1_H1-NO-R3_20140610_063000
17	Arizona_H1_U_T1_H1-NO-R3_20140612_063000
18	Arizona_H1_U_T1_H1-NO-R3_20140901_060000
19	Arizona_H1_U_T1_H1-NO-R3_20140905_070000
20	Arizona_H1_U_T1_H1-NO-R3_20140914_080000
21	Arizona_H1_U_T1_H1-NO-R3_20141003_060000
22	Arizona_H1_U_T1_H1-NO-R3_20141003_063000
23	Arizona_H1_U_T2_H1-NO-R3_20140306_120000
24	Arizona_H1_U_T2_H1-NO-R3_20140306_130000
25	Arizona_H1_U_T2_H1-NO-R3_20140310_120000
26	Arizona_H1_U_T2_H1-NO-R3_20140316_120000
27	Arizona_H1_U_T2_H1-NO-R3_20140419_110000
28	Arizona_H1_U_T2_H1-NO-R3_20140420_130000
29	Arizona_H1_U_T2_H1-NO-R3_20140422_130000
30	Arizona_H1_U_T2_H1-NO-R3_20140502_130000
31	Arizona_H1_U_T2_H1-NO-R3_20140504_130000
32	Arizona_H1_U_T2_H1-NO-R3_20140905_110000
33	Arizona_H1_U_T2_H1-NO-R3_20140906_110000
34	Arizona_H1_U_T2_H1-NO-R3_20140914_120000
35	Arizona_H1_U_T2_H1-NO-R3_20140918_110000
36	Arizona_H1_U_T2_H1-NO-R3_20141003_130000
37	Arizona_H1_U_T3_H1-NO-R3_20140320_180000
38	Arizona_H1_U_T3_H1-NO-R3_20140425_180000
39	Arizona_H1_U_T3_H1-NO-R3_20140505_190000
40	Arizona_H1_U_I3_H1-NO-R3_20140601_180000
41	Arizona_H1_U_15_H1-NO-R5_20140005_180000
42	Arizona_H1_U_13_H1-NO-R3_20140908_190000
45	Arizona_H1_U_15_H1-NO-R5_20140908_200000
44	Arizona H1 U T3 H1 NO P3 20140917 180000
45	Arizona H1 U T3 H1 NO P3 20140917 20000
40	Arizona H1 U T/ H1-NO-R3 20140320 010000
48	Arizona H1 II T4 H1-NO-R3 20140419 010000
40	Arizona H1 U T4 H1-NO-R3 20140419 230000
50	Arizona H1 U T4 H1-NO-R3 20140425 000000
51	Arizona H1 U T4 H1-NO-R3 20140502 230000
52	Arizona H1 U T4 H1-NO-R3 20140601 000000
53	Arizona H1 U T4 H1-NO-R3 20140605 010000
54	Arizona_H1_U_T4_H1-NO-R3_20140609_230000
55	Arizona_H1_U_T4_H1-NO-R3_20140612_230000
56	Arizona_H1_U_T4_H1-NO-R3_20140619_000000
57	Arizona_H1_U_T4_H1-NO-R3_20140916_010000
58	Arizona_H1_U_T4_H1-NO-R3_20141002_010000
59	Arizona_H1_U_T4_H1-NO-R3_20141006_000000
60	Arizona_H1_U_T4_H1-NO-R3_20141007_010000

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1	1	0	6	geophony	1-dawn	Arizona
0	0	0	4	biophony	1-dawn	Arizona
1	1	0	6	geophony	1-dawn	Arizona
1	0	1	7	anthrophony	1-dawn	Arizona
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0	0	0	4	biophony	4-late evening	Arizona

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1	0	0	7	anthrophony	1-dawn	Costa Rica
0	0	0	4	biophony	1-dawn	Costa Rica
0	0	0	4	biophony	1-dawn	Costa Rica
0	0	1	7	anthrophony	1-dawn	Costa Rica
0	0	0	4	biophony	1-dawn	Costa Rica
0	0	0	4	biophony	1-dawn	Costa Rica
1	0	0	4	biophony	1-dawn	Costa Rica
0	1	1	7	anthrophony	1-dawn	Costa Rica
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0	0	0	4	biophony	2-midday	Costa Rica
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1	0	0	4	biophony	3-dusk	Costa Rica

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0	0	1	4	biophony	3-dusk	Costa Rica
1	1	0	6	geophony	4-late evening	Costa Rica
1	0	0	4	biophony	4-late evening	Costa Rica
1	0	0	4	biophony	4-late evening	Costa Rica
0	1	0	4	biophony	4-late evening	Costa Rica
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0	0	0	4	biophony	4-late evening	Costa Rica
0	0	0	4	biophony	4-late evening	Costa Rica
0	0	0	4	biophony	4-late evening	Costa Rica
1	0	1	7	anthrophony	1-dawn	Maine
1	0	0	4	biophony	1-dawn	Maine
1	0	0	4	biophony	1-dawn	Maine
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0	1	0	7	anthrophony	1-dawn	Maine
0	0	1	7	anthrophony	1-dawn	Maine
1	1	0	6	geophony	1-dawn	Maine
1	0	1	7	anthrophony	1-dawn	Maine
0	1	1	7	anthrophony	2-midday	Maine
0	1	1	7	anthrophony	2-midday	Maine
1	0	1	7	anthrophony	2-midday	Maine
1	0	1	7	anthrophony	2-midday	Maine
1	0	1	7	anthrophony	2-midday	Maine
0	0	1	7	anthrophony	2-midday	Maine
0	0	0	7	anthrophony	2-midday	Maine
1	0	0	7	anthrophony	2-midday	Maine
0	0	1	7	anthrophony	2-midday	Maine
1	0	1	7	anthrophony	2-midday	Maine
0	1	1	7	anthrophony	2-midday	Maine
0	0	1	7	anthrophony	2-midday	Maine
0	0	1	7	anthrophony	2-midday	Maine
1	1	1	6	geophony	2-midday	Maine
1	1	1	7	anthrophony	3-dusk	Maine
0	0	1	7	anthrophony	3-dusk	Maine
1	0	0	4	biophony	3-dusk	Maine
1	1	0	7	anthrophony	3-dusk	Maine
0	1	0	7	anthrophony	3-dusk	Maine
0	1	1	7	anthrophony	3-dusk	Maine

159	Wells_PilgerPoint_U_T3_015100_20140810_183000	1	1	0	6	geophony	3-dusk	Maine
160	Wells_PilgerPoint_U_T3_015100_20140813_190000	0	1	0	6	geophony	3-dusk	Maine
161	Wells_PilgerPoint_U_T3_015100_20140815_193000	1	1	0	6	geophony	3-dusk	Maine
162	Wells_PilgerPoint_U_T3_015100_20140819_183000	0	1	0	6	geophony	3-dusk	Maine
163	Wells_PilgerPoint_U_T3_015100_20140824_193000	0	1	1	7	anthrophony	3-dusk	Maine
164	Wells_PilgerPoint_U_T3_015100_20140826_203000	0	0	1	7	anthrophony	3-dusk	Maine
165	Wells_PilgerPoint_U_T3_015100_20140829_193000	0	1	1	7	anthrophony	3-dusk	Maine
166	Wells_PilgerPoint_U_T3_015100_20140830_193000	0	1	1	7	anthrophony	3-dusk	Maine
167	Wells_PilgerPoint_U_T3_015100_20140906_203000	1	0	0	4	biophony	3-dusk	Maine
168	Wells_PilgerPoint_U_T3_015100_20140916_190000	0	1	1	7	anthrophony	3-dusk	Maine
169	Wells_PilgerPoint_U_T3_015100_20141007_183000	0	1	0	7	anthrophony	3-dusk	Maine
170	Wells_PilgerPoint_U_T3_015100_20141013_203000	1	1	1	7	anthrophony	3-dusk	Maine
171	Wells_PilgerPoint_U_T4_015100_20140606_233000	1	1	0	6	geophony	4-late evening	Maine
172	Wells_PilgerPoint_U_T4_015100_20140626_003000	1	1	0	6	geophony	4-late evening	Maine
173	Wells_PilgerPoint_U_T4_015100_20140721_230000	0	1	0	6	geophony	4-late evening	Maine
174	Wells_PilgerPoint_U_T4_015100_20140802_000000	0	1	1	7	anthrophony	4-late evening	Maine
175	Wells_PilgerPoint_U_T4_015100_20140806_013000	0	1	0	6	geophony	4-late evening	Maine
176	Wells_PilgerPoint_U_T4_015100_20140822_010000	1	0	1	4	biophony	4-late evening	Maine
177	Wells_PilgerPoint_U_T4_015100_20140914_003000	0	1	0	6	geophony	4-late evening	Maine
178	Wells_PilgerPoint_U_T4_015100_20140921_233000	1	0	0	4	biophony	4-late evening	Maine
179	Wells_PilgerPoint_U_T4_015100_20140925_233000	1	0	1	7	anthrophony	4-late evening	Maine
180	Wells_PilgerPoint_U_T4_015100_20140928_003000	0	0	1	7	anthrophony	4-late evening	Maine

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Contributions of MIR to Soundscape Ecology. Part 2: Spectral timbral analysis for discrimination of soundscape components

Highlights

- Spectral timbral features used in combination together can differentiate between major soundscape classes
- Classification method distinguishes between classes without template matching or species identification
- Sifting method from resulting discriminant analysis feature groups provides new direction for big data sorting