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Asymptotic analysis of selection-mutation models in the presence of multiple fitness peaks

Tommaso Lorenzi* Camille Pouchol†‡

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Abstract

We study the long-time behaviour of phenotype-structured models describing the evolutionary dynamics of asexual species whose phenotypic fitness landscape is characterised by multiple peaks. First we consider the case where phenotypic variations do not occur, and then we include the effect of heritable phenotypic changes. In the former case the model is formulated in terms of an integrodifferential equation for the phenotype distribution of the individuals of the species, whereas in the latter case the evolution of the phenotype distribution is governed by a nonlocal parabolic equation whereby a linear diffusion operator captures the presence of phenotypic variations. We prove that the long-time limit of the solution to the integrodifferential equation is unique and given by a measure consisting of a weighted sum of Dirac masses centred at the peaks of the phenotypic fitness landscape. We also derive an explicit formula to compute the weights in front of the Dirac masses. Moreover, we demonstrate that the long-time solution of the nonlocal parabolic equation exhibits a qualitatively similar behaviour in the asymptotic regime where the diffusion coefficient modelling the rate of phenotypic variations tends to zero. However, we show that the limit measure of the nonlocal parabolic equation may consist of less Dirac masses, and we provide a sufficient criterion to identify the positions of their centres. Taken together, our results support a more in-depth theoretical understanding of the conditions leading to the emergence of stable phenotypic polymorphism in asexual species.

1 Introduction

Phenotype-structured models formulated in terms of integrodifferential equations (IDEs) or nonlocal partial differential equations (PDEs) have been increasingly used as a theoretical framework to study evolutionary dynamics in a variety of asexual populations [1, 2, 5–8, 10, 12, 14, 17, 23, 27–32, 34–36, 39]. In these models, the phenotypic state of each individual is represented by a continuous real variable x , and the phenotypic distribution of the individuals within the population at a given time $t \geq 0$ is described by a function $n(t, x) \geq 0$. In many scenarios of biological and ecological interest one can assume $x \in \Omega$, where Ω is a smooth bounded domain of \mathbb{R}^d , $d \geq 1$.

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We focus here on the case where, in the absence of phenotypic variations, the evolution of the population density function $n(t, x)$ is governed by an IDE of the form

$$\frac{\partial n}{\partial t} = R(x, \rho(t)) n, \quad n \equiv n(t, x), \quad (t, x) \in (0, \infty) \times \bar{\Omega}. \quad (1.1)$$

The functional $R(x, \rho(t))$ represents the net per capita growth rate of individuals in the phenotypic state x under the environmental conditions determined by the population size

$$\rho(t) := \int_{\Omega} n(t, x) dx, \quad (1.2)$$

and models the effect of natural selection. In fact, depending on the sign of $R(x, \rho(t))$ the number density of individuals in the phenotypic state x will either grow or decay at time t . The functional $R(x, \rho(t))$ can thus be seen as the phenotypic fitness landscape of the population [19, 38].

In those ecological and biological scenarios whereby the effect of heritable random phenotypic changes need to be taken into account, a linear diffusion operator can be included in the IDE (1.1). This leads to a nonlocal parabolic PDE of the form

$$\frac{\partial n}{\partial t} = R(x, \rho(t)) n + \beta \Delta n, \quad n \equiv n(t, x), \quad (t, x) \in (0, \infty) \times \Omega, \quad (1.3)$$

where the diffusion coefficient $\beta > 0$ models the phenotypic variation rate. Since phenotypic changes preserve the total number of individuals within the population, zero Neumann is the most natural choice of boundary conditions for the nonlocal PDE (1.3).

The way in which the fitness functional $R(x, \rho(t))$ is defined depends largely on the underlying application problem, and we consider here the following prototypical definition

$$R(x, \rho(t)) := r(x) - \rho(t). \quad (1.4)$$

In the definition (1.4), the function $r(x)$ is the net per capita growth rate of the individuals in the phenotypic state x (*i.e.* the difference between the rate of proliferation through asexual reproduction and the rate of death under natural selection). Hence the maximum points of this function correspond to the fitness peaks (*i.e.* the peaks of the phenotypic fitness landscape of the population). Moreover, the saturating term $-\rho(t)$ models the limitations on population growth imposed by carrying capacity constraints (*e.g.* limited availability of space and resources).

In the framework of the IDE (1.1), or the nonlocal PDE (1.3), a mathematical depiction of phenotypic adaptation can be obtained by studying the long-time behaviour of the population density function $n(t, x)$. In this regard, whilst the case of one single fitness peak has been broadly studied [3, 9, 11, 16, 33, 37], there is a paucity of literature concerning the case where multiple fitness peaks are present, with the exception of the asymptotic results presented in [13, 15, 24, 36, 40]. Based on these few previous results, we expect the solution to the IDE (1.1) complemented with the definition (1.4) to converge to a limit measure given by a sum weighted Dirac masses centred at the maximum points of the function $r(x)$ as $t \rightarrow \infty$, and we envisage the long-time solution of the nonlocal PDE (1.3) to exhibit a qualitatively similar behaviour in the asymptotic regime where $\beta \rightarrow 0$. This represents a mathematical formalisation of the biological notion that the phenotypic variants corresponding to the fitness peaks (*i.e.* the fittest phenotypic variants)

are ultimately selected. However, the following key questions still remain open: is there a unique weighted sum of Dirac masses defining the limit of the solution to the IDE (1.1) when $t \rightarrow \infty$? If so, what are the only admissible values of the weights in front of the different Dirac masses? Are there any differences between the long-time solution to the IDE (1.1) and the asymptotic limit when $\beta \rightarrow 0$ of the long-time solution to the nonlocal PDE (1.3)? If so, how does the presence of the diffusion term change the values of the weights associated with the Dirac masses?

In this paper we address these questions. In summary, using Laplace's method we derive an explicit formula to compute the weights in front of the Dirac masses that constitute the long-time limit of the solution to the IDE (1.1), and show that the weights are uniquely determined by the initial condition $n(0, x)$ and the Hessian $H(r)$ at the maximum points of the function $r(x)$ (*vid.* Theorem 2). Moreover, exploiting the properties of the principal eigenpair of the elliptic differential operator $\beta\Delta + r$, we prove that when $\beta \rightarrow 0$ the long-time limit of the nonlocal PDE (1.3) converges to a limit measure consisting of a weighted sum of Dirac masses with nonnegative weights centred at the maximum points of the function $r(x)$ (*vid.* Theorem 3). Finally, we provide sufficient conditions for the limit measure to be unique and demonstrate that, all things being equal, there can be a significant difference between this limit measure and the limit measure of the IDE (1.1). In particular, we show that, unless *ad hoc* symmetry assumptions are made (*vid.* Proposition 2), the limit measure for the nonlocal PDE (1.3) may consist of less Dirac masses than the limit measure for the IDE (1.1) (*i.e.* a smaller number of weights will be strictly positive), and we provide a sufficient criterion to identify the maximum points of the function $r(x)$ corresponding to the Dirac masses with positive weights (*vid.* Proposition 3). This criterion relies on a suitable multidimensional characterisation of the concavity of the function $r(x)$ at the maximum points which is borrowed from semi-classical analysis. Taken together, our results support a more in-depth theoretical understanding of the conditions leading to the emergence of stable polymorphism in phenotype-structured populations.

The remainder of the paper is organised as follows. In Section 2 we introduce our main assumptions and a few technical preliminaries. In Section 3 we carry out a qualitative and quantitative characterisation of the solution to the IDE (1.1) when $t \rightarrow \infty$, while in Section 4 we study the asymptotic properties of the solution to the nonlocal PDE (1.3) by letting first $t \rightarrow \infty$ and then $\beta \rightarrow 0$. In both sections, we present a sample of numerical solutions that illustrate the analytical results obtained. Section 5 concludes the paper by providing a brief overview of possible research perspectives.

2 Main assumptions, notation and preliminaries

In this paper, we will consider the following Cauchy problem for the IDE (1.1)

$$\begin{cases} \frac{\partial n}{\partial t} = (r(x) - \rho(t))n, & n \equiv n(t, x), \quad (t, x) \in (0, \infty) \times \bar{\Omega}, \\ n(0, x) = n^0(x), & n^0 \in C(\bar{\Omega}), \quad n^0 \geq 0, \quad n^0 \not\equiv 0 \end{cases} \quad (2.5)$$

and the following initial-boundary value problem for the nonlocal parabolic PDE (1.3)

$$\begin{cases} \frac{\partial n_\beta}{\partial t} - \beta \Delta n_\beta = (r(x) - \rho_\beta(t)) n_\beta, & n_\beta \equiv n_\beta(t, x), \quad (t, x) \in (0, \infty) \times \Omega, \\ \nabla n_\beta(t, x) \cdot \nu(x) = 0, & (t, x) \in (0, \infty) \times \partial\Omega, \\ n_\beta(0, x) = n^0(x), & n^0 \in C(\Omega), \quad n^0 \geq 0, \quad n^0 \not\equiv 0, \end{cases} \quad (2.6)$$

where $\nu(x)$ is the outward normal to the boundary $\partial\Omega$ at the point $x \in \partial\Omega$.

Main assumptions on the function $r(x)$. In order to prevent $n(t, \cdot)$ from vanishing as $t \rightarrow \infty$, we will assume

$$r : \bar{\Omega} \rightarrow \mathbb{R}, \quad r \in C(\bar{\Omega}), \quad \max_{x \in \bar{\Omega}} r(x) = r_M > 0 \quad (2.7)$$

and, being interested in the case where $r(x)$ has multiple maximum points, we will also assume

$$\arg \max(r) = \{\bar{x}_1, \dots, \bar{x}_N\} \subset \Omega \quad \text{with} \quad N \geq 2. \quad (2.8)$$

Notice that we assume all points \bar{x}_i to belong to the interior of Ω in order to simplify the presentation. However, part of our results can be extended to the case where the set $\arg \max(r)$ contains some boundary points and, when appropriate, we will comment on how the proofs presented here could be adapted to such a case. Where necessary, we will make the additional assumptions

$$\text{supp}(n^0) \cap \arg \max(r) \neq \emptyset \quad (2.9)$$

and

$$r \in C^2(\bar{\Omega}) \quad \text{and} \quad \det(H_i) < 0 \quad \text{for} \quad i = 1, \dots, N, \quad (2.10)$$

where H_i is the Hessian $H(r)$ evaluated at the point \bar{x}_i . Assumptions (2.10) ensure that each maximum point \bar{x}_i is nondegenerate.

Laplace's method. We recall some useful results on the asymptotic expansion of integrals involving exponentials, usually referred to as Laplace's method. We refer the reader to [42] for a general presentation of such an asymptotic method and for the related proofs. Let r satisfy assumptions (2.10) and assume $f \in C(\Omega)$. For $\bar{x}_i \in \arg \max(r)$ and ε small enough so that \bar{x}_i is the only maximum point of $r(x)$ in the ball $B(\bar{x}_i, \varepsilon)$, Laplace's method ensures that if $\bar{x}_i \in \text{supp}(f)$ then

$$\int_{B(\bar{x}_i, \varepsilon)} f(x) e^{r(x)t} dx \sim (2\pi)^{d/2} \frac{f(\bar{x}_i)}{\sqrt{|\det(H_i)|}} \frac{e^{r_M t}}{t^{d/2}} \quad \text{as } t \rightarrow \infty, \quad (2.11)$$

whereas if $\bar{x}_i \notin \text{supp}(f)$ then

$$\int_{B(\bar{x}_i, \varepsilon)} f(x) e^{r(x)t} dx = o\left(\frac{1}{\sqrt{|\det(H_i)|}} \frac{e^{r_M t}}{t^{d/2}}\right) \quad \text{as } t \rightarrow \infty. \quad (2.12)$$

Moreover, if $f(x)$ and $r(x)$ are, respectively, of class C^1 and C^3 on the ball $B(\bar{x}_i, \varepsilon)$, higher order terms of the asymptotic expansion can be computed. In this case, Laplace's method ensures that

$$\int_{B(\bar{x}_i, \varepsilon)} f(x) e^{r(x)t} dx = \left(A_i + \frac{B_i}{t} + o\left(\frac{1}{t}\right) \right) \frac{e^{r_M t}}{t^{\frac{d}{2}}} \quad \text{as } t \rightarrow \infty, \quad (2.13)$$

where A_i and B_i are real constants, the values of which are not relevant for our purposes.

Preliminaries about the operator $\beta\Delta + r$. We will consider the elliptic differential operator

$$L_\beta = \beta\Delta + r \quad (2.14)$$

acting on functions defined on Ω , and we will denote by $(\lambda_\beta, \psi_\beta)$ the principal eigenpair of L_β with zero Neumann boundary condition. A useful result is established by the following lemma, which follows from the Krein-Rutman theorem [18, 25]

Lemma 1. *The principal eigenvalue λ_β is simple and there is a unique normalised positive eigenfunction ψ_β associated with λ_β . The eigenfunction ψ_β is smooth and the principal eigenvalue λ_β is given by*

$$\lambda_\beta = \inf_{\phi \in H^1(\Omega) \setminus \{0\}} \mathcal{R}(L_\beta, \phi), \quad (2.15)$$

where \mathcal{R} denotes the Rayleigh quotient, i.e.

$$\mathcal{R}(L_\beta, \phi) := \frac{\beta \int_{\Omega} |\nabla \phi(x)|^2 dx - \int_{\Omega} r(x) \phi^2(x) dx}{\int_{\Omega} \phi^2(x) dx}.$$

The infimum is attained only when ϕ is a multiple of ψ_β .

If the set Ω is symmetric with respect to the some hyperplane S , which without loss of generality we will define as

$$S := \{x_1 = 0\}, \quad (2.16)$$

then

$$x = (x_1, x_2, \dots, x_d) \in \Omega \implies (-x_1, x_2, \dots, x_d) \in \Omega. \quad (2.17)$$

Under assumption (2.17) and given a function $f : \bar{\Omega} \rightarrow \mathbb{R}$, we will use the notation

$$\hat{f}(x) = f(-x_1, x_2, \dots, x_d) \quad \text{for } x \in \Omega.$$

With this notation, we will say f to be symmetric with respect to the hyperplane S if $\hat{f}(x) = f(x)$ for all $x \in \Omega$. A useful result is established by the following lemma.

Lemma 2. *If the set Ω satisfies assumption (2.17) and the function $r(x)$ is symmetric with respect to the hyperplane S , i.e. if*

$$\hat{r}(x) = r(x) \quad \text{for all } x \in \Omega, \quad (2.18)$$

then the principal eigenfunction ψ_β is symmetric with respect to the hyperplane S .

Proof. Since $L_\beta \psi_\beta = -\lambda_\beta \psi_\beta$, that is,

$$\beta \Delta \psi_\beta + r \psi_\beta = -\lambda_\beta \psi_\beta \quad \text{in } \Omega,$$

if assumption (2.17) is satisfied then

$$\beta \Delta \hat{\psi}_\beta + \hat{r} \hat{\psi}_\beta = -\lambda_\beta \hat{\psi}_\beta \quad \text{in } \Omega.$$

Under the additional assumption (2.18) the latter elliptic equation implies that

$$\beta \Delta \hat{\psi}_\beta + r \hat{\psi}_\beta = -\lambda_\beta \hat{\psi}_\beta \quad \text{in } \Omega,$$

that is, $L_\beta \hat{\psi}_\beta = -\lambda_\beta \hat{\psi}_\beta$. Hence $\hat{\psi}_\beta$ is a normalised positive eigenfunction associated with the principal eigenvalue λ_β , and the uniqueness of the principal eigenfunction of the operator L_β ensures that $\hat{\psi}_\beta = \psi_\beta$. \square

Function space framework Throughout the paper, we will consider the space of Radon measures $\mathcal{M}^1(\overline{\Omega})$ as the dual of the space of continuous functions $C(\overline{\Omega})$. The integral of a function $\varphi \in C(\overline{\Omega})$ against a measure $\mu \in \mathcal{M}^1(\overline{\Omega})$ will with a slight abuse of notation be denoted in the same way as the integral of the product of the function φ with an L^1 -function, *i.e.*

$$\int_{\Omega} \varphi(x) \mu(x) dx = \int_{\Omega} \varphi d\mu.$$

Sequences of functions f_k in $L^1(\Omega)$ will be seen as elements of the bigger space $\mathcal{M}^1(\overline{\Omega})$. Given a sequence μ_k in $\mathcal{M}^1(\overline{\Omega})$, we will write $\mu_k \xrightarrow[k \rightarrow \infty]{} \mu$ to indicate the weak-* convergence of μ_k to μ , namely that

$$\int_{\Omega} \varphi(x) \mu_k(x) dx \xrightarrow[k \rightarrow \infty]{} \int_{\Omega} \varphi(x) \mu(x) dx \quad \forall \varphi \in C(\overline{\Omega}).$$

Moreover, we will say that the sequence μ_k concentrates on a set $\omega \subset \Omega$ if

$$\int_{\Omega} \varphi(x) \mu_k(x) dx \xrightarrow[k \rightarrow \infty]{} 0 \quad \forall \varphi \in C(\overline{\Omega}) \quad \text{s.t.} \quad \text{supp}(\varphi) \cap \omega = \emptyset,$$

and we will use the result given by the following lemma, which is a well-known fact in measure theory.

Lemma 3. *If a sequence μ_k in $\mathcal{M}^1(\overline{\Omega})$ concentrates on a finite set $\{\bar{x}_1, \dots, \bar{x}_N\}$ and $\mu_k \xrightarrow[k \rightarrow \infty]{} \mu$ then the limit measure μ must be a linear combination of Dirac masses centred at the points $\bar{x}_1, \dots, \bar{x}_N$.*

Finally, we will say that a measure $\mu \in \mathcal{M}^1(\overline{\Omega})$ is symmetric with respect to the hyperplane S if

$$\int_{\Omega} \varphi(x) \mu(x) dx = \int_{\Omega} \hat{\varphi}(x) \mu(x) dx \quad \forall \varphi \in C(\overline{\Omega}) \quad \text{s.t.} \quad \hat{\varphi}(x) = \varphi(x) \quad \forall x \in \Omega$$

and we will use the result given by the following lemma, the proof of which is straightforward.

Lemma 4. *Let μ_k be a sequence of symmetric measures in $\mathcal{M}^1(\overline{\Omega})$. If $\mu_k \xrightarrow[k \rightarrow \infty]{} \mu$ then the limit measure μ is symmetric as well.*

3 Long-time behaviour of the Cauchy problem (2.5)

In this section we study the asymptotic behaviour of the solutions to the Cauchy problem (2.5) when $t \rightarrow \infty$ (Section 3.1), and we provide a sample of numerical solutions that illustrate the analytical results obtained (Section 3.2).

3.1 Asymptotic analysis

Under assumptions (2.7) there exists a unique nonnegative solution $n \in C([0, +\infty); L^1(\Omega))$ of the Cauchy problem (2.5) [15, 36]. Moreover, solving the Cauchy problem (2.5) yields the semi-explicit formula

$$n(t, x) = n^0(x) e^{r(x)t - \int_0^t \rho(s) ds} \quad (3.19)$$

and, if assumption (2.8) is satisfied as well, the solution $n(t, x)$ is known to concentrate on the set $\arg \max(r)$ when $t \rightarrow \infty$, as established by the following theorem.

Theorem 1. *Under assumptions (2.7), (2.8) and (2.9), the solution to the Cauchy problem (2.5) is such that*

$$\rho(t) \xrightarrow[t \rightarrow \infty]{} r_M \quad (3.20)$$

and, upon extraction of subsequences,

$$n(t, x) \xrightarrow[t \rightarrow \infty]{} r_M \sum_{i=1}^N a_i \delta_{\bar{x}_i}(x) \quad \text{with } a_i \geq 0 \quad \text{and} \quad \sum_{i=1}^N a_i = 1. \quad (3.21)$$

In the case where

$$\min_{x \in \Omega} r(x) = r_m > 0, \quad (3.22)$$

Theorem 1 can be proved through a few simple calculations building upon the method presented in [37], as shown by the proof provided in Appendix 5. Alternatively, when assumption (3.22) is satisfied, one can prove Theorem 1 using the method of proof presented in [36], which relies on the observation that the semi-explicit solution (3.19) can be made explicit as

$$n(t, x) = \frac{n^0(x) e^{r(x)t}}{1 + \int_{\Omega} \frac{n^0(y)}{r(y)} (e^{r(y)t} - 1) dy}.$$

On the other hand, in the case where assumption (3.22) is not satisfied, the proof is much more intricate and requires the use of a Lyapunov functional of the form

$$W(t) = \int_{\Omega} [n(t, x) - n^{\infty}(x) - n^{\infty}(x) \ln(n(t, x))] dx,$$

with n^{∞} being any measure concentrated on the set $\arg \max(r)$ and having total mass r_M . We refer the interested reader to [24, 40] for a proof of Theorem 1 in such a more general case.

We prove here that the coefficients a_1, \dots, a_N that define the limit measure (3.21) are uniquely determined by the initial condition and the Hessian of $r(x)$ at the points $\bar{x}_1, \dots, \bar{x}_N$, which entails the convergence of the whole trajectory $n(t, \cdot)$ to a unique

limit point as $t \rightarrow \infty$. These results are summarised by the following theorem, which also provides a characterisation of the rate of convergence of the total mass $\rho(t)$ to the long-term limit r_M .

Theorem 2. *If the assumptions of Theorem 1 and the additional assumption (2.10) are satisfied then*

$$n(t, x) \xrightarrow[t \rightarrow \infty]{} r_M \sum_{i=1}^N a_i \delta_{\bar{x}_i}(x) \quad (3.23)$$

with

$$a_i = A \frac{n^0(\bar{x}_i)}{\sqrt{|\det(H_i)|}} \quad \text{for } i = 1, \dots, N, \quad (3.24)$$

where $A > 0$ is a normalising constant such that $\sum_{i=1}^N a_i = 1$.

Moreover, if the functions $n^0(x)$ and $r(x)$ are, respectively, of class C^1 and C^3 in a neighbourhood of each maximum point $\bar{x}_1, \dots, \bar{x}_N$ then

$$r_M - \rho(t) \sim \frac{d}{2t} \quad \text{as } t \rightarrow \infty. \quad (3.25)$$

Proof. Throughout the proof we will use the following notation

$$J(t) := \frac{e^{r_M t} e^{-\int_0^t \rho(s) ds}}{t^{d/2}}. \quad (3.26)$$

The results established by Theorem 1 ensure that we can extract a subsequence $n(t_k, \cdot)$ such that

$$n(t_k, \cdot) \xrightarrow[k \rightarrow \infty]{} r_M \sum_{i=1}^N a_i \delta_{\bar{x}_i}(x) \quad \text{with} \quad \sum_{i=1}^N a_i = 1.$$

Moreover, considering $\varepsilon > 0$ small enough so that \bar{x}_i is the only maximum point of the function $r(x)$ in the ball $B(\bar{x}_i, \varepsilon)$ for every $i = 1, \dots, N$ and integrating over $B(\bar{x}_i, \varepsilon)$ both sides of the expression (3.19) for $n(t, x)$ with $t = t_k$ we find that

$$\int_{B(\bar{x}_i, \varepsilon)} n(t_k, x) dx = \left(\int_{B(\bar{x}_i, \varepsilon)} n^0(x) e^{r(x)t_k} dx \right) e^{-\int_0^{t_k} \rho(s) ds}. \quad (3.27)$$

The long-time behaviour of the integral on the right-hand side of the above equation can be characterised using Laplace's method. In particular, the asymptotic relation (2.11) ensures that if $\bar{x}_i \in \text{supp}(n^0)$ then

$$\int_{B(\bar{x}_i, \varepsilon)} n(t_k, x) dx \sim (2\pi)^{d/2} \frac{n^0(\bar{x}_i)}{\sqrt{|\det(H_i)|}} J(t_k) \quad \text{as } k \rightarrow \infty, \quad (3.28)$$

where J is defined according to (3.26). On the other hand, the asymptotic relation (2.12) ensures that if $\bar{x}_i \notin \text{supp}(n^0)$ then

$$\int_{B(\bar{x}_i, \varepsilon)} n(t_k, x) dx = o\left(\frac{1}{\sqrt{|\det(H_i)|}} J(t_k)\right) \quad \text{as } k \rightarrow \infty. \quad (3.29)$$

Taken together, the integral identity (3.27) and the asymptotic relations (3.28) and (3.29) allow us to conclude that there exist some real constants $K > 0$ and $A > 0$ such that

$$J(t_k) \xrightarrow[k \rightarrow \infty]{} K \quad (3.30)$$

and

$$a_i = A \frac{n^0(\bar{x}_i)}{\sqrt{|\det(H_i)|}} \quad \text{with} \quad \sum_{i=1}^N a_i = 1.$$

We remark that K cannot be 0 because otherwise $\rho(t)$ would converge to 0, which cannot be since $\rho(t) \rightarrow r_M$ [cf. the asymptotic result (3.20)]. Hence the coefficients a_i that define the limit measure are uniquely determined and the limit measure is unique. This ensures that the whole trajectory $n(t, \cdot)$ converges to the limit point given by (3.23) and (3.24) as $t \rightarrow \infty$.

To prove claim (3.25) we proceed as follows. We note that the asymptotic result (3.30) now holds true for $J(t)$ and not for a mere subsequence $J(t_k)$. This implies that

$$\int_0^t (r_M - \rho(s)) ds \sim \frac{d}{2} \ln(t) \quad \text{as } t \rightarrow \infty. \quad (3.31)$$

Furthermore, choosing again $\varepsilon > 0$ small enough so that \bar{x}_i is the only maximum point of the function $r(x)$ in the ball $B(\bar{x}_i, \varepsilon)$ for every $i = 1, \dots, N$ and integrating over $B(\bar{x}_i, \varepsilon)$ both sides of the expression (3.19) for $n(t, x)$ we find that

$$\rho(t) = e^{-\int_0^t \rho(s) ds} \sum_{i=1}^N \int_{B(\bar{x}_i, \varepsilon)} n_0(x) e^{r(x)t} dx + e^{-\int_0^t \rho(s) ds} \int_{\Omega \setminus \cup_{i=1}^N B(\bar{x}_i, \varepsilon)} n_0(x) e^{r(x)t} dx.$$

The second term on the right-hand side of the above equation decays exponentially to 0 as $t \rightarrow \infty$, since $\rho(t) \rightarrow r_M$. Moreover, choosing ε small enough so that – under the additional assumption that the functions $n^0(x)$ and $r(x)$ are, respectively, of class C^1 and C^3 in a neighbourhood of each maximum point $\bar{x}_1, \dots, \bar{x}_N$ – we have $n^0 \in C^1(B(\bar{x}_i, \varepsilon))$ and $r \in C^3(B(\bar{x}_i, \varepsilon))$ for every $i = 1, \dots, N$, we can use the asymptotic expansion (2.13) and in so doing obtain the following asymptotic expression for the first integral on the right-hand side of the above equation

$$\int_{B(\bar{x}_i, \varepsilon)} n_0(x) e^{r(x)t} dx = \left(A_i + \frac{B_i}{t} + o\left(\frac{1}{t}\right) \right) \frac{e^{r_M t}}{t^{\frac{d}{2}}} \quad \text{as } t \rightarrow \infty,$$

where A_i and B_i are real constants. Taken together, these results yield

$$\rho(t) = J(t) \left[\sum_{i=1}^N \left(A_i + \frac{B_i}{t} \right) + o\left(\frac{1}{t}\right) \right] \quad \text{as } t \rightarrow \infty, \quad (3.32)$$

with J defined according to (3.26). Since $J(t) \rightarrow K$ and $\rho(t) \rightarrow r_M$ as $t \rightarrow \infty$, the asymptotic expression (3.32) implies that

$$K \sum_{i=1}^N A_i = r_M \quad \text{and} \quad \rho(t) - r_M \sim K \sum_{i=1}^N \frac{B_i}{t} \quad \text{as } t \rightarrow \infty.$$

Combining the latter asymptotic relation together with the asymptotic relation (3.31) we find that

$$K \sum_{i=1}^N B_i = -\frac{d}{2},$$

and this concludes the proof of Theorem 2. \square

Remark 1. In the case where $d = 1$ the expression (3.24) reads as

$$a_i = A \frac{n^0(\bar{x}_i)}{\sqrt{|r''(\bar{x}_i)|}} \quad \text{for } i = 1, \dots, N.$$

Remark 2. The results of Theorem 2 can be extended to the case where some maximum points of the function $r(x)$ belong to the boundary $\partial\Omega$ – a case that might be relevant for applications. In particular, letting $\partial\Omega$ be sufficiently smooth and using Laplace's method one can prove that if $\bar{x}_j \in \arg \max(r) \cap \partial\Omega$ is a stationary point of $r(x)$ then

$$a_j = \frac{A}{2} \frac{n^0(\bar{x}_j)}{\sqrt{|\det(H_j)|}}.$$

This implies that, *ceteris paribus*, the weight in front of a Dirac mass centred at a boundary point will be half that of a Dirac mass centred at an interior point. On the other hand, if $\bar{x}_j \in \arg \max(r) \cap \partial\Omega$ is a nonstationary point of the restriction of $r(x)$ to the boundary, and there is at least one maximum point of $r(x)$ that belongs to the interior of Ω , then the weight a_j in front of $\delta_{\bar{x}_j}(x)$ will be zero (i.e. the mass in a neighbourhood of \bar{x}_j will vanish as $t \rightarrow \infty$).

Remark 3. The asymptotic relation (3.25) shows that the integral $\rho(t)$ of the solution to the IDE (1.1) converges to r_M more slowly than the solution of the related logistic ordinary differential equation

$$\frac{dN}{dt} = (r_M - N)N, \quad N \equiv N(t), \quad t \in (0, \infty),$$

which converges exponentially to r_M as $t \rightarrow \infty$. Moreover, whilst

$$\operatorname{sgn} \left(\frac{dN(t)}{dt} \right) = \operatorname{sgn} (r_M - N(0)) \quad \forall t \in \mathbb{R}^+,$$

which means that $N(t)$ will approach the asymptotic value r_M from below if $N(0) < r_M$ and from above if $N(0) > r_M$, the asymptotic relation (3.25) indicates that $\rho(t)$ will always approach r_M from below independently from the value of $\rho(0)$. This also implies that if $\rho(0) > r_M$ then the derivative of $\rho(t)$ will change sign at least once on \mathbb{R}^+ .

It is also worth comparing the speed of convergence given by the asymptotic relation (3.25) with the one that can be obtained based on the best estimates currently available in the literature, namely

$$(r^M - \rho(t))^2 + \int_{\Omega} (r^M - r(x)) n(t, x) dx = \mathcal{O} \left(\frac{\log(t)}{t} \right) \quad \text{as } t \rightarrow \infty,$$

and also that the latter cannot vanish as $\mathcal{O} \left(\frac{1}{t^\alpha} \right)$ for any $\alpha > 1$ [24, 40].

3.2 Numerical solutions

To illustrate the asymptotic results established by Theorem 2, we solve numerically the Cauchy problem (2.5). In particular, we approximate the IDE (1.1) using the forward Euler method with step size 0.01. We select a uniform discretisation of the interval $\Omega := [-1, 2]$ consisting of 1000 points as the computational domain of the independent variable x , and we consider $t \in [0, 200]$. We choose the initial condition

$$n^0(x) \equiv \frac{2}{3} \quad \text{so that} \quad \int_{\Omega} n^0(x) dx = 2 \quad (3.33)$$

and we use the following definition

$$r(x) := e^{-\frac{(x+0.5)^2}{0.01}} + e^{-\frac{(x-1)^2}{0.1}}, \quad (3.34)$$

which satisfies the assumptions of Theorem 2. As shown in Figure 1, the function $r(x)$ defined according to (3.34) has two maximum points $\bar{x}_1 \in [-1, 0]$ and $\bar{x}_2 \in [0, 2]$.

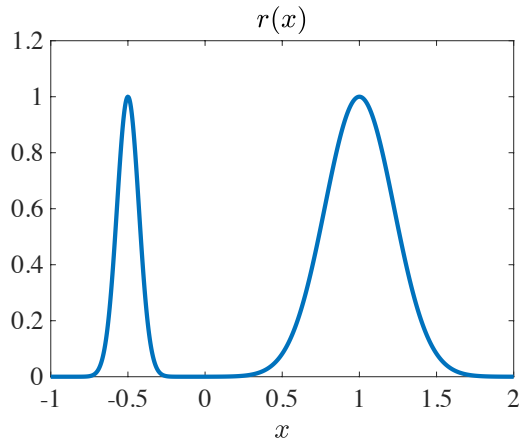


Figure 1: Plot of the function $r(x)$ defined according to (3.34).

We compute numerically the integrals

$$\rho_1(t) = \int_{-1}^{\frac{1}{2}} n(t, x) dx \quad \text{and} \quad \rho_2(t) = \int_{\frac{1}{2}}^2 n(t, x) dx, \quad (3.35)$$

as well as the coefficients a_1 and a_2 given by (3.24). In the one-dimensional setting considered here, the expressions given by (3.24) read as

$$a_1 = A \frac{n^0(\bar{x}_1)}{\sqrt{|r''(\bar{x}_1)|}} \quad \text{and} \quad a_2 = A \frac{n^0(\bar{x}_2)}{\sqrt{|r''(\bar{x}_2)|}} \quad \text{with } A \text{ s.t. } a_1 + a_2 = 1. \quad (3.36)$$

All numerical computations are performed in MATLAB.

The results obtained are summarised in Figure 2 and Figure 3. As we would expect based on Theorem 1, the numerical results displayed in Figure 2 show that $n(t, x)$ becomes concentrated as a sum of two Dirac masses centred at the points \bar{x}_1 and \bar{x}_2 (left panel), while $\rho(t)$ converges to r_M (right panel).

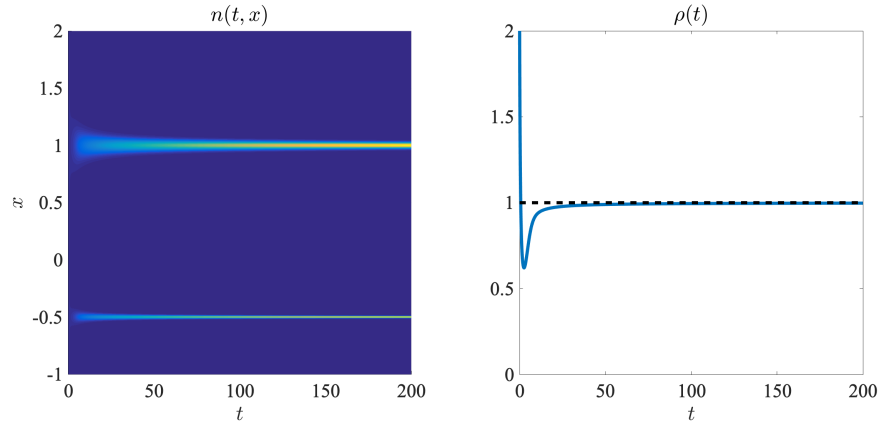


Figure 2: Dynamics of $n(t, x)$ (left panel) and $\rho(t)$ (right panel) obtained by solving numerically the Cauchy problem (2.5) with $n^0(x)$ and $r(x)$ defined according to (3.33) and (3.34). The black line in the right panel highlights the value of r_M .

Furthermore, the curves displayed in the left panel of Figure 3 show that, in agreement with the results established by Theorem 2, the integrals $\rho_1(t)$ and $\rho_2(t)$ converge, respectively, to the values $a_1 r_M$ and $a_2 r_M$, with a_1 and a_2 given by (3.36), while the curves in the right panel of Figure 3 demonstrate that $(r_M - \rho(t)) t \rightarrow \frac{1}{2}$ as $t \rightarrow \infty$, *i.e.* the asymptotic relation (3.25) is verified.

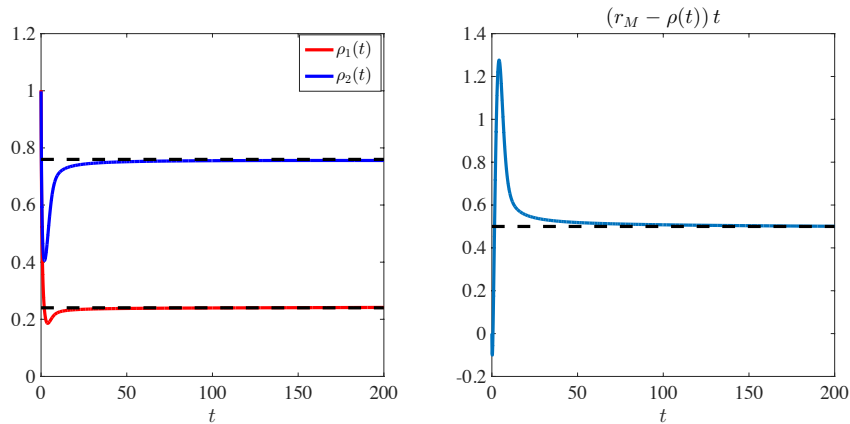


Figure 3: Dynamics of the integrals $\rho_1(t)$ and $\rho_2(t)$ given by (3.35) (left panel), and of the function $(r_M - \rho(t))t$ (right panel). The black lines in the left panel highlight the values of the quantities $a_1 r_M$ and $a_2 r_M$, with a_1 and a_2 given by (3.36), while the black line in the right panel corresponds to the asymptotic value of $(r_M - \rho(t))t$ given by (3.25). The integrals $\rho_1(t)$, $\rho_2(t)$ and $\rho(t)$ are computed using the numerical solution of the Cauchy problem (2.5) subject to the initial condition (3.33) with $r(x)$ defined according to (3.34).

4 Long-time behaviour of the initial-boundary value problem (2.6)

In this section we study the asymptotic behaviour of the solutions to the initial-boundary value problem (2.6) as $t \rightarrow \infty$ (Section 4.1), and we provide a sample of numerical solutions that illustrate the analytical results obtained (Section 4.2).

4.1 Asymptotic analysis

Under assumptions (2.7) there exists a unique nonnegative classical solution $n_\beta \in C([0, +\infty), L^1(\Omega)) \cap C^1((0, +\infty), C^{2,\alpha}(\Omega))$ of the initial-boundary value problem (2.6) [13]. Moreover, the behaviour of $n_\beta(t, x)$ in the asymptotic regime $t \rightarrow \infty$ is known to be governed by the principal eigenpair $(\lambda_\beta, \psi_\beta)$ of the elliptic differential operator L_β defined according to (2.14) with zero Neumann boundary condition, as established by the following proposition [13, 25].

Proposition 1. *Under assumptions (2.7), the solution of the initial-boundary value problem (2.6) is such that if $\lambda_\beta \geq 0$ then*

$$\rho_\beta(t) \xrightarrow[t \rightarrow \infty]{} 0, \quad (4.37)$$

whereas if $\lambda_\beta < 0$ then

$$\rho_\beta(t) \xrightarrow[t \rightarrow \infty]{} -\lambda_\beta \quad \text{and} \quad n_\beta(t, \cdot) \xrightarrow[t \rightarrow \infty]{} -\lambda_\beta \psi_\beta \quad \text{in} \quad L^\infty(\Omega). \quad (4.38)$$

Proof. Let $u_\beta(t, x) := w(t) n_\beta(t, x)$ where $w(t)$ solves the Cauchy problem

$$\begin{cases} w' = (\rho_\beta(t) + \lambda_\beta) w, & w \equiv w(t), \quad t \in (0, \infty), \\ w(0) = 1. \end{cases} \quad (4.39)$$

We have

$$\begin{aligned} \frac{\partial u_\beta}{\partial t} &= w' n_\beta + w \frac{\partial n_\beta}{\partial t} = w' n_\beta + w [(r(x) - \rho_\beta(t)) n_\beta + \beta \Delta n_\beta] \\ &= (w' - \rho_\beta(t) w) n_\beta + w (r(x) n_\beta + \beta \Delta n_\beta) \\ &= (w' - \rho_\beta(t) w) n_\beta + L_\beta[u_\beta]. \end{aligned}$$

Using the fact that $w(t)$ solves the Cauchy problem (4.39) and $n_\beta(t, x)$ is the solution of the initial-boundary value problem (2.6), we obtain the following initial-boundary value problem for $u_\beta(t, x)$

$$\begin{cases} \frac{\partial u_\beta}{\partial t} - L_\beta[u_\beta] = \lambda_\beta u_\beta, & u_\beta \equiv u_\beta(t, x), \quad (t, x) \in (0, \infty) \times \Omega, \\ \nabla u_\beta(t, x) \cdot \nu(x) = 0, & (t, x) \in (0, \infty) \times \partial\Omega, \\ u_\beta(0, x) = n^0(x), & n^0 \in C(\Omega), \quad n^0 \geq 0, \quad n^0 \not\equiv 0. \end{cases}$$

This is a standard parabolic problem the solution of which is such that

$$u_\beta(t, \cdot) \xrightarrow[t \rightarrow \infty]{} C \psi_\beta \quad \text{in } L^\infty(\Omega) \quad \text{for some } C > 0.$$

Since

$$\int_\Omega u_\beta(t, x) \, dx = w(t) \rho_\beta(t) \quad \text{and} \quad \int_\Omega \psi_\beta(x) \, dx = 1,$$

the above convergence result yields

$$w(t) \rho_\beta(t) \xrightarrow[t \rightarrow \infty]{} C. \tag{4.40}$$

Hence the ordinary differential equation for $w(t)$ can be rewritten as

$$w' = \lambda_\beta \left(\frac{C}{\lambda_\beta} + w \right) + f(t),$$

with the function $f(t)$ being such that $f(t) \rightarrow 0$ as $t \rightarrow \infty$. Using the latter ordinary differential equation we conclude that

$$\text{if } \lambda_\beta > 0 \quad \text{then} \quad w(t) \xrightarrow[t \rightarrow \infty]{} \infty, \quad \text{whilst if } \lambda_\beta < 0 \quad \text{then} \quad w(t) \xrightarrow[t \rightarrow \infty]{} \frac{C}{-\lambda_\beta}.$$

These asymptotic results along with the asymptotic result (4.40) ensure that

$$\text{if } \lambda_\beta \geq 0 \quad \text{then} \quad \rho_\beta(t) \xrightarrow[t \rightarrow \infty]{} 0, \quad \text{whereas if } \lambda_\beta < 0 \quad \text{then} \quad \rho_\beta(t) \xrightarrow[t \rightarrow \infty]{} -\lambda_\beta.$$

Moreover, recalling that $u_\beta(t, x) = w(t) n_\beta(t, x)$ we find that if $\lambda_\beta < 0$ then

$$n_\beta(t, \cdot) \xrightarrow[t \rightarrow \infty]{} \psi_\beta \quad \text{in } L^\infty(\Omega).$$

This concludes the proof of Proposition 1. □

The results established by Proposition 1 show that analysing the long-time behaviour of the solution to the initial-boundary value problem (2.6) comes down to studying the properties of the principal eigenpair $(\lambda_\beta, \psi_\beta)$. In particular, a general characterisation of λ_β and $\psi_\beta(x)$ can be obtained when $\beta \rightarrow 0$. To illustrate this, we define $\beta := \varepsilon$, where ε is a small positive parameter, and study the behaviour of λ_ε and $\psi_\varepsilon(x)$ in the asymptotic regime $\varepsilon \rightarrow 0$. Our main findings are summarised by Theorem 3, which shows that the long-time limit of $n_\varepsilon(t, x)$ when $\varepsilon \rightarrow 0$ is given by a measure which has total mass equal to r_M and consists of a weighted sum of Dirac masses centred at the points $\bar{x}_1, \dots, \bar{x}_N$.

Theorem 3. *If the assumptions of Proposition 1 along with assumption (2.8) are satisfied, then*

$$-\lambda_\varepsilon \xrightarrow[\varepsilon \rightarrow 0]{} r_M \tag{4.41}$$

and, upon extraction of subsequences,

$$\psi_\varepsilon(x) \xrightarrow[\varepsilon \rightarrow 0]{} \sum_{i=1}^N a_i \delta_{\bar{x}_i}(x) \quad \text{with } a_i \geq 0 \quad \text{and} \quad \sum_{i=1}^N a_i = 1. \tag{4.42}$$

Proof. We divide the proof of Theorem 3 into two steps. We first prove claim (4.41) and then claim (4.42).

Step 1: proof of (4.41). Since λ_ε is the principal eigenvalue of the differential elliptic operator L_ε , we have [cf. equation (2.15)]

$$\lambda_\varepsilon = \inf_{\phi \in H^1(\Omega) \setminus \{0\}} \mathcal{R}(L_\varepsilon, \phi) \quad \text{with} \quad \mathcal{R}(L_\varepsilon, \phi) = \frac{\varepsilon \int_\Omega |\nabla \phi(x)|^2 dx - \int_\Omega r(x) \phi^2(x) dx}{\int_\Omega \phi^2(x) dx}. \quad (4.43)$$

We start by noting that

$$\varepsilon \int_\Omega |\nabla \phi(x)|^2 dx - \int_\Omega r(x) \phi^2(x) dx \geq -r_M \int_\Omega \phi^2(x) dx \quad \forall \phi \in H^1(\Omega),$$

and, therefore, $\lambda_\varepsilon \geq -r_M$ for all $\varepsilon > 0$. Thus it suffices to show that $\lim \lambda_\varepsilon \leq -r_M$ as $\varepsilon \rightarrow 0$ in order to prove (4.41). To do this we construct a sequence of positive normalised H^1 -functions ϕ_ε such that $\mathcal{R}(L_\varepsilon, \phi_\varepsilon)$ converges to $-r_M$ as $\varepsilon \rightarrow 0$. We introduce the function

$$G : x \mapsto C e^{-|x|^2}, \quad (4.44)$$

where $|\cdot|$ denotes the Euclidean norm on \mathbb{R}^d and C is a normalising constant such that G has integral 1. Recalling the classical result

$$\frac{1}{\sigma^d} G\left(\frac{x - \bar{x}_i}{\sigma}\right) \xrightarrow{\sigma \rightarrow 0} \delta_{\bar{x}_i}(x),$$

we choose $\phi_\varepsilon^2 : x \mapsto \frac{1}{\varepsilon^{\frac{d}{4}}} G\left(\frac{x - \bar{x}_i}{\varepsilon^{\frac{1}{4}}}\right)$ so that $\phi_\varepsilon^2 \xrightarrow{\varepsilon \rightarrow 0} \delta_{\bar{x}_i}$. Using the fact that

$$\int_\Omega r(x) \phi_\varepsilon^2(x) dx \xrightarrow{\varepsilon \rightarrow 0} r_M, \quad \int_\Omega \phi_\varepsilon^2(x) dx \xrightarrow{\varepsilon \rightarrow 0} 1$$

and

$$\varepsilon \int_\Omega |\nabla \phi_\varepsilon(x)|^2 dx = \int_\Omega |x - \bar{x}_i|^2 \phi_\varepsilon^2(x) dx \xrightarrow{\varepsilon \rightarrow 0} |\bar{x}_i - \bar{x}_i|^2 = 0,$$

we obtain

$$\mathcal{R}(L_\varepsilon, \phi_\varepsilon) \xrightarrow{\varepsilon \rightarrow 0} -r_M.$$

This concludes the proof of (4.41).

Step 2: proof of (4.42). The pair $(\lambda_\varepsilon, \psi_\varepsilon)$ satisfies the eigenvalue problem

$$\begin{cases} -L_\varepsilon \psi_\varepsilon = \lambda_\varepsilon \psi_\varepsilon, & \text{in } \Omega, \\ \nabla \psi_\varepsilon \cdot \nu = 0, & \text{on } \partial\Omega, \end{cases}$$

and integrating over Ω we find

$$\int_\Omega (-\lambda_\varepsilon - r(x)) \psi_\varepsilon(x) dx = 0.$$

Hence

$$\int_\Omega (r_M - r(x)) \psi_\varepsilon(x) dx \xrightarrow{\varepsilon \rightarrow 0} 0. \quad (4.45)$$

Finally, for any $\varphi \in C(\overline{\Omega})$ with $\text{supp}(\varphi) \cap \arg \max(r) = \emptyset$ we have

$$\begin{aligned} \left| \int_{\Omega} \varphi(x) \psi_{\varepsilon}(x) \, dx \right| &= \left| \int_{\Omega} \frac{\varphi(x)}{r_M - r(x)} (r_M - r(x)) \psi_{\varepsilon}(x) \, dx \right| \\ &\leq \max_{x \in \text{supp}(\varphi)} \left| \frac{\varphi(x)}{r_M - r(x)} \right| \int_{\Omega} (r_M - r(x)) \psi_{\varepsilon}(x) \, dx. \end{aligned}$$

The latter integral inequality along with the asymptotic result (4.45) yields

$$\int_{\Omega} \varphi(x) \psi_{\varepsilon}(x) \, dx \xrightarrow{\varepsilon \rightarrow 0} 0 \quad \forall \varphi \in C(\overline{\Omega}) \quad \text{s.t.} \quad \text{supp}(\varphi) \cap \arg \max(r) = \emptyset.$$

This concludes the proof of (4.42). \square

Remark 4. The results of Theorem 3 imply that if $\arg \max(r) = \{\bar{x}_1\}$ then the long-time limit of $n_{\varepsilon}(t, x)$ when $\varepsilon \rightarrow 0$ is given by the measure $r_M \delta_{\bar{x}_1}(x)$.

Remark 5. The proof of Theorem 3 can be adapted to the case where the function $r(x)$ attains its maximum only on the boundary $\partial\Omega$. We expect that this can be done, as in Laplace's method, by adjusting the normalising constant C in (4.44), depending on the nature of the maximum at the boundary (stationary or not). However, we consider here only the simpler case corresponding to Theorem 3, which suffices for our purposes.

Remark 6. Since $r_M > 0$, the expression (4.43) for the Rayleigh quotient is such that if ε is small enough then $-\lambda_{\varepsilon} > 0$. Hence, based on the result of Proposition 1, we have that $\rho_{\varepsilon}(t)$ will not vanish as $t \rightarrow \infty$ when ε is sufficiently small.

In the framework of the results established by Theorem 3, to fully characterise the long-time limit of $n_{\varepsilon}(t, x)$ when $\varepsilon \rightarrow 0$ it is necessary to assess whether there exists a unique set of admissible coefficients a_1, \dots, a_N (i.e. if the limit measure is unique); if so, one needs to identify the values of the coefficients that define the only admissible limit measure.

A case where we expect the limit measure to be unique is when the set Ω and the function $r(x)$ are symmetric with respect to the hyperplane S defined according to (2.16). In this case, a complete characterisation of the limit measure is given by the following proposition.

Proposition 2. *Under the assumptions of Theorem 3, letting $N = 2$ and making the additional symmetry assumptions (2.17) and (2.18), we have*

$$\psi_{\varepsilon}(x) \xrightarrow{\varepsilon \rightarrow 0} \frac{1}{2} (\delta_{\bar{x}_1}(x) + \delta_{\bar{x}_2}(x)). \tag{4.46}$$

Proof. Under the symmetry assumptions (2.17) and (2.18) the points $\bar{x}_1 \in \Omega$ and $\bar{x}_2 \in \Omega$ are symmetric with respect to the hyperplane S , i.e.

$$\text{if } \bar{x}_1 = (\bar{x}_{11}, \bar{x}_{12}, \dots, \bar{x}_{1d}) \quad \text{then necessarily} \quad \bar{x}_2 = (-\bar{x}_{11}, \bar{x}_{12}, \dots, \bar{x}_{1d}).$$

Moreover, in the case where $N = 2$, the result established by Theorem 3 implies that

$$\psi_{\varepsilon}(x) \xrightarrow{\varepsilon \rightarrow 0} a \delta_{\bar{x}_1}(x) + (1 - a) \delta_{\bar{x}_2}(x), \quad \text{for some } a \geq 0.$$

Finally, Lemma 2 ensures that ψ_ε is symmetric with respect to the hyperplane S , and Lemma 4 in turn ensures that the weak limit point of ψ_ε for $\varepsilon \rightarrow 0$ is symmetric with respect to the hyperplane S as well. Hence $a = \frac{1}{2}$ and there is a unique limit point given by

$$\frac{1}{2} \delta_{\bar{x}_1}(x) + \frac{1}{2} \delta_{\bar{x}_2}(x).$$

Since the sequence ψ_ε is bounded in $L^1(\Omega)$, the Banach-Alaoglu Theorem ensures that it is relatively (weakly-*) compact in $\mathcal{M}^1(\bar{\Omega})$. This along with the uniqueness of the limit point gives the convergence of the whole sequence ψ_ε , *i.e.*

$$\psi_\varepsilon(x) \xrightarrow{\varepsilon \rightarrow 0} \frac{1}{2} (\delta_{\bar{x}_1}(x) + \delta_{\bar{x}_2}(x)),$$

which concludes the proof of Proposition 2. \square

Furthermore, an almost exhaustive characterisation of the limit measure in the absence of particular symmetries is provided by the following proposition, whereby the function $\zeta : \arg \max(r) \rightarrow \mathbb{R}^+$ defined as

$$\zeta(\bar{x}_i) := \sum_{j=1}^d \sqrt{|\lambda_j^i|}, \tag{4.47}$$

where $(\lambda_j^i)_{1 \leq j \leq d}$ are the eigenvalues of H_i (each counted with its multiplicity), is used to characterise the concavity of the function $r(x)$ at the maximum points, as it was previously done in semi-classical analysis [20, 21].

Proposition 3. *Under the assumptions of Theorem 3,*

$$\psi_\varepsilon \text{ concentrates on the set } \arg \min(\zeta) \text{ as } \varepsilon \rightarrow 0. \tag{4.48}$$

In particular, if $\arg \min(\zeta) = \{\bar{x}_m\}$ for some $1 \leq m \leq N$, then

$$\psi_\varepsilon(x) \xrightarrow{\varepsilon \rightarrow 0} \delta_{\bar{x}_m}(x). \tag{4.49}$$

Proof. We start by noting that studying the asymptotic behaviour of ψ_ε when $\varepsilon \rightarrow 0$ is equivalent to studying the asymptotic behaviour of the principal eigenfunction φ_ε of the differential elliptic operator $\varepsilon \Delta - V$ with $V := -r$. The result of Theorem 3 ensures that the support of the weak limit of φ_ε as $\varepsilon \rightarrow 0$ will be a (possibly improper) subset of the set $\arg \min(V) = (\bar{x}_1, \dots, \bar{x}_N)$. Investigating at which points of this discrete set the weak limit point of the sequence φ_ε will actually be concentrated is a fundamental question in semi-classical analysis. Such a question arises in the study of the dynamics of a particle confined within the region of space surrounding a minimum point of the potential V (*i.e.* a potential well) in the asymptotic regime of small noise (*i.e.* when $\varepsilon \rightarrow 0$) [20–22, 41]. Recasting the problem in this way we can use the asymptotic results presented in [20, 21] which ensure that, under the assumptions of Theorem 3 and when ε tends to 0, the principal eigenfunction φ_ε concentrates on the set $\arg \min(\zeta)$, with ζ defined according to (4.47). Thus, under the additional assumption that the set $\arg \min(\zeta)$ coincides with the singleton $\{\bar{x}_m\}$ for some $1 \leq m \leq N$, we find that φ_ε concentrates at the point \bar{x}_m as $\varepsilon \rightarrow 0$, whence (4.49). \square

Remark 7. In the case where $d = 1$, the assumption $\arg \min(\zeta) = \{\bar{x}_m\}$ reads as

$$\{\bar{x}_m\} = \arg \min_{\bar{x}_i \in \arg \max r} |r''(\bar{x}_i)|. \quad (4.50)$$

Remark 8. Comparing the results of Proposition 3 with the results established by Theorem 2 one can see that there is a stark difference between the long-time behaviour of the solution to the initial-boundary value problem (2.6) for $\beta \rightarrow 0$ and the long-time behaviour of the solution to the Cauchy problem (2.5). In fact, in the case where the set $\arg \min(\zeta)$ is reduced to a singleton and $n^0(x) > 0$ for all $x \in \arg \max(r)$, Theorem 2 shows that the long-time limit of $n(t, x)$ will be given by a sum of multiple Dirac masses with different positive weights, whereas Proposition 3 shows that the long-time limit of $n_\beta(t, x)$ for $\beta \rightarrow 0$ will consist of one single Dirac mass.

Remark 9. We remark that when assumption (4.47) is not satisfied, i.e. if the set $\arg \min(\zeta)$ is not a singleton, it is still possible to go further in reducing the support of the limit point of the sequence ψ_ε as $\varepsilon \rightarrow 0$. However, the conditions determining which of the coefficients a_i will be different from zero become rather convoluted, as shown by the results of semi-classical analysis presented in [22]. Therefore, we consider here only the simpler case corresponding to Proposition 3, which suffices for our purposes.

4.2 Numerical solutions

To illustrate the asymptotic results established by Theorem 3, Proposition 2 and Proposition 3, we solve numerically the initial-boundary value problem (2.6). Numerical solutions are constructed by approximating the diffusion term via a second-order central difference scheme [26] and then using the forward Euler method with step size 0.01 to approximate the resulting system of ordinary differential equations. We select a discretisation of the interval $\Omega := [-1, 2]$ consisting of 1000 points as the computational domain of the independent variable x , and let $t \in [0, t_f]$ with t_f being either 200 or 800. We define $\beta = 10^{-6}$, choose the initial condition (3.33), and use either the definition

$$r(x) := e^{-\frac{(x+0.5)^2}{0.01}} + e^{-\frac{(x-1.5)^2}{0.01}}, \quad (4.51)$$

or definition (3.34). Definition (4.51) satisfies the assumptions of Proposition 2 with $S := \{0.5\}$ (cf. the plot in Figure 4), whereas definition (3.34) satisfies the assumptions of Proposition 3 and, as previously noted, it has two maximum points $\bar{x}_1 \in [-1, 0]$ and $\bar{x}_2 \in [0, 2]$ (cf. the plot in Figure 1).

We compute numerically the following integrals

$$\rho_1(t) = \int_{-1}^{\frac{1}{2}} n_\beta(t, x) dx \quad \text{and} \quad \rho_2(t) = \int_{\frac{1}{2}}^2 n_\beta(t, x) dx. \quad (4.52)$$

All numerical computations are performed in MATLAB.

The results obtained are summarised in Figure 5 and Figure 6. As we would expect based on Theorem 3 and Proposition 2, the numerical results displayed in Figure 5 show that when $r(x)$ is defined according to (4.51) the solution $n(t, x)$ becomes concentrated as a sum of two Dirac masses centred at the points \bar{x}_1 and \bar{x}_2 , the integral $\rho(t)$ converges to r_M , and the integrals $\rho_1(t)$ and $\rho_2(t)$ given by (4.52) both converge to $\frac{r_M}{2}$.

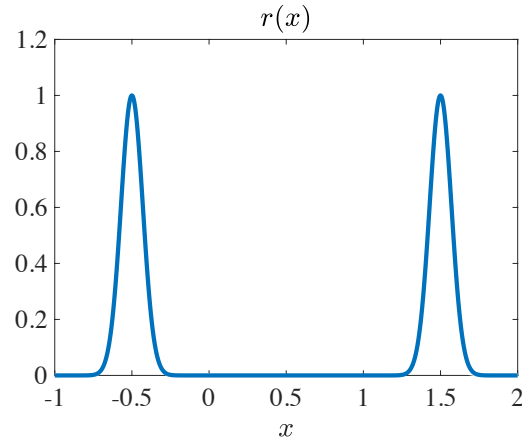


Figure 4: Plot of the function $r(x)$ defined according to (4.51).

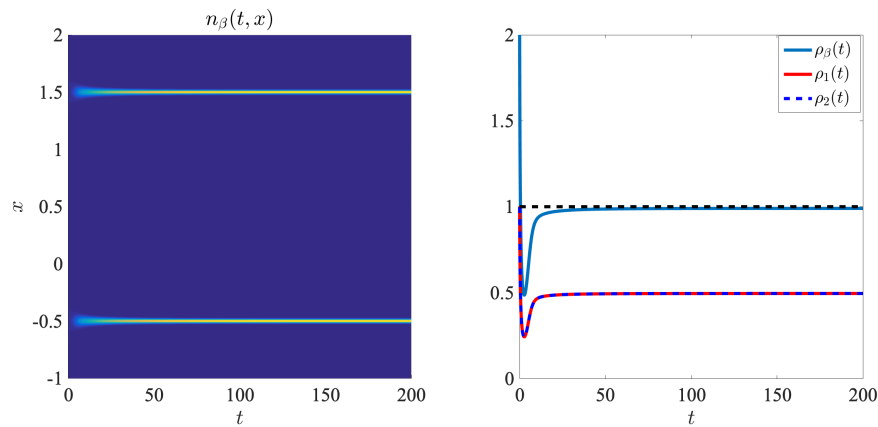


Figure 5: Dynamics of $n(t, x)$ (left panel) and $\rho(t)$ (right panel) obtained by solving numerically the Cauchy problem (2.5) with $n^0(x)$ and $r(x)$ defined according to (3.33) and (4.51). The black line in the right panel highlights the value of r_M , while the red line and the blue line correspond to the integrals $\rho_1(t)$ and $\rho_2(t)$ given by (4.52), respectively.

On the other hand, the numerical results displayed in Figure 6 show that, in agreement with the results of Theorem 3 and Proposition 3, when $r(x)$ is defined according to (3.34) the integral $\rho_\beta(t)$ converges to r_M , while the solution $n_\beta(t, x)$ becomes concentrated as one single Dirac mass centred at the point \bar{x}_2 (left panel), which is the maximum point of the function $r(x)$ that satisfies condition (4.50) – *i.e.* $|r''(\bar{x}_2)| < |r''(\bar{x}_1)|$. As a consequence, the integral $\rho_1(t)$ converges to zero, whereas the integral $\rho_2(t)$ converges to r_M .

5 Research perspectives

There are several possible generalisations of the prototypical selection model (1.1) and selection-mutation model (1.3) for which suitable developments of the methods used here would be relevant.

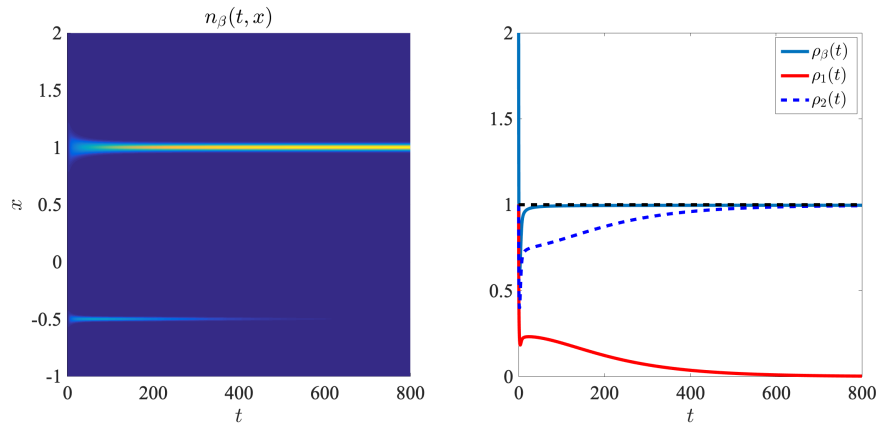


Figure 6: Dynamics of $n_\beta(t, x)$ (left panel) and $\rho_\beta(t)$ (right panel) obtained by solving numerically the Cauchy problem (2.6) with $\beta = 10^{-6}$ and with $n^0(x)$ and $r(x)$ defined according to (3.33) and (3.34). The black line in the right panel highlights the value of r_M , while the red line and the blue line correspond to the integrals $\rho_1(t)$ and $\rho_2(t)$ given by (4.52), respectively.

More general saturating nonlocal terms. A natural way to extend our study would be to replace the saturating term $\rho(t)$ with a more general nonlocal term of the form $\int_\Omega K(x, y) n(t, y) dy$, where the kernel $K(x, y)$ models the effect of competitive interactions between individuals in the phenotypic state x and other individuals in a generic phenotypic state y . While the long-time behaviour of the IDE model with such a more general saturating nonlocal term was extensively studied in [24], where the convergence of the solution to a weighted sum of Dirac masses was also investigated depending on the properties of the kernel K , the existing literature still lacks a precise characterisation of the long-time behaviour of the solutions for the corresponding PDE model, with the exception of the particular case when $K(x, y) \equiv k(y)$ or possible perturbations of such a particular case [13]. While we expect that extending our results to this particular case would be relatively easy, the case of a generic kernel $K(x, y)$ is an open problem.

Integral kernel modelling phenotypic variations. Our results could be extended to the case where the linear diffusion operator in the nonlocal PDE (1.3) is replaced by an integral term of the form $\int_\Omega (M(x, y) n(t, y) - M(y, x) n(t, x)) dy$, where the kernel $M(x, y)$ models the transition of individuals from a generic phenotypic state y to the phenotypic state x . In [4] it was shown that, when phenotypic variations are modelled through such an integral kernel, the solution of selection-mutation models like the one considered here will typically converge to a measure as $t \rightarrow \infty$, and a criterion was derived to determine whether the limit measure would be singular or absolutely continuous. Suitable developments of our methods would make it possible to investigate the dependence of such a criterion on the weight of mutations compared to selection, which would be captured by a scaling parameter analogous to our parameter ε .

Systems of equations. It would also be interesting to extend our results to the case of systems of IDEs of the form of (1.1) and systems of nonlocal PDEs of the form of (1.3). In

this regard, the results presented in [40] for a specific system of IDEs could prove useful, since they establish the convergence of the solution to a measure as $t \rightarrow \infty$ and provide a characterisation of its support. As for systems of corresponding nonlocal PDEs, the convergence of the components of the solution to the principal eigenfunctions of the related elliptic differential operators when $t \rightarrow \infty$ has been proved for a two-by-two competitive system [25]. Apart from these particular cases, the long-time behaviour of the solutions of these systems of IDEs and nonlocal PDEs is still an open problem.

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Appendix. Proof of Theorem 1 under assumption (3.22)

We start by noting that $\rho(t)$ is uniformly bounded in $L^\infty([0, \infty))$. In fact, integrating both sides of the IDE for $n(t, x)$ over Ω and using Grönwall's lemma yields

$$\frac{d\rho}{dt} \geq (r_m - \rho)\rho \implies \rho(t) \geq \min(r_m, \rho(0)) =: \rho_m \quad \forall t \in [0, \infty) \quad (5.53)$$

and

$$\frac{d\rho}{dt} \leq (r_M - \rho)\rho \implies \rho(t) \leq \max(r_M, \rho(0)) =: \rho_M \quad \forall t \in [0, \infty). \quad (5.54)$$

Then we prove that $\rho \in BV([0, +\infty))$. In order to do this, we define

$$q := \frac{d\rho}{dt} = \int_{\Omega} (r(x) - \rho) n(t, x) dx$$

so that, upon differentiation, we obtain

$$\frac{dq}{dt} = \int_{\Omega} (r(x) - \rho)^2 n(t, x) dx - q\rho.$$

Multiplying both sides of the latter differential equation by $-(\text{sgn}(q))_-$ and estimating the right-hand side of the resulting differential equation from above we find that

$$\frac{dq_-}{dt} \leq -\rho_m q_- \implies (q(t))_- \leq (q(0))_- e^{-\rho_m t} \quad \forall t \in [0, \infty). \quad (5.55)$$

Moreover, for any $T > 0$ we have

$$\int_0^T q(t) dt = \rho(T) - \rho(0) \leq \rho_M. \quad (5.56)$$

Using the estimates (5.55) and (5.56) we obtain

$$\int_0^T \left(\frac{d\rho}{dt} \right)_+ dt = \int_0^T \frac{d\rho}{dt} dt + \int_0^T \left(\frac{d\rho}{dt} \right)_- dt < \infty$$

and letting $T \rightarrow \infty$ we obtain

$$\int_0^\infty \left(\frac{d\rho}{dt} \right)_+ dt < \infty.$$

This estimate along with the fact that $\rho \in L^\infty([0, \infty))$ ensures that $\rho \in BV([0, +\infty))$.

Since $\rho \in BV([0, +\infty))$ we conclude that $\rho(t)$ admits a limit ρ^∞ as $t \rightarrow \infty$. The fact that $\rho^\infty = r_M$ can be proved via contradiction. Suppose that $\rho^\infty < r_M$ and consider $\varepsilon > 0$ such that $r(x) > r_M - \varepsilon$ for all $x \in B(x_i, \varepsilon)$, where $B(x_i, \varepsilon)$ is the ball of centre $x_i \in \arg \max(r)$ and radius ε . Since $\rho(t) \rightarrow \rho^\infty$ as $t \rightarrow \infty$, if $\rho^\infty < r_M$ then for ε small enough there exists $\tau_\varepsilon > 0$ such that $\rho(t) < r_M - 2\varepsilon$ for all $t \geq \tau_\varepsilon$. Solving the IDE (1.1) for $t \geq \tau_\varepsilon$ gives

$$n(t, x) = n(\tau_\varepsilon, x) e^{r(x)(t-\tau_\varepsilon) - \int_{\tau_\varepsilon}^t \rho(s) ds}. \quad (5.57)$$

Integrating both sides of (5.57) over Ω and estimating from below we find

$$\rho(t) \geq \int_{B(x_i, \varepsilon)} n(\tau_\varepsilon, x) e^{(r_M - \varepsilon)(t - \tau_\varepsilon) - \int_{\tau_\varepsilon}^t \rho(s) ds} dx \geq e^{\varepsilon(t - \tau_\varepsilon)} \int_{B(x_i, \varepsilon)} n(\tau_\varepsilon, x) dx \quad \forall t \geq \tau_\varepsilon,$$

which implies that $\rho(t) \rightarrow \infty$ as $t \rightarrow \infty$. Thus we arrive at a contradiction because ρ is bounded from above. Now suppose that $\rho^\infty > r_M$. If so, there exist $\varepsilon > 0$ sufficiently small and $\tau_\varepsilon > 0$ sufficiently large so that $\rho(t) > r_M + \varepsilon$ for all $t \geq \tau_\varepsilon$. Solving the IDE (1.1) for $t \geq \tau_\varepsilon$ gives (5.57). Moreover, integrating both sides of (5.57) over Ω and estimating from above yields

$$\rho(t) \leq \int_{\Omega} n(t_\varepsilon, x) e^{r_M(t - \tau_\varepsilon) - \int_{\tau_\varepsilon}^t \rho(s) ds} dx \leq e^{-\varepsilon(t - \tau_\varepsilon)} \int_{\Omega} n(\tau_\varepsilon, x) dx \quad \forall t \geq \tau_\varepsilon,$$

which implies that $\rho(t) \rightarrow 0$ as $t \rightarrow \infty$. Thus we arrive again at a contradiction because $\rho(t) \geq r_m$ for all $t \in [0, \infty)$. In so doing we have proved that $\rho^\infty = r_M$.

Since the sequence $(n(t, \cdot))_{t > 0}$ is bounded in $L^1(\Omega)$, the Banach-Alaoglu Theorem ensures that it is relatively (weakly-*) compact in $\mathcal{M}^1(\bar{\Omega})$. Thus we can extract a subsequence $n(t_k, \cdot) \in \mathcal{M}^1(\bar{\Omega})$ such that

$$n(t_k, \cdot) \xrightarrow[k \rightarrow \infty]{} n^\infty \quad \text{with} \quad n^\infty \in \mathcal{M}^1(\bar{\Omega}),$$

where the measure n^∞ is nonnegative and its total mass is r_M . Finally, since solving the Cauchy problem (2.5) yields

$$n(t_k, x) = n^0(x) e^{r(x)t_k - \int_0^{t_k} \rho(s) ds}$$

and $\rho(t) \rightarrow r_M$ as $t \rightarrow \infty$, we have

$$\int_{\Omega} \varphi(x) n(t_k, x) dx \xrightarrow[k \rightarrow \infty]{} 0 \quad \forall \varphi \in C(\bar{\Omega}) \quad \text{s.t.} \quad \text{supp}(\varphi) \cap \arg \max(r) = \emptyset,$$

which implies that

$$n^\infty = r_M \sum_{i=1}^N a_i \delta(x - x_i) \quad \text{with} \quad \sum_{i=1}^N a_i = 1.$$

This concludes the proof of Theorem 1 in the case where assumption (3.22) is satisfied.

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