

Characterizing N+-perfect line graphs

Mariana Escalante, Graciela Nasini, Annegret K Wagler

▶ To cite this version:

Mariana Escalante, Graciela Nasini, Annegret K Wagler. Characterizing N+-perfect line graphs. International Transactions in Operational Research, 2017, 24 (1-2), pp.325-337. hal-02047314

HAL Id: hal-02047314 https://hal.science/hal-02047314v1

Submitted on 24 Feb 2019

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Characterizing N_{+} -perfect line graphs

Mariana Escalante¹, Graciela Nasini¹, and Annegret Wagler²

¹CONICET and FCEIA, Universidad Nacional de Rosario, Rosario, Argentina, {mariana,nasini} @fceia.unr.edu.ar ²CNRS and LIMOS, Université Blaise Pascal, Clermont-Ferrand, France, wagler@isima.fr

October 16, 2015

Abstract

The subject of this contribution is the study of the Lovász-Schrijver PSD-operator N_+ applied to the edge relaxation of the stable set polytope of a graph. We are particularly interested in the problem of characterizing graphs for which N_+ generates the stable set polytope in one step, called N_+ -perfect graphs. It is conjectured that the only N_+ -perfect graphs are those whose stable set polytope is described by inequalities with near-bipartite support. So far, this conjecture has been proved for near-perfect graphs, fs-perfect graphs, and webs. Here, we verify it for line graphs, by proving that in an N_+ -perfect line graph the only facet-defining subgraphs are cliques and odd holes.

1 Introduction

The context of this paper is the study of the stable set polytope. Our focus lies on N_+ -perfect graphs: those graphs where a single application of the Lovász-Schrijver PSD-operator N_+ to the edge relaxation yields the stable set polytope.

The stable set polytope STAB(G) of a graph G = (V, E) is defined as the convex hull of the incidence vectors of all stable sets of G (in a stable set all nodes are mutually nonadjacent).

Two canonical relaxations of STAB(G) are the fractional or edge constraint stable set polytope

ESTAB(G) = {
$$\mathbf{x} \in \mathbf{R}_{+}^{|V|} : x_i + x_j \le 1, ij \in E$$
},

and the clique constraint stable set polytope

$$\operatorname{QSTAB}(G) = \{ \mathbf{x} \in \mathbf{R}_{+}^{|V|} : \sum_{i \in Q} x_i \leq 1, \ Q \subseteq V \text{ clique} \}$$

(in a clique all nodes are mutually adjacent, hence a clique and a stable set share at most one node). We have

$$STAB(G) \subseteq QSTAB(G) \subseteq ESTAB(G)$$

for any graph, where STAB(G) equals ESTAB(G) for bipartite graphs, and QSTAB(G) for perfect graphs only [5].

According to a famous characterization achieved by Chudnovsky et al. [4], perfect graphs are precisely the graphs without chordless cycles C_{2k+1} with $k \geq 2$, termed *odd holes*, or their complements, the *odd antiholes* \overline{C}_{2k+1} (the complement \overline{G} has the same nodes as G, but two nodes are adjacent in \overline{G} if and only if they are non-adjacent in G).

Perfect graphs turned out to be an interesting and important class with a rich structure and a nice algorithmic behaviour [13]. However, solving the stable set problem for a perfect graph G by maximizing a linear objective function over QSTAB(G) does not work directly [12], but only via a detour involving a geometric representation of graphs [16] and the resulting theta-body TH(G) introduced by Lovász et al. [13].

An orthonormal representation of a graph G=(V,E) is a sequence $(\mathbf{u_i}:i\in V)$ of unit-length vectors $\mathbf{u_i}\in\mathbf{R}^N$, where N is some positive integer, such that $\mathbf{u_i}^T\mathbf{u_j}=0$ for all $ij\notin E$. For any orthonormal representation of G and any additional unit-length vector $\mathbf{c}\in\mathbf{R}^N$, the corresponding orthonormal representation constraint is $\sum_{i\in V}(\mathbf{c}^T\mathbf{u_i})^2x_i\leq 1$. TH(G) denotes the convex set of all vectors $\mathbf{x}\in\mathbf{R}_+^{|V|}$ satisfying all orthonormal representation constraints for G. For any graph G, we have

$$STAB(G) \subseteq TH(G) \subseteq QSTAB(G)$$

and that approximating a linear objective function over TH(G) can be done with arbitrary precision in polynomial time [13]. Most notably, the same authors proved a beautiful characterization of perfect graphs:

$$G$$
 is perfect \Leftrightarrow TH $(G) = \text{STAB}(G)$
 \Leftrightarrow TH $(G) = \text{QSTAB}(G)$
 \Leftrightarrow TH (G) is polyhedral (1)

which even shows that optimizing a linear function on polyhedral TH(G) can be done in polynomial time.

For all imperfect graphs G it follows that STAB(G) does not coincide with any of the above relaxations. It is, thus, natural to study further relaxations and to combinatorially characterize those graphs where STAB(G) equals one of them.

1.1 A linear relaxation and rank-perfect graphs

Rank-perfect graphs are introduced in [20] in order to obtain a superclass of perfect graphs in terms of a further linear relaxation of STAB(G). As natural generalization of the clique constraints describing QSTAB(G), we consider rank constraints

$$\mathbf{x}(G') = \sum_{i \in G'} x_i \le \alpha(G')$$

associated with arbitrary induced subgraphs $G' \subseteq G$. By the choice of the right hand side $\alpha(G')$, denoting the size of a largest stable set in G', rank constraints are obviously valid for STAB(G). The rank constraint stable set polytope

$$RSTAB(G) = \{ \mathbf{x} \in \mathbf{R}^{|V|} : \sum_{i \in G'} x_i \le \alpha(G'), \ G' \subseteq G \}$$

is a further linear relaxation of STAB(G). As clique constraints are special rank constraints (namely exactly those with $\alpha(G')=1$), we immediately obtain

$$STAB(G) \subseteq RSTAB(G) \subseteq QSTAB(G)$$
.

A graph G is rank-perfect by [20] if and only if STAB(G) = RSTAB(G) holds. By definition, rank-perfect graphs include all perfect graphs (where rank constraints associated with cliques suffice). In general, by restricting the facet set to rank constraints associated with certain subgraphs only, several well-known graph classes are defined, e.g., near-perfect graphs [18] where only rank constraints associated with cliques and the whole graph are allowed, or t-perfect [5] and h-perfect graphs [13] where rank constraints associated with edges and odd holes resp. cliques and odd holes are required.

Further classes of rank-perfect graphs are antiwebs [21] and line graphs [8, 9].

An antiweb A_n^k is a graph with n nodes $0, \ldots, n-1$ and edges ij if and only if $k \leq |i-j| \leq n-k$ and $i \neq j$. Antiwebs include all complete graphs $K_n = A_n^1$, all odd holes $C_{2k+1} = A_{2k+1}^k$, and their complements $\overline{C}_{2k+1} = A_{2k+1}^2$, see Fig. 1 for examples.

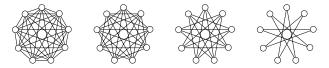


Figure 1: The antiwebs $A_{\mathbf{q}}^k$.

As common generalization of perfect, t-perfect and h-perfect graphs as well as antiwebs, the class of *a-perfect graphs* was introduced in [22] as those graphs whose stable set polytopes are given by nonnegativity constraints and rank constraints associated with antiwebs only. Antiwebs are *a*-perfect by [21], further examples of *a*-perfect graphs were presented in [22].

A line graph is obtained by taking the edges of a graph as nodes and connecting two nodes if and only if the corresponding edges are incident, see Fig. 2 for illustration. Since matchings of the original graph correspond to stable sets of the line graph, the results on the matching polytope by [8, 9] imply that line graphs are also rank-perfect, see Section 3 for details.

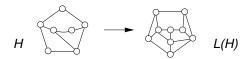


Figure 2: A graph and its line graph.

1.2 A semi-definite relaxation and N_+ -perfect graphs

In the early nineties, Lovász and Schrijver introduced the PSD-operator N_+ which, applied over the edge relaxation ESTAB(G), generates the positive semi-definite relaxation $N_+(G)$ stronger than TH(G) [17]. We denote by $\mathbf{e}_0, \mathbf{e}_1, \ldots, \mathbf{e}_n$ the vectors of the canonical basis of \mathbf{R}^{n+1} (where the first coordinate is indexed zero), $\mathbf{1}$ the vector with all components equal to 1 and S_+^n the space of $(n \times n)$ symmetric and positive semidefinite matrices with real entries. Given a convex set K in $[0,1]^n$, let

cone(K) =
$$\left\{ \begin{pmatrix} x_0 \\ \mathbf{x} \end{pmatrix} \in \mathbf{R}^{n+1} : \mathbf{x} = x_0 \mathbf{y}; \ \mathbf{y} \in K \right\}$$
.

Then, we define the set $M_{+}(K) =$

$$\left\{Y \in S^{n+1}_+: \quad Y \mathbf{e}_0 = \operatorname{diag}(Y), \\ Y \mathbf{e}_i \in \operatorname{cone}(K), \\ Y(\mathbf{e}_0 - \mathbf{e}_i) \in \operatorname{cone}(K), \ i = 1, \dots, n\right\},$$

where $\operatorname{diag}(Y)$ denotes the vector whose *i*-th entry is Y_{ii} , for every $i = 0, \ldots, n$. Projecting this lifting back to the space \mathbf{R}^n results in $N_+(K) =$

$$\left\{ \mathbf{x} \in [0,1]^n : \begin{pmatrix} 1 \\ \mathbf{x} \end{pmatrix} = Y\mathbf{e}_0, \text{ for some } Y \in M_+(K) \right\}.$$

In [17], Lovász and Schrijver proved that $N_+(K)$ is a relaxation of the convex hull of integer solutions in K and that $N_+^n(K) = \operatorname{conv}(K \cap \{0,1\}^n)$, where $N_+^0(K) = K$ and $N_+^k(K) = N_+(N_+^{k-1}(K))$ for $k \geq 1$. In this work we focus on the behaviour of a single application of the N_+ -operator to the edge relaxation of the stable set polytope of a graph.

In order to simplify the notation we write $N_{+}(G) = N_{+}(\mathrm{ESTAB}(G))$. In [17] it is shown that

$$STAB(G) \subseteq N_{+}(G) \subseteq TH(G) \subseteq QSTAB(G).$$

Similarly to what happens with perfect graphs, the stable set problem can be solved in polynomial time for the class of graphs for which $N_+(G) = \text{STAB}(G)$ [12, 13]. We will call these graphs N_+ -perfect. A graph G that is not N_+ -perfect is called N_+ -imperfect.

In [2], the authors look for a characterization of N_+ -perfect graphs similar to the characterizations for perfect graphs given in (1). More precisely, they intend to find an appropriate polyhedral relaxation P(G) of STAB(G) such that

$$G \text{ is } N_{+}\text{-perfect} \Leftrightarrow N_{+}(G) = \text{STAB}(G)$$

 $\Leftrightarrow N_{+}(G) = P(G).$ (2)

Following this line, the following conjecture has been recently proposed in [3]:

Conjecture 1 ([3]). $[N_+$ -Perfect Graph Conjecture] The stable set polytope of every N_+ -perfect graph can be described by facet-defining inequalities with near-bipartite support.

Near-bipartite graphs, defined in [19], are those graphs where removing all neighbors of an arbitrary node and the node itself leaves the resulting

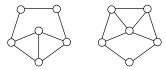


Figure 3: The graphs G_{LT} (on the left) and G_{EMN} (on the right).

graph bipartite. Antiwebs and complements of line graphs are examples of near-bipartite graphs. Again from results in [17], we know that graphs for which every facet-defining inequality of STAB(G) has a near-bipartite support is N_+ -perfect. Thus, Conjecture 1 states that these graphs are the only N_+ -perfect graphs. In particular, near-bipartite and a-perfect graphs are N_+ -perfect.

In addition, it can be proved that every subgraph of an N_+ -perfect graph is also N_+ -perfect. This motivates the definition of minimally N_+ -imperfect graphs as these N_+ -imperfect graphs whose proper induced subgraphs are all N_+ -perfect.

In [10] and [14] it was proved that all the imperfect graphs with at most 6 nodes are N_+ -perfect, except the two imperfect near-perfect graphs depicted in Figure 3. The graph on the left is denoted by G_{LT} and the other one is denoted by G_{EMN} . So, G_{LT} and G_{EMN} are the two smallest minimally N_+ -imperfect graphs. Characterizing all minimally N_+ -imperfect graphs within a certain graph class can be a way to attack Conjecture 1 for this class. That way, Conjecture 1 has been already verified for near-perfect graphs by [2], fs-perfect graphs (where the only facet-defining subgraphs are cliques and the graph itself) by [3], and webs (the complements of antiwebs) by [11].

In this contribution, we verify Conjecture 1 for line graphs. For that, we present three infinite families of N_+ -imperfect line graphs (Section 2) and show that all facet-defining subgraphs of a line graph different from cliques and odd holes contain one of these N_+ -imperfect line graphs (Section 3). Finally, we notice that the graphs in the three presented families are minimally N_+ -imperfect and, in fact, the only minimally N_+ -imperfect line graphs. We close with some concluding remarks and lines of further research.

2 Three families of N_+ -imperfect line graphs

In this section, we provide three infinite families of N_+ -imperfect line graphs. For that, we apply an operation preserving N_+ -imperfection to the two smallest N_{+} -imperfect graphs G_{LT} and G_{EMN} (note that both graphs are line graphs).

In [14], the *stretching* of a node v is introduced as follows: Partition its neighborhood N(v) into two nonempty, disjoint sets A_1 and A_2 (so $A_1 \cup A_2 = N(v)$, and $A_1 \cap A_2 = \emptyset$). A stretching of v is obtained by replacing v by two adjacent nodes v_1 and v_2 , joining v_i with every node in A_i for $i \in \{1, 2\}$, and either subdividing the edge v_1v_2 by one node w or subdividing every edge between v_2 and A_2 with one node. Moreover, it is shown in [14] that the stretching of a node preserves N_+ -imperfection.

For our purpose, we will use the stretching of node v in the case of subdividing the edge v_1v_2 by one node w. If $|A_1| = 1$ or $|A_2| = 1$ the stretching corresponds to the 3-subdivision of an edge (that is, when an edge is replaced by a path of length 3).

We next establish a connection between subdivisions of edges in a graph H and stretchings of nodes in its line graph L(H). Let G be the line graph of H and consider an edge $e = u_1u_2$ in H together with its corresponding node v in G. If e is a simple edge of H (i.e., if there is no edge parallel to e in H), then the neighborhood N(v) of its corresponding node v in G partitions into two cliques U_1 and U_2 representing the edges in H incident to e in u_1 and u_2 , respectively. Accordingly, we call a stretching of a node v in a line graph canonical if these cliques U_1 and U_2 are selected as partition of N(v).

For illustration, see Figure 4 which shows the graph $C_5 + c$ (a 5-hole with one chord c), the graph $C_5 + E_3$ (obtained from $C_5 + c$ by subdividing c into a path E_3 of length 3), and their line graphs, where $L(C_5 + E_3)$ results from $L(C_5 + c)$ by a canonical stretching of the node corresponding to c.

In fact, we have in general:

Lemma 2. Let e be a simple edge in H and v be the corresponding node in its line graph G. If H' is the graph obtained after a 3-subdivision of e in H then L(H') is the canonical stretching of v in G.

Proof. Let $e = u_1u_2$ be a simple edge of H and H' be the graph obtained from H by replacing e by the path u_1, u'_1, u'_2, u_2 .

The line graph L(H') contains a node v_1 representing the edge u_1u_1' of H', a node w corresponding to the edge $u_1'u_2'$ of H', and a node v_2 for the edge $u_2'u_2$ of H'.

In L(H'), v_1 is adjacent to w and to a clique U_1 corresponding to all edges different from $u_1u'_1$ incident to u_1 , w has only v_1 and v_2 as neighbors, and v_2 is adjacent to w and to a clique U_2 corresponding to all edges different from u'_2u_2 incident to u_2 .

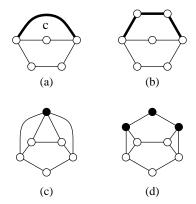


Figure 4: This Figure shows (a) the graph $C_5 + c$ (a 5-hole with one chord c), (b) the graph $C_5 + E_3$ (obtained from $C_5 + c$ by a 3-subdivision of c), (c) the line graph $L(C_5 + c)$, and (d) the line graph $L(C_5 + E_3)$, where $L(C_5 + E_3)$ results from $L(C_5 + c)$ by a canonical stretching of the (black-filled) node corresponding to c.

All other nodes and adjacencies in L(H') are as in L(H), hence L(H') corresponds exactly to the graph obtained from L(H) by the canonical stretching of the node v representing the edge e.

This enables us to show:

Theorem 3. A line graph L(H) is N_+ -imperfect if H is

- an odd hole with one double edge;
- an odd hole with one chord;
- an odd hole with one odd path attached to non-adjacent nodes of the hole.

Proof. Let $C_{2k+1} + d$ (resp. $C_{2k+1} + c$, resp. $C_{2k+1} + E_{\ell}$) denote the graph obtained from an odd hole C_{2k+1} with $k \geq 2$ by adding one edge d parallel to an edge of the hole (resp. adding one chord c to the hole, resp. attaching one path of length ℓ to two non-adjacent nodes of the hole).

To establish the N_+ -imperfection of the three families, we first observe that the two minimally N_+ -imperfect graphs G_{LT} and G_{EMN} are line graphs: indeed, we have $G_{LT} = L(C_5 + d)$ and $G_{EMN} = L(C_5 + c)$.

Clearly, the graph $C_{2k+3} + d$ can be obtained from $C_{2k+1} + d$ by 3-subdivision of a simple edge (not being parallel to d) of the hole. Thus, any

odd hole with one double edge can be obtained from $C_5 + d$ by repeated 3-subdivisions of simple edges.

According to Lemma 2, their line graphs are obtained by repeated canonical stretchings of G_{LT} , which yields the first studied family of graphs.

Analogously, $C_{2k+3} + c$ can be obtained from $C_{2k+1} + c$ by 3-subdivision of an edge of the hole. Thus, any odd hole with one chord can be obtained from $C_5 + c$ by repeated 3-subdivisions of edges different from c. Moreover, applying repeated 3-subdivisions of the chord c yields graphs $C_{2k+1} + E_{\ell}$ where E_{ℓ} is a path of arbitrary odd length ℓ attached to two non-adjacent nodes of the hole at arbitrary distance.

According to Lemma 2, their line graphs are obtained by repeated canonical stretchings of G_{EMN} , which yields the two remaining families of graphs.

That G_{LT} and G_{EMN} are minimally N_+ -imperfect and canonical stretchings preserve N_+ -imperfection completes the proof.

3 Characterizing N_{+} -perfect line graphs

A combination of results by Edmods [8] and Edmonds & Pulleyblank [9] about the matching polytope implies the following description of the stable set polytope of line graphs.

Theorem 4 (Edmods [8], Edmonds & Pulleyblank [9]). If G is the line graph of a graph H, then STAB(G) is described by nonnegativity constraints, maximal clique constraints, and rank constraints

$$x(L(H')) \le \frac{|V(H')| - 1}{2}$$
 (3)

associated with the line graphs of 2-connected hypomatchable induced subgraphs $H' \subseteq H$.

A graph H is *hypomatchable* if, for all nodes v of H, the subgraph H-v admits a perfect matching (i.e., a matching meeting all nodes) and is 2-connected if it remains connected after removing an arbitrary node.

Due to a result by Lovász [15], a graph H is hypomatchable if and only if there is a sequence $H_0, H_1, \ldots, H_k = H$ of graphs such that H_0 is a chordless odd cycle, and for $1 \le i \le k$, H_i is obtained from H_{i-1} by adding an odd path E_i that joins two (not necessarily distinct) nodes of H_{i-1} and has all internal nodes outside H_{i-1} . The odd paths $E_i = H_i - H_{i-1}$ are called ears for $1 \le i \le k$ and the sequence $H_0, H_1, \ldots, H_k = H$ an ear decomposition of H, see Fig. 5 for illustration. Moreover, we call an ear of length at least three long, and short otherwise.

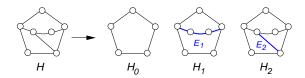


Figure 5: A graph and an ear decomposition.

Hypomatchable graphs have an odd number of nodes, are non-bipartite and connected, but neither necessarily 2-connected (since an ear E_i may be attached to a single node of H_{i-1}) nor simple (since a short ear E_i may become an edge parallel to one edge of H_{i-1}).

However, if H is 2-connected, Cornuéjols & Pulleyblank [6] proved that H admits an ear decomposition $H_0, H_1, \ldots, H_k = H$ with H_i 2-connected for every $0 \le i \le k$. If, in addition, H has at least five nodes, Wagler [20] later proved that H admits an ear decomposition $H_0, H_1, \ldots, H_k = H$ where H_0 has at least five nodes and H_i is 2-connected for every $0 \le i \le k$.

Since the latter result is a key property for our argumentation, we give its proof for the sake of completeness:

Lemma 5 (Wagler [20]). Let H be a 2-connected hypomatchable graph and $|V(H)| \geq 5$. Then there is an ear decomposition $H_0, H_1, \ldots, H_k = H$ of H such that each H_i is 2-connected and H_0 is an odd cycle of length at least five.

Proof. Since H is 2-connected, it admits an ear decomposition $H_0, H_1, \ldots, H_k = H$ with H_i 2-connected for $0 \le i \le k$ by [6]. We are ready if H_0 is an odd cycle of length ≥ 5 , hence assume, for the sake of contradiction, that H_0 is a triangle.

From |V(H)| > 3 follows that there is an ear with at least three edges. Let $i \in \{1, ..., k\}$ be the smallest index such that E_i has length ≥ 3 . Then $V(H_{i-1}) = V(H_0)$ holds and E_i has two distinct nodes $v, v' \in V(H_0)$ as endnodes (since H_i is 2-connected). Hence $(H_0 - vv') \cup E_i, vv', E_1, ..., E_{i-1}$ is an ear decomposition of H_i starting with an odd cycle of length ≥ 5 and defining only 2-connected intermediate graphs. The ears $E_{i+1}, ..., E_k$ complete this ear decomposition to the studied decomposition of H.

With the help of these results, we can give the following characterization of 2-connected hypomatchable graphs:

Theorem 6. If H is a 2-connected hypomatchable graph, then exactly one of the following conditions is true:

- *H* has only three nodes;
- H equals an odd hole;
- H contains one of the following subgraphs:
 - an odd hole with one double edge;
 - an odd hole with one chord;
 - an odd hole with one long ear, attached to non-adjacent nodes of the hole.

Proof. Consider a 2-connected hypomatchable graph H and distinguish the following cases.

If H has more than three nodes, then H admits an ear decomposition $H_0, H_1, \ldots, H_k = H$ where H_0 has at least five nodes and H_i is 2-connected for every $0 \le i \le k$ by Wagler [20].

If $H = H_0$, then H equals an odd hole.

If $H \neq H_0$, then H_1 equals one of the above mentioned graphs:

- an odd hole with one double edge (if E_1 is a short ear attached to adjacent nodes of H_0);
- an odd hole with one chord (if E_1 is a short ear attached to non-adjacent nodes of H_0 or if E_1 is a long ear attached to adjacent nodes of H_0);
- an odd hole with one long ear E_1 , attached to non-adjacent nodes of H_0 (otherwise).

(Recall that E_1 cannot be attached to a single node of H_0 since H_1 is 2-connected.)

Combining Theorem 6 and Theorem 3, we can further prove:

Lemma 7. If H is a 2-connected hypomatchable graph, then L(H) is either a clique, an odd hole, or N_+ -imperfect.

Proof. Consider a 2-connected hypomatchable graph H and distinguish the following cases.

If H has only three nodes, then H has an ear decomposition $H_0, H_1, \ldots, H_k = H$ where H_0 is a triangle and all ears are short, becoming edges parallel to one edge of H_0 . In this case, L(H) is clearly a clique.

If H has more than three nodes, then H admits an ear decomposition $H_0, H_1, \ldots, H_k = H$ where H_0 is an odd hole with at least five nodes and H_i is 2-connected for every $0 \le i \le k$ by Wagler [20].

If $H = H_0$, then H equals an odd hole and L(H) is clearly an odd hole, too.

If $H \neq H_0$, then H_1 equals one of the graphs from proof of Theorem 6:

- an odd hole with one double edge;
- an odd hole with one chord;
- an odd hole with one long ear, attached to non-adjacent nodes of H_0 .

According to Theorem 3, the line graph $L(H_1)$ is N_+ -imperfect, hence L(H) is N_+ -imperfect.

Combining Lemma 7 and the description of stable set polytopes of line graphs from Theorem 4 further yields the following characterization of N_{+} -perfect line graphs.

Theorem 8. A line graph L(H) is N_+ -perfect if and only if all 2-connected hypomatchable induced subgraphs $H' \subseteq H$ either have only three nodes or are odd holes.

Thus, the definition of h-perfect graphs finally implies the following characterization of N_+ -perfect line graphs:

Corollary 9. A line graph is N_+ -perfect if and only if it is h-perfect.

Since both the class of line graphs and the class of N_+ -perfect graphs are hereditary (i.e., closed under taking induced subgraphs), we can derive from a characterization of N_+ -perfect line graphs also a characterization of minimally N_+ -imperfect line graphs.

In fact, combining the assertions from Theorem 3, Theorem 4 by Edmonds [8] and Edmonds & Pulleyblank [9], Theorem 6 and Theorem 8, lead to the following characterization of minimally N_{+} -imperfect line graphs.

Corollary 10. A line graph L(H) is minimally N_+ -imperfect if and only if H is an odd hole with one ear attached to distinct nodes of the hole.

Proof. On the one hand, each of the line graphs L(H) with $H \in \{C_{2k+1} + d, C_{2k+1} + c, C_{2k+1} + E_{\ell}\}$ from Theorem 3 has, by construction, the property that H is a 2-connected hypomatchable graph and admits an ear decomposition $H_0, H_1 = H$ with $H_0 = C_{2k+1}, k \geq 2$.

Removing any edge e from H yields a graph H-e which is either an odd hole (if $e \in \{c,d\}$) or else not hypomatchable anymore. In all cases, H-e is bipartite or contains at most one odd cycle so that L(H-e) has cliques and odd holes as only facet-defining subgraphs.

Hence, L(H) is N_+ -imperfect by Theorem 3, but all proper induced subgraphs are h-perfect (and, thus, N_+ -perfect). This implies that L(H) is minimally N_+ -imperfect for all graphs within the 3 studied families.

On the other hand, any minimally N_+ -imperfect graph needs to have a full-support facet. Thus, any minimally N_+ -imperfect line graph L(H) is the line graph of a 2-connected hypomatchable graph H (by Theorem 4) which has more than 3 nodes and is different from an odd hole (by Theorem 6).

Then H admits an ear decomposition $H_0, H_1, \ldots, H_k = H$ with $k \geq 1$ where H_0 has at least five nodes and H_i is 2-connected for every $0 \leq i \leq k$ by Wagler [20].

In fact, $H_1 \in \{C_{2k+1} + d, C_{2k+1} + c, C_{2k+1} + E_{\ell}\}$ then $L(H_1)$ is N_+ -imperfect by Theorem 3. Also, since $L(H_1)$ is a node induced subgraph of L(H) and L(H) is minimally N_+ -imperfect, it holds that $L(H) = L(H_1)$.

Finally, H_1 has the stated property: it is an odd hole H_0 with one ear attached to distinct nodes of H_0 .

4 Conclusion and further results

In this contribution, we addressed the problem of verifying Conjecture 1 for line graphs. For that, we presented three infinite families of N_+ -imperfect line graphs (Section 2) and showed that all facet-defining subgraphs of a line graph different from cliques and odd holes contain one of these N_+ -imperfect line graphs (Section 3). Since cliques and odd holes are clearly near-bipartite, Corollary 9 shows that Conjecture 1 is true for line graphs.

In the following, we will discuss a reformulation of Conjecture 1.

As superclass of a-perfect graphs, joined a-perfect graphs were introduced in [7] as those graphs whose only facet-defining subgraphs are complete joins of a clique and prime antiwebs (an antiweb A_n^k is prime if k+1 and n are relatively prime integers). The inequalities obtained from complete joins of antiwebs, called joined antiweb constraints, are of the form

$$\sum_{i \le k} \frac{1}{\alpha(A_i)} x(A_i) + x(Q) \le 1,$$

where A_1, \ldots, A_k are different antiwebs and Q is a clique (note that the

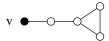


Figure 6: A perfect (and, thus, joined a-perfect) graph with a node v such that removing v and its neighbor(s) leaves a non-bipartite graph.

inequalities are scaled to have the right hand side equal to 1). We denote by $ASTAB^*(G)$ the linear relaxation of STAB(G) obtained by all joined antiweb constraints. Then, a graph G is joined a-perfect if STAB(G) equals $ASTAB^*(G)$.

In particular, Shepherd [19] showed that the stable set polytope of a near-bipartite graph has only facet-defining inequalities associated with complete joins of a clique and prime antiwebs. Thus, every near-bipartite graph is joined a-perfect (but the converse is not true since there exist perfect graphs that are not near-bipartite, see Figure 6 for an example).

Moreover, Conjecture 1 identifies N_+ -perfect graphs and graphs for which its stable set polytope can be described by inequalities with near-bipartite support. It is known that, given a graph G, every facet defining inequality of STAB(G) with support graph G' is a facet defining inequality of STAB(G'). Then, again by Shepherd's results [19], those graphs for which its stable set polytope can be described by inequalities with near-bipartite support are joined a-perfect graphs.

Taking this into account, Conjecture 1 can be reformulated as follows:

Conjecture 11. Every N_+ -perfect graph is joined a-perfect.

The results of Lovász and Schrijver [17] prove that joined a-perfect graphs are N_+ -perfect, thus, the conjecture states that both graph classes coincide and that $ASTAB^*(G)$ shall be the studied polyhedral relaxation P(G) of STAB(G) in (2).

In particular, in this paper we have proved that every N_+ -perfect line graph is h-perfect. Then, combining these results, we obtain that a line graph is joined a-perfect if and only if it is h-perfect. However, it seems natural to look for a proof of the latter result independent of the N_+ -operator.

Theorem 12. A line graph is joined a-perfect if and only if it is h-perfect.

Proof. A joined a-perfect graph has as only facet-defining subgraphs complete joins of a clique and prime antiwebs.

Following the same argumentation as in [19] that odd antiholes are the only prime antiwebs in complements of line graphs, we see that odd holes are the only prime antiwebs in line graphs.

Analogous arguments as in [21, 22] yield that in a line graph, no complete join of a clique and odd holes or of two or more odd holes can occur: every such complete join would particularly contain an odd wheel W_{2k+1} , i.e., the complete join of a single node and an odd hole C_{2k+1} .

The W_5 is one of the minimal forbidden subgraphs of line graphs by Beineke [1], larger odd wheels contain a claw, another minimal forbidden subgraph of line graphs by [1].

Thus, the only remaining facet-defining subgraphs in a joined a-perfect line graph are cliques and odd holes.

Conversely, an h-perfect line graph is clearly joined a-perfect. \Box

Our future lines of further research include

- to look for new families of graphs where the conjecture holds (e.g., by characterizing the minimally N_+ -imperfect graphs within the class);
- to find new subclasses of N_{+} -perfect or joined a-perfect graphs.

In all cases, the structural results would have algorithmic consequences since the stable set problem could be solved in polynomial time for the whole class or its intersection with N_+ -perfect or joined a-perfect graphs by optimizing over $N_+(G)$.

Acknowledgment

This work was supported by an ECOS-MINCyT cooperation France-Argentina, A12E01, PIP-CONICET 0241, PICT-ANPCyT 0361, PID-UNR 415 and 416.

References

- [1] Beineke L.W. (1968). Derived graphs and digraphs, In: Beiträge zur Graphentheorie, H. Sachs, H. Voss und H. Walther (Hrg.), Teubner Verlag, Leipzig, 17–33.
- [2] Bianchi S. M., Escalante M. S., Nasini G. L., Tunçel L. (2011). Near-perfect graphs with polyhedral $N_{+}(G)$, Electronic Notes in Discrete Mathematics 37, 393–398.

- [3] Bianchi S., Escalante M., Nasini G., Tunçel L. (2013). Lovász-Schrijver SDP-operator and a superclass of near-perfect graphs, *Electronic Notes in Discrete Mathematics* 44, 339–344.
- [4] Chudnovsky M., Robertson N., Seymour P., Thomas R. (2006). The Strong Perfect Graph Theorem, *Annals of Mathematics* 164, 51–229.
- [5] Chvátal V. (1975). On Certain Polytopes Associated with Graphs, J. Combin. Theory (B) 18, 138–154.
- [6] Cornuéjols G., Pulleyblank W.R. (1983). Critical Graphs, Matchings, and Tours or a Hierarchy of Relaxations for the Traveling Salesman Problem, *Combinatorica* 3, 35–52.
- [7] Coulonges S., Pêcher A., Wagler A. (2009). Characterizing and bounding the imperfection ratio for some classes of graphs, *Mathematical Programming A* 118, 37–46.
- [8] Edmonds J.R. (1965). Maximum Matching and a Polyhedron with 0, 1-Vertices, J. Res. Nat. Bur. Standards, vol. 69B, 125–130.
- [9] Edmonds J.R., Pulleyblank W.R. (1974) Facets of 1-Matching Polyhedra, In: C. Berge and D.R. Chuadhuri (eds.) *Hypergraph Seminar*. Springer, 214–242.
- [10] Escalante M. S., Montelar M.S., Nasini G. L. (2006). Minimal N_+ -rank graphs: Progress on Lipták and Tunçel's conjecture, *Operations Research Letters* 34, 639–646.
- [11] Escalante M., Nasini G. (2014). Lovász and Schrijver N_+ -relaxation on web graphs, Lecture Notes in Computer Science 8596, 221–229.
- [12] Grötschel M., Lovász L., Schrijver A. (1981). The Ellipsoid Method and its Consequences in Combinatorial Optimization, *Combinatorica* 1, 169–197.
- [13] Grötschel M., Lovász L., Schrijver A. (1988). Geometric Algorithms and Combinatorial Optimization. Springer-Verlag.
- [14] Lipták L., Tunçel L. (2003). The Stable set problem and the lift-and-project ranks of graphs, *Math. Programming B* 98, 319–353.
- [15] Lovász L. (1972). A Note on Factor-critical Graphs, Studia Sci. Math. Hungar. 7, 279–280.

- [16] Lovász L. (1979). On the Shannon capacity of a graph, *IEEE Transactions on Information Theory* 25, 1–7.
- [17] Lovász L., Schrijver A. (1991). Cones of matrices and set-functions and 0-1 optimization, SIAM J. on Optimization 1, 166–190.
- [18] Shepherd F.B. (1994). Near-Perfect Matrices, *Math. Programming* 64, 295–323.
- [19] Shepherd F.B. (1995) Applying Lehman's Theorems to Packing Problems, *Math. Programming* 71, 353–367.
- [20] Wagler A. (2000). Critical Edges in Perfect Graphs. *PhD thesis*, *TU Berlin and Cuvillier Verlag Göttingen*.
- [21] Wagler A.(2004). Antiwebs are rank-perfect, 4OR 2, 149–152.
- [22] Wagler A.(2005). On rank-perfect subclasses of near-bipartite graphs, 4OR 3, 329–336.