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► **To cite this version:**

Annalisa Baldi, Bruno Franchi, Pierre Pansu. L^1 -Poincaré inequalities for differential forms on Euclidean spaces and Heisenberg groups. 2019. hal-02015047

HAL Id: hal-02015047

<https://hal.science/hal-02015047>

Preprint submitted on 11 Feb 2019

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L^1 -POINCARÉ INEQUALITIES FOR DIFFERENTIAL FORMS ON EUCLIDEAN SPACES AND HEISENBERG GROUPS

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ABSTRACT. In this paper, we prove interior Poincaré and Sobolev inequalities in Euclidean spaces and in Heisenberg groups, in the limiting case where the exterior (resp. Rumin) differential of a differential form is measured in L^1 norm. Unlike for L^p , $p > 1$, the estimates are doomed to fail in top degree. The singular integral estimates are replaced with inequalities which go back to Bourgain-Brezis in Euclidean spaces, and to Chanillo-van Schaftingen in Heisenberg groups.

1. INTRODUCTION

1.1. **L^1 -Sobolev and Poincaré inequalities.** The well known Sobolev inequalities on \mathbb{R}^n states that for every $1 \leq p < n$, there exists a constant $C(n, p)$ such that all smooth compactly supported functions u on \mathbb{R}^n satisfy

$$\|u\|_q \leq C(n, p) \|\nabla u\|_p \quad \text{provided} \quad \frac{1}{p} - \frac{1}{q} = \frac{1}{n} \quad (p\text{-Sobolev}).$$

The most important of these inequalities is (1-Sobolev) . Indeed, (1-Sobolev) implies all inequalities $(p\text{-Sobolev})$, $p < n$. Furthermore, (1-Sobolev) is equivalent to the isoperimetric inequality for smooth bounded domains A of \mathbb{R}^n (Federer-Fleming's theorem, [15]),

$$\text{volume}(A)^{(n-1)/n} \leq C(n, 1) \text{area}(\partial A),$$

(with the same constant). Similarly, for noncompactly supported functions, a Poincaré inequality holds for $1 \leq p < n$: there exists a constant c_u such that

$$\|u - c_u\|_q \leq C(n, p) \|\nabla u\|_p \quad \text{provided} \quad \frac{1}{p} - \frac{1}{q} = \frac{1}{n} \quad (p\text{-Poincaré}).$$

We investigate generalizations of these inequalities to differential forms. More precisely, we ask whether, given a closed differential h -form ω in $L^p(\mathbb{R}^n)$, there exists an $(h-1)$ -form ϕ in $L^q(\mathbb{R}^n)$ with $\frac{1}{p} - \frac{1}{q} = \frac{1}{n}$ such that $d\phi = \omega$ and

$$\|\phi\|_q \leq C(n, p, h) \|\omega\|_p.$$

If $p > 1$, the easy proof consists in putting $\phi = d^* \Delta^{-1} \omega$. Here, Δ^{-1} denotes the inverse of the Hodge Laplacian $\Delta = d^* d + d d^*$ and d^* is the formal L^2 -adjoint of d . The operator $d^* \Delta^{-1}$ is given by convolution with a homogeneous kernel of type 1 in the terminology of [16] and [17], hence it is bounded from L^p to L^q if $p > 1$.

1991 *Mathematics Subject Classification.* 58A10, 35R03, 26D15, 43A80, 46E35, 35F35.

Key words and phrases. Heisenberg groups, differential forms, Sobolev-Poincaré inequalities, contact manifolds, homotopy formula.

Unfortunately, this argument does not suffice for $p = 1$ since, by [17], Theorem 6.10, $d^* \Delta^{-1}$ maps L^1 only into the weak Marcinkiewicz space $L^{n/(n-1), \infty}$. Upgrading from $L^{n/(n-1), \infty}$ to $L^{n/(n-1)}$ is possible for functions. Indeed, for characteristic functions of sets, the $L^{n/(n-1), \infty}$ and $L^{n/(n-1)}$ norms coincide, and every function is the sum of characteristic functions of its superlevel sets (see [27], [18], [19]).

This trick does not seem to generalize to differential forms.

Note that locally, $d^* \Delta^{-1}$ maps L^1 to L^q for all $q < n/(n-1)$, but this does not lead to a scale invariant inequality.

1.2. Analysis of L^1 -differential forms. In fact, (1-Poincaré) fails in degree n . There is an obvious obstruction: n -forms belonging to L^1 and with nonvanishing integral cannot be differentials of $L^{n/(n-1)}$ forms, see [43]. But even if integral vanishes, a primitive ϕ such that $\|\phi\|_q \leq C \|\omega\|_1$ need not exist, with $1 - \frac{1}{q} = \frac{1}{n}$. Indeed, if so, then, for every smooth function u on \mathbb{R}^n , one could write, for every n -form $\omega \in L^1$ with vanishing integral,

$$\left| \int u \omega \right| = \left| \int u d\phi \right| = |du \wedge \phi| \leq \|du\|_n \|\phi\|_q \leq C \|du\|_n \|\omega\|_1,$$

which would imply (by Hahn-Banach theorem) the existence of a constant c_u such that $\|u - c_u\|_\infty \leq C \|du\|_n$. Such a (*n-Sobolev*) inequality does not hold, since \mathbb{R}^n is n -parabolic, i.e. for every compact subset K and every $\epsilon > 0$, there exists a smooth compactly supported function χ on \mathbb{R}^n such that $\chi \geq 1$ on K and $\int_{\mathbb{R}^n} |d\chi|^n < \epsilon$, (see [14] Section 4.7).

Surprisingly, Poincaré and Sobolev inequalities persist sometimes for $p = 1$. The first result appeared in [10], whose Theorem 2 states that, if \vec{f} is a divergence free vectorfield in $L^1(\mathbb{R}^n)$, then the solution of $\Delta \vec{u} = \vec{f}$ satisfies $\nabla \vec{u} \in L^{n/(n-1)}$. In differential form notation, this means that $\nabla \Delta^{-1}$ restricted to closed $(n-1)$ -forms is bounded from L^1 to $L^{n/(n-1)}$. *A fortiori*, so is $d^* \Delta^{-1}$, this proves (1-Poincaré) in degree $n-1$.

1.3. Results. In this paper, we prove (1-Poincaré) for h -forms of degree $h < n$ in de Rham's complex (Ω^\bullet, d) . We rely on Lanzani-Stein's observation (see [26]) that the duality estimate (emphasized by van Schaftingen [44]) underlying Bourgain-Brezis' result descends from $(n-1)$ -forms to forms of lower degree, and the resulting Gagliardo-Nirenberg inequalities.

Remarkably, this approach generalizes to the non-commutative Heisenberg groups \mathbb{H}^n equipped with Rumin's complex (E_0^\bullet, d_c) . Indeed, when passing to Heisenberg groups, we can use Lanzani-Stein's type arguments proved in [2], [5]. Precise definitions of Heisenberg groups and related properties as well as of Rumin's complex, can be found in Section 4.

In the Euclidean setting, the integral obstruction generalizes to forms in every degree: if a closed L^1 -form ω is the differential of a form in $L^{n/(n-1)}(\mathbb{R}^n)$, then for every constant coefficient form β of complementary degree, $\int \omega \wedge \beta = 0$. Therefore we introduce the subspace L_0^1 of L^1 -differential forms satisfying these conditions (we call them forms *with vanishing averages*). In Heisenberg groups, constant coefficient forms must be replaced with left-invariant Rumin forms.

We can state our main results. We stress that, in (1) below we are dealing with usual de Rham forms, whereas in (2) we are dealing with Rumin's complex.

Theorem 1.1 (Global Poincaré and Sobolev inequalities). *We have:*

- (1) *Euclidean case* \mathbb{R}^n . Let $h = 1, \dots, n-1$ and set $q = n/(n-1)$. For every closed h -form $\alpha \in L^1_0(\mathbb{R}^n)$, there exists an $(h-1)$ -form $\phi \in L^q(\mathbb{R}^n)$, such that

$$d\phi = \alpha \quad \text{and} \quad \|\phi\|_q \leq C \|\alpha\|_1.$$

- (2) *Heisenberg case* $\mathbb{H}^n \equiv \mathbb{R}^{2n+1}$. Let $h = 1, \dots, 2n$ and set $q = (2n+2)/(2n+1)$ if $h \neq n+1$ and $q = (2n+2)/(2n)$ if $h = n+1$. For every d_c -closed h -form $\alpha \in L^1_0(\mathbb{H}^n)$, there exists an $(h-1)$ -form $\phi \in L^q(\mathbb{H}^n)$, such that

$$d_c\phi = \alpha \quad \text{and} \quad \|\phi\|_q \leq C \|\alpha\|_1.$$

Furthermore, in both cases, if α is compactly supported, so is ϕ .

We also prove local versions of these inequalities, of the following types (see Corollary 6.5).

Theorem 1.2. (1) *Euclidean case.* For $h = 1, \dots, n-1$, let $q = n/(n-1)$. For every $\lambda > 1$, there exists C with the following property. Let $B(R)$ be a ball of radius R in \mathbb{R}^n .

- (a) *Interior Poincaré inequality:* for every closed h -form $\alpha \in L^1(B(\lambda R))$, there exists an $(h-1)$ -form $\phi \in L^q(B(R))$, such that

$$d\phi = \alpha|_{B(R)} \quad \text{and} \quad \|\phi\|_{L^q(B(R))} \leq C \|\alpha\|_{L^1(B(\lambda R))}.$$

- (b) *Sobolev inequality:* for every closed h -form $\alpha \in L^1$ with support in $B(R)$, there exists an $(h-1)$ -form $\phi \in L^q$, with support in $B(\lambda R)$, such that

$$d\phi = \alpha \quad \text{and} \quad \|\phi\|_{L^q(B(\lambda R))} \leq C \|\alpha\|_{L^1(B(R))}.$$

- (2) *Heisenberg case:* for $h = 1, \dots, 2n$, let $q = (2n+2)/(2n+1)$ if $h \neq n+1$ and $q = (2n+2)/(2n)$ if $h = n+1$. There exist $\lambda > 1$ and C with the following property. Let $B(R)$ be a ball of radius R in \mathbb{H}^n .

- (a) *Interior Poincaré inequality.* For every d_c -closed Rumin h -form $\alpha \in L^1(B(\lambda R))$, there exists an $(h-1)$ -form $\phi \in L^q(B(R))$, such that

$$d_c\phi = \alpha|_{B(R)} \quad \text{and} \quad \|\phi\|_{L^q(B(R))} \leq C \|\alpha\|_{L^1(B(\lambda R))}.$$

- (b) *Sobolev inequality:* for every d_c -closed Rumin h -form $\alpha \in L^1$ with support in $B(R)$, there exists an $(h-1)$ -form $\phi \in L^q$, with support in $B(\lambda R)$, such that

$$d_c\phi = \alpha \quad \text{and} \quad \|\phi\|_{L^q(B(\lambda R))} \leq C \|\alpha\|_{L^1(B(R))}.$$

Finally, we construct smoothing homotopies on Riemannian or contact subRiemannian manifolds of bounded geometry (see [13], Proposition 1, p. 77). Roughly speaking, a Riemannian manifold has C^k -bounded geometry if it admits an atlas of charts defined on the unit Euclidean ball, with uniformly bounded Lipschitz constant, and such that changes of charts have uniformly bounded derivatives up to order k . In the contact subRiemannian case, the models are unit Heisenberg balls, the charts are assumed to be contactomorphisms and only horizontal derivatives play a role. Details appear in Definition 7.1.

Theorem 1.3. (1) *Riemannian case:* let M be a Riemannian manifold of dimension $2n+1$ and bounded C^k -geometry, where k is an integer, $k \geq 2$. For $h = 1, \dots, n-1$, let $q = n/(n-1)$. Let $1 \leq q' \leq q$. There exist operators S and T on h -forms on M such that S is bounded from L^1 to

$W^{k-1,q'}$, T is bounded from $L^1 \cap d^{-1}L^1$ to $L^{q'}$, and the homotopy identity $1 = S + dT + Td$ holds on $L^1 \cap d^{-1}L^1$.

- (2) *SubRiemannian contact case:* let M be a subRiemannian contact manifold of dimension $2n+1$ and bounded C^k -geometry, where k is an integer, $k \geq 3$. For $h = 1, \dots, 2n$, let $q = (2n+2)/(2n+1)$ if $h \neq n+1$ and $q = (2n+2)/(2n)$ if $h = n+1$. Let $1 \leq q' \leq q$. There exist operators S and T on h -forms on M such that S is bounded from L^1 to $W^{k-1,q'}$, T is bounded from $L^1 \cap d^{-1}L^1$ to $L^{q'}$, and the homotopy identity $1 = S + d_c T + T d_c$ holds on $L^1 \cap d_c^{-1}L^1$. Furthermore, in degree $h = n+1$, T is bounded from $W^{j-1,1}$ to $W^{j,1}$ for all $1 \leq j \leq k-1$.

Such local Poincaré inequalities and smoothing homotopies are the necessary ingredients in order to prove that Rumin's complex can be used to compute the $\ell^{q,1}$ -cohomology of a subRiemannian contact manifold, see [37]. Therefore Theorem 1.1 has significance in geometric group theory, see Corollary 8.2.

This paper is organised as follows: in Section 2 we provide a sketch of the proof of Theorems 1.1 and 6.5. Section 3 deals with continuity properties of homogeneous kernels in Carnot groups and with function spaces. Most of the results are more or less known, except, as long as we know, for Theorem 3.13. Preliminary results on Heisenberg groups, Rumin's complex and Laplacians are gathered in Section 4. The proof of Theorem 1.1 is contained in Section 5 and relies on Gagliardo-Nirenberg type inequalities proved therein, and interior inequalities stated in Theorem 6.5 are proved in Section 6 via suitable smoothing homotopy formulas. Finally, Sections 7 and 8 deal with Riemannian and contact manifolds with bounded geometry.

2. SCHEME OF PROOF

In this Section we sketch the proof of Theorems with more details in the Euclidean case, whereas the body of this paper will contain only the proofs for differential forms in Heisenberg groups which require several further arguments.

2.1. Euclidean case. Let $q = n/(n-1)$. According to Lanzani-Stein, in degrees $< n$, for smooth compactly supported forms u ,

$$(1) \quad \|u\|_q \leq C (\|du\|_1 + \|d^*u\|_N),$$

where $\|\cdot\|_N$ denotes either L^1 -norm (in degrees $\neq 1$) or the norm of the real Hardy space \mathcal{H}^1 (in degree 1). Since the inverse of the Laplacian, Δ^{-1} , commutes with d , the operator $K = d^* \Delta^{-1}$ satisfies $dK + Kd = 1$ on smooth compactly supported forms. Given a closed form $\alpha \in L^1(\mathbb{R}^n)$, $u = K\alpha$ is not compactly supported, so cannot be directly plugged in (1). Therefore we use a smooth cut-off function χ and put

$$\phi = d^*(\chi \Delta^{-1} \alpha).$$

Then ϕ has compact support, $d^*\phi = 0$ and

$$d\phi = [dd^*, \chi] \Delta^{-1} \alpha + \chi dd^* \Delta^{-1} \alpha = [dd^*, \chi] \Delta^{-1} \alpha + \chi \alpha.$$

The point is to estimate the garbage term $\|[dd^*, \chi] \Delta^{-1} \alpha\|_1$. Notice that $[dd^*, \chi]$ is a first order differential operator, of the form $[dd^*, \chi] = P_0 + P_1$ where P_0 has order 0 and depends on second derivatives $\nabla^2 \chi$ and P_1 has order 1 and depends on first derivatives $\nabla \chi$ only. Both $P_0 \Delta^{-1}$ and $P_1 \Delta^{-1}$ have homogeneous kernels.

Here comes our key trick. If P is the operator of convolution with a kernel of type $\mu > 0$, and $\alpha \in L^1$, then the L^1 norm of $P\alpha$ on shells $B(0, 2R) \setminus B(0, R)$ is $O(R^\mu)$. If furthermore $\alpha \in L^1_0$, this can be improved to $o(R^\mu)$.

Pick $\chi = \chi_R$ such that $d\chi_R$ is supported in the shell $B(0, 2R) \setminus B(0, R)$, $|\nabla\chi_R| \leq \frac{1}{R}$ and $|\nabla^2\chi_R| \leq \frac{1}{R^2}$. Then $\|P_0\Delta^{-1}\alpha\|_1$ and $\|P_1\Delta^{-1}\alpha\|_1$ tend to 0 as $R \rightarrow \infty$. Then $\|\phi\|_q$ stays uniformly bounded, yielding eventually that $d^*\Delta^{-1}\alpha \in L^q$, thanks to Fatou's theorem.

The local Poincaré inequality is based on Iwaniec-Lutoborsky's homotopy, [25]. This homotopy is defined by a kernel k which belongs to L^q in a neighborhood of the origin, for every $q < n/(n-1)$, but not for $q = n/(n-1)$. Fortunately, Young's inequality suffices to prove that a truncation of k maps L^1 to L^1 . This provides an L^1 local primitive for a closed form, up to a smoothed closed form, which belongs to $W^{1,1}$. The L^1 primitive is upgraded to $L^{n/(n-1)}$ using a cut-off and Theorem 1.1. To the smoothed form, one can again apply Iwaniec-Lutoborsky's homotopy, which yields a form in $W^{1,1}$. The Sobolev embedding $W^{1,1} \subset L^{n/(n-1)}$ concludes the argument.

For further details in the Euclidean case, we refer to [4].

2.2. Heisenberg case. We use Rumin's Laplacian $\Delta_{\mathbb{H}}$ on Rumin forms. It does not quite commute with Rumin's differential d_c in degrees $n-1$ and $n+2$ but this turns out to be harmless. Write $K = d_c^*\Delta_{\mathbb{H}}^{-1}$ (with a modification in degrees n and $n+1$), in order that $d_cK + Kd_c = 1$ on smooth compactly supported forms. In spite of the complicated form of Leibniz' formula for d_c , the basic features of commutators $[d_c d_c^*, \chi]\Delta_{\mathbb{H}}^{-1}$ from the Euclidean case persist.

The local Poincaré inequality requires special care in the Heisenberg case, since no analogue of Iwaniec-Lutoborsky's homotopy exists. The kernel of $K = d_c^*\Delta_{\mathbb{H}}^{-1}$ is a valuable replacement. This provides again a L^1 local primitive for a d_c -closed form, up to a smoothed d_c -closed form, which belongs to $W^{3,1}$. The L^1 primitive is upgraded to L^q using a cut-off and Theorem 1.1 in the same manner. To the smoothed form, one can apply Rumin's homotopy, yielding a $W^{2,1}$ d_c -closed form, and then Iwaniec-Lutoborsky's Euclidean homotopy. The resulting form belongs to L^q , with $q = (2n+2)/(2n+1)$ if $h \neq n+1$ and $q = (2n+2)/(2n)$ if $h = n+1$, again by Sobolev embedding.

2.3. Gaffney type inequality in Euclidean spaces. If $p > 1$, an alternative route to Poincaré's inequality could be to first establish a Gaffney type inequality: for every differential form ϕ such that $d\phi$ and $\delta\phi \in L^p$,

$$\|\nabla\phi\|_p \leq C (\|d\phi\|_p + \|\delta\phi\|_p).$$

Combined with (p -Poincaré) inequality for functions, $\|\phi - c_\phi\|_{np/(n-p)} \leq C \|\nabla\phi\|_p$, this implies (p -Poincaré) for forms. Unfortunately, if $p = 1$, Gaffney's inequality trivially holds for forms of degree 0, but fails in every degree ≥ 1 . This follows from Ornstein's non-inequality, [36]. Indeed, in degrees ≥ 1 , $\nabla\phi = \delta\phi + d\phi + R\phi$, where all three components constitute a linearly independent collection of linear first order constant coefficient differential operators on \mathbb{R}^n . Therefore no universal inequality

$$\|R\phi\|_1 \leq C (\|d\phi\|_1 + \|\delta\phi\|_1)$$

can hold, even for forms with compact support in a fixed ball.

However, the following statement is still open for $h \neq 1, n$: in \mathbb{R}^n , for every closed differential h -form ω in L^1 , does there exist an $(h - 1)$ -form ϕ such that $d\phi = \omega$ and

$$\|\nabla\phi\|_1 \leq C \|\omega\|_1 \quad ?$$

This is true if L^1 is replaced with Hardy space \mathcal{H}^1 .

3. KERNELS

In Theorem 1.1, the primitive ϕ of a closed form ω is provided by an operator defined by convolution with a homogeneous (matrix valued) function. We collect in this section the classical properties of such operators, especially their boundedness in function spaces in the Lebesgue and Sobolev scales. A special care will be taken of boundedness on L^1 , a fact which is not standard.

This section applies to the wider class of Carnot groups, which contains both abelian and Heisenberg groups.

3.1. Convolutions on Carnot groups. A *Carnot group* \mathbb{G} of step κ is a connected, simply connected Lie group whose Lie algebra \mathfrak{g} admits a *step κ stratification*, i.e. there exist linear subspaces V_1, \dots, V_κ such that

$$(2) \quad \mathfrak{g} = V_1 \oplus \dots \oplus V_\kappa, \quad [V_1, V_i] = V_{i+1}, \quad V_\kappa \neq \{0\}, \quad V_i = \{0\} \text{ if } i > \kappa,$$

where $[V_1, V_i]$ is the subspace of \mathfrak{g} generated by the commutators $[X, Y]$ with $X \in V_1$ and $Y \in V_i$. The exponential map is a one to one map from \mathfrak{g} onto \mathbb{G} . Using *exponential coordinates*, we identify a point $p \in \mathbb{G}$ with the N -tuple $(p_1, \dots, p_N) \in \mathbb{R}^N$ and we identify \mathbb{G} with (\mathbb{R}^N, \cdot) where the explicit expression of the group operation \cdot is determined by the Campbell-Hausdorff formula (see, e.g., [17]). In exponential coordinates the unit element e of \mathbb{G} is $e = (0, \dots, 0)$.

The first layer V_1 will be called *horizontal layer*; a left-invariant vector field in V_1 , identified with a differential operator, will be called an *horizontal derivative*.

From now on, we shall denote by $\{W_1, \dots, W_m\}$ a basis of V_1 .

The N -dimensional Lebesgue measure \mathcal{L}^N , is the Haar measure of the group \mathbb{G} . For any $\lambda > 0$, the *dilation* $\delta_\lambda : \mathbb{G} \rightarrow \mathbb{G}$, is defined as

$$(3) \quad \delta_\lambda(x_1, \dots, x_N) = (\lambda^{d_1} x_1, \dots, \lambda^{d_N} x_N),$$

where $d_i \in \mathbb{N}$ is called the *homogeneity of the variable x_i* in \mathbb{G} (see [17] Chapter 1). We denote by Q the *homogeneous dimension of \mathbb{G}* defined by

$$(4) \quad Q := \sum_{i=1}^{\kappa} i \dim V_i.$$

Through this paper we shall assume that $Q \geq 3$.

In this paper we denote by $|\cdot|$ a homogeneous norm, smooth outside the origin, that induces a genuine distance on \mathbb{G} as in [42], p. 638. In the special case of $\mathbb{G} = \mathbb{H}^n$, the n -th Heisenberg group, this homogeneous norm is the Korányi norm ρ (see (23)). Later on, we shall use the following gauge distance:

$$d(x, y) = |y^{-1}x|,$$

and we denote by $B(x, R)$ the d -ball of radius R centred at x .

Following e.g. [17], we can define a group convolution in \mathbb{G} : if, for instance, $f \in \mathcal{D}(\mathbb{G})$ and $g \in L^1_{\text{loc}}(\mathbb{G})$, we set

$$(5) \quad f * g(p) := \int f(q)g(q^{-1} \cdot p) dq \quad \text{for } q \in \mathbb{G}.$$

We remind that, if (say) g is a smooth function and P is a left invariant differential operator, then

$$P(f * g) = f * Pg.$$

If f is a real function defined in \mathbb{G} , we denote by ${}^v f$ the function defined by ${}^v f(p) := f(p^{-1})$, and, if $T \in \mathcal{D}'(\mathbb{G})$, then ${}^v T$ is the distribution defined by $\langle {}^v T | \phi \rangle := \langle T | {}^v \phi \rangle$ for any test function ϕ .

We remind also that the convolution is again well defined when $f, g \in \mathcal{D}'(\mathbb{G})$, provided at least one of them has compact support. In this case the following identities hold

$$(6) \quad \langle f * g | \phi \rangle = \langle g | {}^v f * \phi \rangle \quad \text{and} \quad \langle f * g | \phi \rangle = \langle f | \phi * {}^v g \rangle$$

for any test function ϕ , where we use the notation $\langle \cdot | \cdot \rangle$ for the duality between \mathcal{D}' and \mathcal{D} .

As in [17], we also adopt the following multi-index notation for higher-order derivatives. If $I = (i_1, \dots, i_{2n+1})$ is a multi-index, we set $W^I = W_1^{i_1} \dots W_{2n}^{i_{2n}} T^{i_{2n+1}}$. By the Poincaré–Birkhoff–Witt theorem, the differential operators W^I form a basis for the algebra of left invariant differential operators in \mathbb{G} . Furthermore, we set

$$|I| := i_1 + \dots + i_{2n} + i_{2n+1}$$

the order of the differential operator W^I , and

$$d(I) := i_1 + \dots + i_{2n} + 2i_{2n+1}$$

its degree of homogeneity with respect to group dilations.

Suppose now $f \in \mathcal{E}'(\mathbb{G})$ and $g \in \mathcal{D}'(\mathbb{G})$. Then, if $\psi \in \mathcal{D}(\mathbb{G})$, we have

$$\langle (W^I f) * g | \psi \rangle = \langle W^I f | \psi * {}^v g \rangle = (-1)^{|I|} \langle f | \psi * (W^I {}^v g) \rangle = (-1)^{|I|} \langle f * {}^v W^I {}^v g | \psi \rangle.$$

Thus

$$(7) \quad \begin{aligned} \langle (W^I f) * g | \psi \rangle &= \langle W^I f | \psi * {}^v g \rangle = (-1)^{|I|} \langle f | \psi * (W^I {}^v g) \rangle \\ &= (-1)^{|I|} \langle f * {}^v W^I {}^v g | \psi \rangle. \end{aligned}$$

3.2. Kernels, basic properties. Following [16], we remind now the notion of *kernel of type μ* and some properties stated below in Proposition 3.2.

Definition 3.1. *A kernel of type μ is a homogeneous distribution of degree $\mu - Q$ (with respect to group dilations), that is smooth outside of the origin.*

The convolution operator with a kernel of type μ is still called an operator of type μ .

Proposition 3.2. *Let $K \in \mathcal{D}'(\mathbb{G})$ be a kernel of type μ .*

- i) ${}^v K$ is again a kernel of type μ ;
- ii) WK and KW are associated with kernels of type $\mu - 1$ for any horizontal derivative W ;
- iii) If $\mu > 0$, then $K \in L^1_{\text{loc}}(\mathbb{G})$.

Lemma 3.3. *Let g be a kernel of type $\mu > 0$, and let $\psi \in \mathcal{D}(\mathbb{G})$ be a test function. Then $\psi * g$ is smooth on \mathbb{G} .*

If, in addition, R is an homogeneous polynomial of degree $\ell \geq 0$ in the horizontal derivatives, we have

$$R(\psi * g)(p) = O(|p|^{\mu-Q-\ell}) \quad \text{as } p \rightarrow \infty.$$

On the other hand, if g is a smooth function in $\mathbb{G} \setminus \{0\}$ that satisfies the logarithmic estimate $|g(p)| \leq C(1 + |\ln |p||)$ and in addition its horizontal derivatives are homogeneous of degree -1 with respect to group dilations, then, if $\psi \in \mathcal{D}(\mathbb{G})$ and R is an homogeneous polynomial of degree $\ell \geq 0$ in the horizontal derivatives, we have

$$\begin{aligned} R(\psi * g)(p) &= O(|p|^{-\ell}) \quad \text{as } p \rightarrow \infty \quad \text{if } \ell > 0; \\ R(\psi * g)(p) &= O(\ln |p|) \quad \text{as } p \rightarrow \infty \quad \text{if } \ell = 0. \end{aligned}$$

In particular, if $\psi \in \mathcal{D}(\mathbb{G})$, and K is a kernel of type $\mu < Q$, then both $\psi * K$ and all its derivatives belong to $L^\infty(\mathbb{G})$.

In the following theorem we gather some continuity properties for convolutions that can be find in [16] and [17] (or easily derived from [16] [17]).

Theorem 3.4. *We have:*

- i) *Hausdorff-Young inequality holds, i.e., if $f \in L^p(\mathbb{G})$, $g \in L^q(\mathbb{G})$, $1 \leq p, q, r \leq \infty$ and $\frac{1}{p} + \frac{1}{q} - 1 = \frac{1}{r}$, then $f * g \in L^r(\mathbb{G})$ (see [17], Proposition 1.18).*
- ii) *If K is a kernel of type 0 , $1 < p < \infty$, ≥ 0 , then the mapping $T : u \rightarrow u * K$ defined for $u \in \mathcal{D}(\mathbb{G})$ extends to a bounded operator on $W^{s,p}(\mathbb{G})$ (see [16], Theorem 4.9).*
- iii) *Suppose $0 < \mu < Q$, $1 < p < Q/\mu$ and $\frac{1}{q} = \frac{1}{p} - \frac{\mu}{Q}$. Let K be a kernel of type μ . If $u \in L^p(\mathbb{G})$ the convolutions $u * K$ and $K * u$ exists a.e. and are in $L^q(\mathbb{G})$ and there is a constant $C_p > 0$ such that*

$$\|u * K\|_q \leq C_p \|u\|_p \quad \text{and} \quad \|K * u\|_q \leq C_p \|u\|_p$$

(see [16], Proposition 1.11).

- iv) *Suppose $s \geq 1$, $1 < p < Q$, and let \mathcal{U} be a bounded open set. If K is a kernel of type 1 and $u \in W^{s-1,p}(\mathbb{G})$ with $\text{supp } u \subset \mathcal{U}$, then*

$$\|u * K\|_{W^{s,p}(\mathbb{G})} \leq C_{\mathcal{U}} \|u\|_{W^{s-1,p}(\mathbb{G})}.$$

Proof. The proof of iv) can be carried out relying on Theorems 4.10, 4.9 and Proposition 1.11 of [16], keeping into account that $L^{pQ/(Q-p)}(\mathcal{U}) \subset L^p$ and Proposition 3.2, ii). Indeed

$$\begin{aligned} \|u * K\|_{W^{s,p}(\mathbb{G})} &\leq C \left\{ \|u * K\|_{L^p(\mathbb{G})} + \sum_{\ell=1}^m \|u * W_\ell K\|_{W^{s-1,p}(\mathbb{G})} \right\} \\ &\leq C \left\{ \|u * K\|_{L^p(\mathbb{G})} + \|u\|_{W^{s-1,p}(\mathbb{G})} \right\} \\ &\leq C \left\{ \|u\|_{L^{pQ/(Q-p)}(\mathbb{G})} + \|u\|_{W^{s-1,p}(\mathbb{G})} \right\} \leq C_{\mathcal{U}} \|u\|_{W^{s-1,p}(\mathbb{G})}. \end{aligned}$$

□

Definition 3.5. *Let f be a measurable function on \mathbb{G} . If $t > 0$ we set*

$$\lambda_f(t) = |\{ |f| > t \}|.$$

If $1 \leq p \leq \infty$ and

$$\sup_{t>0} \lambda_f^p(t) < \infty,$$

we say that $f \in L^{p,\infty}(\mathbb{G})$.

Definition 3.6. Following [8], Definition A.1, if $1 < p < \infty$, we set

$$\|u\|_{M^p} := \inf\{C \geq 0; \int_K |u| dx \leq C|K|^{1/p'} \text{ for all } L\text{-measurable set } K \subset \mathbb{G}\}.$$

and $M^p = M^p(\mathbb{G})$ is the set of measurable functions u on \mathbb{G} satisfying $\|u\|_{M^p} < \infty$.

Repeating verbatim the arguments of [8], Lemma A.2, we obtain

Lemma 3.7. If $1 < p < \infty$, then

$$\frac{(p-1)^p}{p^{p+1}} \|u\|_{M^p}^p \leq \sup_{\lambda>0} \{\lambda^p |\{|u| > \lambda\}|\} \leq \|u\|_{M^p}^p.$$

In particular, if $1 < p < \infty$, then $M^p = L^{p,\infty}(\mathbb{G})$.

Corollary 3.8. If $1 \leq s < p$, then $M^p \subset L_{\text{loc}}^s(\mathbb{G}) \subset L_{\text{loc}}^1(\mathbb{G})$.

Proof. By Lemma 3.7, if $u \in M^p$ then $|u|^s \in M^{p/s}$, and we can conclude thanks to Definition 3.6. □

Lemma 3.9. Let E be a kernel of type $\alpha \in (0, Q)$. Then for all $f \in L^1(\mathbb{G})$ we have $f * E \in M^{Q/(Q-\alpha)}$ and there exists $C > 0$ such that

$$\|f * E\|_{M^{Q/(Q-\alpha)}} \leq C \|f\|_{L^1(\mathbb{G})}$$

for all $f \in L^1(\mathbb{G})$. In particular, by Corollary 3.8, if $1 \leq p < Q/(Q-\alpha)$, then $f * E \in L_{\text{loc}}^p(\mathbb{G}) \subset L_{\text{loc}}^1(\mathbb{G})$.

As in [5], Lemma 4.4 and Remark 4.5, we have:

Remark 3.10. Suppose $0 < \alpha < Q$. If K is a kernel of type α and $\psi \in \mathcal{D}(\mathbb{G})$, $\psi \equiv 1$ in a neighborhood of the origin, then the statements of Lemma 3.9 still hold if we replace K by $(1-\psi)K$ or by ψK .

3.3. Estimates on shells. Here, we prove a fine boundedness property of kernels in L^1 , expressed in terms of L^1 norms on shells. It will play a crucial role in section 5. We start with a preliminary duality lemma.

Lemma 3.11. If K is a kernel of type $\mu \in (0, Q)$, $u \in L^1(\mathbb{G})$ and $\psi \in \mathcal{D}(\mathbb{G})$, then

$$(8) \quad \langle u * K | \psi \rangle = \langle u | \psi * {}^\vee K \rangle.$$

In this equation, the left hand side is the action of a matrix-valued distribution on a vector-valued test function, see formula (25), the right hand side is the inner product of an L^1 vector-valued function with an L^∞ vector-valued function.

Proof. The assertion follows by Fubini-Tonelli theorem. Indeed

$$(9) \quad \begin{aligned} & \int \int |K(y^{-1}x)| |u(y)| |\psi(x)| dy dx \\ & \leq C \int \int d(x,y)^{\mu-Q} |u(y)| |\psi(x)| dy dx < \infty. \end{aligned}$$

Since ψ is compactly supported there exists $M > 0$ such that the above integral can be written as

$$\int_{|x| \leq M} \int \cdots = \int_{|x| \leq M} \int_{|y| \leq 2M} \cdots + \int_{|x| \leq M} \int_{|y| > 2M} \cdots .$$

Now

$$\begin{aligned} & \int_{|x| \leq M} \int_{|y| \leq 2M} d(x, y)^{\mu-Q} |u(y)| |\psi(x)| dy dx \\ (10) \quad & \leq C_\psi \int_{|x| \leq M} \int_{|y| \leq 2M} d(x, y)^{\mu-Q} |u(y)| dy, dx \\ & \leq C_\psi \int_{|x| \leq M} \left(\int_{d(x, y) \leq 3M} d(x, y)^{\mu-Q} dx \right) |u(y)| dy \\ & \leq C_\psi \|u\|_{L^1(\mathbb{G})}. \end{aligned}$$

On the other hand, if $|x| \leq M$ and $|y| > 2M$, then $d(x, y) > M$. so that

$$\begin{aligned} (11) \quad & \int_{|x| \leq M} \int_{|y| > 2M} d(x, y)^{\mu-Q} |u(y)| |\psi(x)| dy dx \\ & \leq M^{\mu-Q} \|\psi\|_{L^1(\mathbb{G})} \|u\|_{L^1(\mathbb{G})}. \end{aligned}$$

Then

$$\begin{aligned} & \int \left(\int K(y^{-1}x) u(y) dy \right) \psi(x) dx \\ (12) \quad & = \int \left(\int K(y^{-1}x) \psi(x) dx \right) u(y) dy \\ & = \int \left(\int {}^v K(x^{-1}y) \psi(x) dx \right) u(y) dy, \end{aligned}$$

and therefore we are done. □

Remark 3.12. *The conclusion of Lemma 3.11 still holds if we assume $K \in L^1_{\text{loc}}(\mathbb{G})$, provided u is compactly supported.*

Theorem 3.13. *If K is a kernel of type $\alpha \in (0, Q)$, then for any $f \in L^1(\mathbb{G})$ such that*

$$(13) \quad \int_{\mathbb{G}} f(y) dy = 0,$$

we have:

$$R^{-\alpha} \int_{B(e, 2R) \setminus B(e, R)} |K * f| dx \longrightarrow 0 \quad \text{as } R \rightarrow \infty.$$

Proof. If $R > 1$, taking into account (13), we have:

$$\begin{aligned}
R^{-\alpha} \int_{B(e, 2R) \setminus B(e, R)} |K * f| dx &= R^{-\alpha} \int_{R < |x| < 2R} dx \left| \int K(y^{-1}x) f(y) dy \right| \\
&= R^{-\alpha} \int_{R < |x| < 2R} dx \left| \int [K(y^{-1}x) - K(x)] f(y) dy \right| \\
&\leq R^{-\alpha} \int |f(y)| \left(\int_{R < |x| < 2R} |K(y^{-1}x) - K(x)| dx \right) dy \\
&= R^{-\alpha} \int_{|y| < \frac{1}{2}R} |f(y)| (\dots) dy + R^{-\alpha} \int_{\frac{1}{2}R < |y| < 4R} |f(y)| (\dots) dy \\
&\quad + R^{-\alpha} \int_{|y| > 4R} |f(y)| (\dots) dy \\
&=: R^{-\alpha} I_1(R) + R^{-\alpha} I_2(R) + R^{-\alpha} I_3(R).
\end{aligned}$$

Consider first the third term above. By homogeneity we have

$$I_3(R) \leq C_K \int_{|y| > 4R} |f(y)| \left(\int_{R < |x| < 2R} (d(x, y)^{-Q+\alpha} + d(x, e)^{-Q+\alpha}) dx \right) dy$$

Notice now that, if $|y| > 4R$ and $R < |x| < 2R$, then $d(x, y) \geq |y| - |x| \geq 4R - R = \geq \frac{3}{2}|x|$. Therefore, by [17], Corollary 1.16,

$$d(x, y)^{-Q+\alpha} + d(x, e)^{-Q+\alpha} \leq \left\{ \left(\frac{2}{3} \right)^{Q-\alpha} + 1 \right\} |x|^{-Q+\alpha},$$

and then

$$\int_{R < |x| < 2R} (d(x, y)^{-Q+\alpha} + d(x, e)^{-Q+\alpha}) dx \leq C_\alpha R^\alpha.$$

Thus

$$R^{-\alpha} I_3(R) \leq C_{K, \alpha} \int_{|y| > 4R} |f(y)| dy \longrightarrow 0$$

as $R \rightarrow \infty$.

Consider now the second term. Again we have

$$I_2(R) \leq C_K \int_{\frac{1}{2}R < |y| < 4R} |f(y)| \left(\int_{R < |x| < 2R} (d(x, y)^{-Q+\alpha} + d(x, e)^{-Q+\alpha}) dx \right) dy.$$

Obviously, as above,

$$\int_{R < |x| < 2R} d(x, e)^{-Q+\alpha} dx \leq CR^\alpha.$$

Notice now that, if $\frac{1}{2}R < |y| < 4R$ and $R < |x| < 2R$, then $d(x, y) \leq |x| + |y| \leq 6R$.

Hence

$$\int_{\frac{1}{2}R < |y| < 4R} |f(y)| \left(\int_{d(x, y) < 6R} d(x, y)^{-Q+\alpha} dx \right) dy \leq CR^\alpha.$$

Therefore

$$R^{-\alpha} I_2(R) \leq C_K \int_{\frac{1}{2}R < |y| < 4R} |f(y)| dy \longrightarrow 0$$

as $R \rightarrow \infty$. Finally, if $|y| < \frac{R}{2}$ and $R < |x| < 2R$ we have $|y| < \frac{1}{2}|x|$, so that, by [17], Proposition 1.7 and Corollary 1.16,

$$\begin{aligned} R^{-\alpha} I_1(R) &\leq C_K \int_{|y| < \frac{1}{2}R} |f(y)| \left(\int_{R < |x| < 2R} \frac{|y|}{|x|^{Q-\alpha+1}} dx \right) dy \\ &= C_K \int_{\mathbb{G}} |f(y)| |y| \chi_{[0, \frac{1}{2}R]}(|y|) \left(R^{-\alpha} \int_{R < |x| < 2R} \frac{1}{|x|^{Q-\alpha+1}} dx \right) dy \\ &\leq C_K \int_{\mathbb{G}} |f(y)| |y| \chi_{[0, \frac{1}{2}R]}(|y|) R^{-1} dy =: C_K \int_{\mathbb{G}} |f(y)| H_R(|y|) dy. \end{aligned}$$

Obviously, for any fixed $y \in \mathbb{G}$ we have $(|y|)H_R(|y|) \rightarrow 0$ as $R \rightarrow \infty$. On the other hand, $|f(y)|H_R(|y|) \leq \frac{1}{2}|f(y)|$, so that, by dominated convergence theorem,

$$R^{-\alpha} I_1(R) \longrightarrow 0$$

as $R \rightarrow \infty$.

This completes the proof of Theorem 3.13. \square

3.4. Powers of Kohn's Laplacian and Sobolev spaces. In section 8, we shall construct operators of order -1 , and we shall need to show that they improve differentiability. They win one degree of differentiability on the L^p scale when $p > 1$, but not on the L^1 scale. This is why we need introduce fractional Sobolev spaces, fortunately only for exponents $p > 1$. We choose to define them using powers of Kohn's Laplacian.

Let $\{X_1, \dots, X_m\}$ be the fixed basis of the horizontal layer V_1 of \mathfrak{g} chosen above. We denote by $\Delta_{\mathbb{G}}$ the negative horizontal sublaplacian

$$\Delta_{\mathbb{G}} := \sum_{j=1}^m X_j^2.$$

If $1 < p < \infty$ and $a \in \mathbb{C}$, we define $(-\Delta_{\mathbb{G}})^{a/2}$ in $L^p(\mathbb{G})$ following [16]. If in addition $s \geq 0$, again as in [16], we denote by $W_{\mathbb{G}}^{s,p}(\mathbb{G})$ the domain of the realization of $(-\Delta_{\mathbb{G}})^{s/2}$ in $L^p(\mathbb{G})$ endowed with the graph norm. In fact, as soon as $p \in (1, \infty)$ is fixed, to avoid cumbersome notations, we do not stress the explicit dependence on p of the fractional powers $(-\Delta_{\mathbb{G}})^{s/2}$ and of its domain.

Remark 3.14. By [40], Proposition 6, if $p > 1$, then the spaces $W_{\mathbb{G}}^{s,p}(\mathbb{G})$, $s \geq 0$ provide a complex interpolation scale of Banach spaces (see e.g. [9]).

Proposition 3.15. The operators $(-\Delta_{\mathbb{G}})^{s/2}$ are left invariant on $W_{\mathbb{G}}^{s,p}(\mathbb{G})$.

We recall that

Proposition 3.16 ([16], Corollary 4.13). If $1 < p < \infty$ and $\ell \in \mathbb{N}$, then the space $W_{\mathbb{G}}^{\ell,p}(\mathbb{G})$ coincides with the space of all $u \in L^p(\mathbb{G})$ such that

$$X^I u \in L^p(\mathbb{G}) \quad \text{for all multi-indices } I \text{ with } d(I) = \ell,$$

endowed with the natural norm.

Proposition 3.17 ([16], Corollary 4.14). If $1 < p < \infty$ and $s \geq 0$, then the space $W_{\mathbb{G}}^{s,p}(\mathbb{G})$ is independent of the choice of X_1, \dots, X_m .

Proposition 3.18. If $1 < p < \infty$ and $s \geq 0$, then $\mathcal{S}(\mathbb{G})$ and $\mathcal{D}(\mathbb{G})$ are dense subspaces of $W_{\mathbb{G}}^{s,p}(\mathbb{G})$.

Theorem 3.19 ([16], Corollary 4.15). *If $\phi \in \mathcal{D}(\mathbb{G})$, the map $f \rightarrow \phi f$ is continuous from $W^{s,p}(\mathbb{G})$ to $W^{s,p}(\mathbb{G})$ for $p > 1$ and $s \geq 0$.*

The following Proposition is a tool to prove that a given operator maps a suitable function space into a Sobolev space $W^{s,p}$. Indeed, it reduces the question to the case of the kernel of a negative power of $\Delta_{\mathbb{G}}$. It will be used in Lemma 3.26.

Proposition 3.20 (see [16]). *Suppose $0 < \beta < Q$. Denote by $h = h(t, x)$ the fundamental solution of $-\Delta_{\mathbb{G}} + \partial/\partial t$ (see [16], Proposition 3.3). Then the integral*

$$R_{\beta}(x) = \frac{1}{\Gamma(\beta/2)} \int_0^{\infty} t^{\frac{\beta}{2}-1} h(t, x) dt$$

converges absolutely for $x \neq 0$.

Moreover

- i) R_{β} is a kernel of type β ;
- ii) if $\alpha \in (0, 2)$ and $u \in \mathcal{D}(\mathbb{G})$, then

$$(-\Delta_{\mathbb{G}})^{\alpha/2} u = -\Delta_{\mathbb{G}}(u * R_{2-\alpha}).$$

3.5. Function spaces in domains. When dealing with subRiemannian manifolds in section 8, we shall need to localize Sobolev spaces on balls and transport them by contactomorphisms. Therefore we provide a precise definitions of $W^{s,p}(D)$ for D a good domain, typically a ball, in a Carnot group.

Definition 3.21. *As in Proposition 3.16, if $D \subset \mathbb{G}$ is a connected open set, ℓ is a nonnegative integer and $p \geq 1$, we set*

$$W^{\ell,p}(D) := \{u \in L^p(D) : W^I u \in L^p(D), d(I) \leq \ell\}.$$

From now on, we assume that D is an extension domain, i.e.

Definition 3.22. *We say that a connected bounded open set $D \subset \mathbb{G}$ is an extension domain if it enjoys the so-called extension property, i.e. for any $\ell \in \mathbb{N}$ there exists a bounded linear operator*

$$(14) \quad p_{\ell} : W^{\ell,p}(D) \rightarrow W^{\ell,p}(\mathbb{G})$$

such that $p_{\ell} u \equiv u$ in D .

Sufficient conditions yielding that D enjoys the extension property are largely studied in the literature. We do not enter into technical details, but we recall the following facts:

- In general Carnot groups “elementary” qualitative conditions for (14) are not known. Smooth domains may fail to be extension domains.
- The so-called (ϵ, δ) (or uniform) domains are extension domains. In particular, in Heisenberg groups, Carnot-Carathéodory balls are extension domains.
- In Carnot groups of step 2, $C^{1,1}$ -domains are extension domains. In particular, we shall need later that Korányi balls in Heisenberg groups (see (23) below) are extension domains. In particular, in Heisenberg groups there is a basis of the topology made by extension domains. This provides a precise meaning for the fractional local Sobolev spaces $W_{\text{loc}}^{\ell,p}(\mathbb{G})$.
- In general Carnot groups, bounded intrinsic Lipschitz domains are extension domains.

For proofs of the above results and for an overview of the problem we refer for instance to [12], [28], [35], [22], [11], [34] [33], [46], [20].

The following definition is not optimal but suffices for our purposes: if s is a nonnegative integer, the notion of Sobolev space given in Definitions 3.21 is equivalent to the following one when the domain is an extension domain, as we will see in Remark 3.24 below.

Definition 3.23. *Let D be a connected bounded open set enjoying the extension property (14). Denote by r_D the operator of restriction to D . If $s \geq 0$ and $p > 1$ we set*

$$W^{s,p}(D) = \{r_D u, u \in W^{s,p}(\mathbb{G})\},$$

endowed with the norm

$$(15) \quad \|u\|_{W^{s,p}(D)} := \inf\{\|v\|_{W^{s,p}(\mathbb{G})}, r_D v = u\}.$$

Remark 3.24. *If s is a nonnegative integer, then Definitions 3.23 and 3.21 are equivalent (in bounded extension domains). Indeed, denote for a while by $\|u\|_{W^{s,p}(D)}^*$ the norm defined in (15), keeping the notation $\|u\|_{W^{s,p}(D)}$ for the norm of Definition 3.21. Thus, since $r_D p_s u \equiv u$, we have*

$$\|u\|_{W^{s,p}(D)}^* \leq \|p_s u\|_{W^{s,p}(\mathbb{G})} \leq C \|u\|_{W^{s,p}(D)}.$$

On the other hand, let v be an arbitrary extension of u outside D . We notice that for any horizontal derivative W we have $Wu = r_D(Wv)$. Thus

$$\|u\|_{W^{s,p}(D)} \leq \|v\|_{W^{s,p}(\mathbb{G})},$$

so that, taking the infimum of the right-hand side of this inequality for all extensions v , we have

$$\|u\|_{W^{s,p}(D)} \leq \|u\|_{W^{s,p}(D)}^*.$$

Remark 3.25. *It is easy to see that Proposition 3.18 and Theorem 3.19 still hold for Sobolev spaces in D .*

3.6. Truncated kernels. The interior inequalities of Theorem 1.2 rely on convolution with functions of the form ψK where K is a kernel and ψ a smooth cut-off. We establish now boundedness properties of such operators.

Lemma 3.26. *Let K be a kernel of type $\alpha \in (0, 2]$ and let $\psi \in \mathcal{D}(\mathbb{G})$, $\psi \equiv 1$ in a neighborhood of the origin. Let $\chi_0 \in \mathcal{D}(\mathbb{G})$. If D is a bounded extension domain (see Definition 3.22), $\alpha' > 0$, $\alpha - 1 < \alpha' < \alpha$ and $Q/(Q - \alpha) > p > Q/(Q - \alpha + \alpha') > 1$, then the map*

$$\chi_0 f \rightarrow (\chi_0 f) * \psi K$$

is continuous from $L^1(\mathbb{G})$ to $W^{\alpha',p}(D)$.

Proof. Since both χ_0 and ψK are compactly supported, then $(\chi_0 f) * \psi K$ is compactly supported in a bounded open set \mathcal{U} and, obviously, is an extension of $r_D((\chi_0 f) * \psi K)$. Hence

$$\|(\chi_0 f) * \psi K\|_{W^{1,\alpha'}(D)} \leq \|(\chi_0 f) * \psi K\|_{L^p(\mathcal{U})} + \|\Delta_{\mathbb{G}}^{\alpha'/2}((\chi_0 f) * \psi K)\|_{L^p(\mathbb{G})}.$$

Since $p < Q/(Q - \alpha)$, by Theorem 3.4 - i), $f * \psi K$ belongs to $L^p(\mathbb{G})$ and the first term above is estimated as we want.

We are left with the estimation of the second norm above.

By density we can always suppose $f \in \mathcal{D}(\mathbb{G})$, so that $(\chi_0 f) * \psi K \in \mathcal{D}(\mathbb{G})$. Thus, by Proposition 3.20, ii)

$$(16) \quad -\Delta_{\mathbb{G}}^{\alpha'/2}((\chi_0 f) * \psi K) = -\Delta_{\mathbb{G}}(((\chi_0 f) * \psi K) * R_{2-\alpha'}).$$

On the other hand, we can write $(\chi_0 f) * \psi K = (\chi_0 f) * K - (\chi_0 f) * (1 - \psi)K$, so that

$$(17) \quad -\Delta_{\mathbb{G}}^{\alpha'/2}((\chi_0 f) * \psi K) = -\Delta_{\mathbb{G}}^{\alpha'/2}((\chi_0 f) * K) - \Delta_{\mathbb{G}}^{\alpha'/2}((\chi_0 f) * (1 - \psi)K).$$

Let us consider the second term of (17). We notice first that, keeping in mind that $R_{2-\alpha'}$ is a kernel of type $2 - \alpha'$, we can apply Lemma 1.12 of [16], to get

$$(18) \quad (f * (1 - \psi)K) * R_{2-\alpha'} = f * ((1 - \psi)K * R_{2-\alpha'}).$$

Indeed, K is a kernel of type α , and then

$$|(1 - \psi)K| \leq C(1 + |x|^{\alpha-Q}),$$

so that $(1 - \psi)K \in L^q(\mathbb{G})$ for some suitable $q > 1$, provided $1/q < 1 - \alpha/Q$. In addition

$$1 + \frac{1}{q} - \frac{2 - \alpha'}{Q} - 1 > 0,$$

since

$$\frac{Q - \alpha}{Q} - \frac{2 - \alpha'}{Q} > 0,$$

and we can always choose q such that

$$(19) \quad \frac{1}{q} \in \left(\frac{2 - \alpha'}{Q}, \frac{Q - \alpha}{Q} \right).$$

This prove (18).

We stress that the choice of q will not affect the remaining part of the proof, since q is merely a tool used to prove identity (18).

By (18), we get

$$(20) \quad \begin{aligned} \Delta_{\mathbb{G}}(((\chi_0 f) * (1 - \psi)K) * R_{2-\alpha'}) &= (\chi_0 f) * \Delta_{\mathbb{G}}((1 - \psi)K * R_{2-\alpha'}) \\ &= (\chi_0 f) * ({}^{\vee}\Delta_{\mathbb{G}}((1 - \psi)^{\vee}K) * R_{2-\alpha'}). \end{aligned}$$

Take now $s > 1$ such that

$$(21) \quad \frac{1}{s} = \frac{1}{p} + \frac{2 - \alpha'}{Q}.$$

Keeping into account that ${}^{\vee}K$ is still a kernel of type α and that $1 - \psi \equiv 1$ near the infinity, by Lemma 3.3 we have

$$|{}^{\vee}\Delta_{\mathbb{G}}((1 - \psi)^{\vee}K)| \leq C(1 + |x|^{\alpha-Q-2}).$$

Hence ${}^{\vee}\Delta_{\mathbb{G}}((1 - \psi)^{\vee}K) \in L^s(\mathbb{G})$. Therefore, by Theorem 3.4 - iii) and (21)

$$\Delta_{\mathbb{G}}((1 - \psi)K * R_{2-\alpha'}) \in L^p(\mathbb{G}).$$

Combining (16) and (20), by Hausdorff-Young theorem (see Theorem 3.4 -i)) we have

$$\|\Delta_{\mathbb{G}}^{\alpha'/2}((\chi_0 f) * (1 - \psi)K)\|_{L^p(\mathbb{G})} \leq \|f\|_{L^1(\mathbb{G})} \|\Delta_{\mathbb{G}}((1 - \psi)K * R_{2-\alpha'})\|_{L^p(\mathbb{G})}.$$

This provides an estimate of the second term of (17).

Thus, we have but to consider the term $-\Delta_{\mathbb{G}}(((\chi_0 f) * K) * R_{2-\alpha'})$. Since $\alpha + 2 - \alpha' < 3 \leq Q$, by Proposition 1.13 of [16],

$$\begin{aligned} -\Delta_{\mathbb{G}}(((\chi_0 f) * K) * R_{2-\alpha'}) &= -\Delta_{\mathbb{G}}(((\chi_0 f) * (K * R_{2-\alpha'}))) \\ &= -(\chi_0 f) * (\Delta_{\mathbb{G}}(K * R_{2-\alpha'})), \end{aligned}$$

where $K * R_{2-\alpha'}$ is a kernel of type $\alpha + 2 - \alpha'$, so that, by Proposition 3.2, $\Delta_{\mathbb{G}}(K * R_{2-\alpha'})$ is a kernel of type $\alpha - \alpha'$. Therefore, by Lemma 3.9,

$$\|(\chi_0 f) * (\Delta_{\mathbb{G}}(K * R_{2-\alpha'}))\|_{L^p(D)} \leq C \|f\|_{L^1(\mathbb{G})}$$

and the proof is completed. \square

The proof of the following result is similar to the previous one but for sake of completeness we write down the details.

Theorem 3.27. *Suppose $p > 1$, and let $\chi_0 \in \mathcal{D}(\mathbb{G})$ be fixed.*

- i) *Let K be a kernel of type 1 and let $\psi \in \mathcal{D}(\mathbb{G})$ be as in Remark 3.10 above, i.e. $\psi \equiv 1$ in a neighborhood of the origin. In addition, let $D \subset \mathbb{G}$ be a bounded connected extension domain. Then the map $f \rightarrow (\chi_0 f) * \psi K$ is continuous from $W^{s-1,p}(\mathbb{G})$ to $W^{s,p}(D)$ for $s \geq 1$.*
- ii) *Analogously, if K is a kernel of type 0, then the map $(\chi_0 f) \rightarrow f * \psi K$ is continuous from $W^{s,p}(\mathbb{G})$ to $W^{s,p}(D)$.*

for $s \geq 0$.

Proof. Since both χ_0 and ψK are compactly supported, then $(\chi_0 f) * \psi K$ is compactly supported.

Let now ψ_0 be a cut-off function, $\psi_0 \equiv 1$ on D , so that $\psi_0\{(\chi_0 f) * \psi K\}$ is an extension of $r_D\{(\chi_0 f) * \psi K\}$.

Then, by definition (see (15)),

$$\|(\chi_0 f) * \psi K\|_{W^{s,p}(D)} \leq \|\psi_0\{(\chi_0 f) * \psi K\}\|_{W^{s,p}(\mathbb{G})}.$$

Therefore, we have but to prove that

$$(22) \quad \|\psi_0\{(\chi_0 f) * \psi K\}\|_{W^{s,p}(\mathbb{G})} \leq C \|f\|_{W^{s-1,p}(\mathbb{G})}.$$

By density (see Proposition 3.18), we can assume $f \in \mathcal{D}(\mathbb{G})$. In addition, by interpolation (see Remark 3.14), we can assume s integer. As in the proof of Lemma 3.26 we write $\psi K = K - (1 - \psi)K$. By Theorem 3.4, iv),

$$\|\psi_0\{(\chi_0 f) * K\}\|_{W^{s,p}(\mathbb{G})} \leq \|(\chi_0 f) * K\|_{W^{s,p}(\mathbb{G})} \leq \|\chi_0 f\|_{W^{s-1,p}(\mathbb{G})} \leq \|f\|_{W^{s-1,p}(\mathbb{G})}.$$

On the other hand, the $W^{s,p}$ -norm of $\psi_0\{(\chi_0 f) * (1 - \psi)K\}$ can be estimated by a sum of terms of the form

$$\int_{\mathbb{G}} |W^J \psi_0|^p |(\chi_0 f) * W^I((1 - \psi)K)|^p dx \leq C \int_{\text{supp } \psi_0} |(\chi_0 f) * W^I((1 - \psi)K)|^p dx$$

with $d(I) + d(J) \leq s$.

We notice now that $(1 - \psi)K$ is a smooth function supported away from the origin. Therefore, keeping into account that χ_0 and ψ_0 are compactly supported, we can assume that $(1 - \psi)K$ is compactly supported away from the origin, so that $W^I((1 - \psi)K)$ belongs to $L^1(\mathbb{G})$. Thus eventually, once more by Hausdorff-Young inequality (Theorem 3.4)

$$\left(\int_{\text{supp } \psi_0} |(\chi_0 f) * W^I((1 - \psi)K)|^p dx \right)^{1/p} \leq C \|\chi_0 f\|_{L^p(\mathbb{G})} \leq C \|f\|_{L^p(\mathbb{G})} \leq \|f\|_{W^{s-1,p}(\mathbb{G})}.$$

This completes the proof of assertion i).

The proof of assertion ii) can be carried out in the same way, using Theorem 3.4, ii) instead of Theorem 3.4, iv).

□

4. PRELIMINARY RESULTS ON HEISENBERG GROUPS, RUMIN'S COMPLEX AND LAPLACIANS

4.1. Heisenberg groups. The n -dimensional Heisenberg group \mathbb{H}^n is the 2-step Carnot group whose Lie algebra

$$\mathfrak{h} = \mathfrak{h}_1 \oplus \mathfrak{h}_2.$$

has $\mathfrak{h}_2 = \mathbb{R}$, $\mathfrak{h}_1 = \mathbb{R}^{2n}$ and the Lie bracket $\mathfrak{h}_1 \times \mathfrak{h}_1 \rightarrow \mathfrak{h}_2$ is a nondegenerate skew-symmetric form.

The group can be identified with \mathbb{R}^{2n+1} through exponential coordinates and a point $p \in \mathbb{H}^n$ can be denoted by $p = (x, y, t)$, with both $x, y \in \mathbb{R}^n$ and $t \in \mathbb{R}$. For a general review on Heisenberg groups and their properties, we refer to [42], [23] and to [45]. We limit ourselves to fix some notations following [5].

The Heisenberg group \mathbb{H}^n can be endowed with the homogeneous norm (Korányi norm)

$$(23) \quad \varrho(p) = ((|x|^2 + |y|^2)^2 + t^2)^{1/4},$$

and we define the gauge distance (a true distance, see [42], p. 638, that is equivalent to Carnot–Carathéodory distance) as $d(p, q) := \varrho(p^{-1} \cdot q)$. Finally, set $B(p, r) = \{q \in \mathbb{H}^n; d(p, q) < r\}$.

The standard basis of \mathfrak{h} is given, for $i = 1, \dots, n$, by

$$X_i := \partial_{x_i} - \frac{1}{2}y_i\partial_t, \quad Y_i := \partial_{y_i} + \frac{1}{2}x_i\partial_t, \quad T := \partial_t.$$

The only non-trivial commutation relations are $[X_j, Y_j] = T$, for $j = 1, \dots, n$.

The vector space \mathfrak{h} can be endowed with an inner product, indicated by $\langle \cdot, \cdot \rangle$, making $X_1, \dots, X_n, Y_1, \dots, Y_n$ and T orthonormal.

Throughout this paper, we write also

$$(24) \quad W_i := X_i, \quad W_{i+n} := Y_i, \quad W_{2n+1} := T, \quad \text{for } i = 1, \dots, n.$$

The dual space of \mathfrak{h} is denoted by $\wedge^1 \mathfrak{h}$. The basis of $\wedge^1 \mathfrak{h}$, dual to the basis $\{X_1, \dots, Y_n, T\}$, is the family of covectors $\{dx_1, \dots, dx_n, dy_1, \dots, dy_n, \theta\}$ where

$$\theta := dt - \frac{1}{2} \sum_{j=1}^n (x_j dy_j - y_j dx_j)$$

is called the *contact form* in \mathbb{H}^n . A diffeomorphism ϕ between open subsets of \mathbb{H}^n is called a *contactomorphism* if $\phi^{\#}\theta$ is pointwise proportional to θ . In other words, contactomorphisms preserve the *contact structure* $\ker(\theta)$.

The stratification of the Lie algebra \mathfrak{h} induces a family of anisotropic dilations δ_λ , $\lambda > 0$ in \mathbb{H}^n . The homogeneous dimension of \mathbb{H}^n with respect to δ_λ , $\lambda > 0$ equals $Q := 2n + 2$. Unfortunately, when dealing with differential forms in \mathbb{H}^n , the de Rham complex lacks scale invariance under anisotropic dilations. Thus, a substitute for de Rham's complex, that recovers scale invariance under δ_t has been defined by M. Rumin, [38]. In turn, this notion makes sense for arbitrary contact

manifolds. We refer to [38] and [6] for details of the construction. In the present paper, we shall merely need the following list of formal properties.

- For $h = 0, \dots, 2n+1$, the space of Rumin h -forms, E_0^h is the space of smooth sections of a left-invariant subbundle of $\bigwedge^h T^*\mathbb{H}^n$ (that we still denote by E_0^h). Hence it inherits inner products, L^p and $W^{s,p}$ norms.
- A differential operator $d_c : E_0^h \rightarrow E_0^{h+1}$ is defined. It is left-invariant, homogeneous with respect to group dilations. It is a first order homogeneous operator in the horizontal derivatives in degree $\neq n$, whereas it is a second order homogeneous horizontal operator in degree n .
- Contactomorphisms ϕ between open subsets of \mathbb{H}^n pull-back Rumin forms to Rumin forms, and in addition commute with d_c :

$$d_c(\phi^\# \alpha) = \phi^\#(d_c \alpha).$$

- The L^2 (formal) adjoint of d_c is a differential operator d_c^* of the same order as d_c .
- Hypoelliptic ‘‘Laplacians’’ can be formed from d_c and d_c^* (see Definition 4.2 below).
- Altogether, operators d_c form a complex: $d_c \circ d_c = 0$.
- This complex is homotopic to de Rham’s complex (Ω^\bullet, d) . The homotopy is achieved by differential operators $\Pi_E : E_0^\bullet \rightarrow \Omega^\bullet$ and $\Pi_{E_0} : \Omega^\bullet \rightarrow E_0^\bullet$ (Π_E has horizontal order ≤ 1 and Π_{E_0} is an algebraic operator).

In other words, $\Pi_E : E_0^\bullet \rightarrow \Omega^\bullet$ and $\Pi_{E_0} : \Omega^\bullet \rightarrow E_0^\bullet$ intertwine differentials d_c and d ,

$$\begin{array}{ccccccc} \dots & \xrightarrow{d_c} & E_0^h & \xrightarrow{d_c} & E_0^{h+1} & \xrightarrow{d_c} & \dots \\ & & \Pi_E \downarrow & & \Pi_E \downarrow & & \\ \dots & \xrightarrow{d} & \Omega^h & \xrightarrow{d} & \Omega^{h+1} & \xrightarrow{d} & \dots \\ \dots & \xrightarrow{d_c} & E_0^h & \xrightarrow{d_c} & E_0^{h+1} & \xrightarrow{d_c} & \dots \\ & & \uparrow \Pi_{E_0} & & \uparrow \Pi_{E_0} & & \\ \dots & \xrightarrow{d} & \Omega^h & \xrightarrow{d} & \Omega^{h+1} & \xrightarrow{d} & \dots \end{array}$$

and there exists an algebraic operator $A : \Omega^\bullet \rightarrow \Omega^{\bullet-1}$ such that $1 - \Pi_{E_0} \Pi_E \Pi_E \Pi_{E_0} = 0$ on E_0^\bullet and $1 - \Pi_E \Pi_{E_0} \Pi_{E_0} \Pi_E = dA + Ad$ on Ω^\bullet .

4.2. Leibniz formula. When d_c is second order, (E_0^\bullet, d_c) stops behaving like a differential module. This is the source of many complications.

Lemma 4.1 (see also [5], Lemma 3.2). *If ζ is a smooth real function, then*

i) *if $h \neq n$, then on E_0^h we have:*

$$[d_c, \zeta] = P_0^h(W\zeta),$$

where $P_0^h(W\zeta) : E_0^h \rightarrow E_0^{h+1}$ is a linear homogeneous differential operator of order zero with coefficients depending only on the horizontal derivatives of ζ . If $h \neq n+1$, an analogous statement holds if we replace d_c by d_c^ ;*

ii) if $h = n$, then on E_0^n we have

$$[d_c, \zeta] = P_1^n(W\zeta) + P_0^n(W^2\zeta),$$

where $P_1^n(W\zeta) : E_0^n \rightarrow E_0^{n+1}$ is a linear homogeneous differential operator of order 1 (and therefore horizontal) with coefficients depending only on the horizontal derivatives of ζ , and where $P_0^n(W^2\zeta) : E_0^n \rightarrow E_0^{n+1}$ is a linear homogeneous differential operator in the horizontal derivatives of order 0 with coefficients depending only on second order horizontal derivatives of ζ . If $h = n + 1$, an analogous statement holds if we replace d_c by d_c^* .

iii) if $h \neq n + 1$, then

$$[d_c d_c^*, \zeta] = P_1^h(W\zeta) + P_0^h(W^2\zeta),$$

where $P_1^h(W\zeta) : E_0^h \rightarrow E_0^h$ is a linear homogeneous differential operator of order 1 and therefore horizontal) with coefficients depending only on the horizontal derivatives of ζ , and where $P_0^h(W^2\zeta) : E_0^h \rightarrow E_0^h$ is a linear homogeneous differential operator in the horizontal derivatives of order 0 with coefficients depending only on second order horizontal derivatives of ζ .

iv) if $h = n + 1$, then

$$[d_c d_c^*, \zeta] = P_3^{n+1}(W\zeta) + P_2^{n+1}(W^2\zeta) + P_1^{n+1}(W^3\zeta) + P_0^{n+1}(W^4\zeta),$$

where for $j = 0, 1, 2, 3$, the $P_j^{n+1}(W^{4-j}\zeta) : E_0^{n+1} \rightarrow E_0^{n+1}$ are linear homogeneous differential operators of order j and therefore horizontal) with coefficients depending only on the horizontal derivatives of order $4 - j$ of ζ .

Proof. The first two assertions are more or less straightforward. Let us prove the third assertion. If u is a Rumin's differential form of degree h , keeping in mind the first assertion, we have

$$\begin{aligned} [d_c d_c^*, \zeta]u &= d_c d_c^*(\zeta u) - \zeta d_c d_c^* u = d_c(\zeta d_c^* u + P_0^h(W\zeta)u) - \zeta d_c d_c^* u \\ &= \zeta d_c d_c^* u + P_0^{h-1}(W\zeta)d_c^* u + d_c(P_0^h(W\zeta)u) - \zeta d_c d_c^* u \\ &= P_0^{h-1}(W\zeta)d_c^* u + d_c(P_0^h(W\zeta)u). \end{aligned}$$

Denote by $\{\xi_j^h\}$ a left-invariant basis of E_0^h . If $u = \sum_j u_j \xi_j^h$, then $P_0^h(W\zeta)v = \sum_{j,k} a_{j,k}(W_k \zeta) u_k \xi_j^h$. Thus, using i) on $v_k \xi_j^h$ for all j, k , we get

$$\begin{aligned} d_c(P_0^h(W\zeta)u) &= \sum_{j,k} a_{j,k}(W_k \zeta) d_c(u_k \xi_j^h) + \sum_{j,k} P_0^h(W(W_k \zeta)) u_k \xi_j^h \\ &=: P_1^h(W\zeta)u + P_0^h(W^2\zeta)u. \end{aligned}$$

Therefore

$$[d_c d_c^*, \zeta]u = P_0^{h-1}(W\zeta)d_c^* u + P_1^h(W\zeta)u + P_0^h(W^2\zeta)u,$$

and the assertion follows if we still denote by $P_1^h(W\zeta)$ the above operator $P_0^{h-1}(W\zeta)d_c^* + P_1^h(W\zeta)$.

The proof of iv) is similar. \square

4.3. Rumin's Laplacian.

Definition 4.2. In \mathbb{H}^n , following [38], we define the operators $\Delta_{\mathbb{H},h}$ on E_0^h by setting

$$\Delta_{\mathbb{H},h} = \begin{cases} d_c d_c^* + d_c^* d_c & \text{if } h \neq n, n+1; \\ (d_c d_c^*)^2 + d_c^* d_c & \text{if } h = n; \\ d_c d_c^* + (d_c^* d_c)^2 & \text{if } h = n+1. \end{cases}$$

Notice that $-\Delta_{\mathbb{H},0} = \sum_{j=1}^{2n} (W_j^2)$ is the usual sub-Laplacian of \mathbb{H}^n .

For sake of simplicity, once a basis of E_0^h is fixed, the operator $\Delta_{\mathbb{H},h}$ can be identified with a matrix-valued map, still denoted by $\Delta_{\mathbb{H},h}$

$$(25) \quad \Delta_{\mathbb{H},h} = (\Delta_{\mathbb{H},h}^{ij})_{i,j=1,\dots,N_h} : \mathcal{D}'(\mathbb{H}^n, \mathbb{R}^{N_h}) \rightarrow \mathcal{D}'(\mathbb{H}^n, \mathbb{R}^{N_h}),$$

where $\mathcal{D}'(\mathbb{H}^n, \mathbb{R}^{N_h})$ is the space of vector-valued distributions on \mathbb{H}^n , and N_h is the dimension of E_0^h (see [1]).

This identification makes possible to avoid the notion of currents: we refer to [6] for a more elegant presentation.

Definition 4.3. *If a basis of E_0^\bullet is fixed, and $1 \leq p \leq \infty$, we denote by $L^p(\mathbb{H}^n, E_0^\bullet)$ the space of all sections of E_0^\bullet such that their components with respect to the given basis belong to $L^p(\mathbb{H}^n)$, endowed with its natural norm. Clearly, this definition is independent of the choice of the basis itself.*

The notations $M^p(\mathbb{H}^n, E_0^\bullet)$ (see Definition 3.6), $\mathcal{D}(\mathbb{H}^n, E_0^\bullet)$, $\mathcal{S}(\mathbb{H}^n, E_0^\bullet)$, as well as $W^{m,p}(\mathbb{H}^n, E_0^\bullet)$ have the same meaning.

It is proved in [38] that $\Delta_{\mathbb{H},h}$ is hypoelliptic and maximal hypoelliptic in the sense of [24]. In general, if \mathcal{L} is a differential operator on $\mathcal{D}'(\mathbb{H}^n, \mathbb{R}^{N_h})$, then \mathcal{L} is said hypoelliptic if for any open set $\mathcal{V} \subset \mathbb{H}^n$ where $\mathcal{L}\alpha$ is smooth, then α is smooth in \mathcal{V} . In addition, if \mathcal{L} is homogeneous of degree $a \in \mathbb{N}$, we say that \mathcal{L} is maximal hypoelliptic if for any $\delta > 0$ there exists $C = C(\delta) > 0$ such that for any homogeneous polynomial P in W_1, \dots, W_{2n} of degree a we have

$$\|P\alpha\|_{L^2(\mathbb{H}^n, \mathbb{R}^{N_h})} \leq C \left(\|\mathcal{L}\alpha\|_{L^2(\mathbb{H}^n, \mathbb{R}^{N_h})} + \|\alpha\|_{L^2(\mathbb{H}^n, \mathbb{R}^{N_h})} \right).$$

for any $\alpha \in \mathcal{D}(B_\rho(0, \delta), \mathbb{R}^{N_h})$.

Combining [38], Section 3, and [7], Theorems 3.1 and 4.1, we obtain the following result.

Theorem 4.4 (see [7], Theorem 3.1). *If $0 \leq h \leq 2n + 1$, then the differential operator $\Delta_{\mathbb{H},h}$ is homogeneous of degree a with respect to group dilations, where $a = 2$ if $h \neq n, n + 1$ and $a = 4$ if $h = n, n + 1$. It follows that*

i) *for $j = 1, \dots, N_h$ there exists*

$$(26) \quad K_j = (K_{1j}, \dots, K_{N_h j}), \quad j = 1, \dots, N_h$$

with $K_{ij} \in \mathcal{D}'(\mathbb{H}^n) \cap \mathcal{E}(\mathbb{H}^n \setminus \{0\})$, $i, j = 1, \dots, N$;

ii) *if $a < Q$, then the K_{ij} 's are kernels of type a for $i, j = 1, \dots, N_h$*

If $a = Q$, then the K_{ij} 's satisfy the logarithmic estimate $|K_{ij}(p)| \leq C(1 + |\ln \rho(p)|)$ and hence belong to $L_{\text{loc}}^1(\mathbb{H}^n)$. Moreover, their horizontal derivatives $W_\ell K_{ij}$, $\ell = 1, \dots, 2n$, are kernels of type $Q - 1$;

iii) *when $\alpha \in \mathcal{D}(\mathbb{H}^n, \mathbb{R}^{N_h})$, if we set*

$$(27) \quad \Delta_{\mathbb{H},h}^{-1} \alpha := \left(\sum_j \alpha_j * K_{1j}, \dots, \sum_j \alpha_j * K_{N_h j} \right),$$

then $\Delta_h \Delta_{\mathbb{H},h}^{-1} \alpha = \alpha$. Moreover, if $a < Q$, also $\Delta_{\mathbb{H},h}^{-1} \Delta_h \alpha = \alpha$.

iv) *if $a = Q$, then for any $\alpha \in \mathcal{D}(\mathbb{H}^n, \mathbb{R}^{N_h})$ there exists $\beta_\alpha := (\beta_1, \dots, \beta_{N_h}) \in \mathbb{R}^{N_h}$, such that*

$$\Delta_{\mathbb{H},h}^{-1} \Delta_h \alpha - \alpha = \beta_\alpha.$$

Remark 4.5. If $a < Q$, $\Delta_{\mathbb{H},h}(\Delta_{\mathbb{H},h}^{-1} - {}^v\Delta_{\mathbb{H},h}^{-1}) = 0$ and hence $\Delta_{\mathbb{H},h}^{-1} = {}^v\Delta_{\mathbb{H},h}^{-1}$, by the Liouville-type theorem of [7], Proposition 3.2.

Remark 4.6. From now on, if there are no possible misunderstandings, we identify $\Delta_{\mathbb{H},h}^{-1}$ with its kernel.

We notice that, if $n > 1$, then $\Delta_{\mathbb{H},h}^{-1}$ is associated with a kernel of type 2 or 4 and therefore $\Delta_{\mathbb{H},h}^{-1}f$ is well defined when $f \in L^1(\mathbb{H}^n, E_0^h)$. More precisely, by Lemma 3.9 we have:

Lemma 4.7. If $n > 1$, $1 \leq h \leq 2n$, then for any horizontal differential operator W^I with homogeneous order $d(I)$, we have

i) if $h \neq n, n+1$ and $d(I) = 1$, then

$$\|f * W^I \Delta_{\mathbb{H},h}^{-1}\|_{M^{Q/(Q-1)}} \leq C \|f\|_{L^1(\mathbb{H}^n, E_0^h)}$$

for all $f \in L^1(\mathbb{H}^n, E_0^h)$;

ii) if $h = n, n+1$ and $1 \leq d(I) < 4$, then

$$\|f * W^I \Delta_{\mathbb{H},h}^{-1}\|_{M^{Q/(Q-4+d(I))}} \leq C \|f\|_{L^1(\mathbb{H}^n, E_0^h)}$$

for all $f \in L^1(\mathbb{H}^n, E_0^h)$.

By Corollary 3.8, in both cases $f * W^I \Delta_{\mathbb{H},h}^{-1} \in L_{\text{loc}}^1(\mathbb{H}^n, E_0^*)$. In particular, the map

$$(28) \quad \Delta_{\mathbb{H},h}^{-1} : L^1(\mathbb{H}^n, E_0^*) \longrightarrow L_{\text{loc}}^1(\mathbb{H}^n, E_0^*)$$

is continuous.

Remark 4.8. Let $n > 1$. If $\alpha \in L^1(\mathbb{H}^n, E_0^\bullet)$, then $\Delta_{\mathbb{H},h}^{-1}\alpha$ is well defined and belongs to $L_{\text{loc}}^1(\mathbb{H}^n, E_0^\bullet)$. In particular, is a vector-valued distribution. By Lemma 3.11, if $\psi \in \mathcal{D}(\mathbb{H}^n, E_0^h)$, then

$$(29) \quad \langle \Delta_{\mathbb{H},h}^{-1}\alpha | \psi \rangle := \langle \alpha | \Delta_{\mathbb{H},h}^{-1}\psi \rangle.$$

In this equation, the left hand side is the action of a matrix-valued distribution on a vector-valued test function, see formula (25), whereas the right hand side is (with a slight abuse of notation, since $\Delta_{\mathbb{H},h}^{-1}\psi$ is not a test function) the inner product of an L^1 vector-valued function with a L^∞ vector-valued function.

4.4. Commutation relations. Typically, the operator used to invert d_c is $d_c^* \Delta_{\mathbb{H}}^{-1}$. It inverts d_c because d_c commutes with $\Delta_{\mathbb{H}}^{-1}$. Since d_c and d_c^* commute with $\Delta_{\mathbb{H}}$, it is natural that they commute with its inverse. One first shows this for test forms, and then (in a slightly weaker form) for L^1 forms by duality.

Lemma 4.9 (see [5], Lemma 4.11). If $\alpha \in \mathcal{D}(\mathbb{H}^n, E_0^h)$ and $n \geq 1$, then

- i) $d_c \Delta_{\mathbb{H},h}^{-1} \alpha = \Delta_{\mathbb{H},h+1}^{-1} d_c \alpha$, $h = 0, 1, \dots, 2n$, $h \neq n-1, n+1$.
- ii) $d_c \Delta_{\mathbb{H},n-1}^{-1} \alpha = d_c d_c^* \Delta_{\mathbb{H},n}^{-1} d_c \alpha$ ($h = n-1$).
- iii) $d_c d_c^* d_c \Delta_{\mathbb{H},n+1}^{-1} \alpha = \Delta_{\mathbb{H},n+2}^{-1} d_c \alpha$, ($h = n+1$).
- iv) $d_c^* \Delta_{\mathbb{H},h}^{-1} \alpha = \Delta_{\mathbb{H},h-1}^{-1} d_c^* \alpha$ $h = 1, \dots, 2n+1$, $h \neq n, n+2$.
- v) $d_c^* \Delta_{\mathbb{H},n+2}^{-1} \alpha = d_c^* d_c \Delta_{\mathbb{H},n+1}^{-1} d_c^* \alpha$ ($h = n+2$).
- vi) $d_c^* d_c d_c^* \Delta_{\mathbb{H},n}^{-1} \alpha = \Delta_{\mathbb{H},n-1}^{-1} d_c^* \alpha$, ($h = n$).

Lemma 4.10. *Let $h \geq 1$. Let $\omega \in L^1(\mathbb{H}^n, E_0^h)$ be a d_c -closed form. Then $\Delta_{\mathbb{H},h}^{-1}\omega$ is well defined and belongs to $L^1_{\text{loc}}(\mathbb{H}^n, E_0^h)$. Furthermore, $d_c^*d_c\Delta_{\mathbb{H},h}^{-1}\omega = 0$ in distributional sense.*

Proof. Let $\phi \in \mathcal{D}(\mathbb{H}^n, E_0^h)$. By definition, by Corollary 4.8 and by Lemma 4.9, iv),
 $\langle d_c^*d_c\Delta_{\mathbb{H},h}^{-1}\omega|\phi \rangle := \langle d_c\Delta_{\mathbb{H},h}^{-1}\omega|d_c\phi \rangle = \langle \Delta_{\mathbb{H},h}^{-1}\omega|d_c^*d_c\phi \rangle = \langle \omega|\Delta_{\mathbb{H},h}^{-1}d_c^*d_c\phi \rangle = \langle \omega|d_c^*\Delta_{\mathbb{H},h}^{-1}d_c\phi \rangle.$

One can write $\Delta_{\mathbb{H},h}^{-1}d_c\phi = \phi * K$ where K is a kernel of type 1 or 2. Let us show that

$$(30) \quad \int \langle \omega, d_c^*(\phi * K) \rangle dx = 0.$$

By Lemma 3.3, $\phi * K$ is smooth and bounded on \mathbb{H}^n , as well as all its horizontal derivatives. If $N \in \mathbb{N}$, let σ_N be a cut-off function supported in $B(e, N+1)$ and identically 1 on $B(e, N)$. By dominated convergence theorem

$$\int \langle \omega, d_c^*(\phi * K) \rangle dx = \lim_{N \rightarrow \infty} \int \langle \omega, \sigma_N d_c^*(\phi * K) \rangle dx.$$

On the other hand, by Lemma 4.1,

$$\begin{aligned} \int \langle \omega, \sigma_N d_c^*(\psi * K) \rangle dx &= \int \langle \omega, d_c^*(\phi * K) \rangle dx + \int \langle \omega, [d_c^*, \sigma_N](\phi * K) \rangle dx \\ &= \langle d_c\omega | \sigma_N(\phi * K) \rangle + \int \langle \omega, [d_c^*, \sigma_N](\phi * K) \rangle dx \\ &= \int \langle \omega, [d_c^*, \sigma_N](\phi * K) \rangle dx \longrightarrow 0 \quad \text{as } N \rightarrow \infty, \end{aligned}$$

again by dominated convergence theorem, since horizontal derivatives of any order of σ_N vanish as $N \rightarrow \infty$ and $\phi * K \in L^\infty(\mathbb{H}^n)$ by Lemma 3.3. We conclude that $\langle d_c^*d_c\Delta_{\mathbb{H},h}^{-1}\omega|\phi \rangle = 0$ for all test forms, hence $d_c^*d_c\Delta_{\mathbb{H},h}^{-1}\omega = 0$. \square

5. GAGLIARDO-NIRENBERG INEQUALITIES

The following is the core estimate of the paper. It provides primitives for globally defined d_c -closed L^1 forms, under an extra assumption on the vanishing of averages. This assumption is necessary. Indeed, it is obviously satisfied for forms admitting a compactly supported primitive. The extension to L^1 primitives is not hard, see Lemma 6.3. The case of forms admitting an L^q primitive for some $q > 1$ is more subtle, we refer to [43].

The starting point is the collection of Gagliardo-Nirenberg inequalities proven in [3].

Theorem 5.1 ([3], Theorem 1.6). *Let u be a compactly supported Rumin $(h-1)$ -form on \mathbb{H}^n . Assume that $d_c^*u = 0$. Then*

$$(31) \quad \|u\|_{L^{q/(q-1)}(\mathbb{H}^n, E_0^{h-1})} \leq C \|d_c u\|_{L^1(\mathbb{H}^n, E_0^h)} \quad \text{if } h \neq n+1, 2n+1$$

$$(32) \quad \|u\|_{L^{q/(q-2)}(\mathbb{H}^n, E_0^n)} \leq C \|d_c u\|_{L^1(\mathbb{H}^n, E_0^{n+1})} \quad \text{if } h = n+1.$$

In [3], Theorem 1.6, the first case corresponds to statements i), first line ($h = 1$), ii) first line ($h = 2$), iv) fourth line ($h = n+2$), iii) (other values of $h \neq 2n+1$), and the second case to statement iv) first line ($h = n+1$).

Given a d_c -closed L^1 form ω , one would like to apply Theorem 5.1 to $u = d_c^* \Delta_{\mathbb{H},h}^{-1} \omega$, since $d_c^* u = 0$. Since u is not compactly supported, a cut-off is necessary, but this produces error terms which can be estimated thanks to Theorem 3.13, provided averages vanish.

5.1. Estimate for \mathbb{H}^n , $n > 1$.

Theorem 5.2. *Denote by $L_0^1(\mathbb{H}^n, E_0^\bullet)$ the subspace of $L^1(\mathbb{H}^n, E_0^\bullet)$ of forms with vanishing average. If $n > 1$ we have:*

i) *if $h \neq n, n+1$ and $1 \leq h < 2n+1$, then*

$$\|d_c^* \Delta_{\mathbb{H},h}^{-1} \omega\|_{L^{Q/(Q-1)}(\mathbb{H}^n, E_0^{h-1})} \leq C \|\omega\|_{L^1(\mathbb{H}^n, E_0^h)} \quad \text{for all } \omega \in L_0^1(\mathbb{H}^n, E_0^h) \cap \ker d_c;$$

ii) *if $h = n$, then*

$$\|d_c^* d_c d_c^* \Delta_{\mathbb{H},n}^{-1} \omega\|_{L^{Q/(Q-1)}(\mathbb{H}^n, E_0^{n-1})} \leq C \|\omega\|_{L^1(\mathbb{H}^n)} \quad \text{for all } \omega \in L_0^1(\mathbb{H}^n, E_0^n) \cap \ker d_c;$$

iii) *if $h = n+1$, then*

$$\|d_c^* \Delta_{\mathbb{H},n+1}^{-1} \omega\|_{L^{Q/(Q-2)}(\mathbb{H}^n, E_0^n)} \leq C \|\omega\|_{L^1(\mathbb{H}^n)} \quad \text{for all } \omega \in L_0^1(\mathbb{H}^n, E_0^{n+1}) \cap \ker d_c;$$

If $n = 1$, then statement iv) still holds with $h = 3$.

If $n = 1$ and $h = 1, 2$, similar (but slightly different) inequalities are discussed in Proposition 5.3.

Proof. We notice that, if $n > 1$, then $\Delta_{\mathbb{H},h}^{-1}$ is a kernel of type 2 or 4 and therefore, as we pointed out in (28), if $\omega \in L_0^1(\mathbb{H}^n, E_0^h)$, then $\Delta_{\mathbb{H},h}^{-1} \omega$ is well defined and belongs to $L_{\text{loc}}^1(\mathbb{H}^n, E_0^h)$ for $1 \leq h \leq 2n+1$. Thus we can consider the convolution operator $\omega \mapsto d_c^* \Delta_{\mathbb{H},h}^{-1} \omega$ that is associated with a kernel of type 1 if $h \neq n, n+1$ and of type 2 if $h = n+1$. Analogously, if $h = n$, then the convolution operator $\omega \mapsto d_c^* d_c d_c^* \Delta_{\mathbb{H},h}^{-1} \omega$ is associated with a kernel of type 1.

If $N \in \mathbb{N}$, let now χ_N be a cut-off function supported in $B(e, 2N)$, $\chi_N \equiv 1$ on $B(e, N)$. If $\epsilon < 1$ let J_ϵ be an usual Friedrichs' mollifier (for the group structure). Then, set

$$(33) \quad v_{\epsilon,N} := J_\epsilon * d_c^*(\chi_N \Delta_{\mathbb{H},h}^{-1} \omega) \quad \text{if } h \neq n,$$

while

$$(34) \quad v_{\epsilon,N} := J_\epsilon * d_c^*(\chi_N d_c d_c^* \Delta_{\mathbb{H},h}^{-1} \omega) \quad \text{if } h = n.$$

Notice now that both $d_c^*(\chi_N \Delta_{\mathbb{H},h}^{-1} \omega)$ if $h \neq n$, and $d_c^*(\chi_N d_c d_c^* \Delta_{\mathbb{H},h}^{-1} \omega)$ if $h = n$ are compactly supported and uniformly bounded in $L^1(\mathbb{H}^n, E_0^{h-1})$. Indeed, in the first case we can write

$$d_c^*(\chi_N \Delta_{\mathbb{H},h}^{-1} \omega) = \chi_N (d_c^* \Delta_{\mathbb{H},h}^{-1} \omega) + [d_c^*, \chi_N] \Delta_{\mathbb{H},h}^{-1} \omega,$$

and both terms on the right hand side are bounded in $L^1(\mathbb{H}^n, E_0^{h-1})$ by Lemmata 4.1 and 4.7. An analogous argument can be carried out in case $h = n$, keeping in mind that d_c^* is an operator of order 1 and $d_c d_c^* \Delta_{\mathbb{H},h}^{-1}$ is associated with a kernel of type 2.

We observe that

$$d_c^* v_{\epsilon,N} = J_\epsilon * (d_c^*)^2 (\chi_N \Delta_{\mathbb{H},h}^{-1} \omega) = 0,$$

if $h \neq n$. In case $h = n$,

$$d_c^* v_{\epsilon,N} = J_\epsilon * (d_c^*)^2 (\chi_N d_c d_c^* \Delta_{\mathbb{H},h}^{-1} \omega) = 0$$

again.

Let us prove sentences i) and iii) simultaneously. To avoid cumbersome notations, in the sequel when L^p -spaces are involved, we shall drop the target spaces. We apply Theorem 5.1 to $v_{\epsilon, N}$.

$$\begin{aligned}
(35) \quad & \|v_{\epsilon, N}\|_{L^{Q/(Q-1)}(\mathbb{H}^n, E_0^{h-1})} \leq C \|d_c v_{\epsilon, N}\|_{L^1(\mathbb{H}^n)} \\
& = C \|J_\epsilon * d_c d_c^* (\chi_N \Delta_{\mathbb{H}, h}^{-1} \omega)\|_{L^1(\mathbb{H}^n)} \\
& \leq C \{ \|J_\epsilon * [d_c d_c^*, \chi_N](\Delta_{\mathbb{H}, h}^{-1} \omega)\|_{L^1(\mathbb{H}^n)} + \|J_\epsilon * \chi_N (d_c d_c^* \Delta_{\mathbb{H}, h}^{-1} \omega)\|_{L^1(\mathbb{H}^n)} \} \\
& \leq C \{ \|[d_c d_c^*, \chi_N](\Delta_{\mathbb{H}, h}^{-1} \omega)\|_{L^1(\mathbb{H}^n)} + \|\chi_N (d_c d_c^* \Delta_{\mathbb{H}, h}^{-1} \omega)\|_{L^1(\mathbb{H}^n)} \}.
\end{aligned}$$

If $h = n + 1$, then (35) still holds provided we replace $\|v_{\epsilon, N}\|_{L^{Q/(Q-1)}(\mathbb{H}^n, E_0^n)}$ with $\|v_{\epsilon, N}\|_{L^{Q/(Q-2)}(\mathbb{H}^n, E_0^n)}$.

By Lemma 4.10,

$$(36) \quad d_c d_c^* \Delta_{\mathbb{H}, h}^{-1} \omega = \omega - d_c^* d_c \Delta_{\mathbb{H}, h}^{-1} \omega = \omega.$$

By Lemma 4.1, $[d_c d_c^*, \chi_N]$ can be written as a sum of terms of the form $P_j^h(W^k)$ with $j = 0, 1$, $j + k = 2$ if $h \neq n + 1$, and with $j = 0, 1, 2, 3$, $j + k = 4$ if $h = n + 1$. By Proposition 3.2, ii), in both cases the norm $\|[d_c d_c^*, \chi_N](\Delta_{\mathbb{H}, h}^{-1} \omega)\|_{L^1(\mathbb{H}^n)}$ can be estimated by a sum of terms of the form

$$\frac{1}{N^k} \int_{B(e, 2N) \setminus B(e, N)} |K\omega| dx,$$

where K is a kernel of type $k \geq 1$. Thus, we can apply Theorem 3.13 to conclude that

$$\|[d_c d_c^*, \chi_N](\Delta_{\mathbb{H}, h}^{-1} \omega)\|_{L^1(\mathbb{H}^n)} \longrightarrow 0 \quad \text{as } N \rightarrow \infty.$$

If $\epsilon \rightarrow 0$, then $v_{\epsilon, N} \rightarrow d_c^* (\chi_N \Delta_{\mathbb{H}, h}^{-1} \omega)$ in $L^1(\mathbb{H}^n, E_0^{h-1})$ (and therefore we may assume a.e.). By Fatou's theorem, this provides an $L^{Q/(Q-1)}$ bound on $d_c^* (\chi_N \Delta_{\mathbb{H}, h}^{-1} \omega)$. Since

$$d_c^* (\chi_N \Delta_{\mathbb{H}, h}^{-1} \omega) = \chi_N (d_c^* \Delta_{\mathbb{H}, h}^{-1} \omega) + [d_c^*, \chi_N] \Delta_{\mathbb{H}, h}^{-1} \omega,$$

as N tends to ∞ , this converges a.e. to $d_c^* \Delta_{\mathbb{H}, h}^{-1} \omega$. By Fatou again,

$$\|d_c^* \Delta_{\mathbb{H}, h}^{-1} \omega\|_{L^{Q/(Q-1)}(\mathbb{H}^n)} \leq C \|\omega\|_{L^1(\mathbb{H}^n)}.$$

This completes the proof of i) and iii). Finally, the proof of ii) can be carried out through the same argument, provided we keep in mind Lemma 4.9-i) in order to obtain that $d_c d_c^* d_c d_c^* \Delta_{\mathbb{H}, h}^{-1} \omega = \omega$. \square

5.2. The case of \mathbb{H}^1 . When $n = 1$ and $h = 1$ or 2 , the statement and the proof are slightly different, due to the fact that $\Delta_{\mathbb{H}, h}^{-1}$ in degrees $h = 1, 2$ has a logarithmic behavior, since the order of $\Delta_{\mathbb{H}, h}$ equals the homogeneous dimension $Q = 4$ (see Theorem 4.4, ii)). Incidentally, if $h = 0$ or $h = 3$ the order of $\Delta_{\mathbb{H}, h}$ is $2 < Q$ and there is no difference from the case $n > 1$.

If $h = 1, 2$, the way to circumvent this obstacle is to avoid mentioning $\Delta_{\mathbb{H}, h}^{-1}$ and focus on $d_c^* \Delta_{\mathbb{H}, h}^{-1}$ which is still given by convolution with a kernel of type 2 or 3. Indeed, suppose first $\omega \in L^1(\mathbb{H}^1, E_0^h)$, is compactly supported. Then, keeping in mind that $K \in L_{\text{loc}}^1$, by Theorem 4.4, ii) again, we obtain that $\Delta_{\mathbb{H}, h}^{-1} \omega \in L_{\text{loc}}^1(\mathbb{H}^1, E_0^h)$ (therefore it is a distribution), and we can write

$$(37) \quad d_c^* \Delta_{\mathbb{H}, h}^{-1} \omega =: \omega * \tilde{K},$$

where (keeping in mind Proposition 3.2) \tilde{K} is a kernel of type 3 if $h = 1$ and of type 2 if $h = 2$.

Proposition 5.3. *Assume that $h = 1$ or 2 and $n = 1$. Let \tilde{K} the convolution operator associated with the kernel \tilde{K} . Let $\omega \in L^1(\mathbb{H}^1, E_0^h)$ without any support assumption, then $\tilde{K}\omega \in L_{\text{loc}}^1(\mathbb{H}^1, E_0^h)$,*

$$(38) \quad \|d_c^* d_c \tilde{K}\omega\|_{L^{Q/(Q-1)}(\mathbb{H}^1, E_0^0)} \leq C\|\omega\|_{L^1(\mathbb{H}^1, E_0^1)} \quad \text{for all } \omega \in L_0^1(\mathbb{H}^1, E_0^1) \cap \ker d_c;$$

and

$$(39) \quad \|\tilde{K}\omega\|_{L^{Q/(Q-2)}(\mathbb{H}^1, E_0^1)} \leq C\|\omega\|_{L^1(\mathbb{H}^1, E_0^2)} \quad \text{for all } \omega \in L_0^1(\mathbb{H}^1, E_0^2) \cap \ker d_c;$$

Proof. Let us prove for instance (39). The proof is a mere reformulation of that of Theorem 5.2.

Take $\omega \in L_0^1(\mathbb{H}^1, E_0^2) \cap \ker d_c$. First of all, we want to show that

$$(40) \quad d_c \tilde{K}\omega = \omega \quad \text{and} \quad d_c^* K\omega = 0.$$

To this end, we take a sequence $(\omega_N)_{N \in \mathbb{N}}$ of compactly supported forms converging to ω in $L^1(\mathbb{H}^1, E_0^2)$. It is easy to see that

$$d_c^* \Delta_2^{-1} \omega_N = \tilde{K}\omega_N \rightarrow \tilde{K}\omega \quad \text{in } L_{\text{loc}}^1(\mathbb{H}^1, E_0^1) \text{ as } N \rightarrow \infty,$$

and hence $\tilde{K}\omega_N \rightarrow \tilde{K}\omega$ in $\mathcal{D}'(\mathbb{H}^2, E_0^1)$ together with all their derivatives. In particular

$$(41) \quad d_c^* \tilde{K}\omega = \lim_{N \rightarrow \infty} d_c^* d_c^* \Delta_2^{-1} \omega_N = 0.$$

By Lemma 4.10 (and keeping in mind Remark 3.12) for all $\phi \in \mathcal{D}(\mathbb{H}^2, E_0^3)$, so that

$$\begin{aligned} \lim_{N \rightarrow \infty} \langle d_c^* d_c d_c^* d_c \Delta_2^{-1} \omega_N | \phi \rangle &:= \lim_{N \rightarrow \infty} \langle \Delta_2^{-1} \omega_N | d_c^* d_c d_c^* d_c \phi \rangle \\ &= \lim_{N \rightarrow \infty} \langle \omega_N | \Delta_2^{-1} d_c^* d_c d_c^* d_c \phi \rangle = \lim_{N \rightarrow \infty} \langle \omega_N | d_c^* \Delta_2^{-1} d_c d_c^* d_c \phi \rangle. \end{aligned}$$

On the other hand, since $d_c^* \Delta_2^{-1}$ is a kernel of type 2 and hence $d_c^* \Delta_2^{-1} d_c d_c^* d_c \phi \in L^\infty(\mathbb{H}^2, E_0^3)$,

$$\lim_{N \rightarrow \infty} \langle \omega_N | d_c^* \Delta_2^{-1} d_c d_c^* d_c \phi \rangle = \langle u | d_c^* \Delta_2^{-1} d_c d_c^* d_c \phi \rangle = 0$$

i.e.

$$(42) \quad \lim_{N \rightarrow \infty} \langle d_c^* d_c d_c^* d_c \Delta_{\mathbb{H}, h}^{-1} \omega_N | \phi \rangle = 0.$$

Therefore, by Theorem 4.4, iv) there exists a left invariant form $\beta = \beta(\phi)$ such that

$$\begin{aligned} \langle d_c \tilde{K}u | \phi \rangle &= \lim_{N \rightarrow \infty} \langle d_c \tilde{K}\omega_N | \phi \rangle = \lim_{N \rightarrow \infty} \langle d_c d_c^* \Delta_2^{-1} \omega_N | \phi \rangle \\ &= \lim_{N \rightarrow \infty} \langle (d_c d_c^* + (d_c^* d_c)^2) \Delta_2^{-1} \omega_N | \phi \rangle = \lim_{N \rightarrow \infty} \langle \Delta_2 \Delta_2^{-1} \omega_N | \phi \rangle \\ &= \lim_{N \rightarrow \infty} \langle \omega_N | \Delta_2^{-1} \Delta_2 \phi \rangle \quad (\text{by Remark 3.12}) \\ &= \lim_{N \rightarrow \infty} \langle \omega_N | \phi + \beta \rangle = \langle \omega | \phi + \beta \rangle = \langle \omega | \phi \rangle, \end{aligned}$$

i.e. $d_c \tilde{K}\omega = \omega$. Thus, the proof can be completed arguing basically as in the proof of Theorem 5.2. More precisely, let χ_N be a cut-off function supported in $B(e, 2N)$, $\chi_N \equiv 1$ on $B(e, N)$. If J_ϵ is an usual Friedrich's mollifier for $\epsilon < 1$, let us consider

$$v_{\epsilon, N} := J_\epsilon * \chi_N(\tilde{K}\omega)$$

(notice the slight difference from (33), due to the fact that we cannot split \tilde{K} as $d_c^* \Delta_2^{-1}$). As in Theorem 5.2, $v_{\epsilon, N} \in \mathcal{D}(\mathbb{H}^1, E_0^1)$ and $v_{\epsilon, N} \rightarrow \chi_N(\tilde{K}u)$ in $L^1(\mathbb{H}^1, E_0^1)$ (and therefore we may assume a.e.) as $\epsilon \rightarrow 0$. If we apply the estimates of [3], Theorem 1.3 - iv) and (40) above, we get (to avoid cumbersome notations, when L^p -spaces are involved, we shall drop the target spaces):

$$\begin{aligned}
\|v_{\epsilon, N}\|_{L^{Q/(Q-2)}(\mathbb{H}^1)} &\leq C\{\|d_c v_{\epsilon, N}\|_{L^1(\mathbb{H}^1)} + \|d_c d_c^* v_{\epsilon, N}\|_{L^1(\mathbb{H}^1)}\} \\
&= C\{\|J_\epsilon * d_c \chi_N(\tilde{K}\omega)\|_{L^1(\mathbb{H}^1)} + \|J_\epsilon * d_c d_c^*(\chi_N(\tilde{K}\omega))\|_{L^1(\mathbb{H}^1)}\} \\
&\leq C\{\|d_c \chi_N(\tilde{K}\omega)\|_{L^1(\mathbb{H}^1)} + \|d_c d_c^*(\chi_N(\tilde{K}\omega))\|_{L^1(\mathbb{H}^1)}\} \\
&\leq C\{\|\chi_N \omega\|_{L^1(\mathbb{H}^1)} + \|[d_c, \chi_N](\tilde{K}\omega)\|_{L^1(\mathbb{H}^1)} \\
&\quad + \|[d_c d_c^*, \chi_N](\tilde{K}\omega)\|_{L^1(\mathbb{H}^1)}\} \\
&\leq C\{\|u\|_{L^1(\mathbb{H}^1)} + \|[d_c, \chi_N](\tilde{K}\omega)\|_{L^1(\mathbb{H}^1)} + \|[d_c d_c^*, \chi_N](\tilde{K}\omega)\|_{L^1(\mathbb{H}^1)}\}.
\end{aligned}$$

Thus, by Fatou's lemma

$$\begin{aligned}
\|\chi_N(\tilde{K}\omega)\|_{L^1(\mathbb{H}^n)} &\leq C\{\|\omega\|_{L^1(\mathbb{H}^1)} \\
&\quad + \|[d_c, \chi_N](\tilde{K}\omega)\|_{L^1(\mathbb{H}^1)} + \|[d_c d_c^*, \chi_N](\tilde{K}\omega)\|_{L^1(\mathbb{H}^1)}\}.
\end{aligned}$$

Keep now in mind that $\tilde{K}\omega$ is a form of degree 1, so that both d_c and $d_c d_c^*$ are horizontal operators of order 2. By Lemma 4.1 the two terms containing the commutators can be bounded by terms of the form

$$\frac{1}{N^2} \int_{N \leq |p| \leq 2N} |\tilde{K}\omega| dp$$

or by a sum of terms of the form

$$\frac{1}{N} \int_{N \leq |p| \leq 2N} |W_\ell \tilde{K}\omega| dp.$$

Thus we can conclude obtaining (38) again by Fatou's lemma and Theorem 3.13. \square

Once Theorem 5.2 and Proposition 5.3 are proved, the proof of Theorem 1.1 is straightforward:

5.3. Proof of Theorem 1.1. In the Heisenberg case, Theorem 5.2 and Proposition 5.3 provide L^q primitives (with the announced values of q) for d_c -closed L^1 forms with vanishing averages, in all degrees but the top degree. The Euclidean case is even simpler. This proves Theorem 1.1.

6. INTERIOR INEQUALITIES

Interior inequalities are proven in three steps. Applying cut-offs on forms and on kernels, one first constructs a homotopy K which slightly increases differentiability. Then Rumin's homotopy is used to replace Rumin forms with usual differential forms. Finally, Iwaniec-Lutoborsky's Euclidean homotopy is applied.

6.1. The function space $L^1 \cap d_c^{-1}L^1$. A homotopy is an operator K such that $d_c K + K d_c$ equals identity (up to a loss on domain). To make sense of such an identity, one must restrict to forms α which belong to L^1 and such that $d_c \alpha$ belongs to L^1 as well.

Lemma 6.1. *Let B be a ball in \mathbb{H}^n . We set*

$$(L^1 \cap d_c^{-1}L^1)(B, E_0^\bullet) := \{\alpha \in L^1(B, E_0^\bullet); d_c \alpha \in L^1(B, E_0^{\bullet+1})\},$$

endowed with the graph norm. Then $C^\infty(B, E_0^\bullet)$ is dense in $(L^1 \cap d_c^{-1}L^1)(B, E_0^\bullet)$.

Proof. Take $u \in (L^1 \cap d_c^{-1}L^1)(B, E_0^\bullet)$. If u is compactly supported, then it can be approximated by convolution with Friedrichs' mollifiers J_ϵ for the structure of the group, since $d_c(J_\epsilon * u) = J_\epsilon * d_c u$. The proof of the statement for non-compactly supported forms can be carried out by mimicking verbatim the classical Meyers-Serrin's proof (see [41], Theorem 1.3.3, and [21]). \square

Lemma 6.2. *Let B be a ball in \mathbb{H}^n . Set $K = d_c^* \Delta_{\mathbb{H}}^{-1}$ if $n > 1$ and, if $n = 1$ is defined by (37). If*

$$(43) \quad K_0 := K \quad \text{in degree } h \neq n \text{ and} \quad K_0 := d_c^* d_c K \quad \text{in degree } h = n.$$

Then:

- K_0 is a kernel of type 1 on forms of degree h , $h \neq n + 1$ and of type 2 if $h = n + 1$;
- if χ is a smooth function with compact support in B , then the identity

$$\chi = d_c K_0 \chi + K_0 d_c \chi$$

holds on the space $(L^1 \cap d_c^{-1}L^1)(B, E_0^\bullet)$.

Proof. If $h \neq n - 1, n, n + 1$ and $\mathcal{D}(\mathbb{H}^n, E_0^\bullet)$, then, by Theorem 4.4 and Lemma 4.9, i),

$$\begin{aligned} u &= d_c d_c^* \Delta_{\mathbb{H}}^{-1} u + d_c^* d_c \Delta_{\mathbb{H}}^{-1} u = d_c d_c^* \Delta_{\mathbb{H}}^{-1} u + d_c^* \Delta_{\mathbb{H}}^{-1} d_c u \\ &= d_c K u + K d_c u. \end{aligned}$$

If $h = n - 1$, then

$$\begin{aligned} u &= d_c d_c^* \Delta_{\mathbb{H}}^{-1} u + d_c^* d_c \Delta_{\mathbb{H}}^{-1} u = d_c d_c^* \Delta_{\mathbb{H}}^{-1} u + d_c^* d_c d_c^* \Delta_{\mathbb{H}}^{-1} d_c u \\ &= d_c K u + d_c^* d_c K d_c u. \end{aligned}$$

If $h = n$, then

$$\begin{aligned} u &= (d_c d_c^*)^2 \Delta_{\mathbb{H}}^{-1} u + d_c^* d_c \Delta_{\mathbb{H}}^{-1} u = (d_c d_c^*)^2 \Delta_{\mathbb{H}}^{-1} u + d_c^* \Delta_{\mathbb{H}}^{-1} d_c u \\ &= d_c d_c^* d_c K u + d_c^* K d_c u. \end{aligned}$$

Finally, if $h = n + 1$, then

$$\begin{aligned} u &= d_c d_c^* \Delta_{\mathbb{H}}^{-1} u + d_c^* d_c d_c^* d_c \Delta_{\mathbb{H}}^{-1} u = d_c d_c^* \Delta_{\mathbb{H}}^{-1} u + d_c^* \Delta_{\mathbb{H}}^{-1} d_c u \\ &= d_c K u + K d_c u. \end{aligned}$$

In other words, with notations of (43), for any h we can write

$$u = d_c K_0 u + K_0 d_c u,$$

where K_0 is a kernel of type 1 when it acts on forms of degree h , $h \neq n + 1$ and of type 2 if $h = n + 1$,

Take now $u \in (L^1 \cap d_c^{-1}L^1)(B, E_0^h)$, $0 \leq h \leq 2n+1$. By Lemma 6.1 there exists a sequence $(u_N)_{N \in \mathbb{N}}$ of smooth h -forms on B such that

$$u_N \longrightarrow u \quad \text{in } L^1(\mathbb{H}^n, E_0^h) \text{ as } N \rightarrow \infty.$$

and

$$d_c u_N \longrightarrow d_c u \quad \text{in } L^1(\mathbb{H}^n, E_0^{h+1}) \text{ as } N \rightarrow \infty.$$

Obviously

$$\chi u_N = d_c K_0(\chi u_N) + K_0 d_c(\chi u_N) \quad \text{for all } N \in \mathbb{N}.$$

Since $\chi u_N \rightarrow \chi u$ in $L^1(\mathbb{H}^n, E_0^h)$ as $N \rightarrow \infty$, then $K_0(\chi u_N) \rightarrow K_0(\chi u)$ in $L^1(B, E_0^{h-1})$, and $d_c K_0(\chi u_N) \rightarrow d_c K_0(\chi u)$ in the sense of distributions. Let us consider now $K_0 d_c(\chi u_N) = K_0(\chi d_c u_N + [d_c, \chi]u)$. Obviously, $\chi d_c u_N \rightarrow \chi d_c u$ in $L^1(\mathbb{H}^n, E_0^{h+1})$ as $N \rightarrow \infty$, and then $K_0(\chi d_c u_N) \rightarrow K_0(\chi d_c u)$ in $L^1(B, E_0^h)$.

Let us consider the term $K_0[d_c, \chi]u_N$. If $h \neq n$, then, by Lemma 4.1, $[d_c, \chi]u_N \rightarrow [d_c, \chi]u$ in $L^1(\mathbb{H}^n, E_0^h)$ and we can conclude as above. Thus we are left with the case $h = n$. By Lemma 4.1, $[d_c, \chi]u$ can be written as a sum of terms of the form $(W_i W_j \chi)u_N$ and of the form $W_j \{(W_i \chi)(u_N)_\ell\}$, where $(u_N)_\ell$ is the ℓ -th component of u_N . The terms of the form $(W_i W_j \chi)u_N$ can be handled as above. On the other hand, $K_0 W_j$ is a kernel of type 1, and, again, $(W_i \chi)(u_N)_\ell \rightarrow (W_i \chi)u_\ell$ in $L^1(\mathbb{H}^n)$ and we can conclude as above. \square

6.2. A local smoothing homotopy. It is obtained by cutting off the global inverse of d_c provided in Section 5. This operator can be applied only to global forms whose averages vanish. Therefore we begin by checking that averages vanish for d_c -exact forms.

Lemma 6.3 (see [6], Remark 2.16). *Let $\psi \in L^1(\mathbb{H}^n, E_0^h)$ be a compactly supported form with $d_c \psi \in L^1(\mathbb{H}^n, E_0^{h+1})$, and let $\xi \in \bigwedge^{2n-h}$ be a left-invariant invariant form. Then*

$$\int_{\mathbb{H}^n} d_c \psi \wedge \xi = 0.$$

Proof. By [6], identity (16), we have

$$d_c \psi \wedge \xi = d_c \psi \wedge (\Pi_{E_0} \xi),$$

so that we can assume that $\xi \in E_0^{2n-h}$ (and ξ is still a ‘‘constant coefficient form’’). Moreover, by Lemma 6.1, we can assume that $\psi \in \mathcal{D}(\mathbb{H}^n, E_0^h)$. Thus we can conclude by Remark 2.16 in [6]. \square

Proposition 6.4. *Let $B \Subset B'$ be concentric balls in \mathbb{H}^n . For $h = 1, \dots, 2n$, let $q = Q/(Q-1)$ if $h \neq n+1$ and $q = Q/(Q-2)$ if $h = n+1$. For every $s \in \mathbb{N}$, there exists a smoothing operator $S : L^1(B', E_0^h) \rightarrow W^{s,q}(B, E_0^{h-1})$ and a bounded operator $T : L^1(B', E_0^h) \cap d_c^{-1}(L^1(B', E_0^{h+1})) \rightarrow L^q(B, E_0^{h-1})$, and such that, for L^1 -forms α on B' such that $d_c \alpha \in L^1$,*

$$\alpha = d_c T \alpha + T d_c \alpha + S \alpha \quad \text{on } B.$$

In particular, $d_c S = S d_c$ on $L^1 \cap d_c^{-1}L^1$. Furthermore, there exist $r > 0$ and $p > 1$ such that for all $s \geq 0$, T extends to a bounded operator $L^1(B', E_0^h) \rightarrow W^{r,p}(B, E_0^{h-1})$ and $W^{s,p}(B', E_0^h) \rightarrow W^{s+1,p}(B, E_0^{h-1})$. In degree $n+1$, if W is a horizontal derivative, WT extends to a bounded operator $L^1(B', E_0^n) \rightarrow W^{r,p}(B, E_0^n)$ and $W^{s,p}(B', E_0^n) \rightarrow W^{s+1,p}(B, E_0^n)$.

Finally, T and S merely enlarge by a small amount the support of differential forms.

Proof. Let us fix two balls B_0, B_1 with

$$(44) \quad B \Subset B_0 \Subset B_1 \Subset B',$$

and a cut-off function $\chi \in \mathcal{D}(B_1)$, $\chi \equiv 1$ on B_0 . If $\alpha \in (L^1 \cap d_c^{-1})(B', E_0^\bullet)$, we set $\alpha_0 = \chi\alpha$, continued by zero outside B_1 . Denote by k_0 the kernel associated with K_0 in Lemma 6.2. We consider a cut-off function ψ_R supported in a R -neighborhood of the origin, such that $\psi_R \equiv 1$ near the origin. Then we can write $k_0 = k_0\psi_R + (1 - \psi_R)k_0$. Let us denote by $K_{0,R}$ the convolution operator associated with $\psi_R k_0$. By Lemma 6.2,

$$(45) \quad \begin{aligned} \alpha_0 &= d_c K_0 \alpha_0 + K_0 d_c \alpha_0 \\ &= d_c K_{0,R} \alpha_0 + K_{0,R} d_c \alpha_0 + S_0 \alpha_0, \end{aligned}$$

where S_0 is defined by

$$S_0 \alpha_0 := d_c((1 - \psi_R)k_0 * \alpha_0) + (1 - \psi_R)k_0 * d_c \alpha_0.$$

We set

$$T_1 \alpha := K_{0,R} \alpha_0, \quad S_1 \alpha := S_0 \alpha_0.$$

Since the kernel $\psi_R k_0 \in L^1$, $K_{0,R}$ maps L^1 to L^1 .

If $\beta \in L^1(B_1)$, we set

$$T_1 \beta := K_{0,R}(\chi\beta)|_B, \quad S_1 \alpha := S_0 \alpha_0|_B.$$

We notice that, provided $R > 0$ is small enough, the values of $T_1 \beta$ do not depend on the continuation of β outside B_1 . Moreover

$$K_{0,R} d_c \alpha_0|_B = K_{0,R} d_c(\chi\alpha)|_B = K_{0,R}(\chi d_c \alpha)|_B = T_1(d_c \alpha),$$

since $d_c(\chi\alpha) \equiv \chi d_c \alpha$ on B_0 . Thus, by (45),

$$\alpha = d_c T_1 \alpha + T_1 d_c \alpha + S_1 \alpha \quad \text{in } B.$$

Write $\phi = T_1 \alpha \in L^1(B_0)$. By difference, $d_c \phi = \alpha - S_1 \alpha - T_1 d_c \alpha \in L^1(B_0)$.

Unfortunately, so far one cannot assert that $\phi \in L^q(B_0)$ and we must in some sense “iterate” the argument. Let us sketch how this iteration will work: let ζ be a cut-off function supported in B_0 , identically equal to 1 in a neighborhood \mathcal{U} of B , and set $\omega = d_c(\zeta\phi)$. Obviously, the form $\zeta\phi$ (and therefore also ω) are defined on all \mathbb{H}^n and are compactly supported in B_0 . In addition, ω is closed. Suppose for a while we are able to prove that

- a) $\omega \in L^1(\mathbb{H}^n)$;
- b) $\|K_{0,R}\omega\|_{L^q(\mathbb{H}^n)} \leq C\|\alpha\|_{L^1(B')}$ for some $q > 1$,

and let us show how the argument can be carried out (here and in the sequel of the proof, to avoid cumbersome notations, when L^p -spaces are involved, we drop the target spaces).

First we stress that, if R is small enough, then when $x \in B$, $K_{0,R}\omega(x)$ depends only on the restriction of $d_c \phi$ to \mathcal{U} , so that the map

$$\alpha \rightarrow K_{0,R}\omega|_B$$

is linear.

Notice that $\omega = \chi\omega$, so that, by (45),

$$d_c(\zeta\phi) = \omega = d_c K_{0,R}\omega + S_0\omega.$$

Therefore in B

$$\alpha - S_1\alpha - T_1 d_c\alpha = d_c\phi = d_c(\zeta\phi) = d_c K_{0,R}\omega + S_0\omega,$$

and then in B

$$\begin{aligned} \alpha &= T_1 d_c\alpha + d_c(K_{0,R}\omega|_B) + S_1\alpha|_B + S_0\omega|_B \\ &= T_1 d_c\alpha + d_c(K_{0,R}(\chi\omega)|_B) + S\alpha \\ &=: \bar{T}d_c\alpha + d_c T\alpha + S\alpha. \end{aligned}$$

First notice that the map $\alpha \rightarrow \omega = \omega(\alpha)$ is linear, and hence \bar{T} , T and S are linear maps. In addition, by b),

$$\|T\alpha\|_{L^q(B)} \leq \|K_{0,R}(\chi\omega)\|_{L^q(\mathbb{H}^n)} = \|K_{0,R}(\omega)\|_{L^q(\mathbb{H}^n)} \leq C(\|\alpha\|_{L^1(B')} + \|d\alpha\|_{L^1(B')}).$$

As for the map $\alpha \rightarrow S\alpha$ we have just to point out that, when $x \in B$, $S\alpha(x)$ can be written as the convolution of α_0 with a smooth kernel with bounded derivatives of any order.

We observe that the cut-offs χ, ζ have no influence on the restriction of $T\alpha$ or $\bar{T}\alpha$ to B . Therefore T and \bar{T} coincide as bounded operators $L^1(B') \cap d_c^{-1}(L^1(B')) \rightarrow L^q(B)$.

Thus we are left with the proof of a) and b). To this end, we must deal separately with the case when degree of ω equals $n + 1$.

With our previous notations, if the degree of ϕ is different from n (i.e. if the degree of ω is different from $n + 1$), then $[d_c, \zeta]$ is a linear operator of order 0 with coefficients compactly supported in B_0 . Therefore

$$\omega = \zeta d_c\phi + [d_c, \zeta]\phi \in L^1(\mathbb{H}^n).$$

Thus, we can apply Lemma 6.3 to $\psi := \zeta\phi$ and we conclude that

$$\omega \in L_0^1(\mathbb{H}^n) \cap \ker(d).$$

Therefore, by Theorem 5.2, $K_0\omega \in L^q(\mathbb{H}^n)$, where $q = Q/(Q - 1)$. Let us prove that the same assertion holds for $K_{0,R}\omega$ and hence $\phi \in L^q(B')$. In fact,

$$\begin{aligned} K_{0,R}\omega(x) &= K_0\omega(x) + (\psi_R - 1)k_0 * \omega(x) \\ &= K_0\omega(x) + \int_{\mathbb{H}^n} (\psi_R - 1)k_0(y^{-1}x)\omega(y) dy. \end{aligned}$$

Notice now that $(\psi_R - 1)k_0$ is a smooth function and that $y^{-1}x$ lies in a compact set when $x \in B'$ (since ω is compactly supported). Thus

$$\|(\psi_R - 1)k_0 * \omega\|_{L^q(B')} \leq C \|(\psi_R - 1)k_0\|_{L^q(B')} \|\omega\|_{L^1(B')} \leq C' \|\omega\|_{L^1(B')}.$$

Suppose now the degree of ϕ equals n .

Then, by Lemma 4.1 $[d_c, \zeta]$, is the sum of a linear operator $P_0(W^2\zeta)$ of order 0 with coefficients compactly supported in B_0 , and of a linear operator $P_1(W\zeta)$ of order 1 with coefficients compactly supported in B_0 . As above,

$$\omega = \zeta d_c\phi + [d_c, \zeta]\phi = \zeta d_c\phi + P_0(W^2\zeta)\phi + P_1(W\zeta)\phi.$$

Again

$$\zeta d_c\phi + P_0(W^2\zeta)\phi \in L^1(\mathbb{H}^n).$$

Notice now that, if ϕ has degree n , then

$$P_1(W\zeta)\phi = P_1(W\zeta)K_{0,R}(\chi\alpha).$$

But α has degree $n+1$, so that, by Lemma 6.2, it is associated with a kernel of type 2. Thus, by Lemma 3.10 and Corollary 3.8, and keeping in mind that the coefficients of P_1 are compactly supported in B_0

$$P_1(W\zeta)\phi \in L^1(\mathbb{H}^n),$$

so that again

$$\omega \in L^1(\mathbb{H}^n)$$

and

$$(46) \quad \|\omega\|_{L^1(\mathbb{H}^n)} \leq C\|\alpha\|_{L^1(B')}.$$

Again, we can apply Lemma 6.3 to $\psi := \zeta\phi$ and we conclude that

$$\omega \in L_0^1(\mathbb{H}^n) \cap \ker(d).$$

This proves a). On the other hand, by Theorem 5.2, $K_0\omega \in L^q(\mathbb{H}^n)$, where $q = Q/(Q-2)$. Arguing as above, the same assertion holds for $K_{0,R}\omega$ and b) follows keeping in mind (46).

We observe that $T\omega = K_{0,R}(\chi\omega)$, where K has compactly supported kernel $\psi_R k_0$, with k_0 of type 1 (resp. type 2 if $h = n+1$). If $h \neq n+1$, Lemma 3.26 and Theorem 3.27 apply. If $h = n+1$,

$$(47) \quad WT\omega = W(\chi\omega * \psi_R k_0) = \chi\omega * W(\psi_R k_0)$$

$$(48) \quad = \chi\omega * (W\psi_R)k_0 + \chi\omega * \psi_R(Wk_0).$$

Lemma 3.26 and Theorem 3.27 apply to both terms. They provide an $r > 0$ and a $p > 1$ such that T (resp. WT) maps $L^1(\mathbb{H}^n)$ to $W_{\text{loc}}^{r,p}(\mathbb{H}^n)$ and $W^{s,p}(\mathbb{H}^n)$ to $W_{\text{loc}}^{s+1,p}(\mathbb{H}^n)$. □

6.3. Composition of homotopies. This is the final step which provides an inverse to d_c on d_c -closed L^1 forms defined on a ball, as stated in Theorem 1.2.

Corollary 6.5 (Interior Poincaré and Sobolev inequalities). *Let $B \Subset B'$ be concentric balls in \mathbb{H}^n . For $h = 1, \dots, 2n$, let $q = Q/(Q-1)$ if $h \neq n+1$ and $q = Q/(Q-2)$ if $h = n+1$. For every d_c -closed h -form $\alpha \in L^1(B', E_0^h)$, there exists an $h-1$ -form $\phi \in L^q(B, E_0^{h-1})$, such that*

$$d_c\phi = \alpha|_B \quad \text{and} \quad \|\phi\|_{L^q(B, E_0^{h-1})} \leq C\|\alpha\|_{L^1(B', E_0^h)}.$$

Furthermore, if α is compactly supported, so is ϕ .

Proof. Proposition 6.4 allows to replace α with $S\alpha$ whose first 3 derivatives, in L^2 norm, are controlled by $\|\alpha\|_1$. Then $\beta = \Pi_E(S\alpha)$ and its 2 first derivatives are controlled by $\|\alpha\|_1$, and $d\beta = 0$. Apply Iwaniec-Lutoborski's homotopy [25] to get a differential $(h-1)$ -form γ on B such that $d\gamma = \beta$ and with 2 first derivatives controlled by $\|\alpha\|_1$ in L^2 (IL's homotopy is an operator of type 1). The Euclidean

Sobolev inequality implies that $\|\gamma\|_q$ is controlled by $\|\alpha\|_1$, for $q = Q/(Q - 2)$. *A fortiori*, for $q = Q/(Q - 1)$. So is $\|\phi\|_q$, where $\phi = \Pi_{E_0}\gamma$ satisfies

$$\begin{aligned} d_c\phi &= \Pi_{E_0}d\Pi_E\Pi_{E_0}\gamma \\ &= \Pi_{E_0}d\gamma \\ &= \Pi_{E_0}\Pi_E S\alpha \\ &= S\alpha. \end{aligned}$$

This proves the interior Poincaré inequality.

Allowing S to win 4 derivatives instead of 3 provides a control on the $W^{2,p}$ norm of β for some $p > 1$. This allows to replace Iwaniec-Lutoborski's homotopy [25] with Mircea-Mircea-Monnier's homotopy [31] which preserves compactly supported forms. When α is compactly supported, so are $S\alpha$, β , the primitive γ provided by Mircea-Mircea-Monnier, and ϕ . This proves a Sobolev inequality. \square

Remark 6.6. *Without loss of generality, in Corollary 6.5 we can assume that $d_c^*\phi = 0$, provided we replace B by a smaller ball $\tilde{B} \Subset B$. Indeed, let ψ be a cut-off function, $\psi \equiv 1$ on \tilde{B} and $\text{supp } \psi \subset B$. Set*

$$\tilde{\phi} := d_c^*d_c\Delta_{\mathbb{H}}^{-1}(\psi\phi).$$

Obviously, $d_c^*\tilde{\phi} = 0$. Since $d_c^*d_c\Delta_{\mathbb{H}}^{-1}$ is associated with a kernel of type 0 and $q > 1$, we have

$$\begin{aligned} \|\tilde{\phi}\|_{L^q(\tilde{B}, E_0^{h-1})} &\leq \|\tilde{\phi}\|_{L^q(\mathbb{H}^n, E_0^{h-1})} \\ &\leq C\|\psi\phi\|_{L^q(\mathbb{H}^n, E_0^{h-1})} \leq C\|\phi\|_{L^q(B, E_0^{h-1})} \leq C\|\alpha\|_{L^q(B', E_0^h)}. \end{aligned}$$

Notice now that

$$\psi\phi = d_c d_c^* \Delta_{\mathbb{H}}^{-1}(\psi\phi) + d_c^* d_c \Delta_{\mathbb{H}}^{-1}(\psi\phi) = d_c d_c^* \Delta_{\mathbb{H}}^{-1}(\psi\phi) + \tilde{\phi}.$$

Thus in \tilde{B}

$$d_c \tilde{\phi} = d_c(\psi\phi) = d_c\phi = \alpha.$$

The following globalization procedure, established for spaces of L^p differential forms, $p > 1$, in [5], extends to L^1 .

7. BOUNDED GEOMETRY RIEMANNIAN AND CONTACT MANIFOLDS

A contact structure on an odd-dimensional manifold M is a smooth distribution of hyperplanes H which is maximally nonintegrable in the following sense: if θ is a locally defined smooth 1-form such that $H = \ker(\theta)$, then $d\theta$ restricts to a non-degenerate 2-form on H , i.e. if $2n + 1$ is the dimension of M , then $\theta \wedge (d\theta)^n \neq 0$ on M (see [30], Proposition 3.41). A contact manifold (M, H) is the data of a smooth manifold M and a contact structure H on M .

Contact diffeomorphisms are contact structure preserving diffeomorphisms between contact manifolds.

We recall that, by a classical theorem of Darboux, any contact manifold (M, H) is locally contact diffeomorphic to the Heisenberg group \mathbb{H}^n (see [30], p. 112).

We recall that the construction of Rumin's complex can be carried out for general contact manifolds (see, e.g. [38], [39]) yielding a complex of differential forms - still denoted by (E_0^\bullet, d_c) - such that

$$\text{i) } d_c^2 = 0;$$

- ii) the complex (E_0^\bullet, d_c) is homotopically equivalent to the de Rham complex $\Omega := (\Omega^\bullet, d)$. Thus, if $D \subset \mathbb{H}^n$ is an open set, unambiguously we write $H^h(D)$ for the h -th cohomology group;
- iii) $d_c : E_0^h \rightarrow E_0^{h+1}$ is a homogeneous differential operator in the horizontal derivatives (i.e. derivatives along H) of order 1 if $h \neq n$, whereas $d_c : E_0^n \rightarrow E_0^{n+1}$ is an homogeneous differential operator of order 2 in the horizontal derivatives.

Moreover, if ϕ is a contactomorphism from an open set $\mathcal{U} \subset \mathbb{H}^n$ to M , and we denote by \mathcal{V} the open set $\mathcal{V} := \phi(\mathcal{U})$, we have

- i) $\phi^\# E_0^\bullet(\mathcal{V}) = E_0^\bullet(\mathcal{U})$;
- ii) $d_c \phi^\# = \phi^\# d_c$.
- iii) if ζ is a smooth function in M , then the differential operator in $\mathcal{U} \subset \mathbb{H}^n$ defined by $v \rightarrow \phi^\#[d_c, \zeta](\phi^{-1})^\# v$ is a differential operator of order zero if $v \in E_0^h(\mathcal{U})$, $h \neq n$ and a differential operator of order 1 if $v \in E_0^n(\mathcal{U})$

(see [5], Proposition 3.11).

If a Riemannian metric g is defined on H , we refer to the (M, H, g) as to a sub-Riemannian contact manifold.

In turn, in any sub-Riemannian contact manifold (M, H, g) we can define a sub-Riemannian distance d_M (see e.g. [32]) inducing on M the same topology of M as a manifold. In particular, Heisenberg groups can be viewed as sub-Riemannian contact manifolds. If we choose on the contact sub-bundle of \mathbb{H}^n a left-invariant metric, it turns out that the associated sub-Riemannian metric is left-invariant, too.

7.1. Bounded geometry and controlled coverings. We give now the definition of Riemannian manifold of bounded geometry as well as the definition of contact manifold of bounded geometry.

Definition 7.1. *Let k be a positive integer and let $B(0, 1)$ denote the unit ball in \mathbb{R}^n . We say that a Riemannian manifold (M, g) has bounded C^k -geometry if there exist constants $r, C > 0$ such that, for every $x \in M$, there exists a diffeomorphism preserving $\phi_x : B(0, 1) \rightarrow M$ that satisfies*

- (1) $B(x, r) \subset \phi_x(B(0, 1))$;
 - (2) ϕ_x is C -bi-Lipschitz, i.e.
- $$(49) \quad \frac{1}{C}|p - q| \leq d_M(\phi_x(p), \phi_x(q)) \leq C|p - q| \quad \text{for all } p, q \in B(0, 1);$$
- (3) coordinate changes $\phi_x \circ \phi_y^{-1}$ and their first k derivatives are bounded by C .

The counterpart of the above definition for subRiemannian contact manifolds reads as follows:

Definition 7.2. *Let k be a positive integer and let $B(e, 1)$ denote the unit sub-Riemannian ball in \mathbb{H}^n . We say that a subRiemannian contact manifold (M, H, g) has bounded C^k -geometry if there exist constants $r, C > 0$ such that, for every $x \in M$, there exists a contactomorphism (i.e. a diffeomorphism preserving the contact structure) $\phi_x : B(e, 1) \rightarrow M$ that satisfies*

- (1) $B(x, r) \subset \phi_x(B(e, 1))$;
 - (2) ϕ_x is C -bi-Lipschitz, i.e.
- $$(50) \quad \frac{1}{C}d(p, q) \leq d_M(\phi_x(p), \phi_x(q)) \leq Cd(p, q) \quad \text{for all } p, q \in B(e, 1);$$

- (3) coordinate changes $\phi_x \circ \phi_y^{-1}$ and their first k derivatives with respect to unit left-invariant horizontal vector fields are bounded by C .

In [5], Lemma 5.10, we proved the following covering lemma (that is basically [29], Theorem 1,2). We state it for subRiemannian contact manifolds, but it still holds in the Riemannian setting.

Lemma 7.3. *Let (M, H, g) be a bounded C^k -geometry subRiemannian contact manifold, where k is a positive integer. Then there exists $\rho > 0$ (depending only on the radius r of Definition 7.2) and an at most countable covering $\{B(x_j, \rho)\}$ of M such that*

- i) each ball $B(x_j, \rho)$ is contained in the image of one of the contact charts of Definition 7.2;
- ii) $B(x_j, \frac{1}{5}\rho) \cap B(x_i, \frac{1}{5}\rho) = \emptyset$ if $i \neq j$;
- iii) the covering is uniformly locally finite. Even more, there exists a $N = N(M) \in \mathbb{N}$ such that for each ball $B(x, \rho)$

$$\#\{k \in \mathbb{N} \text{ such that } B(x_k, \rho) \cap B(x, \rho) \neq \emptyset\} \leq N.$$

In addition, if $B(x_k, \rho) \cap B(x, \rho) \neq \emptyset$, then $B(x_k, \rho) \subset B(x, r)$, where $B(x, r)$ has been defined in Definition 7.2-(2);

- iv) all balls $B(x_k, \rho)$ have comparable measures.

7.2. Sobolev spaces of Rumin forms on contact manifolds. A key feature of Rumin's complex for Heisenberg groups is its invariance under smooth contactomorphisms: if U and V are open subsets of \mathbb{H}^n and $\phi : U \rightarrow V$ is a contact structure preserving diffeomorphism, then ϕ pulls back Rumin forms. We use the same notation $\phi^\#$ as for the pull-back of usual differential forms. We use this to define Sobolev spaces on bounded geometry contact subRiemannian manifolds. They will be needed in the construction of global smoothing homotopies, Proposition 8.1.

In the Riemannian setting, Sobolev spaces of differential forms are invariant with respect to the pull-back operator associated with sufficiently smooth diffeomorphisms (see, e.g. [41], Lemma 1.3.9). An analogous statement holds for Folland-Stein Sobolev spaces in Heisenberg groups, provided we restrict ourselves to contact diffeomorphisms. Indeed we have:

Lemma 7.4. *If k is a positive integer, let $U, V \subset \mathbb{H}^n$ be connected open extension subsets of \mathbb{H}^n (see Definition 3.22). Let U_0, V_0 be open neighborhoods of U and V , respectively, and let $\phi : U_0 \rightarrow V_0$ be a C^k -bounded contact diffeomorphism such that $\phi(U) \subset V$. If $p > 1$ and s is a real number, $0 \leq s \leq k - 1$ then the pull-back operator $\phi^\#$ from $W^{s,p}(V, E_0^\bullet)$ to $W^{s,p}(U, E_0^\bullet)$ is bounded, and its norm depends only on the C^k norms of ϕ and ϕ^{-1} . This extends to $p = 1$ if s is an integer.*

Proof. Consider the case $p > 1$. The proof for the case $p = 1$ is analogous but shorter, since we do not need interpolation arguments. Let $\psi \in \mathcal{D}(\mathbb{H}^n)$ be a cut-off function supported in V_0 , $\psi \equiv 1$ on V . If $u \in \mathcal{D}(\mathbb{H}^n, E_0^\bullet)$, then $\phi^\#(r_{V_0}(\psi u))$ is well defined and supported in U_0 , so that can be continued by zero outside U_0 . Denote by $(\phi^\#(r_{V_0}(\psi u)))_0$ this extension. Suppose now $u \in \mathcal{D}(\mathbb{H}^n, E_0^\bullet)$, and consider the map

$$u \rightarrow L(u) := (\phi^\#(r_{V_0}(\psi u)))_0.$$

If s is an integer, by the chain rule and our assumptions on ϕ

$$\|(\phi^\#(r_{V_0}(\psi u)))_0\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)} \leq C \|u\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)}.$$

Thus, by density and interpolation, L is a bounded linear operator from $W^{s,p}(\mathbb{H}^n, E_0^\bullet)$ to $W^{s,p}(\mathbb{H}^n, E_0^\bullet)$ for $s \geq 0$.

Take now $\alpha \in W^{s,p}(V, E_0^\bullet)$, and let $\tilde{\alpha} \in W^{s,p}(\mathbb{H}^n, E_0^\bullet)$ an arbitrary extension of α outside V . We notice that $(\phi^\#(r_{V_0}(\psi\tilde{\alpha}))_0)$ is an extension of $\phi^\#(\alpha)$ outside U . Indeed, if $x \in U$ (and therefore $\phi(x) \in V$) and v_1, \dots, v_\bullet are tangent vectors at x , we have

$$\begin{aligned} & (\phi^\#(r_{V_0}(\psi\tilde{\alpha}))_0)(x)(v_1, \dots, v_\bullet) \\ &= \phi^\#(r_{V_0}(\psi\tilde{\alpha}))(x)(v_1, \dots, v_\bullet) \\ &= r_{V_0}(\psi\tilde{\alpha})(\phi(x))(d\phi(x)v_1, \dots, d\phi(x)v_\bullet) \\ &= \psi\tilde{\alpha}(\phi(x))(d\phi(x)v_1, \dots, d\phi(x)v_\bullet) \\ &= \alpha(\phi(x))(d\phi(x)v_1, \dots, d\phi(x)v_\bullet) \\ &= \phi^\#(\alpha)(x)(v_1, \dots, v_\bullet). \end{aligned}$$

Then

$$\|\phi^\#(\alpha)\|_{W^{s,p}(UE_0^\bullet)} \leq \|(\phi^\#(r_{V_0}(\psi\tilde{\alpha}))_0)\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)} \leq C\|\tilde{\alpha}\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)}.$$

Taking the infimum of the right-hand side of this inequality for all extensions $\tilde{\alpha} \in W^{s,p}(\mathbb{H}^n, E_0^\bullet)$ of α , the assertion follows. \square

Definition 7.5. Let k be a positive integer, and let (M, H, g) be a bounded C^k -geometry subRiemannian contact manifold, and let $\{\chi_j\}$ be a partition of unity subordinate to the atlas $\mathcal{U} := \{B(x_j, \rho), \phi_{x_j}\}$ of Lemma 7.3. From now on, for the sake of simplicity, we shall write $\phi_j := \phi_{x_j}$. We stress that $\phi_j^{-1}(\text{supp } \chi_j) \subset B(e, 1)$. Fix $a \geq 1$, $p \geq 1$ and $s \in \mathbb{R}$, $0 \leq s \leq k - 1$. If α is a Rumin differential form on M , we say that $\alpha \in \ell^a(W^{s,p})_{\mathcal{U}}(M, E_0^\bullet)$ if

$$\phi_j^\#(\chi_j\alpha) \in W^{s,p}(\mathbb{H}^n, E_0^\bullet) \quad \text{for } j \in \mathbb{N}$$

(notice that $\phi_j^\#(\chi_j\alpha)$ is compactly supported in $B(e, 1)$ and therefore can be continued by zero on all of \mathbb{H}^n) and the sequence $\|\phi_j^\#(\chi_j\alpha)\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)}^a$ is summable. Then we set

$$\|\alpha\|_{\ell^a(W^{s,p})_{\mathcal{U}}(M, E_0^\bullet)} := \left(\sum_j \|\phi_j^\#(\chi_j\alpha)\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)} \right)^{1/a}.$$

Obviously, the same definition can be formulated for bounded C^k -geometry Riemannian manifolds. One recovers global $W^{s,p}$ spaces of \mathbb{R}^n and \mathbb{H}^n by taking $a = p$.

The following result shows that the definition of the Sobolev spaces $\ell^a(W^{s,p})_{\mathcal{U}}(M, E_0^\bullet)$ do not depend on the atlas \mathcal{U} . An analogous statement holds in the Riemannian setting. Therefore, once the proposition is proved, we drop the index \mathcal{U} from the notation for Sobolev norms.

Proposition 7.6. Let k , a , p and s be as above, and let (M, H, g) be a bounded C^k -geometry subRiemannian contact manifold. If $\mathcal{U}' := \{B(y_j, \rho'), \phi'_{y_j}\}$ is another atlas of M satisfying Definition 7.2 and Lemma 7.3 with the same choice of ρ , and $\{\chi'_j\}$ is an associated partition of unity, then

$$\ell^a(W^{s,p})_{\mathcal{U}}(M, E_0^\bullet) = \ell^a(W^{s,p})_{\mathcal{U}'}(M, E_0^\bullet),$$

with equivalent norms.

Proof. Let $j \in \mathbb{N}$ be fixed, and let $(B(x_j, \rho), \phi_j)$ be a chart of \mathcal{U} . We can write

$$\chi_j = \sum_{k \in I_j} \chi'_k \chi_j,$$

where $\#I_j \leq N$, since, by Lemma 7.3 iii), $B(x_j, \rho)$ is covered by at most N balls of the covering associated with \mathcal{U}' . Thus, by Definition 7.2-(3) and keeping in mind that $\text{supp } \chi'_k \subset B(x_j, r)$ (since $3\rho < r$), we have

$$\begin{aligned} \|\phi_j^\#(\chi_j \alpha)\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)} &\leq \sum_{k \in I_j} \|\phi_j^\#(\chi'_k \chi_j \alpha)\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)} \\ &\leq c \sum_{k \in I_j} \|\phi_j^\#(\chi'_k \alpha)\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)} \\ &= c \sum_{k \in I_j} \|(\phi_j \phi_k'^{-1})^\# \phi_k'^\#(\chi'_k \alpha)\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)} \\ &\leq c \sum_{k \in I_j} \|\phi_k'^\#(\chi'_k \alpha)\|_{W^{s,p}(\mathbb{H}^n, E_0^\bullet)} \\ &\leq cN \|\alpha\|_{W_{\mathcal{U}'}^{s,p}(M, E_0^\bullet)}. \end{aligned}$$

A similar inequality holds for a -th powers, since the number of terms in the sum is bounded. \square

8. SMOOTHING HOMOTOPIES ON BOUNDED GEOMETRY (CONTACT) MANIFOLDS

8.1. Proof of Theorem 1.3. Here, we piece together local smoothing homotopies using contact charts and a partition of unity. The formula for the global smoothing operator S mixes local smoothing operators S and homotopies T , therefore the gain in differentiability is less than 1. It needs to be measured in terms of fractional Sobolev spaces. Iterating the initial operator allows to gain arbitrarily large numbers of derivatives.

Proposition 8.1 (Global smoothing homotopies). *Let $k \geq 3$ be an integer index, and let M be a subRiemannian contact manifold of dimension $2n + 1$ and bounded C^k -geometry. For $h = 1, \dots, 2n$, let $q = Q/(Q - 1)$ if $h \neq n + 1$ and $q = Q/(Q - 2)$ if $h = n + 1$. Let $1 \leq q' \leq q$. There exist an operator T_M on h -forms on M which is bounded from $L^1(M, E_0^\bullet) \cap d^{-1}L^1(M, E_0^\bullet)$ to $L^{q'}(M, E_0^\bullet)$ and an operator S_M which is bounded from $L^1(M, E_0^\bullet) \cap d^{-1}L^1(M, E_0^\bullet)$ to $W^{k-1, q'}(M, E_0^\bullet)$ such that $1 = S_M + d_c T_M + T_M d_c$.*

Proof. The global operators S_M and T_M are obtained in two steps. First, one transports by charts ϕ_j the local operators S and T constructed on Heisenberg balls in Proposition 6.4 and one pieces them together using a controlled partition of unity $\{\chi_j\}$. Note that the following formulae differ from those of [5], section 7.

$$\mathbf{T}u := \sum_j \chi_j((\phi_j^{-1})^\#(T(\phi_j^\#(u|_{10B_j}))_{B'_\mathbb{H}})_{B_\mathbb{H}})|_{B_j},$$

$$\begin{aligned} \mathbf{S}u &:= \sum_j \chi_j((\phi_j^{-1})^\#(S(\phi_j^\#(u|_{10B_j}))_{B'_\mathbb{H}})_{B_\mathbb{H}})|_{B_j} \\ &\quad - \sum_j [\chi_j, d_c]((\phi_j^{-1})^\#(T(\phi_j^\#(u|_{10B_j}))_{B'_\mathbb{H}})_{B_\mathbb{H}})|_{B_j}. \end{aligned}$$

In these formulae, u is a Rumin form defined globally on M . The chart ϕ_j is defined on the larger Heisenberg ball B' , it maps it into $10B_j$. The image of the smaller Heisenberg ball B' contains B_j . Therefore T can be applied to the pulled-back form $\phi_j^\#(u)$ and the form $T\phi_j^\#(u)$, which depends only on the restriction of u to $10B_j$, is defined on all of B . Its push-forward to M is defined on B_j . The product of this form with χ_j has compact support in B_j . Therefore the sum is locally finite (only boundedly many terms do not vanish at a given point). In the sequel, the notation will be abbreviated as

$$(51) \quad \mathbf{T}u := \sum_j \chi_j(\phi_j^{-1})^\# T\phi_j^\#(u)$$

and

$$(52) \quad \mathbf{S}u := \sum_j \chi_j(\phi_j^{-1})^\# S\phi_j^\#(u) - \sum_j [\chi_j, d_c](\phi_j^{-1})^\# T\phi_j^\#(u).$$

Second, one iterates \mathbf{S} , i.e. one sets $S_M = \mathbf{S}^\ell$ for ℓ large enough.

Given a function space F of forms on the unit Heisenberg ball, let us denote by $\ell^\alpha(F)$ the space of differential forms ω on M such that the sequence $\|\phi_j^\#\omega|_{B_j}\|_F$ belongs to ℓ^α .

Since the covering has bounded multiplicity,

$$\ell^1(L^1(M, E_0^\bullet)) = L^1(M, E_0^\bullet)$$

and

$$\ell^1(L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet))) = L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet)).$$

Indeed, let us prove (for instance) the first equality. If N is an upper bound for the multiplicity of the covering $\{10B_i\}$, for every form u ,

$$\|u\|_{\ell^1(L^1(M, E_0^\bullet))} = \sum_j \|u|_{10B_j}\|_{L^1(10B_j, E_0^\bullet)} \leq N \|u\|_{L^1(M, E_0^\bullet)}.$$

Let us show that \mathbf{S} and \mathbf{T} win a bit of differentiability:

- \mathbf{S} and $\mathbf{T} : \ell^1(L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet))) \rightarrow \ell^1(W^{r,p}(M, E_0^\bullet))$ are bounded for some $r > 0$ and some $p > 1$;
- for all $1 \leq s \leq k-1$, \mathbf{S} and $\mathbf{T} : \ell^1(W^{s-1,p}(M, E_0^\bullet)) \rightarrow \ell^1(W^{s,p}(M, E_0^\bullet))$ are bounded;
- for all $0 \leq s \leq k-1$, $\mathbf{T}d_c$ and $d_c\mathbf{T} : \ell^1(W^{s,p}(M, E_0^\bullet)) \rightarrow \ell^1(W^{s,p}(M, E_0^\bullet))$ are bounded.

First, let us understand local continuity properties. In the expressions for \mathbf{S} , \mathbf{T} , $d_c\mathbf{T}$ and $\mathbf{T}d_c$, we find the following types of terms:

$$(53) \quad \chi_j(\phi_j^{-1})^\# S\phi_j^\# = (\phi_j^{-1})^\# (\chi S)\phi_j^\#,$$

$$(54) \quad [\chi_j, d_c](\phi_j^{-1})^\# T\phi_j^\# = (\phi_j^{-1})^\# ([\chi, d_c]T)\phi_j^\#,$$

$$(55) \quad \chi_j(\phi_j^{-1})^\# T\phi_j^\# = (\phi_j^{-1})^\# (\chi T)\phi_j^\#,$$

$$(56) \quad \chi_j(\phi_j^{-1})^\# T\phi_j^\# d_c = (\phi_j^{-1})^\# (\chi T d_c)\phi_j^\#,$$

$$(57) \quad \chi_j d_c(\phi_j^{-1})^\# T\phi_j^\# = (\phi_j^{-1})^\# (\chi d_c T)\phi_j^\#,$$

where $\chi = \chi_j \circ \phi_j$. From Theorem 3.19, we know that multiplication by a function $\chi \in \mathcal{D}$ is a bounded operator on all Sobolev spaces $W^{s,p}$, with norm depending on the size of horizontal derivatives of χ only. Since functions $\chi_j \circ \phi_j$ have uniformly horizontal bounded derivatives, we can ignore them in the sequel.

Proposition 6.4 takes care of terms of the form S , T , Td_c and d_cT . Only $[\chi, d_c]T$ remains. If $h \neq n+1$, then the commutator has order zero and $[\chi, d_c]T$ can be written as a linear combination of components of T multiplied by smooth compactly supported functions. If $h = n+1$, then the commutator has order 1 and $[\chi, d_c]T$ can be written as a linear combination of horizontal derivatives composed with components of T , multiplied by smooth compactly supported functions. Keeping in mind Theorem 3.19, we can apply Proposition 6.4 in both cases, and conclude that all types of terms correspond to operators on the Heisenberg ball which are bounded as required.

By construction, since the covering has bounded multiplicity and derivatives of cut-offs and charts are controlled uniformly, summing up each type of term gives bounded operators from $\ell^1(L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet)))$ to $\ell^1(L^q(M, E_0^\bullet))$ or to $\ell^1(W^{r,p}(M, E_0^\bullet))$ for some $r > 0$ and $p > 1$, and $\ell^1(W^{s-1,p}(M, E_0^\bullet)) \rightarrow \ell^1(W^{s,p}(M, E_0^\bullet))$ or $\ell^1(W^{s,p}(M, E_0^\bullet)) \rightarrow \ell^1(W^{s,p}(M, E_0^\bullet))$, as announced.

By construction, $\mathbf{S} + d_c\mathbf{T} + \mathbf{T}d_c = 1$, hence $d_c\mathbf{S} = \mathbf{S}d_c$.

When iterating, we write $\mathbf{S}^\ell = 1 - d_cT_\ell - T_\ell d_c$. The recursion formula is $T_{\ell+1} = T_\ell + \mathbf{T} - d_cT_\ell\mathbf{T} - T_\ell d_c\mathbf{T}$.

Let us show by induction on ℓ that

- T_ℓ maps $\ell^1(L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet)))$ to $\ell^1(L^q(M, E_0^\bullet))$ and to $\ell^1(W^{r,p}(M, E_0^\bullet))$ for some $r > 0$ and $p > 1$.
- d_cT_ℓ and $T_\ell d_c$ are bounded on $\ell^1(W^{s,p}(M, E_0^\bullet))$ for all $s \leq k-1$ and $p > 1$.

Note that $T_1 = \mathbf{T}$. We have just shown that d_cT_1 and T_1d_c are bounded on $\ell^1(W^{s,p})$ and T_1 maps $\ell^1(L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet)))$ to $\ell^1(L^q(M, E_0^\bullet))$. Assume that T_ℓ does as well. The induction formula

$$d_cT_{\ell+1} = d_cT_\ell + d_cT_1 - d_cT_\ell d_cT_1, \quad T_{\ell+1}d_c = T_\ell d_c + T_1 d_c - d_cT_\ell T_1 d_c - T_\ell d_c T_1 d_c.$$

shows that $d_cT_{\ell+1}$ and $T_{\ell+1}d_c$ are bounded on $\ell^1(W^{s,p}(M, E_0^\bullet))$. This implies that $T_{\ell+1}$ maps $\ell^1(L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet)))$ to $\ell^1(L^q(M, E_0^\bullet))$ and to $\ell^1(W^{r,p}(M, E_0^\bullet))$ for some $r > 0$ and $p > 1$, and completes the induction proof. For ℓ larger enough, $S_M := \mathbf{S}^\ell$ maps $\ell^1(L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet)))$ to $\ell^1(W^{k-1,q}(M, E_0^\bullet))$.

Finally, if $1 \leq q' \leq q$, $\ell^1 \subset \ell^{q'}$ and $L_{\text{loc}}^q \subset L_{\text{loc}}^{q'}$, hence

$$\ell^1(L^q(M, E_0^\bullet)) \subset \ell^{q'}(L^{q'}(M, E_0^\bullet)) = L^{q'}(M, E_0^\bullet).$$

This completes the proof that $T_M := T_\ell$, ℓ large enough, maps $L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet))$ to $L^{q'}(M, E_0^\bullet)$ and S_M maps $L^1(M, E_0^\bullet) \cap d_c^{-1}(L^1(M, E_0^\bullet))$ to $W^{k-1, q'}(M, E_0^\bullet)$. \square

8.2. Application to geometric group theory. According to [37], such smoothing homotopies are the necessary ingredient in order to prove that Rumin's complex can be used to compute the $\ell^{q,1}$ -cohomology of a subRiemannian contact manifold. We shall not define this quasiisometry invariant of groups here, but merely state a consequence of Theorems 1.1, 1.2 and 1.3 for geometric group theory.

Corollary 8.2 ($\ell^{q,1}$ -cohomology of Heisenberg groups). *For $h = 0, \dots, 2n$, let $q = Q/(Q-1)$ if $h \neq n+1$ and $q = Q/(Q-2)$ if $h = n+1$. Then $\ell^{q,1}H^h(\mathbb{H}^n)$ is finite dimensional.*

Proof. [37] asserts that for all subRiemannian contact manifolds M of C^3 -bounded geometry, and all $q \geq 1$, $\ell^{q,1}H^h(M)$ is isomorphic to the quotient of the space of d_c -closed h -forms by the image of d_c on $L^q(M, E_0^h) \cap d_c^{-1}(L^1(M, E_0^{h-1}))$. This applies in particular to $M = \mathbb{H}^n$.

Fix $h = 0, \dots, 2n$. Let C denote the space of left-invariant Rumin $2n+1-h$ -forms on \mathbb{H}^n . Integrating closed L^1 -forms ω against left-invariant forms β defines a bilinear map

$$(\omega, \beta) \mapsto \int_{\mathbb{H}^n} \omega \wedge \beta, \quad (L^1(\mathbb{H}^n, H_0^h) \cap \ker(d_c)) \times C \rightarrow \mathbb{R},$$

whence a map

$$I : L^1(\mathbb{H}^n, H_0^h) \cap \ker(d_c) \rightarrow C^*.$$

Pick d_c -closed L^1 forms (ψ_1, \dots, ψ_k) such that $(I(\psi_1), \dots, I(\psi_k))$ is a basis of its image.

Let ω be a d_c -closed h -form. There exist real numbers $\lambda_1, \dots, \lambda_k$ such that

$$I(\omega) = \sum_{i=1}^k \lambda_i I(\psi_i).$$

Then $\omega_0 = \omega - \sum_{i=1}^k \lambda_i \psi_i$ is d_c -closed and belongs to L_0^1 . According to Theorem 5.2, there exists an $h-1$ -form $\phi \in L^q(\mathbb{H}^n, E_0^{h-1})$ such that $\omega_0 = d_c \phi$ (here, $q = Q/Q-1$ or $Q/Q-2$ depending on h). This shows that the dimension of $\ell^{q,1}H^h(\mathbb{H}^n)$ is at most k . \square

ACKNOWLEDGMENTS

B. F. and A. B. are supported by the University of Bologna, funds for selected research topics, and by MAnET Marie Curie Initial Training Network, by GNAMPA of INdAM (Istituto Nazionale di Alta Matematica "F. Severi"), Italy, and by PRIN of the MIUR, Italy.

P.P. is supported by MAnET Marie Curie Initial Training Network, by Agence Nationale de la Recherche, ANR-10-BLAN 116-01 GGAA and ANR-15-CE40-0018 SRGI. P.P. gratefully acknowledges the hospitality of Isaac Newton Institute, of EPSRC under grant EP/K032208/1, and of Simons Foundation.

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