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Extended Recursive Analysis for Tilera Tile64 NoC Architectures: Towards Inter-NoC Delay Analysis

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ABSTRACT

A heterogeneous network, where a switched-Ethernet backbone, e.g. AFDX, interconnects several end systems based on Network-on-Chip (NoC), is a promising candidate to build new avionics architectures. When using such a heterogeneous network for real-time applications, a global worst-case traversal time (WCTT) analysis is needed. In this short paper we focus on the intra-NoC communication on a Tilera TILE64-like NoC. First, we extend the Recursive Calculus (RC) to achieve tighter intra-NoC WCTT. Then, we explain how this intra-NoC WCTT analysis could be used in a compositional manner for the end-to-end inter-NoC delay analysis.

1 INTRODUCTION

The many-core architectures are promising candidates to support the design of hard real-time systems. They are based on simple cores interconnected using a Network-on-Chip (NoC). In Figure 1, an avionics architecture is composed of two many-core end systems. The data exchange between the cores within the same NoC is called intra-NoC communication (e.g. f_1 in Figure 1), and between the cores in different NoCs, inter-NoC communication (e.g. f₅ in Figure 1). The timing constraints, such as bounded delays have to be guaranteed for hard real-time avionics systems: a worst-case end-to-end delay analysis is needed. The intra-NoC communication has to take into account the wormhole switching mechanism and the possible direct and indirect blocking between communications flows. Inter-NoC communications needs a two level compositional framework: first intra-NoC communication delays due to the conflicts to reach and share the I/O (Ethernet) ports, second the inter-NoC communication delays due to the sharing of the switched-Ethernet network. Many works have been devoted to the worst-case delay analysis of a switched-Ethernet network, e.g. AFDX, using techniques such as the Network Calculus or the trajectory approach [8] [9] [5]. Moreover, an extension of the trajectory approach has been proposed for worst -case delay analysis of several CAN networks interconnected through a Switched Ethernet Backbone [10]. Jérôme Ermont
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However, the intra-NoC worst-case traversal time (WCTT) computation strongly depends on the implemented wormhole switching mechanism. The context of this paper is a commercially existing NoC platform: Tilera TILE64. It implements the wormhole routing and a credit-based flow control in routers. A packet is divided in flow control digits (flits) of fixed size. The first flit contains routing information that define the path for all the flits of the packet. In each cycle one flit is forwarded from each router, provided that there is a free space in the input buffer of the next router. A three flits buffer is associated to each input port. The input ports are polled, based on a Round-Robin Arbitration (RRA).

Several techniques have been proposed for the WCTT analysis of a Tilera TILE64-like NoC. Among them, the Recursive Calculus (RC) [7] offers a simple way to capture the wormhole switching. The RC approach has been studied in [6], [1] and [3] to integrate the inter-release constraints and the available buffer, respectively. In this work, we describe an extended RC method dealing with both the buffer effect and the flow inter-release constraints. Then, we explain how this intra-NoC worst-case delay analysis could be used in a compositional manner for the end-to-end inter-NoC delay analysis.

2 INTRA-NOC TIMING ANALYSIS

The principle of the RC method [7] consists in building the set of packets that can delay (directly or indirectly) the flow under study, in the worst-case and derive a bound on its WCTT. Let's denote by $S_i = \{ < f_j, nb_j^i > \} \cup \{ < f_i, 1 > \}$ this set of packets. For each flow f_j impacting f_i , it gives the maximum number nb_j^i of packets may delay the flow under study f_i . Set S_i is initialized with one packet from flow f_i under study, i.e. $S_i = \{ < f_i, 1 > \}$. The current location of this packet is its source node. This packet is forwarded till it is blocked by another flow f_{j_1} or it reaches its destination. In the later case, building of set S_i is over. In the former case, one packet from f_{j_1} is added in S_i , i.e. $S_i = \{ < f_{j_1}, 1 >, < f_i, 1 > \}$. Its current location is the place in the network where f_{j_1} blocks f_i . For f_1 in NoC 1 of the avionics architecture of Figure 1, $S_1 = \{ < f_4, 2 >, < f_3, 2 >, < f_2, 1 >, < f_1, 1 > \}$. The scenario leading to S_1 is illustrated in Figure 2.

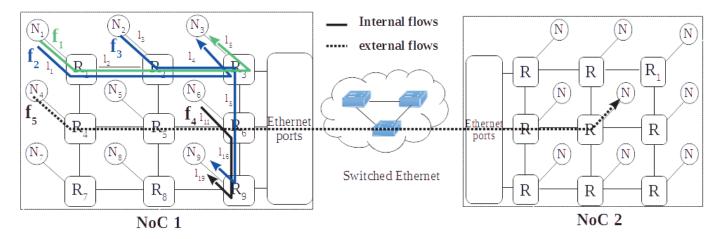


Figure 1: Illustrative example

The initial RC approach ignores the available buffer capacity in routers. It assumes that f_2 , f_3 and f_4 packets block f_1 till they reach their destinations. This assumption simplifies the computation. However it might introduce some pessimism. let's assume, for example, a three-flit packet and a three-flit buffer (typical for Tilera Tile64). Then, a packet from f_3 can be fully stored in R_6 input buffer. Thus, the impact of an f_3 packet on both f_1 and f_2 ends as soon as it leaves R_3 . Since it can leave R_3 even if there is a pending packet from f_4 , f_4 doesn't add any extra delay for f_1 and f_2 . Thus the worst-case list of packets blocking f_1 becomes $S_1 = \{ \langle f_3, 2 \rangle, \langle f_2, 1 \rangle, \langle f_1, 1 \rangle \}$. The integration of available buffer space in WCTT computation has been studied in [1] (the pipeline effect). The authors establish properties to better capture the effect of buffers under wormhole routing. Based on these properties, we integrate the buffer effect in the initial RC approach. The second source of pessimism in the RC computation is due to the fact that flows are sporadic. It means that there is a minimum duration T_i between the generation times of two consecutive packets from a flow f_i . The scenario considered by the RC computation does not take into account these constraints. As illustrated in Figure 2, two packets of flow f_3 are counted in the sequence of blocking packets for f_1 . They are generated at time t_1' and t_6' . Assuming three flit packets for all the flows, we have $t_6' - t_1' = 12$ cycles. As soon as the minimum duration T_3 between two consecutive f_3 packets is more than 12 cycles, this scenario cannot occur. In such a situation one single packet from f_3 can delay f_1 . Thus, the resulting worst-case list of packets blocking f_1 becomes: $S_1 = \{ \langle f_3, 1 \rangle, \langle f_2, 1 \rangle, \langle f_1, 1 \rangle \}$. This second source of pessimism has been addressed in [6].

The basic idea consists in enumerating all the possible sequences of blocking for a given flow, respecting the minimum inter-release constraints, and selecting the sequence leading to the WCTT. Unfortunately, the number of sequences that need to be explored grows exponentially. In order to tackle this problem, we propose an overestimation of all the enumerated sequences. Then by integrating the minimum gap between successive packets of flows in routers, we bound the number of packet instances in each packets set. The sets are then refined in iterative manner, and the WCTT for each flow is derived. Thus, we implemented an extended RC algorithm

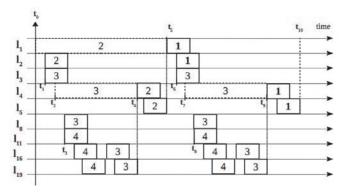


Figure 2: Basic RC sequence for f_1

combining the benefits of the buffer effect and the minimum interrelease constraints of flows. We have done some experiments on $n^{\ast}n$ 2D-mesh NoC, with n=4 or n=6 or n=8. For these experiments, first, we obtained significant reduction on the WCTT (up to 64% compared to the initial RC) of the flows that experiment heavy indirect blocking or those who contend with flows with large inter-release periods. This can lead to guarantee the applications constraints when the classical RC method cannot.

3 INTER-NOC TIMING ANALYSIS: PERSPECTIVES

A Tilera-like NoC, used as a processing element within a backbone network supports two types of communication: (i) the communication between cores; and (ii) the communication between cores and the I/O interfaces to reach the backbone network. The existing works only focus on the inter-core communication and do not consider the I/O interfaces. The Tilera NoC interconnects cores but also Ethernet and DDR-SDRAM memory interfaces that are located on its edges. As each I/O interface can be accessed from the core adjacent to this interface through specific ports, each Ethernet controller of the Tile64 is connected to respectively 2 ports.

Moreover, a core can receive data directly from the Ethernet interface or through an intermediate memory controller. A similar process is used for the egress data flows where a DMA command is sent by the tile wanting to send data to the Ethernet. Efficient mapping of application on a many-core is a key issue to reduce the contention experienced by core to I/O flows [2]. Moreover the size of an Ethernet frame is several factors higher than the size of a NoC packet. Thus, several NoC packets are therefore needed to transmit to a tile an Ethernet payload. Consequently, the bridging strategies have to be optimized and accounted for when evaluating the worst-case core-to-I/O delays. Final objective will be to compute the end-to-end delay including:

- the time needed to go from a source core to the Ethernet port on the emitting NoC;
- the time needed to cross the Ethernet (AFDX) backbone;
- the time needed to go from the Ethernet port to the destination core on the receiving NoC.

One key issue will be to assess the global pessimism introduced at each level on such a heterogeneous network.

The approach proposed in this work, for Tilera TILE64-like NoC architectures, is based on the initial RC [7]. It combines the properties introduced in [1] and [6] to achieve tighter WCTT bounds for intra-NoC communication [4]. This approach, introduced for intra-chip communication (i.e. communication between cores on the same NoC), minimizes the pessimism and seems a good basis for inter-NoC end-to-end delay analysis.

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