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QUASI-OPTIMAL NONCONFORMING APPROXIMATION OF 1 2 ELLIPTIC PDES WITH CONTRASTED COEFFICIENTS AND MINIMAL REGULARITY* 3

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5 Abstract. In this paper we investigate the approximation of a diffusion model problem with 6 contrasted diffusivity and the error analysis of various nonconforming approximation methods. The essential difficulty is that the Sobolev smoothness index of the exact solution may be just barely larger 7 8 than one. The lack of smoothness is handled by giving a weak meaning to the normal derivative of 9 the exact solution at the mesh faces. The error estimates are robust with respect to the diffusivity contrast. We briefly show how the analysis can be extended to the Maxwell's equations. 10

11 Key words. Finite elements, Nonconforming methods, Error estimates, Minimal regularity, 12Nitsche method, Boundary penalty, Elliptic equations, Maxwell's equations.

AMS subject classifications. 35J25, 65N15, 65N30 13

This article is dedicated to the memory of Christine Bernardi.

15 1. Introduction. The objective of the present paper is to revisit and unify the error analysis of various nonconforming approximation techniques applied to a diffusion model problem with contrasted diffusivity. We also briefly show how to 17 extend the analysis to Maxwell's equations. 18

1.1. Content of the paper. The nonconforming techniques we have in mind 19 are Crouzeix-Raviart finite elements [14], Nitsche's boundary penalty method [32], 20the interior penalty discontinuous Galerkin (IPDG) method [2], and the hybrid high-21order (HHO) methods [16, 18] which are closely related to hybridizable discontinuous 22 Galerkin methods [13]. The main difficulty in the error analysis is that owing to 23 the contrast in the diffusivity, the Sobolev smoothness index of the exact solution 24is barely larger than one. This makes the estimation of the consistency error in-25curred by nonconforming approximation techniques particularly challenging since the 26normal derivative of the solution at the mesh faces is not integrable and it is thus 27 not straightforward to give a reasonable meaning to this quantity on each mesh face 28 independently. 29

The main goal of the present paper is to establish quasi-optimal error estimates by 30 using a mesh-dependent norm that remains bounded as long as the exact solution has 31 a Sobolev smoothness index strictly larger than one. By quasi-optimality, we mean that the approximation error measured in the augmented norm is bounded, up to a 33 generic constant, by the best approximation error of the exact solution measured in 34 the same augmented norm by members of the discrete trial space. A key point in the 35 36 analysis is that the above generic constant is independent of the diffusivity contrast. We emphasize that quasi-optimal error estimates are more informative than the more 37 traditional asymptotic error estimates, which bound the approximation error by terms 38

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³⁹ that optimally decay with the mesh size. Indeed, the former estimates cover the whole

40 computational range whereas the latter estimates only cover the asymptotic range. 41 One key novelty herein is the introduction of a weighted bilinear form that accounts

41 One key novelty herein is the introduction of a weighted bilinear form that accounts 42 for the default of consistency in all the cases (see (3.12)).

The paper is organized as follows. The model problem under consideration and 43 the discrete setting are introduced in $\S2$. The weighted bilinear form mentioned above 44 which accounts for the consistency default at the mesh interfaces and boundary faces 45is defined in $\S3$. The key results in this section are Lemma 3.3 and Lemma 3.5. We 46 collect in §4 the error analyses of the approximation of the model problem with the 47 Crouzeix–Raviart approximation, Nitsche's boundary penalty method, the IPDG ap-48 proximation, and the HHO approximation. To avoid invoking Strang's second Lemma, 49 50 we introduce in §4.1 a linear form δ_h that measures consistency but does not need the exact solution to be inserted into the arguments of the discrete bilinear form at hand. The weighted bilinear form (3.12) turns out to an essential tool to deduce robust 52estimates of the norm of the consistency form δ_h for all the nonconforming methods 53 considered. One originality of this paper is that all the error estimates provided in §4 54involve constants that are uniform with respect to the diffusivity contrast. Another salient feature is that the source term is assumed to be only in $L^q(D)$, where q is 56 such that $L^q(D)$ is continuously embedded in $H^{-1}(D) := (H_0^1(D))'$; specifically, this means that $q > 2_* := \frac{2d}{2+d} \ge 1$ (here, $d \ge 2$ is the space dimension). 5758

1.2. Literature overview. Let us put our work in perspective with the liter-59ature. Perhaps a bit surprisingly, error estimates for nonconforming approximation 61 methods are rarely presented in a quasi-optimal form in the literature. A key step toward achieving quasi-optimal error estimates has been achieved in Veeser and Zanotti [34, 35]. Therein, the approximation error and the best-approximation error are both 63 measured using the energy norm and the source term is assumed to be just in the 64 dual space $H^{-1}(D)$. However, at the time of this writing, this setting does not yet 65 cover robust estimates w.r.t. the diffusivity contrast. In the present work, we proceed 67 somewhat differently to obtain robust quasi-optimal error estimates. This is done at the following price: (i) We invoke augmented norms, which are, however, compatible 68 with the elliptic regularity theory; (ii) We only consider source terms in the Lebesgue spaces $L^q(D)$ with $q > 2_* := \frac{2d}{2+d} \ge 1$; notice though that this regularity is weaker 69 70than assuming that source terms are in $L^2(D)$, as usually done in the literature. 71

72 The traditional approach to tackle the error analysis for nonconforming approximation techniques are Strang's lemmas. However, an important shortcoming of this 73 approach whenever the Sobolev smoothness index of the exact solution is barely larger 74 than one, is that it is not possible to insert the exact solution in the first argument of 76 the discrete bilinear form. To do so, one needs to assume some additional regularity on the exact solution which often goes beyond the regularity provided by the prob-77 lem at hand. This approach has nevertheless been used by many authors to analyze 78 discontinuous Galerkin (dG) methods (see, e.g., [15, 21] and the references therein). 79 One way to overcome the limitations of Strang's Second Lemma has been proposed 80 81 by Gudi [29]. The key idea consists of introducing a mapping that transforms the discrete test functions into elements of the exact test space. An important property 82 83 of this operator is that its kernel is composed of discrete (test) functions that are only needed to "stabilize" the discrete bilinear form, but do not contribute to the 84 interpolation properties of the approximation setting. We refer to this mapping as 85 trimming operator. The notion of trimming operator has been used in Li and Mao 86 [31] to perform the analysis of the Crouzeix–Raviart approximation of the diffusion 87

problem and source term in $L^2(D)$ (see e.g., the definitions (5)–(7) and the identity 88 (11) therein). The trimmed error estimate (which is sometimes referred to as "medius 89 analysis" in the literature) has been applied in Gudi [29] to the IPDG approximation 90 of the Laplace equation with a source term in $L^2(D)$ and to a fourth-order problem; it has been applied to the Stokes equations in Badia et al. [3] and to the linear elasticity equations in Carstensen and Schedensack [12]. One problem with methods using the 93 trimming operator, though, is that they require constructing H^1 -conforming discrete 94 quasi-approximation operators that do not account for the diffusivity contrast; this 95 entails error estimates with constants that depend on the diffusivity contrast, i.e., 96 these error estimates are not robust. 97

It is shown in [25] in the case of Nitsche's boundary penalty method that the 98 99 dependency of the constants with respect to the diffusivity contrast can be eliminated by introducing an alternative technique based on mollification and an extension of 100the notion of the normal derivative. The objective of the present paper is to revisit 101 and extend [25]. The analysis presented here is significantly simplified and modified 102to include the Crouzeix-Raviart approximation, the IPDG approximation, and the 103 HHO approximation. One key novelty is the introduction of the weighted bilinear form 104 105 (3.12) that accounts for the consistency default in all the cases. The present analysis hinges on two key ideas which are now part of the numerical analysis folklore. To 106the best of our knowledge, these ideas have been introduced/used in Lemma 4.7 in 107 Amrouche et al. [1], Lemma 2.3 and Corollary 3.1 in Bernardi and Hecht [5] and 108 Lemma 8.2 in Buffa and Perugia [9]. However, we believe that detailed proofs are 109 110 seemingly missing in the literature, and another purpose of this paper is to fill this 111 gap.

The first key idea is a face-to-cell lifting operator. Such an operator is mentioned 112in Lemma 4.7 in [1], and its construction is briefly discussed. The weights used in 113the norms therein, though, cannot give estimates that are uniform with respect to 114 the mesh size. This operator is also mentioned in Lemma 2.3 in [5]. The authors 115116 claim that the face-to-cell operator has been constructed in Bernardi and Girault [4, Eq. (5.1)], which is unclear to us. A similar operator is invoked in Lemma 8.2 in 117 [9]. The operator therein is constructed on the reference element \hat{K} and its stability 118properties are proved in the Sobolev scale $(H^s(\widehat{K}))_{s \in (0,1)}$. The authors invoke also 119 the Sobolev scale $(H^s(K))_{s\in(0,1)}$ for arbitrary cells K in a mesh \mathcal{T}_h belonging the 120 shape-regular sequence $(\mathcal{T}_h)_{h\in\mathcal{H}}$. The norm equipping $H^s(K)$ is not explicitly defined 121therein, which leads to one statement that looks questionable (see e.g., Eq. (8.11)122therein; a fix has been proposed in [8, Lem. A.3]). In particular, it is unclear how 123to keep track of constants that depend on K when one uses the real interpolation 124125method to define $H^{s}(K)$. In order to clarify the status of this face-to-cell operator, which is essential for our analysis, and without claiming originality, we give (recall) 126 all the details of its construction in the proof of Lemma 3.1. As in [1, Lem. 4.7], we 127use the Sobolev–Slobodeckij norm to equip the fractional-order Sobolev spaces; this 128 allows us to track all the constants easily. 129

The second key idea introduced in the above papers is that of extending the notion of face integrals by using a duality argument together with the face-to-cell operator. The argument is deployed in Corollary 3.3 in [5], but the sketch of the proof has typos (e.g., an average has to be removed to make the inverse estimate in step (1) correct). This corollary is quoted and invoked in Cai et al. [11, Lem. 2.1]; it is the cornerstone of the argumentation therein. This argument is also deployed in Lemma 8.2 in [9]. A similar argument is invoked in [1, Lem. 4.7] in a slightly different context. In all

the cases one must use a density argument to complete the proofs, but this argument is omitted and implicitly assumed to hold true in all the above references. We fill this gap in Lemma 3.3 and provide the full argumentation in the proof, including the passage to the limit by density. The proof invokes mollifiers that commute with differential operators and behave properly at the boundary of the domain; these tools have been recently revisited in [22] elaborating on seminal ideas from Schöberl [33].

143 **2. Preliminaries.** In this section we introduce the model problem and the dis-144 crete setting for the approximation.

145 **2.1. Model problem.** Let D be a Lipschitz domain in \mathbb{R}^d , which we assume for 146 simplicity to be a polyhedron. We consider the following scalar model problem:

147 (2.1)
$$-\nabla \cdot (\lambda \nabla u) = f \quad \text{in } D, \qquad \gamma^{g}(u) = g \quad \text{on } \partial D$$

148 where $\gamma^{g} : H^{1}(D) \to H^{\frac{1}{2}}(\partial D)$ is the usual trace map (the superscript g refers to 149 the gradient), and $g \in H^{\frac{1}{2}}(\partial D)$ is the Dirichlet boundary data. The scalar-valued 150 diffusion coefficient $\lambda \in L^{\infty}(D)$ is assumed to be uniformly bounded from below away 151 from zero. For simplicity, we also assume that λ is piecewise constant in D, i.e., there 152 is a partition of D into M disjoint Lipschitz polyhedra D_{1}, \dots, D_{M} s.t. $\lambda_{|D_{i}|}$ is a 153 positive real number for all $i \in \{1:M\}$.

154 It is standard in the literature to assume that $f \in L^2(D)$. We are going to relax 155 this hypothesis in this paper by only assuming that $f \in L^q(D)$ with $q > \frac{2d}{2+d}$. Note 156 that q > 1 since $d \ge 2$. Note also that $L^q(D) \hookrightarrow H^{-1}(D)$ since $H_0^1(D) \hookrightarrow H^{q'}(D)$ 157 with the convention that $\frac{1}{q} + \frac{1}{q'} = 1$. Since $\frac{2d}{2+d} < 2$, we are going to assume without 158 loss of generality that $q \le 2$.

In the case of the homogeneous Dirichlet condition (g = 0), the weak formulation of the model problem (2.1) is as follows:

161 (2.2)
$$\begin{cases} \text{Find } u \in V := H_0^1(D) \text{ such that} \\ a(u, w) = \ell(w), \quad \forall w \in V, \end{cases}$$

162 with the bilinear and linear forms

163 (2.3)
$$a(v,w) := \int_D \lambda \nabla v \cdot \nabla w \, \mathrm{d}x, \qquad \ell(w) := \int_D f w \, \mathrm{d}x.$$

The bilinear form a is coercive in V owing to the Poincaré–Steklov inequality, and it 164 is also bounded on $V \times V$ owing to the Cauchy–Schwarz inequality. The linear form ℓ 165is bounded on V since the Sobolev embedding theorem and Hölder's inequality imply 166that $|\ell(w)| \leq ||f||_{L^q(D)} ||w||_{L^{q'}(D)} \leq c ||f||_{L^q(D)} ||w||_{H^1(D)}$. Note that $q \geq \frac{2d}{2+d}$ is the minimal integrability requirement on f for this boundedness property to hold true. 167 168169 The above coercivity and boundedness properties combined with the Lax-Milgram Lemma imply that (2.2) is well-posed. For the non-homogeneous Dirichlet boundary 170 condition, one invokes the surjectivity of the trace map γ^{g} to infer the existence of a 171lifting of g, say $u_g \in H^1(D)$ s.t. $\gamma^g(u_g) = g$, and one decomposes the exact solution 172as $u = u_g + u_0$ where $u_0 \in H_0^1(D)$ solves the weak problem (2.2) with $\ell(w)$ replaced 173by $\ell_g(w) = \ell(w) - a(u_g, w)$. The weak formulation thus modified is well-posed since 174 ℓ_q is bounded on $H_0^1(D)$. 175

The notion of diffusive flux, which is defined as follows, will play an important role in the paper:

178 (2.4)
$$\boldsymbol{\sigma}(v) := -\lambda \nabla v \in \boldsymbol{L}^2(D), \quad \forall v \in H^1(D)$$

179 We use boldface notation to denote vector-valued functions and vectors in \mathbb{R}^d .

180 LEMMA 2.1 (Exact solution). Assume that there exist r > 0 and $q \in (\frac{2d}{2+d}, 2]$ 181 such that the exact solution u is in $H^{1+r}(D)$ and the source term f is in $L^q(D)$, then

182 (2.5)
$$u \in V_{\mathrm{s}} := \{ v \in H^1_0(D) \mid \boldsymbol{\sigma}(v) \in \boldsymbol{L}^p(D), \ \nabla \cdot \boldsymbol{\sigma}(v) \in L^q(D) \},$$

183 for some real number p > 2.

5

184 Proof. The Sobolev embedding theorem implies that there is p > 2 s.t. $H^r(D) \hookrightarrow$ 185 $L^p(D)$. Indeed, if 2r < d, we have $H^r(D) \hookrightarrow L^s(D)$ for all $s \in [2, \frac{2d}{d-2r}]$ and we can 186 take $p = \frac{2d}{d-2r} > 2$, whereas if $2r \ge d$, we have $H^r(D) \hookrightarrow H^{\frac{d}{2}}(D) \hookrightarrow L^s(D)$ for 187 all $s \in [2, \infty)$, and we can take any p > 2. The above argument implies that $\nabla u \in$ 188 $L^p(D)$, and since λ is piecewise constant and $\sigma(u) = -\lambda \nabla u$, we have $\sigma(u) \in L^p(D)$. 189 Moreover, since $\nabla \cdot \sigma(u) = f$ and $f \in L^q(D)$, we have $\nabla \cdot \sigma(u) \in L^q(D)$.

The regularity assumption $u \in H^{1+r}(D)$, r > 0, is reasonable owing to the elliptic 190 regularity theory (see Theorem 3 in Jochmann [30], Lemma 3.2 in Bonito et al. [7] or 191Bernardi and Verfürth [6]). In general, one expects that $r \leq \frac{1}{2}$ whenever u is supported 192on at least two contiguous subdomains where λ takes different values; otherwise the 193normal derivative of u would be continuous across the interface separating the two 194subdomains in question, and owing to the discontinuity of λ , the normal component 195of the diffusive flux $\sigma(u)$ would be discontinuous across the interface, which would 196 contradict the fact that $\sigma(u)$ has a weak divergence. It is however possible that $r > \frac{1}{2}$ 197 when the exact solution is supported on one subdomain only. If $r \ge 1$, we notice that 198one necessarily has $f \in L^2(D)$ (since $f_{|D_i} = \lambda_{|D_i}(\Delta u)_{D_i}$ for all $i \in \{1:M\}$), i.e., it is 199 legitimate to assume that q = 2 if $r \ge 1$. 200

Remark 2.2 (Extensions). One could also consider lower-order terms in (2.1), 201 e.g., $-\nabla \cdot (\lambda \nabla u) + \beta \cdot \nabla u + \mu u = f$ with $\beta \in W^{1,\infty}(D)$ and $\mu \in L^{\infty}(D)$ s.t. $\mu - \frac{1}{2} \nabla \cdot \beta \ge 0$ 202a.e. in D (for simplicity). The error analysis presented in this paper still applies pro-203 vided the lower-order terms are not too large, e.g., $\lambda \geq \max(h \|\boldsymbol{\beta}\|_{\boldsymbol{L}^{\infty}(\Omega)}, h^2 \|\boldsymbol{\mu}\|_{\boldsymbol{L}^{\infty}(D)}),$ 204 where h denotes the mesh-size. Standard stabilization techniques have to be invoked 205if the lower-order terms are large when compared to the second-order diffusion op-206207erator. Furthermore, the error analysis can be extended to account for a piecewise constant tensor-valued diffusivity d; then, the various constants in the error estimate 208depend on the square-root of the anisotropy ratios measuring the contrast between 209the largest and the smallest eigenvalue of d in each subdomain D_i . Finally, one can 210211 consider that the diffusion tensor d is piecewise smooth instead of being piecewise constant; a reasonable requirement is that $d_{|D_i|}$ is Lipschitz for all $i \in \{1: M\}$. This 212213 last extension is, however, less straightforward because the discrete diffusive flux is no longer a piecewise polynomial function. \square 214

2.2. Discrete setting. We introduce in this section the discrete setting that we 215are going to use to approximate the solution to (2.2). Let \mathcal{T}_h be a mesh from a shape-216regular sequence $(\mathcal{T}_h)_{h\in\mathcal{H}}$. Here, \mathcal{H} is a countable set with 0 as unique accumulation 217point. A generic mesh cell is denoted $K \in \mathcal{T}_h$ and is conventionally taken to be an 218open set. We also assume that \mathcal{T}_h covers each of the subdomains $\{D_i\}_{i \in \{1:M\}}$ exactly 219so that $\lambda_K := \lambda_{|K}$ is constant for all $K \in \mathcal{T}_h$. Let $(\widehat{K}, \widehat{P}, \widehat{\Sigma})$ be the reference finite 220 element; we assume that $\mathbb{P}_{k,d} \subset \widehat{P} \subset W^{k+1,\infty}(\widehat{K})$ for some $k \geq 1$. Here, $\mathbb{P}_{k,d}$ is the 221(real) vector space composed of the d-variate polynomials of degree at most k. For all 222 $K \in \mathcal{T}_h$, let $T_K : \widehat{K} \to K$ be the geometric mapping and let $\psi_K^g(v) = v \circ T_K$ be the 223 pullback by the geometric mapping. We introduce the broken finite element space 224

225 (2.6)
$$P_k^{\mathsf{D}}(\mathcal{T}_h) = \{ v_h \in L^{\infty}(D) \mid v_{h|K} \in P_K, \forall K \in \mathcal{T}_h \},$$

where $P_K := (\psi_K^{\mathrm{g}})^{-1}(\widehat{P}) \subset W^{k+1,\infty}(K)$. For any function $v_h \in P_k^{\mathrm{b}}(\mathcal{T}_h)$, we define the broken diffusive flux $\sigma(v_h) \in L^2(D)$ by setting $\sigma(v_h)_{|K} := -\lambda_K \nabla(v_{h|K})$ for all $K \in \mathcal{T}_h$. Upon introducing the notion of broken gradient $\nabla_h : W^{1,p}(\mathcal{T}_h) := \{v \in L^p(D) \mid \nabla(v_{|K}) \in L^p(K), \forall K \in \mathcal{T}_h\}$ by setting $(\nabla_h v)_{|K} := \nabla(v_{|K})$ for all $K \in \mathcal{T}_h$ and all $v \in W^{1,p}(\mathcal{T}_h)$, we have $\sigma(v_h) = -\lambda \nabla_h v_h$.

For any cell $K \in \mathcal{T}_h$ we denote by \boldsymbol{n}_K the unit normal vector on ∂K pointing 231outward. We denote by \mathcal{F}_h° the collection of the mesh interfaces and \mathcal{F}_h^{∂} the collection 232of the mesh faces at the boundary of D. We assume that \mathcal{T}_h is oriented in a generation-233 compatible way, and for each mesh face $F \in \mathcal{F}_h^{\circ} \cup \mathcal{F}_h^{\partial}$, we denote by n_F the unit vector orienting F. For all $F \in \mathcal{F}_h^{\circ}$, we denote by $K_l, K_r \in \mathcal{T}_h$ the two cells s.t. 234235 $F = \partial K_l \cap \partial K_r$ and the unit normal vector \mathbf{n}_F orienting F points from K_l to K_r , 236i.e., $\boldsymbol{n}_F = \boldsymbol{n}_{K_l} = -\boldsymbol{n}_{K_r}$. For all $F \in \mathcal{F}_h$, let \mathcal{T}_F be the collection of the one or two 237mesh cells sharing F. For all $K \in \mathcal{T}_h$, let \mathcal{F}_K be the collection of the faces of K and 238let $\epsilon_{K,F} = \mathbf{n}_F \cdot \mathbf{n}_K = \pm 1$. The jump across $F \in \mathcal{F}_h^\circ$ of any function $v \in W^{1,1}(\mathcal{T}_h)$ is 239defined by setting $\llbracket v \rrbracket_F(\boldsymbol{x}) = v_{|K_l}(\boldsymbol{x}) - v_{|K_r}(\boldsymbol{x})$ for a.e. $\boldsymbol{x} \in F$. If $F \in \mathcal{F}_h^\partial$, this jump is conventionally defined as the trace on F, i.e., $\llbracket v \rrbracket_F(\boldsymbol{x}) = v_{|K_l}(\boldsymbol{x})$ where $F = \partial K_l \cap \partial D$. 240241We omit the subscript $_F$ in the jump whenever the context is unambiguous. 242

3. The bilinear form n_{\sharp} . In this section, we give a proper meaning to the normal trace of the diffusive flux of the solution to (2.2) over each mesh face. The material presented in §3.1 and §3.2 has been introduced in [25, §5.3] and is inspired from Amrouche et al. [1, Lem. 4.7], Bernardi and Hecht [5, Cor 3.3], and Buffa and Perugia [9, Lem. 8.2]; it is included here for the sake of completeness. The reader familiar with these techniques is invited to jump to §3.3 where the weighted bilinear form n_{\sharp} is introduced. This bilinear form is the main tool for the error analysis in §4.

3.1. Face-to-cell lifting operator. Let us first motivate our approach infor-250mally. Let $K \in \mathcal{T}_h$ be a mesh cell, let \mathcal{F}_K be the collection of all the faces of K, 251and let $F \in \mathcal{F}_K$ be a face of K. Let v be a vector field defined on K. We are 252looking for (mild) regularity requirements on the field v to give a meaning to the 253quantity $\int_{F} (\boldsymbol{v} \cdot \boldsymbol{n}_{K}) \phi \, \mathrm{d}s$, where ϕ is a given smooth function on F (e.g., a polyno-254mial function). It is well established that it is possible to give a weak meaning in 255 $H^{-\frac{1}{2}}(\partial K)$ to the normal trace of \boldsymbol{v} on ∂K by means of an integration by parts for-256mula if $\boldsymbol{v} \in \boldsymbol{H}(\operatorname{div}; K) := \{ \boldsymbol{v} \in \boldsymbol{L}^2(K) \mid \nabla \cdot \boldsymbol{v} \in L^2(K) \}$. In this situation, one can 257define the normal trace $\gamma^{\rm d}_{\partial K}(\boldsymbol{v}) \in H^{-\frac{1}{2}}(\partial K)$ by setting 258

259 (3.1)
$$\langle \gamma^{\mathrm{d}}_{\partial K}(\boldsymbol{v}), \psi \rangle_{\partial K} := \int_{K} \left(\boldsymbol{v} \cdot \nabla w(\psi) + (\nabla \cdot \boldsymbol{v}) w(\psi) \right) \mathrm{d}x,$$

for all $\psi \in H^{\frac{1}{2}}(\partial K)$, where $w(\psi) \in H^{1}(K)$ is a lifting of ψ , i.e., $\gamma_{\partial K}^{g}(w(\psi)) = \psi$, and 260 $\gamma_{\partial K}^{\mathrm{g}}: H^{1}(K) \to H^{\frac{1}{2}}(\partial K)$ is the trace map locally in K. Then, one has $\gamma_{\partial K}^{\mathrm{d}}(\boldsymbol{v}) = \boldsymbol{v}_{|\partial K} \cdot \boldsymbol{n}_{K}$ whenever \boldsymbol{v} is smooth, e.g., if $\boldsymbol{v} \in \boldsymbol{H}(\mathrm{div}; K) \cap \boldsymbol{C}^{0}(\overline{K})$. However, the above 261262meaning is too weak for our purpose because we need to localize the action of the 263normal trace to functions ϕ only defined on a face F, i.e., ϕ may not be defined over 264the whole boundary ∂K . The key to achieve this is to extend ϕ by zero from F to 265 ∂K . This obliges us to change the functional setting since the extended function is 266no longer in $H^{\frac{1}{2}}(\partial K)$. In what follows, we are going to use the fact that the zero-267extension of a smooth function defined on a face F of ∂K is in $W^{1-\frac{1}{t},t}(\partial K)$ if t < 2, 268i.e., $t(1-\frac{1}{t}) < 1$. Let us now present a rigorous construction. 269

270 Let p, q be two real numbers such that

271 (3.2)
$$p > 2, \qquad q > \frac{2d}{2+d}.$$

Notice that q > 1 since $d \ge 2$. Let $\tilde{p} \in (2, p]$ be such that $q \ge \frac{\tilde{p}d}{\tilde{p}+d}$; this is indeed possible since p > 2, $q > \frac{2d}{2+d}$, and the function $z \mapsto \frac{zd}{z+d}$ is increasing over \mathbb{R}_+ . Lemma 3.1 shows that there exists a bounded lifting operator

275 (3.3)
$$L_F^K : W^{\frac{1}{p}, \widetilde{p}'}(F) \longrightarrow W^{1, \widetilde{p}'}(K),$$

with conjugate number \tilde{p}' s.t. $\frac{1}{\tilde{p}} + \frac{1}{\tilde{p}'} = 1$, so that for any $\phi \in W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)$, $L_F^K(\phi)$ is a lifting of the zero-extension of ϕ to ∂K , i.e.,

278 (3.4)
$$\gamma_{\partial K}^{g}(L_{F}^{K}(\phi))|_{\partial K\setminus F} = 0, \qquad \gamma_{\partial K}^{g}(L_{F}^{K}(\phi))|_{F} = \phi.$$

Notice that the domain of L_F^K is of the form $W^{1-\frac{1}{t},t}(F)$ with $t = \tilde{p}' < 2$, which is consistent with the above observation regarding the zero-extension to ∂K of functions defined on F. We also observe that

282 (3.5)
$$L_F^K(\phi) \in W^{1,p'}(K) \cap L^{q'}(K),$$

with conjugate numbers p', q' s.t. $\frac{1}{p} + \frac{1}{p'} = 1$, $\frac{1}{q} + \frac{1}{q'} = 1$. Indeed, $L_F^K(\phi) \in W^{1,p'}(K)$ just follows from $p' \leq \tilde{p}'$ (i.e., $\tilde{p} \leq p$), whereas $L_F^K(\phi) \in L^{q'}(K)$ follows from $W^{1,\tilde{p}'}(K) \hookrightarrow L^{q'}(K)$ owing to the Sobolev Embedding Theorem (since $q' \leq \frac{\tilde{p}'d}{d-\tilde{p}'}$, as can be verified from $d \geq 2 > \tilde{p}'$ and $\frac{1}{\tilde{p}'} - \frac{1}{d} = 1 - (\frac{1}{\tilde{p}} + \frac{1}{d}) \leq 1 - \frac{1}{q} = \frac{1}{q'}$ because $q \geq \frac{\tilde{p}d}{\tilde{p}+d}$). We now state our main result on the lifting operator L_F^K .

LEMMA 3.1 (Face-to-cell lifting). Let p and q satisfy (3.2). Let $\tilde{p} \in (2, p]$ be such that $q \geq \frac{\tilde{p}d}{\tilde{p}+d}$. Let $K \in \mathcal{T}_h$ be a mesh cell and let $F \in \mathcal{F}_K$ be a face of K. There exists a lifting operator $L_F^K : W^{\frac{1}{p}, \tilde{p}'}(F) \to W^{1, \tilde{p}'}(K)$ satisfying (3.4), and there exists c, uniform w.r.t. $h \in \mathcal{H}$, but depending on p and q, s.t. the following holds true:

292 (3.6)
$$h_{K}^{\frac{d}{p}} | L_{F}^{K}(\phi) |_{W^{1,p'}(K)} + h_{K}^{-1+\frac{d}{q}} \| L_{F}^{K}(\phi) \|_{L^{q'}(K)} \le c h_{K}^{-\frac{1}{p}+\frac{d}{p}} \| \phi \|_{W^{\frac{1}{p},\tilde{p}'}(F)},$$

293 for all
$$\phi \in W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)$$
 with the norm $\|\phi\|_{W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)} := \|\phi\|_{L^{\tilde{p}'}(F)} + h_{F}^{\frac{1}{\tilde{p}}} |\phi|_{W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)}$.

Proof. (1) The face-to-cell lifting operator L_F^K is constructed from a lifting op-294erator $L_{\widehat{F}}^{\widehat{K}}$ on the reference cell. Let \widehat{K} be the reference cell and let \widehat{F} be one of 295its faces. Let us define the operator $L_{\widehat{F}}^{\widehat{K}}: W^{\frac{1}{p}, \widetilde{p}'}(\widehat{F}) \to W^{1, \widetilde{p}'}(\widehat{K})$. For any func-296 tion $\psi \in W^{\frac{1}{\tilde{p}}, \tilde{p}'}(\hat{F})$, let $\tilde{\psi}$ denote the zero-extension of ψ to $\partial \hat{K}$. Owing to Grisvard [28, Thm. 1.4.2.4, Cor. 1.4.4.5], $\tilde{\psi}$ is in $W^{\frac{1}{\tilde{p}}, \tilde{p}'}(\partial \hat{K})$ since $\frac{\tilde{p}'}{\tilde{p}} = \frac{1}{\tilde{p}-1} < 1$ (i.e., 297298 $\widetilde{p} > 2$), and we have $\|\widetilde{\psi}\|_{W^{\frac{1}{p},\widetilde{p}'}(\partial\widehat{K})} \leq \widehat{c}_1 \|\psi\|_{W^{\frac{1}{p},\widetilde{p}'}(\widehat{F})}$ with the norm $\|\psi\|_{W^{\frac{1}{p},\widetilde{p}'}(\widehat{F})} :=$ 299 $\|\psi\|_{L^{\tilde{p}'}(\widehat{F})} + \ell_{\widehat{K}}^{\frac{1}{\tilde{p}}} |\psi|_{W^{\frac{1}{\tilde{p}}, \tilde{p}'}(\widehat{F})}$ where $\ell_{\widehat{K}} = 1$ is a length scale associated with \widehat{K} . Then we 300 use the surjectivity of the trace map $\gamma_{\widehat{K}}^{g}: W^{1,\widetilde{p}'}(\widehat{K}) \to W^{\frac{1}{p},\widetilde{p}'}(\partial\widehat{K})$ (see Gagliardo [27, Thm. 1.I]) to define $L_{\widehat{F}}^{\widehat{K}}(\psi) \in W^{1,\widetilde{p}'}(\widehat{K})$ s.t. $\gamma_{\widehat{K}}^{g}(L_{\widehat{F}}^{\widehat{K}}(\psi)) = \widetilde{\psi}$ and $\|L_{\widehat{F}}^{\widehat{K}}(\psi)\|_{W^{1,\widetilde{p}'}(\widehat{K})} \leq U^{1,\widetilde{p}'}(\widehat{K})$ 301 302

7

303 $\widehat{c}_2 \|\widetilde{\psi}\|_{W^{\frac{1}{\widetilde{p}},\widetilde{p}'}(\partial\widehat{K})}$, i.e., $\|L_{\widehat{F}}^{\widehat{K}}(\psi)\|_{W^{1,\widetilde{p}'}(\widehat{K})} \leq \widehat{c}\|\psi\|_{W^{\frac{1}{\widetilde{p}},\widetilde{p}'}(\widehat{F})}$, with $\widehat{c} = \widehat{c}_1\widehat{c}_2$. By construction

304 tion, we have $\gamma^{g}_{\partial \widehat{K}}(L_{\widehat{F}}^{\widehat{K}}(\psi))|_{\widehat{F}} = \psi$ and $\gamma^{g}_{\partial \widehat{K}}(L_{\widehat{F}}^{\widehat{K}}(\psi))|_{\partial \widehat{K}\setminus\widehat{F}} = 0.$

305 (2) We define the lifting operator $L_F^K : W^{\frac{1}{p}, \widetilde{p}'}(F) \to W^{1, \widetilde{p}'}(K)$ by setting

306 (3.7)
$$L_F^K(\phi)(\boldsymbol{x}) := L_{\widehat{F}}^{\widehat{K}}(\phi \circ \boldsymbol{T}_{K|\widehat{F}})(\boldsymbol{T}_K^{-1}(\boldsymbol{x})), \quad \forall \boldsymbol{x} \in K, \quad \forall \phi \in W^{\frac{1}{\widehat{p}}, \widehat{p}'}(F),$$

where $T_K : \widehat{K} \to K$ is the geometric mapping and $\widehat{F} = T_K^{-1}(F)$. By definition, if $x \in F$, then $\widehat{x} := T_K^{-1}(x) \in \widehat{F}$ and $T_{K|\widehat{F}}(\widehat{x}) = x$, so that

309
$$\gamma_{\partial K}^{g}(L_{F}^{K}(\phi))(\boldsymbol{x}) = \gamma_{\partial \widehat{K}}^{g}(L_{\widehat{F}}^{\widehat{K}}(\phi \circ \boldsymbol{T}_{K|\widehat{F}}))(\widehat{\boldsymbol{x}}) = \phi(\boldsymbol{T}_{K|\widehat{F}}(\widehat{\boldsymbol{x}})) = \phi(\boldsymbol{x}),$$

whereas if $\boldsymbol{x} \in \partial K \setminus F$, then $\hat{\boldsymbol{x}} \in \partial \widehat{K} \setminus \widehat{F}$, so that $\gamma_{\partial \widehat{K}}^{g}(L_{\widehat{F}}^{\widehat{K}}(\phi \circ \boldsymbol{T}_{K|\widehat{F}}))(\hat{\boldsymbol{x}}) = 0$. The above argument shows that (3.4) holds true.

(3) It remains to prove (3.6). Let us first bound $|L_F^K(\phi)|_{W^{1,p'}(K)}$. Notice that the definition of L_K^F is equivalent to $L_F^K(\phi) \circ \mathbf{T}_K(\widehat{\mathbf{x}}) := L_{\widehat{F}}^{\widehat{K}}(\phi \circ \mathbf{T}_{K|\widehat{F}})(\widehat{\mathbf{x}})$; that is, $\psi_K^g(L_F^K(\phi)) := L_{\widehat{F}}^{\widehat{K}}(\psi_F^g(\phi))$, where ψ_K^g is the pullback by \mathbf{T}_K , and ψ_F^g is the pullback by $\mathbf{T}_{K|\widehat{F}}$. Denoting by \mathbb{J}_K the Jacobian of the geometric mapping \mathbf{T}_K , we infer that

316
$$|L_{F}^{K}(\phi)|_{W^{1,p'}(K)} \leq c \, \|\mathbb{J}_{K}^{-1}\|_{\ell^{2}} |\det(\mathbb{J}_{K})|^{\frac{1}{p'}} |L_{\widehat{F}}^{\widehat{K}}(\psi_{F}^{g}(\phi))|_{W^{1,p'}(\widehat{K})}$$

317
$$\leq c' \, \|\mathbb{J}_{K}^{-1}\|_{\ell^{2}} |\det(\mathbb{J}_{K})|^{\frac{1}{p'}} |L_{\widehat{F}}^{K}(\psi_{F}^{g}(\phi))|_{W^{1,\widetilde{p'}}(\widehat{K})}$$

$$\leq c'' \|\mathbb{J}_{K}^{-1}\|_{\ell^{2}} |\det(\mathbb{J}_{K})|^{\frac{1}{p'}} \|\psi_{F}^{g}(\phi)\|_{W^{\frac{1}{p},\tilde{p}'}(\widehat{F})}$$

where the first inequality follows from the chain rule, the second is a consequence of $\widetilde{p}' \geq p'$ (since $\widetilde{p} \leq p$), and the third follows from the stability of the reference lifting operator $L_{\widehat{F}}^{\widehat{K}}$. Using now the chain rule and the shape-regularity of the mesh sequence, we infer that $\|\psi_F^{g}(\phi)\|_{W^{\frac{1}{p},\widetilde{p}'}(\widehat{F})} \leq c |\det(\mathbb{J}_F)|^{-\frac{1}{\widetilde{p}'}} \|\phi\|_{W^{\frac{1}{p},\widetilde{p}'}(F)}$, where \mathbb{J}_F is the Jacobian of the mapping $\mathbf{T}_{K|\widehat{F}}: \widehat{F} \to F$. Combining these bounds, we obtain

325
$$|L_{F}^{K}(\phi)|_{W^{1,p'}(K)} \leq c \, \|\mathbb{J}_{K}^{-1}\|_{\ell^{2}} |\det(\mathbb{J}_{K})|^{\frac{1}{p'}} |\det(\mathbb{J}_{F})|^{-\frac{1}{\tilde{p}'}} \|\phi\|_{W^{\frac{1}{\tilde{p}},\tilde{p}'}(F)}$$

$$\leq c' h_K^{-\overline{p}+a(\overline{p}-\overline{p})} \|\phi\|_{W^{\frac{1}{p},\overline{p}'}(F)},$$

where the second bound follows from the shape-regularity of the mesh sequence. This proves the bound on $|L_F^K(\phi)|_{W^{1,p'}(K)}$ in (3.6). The proof of the bound on $||L_F^K(\phi)||_{L^{q'}(K)}$ uses similar arguments together with $W^{1,\widetilde{p}'}(\widehat{K}) \hookrightarrow L^{q'}(\widehat{K})$ owing to the Sobolev Embedding Theorem and $q' \leq \frac{\widetilde{p}'d}{d-\widetilde{p}'}$ (as already shown above).

332 **3.2. Face localization of the normal diffusive flux.** Let $K \in \mathcal{T}_h$ be a mesh 333 cell, $F \in \mathcal{F}_K$ be a face of K, and consider the following functional space:

334 (3.8)
$$\boldsymbol{S}^{\mathrm{d}}(K) := \{ \boldsymbol{\tau} \in \boldsymbol{L}^{p}(K) \mid \nabla \cdot \boldsymbol{\tau} \in L^{q}(K) \},\$$

335 equipped with the following dimensionally-consistent norm:

336 (3.9)
$$\|\boldsymbol{\tau}\|_{\boldsymbol{S}^{d}(K)} := \|\boldsymbol{\tau}\|_{\boldsymbol{L}^{p}(K)} + h_{K}^{1+d(\frac{1}{p}-\frac{1}{q})} \|\nabla \cdot \boldsymbol{\tau}\|_{L^{q}(K)}.$$

With the lifting operator L_F^K in hand, we now define the normal trace on the face F of K of any field $\boldsymbol{\tau} \in \boldsymbol{S}^{\mathrm{d}}(K)$ to be the linear form in $(W^{\frac{1}{p}, \widetilde{p}'}(F))'$ denoted by $(\boldsymbol{\tau} \cdot \boldsymbol{n}_K)_{|F}$ and whose action on any function $\phi \in W^{\frac{1}{p}, \widetilde{p}'}(F)$ is

340 (3.10)
$$\langle (\boldsymbol{\tau} \cdot \boldsymbol{n}_K)_{|F}, \phi \rangle_F := \int_K \left(\boldsymbol{\tau} \cdot \nabla L_F^K(\phi) + (\nabla \cdot \boldsymbol{\tau}) L_F^K(\phi) \right) \mathrm{d}x$$

Here, $\langle \cdot, \cdot \rangle_F$ denotes the duality pairing between $(W^{\frac{1}{p}, \vec{p}'}(F))'$ and $W^{\frac{1}{p}, \vec{p}'}(F)$. Notice that the right-hand side of (3.10) is well-defined owing to Hölder's inequality and (3.6). Owing to (3.4), we readily verify that we have indeed defined an extension of the normal trace since we have $\langle (\boldsymbol{\tau} \cdot \boldsymbol{n}_K)|_F, \phi \rangle_F = \int_F (\boldsymbol{\tau} \cdot \boldsymbol{n}_K) \phi \, ds$ whenever the field $\boldsymbol{\tau}$ is smooth. Let us now derive an important bound on the linear form $(\boldsymbol{\tau} \cdot \boldsymbol{n}_K)|_F$ when acting on a function from the space P_F , which we define to be composed of the restrictions to F of the functions in P_K . Note that $P_F \subset W^{\frac{1}{p}, \vec{p}'}(F)$.

LEMMA 3.2 (Bound on normal component). There exists a constant c, uniform w.r.t. $h \in \mathcal{H}$, but depending on p and q, s.t. the following holds true:

$$|\langle (\boldsymbol{\tau} \cdot \boldsymbol{n}_K)_{|F}, \phi_h \rangle_F| \le c h_K^{d(\frac{1}{2} - \frac{1}{p})} \|\boldsymbol{\tau}\|_{\boldsymbol{S}^{\mathrm{d}}(K)} h_F^{-\frac{1}{2}} \|\phi_h\|_{L^2(F)},$$

for all $\boldsymbol{\tau} \in \boldsymbol{S}^{\mathrm{d}}(K)$, all $\phi_h \in P_F$, all $K \in \mathcal{T}_h$, and all $F \in \mathcal{F}_K$.

353 *Proof.* A direct consequence of (3.10), Hölder's inequality, and Lemma 3.1 is that

354
$$|\langle (\boldsymbol{\tau} \cdot \boldsymbol{n}_K)|_F, \phi \rangle_F| \le c h_K^{-\frac{1}{\tilde{p}} + d(\frac{1}{\tilde{p}} - \frac{1}{p})} \|\boldsymbol{\tau}\|_{\boldsymbol{S}^{\mathrm{d}}(K)} \|\phi\|_{W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)}.$$

for all $\phi \in W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)$. Recalling that $\|\phi\|_{W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)} = \|\phi\|_{L^{\tilde{p}'}(F)} + h_F^{\frac{1}{\tilde{p}}}|\phi|_{W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)}$, the shape-regularity of the mesh sequence implies that the following inverse inequality $\|\phi_h\|_{W^{\frac{1}{\tilde{p}}, \tilde{p}'}(F)} \leq ch_F^{(d-1)(\frac{1}{2}-\frac{1}{\tilde{p}})} \|\phi_h\|_{L^2(F)}$ holds true for all $\phi_h \in P_F$ (note that $\frac{1}{2} - \frac{1}{\tilde{p}} =$ $\frac{1}{\tilde{p}'} - \frac{1}{2}$). The estimate (3.11) follows readily.

3.3. Definition of n_{\sharp} and key identities. Let us consider the functional space 359 $V_{\rm s}$ defined in (2.5). For all $v \in V_{\rm s}$, Lemma 2.1 shows that $\boldsymbol{\sigma}(v)_{|K} \in \boldsymbol{S}^{\rm d}(K)$ for all 360 $K \in \mathcal{T}_h$, and Lemma 3.2 implies that it is possible to give a meaning by duality 361 to the normal component of $\sigma(v)_{|K}$ on all the faces of K separately. Moreover, 362 since we have set $\sigma(v_h)_{|K} := -\lambda_K \nabla(v_{h|K})$ for all $v_h \in P_k^{\rm b}(\mathcal{T}_h)$, and since we have 363 $P_K \subset W^{k+1,\infty}(K)$ with $k \geq 1$, we infer that $\boldsymbol{\sigma}(v_h)_{|K} \in \boldsymbol{S}^{\mathrm{d}}(K)$ as well. Thus, 364 $\boldsymbol{\sigma}(v)_{|K} \in \boldsymbol{S}^{\mathrm{d}}(K)$ for all $v \in (V_{\mathrm{s}} + P_{k}^{\mathrm{b}}(\mathcal{T}_{h}))$. Let us now introduce the bilinear form 365 $n_{\sharp}: (V_{\mathrm{s}} + P_{k}^{\mathrm{b}}(\mathcal{T}_{h})) \times P_{k}^{\mathrm{b}}(\mathcal{T}_{h}) \to \mathbb{R}$ defined as follows: 366

$$\begin{array}{ll} 367 \quad (3.12) \\ 368 \end{array} \qquad n_{\sharp}(v, w_h) := \sum_{F \in \mathcal{F}_h} \sum_{K \in \mathcal{T}_F} \epsilon_{K,F} \theta_{K,F} \langle (\boldsymbol{\sigma}(v)_{|K} \cdot \boldsymbol{n}_K)_{|F}, \llbracket w_h \rrbracket \rangle_F,$$

369 where the weights $\theta_{K,F}$ are still unspecified but are assumed to satisfy

370 (3.13)
$$\theta_{K_l,F}, \theta_{K_r,F} \in [0,1] \text{ and } \theta_{K_l,F} + \theta_{K_r,F} = 1, \quad \forall F \in \mathcal{F}_h^\circ,$$

whereas for all $F \in \mathcal{F}_h^\partial$ with $F = \partial K_l \cap \partial D$, we set $\theta_{K_l,F} := 1$, $\theta_{K_r,F} := 0$. We will see in (3.19) below how these weights must depend on the diffusion coefficient to

373 get a robust boundedness estimate on n_{\sharp} . The definition (3.12) is meaningful since

 $[w_h]_F \in P_F$ for all $w_h \in P_k^{\rm b}(\mathcal{T}_h)$. The factor $\epsilon_{K,F}$ in (3.12) handles the relative orientation of \boldsymbol{n}_K and \boldsymbol{n}_F . For all $v \in W^{1,1}(\mathcal{T}_h)$, we define weighted averages as follows for a.e. $\boldsymbol{x} \in F \in \mathcal{F}_h^{\circ}$:

377 (3.14a)
$$\{v\}_{F,\theta}(\boldsymbol{x}) := \theta_{K_l,F} v_{|K_l}(\boldsymbol{x}) + \theta_{K_r,F} v_{|K_r}(\boldsymbol{x}),$$

378 (3.14b)
$$\{v\}_{F,\bar{\theta}}(\boldsymbol{x}) := \theta_{K_r,F} v_{|K_l}(\boldsymbol{x}) + \theta_{K_l,F} v_{|K_r}(\boldsymbol{x}).$$

Whenever $\theta_{K_l,F} = \theta_{K_r,F} = \frac{1}{2}$, these two definitions coincide with the usual arithmetic average. On boundary faces $F \in \mathcal{F}_h^\partial$, we have $\{v\}_{F,\theta}(\boldsymbol{x}) = v_{|K_l}(\boldsymbol{x})$, and $\{v\}_{F,\bar{\theta}}(\boldsymbol{x}) = 0$ for a.e. $\boldsymbol{x} \in F$. We omit the subscript $_F$ whenever the context is unambiguous. The following identity will be useful:

384 (3.15)
$$[vw] = \{v\}_{\theta} [w] + [v] \{w\}_{\bar{\theta}}.$$

The following lemma is fundamental to understand the role that the bilinear form will play in the next section in the analysis of various nonconforming approximation methods.

LEMMA 3.3 (Identities for n_{\sharp}). The following holds true for any choice of weights $\{\theta_{K,F}\}_{F \in \mathcal{F}_h, K \in \mathcal{T}_F}$ and for all $w_h \in P_k^{\mathrm{b}}(\mathcal{T}_h)$, all $v_h \in P_k^{\mathrm{b}}(\mathcal{T}_h)$, and all $v \in V_{\mathrm{s}}$:

390 (3.16a)
$$n_{\sharp}(v_h, w_h) = \sum_{F \in \mathcal{F}_h} \int_F \{\boldsymbol{\sigma}(v_h)\}_{\theta} \cdot \boldsymbol{n}_F[\![w_h]\!] \, \mathrm{d}s,$$

391 (3.16b)
$$n_{\sharp}(v, w_h) = \sum_{K \in \mathcal{T}_h} \int_K \left(\boldsymbol{\sigma}(v) \cdot \nabla w_{h|K} + (\nabla \cdot \boldsymbol{\sigma}(v)) w_{h|K} \right) \mathrm{d}x. \qquad \Box$$
392

Proof. (1) Proof of (3.16a). Let $v_h, w_h \in P_k^{\rm b}(\mathcal{T}_h)$. Since the restriction of $\boldsymbol{\sigma}(v_h)$ to each mesh cell is smooth, and since the restriction of $L_F^K(\llbracket w_h \rrbracket)$ to ∂K is nonzero only on the face $F \in \mathcal{F}_K$ where it coincides with $\llbracket w_h \rrbracket$, we have

$$\begin{array}{ll} 396 \quad \langle (\boldsymbol{\sigma}(v_h)_{|K} \cdot \boldsymbol{n}_K)_{|F}, \llbracket w_h \rrbracket \rangle_F &= \int_K \left(\boldsymbol{\sigma}(v_h)_{|K} \cdot \nabla L_F^K(\llbracket w_h \rrbracket) + (\nabla \cdot \boldsymbol{\sigma}(v_h)_{|K}) L_F^K(\llbracket w_h \rrbracket) \right) \mathrm{d}x \\ &= \int_{\partial K} \boldsymbol{\sigma}(v_h)_{|K} \cdot \boldsymbol{n}_K L_F^K(\llbracket w_h \rrbracket) \mathrm{d}s = \int_F \boldsymbol{\sigma}(v_h)_{|K} \cdot \boldsymbol{n}_K \llbracket w_h \rrbracket \mathrm{d}s,$$

where we used the divergence formula in K. Therefore, after using the definitions of $\epsilon_{K,F}$ and of $\theta_{K,F}$, we obtain

401
$$n_{\sharp}(v_h, w_h) = \sum_{F \in \mathcal{F}_h} \sum_{K \in \mathcal{T}_F} \epsilon_{K,F} \theta_{K,F} \int_F \boldsymbol{\sigma}(v_h)_{|K} \cdot \boldsymbol{n}_K \llbracket w_h \rrbracket \, \mathrm{d}s$$

402
403
$$= \sum_{F \in \mathcal{F}_h} \int_F \{ \boldsymbol{\sigma}(v_h) \}_{\theta} \cdot \boldsymbol{n}_F \llbracket w_h \rrbracket \, \mathrm{d}s.$$

404 (2) Proof of (3.16b). Let $v \in V_s$ and $w_h \in P_k^{\rm b}(\mathcal{T}_h)$. Let $\mathcal{K}^{\rm d}_{\delta} : L^1(D) \to C^{\infty}(\overline{D})$ and 405 $\mathcal{K}^{\rm b}_{\delta} : L^1(D) \to C^{\infty}(\overline{D})$ be the mollification operators introduced in [22, §3.2]. These 406 two operators satisfy the following key commuting property:

407 (3.17)
$$\nabla \cdot (\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\tau})) = \mathcal{K}^{\mathrm{b}}_{\delta}(\nabla \cdot \boldsymbol{\tau}),$$

for all $\tau \in L^1(D)$ s.t. $\nabla \cdot \tau \in L^1(D)$. It is important to realize that this property can be applied to $\sigma(v)$ for all $v \in V_s$ since $\nabla \cdot \sigma(v) \in L^1(D)$ by definition of V_s . (Note

that this property cannot be applied to $\boldsymbol{\sigma}(v_h)$ with $v_h \in P_k^{\mathrm{b}}(\mathcal{T}_h)$, since the normal component of $\boldsymbol{\sigma}(v_h)$ is in general discontinuous across the mesh interfaces, i.e., $\boldsymbol{\sigma}(v_h)$ does not have a weak divergence.) Let us consider the mollified bilinear form

413
$$n_{\sharp\delta}(v,w_h) := \sum_{F \in \mathcal{F}_h} \sum_{K \in \mathcal{T}_F} \epsilon_{K,F} \theta_{K,F} \langle (\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v))_{|K} \cdot \boldsymbol{n}_K)_{|F}, \llbracket w_h \rrbracket \rangle_F.$$

414 Owing to the commuting property (3.17), we infer that

419 Then Theorem 3.3 from [22] implies that

415

421
$$\lim_{\delta \to 0} \int_{K} \left(\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v)) \cdot L_{F}^{K}(\llbracket w_{h} \rrbracket) + \mathcal{K}^{\mathrm{b}}_{\delta}((\nabla \cdot \boldsymbol{\sigma}(v))) L_{F}^{K}(\llbracket w_{h} \rrbracket) \right) \mathrm{d}x =$$
422
$$\int_{K} \left(\boldsymbol{\sigma}(v) \cdot L_{F}^{K}(\llbracket w_{h} \rrbracket) + (\nabla \cdot \boldsymbol{\sigma}(v)) L_{F}^{K}(\llbracket w_{h} \rrbracket) \right) \mathrm{d}x = \langle (\boldsymbol{\sigma}(v)_{|K} \cdot \boldsymbol{n}_{K})_{|F}, \llbracket w_{h} \rrbracket \rangle_{F}.$$

424 Summing over the mesh faces and the associated mesh cells, we infer that

425
$$\lim_{\delta \to 0} n_{\sharp\delta}(v, w_h) = n_{\sharp}(v, w_h).$$

426 Moreover, since the mollified function $\mathcal{K}^{d}_{\delta}(\boldsymbol{\sigma}(v))$ is smooth, by repeating the calcula-427 tion done in Step (1), we also have

428
429
$$n_{\sharp\delta}(v, w_h) = \sum_{F \in \mathcal{F}_h} \int_F \{\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v))\}_{\theta} \cdot \boldsymbol{n}_F \llbracket w_h \rrbracket \, \mathrm{d}s.$$

430 Using the identity (3.15) with $[\![\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v))]\!] \cdot \boldsymbol{n}_{F} = 0$ for all $F \in \mathcal{F}^{\circ}_{h}$, recalling that 431 $[\![w_{h}\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v))]\!] = w_{h}\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v))|_{F}$ for all $F \in \mathcal{F}^{\partial}_{h}$, and using the divergence formula in 432 K and the commuting property (3.17), we obtain

433
$$n_{\sharp\delta}(v,w_h) = \sum_{F\in\mathcal{F}_h} \int_F \{\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v))\}_{\theta} \cdot \boldsymbol{n}_F \llbracket w_h \rrbracket \,\mathrm{d}s + \sum_{F\in\mathcal{F}^o_h} \int_F \llbracket \mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v)) \rrbracket \cdot \boldsymbol{n}_F \{w_h\}_{\bar{\theta}} \,\mathrm{d}s$$

$$\sum_{F\in\mathcal{F}_h} \int_F \llbracket \mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v)) \rrbracket \cdot \boldsymbol{n}_F \{w_h\}_{\bar{\theta}} \,\mathrm{d}s$$

434
$$= \sum_{F \in \mathcal{F}_h} \int_F \llbracket w_h \mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v)) \rrbracket \cdot \boldsymbol{n}_F \,\mathrm{d}s = \sum_{K \in \mathcal{T}_h} \int_{\partial K} \mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v)) \cdot \boldsymbol{n}_K w_{h|K} \,\mathrm{d}s$$

435
436
$$= \sum_{K \in \mathcal{T}_h} \int_K \left(\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v)) \cdot \nabla w_{h|K} + \mathcal{K}^{\mathrm{b}}_{\delta}(\nabla \cdot \boldsymbol{\sigma}(v)) w_{h|K} \right) \mathrm{d}x.$$

437 Invoking again Theorem 3.3 from [22] leads to the assertion since

438
$$\lim_{\delta \to 0} n_{\sharp \delta}(v, w_h) = \sum_{K \in \mathcal{T}_h} \int_K \left(\boldsymbol{\sigma}(v) \cdot \nabla w_{h|K} + (\nabla \cdot \boldsymbol{\sigma}(v)) w_{h|K} \right) \mathrm{d}x.$$

439 Remark 3.4 (Identity (3.16b)). The identity (3.16b) is the key tool to assert in 440 a weak sense that $\boldsymbol{\sigma}(v) \cdot \boldsymbol{n}$ is continuous across the mesh interfaces without the need 441 to assume that v is smooth, say $v \in H^{1+r}(D)$ with $r > \frac{1}{2}$.

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442 We now establish an important boundedness estimate on the bilinear form n_{\sharp} . 443 Since $\boldsymbol{\sigma}(v)_{|K} \in \mathbf{S}^{d}(K)$ for all $K \in \mathcal{T}_{h}$ and all $v \in V_{s} + P_{k}^{b}(\mathcal{T}_{h})$, we can equip the space 444 $V_{s} + P_{k}^{b}(\mathcal{T}_{h})$ with the seminorm

445 (3.18)
$$|v|_{n_{\sharp}}^{2} := \sum_{K \in \mathcal{T}_{h}} \lambda_{K}^{-1} \Big(h_{K}^{2d(\frac{1}{2} - \frac{1}{p})} \|\boldsymbol{\sigma}(v)|_{K} \|_{\boldsymbol{L}^{p}(K)}^{2} + h_{K}^{2d(\frac{2+d}{2d} - \frac{1}{q})} \|\nabla \cdot \boldsymbol{\sigma}(v)|_{K} \|_{\boldsymbol{L}^{q}(K)}^{2} \Big).$$

446 We notice that this seminorm is dimensionally-consistent with the classical energy-447 norm defined as $\sum_{K \in \mathcal{T}_h} \lambda_K \|\nabla v_{|K}\|_{L^2(K)}^2$. Straightforward algebra shows that $|v|_{\sharp} \leq$ 448 $c\lambda_{\flat}^{-\frac{1}{2}}(\ell_D^{d(\frac{1}{2}-\frac{1}{p})} \|\boldsymbol{\sigma}(v)\|_{L^p(D)} + \ell_D^{d(\frac{2+d}{2d}-\frac{1}{q})} \|\nabla \cdot \boldsymbol{\sigma}(v)\|_{L^q(D)})$, for all $v \in V_s$; here ℓ_D denotes 449 a characteristic length of D. (Recall that $\|a\|_{\ell^s(\mathcal{I})} \leq \|a\|_{\ell^t(\mathcal{I})}$ for any finite sequence 450 $(a_i)_{i\in\mathcal{I}}$ if $0 < t \leq s$, and we assumed that $q \leq 2$.)

In order to get robust error estimates with respect to λ , it is important to avoid any dependency on the ratio of the values taken by λ in two adjacent subdomains; otherwise, the error estimates become meaningless when the diffusion coefficient λ is highly contrasted. To avoid such dependencies, we introduce the following diffusiondependent weights for all $F \in \mathcal{F}_h^{\circ}$, with $F = \partial K_l \cap \partial K_r$:

456 (3.19)
$$\theta_{K_l,F} := \frac{\lambda_{K_r}}{\lambda_{K_l} + \lambda_{K_r}}, \qquad \theta_{K_r,F} := \frac{\lambda_{K_l}}{\lambda_{K_l} + \lambda_{K_r}}$$

457 We also define

458 (3.20)
$$\lambda_F := \frac{2\lambda_{K_l}\lambda_{K_r}}{\lambda_{K_l} + \lambda_{K_r}} \text{ if } F \in \mathcal{F}_h^\circ \text{ and } \lambda_F := \lambda_{K_l} \text{ if } F \in \mathcal{F}_h^\partial.$$

The two properties we are going to use are that $|\mathcal{T}_F|\lambda_K\theta_{K,F} = \lambda_F$, for all $K \in \mathcal{T}_F$, and $\lambda_F \leq \min_{K \in \mathcal{T}_F} \lambda_K$. (Here $|\mathcal{T}_F|$ denotes the cardinality of \mathcal{T}_F .)

461 LEMMA 3.5 (Boundedness of n_{\sharp}). With the weights defined in (3.19) and λ_F 462 defined in (3.20) for all $F \in \mathcal{F}_h$, there is c, uniform w.r.t. $h \in \mathcal{H}$ and λ , but depending 463 on p and q, s.t. the following holds true for all $v \in V_s + P_k^{\rm b}(\mathcal{T}_h)$ and all $w_h \in P_k^{\rm b}(\mathcal{T}_h)$:

464 (3.21)
$$|n_{\sharp}(v, w_h)| \le c |v|_{n_{\sharp}} \left(\sum_{F \in \mathcal{F}_h} \lambda_F h_F^{-1} \| [\![w_h]\!] \|_{L^2(F)}^2 \right)^{\frac{1}{2}}.$$

465 Proof. Let $v \in V_{\rm s} + P_k^{\rm b}(\mathcal{T}_h)$ and $w_h \in P_k^{\rm b}(\mathcal{T}_h)$. Owing to the definition (3.12) of 466 n_{\sharp} and the estimate (3.11) from Lemma 3.2, we infer that

467
$$|n_{\sharp}(v,w_h)| \le c \sum_{F \in \mathcal{F}_h} \sum_{K \in \mathcal{T}_F} \theta_{K,F} h_K^{d(\frac{1}{2} - \frac{1}{p})} \|\boldsymbol{\sigma}(v)|_K \|_{\boldsymbol{S}^d(K)} h_F^{-\frac{1}{2}} \| [\![w_h]\!] \|_{L^2(F)}$$

468
$$\leq c \bigg(\sum_{F \in \mathcal{F}_h} \sum_{K \in \mathcal{T}_F} \lambda_K^{-\frac{1}{2}} h_K^{d(\frac{1}{2} - \frac{1}{p})} \|\boldsymbol{\sigma}(v)|_K \|_{\boldsymbol{L}^p(K)} |\mathcal{T}_F|^{-\frac{1}{2}} \lambda_F^{\frac{1}{2}} h_F^{-\frac{1}{2}} \| [\![w_h]\!] \|_{L^2(F)} \bigg|_{L^p(K)} \|\boldsymbol{\sigma}(v)|_K \|_{\boldsymbol{L}^p(K)} \|\mathcal{T}_F\|^{-\frac{1}{2}} \| \|w_h\| \|_{L^p(F)} \| \|w_h\| \|_{L^p(F)} \|\boldsymbol{\sigma}(v)|_K \| \|\boldsymbol{\sigma}(v)\|_K \| \| \|\boldsymbol{\sigma}(v)\|_K \| \|$$

469
$$+ \sum_{F \in \mathcal{F}_h} \sum_{K \in \mathcal{T}_F} \lambda_K^{-\frac{1}{2}} h_K^{d(\frac{2+d}{2d} - \frac{1}{q})} \|\nabla \cdot \boldsymbol{\sigma}(v)|_K \|_{L^q(K)} |\mathcal{T}_F|^{-\frac{1}{2}} \lambda_F^{\frac{1}{2}} h_F^{-\frac{1}{2}} \|[\![w_h]\!]\|_{L^2(F)} \bigg),$$
470

471 where we used that $\theta_{K,F} \leq \theta_{K,F}^{\frac{1}{2}}$ (since $\theta_{K,F} \leq 1$), $|\mathcal{T}_F|\lambda_K\theta_{K,F} = \lambda_F$, the definition of 472 $\|\cdot\|_{\mathbf{S}^{d}(K)}$, and $1 + d(\frac{1}{2} - \frac{1}{q}) = d(\frac{2+d}{2d} - \frac{1}{q})$. Owing to the Cauchy–Schwarz inequality, we 473 infer that $\sum_{F \in \mathcal{F}_h} \sum_{K \in \mathcal{T}_F} a_K |\mathcal{T}_F|^{-\frac{1}{2}} b_F \leq (\sum_{K \in \mathcal{T}_h} |\mathcal{F}_K| a_K^2)^{\frac{1}{2}} (\sum_{F \in \mathcal{F}_h} b_F^2)^{\frac{1}{2}}$, for all real 474 numbers $\{a_K\}_{K\in\mathcal{T}_h}, \{b_F\}_{F\in\mathcal{F}_h}$, where we used $\sum_{F\in\mathcal{F}_h}\sum_{K\in\mathcal{T}_F} = \sum_{K\in\mathcal{T}_h}\sum_{F\in\mathcal{F}_K}\sum_{F\in\mathcal{F}_K}$ 475 for the term involving the a_K 's. Since $|\mathcal{F}_K|$ is uniformly bounded $(|\mathcal{F}_K| = d + 1$ 476 for simplicial meshes), applying this bound to the two terms composing the above 477 estimate on $|n_{\sharp}(v, w_h)|$ leads to (3.21).

478 Remark 3.6 (Literature). Diffusion-dependent averages have been introduced in 479 Dryja [19] for discontinuous Galerkin methods and have been analyzed, e.g., in Bur-480 man and Zunino [10], Dryja et al. [20], Di Pietro et al. [17], Ern et al. [26]. \Box

481 **4. Applications.** The goal of this section is to perform a unified error analysis 482 for the approximation of the model problem (2.1) with various nonconforming meth-483 ods: Crouzeix–Raviart finite elements, Nitsche's boundary penalty, interior penalty 484 discontinuous Galerkin, and hybrid high-order methods. We assume that the exact 485 solution is in the functional space $V_{\rm s}$ defined in (2.5) with real numbers p, q satisfy-486 ing (3.2). Our unified analysis hinges on the dimensionally-consistent seminorm

487 (4.1)
$$|v|_{\lambda,p,q}^2 := \|\lambda^{\frac{1}{2}} \nabla_h v\|_{L^2(D)}^2 + |v|_{n_{\sharp}}^2, \quad \forall v \in V_{\mathrm{s}} + P_k^{\mathrm{b}}(\mathcal{T}_h).$$

488 with $|\cdot|_{n_{\sharp}}$ defined in (3.18). Since λ is piecewise constant, we have

489
$$|v|_{\lambda,p,q}^{2} := \sum_{K \in \mathcal{T}_{h}} \lambda_{K} \Big(\|\nabla v_{|K}\|_{L^{2}(K)}^{2} + h_{K}^{2d(\frac{1}{2} - \frac{1}{p})} \|\nabla v_{|K}\|_{L^{p}(K)}^{2} + h_{K}^{2d(\frac{d+2}{2d} - \frac{1}{q})} \|\Delta v_{|K}\|_{L^{q}(K)}^{2} \Big).$$

Invoking inverse inequalities shows that there is c, uniform w.r.t. $h \in \mathcal{H}$, but depending on p and q, s.t.

494 (4.3)
$$|v_h|_{\lambda,p,q} \le c \, \|\lambda^{\frac{1}{2}} \nabla v_h\|_{L^2(D)}, \qquad \forall v_h \in P_k^{\mathrm{b}}(\mathcal{T}_h).$$

495 **4.1.** Abstract approximation result. We start by recalling a general approx-496 imation result established in [25, Lem. 4.4]. Let V and W be two real Banach spaces. 497 Let $a(\cdot, \cdot)$ be a bounded bilinear form on $V \times W$, and let $\ell(\cdot)$ be a bounded linear form 498 on W, i.e., $\ell \in W'$. We consider the following abstract model problem:

499 (4.4)
$$\begin{cases} \text{Find } u \in V \text{ such that} \\ a(u, w) = \ell(w), \quad \forall w \in W, \end{cases}$$

which we assume to be well-posed in the sense of Hadamard; that is to say, there is a unique solution and this solution depends continuously on the data.

We now formulate a discrete version of the problem (4.4) by using the Galerkin method. We replace the infinite-dimensional spaces V and W by finite-dimensional spaces V_h and W_h that are members of sequences of spaces $(V_h)_{h\in\mathcal{H}}$, $(W_h)_{h\in\mathcal{H}}$ endowed with some approximation properties as $h \to 0$. The norms in V_h and W_h are denoted by $\|\cdot\|_{V_h}$ and $\|\cdot\|_{W_h}$, respectively. The discrete version of (4.4) is formulated as follows:

508 (4.5)
$$\begin{cases} \text{Find } u_h \in V_h \text{ such that} \\ a_h(u_h, w_h) = \ell_h(w_h), \quad \forall w_h \in W_h \end{cases}$$

where $a_h(\cdot, \cdot)$ is a bounded bilinear form on $V_h \times W_h$ and $\ell_h(\cdot)$ is a bounded linear form on W_h ; note that $a_h(\cdot, \cdot)$ and $\ell_h(\cdot)$ possibly differ from $a(\cdot, \cdot)$ and $\ell(\cdot)$, respectively. We henceforth assume that $\dim(V_h) = \dim(W_h)$ and that

512 (4.6)
$$\inf_{0 \neq v_h \in V_h} \sup_{0 \neq w_h \in W_h} \frac{|a_h(v_h, w_h)|}{\|v_h\|_{V_h} \|w_h\|_{W_h}} =: \alpha_h > 0, \quad \forall h > 0,$$

513 so that the discrete problem (4.5) is well-posed.

514 We formalize the fact that the error analysis requires the solution to (4.4) to be 515 slightly more regular than just being a member of V by introducing a functional space 516 V_s such that $u \in V_s \subsetneq V$. Our setting for the error analysis is therefore as follows:

517 (4.7)
$$u \in V_{\mathsf{S}} \subsetneq V, \qquad u - u_h \in V_{\mathsf{t}} := V_{\mathsf{S}} + V_h,$$

with the norm in V_{\sharp} denoted by $\|\cdot\|_{V_{\sharp}}$. Since V_h is finite-dimensional, we have

519 (4.8)
$$c_{\sharp h} := \sup_{0 \neq v_h \in V_h} \frac{\|v_h\|_{V_\sharp}}{\|v_h\|_{V_h}} < \infty.$$

520 We now introduce the consistency error mapping $\delta_h : V_h \to W'_h := \mathcal{L}(W_h; \mathbb{R})$ 521 defined for all $v_h \in V_h$ and all $w_h \in W_h$ by setting

522 (4.9)
$$\langle \delta_h(v_h), w_h \rangle_{W'_h, W_h} := \ell_h(w_h) - a_h(v_h, w_h) = a_h(u_h - v_h, w_h).$$

523 We further assume that

14

524 (4.10)
$$\omega_{\sharp h} := \sup_{u \in V_{\mathcal{S}}} \sup_{v_h \in V_h \setminus \{u\}} \frac{\|\delta_h(v_h)\|_{W'_h}}{\|u - v_h\|_{V_\sharp}} < \infty$$

525 Example 4.1 (Conforming setting). Assume conformity, $a_h = a$, and $\ell_h = \ell$. 526 Take $V_s := V$, so that $V_{\sharp} = V$, and take $\|\cdot\|_{V_{\sharp}} := \|\cdot\|_V$. The consistency error (4.9) is 527 such that

528
$$\langle \delta_h(v_h), w_h \rangle_{W'_h, W_h} = \ell(w_h) - a(v_h, w_h) = a(u - v_h, w_h),$$

where we used that $\ell(w_h) = a(u, w_h)$ (i.e., the Galerkin orthogonality property). Since a is bounded on $V \times W$, (4.10) holds true with $\omega_{\sharp h} = ||a||$; moreover, $c_{\sharp h} = 1$.

531 The main result we are going to invoke later is the following.

LEMMA 4.2 (Quasi-optimal error estimate). If $u \in V_s$, then

533 (4.11)
$$\|u - u_h\|_{V_{\sharp}} \le \left(1 + c_{\sharp h} \frac{\omega_{\sharp h}}{\alpha_h}\right) \inf_{v_h \in V_h} \|u - v_h\|_{V_{\sharp}}.$$

534 *Proof.* The proof is classical; we sketch it for completeness. For all $v_h \in V_h$, we 535 have

536
$$\|u_{h} - v_{h}\|_{V_{\sharp}} \leq c_{\sharp h} \|u_{h} - v_{h}\|_{V_{h}} \leq \frac{c_{\sharp h}}{\alpha_{h}} \sup_{0 \neq w_{h} \in W_{h}} \frac{|a_{h}(u_{h} - v_{h}, w_{h})|}{\|w_{h}\|_{W_{h}}}$$
537
538
$$= \frac{c_{\sharp h}}{\alpha_{h}} \|\delta_{h}(v_{h})\|_{W_{h}'} \leq \frac{c_{\sharp h}\omega_{\sharp h}}{\alpha_{h}} \|u - v_{h}\|_{V_{\sharp}}.$$

539 We conclude by using the triangle inequality and taking the infimum over $v_h \in V_h$. 540 When the constants $c_{\sharp h}$ and $\omega_{\sharp h}$ can be bounded from above uniformly w.r.t. 541 $h \in \mathcal{H}$, we denote by c_{\sharp} and ω_{\sharp} any constant such that $c_{\sharp} \geq \sup_{h \in \mathcal{H}} c_{\sharp h}$ and $\omega_{\sharp} \geq$ 542 $\sup_{h \in \mathcal{H}} \omega_{\sharp h}$. **4.2.** Crouzeix–Raviart approximation. We consider in this section the approximation of the model problem (2.2) with a homogeneous Dirichlet condition (for simplicity) using the Crouzeix–Raviart finite element space

546 (4.12)
$$P_{1,0}^{CR}(\mathcal{T}_h) := \{ v_h \in P_1^{\rm b}(\mathcal{T}_h) \mid \int_F [\![v_h]\!]_F \, \mathrm{d}s = 0, \, \forall F \in \mathcal{F}_h \}.$$

547 The discrete problem (4.5) is formulated with $V_h := P_{1,0}^{CR}(\mathcal{T}_h)$ and the following forms:

548 (4.13)
$$a_h(v_h, w_h) := \int_D \lambda \nabla_h v_h \cdot \nabla_h w_h \, \mathrm{d}x, \qquad \ell_h(w_h) = \int_D f w_h \, \mathrm{d}x.$$

549 We equip V_h with the norm $||v_h||_{V_h} := ||\lambda^{\frac{1}{2}} \nabla_h v_h||_{L^2(D)}$. The following result is stan-550 dard.

551 LEMMA 4.3 (Coercivity, well-posedness). The bilinear form a_h is coercive on V_h 552 with coercivity constant $\alpha = 1$, and the discrete problem (4.5) is well-posed.

Let $V_{\sharp} := V_{\mathrm{s}} + V_h$ be equipped with the norm $||v||_{V_{\sharp}} := |v|_{\lambda,p,q}$ with $|v|_{\lambda,p,q}$ defined in (4.2) (this is indeed a norm on V_{\sharp} since $|v|_{\lambda,p,q} = 0$ implies that v is piecewise constant and hence vanishes identically owing to the definition of V_h). Owing to (4.3), there is c_{\sharp} , uniform w.r.t. $h \in \mathcal{H}$, but depending on p and q, s.t. $||v_h||_{V_{\sharp}} \le c_{\sharp} ||v_h||_{V_h}$, for all $v_h \in V_h$.

558 LEMMA 4.4 (Consistency/boundedness). There is ω_{\sharp} , uniform w.r.t. $h \in \mathcal{H}$, λ , 559 and $u \in V_{s}$, but depending on p and q, s.t. $\|\delta_{h}(v_{h})\|_{V'_{h}} \leq \omega_{\sharp}\|u - v_{h}\|_{V_{\sharp}}$, for all 560 $v_{h} \in V_{h}$.

561 Proof. Let $v_h, w_h \in V_h$. Since $V_h \subset P_k^{\rm b}(\mathcal{T}_h)$, the identity (3.16a) implies that

562
$$n_{\sharp}(v_h, w_h) = \sum_{F \in \mathcal{F}_h} \int_F \{\boldsymbol{\sigma}(v_h)\}_{\theta} \cdot \boldsymbol{n}_F \llbracket w_h \rrbracket \, \mathrm{d}s = 0,$$

because $\{\boldsymbol{\sigma}(v_h)\}_{\theta} \cdot \boldsymbol{n}_F$ is constant over F. Moreover, invoking the identity (3.16b) with v = u and since $f = \nabla \cdot \boldsymbol{\sigma}(u)$, we have

565
$$\ell_h(w_h) = n_{\sharp}(u, w_h) - \int_D \boldsymbol{\sigma}(u) \cdot \nabla_h w_h \, \mathrm{d}x.$$

566 Combining the two above identities and letting $\eta := u - v_h$, we obtain

$$\int_{568}^{567} \langle \delta_h(v_h), w_h \rangle_{V'_h, V_h} = n_{\sharp}(u, w_h) + \int_D \lambda \nabla_h \eta \cdot \nabla_h w_h \, \mathrm{d}x = n_{\sharp}(\eta, w_h) + \int_D \lambda \nabla_h \eta \cdot \nabla_h w_h \, \mathrm{d}x.$$

The first term on the right-hand side is estimated by invoking the boundedness of n_{\sharp} (Lemma 3.5), the inequality $\lambda_F \leq \min_{K \in \mathcal{T}_F} \lambda_K$ (see (3.20)), and the bound $\sum_{F \in \mathcal{F}_h} \lambda_F h_F^{-1} \| [\![w_h]\!] \|_{L^2(F)}^2 \leq c \| w_h \|_{V_h}^2$, which is standard for Crouzeix–Raviart elements. The second term is estimated by using the Cauchy–Schwarz inequality. \Box

THEOREM 4.5 (Error estimate). Let u solve (2.2) and u_h solve (4.5) with a_h and ℓ_h defined in (4.13). Assume that there is r > 0 s.t. $u \in H^{1+r}(D)$. There is c, uniform w.r.t. $h \in \mathcal{H}$, λ , and $u \in H^{1+r}(D)$, but depending on r, s.t. the following quasi-optimal error estimate holds true:

577 (4.14)
$$\|u - u_h\|_{V_{\sharp}} \le c \inf_{v_h \in V_h} \|u - v_h\|_{V_{\sharp}}.$$

Moreover, letting t := min(1, r), where 1 = k is the degree of the Crouzeix-Raviart finite element, we have

580 (4.15)
$$\|u - u_h\|_{V_{\sharp}} \le c \left(\sum_{K \in \mathcal{T}_h} \lambda_K h_K^{2t} |u|_{H^{1+t}(K)}^2 + \lambda_K^{-1} h_K^{2d(\frac{d+2}{2d} - \frac{1}{q})} \|f\|_{L^q(K)}^2\right)^{\frac{1}{2}}.$$

581 *Proof.* The error estimate (4.14) follows from Lemma 4.2 combined with stability (Lemma 4.3) and consistency/boundedness (Lemma 4.4). We now bound the infimum 582in (4.14) by considering $\eta := u - \mathcal{I}_h^{CR}(u)$, where \mathcal{I}_h^{CR} is the Crouzeix–Raviart interpo-583 lation operator using averages over the faces as degrees of freedom. It is a standard 584approximation result that there is c, uniform w.r.t. $u \in H^{1+t}(K), t \ge 0$, and $h \in \mathcal{H}$, 585 s.t. $\|\nabla \eta_{|K}\|_{L^2(K)} \leq ch_K^t |u|_{H^{1+t}(K)}$ for all $K \in \mathcal{T}_h$. Moreover, invoking the embedding 586 $H^t(\widehat{K}) \hookrightarrow L^p(\widehat{K})$ and classical results on the transformation of Sobolev norms by the 587 geometric mapping, we obtain the bound 588

589 (4.16)
$$h_{K}^{d(\frac{1}{2}-\frac{1}{p})} \|\nabla\eta_{|K}\|_{L^{p}(K)} \le c \left(\|\nabla\eta_{|K}\|_{L^{2}(K)} + h_{K}^{t}|\nabla\eta_{|K}|_{H^{t}(K)}\right).$$

590 Observing that $|\nabla \eta_{|K}|_{H^{t}(K)} = |u|_{H^{1+t}(K)}$ since $\mathcal{I}_{h}^{CR}(u)$ is affine on K and using 591 again the approximation properties of \mathcal{I}_{h}^{CR} , we infer that $h_{K}^{d(\frac{1}{2}-\frac{1}{p})} \|\nabla \eta_{|K}\|_{L^{p}(K)} \leq$ 592 $c h_{K}^{t} |u|_{H^{1+t}(K)}$. Finally, we have $\Delta \eta_{|K} = \lambda_{K}^{-1} f$ in K.

593 Remark 4.6 (Convergence). The rightmost term in (4.15) converges as O(h)594 when q = 2. Moreover, convergence is lost when $q \leq \frac{2d}{d+2}$, which is somewhat natural 595 since in this case the linear form $w \mapsto \int_D fw \, dx$ is no longer bounded on $H^1(D)$. \Box

Remark 4.7 (Weights). Although the weights introduced in (3.19) are not explicitly used in the Crouzeix–Raviart discretization, they play a role in the error analysis. More precisely, we used the boundedness of the bilinear form n_{\sharp} together with $\lambda_F \leq \min_{K \in \mathcal{T}_F} \lambda_K$ in the proof of Lemma 4.4. The present approach is somewhat more general than that in Li and Mao [31] since it delivers error estimates that are robust with respect to the diffusivity contrast. The trimming operator invoked in [31, Eq. (5)–(7)] cannot account for the diffusivity contrast.

4.3. Nitsche's boundary penalty method. We consider in this section the
 approximation of the model problem (2.1) by means of Nitsche's boundary penalty
 method. Now we set

606 (4.17)
$$V_h := P_k^{g}(\mathcal{T}_h) := \{ v_h \in P_k^{b}(\mathcal{T}_h) \mid [\![v_h]\!]_F = 0, \forall F \in \mathcal{F}_h^{o} \}, \quad k \ge 1,$$

607 i.e., V_h is H^1 -conforming The discrete problem (4.5) is formulated with $V_h := P_k^g(\mathcal{T}_h)$ 608 and the following forms:

609 (4.18a)
$$a_h(v_h, w_h) := a(v_h, w_h) + \sum_{F \in \mathcal{F}_h^{\partial}} \int_F \left(\boldsymbol{\sigma}(v_h) \cdot \boldsymbol{n} + \varpi_0 \frac{\lambda_{K_l}}{h_F} v_h \right) w_h \, \mathrm{d}s,$$

610 (4.18b)
$$\ell_h(w_h) := \ell(w_h) + \sum_{F \in \mathcal{F}_h^\partial} \varpi_0 \frac{\lambda_{K_l}}{h_F} \int_F g w_h \, \mathrm{d}s$$

where the exact forms a and ℓ are defined in (2.3), K_l is the unique mesh cell s.t. $F = \partial K_l \cap \partial D$, and the user-specified penalty parameter ϖ_0 is yet to be chosen large enough. It is possible to add a symmetrizing term to the discrete bilinear form a_h .

We equip V_h with the norm $||v_h||^2_{V_h} := ||\lambda^{\frac{1}{2}} \nabla v_h||^2_{L^2(D)} + |v_h|^2_{\partial}$ with $|v_h|^2_{\partial} :=$ 615 $\sum_{F \in \mathcal{F}_h^{\partial}} \frac{\lambda_{K_l}}{h_F} \|v_h\|_{L^2(F)}^2.$ Owing to the shape-regularity of the mesh sequence, there is c_I , uniform w.r.t. $h \in \mathcal{H}$ s.t. 616 617

618 (4.19)
$$\|v_h\|_{L^2(F)} \le c_I h_F^{-\frac{1}{2}} \|v_h\|_{L^2(K_l)},$$

for all $v_h \in V_h$ and all $F \in \mathcal{F}_h^{\partial}$. Let n_{∂} denote the maximum number of boundary 619 faces that a mesh cell can have $(n_{\partial} \leq d \text{ for simplicial meshes})$. The proof of the 620 following result uses standard arguments. 621

LEMMA 4.8 (Coercivity, well-posedness). Assume that the penalty parameter 622 satisfies $\varpi_0 > \frac{1}{4}n_\partial c_I^2$. Then, a_h is coercive on V_h with constant $\alpha := \frac{\varpi_0 - \frac{1}{4}n_\partial c_I^2}{1+\varpi_0} > 0$, and the discrete problem (4.5) is well-posed. 623 624

Let $V_{\sharp} := V_{\mathrm{s}} + V_h$. We equip the space V_{\sharp} with the norm $\|v\|_{V_{\sharp}}^2 := |v|_{\lambda,p,q}^2 + |v|_{\partial}^2$ 625 with 626

$$\begin{aligned} & 627 \qquad |v|_{\lambda,p,q}^2 := \sum_{K \in \mathcal{T}_h} \lambda_K \|\nabla v_{|K}\|_{L^2(K)}^2 \\ & 628 \quad (4.20) \qquad + \sum_{K \in \overline{\mathcal{T}}_h^{\partial}} \lambda_K \Big(h_K^{2d(\frac{1}{2} - \frac{1}{p})} \|\nabla v_{|K}\|_{L^p(K)}^2 + h_K^{2d(\frac{d+2}{2d} - \frac{1}{q})} \|\Delta v_{|K}\|_{L^q(K)}^2 \Big), \end{aligned}$$

where $\overline{\mathcal{T}}_{h}^{\partial}$ is the collection of the mesh cells having at least one boundary face, and $|v|_{\partial}^{2} = \sum_{F \in \mathcal{F}_{h}^{\partial}} \frac{\lambda_{\kappa_{l}}}{h_{F}} ||v||_{L^{2}(F)}^{2}$. Owing to (4.3), there is c_{\sharp} , uniform w.r.t. $h \in \mathcal{H}$, but 630 631 depending on p and q, s.t. $||v_h||_{V_{\sharp}} \leq c_{\sharp} ||v_h||_{V_h}$, for all $v_h \in V_h$. 632

LEMMA 4.9 (Consistency/boundedness). There is ω_{\sharp} , uniform w.r.t. $h \in \mathcal{H}$, λ , 633 and $u \in V_s$, but depending on p and q, s.t. $\|\delta_h(v_h)\|_{V'_h} \leq \omega_{\sharp} \|u - v_h\|_{V_{\sharp}}$, for all 634635 $v_h \in V_h$.

Proof. Let $v_h, w_h \in V_h$. Using the identity (3.16a) for $n_{\sharp}, [w_h]_F = 0$ for all 636 $F \in \mathcal{F}_h^{\circ}$ (since V_h is H^1 -conforming), and the definition of the weights at the bound-637 ary faces, we infer that $n_{\sharp}(v_h, w_h) = \sum_{F \in \mathcal{F}_h^{\partial}} \int_F \boldsymbol{\sigma}(v_h) \cdot \boldsymbol{n} w_h \, \mathrm{d}s$. Hence, $a_h(v_h, w_h) =$ 638 $a(v_h, w_h) + n_{\sharp}(v_h, w_h) + \sum_{F \in \mathcal{F}_h^{\Theta}} \overline{\varpi}_0 \frac{\lambda_{K_l}}{h_F} \int_F v_h w_h \, \mathrm{d}s.$ Therefore, invoking the iden-639 tity (3.16b) for the exact solution u and observing that $f = \nabla \cdot \boldsymbol{\sigma}(u)$, we infer the 640 important identity $\int_D f w_h \, dx = a(u, w_h) + n_{\sharp}(u, w_h)$. Then, recalling that $\gamma^{g}(u) = g$, 641 and letting $\eta := u - v_h$, we obtain 642

643
$$\langle \delta_h(v_h), w_h \rangle_{V'_h, V_h} = n_{\sharp}(\eta, w_h) + a(\eta, w_h) + \sum_{F \in \mathcal{F}_h^{\partial}} \varpi_0 \frac{\lambda_{K_l}}{h_F} \int_F \eta w_h \, \mathrm{d}s.$$

We conclude by using the boundedness of n_{\sharp} from Lemma 3.5 and the Cauchy–Schwarz 644 inequality. Π 645

THEOREM 4.10 (Error estimate). Let u solve (2.1) and u_h solve (4.5) with a_h and 646 ℓ_h defined in (4.18) and penalty parameter $\varpi_0 > \frac{1}{4} n_\partial c_I^2$. Assume that there is r > 0647 s.t. $u \in H^{1+r}(D)$. There is c, uniform with respect to $h \in \mathcal{H}$, λ , and $u \in H^{1+r}(D)$, 648 but depending on r, s.t. the following quasi-optimal error estimate holds true: 649

650 (4.21)
$$\|u - u_h\|_{V_{\sharp}} \le c \inf_{v_h \in V_h} \|u - v_h\|_{V_{\sharp}}.$$

651 Moreover, letting t := min(r,k), $\chi_t = 1$ if $t \le 1$ and $\chi_t = 0$ if t > 1, we have

652 (4.22)
$$\|u - u_h\|_{V_{\sharp}} \le c \left(\sum_{K \in \mathcal{T}_h} \lambda_K h_K^{2t} |u|_{H^{1+t}(\tilde{\mathcal{T}}_K)}^2 + \frac{\chi_t}{\lambda_K} h_K^{2d(\frac{d+2}{2d} - \frac{1}{q})} \|f\|_{L^q(K)}^2 \right)^{\frac{1}{2}}$$

653 where $\check{\mathcal{T}}_K$ is the collection of the mesh cells having at least a common vertex with K. 654 The broken Sobolev norm $|\cdot|_{H^{1+t}(\check{\mathcal{T}}_K)}$ can be replaced by $|\cdot|_{H^{1+t}(K)}$ if $1+t > \frac{d}{2}$. \Box

Proof. The error estimate (4.21) follows from Lemma 4.2 combined with stabil-655 ity (Lemma 4.8) and consistency/boundedness (Lemma 4.9). We now bound the 656 infimum in (4.21) by using $\eta := u - \mathcal{I}_h^{g,av}(u)$, where $\mathcal{I}_h^{g,av}$ is the quasi-interpolation operator introduced in [23, §5]. We take the polynomial degree of $\mathcal{I}_h^{g,av}$ to be $\ell := [t]$, 657 658 where [t] denotes the smallest integer $n \in \mathbb{N}$ s.t. $n \ge t$. Notice that $\ell \ge 1$ be-659cause r > 0 and $k \ge 1$, and $\ell \le k$ because $t \le k$; hence, $\mathcal{I}_h^{g,av}(u) \in V_h$. We 660 need to bound all the terms composing the norm $\|\eta\|_{V_{\sharp}}$. Owing to [23, Thm. 5.2] 661 with m = 1, we have $\|\nabla \eta\|_{L^2(K)} \leq ch_K^t |u|_{H^{1+t}(\check{\mathcal{T}}_K)}$ for all $K \in \check{\mathcal{T}}_h$. Moreover, 662 we have $h_F^{-\frac{1}{2}} \|\eta\|_{L^2(F)} \leq ch_{K_l}^t |u|_{H^{1+t}(\check{\mathcal{T}}_{K_l})}$ for all $F \in \mathcal{F}_h^{\partial}$. It remains to estimate 663 $h_{K}^{d(\frac{1}{2}-\frac{1}{p})} \|\nabla\eta_{|K}\|_{L^{p}(K)} \text{ and } h_{K}^{d(\frac{d+2}{2d}-\frac{1}{q})} \|\Delta\eta_{|K}\|_{L^{q}(K)} \text{ for all } K \in \overline{\mathcal{T}}_{h}^{\partial}. \text{ Using (4.16), the above bound on } \|\nabla\eta\|_{L^{2}(K)}, \text{ and } |\nabla\eta|_{H^{t}(K)} = |\nabla u|_{H^{t}(K)} = |u|_{H^{1+t}(K)} \text{ since } \ell < 1+t,$ 664 665 we infer that $h_K^{d(\frac{1}{2}-\frac{1}{p})} \|\nabla \eta\|_{L^p(K)} \le c h_K^t |u|_{H^{1+t}(\check{\mathcal{T}}_K)}$. Moreover, if $t \le 1$, we have $\ell = 1$ 666 so that $\|\Delta\eta_{K}\|_{L^{q}(K)} = \|\Delta u\|_{L^{q}(K)} = \lambda_{K}^{-1} \|f\|_{L^{q}(K)}$. Instead, if t > 1, we infer that r > 1 so that we can set q = 2 (recall that $f|_{D_{i}} = \lambda_{|D_{i}}(\Delta u)_{D_{i}}$ for all $i \in \{1:M\}$, and 667 668 $u \in H^2(D)$ if $r \ge 1$), and we estimate $\|\Delta \eta_{|K}\|_{L^2(K)}$ using [23, Thm. 5.2] with m = 2. 669 Finally, if $1 + t > \frac{d}{2}$, we can use the canonical Lagrange interpolation operator \mathcal{I}_{h}^{g} instead of $\mathcal{I}_{h}^{g,av}$, and this allows us to replace $|\cdot|_{H^{1+t}(\tilde{\mathcal{T}}_{K})}$ by $|\cdot|_{H^{1+t}(K)}$ in (4.22). 670 671

672 **4.4. Discontinuous Galerkin.** We consider in this section the approximation 673 of the model problem (2.1) by means of the symmetric interior penalty discontinuous 674 Galerkin method. The discrete problem (4.5) is formulated with $V_h := P_k^{\rm b}(\mathcal{T}_h), k \ge 1$, 675 the bilinear forms

676
$$a_h(v_h, w_h) := \int_D \lambda \nabla_h v_h \cdot \nabla_h w_h \, \mathrm{d}x + \sum_{F \in \mathcal{F}_h} \int_F \{ \boldsymbol{\sigma}(v_h) \}_{\boldsymbol{\theta}} \cdot \boldsymbol{n}_F \llbracket w_h \rrbracket \, \mathrm{d}s$$

677 (4.23a)
$$+ \sum_{F \in \mathcal{F}_h} \int_F \llbracket v_h \rrbracket \{ \boldsymbol{\sigma}(w_h) \}_{\theta} \cdot \boldsymbol{n}_F \, \mathrm{d}s + \sum_{F \in \mathcal{F}_h} \varpi_0 \frac{\lambda_F}{h_F} \int_F \llbracket v_h \rrbracket \llbracket w_h \rrbracket \, \mathrm{d}s,$$

678 (4.23b)
$$\ell_h(w_h) := \ell(w_h) + \sum_{F \in \mathcal{F}_h^0} \varpi_0 \frac{\lambda_{K_l}}{h_F} \int_F gw_h \,\mathrm{d}s,$$

where
$$\ell$$
 is defined in (2.3), λ_F in (3.20), and the user-specified penalty parame-
ter ϖ_0 is yet to be chosen large enough. We equip V_h with the norm $||v_h||_{V_h}^2 :=$
 $||\lambda^{\frac{1}{2}}\nabla_h v_h||_{L^2(D)}^2 + |v_h|_J^2$ with $|v_h|_J^2 := \sum_{F \in \mathcal{F}_h} \frac{\lambda_F}{h_F} ||[v_h]||_{L^2(F)}^2$. Recall the discrete trace
inequality (4.19) and recall that n_∂ denotes the maximum number of faces that a
mesh cell can have $(n_\partial \leq d+1$ for simplicial meshes). The proof of the following
result uses standard arguments.

EEMMA 4.11 (Coercivity, well-posedness). Assume that the penalty parameter satisfies $\varpi_0 > n_\partial c_I^2$. Then, a_h is coercive on V_h with constant $\alpha := \frac{\varpi_0 - n_\partial c_I^2}{1 + \varpi_0} > 0$, and the discrete problem (4.5) is well-posed. 689 Let $V_{\sharp} := V_{\mathrm{s}} + V_h$. We equip the space V_{\sharp} with the norm $||v||_{V_{\sharp}}^2 := |v|_{\lambda,p,q}^2 + |v|_{\mathrm{J}}^2$ 690 with $|v|_{\lambda,p,q}$ defined in (4.2) and $|v|_{\mathrm{J}}^2 := \sum_{F \in \mathcal{F}_h} \frac{\lambda_F}{h_F} || \llbracket v \rrbracket ||_{L^2(F)}^2$. Owing to (4.3), there 691 is c_{\sharp} , uniform w.r.t. $h \in \mathcal{H}$, but depending on p and q, s.t. $||v_h||_{V_{\sharp}} \le c_{\sharp} ||v_h||_{V_h}$, for all 692 $v_h \in V_h$.

693 LEMMA 4.12 (Consistency/boundedness). There is ω_{\sharp} , uniform w.r.t. $h \in \mathcal{H}$, 694 λ , and $u \in V_{s}$, but depending on p and q, s.t. $\|\delta_{h}(v_{h})\|_{V'_{h}} \leq \omega_{\sharp} \|u - v_{h}\|_{V_{\sharp}}$, for all 695 $v_{h} \in V_{h}$.

696 Proof. Let $v_h, w_h \in V_h$. Owing to (3.16b) and since $f = \nabla \cdot \boldsymbol{\sigma}(u)$, we infer that 697 $\int_D f w_h \, \mathrm{d}x = \sum_{K \in \mathcal{T}_h} a_K(u, w_h) + n_{\sharp}(u, w_h)$ with $a_K(u, w_h) := -(\boldsymbol{\sigma}(u), \nabla_h w_h)_{L^2(K)}$. 698 Using the identity (3.16a), we obtain

699
$$\ell_h(w_h) = n_{\sharp}(u, w_h) - \int_D \boldsymbol{\sigma}(u) \cdot \nabla_h w_h \, \mathrm{d}x + \sum_{F \in \mathcal{F}_h^{\partial}} \varpi_0 \frac{\lambda_F}{h_F} \int_F g w_h \, \mathrm{d}s,$$

700
$$a_h(v_h, w_h) = \int_D -\boldsymbol{\sigma}(v_h) \cdot \nabla_h w_h \, \mathrm{d}x + n_\sharp(v_h, w_h)$$

$$-\sum_{F\in\mathcal{F}_h}\int_F \llbracket v_h \rrbracket \{\boldsymbol{\sigma}(w_h)\}_{\theta} \cdot \boldsymbol{n}_F \,\mathrm{d}s + \sum_{F\in\mathcal{F}_h} \varpi_0 \frac{\lambda_F}{h_F} \int_F \llbracket v_h \rrbracket \llbracket w_h \rrbracket \,\mathrm{d}s$$

Then setting $\eta := u - v_h$ and using that $\llbracket u \rrbracket_F = 0$ for all $F \in \mathcal{F}_h^{\circ}$ and $\llbracket u \rrbracket_F = g$ for all $F \in \mathcal{F}_h^{\partial}$, we obtain the following representation of the consistency linear form $\delta_h(v_h)$:

705
$$\langle \delta_h(v_h), w_h \rangle_{V'_h, V_h} = n_{\sharp}(\eta, w_h) + \int_D \lambda \nabla \eta \cdot \nabla_h w_h \, \mathrm{d}x$$

706
707
$$-\sum_{F\in\mathcal{F}_h}\int_F \llbracket\eta\rrbracket\{\boldsymbol{\sigma}(w_h)\}_{\theta}\cdot\boldsymbol{n}_F\,\mathrm{d}s + \sum_{F\in\mathcal{F}_h}\varpi_0\frac{\lambda_F}{h_F}\int_F \llbracket\eta\rrbracket[w_h]]\,\mathrm{d}s$$

Bounding the second, third and fourth terms uses standard arguments (see, e.g., [15]), whereas we invoke the boundedness estimate on n_{\sharp} from Lemma 3.5 for the first term.

THEOREM 4.13 (Error estimate). Let u solve (2.1) and u_h solve (4.5) with a_h and ℓ_h defined in (4.23) and penalty parameter $\varpi_0 > n_\partial c_I^2$. Assume that there is r > 0s.t. $u \in H^{1+r}(D)$. There is c, uniform with respect to $h \in \mathcal{H}$, λ , and $u \in H^{1+r}(D)$, but depending on r, s.t. the following quasi-optimal error estimate holds true:

714 (4.24)
$$\|u - u_h\|_{V_{\sharp}} \le c \inf_{v_h \in V_h} \|u - v_h\|_{V_{\sharp}}.$$

715 Moreover, letting t := min(r,k), $\chi_t = 1$ if $t \le 1$ and $\chi_t = 0$ if t > 1, we have

716 (4.25)
$$\|u - u_h\|_{V_{\sharp}} \le c \left(\sum_{K \in \mathcal{T}_h} \lambda_K h_K^{2t} |u|_{H^{1+t}(K)}^2 + \frac{\chi_t}{\lambda_K} h_K^{2d(\frac{d+2}{2d} - \frac{1}{q})} \|f\|_{L^q(K)}^2\right)^{\frac{1}{2}} \square$$

717 Proof. We proceed as in the proof of Theorem 4.10, where we now use the L^{1-} 718 stable interpolation operator $\mathcal{I}_{h}^{\sharp}: L^{1}(D) \to P_{k}^{\mathrm{b}}(\mathcal{T}_{h})$ from [23, §3] to estimate the best 719 approximation error.

4.5. Hybrid high-order methods. We consider in this section the approximation of the model problem (2.1) with a homogeneous Dirichlet condition (for simplicity) by means of the hybrid high-order (HHO) method introduced in [16, 18]. We

⁷²³ consider the discrete product space $\hat{V}_{h,0}^k := V_{\mathcal{T}_h}^k \times V_{\mathcal{F}_h}^k$ with $k \ge 0$, where

(4.26a)
$$V_{\mathcal{T}_h}^k := \{ v_{\mathcal{T}_h} \in L^2(D) \mid v_K := v_{\mathcal{T}_h|K} \in V_K^k, \forall K \in \mathcal{T}_h \},$$

$$\begin{array}{l} \mathbb{Z}_{26}^{25} \quad (4.26b) \qquad V_{\mathcal{F}_h}^k := \{ v_{\mathcal{F}_h} \in L^2(\mathcal{F}_h) \mid v_{\partial K} := v_{\mathcal{F}_h|\partial K} \in V_{\partial K}^k, \, \forall K \in \mathcal{T}_h; \, v_{\mathcal{F}_h|\mathcal{F}_h^\partial} = 0 \}, \end{array}$$

727 with $V_K^k := \mathbb{P}_{k,d}$ and $V_{\partial K}^k := \{ \theta \in L^2(\partial K) \mid \theta \circ T_{K|T_K^{-1}(F)} \in \mathbb{P}_{k,d-1}, \forall F \in \mathcal{F}_K \}.$

Thus, for any pair $\hat{v}_h := (v_{\mathcal{T}_h}, v_{\mathcal{F}_h}) \in \hat{V}_{h,0}^k$, $v_{\mathcal{T}_h}$ a collection of cell polynomials of degree at most k, and $v_{\mathcal{F}_h}$ is a collection of face polynomials of degree at most kwhich are single-valued at the mesh interfaces and vanish at the boundary faces (so as to enforce strongly the homogeneous Dirichlet condition). We use the notation $\hat{v}_K := (v_K, v_{\partial K}) \in \hat{V}_K^k := V_K^k \times V_{\partial K}^k$ for all $K \in \mathcal{T}_h$. We equip the local space \hat{V}_K^k with the H^1 -like seminorm

734 (4.27)
$$|\hat{v}_K|^2_{\hat{V}^k_K} := \|\nabla v_K\|^2_{L^2(K)} + \|h_{\partial K}^{-\frac{1}{2}}(v_K - v_{\partial K})\|^2_{L^2(\partial K)}, \quad \forall \hat{v}_K = (v_K, v_{\partial K}) \in \hat{V}^k_K,$$

and the global space $\hat{V}_{h,0}^k$ with the norm

736 (4.28)
$$\|\hat{v}_{h}\|_{\hat{V}_{h,0}^{k}}^{2} := \sum_{K \in \mathcal{T}_{h}} \lambda_{K} |\hat{v}_{K}|_{\hat{V}_{K}}^{2}.$$

737 We introduce locally in each mesh cell $K \in \mathcal{T}_h$ a reconstruction operator and a 738 stabilization operator. The reconstruction operator $\mathsf{R}_K^{k+1} : \hat{V}_K^k \to \mathbb{P}_{k+1,d}$ is defined 739 such that, for any pair $\hat{v}_K = (v_K, v_{\partial K}) \in \hat{V}_K^k$, the polynomial function $\mathsf{R}_K^{k+1}(\hat{v}_K) \in$ 740 $\mathbb{P}_{k+1,d}$ solves

$$\frac{741}{742} \quad (4.29) \qquad (\nabla \mathsf{R}_{K}^{k+1}(\hat{v}_{K}), \nabla q)_{L^{2}(K)} := -(v_{K}, \Delta q)_{L^{2}(K)} + (v_{\partial K}, \boldsymbol{n}_{K} \cdot \nabla q)_{L^{2}(\partial K)},$$

for all $q \in \mathbb{P}_{k+1,d}$, with the mean-value condition $\int_{K} (\mathsf{R}_{K}^{k+1}(\hat{v}_{K}) - v_{K}) \, \mathrm{d}x = 0$. This local Neumann problem makes sense since the right-hand side of (4.29) vanishes when the test function q is constant. The stabilization operator $\mathsf{S}_{\partial K}^{k} : \hat{V}_{K}^{k} \to V_{\partial K}^{k}$ is defined s.t. for any pair $\hat{v}_{K} = (v_{K}, v_{\partial K}) \in \hat{V}_{K}^{k}$,

(4.30)
$$\mathsf{S}^{k}_{\partial K}(\hat{v}_{K}) := \Pi^{k}_{\partial K} \left(v_{K|\partial K} - v_{\partial K} + \left((I - \Pi^{k}_{K})\mathsf{R}^{k+1}_{K}(\hat{v}_{K}) \right)_{|\partial K} \right),$$

where I is the identity, $\Pi_{\partial K}^k : L^2(\partial K) \to V_{\partial K}^k$ is the L^2 -orthogonal projection onto V₀^k and $\Pi_K^k : L^2(K) \to V_K^k$ is the L^2 -orthogonal projection onto V_K^k . Elementary algebra shows that the stabilization operator can be rewritten as

751 (4.31)
$$\mathsf{S}^{k}_{\partial K}(\hat{v}_{K}) = \Pi^{k}_{\partial K} \left(\delta_{\partial K} - \left((I - \Pi^{k}_{K}) \mathsf{R}^{k+1}_{K}(0, \delta_{\partial K}) \right)_{|\partial K} \right),$$

with $\delta_{\partial K} := v_{K|\partial K} - v_{\partial K}$ is a measure of the discrepancy between the trace of the cell unknown and the face unknown.

754 We now introduce the local bilinear form \hat{a}_K on $\hat{V}_K^k \times \hat{V}_K^k$ s.t. 755

756 (4.32)
$$\hat{a}_{K}(\hat{v}_{K},\hat{w}_{K}) := (\nabla \mathsf{R}_{K}^{k+1}(\hat{v}_{K}), \nabla \mathsf{R}_{K}^{k+1}(\hat{w}_{K}))_{L^{2}(D)} + (h_{\partial K}^{-1}\mathsf{S}_{\partial K}^{k}(\hat{v}_{K}),\mathsf{S}_{\partial K}^{k}(\hat{w}_{K}))_{L^{2}(\partial K)},$$

where $h_{\partial K}$ is the piecewise constant function on ∂K s.t. $h_{\partial K|F} := h_F$ for all $F \in \mathcal{F}_K$. Then we set

761 (4.33)
$$\hat{a}_h(\hat{v}_h, \hat{w}_h) := \sum_{K \in \mathcal{T}_h} \lambda_K \hat{a}_K(\hat{v}_K, \hat{w}_K), \qquad \hat{\ell}_h(\hat{w}_h) := \sum_{K \in \mathcal{T}_h} (f, w_K)_{L^2(K)}.$$

The discrete problem is finally formulated as follows: Find $\hat{u}_h \in \hat{V}_{h,0}^k$ s.t.

763 (4.34)
$$\hat{a}_h(\hat{u}_h, \hat{w}_h) = \hat{\ell}_h(\hat{w}_h), \quad \forall \hat{w}_h \in \hat{V}_{h,0}^k.$$

Notice that HHO methods are somewhat simpler than dG methods when it comes to solving problems with contrasted coefficients. For HHO methods, one assembles cellwise the local bilinear forms \hat{a}_K weighted by the local diffusion coefficient λ_K , whereas, for dG methods one has to invoke interface-based values of the diffusion coefficient to construct the penalty term.

The following result is proved in [16, 18].

TTO LEMMA 4.14 (Stability, boundedness, well-posedness). There are $0 < \alpha \leq \omega$, TT1 uniform w.r.t. $h \in \mathcal{H}$, such that

772
$$\alpha |\hat{v}_K|_{\hat{V}_K^k}^2 \le \|\nabla \mathsf{R}_K^{k+1}(\hat{v}_K)\|_{L^2(K)}^2 + \|h_{\partial K}^{-\frac{1}{2}}\mathsf{S}_{\partial K}^k(\hat{v}_K)\|_{L^2(\partial K)}^2 = \hat{a}_K(\hat{v}_K, \hat{v}_K) \le \omega |\hat{v}_K|_{\hat{V}_K^k}^2,$$

for all $\hat{v}_K \in \hat{V}_K$ and all $K \in \mathcal{T}_h$, and the discrete problem (4.34) is well-posed.

The two key tools in the error analysis of HHO methods are a local reduction operator and the local elliptic projection. For all $K \in \mathcal{T}_h$, the local reduction operator $\hat{\mathcal{I}}_K^k : H^1(K) \to \hat{V}_K^k$ is defined by $\hat{\mathcal{I}}_K^k(v) := (\Pi_K^k(v), \Pi_{\partial K}^k(\gamma_{\partial K}^g(v))) \in \hat{V}_K^k$, for all $v \in H^1(K)$. The local elliptic projection $\mathcal{E}_K^{k+1} : H^1(K) \to \mathbb{P}_{k+1,d}$ is s.t. $(\nabla(\mathcal{E}_K^{k+1}(v) - v), \nabla q)_{L^2(K)} = 0$, for all $q \in \mathbb{P}_{k+1,d}$, and $(\mathcal{E}_K^{k+1}(v) - v, 1)_{L^2(K)} = 0$. The following result is established in [16, 18].

780 LEMMA 4.15 (Polynomial invariance). The following holds true:

781 (4.35a)
$$\mathsf{R}_{K}^{k+1} \circ \hat{\mathcal{I}}_{K}^{k} = \mathcal{E}_{K}^{k+1},$$

$$\mathbf{F}_{83}^{k} \circ \hat{\mathcal{I}}_{K}^{k} \circ \hat{\mathcal{I}}_{K}^{k} = (\gamma_{\partial K}^{\mathrm{g}} \circ \Pi_{K}^{k} - \Pi_{\partial K}^{k} \circ \gamma_{\partial K}^{\mathrm{g}}) \circ (I - \mathcal{E}_{K}^{k+1}).$$

In particular, $\mathsf{R}^{k+1}_K(\hat{\mathcal{I}}^k_K(p)) = p$ and $\mathsf{S}^k_{\partial K}(\hat{\mathcal{I}}^k_K(p)) = 0$ for all $p \in \mathbb{P}_{k+1,d}$.

Recalling the duality pairing $\langle \cdot, \cdot \rangle_F$ defined in (3.10), the generalization of the bilinear form n_{\sharp} in the context of HHO methods is the bilinear form defined on $(V_{\rm s} + P_{k+1}^{\rm b}(\mathcal{T}_h)) \times \hat{V}_{h,0}^k$ that acts as follows:

788 (4.36)
$$n_{\sharp}(v,\hat{w}_h) := \sum_{K \in \mathcal{T}_h} \sum_{F \in \mathcal{F}_K} \langle (\boldsymbol{\sigma}(v) \cdot \boldsymbol{n}_K)_{|F}, (w_K - w_{\partial K})_{|F} \rangle_F.$$

T89 LEMMA 4.16 (Identities and boundedness for n_{\sharp}). The following holds true for 790 all $\hat{w}_h \in \hat{V}_{h,0}^k$, all $v_h \in P_{k+1}^{\rm b}(\mathcal{T}_h)$ and all $v \in V_{\rm S}$:

791 (4.37a)
$$n_{\sharp}(v_h, \hat{w}_h) = \sum_{K \in \mathcal{T}_h} \int_K \lambda_K \nabla v_{h|K} \cdot \nabla(\mathsf{R}_K^{k+1}(\hat{w}_K) - w_K) \, \mathrm{d}x,$$

792 (4.37b)
$$n_{\sharp}(v, \hat{w}_h) = \sum_{K \in \mathcal{T}_h} \int_K \left(\boldsymbol{\sigma}(v) \cdot \nabla w_K + (\nabla \cdot \boldsymbol{\sigma}(v)) w_K \right) \mathrm{d}x.$$

Moreover, there is c, uniform w.r.t. $h \in \mathcal{H}$ and λ , but depending on p and q, s.t. the following holds true for all $v \in V_{s} + P_{k+1}^{b}(\mathcal{T}_{h})$ and all $\hat{w}_{h} \in \hat{V}_{h,0}^{k}$:

796 (4.38)
$$|n_{\sharp}(v, \hat{w}_{h})| \leq c |v|_{n_{\sharp}} \left(\sum_{K \in \mathcal{T}_{h}} \lambda_{K} h_{K}^{-1} \|w_{K} - w_{\partial K}\|_{L^{2}(\partial K)}^{2} \right)^{\frac{1}{2}},$$

797 with the $|\cdot|_{n_{t}}$ -seminorm defined in (3.18).

21

Proof. (i) We first prove (4.37a). Let $v_h \in P_{k+1}^{\mathrm{b}}(\mathcal{T}_h)$ and $\hat{w}_h \in \hat{V}_{h,0}^k$. Since the restriction of $\boldsymbol{\sigma}(v_h)$ to each mesh cell is smooth and since the trace on ∂K of the 798 799 face-to-cell lifting operator L_F^K is nonzero only on F, for all $F \in \mathcal{F}_K$, we have 800

801
$$\langle (\boldsymbol{\sigma}(v_h) \cdot \boldsymbol{n}_K)|_F, (w_K - w_{\partial K})|_F \rangle_F$$

802
$$= \int_K \boldsymbol{\sigma}(v_h)|_K \cdot \nabla L_F^K((w_K - w_{\partial K})|_F) + (\nabla \cdot \boldsymbol{\sigma}(v_h)|_K) L_F^K((w_K - w_{\partial K})|_F) dx$$

803
$$= \int_K \boldsymbol{\sigma}(w_h) w_F w_F L_F^K((w_K - w_{\partial K})|_F) dx = \int_K \boldsymbol{\sigma}(w_h) w_F w_F(w_K - w_{\partial K})|_F dx$$

803
804
$$= \int_{\partial K} \boldsymbol{\sigma}(v_h)_{|K} \cdot \boldsymbol{n}_K L_F^K((w_K - w_{\partial K})_{|F}) \,\mathrm{d}s = \int_F \boldsymbol{\sigma}(v_h)_{|K} \cdot \boldsymbol{n}_K(w_K - w_{\partial K}) \,\mathrm{d}s$$

where we used the divergence formula in K. Therefore, we obtain 805

806
$$n_{\sharp}(v_h, \hat{w}_h)) = \sum_{K \in \mathcal{T}_h} \int_{\partial K} \boldsymbol{\sigma}(v_h)_{|K} \cdot \boldsymbol{n}_K(w_K - w_{\partial K}) \, \mathrm{d}s$$

807
$$= -\sum_{K \in \mathcal{T}_h} \lambda_K \int_{\partial K} \nabla v_{h|K} \cdot \boldsymbol{n}_K (w_K - w_{\partial K}) \,\mathrm{d}s$$

808
809
$$= \sum_{K \in \mathcal{T}_h} \lambda_K \int_K \left(\nabla v_{h|K} \cdot \nabla (\mathsf{R}_K^{k+1}(\hat{w}_K) - w_K) \right) \mathrm{d}x,$$

where we used the definition (4.29) of the local reconstruction operator R_{K}^{k+1} with the 810 test function $v_{h|K} \in \mathbb{P}_{k,d} \subset \mathbb{P}_{k+1,d}$. 811

(ii) Let us now prove (4.37b). Let $v \in V_s$ and $\hat{w}_h \in \hat{V}_{h,0}^k$. We are going to proceed as in 812 the proof of (3.16b). We consider the mollification operators $\mathcal{K}^{\mathrm{d}}_{\delta} : L^1(D) \to C^{\infty}(\overline{D})$ and $\mathcal{K}^{\mathrm{b}}_{\delta} : L^1(D) \to C^{\infty}(\overline{D})$ introduced in [22, §3.2]. Let us consider the mollified 813 814 bilinear form 815

816
$$n_{\sharp\delta}(v,\hat{w}_h) := \sum_{K\in\mathcal{T}_h} \sum_{F\in\mathcal{F}_K} \langle (\mathcal{K}^{\mathrm{d}}_{\delta}(\boldsymbol{\sigma}(v))\cdot\boldsymbol{n}_K)_{|F}, (w_K - w_{\partial K})_{|F} \rangle_F.$$

By using (3.10) and invoking the approximation properties of the mollification opera-817 tors and the commuting property (3.17), we infer that $\lim_{\delta \to 0} n_{\sharp\delta}(v, \hat{w}_h) = n_{\sharp}(v, \hat{w}_h)$. 818 Since the restriction of $\mathcal{K}^{d}_{\delta}(\boldsymbol{\sigma}(v))$ to each mesh cell is smooth and since $\mathcal{K}^{d}_{\delta}(\boldsymbol{\sigma}(v)) \in$ 819 $C^{0}(\overline{D})$, we infer that 820

821
$$n_{\sharp\delta}(v, \hat{w}_{h}) = \sum_{K \in \mathcal{T}_{h}} \int_{\partial K} \mathcal{K}_{\delta}^{d}(\boldsymbol{\sigma}(v)) \cdot \boldsymbol{n}_{K}(w_{K} - w_{\partial K}) \, \mathrm{d}s = \sum_{K \in \mathcal{T}_{h}} \int_{\partial K} \mathcal{K}_{\delta}^{d}(\boldsymbol{\sigma}(v)) \cdot \boldsymbol{n}_{K} w_{K} \, \mathrm{d}s$$
822
823
$$= \sum_{K \in \mathcal{T}_{h}} \int_{K} \left(\mathcal{K}_{\delta}^{d}(\boldsymbol{\sigma}(v)) \cdot \nabla w_{K} + \mathcal{K}_{\delta}^{\mathrm{b}}(\nabla \cdot \boldsymbol{\sigma}(v)) w_{K} \right) \, \mathrm{d}x,$$

where we used the divergence formula and the commuting property (3.17) in the last 824 line. Letting $\delta \to 0$, we conclude that $n_{\sharp\delta}(v, \hat{w}_h)$ also tends to the right-hand side 825 of (4.37b) as $\delta \rightarrow 0$. Hence, (4.37b) holds true. 826

(iii) The proof of (4.38) uses the same arguments as the proof of Lemma 3.5. 827

Remark 4.17 ((4.37b)). The right-hand side of (4.37b) does not depend on the 828 face-based functions $w_{\partial K}$. This identity will replace the argument in [16, 18] invoking 829 the continuity of the normal component of $\sigma(u)$ at the mesh interfaces, which makes 830 sense only when the exact solution is smooth enough, say $\sigma(u) \in H^r(D)$ with $r > \frac{1}{2}$. 831

Let $V_{\sharp} := V_{\mathrm{s}} + P_{k+1}^{\mathrm{b}}(\mathcal{T}_h)$ be equipped with the seminorm $\|v\|_{V_{\sharp}} := |v|_{\lambda,p,q}$ defined 832 in (4.2). Notice that $||v||_{V_{\sharp}} = 0$ implies that v = 0 if v has zero mean-value in each 833 mesh cell $K \in \mathcal{T}_h$; this is the case for instance if one takes $v = u - \mathcal{E}_h^{k+1}(u)$. We define 834 the consistency error $\delta_h : \hat{V}_{h,0}^k \to (\hat{V}_{h,0}^k)'$ by setting, for all $\hat{w}_h \in V_{h,0}^k$, 835

836 (4.39)
$$\langle \delta_h(\hat{v}_h), \hat{w}_h \rangle_{(\hat{V}_{h,0}^k)', \hat{V}_{h,0}^k} := \hat{\ell}_h(\hat{w}_h) - \hat{a}_h(\hat{v}_h, \hat{w}_h)$$

We define global counterparts of the local operators R_{K}^{k+1} , $\hat{\mathcal{I}}_{K}^{k}$, and \mathcal{E}_{K}^{k+1} , namely $\mathsf{R}_{h}^{k+1}: \hat{V}_{h,0}^{k} \to P_{k+1}^{\mathrm{b}}(\mathcal{T}_{h}), \hat{\mathcal{I}}_{h}^{k}: H^{1}(D) \to \hat{V}_{h,0}^{k}$, and $\mathcal{E}_{h}^{k+1}: H^{1}(D) \to P_{k+1}^{\mathrm{b}}(\mathcal{T}_{h})$, by setting $\mathsf{R}_{h}^{k+1}(\hat{v}_{h})|_{K} := \mathsf{R}_{K}^{k+1}(\hat{v}_{K}), \hat{\mathcal{I}}_{h}^{k}(v)|_{K} := \hat{\mathcal{I}}_{K}^{k}(v_{|K})$, and $\mathcal{E}_{h}^{k+1}(v)|_{K} := \mathcal{E}_{K}^{k+1}(v_{|K})$, 837 838 839 for all $\hat{v}_h \in \hat{V}_{h,0}^k$, all $v \in H^1(D)$, and all $K \in \mathcal{T}_h$. 840

LEMMA 4.18 (Consistency/boundedness). There is ω_{\sharp} , uniform w.r.t. $h \in \mathcal{H}$, λ , 841 and $u \in V_{s}$, but depending on p and q, s.t. 842

843 (4.40)
$$\|\delta_h(\hat{\mathcal{I}}_h^k(u))\|_{(\hat{V}_{h,0}^k)'} \le \omega_{\sharp} \|u - \mathcal{E}_h^{k+1}(u)\|_{V_{\sharp}}.$$

Proof. Since $\boldsymbol{\sigma}(u) = -\lambda \nabla u$, $\nabla \cdot \boldsymbol{\sigma}(u) = f$, and $u \in V_s$, the identity (4.37b) yields 844 $\hat{\ell}_h(\hat{w}_h) = \sum_{K \in \mathcal{T}_h} (f, w_K)_{L^2(K)} = \sum_{K \in \mathcal{T}_h} a_K(u, w_K) + n_{\sharp}(u, \hat{w}_h), \text{ where } a_K(u, w_K) := \int_K -\boldsymbol{\sigma}(u) \cdot \nabla w_K \, \mathrm{d}x.$ Using the definition of \hat{a}_h in (4.33), then the identity $\mathsf{R}_K^{k+1} \circ \hat{\mathcal{I}}_K^k = \mathcal{E}_K^{k+1}$ (see (4.35a)), and finally (4.37a) with $v_h = \mathcal{E}_h^{k+1}(u)$, we obtain 845846 847

848

$$\hat{a}_{h}(\hat{\mathcal{I}}_{h}^{k}(u), \hat{w}_{h}) = \sum_{K \in \mathcal{T}_{h}} a_{K}(\mathcal{E}_{K}^{k+1}(u), w_{K}) + n_{\sharp}(\mathcal{E}_{h}^{k+1}(u), \hat{w}_{h})$$

$$+ \sum_{K \in \mathcal{T}_{h}} \lambda_{K}(h_{\partial K}^{-1} \mathsf{S}_{\partial K}^{k}(\hat{\mathcal{I}}_{K}^{k}(u)), \mathsf{S}_{\partial K}^{k}(\hat{w}_{K}))_{L^{2}(\partial K)}$$
850

Subtracting these two identities and using the definition of $\mathcal{E}_{K}^{k+1}(u)$, which implies that 851 $a_K(u - \mathcal{E}_K^{k+1}(u), w_K) = 0, \text{ for all } K \in \mathcal{T}_h, \text{ leads to } \langle \delta_h(\hat{\mathcal{I}}_h^k(u)), \hat{w}_h \rangle_{(\hat{V}_{h,0}^k)', \hat{V}_{h,0}^k} = \mathfrak{T}_1 + \mathfrak{T}_2$ 852 with 853

854
$$\mathfrak{T}_1 := n_{\sharp}(u - \mathcal{E}_h^{k+1}(u), \hat{w}_h), \qquad \mathfrak{T}_2 := -\sum_{K \in \mathcal{T}_h} \lambda_K(h_{\partial K}^{-1} \mathsf{S}_{\partial K}^k(\hat{\mathcal{I}}_K^k(u)), \mathsf{S}_{\partial K}^k(\hat{w}_K)_{L^2(\partial K)}.$$

We invoke (4.38) to bound \mathfrak{T}_1 and observe that $\sum_{K \in \mathcal{T}_h} \lambda_K h_K^{-1} \| w_K - w_{\partial K} \|_{L^2(\partial K)}^2 \leq$ 856 $\|\hat{w}_h\|_{\hat{V}_{k-1}^k}^2$ owing to (4.28). For the bound on \mathfrak{T}_2 , we proceed as in [16, 18]. 857

THEOREM 4.19 (Error estimate). Let u solve (2.1) and \hat{u}_h solve (4.34) with \hat{a}_h 858 and $\hat{\ell}_h$ defined in (4.33). Assume that there is r > 0 s.t. $u \in H^{1+r}(D)$. There is 859 c, uniform w.r.t. $h \in \mathcal{H}, \lambda$, and $u \in H^{1+r}(D)$, but depending on r, s.t. the following 860 holds true: 861

862 (4.41)
$$\|\lambda^{\frac{1}{2}} \nabla_h (u - \mathsf{R}_h^{k+1}(\hat{u}_h))\|_{L^2(D)} \le c \, \|u - \mathcal{E}_h^{k+1}(u)\|_{V_{\sharp}}.$$

Moreover, letting $t := \min(r, k+1)$, $\chi_t = 1$ if $t \le 1$ and $\chi_t = 0$ if t > 1, we have 863 864

865 (4.42)
$$\|\lambda^{\frac{1}{2}} \nabla_h (u - \mathsf{R}_h^{k+1}(\hat{u}_h))\|_{L^2(D)}$$

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867
$$\leq c \left(\sum_{K \in \mathcal{T}_h} \lambda_K h_K^{2t} |u|_{H^{1+t}(K)}^2 + \frac{\chi_t}{\lambda_K} h_K^{2d(\frac{d+2}{2d} - \frac{1}{q})} ||f||_{L^q(K)}^2 \right)^{\frac{1}{2}}. \quad \Box$$

868 Proof. (i) We adapt the proof of Lemma 4.2 to exploit the convergence order of the 869 reconstruction operator. Let us set $\hat{\zeta}_h^k := \hat{\mathcal{I}}_h^k(u) - \hat{u}_h \in \hat{V}_{h,0}^k$ so that $\hat{\zeta}_K^k = \hat{\mathcal{I}}_K^k(u_{|K}) - \hat{u}_K$ 870 for all $K \in \mathcal{T}_h$. The coercivity property from Lemma 4.14 and the definition of the 871 consistency error imply that

872
$$\alpha \|\lambda^{\frac{1}{2}} \nabla_h \mathsf{R}_h^{k+1}(\hat{\zeta}_h^k)\|_{L^2(D)}^2 \le \frac{\hat{a}_h(\zeta_h^k, \zeta_h^k)}{\|\hat{\zeta}_h^k\|_{\hat{V}_{h,0}^k}^2} \|\lambda^{\frac{1}{2}} \nabla_h \mathsf{R}_h^{k+1}(\hat{\zeta}_h^k)\|_{L^2(D)}^2$$

873
874
$$\leq \frac{\left(\hat{a}_{h}(\hat{\zeta}_{h}^{k},\hat{\zeta}_{h}^{k})\right)^{2}}{\|\hat{\zeta}_{h}^{k}\|_{\hat{V}_{h,0}^{k}}^{2}} = \frac{\left\langle\delta_{h}(\hat{\mathcal{I}}_{h}^{k}(u)),\hat{\zeta}_{h}^{k}\right\rangle_{(\hat{V}_{h,0}^{k})',\hat{V}_{h,0}^{k}}^{2}}{\|\hat{\zeta}_{h}^{k}\|_{\hat{V}_{h,0}^{k}}^{2}} \leq \|\delta_{h}(\hat{\mathcal{I}}_{h}^{k}(u))\|_{(\hat{V}_{h,0}^{k})'}^{2}.$$

Then, lemma 4.18 yields $\|\lambda^{\frac{1}{2}} \nabla \mathsf{R}_{h}^{k+1}(\hat{\zeta}_{h}^{k})\|_{L^{2}(D)} \leq c \|u - \mathcal{E}_{h}^{k+1}(u)\|_{V_{\sharp}}$. Moreover, since R_K^{k+1} $(\hat{\mathcal{I}}_{K}^{k}(u)) = \mathcal{E}_{K}^{k+1}(u)$ for all $K \in \mathcal{T}_{h}$, see (4.35a), we have

877
$$u - \mathsf{R}_{h}^{k+1}(\hat{u}_{h}) = u - \mathcal{E}_{h}^{k+1}(u) + \mathsf{R}_{h}^{k+1}(\hat{\zeta}_{h}^{k}).$$

The estimate (4.41) is now a consequence of the triangle inequality.

(ii) We now prove (4.42). Let us set $\eta^{k+1} := u - \mathcal{E}_h^{k+1}(u)$. We need to bound (ii) We now prove (4.42). Let us set $\eta^{k+1} := u - \mathcal{E}_h^{k+1}(u)$. We need to bound (iii) $\|\eta^{k+1}\|_{V_{\sharp}} = |\eta^{k+1}|_{\lambda,p,q}$, i.e., we must estimate $\|\nabla \eta^{k+1}\|_{L^2(K)}$, $h_K^{d(\frac{1}{2}-\frac{1}{p})}\|\nabla \eta^{k+1}\|_{L^p(K)}$, (iii) $\|\eta^{k+1}\|_{V_{\sharp}} = |\eta^{k+1}|_{\lambda,p,q}$, i.e., we must estimate $\|\nabla \eta^{k+1}\|_{L^2(K)}$, $h_K^{d(\frac{1}{2}-\frac{1}{p})}\|\nabla \eta^{k+1}\|_{L^p(K)}$, (iii) $\|\eta^{k+1}\|_{V_{\sharp}} = |\eta^{k+1}|_{\lambda,p,q}$, i.e., we must estimate $\|\nabla \eta^{k+1}\|_{L^2(K)}$, $h_K^{d(\frac{1}{2}-\frac{1}{p})}\|\nabla \eta^{k+1}\|_{L^p(K)}$, (iii) $\|\eta^{k+1}\|_{V_{\sharp}} = |\eta^{k+1}|_{\lambda,p,q}$, i.e., we must estimate $\|\nabla \eta^{k+1}\|_{L^2(K)}$, $h_K^{d(\frac{1}{2}-\frac{1}{p})}\|\nabla \eta^{k+1}\|_{L^p(K)}$, (iii) $\|\eta^{k+1}\|_{V_{\sharp}} = |\eta^{k+1}|_{\lambda,p,q}$, i.e., we must estimate $\|\nabla \eta^{k+1}\|_{L^2(K)}$, $h_K^{d(\frac{1}{2}-\frac{1}{p})}\|\nabla \eta^{k+1}\|_{L^p(K)}$, (iii) $\|\eta^{k+1}\|_{L^p(K)}$, (see (4.2)). Owing to the optimality property of the elliptic projection and the approximation properties of Π_{K}^{k+1} , we have

883
$$\|\nabla \eta^{k+1}\|_{L^2(K)} \le \|\nabla (u - \Pi_K^{k+1}(u))\|_{L^2(K)} \le c h_K^t |u|_{H^{1+t}(K)}.$$

for $t = \min(r, k + 1)$. Let us now consider the other two terms. Let $\ell := \lceil t \rceil$, so that $t \leq \ell \leq 1 + t$. Notice also that $\ell \leq k + 1$, and $\ell \geq 1$ since we assumed that r > 0. Let us set $\eta^{\ell} := u - \mathcal{E}_{h}^{\ell}(u)$, then $\|\nabla \eta^{\ell}\|_{L^{2}(K)} \leq ch_{K}^{t}|u|_{H^{1+t}(K)}$. Invoking the triangle inequality, an inverse inequality, and the triangle inequality again, we infer that

$$\begin{cases} & \qquad h_K^{d(\frac{1}{2} - \frac{1}{p})} \| \nabla \eta^{k+1} \|_{L^p(K)} \le h_K^{d(\frac{1}{2} - \frac{1}{p})} \| \nabla \eta^{\ell} \|_{L^p(K)} + c \left(\| \nabla \eta^{k+1} \|_{L^2(K)} + \| \nabla \eta^{\ell} \|_{L^2(K)} \right) \end{cases}$$

and the two terms between the parentheses are bounded by $ch_K^t |u|_{H^{1+t}(K)}$. Moreover, invoking (4.16), we obtain

892
$$h_{K}^{d(\frac{1}{2}-\frac{1}{p})} \|\nabla\eta^{\ell}\|_{L^{p}(K)} \leq c \left(\|\nabla\eta^{\ell}\|_{L^{2}(K)} + h_{K}^{t}|\nabla\eta^{\ell}|_{H^{t}(K)}\right)$$

$$= c \left(\|\nabla \eta^{\ell}\|_{L^{2}(K)} + h_{K}^{t} |u|_{H^{1+t}(K)} \right) \le c' h_{K}^{t} |u|_{H^{1+t}(K)},$$

895 since $t \leq \ell$. Similarly, we have

$$\{ \{ \{ M_{K}^{d(\frac{d+2}{2d} - \frac{1}{q})} \| \Delta \eta^{k+1} \|_{L^{q}(K)} \le h_{K}^{d(\frac{d+2}{2d} - \frac{1}{q})} \| \Delta \eta^{\ell} \|_{L^{q}(K)} + c \left(\| \nabla \eta^{k+1} \|_{L^{2}(K)} + \| \nabla \eta^{\ell} \|_{L^{2}(K)} \right)$$

898 It remains to estimate $h_K^{d(\frac{d+2}{2d}-\frac{1}{q})} \|\Delta \eta^\ell\|_{L^q(K)}$. We proceed as in the end of the proof 899 of Theorem 4.10. If $t \leq 1$ (so that $\chi_t = 1$), we have $\ell = 1$, and we infer that

900
$$h_{K}^{d(\frac{d+2}{2d}-\frac{1}{q})} \|\Delta\eta^{\ell}\|_{L^{q}(K)} = \lambda_{K}^{-1} h_{K}^{d(\frac{d+2}{2d}-\frac{1}{q})} \|f\|_{L^{q}(K)}$$

Otherwise, we have t > 1 (so that $\chi_t = 0$) and $\ell \ge 2$, and we take q = 2. Then, using the triangle inequality, an inverse inequality, and the triangle inequality again,

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we obtain 903

904
$$h_{K} \|\Delta \eta^{\ell}\|_{L^{q}(K)} \leq h_{K} \|\Delta (u - \Pi_{K}^{\ell}(u)\|_{L^{q}(K)} + c \left(\|\nabla (u - \Pi_{K}^{\ell}(u))\|_{L^{2}(K)} + \|\nabla \eta^{\ell}\|_{L^{2}(K)} \right),$$

where Π_K^{ℓ} is the L^2 -orthogonal projection onto $\mathbb{P}_{\ell,d}$. We conclude by invoking the approximation properties of Π_K^{ℓ} , recalling that $\|\nabla \eta^{\ell}\|_{L^2(K)} \leq ch_K^t |u|_{H^{1+t}(K)}$. 907 908 Remark 4.20 (Supercloseness). Step (i) in the above proof actually shows that 909 $\|\hat{\zeta}_h^k\|_{\hat{V}_{h,0}^k} \leq c \|u - \mathcal{E}_h^{k+1}(u)\|_{V_{\sharp}}$. Since $\zeta_K^k = \Pi_K^k(u) - u_K$ for all $K \in \mathcal{T}_h$, this implies the 910 supercloseness bound $(\sum_{K\in\mathcal{T}_h}\lambda_K \|\nabla(\Pi_K^k(u)-u_K)\|_{L^2(K)}^2)^{\frac{1}{2}} \leq c\|u-\mathcal{E}_h^{k+1}(u)\|_{V_{\sharp}}.$ 911

5. Extensions to Maxwell's equations. The various techniques presented in 912 this paper can be extended to the context of Maxwell's equations, since arguments 913 914 similar to those exposed in §3 can be deployed to define the tangential trace of vectors fields on a face of K. Without going into the details, we show in this section how that 915 can be done. 916

5.1. Lifting and tangential trace. Let p, q be real numbers satisfying (3.2), 917 and let $\widetilde{p} \in (2, p]$ be such that $q \geq \frac{\widetilde{p}d}{\widetilde{p}+d}$. Let K be a cell in \mathcal{T}_h , and let $F \in \mathcal{F}_K$ be a 918 face of K. Following [25], we introduce the space 919

$$\underbrace{\mathfrak{g20}}_{\mathbb{Z}_1} \quad (5.1) \qquad \qquad \mathbf{Y}^{\mathsf{c}}(F) := \{ \boldsymbol{\phi} \in \boldsymbol{W}^{\frac{1}{\tilde{p}}, \tilde{p}'}(F) \mid \boldsymbol{\phi} \cdot \boldsymbol{n}_F = 0 \}$$

which we equip with the norm $\|\phi\|_{\boldsymbol{Y}^{c}(F)} := \|\phi\|_{\boldsymbol{L}^{\tilde{p}'}(F)} + h_{F}^{\frac{1}{\tilde{p}}} |\phi|_{\boldsymbol{W}^{\frac{1}{\tilde{p}},\tilde{p}'}(F)}$. Then the 922 following result can be established by proceeding as in the proof of Lemma 3.1. 923

LEMMA 5.1 (Face-to-cell Lifting). There exist a constant c, uniform w.r.t. h, but 924 depending on p and q, and a lifting operator $E_F^K : \mathbf{Y}^{c}(F) \to \mathbf{W}^{1,\widetilde{p}'}(K)$ such that the 925 following holds true for any $\phi \in \mathbf{Y}^{c}(F)$: $E_{F}^{K}(\phi)_{|\partial K \setminus F} = \mathbf{0}, \ E_{F}^{K}(\phi)_{|F} = \phi, \ and$ 926

927 (5.2)
$$|E_F^K(\phi)|_{W^{1,p'}(K)} + h_K^{-1+d(\frac{1}{q}-\frac{1}{p})} ||E_F^K(\phi)||_{L^{q'}(K)} \le c h_K^{-\frac{1}{\tilde{p}}+d(\frac{1}{\tilde{p}}-\frac{1}{p})} ||\phi||_{Y^c(F)}.$$

With this lifting operator in hand, we can define an extension to the notion of 928 the tangential trace on F of a vector field. To this end, we introduce the functional 929 space 930

$$\mathfrak{g}_{32}^{\mathfrak{s}_{2}} \quad (5.3) \qquad \qquad \mathbf{S}^{\mathfrak{c}}(K) := \{ \boldsymbol{\tau} \in \boldsymbol{L}^{p}(K) \mid \nabla \times \boldsymbol{\tau} \in \boldsymbol{L}^{q}(K) \}$$

where the superscript ^c refers to the fact that the tangential trace is related to the 933 934 curl operator. We equip $S^{c}(K)$ with the following dimensionally-consistent norm:

935 (5.4)
$$\|\boldsymbol{\tau}\|_{\boldsymbol{S}^{c}(K)} := \|\boldsymbol{\tau}\|_{\boldsymbol{L}^{p}(K)} + h_{K}^{1+d(\frac{1}{p}-\frac{1}{q})} \|\nabla \times \boldsymbol{\tau}\|_{L^{q}(K)}.$$

We now define the tangential trace of any field τ in $S^{c}(K)$ on the face F of K to be 936 the linear form $(\boldsymbol{\tau} \times \boldsymbol{n}_K)_{|F} \in \boldsymbol{Y}^{c}(F)'$ such that 937

938 (5.5)
$$\langle (\boldsymbol{\tau} \times \boldsymbol{n}_K)|_F, \boldsymbol{\phi} \rangle_F := \int_K \left(\boldsymbol{\tau} \cdot \nabla \times E_F^K(\boldsymbol{\phi}) - (\nabla \times \boldsymbol{\tau}) \cdot E_F^K(\boldsymbol{\phi}) \right) \mathrm{d}x,$$

for all $\phi \in \mathbf{Y}^{c}(F)$, where $\langle \cdot, \cdot \rangle_{F}$ now denotes the duality pairing between $\mathbf{Y}^{c}(F)'$ 939 and $Y^{c}(F)$. Note that the right-hand side of (5.5) is well-defined owing to Hölder's 940inequality and (5.2). 941

942 The discretization now involves the vector-valued broken finite element space

943 (5.6)
$$\boldsymbol{P}_{k}^{\mathrm{b}}(\mathcal{T}_{h}) = \{\boldsymbol{v}_{h} \in \boldsymbol{L}^{\infty}(D) \mid \boldsymbol{v}_{h|K} \in \boldsymbol{P}_{K}, \forall K \in \mathcal{T}_{h}\},\$$

where $\mathbf{P}_K := (\psi_K)^{-1}(\widehat{\mathbf{P}}) \subset \mathbf{W}^{k+1,\infty}(K), (\widehat{K}, \widehat{\mathbf{P}}, \widehat{\Sigma})$ is the reference element, and ψ_K is an appropriate transformation. For instance, one can take $\psi_K(\mathbf{v}) = \psi_K^g(\mathbf{v}) := \mathbf{v} \circ \mathbf{T}_K$ for continuous Lagrange elements or for dG approximation; one can also take $\psi_K(\mathbf{v}) =$ $\psi_K^c(\mathbf{v}) := \mathbb{J}_K^\mathsf{T}(\mathbf{v} \circ \mathbf{T}_K)$ for edge elements (ψ_K^c is covariant Piola transformation and \mathbb{J}_K the Jacobian of the geometric mapping). For any face $F \in \mathcal{F}_K$, we denote by \mathbf{P}_F the trace of \mathbf{P}_K on F. The following result is the counterpart of Lemma 3.2.

250 LEMMA 5.2 (Bound on tangential component). There exists a constant c, uni-251 form w.r.t. h, but depending on p and q, so that the following estimate holds true for 252 all $\mathbf{v} \in \mathbf{S}^{c}(K)$,

953 (5.7)
$$\|(\boldsymbol{v} \times \boldsymbol{n}_K)|_F\|_{Y^c(F)'} \le c h_K^{-\frac{1}{p}+d(\frac{1}{p}-\frac{1}{p})} \|\boldsymbol{v}\|_{\boldsymbol{S}^c(K)}.$$

954 Moreover, we have

955 (5.8)
$$|\langle (\boldsymbol{v} \times \boldsymbol{n}_K)_{|F}, \boldsymbol{\phi}_h \rangle| \le c h_K^{d(\frac{1}{2} - \frac{1}{p})} \|\boldsymbol{v}\|_{\boldsymbol{S}^c(K)} h_F^{-\frac{1}{2}} \|\boldsymbol{\phi}_h\|_{L^2(F)},$$

956 for all $\phi_h \in \mathbf{P}_F$ s.t. $\phi \cdot \mathbf{n}_F = 0$, all $K \in \mathcal{T}_h$, and all $F \in \mathcal{F}_K$.

Lemma 5.2 is essential for the error analysis of nonconforming approximation techniques of Maxwell's equations. It is a generalization of Bonito et al. [8, Lem. A3] and Buffa and Perugia [9, Lem. 8.2].

960 **5.2. Definition of** n_{\sharp}^{c} and key identities. The consistency analysis of Nitsche's 961 boundary penalty method and of the dG approximation applied to Maxwel's equations 962 can be done by introducing a bilinear form n_{\sharp} as in §3. We henceforth assume that 963 the space dimension is either d = 2 or d = 3.

We define the notion of diffusive flux by introducing $\boldsymbol{\sigma} : \boldsymbol{H}(\operatorname{curl}; D) \to \boldsymbol{L}^2(D)$ such that $\boldsymbol{\sigma}(\boldsymbol{v}) := \lambda \nabla \times \boldsymbol{v}$, for any $\boldsymbol{v} \in \boldsymbol{H}(\operatorname{curl}; D)$. Here, the diffusivity λ is either the reciprocal of the magnetic permeability or the reciprocal of electrical conductivity, depending whether one works with the electric field or the magnetic field. The diffusivity is assumed to satisfy the hypotheses introduced in Section 2. We further define

970 (5.9)
$$\boldsymbol{V}_{s} := \{ \boldsymbol{v} \in \boldsymbol{H}(\operatorname{curl}; D) \mid \boldsymbol{\sigma}(\boldsymbol{v}) \in \boldsymbol{L}^{p}(D), \ \nabla \times \boldsymbol{\sigma}(\boldsymbol{v}) \in \boldsymbol{L}^{q}(D) \},$$

971 and set $V_{\sharp} := V_{\mathrm{s}} + P_k^{\mathrm{b}}(\mathcal{T}_h).$

We adopt the same notation as in §3. Recall that for any $K \in \mathcal{T}_h$ and any $F \in \mathcal{F}_K$, we have defined $\epsilon_{K,F} = \mathbf{n}_F \cdot \mathbf{n}_K = \pm 1$. We consider arbitrary weights $\theta_{K,F}$ satisfying (3.13). We introduce the bilinear form $n_{\sharp}^{c} : (\mathbf{V}_{s} + \mathbf{P}_{k}^{b}(\mathcal{T}_{h})) \times \mathbf{P}_{k}^{b}(\mathcal{T}_{h}) \to \mathbb{R}$ defined as follows:

976 (5.10)
$$n_{\sharp}^{c}(\boldsymbol{v},\boldsymbol{w}_{h}) := \sum_{F \in \mathcal{F}_{h}} \sum_{K \in \mathcal{T}_{F}} \epsilon_{K,F} \theta_{K,F} \langle (\boldsymbol{\sigma}(\boldsymbol{v})_{|K} \times \boldsymbol{n}_{K})_{|F}, \llbracket \Pi_{F}(\boldsymbol{w}_{h}) \rrbracket \rangle_{F},$$

978 where Π_F is the ℓ^2 -orthogonal projection onto the hyperplane tangent to F, i.e., 979 $\Pi_F(\boldsymbol{b}_h) := \boldsymbol{b}_h - (\boldsymbol{b}_h \cdot \boldsymbol{n}_K) \boldsymbol{n}_K = \boldsymbol{n}_K \times (\boldsymbol{b}_h \times \boldsymbol{n}_K)$. Notice that (5.10) is meaningful since 980 $\Pi_F(\boldsymbol{b}_h)_{|F}$ is in $\boldsymbol{W}^{\frac{1}{p}, \widetilde{p}'}(F)$ and $\Pi_F(\boldsymbol{b}_h) \cdot \boldsymbol{n}_F = 0$, i.e., $\Pi_F(\boldsymbol{b}_h) \in \boldsymbol{Y}^c(F)$ for any $F \in \mathcal{F}_h$. 981 The following result is the counterpart of Lemma 3.3.

26

LEMMA 5.3 (Identities for $n_{\rm H}^{\rm c}$). The following holds true for any choice of weights 982 $\{\theta_{K,F}\}_{F\in\mathcal{F}_h,K\in\mathcal{T}_F}$ and for all $w_h \in P_k^{\mathrm{b}}(\mathcal{T}_h)$, all $v_h \in P_k^{\mathrm{b}}(\mathcal{T}_h)$, and all $v \in V_{\mathrm{s}}$: 983

984 (5.11a)
$$n_{\sharp}^{c}(\boldsymbol{v}_{h},\boldsymbol{w}_{h}) = \sum_{F \in \mathcal{F}_{h}} \int_{F} (\{\boldsymbol{\sigma}(\boldsymbol{v}_{h})\}_{\boldsymbol{\theta}} \times \boldsymbol{n}_{F}) \cdot \llbracket \Pi_{F}(\boldsymbol{w}_{h}) \rrbracket \, \mathrm{d}s,$$

985 (5.11b)
$$n_{\sharp}^{c}(\boldsymbol{v},\boldsymbol{w}_{h}) = \sum_{K \in \mathcal{T}_{h}} \int_{K} \left(\boldsymbol{\sigma}(v) \cdot \nabla \times \boldsymbol{w}_{h|K} - (\nabla \times \boldsymbol{\sigma}(v)) \cdot \boldsymbol{w}_{h|K}\right) \mathrm{d}x. \qquad \Box$$

Proof. The proof is similar to that of Lemma 3.3. The proof of (5.11a) is quasi-987 identical to that of (3.16a). For the proof of (5.11b), one invokes the mollifying 988 operators $\mathcal{K}^{c}_{\delta} : \mathbf{L}^{1}(D) \to \mathbf{C}^{\infty}(\overline{D})$ and $\mathcal{K}^{d}_{\delta} : \mathbf{L}^{1}(D) \to \mathbf{C}^{\infty}(\overline{D})$ introduced in [22, §3.2]. 989 These two operators satisfy the following key commuting property: 990

991 (5.12)
$$\nabla \times (\mathcal{K}^{c}_{\delta}(\boldsymbol{\tau})) = \mathcal{K}^{d}_{\delta}(\nabla \times \boldsymbol{\tau}),$$

for all $\tau \in L^1(D)$ s.t. $\nabla \times \tau \in L^1(D)$. Then one uses the identities $[\![v \times \Pi_F(w)]\!] =$ 992 $\{v\}_{\theta} \times \llbracket \Pi_F(w) \rrbracket + \llbracket v \rrbracket \times \{\Pi_F(w)\}_{\overline{\theta}}, \ n_K \times \Pi_F(w_h) = n_K \times w_h, \ \text{and} \ \nabla \cdot (w_h \times \sigma(v)) =$ 993 $\boldsymbol{\sigma}(\boldsymbol{v}) \cdot (\nabla \times \boldsymbol{w}_h) - \boldsymbol{w}_h \cdot (\nabla \times \boldsymbol{\sigma}(\boldsymbol{v})).$ Π 994

We now establish the boundedness of the bilinear form n_{\sharp}^{c} . Since $\boldsymbol{\sigma}(\boldsymbol{v})_{|K} \in \boldsymbol{S}^{c}(K)$ 995 for all $K \in \mathcal{T}_h$ and all $v \in V_s + P_k^{\mathrm{b}}(\mathcal{T}_h)$, we equip the space $V_s + P_k^{\mathrm{b}}(\mathcal{T}_h)$ with the 996 seminorm 997 998

999 (5.13)
$$\|\boldsymbol{v}\|_{n_{\sharp}^{c}}^{2} := \sum_{K \in \mathcal{T}_{h}} \lambda_{K}^{-1} \Big(h_{K}^{2d(\frac{1}{2} - \frac{1}{p})} \|\boldsymbol{\sigma}(\boldsymbol{v})_{|K}\|_{L^{p}(K)}^{2} + h_{K}^{2d(\frac{2+d}{2d} - \frac{1}{q})} \|\nabla \times \boldsymbol{\sigma}(\boldsymbol{v})_{|K}\|_{L^{q}(K)}^{2} \Big).$$

LEMMA 5.4 (Boundedness of n_{\sharp}°). With the weights defined in (3.19) and λ_F de-1002fined in (3.20) for all $F \in \mathcal{F}_h$, there is c, uniform w.r.t. $h \in \mathcal{H}$ and λ , but depending 1003 on p and q, s.t. the following holds true for all $v \in V_s + P_k^b(\mathcal{T}_h)$ and all $w_h \in P_k^b(\mathcal{T}_h)$: 1004

1005 (5.14)
$$|n_{\sharp}^{c}(\boldsymbol{v},\boldsymbol{w}_{h})| \leq c |\boldsymbol{v}|_{n_{\sharp}^{c}} \left(\sum_{F \in \mathcal{F}_{h}} \lambda_{F} h_{F}^{-1} \| \llbracket \Pi_{F}(\boldsymbol{w}_{h}) \rrbracket \|_{\boldsymbol{L}^{2}(F)}^{2} \right)^{\frac{1}{2}}.$$

1006With the above tools in hand, one can revisit Buffa and Perugia [9] and greatly simplify the analysis of the dG approximation of Maxwell's equations. One can also 1007 extend the work in [24] and analyze Nitsche's boundary penalty technique with edge 1008 elements; one can also revisit Bonito et al. [7], where Nitsche's boundary penalty 10091010 technique has been used in conjunction with Lagrange elements. In all the cases one then obtains error estimates that are robust with respect to the diffusivity contrast. 1011

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