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Blow up of the solutions to a linear elliptic system involving Schrödinger operators

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Abstract We show how the solutions to a 2×2 linear system involving Schrödinger operators blow up as the parameter μ tends to some critical value which is the principal eigenvalue of the system; here the potential is continuous positive with superquadratic growth and the square matrix of the system is with constant coefficients and may have a double eigenvalue.

1 Introduction

We study here the behavior of the solutions to a 2×2 system (considered in its variational formulation):

(S)
$$LU := (-\Delta + q(x))U = AU + \mu U + F(x) \text{ in } \mathbb{R}^N,$$
$$U(x)_{|x| \to \infty} \to 0$$

where q is a continuous positive potential tending to $+\infty$ at infinity with superquadratic growth; U is a column vector with components u_1 and u_2 and A is a 2 × 2 square matrix with constant coefficients. F is a column vector with components f_1 and f_2 .

Such systems have been intensively studied mainly for $\mu = 0$ and for A with 2 distinct eigenvalues; here we consider also the case of a double eigenvalue. In both cases, we show the blow up of solutions as μ tends to some critical value ν which is the principal eigenvalue of System (S). This extends to systems involving Schrödinger operators defined on \mathbb{R}^N earlier results valid for systems involving the classical Laplacian defined on smooth bounded domains with Dirichlet boundary conditions.

This paper is organized as follows: In Section 2 we recall known results for one equation. In Section 3 we consider first the case where A has two different eigenvalues and then we study the case of a double eigenvalue.

2 The equation

We shortly recall the case of one equation

(E)
$$Lu := (-\Delta + q(x))u = \sigma u + f(x) \in \mathbb{R}^N,$$
$$\lim_{|x| \to +\infty} u(x) = 0.$$

 σ is a real parameter.

Hypotheses

 (H_q) q is a positive continuous potential tending to $+\infty$ at infinity. (H_f) $f \in L^2(\mathbb{R}^N), f \ge 0$ and f > 0 on some subset with positive Lebesgue measure.

It is well known that if (H_q) is satisfied, L possesses an infinity of eigenvalues tending to $+\infty$: $0 < \lambda_1 < \lambda_2 \leq \ldots$.

Notation: (Λ, ϕ) Denote by Λ the smallest eigenvalue of L; it is positive and simple and denote by ϕ the associated eigenfunction, positive and with L^2 -norm $\|\phi\| = 1$.

It is classical ([15], [19]) that if f > 0 and $\sigma < \Lambda$ the positivity is improved, or in other words, the maximum principle (**MP**) is satisfied:

$$(MP) f \ge 0, \not\equiv 0 \Rightarrow u > 0.$$

Lately, for potentials growing fast enough (faster than the harmonic oscillator), another notion has been introduced ([4], [5], [9], [10]) which improves the maximum (or antimaximum principle): the "groundstate positivity" (**GSP**) (resp. " negativity" (**GSN**)) which means that there exists k > 0such that

 $u > k\phi$ (GSP) (resp. $u < -k\phi$ (GSN))

We also say shortly "fundamenal positivity" or "negativity", or also " ϕ -positivity" or "negativity".

The first steps in this direction use a radial potential. Here we consider a small perturbation of a radial one as in [9].

The potential q We define first a class \mathcal{P} of radial potentials:

$$\mathcal{P} := \{ Q \in \mathcal{C}(\mathbb{R}_+, (0, \infty)) / \exists R_0 > 0, Q' > 0 \, a.e. \, on \, [R_0, \infty), \, \int_{R_0}^{\infty} Q(r)^{-1/2} < \infty \}$$
(1)

The last inequality holds if Q is growing sufficiently fast $(> r^2)$. Now we give results of GSP or GSN for a potential q which is a small perturbation of Q; we assume:

 (H'_q) q satisfies (H_q) and there exists two functions Q_1 and Q_2 in \mathcal{P} , and two positive constants R_0 and C_0 such that

$$Q_1(|x|) \le q(x) \le Q_2(|x|) \le C_0 Q_1(|x|), \ \forall x \in \mathbb{R}^N,$$
(2)

$$\int_{R_0}^{\infty} (Q_2(s) - Q_1(s)) \int_{R_0}^{s} exp\left(-\int_{r}^{s} [Q_1(t)^{1/2} + Q_2(t)^{1/2}] dt\right) dr ds < \infty.$$
(3)

Denoting by Φ_1 (resp. Φ_2) the groundstate of $L_1 := -\Delta + Q_1$ (resp. $L_2 = -\Delta + Q_2$), Corollary 3.3 in [9] says that all these groundstates are "comparable" that is there exists constants $0 < k_1 \leq k_2 \leq \infty$ such that $k_1\phi \leq \Phi_1, \Phi_2 \leq k_2\phi$. Finally

Theorem 1 (GSP) ([9]) If (H'_q) and (H_f) are satisfied, then, for $\sigma < \Lambda$, there is a unique solution u to (E) which is positive, and there exists a constant c > 0, such that

$$u > c\phi. \tag{4}$$

Moreover, if also $f \leq C\phi$ with some constant C > 0, then

$$u \le \frac{C}{\Lambda - \sigma} \phi. \tag{5}$$

The space \mathcal{X} It is convenient for several results to introduce the space of "groundstate bounded functions":

$$\mathcal{X} := \{ h \in L^2(\mathbb{R}^N) : h/\phi \in L^\infty(\mathbb{R}^N) \}, \tag{6}$$

equipped with the norm $||h||_{\mathcal{X}} = ess \sup_{\mathbb{R}^n} (|h|/\phi).$

For a potential satisfying (H'_q) and a function $f \in \mathcal{X}$, there is also a result of "groundstate negativity" **(GSN)** for (E); it is an extension of the antimaximum principle, introduced by Clément and Peletier in 1978 ([13]) for the Laplacian when the parameter σ crosses Λ .

Theorem 2 (GSN) ([9]) Assume (H'_q) and (H_f) are satisfied and $f \in \mathcal{X}$; then there exists $\delta(f) > 0$ and a positive constant c' > 0 such that for all $\sigma \in (\Lambda, \Lambda + \delta)$,

$$u \le -c'\phi. \tag{7}$$

Remark 1 This holds also if we only assume $f^1 := \int f\phi > 0$.

Hypothesis (H'_f) We consider now functions f which are such that (H'_f) : $f \in \mathcal{X}$ and $f^1 := \int f \phi > 0$.

Theorem 3 Assume (H'_q) and (H'_f) are satisfied. Then there exists $\delta > 0$ such that for $\Lambda - \delta < \sigma < \Lambda$ there exists positive constants k' and K', depending on f and δ such that

$$0 < \frac{k'}{\Lambda - \sigma}\phi < u < \frac{K'}{\Lambda - \sigma}\phi.$$
(8)

If $\Lambda < \sigma < \Lambda + \delta$, there exists positive constants k" and K", depending on f and δ such that

$$-\frac{k^{"}}{\Lambda - \sigma}\phi < -u < -\frac{K^{"}}{\Lambda - \sigma}\phi < 0.$$
⁽⁹⁾

This result extends earlier one in [17] and a close result is Theorem 2.03 in [11]. It shows in particular that $u \in \mathcal{X}$ and $|u| \to \infty$ as $|\nu - \mu| \to 0$. **Proof:** Decompose u and f on ϕ and its orthogonal:

$$u = u^{1}\phi + u^{\perp}; \ f = f^{1}\phi + f^{\perp}.$$
 (10)

We derive from (E) $Lu = \sigma u + f$:

$$Lu^{\perp} = \sigma u^{\perp} + f^{\perp} \tag{11}$$

$$Lu^{1}\phi = \Lambda u^{1}\phi = \sigma u^{1}\phi + f^{1}\phi.$$
(12)

We notice that since q is smooth; so is u. Also, since $f \in \mathcal{X}$, f^{\perp} , u and u^{\perp} are also in \mathcal{X} and hence are bounded. Choose $\sigma < \Lambda$ and assume (H'_f) . We derive from Equation (11) (by [6]Thm 3.2) that : $||u^{\perp}||_{\mathcal{X}} < K_1$. Therefore $|u^{\perp}|$ is bounded by some *cste*. $\phi > 0$. From Equation (12) we derive

$$u^{1} = \frac{f^{1}}{(\Lambda - \sigma)} \to \pm \infty \, as \, (\Lambda - \sigma) \to 0.$$
(13)

Choose $\Lambda - \delta$ small enough and $\sigma \in (\Lambda - \delta, \Lambda)$. Hence

$$\frac{K'}{\Lambda - \sigma}\phi < u; \quad u < \frac{K"}{\Lambda - \sigma}\phi.$$

For $\sigma > \Lambda$. we do exactly the same, except that the signs are changed for u^1 in (13).

3 A 2×2 Linear system

Consider now a linear system with constant coefficients.

(S)
$$LU = AU + \mu U + F(x) \text{ in } \mathbb{R}^N$$

As above, $L := -\Delta + q$ where the potential q satisfies (H'_q) , and where μ is a real parameter. L can be detailed as 2 equations:

(S)
$$\begin{cases} Lu_1 = au_1 + bu_2 + \mu u_1 + f_1(x) \\ Lu_2 = cu_1 + du_2 + \mu u_2 + f_2(x) \end{cases} \text{ in } \mathbb{R}^N,.$$

$$u_1(x), u_2(x)_{|x| \to \infty} \to 0.$$

Assume

$$(H_A) A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \text{with } b > 0 \text{and } D := (a-d)^2 + 4bc \ge 0.$$

Note that b > 0 does not play any role since we can always change the order of the equations.

The eigenvalues of A are

$$\xi_1 = \frac{a+d+\sqrt{D}}{2} \ge \xi_2 = \frac{a+d-\sqrt{D}}{2}.$$

As far as we know, all the previous studies suppose that the largest eigenvalue ξ_1 is simple (i.e. $D = (a - d)^2 + 4bc > 0$). Here we also study, in the second subsection, the case of a double eigenvalue $\xi_1 = \xi_2$, that is D = 0; this implies necessarily bc < 0 and necessarily the matrix is not cooperative.

3.1 Case $\xi_1 > \xi_2$

This is the classical case where ξ_1 is simple. Set $\xi_1 > \xi_2$. The eigenvectors are

$$X_k = \left(\begin{array}{c} b\\ \xi_k - a \end{array}\right),$$

Set $X := X_1$. As above, denote by (Λ, ϕ) , $\phi > 0$, the principal eigenpair of the operator $L = (-\Delta + q(x))$. It is easy to see that

$$L(X\phi) - AX\phi = (\Lambda - \xi_1)X\phi.$$

Hence

$$\nu = \Lambda - \xi_1 \tag{14}$$

is the principal eigenvalue of (S) with associated eigenvector $X\phi$. Note that the components of $X\phi$ do not change sign, but, in the case of a non cooperative matrix they are not necessarily both positive. We prove:

Theorem 4 Assume (H'_q) and (H_A) ; f_1 and f_2 satisfy (H'_f) ; assume also D > 0 and d - a > 0. If

$$(\xi_2 - a)f_1^1 < bf_2^1,$$

there exists $\delta > 0$, independent of μ , such that if $\nu - \delta < \mu < \nu$, there exists a positive constant γ depending only on F such that

$$u_1, u_2 \ge \frac{\gamma}{\nu - \mu} \phi > 0. \tag{15}$$

If $\nu < \mu < \nu + \delta$, the sign are reversed:

$$u_1, u_2 \le -\frac{\gamma}{\nu - \mu} \phi < 0. \tag{16}$$

Remark 2 If (H'_q) and (H_A) are satisfied; if f_1 and f_2 satisfy (H'_f) as in Theorem 4, but if d-a < 0 we have, if $(a-\xi_2)f_1^1 + bf_2^1 > 0$ and $\nu - \delta < \mu < \nu$

$$u_1 \ge \frac{\gamma}{\nu - \mu} \phi > 0, \ u_2 \le -\frac{\gamma}{\nu - \mu} \phi < 0$$

Remark 3 It is noticeable that for all these cases, $|u_1|$, $|u_2| \to +\infty$ as $|\nu - \mu| \to 0$.

These results extend Theorem 4.2 in [4].

Proof: As in [3], we use J the associated Jordan matrix (which in this case is diagonal) and P the change of basis matrix which are such that

$$A = PJP^{-1}.$$

Here

$$P = \begin{pmatrix} b & b \\ \xi_1 - a & \xi_2 - a \end{pmatrix}, \quad P^{-1} = \frac{1}{b(\xi_1 - \xi_2)} \begin{pmatrix} a - \xi_2 & b \\ \xi_1 - a & -b \end{pmatrix}.$$
(17)
$$J = \begin{pmatrix} \xi_1 & 0 \\ 0 & \xi_2 \end{pmatrix}.$$

Denoting $\tilde{U} = P^{-1}U$ and $\tilde{F} = P^{-1}F$, we derive from System (S) (after multiplication by $P^{-1}U$ to the left):

$$L\tilde{U} = J\tilde{U} + \mu\tilde{U} + \tilde{F}.$$

Since J is diagonal we have two independent equations:

$$L\tilde{u}_k = (\xi_k + \mu)\tilde{u}_k + \tilde{f}_k, \ k = 1 \text{ or } 2.$$
 (18)

The projection on ϕ and on its orthogonal for k = 1 and 2 gives

$$\tilde{u}_k = (\tilde{u}_k)^1 \phi + \tilde{u}_k^\perp, \quad \tilde{f}_k = (\tilde{f}_k)^1 \phi + \tilde{f}_k^\perp;$$

hence

$$L(\tilde{u}_k)^1 \phi = \Lambda(\tilde{u}_k)^1 \phi = \xi_k(\tilde{u}_k)^1 \phi + \mu(\tilde{u}_k)^1 \phi + (\tilde{f}_k)^1 \phi,$$
(19)

$$L\tilde{u}_k^{\perp} = \xi_k \tilde{u}_k^{\perp} + \mu \tilde{u}_k^{\perp} + \tilde{f}_k^{\perp}.$$
 (20)

If both f_k verify (H'_f) , they are are in \mathcal{X} and bounded and hence both \tilde{f}_k^{\perp} are bounded; therefore, by (20) both \tilde{u}_k^{\perp} are also bounded. We derive from (19) that

$$(\tilde{u}_k)^1 = \frac{(\tilde{f}_k)^1}{\Lambda - \xi_k - \mu} = \frac{(\tilde{f}_k)^1}{\nu - \mu}.$$

Consider again Equation (19) for k = 2; obviously, $(\tilde{u}_2)^1$ stays bounded as $\mu \to \nu = \Lambda - \xi_1$ and therefore \tilde{u}_2 stays bounded. . For k = 1, $(\tilde{u}_1)^1 = \frac{(\tilde{f}_1)^1}{\nu - \mu} \to \infty$ as $\mu \to \nu = \Lambda - \xi_1$, since $(\tilde{f}_1)^1 = \frac{1}{\xi_1 - \xi_2}((a - \xi_2)f_1^1 + bf_2^1) > 0$; this is the condition which appears in Theorem 4. Then, we simply apply Theorem 3 to (18) for k = 1 and deduce that there exists

 $\delta > 0$, such that, for $|\Lambda - \xi_1 - \mu| = |\nu - \mu| < \delta$, there exists a positive constant C > 0 such that $\tilde{u}_1 \phi \ge \frac{C}{\nu - \mu} \phi$. Now, it follows from $U = P\tilde{U}$, that

$$u_1 = b(\tilde{u}_1 + \tilde{u}_2), \ u_2 = (\xi_1 - a)\tilde{u}_1 + (\xi_2 - a)\tilde{u}_2.$$

As $\nu - \mu \to 0$, since \tilde{u}_2 stays bounded, u_1 behaves as $b(\tilde{u}_1)^1 \phi$, u_2 as $(\xi_1 - a)(\tilde{u}_1)^1 \phi$. More precisely, if $|\mu - \nu|$ small enough

$$(\tilde{u}_1)^1 \ge \frac{K}{\nu - \mu} \text{ if } \mu < \nu \text{ ; } \tilde{u}_1^1 \le -\frac{K}{\nu - \mu} \text{ if } \mu > \nu$$

where K is a positive constant depending only on F.

Remark 4 Indeed, we always assume that b > 0, hence $u_1 > 0$ for $\nu - \mu > 0$ small enough. For the sign of u_2 we remark that $(\xi_1 - a)$ and (d - a) have the same sign.

3.2 Case $\xi_1 = \xi_2$

Consider now the case where the coefficients of the matrix A satisfy (H_A) and

$$D := (a - d)^2 + 4bc = 0.$$

Of course this implies bc < 0 and since b > 0, then c < 0: we have a non cooperative system. Now $\xi_1 = \xi_2 = \xi = \frac{a+d}{2}$. We prove here

Theorem 5 Assume (H'_q) and (H_A) with $(a - d)^2 + 4bc = 0$; assume also that f_1, f_2 satisfy (H'_f) and :

$$\frac{(a-d)}{2}f_1^1 + bf_2^1 > 0.$$

If $\mu < \nu = \Lambda - \xi$, $\nu - \mu < \delta$, small enough, there exists a positive constant γ such that

$$u_1 \ge \frac{\gamma}{\nu - \mu} \phi, \ u_2 \le -\frac{\gamma}{\nu - \mu} \phi.$$

If $\nu = \Lambda - \xi < \mu < \nu + \delta$, (δ small enough), there exists a positive constant γ' such that

$$u_1 \le -\frac{\gamma}{\nu - \mu}\phi, \ u_2 \ge \frac{\gamma}{\nu - \mu}\phi$$

Remark 5 Note that the condition $\frac{(a-d)}{2}f_1^1 + bf_2^1 > 0$ in the theorem above is the same than in theorem $4(\xi_2 - a)f_1^1 < bf_2^1$, since in theorem $5\xi_2 = \xi = \frac{a-d}{2}$.

Prrof The eigenvector associated to eigenvalue ξ is

$$X = \left(\begin{array}{c} b\\ \frac{d-a}{2} \end{array}\right).$$

The vector $X\phi$ is thus an eigenvector for L - A,

$$L(X\phi) - AX\phi = (\Lambda - \xi)X\phi = \nu X\phi.$$

We use again J the associated Jordan matrix and P the change of basis matrix; we have

$$A = PJP^{-1}$$

Here

$$P = \begin{pmatrix} b & \frac{2b}{a-d} \\ \frac{d-a}{2} & 0 \end{pmatrix}, \quad P^{-1} = \frac{1}{b} \begin{pmatrix} 0 & -\frac{2b}{a-d} \\ \frac{a-d}{2} & b \end{pmatrix}$$

$$J = \left(\begin{array}{cc} \xi & 1\\ 0 & \xi \end{array}\right).$$

As above, setting $\tilde{U} = P^{-1}U$ and $\tilde{F} = P^{-1}F$, we derive from System (S)

$$L\tilde{U} = J\tilde{U} + \mu\tilde{U} + \tilde{F}$$

We do not have anymore a decoupled system but

$$\begin{cases} L\tilde{u}_1 = (\xi + \mu)\tilde{u}_1 + \tilde{u}_2 + \tilde{f}_1 \\ L\tilde{u}_2 = + (\xi + \mu)\tilde{u}_2 + \tilde{f}_2 \end{cases}$$
(21)

If $\xi + \mu < \Lambda$ (that is $\mu < \nu$) and if $\tilde{f}_2 = \frac{(a-d)}{2b}f_1 + f_2$ and $\tilde{f}_1 = \frac{-2}{a-d}f_2$ satisfies (H'_f) , hence are in \mathcal{X} and $\frac{(a-d)}{2b}f_1^1 + f_2^1 > 0$. By Theorem 3 applied to the second equation, there exists a constant K > 0, such that $\tilde{u}_2 > \frac{K}{\nu - \mu} \phi$. Hence, for $\nu - \mu$ small enough to any $\tilde{f}_1 \in \mathcal{X}$, $\tilde{u}_2 + \tilde{f}_1 > 0$ and is in X; then again Theorem 3 for the first equation implies that there exists a constant K' > 0, such that $\tilde{u}_1 > \frac{K'}{\nu - \mu} \phi$. Since here a > d., there exists a constant $\gamma > 0$,

$$U = P\tilde{U} = \begin{cases} u_1 = b\tilde{u}_1 + \frac{2b}{a-d}\tilde{u}_2 > \frac{\gamma}{\nu-\mu}\phi\\ u_2 = \frac{d-a}{2}\tilde{u}_1 < -\frac{\gamma}{\nu-\mu}\phi \end{cases}$$

Again $u_1 \to +\infty$ as $\nu - \mu \to 0$ and $u_2 \to -\infty$ as $\nu - \mu \to 0$. If $\mu > \Lambda$ (and $\mu - \nu > 0$ small enough we have analogous calculation with signs reversed.

Remark 6 The results in theorem 5 coincide with those of theorem 4 in the case D = 0.

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