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# Error analysis of some operations involved in the Fast Fourier Transform 

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#### Abstract

We are interested in obtaining error bounds for the classical FFT algorithm in floating-point arithmetic, for the 2-norm as well as for the infinity norm. For that purpose we also give some results on the relative error of the complex multiplication by a root of unity, and on the largest value that can take the real or imaginary part of one term of the FFT of a vector $x$, assuming that all terms of $x$ have real and imaginary parts less than some value $b$.


## 1 Introduction and notation

The Fast Fourier Transform was introduced in 1965 by Cooley and Tukey in its modern form $[4,5,14]$, but can be traced back to Gauss [7]. It is widely used in digital signal processing [15]. It also plays a central role in fast mutiple-precision arithmetic, since it lies at the heart of some of the most efficient big polynomial and big integer multiplication algorithms [21, 13].

Several studies have been devoted to the accuracy of Fast Fourier Transforms and fast algorithms for related transforms such as the DCT [18, 8, 20, 9, 16, 17].

The Discrete Fourier Transform (DFT)

$$
Z=\left(Z_{0}, Z_{1}, \ldots, Z_{N-1}\right)
$$

of

$$
z=\left(z_{0}, z_{1}, \ldots, z_{N-1}\right) \in \mathbb{C}^{N}
$$

is $\left(F_{\omega} z^{t}\right)^{t}$, where

$$
F_{\omega}=\left(\begin{array}{lllll}
1 & 1 & 1 & \cdots & 1 \\
1 & \omega & \omega^{2} & \cdots & \omega^{N-1} \\
1 & \omega^{2} & \omega^{4} & \cdots & \omega^{2(N-1)} \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
1 & \omega^{j} & \omega^{2 j} & \cdots & \omega^{j(N-1)} \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
1 & \omega^{N-1} & \omega^{2(N-1)} & \cdots & \omega^{(N-1)(N-1)}
\end{array}\right)
$$

and $\omega=e^{-2 i \pi / N}$.
Note that some authors use the matrix $(1 / \sqrt{N}) \cdot F_{\omega}$ (in order to make the DFT a unitary transformation).

In this paper, we will consider the radix-2 FFT algorithm, and we will assume that $N=2^{n}$ is a power of 2 . More precisely we will assume that the algorithm being implemented is the one described in pseudocode in Fig. 1, and illustrated, in the case $N=8$ by Fig. 2. The presentation of the Algorithm in Fig. 1 aims at clarity and simplicity: in practice one will seldom implement FFT as presented in that figure, if only to have in-place calculation and consequently save memory, or to parallelize/vectorize the computation. However, if the dependency graph of the operations remains unchanged, our analyses remain valid.

```
/* Radix-2 FFT Algorithm
    */
/* We assume the values omega \([k, j]=\exp \left(-i * j * p i / 2^{\wedge}(k-1)\right)\) are
    precomputed and stored, and reverse ( \(\mathrm{n}, \mathrm{j}\) ) is the n -bit
    number whose binary representation is the mirror image of
    the \(n\)-bit representation of \(j\) */
Function reverse ( \(n, j\) )
    return \(\sum_{\mathrm{k}=0}^{\mathrm{n}-1}\left(\left(\mathrm{j} \&\left(2^{\mathrm{n}}-1\right) \gg \mathrm{k}\right) \bmod 2\right) \ll(\mathrm{n}-1-\mathrm{k})\)
end
Function OneStep ( \(\mathrm{x}, \mathrm{k}, \mathrm{n}\) )
    \(\mathrm{N}=2^{\mathrm{n}}\);
    block_size \(=2^{\mathrm{k}}\);
    N_blocks = N/block_size ; /* Number of independent order-2^k
    FFTs */
    for block_number from 0 to N_blocks -1 do
        first_index = block_number \(\cdot\) block_size;
        for \(j\) from 0 to block_size \(/ 2-1\) do
            \(j 1=j+\) first_index;
            \(\mathrm{j} 2=\mathrm{j} 1+\) block_size \(/ 2\);
            \(y[j 1]=x[j 1]+\) omega \([k, j] \cdot x[j 2] ;\)
            \(y[j 2]=x[j 1]-\) omega \([k, j] \cdot x[j 2] ;\)
        end
        return y
    end
end
Function FFT(x, n)
    \(\mathrm{N}=2^{\mathrm{n}}\);
    for j from 0 to \(\mathrm{N}-1\) do
        \(y[j]=x[\operatorname{reverse}(n, j)] ;\)
    end
    for k from 1 to n do
        \(\mathrm{y}=\) OneStep ( \(\mathrm{y}, \mathrm{k}, \mathrm{n}\) );
    end
    return y
end
```

Figure 1: Pseudocode for the radix-2 FFT algorithm.


Figure 2: The various computations performed during an 8-point FFT. The first step can be viewed as 4 independent 2-point FFTs, and the first two steps constitute two independent 4 -point FFTs.

We assume that we use a radix-2, precision- $p$, floating-point arithmetic with unbounded exponent range (which implies that the results presented in the paper hold in "real life" floating-point arithmetic provided that overflows and underflows do not occur). If $x \in \mathbb{R}$, define $\mathrm{RN}(x)$ as $x$ rounded to nearest. This is the default rounding mode in IEEE 754 arithmetic [10], so that when the instruction $c=a * b$ appears in a program, what is effectively computed is $c=\operatorname{RN}(a b)$. We have

$$
\begin{equation*}
\frac{|x-\mathrm{RN}(x)|}{|x|} \leqslant \frac{u}{1+u}<u \tag{1}
\end{equation*}
$$

where $u=2^{-p}$ is called the rounding unit. We also have

$$
\begin{equation*}
|x-\mathrm{RN}(x)| \leqslant \frac{1}{2} \operatorname{ulp}(x) \tag{2}
\end{equation*}
$$

where the ulp function (ulp is an acronym for unit in the last place) is defined as

$$
\operatorname{ulp}(x)= \begin{cases}0 & \text { if } x=0 \\ 2^{\left\lfloor\log _{2}|x|\right\rfloor-p+1} & \text { otherwise } .\end{cases}
$$

One easily notices that if $\operatorname{ulp}(x) \cdot 2^{p-1} \leqslant|x| \leqslant \operatorname{ulp}(x) \cdot\left(2^{p-1}+1 / 4\right)$, then $\mathrm{RN}(x)=\operatorname{ulp}(x) \cdot 2^{p-1}$, and $|x-\mathrm{RN}(x)| \leqslant \frac{1}{4} \mathrm{ulp}(x)$. This leads us to the definition of another "ulp" function:

$$
\operatorname{ulp}^{*}(x)= \begin{cases}\operatorname{ulp}(x) & \text { if }|x|>\left(2^{p-1}+\frac{1}{4}\right) \cdot \operatorname{ulp}(x) \\ \frac{1}{2} \operatorname{ulp}(x) & \text { otherwise }\end{cases}
$$

for which we always have $|x-\mathrm{RN}(x)| \leqslant \frac{1}{2} \mathrm{ulp}^{*}(x)$. Of course, ulp* is almost always equal to ulp, but in the iterative algorithm of Section 5 , where we manipulate values that are frequently just above a power of 2 , using ulp* instead of ulp makes a non-negligible difference.

In Section 5 we will also use the notation $\mathrm{RZ}(x)$ for $x$ rounded towards zero. Functions RN (for all inputs) and RZ (for positive inputs) are increasing functions: if $0 \leqslant t_{1} \leqslant t_{2}$ then $\mathrm{RZ}\left(t_{1}\right) \leqslant \mathrm{RZ}\left(t_{2}\right)$ and $\mathrm{RN}\left(t_{1}\right) \leqslant \mathrm{RN}\left(t_{2}\right)$. Note that $\operatorname{ulp}(x)$ and ulp* $(x)$ are increasing functions of $|x|$. Hence, if we know a bound $B$ on $|x|$, we can deduce a bound $(1 / 2) \operatorname{ulp}^{*}(B) \leqslant(1 / 2) \operatorname{ulp}(B)$ on $|\operatorname{RN}(x)-x|$.

If $z=\left(z_{0}, z_{1}, \ldots, z_{N-1}\right) \in \mathbb{C}^{N}$, we will use the standard notations

$$
\|z\|_{2}=\sqrt{\left|z_{0}\right|^{2}+\left|z_{1}\right|^{2}+\cdots+\left|z_{N-1}\right|^{2}}
$$

(2-norm) and

$$
\|z\|_{\infty}=\max _{i=0, \ldots, N-1}\left|z_{i}\right| .
$$

(infinity norm). We will also use the following notation:

$$
\|z\|_{\infty}^{\perp}=\max _{i=0, \ldots, N-1}\left\{\max \left(\left|\Re\left(z_{i}\right)\right|,\left|\Im\left(z_{i}\right)\right|\right)\right\}
$$

We remind the classical inequalities

$$
\begin{equation*}
\|z\|_{\infty} \leqslant\|z\|_{2} \leqslant \sqrt{N} \cdot\|z\|_{\infty} \tag{3}
\end{equation*}
$$

$$
\begin{equation*}
\|z\|_{\infty}^{\perp} \leqslant\|z\|_{\infty} \leqslant \sqrt{2} \cdot\|z\|_{\infty}^{\perp} \tag{4}
\end{equation*}
$$

Choosing which norm should be used for expressing bounds on numerical errors depends much on the problem being dealt with. For expressing the error of the FFT, and assuming $x$ is the input, $X$ is the exact result and $\hat{X}$ is the computed result, most authors give a bound on

$$
\frac{\|X-\hat{X}\|_{2}}{\|X\|_{2}}
$$

also called root mean square (RMS) relative error. The reason is twofold: first, the 2-norm appears naturally in many signal processing applications, and second, the well-known relation $\|X\|_{2}=\sqrt{N} \cdot\|x\|_{2}$ makes error bounds in terms of 2-norm easier to obtain than error bounds in terms of infinity norms. However, for applications such as the multiplication of big integers (or large polynomials with integer coefficients), we know that the components of the final "exact", theoretical, result of a calculation must be integers. We wish to retrieve these integers by rounding to the nearest integer the coefficients of the actually computed result. For this strategy to work properly, we must be certain that these coefficients are within distance less than $1 / 2$ from the exact value: in such a case, we need a bound on $\|X-\hat{X}\|_{\infty}^{\perp}$, given a bound on $\|x\|_{\infty}^{\perp}$.

The set of the floating-point numbers is invariant through a multiplication by a power of 2 , and if $t=2^{k} x$ then $\mathrm{RN}(t)=2^{k} \mathrm{RN}(x)$. A consequence of this is that if $X$ is the exact DFT of $x$, if $\hat{X}$ is the computed value of that DFT using the FFT algorithm in floating-point arithmetic, then if we compute with the same algorithm the DFT of $2^{k} x$, we will obtain $2^{k} \hat{X}$, so that the relative error will be the same. Therefore, if we wish to bound the relative error of the FFT algorithm, it suffices to focus (for instance) on input values $x$ such that $1 / 2 \leqslant\|x\|_{\infty}^{\perp}<1$.

Let us now consider error bounds proposed in the literature. We start with the results based on the 2 -norm.

Just one year after the publication of the seminal paper by Cooley and Tukey, Gentleman and Sande [6] gave the following result (adapted here to radix-2 FFT and correctly rounded floating-point arithmetic)

Theorem 1 ([6]). Assume radix-2, precision-p arithmetic, with rounding unit $u=2^{-p}$. Let $\hat{X}$ be the computed $2^{n}$-point FFT of $x \in \mathbb{C}^{2^{n}}$, and let $X$ be the exact value. Then

$$
\frac{\|X-\hat{X}\|_{2}}{\|X\|_{2}} \leqslant 8.48 \cdot n \cdot u
$$

Again adapted to the modern context of correctly rounded arithmetic, and assuming that the real and imaginary parts of the roots of unity are rounded to nearest, Theorem 1 of [18] gives

Theorem 2 ([18]). Assume radix-2, precision-p arithmetic, with rounding unit $u=2^{-p}$. Let $\hat{X}$ be the computed $2^{n}$-point FFT of $x \in \mathbb{C}^{2^{n}}$, and let $X$ be the
exact value. Then

$$
\frac{\|X-\hat{X}\|_{2}}{\|X\|_{2}} \leqslant[n \cdot(5+\sqrt{2})-5] \cdot u+\mathcal{O}\left(u^{2}\right)
$$

In his book [9], Higham proves the following result.
Theorem 3 ([9]). Assume radix-2, precision-p arithmetic, with rounding unit $u=2^{-p}$. Assume the roots of unity used in the algorithm are known with error less than or equal to $\mu$. Let $\hat{X}$ be the computed $2^{n}$-point $F F T$ of $x \in \mathbb{C}^{2^{n}}$, and let $X$ be the exact value. Then

$$
\frac{\|X-\hat{X}\|_{2}}{\|X\|_{2}} \leqslant \frac{n \eta}{1-n \eta}
$$

where

$$
\eta=\mu+\frac{4 u}{1-4 u} \cdot(\sqrt{2}+\mu) .
$$

After having proved that the relative error of the naive complex multiplication algorithm is bounded by $\sqrt{5} \cdot u$, Percival [16] deduces the following theorem. The proof of the bound $\sqrt{5} \cdot u$ in [16] turned out to be slightly incorrect: see [2] for a complete proof.

Theorem 4 ([16]). Assume radix-2, precision-p arithmetic, with rounding unit $u=2^{-p}$. Assume the roots of unity used in the algorithm are known with error less than or equal to $\mu$. Let $\hat{X}$ be the computed $2^{n}$-point FFT of $x \in \mathbb{C}^{2^{n}}$, and let $X$ be the exact value. Then

$$
\frac{\|X-\hat{X}\|_{2}}{\|X\|_{2}} \leqslant(1+u)^{n} \cdot(1+u \sqrt{5})^{n} \cdot(1+\mu)^{n}-1
$$

Assuming $n \ll 1 / u$ (which always holds in practice), and assuming that the real and imaginary parts of the roots of unity are rounded to nearest, the bound given by Theorem 2 is around $(6.41 \cdot n-5) \cdot u$, the bound given by Theorem 3 is around $6.36 \cdot n \cdot u$, and the bound given by Theorem 4 is around $3.94 \cdot n \cdot u$.

Calvetti [3] and Schatzman [20] take a different approach to the roundoff error analysis of the FFT. They try to estimate the statistical distribution of the error on the result. They end up with an error that grows like $\sqrt{n}$. We will not consider that approach here, because we want to obtain sure error bounds.

Of course, from bounds involving the 2-norm, one can deduce bounds involving the other norms, using (3) and (4). For instance, from

$$
\begin{equation*}
\frac{\|X-\hat{X}\|_{2}}{\|X\|_{2}} \leqslant B \tag{5}
\end{equation*}
$$

one can deduce

$$
\begin{equation*}
\frac{\|X-\hat{X}\|_{\infty}}{\|X\|_{\infty}} \leqslant B \sqrt{N} \tag{6}
\end{equation*}
$$

$$
\begin{equation*}
\|X-\hat{X}\|_{\infty}^{\perp} \leqslant B \cdot N \cdot \sqrt{2} \cdot\|x\|_{\infty}^{\perp} \tag{7}
\end{equation*}
$$

The bounds (6) and (7) are the best that one can deduce from (5). However, they are not necessarily the best that one can deduce from a direct analysis of the algorithm in terms of infinity norms.

Henrici [8] gives an analysis based on the infinity norm. He shows the following result.

Theorem 5. (Theorem 13.1c of [8]) Assume radix-2, precision-p arithmetic, with rounding unit $u=2^{-p}$. Assume that the roots of unity used in the algorithm are known with error less than or equal to $\mu$, and that the complex arithmetic operations are performed with relative error bounded by the same constant $\mu$. Let $\hat{X}$ be the computed $2^{n}$-point FFT of $x \in \mathbb{C}^{2^{n}}$, and let $X$ be the exact value. Then

$$
\|\hat{X}-X\|_{\infty} \leqslant 2^{n}(2 n+1) \cdot \mu \cdot\|x\|_{\infty}+\mathcal{O}\left(u^{2}\right)
$$

For several recent reasons, it is worth reexamining the problem of finding tight error bounds on the computation of Fast Fourier Transforms in floatingpoint arithmetic:

- first, before Percival's paper [16], the relative error bound $\sqrt{5} \cdot u$ on the naive complex multiplication algorithm was not known;
- the FMA instruction, which evaluates expressions of the form $a b+c$ with one rounding only, is now widespread: it is specified by the IEEE-754 Standard on Floating-Point Arithmetic [10], and available in all recent general purpose processors of commercial significance. It was recently shown [11] that with an FMA, the relative error bound on the complex multiplication becomes $2 u$;
- when implementing the multiplications by roots of unity that occur in the FFT, we approximate "exact" multiplications $\omega \cdot x$ by "rounded" multiplications of $\hat{\omega}$ by $x$, where $\hat{\omega}$ approximates $\omega$, and is a number whose real and imaginary parts are floating-point numbers. Most analyses use a global error bound on these approximations: this simplifies the study and makes it possible to express the error bound on the FFT as a simple expression. However, the approximation error of the multiplication depends much on $\omega$ (it is even rather frequently null: values $\omega= \pm 1, \pm i$ are not so rare), and since the values of $\omega$ are known in advance, one can try to obtain better, if less simple and elegant, error bounds.

The sequel of the paper is organized as follows. We first bound the relative error that can occur when multiplying a complex number by a root of unity in floating-point arithmetic. To be able to use (1) or (2) to bound the error of the floating-point operations, we need to bound, as tightly as possible, the largest value that a variable can take at Step $k$ of the FFT algorithm. This is done in Section 3. These results are used to analyze Step $k$ of the FFT algorithm in

Section 4.1 (similarly to what Percival did in [16], but slightly more accurately and with more details). Then, we derive a relative error bound (for the 2-norm) of the FFT algorithm in Section 4.2.

Finally, Section 5 gives an iterative algorithm that provides an error bound in terms of the $\|\cdot\|_{\infty}^{\perp}$ norm, sometimes tighter than what one could deduce from the known bounds in terms of 2-norm and (7).

## 2 Relative error of the multiplication of a complex number by a root of unity

In this section, we try to bound as tightly as possible the error resulting from the approximation of $\omega x$, where $\omega$ is a root of unity and $x$ a floating-point number, by $\operatorname{Alg}(\hat{\omega}, x)$, where $\hat{\omega}=\mathrm{RN}(\Re(\omega))+i \cdot \mathrm{RN}(\Im(\omega))$ and $A l g$ is a complex multiplication algorithm that is adequately chosen. Let us first consider the error resulting from the approximation of $\omega$ by $\hat{\omega}$.

### 2.1 Relative error of the approximation of a complex number in floating-point arithmetic

### 2.1.1 Case of an arbitrary complex number

Let $z \in \mathbb{C}, z=x+i y$, with $x, y \in \mathbb{R}$. The complex number $z$ is approximated by $\hat{z}=\hat{x}+i \hat{y}$, with $\hat{x}=\mathrm{RN}(x)$ and $\hat{y}=\mathrm{RN}(y)$. We will denote $\hat{z}=\mathrm{RN}(z)$. The componentwise relative error committed when approximating $z$ by $\hat{z}$ is

$$
\max \left\{\left|\frac{x-\hat{x}}{x}\right|,\left|\frac{y-\hat{y}}{y}\right|\right\} \leqslant \frac{u}{1+u}<u
$$

The normwise error committed when approximating $z$ by $\hat{z}$ is

$$
\begin{equation*}
\left|\frac{z-\hat{z}}{z}\right| \leqslant \frac{u}{1+u}<u \tag{8}
\end{equation*}
$$

### 2.1.2 Case of a root of unity

The bound (8) can be significantly improved when the absolute value of $z$ is 1 (which is the case when $z$ is a root of 1 ). In such a case, since $|x|$ and $|y|$ are less than or equal to 1 , we have $|x-\hat{x}| \leqslant u / 2$ and $|y-\hat{y}| \leqslant u / 2$, so that

$$
\left|\frac{z-\hat{z}}{z}\right|^{2}=\frac{(x-\hat{x})^{2}+(y-\hat{y})^{2}}{1} \leqslant \frac{u^{2}}{2}
$$

so that

$$
\begin{equation*}
\left|\frac{z-\hat{z}}{z}\right| \leqslant \frac{u}{\sqrt{2}} \tag{9}
\end{equation*}
$$

Of course, one should not forget that the $2^{n d}$ and $4^{\text {th }}$ roots of 1 are exactly represented in floating-point arithmetic.

For a given floating-point format (i.e., a given precision $p$ ) and a given $N$, one can also compute in advance the largest relative error attained when approximating an $N^{t h}$ root of 1 . In several cases (especially when $N$ is not too large), this leads to bounds significantly smaller than (9). For instance, if $N=128$, in single-precision/binary32 arithmetic (i.e., $p=24$ ), the largest relative error is $0.500 \cdot u$, which is significantly smaller than $(\sqrt{2} / 2) \cdot u \approx 0.707 \cdot u$. Examples are given in Table 1.

Table 1: Largest relative error attained when approximating an $N^{t h}$ root of 1 in precision- $p$, binary, floating-point arithmetic. All errors in this table have been rounded up.

| $N$ | 2 or 4 | 8 | 16 | 32 | 128 | 2048 | 32768 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $p=24$ | 0 | $0.288 \cdot u$ | $0.487 \cdot u$ | $0.500 \cdot u$ | $0.500 \cdot u$ | $0.633 \cdot u$ | $0.707 \cdot u$ |
| $p=53$ | 0 | $0.616 \cdot u$ | $0.616 \cdot u$ | $0.616 \cdot u$ | $0.616 \cdot u$ | $0.641 \cdot u$ | $0.697 \cdot u$ |
| $p=113$ | 0 | $0.692 \cdot u$ | $0.692 \cdot u$ | $0.692 \cdot u$ | $0.692 \cdot u$ | $0.692 \cdot u$ | $0.692 \cdot u$ |

In the following, $\Delta_{z}$ is a bound on the relative error committed when approximating $z$ by $\hat{z}=\mathrm{RN}(\Re(z))+i \operatorname{RN}(\Im(z))$.

### 2.2 Multiplication of a complex number by a root of 1

Normwise relative error bounds on complex multiplication have been derived by Brent et al. [2] for the "naive" algorithm (10), and by Jeannerod et al. [11] assuming an FMA instruction is available, i.e., using (11) or one of the algorithms derived from (11) using symmetries. Let $a+i b$ be a complex number, with $a, b$ floating-point numbers. We wish to evaluate $z=x+i y=(a+i b) \cdot \omega$, where $\omega=c+i s$ is a root of 1 . Since, in general, $c$ and $s$ are not floating-point numbers, they are approximated by $\hat{c}=\mathrm{RN}(c)$ and $\hat{s}=\mathrm{RN}(s)$. The normwise relative error due to that approximation has been studied in Section 2.1.

Let $\hat{z}=\hat{x}+i \hat{y}$ be the computed product. We consider two cases.

- Naive multiplication

$$
\left\{\begin{array}{l}
\hat{x}=\operatorname{RN}(\operatorname{RN}(a \hat{c})-\operatorname{RN}(b \hat{s})),  \tag{10}\\
\hat{y}=\operatorname{RN}(\operatorname{RN}(a \hat{s})+\operatorname{RN}(b \hat{c})) .
\end{array}\right.
$$

- Multiplication with an FMA

$$
\left\{\begin{array}{l}
\hat{x}=\operatorname{RN}(a \hat{c}-\operatorname{RN}(b \hat{s})),  \tag{11}\\
\hat{y}=\operatorname{RN}(a \hat{s}+\operatorname{RN}(b \hat{c})) .
\end{array}\right.
$$

Define $z^{*}=(a+i b) \hat{\omega}$, with $\hat{\omega}=\hat{c}+i \hat{s}$. If the naive multiplication is used then $\left|z-z^{*}\right| \leqslant u \sqrt{5} \cdot\left|z^{*}\right|$ (see [2]), and if multiplication with FMA is used
then $\left|z-z^{*}\right| \leqslant 2 u \cdot\left|z^{*}\right|$ (see [11]). Note that (11) is interesting only when we want to minimize normwise errors (which is the case here). If one wishes to minimize componentwise errors with an FMA instruction, there are better solutions, based on Kahan's algorithm for evaluating expressions of the form $a c-b d[11,12]$. In the following, let us define

$$
\rho_{\times}= \begin{cases}u \sqrt{5} & \text { if }(10) \text { is used } \\ 2 u & \text { if }(11) \text { is used }\end{cases}
$$

We have,

$$
|z-\hat{z}| \leqslant\left|z-z^{*}\right|+\left|z^{*}-\hat{z}\right|
$$

Let us first bound $\left|z-z^{*}\right|$. We have,

$$
\begin{aligned}
\left|z-z^{*}\right| & =|(a+i b) \cdot[(\hat{c}+i \hat{s})-(c+i s)]| \\
& =|a+i b| \cdot\left|\frac{(\hat{c}+i \hat{s})-(c+i s)}{c+i s}\right| \\
& \leqslant|z| \cdot \Delta_{\omega} .
\end{aligned}
$$

We also have $\left|z^{*}-\hat{z}\right| \leqslant \rho_{\times} \cdot\left|z^{*}\right|$, so that

$$
\left|\frac{z^{*}-\hat{z}}{z}\right|=\left|\frac{z^{*}-\hat{z}}{z^{*}}\right| \cdot\left|\frac{z^{*}}{z}\right|=\left|\frac{z^{*}-\hat{z}}{z^{*}}\right| \cdot\left|\frac{\hat{\omega}}{\omega}\right| \leqslant \rho_{\times} \cdot\left|\frac{\hat{\omega}}{\omega}\right| .
$$

Hence $\hat{z}$ approximates $z$ with a relative error bounded by

$$
\begin{equation*}
\Delta_{\omega}+\rho_{\times} \cdot\left|\frac{\hat{\omega}}{\omega}\right| \leqslant \Delta_{\omega}+\rho_{\times} \cdot\left(1+\Delta_{\omega}\right) \tag{12}
\end{equation*}
$$

The bound (12) is rather tight. For instance, in binary64/double precision arithmetic (i.e., $p=53$ ), if we use multiplication with an FMA (i.e., (11)), with $\omega=\exp \left(-7133 \pi / 2^{20}\right)$ and $z=5495961505303309 / 2^{52}+i \cdot 4506137113525543 / 2^{42}$, the relative error is $2.455 u$, whereas the bound given by (12) is $2.460 u$.

## 3 Largest values that can occur when computing the FFT of a vector

Assuming that the chosen rounding mode is round-to-nearest, when we perform an arithmetic operation $a \top b$, where $a$ and $b$ are floating-point numbers, what is actually computed is $\mathrm{RN}(a \top b)$. Using (1) and the fact that RN is an increasing function, from a bound $M$ on $|a \top b|$, we can deduce a bound on the rounding error committed when performing that operation:

$$
|\operatorname{RN}(a \top b)-(a \top b)| \leqslant \frac{1}{2} \operatorname{ulp}(M) \leqslant u \cdot M
$$

We aim at using that property to bound the rounding errors occurring when performing FFTs. This requires bounding all intermediate values that appear in the calculation. This is what we deal with in this section.

### 3.1 A simple bound

Assume that $Z=\left(Z_{0}, Z_{1}, \ldots, Z_{N-1}\right)$ is the order- $N=2^{n}$ DFT of $z=\left(z_{0}, z_{1}, \ldots, z_{N-1}\right)$. We have $\|Z\|_{2}=\sqrt{N} \cdot\|z\|_{2}$, therefore

$$
\|Z\|_{\infty} \leqslant \sqrt{N} \cdot\|z\|_{2} \leqslant N \cdot\|z\|_{\infty}
$$

Note that $\|Z\|_{\infty}$ can be equal to $N \cdot\|z\|_{\infty}$ : just consider $z=(1,1,1, \ldots, 1)$, for which we have $Z=(N, 0,0,0, \ldots, 0)$. Hence, if the real and imaginary parts of the terms $z_{i}$ are of absolute value less than $b$, then the real and imaginary parts of the terms $Z_{i}$ will be of absolute value less than $B=N b \sqrt{2}$.

Since the first $k$ steps of an order- $N$ FFT can be viewed as $N / 2^{k}$ independent FFTs of order $2^{k}$, we deduce that the intermediate values computed at Step $k$ have absolute values of the real and imaginary parts less than $2^{k} b \sqrt{2}$.

As we are going to see, with a significantly more involved reasoning, one can replace the constant $\sqrt{2} \approx 1.414$ by $4 / \pi \approx 1.273$.

### 3.2 Some improvement

Let us now try to obtain a tighter bound.
Let $X=\left(X_{0}, X_{1}, \ldots, X_{N-1}\right)$ be the DFT of $x=\left(x_{0}, x_{1}, \ldots, x_{N-1}\right)$. We have

$$
X_{j}=x_{0}+\omega^{j} x_{1}+\omega^{2 j} x_{2}+\cdots+\omega^{(N-1) j} x_{N-1}
$$

with $\omega=\exp (-2 i \pi / N)$.
Consider a vector $x$ that maximizes the absolute value of the real part of $X_{j}$ under the constraints $\|x\|_{\infty}^{\perp} \leqslant b$ (the reasoning is straightforwardly similar if we want to maximize the imaginary part). Without loss of generality we assume that the real part of $X_{j}$ is nonnegative. Since all the $x_{k}$ can be chosen independently, we maximize the real part of $X_{j}$ by maximizing separately all the terms $\Re\left(\omega^{j k} x_{k}\right)=\cos (2 j k \pi / N) \Re\left(x_{k}\right)+\sin (2 j k \pi / N) \Im\left(x_{k}\right)$, i.e., by choosing $\Re\left(x_{k}\right)=b \cdot \operatorname{sign}\left(\cos (2 j k \pi / N)\right.$, and $\Im\left(x_{k}\right)=b \cdot \operatorname{sign}(\sin (2 j k \pi / N)$, so that the maximum value of $\left|\Re\left(X_{j}\right)\right|$ is $b \cdot S_{j}$, where

$$
S_{j}=\sum_{k=0}^{N-1}(|\cos (2 j k \pi / N)|+|\sin (2 j k \pi / N)|)
$$

Hence the bound we are looking for is $K_{N}=\max _{j=0 \ldots N-1} S_{j}$. Table 2 gives the values of $K_{N}$ and $K_{N} / N$ for the first powers of 2 .

Let us show that we always have $K_{N} \leqslant \frac{4}{\pi} \cdot N$ and $4 / \pi$ is optimal.
Let $m \in \mathbb{N} \backslash\{0\}$, we have

$$
\frac{K_{m}}{m}=\frac{1}{m} \max _{j=0, \ldots, m-1}\left\{\sum_{k=0}^{m-1}(|\cos (2 j k \pi / m)|+|\sin (2 j k \pi / m)|)\right\}
$$

Table 2: First values of $K_{N}$ and $K_{N} / N$. If the terms $x_{k}$ have the absolute values of their real and imaginary parts less than or equal to $b$, then the terms $X_{k}$ have the absolute values of their real and imaginary parts less than or equal to $b K_{N}$, and that bound is attained.

| $N$ | $K_{N}$ | $K_{N} / N$ |
| :--- | :--- | :--- |
| 8 | $4+4 \sqrt{2}=9.6568 \cdots$ | $1.20710678 \cdots$ |
| 16 | $20.10935 \cdots$ | $1.2568348730 \cdots$ |
| 32 | $40.6126815 \cdots$ | $1.269146298451 \cdots$ |
| 64 | $81.421870499 \cdots$ | $1.272216726561699 \cdots$ |
| 128 | $162.9419354883 \cdots$ | $1.2729838710026031 \cdots$ |
| 256 | $325.932960826184 \cdots$ | $1.27317562822728390 \cdots$ |
| 512 | $651.890465652999852 \cdots$ | $1.273223565728515337 \cdots$ |
| 1024 | $1303.7932031908053959 \cdots$ | $1.2732355499910208944 \cdots$ |
| 2048 | $2607.592542309575146472 \cdots$ | $1.273238546049597239488 \cdots$ |
| 4096 | $5215.1881525813276653152 \cdots$ | $1.2732392950638006995398 \cdots$ |
| 8192 | $10430.37783914351841639453 \cdots$ | $1.27323948231732402543878 \cdots$ |
| $\infty$ |  | $4 / \pi=1.2732395447351626861 \cdots$ |

We now define, for all $m, j \in \mathbb{N}, m \neq 0$,

$$
\gamma_{m}^{j}=\frac{1}{m} \sum_{k=0}^{m-1}(|\cos (2 j k \pi / m)|+|\sin (2 j k \pi / m)|)
$$

For all $x \in \mathbb{R}$, let $f(x):=|\cos (x)|+|\sin (x)|$. The function $f$ is $(\pi / 2)$-periodic. Since $1 \leqslant f(x) \leqslant \sqrt{2} / 2$ for all $x$, we have, for all $m, j \in \mathbb{N}, m \neq 0$,

$$
\begin{equation*}
1 \leqslant \gamma_{m}^{j} \leqslant \frac{\sqrt{2}}{2}, \text { hence } 1 \leqslant \frac{K_{m}}{m} \leqslant \frac{\sqrt{2}}{2} \tag{13}
\end{equation*}
$$

Lemma 1. For all $m, j \in \mathbb{N} \backslash\{0\}$ such that $(j, m)=1$, we have $\gamma_{m}^{j}=\gamma_{m}^{1}$.
Proof. Since $j$ and $m$ are relatively prime, we have

$$
\{k \bmod m, k=0, \ldots, m-1\}=\{j k \bmod m, k=0, \ldots, m-1\}
$$

Hence,

$$
\gamma_{m}^{j}=\frac{1}{m} \sum_{x \in\left\{\frac{j k}{m}, 0 \leqslant k \leqslant m-1\right\}} f(2 \pi x)=\frac{1}{m} \sum_{x \in\left\{\frac{k}{m}, 0 \leqslant k \leqslant m-1\right\}} f(2 \pi x)=\gamma_{m}^{1}
$$

Lemma 2. For all $m, j \in \mathbb{N} \backslash\{0\}$, we have $\gamma_{m}^{j}=\gamma_{m /(j, m)}^{j /(j, m)}=\gamma_{m /(j, m)}^{1}$.

Proof. Let $d=(j, m), j=d j^{\prime}, m=d m^{\prime}$ with $\left(j^{\prime}, m^{\prime}\right)=1$, we have for all $k, \ell \in \mathbb{N}$,

$$
f\left(\frac{2 j \pi}{m}\left(k+\ell m^{\prime}\right)\right)=f\left(\frac{2 j^{\prime} k \pi}{m^{\prime}}+2 j^{\prime} \ell \pi\right)=f\left(\frac{2 j^{\prime} k \pi}{m^{\prime}}\right)
$$

since $f$ is $(\pi / 2)$-periodic. Then, it comes
$\gamma_{m}^{j}=\frac{1}{m} \sum_{k=0}^{m-1} f\left(\frac{2 j k \pi}{m}\right)=\frac{1}{m} \sum_{\ell=0}^{d-1} \sum_{k=0}^{m^{\prime}-1} f\left(\frac{2 j\left(k+\ell m^{\prime}\right) \pi}{m}\right)=\frac{d}{m} \sum_{k=0}^{m^{\prime}-1} f\left(\frac{2 j^{\prime} k \pi}{m^{\prime}}\right)=\gamma_{m^{\prime}}^{j^{\prime}}$.
The second equality is a consequence of Lemma 1.
Lemma 3. The sequence $\left(\gamma_{4 m}^{1}\right)_{m \in \mathbb{N}}$ is increasing and tends to $4 / \pi$ as $m$ tends to $+\infty$.

Proof. We have for all $k, \ell \in \mathbb{N}$,

$$
f\left(\frac{2 \pi}{4 m}(k+\ell m)\right)=f\left(\frac{j k \pi}{2 m}+\frac{\ell \pi}{2}\right)=f\left(\frac{j k \pi}{2 m}\right)
$$

since $f$ is $(\pi / 2)$-periodic. Therefore, for all $m \in \mathbb{N} \backslash\{0\}$, we have

$$
\gamma_{4 m}^{1}=\frac{1}{4 m} \sum_{k=0}^{4 m-1} f\left(\frac{2 k \pi}{4 m}\right)=\frac{1}{4 m} \sum_{\ell=0}^{3} \sum_{k=0}^{m-1} f\left(\frac{(k+\ell m) \pi}{2 m}\right)=\frac{1}{m} \sum_{k=0}^{m-1} f\left(\frac{k \pi}{2 m}\right)
$$

Hence, $\left(\frac{\pi}{2} \gamma_{4 m}^{1}\right)_{m \in \mathbb{N}}$ is a sequence of Riemann sums which tends to $\int_{0}^{\pi / 2} f(x) \mathrm{d} x=$ 2 as $n$ tends to $\infty$. Moreover, since $f$ is concave over $[0, \pi / 2$ ], this sequence of Riemann sums is increasing [1, Thm 3A].

Corollary 1. For all $n \in \mathbb{N}$, we have

$$
\frac{1}{2^{n}} K_{2^{n}} \leqslant \frac{4}{\pi} \text { and } \lim _{n \rightarrow \infty} \frac{1}{2^{n}} K_{2^{n}}=\frac{4}{\pi}
$$

Proof. We can assume $n \geqslant 1$ since we know that $K_{1}=1$. It follows from Lemma 2 that there exists $n_{0} \geqslant 1$ such that $\max _{j=1, \ldots, 2^{n}} \gamma_{2^{n}}^{j}=\gamma_{2^{n_{0}}}^{1}$. Thus, $K_{2^{n}} / 2^{n}=\max \left(\gamma_{2^{n}}^{0}, \gamma_{2^{n_{0}}}^{1}\right)=\max \left(1, \gamma_{2^{n_{0}}}^{1}\right)=\gamma_{2^{n_{0}}}^{1}$ thanks to Equation (13). From Lemma 3 and $\gamma_{2}^{1}=1$, we get $K_{2^{n}} / 2^{n}=\gamma_{2^{n_{0}}}^{1} \leqslant 4 / \pi$. Moreover, by definition of $K_{2^{n}}$, we have $\gamma_{2^{n}}^{1} \leqslant K_{2^{n}} / 2^{n}$. The last two inequalities and Lemma 3 imply $\lim _{n \mapsto \infty} K_{2^{n}} / 2^{n}=4 / \pi$.

All this gives the following result.
Theorem 6. Let $Z=\left(Z_{0}, Z_{1}, \ldots, Z_{N-1}\right)$ be the order- $N=2^{n}$ Discrete Fourier Transform of $z=\left(z_{0}, z_{1}, \ldots, z_{N-1}\right)$. If the real and imaginary parts of the terms $z_{i}$ are of absolute value less than or equal to $b$, then the real and imaginary parts of the terms $Z_{i}$ are of absolute value less than or equal to

$$
\begin{equation*}
\frac{4}{\pi} \cdot N \cdot b \tag{14}
\end{equation*}
$$

and the constant $4 / \pi$ in (14) is optimal.

An important consequence, that will be useful in the sequel of this paper is that since the first $k$ steps of an order- $N$ FFT can be viewed as $N / 2^{k}$ independent FFTs of order $2^{k}$, the intermediate values computed at Step $k$ have absolute values of the real and imaginary parts less than $2^{k+2} b / \pi$.

## 4 Bound on the relative error of the FFT for the 2-norm

Let us now use the error bounds on the multiplication by a root of unity, given in Section 2, to bound the relative error of the FFT for the 2-norm. For that purpose, we will first consider Step $k$ of the FFT algorithm.

### 4.1 Step $k$ of the FFT

This section uses a reasoning presented by Percival [16]. We present it with more detail, and extract more information from it by not uniformly bounding the relative errors of the complex multiplications by roots of unity. At Step $k$ $(k=1, \ldots, n)$ of the $N=2^{n}$-point FFT, the $2^{k}$-th roots of 1 are used. Define $\Delta_{k}^{\max }$ as the largest value of $\Delta_{\omega}$, where $\omega$ is a $2^{k}$-th root of 1 . Notice that when $k=1$ or 2 , the $2^{k}$-th root of 1 are exactly represented, and multiplication by them is errorless. From this and (12), the complex products performed at Step $k$ have a relative error bounded by

$$
g_{k}:=\left\{\begin{array}{l}
0 \text { if } k=1,2 \\
\Delta_{k}^{\max }+\rho_{\times} \cdot\left(1+\Delta_{k}^{\max }\right) \text { otherwise }
\end{array}\right.
$$

For instance, for $k \geqslant 3$,

$$
\begin{equation*}
g_{k} \leqslant \frac{\sqrt{2}}{2} u+\rho_{\times} \cdot\left(1+\frac{\sqrt{2}}{2} u\right) . \tag{15}
\end{equation*}
$$

Equation (15) can be interesting for obtaining a bound on the final error of the FFT as a closed form, however, one will get tighter bounds by individually computing the terms $g_{k}$. Now, Step $k$ of the FFT of order $n$ can be viewed as $n / 2$ parallel combinations of the form

$$
\binom{x_{0}}{x_{1}} \rightarrow\binom{x_{0}+\omega x_{1}}{x_{0}-\omega x_{1}}
$$

Let us denote $\widehat{\omega x_{1}}=$ computed value of $\omega x_{1}$ (with relative error bounded by $\left.g_{k}\right)$.

We have

$$
\begin{aligned}
& \left|\widehat{\omega x_{1}}-\omega x_{1}\right| \leqslant\left|x_{1}\right| \cdot g_{k}, \\
& \left|\operatorname{RN}\left(x_{0}-\widehat{\omega x_{1}}\right)-\left(x_{0}-\widehat{\omega x_{1}}\right)\right| \leqslant u \cdot\left|x_{0}-\widehat{\omega x_{1}}\right|, \\
& \left|\operatorname{RN}\left(x_{0}+\widehat{\omega x_{1}}\right)-\left(x_{0}+\widehat{\omega x_{1}}\right)\right| \leqslant u \cdot\left|x_{0}+\widehat{\omega x_{1}}\right| .
\end{aligned}
$$

From which we deduce

$$
\begin{aligned}
\left|\operatorname{RN}\left(x_{0}+\widehat{\omega x_{1}}\right)-\left(x_{0}+\omega x_{1}\right)\right| & \leqslant\left|\operatorname{RN}\left(x_{0}+\widehat{\omega x_{1}}\right)-\left(x_{0}+\widehat{\omega x_{1}}\right)\right|+\left|\widehat{\omega x_{1}}-\omega x_{1}\right| \\
& \leqslant u \cdot\left|x_{0}+\widehat{\omega x_{1}}\right|+\left|x_{1}\right| \cdot g_{k} \\
& \leqslant u \cdot\left(\left|x_{0}+\omega x_{1}\right|+\left|\widehat{\omega x_{1}}-\omega x_{1}\right|\right)+\left|x_{1}\right| \cdot g_{k},
\end{aligned}
$$

which implies

$$
\begin{equation*}
\left|\mathrm{RN}\left(x_{0}+\widehat{\omega x_{1}}\right)-\left(x_{0}+\omega x_{1}\right)\right| \leqslant\left|x_{0}+\omega x_{1}\right| \cdot u+\left|x_{1}\right| \cdot\left(g_{k}+u g_{k}\right) \tag{16}
\end{equation*}
$$

Similarly, we have

$$
\begin{equation*}
\left|\operatorname{RN}\left(x_{0}-\widehat{\omega x_{1}}\right)-\left(x_{0}-\omega x_{1}\right)\right| \leqslant\left|x_{0}-\omega x_{1}\right| \cdot u+\left|x_{1}\right| \cdot\left(g_{k}+u g_{k}\right) \tag{17}
\end{equation*}
$$

Now, let us notice that

$$
\begin{equation*}
\left|x_{0}-\omega x_{1}\right|^{2}+\left|x_{0}+\omega x_{1}\right|^{2}=2 x_{0} \overline{x_{0}}+2\left(\omega x_{1}\right) \overline{\left(\omega x_{1}\right)}=2\left(\left|x_{0}\right|^{2}+\left|x_{1}\right|^{2}\right) \tag{18}
\end{equation*}
$$

a consequence of which is

$$
\begin{equation*}
\left|x_{0}\right|^{2},\left|x_{1}\right|^{2} \leqslant \frac{1}{2}\left(\left|x_{0}-\omega x_{1}\right|^{2}+\left|x_{0}+\omega x_{1}\right|^{2}\right) \tag{19}
\end{equation*}
$$

By combining (16), (17), and (19), we obtain

$$
\begin{aligned}
& \left|\mathrm{RN}\left(x_{0}+\widehat{\omega x_{1}}\right)-\left(x_{0}+\omega x_{1}\right)\right|^{2}+\left|\mathrm{RN}\left(x_{0}-\widehat{\omega x_{1}}\right)-\left(x_{0}-\omega x_{1}\right)\right|^{2} \\
& \leqslant\left|x_{0}+\omega x_{1}\right|^{2} \cdot u^{2}+\frac{1}{2}\left(\left|x_{0}-\omega x_{1}\right|^{2}+\left|x_{0}+\omega x_{1}\right|^{2}\right) \cdot\left(g_{k}+u g_{k}\right)^{2} \\
& +\left|x_{0}-\omega x_{1}\right|^{2} \cdot u^{2}+\frac{1}{2}\left(\left|x_{0}-\omega x_{1}\right|^{2}+\left|x_{0}+\omega x_{1}\right|^{2}\right) \cdot\left(g_{k}+u g_{k}\right)^{2} \\
& \\
& \quad+2 u\left|x_{1}\right|\left(g_{k}+u g_{k}\right)\left(\left|x_{0}+\omega x_{1}\right|+\left|x_{0}-\omega x_{1}\right|\right)
\end{aligned}
$$

We will now use the following lemma.
Lemma 4. For all $u, v \in \mathbb{C}$, we have

$$
(|u+v|+|u-v|) \max (|u|,|v|) \leqslant\left(|u+v|^{2}+|u-v|^{2}\right)
$$

Proof. If $u v=0$, it is obvious. Hence, we assume $u v \neq 0$.
We first notice that it is now equivalent to prove that for all $z \in \mathbb{C} \backslash\{0\}$,

$$
|1+z|+|1-z| \leqslant|1+z|^{2}+|1-z|^{2}
$$

i.e.,

$$
|1+z|+|1-z| \leqslant 2\left(1+|z|^{2}\right)
$$

from the parallelogram law. Now we consider that $|z|$ is fixed and we try to maximize $|1+z|+|1-z|$. Let $A, B, C, I$ be points of respective affixes $0,1+z, 1-z$
and 1 and $\alpha, \alpha_{1}, \alpha_{2}, \beta, \gamma$ denote the respective angles $\widehat{B A C}, \widehat{B A I}, \widehat{C A I}, \widehat{A B C}$ and $\widehat{A C B}$. We have

$$
\begin{aligned}
|1+z| & =|z| \cos \beta+\cos \alpha_{1} \\
|1-z| & =|z| \cos \gamma+\cos \alpha_{2}
\end{aligned}
$$

Then, it follows

$$
\begin{aligned}
|1+z|+|1-z| & =|z|(\cos \beta+\cos \gamma)+\cos \alpha_{1}+\cos \alpha_{2} \\
& =2|z| \cos \left(\frac{\beta+\gamma}{2}\right) \cos \left(\frac{\beta-\gamma}{2}\right)+2 \cos \left(\frac{\alpha}{2}\right) \cos \left(\frac{\alpha_{1}-\alpha_{2}}{2}\right) \\
& =2|z| \sin \left(\frac{\alpha}{2}\right) \cos \left(\frac{\beta-\gamma}{2}\right)+2 \cos \left(\frac{\alpha}{2}\right) \cos \left(\frac{\alpha_{1}-\alpha_{2}}{2}\right),
\end{aligned}
$$

which is maximal if and only if $\alpha_{1}=\alpha_{2}$ and $\beta=\gamma$, i.e., $z=i x, x \in \mathbb{R}$. In this case, $2\left(1+|z|^{2}\right)-|1+z|-|1-z|=2\left(1+x^{2}-\sqrt{1+x^{2}}\right) \geqslant 0$.

All this gives
Lemma 5 (Adapted from [16]).
$\left|\mathrm{RN}\left(x_{0}+\widehat{\omega x_{1}}\right)-\left(x_{0}+\omega x_{1}\right)\right|^{2}+\left|\mathrm{RN}\left(x_{0}-\widehat{\omega x_{1}}\right)-\left(x_{0}-\omega x_{1}\right)\right|^{2} \leqslant\left(\left|x_{0}+\omega x_{1}\right|^{2}+\left|x_{0}-\omega x_{1}\right|^{2}\right) \Omega_{k}^{2}$,
where

$$
\Omega_{k}:=u+g_{k}(1+u)
$$

### 4.2 Application to the error of the FFT

In the following, $X$ is the $N=2^{n}$-point (exact) Fourier transform of $x$, and $t_{k}$ is the transformation performed at Step $k$ of the FFT algorithm. We denote $x^{(0)}=x, x^{(1)}=t_{1}\left(x^{(0)}\right), x^{(2)}=t_{2}\left(x^{(1)}\right), \ldots, x^{(n)}=t_{n}\left(x^{(n-1)}\right)=X$ the intermediate exact values of the FFT algorithm, and $\widehat{x^{(1)}}, \widehat{x^{(2)}}, \ldots, \widehat{x^{(n)}}=\widehat{X}$ the corresponding computed values. We have $\widehat{x^{(0)}}=x^{(0)}$.

From (18) we easily find that for any $y$ and $k,\left\|t_{k}(y)\right\|_{2}=\sqrt{2} \cdot\|y\|_{2}$.
From Lemma 5, we have

$$
\begin{equation*}
\left\|\widehat{x^{(k)}}-t_{k}\left(\widehat{x^{(k-1)}}\right)\right\|_{2} \leqslant \Omega_{k} \cdot\left\|t_{k}\left(\widehat{x^{(k-1)}}\right)\right\|_{2} \tag{20}
\end{equation*}
$$

Let us show by induction on $k$ the following property

$$
\begin{equation*}
\left\|\widehat{x^{(k)}}-x^{(k)}\right\|_{2} \leqslant\left\|x^{(k)}\right\|_{2} \cdot\left[\prod_{i=1}^{k}\left(1+\Omega_{i}\right)-1\right] \tag{21}
\end{equation*}
$$

For $k=1$, it is an almost immediate consequence of (20) and the fact that $t_{1}\left(\widehat{x^{(0)}}\right)=t_{1}\left(x^{(0)}\right)=x^{(1)}$. Now, let us assume (21) is true for some $k$. We have

$$
\begin{aligned}
\left\|\widehat{x^{(k+1)}}-x^{(k+1)}\right\|_{2} & \leqslant\left\|\widehat{x^{(k+1)}}-t_{k+1}\left(\widehat{x^{(k)}}\right)\right\|_{2}+\| t_{k+1}\left(\widehat{\left(x^{(k)}\right)}-x^{(k+1)} \|_{2}\right. \\
& \leqslant\left\|t_{k+1}\left(\widehat{x^{(k)}}\right)\right\|_{2} \cdot \Omega_{k+1}+\left\|t_{k+1}\left(\widehat{x^{(k)}}-x^{(k)}\right)\right\|_{2} \\
& \leqslant \sqrt{2} \cdot\left\|\widehat{x^{(k)}}\right\|_{2} \cdot \Omega_{k+1}+\sqrt{2} \cdot\left\|\widehat{x^{(k)}}-x^{(k)}\right\|_{2} \\
& \leqslant \sqrt{2} \cdot \Omega_{k+1} \cdot\left\|x^{(k)}\right\|_{2} \cdot \prod_{i=1}^{k}\left(1+\Omega_{i}\right)+\sqrt{2} \cdot\left\|x^{(k)}\right\|_{2} \cdot\left[\prod_{i=1}^{k}\left(1+\Omega_{i}\right)-1\right] \\
& \leqslant\left\|x^{(k+1)}\right\|_{2} \cdot\left[\prod_{i=1}^{k+1}\left(1+\Omega_{i}\right)-1\right] .
\end{aligned}
$$

Q.E.D.

This gives
Theorem 7.

$$
\|\hat{X}-X\|_{2} \leqslant\|X\|_{2} \cdot\left(\prod_{i=1}^{n}\left(1+\Omega_{i}\right)-1\right)
$$

with

$$
\begin{aligned}
\Omega_{k} & =u+g_{k}(1+u), \\
g_{k} & =\left\{\begin{array}{l}
0 \text { if } k=1,2, \\
\Delta_{k}^{\max }+\rho_{\times} \cdot\left(1+\Delta_{k}^{\max }\right) \text { otherwise, },
\end{array}\right. \\
\Delta_{k}^{\max } & =\max _{\left\{\omega 2^{k}-\text { th root of } 1\right\}} \Delta_{\omega}, \\
\Delta_{\omega} & =|\hat{\omega}-\omega|, \\
\rho_{\times} & = \begin{cases}u \sqrt{5} & \text { if (10) is used, } \\
2 u & \text { if (11) is used. }\end{cases}
\end{aligned}
$$

That result can be directly used to obtain error bounds, with a preliminary calculation of the terms $g_{k}$. As said above, one can get a simpler yet looser bound by noticing that $g_{1}=g_{2}=0$ and bounding all other terms $g_{k}$ by

$$
g=\frac{\sqrt{2}}{2} u+\rho_{\times} \cdot\left(1+\frac{\sqrt{2}}{2} u\right) .
$$

This gives the following result, which is essentially the same as Percival's result [16] (our bound is slightly better because we use $g_{1}=g_{2}=0$, and when an FMA instruction is available, we know that $\rho_{\times}=2 u$ ).

Theorem 8 (Close to Percival's bound [16]).

$$
\|\hat{X}-X\|_{2} \leqslant\|X\|_{2} \cdot\left[(1+u)^{n}(1+g)^{n-2}-1\right]
$$

Of course, this also gives a bound on $\|\hat{X}-X\|_{\infty}$. Tables 3 and 4 compare the various obtained bounds in the case of a 256 -point and a 65536 -point FFT, respectively.

Table 3: Comparison of the bounds on $\|\hat{X}-X\|_{2} /\|X\|_{2}$ given by Theorems 1, 2,3 (with $\mu=u \sqrt{2} / 2$, the smallest value that always holds), 4 (with the same value of $\mu$ ), 7 and 8 for a $2^{8}$-point FFT.

|  | $p=24$ | $p=53$ | $p=113$ |
| :--- | :--- | :--- | :--- |
| Theorem 1 | $67.84 \cdot u$ | $67.84 \cdot u$ | $67.84 \cdot u$ |
| Theorem 2 | $46.31 \cdot u+\mathcal{O}\left(u^{2}\right)$ | $46.31 \cdot u+\mathcal{O}\left(u^{2}\right)$ | $46.31 \cdot u+\mathcal{O}\left(u^{2}\right)$ |
| Theorem 3 <br> with $\mu=u \sqrt{2} / 2$ <br> (does not assume FMA) | $50.92 \cdot u$ | $50.92 \cdot u$ | $50.92 \cdot u$ |
| Theorem 4 <br> with $\mu=u \sqrt{2} / 2$ <br> (does not assume FMA) | $31.55 \cdot u$ | $31.55 \cdot u$ | $31.55 \cdot u$ |
| Theorem 8 <br> with $\rho_{\times}=2 u$ <br> (FMA) | $24.25 \cdot u$ | $24.25 \cdot u$ | $24.25 \cdot u$ |
| Theorem 8 <br> with $\rho_{\times}=\sqrt{5} u$ <br> (no FMA) | $25.66 \cdot u$ | $25.66 \cdot u$ | $25.66 \cdot u$ |
| Theorem 7 <br> with calculation of the $g_{k} \mathrm{~s}$ <br> with $\rho_{\times}=2 u$ <br> (FMA) | $22.78 \cdot u$ | $23.71 \cdot u$ | $24.16 \cdot u$ |
| Theorem 7 <br> with calculation of the $g_{k} \mathrm{~s}$ <br> with $\rho_{\times}=\sqrt{5} u$ <br> (no FMA) | $24.19 \cdot u$ | $25.11 \cdot u$ | $25.57 \cdot u$ |

## 5 Calculation of an error bound for the infinity norm

In the following, we wish to find a bound for $\|X-\hat{X}\|_{\infty}^{\perp}$, given that $\|x\|_{\infty}^{\perp} \leqslant 1$. Note that if the constraint on $x$ becomes $\|x\|_{\infty}^{\perp} \leqslant 2^{m}$, it will suffice to multiply the bound on $\|X-\hat{X}\|_{\infty}^{\perp}$ by $2^{m}$. Obtaining such bounds is important for implementing Schönhage and Strassen's algorithm for multiplying big integers of large polynomials [21, 13]. One can get such bounds by using Theorem 7 and (7). One might also want to use Henrici's Theorem (Theorem 5): assuming an FMA is used (so that complex multiplication has relative error $2 u$ ), Theorem 5 gives a bound

$$
\|\hat{X}-X\|_{\infty}^{\perp} \leqslant 2^{n+1}(2 n+1) \cdot \sqrt{2} \cdot u \cdot\|x\|_{\infty}^{\perp}+\mathcal{O}\left(u^{2}\right) .
$$

Note, however, the " $\mathcal{O}\left(u^{2}\right)$ " that does not allow to get sure bounds.
Table 5 compares bounds on $\|\hat{X}-X\|_{2} /\|X\|_{2}$ and $\|X-\hat{X}\|_{\infty}^{\perp} /\|x\|_{\infty}^{\perp}$ deduced from Theorem 7 (assuming an FMA instruction is available, and $p=53$-i.e., double-precision arithmetic) and (7) with bounds deduced from Henrici's theorem.

Table 4: Comparison of the bounds on $\|\hat{X}-X\|_{2} /\|X\|_{2}$ given by Theorems 1 , 2,3 (with $\mu=u \sqrt{2} / 2$, the smallest value that always holds), 4 (with the same value of $\mu$ ), 7 and 8 for a $2^{16}$-point FFT.

|  | $p=24$ | $p=53$ | $p=113$ |
| :--- | :--- | :--- | :--- |
| Theorem 1 | $135.68 \cdot u$ | $135.68 \cdot u$ | $135.68 \cdot u$ |
| Theorem 2 | $97.62 \cdot u+\mathcal{O}\left(u^{2}\right)$ | $97.62 \cdot u+\mathcal{O}\left(u^{2}\right)$ | $97.62 \cdot u+\mathcal{O}\left(u^{2}\right)$ |
| Theorem 3 <br> with $\mu=u \sqrt{2} / 2$ <br> (does not assume FMA) | $101.83 \cdot u$ | $101.83 \cdot u$ | $101.83 \cdot u$ |
| Theorem 4 <br> with $\mu=u \sqrt{2} / 2$ <br> (does not assume FMA) | $63.10 \cdot u$ | $63.10 \cdot u$ | $63.10 \cdot u$ |
| Theorem 8 <br> with $\rho_{\times}=2 u$ <br> (FMA) | $53.90 \cdot u$ | $53.90 \cdot u$ | $53.90 \cdot u$ |
| Theorem 8 <br> with $\rho_{\times}=\sqrt{5} u$ <br> (no FMA) | $57.21 \cdot u$ | $57.21 \cdot u$ | $57.21 \cdot u$ |
| Theorem 7 <br> with calculation of the $g_{k} \mathrm{~s}$ <br> with $\rho_{\times}=2 u$ <br> (FMA) | $52.14 \cdot u$ | $53.03 \cdot u$ | $53.69 \cdot u$ |
| Theorem 7 <br> with calculation of the $g_{k} \mathrm{~s}$ <br> with $\rho_{\times}=\sqrt{5} u$ <br> (no FMA) | $55.45 \cdot u$ | $56.33 \cdot u$ | $57.00 \cdot u$ |

Before going further, let us give a "bad" case for that norm, i.e., a case for which we obtain a large error.

### 5.1 A bad case for the infinity norm

It is interesting to build "bad" cases: they help us to know if it is worth trying to improve the error bounds.

We build a bad case as follows. We are interested in having an error as large as possible on the first term of the Fourier transform. Let us quickly explain how this can be done. We assume that $x_{0} \approx x_{1} \approx x_{2} \approx \ldots \approx x_{N-1} \approx 1$. Denoting $u_{i}=x_{\text {reverse }(k, i)}$, we are interested in the calculation of the 1st component of the Fourier Transform. The exact result is $x_{0}+x_{1}+\cdots+x_{N-1}$, and the computed result is

$$
\begin{equation*}
\operatorname{RN}\left\{\cdots \operatorname{RN}\left\{\operatorname{RN}\left[\operatorname{RN}\left(u_{0}+u_{1}\right)+\mathrm{RN}\left(u_{2}+u_{3}\right)\right]+\mathrm{RN}\left[\operatorname{RN}\left(u_{4}+u_{5}\right)+\mathrm{RN}\left(u_{6}+u_{7}\right)\right]\right\}+\cdots\right\} \tag{22}
\end{equation*}
$$

(see the first line in Figure 2). After Step $k$ of the FFT algorithm, the intermediate terms in the sum (22) will be floating-point numbers around $2^{k}$,
which means that they will be of the form $2^{k}+j u 2^{k+1}$ (where $j \in \mathbb{N}$ ) for the terms above $2^{k}$, and $2^{k}-j u 2^{k}$ for the terms below $2^{k}$. We will assume $0 \leqslant j \leqslant 2^{n+1} \ll 1 / u$. Let us explain how we can build a term of the form $2^{k}+j u 2^{k+1}$ from the floating-point addition of two terms around $2^{k-1}$, trying to maximize the rounding error. Since we want all rounding errors to be in the same direction (in order to maximize the global error, which will be the sum of all individual rounding errors), we will make sure that all roundings are downwards. We assume that RN is round to nearest ties to even: if $t$ is halfway between two consecutive FP numbers, then $\mathrm{RN}(t)$ is the one of these two numbers whose significand is even, i.e., its rightmost significand bit is a zero (this is the default in the IEEE 754 standard).

Notice that since the distance between two floating-point numbers in the neighborhood of $2^{k}+j u 2^{k+1}$ is $u \cdot 2^{k+1}$, the maximum rounding error that can result from that floating-point addition is $u \cdot 2^{k}$. Therefore

- if $j$ is even, one easily checks that error $u \cdot 2^{k}$ is attained when adding the two FP numbers $2^{k-1}+j u 2^{k+1}$ and $2^{k-1}+u 2^{k}$. The exact sum is $2^{k}+\left(j+\frac{1}{2}\right) u 2^{k+1}$, the rounded result (thanks to the round ties-to-even rule) is the expected $2^{k}+j u 2^{k+1}$, so that the rounding error is $u \cdot 2^{k}$;
- if $j$ is odd, error $u \cdot 2^{k}$ cannot be attained: if the exact sum was $2^{k}+$ $j u 2^{k+1} \pm u \cdot 2^{k}$, then (due to the ties-to-even rule) that exact sum would not be rounded to $2^{k}+j u 2^{k+1}$, whose significand is odd. To make sure that the exact sum is not halfway between two FP numbers, it must not be a multiple of $u 2^{k}$, which implies that one of the operands must be below $2^{k-1}$. Hence the choice to add $2^{k-1}+u \cdot\left(j+\frac{1}{2}\right) \cdot 2^{k+1}$ and $2^{k-1}-u \cdot 2^{k-1}$. The exact sum is $2^{k}+j u 2^{k+1}+u 2^{k-1}$, resulting in a rounded sum equal to the expected $2^{k}+j u 2^{k+1}$ and a rounding error $u \cdot 2^{k-1}$.
The reasoning would be similar for building a term of the form $2^{k}-j u 2^{k}$. We can formalize these ideas as follows. Let us call $T_{2^{k}, \sigma}$ an array of $2^{k}$ input values (in "mirror order", i.e., one must choose $x_{0}=\overleftarrow{T}_{2^{k}, \sigma}[\operatorname{reverse}(k, 0)], x_{1}=$ $T_{2^{k}, \sigma}[\operatorname{reverse}(k, 1)], x_{2}=T_{2^{k}, \sigma}[\operatorname{reverse}(k, 2)], \ldots$ as first elements ) for which the computed sum that appear in the 1 st component of the $2^{k}$-term FFT is equal to $2^{k}+\sigma$. The number $\sigma$ will be of the form $j \cdot 2^{k+1} u$ for $\sigma \geqslant 0$, and $-j \cdot 2^{k} u$ for $\sigma<0$, where $j$ is a small positive integer. We are going to build $T_{2^{n}, 0}$ so that the error when computing the FFT of that array is as large as possible. We denote $T / / T^{\prime}$ as the concatenation of the arrays $T$ and $T^{\prime}$, we will choose (for $j \geqslant 0$ ):

$$
\begin{gather*}
T_{2^{k}, j \cdot 2^{k+1} u}= \begin{cases}T_{2^{k-1},\left(j+\frac{1}{2}\right) \cdot 2^{k+1} u} / / T_{2^{k-1},-2^{k-1} u} & \text { if } j \text { is odd } \\
T_{2^{k-1}, j \cdot 2^{k+1} u} / / T_{2^{k-1}, 2^{k} u} & \text { if } j \text { is even },\end{cases}  \tag{23}\\
T_{2^{k},-j \cdot 2^{k} u}= \begin{cases}T_{2^{k-1}, 0} / / T_{2^{k-1},-j \cdot 2^{k} u} & \text { if } j \text { is odd } \\
T_{2^{k-1}, 0} / / T_{2^{k-1},(-2 j+1) \cdot 2^{k-1} u} & \text { if } j \text { is even }\end{cases} \tag{24}
\end{gather*}
$$

with, of course

$$
\left\{\begin{array}{l}
T_{1,2 j u}=1+2 j u \\
T_{1,-j u}=1-j u
\end{array}\right.
$$

The error on the 1st term of the Fourier Transform will be $C_{n, 0} \cdot u$, where the terms $C_{k, m}$ (equal to the error that occurs when performing a $2^{k}$-point FFT with the input values defined by $T_{2^{k}, m u}$ ) are defined by the following recurrence

$$
C_{k, m}= \begin{cases}0 & \text { if } k=0  \tag{25}\\ C_{k-1, m+2^{k}}+C_{k-1,-2^{k-1}}+2^{k-1} & \text { if } m / 2^{k+1} \text { is odd and } m \geqslant 0 \\ C_{k-1, m}+C_{k-1,2^{k}}+2^{k} & \text { if } m / 2^{k+1} \text { is even and } m \geqslant 0 \\ C_{k-1,0}+C_{k-1, m} & \text { if } m / 2^{k} \text { is odd and } m<0 \\ C_{k-1,0}+C_{k-1, m+2^{k-1}}+2^{k-1} & \text { if } m / 2^{k} \text { is even and } m<0\end{cases}
$$

Figure 3 illustrates the use of the rules (23) and (24) for building a bad case for $N=8$. Interestingly enough, from the recurrence (25), the GFUN package [19] makes it possible to find an exact closed formula for $C_{n, 0}$. This is based on first computing several terms $C_{n, 0}$, say $n \leqslant 24$, and then using GFUN to guess a linear differential equation with polynomial coefficients, satisfied by the generating function $\sum_{n \geqslant 0} C_{n, 0} x^{n}$. This is obviously not always possible, but such an equation exists when $\left(C_{n, 0}\right)_{n \geqslant 0}$ is a $P$-recursive sequence i.e., it satisfies a linear recurrence with polynomial coefficients in $n$. It turns out that in our case the guessed generating function is a rational fraction,

$$
-\frac{-2 x^{4}+2 x^{3}+x^{2}-2 x}{4 x^{5}-4 x^{4}+x^{3}+4 x^{2}-4 x+1},
$$

allowing to find not only a recurrence for $C_{n, 0}$, but also its closed form, given below. We obtain,
Theorem 9. The terms $C_{n, 0}$ defined by (25) satisfy

$$
\frac{1}{27} \cdot 2^{n} \cdot(15 n+14)-\frac{5}{9} \cdot \cos \left(\frac{n \pi}{3}\right)+\frac{1}{9} \cdot \sqrt{3} \cdot \sin \left(\frac{n \pi}{3}\right)+\frac{(-1)^{n}}{27}
$$

Hence, on the "bad cases" built using the recurrences (23) and (24), the FFT algorithm has an error asymptotically equivalent to $(5 / 9) \cdot n \cdot 2^{n}$. One easily checks that with these bad cases, $\|x\|_{\infty}^{\perp}=1+(2 N-2) \cdot u$, so that

$$
\frac{\|X-\hat{X}\|_{\infty}^{\perp}}{\|x\|_{\infty}^{\perp}} \sim \frac{5}{9} \cdot \frac{n \cdot 2^{n} \cdot u}{1+\left(2^{n+1}-2\right) \cdot u}
$$

Table 5 compares bounds on $\|\hat{X}-X\|_{2} /\|X\|_{2}$ and $\|X-\hat{X}\|_{\infty}^{\perp} /\|x\|_{\infty}^{\perp}$ deduced from Theorem 7 (assuming an FMA instruction is available, and $p=53$-i.e., double-precision arithmetic) and (7) with bounds deduced from Henrici's theorem and the "bad case" we have just built.

### 5.2 Iterative calculation of an error bound

We assume that the input vector to the FFT algorithm satisfies $\|x\|_{\infty}^{\perp} \leqslant 1$. Let us again consider an elementary calculation of the FFT, performed at Step $k$ :

$$
\left\{\begin{array}{l}
y_{1}=x_{1}+\omega x_{2} \\
y_{2}=x_{1}-\omega x_{2}
\end{array}\right.
$$



Figure 3: Building a bad case for $N=8$, according to (23) and (24). The obtained input values are in mirror order: this corresponds to $x_{0}=1, x_{1}=$ $1+14 u, x_{2}=1+6 u, x_{3}=1, x_{4}=1+2 u, x_{5}=1-u, x_{6}=1-u$, and $x_{7}=1-2 u$. The absolute error on $X_{0}$, when applying the FFT algorithm on these input values, is $18 u$.
where $x_{1}, x_{2}, y_{1}$ and $y_{2}$ are "exact" values (i.e., they are obtained from exact calculations, without roundings). We will now iteratively compute error bounds for all the intermediate calculations of the FFT. Denoting $x_{1}^{R}, x_{2}^{R}, y_{1}^{R}, y_{2}^{R}$ and $\omega^{R}$ the real parts of $x_{1}, x_{2}, y_{1}, y_{2}$ and $\omega$, and $x_{1}^{I}, x_{2}^{I}, y_{1}^{I}, y_{2}^{I}$ and $\omega^{I}$ their imaginary parts, we have

$$
\left\{\begin{aligned}
y_{1}^{R} & =x_{1}^{R}+\omega^{R} x_{2}^{R}-\omega^{I} x_{2}^{I} \\
y_{1}^{I} & =x_{1}^{I}+\omega^{I} x_{2}^{R}+\omega^{R} x_{2}^{I} \\
y_{2}^{R} & =x_{1}^{R}-\omega^{R} x_{2}^{R}+\omega^{I} x_{2}^{I} \\
y_{2}^{I} & =x_{1}^{I}-\omega^{I} x_{2}^{R}-\omega^{R} x_{2}^{I}
\end{aligned}\right.
$$

Now, denote $\widehat{x_{1}^{R}}, \widehat{x_{2}^{R}}, \widehat{y_{1}^{R}}, \widehat{y_{2}^{R}}, \widehat{x_{1}^{I}}, \widehat{x_{2}^{I}}, \widehat{y_{1}^{I}}$, and $\widehat{y_{2}^{I}}$ as the calculated values of $x_{1}^{R}$, $x_{2}^{R}, y_{1}^{R}, y_{2}^{R}, x_{1}^{I}, x_{2}^{I}, y_{1}^{I}$, and $y_{2}^{I}$; and denote $\widehat{\omega^{R}}=\operatorname{RN}\left(\omega^{R}\right)$ and $\widehat{\omega^{I}}=\operatorname{RN}\left(\omega^{I}\right)$. We assume that an FMA instruction is available, and that $\widehat{y_{1}^{R}}, \widehat{y_{2}^{R}}, \widehat{y_{1}^{I}}$, and $\widehat{y_{2}^{I}}$ are computed as follows

$$
\left\{\begin{array}{l}
\widehat{y_{1}^{R}}=\operatorname{RN}\left[\widehat{x_{1}^{R}}+\operatorname{RN}\left(\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right)\right]  \tag{26}\\
\widehat{y_{1}^{I}}=\operatorname{RN}\left[\widehat{x_{1}^{I}}+\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{R}}+\operatorname{RN}\left(\widehat{\omega^{R}} \widehat{x_{2}^{I}}\right)\right)\right] \\
\widehat{y_{2}^{R}}=\operatorname{RN}\left[\widehat{x_{1}^{R}}-\operatorname{RN}\left(\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right)\right] \\
\widehat{y_{2}^{I}}=\operatorname{RN}\left[\widehat{x_{1}^{I}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{R}}+\operatorname{RN}\left(\widehat{\omega^{R}} \widehat{x_{2}^{I}}\right)\right)\right]
\end{array}\right.
$$

The terms $\omega^{R}, \omega^{I}, \widehat{\omega^{R}}$ and $\widehat{\omega^{I}}$ are input-independent, so we assume that the errors

$$
\Delta_{\omega}^{R}=\left|\widehat{\omega^{R}}-\omega^{R}\right| \quad \text { and } \quad \Delta_{\omega}^{I}=\left|\widehat{\omega^{I}}-\omega^{I}\right|
$$

Table 5: Bounds on $\|\hat{X}-X\|_{2} /\|X\|_{2}$ and $\|X-\hat{X}\|_{\infty}^{\perp} /\|x\|_{\infty}^{\perp}$ deduced from Theorem 7 (assuming an FMA instruction is available, and $p=53$-i.e., doubleprecision arithmetic) and (7), compared with the bound on $\|X-\hat{X}\|_{\infty}^{\perp} /\|x\|_{\infty}^{\perp}$ given by Theorem 5 and the "bad case" presented in this section.

| $N$ | Bound on <br> $\\|X-\hat{X}\\|_{2} /\\|x\\|_{2}$ <br> deduced from <br> Theorem 7 <br> (with FMA) | $\\|X-\hat{X}\\|_{\infty}^{\perp} /\\|x\\|_{\infty}^{\perp}$ <br> deduced from <br> Theorem 7 <br> and (7) | Bound on <br> $\\|X-\hat{X}\\|_{\infty}^{\perp} /\\|x\\|_{\infty}^{\perp}$ <br> deduced from <br> Theorem 5) | Known bad case for <br> $\\|X-\hat{X}\\|_{\infty}^{\perp} /\\|x\\|_{\infty}^{\perp}$ <br> (see Section 5.1) |
| :--- | :--- | :--- | :--- | :--- |
| $2^{5}$ | $12.85 \cdot u$ | $582 \cdot u$ | $996 \cdot u+\mathcal{O}\left(u^{2}\right)$ | $105 \cdot u$ |
| $2^{8}$ | $23.71 \cdot u$ | $8584 \cdot u$ | $12310 \cdot u+\mathcal{O}\left(u^{2}\right)$ | $1271 \cdot u$ |
| $2^{10}$ | $30.99 \cdot u$ | $44879 \cdot u$ | $60823 \cdot u+\mathcal{O}\left(u^{2}\right)$ | $6220 \cdot u$ |
| $2^{12}$ | $38.28 \cdot u$ | $221720 \cdot u$ | $289631 \cdot u+\mathcal{O}\left(u^{2}\right)$ | $29430 \cdot u$ |
| $2^{14}$ | $45.63 \cdot u$ | $1.058 \times 10^{6} \cdot u$ | $1.344 \times 10^{6} \cdot u+\mathcal{O}\left(u^{2}\right)$ | $135927 \cdot u$ |
| $2^{16}$ | $53.03 \cdot u$ | $4.915 \times 10^{6} \cdot u$ | $6.118 \times 10^{6} \cdot u+\mathcal{O}\left(u^{2}\right)$ | $616524 \cdot u$ |
| $2^{18}$ | $60.43 \cdot u$ | $2.240 \times 10^{7} \cdot u$ | $2.744 \times 10^{7} \cdot u+\mathcal{O}\left(u^{2}\right)$ | $2.757 \times 10^{6} \cdot u$ |
| $2^{20}$ | $67.83 \cdot u$ | $1.006 \times 10^{8} \cdot u$ | $1.216 \times 10^{8} \cdot u+\mathcal{O}\left(u^{2}\right)$ | $1.219 \times 10^{7} \cdot u$ |

are computed in advance. The terms $\left|x_{1}^{R}\right|,\left|x_{1}^{I}\right|,\left|x_{2}^{R}\right|$, and $\left|x_{2}^{I}\right|$ are results of a $2^{k-1}$-point FFT, hence they are bounded by $\frac{2^{k+1}}{\pi}$ as shown in Section 3.2. However, to take advantage from a significantly smaller bound for small values of $k$, we will bound $\left|x_{1}^{R}\right|,\left|x_{1}^{I}\right|,\left|x_{2}^{R}\right|$, and $\left|x_{2}^{I}\right|$ by $\beta_{k}$, defined as

$$
\beta_{k}= \begin{cases}2^{k-1} & \text { if } k \leqslant 3 \\ 4+4 \sqrt{2} & \text { if } k=4 \\ 2^{k+1} / \pi & \text { otherwise }\end{cases}
$$

Since $x_{2}$ results from a $2^{k-1}$-point FFT, it satisfies

$$
\sqrt{\left(x_{2}^{R}\right)^{2}+\left(x_{2}^{I}\right)^{2}} \leqslant 2^{k-1 / 2}
$$

from which we easily deduce

$$
\begin{align*}
& \left|x_{2}^{R} \omega^{R}-x_{2}^{I} \omega^{I}\right| \leqslant 2^{k-1 / 2},  \tag{27}\\
& \left|x_{2}^{R} \omega^{I}+x_{2}^{I} \omega^{R}\right| \leqslant 2^{k-1 / 2} .
\end{align*}
$$

Also, to take into account the fact that multiplications by $\pm 1$ and $\pm i$ are errorless (these multiplications are frequent in the first steps of the FFT algorithm), define, for a (real) floating-point number $t$ :

$$
\mathbb{1}_{t}= \begin{cases}1 & \text { if } t= \pm 1 \\ 0 & \text { otherwise }\end{cases}
$$

so that when multiplying some floating-point number $v$ by $t$, the error committed is bounded by

$$
\frac{1}{2}\left(1-\mathbb{1}_{t}\right) \cdot \operatorname{ulp}^{*}(v t) .
$$

Define also

$$
\mathbb{O}_{t}= \begin{cases}1 & \text { if } t=0, \\ 0 & \text { otherwise } .\end{cases}
$$

Let $\delta_{1}^{R}$ (resp. $\delta_{1}^{I}, \delta_{2}^{R}, \delta_{2}^{I}$ ) be a bound on $\left|x_{1}^{R}-\widehat{x_{1}^{R}}\right|$ (resp., $\left|x_{1}^{I}-\widehat{x_{1}^{I}}\right|,\left|x_{2}^{R}-\widehat{x_{2}^{R}}\right|$, $\left.\left|x_{2}^{I}-\widehat{x_{2}^{I}}\right|\right)$. From these values we wish to compute $\eta_{1}^{R}$ (resp., $\eta_{1}^{I}, \eta_{2}^{R}, \eta_{2}^{I}$ ), bounds on $\left|y_{1}^{R}-\widehat{y_{1}^{R}}\right|$ (resp., $\left|y_{1}^{I}-\widehat{y_{1}^{I}}\right|,\left|y_{2}^{R}-\widehat{y_{2}^{R}}\right|,\left|y_{2}^{I}-\widehat{y_{2}^{I}}\right|$ ). Let us detail the calculation of $\eta_{1}^{R}$. Expressions for $\eta_{1}^{I}, \eta_{2}^{R}$ and $\eta_{2}^{I}$ will be deduced using a straightforward symmetry.
Lemma 6. The number

$$
\Delta_{\omega}^{R}\left|x_{2}^{R}\right|+\Delta_{\omega}^{I}\left|x_{2}^{I}\right|
$$

is less than or equal to
1.

$$
\Delta_{\omega}^{R} \cdot \frac{2^{k+1}}{\pi}+\Delta_{\omega}^{I} \cdot 2^{k} \cdot \sqrt{\frac{1}{2}-\frac{4}{\pi^{2}}}
$$

$$
\text { if }\left(\Delta_{\omega}^{R} / \Delta_{\omega}^{I}\right)^{2} \leqslant \pi^{2} / 8-1 ;
$$

2. 

$$
\begin{array}{r}
2^{k-1 / 2} \cdot \sqrt{\left(\Delta_{\omega}^{R}\right)^{2}+\left(\Delta_{\omega}^{I}\right)^{2}} \\
\text { if } \pi^{2} / 8-1<\left(\Delta_{\omega}^{R} / \Delta_{\omega}^{I}\right)^{2}<1 /\left(\pi^{2} / 8-1\right) \text {, and }
\end{array}
$$

3. 

$$
\Delta_{\omega}^{I} \cdot \frac{2^{k+1}}{\pi}+\Delta_{\omega}^{R} \cdot 2^{k} \cdot \sqrt{\frac{1}{2}-\frac{4}{\pi^{2}}}
$$

otherwise.
Proof. The point $\left(\left|x_{2}^{R}\right|,\left|x_{2}^{I}\right|\right)$ lies in the set

$$
\mathcal{A}=\left\{0 \leqslant x \leqslant \frac{2^{k+1}}{\pi}, 0 \leqslant y \leqslant \frac{2^{k+1}}{\pi}, x^{2}+y^{2} \leqslant 2^{2 k-1}\right\}
$$

Let $\mathcal{C}=\left\{(x, y) \in \mathbb{R}^{2}: x^{2}+y^{2}=2^{2 k-1}\right\}$ and $(a, b) \in \mathcal{C}$, one equation of the tangent line to $\mathcal{C}$ at $(a, b)$ is

$$
\frac{\partial\left(x^{2}+y^{2}\right)}{\partial x}(a, b)(x-a)+\frac{\partial\left(x^{2}+y^{2}\right)}{\partial y}(a, b)(y-b)=0, \text { i.e., } a x+b y=a^{2}+b^{2} .
$$

If we denote $\mathcal{D}=\left\{(x, y) \in \mathbb{R}^{2}: x^{2}+y^{2} \leqslant 2^{2 k-1}\right\}$, for any $(a, b) \in \mathcal{C}$, we have

$$
\begin{equation*}
\mathcal{A} \subset \mathcal{D} \subset\left\{(x, y) \in \mathbb{R}^{2}: a x+b y \leqslant a^{2}+b^{2}\right\} \tag{28}
\end{equation*}
$$

First, we assume $\left(\Delta_{\omega}^{R} / \Delta_{\omega}^{I}\right)^{2} \leqslant \pi^{2} / 8-1$. Let $\left(a_{0}, b_{0}\right)=\left(2^{k} \sqrt{\frac{1}{2}-\frac{4}{\pi^{2}}}, \frac{2^{k+1}}{\pi}\right)=$ $\left(\frac{2^{k+1}}{\pi} \sqrt{\frac{\pi^{2}}{8}-1}, \frac{2^{k+1}}{\pi}\right)$.

For any $(x, y) \in \mathcal{A}$, we have

- either $0 \leqslant x \leqslant x_{0}$, then

$$
\Delta_{\omega}^{R} x+\Delta_{\omega}^{I} y \leqslant \Delta_{\omega}^{R} x_{0}+\Delta_{\omega}^{I} y_{0}
$$

- or, we have, from $(28), 0 \geqslant a_{0}\left(x-a_{0}\right)+b_{0}\left(y-b_{0}\right)$. Now, recall that $a_{0} / b_{0}=\sqrt{\pi^{2} / 8-1} \geqslant \Delta_{\omega}^{R} / \Delta_{\omega}^{I}$ and $x \geqslant x_{0}$. Therefore, it comes

$$
0 \geqslant \frac{a_{0}}{b_{0}}\left(x-a_{0}\right)+\left(y-b_{0}\right) \geqslant \frac{\Delta_{\omega^{R}}}{\Delta_{\omega^{I}}}\left(x-a_{0}\right)+\left(y-b_{0}\right),
$$

i.e.,

$$
\Delta_{\omega}^{R} x+\Delta_{\omega}^{I} y \leqslant \Delta_{\omega}^{R} x_{0}+\Delta_{\omega}^{I} y_{0}
$$

The case $\left(\Delta_{\omega}^{R} / \Delta_{\omega}^{I}\right)^{2} \geqslant 1 /\left(\pi^{2} / 8-1\right)$ follows from symmetry.
Now, if we assume $\pi^{2} / 8-1<\left(\Delta_{\omega}^{R} / \Delta_{\omega}^{I}\right)^{2}<1 /\left(\pi^{2} / 8-1\right)$, we use CauchySchwarz inequality that yields, for any $(x, y) \in \mathcal{A}$,
$\Delta_{\omega}^{R} x+\Delta_{\omega}^{I} y \leqslant \sqrt{x^{2}+y^{2}} \sqrt{\left(\Delta_{\omega}^{R}\right)^{2}+\left(\Delta_{\omega}^{I}\right)^{2}} \leqslant 2^{k-1 / 2} \sqrt{\left(\Delta_{\omega}^{R}\right)^{2}+\left(\Delta_{\omega}^{I}\right)^{2}}$ since $(x, y) \in \mathcal{D}$.

In the following, we denote $P\left(\Delta_{\omega}^{R}, \Delta_{\omega}^{I}\right)$ the bound on $\Delta_{\omega}^{I}\left|x_{2}^{I}\right|+\Delta_{\omega}^{R}\left|x_{2}^{R}\right|$ given by Lemma 6. Define

$$
A_{1}^{R}:=\left|\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)-\omega^{I} x_{2}^{I}\right| .
$$

Notice that since $\widehat{x_{2}^{I}}$ is a floating-point number within $\delta_{2}^{I}$ from $x_{2}^{I}$, and since $\left|x_{2}^{I}\right| \leqslant \beta_{k}$, we have $\left|\widehat{x_{2}^{I}}\right| \leqslant \operatorname{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)$. We obtain,

$$
\begin{align*}
A_{1}^{R} & \leqslant\left|\mathrm{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)-\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right|+\left|\widehat{\omega^{I}} \widehat{x_{2}^{I}}-\omega^{I} x_{2}^{I}\right| \\
& \leqslant \frac{1}{2}\left(1-\mathbb{1}_{\widehat{\omega^{I}}}\right) \operatorname{ulp}^{*}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)+\left|\widehat{\omega^{I}} \widehat{x_{2}^{I}}-\widehat{\omega^{I}} x_{2}^{I}\right|+\left|\widehat{\omega^{I}} x_{2}^{I}-\omega^{I} x_{2}^{I}\right|  \tag{29}\\
& \leqslant \frac{1}{2}\left(1-\mathbb{1}_{\widehat{\omega^{I}}}\right) \operatorname{ulp}^{*}\left(\widehat{\omega^{I}} \mathrm{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)\right)+\left|\widehat{\omega^{I}}\right| \cdot \delta_{2}^{I}+\Delta_{\omega}^{I} \cdot\left|x_{2}^{I}\right| .
\end{align*}
$$

Define

$$
B_{1}^{R}:=\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)
$$

and

$$
C_{1}^{R}:=\left|\operatorname{RN}\left(B_{1}^{R}\right)-\left(\omega^{R} x_{2}^{R}-\omega^{I} x_{2}^{I}\right)\right| .
$$

Note that when $\widehat{\omega^{R}}=0, B_{1}^{R}$ is a floating-point number, hence no error is committed when rounding it. This implies that in all cases the error due to rounding $B_{1}^{R}$ is bounded by

$$
\frac{1}{2}\left(1-\mathbb{O}_{\widehat{\omega^{R}}}\right) \operatorname{ulp}^{*}\left(B_{1}^{R}\right)
$$

We have,

$$
\begin{align*}
C_{1}^{R} \leqslant & \left|\operatorname{RN}\left(\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right)-\left(\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\mathrm{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right)\right| \\
& +\left|\left(\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right)-\left(\omega^{R} x_{2}^{R}-\omega^{I} x_{2}^{I}\right)\right| \\
\leqslant & \frac{1}{2}\left(1-0 \widehat{\omega^{R}}\right) \operatorname{ulp}^{*}\left(B_{1}^{R}\right)+\left|\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\omega^{R} x_{2}^{R}\right|  \tag{30}\\
& +\left|\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)-\omega^{I} x_{2}^{I}\right| .
\end{align*}
$$

Let us first consider the term $\left|\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\omega^{R} x_{2}^{R}\right|$ in (30). We have

$$
\begin{aligned}
\left|\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\omega^{R} x_{2}^{R}\right| & \leqslant\left|\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\widehat{\omega^{R}} x_{2}^{R}\right|+\left|\widehat{\omega^{R}} x_{2}^{R}-\omega^{R} x_{2}^{R}\right| \\
& \leqslant\left|\widehat{\omega^{R}}\right| \cdot \delta_{2}^{R}+\Delta_{\omega}^{R} \cdot\left|x_{2}^{R}\right| .
\end{aligned}
$$

Therefore, the sum

$$
D_{1}^{R}:=\left|\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\omega^{R} x_{2}^{R}\right|+\left|\mathrm{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)-\omega^{I} x_{2}^{I}\right|
$$

that appears in (30) is bounded by $A_{1}^{R}+\left|\widehat{\omega^{R}}\right| \cdot \delta_{2}^{R}+\Delta_{\omega}^{R} \cdot\left|x_{2}^{R}\right|$, which implies from (29) and Lemma 6

$$
D_{1}^{R} \leqslant \frac{1}{2}\left(1-\mathbb{1}_{\widehat{\omega^{I}}}\right) \operatorname{ulp}^{*}\left(\widehat{\omega^{I}} \mathrm{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)\right)+\left|\widehat{\omega^{I}}\right| \cdot \delta_{2}^{I}+\left|\widehat{\omega^{R}}\right| \cdot \delta_{2}^{R}+P\left(\Delta_{\omega}^{R}, \Delta_{\omega}^{I}\right)
$$

Finally, in (30), we need to bound the term $\left|B_{1}^{R}\right|$, in order to obtain a bound on $\frac{1}{2} \mathrm{ulp}^{*}$ of that value. We have

$$
\left|\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\mathrm{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right| \leqslant\left|\widehat{\omega^{R}}\right| \cdot \mathrm{RZ}\left(\beta_{k}+\delta_{2}^{R}\right)+\mathrm{RN}\left(\left|\widehat{\omega^{I}}\right| \cdot \mathrm{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)\right)
$$

and we also have, using (27),

$$
\left|\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right| \leqslant\left|\omega^{R} x_{2}^{R}-\omega^{I} x_{2}^{I}\right|+D_{1}^{R} \leqslant 2^{k-1 / 2}+D_{1}^{R}
$$

All this gives

$$
\left|B_{1}^{R}\right| \leqslant \min \left\{2^{k-1 / 2}+D_{1}^{R} ;\left|\widehat{\omega^{R}}\right| \cdot \operatorname{RZ}\left(\beta_{k}+\delta_{2}^{R}\right)+\mathrm{RN}\left(\left|\widehat{\omega^{I}}\right| \cdot \mathrm{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)\right)\right\}
$$

Now, we have all the elements for obtaining a bound on $C_{1}^{R}$.

$$
C_{1}^{R} \leqslant \frac{1}{2}\left(1-\mathbb{O}_{\widehat{\omega^{R}}}\right) \operatorname{ulp}^{*}\left(B_{1}^{R}\right)+D_{1}^{R}
$$

Finally, define

$$
Z_{1}^{R}:=\widehat{x_{1}^{R}}+\operatorname{RN}\left(\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right)
$$

so that $\widehat{y_{1}^{R}}=\operatorname{RN}\left(Z_{1}^{R}\right)$. Since $\widehat{x_{1}^{R}}$ is a floating-point number less than or equal to $\beta_{k}+\delta_{1}^{R}$, it is less than or equal to $\operatorname{RZ}\left(\beta_{k}+\delta_{1}^{R}\right)$. We therefore have

$$
Z_{1}^{R} \leqslant \operatorname{RZ}\left(\beta_{k}+\delta_{1}^{R}\right)+\left|\operatorname{RN}\left(B_{1}^{R}\right)\right| .
$$

We can now bound the error on $y_{1}^{R}$ :

$$
\begin{aligned}
\left|\widehat{y_{1}^{R}}-y_{1}^{R}\right|= & \left|\operatorname{RN}\left(Z_{1}^{R}\right)-\left(x_{1}^{R}+\omega^{R} x_{2}^{R}-\omega^{I} x_{2}^{I}\right)\right| \\
\leqslant & \left.\mid \operatorname{RN}\left(Z_{1}^{R}\right)-Z_{1}^{R}\right\rfloor+\left|Z_{1}^{R}-\left(x_{1}^{R}+\omega^{R} x_{2}^{R}-\omega^{I} x_{2}^{I}\right)\right| \\
\leqslant & \frac{1}{2} \operatorname{ulp}^{*}\left(Z_{1}^{R}\right)+\left|\widehat{x_{1}^{R}}-x_{1}^{R}\right| \\
& +\left|\operatorname{RN}\left(\widehat{\omega^{R}} \widehat{x_{2}^{R}}-\operatorname{RN}\left(\widehat{\omega^{I}} \widehat{x_{2}^{I}}\right)\right)-\left(\omega^{R} x_{2}^{R}-\omega^{I} x_{2}^{I}\right)\right| \\
\leqslant & \frac{1}{2} \operatorname{ulp}^{*}\left(\operatorname{RZ}\left(\beta_{k}+\delta_{1}^{R}\right)+\operatorname{RN}\left(B_{1}^{R}\right)\right)+\delta_{1}^{R}+C_{1}^{R} .
\end{aligned}
$$

Hence, if we call $\overline{B_{1}^{R}}, \overline{C_{1}^{R}}, \overline{D_{1}^{R}}$ the bounds we have obtained on $\left|B_{1}^{R}\right|, C_{1}^{R}$ and $D_{1}^{R}$, we will choose

$$
\eta_{1}^{R}=\eta_{2}^{R}=\frac{1}{2} \operatorname{ulp}^{*}\left(\mathrm{RZ}\left(\beta_{k}+\delta_{1}^{R}\right)+\mathrm{RN}\left(\overline{B_{1}^{R}}\right)\right)+\delta_{1}^{R}+\overline{C_{1}^{R}}
$$

The same bound straightforwardly applies to $\left|\widehat{y_{2}^{R}}-y_{2}^{R}\right|$. To deduce a bound on $\left|\widehat{y_{1}^{I}}-y_{1}^{I}\right|$ and $\left|\widehat{y_{2}^{I}}-y_{2}^{I}\right|$ it suffices to notice that in (26), one gets line 3 from line 1 and line 4 from line 2 by replacing $\widehat{x_{1}^{R}}$ by $\widehat{x_{1}^{I}}$, exchanging $\widehat{\omega^{R}}$ and $\widehat{\omega^{I}}$, and letting $\widehat{x_{2}^{R}}$ and $\widehat{x_{2}^{I}}$ unchanged. Hence, in the final error formulas, one will have to replace $\delta_{1}^{R}$ by $\delta_{1}^{I}$, exchange $\widehat{\omega^{R}}$ and $\widehat{\omega^{I}}$, exchange $\Delta_{\omega}^{R}$ and $\Delta_{\omega}^{I}$, and let $\delta_{2}^{R}$ and $\delta_{2}^{I}$ unchanged. We obtain,

Lemma 7. We have

$$
\begin{aligned}
& \left|\widehat{y_{1}^{R}}-y_{1}^{R}\right| \leqslant \eta_{1}^{R}, \quad\left|\widehat{y_{2}^{R}}-y_{2}^{R}\right| \leqslant \eta_{2}^{R} \\
& \left|\widehat{y_{1}^{I}}-y_{1}^{I}\right| \leqslant \eta_{1}^{I}, \quad\left|\widehat{y_{2}^{I}}-y_{2}^{I}\right| \leqslant \eta_{2}^{I}
\end{aligned}
$$

where

$$
\begin{equation*}
\eta_{1}^{R}=\eta_{2}^{R}=\frac{1}{2} \operatorname{ulp}^{*}\left(\operatorname{RZ}\left(\beta_{k}+\delta_{1}^{R}\right)+\operatorname{RN}\left(\overline{B_{1}^{R}}\right)\right)+\delta_{1}^{R}+\overline{C_{1}^{R}} \tag{31}
\end{equation*}
$$

with

$$
\overline{B_{1}^{R}}=\min \left\{2^{k-1 / 2}+\overline{D_{1}^{R}} ;\left|\widehat{\omega^{R}}\right| \cdot \operatorname{RZ}\left(\beta_{k}+\delta_{2}^{R}\right)+\mathrm{RN}\left(\left|\widehat{\omega^{I}}\right| \cdot \operatorname{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)\right)\right\} .
$$

and

$$
\overline{C_{1}^{R}}=\frac{1}{2}\left(1-0_{\widehat{\omega^{R}}}\right) \operatorname{ulp}^{*}\left(\overline{B_{1}^{R}}\right)+\overline{D_{1}^{R}} ;
$$

and

$$
\overline{D_{1}^{R}}=\frac{1}{2}\left(1-\mathbb{1}_{\widehat{\omega^{I}}}\right) \operatorname{ulp}^{*}\left(\widehat{\omega^{I}} \cdot \mathrm{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)\right)+\left|\widehat{\omega^{I}}\right| \cdot \delta_{2}^{I}+\left|\widehat{\omega^{R}}\right| \cdot \delta_{2}^{R}+P\left(\Delta_{\omega}^{R}, \Delta_{\omega}^{I}\right)
$$

and

$$
\begin{equation*}
\eta_{1}^{I}=\eta_{2}^{I}=\frac{1}{2} \operatorname{ulp}^{*}\left(\operatorname{RZ}\left(\beta_{k}+\delta_{1}^{I}\right)+\operatorname{RN}\left(\overline{B_{1}^{I}}\right)\right)+\delta_{1}^{I}+\overline{C_{1}^{I}} \tag{32}
\end{equation*}
$$

with

$$
\overline{B_{1}^{I}}=\min \left\{2^{k-1 / 2}+\overline{D_{1}^{I}} ;\left|\widehat{\omega^{I}}\right| \cdot \operatorname{RZ}\left(\beta_{k}+\delta_{2}^{R}\right)+\mathrm{RN}\left(\left|\widehat{\omega^{R}}\right| \cdot \mathrm{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)\right)\right\}
$$

and

$$
\overline{C_{1}^{I}}=\frac{1}{2}\left(1-\mathbb{O}_{\widehat{\omega^{I}}}\right) \operatorname{ulp}^{*}\left(\overline{B_{1}^{I}}\right)+\overline{D_{1}^{I}} ;
$$

and
$\overline{D_{1}^{I}}=\frac{1}{2}\left(1-\mathbb{1}_{\widehat{\omega^{R}}}\right) \operatorname{ulp}^{*}\left(\widehat{\omega^{R}} \cdot \mathrm{RZ}\left(\beta_{k}+\delta_{2}^{I}\right)\right)+\left|\widehat{\omega^{R}}\right| \cdot \delta_{2}^{I}+\left|\widehat{\omega^{I}}\right| \cdot \delta_{2}^{R}+P\left(\Delta_{\omega}^{R}, \Delta_{\omega}^{I}\right)$.
We can now use Lemma 7 to "propagate" the error bounds. The structure of the propagation algorithm is exactly the structure of the FFT algorithm. In the pseudcode of Figure 1 we can just replace the two lines
$y[j 1]=x[j 1]+$ omega $[k, j] \cdot x[j 2]$
$y[j 2]=x[j 1]-$ omega $[k, j] \cdot x[j 2]$
by the calculation of error bounds on the real and imaginary parts of y[j1] and $y[j 2]$ from the error bounds on the real and imaginary parts of $x[j 1]$ and $x[j 2]$ using Eqs (31) and (32). However, instead or starting from Step $k=1$ with initial error bounds equal to zero (the input values are assumed exact), one will obtain tighter error bounds by starting from $k=3$, with initial error bounds equal to the straightforward value $4 u$.

The obtained bounds are given in Table 6.

## Discussion and conclusion

If we consider errors bounds in terms of the 2-norm, in all considered cases, Theorem 7 gives a smaller bound than the previously published ones (the difference is clear in single precision, and by a tight margin in double precision). When the infinite norm is at stake, using again Theorem 7 and (7) has its interest: in all considered cases (see Table 5), it gives better bounds than Henrici's theorem (Theorem 5), without the annoyance of the $\mathcal{O}\left(u^{2}\right)$ terms. The iterative method developed in Section 5.2 gives a better bound than Theorem 7 and (7) only for reasonably small input size (roughly speaking for $N<2^{12}$, see Tables 5 and 6).

When one tries to run the FFT algorithm with input values chosen randomly, one obtains errors that are much smaller than the error bounds presented in this paper and the FFT literature. This may make one believe that the bounds are rather loose and need to be significantly improved. The family of examples built

Table 6: Bounds on $\|X-\hat{X}\|_{\infty}^{\perp}$, provided by the iterative method. We assume double-precision arithmetic $(p=53)$, and we also assume that an FMA instruction is available. These bounds are for $\|x\|_{\infty}^{\perp} \leqslant 1$. To obtain bounds for $\|x\|_{\infty}^{\perp} \leqslant 2^{m}$, it suffices to multiply all the values by $2^{m}$.

| $N$ | Bound on $\\|X-\hat{X}\\|_{\infty}^{\perp}$ |
| :--- | :--- |
| $2^{5}$ | $294.21 \cdot u$ |
| $2^{8}$ | $5757.7 \cdot u$ |
| $2^{10}$ | $36677 \cdot u$ |
| $2^{12}$ | $222685 \cdot u$ |
| $2^{14}$ | $1.321 \times 10^{6} \cdot u$ |
| $2^{16}$ | $7.682 \times 10^{6} \cdot u$ |
| $2^{18}$ | $4.413 \times 10^{7} \cdot u$ |
| $2^{20}$ | $2.519 \times 10^{8} \cdot u$ |

in Section 5.1 shows that this is not the case. The obtained errors (for which we have no proof, and, by the way, no strong reason to believe, that they are worst case errors) are of the same order of magnitude (approximately 8 times smaller) as the bounds given by Theorem 7 and (7), as shown in Table 5.

Finally, the upper bound $\|x\|_{\infty}^{\perp} \cdot N \cdot 4 / \pi$ on the values that can appear in intermediate calculations, given in Section 3 (it was built to be used in Section 5.2), can also be of interest for the designers of hardware implementations of the FFT, since they need to size the internal representations of numbers to the smallest size that makes it possible to prevent overflows.

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