

Data Units as (Co-)Clustering Model Enlargement Christophe Biernacki, Alexandre Lourme

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Clustering searches a hidden structure among data. Co-Clustering [9] and Co-Clustering [7]. But, most of the Mixture Models used in (Co-)Clustering earches a structure among data and variables at the same time. are scale sensitive : changing one descriptor unit/coding may change the estimated structure(s). Instead of being a drawback such a mathematical unsustainability is an opportunity to enlarge the existing set of (Co-)Clustering models; indeed, combining one standard model with several data units provides a new collection of (Co-)Clustering models needing few creative efforts.

Model-Based Clustering and Co-Clustering

Targets

 $\mathbf{x} = (x_{i,i})$: a $n \times d$ data matrix of n individuals (rows) described by d features (columns). Clustering Target : finding a K-class partition $\mathbf{z} = (z_{i,k}) \in \{0,1\}^{n \times K}$ of the rows : $\overline{z_{i,k}} = 1$ iff $\mathbf{x}_{i,\bullet} = (x_{i,1}, \dots, x_{i,d}) \in$ Individual Class k.

<u>Co-Clustering Target</u> : finding \mathbf{z} and a *L*-block partition $\mathbf{w} = (w_{j,l}) \in \{0,1\}^{d \times L}$ of the columns : $w_{j,l} = 1$ iif $\mathbf{x}_{\bullet,j} = (x_{1,j}, \dots, x_{n,j})' \in \text{Feature Block } l.$

Models

Clustering Model : the pdf of \mathbf{x} is the likelihood of a K-component mixture model :

$$p(\mathbf{x}; \boldsymbol{\theta}) = \prod_{i=1}^{n} \sum_{k=1}^{K} \pi_k f(\mathbf{x}_{i, \bullet}; \boldsymbol{\alpha}_k)$$

where π_k and $f(\circ; \boldsymbol{\alpha}_k)$ denote respectively the weight and the pdf of Individual Class k.

Co-Clustering Model (Latent Block Model) : the pdf of \mathbf{x} is :

$$p(\mathbf{x};\boldsymbol{\theta}) = \sum_{\mathbf{z},\mathbf{w}} \prod_{i,k} \pi_k^{z_{i,k}} \prod_{j,l} \rho_l^{w_{j,l}} \prod_{i,j,k,l} \{f(x_{i,j};\boldsymbol{\alpha}_{k,l})\}^{z_{i,k}w_{j,l}}$$
(2)

where π_k is the weight of individual Class k, ρ_l the weight of Feature Block l and $f(\circ; \boldsymbol{\alpha}_{k,l})$ the pdf of one feature of Feature Block l, in Individual Class k.

Inference

Iterative procedures deriving from the EM algorithm [5] can be used to maximize (1) or (2) with respect to $\boldsymbol{\theta}$, providing the Maximum Likelihood estimate $\hat{\boldsymbol{\theta}}$. Clustering Inference. A SEM algorithm [4] implemented into the MixtComp software^a estimates $\boldsymbol{\theta}$ even when (i) **x** includes missing data (ii) **x** columns are mixed type (nominal, count, continuous, etc.). A SE final step (SEM without M step) provides the estimated partition $\hat{\mathbf{z}}$.

Co-Clustering Inference. A SEM-Gibbs algorithm [7, p.74] implemented into the BlockCluster software^a estimates $\boldsymbol{\theta}$ when features are all continuous/binary/categorical/contigency. A SE final step (SEM without M step) provides the estimated partitions $\hat{\mathbf{z}}, \hat{\mathbf{w}}$.

Model Selection

Clustering Model Selection. Noting Θ the space of θ , a clustering model is a 3-tuple m = (K, f, Θ) and BIC criterion [11] defined by : $BIC(\boldsymbol{m}) = -\log p(\mathbf{x}; \hat{\boldsymbol{\theta}}) + (dof/2)\log(n)$ enables to : (i) assess a tradeoff between m goodness of fit and parsimony (ii) compare competing models inferred on \mathbf{x} (iii) select the class pdf f as the class number K. Co-Clustering Model Selection. ICL criterion [2] computed on a co-clustering model

 $\overline{\mathbf{m}} = (K, L, f, \Theta)$ is the logarithm of the integrated likelihood of the complete data $(\mathbf{x}, \mathbf{z}, \mathbf{w}) : ICL(\mathbf{m}) = \log \int_{\mathbf{\Theta}} p(\mathbf{x}, \mathbf{z}, \mathbf{w}; \mathbf{\theta}) d\mathbf{\theta}$. So, *ICL* favours well separated Individual Classes and well separated Feature Blocks. Moreover, when all features are categorical ICL is tractable without approximation [7, p.97].

a. freely available on the MASSICCC web platform https://modal-research-dev.lille.inria.fr

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DATA UNITS AS (CO-)CLUSTERING MODEL ENLARGEMENT

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Unit Change and Model Enlar

Data Types

Each column of \mathbf{x} is a series of numbers since any *M*-level as a M-dimensional vector of dummy variables.

The type of Feature j depends on the set \mathcal{X}_j where $x_{1,j}$ $\mathcal{X}_j = \mathbb{R}, \, \mathcal{X}_j = \mathbb{N} \text{ or } \mathcal{X}_j = \{0, 1\}, \, x_{1,j}, \dots, x_{n,j} \text{ are contin}$

Unit Changes

Feature j can be rescaled/recoded through ϕ_i , a bijective of rescaled data : $\phi_i(\mathcal{X}_i)$.

Remark. The global scaling map $\boldsymbol{\phi} = (\phi_1, \dots, \phi_d)$ is :

- feature wise : the rescaled series $\mathbf{x}^{\phi}_{\bullet i}$ only depends on \mathbf{x} - homogeneous across classes : $\phi_i(x_{i,j})$ does not depend - non parametric

Enlarging the (Co-)Clustering Model

Assuming (1) as a pdf for the rescaled data $\mathbf{x}^{\boldsymbol{\phi}} = (\phi_i(x_i, \mathbf{x}_i))$

$$p^{\phi}(\mathbf{x}, \boldsymbol{\theta}) = \prod_{i=1}^{n} \sum_{k=1}^{K} [\pi_k f(\mathbf{x}_{i, \bullet}^{\phi}, \boldsymbol{\alpha}_k) \prod_{j \in \mathcal{A}} [\pi_k f(\mathbf{x}_{i, \bullet}^{\phi}, \boldsymbol{\alpha}_k)]]$$

where $\mathbf{x}_{i,\bullet}^{\boldsymbol{\varphi}} = (\phi_1(x_{i,1},\ldots,\phi_d(x_{i,d})))$ and $J \subset \{1,\ldots,d\}$ continuous features.

Assuming (2) as a pdf for the rescaled data $\mathbf{x}^{\boldsymbol{\phi}}$ leads to s

$$\phi^{\phi}(\mathbf{x}, \boldsymbol{\theta}) = \sum_{\mathbf{z}, \mathbf{w}} \prod_{i, k} \pi_k^{z_{i, k}} \prod_{j, l} \rho_l^{w_{j, l}} \prod_{i, j, k, l} [f(\phi_j(x_{i, k}))]$$

where $\gamma_{i,j} = |\phi'_i(x_{i,j})|$ if Feature j is continuous and $\gamma_{i,j}$

Any (co-)clustering model $p(\circ; \boldsymbol{\theta})$ on $\mathbf{x}^{\boldsymbol{\phi}}$ data produces a Both models $p(\circ; \boldsymbol{\theta})$ and $p^{\boldsymbol{\phi}}(\circ; \boldsymbol{\theta})$ can be compared on **x**

Consequences

In a clustering context.

 \circ Cluster analysis of *d*-dimensional continuous data with ↓ 28 Gaussian Mixture Models among which 1

• Only one alternative measurement unit is considere $\downarrow 12 \times (2^d - 1)$ additional models are immedia • Similar enlargement can be applied to other packages bgmm [1], mclust [6], pgmm [10], etc.

In a co-clustering context.

 \circ Co-Cluster analysis of *d*-dimensional binary data (0/1) 4 a convenient model : the Latent Block Mode \circ Each one of the *d* series is possibly recoded (permutation) $\downarrow 2^d - 2$ additional models immediately available

em algorithm for the mixture problem. Computatione 1985.

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université

gement	First Experiments and
	A Cluster Analysis Example (using Mixt
ominal variable can be coded	• R dataset rwm1984{COUNT} consists on $n = 3$
$., x_{n,j}$ leave. According to us/count/binary/etc. data.	bed by 11 variables : 4 count, 1 categorical, 5 b \cdot MixtComp model : count ~ Poisson, categor continuous ~ Gaussian + local independence \cdot Data Units. 4 maps ϕ are considered rescaling of the variables are recealed (rew units) (b) tip
p matching \mathcal{X}_j with a space	of the variables are rescaled (raw units) (b) the days instead of days (c) ages are shifted (youn education is shifted (shortest duration taken as
j	BIC values obtained by combining several units and \hat{K} Data units best BIC \hat{K}
<i>i</i> ,•	(a) raw counts (original units)5164721(b) half days into hospital5232720(c) shifted ages5183321(d) shifted years of education 50044 23
leads to set as a pdf for \mathbf{x} :	A Co-Cluster Analysis Example (using)
$_{i,j})]$ (3)	 The Congressional Voting Records Data Set^b; U.S. Congressmen on 16 votes. Standard coding : (1,0,0) for 'y', (0,1,0) for For each vote, an alternative coding : (0,1,0)
ountains the indices of the	$\cdot K = 2$ since the party (Democrat/Republican)
a pdf for \mathbf{x} :	(a) standard coICL 5,916.13error rate 0.4229
$(4) \qquad (4)$	ARI 0.0234 original data (left), co-
otherwise. model $p^{\phi}(\circ; \boldsymbol{\theta})$ on \mathbf{x} data. through <i>BIC</i> or <i>ICL</i> .	clustered data (right), Indi- vidual Class rule (horizon- tal) and Feature Block rule (vertical)
the R package mixmod [8]. 2 are scale dependent 4 for each continuous feature	Recoding five votes (i) provides the b trieve more accurately the party of ea coherence to the vote blocks
v available olving Gaussian mixtures :	Other clustering and co-clustering exa
	Chalenging Issues \cdot Each scaling map ϕ_i could (i) become paramet
K classes and L blocks.	on the class. Parametric classwise and featurew \cdot All combinations : unit \times model cannot be br
.d 1).	putational time when d is large. User friendly p of features to be rescaled. a. MASSICCC web platform https://modal-research-dev.lille.ir b. http://archive.ics.uci.edu/ml/machine-learning-databases/vo
atistics quarterly, 2 :73–82,	pervised and semi-supervised classification $Software, 67(6) : 241-270, 2015.$
Maximum likelihood from al statistical society. Series	[9] Geoffrey McLachlan and David Peel. <i>Finit</i> 2004.
modeling for model-based <i>niversity of Washington</i> :	[10] PD McNicholas, KR Jampani, AF McDaid, T monious gaussian mixture models. <i>R packag</i>
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