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Comparison of Residual and Hierarchical Finite Element Error Estimators in Eddy Current Problems

Zuqi Tang^{1,4}, Patrick Dular^{2,3}, Yvonnick Le M enach⁴, Emmanuel Creus e¹, Francis Piriou⁴

¹ Universit e Lille 1, LPP UMR 8524 and INRIA Lille Nord Europe, Villeneuve d'Ascq, F-59655 France

² University of Li ge, Dept. of Electrical Engineering and Computer Science, ACE, B-4000 Li ge, Belgium

³ F.R.S.-FNRS, Fonds de la Recherche Scientifique, Belgium

⁴ Universit e Lille1, L2EP, Villeneuve d'Ascq, F-59655 France.

Abstract— The finite element computation of eddy current problems gives numerical error. This error cannot be calculated, but can only be estimated. Among all error estimators already developed, it is proposed to compare two proven estimators called residual and hierarchical error estimators.

I. INTRODUCTION

To evaluate the quality of numerical computation of low frequency electromagnetic finite element (FE) problems, a lot of error estimators have been developed. Some of them are based on energy minimization. Others, called equilibrated estimator, are based on the verification of the constitutive relations. More recently the residual *a posteriori* error estimator (REE) [1-4] and the hierarchical error estimator (HEE) have been proposed [5]. In the case of the REE, all the terms weakly verified are evaluated to obtain an estimation of the error [4]. On the other hand, with the HEE, the error estimation is given by using hierarchical higher order (HO) test functions (TFs) [6] in the FE formulation, either to evaluate some residues or to obtain HO solutions [5].

In this paper, we propose to apply the REE to FEs up to second order and to compare the obtained results with the HEE on the same mesh.

II. ERROR ESTIMATORS

A. Weak finite element magnetodynamic formulation

The weak magnetic vector potential *a*-formulation of the magnetodynamic problem is obtained from the weak form of the Amp ere equation, i.e. [5],

$$(\mathbf{h}, \text{curl } \mathbf{a}')_{\Omega} - (\mathbf{j}, \mathbf{a}')_{\Omega} + \langle \mathbf{n} \times \mathbf{h}, \mathbf{a}' \rangle_{\Gamma} = 0, \quad \forall \mathbf{a}' \in F^1(\Omega), \quad (1)$$

where $F^1(\Omega)$ is a curl-conform function space defined on Ω ; $(\cdot, \cdot)_{\Omega}$ and $\langle \cdot, \cdot \rangle_{\Gamma}$ denote a volume integral in Ω and a surface integral on Γ , respectively, of the product of their field arguments; \mathbf{n} is the unit normal on Γ exterior to Ω . Magnetic field \mathbf{h} and electric current density \mathbf{j} are related to magnetic flux density \mathbf{b} and electric field \mathbf{e} (in $\Omega_c \subset \Omega$, with $\Omega = \Omega_c \cup \Omega_c^C$), respectively, through the material relations $\mathbf{h} = \mu^{-1} \mathbf{b}$ and $\mathbf{j} = \mathbf{j}_s + \sigma \mathbf{e}$, with μ the magnetic permeability, σ the electric conductivity and \mathbf{j}_s the source current density in stranded inductors in $\Omega_s \subset \Omega_c^C$. With the magnetic vector potential \mathbf{a} defined via $\mathbf{b} = \text{curl } \mathbf{a}$ and $\mathbf{e} = -\partial_t \mathbf{a} - \text{grad } v$ (∂_t is $j\omega$ with ω the angular frequency in the frequency domain), weak formulation (1) gives the *a-v* formulation (or *A-φ* formulation with notations of [4,5]), i.e.

$$(\mu^{-1} \text{curl } \mathbf{a}, \text{curl } \mathbf{a}')_{\Omega} + (\sigma \partial_t \mathbf{a}, \mathbf{a}')_{\Omega_c} + (\sigma \text{grad } v, \mathbf{a}')_{\Omega_c} - (\mathbf{j}_s, \mathbf{a}')_{\Omega_s} + \langle \mathbf{n} \times \mathbf{h}, \mathbf{a}' \rangle_{\Gamma} = 0, \quad \forall \mathbf{a}' \in F^1(\Omega), \quad (2)$$

with $F^1(\Omega)$ gauged in Ω_c^C , and containing the basis functions for \mathbf{a} as well as for the test function \mathbf{a}' (at the discrete level, this space is defined by edge FEs; the gauge is based on the tree-co-tree technique); note that $F^1(\Omega)$ can be non-gauged if a proper resolution scheme is used [4]. Once a solution is obtained in a particular discrete function space with (2), it can be used *a posteriori* to estimate the associated error.

B. Residual error estimator (REE)

Generally, the discretization error committed by the FE method can be resumed by the error on the energy. In the case of the *a-v* formulation, the local error on \mathbf{a} and v can be written $\mathbf{e}_a = \mathbf{a} - \mathbf{a}_h$ and $\mathbf{e}_v = v - v_h$, with \mathbf{a} and v the exact solutions of the problem and \mathbf{a}_h and v_h the numerical ones. From these local errors, the global error norm can be written, involving error terms on magnetic energy and Joule losses, i.e.

$$\epsilon^2 = \int_{\Omega} \mu^{-1} |\text{curl } \mathbf{e}_a|^2 + \int_{\Omega_c} \frac{\sigma}{\omega} |j\omega \mathbf{e}_a + \text{grad } \mathbf{e}_v|^2. \quad (3)$$

Carrying out an ad-hoc Helmholtz decomposition of (1) and using suitable interpolation operators and Cauchy-Schwarz inequality, the efficiency and the reliability of REE can be obtained [4]. For the *a-v* formulation, the REE η_{ω} on FE $\omega \subset \Omega$ quantifies all the terms weakly verified in (2) via

$$\eta_{\omega}^2 = \eta_{\omega,1}^2 + \eta_{\omega,2}^2 + \eta_{\omega,3}^2 + \sum_{\gamma \subset \partial\omega} (\eta_{\gamma,1}^2 + \eta_{\gamma,2}^2) \quad (4)$$

with

$$\eta_{\omega,1} = h_{\omega} \left\| \pi_h \mathbf{j}_s - \text{curl}(\mu^{-1} \text{curl } \mathbf{a}) - \sigma(j\omega \mathbf{a} + \text{grad } v) \right\|_{\omega}, \quad (5a)$$

$$\eta_{\omega,2} = h_{\omega} \left\| \text{div}(\sigma(j\omega \mathbf{a} + \text{grad } v)) \right\|_{\omega}, \quad (5b)$$

$$\eta_{\omega,3} = h_{\omega} \left\| \mathbf{j}_s - \pi_h \mathbf{j}_s \right\|_{\omega}, \quad (5c)$$

$$\eta_{\gamma,1} = h_{\gamma}^{1/2} \left\| [\mathbf{n} \times \mu^{-1} \text{curl } \mathbf{a}]_{\gamma} \right\|_{\gamma}, \quad (5d)$$

$$\eta_{\gamma,2} = h_{\gamma}^{1/2} \left\| [\sigma(j\omega \mathbf{a} + \text{grad } v) \cdot \mathbf{n}]_{\gamma} \right\|_{\gamma}. \quad (5e)$$

Operator π_h represents the projection operator from $H(\text{div}, \Omega)$ in a discrete approximation space. Coefficients h_{ω} and h_{γ} stand for the diameter of the smallest sphere containing the element ω and the diameter of the smallest circle containing the facet γ , respectively. All these terms must be evaluated on

each FE. Terms (5a-b) quantify the error of the equation to solve. Term (5c) corresponds to the discretization error of the source term. Finally, terms (5d-e) evaluate the jumps (discontinuities) of the tangential component of \mathbf{h} and the normal component of \mathbf{j} through the element facets.

C. Hierarchical error estimator (HEE)

Once weak form (2) has been solved, it is evaluated with the corresponding solution with HO basis functions (BFs) $\mathbf{a}_p' \in F_p^1(\Omega)$ as TFs. This gives a left hand side of (2) not equal to zero anymore but defining a residue R_p that can serve as an error estimator, called HEE [5], i.e.

$$R_p = (\mathbf{u}^{-1} \text{curl} \mathbf{a}, \text{curl} \mathbf{a}_p')_{\Omega} + (\sigma \partial_t \mathbf{a}, \mathbf{a}_p')_{\Omega_c} + (\sigma \text{grad} v, \mathbf{a}_p')_{\Omega_c} - (\mathbf{j}_s, \mathbf{a}_p')_{\Omega_s} + \langle \mathbf{n} \times \mathbf{h}, \mathbf{a}_p' \rangle_{\Gamma}, \quad \mathbf{a}_p' \in F_p^1(\Omega), \quad (6)$$

Hierarchical HO-BFs can be associated with edges, facets and volumes of finite elements (FEs) [6]. For an edge or a facet HO BF \mathbf{a}_p' , respectively in 2-D and 3-D, shared by two FEs ω_a and ω_b , with interface γ_{ab} , residue (6) has a contribution only from these two FEs. Restricting the form (6) to ω_a and ω_b separately, with \mathbf{a}_p' equal to zero on all the boundaries except γ_{ab} , integrating their first volume integral term by parts, and adding the resulting forms, one gets

$$R_p = (\text{curl} \mathbf{h} - \mathbf{j}, \mathbf{a}_p')_{\omega_a + \omega_b} - \langle \mathbf{n}_{ab} \times (\mathbf{h}|_{\omega_a} - \mathbf{h}|_{\omega_b}), \mathbf{a}_p' \rangle_{\gamma_{ab}}, \quad (7)$$

with $\mathbf{n}_{ab} = \mathbf{n}|_{\partial\omega_a} = -\mathbf{n}|_{\partial\omega_b}$ the unit normal to γ_{ab} exterior to ω_a . Residue R_p , calculated via (6), is therefore a union of two errors, pointed out by (7): an error on the equation to solve, via the volume integral term on $\omega_a + \omega_b$, and an error on the tangential continuity of \mathbf{h} , via the surface integral term on γ_{ab} .

For an HO-BF \mathbf{a}_p' associated with the volume of a FE ω_a , thus with a zero trace on $\partial\omega_a$, the residue given by (6) is reduced to

$$R_p = (\text{curl} \mathbf{h} - \mathbf{j}, \mathbf{a}_p')_{\omega_a}. \quad (8)$$

Using TFs $\mathbf{a}' = \text{grad} v'$ in (2) (which is implicitly the case with edge FEs for \mathbf{a}' , that contains the gradient of nodal FEs), weak form (2) becomes the weak form of $\text{div} \mathbf{j} = 0$, i.e.

$$(\sigma \partial_t \mathbf{a}, \text{grad} v')_{\Omega_c} + (\sigma \text{grad} v, \text{grad} v')_{\Omega_c} - \langle \mathbf{n} \cdot \mathbf{j}, v' \rangle_{\Gamma_s} = 0, \quad (9)$$

with Γ_s some possible cross sections of conductors in Ω_c . A residue $R_{v,p}$ can be also defined for (9) when using HO TFs v_p' for v' , being also equal to

$$R_{v,p} = (\text{div} \mathbf{j}, v_p')_{\omega_a + \omega_b} - \langle \mathbf{n}_{ab} \cdot (\mathbf{j}|_{\omega_a} - \mathbf{j}|_{\omega_b}), v_p' \rangle_{\gamma_{ab}}. \quad (10)$$

Residue $R_{v,p}$ points out an error on $\text{div} \mathbf{j} = 0$ on $\omega_a + \omega_b$ and an error on the normal continuity of \mathbf{j} on γ_{ab} .

A useful additional step can consist in using R_p as a source (right hand side) for a local FE problem (limited to the FE support of each TF), calculating the HO correction \mathbf{a}_p to be given to solution \mathbf{a} for satisfying the HO weak formulation [5], i.e.

$$(\mathbf{u}^{-1} \text{curl} \mathbf{a}_p, \text{curl} \mathbf{a}_p')_{\Omega} + (\sigma \partial_t \mathbf{a}_p, \mathbf{a}_p')_{\Omega_c} + (\sigma \text{grad} v_p, \mathbf{a}_p')_{\Omega_c} = -R_p. \quad (11)$$

This allows an error estimation directly relative to the scale of the solution, whereas R_p is only relative to the others residues

for the same mesh (as for the REE; the direct use of R_p can define another kind of REE).

III. COMPARISON OF ERROR ESTIMATORS

REE and HEE show some equivalences and differences. Equivalences can be found in all the volume and surface integral contributions involved in the estimators, where both weakly defined equations and interface conditions are evaluated in a way to express their related contributions to the errors. A difference appears regarding the weighting of the contributions, with coefficients defined as smallest diameters for the REE while such coefficients are implicitly defined via integrations in each FE with the HEE. This gives differences, in particular in anisotropic meshes.

Local contributions to the errors are related to each single FE with the REE and with groups of FEs (sharing edges or facets) or single FE (for volume TFs) with the HEE. In both estimators, the contributions are only relative to other similar contributions (which can be useful for mesh adaptation), and are thus not expressed at the scale of the solution. However, the HEE can be extended to give a solution-relative error by calculating HO corrections.

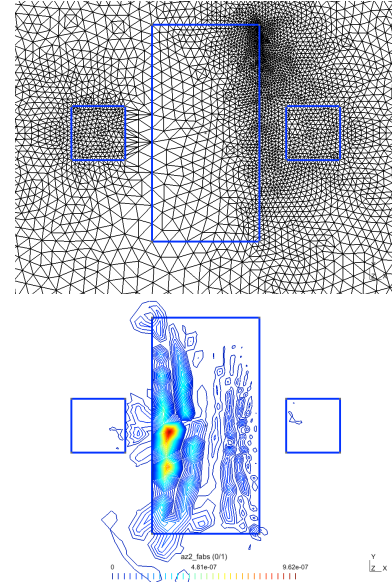


Fig. 1. Example of distribution of local error estimation in an eddy current problem. The highest error is located in the skin depth with a too coarse mesh.

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