# A machine learning approach for online IPC controller selection based on wind features

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#### Introduction

- Motivation
- The idea

#### 2 Methodology

- Cost function
- Relating wind to fatigue

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- Perspectives
- References



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#### Context

#### Wind Energy growth

Wind energy capacity is **exponentially growing**, involving billions of €.



Figure: Cumulative installed capacity of wind energy (ourwoldindata.org).



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Introduction	
The idea	
Individual Pitch Control (IPC)	Control





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# The idea

#### Individual Pitch Control (IPC)

- In addition to Collective Pitch Control (CPC)
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- Many works implemented, with different control architectures
- **Trade offs** between pitch activity, blade fatigue reduction and tower fatigue increase
- The most efficient controller architecture might depend on the disturbance characteristics





The idea		
Wind	Tradeoffs Cost function	Control
	<ul> <li>Wind resource assessm</li> <li>Wind turbulent sp with diurnal and variations [Van de</li> </ul>	ent pectrum varies <b>synoptic</b> er Hoven, 1957]





#### Wind resource assessment

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#### Wind resource assessment

- Wind turbulent spectrum varies with diurnal and synoptic variations [Van der Hoven, 1957]
- [Clifton et al., 2013] clustered WT inflow winds on one site



















# Economic cost function computation

#### Cost function

$$\mathcal{C} = \sum_i \pi_i D_i$$

- ${\mathcal C}~\operatorname{{\bf Cost}}$  of the simulation in  $\in$
- $\pi_i$  Component *i* price of replacement (construction + transportation + installation)
- $D_i\;$  Component  $i\;$  damage under the simulation,  $D_i=1 \rightarrow$  the component is broken



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 $RAWS\,$  Rotor Averaged Wind Speed

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- RATI Rotor Averaged Turbulence Intensity



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CPC Proportional Integral (PI) controller designed as in [Jonkman et al., 2007]

# IPC Double SISO PI controller, with varying parameters $K_P$ and $K_I$

This results in 588 winds  $\times$  100 controllers = 58,800 simulations, which takes 2 weeks on a standard computer parallelized on CPU.



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Scatter plot of fatigue cost





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Controller	$R_2$	Decrease
1	0.93	0.23
2	0.96	0.35
3	0.93	0.36
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# Preliminary results

- 4 controllers complementary to each other are selected among the 100 candidates
- The regression algorithm manages to predict fatigue cost from wind features
- A relative fatigue cost decrease of 23% could be achieved from the best candidate

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- On-line validation in simulation on realistic wind scenarios with varying spectrum parameters
- Step up to advanced control techniques
- Extend wind space definition and improve regression scores
- Study more thoroughly wind evolution on long time scales (day, week)



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Journal of meteorology, 14(2):160–164.



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# Data Generation

#### Wind generation

- NREL wind generator TurbSim
- Coherent turbulent wind field generated from a wind spectrum
- Modification of spectrum parameters (direction, speed, turbulence intensity)
- 588 winds generated

#### Simulations

- NREL WT aeroelastic simulator FAST
- Each controller candidate is simulated with all the winds



# Fatigue theory

Palmgrem-Miner rule

$$D = \sum_{i} \frac{n_i}{N_i(L_i)}$$

 $D \in [0,1]$  is the damage endured D = 1 
ightarrow The component is broken

- $n_i$  is the number of hysteresis cycle i
- $N_i$  is the number of hysteresis cycle i that the component can endure in its lifetime
- $L_i$  is the amplitude of hysteresis cycle i

Hysteresis cycles are counted with a rainflow-counting algorithm.







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Parameters chosen: q = 0.1 and n = 4

