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► To cite this version:

Zeina Abu Aisheh, Sébastien Bougleux, Olivier Lézoray. p-Laplacian regularization of signals on directed graphs. International Symposium on Visual Computing, Nov 2018, Las Vegas, United States. pp.650-661. hal-01923318

HAL Id: hal-01923318

<https://hal.science/hal-01923318>

Submitted on 15 Nov 2018

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p -Laplacian regularization of signals on directed graphs^{*}

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Abstract. The graph Laplacian plays an important role in describing the structure of a graph signal from weights that measure the similarity between the vertices of the graph. In the literature, three definitions of the graph Laplacian have been considered for undirected graphs: the combinatorial, the normalized and the random-walk Laplacians. Moreover, a nonlinear extension of the Laplacian, called the p -Laplacian, has also been put forward for undirected graphs. In this paper, we propose several formulations for p -Laplacians on directed graphs directly inspired from the Laplacians on undirected graphs. Then, we consider the problem of p -Laplacian regularization of signals on directed graphs. Finally, we provide experimental results to illustrate the effect of the proposed p -laplacians on different types of graph signals.

Keywords: Directed graphs · p -Laplacian · Graph signal · Regularization.

1 Introduction

With the development of new sensors, signals can now be generated from many different sources providing images, meshes, social or biological networks, to quote a few. These signals often have a structure much more irregular than a classical Euclidean grid but they can be represented by graphs [9]. When data vectors are associated with graph vertices, a so-called *graph signal* is obtained. The new research field of signal processing on graphs aims at extending the classical discrete signal processing tools to signals living on an underlying irregular graph (see [14] for a review) and one of its key ingredients is the graph Laplacian. Indeed, the graph Laplacian plays an important role in describing the structure of a graph signal from weights that measure the similarity between the vertices of the graph [3]. Several definitions of the graph Laplacian have been considered so far for undirected graphs [10]: the combinatorial Laplacian, the normalized Laplacian and the random-walk Laplacian. These Laplacians have become increasingly popular in graph signal processing [13, 8, 16] and machine learning

^{*} This work received funding from the Agence Nationale de la Recherche (ANR-14-CE27-0001 GRAPH SIP), and from the European Union FEDER/FSE 2014/2020 (GRAPH SIP project).

[11, 10]. Some extensions of the Laplacian have been also proposed for directed graphs [4, 1, 7]. A nonlinear extension of the Laplacian also exists that is called the p -Laplacian. This latter operator has been considered for undirected graphs and enables to recover analogues (when $p = 2$) of the combinatorial Laplacian [2, 6] and of the normalized Laplacian [18]. Unfortunately there exists actually no formulation of the p -Laplacian for the general case of directed graphs and we propose in this paper three different formulations for the latter (i.e., combinatorial, normalized, and random-walk, similarly to the Laplacian on undirected graphs). Then, we consider the problem of p -Laplacian regularization of signals on directed graphs that minimizes a loss function plus a regularization term. To the best of our knowledge this is the first time that the use of the p -Laplacian on directed graphs is considered for graph signal regularization. Finally we show some results for the filtering of different graph signals.

2 Notations

We introduce in this section the notations that will be used in the paper. A graph represents a set of elements and a set of pairwise relationships between those elements [9]. The elements are called vertices and the relationships are called edges. Formally, a graph $\mathcal{G}$ [5] is defined by the sets $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ in which $\mathcal{E} \subseteq \mathcal{V} \times \mathcal{V}$. We denote the i th vertex as $v_i \in \mathcal{V}$. Since each edge is a subset of two vertices, we write $e_{ij} = \{v_i, v_j\}$. A graph is called directed when each edge e_{ij} contains an ordering of the vertices. A directed edge from v_j to v_i will be denoted $v_j \rightarrow v_i$. The edges of a graph can be weighted with a function denoted by $w : \mathcal{E} \rightarrow \mathbb{R}^+$. The adjacency matrix representation of directed graph is a $|\mathcal{V}| \times |\mathcal{V}|$ matrix $\mathbf{W}$ where $\mathbf{W}_{ij} = w(v_i, v_j)$ if $v_i \rightarrow v_j \in \mathcal{E}$ and 0 otherwise. For undirected graphs the matrix $\mathbf{W}$ is symmetric and $\mathbf{W}^T = \mathbf{W}$. This will not be the case in this paper since we consider directed graphs and if $v_i \rightarrow v_j \in \mathcal{E}$ this will not necessarily imply that $v_j \rightarrow v_i \in \mathcal{E}$ or that $w(v_i, v_j) = w(v_j, v_i)$. The out-degree of a node v_i , $d^+(v_i)$, is equal to $d^+(v_i) = \sum_{v_i \rightarrow v_j \in \mathcal{E}} w_{ij}$. The in-degree of a node v_i , $d^-(v_i)$, is equal to $d^-(v_i) = \sum_{v_j \rightarrow v_i \in \mathcal{E}} w_{ji}$. Note that in an undirected graph, $d^+(v_i) = d^-(v_i)$, $\forall v_i \in \mathcal{V}$ and is denoted $d(v_i)$. The out-degree matrix $\mathbf{D}_+$ is a diagonal matrix with $\mathbf{D}_{+ii} = d^+(v_i)$, and similarly for $\mathbf{D}_-$. When the graph is undirected, one has $\mathbf{D}_+ = \mathbf{D}_- = \mathbf{D}$. For undirected graphs, several Laplacian formulation exist [10]. The combinatorial Laplacian is the matrix $\mathbf{L} = \mathbf{D} - \mathbf{W}$. The normalized Laplacian is $\tilde{\mathbf{L}} = \mathbf{D}^{-1/2} \mathbf{L} \mathbf{D}^{-1/2} = \mathbf{I} - \mathbf{D}^{-1/2} \mathbf{W} \mathbf{D}^{-1/2}$. The random walk Laplacian is $\mathbf{L}^{rw} = \mathbf{D}^{-1} \mathbf{L} = \mathbf{I} - \mathbf{D}^{-1} \mathbf{W}$. Now we define the space of functions on graphs (i.e., for graph signals). Let $\mathcal{H}(\mathcal{V})$ be the Hilbert space of real-valued functions defined on the vertices of a graph, a graph signal is a function $f : \mathcal{V} \rightarrow \mathbb{R}^n$ of $\mathcal{H}(\mathcal{V})$ that maps each vertex to a vector $\mathbf{f}(v_i)$. The space $\mathcal{H}(\mathcal{V})$ is endowed with the usual inner product $\langle f, h \rangle_{\mathcal{H}(\mathcal{V})} = \sum_{v_i \in \mathcal{V}} f(v_i)h(v_i)$, where $f, h : \mathcal{V} \rightarrow \mathbb{R}$. Similarly, let $\mathcal{H}(\mathcal{E})$ be the space of real-valued functions defined on the edges of $\mathcal{G}$. It is endowed with the inner product $\langle F, H \rangle_{\mathcal{H}(\mathcal{E})} = \sum_{e_{ij} \in \mathcal{E}} F(e_{ij})H(e_{ij})$, where $F, H : \mathcal{E} \rightarrow \mathbb{R}$ are two functions of $\mathcal{H}(\mathcal{E})$.

3 p -Laplacian on directed graphs

3.1 Definitions

To define the p -Laplacian we need first to introduce several operators that operate on directed graphs. The formulation of these operators is similar to the one found in [18] but are expressed here on directed graphs. It is important to note that in contrast to undirected graphs, there has been few studies on Laplacian for directed graphs [4] and even less for the p -Laplacian [19]. The directed difference operator of a graph signal $f \in \mathcal{H}(\mathcal{V})$, called $d_w : \mathcal{H}(\mathcal{V}) \rightarrow \mathcal{H}(\mathcal{E})$, over a directed edge $v_i \rightarrow v_j$ is denoted by $(d_w f)(v_i, v_j)$. We do not explicitly provide now the definition of this difference operator and will show that with different definitions, different p -Laplacian on directed graphs can be formulated. The adjoint operator $d_w^* : \mathcal{H}(\mathcal{E}) \rightarrow \mathcal{H}(\mathcal{V})$, of a function $H \in \mathcal{H}(\mathcal{E})$, can then be expressed at a vertex $v_i \in \mathcal{V}$ by using the definition of the inner products since $\langle H, d_w f \rangle_{\mathcal{H}(\mathcal{E})} = \langle d_w^* H, f \rangle_{\mathcal{H}(\mathcal{V})}$. The gradient operator of a function $f \in \mathcal{H}(\mathcal{V})$, at vertex $v_i \in \mathcal{V}$, is the vector of all the weighted directed differences $(d_w f)(v_i, v_j)$, with respect to the set of outgoing edges $v_i \rightarrow v_j \in \mathcal{E}$:

$$(\nabla_{\mathbf{w}} \mathbf{f})(v_i) = ((d_w f)(v_i, v_j))^T, \forall (v_i \rightarrow v_j) \in \mathcal{E} . \quad (1)$$

Its $\mathcal{L}_p$ norm is defined by

$$\|(\nabla_{\mathbf{w}} \mathbf{f})(v_i)\|_p = \left[\sum_{v_i \rightarrow v_j \in \mathcal{E}} |(d_w f)(v_i, v_j)|^p \right]^{1/p} . \quad (2)$$

Then, the p -Laplacian $\Delta_w^p f : \mathcal{H}(\mathcal{V}) \rightarrow \mathcal{H}(\mathcal{V})$ can be formulated as the discrete analogue of the continuous one by [6]:

$$\Delta_w^p f(v_i) = \frac{1}{2} d_w^* \left(\|\nabla_{\mathbf{w}} \mathbf{f}(v_i)\|_2^{p-2} (d_w f)(v_i, v_j) \right) = \frac{1}{2} d_w^* \left(\frac{(d_w f)(v_i, v_j)}{\|\nabla_{\mathbf{w}} \mathbf{f}(v_i)\|_2^{2-p}} \right) \quad (3)$$

where $p \in (0, +\infty)$. If we choose specific formulations for the directed difference operator, we can end-up with new formulations of the p -Laplacian on directed graphs, that we propose in the sequel. Details are provided only for the first formulation due to paper length constraints.

3.2 Combinatorial p -Laplacian on directed graphs

First we consider

$$(d_w f)(v_i, v_j) = w(v_i, v_j)(f(v_j) - f(v_i)) \quad (4)$$

as a directed difference operator on the edge $v_i \rightarrow v_j$. This is similar to the one used for the combinatorial Laplacian on undirected graphs. Using the definitions of the inner products in $\mathcal{H}(\mathcal{E})$ and $\mathcal{H}(\mathcal{V})$, we can express the adjoint operator

$$(d_w^* H)(v_i) = \sum_{v_j \rightarrow v_i} H(v_j, v_i) w(v_j, v_i) - \sum_{v_i \rightarrow v_j} H(v_i, v_j) w(v_i, v_j) . \quad (5)$$

Proof.

$$\begin{aligned}
\langle H, d_w f \rangle_{\mathcal{H}(E)} &= \sum_{(v_i, v_j) \in E} (d_w f)(v_i, v_j) H(v_i, v_j) = \sum_{(v_i, v_j) \in E} w(v_i, v_j) (f(v_j) - f(v_i)) H(v_i, v_j) \\
&= \frac{1}{2} \sum_{v_i \in V} \left(\sum_{v_j \rightarrow v_i} H(v_i, v_j) w(v_i, v_j) (f(v_j) - f(v_i)) + \sum_{v_j \rightarrow v_i} H(v_j, v_i) w(v_j, v_i) (f(v_i) - f(v_j)) \right) \\
&= \frac{1}{2} \sum_{v_i \in V} \left(2 \sum_{v_j \rightarrow v_i} H(v_j, v_i) w(v_j, v_i) f(v_i) - 2 \sum_{v_i \rightarrow v_j} H(v_i, v_j) w(v_i, v_j) f(v_i) \right) \\
&= \sum_{v_i \in V} f(v_i) \left(\sum_{v_j \rightarrow v_i} H(v_j, v_i) w(v_j, v_i) - \sum_{v_i \rightarrow v_j} H(v_i, v_j) w(v_i, v_j) \right) = \langle d_w^* H, f \rangle_{\mathcal{H}(V)}
\end{aligned}$$

The adjoint operator measures the difference between the in- and outgoing flows at a vertex and can be associated to the divergence operator denoted by $-d_w^*$. Then, using Equation (3) and the definitions of d_w , d_w^* and $\|\nabla_{\mathbf{w}}\|$, a combinatorial p -Laplacian formulation on directed graphs can be expressed by:

$$\begin{aligned}
\Delta_w^p f(v_i) &= \frac{1}{2} \left(f(v_i) \left(\sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i)^2}{\|\nabla_{\mathbf{w}} \mathbf{f}(v_j)\|_2^{2-p}} + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j)^2}{\|\nabla_{\mathbf{w}} \mathbf{f}(v_i)\|_2^{2-p}} \right) \right. \\
&\quad \left. - \left(\sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i)^2}{\|\nabla_{\mathbf{w}} \mathbf{f}(v_j)\|_2^{2-p}} f(v_j) + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j)^2}{\|\nabla_{\mathbf{w}} \mathbf{f}(v_i)\|_2^{2-p}} f(v_j) \right) \right) \quad (6)
\end{aligned}$$

On the opposite to the classical formulation on undirected graphs [2, 6], the latter takes into account both ingoing and outgoing edges from vertices. However, with a specific (directed or undirected) graph and a given value of p , we can recover several state-of-the-art Laplacian formulations (up to a power of 2 on the weights). With undirected graphs, the formulation of [2] is recovered, with symmetric directed graphs the formulation of [7] is recovered. With $p = 2$, other formulations have been proposed on directed graphs but they only use in-degrees as $\Delta_w^2 f = (\mathbf{D}_- - \mathbf{W})f$ [15] or out-degrees as $\Delta_w^2 f = (\mathbf{D}_+ - \mathbf{W})f$ [12]. Our proposal encompasses these. In particular, for $p = 2$, Equation (6) can be expressed as $\Delta_w^2 f = \frac{1}{2}(\mathbf{D}_- + \mathbf{D}_+ - \mathbf{W} - \mathbf{W}^T)f$ in matrix expression. With undirected graphs and the classical combinatorial Laplacian $\Delta_w^2 f = \mathbf{L}f$ is recovered [3].

3.3 Normalized p -Laplacian on directed graphs

Second we consider

$$(d_w f)(v_i, v_j) = w(v_i, v_j) \left(\frac{f(v_j)}{\sqrt{d^-(v_j)}} - \frac{f(v_i)}{\sqrt{d^+(v_i)}} \right) \quad (7)$$

as a directed difference operator on the edge $v_i \rightarrow v_j$. This is close to the one used for the normalized Laplacian on undirected graphs, except that we normalize

with both in- and out-going degrees since we consider directed graphs. Using the definitions of the inner products in $\mathcal{H}(\mathcal{E})$ and $\mathcal{H}(\mathcal{V})$, we can express the adjoint operator

$$(d_w^* H)(v_i) = \sum_{v_j \rightarrow v_i} \frac{H(v_j, v_i) w(v_j, v_i)}{\sqrt{d^-(v_i)}} - \sum_{v_i \rightarrow v_j} \frac{H(v_i, v_j) w(v_i, v_j)}{\sqrt{d^+(v_i)}}. \quad (8)$$

Then, using Equation (3) and the definitions of d_w , d_w^* and $\|\nabla_{\mathbf{w}}\|$, a normalized p -Laplacian formulation on directed graphs can be expressed by:

$$\begin{aligned} \tilde{\Delta}_w^p f(v_i) = & \frac{1}{2} \left(f(v_i) \left(\sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i)^2}{d^-(v_i) \|\nabla_{\mathbf{w}} \mathbf{f}(v_j)\|_2^{2-p}} + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j)^2}{d^+(v_i) \|\nabla_{\mathbf{w}} \mathbf{f}(v_i)\|_2^{2-p}} \right) \right. \\ & \left. - \left(\sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i)^2 \|\nabla_{\mathbf{w}} \mathbf{f}(v_j)\|_2^{p-2}}{\sqrt{d^-(v_i)} d^+(v_j)} f(v_j) + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j)^2 \|\nabla_{\mathbf{w}} \mathbf{f}(v_i)\|_2^{p-2}}{\sqrt{d^+(v_i)} d^-(v_j)} f(v_j) \right) \right) \end{aligned} \quad (9)$$

As previously we can recover several state-of-the-art formulations. With directed graphs, $p = 2$ and weights replaced by their square root, the formulation can be reduced to

$$\tilde{\Delta}_w^2 f(v_i) = f(v_i) - \frac{1}{2} \left(\sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i) f(v_j)}{\sqrt{d^-(v_i)} d^+(v_j)} + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j) f(v_j)}{\sqrt{d^+(v_i)} d^-(v_j)} \right) \quad (10)$$

or as $\left(\mathbf{I} - \frac{1}{2} \left(\mathbf{D}_-^{-1/2} \mathbf{W} \mathbf{D}_+^{-1/2} + \mathbf{D}_+^{-1/2} \mathbf{W}^T \mathbf{D}_-^{-1/2} \right) \right) f$ in matrix form. This formulation is closely related to the normalized Laplacian for symmetric directed graphs proposed in [7, 17] and expressed as $\left(\mathbf{I} - \frac{1}{2} \left(\mathbf{D}^{-1/2} \mathbf{W} \mathbf{D}^{-1/2} + \mathbf{D}^{-1/2} \mathbf{W}^T \mathbf{D}^{-1/2} \right) \right) f$. As it can be seen they normalize only by $\mathbf{D}$ since the graph is symmetric, in contrast to our approach. A similar remark can be made for the formation of [4] for symmetric directed graphs that are strongly connected. With undirected graphs, our formulation reduces to $\tilde{\Delta}_w^2 f(v_i) = f(v_i) - \sum_{v_j \in V} \frac{w(v_i, v_j)}{\sqrt{d(v_i) d(v_j)}} f(v_j)$ which is exactly the normalized Laplacian $(\mathbf{I} - \mathbf{D}^{-1/2} \mathbf{W} \mathbf{D}^{-1/2}) f$ for undirected graphs [3].

3.4 Random-walk p -Laplacian on directed graphs

Third we consider

$$(d_w f)(v_i, v_j) = \frac{w(v_i, v_j)}{\sqrt{d^+(v_i)}} (f(v_j) - f(v_i)) \quad (11)$$

as a directed difference operator on the edge $v_i \rightarrow v_j$. This is similar to the one used for the random-walk Laplacian on undirected graphs. Using the definitions

of the inner products in $\mathcal{H}(\mathcal{E})$ and $\mathcal{H}(\mathcal{V})$, we can express the adjoint operator

$$(d_w^* H)(v_i) = \sum_{v_j \rightarrow v_i} \frac{H(v_j, v_i)w(v_j, v_i)}{\sqrt{d^+(v_i)}} - \sum_{v_i \rightarrow v_j} \frac{H(v_i, v_j)w(v_i, v_j)}{\sqrt{d^+(v_i)}}. \quad (12)$$

Then, using Equation (3) and the definitions of d_w , d_w^* and $\|\nabla_{\mathbf{w}}\|$, a random-walk p -Laplacian formulation on directed graphs can be expressed by:

$$\begin{aligned} \Delta_w^{p, rw} f(v_i) = & \frac{1}{2} \left(f(v_i) \left(\sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i)^2}{d^+(v_j) \|\nabla_{\mathbf{w}} \mathbf{f}(v_j)\|_2^{2-p}} + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j)^2}{d^+(v_i) \|\nabla_{\mathbf{w}} \mathbf{f}(v_i)\|_2^{2-p}} \right) \right. \\ & \left. - \left(\sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i)^2}{d^+(v_j) \|\nabla_{\mathbf{w}} \mathbf{f}(v_j)\|_2^{2-p}} f(v_j) + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j)^2}{d^+(v_i) \|\nabla_{\mathbf{w}} \mathbf{f}(v_i)\|_2^{2-p}} f(v_j) \right) \right) \end{aligned} \quad (13)$$

Again, with a specific (directed or undirected) graph and a given value of p , we can recover several state-of-the-art Laplacian formulations (up to a power of 2 on the weights). In particular, for $p = 2$, Equation (13) can be expressed as $\Delta_w^{2, rw} f = (\mathbf{I} - \frac{1}{2} \mathbf{D}_+^{-1}(\mathbf{W} + \mathbf{W}^T))f$ in matrix expression. With directed graphs and $p = 2$ the formulation in matrix expression of [7] is recovered, and with undirected graphs and $p = 2$ the classical random-walk Laplacian $\Delta_w^{2, rw} f = \mathbf{L}^{rw} f$ is recovered [10]. With $p = 2$, a similar formulation for directed graphs has been expressed as $(\mathbf{I} - \mathbf{D}_+^{-1} \mathbf{W})f$ in [1].

4 p -Laplacian Regularization on Directed Graphs

In the previous section, we have proposed general formulations for combinatorial, normalized and random-walk p -Laplacians on directed graphs. From these, we consider the problem of p -Laplacian regularization of signals on directed graphs that minimizes a loss function plus a regularization term. Let $f^0 : \mathcal{V} \rightarrow \mathbb{R}$ be a noisy graph signal of a clean graph signal $g : \mathcal{V} \rightarrow \mathbb{R}$ corrupted by a given noise n such that $f^0 = g + n$. To recover the uncorrupted function g , a commonly used method is to seek for a function $f : \mathcal{V} \rightarrow \mathbb{R}$ which is regular enough on $\mathcal{G}$, and also close enough to f^0 . This inverse problem can be formalized by the minimization of an energy functional, that typically involves a regularization term plus an approximation term (also called loss). The proposed graph p -Laplacians can be used to define a regularization functional $R_w^p : \mathcal{H}(\mathcal{V}) \rightarrow \mathbb{R}^+$ on directed graphs by

$$R_w^{p,*}(f) = \langle \Delta_w^{p,*} f, f \rangle_{\mathcal{H}(\mathcal{V})} = \langle d_w f, d_w f \rangle_{\mathcal{H}(\mathcal{E})} = \sum_{v_i \in \mathcal{V}} \|(\nabla_{\mathbf{w}} \mathbf{f})(v_i)\|_2^p \quad (14)$$

where $\Delta_w^{p,*}$ is among equations (6), (9) or (13). Since $R_w^{p,*} \geq 0$, $\Delta_w^{p,*}$ is positive semi-definite. From this we consider the following variational problem of p -Laplacian regularization on directed graphs

$$g \approx \min_{f: \mathcal{V} \rightarrow \mathbb{R}} \left\{ E_w^{p,*}(f, f^0, \lambda) = \frac{1}{p} R_w^{p,*}(f) + \frac{\lambda}{2} \|f - f^0\|_2^2 \right\}, \quad (15)$$

where the regularization functional $R_w^{p,*}$ can be induced from one of the proposed p -Laplacians on directed graphs. When $p \geq 1$, the energy $E_w^{p,*}$ is a convex functional of functions of $\mathcal{H}(\mathcal{V})$. To get the solution of the minimizer (15), we consider the following system of equations

$$\frac{\partial E_w^{p,*}(f, f^0, \lambda)}{\partial f(v_i)} = 0, \forall v_i \in \mathcal{V} \quad (16)$$

For all the p -Laplacians we have proposed, it can be proved that $\frac{1}{p} \frac{\partial R_w^{p,*}}{\partial f(v_i)} = 2\Delta_w^p f(v_i)$ (this is a direct consequence of Equation (14)) and the system of equations is then re-written as follows:

$$2\Delta_w^{p,*} f(v_i) + \lambda(f(v_i) - f^0(v_i)) = 0 \quad (17)$$

By substituting the expression of $\Delta_w^{p,*} f(v_i)$ by one of the proposed p -Laplacians ($\Delta_w^p, \tilde{\Delta}_w^p, \Delta_w^{p,rw}$) into Equation (17), the system of equations can be solved using a linearized Gauss-Jacobi iterative method. Let t be an iteration step, and $f^{(t)}$ be the solution at step t , then the following iterative algorithm is obtained for each of the proposed p -Laplacian on directed graphs.

$$f^{t+1}(v_i) = \frac{\lambda f^0(v_i) + \left(\sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i)^2 f^t(v_j)}{\phi(v_j, v_i) \|\nabla_{\mathbf{w}} \mathbf{f}^t(v_j)\|_2^{2-p}} + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j)^2 f^t(v_j)}{\phi(v_i, v_j) \|\nabla_{\mathbf{w}} \mathbf{f}^t(v_i)\|_2^{2-p}} \right)}{\lambda + \sum_{v_j \rightarrow v_i} \frac{w(v_j, v_i)^2}{\gamma_1(v_j, v_i) \|\nabla_{\mathbf{w}} \mathbf{f}^t(v_j)\|_2^{2-p}} + \sum_{v_i \rightarrow v_j} \frac{w(v_i, v_j)^2}{\gamma_2(v_i, v_j) \|\nabla_{\mathbf{w}} \mathbf{f}^t(v_i)\|_2^{2-p}}} \quad (18)$$

where ϕ , γ_1 and γ_2 are defined as follows, depending on the chosen directed p -Laplacian $\Delta_w^{p,*}$:

- Combinatorial p -Laplacian: $\phi(v_j, v_i) = \gamma_1(v_j, v_i) = \gamma_2(v_i, v_j) = 1$,
- Normalized p -Laplacian: $\phi(v_j, v_i) = \sqrt{d^-(v_i) d^+(v_j)}$, $\gamma_1(v_j, v_i) = d^-(v_i)$ and $\gamma_2(v_i, v_j) = d^+(v_i)$,
- Random-walk p -Laplacian: $\phi(v_i, v_j) = d^+(v_i)$ and $\gamma_1(v_j, v_i) = \gamma_2(v_i, v_j) = d^+(v_i)$.

5 Experiments and Results

In this section we provide sample results for the filtering of three different types of graphs signals for different directed graphs topologies and p -Laplacians. PSNR values will be used to compare the results. To weight the edges of the graphs, we use a parameterless function $w(v_i, v_j) = 1 - \frac{\|\mathbf{F}_\tau^0(v_i) - \mathbf{F}_\tau^0(v_j)\|_2}{\max_{v_k \rightarrow v_l \in \mathcal{E}} \|\mathbf{F}_\tau^0(v_k) - \mathbf{F}_\tau^0(v_l)\|_2}$. The vector

$\mathbf{F}_\tau^0(v_i) = \left(f^0(v_j) : v_j \in \mathcal{N}_\tau(v_i) \cup \{v_i\} \right)^T$ corresponds to the set of values around v_i within a τ -hop $\mathcal{N}_\tau(v_i)$ (for images this is a patch of size $(2\tau + 1)^2$). We will consider two types of directed graphs: 8-adjacency directed grid graph (denoted

$\mathcal{G}_0$, that connects each vertex to its 8 spatially closest nearest neighbors), and k -nearest neighbor directed graphs (denoted $\mathcal{G}_k^{\alpha,\tau}$, that connects each vertex to its k nearest neighbors in terms of $\mathbf{F}_\tau^0$ L_2 norm within a α -hop). Figure 1 illustrates the influence of the graph construction: nearest neighbors with patch-based distances better capture the image geometry and this can be beneficial for latter processing.

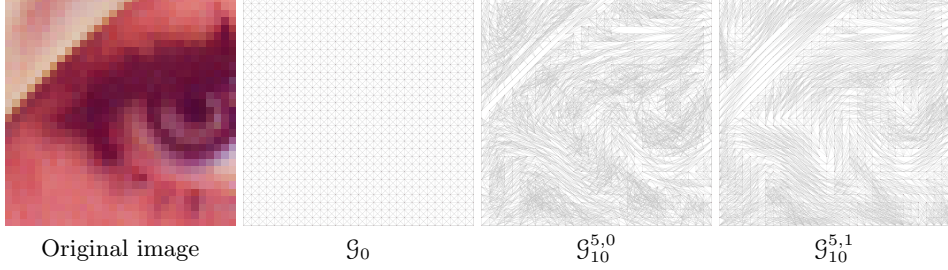


Fig. 1. Examples of directed graphs for an image. From left to right: original image, a symmetric 8-grid graph, 10-nearest neighbor graphs (inside a 11×11 window with color-based or 3×3 patch-based distances).

5.1 Images

The first type of graph signal we consider is 2D color images (see Figure 2) and $f : \mathcal{V} \rightarrow \mathbb{R}^3$. An image has been corrupted by Gaussian noise and we filter the latter with p -Laplacian regularization with different configurations: a 8-adjacency directed grid graph (with $\lambda = 0.05$, $p=1$), and a 8-adjacency directed grid graph augmented with a 10-nearest neighbor graph within a 5-hop ($\lambda = 0.09$ with patches of size 3×3). The nonlinear 1-Laplacian always provides better results than the linear 2-Laplacian. With $\mathcal{G}_0$ the graph is directed but symmetric and the filtering reduces to the undirected case [6], whereas with $\mathcal{G}_0 \cup \mathcal{G}_{10}^{5,1}$ the graph is not symmetric. As it can be seen, adding directed edges to the graph can enhance the results. We have observed that for the directed normalized p -Laplacian the results can degrade when low values of the in-degree occur. This is not the case for $\Delta_w^{p,rw}$ that always enables to obtain better results whatever the configurations we tested.

5.2 Database of images

The second type of graph signal we consider is an image database (see Figure 3) and $f : \mathcal{V} \rightarrow \mathbb{R}^{28 \times 28}$. We selected a subset of 90 images from the MNIST database for digits 0, 1, 3 and corrupted the images with Gaussian noise of standard deviation σ . Then a directed 5-nearest neighbor graph is constructed on the whole dataset ($\alpha = \infty$). This graph is not symmetric. As it can be seen in

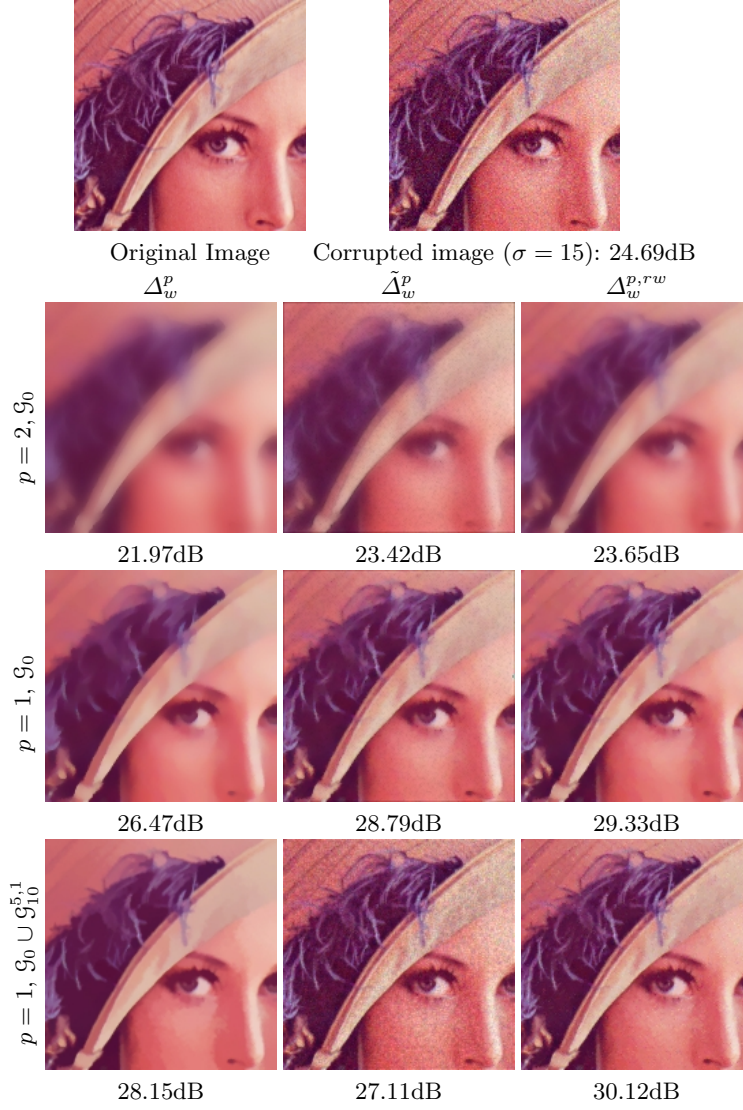
**Fig. 2.** p -Laplacian regularization of a corrupted image. See text for details.

Figure 3, the filtering with the $\tilde{\Delta}_w^1$ enables to remove the noise while preserving the main structures. Table 1 presents additional results for different amounts of noise. Again, better results are obtained with $p = 1$ but the best results are obtained with different p -Laplacians, the normalized Laplacian having this time a much better behavior than for images.

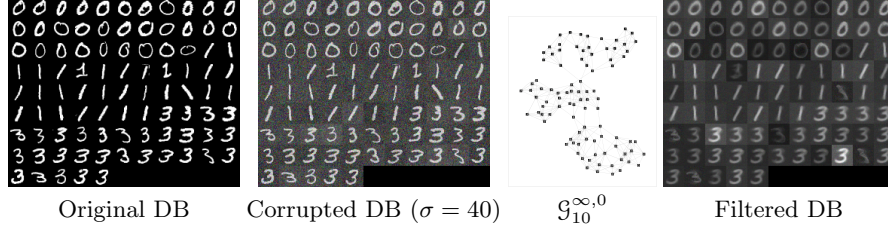


Fig. 3. p -Laplacian regularization of a corrupted image database (with $\tilde{\Delta}_w^p$, $p = 1$, and $\lambda = 10^{-4}$). See text for details.

σ	20			40		
$\Delta_w^{p,*}$	Δ_w^p	$\tilde{\Delta}_w^p$	$\Delta_w^{p,rw}$	Δ_w^p	$\tilde{\Delta}_w^p$	$\Delta_w^{p,rw}$
$p = 2$	14.54	14.63	14.56	12.91	13.08	12.88
$p = 1$	16.37	16.83	16.80	14.01	13.11	13.73

Table 1. Image database regularization on directed graphs ($\lambda = 10^{-4}$). Best results (in terms of PSNR) are bold faced.

5.3 Meshes

Finally, we consider 3D colored meshes as a last graph signal and $f : \mathcal{V} \rightarrow \mathbb{R}^3$. The meshes are 3D scans from an ancient building and a person. The color is noisy due to the scanning process and the objective is to filter the vertices colors and not their 3D coordinates. The considered graph is a symmetric directed mesh graph (provided from the scan) augmented with a 5-nearest neighbor graph within a 3-hop. To compare vertices we use $\mathbf{F}_1^0$. However, since the mesh graph is not regular, the feature vectors are not of the same size. We cannot use a L_2 distance to compare them, so we use instead the Earth Mover Distance between the histograms of $\mathbf{F}_1^0$. For space constraints, we show results only with $\Delta_w^{p,rw}$ that provided the best results. Again with $p = 1$ the filtering enables a much better preservation of the signal sharp edges while removing noise.

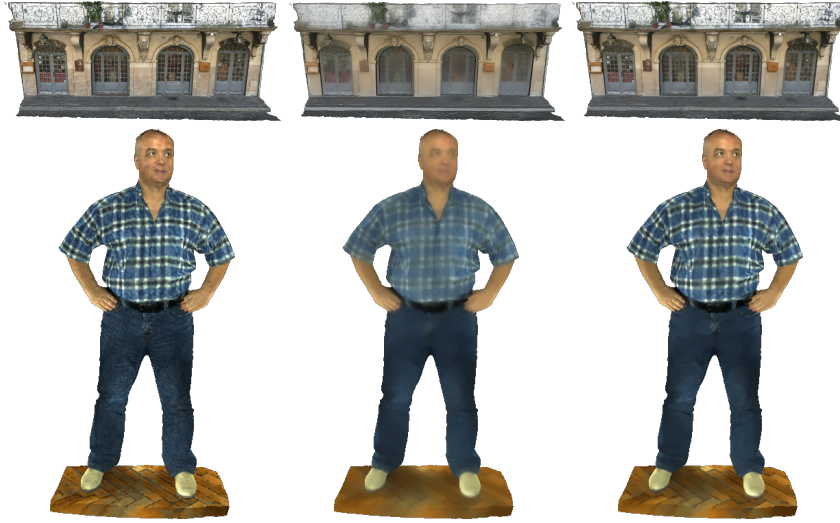


Fig. 4. 3D colored mesh regularization on directed graphs (From left to right: original mesh, filtering with $\Delta_w^{p,rw}$, $\lambda = 0.05$, with $p = 2$ and $p = 1$).

6 Conclusion

In this paper we have proposed three formulations for p -Laplacians on directed graphs. They used specific difference operators on directed graphs that are inspired from the combinatorial, the normalized and the random-walk laplacians. These formulations of p -Laplacians on directed graphs had never been addressed before unless for specific graphs (symmetric and with $p = 2$ [7]). Our proposal goes beyond this. From these formulations, we have considered the problem of p -Laplacian regularization of graph signals and proposed a solution to the latter. Finally, some experimental results show the benefit of the approach for the filtering of three types of graph signals: images, images' databases, and 3D colored meshes. Given the results, none of the proposed p -Laplacians on directed graphs can be considered as always providing the best results which motivates the need for several formulations. Directed and non symmetric graphs have also shown their interest with respect to classical symmetric undirected graphs. In future works, we will consider other optimization schemes as well as the introduction of non symmetric weights for directed symmetric graphs with applications in image semi-supervised segmentation.

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