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Generalized Inverted Kumaraswamy Generated Family of Distributions: Theory and Applications

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Abstract

This paper proposes a new generator function based on the inverted Kumaraswamy distribution "Generalized Inverted Kumaraswamy-G" family of distributions. We provide a comprehensive account of some of its mathematical properties that include the ordinary and incomplete moments, quantile and generating functions and order statistics. The infinite mixture representations for probability density and cumulative density and entropy functions of the new family are also established. The density function of the *i*th order statistics is expressed as an infinite linear combination of baseline densities and model parameters are estimated by maximum likelihood method. Four special models of this family are also derived along with their respective hazard rate functions. The maximum likelihood estimation (MLE) method is used to obtain the model parameters. Monte Carlo simulation experiments are executed to assess the performance of the MLE estimators under the corresponding generated models while some data applications are also illustrated.

Keywords— Kumaraswamy distribution, quantile function, Simulation, maximum likelihood estimation.

Mathematics Subject Classification. 60E05, 62E15, 62F10.

1 Introduction

In the recent times, there has been an increased interest in applying some inverted distributions to data applications in the areas of medical, economic and engineering sciences (See Calabria and Pulcini (1990), Al-Dayian (1999), Abd El-Kader et al. (2003), Prakash (2012)). Such distributions include the inverse Weibull, inverted Burr Type XII, the Pareto Type I and the exponentiated inverted Weibull models. However, to further improve the goodness of fit especially in exploring tail properties, researchers have also considered to derive new generators for univariate continuous families of distributions by introducing one or more additional shape parameter(s) to the baseline distribution.

In this context, some well-known generators are the beta-G by Eugene et al. (2002) and Jones (2004), Kumaraswamy-G (Kw-G) by Cordeiro and de Castro (2011), McDonald-G (Mc-G) by Alexander et al. (2012), gamma-G (type 1) by Zografos and Balakrishnan (2009), gamma-G (type 2) by Ristic and Balakrishnan (2012), gamma-G (type 3) by Torabi and Montazari (2012), logistic-G by Torabi and Montazari (2014), exponentiated generalized-G by Cordeiro et al. (2013), transformed-transformer (T-X) by Alzaatreh et al. (2013), Weibull-G by Bourguignon et al. (2014), Lomax-G by Cordeiro et al. (2014b), and logistic-X by Tahir et al. (2014). Other recent family of distributions are Garhy-G by Elgarhy et al. (2016), Kumaraswamy Weibull-G by Hassan and Elgarhy (2016a), exponentiated Weibull-G by Hassan and Elgarhy (2016b), additive Weibull-G by Hassan et al. (2017).

Most recently,

Al-Fattah et al. (2017) introduced the inverted Kumaraswamy (IKw) distribution with two positive shape parameters $\alpha > 0$ and $\beta > 0$, where the cumulative distribution function (cdf) is given by

$$\Pi(x;\alpha,\beta) = \left[1 - (1+x)^{-\alpha}\right]^{\beta}, \quad x > 0$$
(1.1)

The probability density function (pdf) corresponding to (1.1) is

$$\pi(x;\alpha,\beta) = \alpha \beta (1+x)^{-\alpha-1} \left[1 - (1+x)^{-\alpha} \right]^{\beta-1}.$$
(1.2)

The curves of the pdf show that the IKw distribution exhibits a long right tail and as illustrated in the paper by Al-Fattah et al. (2017), IKw produces optimistic predictions of rare events occurring in the right tail of the distribution as compared with other distributions. However, in many applied areas such as lifetime analysis, finance and insurance, the data are seen to exhibit heavy-tail while in practice, there is also a strong need to generate distributions with symmetric, left-skewed, rightskewed and reverse J-shaped and hence to provide consistently better fits than other generated models under the same underlying distribution.

The basic motivations for obtaining GIKw-G family in practice are: (i) to make the kurtosis more flexible as compared to the baseline model; (ii) to produce skewness for symmetrical distributions; (iii) to construct heavy-tailed distributions that are not longer-tailed for modeling real data; (iv) to generate distributions with symmetric, left-skewed, right-skewed and reversed-J shape; (v) to provide consistently better fits than other generated models under the same underlying distribution.

In this context, this paper proposes a new generalized Inverted Kumaraswamy family of distributions (GIKw-G) using the generator $\frac{G^{\gamma}}{1-G^{\gamma}}$. For the conditions on the baseline distribution see Alzaatreh et al. (2013).

The cdf of the new family, GIKw-G, is given by

$$F(y) = \alpha \beta \int_{0}^{\frac{G^{\gamma}(x,\xi)}{1-G^{\gamma}(x,\xi)}} (1+y)^{-\alpha-1} \left[1-(1+y)^{-\alpha}\right]^{\beta-1} dy$$

= $\left[1-(1-G^{\gamma}(x,\xi))^{\alpha}\right]^{\beta}.$ (1.3)

where the corresponding density function to (3) is given by

$$f(x) = \alpha \beta \gamma g(x,\xi) G^{\gamma-1}(x,\xi) (1 - G^{\gamma}(x,\xi))^{\alpha-1} [1 - (1 - G^{\gamma}(x,\xi))^{\alpha}]^{\beta-1}, \quad \alpha, \beta, \gamma > 0.$$
(1.4)

where ξ is the parametric space of the baseline distribution. Now onward $G(x,\xi) = G(x)$ and $g(x,\xi) = g(x)$. The survival, hazard rate and reversed hazard rate functions of the GIKw-G family are, respectively, given by

$$S(x) = 1 - [1 - (1 - G^{\gamma}(x))^{\alpha}]^{\beta},$$

$$h(x) = \frac{\alpha \beta \gamma g(x) G^{\gamma - 1}(x) (1 - G^{\gamma}(x))^{\alpha - 1} [1 - (1 - G^{\gamma}(x))^{\alpha}]^{\beta - 1}}{1 - [1 - (1 - G^{\gamma}(x))^{\alpha}]^{\beta}},$$

$$H(x) = \frac{\alpha \beta \gamma G^{\gamma - 1}(x) (1 - G^{\gamma}(x))^{\alpha - 1}}{1 - (1 - G^{\gamma}(x))^{\alpha}}.$$

Note that when $\gamma = 1$ we obtain the exponentiated generalized family of distributions that was introduced by Cordeiro et al. (2013). The GIKw-G family is easily simulated by inverting (1.3) as follows: if u has a uniform U(0, 1) distribution, then the solution of the nonlinear equation is given by

$$Q_x(u) = G^{-1} \left\{ 1 - \left(1 - u^{\frac{1}{\beta}}\right)^{\frac{1}{\alpha}} \right\}^{\frac{1}{\gamma}}.$$

The rest of the paper is organized as follows: In Section 2, four special models of the new family are given with their plots of density and hazard rate functions. In Section 3, Structural Properties are discussed while in Section 4, parameter estimation and a Monte Carlo simulation study are presented. In Section 5, the proposed GIKw-G is applied to some real-life data and also compared with other well-known distributions.

2 Some Special Models of the GIKw-G Family

In this section, we give some examples of the GIKw-G family of distributions, namely: the generalized inverted Kumaraswamy-uniform, generalized inverted Kumaraswamy-Weibull, generalized inverted Kumaraswamy-log logistic and generalized inverted Kumaraswamy-Lomax distributions.

2.1 Generalized inverted Kumaraswamy-uniform (GIKw-U) distribution

The pdf of the GIKw-U is derived from (1.4), by taking $g(x;\theta) = \frac{1}{\theta}$, $0 < x < \theta$, and $G(x;\theta) = \frac{x}{\theta}$ as follows:

$$f(x) = \frac{\alpha \beta \gamma}{\theta} \left(\frac{x}{\theta}\right)^{\gamma-1} \left[1 - \left(\frac{x}{\theta}\right)^{\gamma}\right]^{\alpha-1} \left\{1 - \left[1 - \left(\frac{x}{\theta}\right)^{\gamma}\right]^{\alpha}\right\}^{\beta-1}.$$

The corresponding cdf takes the following form

$$F(x) = \left\{ 1 - \left[1 - \left(\frac{x}{\theta} \right)^{\gamma} \right]^{\alpha} \right\}^{\beta}$$

The plots of density and hazard rate functions of the GIKw-U are presented in Figure 1. As seen in 1(a), the density function has reversed J and upside-down bathtub shapes. Figure 1(b) shows that the hazard rate function gives increasing and bathtub shapes.



Figure 1: Plots of pdf and hrf for the GIKw-U distribution with several values of parameters

2.2 Generalized inverted Kumaraswamy-Weibull (GIKw-W) distribution

We consider the Weibull distribution with scale and shape parameters a, b > 0. The pdf and cdf are $g(x) = a b x^{b-1} e^{-a x^b}$ and $G(x) = 1 - e^{-a x^b}$, respectively. Then, the pdf of the GIKw-W is given by

$$f(x) = a b \alpha \beta \gamma x^{b-1} e^{-a x^{b}} \left(1 - e^{-a x^{b}}\right)^{\gamma-1} \left[1 + \left(1 - e^{-a x^{b}}\right)^{\gamma}\right]^{\alpha-1} \left\{1 - \left[1 + \left(1 - e^{-a x^{b}}\right)^{\gamma}\right]^{\alpha}\right\}^{\beta-1}$$

The corresponding cdf takes the following form

$$F(x) = \left\{ 1 - \left[1 + \left(1 - e^{-a x^{b}} \right)^{\gamma} \right]^{\alpha} \right\}^{\beta}$$

Figure 2 shows the plots of density and hazard functions of GIKw-W distribution. The density function in Figure 2(a) has reversed J, left, right skewed and symmetrical shapes. The hrf in Figure 2(b) gives bathtub, upside-down bathtub and increasing shapes.

2.3 Generalized inverted Kumaraswamy-Log logistic (GIKw-LL) distribution

We consider the log-logistic distribution with scale parameter $\theta > 0$. The pdf and cdf are given by $g(x) = \frac{\theta x^{\theta-1}}{(1+x^{\theta})^2}$ and $G(x) = \frac{x^{\theta}}{1+x^{\theta}}$, respectively. Then, the cdf of the GIKw-LL distribution is given



Figure 2: Plots of pdf and hrf for the GIKw-W distribution with several values of parameters

by

$$f(x) = \alpha \beta \gamma \frac{\theta x^{\theta - 1}}{(1 + x^{\theta})^2} \left(\frac{x^{\theta}}{1 + x^{\theta}}\right)^{\gamma - 1} \left[1 - \left(\frac{x^{\theta}}{1 + x^{\theta}}\right)^{\gamma}\right]^{\alpha - 1} \left\{1 - \left[1 - \left(\frac{x^{\theta}}{1 + x^{\theta}}\right)^{\gamma}\right]^{\alpha}\right\}^{\beta - 1}$$

The corresponding cdf takes the following form

$$F(x) = \left\{ 1 - \left[1 - \left(\frac{x^{\theta}}{1 + x^{\theta}} \right)^{\gamma} \right]^{\alpha} \right\}^{\beta}$$

The plots of density and hazard rate functions of GIKw-LL are given in Figure 3. The density in Figure 3(a) gives reversed J, nearly symmetrical and positively skewed shapes. As seen in Figure 3(b), the hazard rate function has the bathtub, upside-down bathtub, increasing and decreasing shapes.

2.4 Generalized inverted Kumaraswamy-Lomax (GIKw-Lx) distribution

We consider the Lomax distribution with scale parameter a, b > 0. The pdf and cdf are $g(x) = \frac{a}{b} \left(1 + \frac{x}{b}\right)^{a-1}$ and $g(x) = 1 - \left(1 + \frac{x}{b}\right)^{a}$, respectively. Then, the pdf of GIKw-L is given by

$$\begin{aligned} f(x) &= \alpha \beta \gamma \frac{a}{b} \left(1 + \frac{x}{b} \right)^{a-1} \left[1 - \left(1 + \frac{x}{b} \right)^a \right]^{\gamma-1} \left\{ 1 - \left[1 - \left(1 + \frac{x}{b} \right)^a \right]^{\gamma} \right\}^{\alpha-1} \\ & \left[1 - \left\{ 1 - \left[1 - \left(1 + \frac{x}{b} \right)^a \right]^{\gamma} \right\}^{\alpha} \right]^{\beta-1} \end{aligned}$$

The corresponding cdf takes the following form

$$F(x) = \left[1 - \left\{1 - \left[1 - \left(1 + \frac{x}{b}\right)^{a}\right]^{\gamma}\right\}^{\alpha}\right]^{\beta}$$



Figure 3: Plots of pdf and hrf for the GIKw-LL distribution with several values of parameters

The plots of density and hazard rate functions of the GIKw-L are given in Figure 4. Figure 4(a) shows that reversed J and positively skewed shapes are possible for the density function. Figure 4(b) also shows that the hazard rate function has upside-down bathtub, increasing and decreasing shapes.



Figure 4: Plots of pdf and hrf for the GIKw-L distribution with several values of parameters

3 Structural Properties

The several types of moments of a random variable are important especially in applied work. Some of the most important features and characteristics of a distribution can be studied through moments, e.g., tendency, dispersion, skewness and kurtosis, mean deviations, Bonferroni and Lorenz curves, etc. In this section, we will provide the expansions of GIKw-G densities, *r*th moment, *s*th incomplete moment, moment generating function and mean deviations.

3.1 Useful expansions

Here, the infinite mixture representations for the cdf and pdf of the GIKw-G family are given in terms of baseline densities. Consider following series expansion

$$(1-z)^b = \sum_{j=0}^{\infty} {b \choose j} (-1)^j z^j.$$
(3.1)

Using the series expansion in (3.1), the equation (1.3) becomes

$$F(x) = \sum_{j=0}^{\infty} {\beta \choose j} (-1)^j \sum_{i=0}^{\infty} {\alpha j \choose i} (-1)^i G^{\gamma i}$$

where $G^{\gamma i} = \sum_{q=0}^{\infty} \sum_{q=k}^{\infty} {\gamma i \choose k} {\gamma i \choose q} (-1)^{q+k} G^q(x)$. Now the above expression can be written as

$$F(x) = \sum_{j=0}^{\infty} \sum_{i=0}^{\infty} {\beta \choose j} {\alpha j \choose i} (-1)^{i+j} \sum_{q=0}^{\infty} \sum_{q=k}^{\infty} {\gamma i \choose k} {k \choose q} (-1)^{q+k} G^q(x)$$

. Rewriting the above expression, we obtain an expansion for the cdf of the GIKw-G family

$$F(x) = \sum_{q=0}^{\infty} a_q H_q(x),$$
(3.2)

where $a_q = \sum_{j=0}^{\infty} \sum_{i=0}^{\infty} {\beta \choose j} {\alpha j \choose i} (-1)^{i+j} \sum_{q=k}^{\infty} {\gamma i \choose k} {k \choose q} (-1)^{q+k}$ and $H_q(x) = G^q(x)$. Similarly, we have an expansion for the pdf of the GIKw-G family as

$$f(x) = \sum_{q=0}^{\infty} a_q h_{q-1}(x)$$
(3.3)

where $h_{q-1}(x) = q \times g(x) G^{q-1}(x)$.

3.2 Moments and moment generating function

Moments are necessary and important in any statistical analysis, especially in applications. It can be used to study the most important features and characteristics of a distribution (e.g., tendency, dispersion, skewness and kurtosis). The *r*th moment of GIKw-G family is given by

$$\mu_r' = \int_0^\infty x^r f(x) \, dx$$

. Using the infinite mixture representation of the pdf in equation (3.3), we have

$$\mu_r' = \sum_{q=0}^\infty a_q \, \Delta_r'$$

where $\Delta'_r = \int_0^\infty x^r h_{q-1}(x) dx$ Similarly, the sth incomplete x

Similarly, the sth incomplete moment of GIKw-G family is defined as

$$\mu'_s = \int\limits_0^x x^s f(x) \, dx$$

From the infinite mixture representation of pdf in equation (3.3), we get

$$\mu'_s = \sum_{q=0}^{\infty} a_q T'_s(x)$$

where $T'_{s}(x) = \int_{0}^{x} x^{s} h_{q-1}(x) dx.$

Now, we define the moment generating function of GIKw-G family as

$$M_0(t) = \int_0^\infty e^{tx} f(x) \, dx$$

From the infinite mixture representation of pdf in equation (3.3), we obtain

$$M_0(t) = \sum_{q=0}^{\infty} a_q M_{q-1}(t)$$

where $M_{q-1}(t) = \int_{0}^{x} e^{tx} h_{q-1}(x) dx$.

Note that the integrals Δ'_r , $T'_s(x)$ and $M_{q-1}(t)$ depend only for any choice of baseline distribution. The mean deviations of GIKw-G family is obtained by

$$\delta_1 = 2 \,\mu F(\mu) - 2 \,J(\mu), \quad \delta_2 = \mu - 2 \,J(\tilde{x})$$

where $\mu = mean = E(X)$, $\tilde{x} = median = Q_x(0.5)$ and $j(c) = \int_0^x x f(x) dx$. Using the infinite mixture representation of pdf in equation (3.3), we get

$$j(c) = \sum_{q=0}^{\infty} a_q S'_{q-1}(c)$$

where $S'_{q-1}(c) = \int_{0}^{c} x h_{q-1}(x) dx$ the integral depends on G(x) and g(x).

3.3 Entropies

The entropy of a random variable X is a measure of variation of uncertainty and has been used in many fields such as physics, engineering, and economics. In this section, we will consider two well known entropy measures, Renyi and Shannon entropies. According to Renyi (1961), the Renyi entropy is defined by

$$I_R = \frac{1}{1-R} \log \int_{0}^{\infty} f^R(x) \, dx$$
 (3.4)

where $f^R(x) = \left[\alpha \beta \gamma g(x) G^{\gamma-1}(x) (1 - G^{\gamma}(x))^{\alpha-1} \left[1 - (1 - G^{\gamma}(x))^{\alpha}\right]^{\beta-1}\right]^R$. Using series expansion in equation (3.1), we have

$$f^{R}(x) = \sum_{i=0}^{\infty} w_{i}(j) g_{\gamma(i+R)-R}(x)$$

Here, we define $w_i(j) = (\alpha \beta \gamma)^R \sum_{j=0}^{\infty} {\binom{R(\beta-1)}{j} \binom{\alpha(j+R)-R}{i} \frac{(-1)^{i+j}}{\gamma(i+R)-R+1}}$ and $g_{\gamma(i+R)-R}(x) = [\gamma(i+R)-R+1] g^R(x) G^{\gamma(i+R)-R}(x)$. Now equation (3.5) becomes

$$I_{R} = \frac{1}{1-R} \log \left[\sum_{i=0}^{\infty} w_{i}(j) \int_{0}^{\infty} g_{\gamma(i+R)-R}(x) \, dx \right]$$
(3.5)

The above integral depends on G(x) and g(x).

The Shannon entropy of a random variable X is defined by Shannon (1948) as

$$\eta_x = -E\left[\log f(x)\right]$$

From equation (1.4), we have

$$\eta_x = -E\left[\log\gamma + \log g(x) + (\gamma - 1)\log(1 - G^{\gamma}(x)) + \log r\left\{\frac{G^{\gamma}(x)}{1 - G^{\gamma}(x)}\right\}\right]$$
(3.6)

Let $T = \frac{G^{\gamma}(x)}{1 - G^{\gamma}(x)}$ then $G(x) = \left[\frac{T}{1 + T}\right]^{\frac{1}{\gamma}}$ and $1 - G^{\gamma}(x) = \left[\frac{1}{1 + T}\right]$. Now equation (3.6) becomes

$$\eta_x = -E\left[\log\gamma + \log g(x) + \left(1 - \frac{1}{\gamma}\right)\log T + \left(1 + \frac{1}{\gamma}\right)\log(1+T) + \log r(T)\right]$$

After some algebra we have

$$\eta_x = \eta_g + \eta_T - \log \gamma - \left(1 - \frac{1}{\gamma}\right) \sum_{j=0}^{\infty} \frac{(-1)^j}{j!} \frac{\mathbf{B}\left(1 - \frac{j}{\alpha}, \beta\right)}{\Gamma(1-j)} \left[\Gamma'(1) - \psi(1-j)\right] + \frac{1}{\alpha} \left(1 + \frac{1}{\gamma}\right) \left[\Gamma'(1) - \psi(\beta + 1)\right]$$

$$(3.7)$$

where η_T is the Shannon entropy of IKw distribution and η_g is the Shannon entropy of baseline distribution. where $\psi(a) = \frac{\Gamma'(a)}{\Gamma(a)}$ and $\Gamma'(1)$ is Euler's constant.

3.4 Order Statistics

Order statistics have been extensively applied in many fields of statistics, such as reliability and life testing. They enter in the problems of estimation and hypothesis tests in a variety of ways. We now discuss some properties of the order statistics for the GIKw-G family. Let $X_{i:n}$ denote the *i*th order statistic from a random sample X_1, \ldots, X_n from the GIKw-G family. Then, the density function of *i*th order statistic is given by

$$f_{i:n}(x) = \frac{n!}{(i-1)!(n-i)!} f(x) F^{i-1}(x) [1 - F(x)]^{n-i}$$

Using series expansion in equation (3.1), we have

$$f_{i:n}(x) = \frac{n!}{(i-1)!(n-i)!} \sum_{j=0}^{n-i} \binom{n-i}{j} (-1)^j f(x) F^{j+i-1}(x)$$
(3.8)

Consider $f(x) F^{j+i-1}(x)$, using infinite mixture representation in equations (3.2) and (3.3), we obtain

$$\left[\sum_{q=0}^{\infty} a_q h_{q-1}(x)\right] \times \left[\sum_{m=0}^{\infty} a_m H_m(x)\right]^{j+i-1}$$

From power series raised to a positive power expansion $\left[\sum_{k=0}^{\infty} a_k G^k(x)\right]^r = \sum_{k=0}^{\infty} d_{k:r} G^k(x)$ we have

$$\left[\sum_{q=0}^{\infty} a_q q g(x) G^q(x)\right] \times \sum_{m=0}^{\infty} d_{m:j+i-1} G^m(x)$$

After simplification, we have

$$\left[\sum_{q=0}^{\infty}\sum_{m=0}^{\infty} a_q \, d_{m:j+i-1} \, q \, g(x) \, G^{q+r}(x)\right]$$

Now equation (3.8) becomes

$$f_{i:n}(x) = \frac{n!}{(i-1)!(n-i)!} \sum_{j=0}^{n-i} \binom{n-i}{j} (-1)^j \sum_{q=0}^{\infty} \sum_{m=0}^{\infty} a_q \, d_{m:j+i-1} \, q \, g(x) \, G^{q+r}(x)$$

Rewriting the equation, the density function of *i*th order statistic is given by

$$f_{i:n}(x) = \sum_{j=0}^{n-i} \sum_{q=0}^{\infty} \sum_{m=0}^{\infty} V_j(q,m) h_{q+m-1}(x)$$

, where $V_j(q,m) = \frac{n!}{(i-1)!(n-i)!} {\binom{n-i}{j}} \frac{(-1)^j a_q d_{m:j+i-1} q}{q+m}$ and $h_{q+m-1}(x) = (q+m) g(x) G^{q+m-1}$.

4 Estimation and Simulation

4.1 Estimation

Here, we consider the estimation of the unknown parameters of GIKw-G family by the maximum likelihood method for the complete samples. The maximum likelihood estimates (MLEs) enjoy desirable properties that can be used when constructing confidence intervals and deliver simple approximations that work well in finite samples. The resulting approximation for the MLEs in distribution theory is easily handled either analytically or numerically. Let $x_1, ..., x_n$ be a sample of size n from GIKw-G family given in (1.3). The log-likelihood function of GIKw-G family for the vector of parameter $\Theta = (\alpha, \beta, \gamma, \xi)^T$ is given by

$$\ell(\Theta) = n \log(\alpha \beta \gamma) + \sum_{i=1}^{n} \log g(x_i, \xi) + (\gamma - 1) \sum_{i=1}^{n} \log G(x_i, \xi) + (\alpha - 1) \sum_{i=1}^{n} \log [1 - G^{\gamma}(x_i, \xi)] + (\beta - 1) \sum_{i=1}^{n} \log [1 - \{1 - G^{\gamma}(x_i, \xi)\}^{\alpha}]$$

The components of score vector $U = (U_{\beta}, U_{\alpha}, U_{\gamma}, U_{\xi})^T$ are given by

$$\begin{split} U_{\beta} &= \frac{n}{\beta} + \sum_{i=1}^{n} \log\left[1 - \{1 - G^{\gamma}(x_{i},\xi)\}^{\alpha}\right] \\ U_{\alpha} &= \frac{n}{\alpha} + \sum_{i=1}^{n} \log\left[1 - G^{\gamma}(x_{i},\xi)\right] + (\beta - 1) \sum_{i=1}^{n} \left[\frac{\{1 - G^{\gamma}(x_{i},\xi)\}^{\alpha} \log\{1 - G^{\gamma}(x_{i},\xi)\}\}^{\alpha}}{1 - \{1 - G^{\gamma}(x_{i},\xi)\}^{\alpha}}\right] \\ U_{\gamma} &= \frac{n}{\gamma} + \sum_{i=1}^{n} \log G(x_{i},\xi) + (\alpha - 1) \sum_{i=1}^{n} \left[\frac{G^{\gamma}(x_{i},\xi) \log G(x_{i},\xi)}{1 - G^{\gamma}(x_{i},\xi)}\right] \\ &+ (\beta - 1)\alpha \sum_{i=1}^{n} \left[\frac{\{1 - G^{\gamma}(x_{i},\xi)\}^{\alpha - 1} G^{\gamma}(x_{i},\xi) \log G(x_{i},\xi)\}}{1 - \{1 - G^{\gamma}(x_{i},\xi)\}^{\alpha}}\right] \\ U_{\xi} &= \sum_{i=1}^{n} \left[\frac{g^{\xi}(x_{i},\xi)}{g(x_{i},\xi)}\right] + (\gamma - 1) \sum_{i=1}^{n} \left[\frac{G^{\xi}(x_{i},\xi)}{G(x_{i},\xi)}\right] - \gamma (\alpha - 1) \sum_{i=1}^{n} \left[\frac{G^{\gamma - 1}(x_{i},\xi) G^{\xi}(x_{i},\xi)}{1 - G^{\gamma}(x_{i},\xi)}\right] \\ &- \alpha \gamma (\beta - 1) \sum_{i=1}^{n} \left[\frac{\{1 - G^{\gamma}(x_{i},\xi)\}^{\alpha - 1} G^{\gamma - 1}(x_{i},\xi) G^{\xi}(x_{i},\xi)}{1 - \{1 - G^{\gamma}(x_{i},\xi)\}^{\alpha}}\right] \end{split}$$

Setting U_{β} , U_{α} , U_{γ} and U_{ξ} equal to zero and solving these equations simultaneously yields the the MLEs. These equations cannot be solved analytically, and analytical softwares are required to solve them numerically.

4.2 Simulation study

In this section, an extensive numerical investigation will be carried out to evaluate the performance of the MLEs for the GIKw-W model. Performance of estimators is evaluated through their biases, and mean square errors (MSEs) for different sample sizes. A numerical study is performed using Mathematica (9) software. Different sample sizes (n = 30, 50, 75, 100, 200 and 300) and different values of parameters are considered. The experiment is repeated 3000 times. In each experiment, the estimates of the parameters are obtained by maximum likelihood method. The means, MSEs and biases for the different estimators are reported from these experiments.

The values in Table 1 indicate that the estimates are quite stable and, more importantly, are close to the true values for the these sample sizes. From Table 1, it is observed that in general the standard deviation decreases as n increases. The simulation study shows that the maximum likelihood method is appropriate for estimating the GIKw-W parameters. In fact, the MSEs of the parameters tend to be closer to the true parameter values when n increases. This fact supports that the asymptotic normal distribution provides an adequate approximation to the finite sample distribution of the MLEs. The normal approximation can be often times improved by using bias adjustments to these estimators.

n	Par	Init	MLE	Bias	MSE	Init	MLE	Bias	MSE
	γ	2	2.0915	0.0915	0.2296	2	2.0905	0.0905	0.2085
	α	2	2.0580	0.0580	0.1427	2	2.0488	0.0488	0.1308
50	β	1.5	1.5316	0.0316	0.0522	1.5	1.5330	0.0330	0.0485
	a	2	2.0752	0.0752	11.7134	2	2.1234	0.1234	0.4287
	b	0.5	0.5293	0.0293	0.0200	2	2.1119	0.1119	0.2870
	γ	2	2.0679	0.0679	0.1361	2	2.0559	0.0559	0.1356
	α	2	2.0311	0.0311	0.0882	2	2.0430	0.0430	0.0897
75	eta	1.5	1.5255	0.0255	0.0335	1.5	1.5196	0.0196	0.0332
	a	2	2.0775	0.0775	0.2373	2	2.0952	0.0952	0.2366
	b	0.5	0.5204	0.0204	0.0114	2	2.0679	0.0679	0.1647
	γ	2	2.0434	0.0434	0.0940	2	2.0433	0.0433	0.0945
	α	2	2.0290	0.0290	0.0625	2	2.0259	0.0259	0.0610
100	eta	1.5	1.5161	0.0161	0.0239	1.5	1.5155	0.0155	0.0241
	a	2	2.0630	0.0630	0.1512	2	2.0598	0.0598	0.1523
	b	0.5	0.5136	0.0136	0.0074	2	2.0526	0.0526	0.1197
	γ	2	2.0190	0.0190	0.0425	2	2.0227	0.0227	0.0426
	α	2	2.0164	0.0164	0.0302	2	2.0122	0.0122	0.0293
200	eta	1.5	1.5071	0.0071	0.0115	1.5	1.5089	0.0089	0.0115
	a	2	2.0335	0.0335	0.0679	2	2.0274	0.0274	0.0663
	b	0.5	0.5063	0.0063	0.0034	2	2.0273	0.0273	0.0547
	γ	2	2.0128	0.0128	0.0272	2	2.0155	0.0155	0.0282
	α	2	2.0070	0.0070	0.0194	2	2.0104	0.0104	0.0200
300	β	1.5	1.5045	0.0045	0.0074	1.5	1.5066	0.0066	0.0077
	a	2	2.0173	0.0173	0.0426	2	2.0211	0.0211	0.0433
	b	0.5	0.5031	0.0031	0.0021	2	2.0199	0.0199	0.0351

Table 1: The parameter estimations from the GIKw-W distribution using the maximum likelihood method

				Continu	ied of Ta	ble 1			
n	Par	Init	MLE	Bias	MSE	Init	MLE	Bias	MSE
	γ	0.5	0.5216	0.0216	0.0133	1.5	1.5602	0.0602	0.1239
	α	2	2.0570	0.0570	0.1301	2	2.0615	0.0615	0.1354
50	β	1.5	1.5308	0.0308	0.0493	1.5	1.5265	0.0265	0.0496
	a	2	2.0233	0.0233	0.0488	2	2.1006	0.1006	0.2491
	b	2	2.1281	0.1281	0.3687	2	2.1099	0.1099	0.3171
	γ	0.5	0.5135	0.0135	0.0078	1.5	1.5482	0.0482	0.0745
	α	2	2.0339	0.0339	0.0884	2	2.0331	0.0331	0.0833
75	β	1.5	1.5188	0.0188	0.0310	1.5	1.5241	0.0241	0.0325
	a	2	2.0115	0.0115	0.0347	2	2.0543	0.0543	0.1424
	b	2	2.0753	0.0753	0.1946	2	2.0867	0.0866	0.1949
	γ	0.5	0.5121	0.0121	0.0058	1.5	1.5321	0.0321	0.0509
	α	2	2.0300	0.0299	0.0615	2	2.0255	0.0255	0.0606
100	β	1.5	1.5192	0.0192	0.0234	1.5	1.5157	0.0157	0.0234
	a	2	2.0141	0.0141	0.0248	2	2.0421	0.0421	0.1029
	b	2	2.0704	0.0704	0.1417	2	2.0565	0.0565	0.1276
	γ	0.5	0.5048	0.0048	0.0027	1.5	1.5162	0.0162	0.0253
	α	2	2.0173	0.0173	0.0322	2	2.0176	0.0176	0.0306
200	β	1.5	1.5073	0.0073	0.0114	1.5	1.5084	0.0084	0.0119
	α	2	2.0077	0.0077	0.0134	2	2.0265	0.0265	0.0497
	b	2	2.0264	0.0264	0.0609	2	2.0313	0.0313	0.0611
	γ	0.5	0.5019	0.0019	0.0018	1.5	1.5152	0.0152	0.0154
	α	2	2.0107	0.0107	0.0198	2	2.0063	0.0063	0.0185
300	β	1.5	1.5017	0.0017	0.0077	1.5	1.5089	0.0089	0.0075
	a	2	2.0042	0.0042	0.0083	2	2.0101	0.0101	0.0290
	b	2	2.0116	0.0116	0.0404	2	2.0273	0.0273	0.0381

				Contin	<u>ued of Ta</u>	<u>ble 1</u>			
n	Par	Init	MLE	Bias	MSE	Init	MLE	Bias	MSE
	γ	2	2.0216	0.0216	0.0377	2	2.0702	0.0702	0.1469
	α	0.5	0.5148	0.0148	0.0085	1.5	1.5481	0.0481	0.0817
50	eta	1.5	1.5336	0.0336	0.0508	1.5	1.5350	0.0350	0.0495
	a	2	2.0929	0.0929	0.2416	2	2.1382	0.1382	0.4421
	b	2	2.1107	0.1107	0.2649	2	2.1004	0.1003	0.2074
	γ	2	2.0142	0.0142	0.0241	2	2.0422	0.0422	0.0921
	α	0.5	0.5090	0.0090	0.0053	1.5	1.5306	0.0306	0.0503
75	eta	1.5	1.5221	0.0221	0.0313	1.5	1.5205	0.0205	0.0318
	a	2	2.0553	0.0552	0.1382	2	2.0844	0.0843	0.2127
	b	2	2.0708	0.0708	0.1574	2	2.0567	0.0567	0.1275
	γ	2	2.0105	0.0105	0.0191	2	2.0358	0.0358	0.0700
	α	0.5	0.5071	0.0071	0.0040	1.5	1.5206	0.0206	0.0355
100	eta	1.5	1.5168	0.0168	0.0245	1.5	1.5180	0.0180	0.0246
	a	2	2.0435	0.0435	0.1038	2	2.0565	0.0565	0.1402
	b	2	2.0526	0.0526	0.1184	2	2.0468	0.04687	0.0962
	γ	2	2.0049	0.0049	0.0093	2	2.0185	0.0185	0.0314
	α	0.5	0.5036	0.0036	0.0018	1.5	1.5074	0.0074	0.0167
200	β	1.5	1.5079	0.0079	0.0115	1.5	1.5094	0.0094	0.0114
	a	2	2.0215	0.0215	0.0453	2	2.0220	0.0220	0.0608
	b	2	2.0271	0.0271	0.0535	2	2.0220	0.0220	0.0446
	γ	2	2.0035	0.0035	0.0063	2	2.0072	0.0072	0.0206
	α	0.5	0.5020	0.0020	0.0012	1.5	1.5090	0.0090	0.0105
300	eta	1.5	1.5054	0.0054	0.0077	1.5	1.5033	0.0033	0.0076
	eta	2	2.0127	0.0127	0.0294	2	2.0221	0.0220	0.0381
	b	2	2.0153	0.0153	0.0361	2	2.0127	0.0126	0.0289

				Continu	ued of Ta	ble 1			
n	Par	Init	MLE	Bias	MSE	Init	MLE	Bias	MSE
	γ	2	2.0677	0.0676	0.1638	2	2.1000	0.1000	0.2439
	α	2	2.0258	0.0258	0.0428	2	2.0811	0.0811	0.2101
50	β	0.5	0.5108	0.0108	0.0059	2	2.0446	0.0446	0.0909
	a	2	2.0540	0.0540	0.1050	2	2.2140	0.2140	1.1668
	b	2	2.1049	0.1049	0.2696	2	2.1151	0.1151	0.2856
	γ	2	2.0479	0.0478	0.1001	2	2.0570	0.0570	0.1322
	α	2	2.0100	0.0100	0.0279	2	2.0519	0.0519	0.1092
75	β	0.5	0.5076	0.0076	0.0038	2	2.0266	0.0266	0.0541
	a	2	2.0257	0.0257	0.0652	2	2.1124	0.1124	0.2881
	b	2	2.0662	0.0661	0.1534	2	2.0685	0.0685	0.1559
	γ	2	2.0308	0.0308	0.0680	2	2.0479	0.0479	0.1035
	α	2	2.0112	0.0112	0.0213	2	2.0379	0.0379	0.0830
100	β	0.5	0.5049	0.0049	0.0027	2	2.0223	0.0223	0.0430
	a	2	2.0241	0.0241	0.0493	2	2.0822	0.0822	0.2088
	b	2	2.0461	0.0461	0.1043	2	2.0563	0.0563	0.1194
	γ	2	2.0258	0.0258	0.0346	2	2.0265	0.0265	0.0445
	α	2	2.0045	0.0045	0.0108	2	2.0153	0.0153	0.0382
200	β	0.5	0.5047	0.0047	0.0014	2	2.0135	0.0134	0.0198
	a	2	2.0096	0.0096	0.0246	2	2.0330	0.0330	0.0849
	b	2	2.0360	0.0360	0.0505	2	2.0316	0.0316	0.0522
	γ	2	2.0056	0.0056	0.0217	2	2.0181	0.0181	0.0302
	α	2	2.0042	0.0042	0.0072	2	2.0105	0.0105	0.0253
300	β	0.5	0.5007	0.0007	0.0009	2	2.0095	0.0095	0.0136
	a	2	2.0093	0.0093	0.0159	2	2.0225	0.0225	0.0542
	b	2	2.0083	0.0083	0.0307	2	2.0204	0.0204	0.0349

5 Applications

In this section, real data modeling performance of GIKw-W distribution is compared with several well-known distributions. We provide four applications to real data sets to illustrate the applicability of the GIKw-G family. We focus on the GIKw-W distribution introduced in Section 2. We compute the log-likelihood function evaluated at the MLEs ($\hat{\ell}$) using a limited-memory quasi-Newton code for bound-constrained optimization (L-BFGS-B). The goodness-of-fit measures, Anderson-Darling (A^*), Cramèr-von Mises (W^*) are computed for all models and used to decide the best model. The lower values of these statistics and higher p-values of K-S indicate good fits. The value for the Kolmogorov Smirnov (KS) statistic and its p-value are also provided. We compare the GIKw-W distribution with those of the Weibull (W), generalized inverted Kumaraswamy (GIKw) and Kumaraswamy (IKw).

The first data is corresponding to the vinyl chloride data obtained from clean upgrading, monitoring wells in mg/L (Bhaumik et al., 2009). The data set are given as follows: 5.1, 1.2, 1.3, 0.6, 0.5, 2.4, 0.5, 1.1, 8.0, 0.8, 0.4, 0.6, 0.9, 0.4, 2.0, 0.5, 5.3, 3.2, 2.7, 2.9, 2.5, 2.3, 1.0, 0.2, 0.1, 0.1, 1.8, 0.9, 2.0, 4.0, 6.8, 1.2, 0.4, 0.2.

The second data set is obtained from Murthy et al. (2004). The data refers to the time between failures for repairable items. The data set are given as follows: 1.43, 0.11, 0.71, 0.77, 2.63, 1.49, 3.46, 2.46, 0.59, 0.74, 1.23, 0.94, 4.36, 0.40, 1.74, 4.73, 2.23, 0.45, 0.70, 1.06, 1.46, 0.30, 1.82, 2.37, 0.63, 1.23, 1.24, 1.97, 1.86, 1.17

The third data set can be obtained from Hinkley (1977) and it represents thirty successive values of March precipitation (in inches) in Minneapolis/St Paul. The data set are given as follows: 0.77, 1.74, 0.81, 1.20, 1.95, 1.20, 0.47, 1.43, 3.37, 2.20, 3.00, 3.09, 1.51, 2.10, 0.52, 1.62, 1.31, 0.32, 0.59, 0.81, 2.81, 1.87, 1.18, 1.35, 4.75, 2.48, 0.96, 1.89, 0.90, 2.05.

The fourth data is based on the waiting times between 65 consecutive eruptions of Blowhole (1998). The data set are given as follows: 83, 51, 87, 60, 28, 95, 8, 27, 15, 10, 18, 16, 29, 54, 91, 8, 17, 55, 10, 35,47, 77, 36, 17, 21, 36, 18, 40, 10, 7, 34, 27, 28, 56, 8, 25, 68, 146, 89, 18, 73, 69, 9, 37, 10, 82, 29, 8, 60, 61, 61, 18, 169, 25, 8, 26, 11, 83, 11, 42, 17, 14, 9, 12.

The MLEs and the goodness of fit statistics of the models for all data sets are presented in Tables 2 to 9, respectively. As seen in Table 3, 5, 7, and 9 the GIKw-W model gives the lowest values. Therefore, it is clear that GIKw-W distribution provides the overall best fit and therefore could be chosen as the more adequate model for explaining data sets.

The histogram of the all data sets and the estimated pdf's and cdf's of the GIKw-W model and the other competitive models are displayed in Figures 5 and 6. It is clear from Figures 5 and 6 that the GIKw-W model provide better fits to these four data sets.

Distribution	α	eta	γ	a	b
GIKw-W	3.8371	9.2165	0.1699	0.0120	1.5582
	(6.2626)	(25.2396)	(0.4264)	(0.0279)	(1.3545)
GIKw	2.0265	0.8848	2.64300	-	-
	(1.8893)	(0.6646)	(3.8870)	-	-
IKw	1.7408	2.1058	-	-	-
	(0.3237)	(0.5373)	-	-	-
W	-	-	-	0.5262	1.0102
	-	-	-	(0.1176)	(0.1326)

Table 2: The MLEs and their standard errors (in parentheses) for the first data set.

Table 3: The goodness-of-fit statistics for the first data set

Distribution	\mathbf{A}^*	\mathbf{W}^*	l	K-S	P-value
GIKw-W	0.1832	0.0270	54.7047	0.0770	0.9899
GIKw	0.2805	0.0379	55.7572	0.0955	0.9153
IKw	0.2764	0.0378	55.7706	0.0965	0.9090
Weibull	0.3000	0.0462	55.4496	0.0918	0.9366

Table 4: The MLEs and their standard errors (in parentheses) for the second data set.

Distribution	α	eta	γ	a	b
GIKw-W	0.1199	1.1017	3.3626	6.0015	1.1272
	(0.0277)	(0.2661)	(0.0524)	(0.0066)	(0.0066)
GIKw	1.1631	1.847	1.4473	-	-
	(1.022)	(1.1798)	(1.3924)	-	-
IKw	2.4601	4.1715	-	-	-
	(0.4213)	(1.2783)	-	-	-
W	-	-	-	0.4560	1.4633
	-	-	-	(0.1141)	(0.2029)

Table 5: The goodness-of-fit statistics for the second data set

Distribution	\mathbf{A}^*	\mathbf{W}^*	$\hat{\ell}$	K-S	P-value
GIKw-W	0.1813	0.0231	39.1069	0.0748	0.9989
GIKw	0.2653	0.0409	40.8189	0.1092	0.8665
IKw	0.3323	0.04948	41.2380	0.1111	0.8523
Weibull	0.1921	0.0299	39.9909	0.0788	0.9900

D:1		0			1
Distribution	α	β	γ	a	b
GIKw-W	0.1308	1.2393	2.7063	4.7484	1.2909
	(0.0297)	(0.3783)	(1.6289)	(0.0038)	(0.0037)
GIKw	1.9540	1.4209	3.9458	-	-
	(1.8055)	(1.0186)	(5.6701)	-	-
IKw	2.9876	8.5933	-	-	-
	(0.4731)	(3.1240)	-	-	-
W	-	-	-	0.3154	1.8088
	-	-	-	(0.0906)	(0.2491)

Table 6: The MLEs and their standard errors (in parentheses) for the third data set.

Table 7: The goodness-of-fit statistics for the third data set

Distribution	\mathbf{A}^*	\mathbf{W}^*	$\hat{\ell}$	K-S	P-value
GIKw-W	0.1038	0.0144	37.9810	0.0547	0.9988
GIKw	0.3226	0.0514	30.3017	0.1097	0.8627
IKw	0.3505	0.0561	39.4255	0.1143	0.8280
Weibull	0.1693	0.0219	38.6432	.0689	0.9901

Table 8: The MLEs and their standard errors (in parentheses) for the fourth data set.

Distribution	α	eta	γ	a	b
GIKw-W	0.1705	4.5176	5.4997	1.9419	0.5709
	(0.0212)	(1.0214)	(0.0069)	(0.0029)	(0.0028)
GIKw	0.3096	4.2274	45.4405	-	-
	(1.1821)	(16.1314)	(16.8344)	-	-
IKw	1.3768	60.9128	-	-	-
	(0.1377)	(23.9816)	-	-	-
W	-	-	-	0.0085	1.2685
	-	-	-	(0.0039)	(0.1089)

Table 9: The goodness-of-fit statistics for the fourth data set

Distribution	\mathbf{A}^*	\mathbf{W}^*	ℓ	K-S	P-value
GIKw-W	0.7649	0.1039	293.2774	0.0981	0.6691
GIKw	1.2613	0.1848	295.4949	0.1018	0.5197
IKw	1.2044	0.1743	295.4044	0.0954	0.5047
Weibull	1.0078	0.1470	296.9085	0.1060	0.4681



Figure 5: Estimated pdf in (a) and cdf in (b) for the first data set and estimated pdf in (c) and cdf in (d) for the second data set, respectively.



Figure 6: Estimated pdf in (a) and cdf in (b) for the third data set and estimated pdf in (c) and cdf in (d) for the fourth data set, respectively.

6 Conclusion

This paper introduces a new class of models called the "GIKw-G" family of distributions which can generate all classical continuous distributions while is proved suitable for data of heavy-tails and exhibiting different features of skewness and reverse J-shapes. For any parent continuous distribution G, we define corresponding GKIw- G distribution. We study some of statistical and mathematical properties of the new generator, such as ordinary moments, quantile functions, Shannon and Rennyi, entropies and order statistics. We discuss maximum likelihood estimates of the model parameters. Four applications of the new family and a simulation study demonstrate its usefulness and potentiality to analysis of real data. This new family and its generated models is commendably useful in several areas such as engineering, survival and lifetime data, hydrology, economics, among others.

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