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## Comment on "Growth of Low-Frequency Electrostatic and Electromagnetic Instabilities in a Hall Thruster"

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We revisit the electrostatic instability model of Singh and Malik (IEEE Trans. Plasma Sci. 39:10 (2011) 1910–1918) and correct some errors.

52.35.Fp Electrostatic waves and oscillations

### I. INTRODUCTION

Hall thrusters are promising devices for satellite station keeping and propulsion because of their high thrust density, and they are undergoing significant development. Understanding and controlling their instabilities is a major research topic.

In this context, low-frequency instabilities have been investigated in particular by Singh and Malik [1]. We refer to Wei *et al.* [2] and Smolyakov *et al.* [3] for recent reviews.

### II. ASSUMPTIONS AND DISPERSION RELATION FOR ELECTROSTATIC MODES

It is well-known that "[the] full picture of instabilities in Hall plasmas is complex and, for typical experimental conditions, likely involves a number of interacting modes which require numerical simulations" [3]. However, analytical approaches with simplified models help to grasp processes intuitively. This motivates the interest for classical stability analyses near simple references states of the plasma. Unfortunately, Hall plasmas are often out-ofequilibrium, nonuniform, unsteady systems, challenging elementary descriptions.

Singh and Malik's model describes the plasma as two fluids in a uniform magnetic field  $\vec{B}_0 = B_0 \vec{e}_z$ , with ions flowing along the *x*-axis and electrons along the *y*-axis, respectively with velocities  $\vec{v}_{i0} = v_{i0}\vec{e}_x$  (denoted  $\vec{v}_0$  in [1]) and  $\vec{v}_{e0} = v_{e0}\vec{e}_y$  (denoted  $\vec{u}_0$  in [1]). This geometry assimilates the cylindrical chamber to a slab, with *z* radial, *x* parallel to the chamber axis, and *y* azimuthal. Due to the axial electric field in the chamber, electrons have a significant azimuthal drift, while ions move essentially axially, and, due to their large mass ratio, ions can be considered unmagnetized while electrons are sensitive to the magnetic force. Both species have finite temperatures,  $T_{\rm i}$  and  $T_{\rm e}$ , and the small pressure oscillations should be understood to be adiabatic<sup>1</sup> ( $\delta(p_s n_s^{-Y_s}) = 0$  with  $Y_s = 2$  for both species  $s = {\rm e}, {\rm i}$  treated as two-dimensional monatomic ideal gases). The model also involves electron collisions with neutrals, with a frequency  $\nu$ .

Dynamics is essentially two-dimensional, in the xy plane (normal to  $\vec{B}_0$ ). The reference state is taken to be uniform, with density  $n_{i0} = n_{e0} = n_0$ . The effect of collisions involving ions are neglected. The effect of elastic electron-neutral collisions is taken into account. The linearized evolution equations read

$$\partial_t n_{i1} + v_{i0} \partial_x n_{i1} + n_{i0} \nabla \cdot \vec{v}_{i1} = 0 \tag{1}$$

$$\partial_t \vec{v}_{i1} + v_{i0} \partial_x \vec{v}_{i1} = \frac{e}{m_i} \vec{E}_1 - \frac{1}{m_i n_{i0}} \nabla p_i$$
 (2)

$$\partial_t n_{\rm e1} + v_{\rm e0} \partial_y n_{\rm e1} + n_{\rm e0} \nabla \cdot \vec{v}_{\rm e1} = 0 \tag{3}$$

$$\partial_t \vec{v}_{e1} + v_{e0} \partial_y \vec{v}_{e1} = -\frac{e}{m_e} (\vec{E}_1 + \vec{v}_{e1} \wedge \vec{B}_0 + \vec{v}_{e0} \wedge \vec{B}_1)$$

$$-\frac{1}{m_{\rm e}n_{\rm e0}}\nabla p_{\rm e} - \nu \vec{v}_{\rm e1} \tag{4}$$

$$\nabla \cdot \vec{E}_1 = \frac{e}{\epsilon_0} (n_{i1} - n_{e1}) \tag{5}$$

Focusing on electrostatic modes, the contribution of  $\vec{B}_1$  is neglected, while electric field oscillations derive from a potential,  $\vec{E}_1 = -\nabla \phi_1$ . This system is Fourier-transformed with  $\partial_t = i\omega$  and  $\nabla = -i\vec{k}$ , and the Poisson equation reads

$$(k_x^2 + k_y^2)e\phi_1 = \frac{e^2}{\epsilon_0}(n_{i1} - n_{e1}) = \omega_{pi}^2 m_i \frac{n_{i1} - n_{e1}}{n_{i0}} \quad (6)$$

where we highlight the ion plasma frequency which will be used to normalize all frequencies and growth rates.

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<sup>&</sup>lt;sup>1</sup> Rather than obeying the unusual  $p_s = Y_s n_s T_s$ .

The dispersion relation of system (1)–(5) is then a fifth-degree polynomial in  $\tilde{\omega} := \omega/\omega_{\rm pi}$ . Focusing on low-frequency oscillations leads the authors to a thirddegree polynomial, under the assumption that the electron gyrofrequency  $\Omega = |e|B_0/m_e$  be much larger than  $\max(\omega, k_y v_{e0}, \nu)$ . Computing the coefficients in the polynomial is tedious, but straightforward, see [1], leading to the lengthy Eq. (18) in Ref. [1]. Inspection of the coefficient of the  $\omega^2$  term in the polynomial shows that the sum of all three roots has a positive imaginary part (proportional to  $i\nu$ ); actually, there are generally two roots with positive Im $\omega$ , corresponding to damped modes. Therefore, the largest Im ( $-\omega$ ) characterizes either the instability (when it is positive) or the least damped stable mode (when it is negative).

The numerical values they report from studying this equation turn out to be erroneous. With their numerical data, we find much smaller growth rates and qualitatively different dependences on physical parameters.

We followed Ref. [1] for all data selections on figures 1– 6. For all figures, except for the abscissa, parameters are  $n_0 = 10^{18} \text{ m}^{-3}$ ,  $B_0 = 15 \text{ mT}$ ,  $k_x = 20 \text{ rad/m}$ ,  $k_y = 400 \text{ rad/m}$ ,  $T_e = 10 \text{ eV}$ ,  $T_i = 1 \text{ eV}$ ,  $v_{e0} = 10^6 \text{ m/s}$ ,  $v_{i0} = 5 \cdot 10^4 \text{ m/s}$ ,  $\nu = 10^6 \text{ s}^{-1}$  with xenon ions ( $m_i = 131 \text{ Da}$ ). The ordinate (note factor  $10^6$ ) is the instability growth rate scaled to the ion plasma angular frequency  $\omega_{pi} = 1.15 \cdot 10^8 \text{ rad/s}$ , according to Eq. (18) in Ref. [1].

For Figure 7, we consider another range of electron

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drift velocities, showing that a smaller  $v_{e0}$  (outside the thruster regular operation regime) results in a significantly stronger instability, except for a tiny velocity interval around  $k_x v_{i0}/k_y$  (the value for which both ion drift and electron drift generate the same Doppler shift in the system (1)-(4)) where the growth rate decreases and the instability can even be suppressed : all eigenmodes (with the same wavenumbers) are stable for these small  $v_{e0}$ 's.

We leave the analysis of these figures for a later publication, as this discussion requires deeper investigation in the physics of the instability process. Besides, the consistency of the linearized equations may be questioned, as Hall thruster plasmas are often neither uniform nor stationary.

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FIG. 1. Growth rate as a function of magnetic field.

 $\tt SinghMalik\_rev\_fig2-eps-converted-to.pdf$ 

FIG. 2. Growth rate as a function of azimuthal wavenumber.



FIG. 3. Growth rate as a function of electron-neutral collision frequency.

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FIG. 4. Growth rate as a function of electron drift velocity.



FIG. 5. Growth rate as a function of electron temperature.

 $\tt SinghMalik\_rev\_fig6-eps-converted-to.pdf$ 

FIG. 6. Growth rate as a function of ion temperature.



FIG. 7. Growth rate as a function of electron drift velocity.