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# 3D Bifurcations characterization for intra-cranial aneurysms prediction

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#### ABSTRACT

An aneurysm is a vascular disorder represented by a ballooning of a blood vessel. The blood vessel's wall is distorted by the blood flow, and a bulge forms there. When ruptured, the aneurysm may cause irreversible damage and could even lead to premature death. Intra-cranial aneurysms are the ones presenting the higher risks. In this work, thanks to a graph based approach, we detect the bifurcations located on the circle of Willis within brain mice cerebral vasculature. Once properly located in the 3D stack, we characterize the cerebral arteries bifurcations, i.e. we gather several properties of the bifurcation, such as their angles, or area cross section, in order to further estimate geometrical patterns that can favor the risk of occurrence of an intra-cranial aneurysm. Effectively, apart from genetic predisposition, and environmental risk factors (high blood pressure, smoking habits, ...) the anatomical disposition of the brain vasculature may influence the chances of an aneurysm to form. Our objectives in this paper is to obtain accurate measurements on the 3D bifurcations.

#### 1. INTRODUCTION

### 1.1 Project Context

An aneurysm is a bulge of an artery, it may occur on any artery of the human body. The formation of aneurysms could be due to various factors that lead to a weakened vessel wall. Hypertension may increase the risk of formation of an aneurysm and it has recently been showed that a genetical anomaly could also cause aneurysms. The main complication of aneurysm is the rupture, it may then lead to a subarachnoid hemorrhage and at last to the death. Commonly, intra-cranial aneurysms are monitored thanks to Computed Tomography Angiography or Magnetic Resonance Angiography. The imaging strategy produces a digital 3D stack. A cerebral angiography thus displays the full brain vasculature as a 3D volume. Regular Magnetic Resonance Imaging, and more particularly T1 acquisitions, can be exploited, but will necessitate a proper blood vessels segmentation in order to be able to distinguish the aneurysms.

This work is part of a wide national research project<sup>3</sup> (the ICAN project) which aims to understand the multiple factors that may favor the formation of saccular intra-cranial aneurysms along the<sup>4,5</sup> circle of Willis. During the first part of the project, mice are stressed (drinking only salt water) in order to induce saccular intra-cranial aneurysms, and then go through micro scan acquisition. In the second part of this project, the tools for aneurysms detection will be applied directly on human acquisition, on MRI (T1) acquisitions. In this project, we are particularly interested in investigating the saccular aneurysms occurring onto the 9 main bifurcations composing the circle of Willis. We thus need to correctly detect these bifurcations. Unlike most studies from

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the literature, in this work, the volumes are acquired using a micro-scan instead of MRA or MRI acquisitions. Mice went through a Baryum Sulfate injection in the vascular tree, prior to a cerebral micro-scan acquisition. We have at our disposal the micro scan acquisition of 22 mice brains.

#### 1.2 Related works

In the literature, many studies are devoted to the detection of blood vessels bifurcations, these works may focus on the vascular tree within the liver,<sup>6</sup> the lungs<sup>7–9</sup> or even<sup>10</sup> the retina. Some works do focus on cerebral<sup>11,12</sup> vasculature. The reader is directed to two interesting reviews<sup>13,14</sup> for further details on the various methods for vessels segmentation.

Although many studies can be found on the detection of blood vessels in 3D imaged stacks, <sup>13, 14</sup> fewer works can be found on the arteries characterization. As explained in <sup>15</sup> the detection of bifurcations in a vascular tree is very important. In their works, the authors propose a parametric geometric deformable model in order to fit the actual 3D medical images of bifurcations. A common method for detecting blood vessels directions, and hence possibly detect bifurcations within CT or MRA images is to use<sup>16,17</sup> the Eigenvalues of the Hessian matrix. In, <sup>17</sup> the authors use a multi-scale analysis to extract blood vessels of various diameters. They propose several models of vessels, such as Gaussian, toroidal or elliptical-like cross-sections vessels. Using the Eigenvectors and Eigenvalues of the Hessian matrix, the authors then estimate the center-lines and are further able to detect the junctions formed by the modeled vessels. Some authors opt for the use of variational region growing methods, such as in,<sup>7</sup> where the authors had to face the delineation of the lung within CT images, in order to properly extract the pulmonary vascular tree. Such methods may suffer from weak performances against the smallest vessels. When cerebral vasculature is considered, it is actually rather difficult to use learning based methods, as there is a significant variability<sup>5,11</sup> amongst different vasculatures. In<sup>5</sup> a skeletonization method is used to extract the vessels center-lines, but seed points have to be manually determined.

As was pointed out in 18, it has been showed that the geometry of the bifurcation correlates quite well with various diseases, as it influences the fluid mechanics of the blood flow. Again, works in 19 show that fluid dynamics play an important role in the formation of aneurysms. Authors in 20 studied the deviation of the saccular aneurysm away from the bifurcation. Their study was dedicated to aneurisms occurring on the internal carotid artery. They mostly focused on the angle formed by the three branches of the bifurcation. They measured the bifurcation angles as well as the shift of the aneurysmal neck away from the mother branch of the artery. Among the various factors that may affect the fluid dynamics of the blood flow, the geometry of the bifurcations (angles), the distance separating two consecutive bifurcations, the tortuosity of the artery branch, the diameters of the arteries at the bifurcation are all the parameters that have an impact on the blood speed, and thus the risk of formation of an aneurysm. In this work, we thus intend to propose a method that first searches for the bifurcations, and then automatically computes the various parameters characterizing the arterial tree (see the above mentioned characteristics).

This paper is organized as follows: We first present in section 2, the method we use to detect the bifurcations within the 3D stack. In section 3, we propose some new methods to measure the bifurcation's geometrical properties, such as the angles, geodesic distance, arteries cross-section, or the branches tortuosity. We finally conclude this study in section 4.

#### 2. AUTOMATIC 3D BIFURCATION DETECTION

In this paper, we are interested in the characterization of 3D bifurcations in the cerebral vasculature. Therefore, the first stage of the characterization pipeline consists in the automatic detection of the bifurcations in the vascular tree. We present in this section an accurate and fast approach that detects and provides 3D coordinates of the bifurcations centers in 3D stacks. In the following, a 3D volume is denoted by U.

#### 2.1 Graph-based detection

We first compute the 3D skeleton S associated to the stack U using the method<sup>21</sup> proposed by Lee at al. . To each voxel  $s_i$  of S are associated its 3D coordinates  $\mathbf{s}_i = (x_i, y_i, z_i)$ . Exploiting the skeleton instead of the 2D slices pixels permits both a gain in processing time (since the images are reduced to 1 pixel wide representation) and

to accurately detect the center of the bifurcation. Afterwards, a non oriented graph G = (V, E, w) is constructed on the entire 3D skeleton where V represents the set of nodes,  $E \in V \times V$  the set of edges and  $w(v_i, v_j)$  the weight of the edge  $e(v_i, v_j) \in E$  connecting the nodes  $v_i$  and  $v_j$ . Similarly to S, to each node  $v_i \in V$  of the graph are associated its 3D coordinates  $\mathbf{v}_i = (x, y, z)$ . The significant benefits from using the graph structure can be summarized in 3 points: 1) The graph allows to scour the skeleton (and hence the stack) in 3D thus avoiding the 2D slice by slice analysis. This preserves the 3D information that may be lost when moving to 2D analysis. 2) Accurate localization of the bifurcation center in the 3D space. 3) Only locate the bifurcations of interest along the Circle of Willis, since this is where most intra-cranial aneurysms<sup>11</sup> occur.

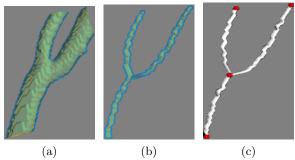


Figure 1: (a), (b) and (c) respectively represent a bifurcation, its 3D skeleton and the graph with red nodes and white edges.

It is important to note that the graph skeleton of a bifurcation has a Y-junction shape and contains four nodes (see Fig. 1), one node at the center of the 3D skeleton bifurcation and the three remaining at the end points of the three branches. Therefore, if any of the graph nodes has three neighbors, this node is considered as the center of the bifurcation. Such selected point undoubtedly represents a true bifurcation.

#### 2.2 Results

As previously explained, we are strongly interested by the detection of bifurcations belonging to the Circle of Willis since  $^{11}$  intra-cranial aneurysms mainly occur there. Hence, we have tested our approach on different 3D cerebral vasculatures in order to verify if all the bifurcations located in the circle of Willis are detected. We have tested our approach on different 3D cerebral vasculature stacks. Figure 2(a) presents a gray level 3D stack of size  $1185 \times 1008 \times 1008$  acquired using a micro scan. We can notice that the proposed approach detects all possible 3D bifurcations along the Circle of Willis which are the bifurcations of interest.

#### 2.2.1 Comparison with the state of the art

We compare the proposed approach with two methods of the literature<sup>15,22</sup> considering the  $Vascusynth^{23,24}$  database. This database consists of 12 randomly generated 3D stacks with a varying number of bifurcations. The bifurcation centers are given in the form of 3D coordinates (x, y, z).

A subset of the *Vascusynth* database constituted of 10 volumes with 16 bifurcations each is considered to compare the three methods. We used cumulative histograms of distances from detected center bifurcations (DB) to the closest ground truth locations (GT). Fig. 3 presents the obtained cumulative histograms. We can notice from these histograms that our approach succeeds in detecting all the bifurcations located at most 19 pixels away from the ground truth centers (Fig. 3(a)) while the two competing methods <sup>15,22</sup> both require a distance greater than 50 pixels to achieve a complete detection. One can also notice that the curve associated to our approach (Fig. 3(a)) is steeper than the ones of the two competing methods (Figure 3(b)). This means that the majority of the bifurcations have been detected with high precision.

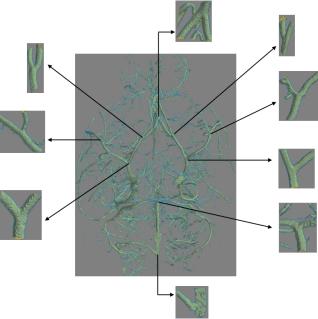


Figure 2: Detected bifurcations in a 3D mouse cerebral vasculature. All possible bifurcations in the 3D stack and particularly those located in the Circle of Willis are correctly detected.

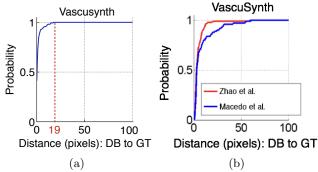


Figure 3: Cumulative histograms of distances between the predicted bifurcation localizations and the ground truth localizations of 10 volumes with 16 bifurcations each:<sup>23,24</sup> (a) Our approach and (b) approaches of <sup>15,22</sup> (Fig. from <sup>15</sup>).

#### 3. 3D BIFURCATIONS CHARACTERIZATION

In this section, we present a geometric characterization of 3D bifurcations which is based on different intrinsic attributes of the detected bifurcations geometry. Geometrical characterization of intra-cranial bifurcations can be analyzed for saccular aneurysms prediction<sup>18</sup> purpose. This constitutes the second part of the project as described in the introduction.

In the following, we propose some methods to automatically measure the bifurcations angles, their cross-section, as well as the branches' tortuosity. In this paper, we voluntarily omit the measures of the geodesic distances between bifurcations, as a simple count of the skeleton's voxels precisely determines the length of the branch.

#### 3.1 Angles computation

Aneurysms are more prevalent at bifurcations with greater bifurcation angles <sup>18</sup> (wider angle between the daughter branches). Quantifying automatically this anatomical attribute is of great interest for aneurysms prediction. We thus compute all possible angles in the bifurcations as illustrated in Fig. 4(b). In order to best illustrate the measured angles, a 3D bifurcation B was extracted from the stack within a  $20 \times 20 \times 20$  3D block. Then we consider its 3D skeleton  $S_B$  as well as the graph constructed on the latter  $G_B$ . Figure 4(b) presents the 3D skeleton  $S_B$  with the four graph nodes: the bifurcation center  $v_C$ , and the three remaining nodes  $v_L, v_M, v_N$  representing the bifurcation end points. Once these nodes defined, the bifurcation angles can be computed as:

$$\widehat{A1} = atan2(|| - \mathbf{CN \cdot CL}||_2, -\mathbf{CN \cdot CL})$$
(1)

where the vectors **CN** and **CL** are defined respectively as **CN** = **N** - **C**, **CL** = **L** - **C**. The function atan2(y, x) computes the arc tangent of all four quadrants, providing a result in  $[-\pi, \pi]$ . The symbols • and • respectively represent the cross and dot product. The notation  $||.||_2$  refers the second norm. Each remaining angle is computed similarly to  $\widehat{A1}$ .

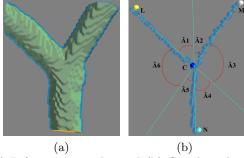


Figure 4: (a) Bifurcation angles and (b) Graph and target angles.

We have compared the angle values obtained from our approach with those measured using the well known FIJI (ImageJ)<sup>25</sup> software. Table 1 presents these results. We can notice that the angle values provided by our approach are highly correlated with those given by FIJI. Moreover, these angles are automatically computed, without any user intervention.

Table 1: Comparison between the angle values measured using the FIJI software and those obtained by our approach.

| Angles        | <b>A</b> 1 | <b>A2</b> | <b>A3</b> | <b>A4</b> | $\mathbf{A5}$ | <b>A6</b> |
|---------------|------------|-----------|-----------|-----------|---------------|-----------|
| FIJI software | 45.70      | 34.86     | 100.27    | 45.70     | 34.86         | 100.27    |
| Our approach  | 45.73      | 34.87     | 100.29    | 45.73     | 34.87         | 100.29    |

#### 3.2 Branches area sections

Yet another significant anatomical property that may explain the occurrence of intra-cranial aneurysms is the thickness of the arteries. Considering a bifurcation B of center  $v_C$  in the 3D skeleton S, we delimit the latter with three voxels  $A_1$ ,  $A_2$  and  $A_3$  located at a distance of 30 voxels from the bifurcation center  $v_C$  on each branch. The aim is to compute three discrete plans  $\mathbf{P}_1$ ,  $\mathbf{P}_2$  and  $\mathbf{P}_3$  in the 3D space which will cut each respective branch (b1, b2, b3) of the bifurcation B through three respective skeleton voxels  $A_1$ ,  $A_2$  and  $A_3$ .

Suppose that we have to compute the discrete plan  $\mathbf{P}_1$  cutting the branch b1 through the voxel  $A_1$ . For this, we select a voxel  $A_{1N} \in b1$  nearby  $A_1$  (we choose a distance equal to seven voxels) in order to have a cut plane  $\mathbf{P}_1$  tangent to the voxel  $A_1$  and perpendicular to the vector  $\mathbf{A}_1\mathbf{A}_{1N}$ . Once the voxels  $A_1$  and  $A_{1N}$  determined, the cut plan can be computed according to the algorithm 1. Figure 5(a) presents a 3D bifurcation with a plan

cutting its branch b1. Figure 5(b) shows the 3D skeleton of 5(a). The voxels located at the intersection between the 3D skeleton and the discrete plane represent the cross section of the branch (see yellow voxels in figure5(b)). These can be easily selected since the 3D skeleton as well as the plan are represented as 3D matrices. The area section is then simply obtained by counting the intersection vertices (yellow vertices). In order to cope with branches having different localized cross sections areas, we propose to compute three different cut planes with three different cross section areas. The final branch cross section area is defined as the average of the three computed areas.

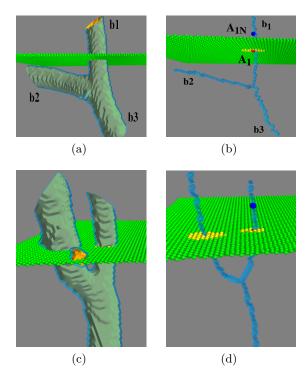


Figure 5: Cut plan through the branches of a 3D bifurcation. Left: 3D bifurcations with cutting plane, and right: skeleton and cross section (see text for details).

In some cases, the angle between the daughter branches of a 3D bifurcation is relatively small. This leads to a plane cutting the bifurcation through two branches as presented in 5(c). Also, we can remark from figure 5(d) presenting the 3D skeleton of 5(c) that the intersection voxels  $I_i$  colored in yellow are related to the two branches at the same time. The aim now is to distinguish between the intersection voxels related to each branch in order to compute their different cross section areas. To tackle this problem, we propose a simple and fast clustering approach. Having the coordinates of the voxel A (red voxel in figure 5(d)) through which the plane cuts the bifurcation, we compute the euclidean distance  $D_i$  between A and all the intersection voxels  $I_i$  (colored in yellow in figure 5(d)) and sort them. Afterwards, a clustering method is applied on the inter-voxels distances to separate the two branches.

#### 3.3 Tortuosity estimation

Artery tortuosity is significantly associated  $^{26}$  with intracranial aneurysm. Among the tortuosity definitions, we find the curvature degree. Hence, we propose in this section an approach computing the tortuosity of an artery based on the curvature of its voxels. Given a 3D skeleton S' of an artery, normal vectors of binary voxels are

#### Algorithm 1 Cut plane of a 3D bifurcation branch in the 3D space

```
 \begin{array}{l} \mathbf{AB} \leftarrow (B_x - A_x, B_y - A_y, B_z - A_z) \\ X \leftarrow [1:120] \\ y \leftarrow [1:120] \\ indicesplan \leftarrow \text{List } (Indices \ of \ voxels \ constituting \ the \ cut \ plan) \\ \mathbf{for \ each} \ i \ in \ X \ \mathbf{do} \\ \mathbf{for \ each} \ j \ in \ Y \ \mathbf{do} \\ z \leftarrow (-(\mathbf{AB}_x * (i - A_x)) - (\mathbf{AB}_y * (j - A_y)))/\mathbf{AB}_z + A_z \\ \mathbf{if} \ z < 120 \ \mathbf{then} \\ z = \lfloor z \rfloor \\ indicesplan. \mathrm{push}(i,j,z) \\ \mathbf{end \ if} \\ \mathbf{end \ for} \\ \mathbf{end \ for} \\ \mathbf{end \ for} \\ \mathbf{end \ for} \\ \mathbf{return} \ indicesplan \end{array}
```

first computed and oriented in the same direction (Fig. 6). Then, the curvature of a voxel  $S'_i$  is defined as:

$$Curvature(S_i') = \frac{1}{|N(S_i')|} \sum_{j=i-1}^{|N(S_i')|} \delta_j$$
(2)

where  $|N(S_i')|$  is the cardinality of the neighborhood of  $S_i'$  and  $\delta_j$  represents the difference between the normal vectors, such as:

$$\delta_i = \frac{(n_j - n_i) \cdot (S'_j - S'_i)}{||S'_j - S'_i||_2^2} \text{ with } S'_j \sim S'_i$$
(3)

where  $n_i$  and  $n_j$  represent the normal vectors defined on the voxels  $S_i'$  and  $S_j'$ . The symbol  $\sim$  refers to adjacency.

Finally, the tortuosity of a 3D artery is defined as the average of its voxels's curvature. Figure 7 presents the tortuosity of an artery.

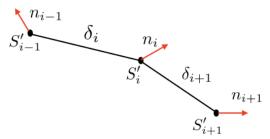


Figure 6: Oriented normal vectors on each skeleton voxel  $S_i'$ .

#### 4. CONCLUSION AND PERSPECTIVES

Neuroradiologists suspect that the apparition of intra-cranial saccular aneurysms may be correlated with some particular anatomical properties of the cerebral vasculature. Indeed fluid mechanics of the blood flow within the cerebral arteries could induce the aneurysms. The bifurcations are of particular interest. In this work, we have presented a simple full automatic method for the bifurcation detection and characterization in 3D cerebral vasculature. The proposed approach was tested on different 3D micro scan acquisitions and the associated results show that all bifurcations have been detected and especially those located in the circle of Willis which was our focus in this work. We also compared the proposed approach with two state-of-the-art methods using a ground

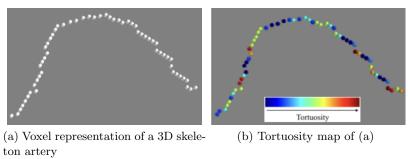


Figure 7: Tortuosity of a 3D artery.

truth providing 3D coordinates of center bifurcations generated randomly with an increasing bifurcation number. Results show that the proposed approach is very competitive and outperforms the two considered state-of-the-art approaches.

Thanks to the use of a 3D graph applied onto the vasculature skeleton, we can accurately determine the bifurcation centers. Once the bifurcations detected, we have proposed some methods to characterize the various geometrical features of the bifurcation. We can thus measure the angles formed by the daughter branches, the cross-sections of the three arteries composing the bifurcation, as well as the tortuosity of the mother branch. The proposed automatic computation of the geometrical features proved to fit very accurately the ground truth (manual measurements). In future works the proposed method will be tested on human brain acquisitions (Magnetic Resonance Angiography volumes). We will also compare the various features estimations (cross-sections, tortuosity) with ground truth measurements (collected from experts). Moreover, we will also conduct an in depth study on the influence of the bifurcation geometry on the probability of aneurysm occurence.

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