



HAL
open science

A topological obstruction to the controllability of nonlinear wave equations with bilinear control term

Thomas Chambrion, Laurent Thomann

► **To cite this version:**

Thomas Chambrion, Laurent Thomann. A topological obstruction to the controllability of nonlinear wave equations with bilinear control term. 2018. hal-01876952v1

HAL Id: hal-01876952

<https://hal.science/hal-01876952v1>

Preprint submitted on 19 Sep 2018 (v1), last revised 1 May 2019 (v3)

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

A TOPOLOGICAL OBSTRUCTION TO THE CONTROLLABILITY OF NONLINEAR WAVE EQUATIONS WITH BILINEAR CONTROL TERM

THOMAS CHAMBRION AND LAURENT THOMANN

ABSTRACT. In this paper we prove that the Ball-Marsden-Slemrod controllability obstruction also holds for nonlinear equations, with L^1 bilinear controls. We first show an abstract result and then we apply it to nonlinear wave equations. The first application to the Sine-Gordon equation directly follows from the abstract result, and the second application concerns the cubic wave/Klein-Gordon equation and needs some additional work.

CONTENTS

| | |
|---|----|
| 1. Introduction and main result | 2 |
| 1.1. Introduction | 2 |
| 1.2. Notations | 2 |
| 1.3. Main result | 3 |
| 2. Ball-Marsden-Slemrod obstructions for nonlinear equations | 3 |
| 2.1. Dyson expansion of the solutions | 3 |
| 2.2. A compactness result | 5 |
| 2.3. Proof of the nonlinear Ball-Marsden-Slemrod obstructions | 6 |
| 3. Applications | 7 |
| 3.1. The Sine-Gordon equation | 7 |
| 3.2. The wave equation in dimension 3 | 7 |
| Appendix A. Sobolev spaces | 12 |
| A.1. Definition | 12 |
| A.2. Sobolev embedding theorem | 13 |
| Acknowledgments | 13 |
| References | 13 |

2000 *Mathematics Subject Classification.* 35Q93 ; 35L05.

Key words and phrases. Control theory, bilinear control, obstructions, nonlinear wave and Klein-Gordon equations.

1. INTRODUCTION AND MAIN RESULT

1.1. Introduction. Evolution equations with a bilinear control term are often used to model the dynamics of a system driven by an external field (for instance, a quantum system driven by an electric field). In view of their importance, very few satisfactory description of the attainable set of such systems are available (among the rare exceptions, see Beauchard [3] for the case of the linear Schrödinger equation on a 1D compact domain or [4] for the linear wave equation on a 1D compact domain). For an overview of controllability results of bilinear control systems, we refer to Khapalov [9].

Roughly speaking, the attainable set for such systems does not coincide with the natural functional space where the system is defined. An explanation came with a celebrated article of Ball, Marsden and Slemrod [2] who proved that the attainable set of linear dynamics with a bounded bilinear control using L^r , $r > 1$ real valued controls, is contained in a countable union of compact sets. This result has been adapted to the case of the Schrödinger equation by Turinici [11]. For partial differential equations posed in an infinite dimensional Banach space, this represents a strong topological obstruction to the controllability (since the attainable set has hence empty interior by the Baire theorem). The proof heavily relies on the reflectiveness of L^r , $r > 1$ and could not be directly extended to L^1 controls.

Boussaïd, Caponigro and Chambrion [6] recently extended this obstruction to the case of L^1 (and even Radon measures) controls by considering Dyson expansion of the solution. We show here that this technique can be adapted to the case of some nonlinear wave equations. This shows in particular that the nonlinear term does not help to control the equation in its natural energy space.

We consider the following abstract control system

$$(1.1) \quad \begin{cases} \psi'(t) = A\psi(t) + u(t)B\psi(t) + K(\psi(t)), \\ \psi(0) = \psi_0 \in \mathcal{X}, \end{cases}$$

with real valued controls $u : \mathbf{R} \rightarrow \mathbf{R}$ and with the following assumptions

Assumption 1.1. The element (\mathcal{X}, A, B, K) satisfies

- (i) \mathcal{X} is Banach space endowed with norm $\|\cdot\|_{\mathcal{X}}$.
- (ii) $A : D(A) \rightarrow \mathcal{X}$ is a linear operator with domain $D(A) \subset \mathcal{X}$ that generates a C^0 semi-group of bounded linear operators. We denote by $\omega \geq 0$ and $M > 0$ two numbers such that $\|e^{tA}\|_{L(\mathcal{X}, \mathcal{X})} \leq Me^{\omega t}$ for every $t \geq 0$.
- (iii) $B : \mathcal{X} \rightarrow \mathcal{X}$ is a linear bounded operator.
- (iv) $K : \mathcal{X} \rightarrow \mathcal{X}$ is k -Lipschitz-continuous (not necessarily linear), with $k > 0$.

In the sequel, the equation (1.1) is interpreted in its mild form, namely, we say that a function $\psi : [0, T] \rightarrow \mathcal{X}$ is a solution of (1.1) if, for every t in $[0, T]$,

$$(1.2) \quad \psi(t) = e^{tA}\psi_0 + \int_0^t u(s)e^{(t-s)A}B\psi(s)ds + \int_0^t e^{(t-s)A}K(\psi(s))ds.$$

Equation (1.2) is often called the Duhamel formula.

1.2. Notations. Throughout the paper, for the sake of readability, we omit the range in the notation of spaces of real-valued functions. For instance, if X is a space, $H^k(X)$ denotes the set of H^k regular real functions on X .

In a metric space X endowed with distance d_X , we define the ball centered in $x \in X$ with radius $r > 0$ by $B_X(x, r) = \{y \in X | d_X(x, y) < r\}$. If X is a vector space endowed with norm $\|\cdot\|_X$, the distance associated with the norm is denoted d_X : $d_X(x, y) = \|x - y\|_X$, for every x, y in X .

1.3. Main result. Under Assumption 1.1, one can show that equation (1.1) admits a global flow Φ^u (see Propositions 2.2 and 2.3). Our main result concerning the control of (1.1) gives a description of the attainable set and reads as follows

Theorem 1.2. *Let (\mathcal{X}, A, B, K) satisfy Assumption 1.1. Then, for every ψ_0 in \mathcal{X} , the attainable set from ψ_0 of (1.1) with controls u in $L^1([0, +\infty))$:*

$$\bigcup_{t \geq 0} \bigcup_{u \in L^1([0, t])} \left\{ \Phi^u(t) \psi_0 \right\}$$

is contained in a countable union of compact subsets of \mathcal{X} .

This result gives a clear obstruction to the controllability of (1.1) in a general setting, since it shows that the attainable set is meager in the sense of Baire. However, as noted by Beauchard and Laurent in [5, Section 1.4.1], this result does not forbid exact controllability in a smaller space, endowed with a stronger norm (for which the operator B is not continuous anymore). In this sense, this obstruction to controllability may be seen as an unfortunate choice of the ambient space.

The proof of Theorem 1.2 relies on the description of the solutions of (1.1) using series, called Dyson expansion (see Section 2). This strategy has been successfully carried out in [6], and we show here that it can also be applied to nonlinear problems. For more details on Dyson expansions, we refer to [10, Theorem X.69 and equation (X.129)].

In the assumptions of the Theorem 1.2, the fact that K is Lipschitz is needed in order to ensure the existence of a global flow of (1.1), but in the core of the proof of our result we only need that K is continuous (see Proposition 2.6).

We give two explicit applications of Theorem 1.2 to nonlinear wave equations. We first give the example of the Sine-Gordon equation, which exactly matches Assumption 1.1 and where the result of Theorem 1.2 directly applies. Then, by the means of the 3-dimensional cubic Klein-Gordon equation, we show that the hypothesis " K is Lipschitz " can be relaxed. Actually, for the nonlinear wave equation (see Section 3.2), the gain of derivative in the Duhamel formula allows to bound the nonlinearity using Sobolev estimates, and the global existence of a flow can be obtained thanks to energy estimates.

We are also able to obtain negative controllability results for the nonlinear Schrödinger equation, and this will be treated in our forthcoming paper [7].

Remark 1.3. By rather simple modifications, the result of Theorem 1.2 can be extended to the case of the equation

$$\psi'(t) = A\psi(t) + \sum_{j=1}^n u_j(t) B_j \psi(t) + \alpha(t) K(\psi(t)),$$

with the same assumptions on the controls $u_j \in L^1([0, +\infty))$ and where $\alpha \in L^1([0, +\infty))$ is given. Such models are relevant in some physical contexts (e.g. the Schrödinger equation with electric and magnetic fields combined with coupling with the environment in the spirit of [8]), but we did not write down the details in order to simplify the presentation.

2. BALL-MARSDEN-SLEMROD OBSTRUCTIONS FOR NONLINEAR EQUATIONS

2.1. Dyson expansion of the solutions. Let $T > 0$ and u be given in $L^1([0, T])$. Define by induction on $p \geq 0$,

$$(2.1) \quad \begin{cases} Y_{0,t}^u \psi_0 = 0 \\ Y_{p+1,t}^u \psi_0 = e^{tA} \psi_0 + \int_0^t e^{(t-s)A} [u(s) B Y_{p,s}^u \psi_0 + K(Y_{p,s}^u \psi_0)] ds \end{cases}$$

and $Z_{p,t}^u \psi_0 = Y_{p+1,t}^u \psi_0 - Y_{p,t}^u \psi_0$.

We aim to show that the series $(\sum_p Z_{p,t}^u \psi_0)$ converges. Therefore we need some quantitative bounds, which are stated in the next result.

Proposition 2.1. *For every j in \mathbf{N} , every $t > 0$ and every u in $L^1([0, +\infty))$,*

$$(2.2) \quad \|Z_{j,t}^u \psi\|_{\mathcal{X}} \leq \frac{e^{\omega t} M^{j+1} \left(k + \|B\|_{L(\mathcal{X}, \mathcal{X})} \int_0^t |u(s)| ds \right)^j}{j!} \|\psi\|_{\mathcal{X}}.$$

Proof. We proceed by induction on $j \geq 0$. The inequality (2.2) for $j = 0$ follows from Assumption 1.1(ii). Assume now that we have proved (2.2) for a given j . Then, since

$$\begin{aligned} \|Z_{j+1,t}^u \psi\|_{\mathcal{X}} &\leq \int_0^t M e^{\omega(t-s)} (k + |u(s)| \|B\|_{L(\mathcal{X}, \mathcal{X})}) \|Z_{j,s}^u \psi\|_{\mathcal{X}} ds \\ &\leq \frac{M^{j+2}}{j!} e^{\omega t} \int_0^t (k + |u(s)| \|B\|_{L(\mathcal{X}, \mathcal{X})}) \left(k + \|B\|_{L(\mathcal{X}, \mathcal{X})} \int_0^s |u(\tau)| d\tau \right)^j ds \\ &\leq \frac{M^{j+2}}{(j+1)!} e^{\omega t} \left(k + \|B\|_{L(\mathcal{X}, \mathcal{X})} \int_0^t |u(s)| ds \right)^{j+1} \|\psi\|_{\mathcal{X}}, \end{aligned}$$

which concludes the proof. \square

From Proposition 2.1, for every t in $[0, T]$ and every ψ in \mathcal{X} , the sum $\sum_j Z_{j,t}^u \psi$ converges in \mathcal{X} . We denote this sum by $Y_{\infty,t}^u \psi$:

$$Y_{\infty,t}^u \psi = \sum_{j=0}^{+\infty} Z_{j,t}^u \psi.$$

Proposition 2.2. *For every ψ in \mathcal{X} , every $T > 0$ and every u in $L^1([0, +\infty), \mathbf{R})$, the function $(t, \psi) \mapsto Y_{\infty,t}^u \psi$ is continuous from $\mathbf{R} \times \mathcal{X}$ to \mathcal{X} .*

Proof. This follows from the continuity of the functions $(t, \psi) \mapsto Z_{j,t}^u \psi$ for every $j \geq 0$ and from the convergence of $\sum_j Z_{j,t}^u \psi$ (locally uniform in t and ψ) from Proposition 2.1. \square

Proposition 2.3. *For every $T \in [0, +\infty)$, every u in $L^1([0, T], \mathbf{R})$ and every ψ_0 in \mathcal{X} , $t \mapsto Y_{\infty,t}^u \psi_0$ is the unique mild solution on $[0, T]$ of (1.1) taking value ψ_0 at 0.*

Proof. The mapping

$$\begin{aligned} F : C^0([0, T], \mathcal{X}) &\longrightarrow C^0([0, T], \mathcal{X}) \\ (t \mapsto \psi(t)) &\longmapsto (t \mapsto e^{tA} \psi_0 + \int_0^t e^{(t-s)A} [u(s)B\psi + K(\psi)] ds) \end{aligned}$$

is continuous for the norm $L^\infty([0, T], \mathcal{X})$. By (2.1), $t \mapsto Y_{\infty,t}^u \psi_0$ is a fixed point of F , hence a mild solution on $[0, T]$ of (1.1) taking value ψ_0 at 0.

Assume that $t \mapsto \psi_1(t)$ and $t \mapsto \psi_2(t)$ are two mild solutions on $[0, T]$ of (1.1) taking value ψ_0 at 0. Define $T^* = \sup_{t \in [0, T]} \{t \mid \psi_1(s) = \psi_2(s), \text{ for almost every } s \leq t\}$. We will prove by contradiction

that $T^* = T$, that is, $\psi_1 = \psi_2$ almost everywhere. Assume that $T^* < T$. We chose $t_1 \in (T^*, T]$ such that

$$Me^{(t_1 - T^*)\omega} (k(t_1 - T^*) + \|u\|_{L^1([T^*, t_1], \mathbf{R})} \|B\|_{L(\mathcal{X}, \mathcal{X})}) := C_0 < 1.$$

Then, for all $T^* \leq t_2 \leq t_1$

$$\begin{aligned}
 & \|\psi_2(t_2) - \psi_1(t_2)\|_{\mathcal{X}} \\
 &= \left\| \int_{T^*}^{t_2} u(s)e^{(t_2-s)A}B(\psi_2(s) - \psi_1(s))ds + \int_{T^*}^{t_2} e^{(t_2-s)A} \left(K(\psi_2(s)) - K(\psi_1(s)) \right) ds \right\|_{\mathcal{X}} \\
 &\leq \int_{T^*}^{t_2} |u(s)|Me^{(t_2-s)\omega}\|B\|_{L(\mathcal{X},\mathcal{X})}\|\psi_2(s) - \psi_1(s)\|_{\mathcal{X}}ds + \int_{T^*}^{t_2} Me^{(t_2-s)\omega}k\|\psi_2(s) - \psi_1(s)\|_{\mathcal{X}}ds \\
 &\leq \|\psi_2 - \psi_1\|_{L^\infty([T^*,t_1],\mathcal{X})} \int_{T^*}^{t_1} (k + |u(s)|\|B\|_{L(\mathcal{X},\mathcal{X})}) Me^{(t_1-s)\omega} ds \\
 &\leq C_0\|\psi_2 - \psi_1\|_{L^\infty([T^*,t_1],\mathcal{X})},
 \end{aligned}$$

therefore we deduce that

$$\|\psi_2 - \psi_1\|_{L^\infty([T^*,t_1],\mathcal{X})} \leq C_0\|\psi_2 - \psi_1\|_{L^\infty([T^*,t_1],\mathcal{X})},$$

which gives the desired contradiction. To achieve the proof, it remains to see that any mild solution is continuous (since two continuous functions coincide as soon as they are equal almost everywhere). Indeed, any mild solution solution of (1.1) is equal almost everywhere to Y_∞^u , which is continuous (Proposition 2.2), hence any mild solution of (1.1) is essentially bounded and then is continuous by its definition (1.2). \square

Definition 2.4. Let $T > 0$, u in $L^1([0, +\infty), \mathbf{R})$ and ψ_0 in \mathcal{X} . In the following, we denote with $t \mapsto \Phi^u(t)\psi_0$ the (nonlinear) mapping associating the mild solution of system (1.1) with initial condition ψ_0 associated with control u in $L^1([0, T])$.

We sum up the above results in the following

Proposition 2.5 (Dyson expansion of the solutions of (1.2)). *Let $t > 0$, u in $L^1([0, +\infty), \mathbf{R})$ and ψ_0 in \mathcal{X} . Then*

$$(2.3) \quad \Phi^u(t)\psi_0 = \sum_{j=0}^{\infty} Z_{j,t}^u(\psi_0).$$

2.2. A compactness result. Recall that $Y_{j,t}^u\psi_0$ is defined in (2.1) and $Z_{j,t}^u\psi_0 = Y_{j+1,t}^u\psi_0 - Y_{j,t}^u\psi_0$.

Proposition 2.6. *For every j in \mathbf{N} , $T \geq 0$ and $L \geq 0$, and ψ_0 in \mathcal{X} , the sets*

$$\mathcal{Z}_j^{T,L} = \{Z_{j,t}^u\psi_0 \mid 0 \leq t \leq T, \|u\|_{L^1(0,T)} \leq L\} \text{ and } \mathcal{Y}_j^{T,L} = \{Y_{j,t}^u\psi_0 \mid 0 \leq t \leq T, \|u\|_{L^1(0,T)} \leq L\}$$

are relatively compact in \mathcal{X} .

Proof. We adapt the proof of [6] (valid for $K = 0$) to the general case of a continuous function K .

Since a finite sum of relatively compact sets is still relatively compact, it is enough to prove the result for $\mathcal{Y}_j^{T,L}$. We do the proof by induction on $j \geq 0$.

For $j = 0$, the result is clear.

Assume that $\mathcal{Y}_j^{T,L}$ is relatively compact in \mathcal{X} for some $j \geq 0$. We aim to prove that $\mathcal{Y}_{j+1}^{T,L}$ is relatively compact in \mathcal{X} as well. For this, we chose $\varepsilon > 0$ and we try to exhibit an ε -net of $\mathcal{Y}_{j+1}^{T,L}$.

The mappings

$$G_1 : [0, T] \times \mathcal{X} \longrightarrow \mathcal{X} \quad \text{and} \quad G_2 : [0, T] \times \mathcal{X} \longrightarrow \mathcal{X}$$

$$(s, \psi) \longmapsto e^{(T-s)A}B\psi \quad \text{and} \quad (s, \psi) \longmapsto e^{(T-s)A}K(\psi)$$

being continuous, the sets $G_1([0, T] \times \mathcal{Y}_j^{T,L})$ and $G_2([0, T] \times \mathcal{Y}_j^{T,L})$ are relatively compact as well. Hence, there exists a finite family $(x_i)_{1 \leq i \leq N}$ such that, for $\ell = 1, 2$,

$$G_\ell([0, T] \times \mathcal{Y}_j^{T,L}) \subset \bigcup_{i=1}^N B_{\mathcal{X}} \left(x_i, \frac{\varepsilon}{4(L+T)} \right).$$

Let $(\varphi_i)_{1 \leq i \leq N}$ be a partition of unity associated with the above covering of $G_\ell([0, T] \times \mathcal{Y}_j^{T, L})$, $\ell = 1, 2$. That is, functions satisfying $0 \leq \varphi_i \leq 1$ and such that for every x in $G_\ell([0, T] \times \mathcal{Y}_j^{T, L})$,

$$\sum_{i=1}^N \varphi_i(x) = 1 \text{ and } \left\| x - \sum_{i=1}^N \varphi_i(x) x_i \right\|_{\mathcal{X}} < \frac{\varepsilon}{2(L+T)}.$$

Then, for every u in $L^1([0, T], \mathbf{R})$ such that $\|u\|_{L^1(0, T)} \leq L$,

$$\left\| \int_0^t u(s) e^{(t-s)A} (BY_{j,s}^u \psi_0) ds - \sum_{i=1}^N \int_0^t u(s) \varphi_i(e^{(t-s)A} (BY_{j,s}^u \psi_0)) x_i ds \right\|_{\mathcal{X}} \leq \frac{L\varepsilon}{2(L+T)},$$

and

$$\left\| \int_0^t e^{(t-s)A} K(Y_{j,s}^u \psi_0) ds - \sum_{i=1}^N \int_0^t \varphi_i(e^{(t-s)A} K(Y_{j,s}^u \psi_0)) x_i ds \right\|_{\mathcal{X}} \leq \frac{T\varepsilon}{2(L+T)}.$$

Now we use that the compact sets $\sum_{i=1}^N [0, L] x_i$ and $\sum_{i=1}^N [0, T] x_i$ admit a $\varepsilon/4$ -net $(y_i)_{1 \leq i \leq N_2}$, and thanks to the previous lines, we get $\mathcal{Y}_{j+1}^{T, L} \subset \bigcup_{i=1}^{N_2} B_{\mathcal{X}}(y_i, \varepsilon)$, which concludes the proof. \square

Remark 2.7. In the proof of Proposition 2.6, we only used the continuity of K . Actually, in this paper, we assume that K is Lipschitz continuous in order to ensure the global existence of a flow of (1.2) and the Dyson expansion (2.3). In Section 3.2, we will show that our approach applies to more general nonlinearities, which are only locally (not globally) Lipschitz continuous.

2.3. Proof of the nonlinear Ball-Marsden-Slemrod obstructions. We are now able to complete the proof of Theorem 1.2.

For $T > 0$ and $L > 0$ define

$$\mathcal{V}^{T, L} = \{ \Phi^u(t) \psi_0 \mid u \in L^1([0, T]), \|u\|_{L^1([0, T])} \leq L, 0 \leq t \leq T \},$$

and notice that

$$\bigcup_{t \geq 0} \bigcup_{u \in L^1} \{ \Phi^u(t) \psi_0 \} = \bigcup_{T \in \mathbf{N}} \bigcup_{L \in \mathbf{N}} \mathcal{V}^{T, L},$$

thus it is enough to prove that, for every $T > 0$ and every $L > 0$, the set $\mathcal{V}^{T, L}$ is relatively compact.

Let $\delta > 0$ be given. We aim to find a δ -net of $\mathcal{V}^{T, L}$.

From Propositions 2.1 and 2.5, $\left\| \sum_{j=N}^{\infty} Z_{j, T}^u(\psi_0) \right\|_{\mathcal{X}}$ tends to zero as N tends to infinity uniformly

with respect to u in $B_{L^1([0, T], \mathbf{R})}(0, L)$, there exists N_1 large enough such that, for every u in $B_{L^1([0, T], \mathbf{R})}(0, L)$,

$$\left\| \sum_{j=N_1}^{\infty} Z_{j, T}^u(\psi_0) \right\|_{\mathcal{X}} < \frac{\delta}{2}.$$

The set $\mathcal{Y}_{N_1}^{T, L}$ is relatively compact (Proposition 2.6) hence admits a $\delta/2$ -net.

Thus

$$\mathcal{V}^{T, L} \subset \left\{ x \in \mathcal{X} \mid d_{\mathcal{X}}\left(x, \mathcal{Y}_{N_1}^{T, L}\right) \leq \frac{\delta}{2} \right\}$$

admits a δ -net, which finishes the proof.

3. APPLICATIONS

3.1. The Sine-Gordon equation. We consider the Sine-Gordon equation which reads

$$(3.1) \quad \begin{cases} \partial_t^2 \psi - \partial_x^2 \psi = u(t)B(x)\psi - \sin \psi, & (t, x) \in \mathbf{R} \times \mathbf{R}, \\ \psi(0, \cdot) = \psi_0 \in H^1(\mathbf{R}), \\ \partial_t \psi(0, \cdot) = \psi_1 \in L^2(\mathbf{R}), \end{cases}$$

where B is a given function, and with a control $u \in L^1_{loc}(\mathbf{R})$. In the case $B \equiv 0$, this equation appears in relativistic field theory or in the study of mechanical transmission lines. We rewrite this equation as a first order (in time) system, so that it fits in the frame of our study. Equation (3.1) is equivalent to

$$\begin{cases} \partial_t \begin{pmatrix} \psi \\ \varphi \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ \partial_x^2 & 0 \end{pmatrix} \begin{pmatrix} \psi \\ \varphi \end{pmatrix} + u(t)B(x) \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \psi \\ \varphi \end{pmatrix} + \begin{pmatrix} 0 \\ -\sin \psi \end{pmatrix}, & (t, x) \in \mathbf{R} \times \mathbf{R}, \\ (\psi(0, \cdot), \varphi(0, \cdot)) = (\psi_0, \psi_1) \in H^1(\mathbf{R}) \times L^2(\mathbf{R}). \end{cases}$$

Then Theorem 1.2 directly applies with $\mathcal{X} = H^1(\mathbf{R}) \times L^2(\mathbf{R})$, $A = \begin{pmatrix} 0 & 1 \\ \partial_x^2 & 0 \end{pmatrix}$, $D(A) = H^2(\mathbf{R}) \times H^1(\mathbf{R})$, $B \in L^\infty(\mathbf{R})$ and $K(\psi, \varphi) = (0; -\sin(\psi))$.

3.2. The wave equation in dimension 3. Actually, the result of Theorem 1.2 also applies to nonlinear equations, with local Lipschitz nonlinear terms. We develop here the example of the wave and Klein-Gordon equations. Denote by \mathcal{M} a boundaryless compact manifold of dimension 3, or $\mathcal{M} = \mathbf{R}^3$. We consider the defocusing cubic wave equation

$$(3.2) \quad \begin{cases} \partial_t^2 \psi - \Delta \psi + m\psi = u(t)B(x)\partial_t \psi - \psi^3, & (t, x) \in \mathbf{R} \times \mathcal{M}, \\ \psi(0, \cdot) = \psi_0 \in H^1(\mathcal{M}), \\ \partial_t \psi(0, \cdot) = \psi_1 \in L^2(\mathcal{M}), \end{cases}$$

with $m \geq 0$ and $B \in L^\infty(\mathcal{M})$. Positive exact controllability results for such non-linear dynamics in the case $\mathcal{M} = (0, 1)$ were obtained by Beauchard and Laurent [5, Theorem 5].

The control function is $u \in L^1_{loc}(\mathbf{R})$. The mild solution reads

$$\psi(t) = S_0(t)\psi_0 + S_1(t)\psi_1 + \int_0^t S_1(t-s)(u(s)B(x)\partial_s \psi(s) - \psi^3(s))ds$$

where

$$(3.3) \quad S_0(t) = \cos(t\sqrt{-\Delta + m}) \quad \text{and} \quad S_1(t) = \frac{\sin(t\sqrt{-\Delta + m})}{\sqrt{-\Delta + m}}.$$

3.2.1. The obstruction result to controllability to the wave equation. We state the main result of this section, which is an analogue result to Theorem 1.2 concerning equation (3.2).

Theorem 3.1. *For all $(\psi_0, \psi_1) \in H^1(\mathcal{M}) \times L^2(\mathcal{M})$ and $u \in L^1(\mathbf{R})$, there exists a unique solution to (3.2)*

$$\psi \in \mathcal{C}^0(\mathbf{R}; H^1(\mathcal{M})) \cap \mathcal{C}^1(\mathbf{R}; L^2(\mathcal{M})).$$

This enables us to define a global flow

$$\Phi = (\Phi_1, \Phi_2) : \begin{array}{ccc} H^1(\mathcal{M}) \times L^2(\mathcal{M}) \times L^1(\mathbf{R}) & \longrightarrow & \mathcal{C}^0(\mathbf{R}; H^1(\mathcal{M})) \times \mathcal{C}^0(\mathbf{R}; L^2(\mathcal{M})) \\ (\psi_0, \psi_1, u) & \longmapsto & (\psi, \psi_t) \end{array}.$$

Moreover for every $(\psi_0, \psi_1) \in H^1(\mathcal{M}) \times L^2(\mathcal{M})$, the attainable set

$$\bigcup_{t \in \mathbf{R}} \bigcup_{u \in L^1} \{\Phi^u(t)(\psi_0, \psi_1)\}$$

is contained in a countable union of compact subsets of $H^1(\mathcal{M}) \times L^2(\mathcal{M})$.

We decided to illustrate our method on the equation (3.2), but our approach can be applied to other wave-type equations, for example with

$$\partial_t^2 \psi - \Delta \psi + m\psi = u(t)B(x)\psi - \psi^3,$$

with a given potential $B \in L^3(\mathcal{M})$. We do not write the details.

3.2.2. Local and global existence results. Since the equation (3.2) is reversible, in the sequel, we restrict to non-negative times. Let $T > 0$ and $u \in L^1([0, T])$ be given. Let also $t_0 \geq 0$. We define by induction on $p \geq 0$,

$$\begin{cases} \tilde{Y}_{0,t,t_0}^u = 0 \\ \tilde{Y}_{p+1,t,t_0}^u(\psi_0, \psi_1) = S_0(t)\psi(t_0) + S_1(t)\partial_t\psi(t_0) + \int_0^t S_1(t-s) \left[u(s+t_0)B(x)\partial_s\tilde{Y}_{p,s,t_0}^u - (\tilde{Y}_{p,s,t_0}^u)^3 \right] ds \end{cases}$$

with $\tilde{Y}_{p,s,t_0}^u = \tilde{Y}_{p,s,t_0}^u(\psi_0, \psi_1)$, and where S_0 and S_1 are defined in (3.3).

We now state a global existence result, which is an application of the Picard fixed point theorem.

Proposition 3.2. (i) For all $(\psi_0, \psi_1) \in H^1(\mathcal{M}) \times L^2(\mathcal{M})$ there exists a unique solution to (3.2)

$$\psi \in \mathcal{C}^0(\mathbf{R}; H^1(\mathcal{M})) \cap \mathcal{C}^1(\mathbf{R}; L^2(\mathcal{M})).$$

(ii) Moreover, for all $T > 0$, for all $L > 0$ and u such that $\int_0^T |u(s)|ds \leq L$,

$$\sup_{0 \leq t \leq T} \|(\psi, \partial_t \psi)(t)\|_{H^1(\mathcal{M}) \times L^2(\mathcal{M})} \leq C(\|\psi_0\|_{H^1}, \|\psi_1\|_{L^2}, L, T),$$

where C is a continuous function.

(iii) Furthermore, for all $T > 0$, and $L > 0$, there exists $k \geq 1$, $0 < c_0 < 1$ and a continuous function $\tau = \tau(\|\psi_0\|_{H^1}, \|\psi_1\|_{L^2}, L, T) > 0$ such that for all $0 \leq t_0 \leq T$, $p \geq 0$ and u such that $\int_0^T |u(s)|ds \leq L$,

$$(3.4) \quad \sup_{t \in [0, \tau]} \|(\psi(t+t_0) - \tilde{Y}_{kp,t,t_0}^u, \partial_t \psi(t+t_0) - \partial_t \tilde{Y}_{kp,t,t_0}^u)\|_{H^1(\mathcal{M}) \times L^2(\mathcal{M})} \leq Cc_0^p.$$

In the previous result, it is crucial that we obtain a time $\tau = \tau(\|\psi_0\|_{H^1}, \|\psi_1\|_{L^2}, L, T)$ which only depends on the norms of ψ_0 , ψ_1 and u (and not ψ_0 , ψ_1 or u themselves). This fact will be used in the compactness argument (see Section 3.2.3).

Proof. A first local existence result: Let $t_0 \geq 0$. To begin with, we prove a local in time existence result for the problem

$$(3.5) \quad \begin{cases} \partial_t^2 \tilde{\psi} - \Delta \tilde{\psi} + m\tilde{\psi} = u(t)B(x)\partial_t \tilde{\psi} - \tilde{\psi}^3, & (t, x) \in \mathbf{R} \times \mathcal{M}, \\ \tilde{\psi}(t_0, \cdot) = \tilde{\psi}_0 \in H^1(\mathcal{M}), \\ \partial_t \tilde{\psi}(t_0, \cdot) = \tilde{\psi}_1 \in L^2(\mathcal{M}). \end{cases}$$

We consider the map

$$F(\psi)(t) = S_0(t)\tilde{\psi}_0 + S_1(t)\tilde{\psi}_1 + \int_0^t S_1(t-s) \left[u(s+t_0)B(x)\partial_s \psi(s) - (\psi(s))^3 \right] ds,$$

and we will show that, for $t > 0$ small enough, it is a contraction in some Banach space. Then by the Picard theorem there will exist a unique fixed point ψ and $\tilde{\psi}(t) = \psi(t-t_0)$ will be the unique solution to (3.5).

We define the norm $\|\psi\|_T = \|\psi\|_{L_T^\infty H^1} + \|\partial_t \psi\|_{L_T^\infty L^2}$ and the space

$$X_{T,R} = \{\|\psi\|_T \leq R\},$$

with $R > 0$ and $T > 0$ to be fixed.

By the Sobolev embedding $H^1(\mathcal{M}) \subset L^6(\mathcal{M})$ (see Proposition (A.1) with $p = 2$ and $n = 3$), there exists $c = c(m, T) > 0$ such that

$$\begin{aligned} \|F(\psi)\|_T &\leq 2(\|\tilde{\psi}_0\|_{H^1} + \|\tilde{\psi}_1\|_{L^2}) + c \int_0^T (\|u(s+t_0)B\partial_s \psi\|_{L^2} + \|\psi(s)\|_{L^6}^3) ds \\ (3.6) \quad &\leq 2(\|\tilde{\psi}_0\|_{H^1} + \|\tilde{\psi}_1\|_{L^2}) + c \left(\int_0^T |u(s+t_0)| ds \right) \|B\|_{L^\infty} \|\partial_t \psi\|_{L_T^\infty L^2} + cT \|\psi\|_{L_T^\infty H^1}^3. \end{aligned}$$

Let us set $R = 4(\|\tilde{\psi}_0\|_{H^1} + \|\tilde{\psi}_1\|_{L^2})$. Then we fix $T_1 = c_1 R^{-2}$ with $c_1 > 0$ small enough such that $cT_1 R^2 \leq 1/4$ and we fix $T_2 > 0$ such that $c \int_0^{T_2} |u(s+t_0)| ds \leq \|B\|_{L^\infty}^{-1}/4$. Therefore, for $T = \min(T_1, T_2)$, F maps $X_{T,R}$ into itself. With similar estimates we can show that F is a contraction in $X_{T,R}$, namely

$$\|F(\psi_1) - F(\psi_2)\|_T \leq [cTR^2 + c \left(\int_0^T |u(s+t_0)| ds \right) \|B\|_{L^\infty}] \|\psi_1 - \psi_2\|_T.$$

As a consequence, there exists a unique local in time solution to (3.5), with time of existence τ depending on the norms of $\tilde{\psi}_0$, $\tilde{\psi}_1$ and u .

Energy bound: We define

$$E(\psi)(t) = \frac{1}{2} \int_{\mathcal{M}} ((\partial_t \psi)^2 + |\nabla \psi|^2 + m\psi^2) + \frac{1}{4} \int_{\mathcal{M}} \psi^4.$$

By derivation in time, we get

$$\begin{aligned} \frac{d}{dt} E(\psi)(t) &= \int_{\mathcal{M}} \partial_t \psi (\partial_t^2 \psi - \Delta \psi + m\psi + \psi^3) dx \\ &= u(t) \int_{\mathcal{M}} B (\partial_t \psi)^2 dx. \end{aligned}$$

Next, since $B \in L^\infty(\mathcal{M})$, we get

$$\begin{aligned} \frac{d}{dt} E(\psi)(t) &\leq |u(t)| \|B\|_{L^\infty} \|\partial_t \psi\|_{L^2}^2 \\ &\leq C |u(t)| E(\psi)(t) \end{aligned}$$

which implies

$$(3.7) \quad E(\psi)(t) \leq E(\psi)(0) e^{C \int_0^t |u(s)| ds}.$$

In the particular case $m = 0$, the energy E does not control the term $\int_{\mathcal{M}} \psi^2$, and we bound this latter term as follows. We set $M(\psi)(t) = \left(\int_{\mathcal{M}} \psi^2 \right)^{1/2}$. Thus

$$\frac{d}{dt} M(\psi)(t) \leq \|\partial_t \psi\|_{L^2} \leq 2E^{1/2}(\psi)(t),$$

and by integration in time together with (3.7) we obtain

$$(3.8) \quad E(\psi)(t) + \int_{\mathcal{M}} \psi^2 \leq C_0(t, \int_0^t |u(s)| ds, \|\psi_0\|_{H^1}, \|\psi_1\|_{L^2}).$$

Proof of (i) and (ii): Assume that one can solve (3.5) on $[0, T^*]$, starting from $t_0 = 0$. By (3.8), there is a time $T_1^* > 0$ such that $cT_1^*(R^*)^2 \leq 1/4$ with $R^* = 4c(\|\psi\|_{L_{T^*}^\infty H^1} + \|\partial_t \psi\|_{L_{T^*}^\infty L^2})$. Then we fix $T_2^* > 0$ with

$$c \left(\int_{T^* - \frac{T_2^*}{2}}^{T^* + \frac{T_2^*}{2}} |u(s)| ds \right) \|B\|_{L^\infty} \leq 1/4.$$

As a consequence, with the arguments of the local theory step, we are able to solve the equation (3.5), with an initial condition at $t_0 = T^* - \min(T_1^*, T_2^*)/2$, on the time interval $[T^* - \min(T_1^*, T_2^*)/2, T^* + \min(T_1^*, T_2^*)/2]$. This shows that the maximal solution is global in time.

Proof of (iii): To prove this last statement, we will find a time of existence which does not depend on $t_0 \in [0, T]$ and which only depends on u through the quantity $\int_0^T |u(s)| ds$. Assume that $\int_0^T |u(s)| ds \leq L$.

For $k \geq 0$, we denote by $F^k = F \circ F \circ \dots \circ F$ the k th iterate of F . From (3.9) and (3.10) (see Lemma 3.3 below) we infer the bounds (with $L = L(T)$)

$$\|F^k(\psi)\|_{T_1} \leq C_k(L, \|\psi\|_0) + \frac{(CL)^k}{k!} \|\psi\|_{T_1} + T_1 P_k(T_1, L, \|\psi\|_{T_1})$$

and

$$\|F^k(\psi) - F^k(\varphi)\|_{T_1} \leq \left[\frac{(CL)^k}{k!} + T_1 Q_k(T_1, L, \|\psi\|_{T_1}, \|\varphi\|_{T_1}) \right] \|\psi - \varphi\|_{T_1}.$$

Set $k \geq 0$ such that $\frac{(CL)^k}{k!} \leq 1/2$. Let $R_1 = \max(2C_k, C_0)$, where $C_k = C_k(L, \|\psi\|_0)$ is given in (3.9) and $C_0 = C_0(T, L, \|\psi\|_0)$ is given in (3.8). Set

$$X_{T_1, R_1} = \{\|\varphi\|_{T_1} \leq R_1\}.$$

Then from the two previous estimates we infer that $F^k : X_{T_1, R_1} \rightarrow X_{T_1, R_1}$ is a contraction, provided that $T_1 = T_1(L, R_1)$ is small enough. As a consequence, there exists a unique solution in X_{T_1, R_1} to the equation $\varphi = F^k(\varphi)$. However $F : X_{T_1, R_1} \not\rightarrow X_{T_1, R_1}$, and we can not conclude directly that $\varphi = F(\varphi)$, in other words that φ satisfies (3.2). By the global well-posedness result, there exists a unique $\psi = F(\psi)$ for $t \in [0, T_1]$. Let us prove that $\varphi \equiv \psi$ on $[0, T_1]$. Observe that we have $\psi = F^k(\psi)$. To conclude the proof, by uniqueness of the fixed point of F^k in X_{T_1, R_1} , it is enough to check that $\psi \in X_{T_1, R_1}$. By (3.8), $\|\psi\|_{T_1} \leq C_0(T, L, \|\psi\|_0) \leq R_1$, hence the result.

Finally the bound (3.4) directly follows from the Picard iteration procedure, since

$$\tilde{Y}_{k(p+1), t, t_0}^u(\psi_0, \psi_1) = F^k(\tilde{Y}_{kp, t, t_0}^u(\psi_0, \psi_1)).$$

□

Recall that $\|\psi\|_T = \|\psi\|_{L_T^\infty H^1} + \|\partial_t \psi\|_{L_T^\infty L^2}$.

Lemma 3.3. *Let $0 < T_1 \leq T$. For $0 \leq t \leq T$, set $L(t) = \int_0^t |u(s)| ds$ and $L = L(T)$. Then there exists a constant $C > 0$ such that for all $k \geq 0$ and $0 \leq t + t_0 \leq T$, there exist polynomials C_k , P_k and Q_k such that*

$$(3.9) \quad \|F^k(\psi)\|_t \leq C_k(L, \|\psi\|_0) + \frac{(CL(t+t_0))^k}{k!} \|\psi\|_{T_1} + T_1 P_k(T_1, L, \|\psi\|_{T_1})$$

and

$$(3.10) \quad \|F^k(\psi) - F^k(\varphi)\|_t \leq \left[\frac{(CL(t+t_0))^k}{k!} + T_1 Q_k(T_1, L, \|\psi\|_{T_1}, \|\varphi\|_{T_1}) \right] \|\psi - \varphi\|_{T_1}.$$

Proof. Let us prove (3.9) by induction. For $k = 0$ the result holds true. Let $k \geq 0$ such that we have (3.9). As in (3.6) we get

$$(3.11) \quad \|F^{k+1}(\psi)\|_t \leq 2(\|\tilde{\psi}_0\|_{H^1} + \|\tilde{\psi}_1\|_{L^2}) + c\|B\|_{L^\infty} \left(\int_0^t |u(s+t_0)| \|F^k(\psi)\|_s ds \right) + cT_1 \|F^k(\psi)\|_{T_1}^3,$$

where $c > 0$ is an universal constant. To begin with, by (3.8),

$$\|\tilde{\psi}_0\|_{H^1} + \|\tilde{\psi}_1\|_{L^2} \leq D(L, \|\psi\|_0).$$

Next, by (3.9)

$$\begin{aligned} \int_0^t |u(s+t_0)| \|F^k(\psi)\|_s ds &\leq \\ &\leq C_k(L, \|\psi\|_0)L + \|\psi\|_{T_1} \int_0^t |u(s+t_0)| \frac{(CL(s+t_0))^k}{k!} ds + T_1 LP_k(T_1, L, \|\psi\|_{T_1}) \\ &\leq C_k(L, \|\psi\|_0)L + C^k \frac{(L(t+t_0))^{k+1}}{(k+1)!} \|\psi\|_{T_1} + T_1 LP_k(T_1, L, \|\psi\|_{T_1}). \end{aligned}$$

The term $\|F^k(\psi)\|_{T_1}^3$ is directly controlled by (3.9). Now if we make the choice $C = c\|B\|_{L^\infty}$, thanks to (3.11) we get (3.9) at rank $k+1$.

The proof of (3.10) is similar and left here. \square

As in the abstract result, a major ingredient in the proof is a Dyson expansion of the form (2.3). However, since the nonlinearity is stronger than in our abstract result, the expansion only holds true for finite times. Set

$$\tilde{Z}_{p,t,t_0}^u(\psi_0, \psi_1) := \tilde{Y}_{k(p+1),t,t_0}^u(\psi_0, \psi_1) - \tilde{Y}_{kp,t,t_0}^u(\psi_0, \psi_1),$$

where $k \geq 0$ is given by the proof of Proposition 3.2.

Proposition 3.4. *Let $T > 0$ and $u \in L^1([0, T], \mathbf{R})$ such that $\int_0^T |u(s)| ds \leq L$. Consider $\tau = \tau(\|\psi_0\|_{H^1}, \|\psi_1\|_{L^2}, L, T) > 0$ given by Proposition 3.2 (iii). Then for all $t \in [0, \tau]$*

$$\Phi^u(t+t_0)(\psi_0, \psi_1) = \left(\sum_{j=0}^{\infty} Z_{j,t,t_0}^u(\psi_0, \psi_1), \sum_{j=0}^{\infty} \partial_t Z_{j,t,t_0}^u(\psi_0, \psi_1) \right).$$

Proof. This result is a direct consequence of (3.4). \square

3.2.3. Proof of the compactness result. We now proceed to the end of the proof of Theorem 3.1. For every $(\tilde{\psi}_0, \tilde{\psi}_1)$ in $H^1(\mathcal{M}) \times L^2(\mathcal{M})$, we define the attainable set from $(\tilde{\psi}_0, \tilde{\psi}_1)$ in time less than T with control of L^1 norm less than L :

$$\mathcal{V}^{T,L}(\tilde{\psi}_0, \tilde{\psi}_1) = \{ \Phi^u(t)(\tilde{\psi}_0, \tilde{\psi}_1) \mid u \in L^1([0, T], \mathbf{R}), \|u\|_{L^1([0, T], \mathbf{R})} \leq L, 0 \leq t \leq T \}.$$

Proposition 3.5. *For every $(\tilde{\psi}_0, \tilde{\psi}_1)$ in $H^1(\mathcal{M}) \times L^2(\mathcal{M})$, for every $L > 0$, for every $T \leq \tau$ (defined in Proposition 3.2 (iii)), $\mathcal{V}^{T,L}(\tilde{\psi}_0, \tilde{\psi}_1)$ is contained in a compact set of $H^1(\mathcal{M}) \times L^2(\mathcal{M})$.*

Proof. The proof of Proposition 3.5 goes exactly as the proof of Theorem 1.2, using the Dyson expansion (Proposition 3.4) and the fact that the mappings

$$\begin{aligned} G_1 : [0, T] \times L^2(\mathcal{M}) &\longrightarrow H^1(\mathcal{M}) \\ (s, \varphi) &\longmapsto \frac{\sin((T-s)\sqrt{-\Delta+m})}{\sqrt{-\Delta+m}} B\varphi \end{aligned}$$

and

$$\begin{aligned} G_2 : [0, T] \times H^1(\mathcal{M}) &\longrightarrow H^1(\mathcal{M}) \\ (s, \psi) &\longmapsto \frac{\sin((T-s)\sqrt{-\Delta+m})}{\sqrt{-\Delta+m}} \psi^3 \end{aligned}$$

are continuous. \square

Proposition 3.6. *For every (ψ_0, ψ_1) in $H^1(\mathcal{M}) \times L^2(\mathcal{M})$, for every $L, T > 0$, there exists $\tau^* > 0$ such that for every $(\tilde{\psi}_0, \tilde{\psi}_1)$ in the topological closure of $\mathcal{V}^{T,L}(\psi_0, \psi_1)$, the time τ given in Proposition 3.2 (iii) satisfies $\tau > \tau^*$.*

Proof. The time τ appearing in Proposition 3.2 (iii) is the time τ for which the Dyson expansion (Proposition 3.4) is valid. As proved in Proposition 3.2, this time depends on the norm of ψ_0 and ψ_1 (not on ψ_0 and ψ_1 themselves). Conclusion follows from the energy bound (3.8). \square

Proposition 3.7. *For every $T, L > 0$, for every (ψ_0, ψ_1) in $H^1(\mathcal{M}) \times L^2(\mathcal{M})$, the set $\mathcal{V}^{T,L}(\psi_0, \psi_1)$ is relatively compact in $H^1(\mathcal{M}) \times L^2(\mathcal{M})$.*

Proof. In the following, for every real function $u : \mathbf{R} \rightarrow \mathbf{R}$ and every interval $I = [a, b]$ of \mathbf{R} , we define the function $R_I u$ by $R_I u(x) = u(a+x)$ for x in $[0, b-a]$ and $R_I u(x) = 0$ else.

Let τ^* be as defined in Proposition 3.6. We proceed by induction on p in \mathbf{N} to prove Proposition 3.7 for $T \leq p\tau^*$.

For $p = 1$, this is just Proposition 3.5.

Assume the result is proven for some $p \geq 1$. Let T be in $(p\tau^*, (p+1)\tau^*]$ and $(A_n)_{n \in \mathbf{N}} = (\Phi^{u_n}(t_n)(\psi_0, \psi_1))_{n \in \mathbf{N}}$ be a sequence in $\mathcal{V}^{T,L}(\psi_0, \psi_1)$. We aim to find a convergent subsequence of $(A_n)_{n \in \mathbf{N}}$, which will prove the relative compactness of $\mathcal{V}^{T,L}(\psi_0, \psi_1)$.

By the induction hypothesis, the set $\mathcal{V}^{p\tau^*, L}(\psi_0, \psi_1)$ is relatively compact, hence up to extraction, one may assume that the sequence $(\Phi^{u_n}(p\tau^*)(\psi_0, \psi_1))_{n \in \mathbf{N}}$ converges to some limit $A_{p\tau^*}^\infty$. By Proposition 3.6, $\tau(A_{p\tau^*}^\infty, L) > \tau^*$. Hence, by Proposition 3.5, the set $\mathcal{V}^{\tau^*, L}(A_{p\tau^*}^\infty)$ is relatively compact. Hence, up to extraction, one may assume that the sequence $(\Phi^{R_{[p\tau^*, t_n]} u_n}(t_n - \tau^*)(A_{p\tau^*}^\infty))_{n \in \mathbf{N}}$ converges to some limit $A_{T_\infty}^\infty$. By continuity of $\Phi^u(t)(\cdot, \cdot)$, the sequence $(\Phi^{u_n}(t_n)(\psi_0, \psi_1))_{n \in \mathbf{N}}$ also converges to $A_{T_\infty}^\infty$, and that concludes the proof of Proposition 3.7. \square

Proof of Theorem 3.1: It remains to prove the last statement of Theorem 3.1. This follows from Proposition 3.7 by noticing that $\bigcup_{t \in \mathbf{R}} \bigcup_{u \in L^1} \{\Phi^u(t)(\psi_0, \psi_1)\} \subset \bigcup_{\ell \in \mathbf{N}} \bigcup_{n \in \mathbf{N}} \mathcal{V}^{n, \ell}(\psi_0, \psi_1)$. \square

APPENDIX A. SOBOLEV SPACES

The aim of this Appendix is to recall the classical Sobolev embedding theorem, which is instrumental in the proof of Proposition 3.2. For more details, the reader may refer to the classical reference [1, Theorem 5.4, statements (3) and (4)].

A.1. Definition. Let \mathcal{M} be an open subset of \mathbf{R}^n or a Riemannian compact manifold of dimension n . For every k in \mathbf{N} and every p in $[1, +\infty]$, the Sobolev space $W^{k,p}(\mathcal{M})$ is defined as the set of functions from \mathcal{M} to \mathbf{R} whose partial derivatives up to order k belongs to $L^p(\mathcal{M})$, that is:

$$W^{k,p}(\mathcal{M}) = \{\psi \in L^p(\mathcal{M}) \mid D^\alpha \psi \in L^p(\mathcal{M}), \quad \forall |\alpha| \leq k\}.$$

When endowed with the norm $\|\psi\|_{W^{k,p}(\mathcal{M})} = \sum_{|\alpha| \leq p} \|D^\alpha \psi\|_{L^p}$, $W^{k,p}(\mathcal{M})$ turns into a Banach space.

In the case where $p = 2$, $W^{k,2}(\mathcal{M})$ turns into a Hilbert space and is usually denoted by $H^2(\mathcal{M})$.

A.2. Sobolev embedding theorem. For every integers k, ℓ and every real numbers p, q such that $k > \ell$, $(k - \ell)p < n$, and $1 \leq p < q \leq np/(n - (k - \ell)p) \leq +\infty$, then

$$W^{k,p}(\mathcal{M}) \subset W^{\ell,q}(\mathcal{M})$$

and the embedding is continuous. In particular, there exists $C_{Sob}(p, q, k, n) > 0$ such that

$$\|\psi\|_{W^{\ell,q}(\mathcal{M})} \leq C_{Sob}(p, q, k, n) \|\psi\|_{W^{k,p}(\mathcal{M})}.$$

In particular, if $k = 1$ and $\ell = 0$, one gets

Proposition A.1 (Sobolev embedding). *If $1/p^* = 1/p - 1/n$ then $W^{1,p}(\mathcal{M}) \subset L^{p^*}(\mathcal{M})$.*

ACKNOWLEDGMENTS

T. Chambrion is supported by the grant ‘‘QUACO’’ ANR-17-CE40-0007-01. L. Thomann is supported by the grants ‘‘BEKAM’’ ANR-15-CE40-0001 and ‘‘ISDEEC’’ ANR-16-CE40-0013.

REFERENCES

- [1] R. Adams. Sobolev Spaces. *Pure and Applied Mathematics* 65 (1975) Academic Press.
- [2] J. Ball, J. Marsden and M. Slemrod. Controllability for distributed bilinear systems. *SIAM J. Control Optim.* 20 (1982), no. 4, 575–597.
- [3] K. Beauchard. Local controllability of a 1D Schrödinger equation. *J. Math. Pures et Appl.*, 84 (2005), 851–956.
- [4] K. Beauchard. Local controllability and non controllability of a 1D wave equation. *Journal of Differential Equations*, 250 (2011) 2064–2098.
- [5] K. Beauchard and C. Laurent. Local controllability of 1D linear and nonlinear Schrödinger equations with bilinear control. *J. Math. Pures Appl.* (9) 94 (2010), no. 5, 520–554.
- [6] N. Boussaïd, M. Caponigro and T. Chambrion. Regular propagators of bilinear quantum systems. *Preprint : hal-01016299*.
- [7] T. Chambrion and L. Thomann. On the bilinear control of the Gross-Pitaevskii equation. *Preprint*.
- [8] J. Hansom, C. Schulte, Carsten, C. Le Gall, C. Matthiesen, C. Edmund, M. Hugues, Maxime, J. Taylor and A. Mete. Environment-assisted quantum control of a solid-state spin via coherent dark states. *Nature Physics*. 10.1038/nphys3077, 2014.
- [9] A. Khapalov. Controllability of partial differential equations governed by multiplicative controls. *Lecture Notes in Mathematics*, 1995. Springer-Verlag, Berlin, 2010. xvi+284 pp.
- [10] M. Reed and B. Simon. *Methods of modern mathematical physics. II. Fourier analysis, self-adjointness*. Academic Press [Harcourt Brace Jovanovich, Publishers], New York-London, 1975. xv+361 pp.
- [11] G. Turinici. On the controllability of bilinear quantum systems. *Mathematical models and methods for ab initio quantum chemistry*, 75–92, *Lecture Notes in Chem.*, 74, Springer, Berlin, 2000.

Thomas Chambrion, UNIVERSITÉ DE LORRAINE, CNRS, INRIA, IECL, F-54000 NANCY, FRANCE
E-mail address: `Thomas.Chambrion@univ-lorraine.fr`

Laurent Thomann, UNIVERSITÉ DE LORRAINE, CNRS, IECL, F-54000 NANCY, FRANCE
E-mail address: `Laurent.Thomann@univ-lorraine.fr`