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Global exact controllability of bilinear quantum systems on compact graphs and energetic controllability

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Abstract

The aim of this work is to study the controllability of the bilinear Schrödinger equation on compact graphs. In particular, we consider the equation (BSE) $i\partial_t\psi = -\Delta\psi + u(t)B\psi$ in the Hilbert space $L^2(\mathcal{G}, \mathbb{C})$, with \mathcal{G} being a compact graph. The Laplacian $-\Delta$ is equipped with self-adjoint boundary conditions, B is a bounded symmetric operator and $u \in L^2((0, T), \mathbb{R})$ with $T > 0$. We provide a new technique leading to the global exact controllability of the (BSE) in $D(|\Delta|^{s/2})$ with $s \geq 3$. Afterwards, we introduce the “energetic controllability”, a weaker notion of controllability useful when the global exact controllability fails. In conclusion, we develop some applications of the main results involving for instance star graphs.

1 Introduction

In quantum mechanics, any state of a closed system is mathematically represented by a wave function ψ in the unit sphere of a Hilbert space \mathcal{H} . We consider the evolution of a particle confined in a network shaped as compact graph \mathcal{G} (see Figure 1) and subjected to a controlling external field.

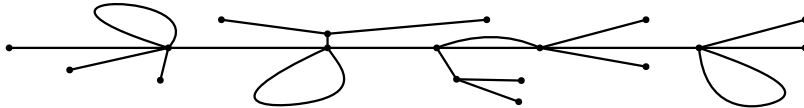


Figure 1: A compact graph is a one-dimensional domain composed by finite vertices (points) connected by edges (segments) of finite lengths.

A standard choice for such setting is to represent the action of the field by an operator B and its intensity by a real function u ; we also impose $\mathcal{H} := L^2(\mathcal{G}, \mathbb{C})$. The evolution of ψ is modeled by the bilinear Schrödinger equation in \mathcal{H}

$$(BSE) \quad \begin{cases} i\partial_t\psi(t) = A\psi(t) + u(t)B\psi(t), & t \in (0, T), \\ \psi(0) = \psi_0, & T > 0. \end{cases}$$

The Laplacian $A = -\Delta$ is equipped with self-adjoint boundary conditions, B is a bounded symmetric operator and $u \in L^2((0, T), \mathbb{R})$. In this context, the well-posedness of the (BSE) can be deduced by the seminal work on bilinear systems [BMS82] by Ball, Mardsen and Slemrod where it is also proved the existence of the unitary propagator Γ_t^u generated by $A + u(t)B$.

The aim of this work is to study the controllability of the (BSE) according to the structure of the graph \mathcal{G} , the choice of control field B and the boundary conditions defining the domain of A .

The controllability of finite-dimensional quantum systems modeled by the (BSE) , when A and B are $N \times N$ Hermitian matrices, is well-known for being linked to the rank of the Lie algebra spanned by A and B (see [Alt02, Cor07]); nevertheless the Lie algebra rank condition can not be used for infinite-dimensional quantum systems (see [Cor07]).

The *global approximate controllability* of the (BSE) has been proved with different techniques in literature. We refer to [Mir09, Ner10] for Lyapunov techniques, while we cite [BCMS12, BGRS15] for adiabatic arguments and [BdCC13, BCS14] for Lie-Galerking methods.

The *exact controllability* of infinite-dimensional quantum systems is in general a more delicate matter. When we consider the linear Schrödinger equation, the controllability and observability properties are reciprocally dual. Different results were developed by addressing directly or by duality the control problem with different techniques: multiplier methods [Lio83, Mac94], microlocal analysis [BLR92, Bur91, Leb92] and Carleman estimates [BM08, LT92, MOR08]. In any case, when one considers graph type domains, a complete theory is far from being formulated. Indeed, the interaction between the different components of a graph may generate unexpected phenomena (see [DZ06]).

The *bilinear Schrödinger equation* is well-known for not being exactly controllable in the Hilbert space where it is defined when B is a bounded operator and $u \in L^2((0, T), \mathbb{R})$ with $T > 0$ (even though it is well-posed in such space). This result has been proved by Turinici in [Tur00], but it can also be deduced by the work [BMS82]. As a consequence, the exact controllability of bilinear quantum systems can not be addressed with the classical techniques valid for the linear Schrödinger equation and weaker notions of controllability are necessary. The turning point for this kind of studies has been the idea of controlling the equation in subspaces of $D(A)$ introduced by Beauchard in [Bea05]. Following this approach, different works were developed for the bilinear Schrödinger equation (BSE) with $\mathcal{G} = (0, 1)$ and $A = -\Delta_D$ the Dirichlet Laplacian:

$$D(-\Delta_D) = H^2((0, 1), \mathbb{C}) \cap H_0^1((0, 1), \mathbb{C}), \quad -\Delta_D \psi := -\Delta \psi, \quad \forall \psi \in D(-\Delta_D).$$

For instance, in [BL10], Beauchard and Laurent proved the *well-posedness* and the *local exact controllability* of the bilinear Schrödinger equation in $H_{(0)}^s := D(|-\Delta_D|^{s/2})$ for $s = 3$. For the *global exact controllability* in $H_{(0)}^3$, we refer to [BL17, Duc19], while we mention [Mor14, MN15] for *simultaneous exact controllability* results in $H_{(0)}^3$ and $H_{(0)}^4$.

Studying the controllability of the bilinear Schrödinger equation (BSE) on compact graphs presents an additional problem. In particular, when we consider $(\lambda_k)_{k \in \mathbb{N}^*}$, the ordered sequence of eigenvalues of A , it is possible to show that there exists $\mathcal{M} \in \mathbb{N}^*$ such that

$$(1) \quad \inf_{k \in \mathbb{N}^*} |\lambda_{k+\mathcal{M}} - \lambda_k| > 0$$

(as presented in [Duc18a, relation (2)]). Nevertheless the uniform spectral gap $\inf_{k \in \mathbb{N}^*} |\lambda_{k+1} - \lambda_k| > 0$ is only valid when $\mathcal{G} = (0, 1)$. This hypothesis is crucial for the techniques developed in the works [BL10, Duc19, Mor14], which can not be directly applied without imposing further assumptions.

As far as we know, the bilinear Schrödinger equation on compact graphs has only been studied in [Duc18a]. There, the author ensures that, if there exist $C > 0$ and suitable $\bar{d} \geq 0$ such that

$$(2) \quad |\lambda_{k+1} - \lambda_k| \geq Ck^{-\bar{d}}, \quad \forall k \in \mathbb{N}^*,$$

then the *well-posedness* and the *global exact controllability* of the bilinear Schrödinger equation (BSE) can be guaranteed in some subspaces of $L^2(\mathcal{G}, \mathbb{C})$.

Novelties of the work: Global exact controllability

The aim of this work is to present a new technique ensuring the *global exact controllability* of the (BSE) in different frameworks from the ones considered in [Duc18a]. Such result is postponed to the next section in Theorem 2.3 in order to avoid further technicalities at this moment. Here, we focus on discussing two interesting applications involving *star graphs* composed by any number of edges.

Let \mathcal{G} be a star graph with $N \in \mathbb{N}^*$ edges $\{e_j\}_{j \leq N}$. We denote by v the internal vertex of \mathcal{G} and by $\{v_j\}_{j \leq N}$ the set of the external vertices such that $v_j \in e_j$ for every $j \leq N$. Each edge e_j with $j \leq N$ is equipped with a coordinate going from 0 to the length of the edge L_j ; we set the coordinate 0 in v_j .

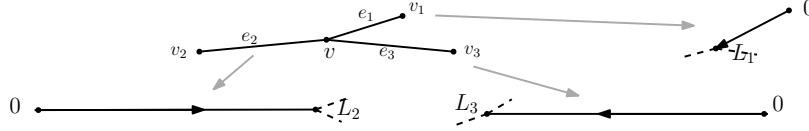


Figure 2: Parametrization of a star graph with $N = 3$ edges.

We consider functions $f := (f^1, \dots, f^N) : \mathcal{G} \rightarrow \mathbb{C}$ so that $f^j : (0, L_j) \rightarrow \mathbb{C}$ for every $j \leq N$. We denote $L^2(\mathcal{G}, \mathbb{C}) = \prod_{j \leq N} L^2((0, L_j), \mathbb{C})$ the Hilbert space equipped with the norm $\|\cdot\|_{L^2}$. The controllability result that we present is guaranteed when the lengths $\{L_j\}_{j \leq N}$ satisfy suitable assumptions introduced in the following definition.

Definition 1.1. Fixed $N \in \mathbb{N}^*$, we define $\mathcal{AL}(N)$ such as the set of elements $\{L_j\}_{j \leq N} \in (\mathbb{R}^+)^N$ so that: the numbers $\{1, \{L_j\}_{j \leq N}\}$ are linearly independent over \mathbb{Q} and all the ratios L_k/L_j are algebraic irrational numbers.

The set $\mathcal{AL}(N)$ with $N \in \mathbb{N}^*$ contains the uncountable set of numbers $\{L_j\}_{j \leq N} \in (\mathbb{R}^+)^N$ so that each L_j can be written in the form $t\tilde{L}_j$ where all the ratios \tilde{L}_j/\tilde{L}_k are algebraic irrational numbers and t is a transcendental number. For instance, $\{\pi\sqrt{2}, \pi\sqrt{3}\}$ belongs to $\mathcal{AL}(2)$.

Definition 1.2. Let Γ_T^u be the unitary propagator associated to the (BSE) with $u \in L^2((0, T), \mathbb{R})$ and $T > 0$. The (BSE) is globally exactly controllable in $D(|A|^{\frac{s}{2}})$ with $s \geq 3$ when, for every $\psi^1, \psi^2 \in D(|A|^{\frac{s}{2}})$ such that $\|\psi^1\|_{L^2} = \|\psi^2\|_{L^2}$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that $\Gamma_T^u \psi^1 = \psi^2$.

We are finally ready to present the applications of the main results of the works presented in the next section in Theorem 2.3.

Theorem 1.3. Let \mathcal{G} be a star graph. Let $D(A)$ be the set of functions $f \in \prod_{j \leq N} H^2(e_j, \mathbb{C})$ such that:

- $f^j(0) = 0$ for every $j \leq N$ (Dirichlet boundary conditions in the external vertices $\{v_j\}_{j \leq N}$);
- f is continuous in the vertex v and $\sum_{j \leq N} \partial_x f^j(L_j) = 0$ (Neumann-Kirchhoff boundary conditions).

Let the control field B be such that, for every $\psi \in \mathcal{H}$,

$$\begin{cases} B\psi(x) = (x - L_1)^4 \psi(x), & x \in e_1, \\ B\psi(x) = 0, & x \in \mathcal{G} \setminus e_1. \end{cases}$$

There exists $\mathcal{C} \subset (\mathbb{R}^+)^N$ countable such that, for every $\{L_j\}_{j \leq N} \in \mathcal{AL}(N) \setminus \mathcal{C}$, the (BSE) is globally exactly controllable in $D(|A|^{\frac{4+\epsilon}{2}})$ for every $\epsilon > 0$.

A similar result to Theorem 1.3 is the following where the (BSE) is considered on a generic star graph equipped with Neumann boundary conditions on the external vertices instead of the Dirichlet ones.

Theorem 1.4. Let \mathcal{G} be a star graph. Let $D(A)$ be the set of functions $f \in \prod_{j \leq N} H^2(e_j, \mathbb{C})$ such that:

- $\partial_x f^j(0) = 0$ for every $j \leq N$ (Neumann boundary conditions in the external vertices $\{v_j\}_{j \leq N}$);
- f is continuous in the vertex v and $\sum_{j \leq N} \partial_x f^j(L_j) = 0$ (Neumann-Kirchhoff boundary conditions).

Let the control field B be such that, for every $\psi \in \mathcal{H}$,

$$\begin{cases} B\psi(x) = (5x^6 - 24x^5 L_1 + 45x^4 L_1^2 - 40x^3 L_1^3 + 15x^2 L_1^4 - L_1^6) \psi(x), & x \in e_1, \\ B\psi(x) = 0, & x \in \mathcal{G} \setminus e_1. \end{cases}$$

There exists $\mathcal{C} \subset (\mathbb{R}^+)^N$ countable such that, for every $\{L_j\}_{j \leq N} \in \mathcal{AL}(N) \setminus \mathcal{C}$, the (BSE) is globally exactly controllable in $D(|A|^{\frac{5+\epsilon}{2}})$ for every $\epsilon > 0$.

The main novelty of Theorem 1.3 and Theorem 1.4 is the validity of the controllability results when \mathcal{G} is a star graph with any number of edges. In fact, the techniques developed in the existing work [Duc18a] only allow to consider star graphs with at most 4 edges (see [Duc18a, Theorem 2.5]). In addition, the controllability is guaranteed even though the control field B acts only on one edges of the graph, which is due to the choice of the lengths $\{L_j\}_{j \leq N}$ in $\mathcal{AL}(N)$. About this fact, if some ratios L_k/L_1 are rationals, then the spectrum of the operator A presents multiple eigenvalues and there exist eigenfunctions of A vanishing in e_1 (we refer to Remark 5.3 for further details on this fact). As a consequence, the dynamics of the bilinear Schrödinger equation (BSE) stabilizes such eigenfunctions since the control operator B only acts on e_1 . It is an obvious obstruction to the controllability which underlines the importance of choosing suitable lengths for the edges of the graph in this kind of problems.

Theorem 1.3 and Theorem 1.4 are proved by concatenating several intermediate outcomes. As it is common for this type of result, the global exact controllability can be proved by extending a local exact controllability result that follows from the solvability of a suitable “moment problem” (an example can be found in (8)). Hence, in the very first moment, we study assumptions on $(\lambda_k)_{k \in \mathbb{N}^*}$ ensuring the solvability of such moment problem. The main obstacle of this step follows from the nature of the spectrum $(\lambda_k)_{k \in \mathbb{N}^*}$, which may be difficult to characterize when \mathcal{G} is a general compact graph. In the second step, we ensure an abstract global exact controllability result for the (BSE) with respect to two types of hypotheses. The first conditions are on the spectrum $(\lambda_k)_{k \in \mathbb{N}^*}$, while the second on B . Afterwards, we prove the validity of the assumptions on $(\lambda_k)_{k \in \mathbb{N}^*}$ when \mathcal{G} is a star graph with edges of suitable lengths and external vertices equipped with Dirichlet or Neumann boundary conditions. Only in the very last moment, we validate the remaining hypotheses on the operator B of the abstract controllability result when B is defined such as in Theorem 1.3 and Theorem 1.4.

Energetic controllability

When the global exact controllability fails, in the spirit of the results provided in [BC06], we introduce a weaker notion of controllability: the *energetic controllability*.

Definition 1.5. Let $(\varphi_k)_{k \in \mathbb{N}^*}$ be an orthonormal system of \mathcal{H} (not necessarily complete) composed by eigenfunctions of A and $(\mu_k)_{k \in \mathbb{N}^*}$ be the corresponding eigenvalues. Let Γ_T^u be the unitary propagator associated to the (BSE) with $u \in L^2((0, T), \mathbb{R})$ and $T > 0$. The (BSE) is energetically controllable in $(\mu_k)_{k \in \mathbb{N}^*}$ if, for every $m, n \in \mathbb{N}^*$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ so that $\Gamma_T^u \varphi_m = \varphi_n$.

The energetic controllability guarantees the controllability of specific energy levels of the quantum system $i\partial_t \psi = A\psi$ in $L^2(\mathcal{G}, \mathbb{C})$ via the external field $u(t)B$. An application of the abstract result, which is stated in Theorem 6.1, is the following theorem.

Theorem 1.6. Let \mathcal{G} be a star graph with edges of equal length L . Let $D(A)$ be defined such as in Theorem 1.3. Let the control field B be such that, for every $\psi \in \mathcal{H}$,

$$\begin{cases} B\psi(x) = (x - L)^2\psi(x), & x \in e_1, \\ B\psi(x) = 0, & x \in \mathcal{G} \setminus e_1. \end{cases}$$

The (BSE) is energetically controllable in $(\frac{k^2\pi^2}{4L^2})_{k \in \mathbb{N}^*}$.

Theorem 1.6 is valid although the spectrum of A presents multiple eigenvalues and then the global exact controllability from Theorem 2.3 is not satisfied (also [Duc18a, Theorem 2.3] is not guaranteed). In addition, the energetic controllability is ensured with respect to all the energy levels of the quantum system $i\partial_t \psi = A\psi$, since the eigenvalues of A are $(\frac{k^2\pi^2}{4L^2})_{k \in \mathbb{N}^*}$ (without considering their multiplicity).

The energetic controllability is useful when it is not possible to fully characterize the spectrum of A because of the complexity of the graph \mathcal{G} . By studying the structure of \mathcal{G} , it is possible to explicit some eigenvalues $(\mu_k)_{k \in \mathbb{N}^*}$ and verify if the system is energetically controllable in $(\mu_k)_{k \in \mathbb{N}^*}$. In Section 6.1, we discuss some examples where the result is satisfied, e.g. graphs containing loops as in Figure 3 (a loop is an edge of the graph which is connected from both extremes to the same vertex).

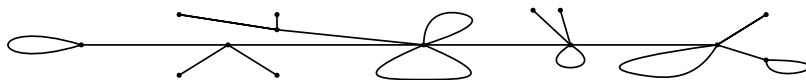


Figure 3: Example of compact graph containing more loops.

Scheme of the work

In Section 2, we present the main assumptions adopted in the work, the well-posedness of the (BSE) in specific subspaces of $L^2(\mathcal{G}, \mathbb{C})$ and the abstract global exact controllability result in Theorem 2.3. In Section 3, we study the solvability of the “moment problem” under the hypotheses of Theorem 2.3. In Section 4, we prove Theorem 2.3 by using the results developed in Section 3 and Appendix A. In Section 5, we study the (BSE) on star graphs and we prove Theorem 1.3 and Theorem 1.4. In Section 6, we discuss the energetic controllability of the (BSE) and we prove Theorem 1.6. In Appendix A, we present the global approximate controllability of the bilinear Schrödinger equation. In Appendix B, we study some spectral results adopted in the work.

2 The bilinear Schrödinger equation on compact graphs

2.1 Preliminaries

Let \mathcal{G} be a compact graph composed by $N \in \mathbb{N}^*$ edges $\{e_j\}_{j \leq N}$ of lengths $\{L_j\}_{j \leq N}$ and $M \in \mathbb{N}^*$ vertices $\{v_j\}_{j \leq M}$. For every vertex v , we denote $N(v) := \{l \in \{1, \dots, N\} \mid v \in e_l\}$ and $n(v) := |N(v)|$. We call V_e and V_i the external and the internal vertices of \mathcal{G} , *i.e.*

$$(3) \quad V_e := \{v \in \{v_j\}_{j \leq M} \mid \exists! e \in \{e_j\}_{j \leq N} : v \in e\}, \quad V_i := \{v_j\}_{j \leq M} \setminus V_e.$$

We study graphs equipped with a metric, which parametrizes each edge e_j with a coordinate going from 0 to its length L_j . A graph is compact when it is composed by a finite number of vertices and edges of finite lengths. We consider functions $f := (f^1, \dots, f^N) : \mathcal{G} \rightarrow \mathbb{C}$ with domain a compact metric graph \mathcal{G} so that $f^j : e_j \rightarrow \mathbb{C}$ for every $j \leq N$. We denote

$$\mathcal{H} = L^2(\mathcal{G}, \mathbb{C}) = \prod_{j \leq N} L^2(e_j, \mathbb{C}).$$

The Hilbert space \mathcal{H} is equipped with the norm $\|\cdot\|_{L^2}$ and the scalar product

$$\langle \psi, \varphi \rangle_{L^2} := \sum_{j \leq N} \langle \psi^j, \varphi^j \rangle_{L^2(e_j, \mathbb{C})} = \sum_{j \leq N} \int_{e_j} \overline{\psi^j(x)} \varphi^j(x) dx, \quad \forall \psi, \varphi \in \mathcal{H}.$$

For $s > 0$, we define the spaces

$$H^s = H^s(\mathcal{G}, \mathbb{C}) := \prod_{j=1}^N H^s(e_j, \mathbb{C}),$$

$$h^s = \left\{ (x_j)_{j \in \mathbb{N}^*} \subset \mathbb{C} \mid \sum_{j=1}^{\infty} |j^s x_j|^2 < \infty \right\}.$$

We equip h^s with the norm $\|(x_j)_{j \in \mathbb{N}^*}\|_{(s)} = \left(\sum_{j=1}^{\infty} |j^s x_j|^2 \right)^{\frac{1}{2}}$ for every $(x_j)_{j \in \mathbb{N}^*} \in h^s$.

Let $f = (f^1, \dots, f^N) : \mathcal{G} \rightarrow \mathbb{C}$ be smooth and v be a vertex of \mathcal{G} connected once to an edge e_j with $j \leq N$. When the coordinate parametrizing e_j in the vertex v is equal to 0 (resp. L_j), we denote

$$\partial_x f^j(v) = \partial_x f^j(0), \quad (\text{resp. } \partial_x f^j(v) = -\partial_x f^j(L_j)).$$

When e_j is a loop and it is connected to v in both of its extremes

$$\partial_x f^j(v) = \partial_x f^j(0) - \partial_x f^j(L_j).$$

When v is an external vertex of \mathcal{G} and then e_j is the only edge connected with v , we denote

$$\partial_x f(v) = \partial_x f^j(v).$$

In the bilinear Schrödinger equation (BSE), we consider the Laplacian A being self-adjoint and we denote \mathcal{G} as quantum graph. From now on, when we introduce a quantum graph \mathcal{G} , we implicitly define on \mathcal{G} a self-adjoint Laplacian A . Formally, $D(A)$ is characterized via the following boundary conditions.

Boundary conditions. Let \mathcal{G} be a quantum compact graph.

(\mathcal{D}) A vertex $v \in V_e$ is equipped with Dirichlet boundary conditions when $f(v) = 0$ for every $f \in D(A)$.

(\mathcal{N}) $v \in V_e$ is equipped with Neumann boundary conditions when $\partial_x f(v) = 0$ for every $f \in D(A)$.

(\mathcal{NK}) $v \in V_i$ is equipped with Neumann-Kirchhoff boundary conditions when every $f \in D(A)$ is continuous in v and $\sum_{j \in N(v)} \partial_x f^j(v) = 0$.

Notations. Let \mathcal{G} be a quantum compact graph.

- The graph \mathcal{G} is said to be equipped with (\mathcal{D}) (resp. (\mathcal{N})) when every $v \in V_e$ is equipped with (\mathcal{D}) (resp. (\mathcal{N})) and every $v \in V_i$ with (\mathcal{NK}).
- The graph \mathcal{G} is said to be equipped with (\mathcal{D}/\mathcal{N}) when every $v \in V_e$ is equipped with (\mathcal{D}) or (\mathcal{N}), while every $v \in V_i$ with (\mathcal{NK}).

When the introduced boundary conditions are satisfied, the Laplacian A is self-adjoint (see [Kuc04, Theorem 3] for further details) and admits purely discrete spectrum (see [Kuc04, Theorem 18]). We define $(\lambda_k)_{k \in \mathbb{N}^*}$ the ordered sequence of eigenvalues of A and a Hilbert basis of \mathcal{H} :

$$(4) \quad \Phi := (\phi_k)_{k \in \mathbb{N}^*}$$

composed by corresponding eigenfunctions. From [Duc18a, Remark A.4], there exist $C_1, C_2 > 0$ so that

$$(5) \quad C_1 k^2 \leq \lambda_k \leq C_2 k^2, \quad \forall k \geq 2.$$

Let $[r]$ be the entire part of $r \in \mathbb{R}$. For $s > 0$, we denote

$$H_{\mathcal{NK}}^s := \left\{ \psi \in \prod_{j=1}^N H^s(e_j, \mathbb{C}) \mid \begin{array}{l} \partial_x^{2n} \psi \text{ is continuous in } v, \forall n \in \mathbb{N}, n < [(s+1)/2], \forall v \in V_i; \\ \sum_{j \in N(v)} \partial_x^{2n+1} \psi^j(v) = 0, \forall n \in \mathbb{N}, n < [s/2], \forall v \in V_i \end{array} \right\},$$

$$H_{\mathcal{G}}^s = H_{\mathcal{G}}^s(\mathcal{G}, \mathbb{C}) := D(A^{s/2}), \quad \|\cdot\|_{(s)} := \|\cdot\|_{H_{\mathcal{G}}^s} = \left(\sum_{k \in \mathbb{N}^*} |k^s \langle \cdot, \phi_k \rangle_{L^2}|^2 \right)^{\frac{1}{2}}.$$

We introduce the main assumptions adopted in the manuscript by considering $(\mu_k)_{k \in \mathbb{N}^*} \subseteq (\lambda_k)_{k \in \mathbb{N}^*}$ an ordered sequence of some eigenvalues of A and the corresponding eigenfunctions

$$\varphi := (\varphi_k)_{k \in \mathbb{N}^*} \subseteq (\phi_k)_{k \in \mathbb{N}^*}.$$

Let $\eta > 0$, $a \geq 0$, $I := \{(j, k) \in (\mathbb{N}^*)^2 : j \neq k\}$ and $\widetilde{\mathcal{H}} := \overline{\text{span}\{\varphi_k \mid k \in \mathbb{N}^*\}}^{L^2}$.

Assumptions I (φ, η). The bounded symmetric operator B satisfies the following conditions.

1. There exists $C > 0$ such that $|\langle \varphi_k, B\varphi_1 \rangle_{L^2}| \geq \frac{C}{k^{2+\eta}}$ for every $k \in \mathbb{N}^*$.
2. For every $(j, k), (l, m) \in I$ such that $(j, k) \neq (l, m)$ and $\mu_j - \mu_k - \mu_l + \mu_m = 0$, it holds

$$\langle \varphi_j, B\varphi_j \rangle_{L^2} - \langle \varphi_k, B\varphi_k \rangle_{L^2} - \langle \varphi_l, B\varphi_l \rangle_{L^2} + \langle \varphi_m, B\varphi_m \rangle_{L^2} \neq 0.$$

Assumptions I (η). The couple (A, B) satisfies Assumptions I(Φ, η) with Φ defined in (4).

The first condition of Assumptions I(φ, η) (resp. Assumptions I(η)) quantifies how much B mixes the eigenspaces associated to the eigenfunctions $\{\varphi_k\}_{k \in \mathbb{N}^*}$ (resp. $\{\phi_k\}_{k \in \mathbb{N}^*}$). This assumption is crucial for the controllability. Indeed, when B stabilizes such spaces, also Γ_T^u does the same and we can not expect to obtain controllability results. The second hypothesis is used to decouple some eigenvalues resonances appearing in the proof of the approximate controllability that we will use in order to prove our main results.

Assumptions II (φ, η, a) . Let $\text{Ran}(B|_{H_{\mathcal{G}}^2 \cap \widetilde{\mathcal{H}}}) \subseteq H_{\mathcal{G}}^2 \cap \widetilde{\mathcal{H}}$ and one of the following points be satisfied.

1. When \mathcal{G} is equipped with $(\mathcal{D}/\mathcal{N})$ and $a + \eta \in (0, 3/2)$, there exists $d \in [\max\{a + \eta, 1\}, 3/2)$ so that

$$\text{Ran}(B|_{H_{\mathcal{G}}^{2+d} \cap \widetilde{\mathcal{H}}}) \subseteq H^{2+d} \cap H_{\mathcal{G}}^2 \cap \widetilde{\mathcal{H}}.$$

2. When \mathcal{G} is equipped with (\mathcal{N}) and $a + \eta \in (0, 7/2)$, there exist $d \in [\max\{a + \eta, 2\}, 7/2)$ and $d_1 \in (d, 7/2)$ such that

$$\text{Ran}(B|_{H_{\mathcal{N}\mathcal{K}}^{d_1} \cap \widetilde{\mathcal{H}}}) \subseteq H_{\mathcal{N}\mathcal{K}}^{d_1} \cap \widetilde{\mathcal{H}}, \quad \text{Ran}(B|_{H_{\mathcal{G}}^{2+d} \cap \widetilde{\mathcal{H}}}) \subseteq H^{2+d} \cap H_{\mathcal{N}\mathcal{K}}^{1+d} \cap H_{\mathcal{G}}^2 \cap \widetilde{\mathcal{H}}.$$

3. When \mathcal{G} is equipped with (\mathcal{D}) and $a + \eta \in (0, 5/2)$, there exists $d \in [\max\{a + \eta, 1\}, 5/2)$ such that

$$\text{Ran}(B|_{H_{\mathcal{G}}^{2+d} \cap \widetilde{\mathcal{H}}}) \subseteq H^{2+d} \cap H_{\mathcal{N}\mathcal{K}}^{1+d} \cap H_{\mathcal{G}}^2 \cap \widetilde{\mathcal{H}}.$$

If $a + \eta \geq 2$, then there exists $d_1 \in (d, 5/2)$ such that $\text{Ran}(B|_{H_{\mathcal{N}\mathcal{K}}^{d_1} \cap \widetilde{\mathcal{H}}}) \subseteq H^{d_1} \cap \widetilde{\mathcal{H}}$.

Assumptions II (η, a) . The couple (A, B) satisfies Assumptions II (Φ, η, a) with Φ defined in (4).

We introduce Assumptions II (φ, η, a) and Assumptions II (φ, η) since the choice of the boundary conditions defining $D(A)$ affects the definition of the spaces $H_{\mathcal{G}}^s = D(|A|^{\frac{s}{2}})$ with $s > 0$. For this reason, we have to calibrate the regularity of the control potential B according to such choice.

2.2 Well-posedness of the bilinear Schrödinger equation

Now, we cite [Duc18a, Proposition 3.1] where the well-posedness of the bilinear Schrödinger equation (BSE) is ensured in $H_{\mathcal{G}}^s$ with suitable $s \geq 3$.

Proposition 2.1. [Duc18a, Proposition 3.1] *Let \mathcal{G} be a compact quantum graph and (A, B) satisfy Assumptions II (η, \tilde{d}) with $\eta > 0$ and $\tilde{d} \geq 0$. For any $T > 0$ and $u \in L^2((0, T), \mathbb{R})$, the flow of the (BSE) is unitary in $\widetilde{\mathcal{H}}$ and, for any initial data $\psi^0 \in H_{\mathcal{G}}^{2+\tilde{d}}$ with d from Assumptions II (η, \tilde{d}) , there exists a unique mild solution of (BSE) in $H_{\mathcal{G}}^{2+\tilde{d}}$, i.e. a function $\psi \in C^0([0, T], H_{\mathcal{G}}^{2+\tilde{d}})$ such that*

$$(6) \quad \psi(t, x) = e^{-iAt}\psi^0(x) - i \int_0^t e^{-iA(t-s)}u(s)B\psi(s, x)ds, \quad \forall t \in [0, T].$$

Remark 2.2. *Let $\varphi := (\varphi_k)_{k \in \mathbb{N}^*} \subseteq (\phi_k)_{k \in \mathbb{N}^*}$ be an orthonormal system of \mathcal{H} made by eigenfunctions of A and $\widetilde{\mathcal{H}} := \overline{\text{span}\{\varphi_k \mid k \in \mathbb{N}^*\}}^{L^2}$. We notice that the statement of Proposition 2.1 can be ensured in $\widetilde{\mathcal{H}}$ as the propagator Γ_t^u preserves the space $H_{\mathcal{G}}^2 \cap \widetilde{\mathcal{H}}$ when $B : H_{\mathcal{G}}^2 \cap \widetilde{\mathcal{H}} \rightarrow H_{\mathcal{G}}^2 \cap \widetilde{\mathcal{H}}$. Thus, if (A, B) satisfies Assumptions II $(\varphi, \eta, \tilde{d})$ with $\eta > 0$ and $\tilde{d} \geq 0$, then, for every $\psi^0 \in H_{\mathcal{G}}^{2+\tilde{d}} \cup \widetilde{\mathcal{H}}$ with d from Assumptions II $(\varphi, \eta, \tilde{d})$ and $u \in L^2((0, T), \mathbb{R})$, there exists a unique mild solution of the (BSE) in*

$$H_{\mathcal{G}}^{2+\tilde{d}} \cup \widetilde{\mathcal{H}}.$$

2.3 Abstract global exact controllability result

In the following theorem, we provide the main abstract result of the work regarding the global exact controllability of the (BSE) in $H_{\mathcal{G}}^s$ with $s \geq 3$.

Theorem 2.3. *Let \mathcal{G} be a compact quantum graph and $(\lambda_k)_{k \in \mathbb{N}^*}$ be the ordered sequence of eigenvalues of A . Let the following hypotheses be satisfied.*

- *There exists an entire function $G \in L^\infty(\mathbb{R}, \mathbb{R})$ such that there exist $J, I > 0$ such that*

$$|G(z)| \leq J e^{I|z|}, \quad \forall z \in \mathbb{C}.$$

- The eigenvalues $(\lambda_k)_{k \in \mathbb{N}^*}$ are simple, the numbers $\{\pm\sqrt{\lambda_k}\}_{k \in \mathbb{N}^*}$ are simple zeros of G and there exist $\tilde{d} \geq 0$ and $C > 0$ such that

$$(7) \quad |G'(\pm\sqrt{\lambda_k})| \geq \frac{C}{k^{1+\tilde{d}}}, \quad \forall k \in \mathbb{N}^*.$$

If the couple (A, B) satisfies Assumptions I(η) and Assumptions II(η, \tilde{d}) for $\eta > 0$, then the (BSE) is globally exactly controllable in $H_{\mathcal{G}}^s$ for $s = 2 + d$ and d from Assumptions II(η, \tilde{d}).

Proof. See Section 4. □

The proof of Theorem 2.3 is obtained by extending a local exact controllability result which follows from the solvability of a suitable moment problem in a specific subspace of $\ell^2(\mathbb{C})$. Namely, we will ensure that, for every $(x_k)_{k \in \mathbb{N}^*}$ in such subspace, there exists $u \in L^2((0, T), \mathbb{R})$ with $T > 0$ such that

$$(8) \quad x_k = -i \int_0^T u(\tau) e^{i(\lambda_k - \lambda_1)\tau} d\tau, \quad \forall k \in \mathbb{N}^*.$$

In the next section, we develop a new technique leading to such result when the hypotheses of Theorem 2.3 are satisfied. In particular, the entire function G is used to construct the control u satisfying (8) thanks to the Paley-Wiener's Theorem and the lower bound (7) provides the regularity of the subspace of $\ell^2(\mathbb{C})$ where we can consider $(x_k)_{k \in \mathbb{N}^*}$ in the moment problem (8).

In Section 5, we will show how to provide an entire function G satisfying the hypothesis of Theorem 2.3 when \mathcal{G} is an appropriate star graph. In such framework, it is possible to see the numbers $\{\pm\sqrt{\lambda_k}\}_{k \in \mathbb{N}^*}$ as the zeros of a specific function that we will use to construct G when we chose suitable $\{L_j\}_{j \leq N}$.

Remark. When $\mathcal{G} = (0, 1)$, Ingham's type theorems lead to the solvability of (26) for sequences $(x_k)_{k \in \mathbb{N}^*} \in \ell^2$. Such techniques are valid thanks to the spectral gap $\inf_{k \in \mathbb{N}^*} |\lambda_{k+1} - \lambda_k| > 0$ as explained in [BL10, Appendix B]. When \mathcal{G} is a compact graph and the weak spectral gap (2) is satisfied with suitable $\tilde{d} > 0$, such result can be ensured for $(x_k)_{k \in \mathbb{N}^*} \in h^{\tilde{d}(\mathcal{M}-1)}$ with \mathcal{M} from (1) (see [Duc18a, Appendix B]).

3 Trigonometric moment problems

3.1 On the solvability of the moment problem

The aim of this section is to prove the next proposition which ensures the solvability of the moment problem (8) when the hypotheses of Theorem 2.3 are valid.

Proposition 3.1. *Let $(\lambda_k)_{k \in \mathbb{N}^*} \subset \mathbb{R}^+$ be an ordered sequence of pairwise distinct numbers so that there exist $\delta, C_1, C_2 > 0$ and $\mathcal{M} \in \mathbb{N}^*$ such that*

$$\inf_{k \in \mathbb{N}^*} |\sqrt{\lambda_{k+\mathcal{M}}} - \sqrt{\lambda_k}| \geq \delta \mathcal{M}, \quad C_1 k^2 \leq \lambda_k \leq C_2 k^2, \quad \forall k \in \mathbb{N}^*.$$

Let G be an entire function so that $\{\pm\sqrt{\lambda_k}\}_{k \in \mathbb{N}^}$ are its simple zeros, $G \in L^\infty(\mathbb{R}, \mathbb{R})$ and there exist $J, I > 0$ such that $|G(z)| \leq J e^{I|z|}$ for every $z \in \mathbb{C}$. If there exist $\tilde{d} \geq 0$ and $C > 0$ such that*

$$|G'(\pm\sqrt{\lambda_k})| \geq \frac{C}{k^{1+\tilde{d}}}, \quad \forall j \in \mathbb{N}^*,$$

then for $T > 2\pi/\delta$ and for every $(x_k)_{k \in \mathbb{N}^} \in h^{\tilde{d}}(\mathbb{N}^*, \mathbb{C})$ with $x_1 \in \mathbb{R}$, there exists $u \in L^2((0, T), \mathbb{R})$ so that*

$$(9) \quad x_k = \int_0^T u(\tau) e^{i(\lambda_k - \lambda_1)\tau} d\tau, \quad \forall k \in \mathbb{N}^*.$$

The proof of Proposition 3.1 is provided in Section 3.5 by gathering some technical results developed below. We suggest to the uninterested reader to skip it and pass to the Section 4.

Remark 3.2. Let the hypotheses of Proposition 3.1 be guaranteed. For $T > 2\pi/\delta$ and for every $(x_k)_{k \in \mathbb{N}^*} \in h^{\bar{d}}(\mathbb{N}^*, \mathbb{C})$ with $x_1 \in \mathbb{R}$, there exists $u \in L^2((0, T), \mathbb{R})$ such that

$$(10) \quad x_k = \int_0^T u(\tau) e^{-i(\lambda_k - \lambda_1)\tau} d\tau, \quad \forall k \in \mathbb{N}^*.$$

The result follows from Proposition 3.1. Indeed, for every $(x_k)_{k \in \mathbb{N}^*} \in h^{\bar{d}}(\mathbb{N}^*, \mathbb{C})$ with $x_1 \in \mathbb{R}$, there exists $u \in L^2((0, T), \mathbb{R})$ such that $\bar{x}_k = \int_0^T u(\tau) e^{i(\lambda_k - \lambda_1)\tau} d\tau$ for every $k \in \mathbb{N}^*$. By conjugating the last expression, the identity (10) is satisfied since u is real.

3.2 Families of functions in a Hilbert space

Let $\mathbb{Z}^* = \mathbb{Z} \setminus \{0\}$. We denote by $\langle \cdot, \cdot \rangle_{L^2(0, T)}$ the scalar product in $L^2((0, T), \mathbb{C})$ with $T > 0$.

Definition 3.3. Let $(f_k)_{k \in \mathbb{Z}^*}$ be a family of functions in $L^2((0, T), \mathbb{R})$ with $T > 0$. The family $(f_k)_{k \in \mathbb{Z}^*}$ is said to be minimal if and only if $f_k \notin \overline{\text{span}\{f_j : j \neq k\}}^{L^2}$ for every $k \in \mathbb{Z}^*$.

Definition 3.4. A biorthogonal family to $(f_k)_{k \in \mathbb{Z}^*} \subset L^2((0, T), \mathbb{R})$ is a sequence of functions $(g_k)_{k \in \mathbb{Z}^*}$ in $L^2((0, T), \mathbb{R})$ such that $\langle f_k, g_j \rangle_{L^2(0, T)} = \delta_{k, j}$ for every $j, k \in \mathbb{Z}^*$.

Remark 3.5. When $(f_k)_{k \in \mathbb{Z}^*}$ is minimal, there exists an unique biorthogonal family $(g_k)_{k \in \mathbb{Z}^*}$ to $(f_k)_{k \in \mathbb{Z}^*}$ belonging to $X := \overline{\text{span}\{f_j : j \in \mathbb{Z}^*\}}^{L^2}$. Indeed, $(g_k)_{k \in \mathbb{Z}^*}$ can be constructed by setting

$$g_k = (f_k - \pi_k f_k) \|f_k - \pi_k f_k\|_{L^2(0, T)}^{-2}, \quad \forall k \in \mathbb{Z}^*$$

where π_k is the orthogonal projector onto $\overline{\text{span}\{f_j : j \neq k\}}^{L^2}$. The unicity of $(g_k)_{k \in \mathbb{Z}^*}$ follows as, for any biorthogonal family $\{g_k^1\}_{k \in \mathbb{Z}^*}$ in X , we have $\langle g_k - g_k^1, f_j \rangle_{L^2(0, T)} = 0$ for every $j, k \in \mathbb{Z}^*$, which implies $g_k = g_k^1$ for every $k \in \mathbb{Z}^*$.

Remark 3.6. If a sequence of functions $(f_k)_{k \in \mathbb{Z}^*} \subset L^2((0, T), \mathbb{C})$ admits a biorthogonal family $(g_k)_{k \in \mathbb{Z}^*}$, then it is minimal. Indeed, if we assume that there exists $k \in \mathbb{Z}^*$ such that $f_k \in \overline{\text{span}\{f_j : j \neq k\}}^{L^2}$, then the relations $\langle f_k, g_j \rangle_{L^2(0, T)} = 0$ for every $j \in \mathbb{Z}^* \setminus \{k\}$ would imply $\langle f_k, g_k \rangle_{L^2(0, T)} = 0$ which is absurd.

Definition 3.7. Let $(f_k)_{k \in \mathbb{Z}^*}$ be a family of functions in $L^2((0, T), \mathbb{R})$ with $T > 0$. The family $(f_k)_{k \in \mathbb{Z}^*}$ is a Riesz basis of $\overline{\text{span}\{f_j : j \in \mathbb{Z}^*\}}^{L^2}$ if and only if it is isomorphic to an orthonormal system.

Remark 3.8. Let $(f_k)_{k \in \mathbb{Z}^*}$ be a Riesz basis of $X := \overline{\text{span}\{f_j : j \in \mathbb{Z}^*\}}^{L^2}$. The sequence $(f_k)_{k \in \mathbb{Z}^*}$ is also minimal and the biorthogonal family to $(f_k)_{k \in \mathbb{Z}^*}$ can be uniquely defined in X thanks to Remark 3.5. The biorthogonal family to $(f_k)_{k \in \mathbb{Z}^*}$ forms a Riesz basis of X .

Now, we provide an important property on the Riesz basis proved in [BL10, Appendix B.1].

Proposition 3.9. [BL10, Appendix B; Proposition 19] Let $(f_k)_{k \in \mathbb{Z}^*}$ be a family of functions in $L^2((0, T), \mathbb{R})$ with $T > 0$ and let $(f_k)_{k \in \mathbb{Z}^*}$ be a Riesz basis of $\overline{\text{span}\{f_k : k \in \mathbb{Z}^*\}}^{L^2}$. There exist $C_1, C_2 > 0$ such that

$$(11) \quad C_1 \|\mathbf{x}\|_{\ell^2}^2 \leq \int_0^T \left| \sum_{k \in \mathbb{Z}^*} x_k f_k \right|^2 ds \leq C_2 \|\mathbf{x}\|_{\ell^2}^2, \quad \forall \mathbf{x} := (x_k)_{k \in \mathbb{N}^*} \in \ell^2(\mathbb{Z}^*, \mathbb{C}).$$

3.3 Riesz basis made by divided differences of exponentials

Let $\mathbf{v} = (\nu_k)_{k \in \mathbb{Z}^*} \subset \mathbb{R}^+$ be an ordered sequence of pairwise distinct numbers such that there exist $\mathcal{M} \in \mathbb{N}^*$ and $\delta > 0$ such that

$$(12) \quad \inf_{\{k \in \mathbb{Z}^* : k + \mathcal{M} \neq 0\}} |\nu_{k + \mathcal{M}} - \nu_k| \geq \delta \mathcal{M}.$$

The last relation yields that there does not exist \mathcal{M} consecutive $k, k+1 \in \mathbb{Z}^*$ such that $|\nu_{k+1} - \nu_k| < \delta$. It leads to a partition of \mathbb{Z}^* in subsets E_m with $m \in \mathbb{Z}^*$ and defines an equivalence relation in \mathbb{Z}^* :

$$k \sim n \text{ if and only if there exists } m \in \mathbb{Z}^* \text{ such that } k, n \in E_m.$$

Now, $\{E_m\}_{m \in \mathbb{Z}^*}$ are the equivalence classes corresponding to such relation and $|E_m| \leq \mathcal{M} - 1$. Let $s(m)$ be the smallest element of E_m . For every $\mathbf{x} := (x_k)_{k \in \mathbb{Z}^*} \subset \mathbb{C}$ and $m \in \mathbb{Z}^*$, we define

$$\mathbf{x}^m := (x_l^m)_{l \leq |E_m|}, \quad : \quad x_l^m = x_{s(m)+(l-1)}, \quad \forall l \leq |E_m|.$$

In other words, \mathbf{x}^m is the vector in $\mathbb{C}^{|E_m|}$ composed by those elements of \mathbf{x} with indices in E_m . For every $m \in \mathbb{Z}^*$, we denote $F_m(\mathbf{v}^m) : \mathbb{C}^{|E_m|} \rightarrow \mathbb{C}^{|E_m|}$ the matrix with components

$$F_{m;j,k}(\mathbf{v}^m) := \begin{cases} \prod_{\substack{l \neq j \\ l \leq k}} (\nu_j^m - \nu_l^m)^{-1}, & j \leq k, \\ 1, & j = k = 1, \\ 0, & j > k, \end{cases} \quad \forall j, k \leq |E_m|.$$

For each $k \in \mathbb{Z}^*$, there exists $m(k) \in \mathbb{Z}^*$ such that $k \in E_{m(k)}$, while $s(m(k))$ represents the smallest element of $E_{m(k)}$. Let $F(\mathbf{v})$ be the infinite matrix acting on $\mathbf{x} = (x_k)_{k \in \mathbb{Z}^*} \subset \mathbb{C}$ as follows

$$(F(\mathbf{v})\mathbf{x})_k = \left(F_{m(k)}(\mathbf{v}^{m(k)})\mathbf{x}^{m(k)} \right)_{k-s(m(k))+1}, \quad \forall k \in \mathbb{Z}^*.$$

We consider $F(\mathbf{v})$ as the operator on $\ell^2(\mathbb{Z}^*, \mathbb{C})$ defined by the action above and with domain

$$H(\mathbf{v}) := D(F(\mathbf{v})) = \{ \mathbf{x} := (x_k)_{k \in \mathbb{Z}^*} \in \ell^2(\mathbb{Z}^*, \mathbb{C}) : F(\mathbf{v})\mathbf{x} \in \ell^2(\mathbb{Z}^*, \mathbb{C}) \},$$

Remark 3.10. Each matrix $F_m(\mathbf{v}^m)$ with $m \in \mathbb{Z}^*$ is invertible and we call $F_m(\mathbf{v}^m)^{-1}$ its inverse. Now, $F(\mathbf{v}) : H(\mathbf{v}) \rightarrow \text{Ran}(F(\mathbf{v}))$ is invertible and $F(\mathbf{v})^{-1} : \text{Ran}(F(\mathbf{v})) \rightarrow H(\mathbf{v})$ is so that, for $\mathbf{x} \in \text{Ran}(F(\mathbf{v}))$,

$$(F(\mathbf{v})^{-1}\mathbf{x})_k = \left(F_{m(k)}(\mathbf{v}^{m(k)})^{-1}\mathbf{x}^{m(k)} \right)_{k-s(m(k))+1}, \quad \forall k \in \mathbb{Z}^*.$$

Let $F_{m(k)}(\mathbf{v}^{m(k)})^*$ be the transposed matrix of $F_{m(k)}(\mathbf{v}^{m(k)})$ for every $m \in \mathbb{Z}^*$ and $F(\mathbf{v})^*$ be the infinite matrix so that, for every $\mathbf{x} = (x_k)_{k \in \mathbb{Z}^*} \subset \mathbb{C}$,

$$(F(\mathbf{v})^*\mathbf{x})_k = \left(F_{m(k)}(\mathbf{v}^{m(k)})^*\mathbf{x}^{m(k)} \right)_{k-s(m(k))+1}, \quad \forall k \in \mathbb{Z}^*.$$

Remark 3.11. When $H(\mathbf{v})$ is dense in $\ell^2(\mathbb{Z}^*, \mathbb{C})$, we can consider $F(\mathbf{v})^*$ as the unique adjoint operator of $F(\mathbf{v})$ in $\ell^2(\mathbb{Z}^*, \mathbb{C})$ with domain $H(\mathbf{v})^* := D(F(\mathbf{v})^*)$. As in Remark 3.10, we define $(F(\mathbf{v})^*)^{-1}$ the inverse operator of $F(\mathbf{v})^* : H(\mathbf{v})^* \rightarrow \text{Ran}(F(\mathbf{v})^*)$ and $(F(\mathbf{v})^*)^{-1} = (F(\mathbf{v})^{-1})^*$.

Let \mathbf{e} be sequence of functions in $L^2((0, T), \mathbb{C})$ with $T > 0$ so that $\mathbf{e} := (e^{i\nu_k(\cdot)})_{k \in \mathbb{Z}^*}$. We denote by Ξ the so-called *divided differences* of the family $(e^{i\nu_k t})_{k \in \mathbb{Z}^*}$ such that

$$(13) \quad \Xi := (\xi_k)_{k \in \mathbb{Z}^*} = F(\mathbf{v})^*\mathbf{e}.$$

In the following theorem, we rephrase a result of Avdonin and Moran [AM01], which is also proved by Baiocchi, Komornik and Loreti in [BKL02].

Theorem 3.12 (Theorem 3.29; [DZ06]). *Let $(\nu_k)_{k \in \mathbb{Z}^*}$ be an ordered sequence of pairwise distinct real numbers satisfying (12). If $T > 2\pi/\delta$, then $(\xi_k)_{k \in \mathbb{Z}^*}$ forms a Riesz Basis in the space $\overline{\text{span}\{\xi_k : k \in \mathbb{Z}^*\}}^{L^2}$.*

Remark 3.13. *Let Theorem 3.12 be valid. As Ξ is a Riesz basis, it is minimal in $\overline{\text{span}\{\xi_k : k \in \mathbb{Z}^*\}}^{L^2}$ and it admits a biorthogonal family $\mathbf{u} := (u_k)_{k \in \mathbb{Z}^*}$ thanks to Remark 3.6. Now, it is possible to see that*

$$\langle u_k, \xi_j \rangle_{L^2(0, T)} = \langle u_k, (F(\mathbf{v})^*\mathbf{e})_j \rangle_{L^2(0, T)} = \langle (F(\mathbf{v})\mathbf{u})_k, e^{i\nu_j t} \rangle_{L^2(0, T)}, \quad \forall j, k \in \mathbb{Z}^*.$$

The last relation ensures that $F(\mathbf{v})\mathbf{u}$ is a biorthogonal family to \mathbf{e} , which is then minimal.

3.4 Auxiliary results

In this subsection, we provide few intermediate results required in the proof of Proposition 3.1.

In Lemma 3.14 and Lemma 3.15, we consider a sequence $\mathbf{v} := (\nu_k)_{k \in \mathbb{Z}^*}$. We construct and characterize a suitable biorthogonal family to $\{e^{i\nu_k t}\}_{k \in \mathbb{Z}^*}$ by using a function G defined as in Proposition 3.1.

In Lemma 3.16, the preceding results lead to specific estimations on $F_m(\mathbf{v}^m)$ with $m \in \mathbb{Z}^*$.

In Lemma 3.18 and Lemma 3.19, we consider a sequence $\Theta := (\theta_k)_{k \in \mathbb{Z}^*}$ and another one defined as $(\nu_k)_{k \in \mathbb{Z}^*} = (\text{sgn}(\theta_k) \sqrt{|\theta_k|})_{k \in \mathbb{Z}^*}$. We use Lemma 3.16 with respect to the sequence $(\nu_k)_{k \in \mathbb{Z}^*}$ to provide estimations on $F_m(\Theta^m)$ with $m \in \mathbb{Z}^*$ and on the domain of the operator $F(\Theta)$.

In the proof of Proposition 3.1, we respectively denote by Θ and \mathbf{v} the sequences obtained by reordering $\{\pm \lambda_k\}_{k \in \mathbb{N}^*}$ and $\{\pm \sqrt{\lambda_k}\}_{k \in \mathbb{N}^*}$ and we use Lemma 3.19 to ensure the statement.

Lemma 3.14. *Let $\mathbf{v} := (\nu_k)_{k \in \mathbb{Z}^*}$ be an ordered sequence of pairwise distinct real numbers. Let G be an entire function such that $G \in L^\infty(\mathbb{R}, \mathbb{R})$ and there exist $J, I > 0$ such that $|G(z)| \leq J e^{I|z|}$ for every $z \in \mathbb{C}$. Denoted $G_k(z) := G(z)(z - \nu_k)^{-1}$ with $z \in \mathbb{C}$ for every $k \in \mathbb{Z}^*$, there exists $C > 0$ such that*

$$\|G_k\|_{L^2(\mathbb{R}, \mathbb{R})} \leq C, \quad \forall k \in \mathbb{Z}^*.$$

Proof. We know that there exists $M > 0$ so that $|G(x)| \leq M$ for every $x \in \mathbb{R}$, which implies that, for every $k \in \mathbb{Z}^*$, there exists $C_1 > 0$, not depending on k , so that

$$\|G_k\|_{L^2(\mathbb{R})}^2 = \int_{\mathbb{R}} \overline{G_k(x)} G_k(x) dx = \int_{\mathbb{R}} \frac{\overline{G(x)} G(x)}{(x - \nu_k)^2} dx \leq \int_{|x - \nu_k| \leq 1} \overline{G(x)} G(x) (x - \nu_k)^{-2} dx + M^2 C_1.$$

Now, from [You80, p. 82; Theorem 11], we have $|G(x + iy)| \leq M e^{I|y|}$ for $x, y \in \mathbb{R}$ and the Cauchy Integral Theorem ensured the existence of $C_2 > 0$, not depending on k , so that

$$\int_{|x - \nu_k| \leq 1} \frac{\overline{G(x)} G(x)}{(x - \nu_k)^2} dx \leq \int_0^\pi |\overline{G(\nu_k + e^{i\theta})} G(\nu_k + e^{i\theta})| d\theta \leq M^2 \int_0^\pi e^{2I \sin(\theta)} d\theta \leq M^2 C_2. \quad \square$$

Lemma 3.15. *Let $\mathbf{v} := (\nu_k)_{k \in \mathbb{Z}^*}$ be an ordered sequence of pairwise distinct real numbers satisfying (12) with $\delta > 0$. Let G be an entire function such that $G \in L^\infty(\mathbb{R}, \mathbb{R})$ and there exist $J, I > 0$ such that $|G(z)| \leq J e^{I|z|}$ for every $z \in \mathbb{C}$. Let $(\xi_k)_{k \in \mathbb{Z}^*}$ from (13) defined on $L^2((0, T), \mathbb{C})$ with $T > \max\{2\pi/\delta, 2I\}$. If $(\nu_k)_{k \in \mathbb{Z}^*}$ are simple zeros of G such that there exist $\tilde{d} \geq 0, C > 0$ such that*

$$(14) \quad |G'(\nu_k)| \geq \frac{C}{|k|^{1+\tilde{d}}}, \quad \forall k \in \mathbb{Z}^*,$$

then there exists $(w_k)_{k \in \mathbb{Z}^}$ an unique biorthogonal family to $(e^{i\nu_k t})_{k \in \mathbb{Z}^*}$ in $\overline{\text{span}\{\xi_k : k \in \mathbb{Z}^*\}}^{L^2}$ satisfying the following property. There exists $C_1 > 0$ such that $\|w_k\|_{L^2(0, T)} \leq C_1 |k|^{1+\tilde{d}}$ for every $k \in \mathbb{Z}^*$.*

Proof. For every $k \in \mathbb{Z}^*$, we define $G_k(z) := G(z)(z - \nu_k)^{-1}$. Thanks to the Paley-Wiener's Theorem [DZ06, Theorem 3.19], for every $k \in \mathbb{Z}^*$, there exists $f_k \in L^2(\mathbb{R}, \mathbb{R})$ with support in $[-I, I]$ such that

$$G_k(z) = \int_{-I}^I e^{izs} f_k(s) ds = \int_{-T/2}^{T/2} e^{izs} f_k(s) ds = \int_0^T e^{izt} e^{-iz\frac{T}{2}} f_k(t - T/2) dt.$$

For $j, k \in \mathbb{Z}^*$ and $c_k := G'(\nu_k)$, we call $v_k(t) := e^{i\nu_k \frac{T}{2}} \overline{f_k}(t - T/2)$ and

$$\langle v_k, e^{i\nu_j(\cdot)} \rangle_{L^2(0, T)} = G_k(\nu_j) = \delta_{k,j} G'(\nu_k) = \delta_{k,j} c_k.$$

Thus, the sequence $(v_k)_{k \in \mathbb{Z}^*}$ is biorthogonal to $(c_k^{-1} e^{i\nu_k(\cdot)})_{k \in \mathbb{Z}^*}$. Thanks to the Plancherel's identity and to Lemma 3.14, there exists $C_1 > 0$ such that

$$(15) \quad \|v_k\|_{L^2(0, T)} = \|G_k\|_{L^2(\mathbb{R}, \mathbb{R})} \leq C_1, \quad \forall k \in \mathbb{Z}^*.$$

The family $(e^{i\nu_k(\cdot)})_{k \in \mathbb{Z}^*}$ is minimal in $X := \overline{\text{span}\{\xi_k : k \in \mathbb{Z}^*\}}^{L^2}$ thanks to Remark 3.6 and then $(c_k^{-1} e^{i\nu_k(\cdot)})_{k \in \mathbb{Z}^*}$ is also minimal in X . Defined π_X the orthogonal projector onto X , we see that, for every $j, k \in \mathbb{Z}^*$,

$$\langle \pi_X v_k, c_j^{-1} e^{i\nu_j(\cdot)} \rangle_{L^2(0, T)} = \langle v_k, c_j^{-1} e^{i\nu_j(\cdot)} \rangle_{L^2(0, T)} = \delta_{k,j}.$$

The last relation and Remark 3.8 imply that $(\pi_X v_k)_{k \in \mathbb{Z}^*}$ is the unique biorthogonal family to $(c_k^{-1} e^{i\nu_k(\cdot)})_{k \in \mathbb{Z}^*}$ in X . We denote $w_k = (\overline{c_k})^{-1} \pi_X v_k$ for every $k \in \mathbb{Z}^*$ and $(w_k)_{k \in \mathbb{Z}^*}$ is the unique biorthogonal family to $(e^{i\nu_k(\cdot)})_{k \in \mathbb{Z}^*}$ in X . In conclusion, thanks to (14) and (15), there exists $C_2 > 0$ such that

$$\|w_k\|_{L^2(0,T)} \leq \|\pi_X v_k\|_{L^2(0,T)} |c_k|^{-1} \leq \|v_k\|_{L^2(0,T)} |G'(\nu_k)|^{-1} \leq C_2 |k|^{1+\tilde{d}}, \quad \forall k \in \mathbb{Z}^*. \quad \square$$

Lemma 3.16. *Let $\mathbf{v} := (\nu_k)_{k \in \mathbb{Z}^*}$ be an ordered sequence of pairwise distinct real numbers satisfying (12). Let G be an entire function such that $G \in L^\infty(\mathbb{R}, \mathbb{R})$ and there exist $J, I > 0$ such that $|G(z)| \leq J e^{I|z|}$ for every $z \in \mathbb{C}$. If $(\nu_k)_{k \in \mathbb{Z}^*}$ are simple zeros of G such that there exist $\tilde{d} \geq 0$, $C > 0$ such that $|G'(\nu_k)| \geq \frac{C}{|k|^{1+\tilde{d}}}$ for every $k \in \mathbb{Z}^*$, then there exists $C > 0$ so that*

$$\text{Tr}\left(F_m(\mathbf{v}^m)^* F_m(\mathbf{v}^m)\right) \leq C \min\{|l| \in E_m\}^{2(1+\tilde{d})}, \quad \forall m \in \mathbb{Z}^*$$

where the matrices $F_m(\mathbf{v}^m)$ are defined in Section 3.3.

Proof. Let $T > \max(2\pi/\delta, 2I)$ with $\delta > 0$ from (12). Let $\mathbf{e} := (e^{i\nu_k(\cdot)})_{k \in \mathbb{Z}^*} \subset L^2((0, T), \mathbb{C})$ and $\mathbf{v} := (\nu_k)_{k \in \mathbb{Z}^*}$ be defined in (13). Thanks to Proposition 3.12, the sequence of functions $\Xi = (\xi_k)_{k \in \mathbb{Z}^*} := (F(\mathbf{v})^* \mathbf{e})$ forms a Riesz basis of $X := \overline{\text{span}\{\xi_k : k \in \mathbb{Z}^*\}}^{L^2}$. We call $\mathbf{u} := (u_k)_{k \in \mathbb{Z}^*}$ the corresponding biorthogonal sequence to Ξ in X which is also a Riesz basis of X (see Remark 3.8). From Remark 3.10, the matrix $F(\mathbf{v})$ is invertible and $(F(\mathbf{v})^*)^{-1} = (F(\mathbf{v})^{-1})^*$. Let $\mathbf{w} = (w_k)_{k \in \mathbb{Z}^*}$ be the biorthogonal family in X to $(e^{i\nu_k(\cdot)})_{k \in \mathbb{Z}^*}$ defined in Lemma 3.15. For every $j, k \in \mathbb{Z}^*$,

$$\delta_{k,j} = \langle w_k, e^{i\nu_j(\cdot)} \rangle_{L^2(0,T)} = \langle w_k, ((F(\mathbf{v})^*)^{-1} \Xi)_j \rangle_{L^2(0,T)} = \langle (F(\mathbf{v})^{-1} \mathbf{w})_k, \xi_j \rangle_{L^2(0,T)},$$

which implies $\mathbf{w} = F(\mathbf{v}) \mathbf{u}$. Let $f(t) = \sum_{k \in \mathbb{Z}^*} \xi_k x_k$ with $\mathbf{x} := (x_k)_{k \in \mathbb{Z}^*} \in \ell^2(\mathbb{Z}^*, \mathbb{C})$. The biorthogonality relation between Ξ and \mathbf{u} yields that $x_k = \langle u_k, f \rangle_{L^2(0,T)}$ for every $k \in \mathbb{Z}^*$. From Proposition 3.9, there exist $C_1, C_2 > 0$ such that

$$(16) \quad C_1 \|\mathbf{x}\|_{\ell^2}^2 \leq \|f\|_{L^2(0,T)}^2 \leq C_2 \|\mathbf{x}\|_{\ell^2}^2.$$

For $k \in \mathbb{Z}^*$, we call $m(k) \in \mathbb{Z}^*$ the number such that $k \in E_{m(k)}$. Thanks to Lemma 3.15 and (16), there exist $C_3, C_4 > 0$ such that, for every $k \in \mathbb{Z}^*$, we have

$$(17) \quad \begin{aligned} |(F(\mathbf{v}) \mathbf{x})_k| &= |((F(\mathbf{v}))(\langle u_l, f \rangle_{L^2(0,T)})_{l \in \mathbb{Z}})_k| = |\langle w_k, f \rangle_{L^2(0,T)}| \leq \|w_k\|_{L^2(0,T)} \|f\|_{L^2(0,T)} \\ &\leq C_2^{\frac{1}{2}} \|w_k\|_{L^2(0,T)} \|\mathbf{x}\|_{\ell^2} \leq C_3 |k|^{1+\tilde{d}} \|\mathbf{x}\|_{\ell^2} \leq C_4 \min_{l \in E_{m(k)}} |l|^{1+\tilde{d}} \|\mathbf{x}\|_{\ell^2}. \end{aligned}$$

For every $m \in \mathbb{Z}^*$, we denote by $s(m)$ the smallest element of E_m and, for every $j \leq |E_m|$, we consider

$$\mathbf{x} \in \ell^2(\mathbb{Z}^*, \mathbb{C}) \quad : \quad x_{s(m)+j-1} = 1, \quad x_l = 0, \quad \forall l \in \mathbb{Z}^* \setminus \{s(m) + j - 1\}.$$

For every $j, n \leq |E_m|$, we use the sequence \mathbf{x} in the identity (17) with $k = s(m) + n - 1$ and we obtain $|(F_{m;n,j}(\mathbf{v}^m))| \leq C_4 \min_{l \in E_m} |l|^{1+\tilde{d}}$ which leads to the statement. \square

Remark 3.17. *Let $\Theta := (\theta_k)_{k \in \mathbb{Z}^*}$ be an ordered sequence of pairwise distinct real numbers and let the sequence $(\nu_k)_{k \in \mathbb{Z}^*} = (\text{sgn}(\theta_k) \sqrt{|\theta_k|})_{k \in \mathbb{Z}^*}$ satisfy the identity (12) with $\mathcal{M} \in \mathbb{N}^*$ and $\delta > 0$. As $\inf_{\substack{k \in \mathbb{Z}^* \\ k+\mathcal{M} \neq 0}} |\nu_{k+\mathcal{M}} - \nu_k| \geq \delta \mathcal{M} \min_{\substack{k \in \mathbb{Z}^* \\ \nu_k \neq 0}} (|\nu_k|, 1)$, we have*

$$\inf_{\substack{k \in \mathbb{Z}^* \\ k+\mathcal{M} \neq 0}} |\theta_{k+\mathcal{M}} - \theta_k| = \inf_{\substack{k \in \mathbb{Z}^* \\ k+\mathcal{M} \neq 0}} \left| |\nu_{k+\mathcal{M}}| - |\nu_k| \right| \left| |\nu_{k+\mathcal{M}}| + |\nu_k| \right| \geq \min_{\substack{k \in \mathbb{Z}^* \\ \nu_k \neq 0}} (|\nu_k|, 1) \delta \mathcal{M}.$$

Now, both the sequences Θ and $\mathbf{v} := (\nu_k)_{k \in \mathbb{Z}^*}$ satisfy (12) with respect to the same $\delta' := \min_{\substack{k \in \mathbb{Z}^* \\ \nu_k \neq 0}} \{|\nu_k|, 1\} \delta$ and \mathcal{M} . This fact ensures that Θ and \mathbf{v} induce the definition of the same equivalence classes $\{E_m\}_{m \in \mathbb{Z}^*}$ of \mathbb{Z}^* discussed in Section 3.3. Thus, we can use $\{E_m\}_{m \in \mathbb{Z}^*}$ in order to define the matrices $F_m(\Theta^m)$ and $F_m(\mathbf{v}^m)$ for every $m \in \mathbb{Z}^*$ and the operators $F(\Theta)$ and $F(\mathbf{v})$ on $\ell^2(\mathbb{Z}^*, \mathbb{C})$.

Lemma 3.18. Let $\Theta := (\theta_k)_{k \in \mathbb{Z}^*}$ be an ordered sequence of pairwise distinct real numbers such that $(\nu_k)_{k \in \mathbb{Z}^*} = (\text{sgn}(\theta_k) \sqrt{|\theta_k|})_{k \in \mathbb{Z}^*}$ satisfies (12). Let exist $C_1, C_2 > 0$ such that

$$(18) \quad C_1 |k| \leq |\nu_k| \leq C_2 |k|, \quad \forall k \in \mathbb{Z}^*, \quad \nu_k \neq 0.$$

Let G be an entire function so that $(\nu_k)_{k \in \mathbb{Z}^*}$ are its simple zeros, $G \in L^\infty(\mathbb{R}, \mathbb{R})$ and there exist $J, I > 0$ such that $|G(z)| \leq J e^{I|z|}$ for every $z \in \mathbb{C}$. If there exist $\tilde{d} \geq 0$ and $C > 0$ such that $|G'(\nu_k)| \geq \frac{C}{|k|^{1+\tilde{d}}}$ for every $k \in \mathbb{Z}^*$, then there exists $C > 0$ so that

$$\text{Tr} \left(F_m(\Theta^m)^* F_m(\Theta^m) \right) \leq C \min\{|l| \in E_m\}^{2\tilde{d}}, \quad \forall m \in \mathbb{Z}^*$$

where the matrices $F_m(\Theta^m)$ are defined as in Remark 3.17 from the sequence Θ .

Proof. We notice $|\theta_l - \theta_k| \geq \min\{|\nu_l|, |\nu_k|\} |\nu_l - \nu_k|$ for every $l, k \in \mathbb{Z}^*$. Let $m \in \mathbb{Z}^*$ and $I \subseteq E_m$ so that $I \neq \emptyset$. Now, $|I| \leq |E_m| \leq \mathcal{M} - 1$ and

$$\prod_{j, k \in I} |\theta_k - \theta_j| \geq \min_{\substack{l \in I \\ \nu_l \neq 0}} |\nu_l|^{I} \prod_{j, k \in I} |\nu_k - \nu_j| \geq C_1 \min_{\substack{l \in I \\ \nu_l \neq 0}} |\nu_l| \prod_{j, k \in I} |\nu_k - \nu_j|$$

for $C_1 = \min_{\substack{l \in \mathbb{Z}^* \\ \nu_l \neq 0}} (|\nu_l|^{\mathcal{M}-2}, 1)$. Thus, there exists $C_2 > 0$ so that, for every m and $j, k \in E_m$, we have

$$|F_{m;j,k}(\Theta^m)| \leq C_2 |F_{m;j,k}(\mathbf{v}^m)| \min\{|\nu_l|^{-1} : l \in E_m, \nu_l \neq 0\}.$$

In conclusion, thanks to (19) and Lemma 3.16, there exists $C_3 > 0$ such that

$$\text{Tr} \left(F_m(\Theta^m)^* F_m(\Theta^m) \right) \leq C_2^2 \min_{\substack{l \in E_m \\ \nu_l \neq 0}} |\nu_l|^{-2} \text{Tr} \left(F_m(\mathbf{v}^m)^* F_m(\mathbf{v}^m) \right) \leq C_3 \min_{l \in E_m} |l|^{2\tilde{d}}. \quad \square$$

Lemma 3.19. Let $\Theta := (\theta_k)_{k \in \mathbb{Z}^*}$ be an ordered sequence of pairwise distinct real numbers such that $(\nu_k)_{k \in \mathbb{Z}^*} = (\text{sgn}(\theta_k) \sqrt{|\theta_k|})_{k \in \mathbb{Z}^*}$ satisfies (12). Let exist $C_1, C_2 > 0$ such that

$$(19) \quad C_1 |k| \leq |\nu_k| \leq C_2 |k|, \quad \forall k \in \mathbb{Z}^*, \quad \nu_k \neq 0.$$

Let G be an entire function so that $(\nu_k)_{k \in \mathbb{Z}^*}$ are its simple zeros, $G \in L^\infty(\mathbb{R}, \mathbb{R})$ and there exist $J, I > 0$ such that $|G(z)| \leq J e^{I|z|}$ for every $z \in \mathbb{C}$. If there exist $\tilde{d} \geq 0$ and $C > 0$ such that $|G'(\nu_k)| \geq \frac{C}{|k|^{1+\tilde{d}}}$ for every $k \in \mathbb{Z}^*$, then

$$H(\Theta) \subseteq h^{\tilde{d}}(\mathbb{Z}^*, \mathbb{C})$$

where $H(\Theta)$ is the domain of the operator $F(\Theta)$ defined as in Remark 3.17 from the sequence Θ .

Proof. Let $\rho(M)$ be the spectral radius of a matrix M and let $\|M\| = \sqrt{\rho(M^*M)}$ be its euclidean norm. We consider Lemma 3.18 and, thanks to the fact that $(F_m(\Theta^m)^* F_m(\Theta^m))$ is positive-definite, there exists $C > 0$ such that

$$\|F_m(\Theta^m)\|^2 = \rho(F_m(\Theta^m)^* F_m(\Theta^m)) \leq \text{Tr} \left(F_m(\Theta^m)^* F_m(\Theta^m) \right) \leq C \min_{l \in E_m} |l|^{2\tilde{d}}, \quad m \in \mathbb{Z}^*.$$

In conclusion, we obtain that $h^{\tilde{d}}(\mathbb{Z}^*, \mathbb{C}) \subset H(\Theta)$ since, for every $\mathbf{x} = (x_k)_{k \in \mathbb{Z}^*} \in h^{\tilde{d}}(\mathbb{Z}^*, \mathbb{C})$,

$$\|F(\Theta)\mathbf{x}\|_{\ell^2}^2 \leq \sum_{m \in \mathbb{Z}^*} \|F_m(\Theta^m)\|^2 \sum_{l \in E_m} |x_l|^2 \leq C \sum_{m \in \mathbb{Z}^*} \min_{l \in E_m} |l|^{2\tilde{d}} \sum_{l \in E_m} |x_l|^2 \leq C \|\mathbf{x}\|_{h^{\tilde{d}}}^2 < +\infty. \quad \square$$

Remark 3.20. If Proposition 3.18 is satisfied with $\Theta = (\theta_k)_{k \in \mathbb{Z}^*}$ and $\tilde{d} \geq 0$, then $H(\Theta) \supseteq h^{\tilde{d}}(\mathbb{Z}^*, \mathbb{C})$ which is dense in $\ell^2(\mathbb{Z}^*, \mathbb{C})$. Thanks to Remark 3.11, we consider $F(\Theta)^*$ as the unique adjoint operator of $F(\Theta)$. As $\text{Tr}(F_m(\Theta^m)^* F_m(\Theta^m)) = \text{Tr}(F_m(\Theta^m) F_m(\Theta^m)^*)$ for every $m \in \mathbb{Z}^*$, the techniques developed in the proof of Proposition 3.18 lead to $H(\Theta)^* = D(F(\Theta)^*) \supseteq h^{\tilde{d}}(\mathbb{Z}^*, \mathbb{C})$.

3.5 Proof of Proposition 3.1

Let us introduce the following sequences:

$$\begin{aligned} \Theta &:= (\theta_k)_{k \in \mathbb{Z}^*} & : & \quad \theta_k = -\lambda_k, \quad \forall k > 0; \quad \theta_k = \lambda_{-k}, \quad \forall k < 0; \\ \mathbf{v} &:= (\nu_k)_{k \in \mathbb{Z}^*} & : & \quad \nu_k = -\sqrt{\lambda_k}, \quad \forall k > 0; \quad \nu_k = \sqrt{\lambda_{-k}}, \quad \forall k < 0; \\ \alpha &:= (\alpha_k)_{k \in \mathbb{Z}^* \setminus \{-1\}} & : & \quad \alpha_k = -\lambda_k + \lambda_1, \quad \forall k > 0; \quad \alpha_k = \lambda_{-k} - \lambda_1, \quad \forall k < -1. \end{aligned}$$

We consider $\mathcal{M}' \in \mathbb{N}^*$ and $\delta' > 0$ so that Θ and \mathbf{v} satisfy (12) with respect to \mathcal{M}' and δ' , while

$$(20) \quad \inf_{\{k \in \mathbb{Z}^* \setminus \{-1\} : k + \mathcal{M}' \in \mathbb{Z}^* \setminus \{-1\}\}} |\alpha_{k+\mathcal{M}'} - \alpha_k| \geq \delta' \mathcal{M}'.$$

Let $\{E_m\}_{m \in \mathbb{Z}^*}$ be the equivalence classes in \mathbb{Z}^* defined by Θ and \mathbf{v} (as in Remark 3.17). Let us assume that $-1 \in E_{-1}$. Now, $\{E_m\}_{m \in \mathbb{Z}^* \setminus \{-1\}} \cup \{E_{-1} \setminus \{-1\}\}$ are the equivalence classes in $\mathbb{Z}^* \setminus \{-1\}$ defined by (20) as in Section 3.3. Remark 3.20 implies $H(\Theta)^* \supseteq h^{\bar{d}}(\mathbb{Z}^*, \mathbb{C})$. We define as in Section 3.3, the operator $F(\alpha)$ in $\ell^2(\mathbb{Z}^* \setminus \{-1\}, \mathbb{C})$ from the sequence α and we notice that, for every $m \neq -1$, we have $F_m(\alpha^m) = F_m(\Theta^m)$ and $F_m(\alpha^m)^* = F_m(\Theta^m)^*$. Thus, as in Lemma 3.19 and Remark 3.20, there holds

$$H(\alpha) \supseteq h^{\bar{d}}(\mathbb{Z}^* \setminus \{-1\}, \mathbb{C}), \quad H(\alpha)^* \supseteq h^{\bar{d}}(\mathbb{Z}^* \setminus \{-1\}, \mathbb{C}).$$

We define $\mathbf{e} := (e^{i\alpha_k(\cdot)})_{k \in \mathbb{Z}^* \setminus \{-1\}}$ and $\Xi := (\xi_k)_{k \in \mathbb{Z}^* \setminus \{-1\}} = F(\alpha)^* \mathbf{e}$. When $T > 2\pi/\delta$, Theorem 3.12 ensures that $(\xi_k)_{k \in \mathbb{Z}^* \setminus \{-1\}}$ is a Riesz Basis of the space $X := \overline{\text{span}\{\xi_k : k \in \mathbb{Z}^* \setminus \{-1\}\}}^{L^2}$. Now, the map

$$M : g \in X \mapsto (\langle \xi_k, g \rangle_{L^2(0,T)})_{k \in \mathbb{Z}^* \setminus \{-1\}} \in \ell^2(\mathbb{Z}^* \setminus \{-1\}, \mathbb{C})$$

is invertible thanks to Proposition 3.9. Denoted $\tilde{X} := M^{-1} \circ F(\alpha)^*(h^{\bar{d}}(\mathbb{Z}^* \setminus \{-1\}, \mathbb{C}))$, the map

$$(F(\alpha)^*)^{-1} \circ M : g \in \tilde{X} \mapsto (\langle \mathbf{e}, g \rangle_{L^2(0,T)})_{k \in \mathbb{Z}^* \setminus \{-1\}} \in h^{\bar{d}}(\mathbb{Z}^* \setminus \{-1\}, \mathbb{C})$$

is invertible. Thus, for every $(x_k)_{k \in \mathbb{Z}^* \setminus \{-1\}} \in h^{\bar{d}}(\mathbb{Z}^* \setminus \{-1\}, \mathbb{C})$, there exists $u \in L^2((0, T), \mathbb{C})$ such that

$$(21) \quad x_k = \int_0^T u(\tau) e^{-i\alpha_k \tau} d\tau, \quad \forall k \in \mathbb{Z}^* \setminus \{-1\}.$$

Given $(x_k)_{k \in \mathbb{N}^*} \in h^{\bar{d}}(\mathbb{N}^*, \mathbb{C})$, we introduce $(\tilde{x}_k)_{k \in \mathbb{Z}^* \setminus \{-1\}} \in h^{\bar{d}}(\mathbb{Z}^* \setminus \{-1\}, \mathbb{C})$ so that $\tilde{x}_k = x_k$ for $k > 0$, while $\tilde{x}_k = \bar{x}_{-k}$ for $k < -1$. From (21) and to the definition of α , there exists $u \in X \subseteq L^2((0, T), \mathbb{C})$ so that

$$(22) \quad \int_0^T u(s) e^{i(\lambda_k - \lambda_1)s} ds = x_k = \int_0^T \bar{u}(s) e^{i(\lambda_k - \lambda_1)s} ds, \quad k \in \mathbb{N}^* \setminus \{1\},$$

while $\int_0^T u(s) ds = x_1$. The last relations and the fact that $x_1 \in \mathbb{R}$ imply that

$$(23) \quad \langle \text{Im}(u), e^{i\alpha_k(\cdot)} \rangle_{L^2(0,T)} = 0, \quad \forall k \in \mathbb{Z}^* \setminus \{-1\}.$$

From Remark 3.13, the family $\{e^{i\alpha_k t}\}_{k \in \mathbb{Z}^* \setminus \{-1\}}$ is minimal in X and $X = \overline{\text{span}\{e^{i\alpha_k t} : k \in \mathbb{Z}^* \setminus \{-1\}\}}^{L^2}$. Now, we recall that $-\alpha_k = \alpha_{-k}$ for every $k \in \mathbb{Z}^* \setminus \{\pm 1\}$ and $\alpha_1 = 0$. For every $u \in X$, we have

$$\bar{u} \in \overline{\text{span}\{e^{-i\alpha_k t} : k \in \mathbb{Z}^* \setminus \{-1\}\}}^{L^2} = X, \quad \implies \quad \text{Im}(u) = \frac{u - \bar{u}}{2i} \in X.$$

In conclusion, for $u \in X$ satisfying (22), the identity (23) and the fact that $\text{Im}(u) \in X$ yield that $\text{Im}(u) = 0$ which implies that u is real.

4 Proof of Theorem 2.3

4.1 Local exact controllability

Let $s = 2 + d$ and d from Assumptions II(η, \tilde{d}). For $\varepsilon, T > 0$, we introduce the following subspace of $H_{\mathcal{G}}^s$

$$O_{\varepsilon, T}^s := \{ \psi \in H_{\mathcal{G}}^s \mid \|\psi\|_{L^2} = 1, \|\psi - \phi_1(T)\|_{(s)} < \varepsilon \}, \quad \phi_1(T) := e^{-i\lambda_1 T} \phi_1.$$

We say that the (BSE) is locally exactly controllable in $O_{\varepsilon, T}^s$ when, for every $\psi \in O_{\varepsilon, T}^s$, there exists $u \in L^2((0, T), \mathbb{R})$ such that $\psi = \Gamma_T^u \phi_1$. The result corresponds to the surjectivity of the map

$$\Gamma_T^{(\cdot)} \phi_1 : L^2((0, T), \mathbb{R}) \longrightarrow O_{\varepsilon, T}^s.$$

Let us define $\phi_k(T) := e^{-i\lambda_k T} \phi_k$ with $k \in \mathbb{N}^*$. We decompose $\Gamma_T^{(\cdot)} \phi_1 = \sum_{k \in \mathbb{N}^*} \phi_k(T) \langle \phi_k(T), \Gamma_T^{(\cdot)} \phi_1 \rangle_{L^2}$ and we consider

$$\alpha : u \in L^2((0, T), \mathbb{R}) \longmapsto (\langle \phi_k(T), \Gamma_T^u \phi_1 \rangle_{L^2})_{k \in \mathbb{N}^*}.$$

Now, $\Gamma_T^u \phi_1 \in H_{\mathcal{G}}^s$ for every $u \in L^2((0, T), \mathbb{R})$ and $T > 0$ thanks to Proposition 2.1. Thus, α takes value in $Q^s := \{ \mathbf{x} := (x_k)_{k \in \mathbb{N}^*} \in h^s(\mathbb{C}) \mid \|\mathbf{x}\|_{\ell^2} = 1 \}$. Defined $\delta := (\delta_{k,1})_{k \in \mathbb{N}^*}$, we notice that

$$\alpha(0) = (\langle \phi_k(T), \Gamma_T^0 \phi_1 \rangle_{L^2})_{k \in \mathbb{N}^*} = (\langle \phi_k(T), \phi_1(T) \rangle_{L^2})_{k \in \mathbb{N}^*} = \delta.$$

The local exact controllability of the (BSE) in $O_{\varepsilon, T}^s$ is equivalent to the surjectivity of the function

$$\alpha : L^2((0, T), \mathbb{R}) \longrightarrow Q_{\varepsilon}^s := \{ \mathbf{x} := (x_k)_{k \in \mathbb{N}^*} \in Q^s \mid \|\mathbf{x} - \delta\|_{(s)} \leq \varepsilon \}.$$

Let $T_{\delta} Q^s$ be the tangent space of Q^s in the point $\alpha(0) = \delta$. For every $f : [0, 1] \rightarrow Q^s$ such that $f(0) = \delta$ and $f'(0) = \mathbf{x} \in h^s(\mathbb{C})$, we have $0 = (\partial_t \langle f(t), f(t) \rangle)(t=0) = 2\Re(\langle \mathbf{x}, \delta \rangle_{\ell^2})$, which implies

$$T_{\delta} Q^s = \{ \mathbf{x} := (x_k)_{k \in \mathbb{N}^*} \in h^s(\mathbb{C}) \mid ix_1 \in \mathbb{R} \}.$$

Let P be the orthogonal projector onto $T_{\delta} Q^s$. We define $\tilde{Q}^s := \{ \mathbf{x} := (x_k)_{k \in \mathbb{N}^*} \in h^s(\mathbb{C}) \mid \|\mathbf{x}\|_{\ell^2} \leq 1 \}$ and $\tilde{Q}_{\varepsilon}^s := \{ \mathbf{x} := (x_k)_{k \in \mathbb{N}^*} \in \tilde{Q}^s \mid \|\mathbf{x}\|_{(s)} \leq \varepsilon \}$. We consider the Fréchet derivative of α in $u = 0$:

$$\gamma : v \in L^2((0, T), \mathbb{R}) \longmapsto (d_u \alpha(u=0)) \cdot v \in T_{\delta} Q^s.$$

If γ is surjective in $T_{\delta} Q^s$, then the Generalized Inverse Function Theorem ([Lue69, Theorem 1; p. 240]) guarantees the existence of $\varepsilon > 0$ sufficiently small so that $P\alpha$ is surjective in $\tilde{Q}_{\varepsilon}^s \cap T_{\delta} Q^s$ (γ is also the Fréchet derivative of $P\alpha$). Now, for every $\mathbf{x} = \{x_k\}_{k \in \mathbb{N}^*} \in Q_{\varepsilon}^s$, we have $P\mathbf{x} \in \tilde{Q}_{\varepsilon}^s$ and there exists $u \in L^2((0, T), \mathbb{R})$ such that $P\mathbf{x} = P\alpha(u)$. Thus,

$$\mathbf{x} = P\mathbf{x} + \sqrt{1 - \|P\mathbf{x}\|_{\ell^2}^2} \delta = P\alpha(u) + \sqrt{1 - \|P\alpha(u)\|_{\ell^2}^2} \delta = \alpha(u).$$

Fixed $T > 0$, the last relation and the Generalized Inverse Function Theorem imply that if γ is surjective in $T_{\delta} Q^s$, then α is surjective in Q_{ε}^s with $\varepsilon > 0$ sufficiently small. Thus, we study the function γ and, thanks to the Duhamel's formula provided in (6), we notice that it is composed by the elements

$$\gamma_k(v) = -i \left\langle e^{-i\lambda_k T} \phi_k, \int_0^T e^{-iA(T-\tau)} v(\tau) B e^{-i\lambda_1 \tau} \phi_1 d\tau \right\rangle_{L^2} = -i \int_0^T v(\tau) e^{i(\lambda_k - \lambda_1)\tau} d\tau \langle \phi_k, B\phi_1 \rangle_{L^2}.$$

Proving the surjectivity of γ corresponds to ensure the solvability of the following moment problem

$$(24) \quad x_k \langle \phi_j, B\phi_k \rangle_{L^2}^{-1} = -i \int_0^T u(\tau) e^{i(\lambda_k - \lambda_1)\tau} d\tau, \quad \forall k \in \mathbb{N}^*$$

for every $(x_k)_{k \in \mathbb{N}^*} \in T_{\delta} Q^s$. We notice that $(x_k \langle \phi_k, B\phi_1 \rangle_{L^2}^{-1})_{k \in \mathbb{N}^*} \in h^{s-2-\eta} = h^{d-\eta} \subseteq h^{\tilde{d}}$ thanks to the point 1. of Assumptions I(η). As B is symmetric, we have $\langle \phi_1, B\phi_1 \rangle_{L^2} \in \mathbb{R}$ and $ix_1 \langle \phi_1, B\phi_1 \rangle_{L^2}^{-1} \in \mathbb{R}$. Thanks to [DZ06, relation (6.6)], there exist $\delta > 0$ and $\mathcal{M} \in \mathbb{N}^*$ such that

$$\inf_{k \in \mathbb{N}^*} |\sqrt{\lambda_{k+\mathcal{M}}} - \sqrt{\lambda_k}| \geq \delta \mathcal{M}.$$

This fact and (5) ensure that Proposition 3.1 is satisfied. The solvability of (26) is guaranteed for $T > 0$ large enough as $(x_k \langle \phi_k, B\phi_1 \rangle_{L^2}^{-1})_{k \in \mathbb{N}^*} \in \{(x_k)_{k \in \mathbb{N}^*} \in h^{\vec{d}}(\mathbb{C}) \mid ix_1 \in \mathbb{R}\}$ leading to the local exact controllability. Thus, for every $\psi \in O_{\varepsilon, T}^s$, there exists $u \in L^2((0, T), \mathbb{R})$ such that

$$(25) \quad \psi = \Gamma_T^u \phi_1.$$

Remark 4.1. We consider the unitary propagator $\tilde{\Gamma}_t^u$ generated by the time-dependent Hamiltonian $-A - u(T-t)B$ with $u \in L^2((0, T), \mathbb{R})$ with $T > 0$. As explained in [Duc18b, Section 2.3], the propagator $\tilde{\Gamma}_t^u$ represents the reversed dynamics of the (BSE) with the same u and

$$(\tilde{\Gamma}_T^u)(\Gamma_T^u) = (\Gamma_T^u)(\tilde{\Gamma}_T^u) = I.$$

The local exact controllability results provided in the previous part of the proof is also valid for the reversed dynamics. Indeed, the functions $(\phi_k)_{k \in \mathbb{N}^*}$ are the eigenfunctions of $-A$ corresponding to the eigenvalues $(-\lambda_k)_{k \in \mathbb{N}^*}$. As above, the local exact controllability of the reversed dynamics in the neighborhood

$$\tilde{O}_{\varepsilon, T}^s := \{\psi \in H_{\mathcal{G}}^s \mid \|\psi\|_{L^2} = 1, \|\psi - e^{i\lambda_1 T} \phi_1\|_{(s)} < \varepsilon\},$$

can be ensured by proving the solvability of a moment problem of the form

$$(26) \quad x_k \langle \phi_j, B\phi_k \rangle_{L^2}^{-1} = -i \int_0^T u(\tau) e^{-i(\lambda_k - \lambda_1)\tau} d\tau, \quad \forall k \in \mathbb{N}^*$$

for every $(x_k)_{k \in \mathbb{N}^*} \in T_{\delta} Q^s$. The result is proved as above thanks to Remark 3.2 and, for every $\psi \in \tilde{O}_{\varepsilon, T}^s$, there exists $u \in L^2((0, T), \mathbb{R})$ such that $\psi = \tilde{\Gamma}_T^u \phi_1$. Finally, the last relation yields that

$$(27) \quad \phi_1 = \Gamma_T^{\tilde{u}} \psi, \quad \text{for} \quad \tilde{u}(t) = u(T-t).$$

4.2 Global exact controllability

Let us consider $\psi_1, \psi_2 \in H_{\mathcal{G}}^s$ be so that $\|\psi_1\|_{L^2} = \|\psi_2\|_{L^2}$. We assume that $\|\psi_1\|_{L^2} = \|\psi_2\|_{L^2} = 1$, but the result is equivalently proved in the general case. Let $T, \varepsilon > 0$ be so that the local exact controllability from Section 4.1 is valid. Thanks to Proposition A.2 and Corollary A.3, there exist $T_1, T_2 > 0$, $u_1 \in L^2((0, T_1), \mathbb{R})$ and $u_2 \in L^2((0, T_2), \mathbb{R})$ such that

$$\|\Gamma_{T_1}^{u_1} \psi_1 - e^{i\lambda_1 T} \phi_1\|_{(s)} < \varepsilon, \quad \|\tilde{\Gamma}_{T_2}^{u_2} \psi_2 - e^{-i\lambda_1 T} \phi_1\|_{(s)} < \varepsilon, \quad \implies \quad \Gamma_{T_1}^{u_1} \psi_1 \in \tilde{O}_{\varepsilon, T}^s, \quad \Gamma_{T_2}^{u_2} \psi_2 \in O_{\varepsilon, T}^s.$$

From Remark 4.1 (relation (27)), there exists $u_3 \in L^2((0, T), \mathbb{R})$ such that $\Gamma_T^{u_3} \Gamma_{T_1}^{u_1} \psi_1 = \phi_1$. From Section 4.1 (relation (25)), there exist $u_4 \in L^2((0, T), \mathbb{R})$ such that $\Gamma_T^{u_4} \phi_1 = \tilde{\Gamma}_{T_2}^{u_2} \psi_2$ and then

$$\Gamma_T^{u_4} \Gamma_T^{u_3} \Gamma_{T_1}^{u_1} \psi_1 = \tilde{\Gamma}_{T_2}^{u_2} \psi_2 \quad \implies \quad \Gamma_{T_2}^{\tilde{u}_2} \Gamma_T^{u_4} \Gamma_T^{u_3} \Gamma_{T_1}^{u_1} \psi_1 = \psi_2, \quad \text{for} \quad \tilde{u}_2(t) = u_2(T_2 - t).$$

In conclusion, there exists $\hat{T} > 0$ and $\hat{u} \in L^2((0, \hat{T}), \mathbb{R})$ such that $\Gamma_{\hat{T}}^{\hat{u}} \psi_1 = \psi_2$.

5 Global exact controllability of bilinear quantum systems on star graphs

In the current section, we study the global exact controllability when \mathcal{G} is a star graph by applying Theorem 2.3. The result is obtained by providing a suitable entire function G satisfying the hypotheses of the theorem. From now on, when we call \mathcal{G} star graph, we also consider it as a quantum graph.

Theorem 5.1. Let \mathcal{G} be a star graph equipped with $(\mathcal{D}/\mathcal{N})$ made by edges long $\{L_j\}_{j \leq N} \in \mathcal{AL}(N)$. If the couple (A, B) satisfies Assumptions I(η) and Assumptions II(η, ϵ) for $\eta, \epsilon > 0$, then the (BSE) is globally exactly controllable in $H_{\mathcal{G}}^s$ for $s = 2 + d$ and d from Assumptions II(η, ϵ).

Proof. 1) Star graph equipped with (D). The boundary conditions (D) on V_e imply that $\phi_k = (a_k^1 \sin(\sqrt{\lambda_k}x), \dots, a_k^n \sin(\sqrt{\lambda_k}x))$ for each $k \in \mathbb{N}^*$ and suitable $\{a_k^l\}_{l \leq N} \subset \mathbb{C}$ such that $(\phi_k)_{k \in \mathbb{N}^*}$ is orthonormal in \mathcal{H} . The conditions (NK) in the internal vertex $v \in V_i$ ensure that

$$(28) \quad \begin{cases} a_k^1 \sin(\sqrt{\lambda_k}L_1) = \dots = a_k^N \sin(\sqrt{\lambda_k}L_N), \\ \sum_{l \leq N} a_k^l \cos(\sqrt{\lambda_k}L_l) = 0, \end{cases} \implies \sum_{l=1}^N \cot(\sqrt{\lambda_k}L_l) = 0.$$

We use the provided identities in order to construct an entire function satisfying the hypotheses of Theorem 2.3. To this purpose, we define an entire function G and two maps \tilde{G} and H such that

$$(29) \quad \begin{aligned} G(x) &:= \prod_{l \leq N} \sin(xL_l) \sum_{l \leq N} \cot(xL_l) & G'(x) &= -\tilde{G}(x) + H(x), \\ \tilde{G}(x) &:= \prod_{l \leq N} \sin(xL_l) \sum_{l \leq N} \frac{L_l}{\sin^2(xL_l)}, & H(x) &:= \frac{d}{dx} \left(\prod_{l \leq N} \cos(xL_l) \right) \sum_{l \leq N} \cot(xL_l). \end{aligned}$$

For $L^* := \min_{l \leq N} L_l$ and $x \in \mathbb{R}$, we have

$$(30) \quad |\tilde{G}(x)| = \frac{\prod_{l \leq N} |\sin(xL_l)| \sum_{l \leq N} L_l \prod_{k \neq l} \sin^2(xL_k)}{\prod_{l \leq N} \sin^2(xL_l)} \geq L^* \sum_{l \leq N} \prod_{k \neq l} |\sin(xL_k)|.$$

We refer to [DZ06, Corollary A.10; (2)], which contains a misprint as it is valid for every $\lambda > \frac{\pi}{2} \max\{1/L_j : j \leq N\}$. The identities (28) and (29) imply that $H(\sqrt{\lambda_k}) = 0$ and $G'(\sqrt{\lambda_k}) = -\tilde{G}(\sqrt{\lambda_k})$ for every $k \in \mathbb{N}^*$. Thanks to (30), [DZ06, Corollary A.10; (2)] ensures that, for every $\epsilon > 0$, there exists $C_1 > 0$ such that

$$(31) \quad |G'(\pm\sqrt{\lambda_k})| \geq L^* \sum_{l=1}^N \prod_{j \neq l} |\sin(\sqrt{\lambda_k}L_j)| \geq \frac{C_1}{(\sqrt{\lambda_k})^{1+\epsilon}}, \quad \forall k \in \mathbb{N}^* \quad : \quad \lambda_k > \frac{\pi}{2} \max\{L_j^{-1}\}_{j \leq N}.$$

Remark 5.2. For every $k \in \mathbb{N}^*$ and $j \leq N$, we have $|\phi_k^j(L_j)| \neq 0$, otherwise the (NK) conditions would ensure that $\phi_k^l(L_l) = \phi_k^m(L_m) = 0$ with $l, m \leq N$ so that $\phi_k^l, \phi_k^m \neq 0$ and there would be satisfied $a_k^l \sin(L_l \sqrt{\lambda_k}) = a_k^m \sin(L_m \sqrt{\lambda_k}) = 0$ with $a_k^l, a_k^m \neq 0$, which is absurd as $\{L_j\}_{j \leq N} \in \mathcal{AL}(N)$.

Remark 5.2 implies $|G'(\pm\sqrt{\lambda_k})| \neq 0$ for $k \in \mathbb{N}^*$. Thanks to (5) and (31), there exists $C_2 > 0$ so that

$$|G'(\pm\sqrt{\lambda_k})| \geq C_2 k^{-(1+\epsilon)}, \quad \forall k \in \mathbb{N}^*.$$

We notice that the spectrum of A is simple. Indeed, if there would exist two orthonormal eigenfunctions f and g of A corresponding to the same eigenvalue λ , then $h(x) = f(v)g(x) - g(v)f(x)$ would be another eigenfunction of A . Now, h is an eigenfunction and $h(v) = 0$ that is impossible thanks to Remark 5.2.

As $|\cos(zL_l)| \leq e^{L_l|z|}$ and $|\sin(zL_l)| \leq e^{L_l|z|}$ for every $l \leq N$ and $z \in \mathbb{C}$, we notice that $|G(z)| \leq N e^{|\sum_{l=1}^N L_l|}$ for every $z \in \mathbb{C}$. Now, $G(\sqrt{\lambda_k}) = 0$ for every $k \in \mathbb{N}^*$ thanks to (28) and $G \in L^\infty(\mathbb{R}, \mathbb{R})$.

In conclusion, the claim is achieved as Theorem 2.3 is valid with respect to the function G when $d = \epsilon$.

2) Generic star graph. Let $I_1 \subseteq \{1, \dots, N\}$ be the set of indices of those edges containing an external vertex equipped with (N) and $I_2 := \{1, \dots, N\} \setminus I_1$. The proof follows from the techniques adopted in 1) by considering Proposition B.2 (instead of [DZ06, Corollary A.10; (2)]) and the entire map

$$G(x) := \prod_{l \in I_2} \sin(xL_l) \prod_{l \in I_1} \cos(xL_l) \left(\sum_{l \in I_2} \cot(xL_l) + \sum_{l \in I_1} \tan(xL_l) \right). \quad \square$$

Remark 5.3. When \mathcal{G} is star graph with equipped with (D) such that L_2/L_1 and L_3/L_1 are rationals,

$$\exists n_2, n_3, m_2, m_3 \in \mathbb{N}^* \quad : \quad L_2/L_1 = n_2/m_2, \quad L_3/L_1 = n_3/m_3.$$

The sequence $\{\mu_k\}_{k \in \mathbb{N}^*}$ with $\mu_k = k \frac{n_2 n_3}{L_1}$ are eigenvalues of A and they are multiple. Indeed, fixed $k \in \mathbb{N}^*$,

$$f_k = (\sin(\mu_k x), \sin(\mu_k x), -2 \sin(\mu_k x), 0, \dots, 0), \quad g_k = (0, \sin(\mu_k x), -\sin(\mu_k x), 0, \dots, 0)$$

are eigenfunctions of A reciprocally orthogonal and corresponding to μ_k . In addition, we notice that the sequence $\{g_k\}_{k \in \mathbb{N}^*}$ is composed by eigenfunctions vanishing in the edge e_1 . The same kind of construction can be repeated when the star graph \mathcal{G} is equipped with the general boundary conditions (D/N).

Corollary 5.4. Let \mathcal{G} be a star graph equipped with $(\mathcal{D}/\mathcal{N})$. Let \mathcal{G} satisfy the following conditions with $\tilde{N} \in 2\mathbb{N}^*$ such that $\tilde{N} \leq N$.

- For $j \leq \tilde{N}/2$, the two external vertices belonging to e_{2j-1} and e_{2j} are equipped with (\mathcal{D}) or (\mathcal{N}) .
- The couples of edges $\{e_{2j-1}, e_{2j}\}_{j \leq \tilde{N}/2}$ are long $\{L_j\}_{j \leq \tilde{N}/2}$, while the edges $\{e_j\}_{\tilde{N} < j \leq N}$ measure $\{L_j\}_{\tilde{N} < j \leq N}$. In addition, $\{L_j\}_{j \leq \frac{\tilde{N}}{2}} \cup \{L_j\}_{\tilde{N} < j \leq N} \in \mathcal{AL}(\frac{\tilde{N}}{2} + N - \tilde{N})$.

If (A, B) satisfies Assumptions I(η) and Assumptions II(η, ϵ) for $\eta, \epsilon > 0$, then the (BSE) is globally exactly controllable in $H_{\mathcal{G}}^s$ for $s = 2 + d$ and d from Assumptions II(η, ϵ).

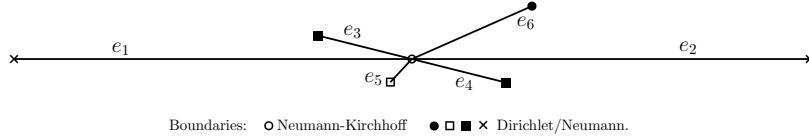


Figure 4: Example of graph described in Corollary 5.4 with $\tilde{N} = 4$ and $N = 6$.

Proof. Let $I_1 \subseteq \{1, \dots, \tilde{N}/2\}$ be the set of j such that e_{2j-1} and e_{2j} contain two external vertices of \mathcal{G} equipped with (\mathcal{N}) and $I_2 := \{1, \dots, \tilde{N}/2\} \setminus I_1$. Let $I_3 \subseteq \{\tilde{N} + 1, \dots, N\}$ be the set of j such that e_j contains an external vertex of \mathcal{G} equipped with (\mathcal{N}) and $I_4 := \{\tilde{N} + 1, \dots, N\} \setminus I_3$. Let

$$(\lambda_k^1)_{k \in \mathbb{N}^*} := \left(\frac{(2k-1)^2 \pi^2}{4L_j^2} \right)_{\substack{j, k \in \mathbb{N}^* \\ j \in I_1}}, \quad (\lambda_k^2)_{k \in \mathbb{N}^*} := \left(\frac{k^2 \pi^2}{L_j^2} \right)_{\substack{j, k \in \mathbb{N}^* \\ j \in I_2}}.$$

We notice that $(\lambda_k^1)_{k \in \mathbb{N}^*} \cup (\lambda_k^2)_{k \in \mathbb{N}^*} \subset (\lambda_k)_{k \in \mathbb{N}^*}$ are the only eigenvalues of A corresponding to eigenfunctions vanishing in the internal vertex v . For every $f \in (\phi_k)_{k \in \mathbb{N}^*}$ of A corresponding to an eigenvalue $\lambda \in (\lambda_k^1)_{k \in \mathbb{N}^*}$, f is uniquely defined (up to multiplication for $\alpha \in \mathbb{C}$ such that $|\alpha| = 1$) by the identities

$$f^{2j-1}(x) = -f^{2j}(x) = \sqrt{L_j^{-1}} \cos(\sqrt{\lambda}x), \quad f^l \equiv 0, \quad \forall l \in \{1, \dots, N\} \setminus \{2j-1, 2j\}.$$

Equivalently, it is valid with $(\lambda_k^2)_{k \in \mathbb{N}^*}$ and then the eigenvalues $(\lambda_k^1)_{k \in \mathbb{N}^*} \cup (\lambda_k^2)_{k \in \mathbb{N}^*}$ are simple. In conclusion, the discrete spectrum of A is simple since, if there would exist a multiple eigenvalue

$$\lambda \in (\lambda_k)_{k \in \mathbb{N}^*} \setminus ((\lambda_k^1)_{k \in \mathbb{N}^*} \cup (\lambda_k^2)_{k \in \mathbb{N}^*}),$$

then there would exist two orthonormal eigenfunctions f and g corresponding to the same eigenvalue λ . Now, $h(x) = f(v)g(x) - g(v)f(x)$ would be another eigenfunction corresponding to λ such that $h(v) = 0$, which is impossible as it would imply that $\lambda \in (\lambda_k^1)_{k \in \mathbb{N}^*} \cup (\lambda_k^2)_{k \in \mathbb{N}^*}$. Thus, $(\lambda_k)_{k \in \mathbb{N}^*}$ are simple eigenvalues. The remaining part of proof follows the one of Theorem 5.1 thanks to Proposition B.2 by considering

$$G(x) := \prod_{l \in I_2 \cup I_4} \sin(xL_l) \prod_{l \in I_1 \cup I_3} \cos(xL_l) \left(2 \sum_{l \in I_2} \cot(xL_l) + 2 \sum_{l \in I_1} \tan(xL_l) + \sum_{l \in I_4} \cot(xL_l) + \sum_{l \in I_3} \tan(xL_l) \right). \quad \square$$

5.1 Proofs of Theorem 1.3 and of Theorem 1.4

In the following theorem, we apply Theorem 5.1 for a specific problem.

Proof of Theorem 1.4. The conditions (\mathcal{N}) in V_i imply the existence, for every $k \in \mathbb{N}^*$, of $\{a_k^l\}_{l \leq N} \subset \mathbb{C}$ such that $\phi_k = (a_k^1 \cos(x\sqrt{\lambda_k}), \dots, a_k^N \cos(x\sqrt{\lambda_k}))$. The coefficients $\{a_k^l\}_{l \leq N} \subset \mathbb{C}$ are so that $(\phi_k)_{k \in \mathbb{N}^*}$ forms a Hilbert basis of \mathcal{H} and then

$$(32) \quad 1 = \sum_{l \leq N} \int_0^{L_l} |a_k^l|^2 \cos^2(x\sqrt{\lambda_k}) dx = \sum_{l \leq N} |a_k^l|^2 \left(\frac{L_l}{2} + \frac{\sin(2L_l\sqrt{\lambda_k})}{4\sqrt{\lambda_k}} \right).$$

For every $k \in \mathbb{N}^*$, the (\mathcal{NK}) boundary conditions in V_i ensure

$$(33) \quad \begin{aligned} a_k^1 \cos(\sqrt{\lambda_k} L_1) = \dots = a_k^N \cos(\sqrt{\lambda_k} L_N), \quad \sum_{l \leq N} a_k^l \sin(\sqrt{\lambda_k} L_l) = 0, \\ \sum_{l \leq N} \tan(\sqrt{\lambda_k} L_l) = 0, \quad \sum_{l \leq N} |a_k^l|^2 \sin(2L_l \sqrt{\lambda_k}) = 0. \end{aligned}$$

The last identities and (32) imply $1 = \sum_{l=1}^N |a_k^l|^2 L_l / 2$. Thanks to (33), we have $a_k^l = a_k^1 \frac{\cos(\sqrt{\lambda_k} L_1)}{\cos(\sqrt{\lambda_k} L_l)}$ for $l \neq 1$ and $k \in \mathbb{N}^*$. Thus, $|a_k^1|^2 (L_1 + \sum_{l=2}^N L_l \frac{\cos^2(\sqrt{\lambda_k} L_1)}{\cos^2(\sqrt{\lambda_k} L_l)}) = 2$ for every $k \in \mathbb{N}^*$ and

$$(34) \quad |a_k^1|^2 = 2 \prod_{m=2}^N \cos^2(\sqrt{\lambda_k} L_m) \left(\sum_{j=1}^N L_j \prod_{m \neq j} \cos^2(\sqrt{\lambda_k} L_m) \right)^{-1}.$$

Validation of Assumptions I(3 + ϵ) with $\epsilon > 0$. For every $k \in \mathbb{N}^*$, thanks to the relation (33)

$$\prod_{l \leq N} \cos(\sqrt{\lambda_k} L_l) \sum_{l \leq N} \tan(\sqrt{\lambda_k} L_l) = 0, \quad \implies \quad \sum_{l=1}^N \sin(\sqrt{\lambda_k} L_l) \prod_{m \neq l} \cos(\sqrt{\lambda_k} L_m) = 0.$$

Thanks to the relation (5) and Corollary B.3, for every $\epsilon > 0$, there exist $C_1, C_2 > 0$ such that,

$$(35) \quad |a_k^1| \geq \sqrt{\frac{2}{\sum_{l=1}^N L_l \cos^{-2}(\sqrt{\lambda_k} L_l)}} \geq \sqrt{\frac{2}{\sum_{l=1}^N L_l C_1^{-2} \lambda_k^{1+\epsilon}}} \geq \frac{C_2}{k^{1+\epsilon}}, \quad \forall k \in \mathbb{N}^*.$$

In addition, $\langle \phi_1^l, B\phi_k^l \rangle_{L^2(e_l, C)} = 0$ for $2 \leq l \leq N$ and, for every $k \in \mathbb{N}^*$,

$$(36) \quad \langle \phi_1, B\phi_k \rangle_{L^2} = \langle \phi_1^1, B\phi_k^1 \rangle_{L^2(e_1, C)} = -\frac{120a_k^1 a_1^1 L_1^6}{(\sqrt{\lambda_k} + \sqrt{\lambda_1})^4} - \frac{120a_k^1 a_1^1 L_1^6}{(\sqrt{\lambda_k} - \sqrt{\lambda_1})^4} + o(\sqrt{\lambda_k}^{-5}).$$

From the relations (35) and (36), thanks to the relation (5), for every $\epsilon > 0$, there exists $C_3 > 0$, such that for $k \in \mathbb{N}^*$ sufficiently large,

$$(37) \quad |\langle \phi_1, B\phi_k \rangle_{L^2}| \geq C_3 k^{-(5+\epsilon)}.$$

Now, it is possible to compute $a_k(\cdot)$ and $B_k(\cdot)$ with $k \in \mathbb{N}^*$, analytic functions in \mathbb{R}^+ , so that

$$a_k(L_1)^2 = (a_k^1)^2, \quad a_1(L_1) a_k(L_1) B_k(L_1) = \langle \phi_1, B\phi_k \rangle_{L^2}$$

and such that each $a_1(\cdot) a_k(\cdot) B_k(\cdot)$ is non-constant and analytic. Thus, each $a_1(\cdot) a_k(\cdot) B_k(\cdot)$ has discrete zeros $\tilde{V}_k \subset \mathbb{R}^+$ and $\tilde{V} = \bigcup_{k \in \mathbb{N}^*} \tilde{V}_k$ is countable. For every $\{L_l\}_{l \leq N} \in \mathcal{AL}(N)$ so that $L_1 \notin \tilde{V}$, we have $|\langle \phi_1, B\phi_k \rangle_{L^2}| \neq 0$ for every $k \in \mathbb{N}^*$. Thus, the point **1.** of Assumptions I(3 + ϵ) is ensured thanks to the relations (37) since, for every $\epsilon > 0$, there exists $C_4 > 0$ such that

$$|\langle \phi_1, B\phi_k \rangle_{L^2}| \geq C_4 k^{-(5+\epsilon)}, \quad \forall k \in \mathbb{N}^*.$$

Let $(k, j), (m, n) \in I$, $(k, j) \neq (m, n)$ for $I := \{(j, k) \in (\mathbb{N}^*)^2 : j \neq k\}$. We prove the validity of the point **2.** of Assumptions I(3 + ϵ). As above, we compute $F_k(\cdot)$ with $k \in \mathbb{N}^*$, analytic in \mathbb{R}^+ , such that $\langle \phi_k, B\phi_k \rangle_{L^2} = F_k(L_1)$. Each $F_{j,k,l,m}(\cdot) := F_j(\cdot) - F_k(\cdot) - F_l(\cdot) + F_m(\cdot)$ is non-constant and analytic in \mathbb{R}^+ , the set of its positive zeros $V_{j,k,l,m}$ is discrete. Now, we introduce the countable set:

$$V := \bigcup_{(j,k),(l,m) \in I : (j,k) \neq (l,m)} V_{j,k,l,m}.$$

For $\{L_l\}_{l \leq N} \in \mathcal{AL}(N)$ so that $L_1 \notin V \cup \tilde{V}$, the point **2.** of Assumptions I(3 + ϵ) with $\epsilon > 0$ is satisfied.

Validation of Assumptions II(3 + ϵ_1, ϵ_2) with $\epsilon_1, \epsilon_2 > 0$ so that $\epsilon_1 + \epsilon_2 \in (0, \frac{1}{2})$. Let

$$P(x) := (5x^6 - 24x^5 L_1 + 45x^4 L_1^2 - 40x^3 L_1^3 + 15x^2 L_1^4 - L_1^6).$$

For $m > 0$, we notice $B : H^m \rightarrow H^m$ and $\partial_x(B\psi)(\tilde{v}) = 0$ for every $\tilde{v} \in V_e$ since $\partial_x P(0) = 0$. Now, $\partial_x(B\psi)(v) = (B\psi)(v) = 0$ with $v \in V_i$ since $\partial_x P(L_1) = P(L_1) = 0$. Then, $B : H_{\mathcal{G}}^2 \rightarrow H_{\mathcal{G}}^2$. Moreover, $\partial_x^2 P(L_1) = \partial_x^3 P(L_1) = 0$, which imply $B : H_{\mathcal{NK}}^m \rightarrow H_{\mathcal{NK}}^m$ for every $m \in (0, \frac{9}{2})$. For $d \in [3 + \epsilon_1 + \epsilon_2, \frac{7}{2})$ and $d_1 \in (d, \frac{7}{2})$, there follow

$$\text{Ran}(B|_{H_{\mathcal{NK}}^{d_1}}) \subseteq H_{\mathcal{NK}}^{d_1}, \quad \text{Ran}(B|_{H_{\mathcal{G}}^{2+d}}) \subseteq \text{Ran}(B|_{H^{2+d} \cap H_{\mathcal{NK}}^{1+d} \cap H_{\mathcal{G}}^2}) \subseteq H^{2+d} \cap H_{\mathcal{NK}}^{1+d} \cap H_{\mathcal{G}}^2.$$

The point **2.** of Assumptions II(3 + ϵ_1, ϵ_2) with $\epsilon_1, \epsilon_2 > 0$ so that $\epsilon_1 + \epsilon_2 \in (0, \frac{1}{2})$ is valid.

Conclusion. The couple (A, B) satisfies Assumptions I(3 + ϵ) and Assumptions II(3 + ϵ_1, ϵ_2) with $\epsilon_1, \epsilon_2 > 0$ so that $\epsilon_1 + \epsilon_2 \in (0, \frac{1}{2})$. Theorem 5.1 guarantees the global exact controllability of the (BSE) in $H_{\mathcal{G}}^s$ with $s = 2 + d$ and $d \geq 3 + \epsilon_1 + \epsilon_2$. \square

Proof of Theorem 1.3. Theorem 1.3 is proved as [Duc18a, Theorem 1.2] that is stated for $N = 4$. The only difference between the two results is the fact that Theorem 1.3 follows from Theorem 5.1 instead of [Duc18a, Theorem 2.4], which is only valid for $N \leq 4$. \square

6 Energetic controllability

Let us recall the notation $(\varphi_k)_{k \in \mathbb{N}^*} \subseteq (\phi_k)_{k \in \mathbb{N}^*}$ indicating an orthonormal system (not necessarily complete) of \mathcal{H} made by some eigenfunctions of A . Let

$$(\mu_k)_{k \in \mathbb{N}^*}$$

be the ordered sequence of corresponding eigenvalues. We refer to Definition 1.5 for the formal definition of energetic controllability.

Theorem 6.1. *Let \mathcal{G} be a compact quantum graph and one of the following points be verified.*

1. *There exists an entire function G such that $G \in L^\infty(\mathbb{R}, \mathbb{R})$ and there exist $J, I > 0$ so that $|G(z)| \leq J e^{I|z|}$ for every $z \in \mathbb{C}$. The numbers $\{\pm\sqrt{\mu_k}\}_{k \in \mathbb{N}^*}$ are simple zeros of G and there exist $\tilde{d} \geq 0$ and $C > 0$ so that $|G'(\pm\sqrt{\mu_k})| \geq \frac{C}{k^{1+\tilde{d}}}$ for every $k \in \mathbb{N}^*$.*
2. *There exist $C > 0$ and $\tilde{d} \geq 0$ so that $|\mu_{k+1} - \mu_k| \geq C k^{-\frac{\tilde{d}}{\mathcal{M}-1}}$ for each $k \in \mathbb{N}^*$ with \mathcal{M} from (1).*

If (A, B) satisfies Assumptions I(φ, η) and Assumptions II(φ, η, \tilde{d}) for $\eta > 0$, then the (BSE) is globally exactly controllable in $H_{\mathcal{G}}^s \cap \mathcal{H}$ for $s = 2 + d$ with d from Assumptions II(φ, η, \tilde{d}) and energetically controllable in $(\mu_k)_{k \in \mathbb{N}^*}$.

Proof. From Remark 2.2, the (BSE) is well-posed in $H_{\mathcal{G}}^s \cap \widetilde{\mathcal{H}}$ with $s = 2 + d$ and d from Assumptions II(φ, η, \tilde{d}). The statement of Theorem 2.3 holds in $\widetilde{\mathcal{H}}$ when the point **1.** is valid, while the validity of [Duc18a, Theorem 2.3] in $\widetilde{\mathcal{H}}$ is guaranteed by **2.**. The global exact controllability is provided in $H_{\mathcal{G}}^s \cap \mathcal{H}$ and the energetic controllability follows as $\varphi_k \in H_{\mathcal{G}}^s \cap \mathcal{H}$ for every $k \in \mathbb{N}^*$. \square

Let \mathcal{G} be a compact quantum graph. By watching the structure of the graph and the boundary conditions of $D(A)$, it is possible to construct some eigenfunctions $(\varphi_k)_{k \in \mathbb{N}^*}$ of A corresponding to some eigenvalues $(\mu_k)_{k \in \mathbb{N}^*}$. For instance, we consider \mathcal{G} containing one loop e_1 of length 1 connected to the graph in a vertex v . In such case, we point out that the Neumann-Kirchhoff boundary conditions in v for a function $\psi \in D(A)$ yield that $\sum_{j \in \mathcal{N}(v) \setminus \{1\}} \partial_x \psi^j(v) + \partial_x \psi^1(0) - \partial_x \psi^1(1) = 0$.

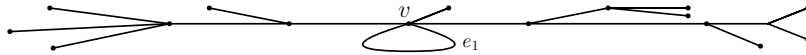


Figure 5: Example of compact graph containing a loop.

We define $\varphi := (\varphi_k)_{k \in \mathbb{N}^*}$ such that $\varphi_k = (\sqrt{2} \sin(2k\pi x), 0, \dots, 0)$ and the corresponding eigenvalues $(\mu_k)_{k \in \mathbb{N}^*} = (4k^2\pi^2)_{k \in \mathbb{N}^*} \subseteq (\lambda_k)_{k \in \mathbb{N}^*}$, satisfying the gap condition

$$\inf_{k \in \mathbb{N}^*} |\mu_{k+1} - \mu_k| = 12\pi^2 > 0.$$

If Assumptions I(φ, η) and Assumptions II($\varphi, \eta, 0$) are satisfied for $\eta > 0$, then Theorem 6.1 implies the energetic controllability in $(\mu_k)_{k \in \mathbb{N}^*}$. As we will show in the proof of Theorem 6.4, this approach is also valid when \mathcal{G} contains more loops (e.g. Figure 3).

Remark. The idea described above can be adopted when \mathcal{G} contains suitable sub-graphs denoted “uniform chains”. A uniform chain is a sequence of edges of equal length L connecting $M \in \mathbb{N}^*$ vertices $\{v_j\}_{j \leq M}$ such that $v_2, \dots, v_{M-1} \in V_i$ when $M \geq 3$. Moreover, one of the following is valid: either $v_1, v_M \in V_e$ are equipped with (\mathcal{D}) , or $v_1 = v_M$ belong to V_i , or $M \in \{2, 3\}$ and $v_1, v_M \in V_e$ are equipped with (\mathcal{N}) .

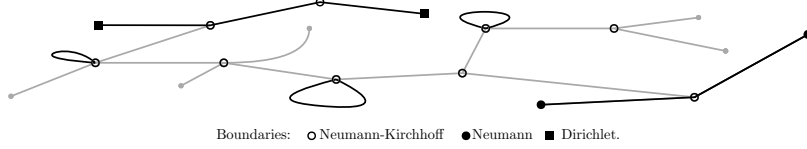


Figure 6: The figure underlines the uniform chains in a compact graph.

Let \mathcal{G} contain $\tilde{N} \in \mathbb{N}^*$ uniform chains $\{\tilde{\mathcal{G}}_j\}_{j \leq \tilde{N}}$, composed by edges of lengths $\{L_j\}_{j \leq \tilde{N}} \in \mathcal{AL}(\tilde{N})$. Let $I_1 \subseteq \{1, \dots, \tilde{N}\}$ and $I_2 \subseteq \{1, \dots, \tilde{N}\} \setminus I_1$ be respectively the sets of indices j such that the external vertices of $\tilde{\mathcal{G}}_j$ are equipped with (\mathcal{N}) and (\mathcal{D}) , while $I_3 := \{1, \dots, \tilde{N}\} \setminus (I_1 \cup I_2)$. We consider the eigenvalues $(\mu_k)_{k \in \mathbb{N}^*}$ obtained by reordering

$$\left(\frac{(2k-1)^2 \pi^2}{4L_j^2} \right)_{\substack{k, j \in \mathbb{N}^* \\ j \in I_1}} \cup \left(\frac{k^2 \pi^2}{L_j^2} \right)_{\substack{k, j \in \mathbb{N}^* \\ j \in I_2}} \cup \left(\frac{(2k-1)^2 \pi^2}{L_j^2} \right)_{\substack{k, j \in \mathbb{N}^* \\ j \in I_3}}.$$

As in the proof of [Duc18a, Lemma A.2], the Roth’s Theorem [Duc18a, Proposition A.1] ensures that, if $\{L_j\}_{j \leq \tilde{N}} \in \mathcal{AL}(\tilde{N})$, then for every $\epsilon > 0$, there exists $C > 0$ so that

$$|\mu_{k+1} - \mu_k| \geq Ck^{-\epsilon}, \quad \forall k \in \mathbb{N}^*.$$

In conclusion, if (A, B) satisfies Assumptions I(φ, η) and Assumptions II(φ, η, ϵ) with $\eta > 0$, then Theorem 6.1 implies the energetic controllability in $(\mu_k)_{k \in \mathbb{N}^*}$.

6.1 Proof of Theorem 1.6 and some applications of Theorem 6.1

Proof of Theorem 1.6. Let us assume $N = 3$. The (\mathcal{D}) conditions to the external vertices V_e imply $\phi_k = (a_k^1 \sin(\sqrt{\mu_k}x), a_k^2 \sin(\sqrt{\mu_k}x), a_k^3 \sin(\sqrt{\mu_k}x))$ with suitable $(a_k^1, a_k^2, a_k^3) \in \mathbb{C}^3$. From the (\mathcal{NK}) in $v \in V_i$, there follow $\sum_{l \leq 3} a_k^l \cos(\sqrt{\mu_k}L) = 0$ and $a_k^m \sin(\sqrt{\mu_k}L) = c \in \mathbb{R}$ for every $m \leq 3$. When $c \neq 0$, we have the eigenvalues $(\frac{(2k-1)^2 \pi^2}{4L^2})_{k \in \mathbb{N}^*}$ corresponding to the eigenfunctions $(g_k)_{k \in \mathbb{N}^*}$ so that

$$g_k = \left(\sqrt{\frac{2}{3L}} \sin\left(\frac{(2k-1)\pi}{2L}x\right), \sqrt{\frac{2}{3L}} \sin\left(\frac{(2k-1)\pi}{2L}x\right), \sqrt{\frac{2}{3L}} \sin\left(\frac{(2k-1)\pi}{2L}x\right) \right), \quad \forall k \in \mathbb{N}^*.$$

When $c = 0$, we obtain the eigenvalues $(\frac{k^2 \pi^2}{L^2})_{k \in \mathbb{N}^*}$ of multiplicity two that we associate to the couple of sequences of eigenfunctions $(f_k^1)_{k \in \mathbb{N}^*}$ and $(f_k^2)_{k \in \mathbb{N}^*}$ such that, for every $k \in \mathbb{N}^*$,

$$f_k^1 := \left(-\sqrt{\frac{4}{3L}} \sin\left(\frac{k\pi}{L}x\right), \sqrt{\frac{1}{3L}} \sin\left(\frac{k\pi}{L}x\right), \sqrt{\frac{1}{3L}} \sin\left(\frac{k\pi}{L}x\right) \right),$$

$$f_k^2 := \left(0, -\sqrt{\frac{1}{L}} \sin\left(\frac{k\pi}{L}x\right), \sqrt{\frac{1}{L}} \sin\left(\frac{k\pi}{L}x\right) \right).$$

Moreover, $(f_k^1)_{k \in \mathbb{N}^*} \cup (f_k^2)_{k \in \mathbb{N}^*} \cup (g_k)_{k \in \mathbb{N}^*}$ is a Hilbert basis of \mathcal{H} and $(\frac{k^2 \pi^2}{L^2})_{k \in \mathbb{N}^*} \cup (\frac{(2k-1)^2 \pi^2}{4L^2})_{k \in \mathbb{N}^*}$ are the eigenvalues of A (not considering their multiplicity).

Validation of Assumptions I($\varphi, 1$). We reorder $(f_k^1)_{k \in \mathbb{N}^*} \cup (g_k)_{k \in \mathbb{N}^*}$ in $\varphi = (\varphi_k)_{k \in \mathbb{N}^*}$. The point 1. of Assumptions I($\varphi, 1$) is verified as there exists $C_1, C_2 > 0$ such that

$$|\langle \varphi_1, B\varphi_k \rangle_{L^2}| \geq \frac{C_1 \sqrt{\mu_k} \sqrt{\mu_1}}{(\mu_k - \mu_1)^2} \geq \frac{C_2}{k^3}, \quad \forall k \in \mathbb{N}^*.$$

After, there exist $C_3, C_4 > 0$ so that $B_{k,k} := \langle \varphi_k, B\varphi_k \rangle_{L^2} = C_3 + C_4 k^{-2}$ for every $k \in \mathbb{N}^*$ and $\mu_k = \frac{\pi^2 k^2}{4L^2}$. Now, if $\mu_j - \mu_k - \mu_l + \mu_m = \frac{\pi^2}{4L^2}(j^2 - k^2 - l^2 + m^2) = 0$, then

$$B_{j,j} - B_{k,k} - B_{l,l} + B_{m,m} = C_4(j^{-2} - k^{-2} - l^{-2} + m^{-2}) \neq 0,$$

which implies the point **2.** of Assumptions I($\varphi, 1$).

Validation of Assumptions II($\varphi, 1, 0$) and conclusion. The operator B stabilizes the spaces H^m with $m > 0$ and $\overline{\text{span}\{\varphi_k : k \in \mathbb{N}^*\}}^{L^2} \cap H_{\mathcal{G}}^2$, ensuring the point **1.** of Assumptions II($\varphi, 1, 0$). Since

$$\inf_{j,k \in \mathbb{N}^*} |\mu_k - \mu_j| = \frac{\pi^2}{4L^2},$$

the point **2.** of Theorem 6.1 holds and the global exact controllability is proved in $H_{\mathcal{G}}^3 \cap \widetilde{\mathcal{H}}$. As $\varphi_k \in H_{\mathcal{G}}^3 \cap \widetilde{\mathcal{H}}$ for every $k \in \mathbb{N}^*$, the energetic controllability follows in $(\frac{k^2 \pi^2}{4L^2})_{k \in \mathbb{N}^*}$.

When $N > 3$, the spectrum contains simple eigenvalues relative to some eigenfunctions $(g_k)_{k \in \mathbb{N}^*}$ and multiple eigenvalues, each one corresponding to $N - 1$ eigenfunctions $\{f_{k;j}\}_{l \leq N-1}$ with $k \in \mathbb{N}^*$. For each $k \in \mathbb{N}^*$, we construct $\{f_{k;j}\}_{l \leq N-1}$ such that only the functions $\{f_{k;j}\}_{l \leq N-2}$ vanish in e_1 . We reorder $(f_{k;N-1})_{k \in \mathbb{N}^*} \cup (g_k)_{k \in \mathbb{N}^*}$ in $\varphi = (\varphi_k)_{k \in \mathbb{N}^*}$ and the proof is achieved as done for $N = 3$. \square

Theorem 6.2. Let \mathcal{G} be a star graph equipped with (\mathcal{D}/N) . Let \mathcal{G} contain two edges e_1 and e_2 long 1 connected two external vertices both equipped with (\mathcal{D}) .

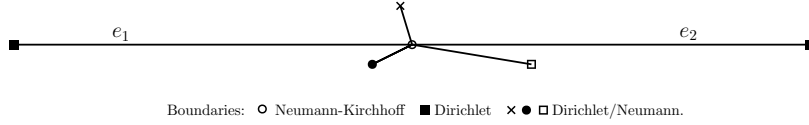


Figure 7: Example of star graph described by Theorem 6.2 with $N = 5$.

Let $B\psi = (x^2(\psi^1(x) - \psi^2(x)), x^2(\psi^2(x) - \psi^1(x)), 0, \dots, 0)$ for every $\psi \in \mathcal{H}$. There exists $(\varphi_k)_{k \in \mathbb{N}^*} \subset (\phi_k)_{k \in \mathbb{N}^*}$ such that the (BSE) is globally exactly controllable in $H_{\mathcal{G}}^3 \cap \widetilde{\mathcal{H}}$ and energetically controllable in $(k^2 \pi^2)_{k \in \mathbb{N}^*}$.

Proof. Let $(\mu_k)_{k \in \mathbb{N}^*}$ and $(\varphi_k)_{k \in \mathbb{N}^*}$ be so that $\mu_k = k^2 \pi^2$, $\varphi_k^1 = -\varphi_k^2 = \sin(k\pi x)$ and $\varphi_k^l = 0$ with $k \in \mathbb{N}^*$ and $3 \leq l \leq N$. The claim follows from the point **2.** of Theorem 6.1 with $\tilde{d} = 0$ as Theorem 1.6. \square

Theorem 6.3. Let \mathcal{G} be a star graph equipped with (\mathcal{D}) and composed by $\frac{N}{2}$ couples of edges $\{e_{2j-1}, e_{2j}\}_{j \leq \frac{N}{2}}$ long $\{L_j\}_{j \leq \frac{N}{2}} \in \mathcal{AL}(\frac{N}{2})$ with $N \in 2\mathbb{N}^*$.

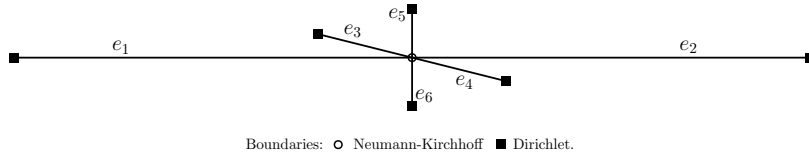


Figure 8: Example of star graph described by Theorem 6.3 with $N = 6$.

Let B be such that $B\psi = ((B\psi)^1, \dots, (B\psi)^N)$ for every $\psi \in \mathcal{H}$ and

$$(B\psi)^{2j} = -(B\psi)^{2j-1} = \sum_{l=1}^{N/2} \frac{L_l^{3/2}}{L_j^{3/2}} x^2 \left(\psi^{2l} \left(\frac{L_l}{L_j} x \right) - \psi^{2l-1} \left(\frac{L_l}{L_j} x \right) \right), \quad \forall j \leq \frac{N}{2}.$$

There exists $\mathcal{C} \subset (\mathbb{R}^+)^N$ countable so that, for every $\{L_j\}_{j \leq N} \in \mathcal{AL}(N) \setminus \mathcal{C}$, there exists $(\varphi_k)_{k \in \mathbb{N}^*} \subset (\phi_k)_{k \in \mathbb{N}^*}$ such that (BSE) is globally exactly controllable in $H_{\mathcal{G}}^{3+\epsilon} \cap \widetilde{\mathcal{H}}$ with $\epsilon > 0$ and energetically controllable in $(\frac{k^2 \pi^2}{L_j^2})_{\substack{k, j \in \mathbb{N}^* \\ j \leq N/2}}$.

Proof. Let $(\mu_k)_{k \in \mathbb{N}^*} \subset (\lambda_k)_{k \in \mathbb{N}^*}$ be eigenvalues obtained by reordering $(\frac{k^2 \pi^2}{L_j^2})_{k \in \mathbb{N}^*}$ for every $j \leq N/2$ and $(\varphi_k)_{k \in \mathbb{N}^*}$ be an orthonormal system of \mathcal{H} made by corresponding eigenfunctions. For $k \in \mathbb{N}^*$, there exist $m(k) \in \mathbb{N}^*$ and $l(k) \leq N/2$ so that $\varphi_k^n \equiv 0$ for $n \neq 2l(k), 2l(k) - 1$ and

$$\mu_k = \frac{m(k)^2 \pi^2}{L_{l(k)}^2}, \quad \varphi_k^{2l(k)-1}(x) = -\varphi_k^{2l(k)}(x) = \sqrt{\frac{1}{L_{l(k)}}} \sin(\sqrt{\mu_k} x).$$

Let $[r]$ be the entire part of $r \in \mathbb{R}^+$. For $k \in \mathbb{N}^*$ and $C = 4 \min_{l \leq N} L_l$, we have

$$\begin{aligned} |\langle \varphi_1, B\varphi_k \rangle_{L^2}| &= \left| \sum_{l=1}^N \left\langle \varphi_k^l(x), \sum_{n=1}^{N/2} \frac{L_n^{\frac{3}{2}} x^2}{L_{[(l+1)/2]}^{\frac{3}{2}}} (\varphi_1^{2n-1}(\frac{L_n}{L_{[(l+1)/2]}} x) - \varphi_1^{2n}(\frac{L_n}{L_{[(l+1)/2]}} x)) \right\rangle_{L^2(e_l)} \right| \\ &= \left| \int_0^{L_{l(k)}} \frac{4x^2 L_{l(1)}^{\frac{3}{2}}}{L_{l(k)}^{\frac{3}{2}}} \sin\left(\frac{m(1)\pi x}{L_{l(1)}}\right) \sin\left(\frac{m(k)\pi x}{L_{l(k)}}\right) dx \right| \geq C \left| \int_0^1 x^2 \sin(m(1)\pi x) \sin(m(k)\pi x) dx \right|. \end{aligned}$$

Assumptions I($\varphi, 1$) and Assumptions II($\varphi, 1, \epsilon$) with $\epsilon \in (0, \frac{1}{2})$ hold as in the proofs of Theorem 1.4 and Theorem 1.6. We consider the techniques adopted in the proof of [Duc18a, Lemma A.2] which are due to the Roth's Theorem [Duc18a, Proposition A.1]. For every $\epsilon > 0$, there exists $C > 0$ so that

$$|\mu_{k+1} - \mu_k| \geq Ck^{-\epsilon}, \quad \forall k \in \mathbb{N}^*.$$

The claim follows since the hypotheses **2.** of Theorem 6.1 are verified with $\tilde{d} = \epsilon > 0$. \square

Theorem 6.4. *Let \mathcal{G} be a compact quantum graph. Let the first $\tilde{N} \leq N$ edges $\{e_j\}_{j \leq \tilde{N}}$ of the graph be loops of lengths $\{L_j\}_{j \leq \tilde{N}}$ (e.g Figure 3). For $\psi = (\psi^1, \dots, \psi^N)$, let B be such that*

$$(B\psi)^l = \sum_{j \leq \tilde{N}} \frac{L_j^{3/2}}{L_l^{3/2}} x^2 \left(\frac{x}{L_l} - 1\right) \psi^j \left(\frac{L_j}{L_l} x\right), \quad (B\psi)^m \equiv 0, \quad \forall l \leq \tilde{N}, \quad \tilde{N} < m \leq N.$$

There exists $\mathcal{C} \subset (\mathbb{R}^+)^{\tilde{N}}$ countable so that, if $\{L_j\}_{j \leq \tilde{N}} \in \mathcal{AL}(\tilde{N}) \setminus \mathcal{C}$, then there exists $(\varphi_k)_{k \in \mathbb{N}^} \subseteq (\phi_k)_{k \in \mathbb{N}^*}$ such that (BSE) is globally exactly controllable in $H_{\mathcal{G}}^{3+\epsilon} \cup \widetilde{\mathcal{H}}$ with $\epsilon > 0$ and energetically controllable in $(\frac{k^2 \pi^2}{L_j^2})_{\substack{k, j \in \mathbb{N}^* \\ j \leq \tilde{N}}}$.*

Proof. Let $(\varphi_k)_{k \in \mathbb{N}^*}$ be such that, for each $k \in \mathbb{N}^*$, there exist $m(k) \in \mathbb{N}^*$ and $l(k) \leq \tilde{N}$ such that $\mu_k = \frac{4m(k)^2 \pi^2}{L_{l(k)}^2}$, $\varphi_k^{l(k)}(x) = \sqrt{\frac{2}{L_{l(k)}}} \sin(\sqrt{\mu_k} x)$ and $\varphi_k^n \equiv 0$ for every $n \neq l(k)$ and $n \leq N$. Now, $(\varphi_k)_{k \in \mathbb{N}^*}$ is an orthonormal system made by eigenfunctions of A and the claim yields as Theorem 6.3. \square

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A Appendix: Global approximate controllability

In the current appendix, for the sake of completeness, we propose the global approximate controllability result provided in [Duc18a, Section 4.2]. The outcome is adopted in the proof of Theorem 2.3.

Definition A.1. The (BSE) is said to be globally approximately controllable in $H_{\mathcal{G}}^s$ with $s > 0$ when, for every $\psi \in H_{\mathcal{G}}^s$, $\hat{\Gamma} \in U(\mathcal{H})$ such that $\hat{\Gamma}\psi \in H_{\mathcal{G}}^s$ and $\varepsilon > 0$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that $\|\hat{\Gamma}\psi - \Gamma_T^u \psi\|_{(s)} < \varepsilon$.

Proposition A.2. *Let (A, B) satisfy Assumptions I(η) and Assumptions II(η, \tilde{d}) for $\eta > 0$ and $\tilde{d} \geq 0$. The (BSE) is globally approximately controllable in $H_{\mathcal{G}}^s$ for $s = 2 + d$ with d from Assumptions II(η, \tilde{d}).*

Proof. In the point **1)** of the proof, we suppose that (A, B) admits a non-degenerate chain of connectness (see [BdCC13, Definition 3]). We treat the general case in the point **2)**.

1) (a) Preliminaries. Let π_m be the orthogonal projector onto $\mathcal{H}_m := \overline{\text{span}\{\phi_j : j \leq m\}}^{L^2}$ with $m \in \mathbb{N}^*$. Up to reordering $(\phi_k)_{k \in \mathbb{N}^*}$, the couples $(\pi_m A \pi_m, \pi_m B \pi_m)$ for $m \in \mathbb{N}^*$ admit non-degenerate chains of connectedness in \mathcal{H}_m . Let $\|\cdot\|_{BV(T)} = \|\cdot\|_{BV((0,T),\mathbb{R})}$ and $\|\|\cdot\|\|_{(s)} := \|\|\cdot\|\|_{L(H_{\mathcal{G}}^s, H_{\mathcal{G}}^s)}$ for $s > 0$.

Claim. $\forall \hat{\Gamma} \in U(\mathcal{H}), \forall \varepsilon > 0, \exists N_1 \in \mathbb{N}^*, \tilde{\Gamma}_{N_1} \in U(\mathcal{H}) : \pi_{N_1} \tilde{\Gamma}_{N_1} \pi_{N_1} \in SU(\mathcal{H}_{N_1}),$

$$(38) \quad \|\tilde{\Gamma}_{N_1} \phi_1 - \hat{\Gamma} \phi_1\|_{L^2} < \varepsilon.$$

Let $N_1 \in \mathbb{N}^*$ and $\tilde{\phi}_1 := \|\pi_{N_1} \hat{\Gamma} \phi_1\|_{L^2}^{-1} \pi_{N_1} \hat{\Gamma} \phi_1$. We define $(\tilde{\phi}_j)_{2 \leq j \leq N_1}$ such that $(\tilde{\phi}_j)_{j \leq N_1}$ is an orthonormal basis of \mathcal{H}_{N_1} and we complete it to $(\tilde{\phi}_j)_{j \in \mathbb{N}^*}$, an Hilbert basis of \mathcal{H} . The operator $\tilde{\Gamma}_{N_1}$ is the unitary map such that $\tilde{\Gamma}_{N_1} \phi_j = \tilde{\phi}_j$ for every $j \in \mathbb{N}^*$. The provided definition implies $\lim_{N_1 \rightarrow \infty} \|\tilde{\Gamma}_{N_1} \phi_1 - \hat{\Gamma} \phi_1\|_{L^2} = 0$. Thus, for every $\varepsilon > 0$, there exists $N_1 \in \mathbb{N}^*$ large enough satisfying the claim.

1) (b) Finite dimensional controllability. Let M_{ad} be the set of $(j, k) \in \{1, \dots, N_1\}^2$ such that $B_{j,k} := \langle \phi_j, B \phi_k \rangle_{L^2} \neq 0$ and $|\lambda_j - \lambda_k| = |\lambda_m - \lambda_l|$ with $m, l \in \mathbb{N}^*$ implies $\{j, k\} = \{m, l\}$ for $B_{m,l} = 0$. For every $(j, k) \in \{1, \dots, N_1\}^2$ and $\theta \in [0, 2\pi)$, we define $E_{j,k}^\theta$ the $N_1 \times N_1$ matrix with elements $(E_{j,k}^\theta)_{l,m} = 0, (E_{j,k}^\theta)_{j,k} = e^{i\theta}$ and $(E_{j,k}^\theta)_{k,j} = -e^{-i\theta}$ for $(l, m) \in \{1, \dots, N_1\}^2 \setminus \{(j, k), (k, j)\}$. Let $E_{ad} = \{E_{j,k}^\theta : (j, k) \in M_{ad}, \theta \in [0, 2\pi)\}$. Let $L_1 := E_{ad}$. We define by iteration $L_m := [E_{ad}, L_{m-1}] + L_{m-1}$ with $m \in \mathbb{N}^* \setminus \{1\}$ and there exists $\tilde{m} \in \mathbb{N}^*$ such that $L_{\tilde{m}} = L_{\tilde{m}+1}$ as E_{ad} is composed by $N_1 \times N_1$ matrices. We denote $Lie(E_{ad}) = L_{\tilde{m}}$. Fixed v a piecewise constant control taking value in E_{ad} and $\tau > 0$, we introduce the control system on $SU(\mathcal{H}_{N_1})$

$$(39) \quad \begin{cases} \dot{x}(t) = x(t)v(t), & t \in (0, \tau), \\ x(0) = Id_{SU(\mathcal{H}_{N_1})}. \end{cases}$$

Claim. (39) is controllable, *i.e.* for $R \in SU(\mathcal{H}_{N_1})$, there exist $p \in \mathbb{N}^*, M_1, \dots, M_p \in E_{ad}, \alpha_1, \dots, \alpha_p \in \mathbb{R}^+$ such that $R = e^{\alpha_1 M_1} \circ \dots \circ e^{\alpha_p M_p}$.

For every $(j, k) \in \{1, \dots, N_1\}^2$, we define the $N_1 \times N_1$ matrices $R_{j,k}, C_{j,k}$ and D_j as follow. For $(l, m) \in \{1, \dots, N_1\}^2 \setminus \{(j, k), (k, j)\}$, we have $(R_{j,k})_{l,m} = 0$ and $(R_{j,k})_{j,k} = -(R_{j,k})_{k,j} = 1$, while $(C_{j,k})_{l,m} = 0$ and $(C_{j,k})_{j,k} = (C_{j,k})_{k,j} = i$. Moreover, for $(l, m) \in \{1, \dots, N_1\}^2 \setminus \{(1, 1), (j, j)\}$, $(D_j)_{l,m} = 0$ and $(D_j)_{1,1} = -(D_j)_{j,j} = i$. We consider the basis of $su(\mathcal{H}_{N_1})$

$$\{R_{j,k}\}_{j,k \leq N_1} \cup \{C_{j,k}\}_{j,k \leq N_1} \cup \{D_j\}_{j \leq N_1}.$$

Thanks to [Sac00, Theorem 6.1], the controllability of (39) is equivalent to prove that $Lie(E_{ad}) \supseteq su(\mathcal{H}_{N_1})$ for $su(\mathcal{H}_{N_1})$ the Lie algebra of $SU(\mathcal{H}_{N_1})$. The claim is valid since it is possible to obtain the matrices $R_{j,k}, C_{j,k}$ and D_j for every $j, k \leq N_1$ by iterated Lie brackets of elements in E_{ad} as follows.

- For every $(j, k) \in M_{ad}$, we have $R_{j,k} = E_{j,k}^0$ and $C_{j,k} = E_{j,k}^{\pi/2}$. For every $(j, k) \notin M_{ad}$ such that there exists $j_1 \leq N_1$ so that $(j, j_1), (j_1, k) \in M_{ad}$, we have $R_{j,k} = [E_{j,j_1}^0, E_{j_1,k}^0]$ and $C_{j,k} = [E_{j,j_1}^0, E_{j_1,k}^{\pi/2}]$.
- If $(1, j) \in M_{ad}$, then $2D_j = [E_{1,j}^0, E_{1,j}^{\frac{\pi}{2}}]$, while if $(1, j) \notin M_{ad}$ and there exists $j_1 \leq N_1$ such that $(1, j_1), (j_1, j) \in M_{ad}$, then $-2D_j = \left[[E_{1,j_1}^{\frac{\pi}{2}}, E_{j_1,j}^{\frac{\pi}{2}}], [E_{1,j_1}^0, E_{j_1,j}^{\frac{\pi}{2}}] \right]$.
- For every $(j, k) \notin M_{ad}$, there exist $m \leq N_1$ and $\{j_l\}_{l \leq m}$ such that $(j, j_1), \dots, (j_m, k) \in M_{ad}$. We call $S = \{(j, j_1), \dots, (j_m, k)\}$. By repeating the previous point, we can generate each $R_{j,k}, C_{j,k}$ and D_j with $j, k \in \{1, \dots, N_1\}$ by iterating Lie brackets of $E_{l,m}^\theta$ for $(l, m) \in S$ and $\theta \in [0, 2\pi)$.

1) (c) Finite dimensional estimates. Let $\hat{\Gamma} \in U(\mathcal{H})$ and $\tilde{\Gamma}_{N_1} \in U(\mathcal{H})$ be defined in **1) (a)**. Thanks to the previous claim and to the fact that $\pi_{N_1} \tilde{\Gamma}_{N_1} \pi_{N_1} \in SU(\mathcal{H}_{N_1})$, there exist $p \in \mathbb{N}^*, M_1, \dots, M_p \in E_{ad}$ and $\alpha_1, \dots, \alpha_p \in \mathbb{R}^+$ such that

$$(40) \quad \pi_{N_1} \tilde{\Gamma}_{N_1} \pi_{N_1} = e^{\alpha_1 M_1} \circ \dots \circ e^{\alpha_p M_p}.$$

Claim. For every $l \leq p$ and $e^{\alpha_l M_l}$ from (40), there exist $\{T_n^l\}_{l \in \mathbb{N}^*} \subset \mathbb{R}^+$ and $\{u_n^l\}_{n \in \mathbb{N}^*}$ such that $u_n^l \in L^2((0, T_n^l), \mathbb{R})$ for every $n \in \mathbb{N}^*$ and

$$(41) \quad \lim_{n \rightarrow \infty} \|\Gamma_{T_n^l}^{u_n^l} \phi_k - e^{\alpha_l M_l} \phi_k\|_{L^2} = 0, \quad \forall k \leq N_1,$$

$$(42) \quad \sup_{n \in \mathbb{N}^*} \|u_n^l\|_{BV(T_n^l)} < \infty, \quad \sup_{n \in \mathbb{N}^*} \|u_n^l\|_{L^\infty((0, T_n^l), \mathbb{R})} < \infty, \\ \sup_{n \in \mathbb{N}^*} T_n^l \|u_n^l\|_{L^\infty((0, T_n^l), \mathbb{R})} < \infty.$$

We consider the results developed in [Cha12, Section 3.1 & Section 3.2] by Chambrión and leading to [Cha12, Proposition 6] since (A, B) admits a non-degenerate chain of connectedness ([BdCC13, Definition 3]). Each $e^{\alpha_l M_l}$ is a rotation in a two dimensional space for every $l \in \{1, \dots, p\}$ and this work explicits $\{T_n^l\}_{n \in \mathbb{N}^*} \subset \mathbb{R}^+$ and $\{u_n^l\}_{n \in \mathbb{N}^*}$ satisfying (42) such that $u_n^l \in L^2((0, T_n^l), \mathbb{R})$ for every $n \in \mathbb{N}^*$ and

$$(43) \quad \lim_{n \rightarrow \infty} \|\pi_{N_1} \Gamma_{T_n^l}^{u_n^l} \phi_k - e^{\alpha_l M_l} \phi_k\|_{L^2} = 0, \quad \forall k \leq N_1.$$

Now, $\lim_{n \rightarrow \infty} \|\pi_{N_1} \Gamma_{T_n^l}^{u_n^l} \phi_k\|_{L^2} = 1$ since $e^{\alpha_l M_l} \in SU(\mathcal{H}_{N_1})$. Thus, $\lim_{n \rightarrow \infty} \|(1 - \pi_{N_1}) \Gamma_{T_n^l}^{u_n^l} \phi_k\|_{L^2} = 0$ and

$$\lim_{n \rightarrow \infty} \|\Gamma_{T_n^l}^{u_n^l} \phi_k - e^{\alpha_l M_l} \phi_k\|_{L^2} \leq \lim_{n \rightarrow \infty} \left(\|\pi_{N_1} \Gamma_{T_n^l}^{u_n^l} \phi_k - e^{\alpha_l M_l} \phi_k\|_{L^2} + \|(1 - \pi_{N_1}) \Gamma_{T_n^l}^{u_n^l} \phi_k\|_{L^2} \right) = 0.$$

1) (d) Infinite dimensional estimates.

Claim. Let $\widehat{\Gamma} \in U(\mathcal{H})$. There exist $K_1, K_2, K_3 > 0$ such that for every $\varepsilon > 0$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that $\|\Gamma_T^u \phi_1 - \widehat{\Gamma} \phi_1\|_{L^2} < \varepsilon$ and

$$(44) \quad \|u\|_{BV(T)} \leq K_1, \quad \|u\|_{L^\infty((0, T), \mathbb{R})} \leq K_2, \quad T \|u\|_{L^\infty((0, T), \mathbb{R})} \leq K_3.$$

Let us assume that **1) (c)** be valid with $p = 2$. Although, the following result is valid for any $p \in \mathbb{N}^*$. As $e^{\alpha_1 M_1} \in SU(\mathcal{H}_{N_1})$, there exists $2 \leq l \leq N_1$ such that $e^{\alpha_1 M_1} \phi_1 = \phi_l$. Thanks to (41), there exists $n \in \mathbb{N}^*$ large enough such that,

$$\|\Gamma_{T_n^2}^{u_n^2} \Gamma_{T_n^1}^{u_n^1} \phi_1 - e^{\alpha_2 M_2} e^{\alpha_1 M_1} \phi_1\|_{L^2} \leq \|\Gamma_{T_n^2}^{u_n^2}\| \|\Gamma_{T_n^1}^{u_n^1} \phi_1 - e^{\alpha_1 M_1} \phi_1\|_{L^2} + \|\Gamma_{T_n^2}^{u_n^2} \phi_l - e^{\alpha_2 M_2} \phi_l\|_{L^2} < \varepsilon.$$

The identity (40) leads to the existence of $K_1, K_2, K_3 > 0$ such that for every $\varepsilon > 0$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that $\|\Gamma_T^u \phi_1 - \widetilde{\Gamma}_{N_1} \phi_1\|_{L^2} < \varepsilon$ and

$$(45) \quad \|u\|_{BV(T)} \leq K_1, \quad \|u\|_{L^\infty((0, T), \mathbb{R})} \leq K_2, \quad T \|u\|_{L^\infty((0, T), \mathbb{R})} \leq K_3.$$

The relation (38) and the triangular inequality achieve the claim.

1) (e) Approximate controllability with respect to the L^2 -norm. Let $\psi \in \mathcal{H}$ and $\widehat{\Gamma} \in U(\mathcal{H})$.

Claim. There exist $K_1, K_2, K_3 > 0$ such that for every $\varepsilon > 0$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that $\|\Gamma_T^u \psi - \widehat{\Gamma} \psi\|_{L^2} < \varepsilon$ and

$$(46) \quad \|u\|_{BV(T)} \leq K_1, \quad \|u\|_{L^\infty((0, T), \mathbb{R})} \leq K_2, \quad T \|u\|_{L^\infty((0, T), \mathbb{R})} \leq K_3.$$

We assume that $\|\psi\|_{L^2} = 1$ but the same proof is also valid in the general case. We consider the unitary propagator $\widehat{\Gamma}_t^u$ describing the reversed dynamics of the (BSE) introduced in Remark 4.1. Now, the results from [Cha12], which are adopted in the point **1) (c)**, are also valid for the reversed dynamics. Thus, such as in **1) (d)**, it is also true that, for every $\widehat{\Gamma} \in U(\mathcal{H})$, there exist $K_1, K_2, K_3 > 0$ such that for every $\varepsilon > 0$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that the relations (46) are satisfied and $\|\widetilde{\Gamma}_T^u \phi_1 - \widehat{\Gamma} \phi_1\|_{L^2} < \varepsilon$. By keeping in mind that $\widetilde{\Gamma}_T^u = (\Gamma_T^u)^{-1}$ and $\|\Gamma_T^u\| = 1$, we have

$$\|\phi_1 - \Gamma_T^u \widehat{\Gamma} \phi_1\|_{L^2} = \|\Gamma_T^u \widetilde{\Gamma}_T^u \phi_1 - \Gamma_T^u \widehat{\Gamma} \phi_1\|_{L^2} \leq \|\Gamma_T^u\| \|\widetilde{\Gamma}_T^u \phi_1 - \widehat{\Gamma} \phi_1\|_{L^2} < \varepsilon.$$

The last relation guarantees that, for every $\psi \in \mathcal{H}$ such that $\|\psi\|_{L^2} = 1$, there exist $T_1 > 0$ and $u_1 \in L^2((0, T_1), \mathbb{R})$ such that

$$\|\Gamma_{T_1}^{u_1} \psi - \phi_1\|_{L^2} < \varepsilon.$$

Now, **1) (d)** ensures that, for every $\widehat{\Gamma} \in U(\mathcal{H})$, there exist $T_2 > 0$ and $u_2 \in L^2((0, T_2), \mathbb{R})$ such that

$$\|\Gamma_{T_2}^{u_2} \phi_1 - \widehat{\Gamma} \psi\|_{L^2} < \varepsilon.$$

The chosen controls u_1 and u_2 satisfy (46). In conclusion, the claim is proved as

$$\|\Gamma_{T_2}^{u_2} \Gamma_{T_1}^{u_1} \psi - \widehat{\Gamma} \psi\|_{L^2} \leq \|\Gamma_{T_2}^{u_2} \Gamma_{T_1}^{u_1} \psi - \Gamma_{T_2}^{u_2} \phi_1\|_{L^2} + \|\Gamma_{T_2}^{u_2} \phi_1 - \widehat{\Gamma} \psi\|_{L^2} < 2\varepsilon.$$

1) (f) Global approximate controllability in higher regularity norms. Let $\psi \in H_{\mathcal{G}}^s$ with $s \in [s_1, s_1 + 2)$ and $s_1 \in \mathbb{N}^*$. Let $\widehat{\Gamma} \in U(\mathcal{H})$ be such that $\widehat{\Gamma} \psi \in H_{\mathcal{G}}^s$ and $B : H_{\mathcal{G}}^{s_1} \rightarrow H_{\mathcal{G}}^{s_1}$.

Claim. There exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that $\|\Gamma_T^u \psi - \widehat{\Gamma} \psi\|_{(s)} < \varepsilon$.

We notice that the operator $-i(A + u(t)B - ic)$ is dissipative in $H_{\mathcal{G}}^{s_1}$ for $c := \|u\|_{L^\infty((0, T), \mathbb{R})} \|B\|_{(s_1)}$. Indeed, for every $\lambda > 0$ and $\psi \in H_{\mathcal{G}}^{s_1+2}$, we have

$$\|(\lambda + i(A + u(t)B - ic))\psi\|_{(s_1)} \geq \|(\lambda + c + iA)\psi\|_{(s_1)} - \|u\|_{L^\infty((0, T), \mathbb{R})} \|B\|_{(s_1)} \|\psi\|_{(s_1)}.$$

Now, the operator A with domain $H_{\mathcal{G}}^{s_1+2}$ is self-adjoint in the Hilbert space $H_{\mathcal{G}}^{s_1}$ and we have the inequality $\|(\lambda + c + iA)\psi\|_{(s_1)} \geq (\lambda + c)\|\psi\|_{(s_1)}$. By recalling that $c = \|u\|_{L^\infty((0, T), \mathbb{R})} \|B\|_{(s_1)}$, we obtain

$$(47) \quad \|(\lambda - i(-A + u(T-t)B - ic))\psi\|_{(s_1)} \geq (\lambda + c)\|\psi\|_{(s_1)} - c\|\psi\|_{(s_1)} = \lambda\|\psi\|_{(s_1)}.$$

Thus, $-i(A + u(t)B - ic)$ is dissipative and the Kato-Rellich's Theorem yields that it is also maximal dissipative. We consider the propagation of regularity developed by Kato in the work [Kat53]. Let $\lambda > c$ and $\widehat{H}_{\mathcal{G}}^{s_1+2} := D(A^{\frac{s_1}{2}}(i\lambda - A)) \equiv H_{\mathcal{G}}^{s_1+2}$. We know that $B : \widehat{H}_{\mathcal{G}}^{s_1+2} \subset H_{\mathcal{G}}^{s_1} \rightarrow H_{\mathcal{G}}^{s_1}$ and the arguments of [Duc18b, Remark 2.1] imply that $B \in L(\widehat{H}_{\mathcal{G}}^{s_1+2}, H_{\mathcal{G}}^{s_1})$. For $T > 0$ and $u \in BV((0, T), \mathbb{R})$, we have

$$M := \sup_{t \in [0, T]} \|(i\lambda - A - u(t)B)^{-1}\|_{L(H_{\mathcal{G}}^{s_1}, \widehat{H}_{\mathcal{G}}^{s_1+2})} < +\infty.$$

We know $\|k + f(\cdot)\|_{BV((0, T), \mathbb{R})} = \|f\|_{BV((0, T), \mathbb{R})}$ for $f \in BV((0, T), \mathbb{R})$ and $k \in \mathbb{R}$. Equivalently,

$$N := \|i\lambda - A - u(\cdot)B\|_{BV([0, T], L(\widehat{H}_{\mathcal{G}}^{s_1+2}, H_{\mathcal{G}}^{s_1}))} = \|u\|_{BV(T)} \|B\|_{L(\widehat{H}_{\mathcal{G}}^{s_1+2}, H_{\mathcal{G}}^{s_1})} < +\infty.$$

We call $C_1 := \|A(A + u(T)B - i\lambda)^{-1}\|_{(s_1)} < \infty$ and U_t^u the propagator generated by $A + uB - ic$ such that $U_t^u \psi = e^{-ct} \Gamma_t^u \psi$. Thanks to [Kat53, Section 3.10], for every $\psi \in H_{\mathcal{G}}^{s_1+2}$, it follows

$$\|(A + u(T)B - i\lambda)U_t^u \psi\|_{(s_1)} \leq M e^{MN} \|(A - i\lambda)\psi\|_{(s_1)} \implies \|\Gamma_T^u \psi\|_{(s_1+2)} \leq C_1 M e^{MN+cT} \|\psi\|_{(s_1+2)}.$$

For every $T > 0$, $u \in BV((0, T), \mathbb{R})$ and $\psi \in H_{\mathcal{G}}^{s_1+2}$, there exists $C = C(K) > 0$ depending on $K = (\|u\|_{BV(T)}, \|u\|_{L^\infty((0, T), \mathbb{R})}, T\|u\|_{L^\infty((0, T), \mathbb{R})})$ such that

$$(48) \quad \|\Gamma_T^u \psi\|_{(s_1+2)} \leq C \|\psi\|_{(s_1+2)}.$$

Now, we notice that, for every $\psi \in H_{\mathcal{G}}^6$, we have $\|A\psi\|_{L^2}^2 \leq \|\psi\|_{L^2} \|A^2\psi\|_{L^2}$ from the Cauchy-Schwarz inequality and there exists $C_2 > 0$ such that $\|A^2\psi\|_{L^2}^4 \leq \|A\psi\|_{L^2}^2 \|A^3\psi\|_{L^2}^2 \leq C_2 \|\psi\|_{L^2} \|A^3\psi\|_{L^2}^3$. By following the same idea, for every $\psi \in H_{\mathcal{G}}^{s_1+2}$, there exist $m_1, m_2 \in \mathbb{N}^*$ and $C_3, C_4 > 0$ such that

$$(49) \quad \|A^{\frac{s_1}{2}} \psi\|_{L^2}^{m_1+m_2} \leq C_3 \|\psi\|_{L^2}^{m_1} \|A^{\frac{s_1+2}{2}} \psi\|_{L^2}^{m_2} \implies \|\psi\|_{(s)}^{m_1+m_2} \leq C_4 \|\psi\|_{L^2}^{m_1} \|\psi\|_{(s_1+2)}^{m_2}.$$

In conclusion, the point **1) (e)**, the relation (48) and the relation (49) ensure the claim.

1) (g) Conclusion. Let d be defined in Assumptions II(η, \tilde{d}). If $d < 2$, then $B : H_{\mathcal{G}}^2 \rightarrow H_{\mathcal{G}}^2$ and the global approximate controllability is verified in $H_{\mathcal{G}}^{d+2}$ since $d+2 < 4$. If $d \in [2, 5/2)$, then $B : H^{d_1} \rightarrow H^{d_1}$ with

$d_1 \in (d, 5/2)$ from Assumptions II(η, \tilde{d}). Now, $H_{\mathcal{G}}^{d_1} = H^{d_1} \cap H_{\mathcal{G}}^2$, thanks to [Duc18a, Proposition 3.2], and $B : H_{\mathcal{G}}^2 \rightarrow H_{\mathcal{G}}^2$ implies $B : H_{\mathcal{G}}^{d_1} \rightarrow H_{\mathcal{G}}^{d_1}$. The global approximate controllability is verified in $H_{\mathcal{G}}^{d+2}$ since $d+2 < d_1+2$. If $d \in [5/2, 7/2)$, then $B : H_{\mathcal{N}\mathcal{K}}^{d_1} \rightarrow H_{\mathcal{N}\mathcal{K}}^{d_1}$ for $d_1 \in (d, 7/2)$ and $H_{\mathcal{G}}^{d_1} = H_{\mathcal{N}\mathcal{K}}^{d_1} \cap H_{\mathcal{G}}^2$ from [Duc18a, Proposition 3.2]. Now, $B : H_{\mathcal{G}}^2 \rightarrow H_{\mathcal{G}}^2$ that implies $B : H_{\mathcal{G}}^{d_1} \rightarrow H_{\mathcal{G}}^{d_1}$. The global approximate controllability is verified in $H_{\mathcal{G}}^{d+2}$ since $d+2 < d_1+2$.

2) Generalization. Let (A, B) do not admit a non-degenerate chain of connectedness. We decompose

$$A + u(\cdot)B = (A + u_0B) + u_1(\cdot)B, \quad u_0 \in \mathbb{R}, \quad u_1 \in L^2((0, T), \mathbb{R}).$$

We notice that, if (A, B) satisfies Assumptions I(η) and Assumptions II(η, \tilde{d}) for $\eta > 0$ and $\tilde{d} \geq 0$, then [Duc18a, Lemma C.2 & Lemma C.3] are valid. We consider u_0 belonging to the neighborhoods provided by [Duc18a, Lemma C.2 & Lemma C.3] and we denote $(\phi_k^{u_0})_{k \in \mathbb{N}^*}$ a Hilbert basis of \mathcal{H} made by eigenfunctions of $A + u_0B$. The steps of the point 1) can be repeated by considering the sequence $(\phi_k^{u_0})_{k \in \mathbb{N}^*}$ instead of $(\phi_k)_{k \in \mathbb{N}^*}$ and the spaces $D(|A + u_0B|^{\frac{s_1}{2}})$ in substitution of $H_{\mathcal{G}}^{s_1}$ with $s_1 > 0$. Thanks to the mentioned results, the claim is equivalently proved since $(A + u_0B, B)$ admits a non-degenerate chain of connectedness and $\| |A + u_0B|^{\frac{s_1}{2}} \cdot \|_{L^2} \asymp \| \cdot \|_{(s_1)}$ with $s_1 \in [s, s+2)$, $s = 2 + d$ and d from Assumptions II(η, \tilde{d}). \square

By referring to Remark 4.1, we consider the reversed dynamics of the (BSE) and the unitary propagator $\tilde{\Gamma}_t^u$ generated by the time-dependent Hamiltonian $-A - u(T-t)B$ with $u \in L^2((0, T), \mathbb{R})$. In the following corollary, we present the global approximate controllability for the reversed dynamics.

Corollary A.3. *Let (A, B) satisfy Assumptions I(η) and Assumptions II(η, \tilde{d}) for $\eta > 0$ and $\tilde{d} \geq 0$. Let $s = 2 + d$ be defined by d from Assumptions II(η, \tilde{d}). For every $\psi \in H_{\mathcal{G}}^s$, $\hat{\Gamma} \in U(\mathcal{H})$ such that $\hat{\Gamma}\psi \in H_{\mathcal{G}}^s$ and $\varepsilon > 0$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that $\|\hat{\Gamma}\psi - \tilde{\Gamma}_T^u\psi\|_{(s)} < \varepsilon$.*

Proof. The proof follows from the one of Proposition A.2. First, for every $\psi \in \mathcal{H}$ and $\hat{\Gamma} \in U(\mathcal{H})$, we call $\tilde{\psi} = \hat{\Gamma}\psi$ and $\tilde{\Gamma} = (\hat{\Gamma})^{-1} \in U(\mathcal{H})$. Now, the point 1) (e) of the mentioned proof yields the existence of $K_1, K_2, K_3 > 0$ such that, for every $\varepsilon > 0$, there exist $T > 0$ and $u \in L^2((0, T), \mathbb{R})$ such that

$$\|\Gamma_T^u \tilde{\psi} - \tilde{\Gamma} \tilde{\psi}\|_{L^2} < \varepsilon$$

and the identities (46) are verified. Thanks to the relations $\tilde{\Gamma}_T^u = (\Gamma_T^u)^{-1}$ and $\|\tilde{\Gamma}_T^u\| = 1$,

$$\|\tilde{\Gamma}_T^u \psi - \hat{\Gamma}\psi\|_{L^2} = \|\tilde{\Gamma}_T^u \psi - \tilde{\Gamma}_T^u \Gamma_T^u \hat{\Gamma}\psi\|_{L^2} \leq \|\tilde{\Gamma}_T^u\| \|\psi - \Gamma_T^u \hat{\Gamma}\psi\|_{L^2} = \|\tilde{\Gamma}\tilde{\psi} - \Gamma_T^u \tilde{\psi}\|_{L^2} < \varepsilon.$$

The last relation ensures the global approximate controllability of the reversed dynamics with respect to the L^2 -norm. Second, the estimation provided in (47) is also valid for the operator $i(A + u(T-t)B + ic)$ which is dissipative in $H_{\mathcal{G}}^{s_1}$ when $B : H_{\mathcal{G}}^{s_1} \rightarrow H_{\mathcal{G}}^{s_1}$ and for $c := \|u\|_{L^\infty((0, T), \mathbb{R})} \|B\|_{(s_1)}$. The claim is ensured by repeating for the propagator $\tilde{\Gamma}_T^u$ the arguments developed in 1) (f) and in the remaining part of the proof of Proposition A.2. \square

B Appendix: Spectral properties

For $x \in \mathbb{R}$, we denote $E(x)$ the closest integer number to x , $\|x\| = \min_{z \in \mathbb{Z}} |x - z|$ and $F(x) = x - E(x)$. We notice $|F(x)| = \|x\|$ and $-\frac{1}{2} \leq F(z) \leq \frac{1}{2}$. Let $\{L_j\}_{j \leq N} \in (\mathbb{R}^+)^N$ and $i \leq N$, we also define

$$n(x) := E\left(x - \frac{1}{2}\right), \quad r(x) := F\left(x - \frac{1}{2}\right), \quad d(x) := \|x - \frac{1}{2}\|, \quad \tilde{m}^i(x) := n\left(\frac{L_i}{\pi}x\right).$$

In this appendix, we pursue [Duc18a, Appendix A], which is based on the techniques from [DZ06, Appendix A].

Lemma B.1. *Let $\{L_k\}_{k \leq N} \subset \mathbb{R}^+$, $I_1 \subseteq \{1, \dots, N\}$, $I_2 := \{1, \dots, N\} \setminus I_1$ and*

$$a(\cdot) := \prod_{i \in I_2} |\sin(\cdot L_i)| \sum_{i \in I_1} \prod_{\substack{j \in I_1 \\ j \neq i}} |\cos(\cdot L_j)| + \prod_{i \in I_1} |\cos(\cdot L_i)| \sum_{i \in I_2} \prod_{\substack{j \in I_2 \\ j \neq i}} |\sin(\cdot L_j)|.$$

Let $\{\tilde{L}_j\}_{j \leq N} \subset \mathbb{R}^+$ be such that $\tilde{L}_j = 2L_j$ when $j \in I_1$ and $\tilde{L}_j = L_j$ when $j \in I_2$. There exists $C > 0$ such that, for every $x \in \mathbb{R}$, there holds

$$a(x) \geq C \min \left(\min_{i \leq N} \prod_{j \neq i} \left\| \left(\tilde{m}^i(x) + \frac{1}{2} \right) \frac{\tilde{L}_j}{L_i} \right\|, \min_{i \leq N} \prod_{j \neq i} \left\| m^i(x) \frac{\tilde{L}_j}{L_i} \right\| \right).$$

Proof. From [DZ06, relation (A.3)], for every $x \in \mathbb{R}$, there follows

$$(50) \quad 2d(x) \leq |\cos(\pi x)| \leq \pi d(x).$$

As $2d\left(\left(\tilde{m}^i(x) + \frac{1}{2}\right) \frac{L_j}{L_i}\right) \leq \left| \cos\left(\left(\tilde{m}^i(x) + \frac{1}{2}\right) \frac{L_j}{L_i} \pi\right) \right|$ and $\tilde{m}^i(x) + \frac{1}{2} = \frac{L_i}{\pi} x - r\left(\frac{L_i}{\pi} x\right)$ for $x \in \mathbb{R}$ and $i, j \leq N$,

$$(51) \quad 2d\left(\left(\tilde{m}^i(x) + \frac{1}{2}\right) \frac{L_j}{L_i}\right) \leq |\cos(L_j x)| + \left| \sin\left(\pi \frac{L_j}{L_i} \left| r\left(\frac{L_i}{\pi} x\right) \right| \right) \right|.$$

Now, $|\sin(\pi|r(\cdot)|)| \leq \pi \||r(\cdot)\|| \leq \pi|r(\cdot)| = \pi d(\cdot) \leq \frac{\pi}{2} |\cos(\pi(\cdot))|$ thanks to [DZ06, relation (A.3)] and (50). For every $x \in \mathbb{R}$, it holds

$$(52) \quad \left| \sin\left(\pi \frac{L_j}{L_i} \left| r\left(\frac{L_i}{\pi} x\right) \right| \right) \right| \leq \pi \frac{L_j}{L_i} \left| r\left(\frac{L_i}{\pi} x\right) \right| \leq \frac{\pi L_j}{2L_i} |\cos(L_i x)|.$$

From (51) and (52), there exists $C_1 > 0$ such that, for every $i, j \leq N$,

$$(53) \quad 2d\left(\left(\tilde{m}^i(x) + \frac{1}{2}\right) \frac{L_j}{L_i}\right) \leq |\cos(L_j x)| + \frac{\pi L_j}{2L_i} |\cos(L_i x)|, \quad \forall x \in \mathbb{R}^+, \\ \implies C_1 \prod_{\substack{j \in I_1 \\ j \neq i}} d\left(\left(\tilde{m}^i(x) + \frac{1}{2}\right) \frac{L_j}{L_i}\right) \leq \prod_{\substack{j \in I_1 \\ j \neq i}} |\cos(L_j x)| + |\cos(L_i x)|.$$

From [DZ06, relation (A.3)], as done in (51) and (52), there exists $C_2 > 0$ such that

$$(54) \quad 2 \left\| \left(\tilde{m}^i(x) + \frac{1}{2} \right) \frac{L_j}{L_i} \right\| \leq |\sin(L_j x)| + \frac{\pi L_j}{2L_i} |\cos(L_i x)|, \quad \forall x \in \mathbb{R}, \\ \implies C_2 \prod_{\substack{j \in I_1 \\ j \neq i}} d\left(\left(\tilde{m}^i(x) + \frac{1}{2}\right) \frac{L_j}{L_i}\right) \prod_{\substack{j \in I_2 \\ j \neq i}} \left\| \left(\tilde{m}^i(x) + \frac{1}{2} \right) \frac{L_j}{L_i} \right\| \leq \prod_{\substack{j \in I_2 \\ j \neq i}} |\sin(L_j x)| \prod_{\substack{j \in I_1 \\ j \neq i}} |\cos(L_j x)| + |\cos(L_i x)|.$$

Now, $d(x) = \left\| \frac{1}{2}(2x - 1) \right\| \geq \frac{1}{2} \||2x - 1\|| = \frac{1}{2} \||2x\||$ for every $x \in \mathbb{R}$ and $d\left(\left(\tilde{m}^i(x) + \frac{1}{2}\right) \frac{L_j}{L_i}\right) \geq \frac{1}{2} \left\| \left(\tilde{m}^i(x) + \frac{1}{2} \right) \frac{2L_j}{L_i} \right\|$, which imply

$$(55) \quad C_2 \prod_{\substack{j \leq N \\ j \neq i}} \frac{1}{2} \left\| \left(\tilde{m}^i(\cdot) + \frac{1}{2} \right) \frac{\tilde{L}_j}{L_i} \right\| \leq a(\cdot) + |\cos(L_i(\cdot))|.$$

Equivalently, from the proof of [DZ06, Proposition A.1], for every $x \in \mathbb{R}$,

$$(56) \quad 2 \left\| m^i(x) \frac{L_j}{L_i} \right\| \leq |\sin(L_j x)| + \frac{\pi L_j}{2L_i} |\sin(L_i x)|, \quad 2d\left(m^i(x) \frac{L_j}{L_i}\right) \leq |\cos(L_j x)| + \frac{\pi L_j}{2L_i} |\sin(L_i x)|, \\ (57) \quad \implies C_2 \prod_{\substack{j \leq N \\ j \neq i}} \frac{1}{2} \left\| m^i(\cdot) \frac{\tilde{L}_j}{L_i} \right\| \leq a(\cdot) + |\sin(L_i(\cdot))|.$$

The claim follows as [DZ06, Proposition A.1]. Indeed, if $(\lambda_k)_{k \in \mathbb{N}^*} \subset \mathbb{R}^+$ is so that $a(\lambda_k) \xrightarrow{k \rightarrow \infty} 0$, then there exist some $i_0 \leq N$ such that $|\sin(\lambda_k L_{i_0})| \xrightarrow{k \rightarrow \infty} 0$ or $|\cos(\lambda_k L_{i_0})| \xrightarrow{k \rightarrow \infty} 0$. By considering (55) and (57) with $i = i_0$, we have

$$z(\lambda_k) := \min \left(\min_{i \leq N} \prod_{j \neq i} \left\| \left(\tilde{m}^i(\lambda_k) + \frac{1}{2} \right) \frac{\tilde{L}_j}{L_i} \right\|, \min_{i \leq N} \prod_{j \neq i} \left\| m^i(\lambda_k) \frac{\tilde{L}_j}{L_i} \right\| \right) \xrightarrow{k \rightarrow \infty} 0.$$

The lemma is proved since $z(\lambda_k)$ converges to 0 at least as fast as $a(\lambda_k)$ thanks (53), (54) and (56). \square

Proposition B.2. Let $\{L_j\}_{j \leq N} \subset \mathbb{R}$, $I_1 \subseteq \{1, \dots, N\}$ and $I_2 := \{1, \dots, N\} \setminus I_1$. If $\{L_j\}_{j \leq N} \in \mathcal{AL}(N)$, then, for every $\epsilon > 0$, there exists $C_\epsilon > 0$ such that, for every $x > \max\{\pi/2L_j : j \leq N\}$, we have

$$\prod_{j \in I_2} |\sin(xL_j)| \sum_{j \in I_1} \prod_{\substack{k \in I_1 \\ k \neq j}} |\cos(xL_k)| + \prod_{j \in I_1} |\cos(xL_j)| \sum_{j \in I_2} \prod_{\substack{k \in I_2 \\ k \neq j}} |\sin(xL_k)| \geq \frac{C_\epsilon}{x^{1+\epsilon}}.$$

Proof. The claim is due to Lemma B.1 and to the Schmidt's Theorem [DZ06, Theorem A.8], which implies that, for every $\epsilon > 0$ and $i \leq N$, there exist $C_1(i), C_2(i), C_3(i) > 0$ such that, for every $x \in \mathbb{R}$,

$$(58) \quad \prod_{\substack{j \leq N \\ j \neq i}} \left\| \left(\tilde{m}^i(x) + \frac{1}{2} \right) \frac{\tilde{L}_j}{L_i} \right\| \geq \frac{C_1(i)}{(2\tilde{m}^i(x) + 1)^{1+\epsilon}} \geq \frac{C_1(i)}{\left(\frac{2L_i}{\pi}x + 1\right)^{1+\epsilon}} \geq \frac{C_2(i)}{x^{1+\epsilon}}$$

and $\prod_{\substack{j \leq N \\ j \neq i}} \left\| m^i(x) \frac{\tilde{L}_j}{L_i} \right\| \geq C_3(i)x^{-1-\epsilon}$ for every $x > \frac{\pi}{2} \max\{1/L_j : j \leq N\}$. The statement follows with $C_\epsilon := \min(\min_{i \leq N} C_2(i), \min_{i \leq N} C_3(i))$. \square

Corollary B.3. Let $\{L_k\}_{k \leq N} \in \mathcal{AL}(N)$ with $N \in \mathbb{N}^*$. Let $\{\omega_n\}_{n \in \mathbb{N}^*}$ be the unbounded sequence of positive solutions of the equation

$$(59) \quad \sum_{l \leq N} \sin(xL_l) \prod_{m \neq l} \cos(xL_m) = 0, \quad x \in \mathbb{R}.$$

For every $\epsilon > 0$, there exists $C_\epsilon > 0$ so that $|\cos(\omega_n L_l)| \geq \frac{C_\epsilon}{\omega_n^{1+\epsilon}}$ for every $l \leq N$ and $n \in \mathbb{N}$.

Proof. If there exists $\{\omega_{n_k}\}_{k \in \mathbb{N}^*}$, subsequence of $\{\omega_n\}_{n \in \mathbb{N}^*}$, such that $|\cos(L_j \omega_{n_k})| \xrightarrow{k \rightarrow \infty} 0$ for some $j \leq N$, then there exists $i \leq N$ such that $i \neq j$ and $|\cos(L_i \omega_{n_k})| \xrightarrow{k \rightarrow \infty} 0$ thanks to (59). From (53), we have $\prod_{j \neq i} d\left(\left(\tilde{m}^i(\omega_{n_k}) + \frac{1}{2}\right) \frac{L_j}{L_i}\right) \xrightarrow{k \rightarrow \infty} 0$ and, as in the proof of Lemma B.1, there exists $C_2 > 0$ so that

$$C_2 |\cos(L_i \omega_n)| \geq \prod_{j \neq i} d\left(\left(\tilde{m}^i(\omega_n) + \frac{1}{2}\right) \frac{L_j}{L_i}\right) = \prod_{j \neq i} \left\| \frac{1}{2} \left(\left(\tilde{m}^i(\omega_n) + \frac{1}{2}\right) \frac{2L_j}{L_i} - 1 \right) \right\|.$$

The last identity and the techniques leading to the equation (58) achieve the claim. \square

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