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To cite this version:
Salah Naili, Christian Oddou. Buckling of a Short Cylindrical Shell Surrounded by an Elastic Medium. Journal of Applied Mechanics, 2000, 67 (1), 10.1115/1.321173. hal-01870695

HAL Id: hal-01870695
https://hal.science/hal-01870695
Submitted on 8 Sep 2018

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Buckling of a Short Cylindrical Shell Surrounded by an Elastic Medium

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The lateral surface of a cylindrical structure, which is composed of a thin tube embedded in a large outer medium, is submitted to a uniform external pressure. The buckling pressure of such a structure, corresponding to a low flexural state of the inner tube wall, is theoretically analyzed on the basis of the asymptotic method. The theoretical results are compared with experimental ones obtained from a compression test realized on an elastic tube inserted in a foam. It is found that the Euler pressure and the associated buckling mode index strongly depend upon the rheological and geometrical parameters of both the tube and the surrounding medium. {S0021-8936(00)00201-4}

1 Formulation of the Problem and Buckling Study

A nonhomogeneous cylindrical structure composed of a thin shell inserted in a surrounding elastic medium was subjected to a state of plane strain by external pressurization and zero axial longitudinal displacement constraint. The onset of the buckling process for such a structure was analyzed. The theoretical results were compared with original experimental ones as derived from a hoop compression test which was conducted with elastic rubber tubes embedded in foamy materials.

Thus, we consider the mechanical behavior of a cylindrical nonhomogeneous structure made of an internal shell confined in a large outer medium, the whole structure being submitted to a uniform pressure \( p \) on its external lateral surface. Each solid is elastic, cylindrical—of same axis—with a circular cross section in the reference configuration. In this configuration, the mean radius of the shell is denoted as \( r_0 \). The outer radius \( r_e \) of the medium is assumed to be very large compared to \( r_0 \). We will denote as \( e_0 \) the thickness of the shell. The two solids have the same height which is small in comparison with \( r_e \). The outer lateral boundary of the medium is subjected to a uniform pressure \( p \). We assume frictionless contact between the two tubes. Body forces and inertia effects are deemed to be negligibly small.

The work of Forrestal and Herrman [1] presents solutions for both bonded and smooth conditions at the shell-medium interface; it includes a geometrically nonlinear formulation for both the shell and the medium. Moore and Booker [2] presented the linear approximation of Forrestal and Herrman’s formulation. The physical unknowns which are involved in these theoretical formulations are the buckling pressure of the shell in the first work and the hoop compression stress inside this shell in the second one.

In the present work, we use the dimensionless buckling pressure of the overall structure consisting of the shell and surrounding medium developed by Razakamiadana et al. [3] and which is given by the relation

\[
\bar{p} = n^2 - 1 + \frac{\beta}{n^2 - 1},
\]

where the dimensionless variables are given as follows:

\[
\bar{p} = \frac{\alpha p_0^3}{D}, \quad \bar{\beta} = \frac{\beta p_0^4}{D},
\]

and where \( D = E_1 e_0^3/12(1 - \nu_1^2) \) is the flexural rigidity modulus of the shell, \( E_1 \) and \( \nu_1 \) being, respectively, its Young’s modulus and its Poisson’s ratio, while the index \( n \) characterizes the buckling mode. The parameters \( \alpha \) and \( \beta \) are defined by

\[
\alpha = \frac{\lambda_1 + 2 \mu_2}{\lambda_2 + \mu_2} \left( \frac{2 e_0}{r_0} \right),
\]

\[
\beta = 2 \frac{\mu_2}{r_0} \left( \lambda_2 + \mu_2 \right) \left[ \frac{n^2 - 1}{n(\lambda_1 + 2 \mu_1 + \mu_2)} \right],
\]

in which the Lame’s parameters of the shell and of the medium are denoted by \( \lambda_1, \mu_1 \) and \( \lambda_2, \mu_2 \), respectively.

In this study, we were interested in the smallest value of the buckling pressure—the Euler pressure—while varying the index \( n \) associated with the buckling mode; such a mode index characterizes the number of axes of symmetry in the actual configuration. Indeed, this minimal pressure is the most frequently observed experimentally while applying incremental loading to the structure. This pressure is expressed as

\[
p_e = \min_{n=2} \left[ \frac{1}{\alpha} \left( \frac{D}{r_0^3} + \frac{\beta r_0^4}{n^2 - 1} \right) \right].
\]

Fig. 1 Experimental apparatus for hoop compression tests. The tube inserted in the foam medium is in a buckled state with index of buckling mode equal to two.
relations of external radius \( r_e \) with a circular cross section composed by a thin rubber shell, the thickness \( \varepsilon_0 \) of the shell remains circular before undergoing a change of shape. In the extreme case corresponding to a significant variation of this shape, the relative uncertainty of area measurement was estimated to be of the order of two percent. Indeed, when the shell is "very low," the relative accuracy of the pressure measurement was repeated ten times at least and the relative gap compared to the mean value varies between 1 percent and 30 percent.

### 3 Analysis and Discussion

We show, in columns 5 and 6 of Table 1, the experimental results obtained on 110 tests implying 12 structures of different geometry and elastic properties. The results are discussed by using the dimensionless geometrical and mechanical parameters \( \bar{\varepsilon} = \varepsilon_0/r_0 \) and \( \bar{E} = E_1/E_2 \) in the case of rather thin tubes and external incompressible fluid—i.e., \( \mu_2 = 0 \) and \( \lambda_2 \to \infty \)—surrounding the shell, so that \( \alpha = 1 \) and \( \beta = 0 \) in relations (1) and (2).

#### 2 Experimental Procedure

Hoop compression tests were performed on a cylindrical structure with a circular cross section composed by a thin rubber shell, of external radius \( r_e = 13 \, \text{mm} \) which was inserted in a large foam medium of external radius \( r_e = 110 \, \text{mm} \). Both tubes had a height \( H = 30 \, \text{mm} \). The thin rubber shell was slightly stressed when inserted within the foam medium in order to establish a good contact between the two solids.

A steady loading was applied on the external lateral wall of the surrounding foam medium by means of a tire inner tube connected to a standard pressurization system. The plane strain of the structure was obtained by maintaining it between two circular and polished PMMA transparent plates. In order to avoid significant friction between the foam and the plates, the lower and upper faces of the foam were sprinkled with talc powder.

The applied pressure was measured by using a mercury U-manometer graded every 1 mm in height with a maximum reading error estimated at about 0.5 mm. When the buckling pressure is "very low," the relative accuracy of the pressure measurement was estimated at about seven percent. But, in 90 percent of the cases, the measured pressure was about 50 mm Hg and the relative uncertainty of measurement was estimated, on average, to be one percent.

With this experimental setup, several tests of compression were conducted on the structure with given geometrical and mechanical characteristics. The tested structure was submitted to a gradual and slow loading so that, for each step, the system can be considered in stationary equilibrium state. The shape of the cross section of the shell remains circular before undergoing a change of shape. We monitored the evolution of shape with a CCD camera video placed on the axis of the tubes—see Fig. 1.

The thickness \( \varepsilon_0 \) of the shell, in its reference configuration, was inferred from the mean value of the measurements conducted with a micrometer at various locations on the wall. The variations around the mean value were found to be in the order of two percent. The values of Young’s modulus of the shell and of the medium were derived from traction and compression tests, respectively applied on samples of the constitutive materials. In the different experimental setup, four types of latex foam media with different Young’s modulus and Poisson’s ratio were combined with tubes made of various PCP, PCV, or latex materials having different characteristic mechanical properties as indicated in Table 1. For the deformations up to ten percent each Young’s modulus was evaluated with a maximum error of five percent. Besides, these tests have shown that the Poisson’s ratio of the shell was about 0.5—i.e., the material is incompressible—whereas the Poisson’s ratio for the foam media were around zero.

Next, the video images were digitized and then automatically processed using a global thresholding method so as to quantify the inner cross section area of the inserted tube and to characterize its shape. The thickness \( \varepsilon_0 \) of the shell was evaluated with a maximum error of five percent. Besides, these tests have shown that the Poisson’s ratio of the shell was about 0.5—i.e., the material is incompressible—whereas the Poisson’s ratio for the foam media were around zero.

![Fig. 2 Top view of the test cell giving an illustrative example of the tube inserted in the foam medium in a buckled state with index of buckling mode equal to four.](image)

<table>
<thead>
<tr>
<th>( E ) (kPa)</th>
<th>( E_2 ) (kPa)</th>
<th>( \bar{\varepsilon} )</th>
<th>( e_0 ) (mm)</th>
<th>( p_e/E_2 \times 10^{-2} )</th>
<th>( n )</th>
<th>( p_e/E_2 \times 10^{-2} )</th>
<th>( n )</th>
</tr>
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<tr>
<td>14.50</td>
<td>100</td>
<td>0.078</td>
<td>1.00</td>
<td>(8.69 ± 0.80)</td>
<td>6</td>
<td>8.39</td>
<td>6</td>
</tr>
<tr>
<td>14.50</td>
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<td>0.189</td>
<td>2.40</td>
<td>(15.34 ± 2.19)</td>
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<td>13.00</td>
<td>2</td>
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<tr>
<td>26.07</td>
<td>79</td>
<td>0.037</td>
<td>0.46</td>
<td>(4.21 ± 0.40)</td>
<td>4</td>
<td>4.21</td>
<td>6</td>
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<tr>
<td>28.70</td>
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<td>0.105</td>
<td>1.30</td>
<td>(11.00 ± 1.00)</td>
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<td>4</td>
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<tr>
<td>28.70</td>
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<td>(12.89 ± 0.92)</td>
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<td>12.05</td>
<td>3</td>
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<tr>
<td>28.86</td>
<td>79</td>
<td>0.032</td>
<td>0.40</td>
<td>(3.98 ± 0.33)</td>
<td>3</td>
<td>4.87</td>
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<td>(6.13 ± 0.63)</td>
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<td>7.65</td>
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<tr>
<td>29.85</td>
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<td>0.46</td>
<td>(4.66 ± 0.78)</td>
<td>4</td>
<td>5.24</td>
<td>6</td>
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<tr>
<td>33.00</td>
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<td>0.032</td>
<td>0.40</td>
<td>(4.21 ± 0.21)</td>
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<td>4.79</td>
<td>6</td>
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<tr>
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<tr>
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<td>0.46</td>
<td>(11.76 ± 3.69)</td>
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<tr>
<td>175.38</td>
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<td>0.90</td>
<td>(17.69 ± 10.00)</td>
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<td>9.61</td>
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</table>
nal foamy material softer than the rubbery one of the tube. Start-
ing with Eq. (2), we determined the variations of the Euler pres-
sure $p_\varepsilon$ normalized by $E_2$—denoted as $\bar{p}_\varepsilon$—as a function of $\bar{E}$ for
various values of $\bar{\varepsilon}$. The associated buckling mode index $n$ then
depends on $\bar{E}$. It is worth noting that the assessment of the buck-
ling pressure in such an experiment was based on the variation of
a global geometrical parameter such as the area of the internal
cross section of the inserted shell—see Fig. 2. Other more sensi-
tive parameters, related to the changes in local shape properties
could, however, be envisaged but their quantification by an
image-processing system would have been more difficult to
implement.

In columns 7 and 8 of Table 1, the theoretical results are com-
pared with experimental ones. These results show that the Euler
pressures, evaluated theoretically and determined experimentally,
agree well accounting for the inherent scatter in experimental
measurements. Moreover, the mode index $n$ associated with $\bar{p}_\varepsilon$
coincides exactly for 50 percent of the cases. Nevertheless, it is
worth emphasizing that significant differences arised in the case
of very thin tubes for which the mode index are rather high, the
large number of lobes being more sensitive to small heterogene-
ities in material property and geometry. Despite this, the observed
experimental results are, in general, well reproduced by our theo-
retical model.

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