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Mechanical characterization and modeling of a Powder-In-Tube MgB_2 strand

G. Lenoir and V. Aubin

Abstract—The strain dependence of superconducting material is known to be responsible for the degradation of the electrical performance of cables. As such, their electrical optimization requires an understanding of their mechanical behavior. The present paper introduces a method for elasto-plastic modeling of commercial MgB_2 multi-filamentary strands manufactured by the ex-situ powder-in-tube method. The model is based on a simplified representation of the structure, built using components' volume fractions and nano-indentation test data. Monotonic and cyclic tension-compression tests were performed on the strands before and after chemical dissolution of the Monel outer layer to provide a multi-scale experimental database. These tests were used to identify the parameters of the kinematic and isotropic hardening laws of the elasto-plastic model. The model intends to be subsequently used to simulate the electrical behavior of cables and define guidelines for the manufacturing process, cabling process and end-product operating condition.

Index Terms—Superconducting strand, mechanical behavior, modeling, MgB_2 , Multi-scale mechanical tests.

I. INTRODUCTION

SUPERCONDUCTING cables are assemblies of twisted strands. A strand is a composite wire with superconducting filaments twisted in a metallic matrix resulting in a complex, multi-scale structure. It is well known that the strain state of the strands, depending on loading conditions, affects the electrical performance of cables [1], [2]. This dependency has been well studied since initial work by [3]. The manufacturing process, cabling process and operating conditions lead to tension-compression and bending loadings on the strands in cables [4].

The COCASCOPE project aims to model the behavior of superconducting cables at different scales for the optimization of their electrical performance. In the framework of this project, a commercial MgB_2 strand used in superconducting cables based on the "react-and-wind" process was studied. Several studies have investigated the mechanical properties of MgB_2 strands with different structures [5]-[9]. However, electrical modeling requires an accurate description of the mechanical behavior of the strand. Studies have previously been performed to model the mechanical behavior of Nb_3Sn

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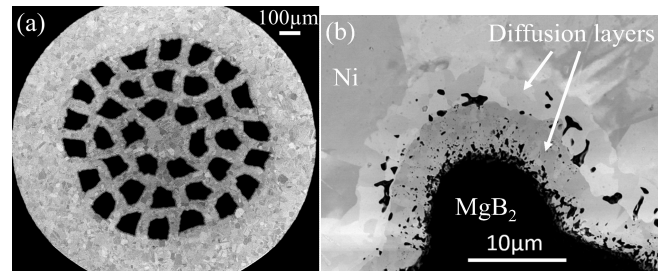


Fig.1. SEM observations of (a) the MgB_2 strand and (b) enlarged view at the interface between MgB_2 filament and Nickel matrix.

based strands using various approaches [10]-[14]. Cyclic behavior with Bauschinger effect is rarely taking into account in these models, except by [14]. In this paper, we propose a method to model the mechanical behavior of superconducting strands thorough macroscopic, mesoscopic and microscopic approaches. This method is applied to a commercial MgB_2 strand. The constitutive equations are built for future use in multi-scale finite element simulations to predict the mechanical behavior [15] or the electrical behavior [16], [17].

II. MODELING OF THE COMPOSITE STRUCTURE

A. Samples

The MgB_2 strands were manufactured by Columbus Superconductors with an ex-situ Powder-In-Tube (PIT) method. A cross-sectional image of the strand is shown in Fig. 1(a). Two strands with a diameter of 1.33mm and 1.55mm were tested. Each strand includes thirty-six MgB_2 filaments, surrounded by a Nickel inter-filamentary matrix and an outer layer of Monel. Fig. 1(b) shows two reaction layers with porosities at the interface of an MgB_2 filament and the Nickel matrix. These layers were created by diffusion of Magnesium from MgB_2 into the Nickel matrix.

B. Numerical representation of the strand

The first step of the modeling is to represent the complex composite structure of the strand by a simplified one which can be implemented in finite element simulation. To choose a well-adapted representation of the strand structure, the study of the strand components is required.

Given the small scale of the microstructure, nano-indentation tests are well-suited for characterizing the local mechanical properties of each component. During nano-indentation, a precisely-dimensioned indenter tip is pressed into the surface of the material to a pre-defined depth measured from the position of the tip and a previous definition

TABLE I
NANO-INDENTATIONS RESULTS

COMPONENTS	Num. of indents	E^1 (GPa)	SD^2 (GPa)	H^3 (GPa)	SD^2 (GPa)
Ni in matrix	513	204	7	1.6	0.1
Ni in core	144	204	5	1.7	0.2
Monel	40	170	5	2.1	0.1
Diff. layer adj. Ni	24	191	15	11	1.4
Diff. layer adj. MgB ₂	39	215	6	12	0.8

¹Elastic modulus, ²Standard Deviation and ³Nano-hardness

of the surface of the sample. The load and the penetration depth are recorded. Oliver and Pharr [18] showed that the nano-hardness H and the elastic modulus E can be determined from the indentation test load-depth curve and the geometry of the indenter. Tests were performed with a commercial nano-indenter with a Berkovich tip (three-sided diamond pyramid) and using the Continuous Stiffness Measurement (CSM) mode [19]. The indents were 200 nm in depth with a width of around 1.4 μ m. This indent size made it possible to characterize each constituent phase individually. The tests were performed in several transverse cross-sections. Table I summarizes the results with the number of indents and standard deviation for each measurement. Two diffusion layers have been characterized, one adjacent to the MgB₂ and one adjacent to the Nickel. Nano-indentation in the MgB₂ was not possible due to its porous structure. Results in the literature (E_{MgB_2} =76-172 GPa [9], [20]) show a strong dependence on the manufacturing process, material structure and measurement methods. The Young's moduli of Monel and Nickel measured by nano-indentation tests are in agreement with published values (E_{Monel} =160-185 GPa [8], [21] and E_{Ni} =186-207 GPa [9], [22]) regarding the different manufacturing processes. Nano-hardness is related to the initial size of the elastic domain and can be used to constrain the elastic limits when optimizing model parameters as described in Section III. The diffusion layers are purely elastic in the loading range but their behavior is closer to the one of Nickel than that of MgB₂.

The volume fractions of components were determined by area measurements on images of the transverse cross-section of the strand. Observations were performed both using SEM with backscattered electrons and an optical microscope. Cross-sectional samples were prepared by manual polishing followed by vibro-polishing. Table II summarizes the volume fractions obtained grouped by set. The standard deviation in Table II corresponds to the difference between measurements made on SEM and optical observations of the transverse cross-section. Porosities are observed at the interface between MgB₂ filaments and diffusion layers, as in Fig.1(b). Voids were also observed in the MgB₂ phase, due to its porous structure. For this reason, it was not possible to distinguish the volume fraction of MgB₂ and porosities. The volume fraction of the {Nickel, diffusion layers} set was calculated from the areas of the inter-filamentary zone minus the area of the {porosities, MgB₂} set.

To predict the electrical performance, the stress and strain predictions in the filaments are required. A model has thus been developed to predict the mechanical behavior of the composite strand. From the structure of the strand and the

TABLE II
VOLUME FRACTION OF MONEL, {NICKEL, DIFFUSION LAYERS} AND {POROSITIES, MgB₂}

	Monel	{Porosities, MgB ₂ }	{Nickel, diff. layers}
Average Area (mm ²)	0.728	0.225	0.419
Volume fraction f_v	0.531	0.164	0.305
Standard Deviation	1.1×10^{-3}	0.2×10^{-3}	1.3×10^{-3}

microscopic results, we defined three sets to represent the composite structure: an outer-layer set, a matrix set and a filament set. The outer-layer set is composed of the Monel and has an elasto-plastic behavior. The matrix set is composed of the diffusion layers and the Nickel. It is also modeled with an elasto-plastic constitutive law. As it was not possible to measure precisely the porosity volume fraction of the porous MgB₂ filaments the filament set is composed of both MgB₂ and porosities with an elastic behavior in the domain studied.

C. Elasto-plastic modeling

Each set has its own behavior as described above. Various approaches can be used to calculate the elasto-plastic response of a material. Plastic modulus or power laws are usually used in literature for elasto-plastic modeling of superconducting strands [10]-[13], [16]. However, this kind of model is not well-adapted to describe cyclic behavior and more particularly the Bauschinger effect. To be able to predict the cyclic response of the strand, it is necessary to introduce kinematic hardening variables [14], [23].

For a single material, the model assumes that a domain exists where the behavior remains linear elastic and can be described by Hooke's law. Once the limit of this elastic domain is reached, the behavior of the material becomes plastic. The evolution of this domain characterizes the macroscopic mechanical response of the material. A variable R characterizes the evolution of its diameter (isotropic hardening) and X the displacement of the elastic domain (kinematic hardening). The changes of these hardening variables are defined by [23]:

$$\dot{R} = b(Q - R)\dot{p} \quad (1)$$

$$\dot{X} = C\dot{\epsilon}_p - \gamma X\dot{p} \quad (2)$$

where b and γ represent the hardening rates, Q and C the saturation values and the plastic state is described by the plastic strain tensor ϵ_p and accumulated plastic strain p .

The classical von Mises criterion is selected to describe the boundary of the elastic domain. It is represented by:

$$f(\sigma, X, R) = \sqrt{\frac{3}{2}}(\mathbf{S} - \mathbf{X}) : (\mathbf{S} - \mathbf{X}) - R - \sigma_0 \leq 0 \quad (3)$$

where \mathbf{S} is the deviatoric part of the stress tensor σ and σ_0 is the initial size of the elastic domain.

D. Parallel materials consideration for composite structure

The mechanical behavior is based on a composite description of the strand in which the microstructure is shared out among three sets, as defined in Section II.B. The filament set has an elastic response in the domain studied. The elasto-plastic models for the outer layer and the matrix are calculated separately.

The composite model assumes homogeneous strain in the

strand and a stress distribution in the components that depends on component volume fractions defined as:

$$\varepsilon_s = \varepsilon_f = \varepsilon_m = \varepsilon_o \quad (4)$$

$$\sigma_s = f_v f_f \sigma_f = f_v m \sigma_m = f_v o \sigma_o \quad (5)$$

where the subscript s stands for strand, f for filament, m for matrix and o for outer layer.

III. IDENTIFICATION PROCESS

A. Step of identification process

The elasto-plastic mechanical behavior described by constitutive equation is based on kinematic and isotropic hardening laws which depend on material parameters. These parameters need to be identified by defining an inverse identification problem. The identification process uses observable variables (here stress and strain) determined from experimental data. The set of parameters retained is the one for which the comparison between the experimental response and the simulated response is considered satisfactory. The methodology is synthetized in Fig. 2.

The first step consists in calculating the response of the model to an experimental loading. It is done by numerically solving the mechanical differential systems using a fourth order Runge-Kutta method. Then the simulation is compared to the real behavior by calculating the difference between the experimental response and the calculated one. A cost function is used, defined as the normalized least square error:

$$f_{cost} = \frac{\sum (y_{exp}^2 - y_{simu}^2)}{\sum y_{exp}^2} \quad (6)$$

where y is the stress response (resp. strain) when the test is controlled in strain (resp. stress) and the subscripts exp and $simu$ mean experimental and simulated, respectively.

The identification of the material parameters consists thus in an optimization problem solved by iteratively generating a set of parameters and calculating the cost function in order to minimize it. A specific strategy of identification, detailed in Section III.B., and various optimization methods were used successively to obtain a set of parameters physically representative of the mechanical behavior of the strand and

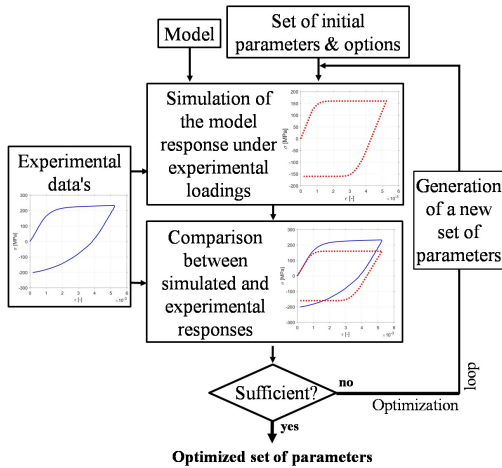


Fig. 2. Methodology of the identification process.

TABLE III ELASTIC MODULI MEASURED FROM TENSILE TESTS AND AS CALCULATED				
SAMPLES	E measured (GPa)	SD^* (GPa)	E_f calculated (GPa)	SD^* (GPa)
Complete strand	180	8.5	167	50
Inter. Filament. strand	160	8.8	78	25

*Standard Deviation

avoiding local minima.

B. Identification strategy

The material parameters of the model are

- Outer layer: $f_v o / E_o / \sigma_{yo} / b_o / Q_o / C_o / \gamma_o$,
- Filaments: $f_v f / E_f$,
- Matrix: $f_v m / E_m / \sigma_{ym} / b_m / Q_m / C_m / \gamma_m$,

where σ_y designates the yield stress of each component.

Ideally, tests would be carried out on each individual material to correctly identify their parameters. Due to the manufacturing process and their composition, the Nickel, diffusion layers and MgB_2 are not available independently. Bars of Monel having the same composition as the outer-layer specified by Columbus Superconductors have been tested. To access to the parameters of the matrix, tests on strands after dissolving the Monel outer layer, called inter-filamentary area strands, were carried out and described in Section IV.B.

The volume fractions $f_v o$, $f_v f$, $f_v m$ are measured from image analyses. Elastic moduli E_o and E_m are defined from nano-indentation tests: $E_o = E_{Monel}$ and $E_m = E_{Ni}$. Elastic limits σ_{yo} and σ_{ym} are evaluated by tests on Monel bars and inter-filamentary area strands. They will be accurately identified during the optimization process by using the nano-hardness results detailed in Table II and literature values from [26] as limits.

As MgB_2 is porous, it is not possible to measure its elastic modulus by nano-indentation tests. It has to be evaluated using the composite nature of the strand. Indeed, the elastic modulus of the filaments set E_f should verify the two following mixture laws, expressed at the strand scale (7) or at the inter-filamentary scale (8):

$$E_S = f_v f E_f + f_v o E_o + f_v m E_m \quad (7)$$

$$E_{IFA} = \frac{f_v f}{f_v f + f_v m} E_f + \frac{f_v m}{f_v f + f_v m} E_m \quad (8)$$

The elastic moduli measured on the complete strands E_S and the inter-filamentary area strands E_{IFA} allow to calculate the filament elastic modulus E_f from (7) and (8). One can observe in Table III that results do not agree. This difference may be explained by the difficulty to handle inter-filamentary strands before and during mechanical tests, which may cause more damage, and then lowers the apparent elastic modulus of the inter-filamentary strand. Nevertheless, to remain compatible with both experiments on complete and inter-filamentary area strands during the identification process, a compromise for E_f at 120 GPa has been chosen.

The volume fractions and elastic moduli remain constant during the optimization process. Several tests exploring various ranges and types of loadings were used to ensure a wide domain of prediction and the uniqueness of the set of parameters. To differentiate isotropic and kinematic hardening components for cyclic modeling, both monotonic tensile tests

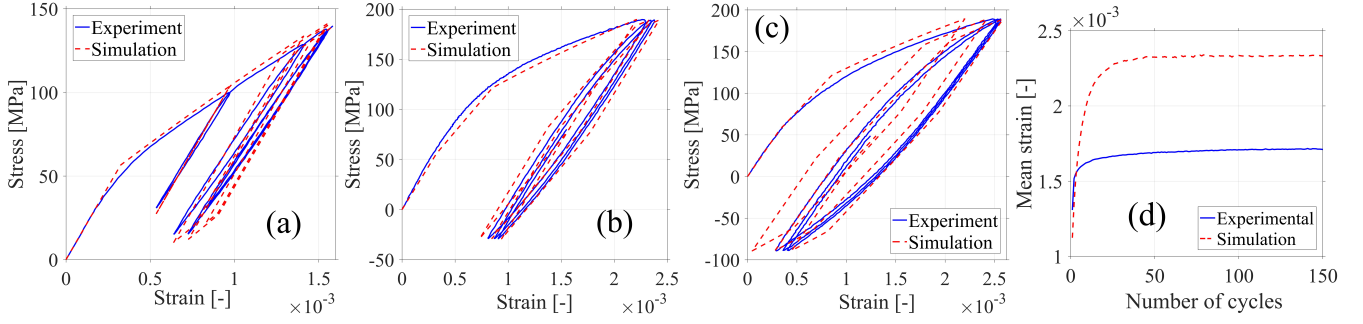


Fig. 4. Stress-strain curve of experimental and simulated results of (a) Inter-filamentary area with plastic unloads, tension-compression cyclic test on complete strand used for (b) the identification and (c) the validation. (d) Evolution of calculated and experimental mean strain of test (c) with number of cycles.

with plastic unloads and cyclic tests were used.

To ensure that each parameter of a set has a physical meaning, we identified $\sigma_{yo}/b_o/Q_o/C_o/\gamma_o$ from tests on Monel Bars and $\sigma_{ym}/b_m/Q_m/C_m/\gamma_m$ from tests on inter-filamentary area strands. A genetic algorithm [27] was used during these mesoscopic optimizations to sweep a large range of solutions and gave us an idea of the optimal parameter values. They provide us initial parameters and have enabled us to define reduced variation ranges for the parameters of the outer-layer and matrix sets for the global optimization.

Direct-search or gradient-based methods were used on the refined ranges obtained by meso-scale optimizations to find the global set of parameters representing the complete strand. The global optimization uses monotonic and cyclic tests carried out on macroscopic complete strands. This last step is required to find the final set of parameters which represents the complete composite strand.

IV. INVERSE IDENTIFICATION OF MATERIAL PARAMETERS

A. Experimental procedure

Tensile tests were carried out using a commercial electromechanical tensile test machine and a specific device to avoid any damage to the strand. The stress applied on the sample is calculated from load measurements made using a 1 kN load cell. The strain was calculated from displacement measurements made with a compact and light axial extensometer. Tests were performed at room temperature on 40 mm long strands at a strain rate of $5 \times 10^{-4} \text{ s}^{-1}$.

B. Mesoscopic scale tests and optimizations

Monotonic tensile tests were carried out on commercial 3 mm diameter Monel rods up to 15% strain and a test of one cycle of tension-compression was performed up to 0.5% strain, between $\sigma_{max}=250 \text{ MPa}$ and $\sigma_{min}=-200 \text{ MPa}$. We identified $b_o/Q_o/C_o/\gamma_o$ from these tests.

Tests on the inter-filamentary area were carried out. The sample was prepared by dissolving the Monel outer layer with a solution of HNO_3 and CH_3COOH . The parameters of the kinematic hardening law were identified by tensile tests with plastic unloads. The results show that the isotropic hardening does not exist in the domain studied. Thus, the matrix is modeled with only a kinematic hardening. Fig. 4(a) shows the experimental and simulated responses for the inter-filamentary

TABLE IV
PARAMETERS OF THE STRAND MODEL

	f_v	E (GPa)	σ_v (GPa)	b	Q	C	γ
Outer layer	0.531	170	140	0.95	2466	0.16	638
Matrix	0.305	204	66	-	-	0.29	488
Filaments	0.164	120	-	-	-	-	-

area with the retained $\sigma_{ym}/C_m/\gamma_m$ parameters.

C. Macroscopic scale and global optimization

Cyclic tests were carried out using pneumatic grips with a sufficiently short length of the strand between the grips to avoid buckling. The test was controlled in stress with a mean stress $\sigma_m=80 \text{ MPa}$ and a stress amplitude $\sigma_a=110 \text{ MPa}$. Stress-strain results are shown in Fig. 4(b) with the calculated response. The value of the parameters identified in the global optimization are summarized in Table IV.

D. Model validation using cyclic tests

To evaluate the robustness of the model, two independent cyclic tests were used. Fig. 4(c) displays the experimental and simulated stress-strain curves of a cyclic test performed at $\sigma_m=80 \text{ MPa}$ and $\sigma_a=120 \text{ MPa}$. One can observe that the strain amplitude is well predicted. However, during these tests, a plastic strain increment occurs every cycle, which is called ratchetting. Fig. 4(d) shows the evolution of the mean strain with the number of cycles for cyclic test. It can be seen that the model is able to predict the existence of such ratchetting during cyclic loading, although its level is not well described. It could be improved by adding one or more kinematic hardening terms or by modifying its constitutive law [28], at the expense of the identification cost.

V. CONCLUSION

This work presents a mechanical composite elasto-plastic modeling of MgB_2 strands based on a multi-scale characterization, an elasto-plastic calculation and a complete optimization process. The model of strand's mechanical behavior as identified has a low computation cost, it can henceforth be used for the simulation of the mechanical response of superconducting cables under loading representative of in-service conditions, which is necessary for accurately predicting their coupled electrical response.

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