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CONFIGURATIONS OF FLAGS IN ORBITS OF REAL FORMS

ELISHA FALBEL, MARCO MACULAN, AND GIULIA SARFATTI

ABSTRACT. In this paper we start the study of configurations of flags in closed orbits of real forms using mainly tools of GIT. As an application, using cross ratio coordinates for generic configurations, we identify boundary unipotent representations of the fundamental group of the figure eight knot complement into real forms of PGL(4, \mathbb{C}).

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1. INTRODUCTION

1.1. Configurations of flags. Let $n \ge 1$ be a positive integer and $V = \mathbb{C}^n$. Given integers $1 \le d \le n-1$ and $r \ge 2$, what are the possible configurations of r ordered sub-vector spaces of dimension d?

A precise way to formulate this question is to consider the Grassmannian $\operatorname{Gr}_d(V)$ of *d*-dimensional subspaces, which is a complex manifold, and study the quotient $\operatorname{Gr}_d(V)^r/\operatorname{GL}(V)$. Yet the quotient topology on $\operatorname{Gr}_d(V)^r/\operatorname{GL}(V)$ is wildly pathological.

The idea behind Geometric Invariant Theory (GIT) is to circumvent this obstacle by excluding some degenerate configurations. To describe the non-degenerate configurations, embed first the Grassmannian $\operatorname{Gr}_d(V)^r$ into the projective space $\mathbb{P}((\bigwedge^d V)^{\otimes r})$ by composing the Plücker and the Segre embedding:

$$\operatorname{Gr}_{d}(V)^{r} \xrightarrow{\operatorname{Plücker}} \mathbb{P}(\bigwedge^{d} V)^{r} \xrightarrow{\operatorname{Segre}} \mathbb{P}((\bigwedge^{d} V)^{\otimes r})$$
$$(W_{1},\ldots,W_{r}) \longmapsto (\bigwedge^{d} W_{1},\ldots,\bigwedge^{d} W_{r}) \longmapsto \bigwedge^{d} W_{1} \otimes \cdots \otimes \bigwedge^{d} W_{r}.$$

Then, the non-degenerate configurations, called semi-stable, are defined as follows: **Definition 1.1.** A point $x \in \operatorname{Gr}_d(V)^r$ is said to be *semi-stable* if there is a homogeneous polynomial on $(\bigwedge^d V)^{\otimes r}$ of positive degree which is invariant under the action of $\operatorname{SL}_n(\mathbb{C})$ and does not vanish at x.

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The subset of semi-stable points $\operatorname{Gr}_d(V)^{r,\operatorname{ss}}$ is open and contains the closure of the orbits of its points. The set Y of the closed orbits of $\operatorname{Gr}_d(V)^{r,\operatorname{ss}}$, which can be seen also as the quotient by the equivalence relation

$$x \sim x' \iff$$
 the closure of their orbits meet in $\operatorname{Gr}_d(V)^{r,\mathrm{ss}}$,

is a Hausdorff topological space. Even better, Y inherits a structure of complex algebraic variety, even though it is often singular.

A warning on notations: in the literature, both the symbols $\operatorname{Gr}_d(V)^{r,\operatorname{ss}}/\operatorname{SL}_n(\mathbb{C})$ and $\operatorname{Gr}_d(V)^{r,\operatorname{ss}}/\!\!/\operatorname{SL}_n(\mathbb{C})$ are used to indicate the quotient Y. Throughout this article, we will prefer the first, as the whole set of orbits in $\operatorname{Gr}_d(V)^{r,\operatorname{ss}}$ with its quotient topology will never be considered.

Understanding Y for n = 2 and d = 1, *i.e.* configurations of r ordered points on the complex projective line $\mathbb{P}^1(\mathbb{C})$, is a non trivial task already for r = 5 and for $r \ge 11$ a complete answer is not known¹.

The question undertaken here is different in two directions. First, instead of a single subspace of V, we consider *flags* of subspaces

$$0 \subsetneq W_1 \subsetneq W_2 \subsetneq \cdots \subsetneq W_N \subsetneq V.$$

Second, the sub-vector spaces have additional properties, like being totally isotropic with respect to a given hermitian form. The following example are studied in detail:

- (1) r couples (L_i, H_i) made of a vector line L_i and a hyperplane H_i containing it, with one of the following additional properties:
 - (a) L_i and H_i are complexifications of real sub-vector spaces of \mathbb{R}^n ;
 - (b) L_i is an isotropic line with respect to a hermitian form of signature (1, n 1), and H_i is its orthogonal.
 - An explicit description is given for r = 3, 4.
- (2) Four planes in \mathbb{C}^4 , with one of the following additional properties:
 - (a) the planes are complexifications of real sub-vector spaces of \mathbb{R}^4 ;
 - (b) the planes are totally isotropic with respect to a hermitian form of signature (2, 2);
 - (c) the planes correspond to quaternionic lines in the quaternionic plane.

The original motivation for this work was the general idea that from decorated triangulations of a manifold one obtains precise informations on representations of its fundamental group and eventually on geometric structures associated to it (see Section 6.11). A decorated triangulation of a manifold is an assignment of a configuration of flags to each simplex of the triangulation. The flags are thought to be attached to the vertices of the simplices and one imposes that the pairings between the simplices are compatible with the configurations of flags. If the stabilizer of the face configurations for each simplex is trivial one can define a representation of the fundamental group of the triangulated manifold. This was implemented in the case of surfaces in [FG07] and for 3-manifolds in [BFG14, GGZ15, DGG16]. The most studied case consists of complete flags in V acted upon by $PGL(n, \mathbb{C})$. In the case of 3-manifolds, it was observed in certain cases (see [Fal08, FKR15, FST15]), that if the decoration has values in configurations in an orbit of a real form then the 3-manifold has a geometric structure whose holonomy coincides with the representation obtained from the decorated triangulation. This justifies the search of decorated triangulations with values in configurations of real flags.

In computations, coordinates for generic configurations of flags [FG07, BFG14, GGZ15] were used to obtain a census of decorated triangulations (see [FKR15,

¹The quotient Y/\mathfrak{S}_r is described by the ring of invariants of *binary quantics*: it is the ring of polynomials in the variables a_0, \ldots, a_r that are invariant under the action of $\mathrm{SL}_2(\mathbb{C})$ on $\mathbb{C}[a_0, \ldots, a_r]$ defined by $(g \cdot f)(x, y) = f(g^{-1}(x, y))$ where $g \in \mathrm{SL}_2(\mathbb{C})$ and $f = \sum_i a_i x^{r-i} y^i$.

C]). We will describe these coordinates (Section 6) defined on an open set of the configuration space and obtain, in these coordinates, the projection onto the previous spaces of partial flags configurations (see Propositions 6.8 and 6.11). This allows us to write equations for configurations to be in real orbits in the cases of PU(n, 1) and all real forms of $PGL(4, \mathbb{C})$. In the last section we explain the use of decorated triangulations to obtain representations with values in real forms. Finally, from the computation of boundary unipotent generically decorated representations of the fundamental group of the figure eight knot obtained in [C], we obtain that the only one of these representations decorated by configurations in a real orbit (for a real form of $PGL(4, \mathbb{C})$) is a representation into SO(3, 1) (see Proposition 7.3).

1.2. The role of real GIT. Let G_0 be a real form of $\mathrm{SL}_n(\mathbb{C})$. The Cartan involution associated with G_0 allows to define a real algebraic group G whose real points $G(\mathbb{R})$ are naturally identified with G_0 , and the complex points $G(\mathbb{C})$ with $\mathrm{SL}_n(\mathbb{C})$.

Given integers $0 < d_1 \leq \cdots \leq d_N < n$, the group G_0 acts on the flag variety $\operatorname{Flag}_d(V)$ of flags of V of type $d = (d_1, \ldots, d_N)$. A theorem of J. Wolf ([Wol69]) asserts that there exists a unique closed orbit F_0 of G_0 in $\operatorname{Flag}_d(V)$, and

(1.2.1)
$$\dim_{\mathbb{R}} F_0 \ge \dim_{\mathbb{C}} \operatorname{Flag}_d(V).$$

Moreover, equality comes exactly when there is a flag $x \in \operatorname{Flag}_d(V)$ whose stabilizer $\operatorname{Stab}_{\operatorname{GL}(V)}(x)$ is stable under the Cartan involution defining G_0 . If this is the case, the stabilizer $\operatorname{Stab}_{\operatorname{GL}(V)}(x)$ is the group of complex points of a parabolic subgroup P of the real algebraic G, and the real projective variety F := G/P verifies $F(\mathbb{R}) = F_0$ and $F(\mathbb{C}) = \operatorname{Flag}_d(V)$.

The map induced between quotients,

$$F_0^r/G_0 \longrightarrow \operatorname{Flag}_d(V)^r/\operatorname{SL}_n(\mathbb{C}),$$

is in general far from being injective, and inequality (1.2.1) propagates to the quotient: there are dense open subsets $U_0 \subset F_0^r/G_0$ and $U \subset \operatorname{Flag}_d(V)^r/\operatorname{SL}_n(\mathbb{C})$ that are respectively a real and a complex manifold, and

$$\dim_{\mathbb{R}} U_0 \geq \dim_{\mathbb{C}} U,$$

with equality precisely when $\dim_{\mathbb{R}} F_0 = \dim_{\mathbb{C}} \operatorname{Flag}_d(V)$.

In this paper we work under the hypothesis $\dim_{\mathbb{R}} F_0 = \dim_{\mathbb{C}} \operatorname{Flag}_d(V)$. As explained above, the closed orbit F_0 is the set of real points of a real projective variety F whose complex points are identified with $\operatorname{Flag}_d(V)$. The problem of studying the quotient F_0^r/G_0 can be approached from the point of view of real Geometric Invariant Theory, as developed by Luna, Birkes, Richardson-Slodowy ([Lun75], [Lun76], [Bir71], [RS90]).

Let $X := F^r$. The set of semi-stable points of $X(\mathbb{C}) = \operatorname{Flag}_d(V)^r$ is stable under complex conjugation and defines a Zariski open subset X^{ss} . Unwinding the definitions, a point x of $X(\mathbb{R}) = F_0^r$ is semi-stable if it is so as a point of $\operatorname{Flag}_d(V)^r$ under the action of $\operatorname{SL}_n(\mathbb{C})$. The GIT quotient of X^{ss} by G inherits the structure of a real projective variety Y: the set of its complex points is the set of closed orbits of $\operatorname{SL}_n(\mathbb{C})$ in $X^{\operatorname{ss}}(\mathbb{C}) = \operatorname{Flag}_d(V)^r$.

However, the set of real points does not necessarily verify the analogous property for real points. To be more precise let us introduce the set $X^{ss}(\mathbb{R})/G(\mathbb{R})$ of closed $G(\mathbb{R})$ -orbits in $X(\mathbb{R})$: following Luna, since the set of all $G(\mathbb{R})$ -orbits is not so interesting, in this paper we reserve the symbol $X^{ss}(\mathbb{R})/G(\mathbb{R})$ for the set of closed orbits.

Theorem 1.2. With the notations introduced above, the following holds:

(1) for $x \in X^{ss}(\mathbb{R})$ there is a unique closed $G(\mathbb{R})$ -orbit contained in

$$G(\mathbb{R}) \cdot x \cap X^{\mathrm{ss}}(\mathbb{R});$$

(2) the set $X^{ss}(\mathbb{R})/G(\mathbb{R})$, endowed with the quotient topology given by seeing it as the quotient by the equivalence relations

$$x \sim x' \Longleftrightarrow \overline{G(\mathbb{R}) \cdot x} \cap \overline{G(\mathbb{R}) \cdot x'} \cap X^{\mathrm{ss}}(\mathbb{R}) \neq \emptyset,$$

is Hausdorff and compact;

(3) the natural map $\theta: X^{ss}(\mathbb{R})/G(\mathbb{R}) \longrightarrow Y(\mathbb{R})$ is proper, with finite fibres and open onto its image.

The map θ is neither injective nor surjective in general, as the examples discussed in this text show. The openness of θ is proved in Section 3 as we are unable to retrieve this statement from the literature.

1.3. Statement of the results.

1.3.1. Arrangements of flags line-hyperplane. In the first example we study configurations of flags of the type (L, H) where L is a line of V and H is a hyperplane containing it.

We consider the following two real forms of $SL_n(\mathbb{C})$ admitting a parabolic subgroup stabilizing such a flag:

- (a) the split form $SL_n(\mathbb{R})$;
- (b) the special unitary group SU(1, n-1) with respect to a hermitian form on V of signature (1, n-1).

A r-tuple $\{(L_i, H_i)\}_{i=1,...,r}$ of flags line-hyperplane is semi-stable if and only if there exists a permutation $\sigma \in \mathfrak{S}_r$ (necessarily without fixed points) such that, for all i = 1, ..., r, the line L_i is not contained in $H_{\sigma(i)}$.

To a fixed-point free permutation σ , called also derangement, one associates an invariant s_{σ} consisting in evaluating a linear form defining the hyperplane $H_{\sigma(i)}$ on a generator of the line L_i .

Through the invariants s_{σ} , the GIT quotient $Y_{n,r}$ of $\operatorname{Flag}_{1,n-1}(V)^{r,ss}$, which is a variety of dimension

$$r^{2} - 3r + 1 - \min\{0, n - r\}^{2},$$

is embedded in the projective space $\mathbb{P}^{!r-1}(\mathbb{C})$ where !r is the number of derangements in \mathfrak{S}_r . Similarly to the factorial of a number, for $r \geq 3$ the number of derangements satisfies the recurrence relation

$$!r = (r-1)(!(r-1)+!(r-2)).$$

In particular !3 = 2 (the only derangements being the two 3-cycles) and !4 = 9.

- $Y_{n,3} = \mathbb{P}^1(\mathbb{C})$ and the quotient map is given by the triple ratio;
- For r = 4 and $n \ge 4$, $Y_{n,4}$ is the complete intersection in $\mathbb{P}^8(\mathbb{C})$ of the quadrics

 $x_1x_5 = x_3x_4,$ $x_1x_9 = x_2x_7,$ $x_5x_9 = x_6x_8.$

If n = 3 the quotient $Y_{3,4}$ is a hyperplane section of the previous variety. Let $\{(L_i, H_i)\}_{i=1,...,r}$ be a *r*-tuple of flags. If $n \ge r$, it is said to be in *general* position if the following properties are satisfied:

- (1) $\dim L_1 + \dots + L_r = r;$
- (2) dim $H_1 \cap \cdots \cap H_r = n r;$
- (3) $L_i \cap H_j = 0$ whenever $i \neq j$;
- (4) $(L_1 + \cdots + L_r) \cap H_1 \cap \cdots \cap H_r = 0.$

If r > n, the *r*-tuple is in general position if every subset of *n* elements verifies the previous conditions.

When n = 3 the flags of the type line-hyperplane are complete flags. The notion of "general position" then competes with that of "generic configurations of flags" of Goncharov. However, we show in Example 6.6 (see also Proposition 4.8)

that the orbits of generic configurations are not necessarily closed. In this sense, configurations in general position are better behaved with respect to GIT.

Consider the real form $G_0 = \operatorname{SL}_n(\mathbb{R})$ and the associated real algebraic group $G = \operatorname{SL}_{n,\mathbb{R}}$. The set of real points of the associated flag variety F is the set of (L, H) where L is a real line of \mathbb{R}^n and H is a real hyperplane containing it. Let U be the open subset of $X = F^r$ made of configurations of flags in general position.

Theorem 1.3. With the notations introduced above, the map

$$\theta: U(\mathbb{R})/\operatorname{SL}_n(\mathbb{R}) \longrightarrow \mathbb{P}^{!r-1}(\mathbb{R}),$$

induced by the invariants s_{σ} , is

- injective if n is odd or n > r;
- two-to-one if n is even and $n \ge r$.

This lack of injectivity can be prevented by taking the quotient by the group $\operatorname{GL}_n(\mathbb{R})$ instead of $\operatorname{SL}_n(\mathbb{R})$.

Consider the special unitary group SU(1, n-1) with respect to a hermitian form h of signature (1, n-1). The unique closed orbit F_0 in $\operatorname{Flag}_{1,n-1}(V)$ is made of couples (L, H) where L is an isotropic line and H its orthogonal: therefore F_0 can be identified with the set of isotropic lines in V. Consider the open subset $W \subset F_0^{r,ss}$ made of r-tuples of lines L_1, \ldots, L_r generating a space of dimension ≥ 3 .

Theorem 1.4. The map $\theta: W/SU(1, n-1) \to \mathbb{P}^{!r-1}(\mathbb{R})$ induced by the invariants s_{σ} is injective.

As the case r = 3 shows, the map θ on the complement of W is not injective, so that the preceding theorem is sharp. Nonetheless, a more precise statement is proved when r is odd. A r-tuple $x = (L_1, \ldots, L_r)$ of isotropic lines is seen to be semi-stable if and only if none of them is repeated more than r/2 times. Pick for every line L_i a generator v_i and, for a derangement σ , set

$$\varepsilon_{\sigma}(x) = \prod_{i=1}^{r} h(v_i, v_{\sigma(i)}).$$

Note that $\varepsilon_{\sigma}(x)$ is the complex conjugated of $\varepsilon_{\sigma^{-1}}(x)$. Let D be a subset of the derangements of \mathfrak{S}_r with !r/2 elements and the property: $\sigma \in D \Rightarrow \sigma^{-1} \notin D$.

Theorem 1.5. With the notations introduced above, the map

$$\varepsilon \colon F_0^{r,\mathrm{ss}}(\mathbb{R})/\mathrm{SU}(1,n-1) \longrightarrow (\mathbb{C}^{!r/2} \setminus \{0\})/\mathbb{R}_{>0}$$

defined by sending a point $F_0^{r,ss}(\mathbb{R})$ to the open ray generated by $(\varepsilon_{\sigma}(x))_{\sigma\in D}$, is injective.

1.3.2. Four planes. The second example studies the real forms G_0 of $SL_4(\mathbb{C})$ admitting a parabolic subgroup P stabilizing a plane in \mathbb{C}^4 . There are three (isomorphism classes) of this kind:

- (a) the split form $SL_4(\mathbb{R})$;
- (b) the special unitary group SU(2,2) with respect to a hermitian form on C⁴ of signature (2,2);
- (c) if \mathbb{H} denotes the Hamilton quaternions, the group $SL_2(\mathbb{H})$ of \mathbb{H} -linear automorphisms of \mathbb{H}^2 whose associated complex matrix has determinant 1^2 .

$$m(q) := \begin{pmatrix} a+bi & c+di \\ -c+di & a-bi \end{pmatrix}.$$

 $^{^2 \}text{To}$ a quaternion $q = a + bi + cj + dk \in \mathbb{H}$ one can associate the 2×2 matrix with complex entries

A quadruple (W_1, W_2, W_3, W_4) of complex planes of \mathbb{C}^4 is semi-stable with respect to $\mathrm{SL}_4(\mathbb{C})$ if and only $W_{\sigma(1)} \cap W_{\sigma(2)} = 0$ and $W_{\sigma(3)} \cap W_{\sigma(4)} = 0$ for some permutation $\sigma \in \mathfrak{S}_4$.

The GIT quotient of $\operatorname{Gr}_2(\mathbb{C}^4)^{\operatorname{ss}}$ by $\operatorname{SL}_4(\mathbb{C})$ is the complex projective plane $\mathbb{P}^2(\mathbb{C})$, and the quotient map is given by 3 invariants s_{1234} , s_{1324} and s_{1423} : for a semi-stable quadruple of planes (W_1, W_2, W_3, W_4) and for basis w_{i1}, w_{i2} of W_i , the invariant s_{1234} is defined as the product of determinants

$$s_{1234} = \det(w_{11}, w_{12}, w_{21}, w_{22}) \cdot \det(w_{31}, w_{32}, w_{41}, w_{42})$$

The invariants s_{1324} and s_{1423} are defined similarly.

For a real form G_0 of $SL_4(\mathbb{C})$ among the ones mentioned above, let G the be associated real reductive groupe, F the flag variety G/P and $X = F^4$. The GIT quotient Y of X^{ss} by G is a form of the projective space, *i.e.* it becomes isomorphic to $\mathbb{P}^2(\mathbb{C})$ as soon as one extends scalars to \mathbb{C} .

In other words, it is a Severi-Brauer variety: it is the "trivial" one, that is, the one isomorphic to $\mathbb{P}^2_{\mathbb{R}}$ as a real algebraic variety. In particular, $Y(\mathbb{R}) = \mathbb{P}^2(\mathbb{R})$.

Theorem 1.6. With the notations introduced above, consider the natural map

$$\theta \colon F_0^{4,\mathrm{ss}}/G(\mathbb{R}) \longrightarrow \mathbb{P}^2(\mathbb{R}).$$

Then, in cases (a) and (b) it is bijective (thus a homeomorphism). In case (c) it is injective and its image is the set of points $[t_0 : t_2 : t_2] \in \mathbb{P}^2(\mathbb{R})$ satisfying the inequality

$$t_0^2 + t_1^2 + t_2^2 \le 2(t_0t_1 + t_1t_2 + t_0t_2).$$

The results are better resumed in the following table:

G_0	F_0	$F_0^{4,\mathrm{ss}}/G_0$
$\mathrm{SL}_4(\mathbb{R})$	$\{\text{real planes in } \mathbb{R}^4\}$	$\mathbb{P}^2(\mathbb{R})$
SU(2,2)	{totally isotropic planes}	$\mathbb{P}^2(\mathbb{R})$
$\mathrm{SL}_2(\mathbb{H})$	{quaternionic lines in \mathbb{H}^2 }	closed interior in $\mathbb{P}^{2}(\mathbb{R})$ of the conic $t_{0}^{2} + t_{1}^{2} + t_{2}^{2} \leq 2(t_{0}t_{1} + t_{1}t_{2} + t_{0}t_{2})$

In case (c), if the four quaternionic lines are pairwise distinct, the projection on the quotient makes intervene the quaternionic cross-ratio studied in [BG09, GL12].

1.4. **Organization of the paper.** In Section 2 we recall some basic facts on real algebraic groups and flag varieties. In Section 3 we pass in review GIT over the real numbers. In Section 4 we treat the example of flags line-hyperplane. In Section 5, the case of four plane is treated. In Section 6 the link with generic configurations of flags is studied, while in the last section we discuss the relation with decorated representations.

1.5. Acknowledgements. We thank Claudio Gorodski, Antonin Guilloux, Greg Kuperberg and Maxime Wolff for several discussions.

$$\begin{pmatrix} q_1 & q_2 \\ q_3 & q_4 \end{pmatrix} \in \mathrm{GL}_2(\mathbb{H})$$

belongs to $SL_2(\mathbb{H})$ if and only if the associated 4×4 matrix with complex coefficients,

$$\begin{pmatrix} m(q_1) & m(q_2) \\ m(q_3) & m(q_4) \end{pmatrix},$$

has determinant 1. If $q_1 \neq 0$ this is equivalent to saying that the norm of $q_1q_4 - q_1q_3q_1^{-1}q_2$ is 1.

This induces an isomorphism of non-commutative \mathbb{C} -algebras $m: H \otimes_{\mathbb{R}} \mathbb{C} \to \text{End}(\mathbb{C}^2)$. A 2 × 2 matrix with quaternionic coefficients,

2. Conventions and reminders

2.1. **Real algebraic varieties.** In this paper we try not to confuse algebraic varieties with their set of points: while it may seem pedantic in the complex case, it is worth it in the real one. If X is a complex algebraic variety, its set complex points is denoted by $X(\mathbb{C})$; if X is real the set of its real points is denoted by $X(\mathbb{R})$, its complexification $X_{\mathbb{C}}$ and its complex points $X(\mathbb{C})$. The set of complex (resp. real) points will be always endowed with its natural complex (resp. real) topology.

For a positive integer $n \ge 1$ the *n*-dimensional affine space is denoted \mathbb{A}^n , the *n*-dimensional projective space \mathbb{P}^n . The associated real/complex points are

$$\begin{split} \mathbb{A}^{n}(\mathbb{R}) &= \mathbb{R}^{n}, \\ \mathbb{P}^{n}(\mathbb{R}) &= (\mathbb{R}^{n} \smallsetminus \{0\}) / \mathbb{R}^{\times}, \end{split} \qquad \qquad \mathbb{A}^{n}(\mathbb{C}) &= \mathbb{C}^{n}, \\ \mathbb{P}^{n}(\mathbb{C}) &= (\mathbb{C}^{n} \smallsetminus \{0\}) / \mathbb{C}^{\times}. \end{split}$$

If we want to insist on the field of definition we write $\mathbb{A}^n_{\mathbb{R}}$, $\mathbb{A}^n_{\mathbb{C}}$, $\mathbb{P}^n_{\mathbb{R}}$ or $\mathbb{P}^n_{\mathbb{C}}$.

The datum of a quasi-projective real algebraic variety X is equivalent to the datum of a complex algebraic variety $X_{\mathbb{C}}$ (its *complexification*) together with an anti-holomorphic involution τ_X such that there exists a locally closed embedding $\varepsilon \colon X \to \mathbb{P}^n_{\mathbb{C}}$ verifying, for all $x \in \mathbb{P}^n(\mathbb{C})$,

$$\varepsilon(\tau_X(x)) = \overline{\varepsilon(x)},$$

where, for a complex number $z \in \mathbb{C}$, \overline{z} stands for its conjugate and, for a point $x = [x_0 : \cdots : x_n] \in \mathbb{P}^n(\mathbb{C}),$

$$\bar{x} = [\bar{x}_0 : \dots : \bar{x}_n]$$

This is equivalent to asking that the polynomials defining $X_{\mathbb{C}}$ in $\mathbb{P}^n_{\mathbb{C}}$ have real coefficients.

A map $f: X \to Y$ between real algebraic varieties is a complex algebraic map $f_{\mathbb{C}}: X_{\mathbb{C}} \to Y_{\mathbb{C}}$ compatible with the anti-holomorphic involutions τ_X, τ_Y of X, Y, that is, $\tau_Y \circ f_{\mathbb{C}} = f_{\mathbb{C}} \circ \tau_X$.

2.2. Real algebraic groups and forms. A real algebraic group is an algebraic variety G together with maps

$$\operatorname{mult}: G \times_{\mathbb{R}} G \to G,$$
$$\operatorname{inv}: G \to G,$$

defining respectively the group law and the inverse, and a point $e \in G(\mathbb{R})$. The datum is supposed to verify the usual relations [Bor91, Chapter I, §1.5].

Given a complex algebraic group G, a real form of G is a real algebraic group H whose complexification $H_{\mathbb{C}}$ is isomorphic to G. It is well known that real forms do not need to be isomorphic. For instance, the following real algebraic groups defined as closed subvarieties of $\mathbb{A}^2_{\mathbb{P}}$,

$$\mathbb{G}_m : xy = 1,$$
 $U(1) : x^2 + y^2 = 1$

are isomorphic over \mathbb{C} (this is seen taking the change of coordinates $x \mapsto x + iy$, $y \mapsto x - iy$) but not over \mathbb{R} .

Some words on notation. The multiplicative group is denoted \mathbb{G}_m . At the level of real or complex points one has

$$\mathbb{G}_m(\mathbb{R}) = \mathbb{R}^{\times}, \qquad \qquad \mathbb{G}_m(\mathbb{C}) = \mathbb{C}^{\times}$$

If the field of definition is not clear from the context, we specify it by writing $\mathbb{G}_{m,\mathbb{R}}$ or $\mathbb{G}_{m,\mathbb{C}}$. Similarly for the general linear group: GL_n denotes the algebraic group, $\mathrm{GL}_n(\mathbb{R})$ and $\mathrm{GL}_n(\mathbb{C})$ the groups over matrices, $\mathrm{GL}_{n,\mathbb{R}}$ and $\mathrm{GL}_{n,\mathbb{C}}$ respectively the real and complex algebraic group. For a real algebraic group G, we denote by G_0 the set of its real points $G(\mathbb{R})$. A connected complex algebraic group is said to be reductive if every representation is completely reducible: for every algebraic representation $G \to \operatorname{GL}(V)$ and every *G*-stable subspace $W \subset V$ there exists a *G*-stable complement W'. This is equivalent to the fact that the complex Lie group $G(\mathbb{C})$ contains a Zariski-dense compact subgroup. A semi-simple group is a reductive group whose center is finite.

A real algebraic group is said to be reductive (resp. semi-simple) if its complexification is reductive (resp. semi-simple).

2.3. **Parabolic subgroups.** A subgroup P of a complex reductive group is said to be parabolic if the quotient variety G/P is projective.

A parabolic subgroup of a real reductive group G is an algebraic subgroup Pwhose complexification $P_{\mathbb{C}}$ is a parabolic subgroup of $G_{\mathbb{C}}$. The quotient is then a projective real algebraic variety. A complex parabolic subgroup Q of $G_{\mathbb{C}}$ is the complexification of a real parabolic subgroup of G if and only if the dimension of Qequals the dimension of the real Lie group $Q(\mathbb{C}) \cap G(\mathbb{R})$. Over both real and complex numbers, two parabolic subgroups are said to be opposite if their intersection is a common Levi factor. This turns out to be equivalent to say that their intersection is of minimal dimension.

Let G be a real or complex reductive group and let P be a parabolic subgroup of G. Then there is a parabolic subgroup $P_{\rm op}$ opposite to P. Moreover the subset $\operatorname{Opp}(P)$ of $X = G/P_{\rm op}$ made of points $x \in X$ whose stabilizer is a parabolic subgroup opposite to P is Zariski open. Let $x_{\rm op} \in X$ be point associated to $P_{\rm op}$. The natural map

$$\begin{array}{rccc} P & \longrightarrow & \operatorname{Opp}(P) \\ g & \longmapsto & gx_{\operatorname{op}} \end{array}$$

induces an isomorphism

$$\operatorname{rad}^{u} P \xrightarrow{\sim} \operatorname{Opp}(P).$$

Example 2.1. Let V be a finite-dimensional real or complex vector space. A parabolic subgroup of GL(V) is the subgroup stabilizing a flag of vector subspaces

$$F_{\bullet}: 0 \subset F_1 \subset F_2 \subset \cdots \subset F_r,$$

(the inclusions are strict). Conversely the stabilizer of a flag is a parabolic subgroup of $\operatorname{GL}(V)$. Let $F_{\bullet} = (F_i)_{i=1,\ldots,r}$ be a flag and $P = \operatorname{Stab}(F_{\bullet})$ its stabilizer. Set $d_i = \dim F_i$ for all $i = 1, \ldots, r$. Then the projective variety $\operatorname{GL}(V)/P$ is the variety of flags $\operatorname{Flag}(d_1, \ldots, d_r)$.

Example 2.2 (Incidence variety). Let $V = \mathbb{C}^n$. The *incidence variety* is the flag variety $\operatorname{Flag}_{(1,n-1)}$ of couples (L, H) made of a line $L \subset V$ and of a hyperplane $H \subset \operatorname{containing} L$.

It can be seen as a subvariety of $\mathbb{P}(V) \times \mathbb{P}(V^*)$ sending a couple (L, H) to the couple (L, H^{\perp}) where H^{\perp} is the set of linear forms vanishing on H. The equation is

$$\phi_1 x_1 + \dots + \phi_n x_n = 0,$$

where $x = (x_1, \ldots, x_n) \in V$ and $\phi = \phi_1 e_1^* + \cdots + \phi_n e_n^*$ (here e_1^*, \ldots, e_n^* is the dual basis of standard one of \mathbb{C}^n).

Example 2.3 (Klein quadric). Let $V = \mathbb{C}^4$. The flag manifolds correspondences are gathered in the following diagram:



Consider the Grassmannian $\operatorname{Gr}(2,4)$ of planes in V. Through the Plücker embedding

$$\begin{array}{rcl} \operatorname{Gr}(2,4) & \longrightarrow & \mathbb{P}(\bigwedge^2 V) \\ W & \longmapsto & \bigwedge^2 W, \end{array}$$

it can be seen as subvariety of $\mathbb{P}(\bigwedge^2 V)$. The wedge product induces a nondegenerate quadratic form on $\bigwedge^2 V$,

$$\begin{array}{rccc} Q \colon \bigwedge^2 V & \longrightarrow & \bigwedge^4 V \\ & w & \longmapsto & w \wedge w \end{array}$$

and Gr(2, 4) is the quadric given by the equation Q = 0. It is classically known as *Klein's quadric*. Let e_1, \ldots, e_4 be the standard basis of V and fix $e_1 \wedge e_2 \wedge e_3 \wedge e_4$ as basis of $\bigwedge^4 V$. Writing a vector $w \in \bigwedge^2 V$ as

$$w = \sum_{1 \le i < j \le 4} w_{ij} e_i \wedge e_j,$$

one obtains

$$Q(w) = w \wedge w = w_{12}w_{34} - w_{13}w_{24} + w_{14}w_{23},$$

recovering the classical equation of Klein's quadric.

2.4. Galois cohomology. Let G be an affine real algebraic group. A *(right) principal homogenous G-space* is a non-empty real algebraic variety P endowed with a (right) action of G such that the map

$$P \times_{\mathbb{R}} G \longrightarrow P \times_{\mathbb{R}} P$$
$$(p,g) \longmapsto (p,pg),$$

is an isomorphism. A principal homogeneous G-space is trivial if $P(\mathbb{R}) \neq \emptyset$.

The set of isomorphism classes of principal homogeneous G-spaces is denoted $\mathrm{H}^1(\mathbb{R}, G)$. It can be computed also as the set of 1-cocyles $\mathrm{H}^1(\mathrm{Gal}(\mathbb{C}/\mathbb{R}), G(\mathbb{C}))$ (see [Ser94, Chapitre III]). The set $\mathrm{H}^1(\mathbb{R}, G)$ is finite [Ser94, Chapitre III, Théorème 4] and is pointed by considering the class of trivial principal homogeneous spaces.

Theorem 2.4. Let $n \ge 1$ be an integer. Then $H^1(\mathbb{R}, \operatorname{GL}_n) = 0$.

Let $f: G \to G'$ a map of affine real algebraic groups and P a right principal homogenous G-space. Then the quotient $(P \times_{\mathbb{R}} G')/G$ of $P \times_{\mathbb{R}} G'$ by the (left) action $g(g', p) = (f(g)g', pg^{-1})$ of G exists as a real algebraic variety and is a principal homogenous G'-space. This construction leads to a map of pointed sets

$$\mathrm{H}^{1}(\mathbb{R},G) \longrightarrow \mathrm{H}^{1}(\mathbb{R},G').$$

Suppose G acts on affine variety X. Let $x \in X(\mathbb{R})$ and $T = G \cdot x$ be its orbit (as a real algebraic variety). Then $T(\mathbb{R})$ is not necessarily made of one single $G(\mathbb{R})$ orbit. For $x' \in T(\mathbb{R})$ consider the transporter

$$\operatorname{Trans}(x, x') = \{g \in G : gx = x'\}$$

It is a principal homogeneous G_x -space where G_x is the stabilizer of x. This leads to a map

$$\delta \colon T(\mathbb{R}) \longrightarrow \mathrm{H}^{1}(\mathbb{R}, G_{x}).$$

Proposition 2.5. The map δ induces a bijection

$$T(\mathbb{R})/G(\mathbb{R}) \xrightarrow{\sim} \ker(\mathrm{H}^1(\mathbb{R}, G_x) \to \mathrm{H}^1(\mathbb{R}, G)).$$

In particular, if $\mathrm{H}^{1}(\mathbb{R}, G) = 0$ then $T(\mathbb{R})/G(\mathbb{R}) \simeq \mathrm{H}^{1}(\mathbb{R}, G_{x})$.

Proof. The maps δ fits into the following exact sequence of pointed sets (see [Ser94, Chapitre I §5.4 Proposition 36]):

$$1 \longrightarrow G_x(\mathbb{R}) \longrightarrow G(\mathbb{R}) \longrightarrow T(\mathbb{R}) \longrightarrow \mathrm{H}^1(\mathbb{R}, G_x) \longrightarrow \mathrm{H}^1(\mathbb{R}, G).$$

In particular,

$$T(\mathbb{R})/G(\mathbb{R}) \xrightarrow{\sim} \ker(\mathrm{H}^1(\mathbb{R}, G_x) \to \mathrm{H}^1(\mathbb{R}, G)).$$

3. GIT OVER THE COMPLEX AND THE REAL NUMBERS

3.1. The complex affine case. Let G be a complex reductive group acting on an affine variety X. Geometric Invariant Theory (GIT) deals with the problem of constructing a quotient of X by G as an algebraic variety.

One cannot expect the underlying topological space of the putative quotient to be the quotient of X by $G(\mathbb{C})$ as a topological space, as the latter is too non separated in general to be an algebraic variety. For instance, looking at the action of $\mathbb{G}_{m,\mathbb{C}}$ on $\mathbb{A}^2_{\mathbb{C}}$ by t(x,y) = (tx,ty), one sees that the origin lies in the closure of every orbit.

Instead, consider the \mathbb{C} -algebra A of regular functions of X and denote by A^G the sub- \mathbb{C} -algebra of G-invariant elements.

Theorem 3.1. The \mathbb{C} -algebra A^G is finitely generated. Let $Y = \operatorname{Spec} A^G$. Then, the morphism $\pi \colon X \to Y$ induced by the inclusion $A^G \subset A$ enjoys the following properties:

(1) π is G-invariant et surjective;

(2) if $F \subset X$ is a Zariski closed G-stable subset, then $\pi(F) \subset Y$ is closed;

(3) let $x, x' \in X(\mathbb{C})$; then $\pi(x) = \pi(x')$ if and only if

$$\overline{G \cdot x} \cap \overline{G \cdot x'} \neq \emptyset;$$

(4) if $U \subset X$ is a Zariski open G-saturated³, then $\pi(U)$ is Zariski open in Y;

(5) the homomorphism of sheaves $\pi^* \colon \mathcal{O}_Y \to \pi_*\mathcal{O}_X$ induces an isomorphism

$$\pi^* \colon \mathcal{O}_Y \xrightarrow{\sim} (\pi_* \mathcal{O}_X)^G.$$

This makes Y the *categorical quotient* of X by G in the category of complex algebraic varieties: for every complex algebraic variety Z and every G-invariant map $f: X \to Z$ there exists a unique map $\tilde{f}: Y \to Z$ such that $f = \tilde{f} \circ \pi$.

The quotient Y is called the *GIT quotient* of X by G and denoted by X/G^4 .

³That is, for every $x \in X(\mathbb{C})$, the closure of the orbit $G(\mathbb{C}) \cdot x$ is contained in $U(\mathbb{C})$.

⁴As already mentioned in the Introduction, a competing symbol in the literature is $X/\!\!/G$.

$$\sum_{i,j} a_{ij} x^i y^j \longmapsto \sum_{i,j} a_{ij} t^{i+j} x^i y^j.$$

No non-constant polynomial invariant is left invariant. In other terms, the quotient of $\mathbb{A}^2_{\mathbb{C}}$ by \mathbb{G}_m is a point.

Example 3.3. Let $n \ge 1$ be an integer and $M_{n,\mathbb{C}}$ be the space of $n \times n$ matrices. The group $GL_{n,\mathbb{C}}$ acts on it by conjugation. For a matrix $A \in M_n(\mathbb{C})$ let

$$P_A(T) := \det(T \cdot \operatorname{id}_n - A) = T^n - \sigma_1(A)T^{n-1} + \dots + (-1)^n \sigma_n(A),$$

be the characteristic polynomial of A. The map

$$\begin{array}{cccc} \sigma \colon \mathrm{M}_{n,\mathbb{C}} & \longrightarrow & \mathbb{A}^n_{\mathbb{C}} \\ & A & \longmapsto & (\sigma_1(A), \dots, \sigma_n(A)), \end{array}$$

is $\operatorname{GL}_{n,\mathbb{C}}$ -invariant and makes $\mathbb{A}^n_{\mathbb{C}}$ the GIT quotient of $\operatorname{M}_{n,\mathbb{C}}$ by $\operatorname{GL}_{n,\mathbb{C}}$ (see [MS72, Proposition 2]).

3.2. The real affine case. Let X be an affine real algebraic variety acted upon by a real reductive group G. Let A denote de \mathbb{R} -algebra of regular functions on X. Then G acts on the \mathbb{R} -algebra A and we consider the sub- \mathbb{R} -algebra A^G of G-invariants elements.

Theorem 3.4. The \mathbb{R} -algebra A^G is finitely generated. Let $Y = \operatorname{Spec} A^G$. Then, the morphism $\pi \colon X \to Y$ induced by the inclusion $A^G \subset A$ enjoys the following properties:

(1) π is G-invariant et surjective;

(2) if $F \subset X$ is a Zariski closed G-stable subset, then $\pi(F) \subset Y$ is closed;

(3) let $x, x' \in X(\mathbb{C})$; then $\pi(x) = \pi(x')$ if and only if

$$\overline{G(\mathbb{C})\cdot x}\cap\overline{G(\mathbb{C})\cdot x'}\neq\emptyset;$$

(4) if $U \subset X$ is a Zariski open G-saturated, then $\pi(U)$ is Zariski open in Y; (5) we have $A^G \otimes_{\mathbb{R}} \mathbb{C} = (A \otimes_{\mathbb{R}} \mathbb{C})^{G_{\mathbb{C}}}$.

Proof. See [GIT, Theorem 1.1].

The real algebraic variety Y is called the *GIT quotient* of X by G and is denoted X/G.

Remark 3.5.

- (1) While stating (2) we did not specify whether the closure is taken with respect to the Zariski or the usual topology: this does not matter as those closures coincide (see [Ser56]).
- (2) Statement (2) implies that, given a point $x \in X(\mathbb{C})$, there exists a unique closed orbit contained in $\overline{G(\mathbb{C}) \cdot x}$.
- (3) Statement (5) can be restated by saying that $Y_{\mathbb{C}}$ is the GIT quotient of $X_{\mathbb{C}}$ by $G_{\mathbb{C}}$.
- (4) Statements (3) and (4) still hold when we replace the Zariski topology by the usual one, e.g. if $F \subset X(\mathbb{C})$ is a closed $G(\mathbb{C})$ -stable subset, then $\pi(F)$ is closed in $Y(\mathbb{C})$.

The task undertaken in this section is to understand what happens at the level of real points. Luna [Lun75, Lun76], Birkes [Bir71], Richardson-Slodowy [RS90] and others have extensively studied the problem and the following results will be of particular interest for us:

Theorem 3.6. With the notations introduced above, let $x \in X(\mathbb{R})$. Then the following hold:

- the unique closed orbit contained in the closure of G(C) ⋅ x has a real point. In particular, it is defined over R.
- (2) the orbit $G(\mathbb{R}) \cdot x$ is closed if and only if $G(\mathbb{C}) \cdot x$ is closed;
- (3) the closure of $G(\mathbb{R}) \cdot x$ in $X(\mathbb{R})$ contains a unique closed orbit;
- (4) if $F \subset X(\mathbb{R})$ is a closed $G(\mathbb{R})$ -stable subset then $\pi(F)$ is closed in $Y(\mathbb{R})$.

Proof. (1) See [Kem78, Corollary 4.4]. The argument ultimately relies on the existence of rational destabilizing one parameter subgroups, which is due to Birkes [Bir71, Theorem 5.2] over the real numbers whether, over an arbitrary perfect field, is due to Kempf [Kem78, Theorem 4.2] and Rousseau [Rou81].

(2) Suppose that the orbit $G(\mathbb{C}) \cdot x$ is not closed. Then by [Kem78, Theorem 4.2] there exists a one parameter subgroup $\lambda \colon \mathbb{G}_{m,\mathbb{R}} \to G$ such that the point

$$x_0 := \lim_{t \to 0} \lambda(t) \cdot x \in X(\mathbb{R}),$$

belongs to the unique closed orbit contained in $G(\mathbb{C}) \cdot x$. Thus x_0 lies in the closure of the map $\mathbb{R}^{\times} \to X(\mathbb{R}), t \mapsto \lambda(t) \cdot x$ and $G(\mathbb{R}) \cdot x$ is not closed.

(3) To avoid the smoothness assumption in [Lun75, Théorème 2.7], take a closed G-equivariant embedding of X in $\mathbb{A}^n_{\mathbb{R}}$ and apply the cited result to $\mathbb{A}^n_{\mathbb{R}}$.

(4) See [Lun75, Lemme 2.6] or [RS90, Proposition 6.8].

In order to complete the analogy with the complex case we prove the following:

Theorem 3.7. With the notations introduced above, the following hold:

- (1) if $U \subset X(\mathbb{R})$ is a $G(\mathbb{R})$ -saturated⁵ open subset, then $\pi(U)$ is open in the image $\pi(X(\mathbb{R}))$;
- (2) if $V \subset Y$ is a Zariski open subset such that the induced map

 $\pi \colon U := \pi^{-1}(V) \longrightarrow V,$

is smooth, then $\pi(U(\mathbb{R}))$ is a finite union of connected components of $V(\mathbb{R})$. In particular, if $W \subset V(\mathbb{R})$ is a connected component, either it is contained in $\pi(X(\mathbb{R}))$ or it does not meet $\pi(X(\mathbb{R}))$.

This statement is probably known to experts in GIT over \mathbb{R} . Nonetheless we could not find it stated as it is, so we give a proof of it. Before doing this, let us illustrate the theorem through two examples.

Example 3.8. Let $X = \mathbb{A}^1_{\mathbb{R}}$ be the affine line endowed with the action of $G = \{\pm id\}$ defined by $\pm id \cdot x = \pm x$. Then the GIT quotient Y is again $\mathbb{A}^1_{\mathbb{R}}$ and the quotient map is $\pi(x) = x^2$. In particular, we have

$$\pi(\mathbb{R}) = \mathbb{R}_+$$

so that $\pi(X(\mathbb{R}))$ cannot be open in $Y(\mathbb{R})$ in general.

Remark that, if $V = Y \setminus \{0\}$, then $V(\mathbb{R})$ has exactly two connected components,

$$W_+ = \mathbb{R}_{>0}, \quad W_- = \mathbb{R}_{<0}$$

one contained in the image and the other not meeting it.

Example 3.9. One may wonder whether in the previous example the non-openness of the image of $X(\mathbb{R})$ in $Y(\mathbb{R})$ were due to the fact that G is not connected. This is not true.

⁵That is, for every $x \in U(\mathbb{R})$ the closure of the orbit $G(\mathbb{R}) \cdot x$ is contained in $U(\mathbb{R})$.

Indeed, let G denote the real form of SL_2 whose real points are

$$G(\mathbb{R}) = \operatorname{SU}(2) = \left\{ \begin{pmatrix} a & -\overline{b} \\ b & \overline{a} \end{pmatrix} : a, b \in \mathbb{C}, |a|^2 + |b|^2 = 1 \right\}$$

The GIT quotient of X = G under the action of G by conjugation is the affine $\mathbb{A}^1_{\mathbb{R}}$ and the quotient map is the trace (*cf.* Example 3.3): for $a, b \in \mathbb{C}$ such that $|a|^2 + |b|^2 = 1$,

$$\pi \begin{pmatrix} a & -\bar{b} \\ b & \bar{a} \end{pmatrix} = a + \bar{a} = 2 \operatorname{Re}(a),$$

hence $\pi(SU(2)) = [-2, 2]$. The points ± 2 correspond to the points where the trace map is not smooth.

Proof of Theorem 3.7. Let $U \subset X(\mathbb{R})$ be an open $G(\mathbb{R})$ -saturated subset. The naive argument would go as follows.

Consider the complement $F = X(\mathbb{R}) \setminus U$ of U: it is a closed $G(\mathbb{R})$ -stable subset of $X(\mathbb{R})$, hence its image in $Y(\mathbb{R})$ is closed. Nonetheless it may happen that $\pi(F)$ and $\pi(U)$ meet. Indeed, if $T \subset X$ is a closed G-orbit, then $T(\mathbb{R})$ may be made of more than one $G(\mathbb{R})$ -orbit (see Example 3.12 for instance). Then it can occur that one of these $G(\mathbb{R})$ -orbits lies in U and another in the complement F. For this reason the argument is more involved.

(1) Let $U \subset X(\mathbb{R})$ be an open $G(\mathbb{R})$ -saturated subset and let $x \in X(\mathbb{R})$. One has to show that $\pi(U)$ contains an open neighborhood of $\pi(x)$ in $\pi(X(\mathbb{R}))$.

First of all, one may suppose that the orbit $G(\mathbb{R}) \cdot x$ is closed. If this is not the case, consider the unique closed orbit contained in $\overline{G(\mathbb{R}) \cdot x}$. The latter belongs to U because is $G(\mathbb{R})$ -saturated.

From now on assume that the $G(\mathbb{R})$ -orbit of x is closed. By Luna's Slice Étale Theorem [Lun73], there exists an affine locally closed complex subvariety Z of $X_{\mathbb{C}}$ containing x, stable under the action of the stabilizer G_x of x, and such that

$$W = \{g \cdot z \in X_{\mathbb{C}} : g \in G, z \in Z\},\$$

is a $G_{\mathbb{C}}$ -saturated Zariski open subset of $X_{\mathbb{C}}$. Moreover the induced map between GIT quotients $\phi: V/G_x \to \pi(W)$ is étale. Clearly, up to taking V smaller, one may suppose that it is defined over \mathbb{R} : it suffices to consider $V \cap \overline{V}$ where $\overline{V} \subset X_{\mathbb{C}}$ is the conjugated variety.

It is now possible to conclude the argument. Let $p: V \to V/G_x$ be the quotient map. The open subset $U \cap V(\mathbb{R})$ of $V(\mathbb{R})$ is $G_x(\mathbb{R})$ -saturated. Remark that it suffices to prove that $p(U \cap V(\mathbb{R}))$ contains an open neighborhood of p(x) in $p(V(\mathbb{R}))$. This is because the map ϕ is étale, hence an open map at the level of real points [MB12, Proposition 2.2.1].

The complement $F = V(\mathbb{R}) \setminus U$ of U in $V(\mathbb{R})$ is a closed $G_x(\mathbb{R})$ -stable subset, thus its image in $(V/G_x)(\mathbb{R})$ is closed by Theorem 3.6. It remains to show that p(x) belongs to the open subset

$$p(V(\mathbb{R})) \smallsetminus p(F)$$

of $p(V(\mathbb{R}))$. Suppose the contrary. Then there would exist a point $y \in F$ such that p(y) = p(x), that is, $\{x\}$ would be the unique closed $G_x(\mathbb{R})$ -orbit contained in the closure of $G_x(\mathbb{R}) \cdot y$. Since F is closed, this would imply that x belongs to F, leading to a contradiction.

(2) Let us consider a Zariski open subset V of Y such that the induced map

$$\pi: U := \pi^{-1}(V) \longrightarrow V,$$

is smooth. Then, the induced map at the level of real points is open [MB12, Proposition 2.2.1]. Moreover, $U(\mathbb{R})$ is a $G(\mathbb{R})$ -saturated open subset by definition and if $F \subset U(\mathbb{R})$ is a closed $G(\mathbb{R})$ -stable subset then its image in $V(\mathbb{R})$ is closed

(cover V by affine open subsets to reduce to the case of Theorem 3.6). In particular, the image of $U(\mathbb{R})$ is open and closed in $V(\mathbb{R})$.

As said before for $x \in X(\mathbb{R})$ there exists a unique closed $G(\mathbb{R})$ -orbit contained in the closure of $G(\mathbb{R}) \cdot x$. Therefore the space of $G(\mathbb{R})$ -orbits does not have that much interest. The notation $X(\mathbb{R})/G(\mathbb{R})$ will be reserved for the set of closed $G(\mathbb{R})$ -orbits. Consider the map

$$p: X(\mathbb{R}) \longrightarrow X(\mathbb{R})/G(\mathbb{R}),$$

sending a point x to the unique closed $G(\mathbb{R})$ -orbit contained in $\overline{G(\mathbb{R})} \cdot x$. Endow the set $X(\mathbb{R})/G(\mathbb{R})$ with the finest topology such that p is continuous: this is obtained declaring a subset $V \subset X(\mathbb{R})/G(\mathbb{R})$ open if $p^{-1}(V)$ is an open subset of $X(\mathbb{R})$. Since for a point $x \in X(\mathbb{R})$ the orbit $G(\mathbb{R}) \cdot x$ is closed if and only if $G(\mathbb{C}) \cdot x$ is closed, one obtains a map

$$\theta \colon X(\mathbb{R})/G(\mathbb{R}) \longrightarrow Y(\mathbb{R}),$$

whose image is contained in $\pi(X(\mathbb{R}))$.

Proposition 3.10. With the notations introduced above:

- (1) the topological space $X(\mathbb{R})/G(\mathbb{R})$ is Hausdorff and locally compact;
- (2) the map θ is proper with finite fibers and open onto its image;
- (3) $X(\mathbb{R})/G(\mathbb{R})$ is the categorical quotient of $X(\mathbb{R})$ by $G(\mathbb{R})$ in the category of Hausdorff spaces: for all Hausdorff topological space Z and all $G(\mathbb{R})$ invariant continuous map $f: X(\mathbb{R}) \to Z$ there exists a unique continuous map $\tilde{f}: X(\mathbb{R})/G(\mathbb{R}) \to Z$ such that $f = \tilde{f} \circ p$.

Remark 3.11.

- (1) Statement (3) characterizes $X(\mathbb{R})/G(\mathbb{R})$ up to a unique homeomorphism. The quotient $X(\mathbb{R})/G(\mathbb{R})$ is called the *separated quotient* of $X(\mathbb{R})$ by $G(\mathbb{R})$.
- (2) The Hausdorff topological space X(R)/G(R) is more generally the quotient of X(R) by G(R) in the category of T₁ topological spaces, that is, topological spaces whose points are closed (these are also called "accessible", "Fréchet" or "Tikhonov").

Proof. (1) See [RS90, Theorem 7.6]⁶ and [RS90, Proposition 7.4].

(2) Openness of the map θ is a reformulation of Theorem 3.7. If $x \in X(\mathbb{R})$ has closed orbit $T = G \cdot x$ then, by Proposition 2.5,

$$#\theta^{-1}(\pi(x)) = #T(\mathbb{R})/G(\mathbb{R}) = # \ker(\mathrm{H}^1(\mathbb{R}, G_x) \to \mathrm{H}^1(\mathbb{R}, G)),$$

where G_x stands for the stabilizer of x. In particular $f^{-1}(\pi(x))$ is a finite set.

(3) For $x \in X(\mathbb{R})$ set $\tilde{f}(p(x)) = f(x)$. The map \tilde{f} is well-defined: if x' lies in the unique closed $G(\mathbb{R})$ -orbit contained in $\overline{G(\mathbb{R}) \cdot x}$ then f(x) = f(x'). To show that \tilde{f} is continuous, remark that for an open subset $U \subset Z$,

$$f^{-1}(U) = p^{-1}(\tilde{f}^{-1}(U)),$$

is an open $G(\mathbb{R})$ -saturated subset. In particular $\tilde{f}^{-1}(U)$ is open.

Example 3.12. Consider the action of $G = \operatorname{SL}_{2,\mathbb{R}}$ by conjugation on itself. Then the GIT quotient of $X = \operatorname{SL}_{2,\mathbb{R}}$ by G is $\mathbb{A}^1_{\mathbb{R}}$ and the quotient map is given by the trace (*cf.* Example 3.3):

$$\begin{array}{rccc} \mathrm{Ir}\colon \mathrm{SL}_{2,\mathbb{R}} & \longrightarrow & \mathbb{A}^1_{\mathbb{R}} \\ & A & \longmapsto & \mathrm{Tr}\,A \end{array}$$

⁶The space $X(\mathbb{R})/G(\mathbb{R})$ being Hausdorff is due to Luna (see [RS90, 7.3.3]). However the techniques employed by Richardon and Slodowy permit to give a proof of this which does not have recourse to Luna's Slice Étale theorem (see [RS90, §9]).

For a real matrix $A \in SL_2(\mathbb{R})$ three cases need to be distinguished:

- $|\operatorname{Tr}(A)| > 2$: the matrix A is diagonalisable over \mathbb{R} with distinct eigenvalues. The G-orbit $G \cdot A$ is closed and its real points consists of one $G(\mathbb{R})$ -orbit.
- $|\operatorname{Tr}(A)| = 2$: the matrix A has one real eigenvalue of multiplicity 2 but may be not diagonalisable. Anyway the unique closed orbit in the closure of $G \cdot A$ is {id} if $\operatorname{Tr}(A) = 2$ and it is {-id} if $\operatorname{Tr}(A) = -2$.
- $|\operatorname{Tr}(A)| < 2$: the matrix A is a rotation of angle $\theta \not\equiv 0 \pmod{\pi \mathbb{Z}}$. Since elements in $\operatorname{SL}_2(\mathbb{R})$ respect the orientation of \mathbb{R}^2 , the matrices A and A^{-1} cannot lie on the same $G(\mathbb{R})$ -orbit. On the other hand it is easily seen that these are the unique two $G(\mathbb{R})$ -orbits.

The situation can be depicted as follows:



3.3. The complex projective case. Let G be a complex reductive group acting on a projective variety X. In order to be led back to the affine case, let L be a G-linearized ample line bundle on X ([GIT, §1.3]). A G-linearized very ample line bundle is equivalent to the a G-equivariant closed embedding $\iota: X \to \mathbb{P}(V)$, where G acts linearly on V.⁷

Even with this supplementary hypothesis, one cannot hope to obtain theorems analogous to the one in the affine case. For instance, letting $\mathbb{G}_{m,\mathbb{C}}$ acting on the projective line $\mathbb{P}^1_{\mathbb{C}}$ by $t[x:y] = [tx:t^{-1}y]$, both 0 and ∞ lie in the closure of the orbit of 1.

To avoid such a situation one has to restrict itself to consider just an open subset of X.

Definition 3.13. A point $x \in X(\mathbb{C})$ is said to be *semi-stable* with respect to G and L if there exists a positive integer $d \ge 1$ and a G-invariant section $s \in \mathbb{H}^0(X, L^{\otimes d})$ not vanishing at x. The subset of semi-stable points is denoted X^{ss} ; it is open in X.

Consider the graded \mathbb{C} -algebra of finite type

$$A := \bigoplus_{d>0} \mathrm{H}^0(X, L^{\otimes d}),$$

and its sub- \mathbb{C} -algebra of G-invariant elements,

$$A^G := \bigoplus_{d \ge 0} \mathrm{H}^0(X, L^{\otimes d})^G.$$

Theorem 3.14. The graded \mathbb{C} -algebra A^G is finitely generated. Consider the projective variety $Y = \operatorname{Proj}(A^G)$.

Then, the inclusion $A^G \subset A$ induces a morphism $\pi \colon X^{ss} \to Y$ satisfying the following properties:

⁷Under this correspondence $L = \iota^* \mathcal{O}(1)$ and $V = \mathrm{H}^0(X, L)^*$.

- (1) π is G-invariant and surjective;
- (2) let $x, x' \in X^{ss}(\mathbb{C})$; then $\pi(x) = \pi(x')$ if and only if

$$\overline{G \cdot x} \cap \overline{G \cap x'} \cap X^{\mathrm{ss}} \neq \emptyset;$$

- (3) if $F \subset X^{ss}$ is a Zariski closed G-stable subset, then $\pi(F)$ is Zariski closed in Y;
- (4) if $U \subset X$ is a Zariski open G-saturated subset, then $\pi(U)$ is Zariski open;
- (5) the homomorphism of sheaves $\pi^* : \mathcal{O}_Y \to \pi_* \mathcal{O}_{X^{ss}}$ induces an isomorphism

$$\pi^*\colon \mathcal{O}_Y \xrightarrow{\sim} (\pi_*\mathcal{O}_{X^{\mathrm{ss}}})^G$$

The projective variety Y is called the *GIT quotient* of X^{ss} by G and denoted X^{ss}/G .⁸

Example 3.15. Let $\mathbb{G}_{m,\mathbb{C}}$ act on $X = \mathbb{P}^1_{\mathbb{C}}$ by $t[x : y] = [tx : t^{-1}y]$. The set of semi-stable points is $X \setminus \{0, \infty\}$, so that the orbit of 1 is closed in X^{ss} and the quotient is a point.

Example 3.16. Let $M_{n,\mathbb{C}}$ be the space of $n \times n$ matrices. Then $GL_{n,\mathbb{C}}$ acts on $\mathbb{P}(M_n(\mathbb{C}))$ by conjugation and a matrix $A \in M_n(\mathbb{C})$ is semi-stable if and only if its characteristic polynomial is not T^n , that is, A is not nilpotent (*cf.* Example 3.3).

3.4. The real projective case. Let X be a real projective variety and let G be a reductive group acting on X. Let L be a G-linearized ample line bundle on X. We consider the open subset X^{ss} (resp. X^{s}) of X made of semi-stable (resp. stable) points with respect to the action of G and the polarization L. Consider the graded \mathbb{R} -algebra

$$A := \bigoplus_{d \ge 0} \operatorname{H}^0(X, L^{\otimes d}),$$

and its sub- \mathbb{R} -algebra of G-invariant elements,

$$A^G := \bigoplus_{d \ge 0} \mathrm{H}^0(X, L^{\otimes d})^G.$$

Theorem 3.17. The graded \mathbb{R} -algebra A^G is finitely generated. Consider the real projective variety $Y = \operatorname{Proj}(A^G)$.

Then, the inclusion $A^G \subset A$ induces a morphism $\pi \colon X^{ss} \to Y$ satisfying the following properties:

- (1) π is G-invariant and surjective;
- (2) let $x, x' \in X^{ss}(\mathbb{C})$; then $\pi(x) = \pi(x')$ if and only if

$$\overline{G(\mathbb{C}) \cdot x} \cap \overline{G(\mathbb{C}) \cap x'} \cap X^{\mathrm{ss}}(\mathbb{C}) \neq \emptyset;$$

- (3) if $F \subset X^{ss}$ is a Zariski closed G-stable subset, then $\pi(F)$ is Zariski closed in Y;
- (4) if $U \subset X$ is a Zariski open G-saturated subset, then $\pi(U)$ is Zariski open;
- (5) $A^G \otimes_{\mathbb{R}} \mathbb{C} = (A \otimes_{\mathbb{R}} \mathbb{C})^{G_{\mathbb{C}}};$
- (6) $V := \pi(X^{s})$ is Zariski open in Y and $\pi^{-1}(V) = X^{s}$.

The projective variety Y is called the *GIT quotient* of X^{ss} by G and denoted X^{ss}/G . Remarks analogous to the ones in the affine case (see Remark 3.5) apply also in this case.

Turning to the situation on real points, Theorems 3.6 and 3.7 imply the following:

Theorem 3.18. With the notations introduced above, let $x \in X(\mathbb{R})$. Then the following hold:

⁸Again in the literature it can be denoted $X/\!\!/ G$ or $X^{ss}/\!\!/ G$.

- (1) the unique closed orbit contained in $G(\mathbb{C}) \cdot x \cap X^{ss}(\mathbb{C})$ has a real point. In particular, it is defined over \mathbb{R} .
- (2) the orbit $G(\mathbb{R}) \cdot x$ is closed in $X^{ss}(\mathbb{R})$ if and only if the orbit $G(\mathbb{C}) \cdot x$ is closed in $X^{ss}(\mathbb{C})$;
- (3) the closure of $G(\mathbb{R}) \cdot x$ in $X^{ss}(\mathbb{R})$ contains a unique $G(\mathbb{R})$ -orbit;
- (4) if F ⊂ X^{ss}(ℝ) is a closed G(ℝ)-stable subset, then π(F) is closed in Y(ℝ);
 (5) if U ⊂ X^{ss}(ℝ) is an open G(ℝ)-saturated subset, then π(U) is open in π(X^{ss}(ℝ));
- (6) if $V \subset Y$ is a Zariski open subset such that the induced map

$$\pi \colon U := \pi^{-1}(V) \longrightarrow V,$$

is smooth, then $\pi(U(\mathbb{R}))$ is a finite union of connected components of $V(\mathbb{R})$.

As for the affine case, because of statement (3) the set of $G(\mathbb{R})$ -orbits in $X^{ss}(\mathbb{R})$ is not very interesting. The notation $X(\mathbb{R})/G(\mathbb{R})$ is therefore reserved for the set of closed $G(\mathbb{R})$ -orbits in $X^{ss}(\mathbb{R})$ endowed with the strongest topology such that the natural map

$$p: X^{\mathrm{ss}}(\mathbb{R}) \longrightarrow X^{\mathrm{ss}}(\mathbb{R})/G(\mathbb{R})$$

is continuous. Similarly to Proposition 3.10, an immediate consequence of Theorem 3.18 is the following:

Proposition 3.19. With the notations introduced above:

- (1) the topological space $X^{ss}(\mathbb{R})/G(\mathbb{R})$ is Hausdorff and locally compact;
- (2) the map θ is proper with finite fibers and open onto its image;
- (3) $X^{ss}(\mathbb{R})/G(\mathbb{R})$ is the categorical quotient of $X^{ss}(\mathbb{R})$ by $G(\mathbb{R})$ in the category of Hausdorff spaces: for all Hausdorff topological space Z and all $G(\mathbb{R})$ invariant continuous map $f: X^{ss}(\mathbb{R}) \to Z$ there exists a unique continuous map $\tilde{f}: X^{ss}(\mathbb{R})/G(\mathbb{R}) \to Z$ such that $f = \tilde{f} \circ p$.

The topological space $X^{ss}(\mathbb{R})/G(\mathbb{R})$ is determined (up to a unique homeomorphism) by statement (3) and is called the *separated quotient* of $X^{ss}(\mathbb{R})$ by $G(\mathbb{R})$.

3.5. Configurations of real flags. Let G be a real reductive group and $G_{\rm sp}$ its split form. Let us identify their complexification: $G_{\mathbb{C}} = G_{\rm sp,\mathbb{C}}$. Let $P_{\rm sp} \subset G_{\rm sp}$ be a parabolic subgroup and $F_{\rm sp} = G_{\rm sp}/P_{\rm sp}$.

Definition 3.20. We say that the type of the parabolic P_{sp} is defined over \mathbb{R} for G if there exists a parabolic subgroup P of G such that $P_{\mathbb{C}}$ is conjugated to $P_{sp,\mathbb{C}}$.

The group $G_0 = G(\mathbb{R})$ acts on the flag variety $F_{sp}(\mathbb{C})$.

Theorem 3.21 ([Wol69, Theorems 3.3 and 3.5]). With the notations introduced above,

- (1) there exists a unique closed G_0 -orbit T in $F_{sp}(\mathbb{C})$;
- (2) for $x \in X(\mathbb{C})$, the orbit T is contained in the closure of G_0x and

 $\dim_{\mathbb{R}} G_0 x \ge \dim_{\mathbb{R}} T \ge \dim_{\mathbb{C}} F_{\rm sp}(\mathbb{C}),$

with equality if and only the type of the parabolic P_{sp} is defined over \mathbb{R} for G. In this case T is the set of real points of the associated real flag variety.

The orbit T has the following algebraic nature. Let $W = \operatorname{Res}_{\mathbb{C}/\mathbb{R}}(F_{\operatorname{sp},\mathbb{C}})$ the \mathbb{R} algebraic variety obtained by Weil restriction of $F_{\operatorname{sp},\mathbb{C}}$. Concretely, it is the complex variety $F_{\operatorname{sp},\mathbb{C}} \times F_{\operatorname{sp},\mathbb{C}}$ together with the anti-holomorphic involution

$$(x_1, x_2) \longmapsto (\sigma(x_2), \sigma(x_1)),$$

where σ is the anti-holomorphic involution on $F_{sp,\mathbb{C}}$ given by F_{sp} .

The group G acts naturally on W: if θ denotes the automorphism of $G_{sp,\mathbb{C}}$ defining the form G, the action of G corresponds to the action

$$g(x_1, x_2) = (gx_1, \theta(g)x_2)$$

for $g \in G_{\rm sp}(\mathbb{C})$ and $x_1, x_2 \in F_{\rm sp}(\mathbb{C})$.

For a point $t \in T$ let $S \subset W$ be the *G*-orbit of *x*. Let *F* be the Zariski closure of S in W: it is a projective variety.

Lemma 3.22. With the notations introduced above:

(1) $F(\mathbb{R}) = T;$

(2) S is projective if and only if the stabilizer of t is a parabolic subgroup of G.

Proof. (1) The closure F of the orbit S in W is made of S and lower dimensional orbits [Bor91, §1.8]. Therefore if $x \in F(\mathbb{R})$ does not lie in T, then its $G(\mathbb{R})$ -orbit has dimension strictly smaller than T, contradicting the minimality of T.

(2) Clear by definition.

Let $L_{\rm sp}$ be a $G_{\rm sp}$ -equivariant line bundle on $F_{\rm sp}$. The line bundle

$$\operatorname{pr}_1^* L_{\operatorname{sp}} \otimes \operatorname{pr}_2^* L_{\operatorname{sp}}$$

on $F_{\mathrm{sp},\mathbb{C}} \times F_{\mathrm{sp},\mathbb{C}}$ descends into a G-equivariant line bundle L on W, and by restriction, on F.

Let $n \ge 1$ be an integer, $X_{sp} = F_{sp}^n$ and $X = F^n$. Let X^{ss} be the set of semistable points of X with respect to G and the polarization induced by L on every copy of F. Similarly, let X_0^{ss} be the set of semi-stable points of X_{sp} with respect to $G_{\rm sp}$ and the polarization induced by $L_{\rm sp}$ on every copy of $F_{\rm sp}$.

Proposition 3.23. With the notations introduced above:

- (1) A point $x \in T^n$ is semi-stable if and only if it is so for every one-parameter subgroup $\lambda \colon \mathbb{G}_{m,\mathbb{R}} \to G$ defined over \mathbb{R} .
- The quotient $T^{n,ss}/G(\mathbb{R})$ is compact. (2)
- (3) The open subset $T^n \cap X_{\rm sp}(\mathbb{C})^{n,{\rm ss}}$ of $T^{n,{\rm ss}}$ is $G(\mathbb{R})$ -saturated.
- (4) The inclusion $T \subset X_{sp}(\mathbb{C})$ induces a continuous map

$$(T^n \cap X_{\rm sp}(\mathbb{C})^{n,{\rm ss}})/G(\mathbb{R}) \longrightarrow X_{\rm sp}(\mathbb{C})^{\rm ss}/G(\mathbb{C})$$

and $\dim_{\mathbb{R}} T^{n,\mathrm{ss}}/G(\mathbb{R}) \geq \dim_{\mathbb{C}} X_{\mathrm{sp}}(\mathbb{C})^{\mathrm{ss}}/G(\mathbb{C}).$

Proof. Clear.

Example 3.24. Let $V = \mathbb{R}^2$ and h be the standard hermitian form on \mathbb{C}^2 . Let $G_{\rm sp} = {\rm SL}_{2,\mathbb{R}}$ and G be the real form of ${\rm SL}_{2,\mathbb{C}}$ whose points are ${\rm SU}(2)$.

Let $F_{sp} = \mathbb{P}^1_{\mathbb{R}}$. The group SU(2) acts transitively on $\mathbb{P}^1(\mathbb{C})$ thus, with the no-tations above, $F = \operatorname{Res}_{\mathbb{C}/\mathbb{R}}(\mathbb{P}^1_{\mathbb{C}})$. There is no one-parameter subgroup of G defined over \mathbb{R} , thus all points of $F(\mathbb{R})^n = \mathbb{P}^1(\mathbb{C})^n$ are semi-stable. Because of this, the superscript ss is reserved for semi-stable points of $\mathbb{P}^1(\mathbb{C})^n$ with respect to $\mathrm{SL}_2(\mathbb{C})$. The separated quotient $\mathbb{P}^1(\mathbb{C})^n/\mathrm{SU}(2)$ is the quotient in the usual sense and has real dimension 2n-3 for $n \ge 2$ and it is a point for n = 1.

On the other hand, a *n*-tuple (x_1, \ldots, x_n) of points of $X_{sp}(\mathbb{C}) = \mathbb{P}^1(\mathbb{C})$ is semistable under the action of $SL_{2,\mathbb{C}}$ if and only if none of the points is repeated more than $\frac{n}{2}$ times. The quotient $(\mathbb{P}^1)^{n,\mathrm{ss}}/\mathrm{SL}_{2,\mathbb{C}}$ has complex dimension n-3 for $n \geq 3$, is a point for n = 2 and is empty for n = 1.

n	$\mathbb{P}^1(\mathbb{C})^n/\operatorname{SU}(2)$	$\mathbb{P}^1(\mathbb{C})^{n,\mathrm{ss}}/\mathrm{SU}(2)$	$\mathbb{P}^1(\mathbb{C})^{n,\mathrm{ss}}/\mathrm{SL}_2(\mathbb{C})$
1	point	Ø	Ø
2	[0,1]	[0, 1[point
3	$\mathbb{P}^1(\mathbb{C})^3/\operatorname{SU}(2)$	{hermitian forms on \mathbb{C}^2 }/ $\mathbb{R}_{>0}$	point

Example 3.25. Let G be a reductive group over \mathbb{R} and G_{sp} its split form. Let F_{sp}, F'_{sp} be flag varieties of G_{sp} with a G_{sp} -equivariant surjection $\pi_{sp} \colon F_{sp} \to F'_{sp}$. Let T, T' be respectively the unique $G(\mathbb{R})$ -closed orbit contained in $F_{sp}(\mathbb{C})$ and $F'_{sp}(\mathbb{C})$.

Clearly $\pi_{sp}(T) = T'$. The G_{sp} -equivariant projection π_{sp} induces a G-equivariant surjection

$$\pi \colon W := \operatorname{Res}_{\mathbb{C}/\mathbb{R}}(F_{\operatorname{sp},\mathbb{C}}) \longrightarrow W' := \operatorname{Res}_{\mathbb{C}/\mathbb{R}}(F'_{\operatorname{sp},\mathbb{C}}).$$

Denote by F the Zariski closure of T in W and similarly F' for that of T'. The map π restricts to a projection $\pi: F \to F'$.

Let $L_{\rm sp}, L'_{\rm sp}$ be $G_{\rm sp}$ -equivariant ample line bundles respectively on $F_{\rm sp}, F'_{\rm sp}$ and L, L' the *G*-equivariant ample line bundles induced on F, F'. Let $n \ge 1$ be an integer and $X = F^n, X' = F'^n$. As in the general construction, consider semi-stable points with respect the polarizations induced by L, L'. This induces a continuous map between quotients

$$T^{n,\mathrm{ss}} \cap \pi^{-1}(T'^{n,\mathrm{ss}})/G(\mathbb{R}) \longrightarrow T'^{n,\mathrm{ss}}/G(\mathbb{R}).$$

We will take profit of this construction in two situations. The first one is:

- $G_{\rm sp} = {\rm SL}_{n,\mathbb{R}};$
- $G(\mathbb{R}) = \mathrm{SU}(n-1,1);$
- $F_{sp} = Flag(1, 2, ..., n)$ the flag variety of complete flags;
- $F'_{sp} = Flag(1, n-1)$ the variety of flags (L, H) made of a line and hyperplane containing it.

The second one is:

- $G_{\rm sp} = {\rm SL}_{4,\mathbb{R}};$
- $G(\mathbb{R}) = SU(2,2)$ or $SL_2(\mathbb{H})$;
- $F_{sp} = Flag(1, 2, 3)$ the flag variety of complete flags;
- $F'_{sp} = Gr(2, 4)$ the grassmannian of planes in dimension 4.

In both cases the stabilizer of a point $t \in T'$ is a parabolic subgroup of G.

4. Sequences of flags line-hyperplane

4.1. Setup. Let $n, r \geq 3$ be integers and consider the variety $\operatorname{Flag}_{(1,n-1)}(\mathbb{C}^n)$ of couples (L, H) of subspaces of \mathbb{C}^n where L is line and H is a hyperplane containing it. Set:

$$V = \mathbb{C}^n, \qquad G = \operatorname{SL}_{n,\mathbb{C}}, \qquad F = \operatorname{Flag}_{(1,n-1)}(V), \qquad X = F^r.$$

Let $\mathcal{O}(1,1)$ be the line bundle $\operatorname{pr}_1^* \mathcal{O}(1) \otimes \operatorname{pr}_2^* \mathcal{O}(1)$ on the variety $\mathbb{P}(V) \times \mathbb{P}(V^{\vee})$ (here $\operatorname{pr}_1, \operatorname{pr}_2$ are be respectively the projection onto the first and second factor).

The semi-simple group G acts on X. Consider the linearization of this action given by the embedding

$$\iota \colon X = F^r \longrightarrow (\mathbb{P}(V) \times \mathbb{P}(V^{\vee}))^r.$$

This linearization corresponds to the G-linearized line bundle

$$L = \iota^*(\operatorname{pr}_1^* \mathcal{O}(1, 1) \otimes \cdots \otimes \operatorname{pr}_r^* \mathcal{O}(1, 1)),$$

where $\operatorname{pr}_i \colon X \to F$ denotes the projection onto the *i*-th factor.

4.2. **Invariants.** We introduce some natural invariants for this action. For a permutation $\sigma \in \mathfrak{S}_r$ consider the linear form $s_{\sigma} \colon (V \otimes V^{\vee})^{\otimes r} \to \mathbb{C}$ defined, for $v_1, \ldots, v_r \in V$ and $\phi_1, \ldots, \phi_r \in V^{\vee}$, by

$$s_{\sigma}(v_1 \otimes \phi_1, \ldots, v_r \otimes \phi_r) := \prod_{i=1}^r \phi_i(v_{\sigma(i)}).$$

The linear form s_{σ} is *G*-invariant. The restriction to *X* of the induced global section of $\bigotimes_{i=1}^{r} \operatorname{pr}_{i}^{*} \mathcal{O}(1,1)$ is a *G*-invariant global section of *L*:

$$s_{\sigma} \in \mathrm{H}^{0}(X, L)^{G}.$$

If the permutation σ has a fixed point then s_{σ} vanishes identically on X. Therefore it is interesting to consider the section only for *derangements*, that is, fixed-pointsfree permutations. Denote by \mathfrak{D}_r the set of derangements and by !r its cardinality. One has the recurrence relation

$$!r = (r-1)(!(r-1)+!(r-2)).$$

The global section s_{σ} vanishes at a *r*-tuple $\{(L_i, H_i)\}_{i=1,...,r}$ if and only if there exists i = 1, ..., r such that L_i is contained in $H_{\sigma(i)}$.

4.3. The quotient.

Definition 4.1. Let $x = \{(L_i, H_i)\}_{i=1,...,r}$ be a point of X.

For $n \ge r$, the point x is said to be in *general position* if the following conditions are satisfied:

(1) $\dim L_1 + \dots + L_r = r;$

(2) dim $H_1 \cap \cdots \cap H_r = n - r;$

(3) $L_i \cap H_j = 0$ for all $i \neq j$;

(4) $(L_1 + \dots + L_r) \cap (H_1 \cap \dots \cap H_r) = 0.$

Suppose n < r. The point x is said to be in general position if, for every subset $I \subset \{1, \ldots, n\}$ of n elements, the n-tuple $\{(L_i, H_i)\}_{i \in I}$ is in general position in the preceding sense.

Let U be the Zariski open subset of X^{ss} made of r-tuples in general position.

Theorem 4.2. With the notations introduced above:

(1) The graded \mathbb{C} -algebra of G-invariant elements

$$\bigoplus_{d\geq 0} \mathrm{H}^0(X, L^{\otimes d})^G,$$

is generated by the sections s_{σ} with $\sigma \in \mathfrak{D}_r$.

- (2) A r-tuple $\{(L_i, H_i)\}_{i=1,...,r}$ is semi-stable if and only if there exists a derangement $\sigma \in \mathfrak{S}_r$ such that L_i is not contained in $H_{\sigma(i)}$ for all i = 1, ..., r.
- (3) Let $\sigma_1, \ldots, \sigma_{!r}$ be the derangements on r elements and let $s_i = s_{\sigma_i}$ for $i = 1, \ldots, !r$. The map $\pi \colon X^{ss} \to \mathbb{P}^{!r-1}_{\mathbb{C}}$,

$$\pi(x) = [s_1(x) : \cdots : s_{!r}(x)]$$

is G-invariant and induces a closed embedding $X^{ss}/G \to \mathbb{P}^{lr-1}_{\mathbb{C}}$.

- (4) Let $x, x' \in U$ be such that $\pi(x) = \pi(x')$. Then, x, x' lie in the same orbit. In particular, U is a G-saturated open subset.
- (5) An element $g \in G$ belongs to the stabilizer of a r-tuple $x = \{(L_i, H_i)\}_{i=1,...,r}$ in U if and only if
 - (a) $g_{|L_1+\cdots+L_r|} = t \cdot \operatorname{id}_{L_1+\cdots+L_r}$ for some $t \in \mathbb{C}^{\times}$;
 - (b) $H_1 \cap \cdots \cap H_r$ is stable under g.

In particular the stabilizer of x has dimension $\max\{0, n-r\}^2$.

(6) The quotient Y of X^{ss} by G has dimension

$$r^{2} - 3r + 1 - \min\{0, n - r\}^{2}$$
.

Proof. (1) This is a consequence of the First Main Theorem of Invariant Theory. It states that, given a positive integer $N \ge 1$, the subspace of SL(V)-invariants of $End(V^{\otimes N})$ is generated by endomorphisms of the form

$$\phi_{\sigma} \colon v_1 \otimes \cdots \otimes v_N \longmapsto v_{\sigma(1)} \otimes \cdots \otimes v_{\sigma(N)},$$

 $\operatorname{Sym}^d\operatorname{End}(V^{\otimes r})=\operatorname{H}^0((\mathbb{P}(V)\times\mathbb{P}(V^\vee))^r,\bigotimes_{i=1}^r\operatorname{pr}_i^*\mathcal{O}(1,1))\longrightarrow\operatorname{H}^0(X,L^{\otimes d}),$

is surjective, the induced map

$$(\operatorname{Sym}^d \operatorname{End}(V^{\otimes r}))^G \longrightarrow \operatorname{H}^0(X, L^{\otimes d})^G$$

is surjective 9. Identifying the $\operatorname{Sym}^d\operatorname{End}(V^{\otimes r})$ with the subspace of symmetric tensors of

$$(V \otimes V^{\vee})^{\otimes rd} = \operatorname{End}(V^{\otimes rd}),$$

the First Main Theorem of Invariant Theory implies that $\mathrm{H}^0(X, L^{\otimes d})^G$ is generated by the restriction to elements of the sections ϕ_{σ} . Let $\sigma \in \mathfrak{S}_{rd}$ be a permutation. By evaluating ϕ_{σ} at a tensor of the form

$$x = (v_1 \otimes \phi_1 \otimes \cdots \otimes v_r \otimes \phi_r)^{\otimes d}$$

for vectors $v_1, \ldots, v_r \in V$ and linear forms $\phi_1, \ldots, \phi_r \in V^{\vee}$, one obtains

$$\phi_{\sigma}(x) = \prod_{i=1}^{r} \prod_{j=1}^{d} \phi_i(v_{\sigma((i-1)d+j)}).$$

For i, j = 1, ..., r let a_{ij} be the number of times that the term $\phi_i(v_j)$ occurs in the preceding product. If $a_{ii} \neq 0$ for some *i* then the section ϕ_{σ} vanishes identically on X. Suppose $a_{ii} = 0$ for all i = 1, ..., r.

The vector v_i as well as the linear form ϕ_i have to appear exactly d times in the product. That is,

$$\sum_{k=1}^{r} a_{ik} = d, \qquad \sum_{k=1}^{r} a_{kj} = d,$$

for all i, j = 1, ..., r. Consider the matrix $A = (a_{ij})_{i,j=1,...,r}$. It remains to show that A is sum of permutation matrices associated to derangements.¹⁰ It suffices to show that there is a permutation $\sigma \in \mathfrak{S}_r$ such that $a_{i\sigma(i)} \neq 0$ for all i = 1, ..., r. Indeed, if such a permutation σ exists, then it is fixed-point free because of the condition $a_{ii} = 0$ for all i = 1, ..., r.

The fact that such a permutation exists is a consequence of Hall's Marriage Theorem [HV50]. Let $I = J = \{1, \ldots, r\}$ and consider the bipartite graph Γ on $I \sqcup J$ defined by the relation: for $i \in I$ and $j \in J$, let $i \sim j$ if $a_{ij} \neq 0$. For a subset $S \subset I$ the neighbourhood $N_{\Gamma}(S)$ of S in Γ is the set of vertices in Y adjacent to some element of S:

$$N_{\Gamma}(S) = \{ j \in J : i \sim j \}.$$

Hall's Theorem states that there is a perfect matching for the graph (that is, in this case, a bijection $\sigma \in \mathfrak{S}_n$ such that $a_{i\sigma(i)} \neq 0$ for all $i = 1, \ldots, r$) if and only if

$$\#S \le \#N_{\Gamma}(S),$$

$$A = \sum_{\sigma \in \mathfrak{S}_r} \lambda_\sigma A_\sigma,$$

⁹This follows from the fact that the representations of G are completely reducible.

¹⁰One could argue by remarking that $\frac{1}{d}A$ is a doubly stochastic matrix. The Birkhoff-von Neumann theorem therefore states that $\frac{1}{d}A$ is a convex combination of permutation matrices. It follows that A can be written as a sum

where, for a permutation $\sigma \in \mathfrak{S}_r$, A_{σ} is the associated permutation matrix and λ_{σ} is a nonnegative real number. Nonetheless it is not clear that the coefficients λ_{σ} can be taken as integers (the decomposition is not unique).

for all subsets S of I. The preceding condition is satisfied in this case. Indeed, let S be a subset of I. Then,

$$\#S = \frac{1}{d} \sum_{i \in S} \sum_{j \in N_{\Gamma}(S)} a_{ij} \le \frac{1}{d} \sum_{i \in I} \sum_{j \in N_{\Gamma}(S)} a_{ij} = \#N_{\Gamma}(S).$$

(2) and (3) follow from (1).

(4) First of all remark that it suffices to find $g \in \operatorname{GL}_n(\mathbb{C})$ such that gx = x'. Write $x = \{(L_i, H_i)\}_{i=1,\ldots,r}$ and $x' = \{(L'_i, H'_i)\}_{i=1,\ldots,r}$. For $i = 1,\ldots,r$ let v_i, v'_i be respectively a basis of L_i, L'_i and ϕ_i, ϕ'_i linear forms defining respectively H_i, H'_i .

Lemma 4.3. Let $t_1, \ldots, t_r, u_1, \ldots, u_r \in \mathbb{C}$. With the notations introduced above, there exists $g \in GL_n(\mathbb{C})$ such that, for all $i = 1, \ldots, r$,

$$gv_i = t_i v_i,$$
 $\phi_i \circ g^{-1} = u_i \phi'_i,$

if and only if, for all $\alpha, \beta, i, j = 1, ..., r$ with $\alpha, \beta \notin \{i, j\}$,

(4.3.1)
$$\frac{\phi_i(v_\alpha)\phi_j(v_\beta)}{\phi_j(v_\alpha)\phi_i(v_\beta)} = \frac{\phi_i'(v_\alpha')\phi_j'(v_\beta')}{\phi_j'(v_\alpha')\phi_i'(v_\beta')},$$

and

$$t_{\alpha}^{-1}t_{\beta} = \frac{\phi_i'(v_{\alpha}')}{\phi_i(v_{\alpha})}\frac{\phi_i(v_{\beta})}{\phi_i'(v_{\beta}')}, \qquad t_{\alpha}u_i = \frac{\phi_i(v_{\alpha})}{\phi_i'(v_{\alpha})}.$$

Proof of the Lemma. (\Rightarrow) Suppose that such an element $g \in GL_n(\mathbb{C})$ exists. Then, for $\alpha, i = 1, \ldots, r$,

$$u_i\phi_i'(v_\alpha) = \phi_i(g^{-1}v_\alpha') = t_\alpha^{-1}\phi_i(v_\alpha).$$

In particular, for $\alpha \neq i$,

$$u_i = t_\alpha^{-1} \frac{\phi_i(v_\alpha)}{\phi_i'(v_\alpha')},$$

is independent of α . That is, for all $\alpha, \beta = 1, \ldots, r$ different from i,

$$t_{\alpha}^{-1}\frac{\phi_i(v_{\alpha})}{\phi_i'(v_{\alpha}')} = t_{\beta}^{-1}\frac{\phi_i(v_{\beta})}{\phi_i'(v_{\beta}')}$$

In particular, the quantity $t_{\alpha}^{-1}t_{\beta}$ is independent of *i*, whence (4.3.1).

 (\Leftarrow) Set $t_1 = 1$ and, for $\alpha = 2, \ldots, r$,

$$t_{\alpha} = \frac{\phi_i(v_{\alpha})\phi_i'(v_1')}{\phi_i'(v_{\alpha}')\phi_i(v_1)},$$

where i = 1, ..., r is different from 1 and α . Condition (4.3.1) implies that this does not depend on the chosen i.

Suppose first $n \geq r$. Pick $g \in GL_n(\mathbb{C})$ such that

$$gv_i = t_i v'_i$$
, for all $i = 1, \dots, r$, $g(H_1 \cap \dots \cap H_r) = H'_1 \cap \dots \cap H'_r$.

It remains to show $[\phi_i \circ g^{-1}] = [\phi'_i]$ for all $i = 1, \ldots, r$. Write $v \in V$ as

$$v = \lambda_1 v_1' + \dots + \lambda_r v_r' + w,$$

with $\lambda_1, \ldots, \lambda_r \in \mathbb{C}$ and $w \in H'_1 \cap \cdots \cap H'_r$. Then,

$$\phi_i(g^{-1}v) = \sum_{\alpha=1}^r \lambda_\alpha \phi_i(g^{-1}v'_\alpha) = \sum_{\alpha=1}^r \lambda_\alpha t_\alpha^{-1} \phi_i(v_\alpha),$$

because $g^{-1}w$ belongs to $H_1 \cap \cdots \cap H_r$. By construction, for all $\alpha, \beta = 1, \ldots, r$ different from i,

$$t_{\alpha}^{-1}\frac{\phi_i(v_{\alpha})}{\phi_i'(v_{\alpha}')} = t_{\beta}^{-1}\frac{\phi_i(v_{\beta})}{\phi_i'(v_{\beta}')}.$$

Call μ such a complex number. Then

$$\sum_{\alpha=1}^{r} \lambda_{\alpha} t_{\alpha}^{-1} \phi_i(v_{\alpha}) = \mu \sum_{\alpha=1}^{r} \lambda_{\alpha} \phi_i'(v_{\alpha}') + \mu \phi_i'(w) = \mu \phi_i'(v),$$

since $\phi'_i(w) = 0$ by assumption.

Suppose n < r. Applying the preceding case to the first n couples (L_i, H_i) , there exists $g \in GL_n(\mathbb{C})$ such that, for all i = 1, ..., n,

$$gv_i = t_i v_i,$$
 $\phi_i \circ g^{-1} = u_i \phi'_i.$

It remains to show the preceding property for i = n + 1, ..., r. In order to verify the equality $\phi_i \circ g^{-1} = u_i \phi'_i$ it suffices to show

$$\phi_i(g^{-1}v'_\alpha) = u_i\phi'_i(v'_\alpha),$$

for $\alpha = 1, \ldots, n$ as v'_1, \ldots, v'_n is a basis of V. On the other hand,

$$\phi_i(g^{-1}v'_\alpha) = t_\alpha^{-1}\phi_i(v_\alpha)$$

so that the preceding condition is equivalent to

$$t_{\alpha}^{-1}\phi_i(v_{\alpha}) = u_i\phi_i'(v_{\alpha}'),$$

which is satisfied by hypothesis.

The argument to show $gv_i = t_i v_i$ for i > n is similar.

Suppose $r \ge 4$ and remark the following:

Lemma 4.4. Suppose $r \ge 4$ and let $i, j, \alpha, \beta = 1, ..., r$ be pairwise distinct. Then there exists derangements $\sigma, \tau \in \mathfrak{D}_r$ such that $\sigma(k) = \tau(k)$ for all $k \ne i, j$ and

$$\sigma(i) = \alpha,$$
 $\sigma(j) = \beta,$ $\tau(i) = \beta,$ $\tau(j) = \alpha.$

Let $i, j, \alpha, \beta = 1, ..., n$ be pairwise distinct and σ, τ derangements as in Lemma 4.4. If s_{σ}, s_{τ} denote the corresponding *G*-invariant sections, then

$$\frac{s_{\sigma}(x)}{s_{\tau}(x)} = \frac{\phi_i(v_{\alpha})\phi_j(v_{\beta})}{\phi_j(v_{\alpha})\phi_i(v_{\beta})}$$

and similarly for x'. The condition $\pi(x) = \pi(x')$ implies $s_{\sigma}(x)/s_{\tau}(x) = s_{\sigma}(x')/s_{\tau}(x')$ and one concludes thanks to Lemma 4.3.

Suppose r = 3. Set

$$t_1 = 1, t_2 = \frac{\phi'_3(v'_1)\phi_3(v_2)}{\phi_3(v_1)\phi'_3(v'_2)}, t_3 = \frac{\phi'_2(v'_1)\phi_2(v_3)}{\phi_2(v_1)\phi'_2(v'_3)}.$$

Let $g \in GL_n(\mathbb{C})$ be such that $gv_i = t_iv_i$ for all i = 1, 2, 3. If n > 3 suppose moreover

$$g(H_1 \cap H_2 \cap H_3) = H_1' \cap H_2' \cap H_3'.$$

The rest of the proof goes similarly to Lemma 4.3. Indeed, by definition,

$$t_2 t_1^{-1} = t_2 = \frac{\phi'_3(v'_1)\phi_3(v_2)}{\phi_3(v_1)\phi'_3(v'_2)}, \qquad t_3 t_1^{-1} = t_3 = \frac{\phi'_2(v'_1)\phi_2(v_3)}{\phi_2(v_1)\phi'_2(v'_3)},$$

and $\pi(x) = \pi(x')$ translates into

$$t_3 t_2^{-1} = \frac{\phi_1'(v_2')\phi_1(v_3)}{\phi_1(v_2)\phi_1'(v_3')}.$$

(5) For all i = 1, ..., r let $v_i \in V$ be a generator of the line L_i and let $\phi_i \in V^{\vee}$ be a linear form defining H_i .

Suppose $g \in G_x$. Then, for all i = 1, ..., r, there exists $t_i, u_i \in \mathbb{C}^{\times}$ such that $g(v_i) = t_i v_i$ and $\phi_i \circ g^{-1} = u_i \phi_i$. For all i, j = 1, ..., n,

$$\phi_i(v_j) = \phi_i(g^{-1}g(v_j)) = u_i\phi_i(t_jv_j) = u_it_j\phi_i(v_j).$$

Suppose $i \neq j$. By assumption $\phi_i(v_j)$ does not vanish, thus $u_i t_j = 1$. In particular $t_1 = \cdots = t_r = u_1^{-1} = \cdots = u_r^{-1}$.

Conversely, suppose that g satisfies conditions (a) and (b) in the statement. Suppose $n \ge r$. Since the point x is in general position, a vector $v \in V$ can be written in a unique way as $v = \lambda_1 v_1 + \cdots + \lambda_r v_r + w$, with $\lambda_1, \ldots, \lambda_r \in \mathbb{C}$ and $w \in H_1 \cap \cdots \cap H_r$. Thus, for $i = 1, \ldots, r$,

$$\phi_i(g^{-1}v) = \phi_i(t^{-1}(\lambda_1v_1 + \dots + \lambda_rv_r) + g^{-1}w)$$

= $t^{-1}\phi_i(\lambda_1v_1 + \dots + \lambda_rv_r)$
= $t^{-1}[\phi_i(\lambda_1v_1 + \dots + \lambda_rv_r) + \phi_i(w)]$
= $t^{-1}\phi_i(v)$,

since w and $g^{-1}w$ belong to $H_1 \cap \cdots \cap H_r$. In particular g stabilizes H_i . The proof for n < r goes similarly.

(6) Apply the formula dim $Y = \dim X - (\dim G - \dim G_x)$ for a point $x \in U$. \Box

4.4. **Triplets of flags.** Keep the notations introduced previously. In this section suppose r = 3 and $n \geq 3$. The situation in this is quite simple since there are two derangements in \mathfrak{S}_3 : the 2-cycles (123) and (132). Write s_{123} and s_{132} the corresponding invariant sections. The quotient $X^{\rm ss}/G$ is isomorphic to \mathbb{P}^1 and the map $\pi: X^{\rm ss} \to \mathbb{P}^1_{\mathbb{C}}$,

$$\pi(x) = [s_{123}(x) : s_{132}(x)],$$

is the quotient map.

The map $\pi: X^{ss} \to \mathbb{P}^1$ has 3 fibers that contain more than one orbit: those at $0 = [1:0], \infty = [0:1]$ and -1 = [1:-1].

The fibers at 0 and ∞ of π correspond to points in X^{ss} where exactly one invariant vanishes. Up to action of \mathfrak{S}_3 on X^{ss} by permuting factors, it suffices to study the fiber at ∞ .

Definition 4.5. A semi-stable point $x = \{(L_i, H_i)\}_{i=1,2,3}$ such that $\pi(x) = \infty$ is said maximally degenerate if $L_1 \subset H_2$, $L_2 \subset H_3$, $L_3 \subset H_1$.

For such a maximally degenerate semi-stable point $x = \{(L_i, H_i)\}_{i=1,2,3}$ point there exists a basis v_1, \ldots, v_n of \mathbb{C}^n such that

(4.4.1)
$$L_1 = \langle v_1 \rangle, \qquad L_2 = \langle v_2 \rangle, \qquad L_3 = \langle v_3 \rangle, H_1 : v_2^{\vee} = 0, \qquad H_2 : v_3^{\vee} = 0, \qquad H_3 : v_1^{\vee} = 0,$$

where $v_1^{\vee}, \ldots, v_n^{\vee} \in V^{\vee}$ is the dual basis. To prove this, it suffices to take v_i to be a basis of L_i for i = 1, 2, 3 and v_4, \ldots, v_n to be a basis of $H_1 \cap H_2 \cap H_3$.

Proposition 4.6. With the notations introduced above:

- (1) An element g ∈ G stabilizes a maximally degenerate point x = {(L_i, H_i)}_{i=1,2,3} if and only if
 (a) for i = 1,2,3, g_{Li} = t_i · id_{Li} for some t_i ∈ C[×];
 (b) H₁ ∩ H₂ ∩ H₃ is stable under g. In particular the stabilizer of x has dimension (n − 3)² + 2.
- (2) The unique closed orbit contained in $\pi^{-1}(\infty)$ is the one given by maximally degenerate points.

Proof. (1) Clear according to (4.4.1).

(2) It suffices to show that the orbit of x is of minimal dimension among the orbits contained in $\pi^{-1}(\infty)$. Let $x = \{(L_i, H_i)\}_{i=1,2,3}$ be a semi-stable point of X such that $\pi(x) = \infty$ and which is not maximally degenerate. One has to show that the stabilizer of x has dimension $\leq (n-3)^2 + 1$. For i = 1, 2, 3 let P_i be the stabilizer of the flag (L_i, H_i) .

Up to permutations, one may suppose that the flags (L_1, H_1) and (L_2, H_2) are opposite and $L_3 \subset H_1$. For i = 1, 2, 3 let v_i be a generator of L_i . Since $L_3 \not\subset H_2$ one can take $v_3 = v_1 + w$ with $w \in H_1 \cap H_2$ non-zero.

The intersection $P_1 \cap P_2$ is made of matrices $g \in GL_n(\mathbb{C})$ such that

- for i = 1, 2 there is $t_i \in \mathbb{C}^{\times}$ such that $gv_i = t_i v_i$;
- $g(H_1 \cap H_2) = H_1 \cap H_2.$

Therefore for $g \in P_1 \cap P_2$ one has $gv_3 = t_1v_1 + gw$ and $gw \in H_1 \cap H_2$. Thus g stabilizes the line L_3 if and only if $gw = t_1w$.

This implies $\dim(P_1 \cap P_2 \cap P_3) \le (n-3)^2 + 1.$

Definition 4.7. A semi-stable point $x = \{(L_i, H_i)\}_{i=1,2,3}$ such that $\pi(x) = -1$ is said maximally degenerate if dim $L_1 + L_2 + L_3 = 2$ and dim $H_1 \cap H_2 \cap H_3 = n-2$.

For i = 1, 2, 3 let v_i be a basis of L_i and ϕ_i a linear form defining H_i . If x is maximally degenerate then one can take

$$v_3 = v_1 + v_2,$$
 $\phi_3 = \phi_2(v_1)\phi_1 - \phi_1(v_2)\phi_2.$

Proposition 4.8. With the notations introduced above:

- (1) An element $g \in G$ stabilizes a maximally degenerate point $x = \{(L_i, H_i)\}_{i=1,2,3}$ if and only if
 - (a) $g_{|L_1+L_2} = t \cdot \operatorname{id}_{L_1+L_2}$ for some $t \in \mathbb{C}^{\times}$;
 - (b) $H_1 \cap H_2$ is stable under g.
 - In particular the stabilizer of x has dimension $(n-2)^2$.
- (2) The unique closed orbit contained in $\pi^{-1}(-1)$ is the one given by maximally degenerate points.

Proof. (1) Similar to the proof of Theorem 4.2 (5).

(2) It suffices to show that the orbit of x is of minimal dimension among the orbits contained in $\pi^{-1}(-1)$. Let $x = \{(L_i, H_i)\}_{i=1,2,3}$ be a semi-stable point of X such that $\pi(x) = -1$ and which is not maximally degenerate. One has to show that the stabilizer of x has dimension $\leq (n-2)^2 - 1$.

For i = 1, 2, 3 let v_i be a generator of L_i , ϕ_i a linear form defining H_i . If $g \in G$ belongs to the stabilizer of x the there exists $t_i, u_i \in \mathbb{C}^{\times}$ (i = 1, 2, 3) such that $gv_i = t_i v_i$ and $\phi_i \circ g^{-1} = u_i \phi_i$. For $i \neq j$ one has

$$\phi_i(v_j) = \phi_i(g^{-1}g(v_j)) = u_i\phi_i(t_jv_j) = u_it_j\phi_i(v_j),$$

thus $u_i t_j = 1$. This implies $t_1 = t_2 = t_3 = u_1^{-1} = u_2^{-1} = u_3^{-1}$. In particular,

(1) $g_{|L_1+L_2+L_3} = t \operatorname{id}_{L_1+L_2+L_3}$ for some $t \in \mathbb{C}^{\times}$;

(2) $H_1 \cap H_2 \cap H_3$ is stable under g.

If the vectors v_1, v_2, v_3 or the linear forms ϕ_1, ϕ_2, ϕ_3 are linearly independent, then $\dim G_x \leq (n-3)^2$. This concludes the proof.

4.5. Quadruples of flags. A permutation $\sigma \in \mathfrak{S}_4$ is written $(\sigma(1)\sigma(2)\sigma(3)\sigma(4))$. Put the derangements of 4 elements in lexicographic order:

$$\sigma_1 = (2143)$$
 $\sigma_2 = (2341)$ $\sigma_3 = (2413)$ $\sigma_4 = (3142)$ $\sigma_5 = (3412)$ $\sigma_6 = (3421)$ $\sigma_7 = (4123)$ $\sigma_8 = (4312)$ $\sigma_9 = (4321).$

For i = 1, ..., 9 denote s_i the *G*-invariant global section associated to the derangement σ_i .

Theorem 4.9. If $n \ge 4$ the map $\pi: X^{ss} \to \mathbb{P}^8_{\mathbb{C}}$ identifies the GIT quotient X^{ss}/G with the subvariety of $\mathbb{P}^8_{\mathbb{C}}$ given by the equations

$$x_1 x_5 = x_3 x_4, \qquad \qquad x_1 x_9 = x_2 x_7, \qquad \qquad x_5 x_9 = x_6 x_8,$$

whereas for n = 3 the equation

$$x_1 + x_5 + x_9 = x_2 + x_3 + x_4 + x_6 + x_7 + x_8,$$

has to be added.

Remark 4.10. In each of the previous equations, the left-hand side is made of variables corresponding to derangements of order 2. On the right-hand side, if the variable corresponding to a derangement σ appears, then the variable corresponding to σ^{-1} occurs too.

Proof. It is an elementary computation showing that the relations

$$s_1 s_5 = s_3 s_4,$$
 $s_1 s_9 = s_2 s_7,$ $s_5 s_9 = s_6 s_8,$

hold. The equations in the statement give rise to a 5-dimensional, irreducible, complete intersection in \mathbb{P}^8 . On the other hand, the GIT quotient X^{ss}/G is an integral variety of dimension 5 by Theorem 4.2.

4.6. **Real forms.** Let G be a real form of $SL_{n,\mathbb{C}}$ admitting a parabolic subgroup of type (1, n-1) defined over \mathbb{R} .

Let F be the corresponding flag variety and $X = F^r$ and L the line bundle induced by the Plücker embedding of $X_{\mathbb{C}}$. Consider the Zariski open subset of semi-stable points X^{ss} with respect to G and L. Because of the compatibility of construction of invariants with extension of scalars (cf. Theorem 3.4 (5)) the real vector space $\mathrm{H}^0(X, L)^G$ is of dimension !r and one has a well-defined map

$$\pi\colon X^{\mathrm{ss}} \longrightarrow \mathbb{P}(\mathrm{H}^0(X, L)^G),$$

which induces a closed embedding $X^{ss}/G \to \mathbb{P}(\mathrm{H}^0(X, L)^G)$.

4.6.1. $\operatorname{SL}_n(\mathbb{R})$. Let $G = \operatorname{SL}_{n,\mathbb{R}}$. Then F is the algebraic variety $\operatorname{Flag}_{(1,n-1)}(\mathbb{R}^n)$ of flags of type (1, n - 1) of \mathbb{R}^n . For a derangement σ the global section s_{σ} is real. Let $\sigma_1, \ldots, \sigma_{!r}$ be the derangement on r elements and, for $i = 1, \ldots, !r, s_i$ be the associated G-invariant global section. The map π is given by

$$\pi(x) = [s_1(x) : \cdots : s_{!r}(x)].$$

The open subset $U_{\mathbb{C}} \subset X_{\mathbb{C}}$ of points in general position is stable under complex conjugation and therefore comes from an open subset $U \subset X$.

Proposition 4.11. The map $\theta: U(\mathbb{R})/\operatorname{SL}_n(\mathbb{R}) \to \mathbb{P}^{!r-1}(\mathbb{R})$ is injective as soon as n is odd or n > r. If $n \leq r$ and n is even then θ is two-to-one.

Proof. This can be seen by reproducing the argument of Theorem 4.2 (4) over \mathbb{R} . The difference is that, when $n \leq r$, it is not always possible to have an element of the transporter of determinant 1.

An alternative way to prove the statement is computing Galois cohomology groups of the stabilizer of a point $x \in U(\mathbb{R})$. The argument in the proof of Theorem 4.2 (5) works over \mathbb{R} and shows that an element $g \in SL_n(\mathbb{R})$ stabilizes x if and only if

(1)
$$g_{|L_1+\cdots+L_r|} = t \cdot \operatorname{id}_{L_1+\cdots+L_r}$$
 for some $t \in \mathbb{C}^{\times}$

(2) $H_1 \cap \cdots \cap H_r$ is stable under g.

Therefore for n > r the stabilizer of x is isomorphic to the algebraic group

$$H = \{ (t,g) \in \mathbb{G}_{m,\mathbb{R}} \times_{\mathbb{R}} \operatorname{GL}_{n-r,\mathbb{R}} : t^r \det g = 1 \}.$$

Taking the Galois cohomology sequence associated to the short exact sequence

$$1 \longrightarrow \mathbb{G}_{m,\mathbb{R}} \longrightarrow H \longrightarrow \mathrm{GL}_{n-r,\mathbb{R}} \longrightarrow 1,$$

one obtains $\mathrm{H}^1(\mathbb{R}, H) = 0$ thanks to Theorem 2.4. For $n \leq r$ the stabilizer of x is the center μ_n of SL_n , thus

$$\mathbf{H}^{1}(\mathbb{R},\mu_{n}) = \begin{cases} \mathbb{Z}/2\mathbb{Z} & \text{if } n \text{ is even,} \\ 0 & \text{otherwise.} \end{cases}$$

This concludes the proof.

Remark 4.12. The lack of injectivity disappears as soon as one quotients by $GL_n(\mathbb{R})$ instead of $SL_n(\mathbb{R})$.

Example 4.13. Suppose r = 3 and go back to the notations introduced in paragraph 4.4. The global sections s_{123} and s_{132} are real, thus the quotient map $\pi: X^{ss} \to \mathbb{P}^1_{\mathbb{R}}$ is given by $\pi(x) = [s_{123}(x): s_{132}(x)]$. It induces a natural map

$$\theta: X^{\mathrm{ss}}(\mathbb{R}) / \mathrm{SL}_n(\mathbb{R}) \to \mathbb{P}^1(\mathbb{R})$$

Proposition 4.14. The map θ is a homeomorphism.

Proof. According to Proposition 3.19 it suffices to prove that θ is bijective. Surjectivity is easy: let $e_1^{\vee}, \ldots, e_n^{\vee}$ be the dual basis and set

$$\begin{split} L_1 &= \langle e_1 \rangle, & L_2 &= \langle e_n \rangle, & L_3 &= \langle v \rangle, \\ H_1 &: e_n^{\vee} &= 0, & H_2 &: e_1^{\vee} &= 0, & H_2 &: \phi &= 0, \end{split}$$

where $v \in V$ and $\phi \in V^{\vee}$ are such that $e_n^{\vee}(v) = \phi(e_1) = 1$. Then,

$$\pi(x) = [e_1^{\vee}(v) : \phi(e_n)],$$

whence the surjectivity of θ .

Concerning the injectivity, according to Proposition 4.11, it suffices to prove it only for points lying on the closed orbits contained in the fibers at $0, \infty$ and -1. In each of these cases maximally degenerate points lie clearly in the same orbit under $SL_n(\mathbb{R})$.

4.6.2. SU(n-1,1). Let h be a hermitian form of signature (n-1,1) on \mathbb{C}^n and SU(n-1,1) the subgroup of SL_n(\mathbb{C}) of elements respecting the hermitian form h.

Let G be the real form of $\operatorname{SL}_{n,\mathbb{C}}$ such that $G(\mathbb{R}) = \operatorname{SU}(n-1,1)$. For a linear subspace $W \subset V$ denote by W^{\perp} its orthogonal with respect to the hermitian form h. The flag variety F is defined by the anti-holomorphic involution τ on F associating to a complex flag (L, H) the flag (H^{\perp}, L^{\perp}) .

The anti-holomorphic involution τ can be extended to $\mathbb{P}(V) \times_{\mathbb{C}} \mathbb{P}(V^*)$ in a way such that the Plücker embedding is compatible to these involutions. For $v \in V$ denote by α_v the linear form on V defined for every $w \in V$ by $\alpha_v(w) := h(v, w)$. Conversely for a linear form α on V write $v_{\alpha} \in V$ for the unique vector such that $\alpha_{v_{\alpha}} = \alpha$. Consider the anti-holomorphic involution τ on $\mathbb{P}(V) \times_{\mathbb{C}} \mathbb{P}(V^*)$ given by

$$\tau \colon (v, \alpha) \mapsto (v_{\alpha}, \alpha_v).$$

For $i = 1, \ldots, r$ let $v_i \in V$ be an isotropic vector and $\alpha_i := \alpha_{v_i}$. For a derangement σ ,

$$s_{\sigma}((v_1 \otimes \alpha_1) \otimes \cdots \otimes (v_r \otimes \alpha_r)) = \prod_{i=1}^r h(v_i, v_{\sigma(i)}).$$

In particular $\tau^* s_{\sigma} = \bar{s}_{\sigma^{-1}}$. If a derangement σ is order 2, then

$$s_{\sigma}((v_1 \otimes \alpha_1) \otimes \cdots \otimes (v_r \otimes \alpha_r)) = \prod_{i=1}^r |h(v_i, v_{\sigma(i)})|,$$

which is a non-negative real number. If σ is not of order 2 the global sections

$$\frac{1}{2}(s_{\sigma}+s_{\sigma^{-1}}), \qquad \qquad \frac{1}{2\sqrt{-1}}(s_{\sigma}-s_{\sigma^{-1}}),$$

are defined over \mathbb{R} and take as values the real and imaginary part of s_{σ} .

Proposition 4.15. Let $x = (L_1, \ldots, L_r)$ be a r-tuple of isotropic lines.

(1) x is semi-stable if and only if, for every isotropic line L,

$$\#\{i: L=L_i\} \le \frac{\prime}{2};$$

(2) if r is even, then x is semi-stable if and only if there is a derangement of order 2 such that $s_{\sigma}(x) \neq 0$.

Proof. If an isotropic line is repeated more than r/2 times, then it is clear that all invariants s_{σ} vanish at x.

The converse implication is proved separately for r odd and even.

Suppose r = 2r' with r' integer. We prove statement (2) by induction on $r' \ge 2$. Suppose $s_{\sigma}(x) = 0$ for all derangements of order 2. For r' = 2 one sees that there is a line repeated at least 3 times. Assume $r' \ge 3$ and that the statement is true for r'-1. One may suppose $L_{r-1} \ne L_r$. Then, by the inductive hypothesis, among the lines L_1, \ldots, L_{r-2} there is a line L repeated at least $\frac{r}{2}$ times. Up to permutation one may suppose $L = L_1 = \cdots = L_{r/2}$. Consider the derangement of order 2 given by $\sigma(i) = \frac{r}{2} + i$ and $\sigma(\frac{r}{2} + i) = i$ for $i = 1, \ldots, \frac{r}{2}$. The hypothesis $s_{\sigma}(x) = 0$ implies that there is $j = \frac{r}{2}, \ldots, r$ such that $L_j = L$. This contradicts the semi-stability.

Suppose r odd and write r = 2r' + 1. The statement is proved by induction on $r' \ge 1$. For r' = 1 the statement is clear. Suppose $r' \ge 2$. Up to permutation one may assume $L_1 \ne L_2$. Suppose $s_{\sigma}(x) = 0$ for all derangements σ such that $\sigma_{\{1,2\}} = (12)$. Then, by inductive hypothesis, there is a line L such that

$$\#\{i \in \{3, \dots, r\} : L = L_i\} \ge \frac{r-1}{2}.$$

By hypothesis $L_1, L_2 \neq L$. Let k be such that $L_k = L$. Suppose $s_{\sigma}(x) = 0$ for all derangements σ such that $\sigma_{\{1,2,k\}} = (12k)$. By the case with even r, among the lines L_i for $i \neq 1, 2, k$ there is a line L' repeated at least $\frac{r-1}{2}$ times. One has necessarily L = L' thus the line L is repeated at least $\frac{r+1}{2}$ times, contradicting the hypothesis.

Let ℓ be the number of derangements of order 2: it is 0 if r is odd and

$$(r-1)!! := \prod_{i=0}^{\frac{i}{2}-1} (r-2i),$$

if r is even. Let m the cardinality of the quotient of \mathfrak{D}_r by the relation $\sigma \sim \tau$ if $\tau = \sigma^{-1}$: it is !r if r is odd and $\frac{!r-(r-1)!!}{2}$ if r is even.

Order the derangements on r elements in a way such that

- σ_i is of order 2 for $i = 1, \ldots, \ell$;
- if $i = \ell + 1, \ldots, m$ then $\sigma_i^{-1} = \sigma_j$ for j > m.

Identify $\mathbb{P}^{!r-1}(\mathbb{R})$ with the projective space associated to $\mathbb{R}^{\ell} \times \mathbb{C}^{m-\ell}$ (seen as a real vector space). For $x \in X^{\mathrm{ss}}(\mathbb{R})$ the point $\pi(x)$ is the line generated by

$$(s_1(x), \ldots, s_\ell(x), s_{\ell+1}(x), \ldots, s_m(x)).$$

On the other hand, for isotropic vectors v_1, \ldots, v_r , for non-zero complex numbers $\lambda_1, \ldots, \lambda_r$ and for a derangement σ ,

$$\prod_{i=1}^r h(\lambda_i v_i, \lambda_{\sigma(i)} v_{\sigma(i)}) = |\lambda_1|^2 \cdots |\lambda_r|^2 \prod_{i=1}^r h(v_i, v_{\sigma(i)})$$

This shows that the class p(x) of the vector $(s_1(x), \ldots, s_m(x))$ in the sphere

$$\mathbb{S}(\mathbb{R}^{\ell} \times \mathbb{C}^m) := (\mathbb{R}^{\ell} \times \mathbb{C}^m \setminus \{0\}) / \mathbb{R}_{>0},$$

only depends on the line generated by the vectors v_1, \ldots, v_r . This induces welldefined maps $p: X^{ss}(\mathbb{R}) \to \mathbb{S}(\mathbb{R}^{\ell} \times \mathbb{C}^m)$ and

$$\varepsilon\colon X^{\mathrm{ss}}(\mathbb{R})/G(\mathbb{R}) \longrightarrow \mathbb{S}(\mathbb{R}^\ell \times \mathbb{C}^m)$$

Consider the $G(\mathbb{R})$ -saturated open subset

$$W = \{ (L_1, \dots, L_r) \in X^{ss}(\mathbb{R}) : \dim(L_1 + \dots + L_r) \ge 3 \}.$$

Theorem 4.16. With the notations introduced above:

- (1) the map $W/\operatorname{SU}(1, n-1) \to \mathbb{P}(\mathbb{R}^{\ell} \times \mathbb{C}^m)$ is injective;
- (2) for r odd the map $\varepsilon \colon X^{\mathrm{ss}}(\mathbb{R})/G(\mathbb{R}) \to \mathbb{S}(\mathbb{C}^{!r/2})$ is injective;
- (3) for r even and $x, x' \in X^{ss}(\mathbb{R})$,

$$p(x) = p(x')$$
 if and only if $\pi(x) = \pi(x')$.

Remark 4.17. When r is odd, statement (1) implies that the image of ε in $\mathbb{S}(\mathbb{C}^{!r/2})$ is contained in a "hemisphere".

Before proving Theorem 4.16 let us illustrate it through two examples.

Example 4.18. Let r = 3 and go back to the notation introduced in paragraph 4.4. Identify $\mathbb{S}(\mathbb{C})$ with U(1). For a semi-stable triple $x = ([v_1], [v_2], [v_3])$ of isotropic lines,

$$p([v_1], [v_2], [v_3]) = \arg(h(v_1, v_3)h(v_3, v_2)h(v_2, v_1)),$$

where $\arg(z) = z/|z|$ is the argument of a non-zero complex number z.

Identify the real projective line $\mathbb{P}^1(\mathbb{R})$ with $U(1)/\{\pm 1\}$ and in turn with U(1) through the map $u \mapsto u^2$. The map π can be expressed as

 $\pi([v_1], [v_2], [v_3]) = \arg(h(v_1, v_3)h(v_3, v_2)h(v_2, v_1))^2.$

Proposition 4.19. With the notations introduced above, the map p induces a homeomorphism of $X^{ss}(\mathbb{R})/G(\mathbb{R})$ with

$$H := \{ u \in U(1) : \operatorname{Re}(u) \le 0 \}.$$



FIGURE 1. The map θ maps the half-circle onto the entire circle. It is injective outside $\pm i$. The Cartan invariant $\pm i$ corresponds to configurations of 3 isotropic lines in \mathbb{C}^n which, seen as points of $\mathbb{P}^{n-1}(\mathbb{C})$, lie on a line.

Proof. One may suppose that the hermitian form h is given by the matrix

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & \text{id} & 0 \\ 1 & 0 & 0 \end{pmatrix}.$$

In this case the vectors e_1 , e_n are isotropic. It is easy to prove that p is surjective onto H: consider the isotropic vectors $v_1 = e_1$, $v_2 = e_n$ and

$$v_3 = ue_1 + \sqrt{2|\operatorname{Re}(u)|e_2 + e_n},$$

where $u \in U(1)$ has non-positive real part. Then $h(v_1, v_3)h(v_3, v_2)h(v_2, v_1) = u$ whence the surjectivity.

Let us prove that the image is contained in H. Let v_1, v_2, v_3 be isotropic vectors of V such that $\lambda := h(v_1, v_2)h(v_2, v_3)h(v_3, v_1) \neq 0$. One may assume $v_1 = e_1$ and $v_2 = e_n$. Write $v_3 = x_1e_1 + \cdots + x_ne_n$. Then $\lambda = \bar{x}_nx_1$ and

$$0 = h(v_3, v_3) = 2 \operatorname{Re}(\lambda) + |x_2|^2 + \dots + |x_{n-1}|^2.$$

This implies $\operatorname{Re}(\lambda) \leq 0$, that is, the image of f is contained in H. The injectivity outside $\{\pm i\}$ follows immediately.

Example 4.20. Let r = 4 and suppose that the hermitian form h is given by the matrix

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & \text{id} & 0 \\ 1 & 0 & 0 \end{pmatrix}.$$

Consider the following isotropic vectors:

$$\begin{aligned} v_1 &= e_1, & v_2 &= e_n, & v_3 &= v_4 &= ie_1 + e_n, \\ v_1' &= e_1, & v_2' &= e_n, & v_3' &= v_4' &= -ie_1 + e_n. \end{aligned}$$

One has

$$h(v_1, v_2)h(v_2, v_3)h(v_3, v_1) =$$

$$h(v_1', v_2')h(v_2', v_3')h(v_3', v_1') = -i,$$

thus the semi-stable quadruplets

$$x = ([v_1], [v_2], [v_3], [v_4]), \qquad \qquad x' = ([v'_1], [v'_2], [v'_3], [v'_4]),$$

i,

cannot be conjugated by SU(n-1, 1). On the other hand one has p(x) = p(x').

The rest of this section is devoted to the proof of the Theorem 4.16: it is made of three lemmas. Before dipping into the proof, let us fix some notation.

Let $v = (v_1, \ldots, v_n)$, $v' = (v'_1, \ldots, v'_n)$ be *n*-tuples of non-zero isotropic vectors. For $i = 1, \ldots, r$ let L_i , L'_i be the line generated respectively by v_i , v'_i and denote by $x_i, x'_i \in F(\mathbb{R})$ the associated points. The *n*-tuples $x = (x_1, \ldots, x_n)$, $x' = (x'_1, \ldots, x'_n)$ are supposed to be semi-stable points of X.

Definition 4.21. Let i, j, k = 1, ..., r be such that the lines generated by the vector v_i, v_j, v_k are pairwise distinct. Set

$$\lambda_{ijk}(v,v') := \frac{h(v_i, v_j)}{h(v'_i, v'_j)} \cdot \frac{h(v'_k, v'_j)}{h(v_k, v_j)} \cdot \frac{h(v'_i, v'_k)}{h(v_i, v_k)}.$$

Lemma 4.22. Suppose that there exists k = 1, ..., r with the following property: for $i, j, \alpha, \beta = 1, ..., r$ such that the lines L_i, L_j, L_k as well as the lines L_α, L_β, L_k are pairwise distinct,

$$\lambda_{ijk}(v,v') = \lambda_{\alpha\beta k}(v,v'),$$

and such a complex number is real and positive. Then, there exists $g \in SU(n-1,1)$ such that gx = x'.

Proof. First of all remark that it suffices to look for $g \in U(n-1,1)$ such that gx = x': indeed, if det $g \neq 1$ it suffices to divide g by a n-th root of its determinant.

Let s be the dimension of the vector space generated by v_1, \ldots, v_r . The semistability hypothesis implies $s \geq 2$. Up to permutation, one may assume that v_1, \ldots, v_s are linearly independent.

Suppose $n \ge s$. Set $t_k = 1$ and

$$\bar{t}_i = \frac{h(v_i, v_j)}{h(v'_i, v'_j)} \cdot \frac{h(v'_k, v'_j)}{h(v_k, v_j)},$$

for $j \neq i, k$ (it is independent of j by hypothesis). Then, for $i \neq j$,

$$\frac{h(t_i v'_i, t_j v'_j)}{h(v_i, v_j)} = \bar{t}_i t_j \frac{h(v'_i, v'_j)}{h(v_i, v_j)} = \lambda_{ijk}(v, v'),$$

which is a positive real number independent of i and j by hypothesis. Call λ such a number. Then there exists an isometry of the sub-vector space $\langle v_1, \ldots, v_s \rangle$ onto $\langle v'_1, \ldots, v'_s \rangle$ sending the vector v_i to $t_i/\sqrt{\lambda}v'_i$. By Witt's Theorem, such an isometry can be extended to $g \in U(n-1, 1)$.

If r = s there is nothing left to prove. Suppose s < r and let j > s. Since v_j belongs to the vector space generated by v_1, \ldots, v_s , in order to prove $[gv_j] = [v'_j]$ it suffices to prove that the complex number

$$\frac{h(v_i', gv_j)}{h(v_i', v_j')}$$

does not depend on i. Since g is an isometry,

$$h(v'_i, gv_j) = h(g^{-1}v'_i, v_j) = \sqrt{\lambda} \bar{t}_i^{-1} h(v_i, v_j).$$

In particular,

$$\frac{h(v_i',gv_j)}{h(v_i',v_j')} = \sqrt{\lambda} \frac{h(v_i',v_j')}{h(v_i,v_j)} \cdot \frac{h(v_k,v_j)}{h(v_k',v_j')} \cdot \frac{h(v_i,v_j)}{h(v_i',v_j')} = \sqrt{\lambda} \frac{h(v_k,v_j)}{h(v_k',v_j')},$$

which does not depend on i. This concludes the proof.

Lemma 4.23. Suppose there exists $g \in GL_n(\mathbb{C})$ such that gx = x'. Then,

(1) For $i, j, k, \alpha, \beta = 1, ..., r$ such that the lines L_i, L_j, L_k as well as the lines $L_{\alpha}, L_{\beta}, L_k$ are pairwise distinct,

$$\lambda_{ijk}(v, v') = \lambda_{\alpha\beta k}(v, v').$$

- In particular both sides of the previous identity are real numbers.
- (2) Let i, j, k = 1, ..., r be such that $\dim(L_i + L_j + L_k) = 3$. Then,

$$\lambda_{iik}(v, v') > 0.$$

(3) Suppose r odd and p(x) = p(x'). Then, there exists k with the following property: for all i, j = 1, ..., r such that L_i, L_j, L_k are pairwise distinct

$$\lambda_{ijk}(v, v') > 0.$$

Proof. Let us fix some notation. For simplicity write $\lambda_{ij} = \lambda_{ijk}(v, v')$. For $\rho = 3, 4$ let $X_{\rho} = F^{\rho}$ and $\pi_{\rho} \colon X_{\rho}^{ss} \to \mathbb{P}_{\mathbb{R}}^{!\rho-1}$ be the quotient map. (1) In order to prove $\lambda_{ij} = \lambda_{\alpha\beta}$ for all $\alpha, \beta = 1, \ldots, r$ such that the lines

(1) In order to prove $\lambda_{ij} = \lambda_{\alpha\beta}$ for all $\alpha, \beta = 1, \ldots, r$ such that the lines $L_{\alpha}, L_{\beta}, L_k$ are pairwise distinct, it suffices to show $\lambda_{ij} = \lambda_{ji}$ and $\lambda_{ij} = \lambda_{i\beta}$. The semi-stable points

$$y = ([L_i], [L_j], [L_k]),$$
 $y' = ([L'_i], [L'_j], [L'_k]),$

of X_3 verify gy = y' because of the hypothesis gx = x'. Thus $\pi_3(y) = \pi_3(y)$ which implies,

$$\frac{h(v_i, v_j)h(v_j, v_k)h(v_k, v_i)}{h(v_i, v_k)h(v_k, v_j)h(v_j, v_i)} = \frac{h(v_i', v_j')h(v_j', v_k')h(v_k', v_i')}{h(v_i', v_k')h(v_k', v_j')h(v_j', v_i')},$$

thus $\lambda_{ij} = \lambda_{ji}$.

Suppose $r \geq 5$. In order to show $\lambda_{ij} = \lambda_{\alpha\beta}$ for $\alpha, \beta = 1, \ldots, r$ distinct, it suffices to prove the equalities $\lambda_{ij} = \lambda_{i\beta}$ for $i \neq \beta$. The latter is equivalent to

$$\frac{h(v_i, v_j)h(v_k, v_\beta)}{h(v_i, v_\beta)h(v_k, v_j)} = \frac{h(v'_i, v'_j)h(v'_k, v'_\beta)}{h(v'_i, v'_\beta)h(v'_k, v'_j)}.$$

Again the semi-stable points

$$y = ([L_i], [L_j], [L_k], [L_\beta]), \qquad y' = ([L'_i], [L'_j], [L'_k], [L'_\beta]),$$

of X_4 satisfy $\pi_4(y) = \pi_4(y')$ because of the assumption gx = x'. Let σ, τ be derangements such that $\sigma(\alpha) = \tau(\alpha)$ for all $\alpha \neq i, k$ and $\sigma(i) = j, \tau(i) = \beta$, $\sigma(k) = \beta, \tau(k) = j$ (they exists thanks to Lemma 4.4). Let s_{σ}, s_{τ} the corresponding *G*-invariant sections. Then,

$$\frac{s_{\sigma}(y)}{s_{\tau}(y)} = \frac{h(v_i, v_j)h(v_k, v_{\beta})}{h(v_i, v_{\beta})h(v_k, v_j)},$$

and similarly for y'. The condition $\pi_4(y) = \pi_4(y')$ implies

$$s_{\sigma}(y)/s_{\tau}(y) = s_{\sigma}(y')/s_{\tau}(y').$$

Since $\bar{\lambda}_{ij} = \lambda_{ji}$, then complex number λ_{ij} is real because $\lambda_{ij} = \lambda_{ji}$.

(2) Multiplying and dividing by $h(v'_j, v'_i)/h(v_j, v_i)$ one sees that the positivity of λ_{ij} is equivalent to the positivity of the real number

$$\mu = \frac{h(v'_i, v'_k)}{h(v_i, v_k)} \cdot \frac{h(v'_k, v'_j)}{h(v_k, v_j)} \cdot \frac{h(v'_j, v'_i)}{h(v_j, v_i)}.$$

Suppose dim $(L_i + L_j + L_k) = 3$. The semi-stable points

$$y = ([L_i], [L_j], [L_k]),$$
 $y' = ([L'_i], [L'_j], [L'_k]),$

of X_3 are conjugated under $\mathrm{SL}_n(\mathbb{C})$ thus $\pi_3(y) = \pi_3(y')$. According to Proposition 4.19 the hypothesis $\dim(L_i + L_j + L_k) = 3$ implies that the points y, y' are actually conjugated under $\mathrm{SU}(1, n-1)$, thus $\mu > 0$.

(3) This is based on the following:

Lemma 4.24. Suppose $r \geq 5$ odd. Let $x = (L_1, \ldots, L_r)$ be a semi-stable r-tuple of isotropic lines. There exists $k = 1, \ldots, r$ with the following property: for all $i, j = 1, \ldots, r$ such that the lines L_i, L_j, L_k are pairwise distinct, there exists a derangement $\sigma \in \mathfrak{D}_r$ such that

- (1) $\sigma_{|\{i,j,k\}} = (ijk),$
- (2) the induced derangement $\sigma_{|\{1,...,r\}\smallsetminus\{i,j,k\}}$ is of order 2,
- (3) $s_{\sigma}(x) \neq 0.$

The proof of the preceding Lemma is postponed to the end of the proof. Let k as in the statement. Let i, j = 1, ..., r be such that the lines L_i, L_j, L_k are pairwise distinct. Let σ be a derangement such that $\sigma_{\{i,j,k\}} = (ijk), \sigma$ induces a derangement of order 2 on $\{1, ..., r\} \setminus \{i, j, k\}$ such that $s_{\sigma}(x) \neq 0$. Then,

$$\prod_{\alpha \neq i,j,k} h(v_{\alpha}, v_{\sigma(\alpha)}) = \prod_{\alpha \neq i,j,k} |h(v_{\alpha}, v_{\sigma(\alpha)})| > 0,$$

and similarly for v'_1, \ldots, v'_r . It follows that μ is positive if and only if $s_{\sigma}(x')/s_{\sigma}(x)$ is positive, which is implied by the hypothesis p(x) = p(x').

Proof of Lemma 4.24. If none of the lines L_1, \ldots, L_r is repeated exactly $\frac{r-1}{2}$ times, then every k does the job. Indeed, let $i, j, k = 1, \ldots, r$ be such that the lines L_i, L_j, L_k are pairwise distinct. By contradiction suppose $s_{\sigma}(x) = 0$ for every derangement σ such that $\sigma_{|\{i,j,k\}} = (ijk)$ and $\sigma_{|\{1,\ldots,r\}\smallsetminus\{i,j,k\}}$ is of order 2. Then Proposition 4.15 implies that there is a line repeated at least $\frac{r-1}{2}$ times contradicting the previous assumption.

Suppose there is a line L repeated exactly $\frac{r-1}{2}$ times. Pick k such that $L_k = L$ and let i, j = 1, ..., r be such that the lines L_i, L_j, L_k are pairwise distinct. By contradiction suppose $s_{\sigma}(x) = 0$ for every derangement σ such that $\sigma_{|\{i,j,k\}} = (ijk)$ and $\sigma_{|\{1,...,r\} \setminus \{i,j,k\}}$ is of order 2. Then Proposition 4.15 implies that there is a line L' repeated at least $\frac{r-1}{2}$ times. Necessarily L' = L, thus the line L is repeated at least $\frac{r+1}{2}$ times contradicting the semi-stability of x.

5. Quadruples of planes in \mathbb{C}^4

5.1. Setup. Consider the Grassmannian variety $\operatorname{Gr}(2, 4)$ of 2-dimensional subvector spaces of \mathbb{C}^4 . Two planes W_1 , W_2 are opposite if and only if their intersection is 0. For i = 1, 2 let P_i denote the stabilizer of W_i . The subset $\operatorname{Opp}(W_i)$ of planes opposite to W_i is Zariski open in $\operatorname{Gr}(2, 4)$. Set:

$$V = \mathbb{C}^4$$
, $G = \operatorname{SL}_{4,\mathbb{C}}$, $F = \operatorname{Gr}(2,4)$, $X = F^4$.

The semi-simple group G acts on X. Consider the linearization of this action given by the Plücker embedding,

$$j: X = F^4 \longrightarrow \mathbb{P}(\bigwedge^2 V)^4.$$

The considered linearization corresponds to the line bundle

$$L = j^*(\mathrm{pr}_1^* \mathcal{O}(1) \otimes \cdots \otimes \mathrm{pr}_4^* \mathcal{O}(1))$$

where $\operatorname{pr}_i : \mathbb{P}(\bigwedge^2 V)^4 \to F$ denotes the projection onto the *i*-th factor.

5.2. **Invariants.** Let us introduce some natural invariants for this action. Identify the 1-dimensional vector space $\bigwedge^4 V$ with \mathbb{C} by choosing the basis $e_1 \land e_2 \land e_3 \land e_4$. With this in mind, let $t = w_1 \land w_2$, $t' = w'_1 \land w'_2$ for some vectors w_1, w_2, w'_1, w'_2 of V. Then $t \land t'$ is the determinant of the matrix having w_1, w_2, w'_1, w'_2 as columns,

$$t \wedge t' = \det(w_1, w_2, w_1', w_2').$$

Consider the linear forms,

$$s_{1234}, s_{1324}, s_{1423} \colon (\bigwedge^2 V)^{\otimes 4} \longrightarrow \mathbb{C},$$

defined, for $t_1, t_2, t_3, t_4 \in \bigwedge^2 V$, by

$$s_{1234}(t_1 \otimes t_2 \otimes t_3 \otimes t_4) := t_1 \wedge t_2 \cdot t_3 \wedge t_4, \\ s_{1324}(t_1 \otimes t_2 \otimes t_3 \otimes t_4) := t_1 \wedge t_3 \cdot t_2 \wedge t_4, \\ s_{1423}(t_1 \otimes t_2 \otimes t_3 \otimes t_4) := t_1 \wedge t_4 \cdot t_2 \wedge t_3.$$

They are G-invariant linear forms on $(\bigwedge^2 V)^{\otimes 4}$ hence they induce G-invariant global sections of L:

$$s_{1234}, s_{1324}, s_{1423} \in \mathrm{H}^0(X, L)^G.$$

For i = 1, ..., 4 let w_{i1}, w_{i2} be a basis of W_i . The section s_{1234} evaluated at the vector $w_{11} \wedge w_{12} \otimes \cdots \otimes w_{41} \wedge w_{42}$ takes the value

$$\det(w_{11}, w_{12}, w_{21}, w_{22}) \cdot \det(w_{31}, w_{32}, w_{41}, w_{42}).$$

In particular s_{1234} vanishes at a quadruple (W_1, W_2, W_3, W_4) if and only if

$$W_1 \cap W_2 \neq 0$$
 or $W_3 \cap W_4 \neq 0$.

Similar statements hold for s_{1324} and s_{1423} .

5.3. The quotient.

Theorem 5.1. With notations introduced above:

(1) The graded \mathbb{C} -algebra of G-invariant elements

$$\bigoplus_{d\geq 0} \mathrm{H}^0(X, L^{\otimes d})^G$$

is generated by s_{1234} , s_{1324} and s_{1423} .

- (2) A quadruple (W_1, W_2, W_3, W_4) is semi-stable as a point of X (with respect to the action of G and to the linearization L) if and only if one of the following conditions holds:
 - (a) $W_1 \cap W_2 = 0$ and $W_3 \cap W_4 = 0$;
 - (b) $W_1 \cap W_3 = 0$ and $W_2 \cap W_4 = 0$;
 - (c) $W_1 \cap W_4 = 0$ and $W_2 \cap W_3 = 0$.
- (3) The map $\pi: X^{ss} \to \mathbb{P}^2_{\mathbb{C}}$ defined by $\pi(x) := [s_{1234}(x) : s_{1324}(x) : s_{1423}(x)]$ is *G*-invariant and induces an isomorphism

$$X^{\mathrm{ss}}/G \xrightarrow{\sim} \mathbb{P}^2_{\mathbb{C}}.$$

Proof. (2) and (3) follows from (1).

(1) This is a consequence of the exceptional isogeny $SL_{4,\mathbb{C}} \to SO(6)$ and the invariant theory for SO(6). The wedge product induces a non-degenerate quadratic form on $\bigwedge^2 V$ which is invariant under the action of $SL_{4,\mathbb{C}}$. This gives a map $SL_{4,\mathbb{C}} \to SO(6)$ which is seen to be surjective.

The First Theorem of Invariant Theory for SO(6) states that, a positive integer d being fixed, the subspace of SO(6)-invariant linear forms $\phi: (\bigwedge^2 V)^{\otimes 2d} \to \mathbb{C}$ is generated by products of "contractions", *i.e.* by products of the form

$$\prod_{\alpha=1}^{d} v_{\sigma(\alpha)} \wedge v_{\sigma(2d+\alpha)},$$

for some permutation $\sigma \in \mathfrak{S}_{2d}$ and $v_1, \ldots, v_{2d} \in \bigwedge^2 V$. Refer to [ABP73, Appendix I] for an elegant proof of this fact avoiding the Capelli Identity.

In order to compute the *G*-invariants of $\mathrm{H}^0(X, L^{\otimes d})$ one has to evaluate the afore-mentioned contractions on vectors of the form $(v_1 \otimes \cdots \otimes v_4)^{\otimes d}$, where, for $i = 1, \ldots, 4, W_i$ is a plane of V, w_{i1}, w_{i2} a basis of W_i and $v_i = w_{i1} \wedge w_{i2}$. Evaluated at this point a contraction *s* is of the form

$$\prod_{\alpha=1}^d v_{i_\alpha} \wedge v_{j_\alpha}$$

with $i_{\alpha}, j_{\alpha} \in \{1, \ldots, 4\}$. One may assume $i_{\alpha} < j_{\alpha}$ for every α : indeed, if $i_{\alpha} = j_{\alpha}$ the contraction *s* vanishes. For $i, j = 1, \ldots, 4$ with i < j let a_{ij} be the number of times $v_i \wedge v_j$ appears in the product. Since v_i occurs exactly *d* times in $(v_1 \otimes \cdots \otimes v_4)^{\otimes d}$ one has

$$a_{12} + a_{13} + a_{14} = d,$$

$$a_{12} + a_{23} + a_{24} = d,$$

$$a_{13} + a_{23} + a_{34} = d,$$

$$a_{14} + a_{24} + a_{34} = d.$$

This readily implies

$$a_{12} = a_{34}, \qquad a_{13} = a_{24}, \qquad a_{14} = a_{23}.$$

Thus s is a product of s_{1234} , s_{1324} and s_{1423} .

5.4. Affine charts. Consider the Zariski open subset U of X of quadruples of planes (W_1, W_2, W_3, W_4) such that W_1 is opposite to W_2 and W_4 , and W_2 is also opposite to W_3 . Write a point in $\mathbb{P}^2_{\mathbb{C}}$ as $[t_0: t_1: t_2]$ so that for a semi-stable point $x \in X^{ss}$ one has

$$\pi(x) = [s_{1234}(x) : s_{1324}(x) : s_{1423}(x)] = [t_0 : t_1 : t_2]$$

Set $V := \mathbb{P}^2_{\mathbb{C}} \smallsetminus \{t_2 = 0\}, U := \pi^{-1}(V)$ and
 $W_1 = \langle e_1, e_2 \rangle, \qquad \qquad W_2 = \langle e_3, e_4 \rangle.$

For i = 1, 2 let P_i be the stabilizer of W_i . Since W_1 is opposite to W_2 , for i = 1, 2 the action of $\operatorname{rad}^u(P_i)$ on $\operatorname{Opp}(W_i)$ yields an isomorphism

$$\phi_i \colon \operatorname{rad}^u(P_i) \xrightarrow{\sim} \operatorname{Opp}(W_i),$$
$$u \longmapsto u \cdot W_{3-i}.$$

The map $\operatorname{rad}^{u}(P_1) \times \operatorname{rad}^{u} P_2 \to U$,

$$(u_1, u_2) \longmapsto (W_1, W_2, u_2 \cdot W_1, u_1 \cdot W_2),$$

is P_{12} -equivariant and induces an isomorphism

$$(\operatorname{rad}^{u} P_1 \times \operatorname{rad}^{u} P_2)/P_{12} \xrightarrow{\sim} V.$$

Let us make more explicit the quotient $(\operatorname{rad}^u P_1 \times \operatorname{rad}^u P_2)/P_{12}$. An element of $P_{12} := P_1 \cap P_2$ can be written as

$$\begin{pmatrix} M_1 & 0 \\ 0 & M_2 \end{pmatrix},$$

where M_1, M_2 are 2 × 2 invertible matrices such that det $M_1M_2 = 1$. Such an element will be denoted by the couple (M_1, M_2) . The action of P_{12} on $Opp(W_i)$ induces through ϕ_i the action of P_{12} on $rad^u(P_i)$ by conjugation.¹¹

The Lie algebra of $\operatorname{rad}^{u} P_{1}$ and $\operatorname{rad}^{u} P_{2}$ are respectively made of block matrices of the form

$$\begin{pmatrix} 0 & A_1 \\ 0 & 0 \end{pmatrix}, \qquad \qquad \begin{pmatrix} 0 & 0 \\ A_2 & 0 \end{pmatrix},$$

where A_1, A_2 are 2×2 matrices. Therefore in what follows Lie rad^{*u*} P_i is identified with $M_2(\mathbb{C})$. For i = 1, 2 the exponential map exp: Lie rad^{*u*} $P_i \to rad^u P_i$,

$$\exp(A_1) = \begin{pmatrix} \operatorname{id} & A_1 \\ 0 & \operatorname{id} \end{pmatrix}, \qquad \exp(A_2) = \begin{pmatrix} \operatorname{id} & 0 \\ A_2 & \operatorname{id} \end{pmatrix},$$

is an isomorphism. The adjoint action of P_{12} on $\operatorname{Lie} \operatorname{rad}^u P_1 \times \operatorname{Lie} \operatorname{rad}^u P_2$ is given by

$$(M_1, M_2) \cdot (A_1, A_2) = (M_1 A_1 M_2^{-1}, M_2 A_2 M_1^{-1}).$$

The exponential map is P_{12} -equivariant and induces isomorphisms between the quotients

$$(\operatorname{Lie}\operatorname{rad}^{u} P_{1} \times \operatorname{Lie}\operatorname{rad}^{u} P_{2})/P_{12} \xrightarrow{\sim} (\operatorname{rad}^{u} P_{1} \times \operatorname{rad}^{u} P_{2})/P_{12} \xrightarrow{\sim} V = \mathbb{A}^{2}_{\mathbb{C}}.$$

Proposition 5.2. With the notations introduced above, let $A_i \in \text{Lierad}^u P_i$ for i = 1, 2 and $x = (W_1, W_2, \exp(A_2)W_1, \exp(A_1)W_2)$. Then:

(1) the quotient map $\pi: U \to V$ is given by

$$\pi(x) = [\det(A_1A_2 - \mathrm{id}) : \det(A_1A_2) : 1].$$

¹¹Given $g \in P_1 \cap P_2$ and $h \in \operatorname{rad}^u(P_1)$ one has to find the unique element $h' \in \operatorname{rad}^u(P_1)$ such that $gh \cdot W_2 = h' \cdot W_2$. Since g belongs to stabilizer of W_2 by hypothesis, $gh \cdot W_2 = ghg^{-1} \cdot W_2$. On the other hand ghg^{-1} belongs to $\operatorname{rad}^u(P_1)$ because the unipotent radical is a normal subgroup of P_1 . Thus $h' = ghg^{-1}$.

(2) the orbit of x is closed if and only if the matrices A_1, A_2 are semi-simple and $\operatorname{rk} A_1 = \operatorname{rk} A_2$.

Proof. (1) By definition the invariant section s_{1423} does not vanish on U. The rational functions s_{1234}/s_{1423} , s_{1324}/s_{1423} are regular on U and generate the algebra of $SL_{4,\mathbb{C}}$ -invariant elements. Evaluating at x one obtains:

$$\frac{s_{1234}}{s_{1423}}(x) = \det\begin{pmatrix} \mathrm{id} & A_1\\ A_2 & \mathrm{id} \end{pmatrix} = \det(A_1A_2 - \mathrm{id}),$$

$$\frac{s_{1324}}{s_{1423}}(x) = \det(A_1A_2).$$

(2) If A_1A_2 or A_2A_1 is zero, then the orbit of x is closed if and only if A_1 and A_2 are zero.

Suppose A_1A_2, A_2A_1 non-zero and set $A = A_1A_2$.

If A_1 is invertible, then (id, A) belongs to the orbit of (A_1, A_2) : it suffices to take $M_1 = A^{-1}$ and $M_2 = id$. The stabilizer of (id, A) in P_{12} is given by couples (M_1, M_2) with $M_1 = M_2$ and $M_1A = AM_1$. If the eigenvalues of A are distinct, the stabilizer has dimension ≤ 1 ; on the contrary if they are equal the dimension is ≤ 2 . In both cases the equality is attained if and only if A is semi-simple. This concludes the proof when A is invertible.

Suppose A_1, A_2 are of rank 1. Then A_1, A_2 are automatically semi-simple (their eigenvalues are distinct). It suffices to show that the stabilizer of the couple (A_1, A_2) has dimension 2.

Up to conjugating A_1 by an invertible matrix N (*i.e.* taking $M_1 = M_2 = N$) and up to scalar factors, one may suppose

$$A_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}.$$

Since $rk(A_2) = 1$ and $A_1A_2 \neq 0$ one may write

$$A_2 = \begin{pmatrix} a_1 & a_2 \\ \lambda a_1 & \lambda a_2 \end{pmatrix},$$

with $(a_1, a_2) \in \mathbb{C}^2$ non-zero and $\lambda \in \mathbb{C}$. The hypothesis $A_2A_1 \neq 0$ implies $a_1 \neq 0$ therefore up to dividing by a_1 one may suppose

$$A_2 = \begin{pmatrix} 1 & a \\ \lambda & \lambda a \end{pmatrix},$$

for some $a \in \mathbb{C}$. For $\alpha = 1, 2$ write

$$M_{\alpha} = \begin{pmatrix} m_{11}^{(\alpha)} & m_{12}^{(\alpha)} \\ m_{21}^{(\alpha)} & m_{22}^{(\alpha)} \end{pmatrix}.$$

The condition $M_1A_1 = A_1M_2$ implies

$$m_{11}^{(1)} = m_{11}^{(2)},$$
 $m_{21}^{(1)} = 0,$ $m_{12}^{(2)} = 0,$

whereas $M_2A_2 = A_2M_1$ infers

$$m_{12}^{(1)} = a(m_{11}^{(1)} - m_{22}^{(1)})$$
 $m_{21}^{(2)} = \lambda(m_{11}^{(2)} - m_{22}^{(2)}).$

Imposing the condition det $M_1M_2 = 1$ one obtains that M_1, M_2 are of the form

$$M_1 = \begin{pmatrix} e & a(e-f) \\ 0 & f \end{pmatrix}, \qquad \qquad M_2 = \begin{pmatrix} e & 0 \\ \lambda(e-g) & g \end{pmatrix},$$

with $e, f, g \in \mathbb{C}^{\times}$ such that $e^2 fg = 1$. In particular the stabilizer of (A_1, A_2) has dimension 2.

5.5. **Real forms.** Let G be a real form of $SL_{4,\mathbb{C}}$ admitting a parabolic subgroup of type (2,2) defined over \mathbb{R} . Let F the associated flag variety and $X = F^4$ and L the line bundle induced by the Plücker embedding of $X_{\mathbb{C}}$. Let X^{ss} be the set of semi-stable points of X with respect to G and L. The GIT quotient of X^{ss} by G is the projective space $\mathbb{P}(\mathbb{H}^0(X, L)^G)$ together with the natural map

$$\pi\colon X^{\mathrm{ss}} \longrightarrow \mathbb{P}(\mathrm{H}^0(X, L)^G).$$

5.5.1. $SL_4(\mathbb{R})$. Let $G(\mathbb{R}) = SL_4(\mathbb{R})$ and F be the grassmannian Gr(2,4) over the real numbers. Consider the Plücker embedding

$$i: \operatorname{Gr}(2,4) \longrightarrow \mathbb{P}(\bigwedge^2 \mathbb{R}^4).$$

The global sections $s_{1234}, s_{1324}, s_{1423}$ are defined over \mathbb{R} , that is, they are *G*-invariant global sections of *L*. The quotient map π is thus given by

$$\begin{aligned} \pi \colon X^{\mathrm{ss}} &\longrightarrow & \mathbb{P}^2_{\mathbb{R}} \\ x &\longmapsto & [s_{1234}(x) : s_{1324}(x) : s_{1423}(x)]. \end{aligned}$$

Proposition 5.3. The map $\theta: X^{ss}(\mathbb{R})/SL_4(\mathbb{R}) \to \mathbb{P}^2(\mathbb{R})$ is a homeomorphism.

Proof. It suffices to prove that θ is bijective. This can be checked on affine charts, so that, thanks to isomorphism given by Proposition 5.2, this boils down to proving that the map

$$\begin{aligned} \mathbf{M}_2(\mathbb{R}) \times \mathbf{M}_2(\mathbb{R}) &\longrightarrow & \mathbb{R}^2, \\ & (A_1, A_2) &\longmapsto & (\det(A_1A_2 - \mathrm{id}), \det(A_1A_2)), \end{aligned}$$

induces a bijection $(M_2(\mathbb{R}) \times M_2(\mathbb{R}))/H(\mathbb{R}) \to \mathbb{R}^2$ where

$$H = \{ (M_1, M_2) \in \mathrm{GL}^2_{2,\mathbb{R}} : \det M_1 M_2 = 1 \}$$

is acting on $M_{2,\mathbb{R}} \times M_{2,\mathbb{R}}$ by $(M_1, M_2) \cdot (A_1, A_2) = (M_1 A_1 M_2^{-1}, M_2 A_2 M_1^{-1}).$

The map is clearly surjective, thus only the injectivity is left to show. By Proposition 5.2 (2) the orbit of (A_1, A_2) is closed if and only if A_1, A_2 are semi-simple and $\operatorname{rk}(A_1) = \operatorname{rk}(A_2)$.

If $A_1 = A_2 = 0$ there is nothing to prove.

If $\operatorname{rk}(A_1) = \operatorname{rk}(A_2) = 1$ then it follows from the proof of Proposition 5.2 that the stabilizer in H of the couple (A_1, A_2) isomorphic to $\mathbb{G}_{m,\mathbb{R}}^2$. Denote by T the orbit of (A_1, A_2) under H (as real algebraic variety). Then, Theorem 2.4 implies $\operatorname{H}^1(\mathbb{R}, \mathbb{G}_{m,\mathbb{R}}^2) = 0$ thus $T(\mathbb{R})/H(\mathbb{R}) = \{*\}$ by Proposition 2.5.

If A_1 , A_2 are invertible, then the couple (A_1, A_2) belongs to the orbit of (id, A_1A_2) . Setting $A = A_1A_2$ and $M_1 = M_2$, one is led back to understand the separated quotient of $M_2(\mathbb{R})$ by conjugation by the subgroup of matrices in $GL_2(\mathbb{R})$ of determinant ± 1 . The orbit of a matrix $A \in M_2(\mathbb{R})$ under $GL_2(\mathbb{R})$ is closed if and only if A is semi-simple. Moreover, semi-simple matrices are classified up to $GL_2(\mathbb{R})$ -conjugacy by their characteristic polynomial. Therefore, if $A, B \in M_2(\mathbb{R})$ verify det $A = \det B$, $\operatorname{Tr} A = \operatorname{Tr} B$ then there exists $g \in GL_2(\mathbb{R})$ such that $B = gAg^{-1}$.

Set $g' := |\det g|^{-1/2}g$. Then $B = g'Ag'^{-1}$ and $|\det g'| = 1$. This concludes the proof.

5.5.2. SU(2, 2). Let h be a hermitian form of signature (2, 2). Up to changing coordinates we may assume that it is given by the matrix

$$\begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

Let $\mathrm{SU}(2,2)$ be the subgroup of $\mathrm{SL}_4(\mathbb{C})$ respecting this hermitian form and let G be the real form of $\mathrm{SL}_{4,\mathbb{C}}$ such that $G(\mathbb{R}) = \mathrm{SU}(2,2)$. Let F be the flag variety of G corresponding to the grassmannian $\mathrm{Gr}(2,4)$. The involution σ defining F associates to a complex plane W in \mathbb{C}^4 its orthogonal W^{\perp} with respect the hermitian form h. The fixed points are the isotropic planes of \mathbb{C}^4 . Consider the isotropic planes

$$W_1 = \langle e_1, e_2 \rangle, \qquad W_2 = \langle e_3, e_4 \rangle.$$

For $\alpha = 1, 2$ let P_{α} the parabolic subgroup of G stabilizing x_{α} . The Lie algebra of rad^{*u*} P_{α} can be identified with the real vector space of 2 × 2 matrices of the form

$$\begin{pmatrix} a & ib \\ ic & -\bar{a} \end{pmatrix}$$

with $a \in \mathbb{C}$, $b, c \in \mathbb{R}$ and $i^2 = -1$.

Lemma 5.4. The global sections s_{1234} , s_{1324} and s_{1423} are defined over \mathbb{R} .

Proof. It suffices to verify the following statement: for $\alpha = 1, 2, A_{\alpha} \in \text{Lie rad}^{u} P_{\alpha}$ and $x = (W_1, W_2, \exp(A_2)W_1, \exp(A_1)W_2)$ then the complex numbers

$$\frac{S_{1234}}{S_{1423}}(x) = \det(A_1A_2 - \mathrm{id}) = \det(A_1A_2) - \mathrm{Tr}(A) + 1,$$

$$\frac{S_{1324}}{S_{1423}}(x) = \det(A_1A_2),$$

are real. For $\alpha = 1, 2$ write

$$A_{\alpha} = \begin{pmatrix} a_{\alpha} & ib_{\alpha} \\ ic_{\alpha} & -\bar{a}_{\alpha} \end{pmatrix},$$

with $a_{\alpha} \in \mathbb{C}, b_{\alpha}, c_{\alpha} \in \mathbb{R}$. Then,

$$A_1 A_2 = \begin{pmatrix} a_1 a_2 - b_1 c_2 & i(a_1 b_2 - b_1 \bar{a}_2) \\ i(c_1 a_2 - \bar{a}_1 c_2) & \bar{a}_1 \bar{a}_2 - b_2 c_1 \end{pmatrix},$$

and

$$Tr(A_1A_2) = 2 \operatorname{Re}(a_1a_2) - b_1c_2 - b_2c_1,$$
$$det(A_1A_2) = (|a_1|^2 - b_1c_1)(|a_2|^2 - b_2c_2),$$

which are real.

Let H be the real form of $\operatorname{GL}_{2,\mathbb{C}}$ such that $H(\mathbb{R})$ is the subgroup of elements respecting the hermitian form on \mathbb{C}^2 given by the matrix

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

Proposition 5.5. The map $\theta: X^{ss}(\mathbb{R})/SU(2,2) \to \mathbb{P}^2(\mathbb{R})$ is a homeomorphism.

Proof. It suffices to verify the statement on the chart $\{t_2 \neq 0\}$ in $\mathbb{P}^2(\mathbb{R})$. Surjectivity is easy. Indeed, take

$$A_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \qquad \qquad A_2 = \begin{pmatrix} a & ib \\ ic & -\bar{a} \end{pmatrix},$$

with $a \in \mathbb{C}$, $b, c \in \mathbb{R}$ and $i^2 = -1$. Then by Proposition 5.2 the projection of the semi-stable point $x = (W_1, W_2, \exp(A_2)W_1, \exp(A_1)W_2)$ is

$$\pi(x) = [|a|^2 - bc - 2\operatorname{Re}(a) + 1 : |a|^2 - bc : 1]$$

Since there are no constraints on a, b, c, the map is seen to be surjective.

For the injectivity one is led back to the situation discussed in the proof of Proposition 5.3 because the subgroup

$$\{g \in H(\mathbb{R}) : \det g = \pm 1\},\$$

is conjugated in $GL_2(\mathbb{C})$ to the subgroup

$$\{g \in \operatorname{GL}_2(\mathbb{R}) : \det g = \pm 1\}.$$

The remaining details are left to the reader.

5.5.3. $\operatorname{SL}_2(\mathbb{H})$. Let \mathbb{H} be the quaternions and let i, j, k be generators satisfying the usual relations. Let $\mathbb{P}^1(\mathbb{H})$ be the set of rank 1 right \mathbb{H} -modules of \mathbb{H}^2 . For a non-zero $(x, y) \in \mathbb{H}^2$ the right \mathbb{H} -module that it generates is denoted [x : y]. The group $\operatorname{GL}_2(\mathbb{H})$ acts on $\mathbb{P}^1(\mathbb{H})$ on the left: for

$$g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \mathrm{GL}_2(\mathbb{H}),$$

and $(x, y) \in \mathbb{H}^2$ non-zero,

$$g \cdot [x:y] = [ax + by: cx + dy].$$

Let G the real form of $SL_4(\mathbb{C})$ such that $G(\mathbb{R}) = SL_2(\mathbb{H})$. Let F the flag variety of G corresponding to the Grassmannian of planes in \mathbb{C}^4 . The anti-holomorphic involution σ defining F associates to a complex plane $\langle x, y \rangle$ the plane $\langle \tau(x), \tau(y) \rangle$, where

$$\tau(x_1, x_2, x_3, x_4) = (-\bar{x}_2, \bar{x}_1, -\bar{x}_4, \bar{x}_3).$$

Fixed points under the anti-holomorphic involution σ are planes of \mathbb{C}^4 of the form $\langle x, \tau(x) \rangle$ for a non-zero $x \in \mathbb{C}^4$. The correspondence between real points of F and points of $\mathbb{P}^1(\mathbb{H})$ is given by

$$F(\mathbb{R}) \longrightarrow \mathbb{P}^{1}(\mathbb{H})$$

(x₁, x₂, x₃, x₄) $\longmapsto [x_1 + jx_2 : x_3 + jx_4].$

Proposition 5.6. The sections $s_{1234}, s_{1324}, s_{1423}$ are defined over \mathbb{R} .

Proof. This follows from the identity

$$\begin{vmatrix} -\bar{x}_2 & -\bar{y}_2 & -\bar{x}'_2 & -\bar{y}'_2 \\ \bar{x}_1 & \bar{y}_1 & \bar{x}'_1 & \bar{y}'_1 \\ -\bar{x}_4 & -\bar{y}_4 & -\bar{x}'_4 & -\bar{y}'_4 \\ \bar{x}_3 & \bar{y}_3 & \bar{x}'_3 & \bar{y}'_3 \end{vmatrix} = \begin{vmatrix} x_1 & y_1 & x'_1 & y'_1 \\ x_2 & y_2 & x'_2 & y'_2 \\ x_3 & y_3 & x'_3 & y'_3 \\ x_4 & y_4 & x'_4 & y'_4 \end{vmatrix},$$

for $x, y, x', y' \in \mathbb{C}^4$.

The map $\pi \colon \mathbb{P}^1(\mathbb{H})^{4,\mathrm{ss}} \to \mathbb{P}^2(\mathbb{R})$ is therefore given by

 $\pi(x) = [s_{1234}(x) : s_{1324}(x) : s_{1423}(x)].$

Proposition 5.7. A quadruple of points in $\mathbb{P}^1(\mathbb{H})$ is semi-stable if and only if no point is repeated more than twice.

Proof. Let $L_1, L_2 \subset \mathbb{H}^2$ be rank 1 right \mathbb{H} -modules and let $W_1, W_2 \subset \mathbb{C}^4$ be the corresponding complex planes. If W_1, W_2 meet then $L_1 \cap L_2$ is a right \mathbb{H} -module of rank 1. Therefore L_1 and L_2 coincide.

The previous observation implies that the section s_{1234} vanishes at a quadruple $x = (L_1, \ldots, L_4)$ of points in $\mathbb{P}^1(\mathbb{H})$ if and only if $L_1 = L_2$ or $L_3 = L_4$. The statement follows immediately.

Consider the points $x_1 = [1:0]$ and $x_2 = [0:1]$. For $\alpha = 1, 2$ let P_{α} the parabolic subgroup of G stabilizing x_{α} . Identify Lie rad^{*u*} P_{α} with \mathbb{H} . Then the quotient map given by Proposition 5.2 induces the following map on real points:

(5.5.1) $\begin{aligned} \mathbb{H} \times \mathbb{H} &\longrightarrow \mathbb{P}^2(\mathbb{R}), \\ (q_1, q_2) &\longmapsto [|q_1 q_2 - 1|^2 : |q_1 q_2|^2 : 1]. \end{aligned}$

Proposition 5.8. With the notations introduced above:

(1) the image of π is the subset

$$S = \{ [t_0: t_1: t_2] \in \mathbb{P}^2(\mathbb{R}) : t_0^2 + t_1^2 + t_2^2 \le 2(t_0t_1 + t_0t_2 + t_1t_2) \};$$

- (2) the induced map $\theta \colon \mathbb{P}^1(\mathbb{H})^{4, ss} / \operatorname{SL}_2(\mathbb{H}) \to S$ is a homeomorphism;
- (3) a quadruple $(x_1, \ldots, x_4) \in X^{ss}(\mathbb{R})$ is made of pairwise distinct points if and only if

$$\pi(x_1, \dots, x_4) \in \{ [t_0 : t_1 : t_2] \in \mathbb{P}^2(\mathbb{R}) : t_0 t_1 t_2 \neq 0 \}.$$



FIGURE 2. Through the map θ one can see the separated quotient $\mathbb{P}^1(\mathbb{H})^{4,ss}/\operatorname{SL}_2(\mathbb{H})$ as the filled conic in the figure. It is a parabola in the complement of each coordinate axis. The three points of tangency correspond to the degenerate quadruples. Points on the boundary of the conic correspond to configurations whose quaternionic cross-ratio is real.

Proof. It suffices to verify the assertions (1) and (2) on the affine chart $\{t_2 \neq 0\}$. (1) For $q_1, q_2 \in \mathbb{H}$ set $q = q_1q_2$ and $[t_0: t_1: t_2] = [|q-1|^2: |q|^2: 1]$. Then,

$$\left(\frac{t_1 + t_2 - t_0}{t_0}\right)^2 = 4\operatorname{Re}(q)^2 \le 4|q|^2 = \frac{t_1}{t_2}.$$

In order to see that π_0 is onto the subset S it suffices to consider $(q_1, q_2) = (1, q)$.

(2) It suffices to prove that π is injective. If $q_1 = 0$ the unique closed orbit contained in the closure of the orbit (q_1, q_2) in \mathbb{H}^2 is (0, 0). If $q_1 \neq 0$, then (q_1, q_2) lies in the same orbit of $(1, q_1q_2)$. Set $q = q_1q_2$. There exists $h \in \mathbb{H}^{\times}$ and $\lambda \in \mathbb{C}$

(unique up to complex conjugation) such that $h\lambda h^{-1} = q.^{12}$ On the other hand,

$$|q|^2 = |\lambda|^2,$$
 $|q-1|^2 = |\lambda|^2 - 2\operatorname{Re}(\lambda) + 1,$

thus $\pi(q_1, q_2)$ determines λ up to complex conjugation.

(3) is clear.

The map π is related to the notion of quaternionic cross-ratio. Let x_1, \ldots, x_4 be four pairwise distinct points of $\mathbb{P}^1(\mathbb{H})$. Then there exists $g \in GL_2(\mathbb{H})$ such that

$$g \cdot x_1 = [0:1],$$
 $g \cdot x_2 = [1:1],$ $g \cdot x_3 = [1:0].$

Let $q \in \mathbb{H}^{\times}$ be such that $g \cdot x_4 = [q:1]$. Over the complex numbers one defines the cross-ratio of x_1, \ldots, x_4 as q. However in this situation q is not well-defined. Indeed, the subgroup $\{g \in \operatorname{GL}_2(\mathbb{H}) : gx_i = x_i \text{ for } i = 1, 2, 3\}$ is the subgroup of matrices $h \cdot \operatorname{id}$ with $h \in \mathbb{H}^{\times}$ and

$$[hq:h] = [hqh^{-1}:1]$$

as right \mathbb{H} -modules of rank 1. The quaternion q is thus well-defined only up to conjugation.

Definition 5.9. The quaternionic cross-ratio of x_1, \ldots, x_4 is the conjugacy class [q] of the quaternion q.

In the literature the quaternionic cross-ratio is defined in various manners, depending on the way the quotient $\mathbb{H}^{\times}/\mathbb{H}^{\times}$ is presented (\mathbb{H}^{\times} acting on itself by conjugation). For instance, the map

$$\begin{aligned} \mathbb{H}^{\times}/\mathbb{H}^{\times} &\longrightarrow & \mathbb{R}^2, \\ [q] &\longmapsto & (|q|, \operatorname{Re} q) \end{aligned}$$

is well-defined (the modulus and the real part of a quaternion are invariant under conjugation) and injective¹³. In [GL12] the quaternionic cross-ratio is defined as the image of the quaternionic cross-ratio in the present sense through the preceding map.

Proposition 5.10. Let x_1, \ldots, x_4 be four distinct points of $\mathbb{P}^1(\mathbb{H})$ and let [q] their quaternionic cross-ratio. Then,

$$\pi(x_1,\ldots,x_4) = [|q-1|^2:|q|^2:1].$$

The quaternionic cross-ratio is real if and only if

$$\pi(x_1,\ldots,x_4) \in \{ [t_0:t_1:t_2] \in \mathbb{P}^2(\mathbb{R}) : t_0^2 + t_1^2 + t_2^2 = 2(t_0t_1 + t_0t_2 + t_1t_2) \}.$$

This shows in particular that the notion of quaternionic cross-ratio can be extended as a function taking values in $\mathbb{P}^2(\mathbb{R})$ and defined on the set of quadruples of points in $\mathbb{P}^1(\mathbb{H})$ whose entries are not repeated more than twice.

$$A = \begin{pmatrix} a & -\bar{b} \\ b & \bar{a} \end{pmatrix},$$

$$UAU^{-1} = \begin{pmatrix} \lambda & 0\\ 0 & \overline{\lambda} \end{pmatrix}.$$

 13 This is essentially the proof of (2) in the preceding Proposition.

 \square

¹²This can be seen as follows. Write q as a matrix

with $a, b \in \mathbb{C}$. The matrix A commutes with its adjoint, thus there is an orthonormal basis of \mathbb{C}^2 made of eigenvectors. In other words there exists $U \in U(2)$ and $\lambda \in \mathbb{C}$ such that

Proof. Since the quaternionic cross-ratio is invariant under the action of $GL_2(\mathbb{H})$ it suffices to verify the statement for the quadruple

$$x_1 = [0:1],$$
 $x_2 = [1:1],$ $x_3 = [1:0],$ $x_4 = [q:1].$

In this case the formula follows from the expression given in (5.5.1).

For the second part remark that q is real if and only if $|q| = |\operatorname{Re}(q)|$. Then the statement follows from the equality $|q-1|^2 = |q|^2 - 2\operatorname{Re}(q) + 1$.

The injectivity of $\theta: X^{ss}(\mathbb{R})/\operatorname{SL}_2(\mathbb{H}) \to \mathbb{P}^2(\mathbb{R})$ and the previous expression for π prove:

Corollary 5.11 ([GL12, Theorem 8]). Let (x_1, \ldots, x_4) , (y_1, \ldots, y_4) be quadruplets of pairwise distinct points in $\mathbb{P}^1(\mathbb{H})$.

Then there exists $g \in SL_2(\mathbb{H})$ such that $g \cdot x_{\alpha} = y_{\alpha}$ for $\alpha = 1, 2, 3, 4$ if and only if their quaternionic cross-ratio coincide.

6. Coordinates for generic configurations

Cross ratios and triple ratios for complete flags are classical invariants of flags and have been used by Fock and Goncharov ([FG07]) to describe higher Teichmüller spaces for representations of surface groups. They have also been used to study representations of fundamental groups of three manifolds in (see [BFG14], [GGZ15], [DGG16]).

In this section cross ratios for complete flags are related to the invariants introduced in the preceding sections of the associated partial flags. Explicit computations with these coordinates allow us to obtain representations of fundamental groups of three manifolds with values in real forms of $SL(n, \mathbb{C})$ or $PGL(n, \mathbb{C})$.

6.1. Generic flags. Let $n, r \ge 1$ be positive integers, $\operatorname{Flag}(V)$ the variety of complete flags of $V = \mathbb{C}^n$ and $X = \operatorname{Flag}(V)^r$.

Let $\mathcal{O}(1,\ldots,1)$ be the line bundle $\operatorname{pr}_1^* \mathcal{O}(1) \otimes \cdots \otimes \operatorname{pr}_{n-1}^* \mathcal{O}(1)$ on the variety

$$\prod_{i=1}^{n-1} \mathbb{P}(\bigwedge^i V),$$

where pr_i is the projection onto the *i*-th factor. The semi-simple group G = SL(V) acts on X. Consider the linearization of this action given by the embedding

$$\iota\colon X\longrightarrow \left(\prod_{i=1}^{n-1}\mathbb{P}(\bigwedge^i V)\right)^r.$$

This linearization corresponds to the G-linearized line bundle

$$L = \iota^*(\operatorname{pr}_1^* \mathcal{O}(1, \ldots, 1) \otimes \cdots \otimes \operatorname{pr}_r^* \mathcal{O}(1, \ldots, 1)),$$

where $pr_i: X \to F$ denotes the projection onto the *i*-th factor.

Definition 6.1. Let $r \ge 1$ be a positive integer and for $i = 1, \ldots, r$ let

$$F^{(i)}: F_0^{(i)} = 0 \subset F_1^{(i)} \subset F_2^{(i)} \subset \dots \subset F_{n-1}^{(i)} \subset F_n^{(i)} = V_2$$

be a complete flag of V. The configuration $(F^{(1)}, \ldots, F^{(r)})$ is said to be *generic* if, for all $\alpha_1, \ldots, \alpha_r = 0, \ldots, n$ such that $\alpha_1 + \cdots + \alpha_r = n$,

$$\dim_{\mathbb{C}}(F_{\alpha_1}^{(1)} + \dots + F_{\alpha_r}^{(r)}) = n.$$

The subset of X made of generic r-tuples is denoted X^{gen} .

6.2. Generic invariants. Let $A_{n,r}$ be the set of r-tuples $\alpha = (\alpha_1, \ldots, \alpha_r)$ made of integers $\alpha_i = 0, \ldots, n$ such that $\alpha_1 + \cdots + \alpha_r = n$. Consider the product of Grassmannians

$$X_{\alpha} = \operatorname{Gr}_{\alpha_1}(V) \times \cdots \times \operatorname{Gr}_{\alpha_r}(V),$$

and the Plücker embedding $\iota_{\alpha} \colon X_{\alpha} \longrightarrow \mathbb{P}(\bigwedge^{\alpha_1} V) \times \cdots \times \mathbb{P}(\bigwedge^{\alpha_r} V)$. Denote by L_{α} the line bundle

$$\iota_{\alpha}^{*}(\mathrm{pr}_{1}^{*}\mathcal{O}(1)\otimes\cdots\otimes\mathrm{pr}_{r}^{*}\mathcal{O}(1))$$

on X_{α} . The semi-simple group G = SL(V) acts naturally on X_{α} , the Plücker embedding ι_{α} is *G*-equivariant and L_{α} is an ample *G*-linearized line bundle. The wedge product induces a linear map

$$s_{\alpha} \colon \bigwedge^{\alpha_{1}} V \otimes \cdots \otimes \bigwedge^{\alpha_{r}} V \longrightarrow \bigwedge^{n} V$$
$$t_{\alpha_{1}} \otimes \cdots \otimes t_{\alpha_{r}} \longmapsto t_{\alpha_{1}} \wedge \cdots \wedge t_{\alpha_{r}}.$$

Identify $\bigwedge^n V$ with \mathbb{C} by fixing $e_1 \land \cdots \land e_n$ as basis. Then s_α can be seen as *G*-invariant linear form on $\bigwedge^{\alpha_1} V \otimes \cdots \otimes \bigwedge^{\alpha_r} V$, thus a *G*-invariant global section of the line bundle L_α . For $\alpha \in A_{n,r}$ let $\operatorname{pr}_\alpha \colon X \to X_\alpha$ be the projection

$$\operatorname{pr}(F) = (F_{\alpha_i}^{(1)}, \dots, F_{\alpha_r}^{(r)}).$$

Let X^{ss} be the open subset of semi-stable points of X with respect the action of G and the linearization L and $\pi: X^{ss} \to Y$ be the GIT quotient of X^{ss} by G.

Proposition 6.2. A generic r-tuple of complete flags F is a semi-stable point of X with respect the polarization L.

Proof. We prove the statement when r is even, leaving the odd case to the reader. Write r = 2r' and, for i = 1, ..., r' and $\ell = 1, ..., n-1$ let

$$\alpha_{i\ell} = (0, \ldots, \ell, 0, \ldots, n - \ell, 0, \ldots, 0),$$

where the ℓ is the *i*-th position and $n - \ell$ in the (r' + i)-th position. Set also

$$\beta_{i\ell} = (0, \dots, n - \ell, 0, \dots, \ell, 0, \dots, 0),$$

with the same conventions. Consider the global section

$$s_{i\ell} = \operatorname{pr}_{\alpha_{i\ell}}^* s_{\alpha_{i\ell}} \otimes \operatorname{pr}_{\beta_{i\ell}}^* s_{\beta_{i\ell}},$$

of the line bundle $\operatorname{pr}_{\alpha_{i\ell}}^* L_{\alpha_{i\ell}} \otimes \operatorname{pr}_{\beta_{i\ell}}^* L_{\beta_{i\ell}}$ on X. The global section $s_{i\ell}$ does not vanish at F as

$$F_{\ell}^{(i)} \cap F_{n-\ell}^{(r'+i)} = 0, \qquad \qquad F_{n-\ell}^{(i)} \cap F_{\ell}^{(r'+i)} = 0.$$

Therefore

$$s = \bigotimes_{\ell=1}^{n-1} \bigotimes_{i=1}^{r'} s_{i\ell}$$

is a G-invariant global section of L which does not vanish at F. In particular, F is semi-stable. $\hfill \Box$

Let $\operatorname{Flag}_{1,n-1}(V)$ be the variety of couples (L, H) made of a line L and a hyperplane H containing it and $X_{1,n-1} = \operatorname{Flag}_{1,n-1}(V)^r$. Let $X_{1,n-1}^{ss}$ be the open subset of semi-stable points of $X_{1,n-1}$ under the action of G and with respect to the Plücker embedding (*cf.* Section 4.5) and $\pi_{1,n-1}: X_{1,n-1}^{ss} \to Y_{1,n-1}$ the GIT quotient of $X_{1,n-1}^{ss}$ by G.

6.3. Triplets of flags. Suppose r = 3. Let $F = (F^{(1)}, F^{(2)}, F^{(3)})$ be a generic triple of complete flags. For $\alpha \in A_{n,3}$ let $\Delta_{\alpha} := \operatorname{pr}^*_{\alpha} s_{\alpha}$.

Definition 6.3. (see [FG07] pg. 133) For a triple $\alpha = (\alpha_1, \alpha_2, \alpha_3)$ of integers $\alpha_i = 1, \ldots, n-1$ such that $\alpha_1 + \alpha_2 + \alpha_3 = n$ define

$$t_{\alpha} := \frac{\Delta_{\alpha+(0,-1,1)} \otimes \Delta_{\alpha+(1,0,-1)} \otimes \Delta_{\alpha+(-1,1,0)}}{\Delta_{\alpha+(1,-1,0)} \otimes \Delta_{\alpha+(0,1,-1)} \otimes \Delta_{\alpha+(-1,0,1)}}.$$

Remark that both the numerator and the denominator of t_{α} are global sections of the line bundle $L_{\alpha}^{\otimes 3}$, so that t_{α} is a well-defined rational function $X \dashrightarrow \mathbb{P}^1$ called the *triple ratio* relative to the index α .



FIGURE 3. The triple ratio T_{α} .

For a triple $\alpha = (\alpha_1, \alpha_2, \alpha_3)$ of integers $\alpha_i = 1, \ldots, n-1$ such that $\alpha_1 + \alpha_2 + \alpha_3 = n$ the map $t_{\alpha} \colon X \dashrightarrow \mathbb{P}^1$ is *G*-invariant, thus factors in a unique way through a rational map on the quotient $t_{\alpha} \colon Y \dashrightarrow \mathbb{P}^1$. Since there are $\frac{(n-1)(n-2)}{2}$ triple ratios, they induce a rational map

$$t: Y \longrightarrow (\mathbb{P}^1)^{(n-1)(n-2)/2}$$
$$[F] \longmapsto (t_{\alpha}(F))_{\alpha}.$$

One can state the fact that the triple ratio parametrizes configurations of three complete flags (see [FG07]) as follows:

Proposition 6.4. With the notations introduced above,

- (1) $\pi(X^{\text{gen}})$ is an open subset of Y;
- (2) the rational map t is regular on $\pi(X^{\text{gen}})$ and induces an isomorphism

$$t: \pi(X^{\text{gen}}) \xrightarrow{\sim} (\mathbb{P}^1 \setminus \{0, \infty\})^{(n-1)(n-2)/2}$$

The GIT quotient of $X_{1,n-1}^{ss}$ by G is \mathbb{P}^1 and the projection on the quotient $\pi_{1,n-1}$ is given, for a semi-stable triplet $x = \{(L_i, H_i)\}_{i=1,2,3}$, by

$$\pi_{1,n-1}(x) = [\phi_1(v_2)\phi_2(v_3)\phi_3(v_1):\phi_1(v_3)\phi_3(v_2)\phi_2(v_1)].$$

The natural projection $p_{1,n-1} \colon X \to X_{1,n-1}$ is *G*-equivariant, therefore it induces a rational map between quotients $\tilde{p}_{1,n-1} \colon Y \dashrightarrow \mathbb{P}^1$.

Proposition 6.5. With these notations, the rational map $\tilde{p}_{1,n-1}: Y \dashrightarrow \mathbb{P}^1$ is the product of all triple ratios.

Proof. It is easy to see that the product of all triple ratios simplifies to

$$\frac{\Delta_{(n-1,1,0)} \otimes \Delta_{(0,n-1,1)} \otimes \Delta_{(1,0,n-1)}}{\Delta_{(n-1,0,1)} \otimes \Delta_{(1,n-1,0)} \otimes \Delta_{(0,1,n-1)}}.$$

Indeed each factor $\Delta_{(i,j,k)}$ appears in the numerator and the denominator the same number of times except for the terms above which correspond to the nearest points at the three vertices of the triangle as in Figure.



FIGURE 4

Observe than that $\Delta_{(n-1,1,0)} = \phi_1(v_2)$ where ϕ_1 is a linear form defining the hyperplane $F_{n-1}^{(1)}$ and v_2 is a generator of the line $F_1^{(2)}$. The analogous formulas for the other terms yield the desired result.

Example 6.6 (n = 3, [FG07, BFG14]). In this case there is just one triple ratio (corresponding to the index (1, 1, 1), see Figure 5) and the map \tilde{p} induces an isomorphism $Y \simeq \mathbb{P}^1$.



FIGURE 5

However, for a complete flag being generic is a weaker condition than being in general position. More precisely, for i = 1, 2, 3, let $F^{(i)} = (L_i, H_i)$ be a complete flag of $V = \mathbb{C}^3$. Then the triplet $F = (F^{(1)}, F^{(2)}, F^{(3)})$ is

- generic if and only if L₁ + L₂ + L₃ = V and L_i ∩ H_j = 0 for all i ≠ j;
 in general position if and only if it is generic and H₁ ∩ H₂ ∩ H₃ = 0.

For i = 1, 2, 3 let v_i be a generator of L_i and ϕ_i a linear form defining H_i . If F is generic, then the triple ratio

$$t_{(1,1,1)}(F) = \frac{\phi_1(v_2)\phi_2(v_3)\phi_3(v_1)}{\phi_1(v_3)\phi_3(v_2)\phi_2(v_1)},$$

is a non-zero complex number. If $\dim(L_1 + L_2 + L_3) = 2$ then $t_{(1,1,1)}(F) = -1$. For instance consider:

$$\begin{split} L_1 &= \langle e_1 \rangle, & L_2 &= \langle e_2 \rangle, & L_3 &= \langle e_1 + e_2 \rangle, \\ H_1 &= \{ x_2 + x_3 = 0 \}, & H_2 &= \{ x_1 + x_3 = 0 \}, & H_3 &= \{ x_1 - x_2 = 0 \} \end{split}$$

Then F is generic but not in general position. Moreover, the orbit of F is not closed (*cf.* Proposition 4.8).

6.4. Quadruples of flags. Suppose r = 4. For a quadruple $F = (F^{(1)}, \ldots, F^{(4)})$ of complete flags of V and $\alpha \in A_{n-2,4}$ consider the following subspace of V:

$$E_{\alpha}(F) = F_{\alpha_1}^{(1)} + F_{\alpha_2}^{(2)} + F_{\alpha_3}^{(3)} + F_{\alpha_4}^{(4)}.$$

If the quadruple F is generic, then

$$\dim_{\mathbb{C}} E_{\alpha}(F) = \sum_{i=1}^{4} \dim_{\mathbb{C}} F_{\alpha_i}^{(i)} = \alpha_1 + \dots + \alpha_4 = n - 2.$$

For $i = 1, \ldots, 4$ the vector subspace of $V/E_{\alpha}(F)$,

$$L_{i} = (F_{\alpha_{i}+1}^{(i)} + E_{\alpha}(F)) / E_{\alpha}(F),$$

is of dimension 1. Let $\chi_{\alpha}(F) \in \mathbb{P}^{1}(\mathbb{C})$ be the cross-ratio of the points

$$[L_1],\ldots,[L_4] \in \mathbb{P}(V/E_{\alpha}(F)).$$

This defines a rational map $\chi_{\alpha} \colon X \dashrightarrow \mathbb{P}^{1}$. Since χ_{α} is *G*-invariant it induces a rational map on the quotient $\chi_{\alpha} \colon Y \dashrightarrow \mathbb{P}^{1}$. Putting together all these rational maps, one obtains a rational map

$$\chi\colon Y \dashrightarrow (\mathbb{P}^1)^{\#A_{n-2,4}}.$$

In the literature the functions χ_{α} are often denote by z_{α} . Here we adopted the letter χ in order to avoid confusion in the case of complete flags in a space of dimension 3 (Example 6.9). We refer to [FG07] and its references for the following:

Proposition 6.7. With the notations introduced above,

- (1) $\pi(X^{\text{gen}})$ is an open subset of Y;
- (2) the rational map χ is regular on $\pi(X^{\text{gen}})$ and induces an embedding

$$\chi \colon \pi(X^{\text{gen}}) \longrightarrow (\mathbb{P}^1 \smallsetminus \{0, \infty\})^{\#A_{n-2,4}}$$

The quotient Y' is embedded in \mathbb{P}^8 through derangements. Going back to the notations introduced in Section 4.5, set

$$w_{12} = \frac{x_5}{x_8}, \quad w_{13} = \frac{x_9}{x_2}, \quad w_{14} = \frac{x_3}{x_5}, \quad w_{23} = \frac{x_1}{x_3}, \quad w_{24} = \frac{x_2}{x_1}, \quad w_{34} = \frac{x_5}{x_6}.$$

Let $x' = \{(L_i, H_i)\}_{i=1,...,4}$ be a quadruple of flags line-hyperplane such that L_i is not contained in H_j for $i \neq j$. Then, for all i < j,

$$w_{ij}(F) = \frac{\phi_i(v_\alpha)\phi_j(v_\beta)}{\phi_i(v_\alpha)\phi_j(v_\beta)},$$

where $\{i, j, \alpha, \beta\} = (1, 2, 3, 4).$

Proposition 6.8. Let F be a generic quadruple of complete flags. Write

$$\chi_{\alpha} := \chi_{\alpha}(F) \text{ for } \alpha \in A_{n-2,4}, \qquad \qquad w_{ij} := w_{ij}(p(F)) \text{ for } i < j.$$

Then,

$$\begin{split} w_{12} &= \prod_{i+j=n-2} \chi_{ij00}, & w_{34} = \prod_{i+j=n-2} \chi_{00ij}, \\ w_{14} &= \prod_{i+j=n-2} 1 - \frac{1}{\chi_{i00j}}, & w_{23} = \prod_{i+j=n-2} 1 - \frac{1}{\chi_{0ij0}}, \\ w_{24} &= \prod_{i+j=n-2} \frac{1}{1 - \chi_{0i0j}}, & w_{13} = \prod_{i+j=n-2} \frac{1}{1 - \chi_{i0j0}}. \end{split}$$

Proof. We prove the first equality, the others being obtained analogously. For nonnegative integers α , β such that $\alpha + \beta = n - 1$ let $\phi_{\alpha\beta}$ be a linear form on V defining the hyperplane $F_{\alpha}^{(1)} + F_{\beta}^{(2)}$. Let v_3, v_4 be respectively generators of the lines $F_1^{(3)}$ and $F_1^{(4)}$. With these notations and setting $E = F_i^{(1)} + F_j^{(2)}$, the cross-ratio of the lines

$$(F_{i+1}^{(1)}+E)/E, \qquad (F_{j+1}^{(2)}+E)/E, \qquad (F_1^{(3)}+E)/E, \qquad (F_1^{(4)}+E)/E,$$
 is

$$\frac{\phi_{i+1,j}(v_3)\phi_{i,j+1}(v_4)}{\phi_{i+1,j}(v_4)\phi_{i,j+1}(v_3)}.$$

Therefore,

$$\prod_{i+j=n-2} \chi_{ij00} = \prod_{i=0}^{n-2} \frac{\phi_{i,n-1-i}(v_4)\phi_{i+1,n-2-i}(v_3)}{\phi_{i,n-1-i}(v_3)\phi_{i+1,n-2-i}(v_4)}$$
$$= \frac{\phi_{0,n-1}(v_4)\phi_{n-1,0}(v_3)}{\phi_{0,n-1}(v_3)\phi_{n-1,0}(v_4)} = w_{ij},$$

as $\phi_{n-1,0}, \phi_{0,n-1}$ are respectively linear forms defining $F_{n-1}^{(1)}, F_{n-1}^{(2)}$. **Example 6.9** (n = 3). In this case N = 4 and the elements of $A_{1,4}$ are (1,0,0,0), (0,1,0,0), (0,0,1,0), (0,0,0,1),

and $\binom{4}{2} = 6$. In particular,

$$w_{12} = \chi_{1000}\chi_{0100}, \qquad w_{34} = \chi_{0010}\chi_{0001},$$

$$w_{14} = \left(1 - \frac{1}{\chi_{1000}}\right) \left(1 - \frac{1}{\chi_{0001}}\right), \qquad w_{23} = \left(1 - \frac{1}{\chi_{0100}}\right) \left(1 - \frac{1}{\chi_{0010}}\right),$$

$$w_{24} = \frac{1}{1 - \chi_{0100}} \cdot \frac{1}{1 - \chi_{0001}}, \qquad w_{13} = \frac{1}{1 - \chi_{1000}} \cdot \frac{1}{1 - \chi_{0010}}.$$

With the notations of [BFG14],

$$z_{12} = \chi_{1000}, \qquad z_{21} = \chi_{0100}$$

$$\begin{aligned} z_{12} &= \chi_{1000} & z_{21} &= \chi_{0100}, \\ z_{13} &= \frac{1}{1 - \chi_{1000}} & z_{31} &= \frac{1}{1 - \chi_{0010}}, \\ z_{14} &= 1 - \frac{1}{\chi_{1000}}, & z_{41} &= 1 - \frac{1}{\chi_{0001}}, \\ z_{23} &= 1 - \frac{1}{\chi_{0100}}, & z_{32} &= 1 - \frac{1}{\chi_{0010}}, \\ z_{24} &= \frac{1}{1 - \chi_{0100}}, & z_{42} &= \frac{1}{1 - \chi_{0001}}, \\ z_{34} &= \chi_{0001}, & z_{43} &= \chi_{0001}. \end{aligned}$$



FIGURE 6. The z-coordinates.

so that,

$$\begin{aligned} w_{12} &= z_{12}z_{21}, & w_{13} &= z_{13}z_{31}, & w_{14} &= z_{14}z_{41}, \\ w_{23} &= z_{23}z_{32}, & w_{24} &= z_{24}z_{42}, & w_{34} &= z_{34}z_{43}, \end{aligned}$$

A geometric way to remember this equations is shown in Figure 6.

Example 6.10 (n = 4). Let $\operatorname{Gr}_2(V)$ be the Grassmannian of planes in $V = \mathbb{C}^4$ and $X_2 = \operatorname{Gr}_2(V)^4$. Let X_2^{ss} be the open subset of semi-stable points of X_2 under the action of G and with respect to the Plücker embedding (*cf.* Section 5). The GIT quotient of X_2^{ss} by G is isomorphic to \mathbb{P}^2 and the projection $\pi_2 \colon X_2^{ss} \to \mathbb{P}^2$ is given by non trivial elements of the Klein group (see Theorem 5.1). Write $p_2 \colon X \to X_2$ the canonical projection.

Proposition 6.11. Let F be a generic quadruple of complete flags of $V = \mathbb{C}^4$. For $\alpha \in A_{2,4}$ write $\chi_{\alpha} := \chi_{\alpha}(F)$. Then,

$$\begin{aligned} \frac{s_{1234}}{s_{1423}}(p(F)) &= \chi_{0110}\chi_{0101}\chi_{1010}\chi_{1001}, \\ \frac{s_{1324}}{s_{1423}}(p(F)) &= \left(1 - \frac{1}{\chi_{0011}}\right) \left(1 - \frac{1}{\chi_{1100}}\right) \left(1 - \frac{1}{\chi_{0101}}\right) \left(1 - \frac{1}{\chi_{1010}}\right). \end{aligned}$$

Proof. For i = 1, ..., 4 let v_i be a generator of the line $F_1^{(i)}$ and ϕ_i a linear form defining the hyperplane $F_3^{(i)}$. For i, j = 1, ..., 4 distinct let ϕ_{ij} be a linear form for the hyperplane $F_2^{(i)} + F_1^{(j)}$. Writing $E = F_1^{(1)} + F_1^{(2)}$, the cross-ratio χ_{1100} of the lines

$$(F_2^{(1)} + E)/E,$$
 $(F_2^{(2)} + E)/E,$ $(F_1^{(3)} + E)/E,$ $(F_1^{(4)} + E)/E,$

is

$$\frac{\phi_{12}(v_3)\phi_{21}(v_4)}{\phi_{12}(v_4)\phi_{21}(v_3)}$$

Analogously,

$$\begin{aligned} \frac{1}{1-\chi_{1010}} &= \frac{\phi_{13}(v_4)\phi_{31}(v_2)}{\phi_{13}(v_2)\phi_{31}(v_4)}, & 1 - \frac{1}{\chi_{1001}} &= \frac{\phi_{14}(v_2)\phi_{41}(v_3)}{\phi_{14}(v_3)\phi_{41}(v_2)}, \\ 1 - \frac{1}{\chi_{0110}} &= \frac{\phi_{23}(v_1)\phi_{32}(v_4)}{\phi_{23}(v_4)\phi_{32}(v_1)}, & \frac{1}{1-\chi_{0101}} &= \frac{\phi_{42}(v_1)\phi_{24}(v_3)}{\phi_{42}(v_3)\phi_{24}(v_1)}, \\ \chi_{0011} &= \frac{\phi_{34}(v_1)\phi_{43}(v_2)}{\phi_{34}(v_2)\phi_{43}(v_1)}. \end{aligned}$$

Up to action of $SL_4(\mathbb{C})$ the complete flags $F^{(1)}, \ldots, F^{(4)}$ can be taken as:

where $\lambda_1, \ldots, \lambda_4, \mu_1, \ldots, \mu_4 \in \mathbb{C}$ and $a, b \in \mathbb{C}^{\times}$. According to Proposition 5.2,

$$\frac{s_{1234}}{s_{1423}} = \frac{1}{ab},$$
 $\frac{s_{1324}}{s_{1423}} = (a-1)(b-1).$

We leave the remaining computations to the reader.

7. Representations

In this section we recall the definition of decorated triangulations of three manifolds following [BFG14, GGZ15, DGG16]. The definition is related to the case of decorated triangulated surfaces (see [FG07]). The decoration corresponds to an assignment of a configuration of four complete flags in \mathbb{C}^n to each 3-simplex in the 3-manifold satisfying certain compatibility conditions. The flags in the configuration can be thought as associated to each of the four vertices of a simplex. We will be interested mainly in the case n = 4. See [BFG14, FKR15] for the case n = 3. The decorated triangulations will give rise to representations of the fundamental group into PGL(4, \mathbb{C}) or SL(4, \mathbb{C}) and the goal is to find, among these representations, those with values in one of the real forms. Recall that the non-compact real forms of SL(4, \mathbb{C}) are SL(4, \mathbb{R}), SU(3, 1), SU(2, 2) and SL(2, \mathbb{H}).

We use coordinates on generic configurations of the configuration space (modulo $\operatorname{PGL}(n, \mathbb{C})$) introduced in the previous section and recall that these coordinates can be expressed using the invariant functions described using GIT for $\operatorname{SL}(n, \mathbb{C})$. This allows one to use the description in Proposition 6.8 and Example 6.9 to identify configurations in the closed orbit of certain real forms of $\operatorname{PGL}(n, \mathbb{C})$.



FIGURE 7. The n = 4 case of the cross-ratio coordinates. Each coordinate is associated to a quadruple $\alpha = (\alpha_1, \alpha_2, \alpha_3, \alpha_4)$ of non-negative integers α_i whose sum is n-2, attached to a point in one edge.

7.1. Decorated triangulations of 3-manifolds and representations. We consider an ideal triangulated compact oriented 3-manifold M with boundary ∂M . That is, there exists a finite number of oriented 3-simplices T_{ν} $(1 \leq \nu \leq N)$ and an orientation reversing matching of their faces so that if one truncates all the simplices at their vertices one obtains, after identifying the truncated faces, a manifold homeomorphic to M with ∂M identified to a triangulated 2-surface.

Let $V = \mathbb{C}^n$ and the flag variety F of complete flags. We let $G = PGL(n, \mathbb{C})$ be the projective group acting on the space of flags.

Definition 7.1. A decoration of an ideal triangulation of a manifold M is a collection of maps from tetrahedra T_{ν} to the space of configurations $F^{4,\text{gen}}/G$ compatible with the matchings. More precisely, to the 0-simplex of T_{ν} one associates a configuration of flags up to conjugation such that to each matching face one associates the same point in $F^{3,\text{gen}}/G$.

We will impose in the following that the decorations are chosen such that the configurations in $F^{3,\text{gen}}$ have trivial stabilizer. This condition is clearly satisfied for generic configurations as defined in the previous section. We also assume that the *holonomy* around the 1-skeleton be trivial. That is, around each edge one choses an abutted face and consider a configuration in $F^{3,\text{gen}}$ associated to it (a lift of the element in $F^{3,\text{gen}}/G$ associated to the face). Turning around the edge one constructs a sequence of flags corresponding to the vertices (not contained in the edge) of the faces of each of the simplices around the edge. After completing a turn

around the edge we suppose that the we recover the same original configuration in $F^{3,\text{gen}}$.

One can then obtain a holonomy representation (defined up to conjugation)

$$\rho: \pi_1(M) \longrightarrow \mathrm{PGL}(n, \mathbb{C}).$$

Indeed, chose a base face and consider a configuration in $F^{3,\text{gen}}$ associated to it (a lift of the element in $F^{3,\text{gen}}/G$ associated to the face). Any closed path γ (based at the chosen face and not intersecting any edge) determines a sequence of configurations in $F^{3,\text{gen}}$ corresponding to the configurations for each successive face crossed by the path. The last face configuration of flags along the path is the image of the reference configuration of flags by a unique element in G. This element is called the *holonomy* along γ . Clearly, if the holonomy around all edges are trivial, the paths may cross edges without modifying the holonomy and therefore the holonomy representation is well defined on $\pi_1(M)$.

7.1.1. Unipotent decorations. An important class of decorations is obtained by restricting the boundary holonomy, that is, the holonomy along paths on the boundary of M, to be in a subgroup which is conjugate to a unipotent radical of a Borel subgroup of G. In this paper, we consider only the case of $SL(n, \mathbb{C})$ or $PGL(n, \mathbb{C})$ and therefore, for a boundary component, the boundary holonomy may be considered to consist of upper triangular matrices with equal entries in the diagonal.

Computations of decorations with complete flags were implemented in [C]. Unipotent decorations were computed for $PGL(2, \mathbb{C})$, $PGL(3, \mathbb{C})$ in many cases and for one manifold, the complement of the figure eight knot, for $PGL(4, \mathbb{C})$.

7.1.2. G_0 -decorations and representations.

Definition 7.2. Let G_0 be a real form of G and F_0 the closed G_0 -orbit in F. A G_0 -decoration of an ideal triangulation of M is a decoration obtained through a family of maps from each tetrahedron to $F_0^{4,\text{gen}}/G_0$ (here $F_0^{4,\text{gen}} = F^{4,\text{gen}} \cap F_0$).

The holonomy representation representation $\rho:\pi_1(M)\to G_0$ will be $G_0\text{-valued}$ in this case.

In order to obtain explicit G_0 -decorations we use coordinates for generic flags, excluding certain degenerate configurations. For a given triangulation of a 3-manifold this might result in a loss of certain representations of its fundamental group but passing to a barycentric subdivision one obtains all representations. In generic coordinates, the G_0 -decorations are described as a constructible set given by algebraic equations implying face matchings and trivial holonomy around edges. The condition that the decoration be unipotent is described by additional algebraic equations. We will not reproduce these equations here but refer to references [BFG14, GGZ15, DGG16].

Unfortunately, computations are difficult and were completed only for triangulations with less than or equal to four tetrahedra in the case of PGL(3, \mathbb{C}) or 2 tetrahedra in the case of PGL(4, \mathbb{C}). The case PGL(3, \mathbb{C}), for manifolds obtained with less than 3 simplices, was treated in [FKR15] (see also [C] for a census of manifolds triangulated by four tetrahedra). G_0 -decorations give rise to representations into the real forms PU(2, 1) and SL(3, \mathbb{R}). In both cases, one can, in certain cases, associate (G_0, F_0)-structures to the 3-manifold such that its holonomy coincides with the representation. We refer to [Fal08, FST15] for more details.

In the case $PGL(4, \mathbb{C})$, a complete computation for unipotent decorated representations of the standard triangulation of the complement of the figure eight knot M_8 by two tetrahedra was completed by Matthias Goerner ([C]). Using those data, Antonin Guilloux checked, using the description in Proposition 6.8 and Example 6.9 that there exists, up to conjugation, only one family of unipotent decorated triangulations which gives rise to a unique representation in a real form. Namely, the representation obtained from the geometric representation $\pi_1(M_8) \to SO(3, 1)$ which realizes a lift of the holonomy of the complete hyperbolic structure on the isometry group of hyperbolic space. Observe that the image of the representation is contained in both $SL(4, \mathbb{R})$ and SU(3, 1).

Proposition 7.3. The only G_0 decorations associated to the standard triangulation of the figure eight knot by two tetrahedra correspond to a unique representation, up to conjugation, $\pi_1(M_8) \to SO(3,1)$ identified to the geometric representation.

We believe that this is the only irreducible boundary unipotent representation in a real form up to conjugation.

It is interesting to note that (see Theorem 1.4 in [BPW17]) this unipotent representation is contained in a one parameter family of discrete and faithful boundary parabolic representations with values in SU(3, 1).

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