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► To cite this version:

Markus Köppel, Vincent Martin, Jean Roberts. A stabilized Lagrange multiplier finite-element method for flow in porous media with fractures. 2018. hal-01761591v1

HAL Id: hal-01761591

<https://hal.science/hal-01761591v1>

Preprint submitted on 9 Apr 2018 (v1), last revised 29 Dec 2018 (v3)

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A stabilized Lagrange multiplier finite-element method for flow in porous media with fractures

April 2018

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Abstract In this work we introduce a stabilized, numerical method for a multi-dimensional, discrete-fracture model (DFM) for single-phase Darcy flow in fractured porous media. In the model, introduced in an earlier work, flow in the $(n - 1)$ -dimensional fracture domain is coupled with that in the n -dimensional bulk or matrix domain by the use of Lagrange multipliers. Thus the model permits a finite element discretization in which the meshes in the fracture and matrix domains are independent so that irregular meshing and in particular the generation of small elements can be avoided. In this paper we introduce in the numerical formulation, which is a saddle-point problem based on a primal, variational formulation for flow in the matrix domain and in the fracture system, a consistent stabilizing term which penalizes discontinuities in the Lagrange multipliers. For this penalized scheme we show stability and prove convergence. With numerical experiments we analyze the performance of the method for various choices of the penalization parameter and compare with other numerical DFM's.

Keywords discrete fracture model · finite element method · stabilized Lagrange multiplier method · penalization · nonconforming grids

1 Introduction

Fractures represent one of the most challenging heterogeneities for the approximation of fluid flow in porous media. Typically their lateral dimension is considerably smaller compared to their extensions in other directions. Moreover fractures may act as barriers to and/or conduits for fluid flow. Depending on the hydrogeological properties and the scale of consideration, the presence of fractures thus may lead to a significant change in the flow behavior in the subsurface. Because fault zones occur in many applications, such as CO₂ sequestration, underground storage of radioactive waste and enhanced oil recovery, the consideration of fractures in modeling of flow in porous media has received more and more attention in the last decades. A variety of different models have been proposed.

A common way to incorporate fractures in models is the discrete-fracture (DFM) approach, in which information concerning the fracture location in the domain of interest is required, and the fluid flow in the fracture as well as in the surrounding domain is calculated. In this context the fractures are often considered as $(n - 1)$ -dimensional objects within the surrounding n -dimensional matrix domain in order to avoid the generation of small elements of the spatial discretization grid. Such models have been studied, in e.g. (Alboin et al, 2002; Angot et al, 2009), assuming Darcy flow in both, fracture and matrix, parts of the domain. Other studies addressed Forchheimer flow in the fractures (Knabner and Roberts, 2014) or Darcy-Brinkman flow (Lesinigo et al, 2011). Multiphase flow has also been considered, e.g. (Ahmed et al, 2017; Brenner et al, 2015; Hoteit and Firoozabadi, 2008). Some articles deal with discrete fracture network (DFN) models, e.g. (Berrone et al, 2014; Pichot et al, 2012). Whereas some of these models are based on finite element methods, (Baca et al, 1984), others use mixed or mixed-hybrid finite elements, (Martin et al, 2005), finite volume methods, (Karimi-Fard et al, 2004; Reichenberger et al, 2006), multi-point flux methods, (Sandve et al, 2012), or mimetic finite difference methods, (Antonietti et al, 2016), to discretize the problem.

For discretization schemes, in what may be referred to as a matching fracture and matrix grid approach, the fracture mesh elements coincide with faces of the matrix mesh elements. However one may wish to discretize the fracture more finely in the case of a highly conductive fracture or more coarsely in the case of a barrier. Therefore it may be necessary to use methods allowing for non-matching grids; see e.g. (Faille et al, 2016; Frih et al, 2012). Still with these methods the matrix grid must be aligned with the fracture. By contrast, with nonconforming methods a fracture can cut through the interior of matrix elements because of an independent meshing of the corresponding domains. This can be achieved, for example, with locally enriched basis functions in the vicinity of the fracture to account for the resulting discontinuities, in what is commonly referred to as an extended finite element method (XFEM), e.g. in (Fumagalli and Scotti, 2013; Schwenck et al, 2015).

This work presents an alternative nonconforming discretization of a model introduced in Köppel et al (2018). Following ideas of Burman and Hansbo (2010), we present a new stabilized discretization scheme for single-phase, Darcy flow in fractured porous media. As presented in Köppel et al (2018), the method uses

Lagrange multiplier variables, which represent a local fluid exchange between fracture and matrix, in a primal variational formulation. The permeability in the fracture is assumed to be larger than that in the matrix. Hence the fluid pressure is continuous excluding the case of a geological barrier. Because of the use of the multiplier this model allows for mutually independent grids of the matrix and the fracture, both discretized with continuous, piecewise-(bi)linear basis functions. As in Köppel et al (2018), the Lagrange multiplier is discretized by means of discontinuous, piecewise-constant, basis functions, though here the multipliers are no longer associated with an independent but size-constrained grid but with a grid generated by intersections of the matrix grid with the fracture. Following Burman and Hansbo (2010), we add a consistent stabilizing term which penalizes the jumps of the discrete multipliers. This leads to a stabilization of the discrete saddle point system and thus reduces the condition numbers involved.

In Section 2, we recall briefly the continuous formulation of the Lagrange multiplier method. Section 3 concerns the discrete formulation of the problem. We introduce a weakly consistent penalty term to stabilize the discrete system, prove the stability of the discrete formulation and discuss the convergence of the approach. In Section 4, the theoretical findings are analyzed numerically by means of several numerical experiments, including two benchmarks from Flemisch et al (2018), validating the method. Finally we conclude and discuss the proposed method in Section 5.

2 The continuous formulation for the Lagrange multiplier model

In this section we recall briefly the continuous model for the Lagrange-multiplier DFM, introduced in Köppel et al (2018). Let Ω be a domain in \mathbb{R}^n , $n = 2$ or 3 , representing a porous medium and let $\gamma \subset \Omega$ be an $(n - 1)$ -dimensional surface representing a fracture. Let \mathbf{n}_γ denote one of the two possible continuous unit vector fields on γ , and let \mathbf{K} and \mathbf{K}_γ be symmetric, uniformly positive-definite, bounded, permeability tensor fields on Ω and γ respectively, with constants $C_{\mathbf{K}}^M$ and $C_{\mathbf{K}}^m > 0$ such that

$$\begin{aligned} \|\mathbf{K}(x)\| &\leq C_{\mathbf{K}}^M, \quad \forall x \in \Omega, & C_{\mathbf{K}}^m \|\mathbf{v}\|_{0,\Omega} &\leq (\mathbf{K}\mathbf{v}, \mathbf{v})_\Omega, \quad \forall \mathbf{v} \in L^2(\Omega), \\ \|\mathbf{K}_\gamma(x_\gamma)\| &\leq C_{\mathbf{K}}^M, \quad \forall x_\gamma \in \gamma, & C_{\mathbf{K}}^m \|\mathbf{v}_\gamma\|_{0,\gamma} &\leq (\mathbf{K}_\gamma \mathbf{v}_\gamma, \mathbf{v}_\gamma)_\gamma, \quad \forall \mathbf{v}_\gamma \in L^2(\gamma), \end{aligned}$$

where we use the notation $(\cdot, \cdot)_\Omega$ and $(\cdot, \cdot)_\gamma$ for the L^2 inner products on $L^2(\Omega)$ and $L^2(\gamma)$, respectively, and $\|\cdot\|_{0,\mathcal{O}}$ for the $L^2(\mathcal{O})$ norm on an open set $\mathcal{O} \subset \mathbb{R}^d$, $d = 1, 2$ or 3 . Here $\|\mathbf{K}(x)\|$ denotes the operator norm as does $\|\mathbf{K}_\gamma(x_\gamma)\|$. For simplicity assume that γ is a planar surface if $n = 2$ or if $n = 1$ a line segment and that $\partial\gamma \subset \partial\Omega$. Flow in both Ω and γ is assumed to be governed by Darcy's law and the law of mass conservation, and for simplicity homogeneous Dirichlet boundary conditions are imposed on both $\partial\gamma$ and $\partial\Omega$. Fluid exchange between Ω and γ is through a source/sink term λ representing the discontinuity in the flux in Ω from one side of γ to the other. Letting p and p_γ represent the fluid pressure and f and f_γ external source terms in Ω and γ respectively we may

write the equations for the model as follows:

$$\begin{aligned} \operatorname{div}(-\mathbf{K}\nabla p) - \lambda &= f, & \text{in } \Omega, \\ \operatorname{div}_\tau(-\mathbf{K}_\gamma \nabla_\tau p_\gamma) + \lambda &= f_\gamma, & \text{in } \gamma, \\ p &= 0, & \text{on } \Gamma = \partial\Omega, \\ p_\gamma &= 0, & \text{on } \partial\gamma, \end{aligned} \quad (1)$$

where div_τ and ∇_τ denote the divergence and gradient operators in the plane of γ if $n = 3$, whereas if $n = 2$ they are both just derivatives in the direction obtained by rotating \mathbf{n}_γ through 90 degrees.

For the variational formulation, the spaces $V_\Omega, V_\gamma, \mathbf{V}$ and Λ are used:

$$V_\Omega = H_0^1(\Omega), \quad V_\gamma = H_0^1(\gamma), \quad \mathbf{V} = V_\Omega \times V_\gamma, \quad \text{and} \quad \Lambda = H_{00}^{-\frac{1}{2}}(\gamma). \quad (2)$$

We use the same notation $\langle \cdot, \cdot \rangle_\gamma$ for the duality pairing between $H_{00}^{-\frac{1}{2}}(\gamma)$ and $H_{00}^{\frac{1}{2}}(\gamma)$ as that which is used for the $L^2(\gamma)$ -inner product when the functions are sufficiently regular. Now with the bilinear form \mathcal{A} on $(\mathbf{V} \times \Lambda)^2$ defined by

$$\mathcal{A}(P, Q) = \int_\Omega \mathbf{K} \nabla p \cdot \nabla q + \int_\gamma \mathbf{K}_\gamma \nabla_\tau p_\gamma \cdot \nabla_\tau q_\gamma - \langle \lambda, q|_\gamma - q_\gamma \rangle_\gamma + \langle \mu, p|_\gamma - p_\gamma \rangle_\gamma,$$

for $P = (p, p_\gamma; \lambda)$ and $Q = (q, q_\gamma; \mu)$ in $\mathbf{V} \times \Lambda$, and the linear form ℓ on \mathbf{V} defined by

$$\ell(q, q_\gamma) = \int_\Omega f q + \int_\gamma f_\gamma q_\gamma,$$

for $(q, q_\gamma) \in \mathbf{V}$, the variational formulation of (1) may be written as follows:

$$\begin{aligned} \text{Find } P = (p, p_\gamma; \lambda) &\in \mathbf{V} \times \Lambda \text{ such that} \\ \mathcal{A}(P, Q) &= \ell(q, q_\gamma), \quad \forall Q = (q, q_\gamma; \mu) \in \mathbf{V} \times \Lambda. \end{aligned} \quad (3)$$

In Köppel et al (2018), it was proved that (3) has a unique solution. Note that λ can be interpreted as the jump in the flux across γ : $\lambda = \llbracket \mathbf{K} \nabla p \cdot \mathbf{n}_\gamma \rrbracket_\gamma$.

3 Discretization

Inspired by the work in Burman and Hansbo (2010), we introduce a stabilized numerical discretization of problem (3) and show existence and uniqueness of the discrete solution as well as convergence. For the discretization we restrict our attention to the case that Ω is of dimension 2 and thus γ is of dimension 1. Recall that in Köppel et al (2018), a different primal finite element method was used to discretize (3), one that uses different discretization spaces for the Lagrange multiplier and does not have a stabilization term. With the stabilized method we do not have the minimum size constraint on the support of the Lagrange multipliers.

3.1 A stabilized discrete formulation

We introduce independent finite element meshes, \mathcal{T}_h and $\mathcal{T}_{h,\gamma}$, to define the approximation spaces $V_{h,\Omega} \subset V_\Omega$ and $V_{h,\gamma} \subset V_\gamma$. The mesh \mathcal{T}_h on Ω is made up of triangles and/or rectangles, and $\mathcal{T}_{h,\gamma}$ is a mesh on γ . We assume that each of \mathcal{T}_h and $\mathcal{T}_{h,\gamma}$ belongs to a uniformly regular family of discretizations. Let h and h_γ be the parameters associated with these families:

$$h = \max_{T \in \mathcal{T}_h} h_T, \quad \text{where } h_T = \text{diam}(T),$$

$$h_\gamma = \max_{t \in \mathcal{T}_{h,\gamma}} h_t, \quad \text{where } h_t = \text{diam}(t),$$

For each $T \in \mathcal{T}_h$ let $\rho_T =$ the radius of the incircle of T , and let $\sigma_T = \frac{h_T}{\rho_T}$. Let $\rho_h = \min_{T \in \mathcal{T}_h} \rho_T$ and let $\sigma_h = \frac{h}{\rho_h}$. Let $\sigma_\Omega = \max_h \sigma_h$ be the upper bound guaranteed by uniform regularity.

There is naturally induced on γ a second mesh, which we will denote $\mathcal{T}_{h,\lambda}$ (as it will be associated with the space of discrete Lagrange multipliers), that consists of the segments $T \cap \gamma$ such that $T \in \mathcal{T}_h$, see Fig. 1:

$$\mathcal{T}_{h,\lambda} = \{s \subset \gamma : s = T \cap \gamma \text{ for some } T \in \mathcal{T}_h\}.$$

Let \mathcal{F}_h denote the set of faces F (*i.e.* edges) of elements $T \in \mathcal{T}_h$, and $\mathcal{F}_{h,\lambda}$ the set of faces f (*i.e.* vertices) of elements $s \in \mathcal{T}_{h,\lambda}$ which do not lie on the boundary: $f \notin \partial\gamma$. The conforming approximation spaces $V_{h,\Omega}$ and $V_{h,\gamma}$ will consist of

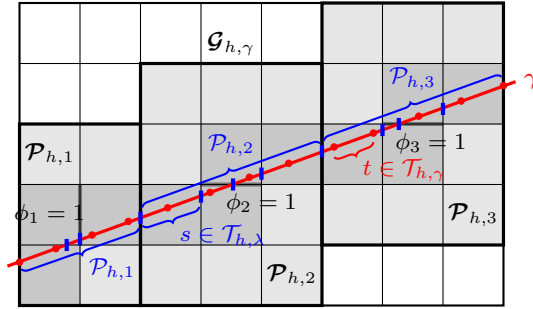


Fig. 1 Meshes \mathcal{T}_h , $\mathcal{T}_{h,\gamma}$ (elements t delimited by red dots) and $\mathcal{T}_{h,\lambda}$ (elements s delimited by blue segments). The domain $\mathcal{G}_{h,\gamma}$ around γ is in grey. The supports of the patch elements $\mathcal{P}_{h,i}$ (in blue) and $\mathcal{P}_{h,i}$ (grey) are also depicted, with the chosen edge for ϕ_i .

continuous functions that vanish on the boundary of Ω and γ , respectively. The functions in $V_{h,\gamma}$ will be piecewise linear subordinate to the mesh $\mathcal{T}_{h,\gamma}$ while those of $V_{h,\Omega}$, subordinate to the mesh \mathcal{T}_h will be piecewise linear or bilinear depending on whether the element is a triangle or a rectangle:

$$V_{h,\Omega} = \left\{ q \in H_0^1(\Omega) : \forall T \in \mathcal{T}_h, \quad q|_T \in \begin{cases} \mathbb{P}^1(T) & \text{if } T \text{ is a triangle} \\ \mathbb{Q}^{1,1}(T) & \text{if } T \text{ is a rectangle} \end{cases} \right\}, \quad (4)$$

$$V_{h,\gamma} = \{ q_\gamma \in H_0^1(\gamma) : \forall t \in \mathcal{T}_{h,\gamma}, \quad q_\gamma|_t \in \mathbb{P}^1(t) \}, \quad \text{and } \mathbf{V}_h = V_{h,\Omega} \times V_{h,\gamma}.$$

The approximation space Λ_h for the Lagrange multiplier is defined as follows:

$$\Lambda_h = \{\lambda_h \in L^2(\gamma) \mid \lambda_h|_s \in \mathbb{P}^0(s), \forall s \in \mathcal{T}_{h,\lambda}\}. \quad (5)$$

Following Burman and Hansbo (2010) we will introduce a stabilizing term \mathcal{J} in the form of a bilinear operator on $\Lambda_h \times \Lambda_h$:

$$\mathcal{J}(\lambda_h, \mu_h) = \sum_{f \in \mathcal{F}_{h,\lambda}} \xi h^2 \llbracket \lambda_h \rrbracket_f \llbracket \mu_h \rrbracket_f, \quad (6)$$

where for $\mu_h \in \Lambda_h$, and $f \in \mathcal{F}_{h,\lambda}$, $\llbracket \mu_h \rrbracket_f$ denotes the jump in μ_h across f . Here, for simplicity, we assume that no face $F \in \mathcal{F}_h$ lies along γ and that γ does not contain any vertex of the mesh \mathcal{T}_h . This ensures that $\llbracket \lambda_h \rrbracket_f$ is uniquely defined when $f \in \mathcal{F}_{h,\lambda}$ and $\lambda_h \in \Lambda_h$. Otherwise defining the jump term is more cumbersome, though it poses no real problem, and in fact, some of our numerical experiments treat such cases. We remark that we will at times use the notation $\llbracket \phi \rrbracket_f$ for functions ϕ not necessarily belonging to Λ_h but for which the jumps over the faces $f \in \mathcal{F}_{h,\lambda}$ are well defined. Indeed, $\mathcal{J}(\cdot, \cdot)^{\frac{1}{2}}$ defines a semi-norm on Λ_h , and for the \mathcal{J} operator we have the following Cauchy–Schwarz type estimate:

$$|\mathcal{J}(\lambda_h, \mu_h)| \leq \mathcal{J}(\lambda_h, \lambda_h)^{\frac{1}{2}} \mathcal{J}(\mu_h, \mu_h)^{\frac{1}{2}} \quad \forall \lambda_h, \mu_h \in \Lambda_h. \quad (7)$$

The formulation of the discrete stabilized problem may be written as follows:

$$\begin{aligned} &\text{Find } P_h = (p_h, p_{\gamma,h}; \lambda_h) \in \mathbf{V}_h \times \Lambda_h \text{ such that} \\ &\mathcal{A}(P_h, Q_h) + \mathcal{J}(\lambda_h, \mu_h) = \ell(q_h, q_{\gamma,h}), \quad \forall Q_h = (q_h, q_{\gamma,h}; \mu_h) \in \mathbf{V}_h \times \Lambda_h. \end{aligned} \quad (8)$$

The following proposition states a Galerkin orthogonality for (8).

Proposition 1 *If P is the solution of (3) and P_h the solution of (8), then*

$$\mathcal{A}(P - P_h, Q_h) = \mathcal{J}(\lambda_h, \mu_h) \quad \forall Q_h = (q_h, q_{\gamma,h}; \mu_h) \in \mathbf{V}_h \times \Lambda_h. \quad (9)$$

Proof As $\mathbf{V}_h \subset \mathbf{V}$ and $\Lambda_h \subset \Lambda$, it suffices to take $Q = Q_h \in \mathbf{V}_h \times \Lambda_h$ in (3), subtract (8) from (3) and use the bilinearity of \mathcal{A} to obtain (9). \blacksquare

3.2 Some discrete norms

We give the definition of some norms that will be useful for obtaining the approximation properties of the space $\mathbf{V}_h \times \Lambda_h$. For $\zeta \in L^2(\gamma)$ we define the discrete norms

$$\|\zeta\|_{\frac{1}{2},h,\gamma}^2 = \int_{\gamma} h^{-1} \zeta^2 = h^{-1} \|\zeta\|_{0,\gamma}^2 \quad \text{and} \quad \|\zeta\|_{-\frac{1}{2},h,\gamma}^2 = \int_{\gamma} h \zeta^2 = h \|\zeta\|_{0,\gamma}^2, \quad (10)$$

and we recall the associated Cauchy–Schwarz type inequality

$$\langle \zeta, \eta \rangle_{\gamma} \leq \|\zeta\|_{-\frac{1}{2},h,\gamma} \|\eta\|_{\frac{1}{2},h,\gamma}, \quad \forall \zeta \text{ and } \eta \in L^2(\gamma). \quad (11)$$

We will also use two more norms defined respectively for $Q = (q, q_\gamma; \mu) \in \mathbf{V} \times L^2(\gamma)$ and for $Q_h = (q, q_\gamma; \mu_h) \in \mathbf{V} \times \Lambda_h$, by

$$\begin{aligned} \|Q\|_{0,h}^2 &:= \|\nabla q\|_{0,\Omega}^2 + \|\nabla_\tau q_\gamma\|_{0,\gamma}^2 + \|\mu\|_{-\frac{1}{2},h,\gamma}^2 + \|q|_\gamma - q_\gamma\|_{\frac{1}{2},h,\gamma}^2 \\ \|Q_h\|_{1,h}^2 &:= \|Q_h\|_{0,h}^2 + \mathcal{J}(\mu_h, \mu_h). \end{aligned}$$

That $\|\cdot\|_{0,h}$ indeed defines a norm on $\mathbf{V} \times L^2(\gamma)$ follows immediately from the Poincaré inequality. Thus $\|\cdot\|_{1,h}$ also defines a norm on $\mathbf{V} \times \Lambda_h$. That \mathcal{A} is continuous in the $\|\cdot\|_{0,h}$ norm follows from the Cauchy–Schwarz inequality:

Proposition 2 *There exists a constant C_c , independent of h , such that if P and Q belong to $\mathbf{V} \times L^2(\gamma)$, then*

$$\mathcal{A}(P, Q) \leq C_c \|P\|_{0,h} \|Q\|_{0,h}. \quad (12)$$

Proof The Cauchy–Schwarz inequality, (7) and (11) yield (12) with $C_c = C_{\mathbf{K}}^M$. \blacksquare

3.3 A subspace of Λ_h and some approximation lemmas

The family of inherited meshes $\mathcal{T}_{h,\lambda}$ on γ suffers from the fact that it is not uniformly regular: while for $s \in \mathcal{T}_{h,\lambda}$, its length $h_s \leq h$, there is not necessarily a $\sigma_\lambda > 0$, independent of h , such that $h_s \geq \frac{h}{\sigma_\lambda}$. For this reason we amalgamate elements of $\mathcal{T}_{h,\lambda}$ to obtain a supermesh $\mathcal{T}_{h,\mathcal{P}}$ of $\mathcal{T}_{h,\lambda}$ made up of patch-elements obtained by fusing two or more contiguous elements of $\mathcal{T}_{h,\lambda}$ to form n_h pairwise-disjoint patches, $\mathcal{P}_{h,i}$, $i = 1, \dots, n_h$, see Fig. 1. The patches should be constructed in such a way that the length of each patch segment is bounded above and below by a multiple of h ; *i.e.* there are positive constants c_1 and c_2 , independent of h , such that

$$c_1 h \leq h_{\mathcal{P}_{h,i}} \leq c_2 h, \quad i = 1, \dots, n_h, \quad (13)$$

where $h_{\mathcal{P}_{h,i}}$ denotes the length of the patch-segment $\mathcal{P}_{h,i}$. Let $h_{\mathcal{P}}$ be the maximum value of $h_{\mathcal{P}_{h,i}}$, $\mathcal{P}_{h,i} \in \mathcal{T}_{h,\mathcal{P}}$. An additional constraint on the patch construction will be given in Section 3.4 following the proof of Lemma 3. From the uniform regularity of \mathcal{T}_h , the patch-segments can clearly be constructed so that the maximum number of elements $s \in \mathcal{T}_{h,\lambda}$ in a patch-element $\mathcal{P}_{h,i}$ is bounded above by some number \bar{n} independent of h . The patches can be numbered in such a way that each of $\mathcal{P}_{h,1}$ and \mathcal{P}_{h,n_h} has a vertex on the boundary of γ , and such that for $i = 1, \dots, n_h - 1$, $\mathcal{P}_{h,i}$ and $\mathcal{P}_{h,i+1}$ have a vertex in common. Similarly, for each i ; $i = 1, \dots, n_h$, the patch $\mathcal{P}_{h,i}$ contains as subsets a certain number, n_i , of cells $s_{i,\ell} \in \mathcal{T}_{h,\lambda}$, $\ell = 1, \dots, n_i$ which we may assume are numbered such that the first and last cells have a vertex on $\partial\mathcal{P}_{h,i}$ and contiguous cells are numbered consecutively. Now define the space of patch-wise constant functions on γ :

$$\mathcal{X}_h = \{x_h \in L^2(\gamma) : x_h|_{\mathcal{P}_{h,i}} \in \mathbb{P}^0(\mathcal{P}_{h,i}), i = 1, \dots, n_h\},$$

and let $\pi_{\mathcal{P}}: L^2(\gamma) \rightarrow \mathcal{X}_h$ be defined by $\eta \mapsto \pi_{\mathcal{P}} \eta$ where $\pi_{\mathcal{P}} \eta|_{\mathcal{P}_{h,i}} = \frac{1}{h_{\mathcal{P}_{h,i}}} \int_{\mathcal{P}_{h,i}} \eta$.

As $\pi_{\mathcal{P}}$ is the $L^2(\gamma)$ -projection operator from $L^2(\gamma)$ onto \mathcal{X}_h , for $\mu \in L^2(\gamma)$

$$\langle \mu, \zeta_h \rangle_{\gamma} = \langle \pi_{\mathcal{P}} \mu, \zeta_h \rangle_{\gamma}, \quad \forall \zeta_h \in \mathcal{X}_h, \quad (14)$$

$$\|\pi_{\mathcal{P}} \mu\|_{0,\gamma} \leq \|\mu\|_{0,\gamma}, \quad (15)$$

and if further $\mu \in H^1(\gamma)$, there is a constant $C_{\pi_{\mathcal{P}}}$, independent of h , such that

$$\|\mu - \pi_{\mathcal{P}} \mu\|_{0,\gamma} \leq C_{\pi_{\mathcal{P}}} h_{\mathcal{P}} \|\nabla_{\tau} \mu\|_{0,\gamma}. \quad (16)$$

Before stating approximation lemmas we define a mesh-dependent, thickened γ made up of the cells of \mathcal{T}_h crossed by γ plus an extra layer of cells on each side of γ . Let

$$\mathcal{S}_h = \{T \in \mathcal{T}_h : \exists T' \in \mathcal{T}_h \text{ with } \bar{T} \cap \bar{T}' \neq \emptyset \text{ and } \bar{T}' \cap \gamma \neq \emptyset\},$$

and let $\mathcal{G}_{h,\gamma}$ be the interior of the union of the closures of the cells $T \in \mathcal{S}_h$:

$$\mathcal{G}_{h,\gamma} = \text{Int}\left(\bigcup_{T \in \mathcal{S}_h} \bar{T}\right). \quad (17)$$

The following two lemmas concern approximation in \mathcal{X}_h :

Lemma 1 *There exist constants $C_1 \geq 1$ and $\tilde{C}_1 > 0$ such that for $(q_h, q_{\gamma,h}) \in V_h$*

$$\begin{aligned} \|(q_h|_{\gamma} - q_{\gamma,h}) - \pi_{\mathcal{P}}(q_h|_{\gamma} - q_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2 &\leq C_1 (\|\nabla q_h\|_{0,\mathcal{G}_{h,\gamma}}^2 + h \|\nabla_{\tau} q_{\gamma,h}\|_{0,\gamma}^2), \\ \tilde{C}_1 \|q_h|_{\gamma} - q_{\gamma,h}\|_{\frac{1}{2},h,\gamma}^2 - \|\nabla q_h\|_{0,\mathcal{G}_{h,\gamma}}^2 - h \|\nabla_{\tau} q_{\gamma,h}\|_{0,\gamma}^2 &\leq \|\pi_{\mathcal{P}}(q_h|_{\gamma} - q_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2. \end{aligned}$$

Proof The second inequality follows directly from the first with $\tilde{C}_1 = \frac{1}{2C_1}$, so we only need to prove the first. For $q_{\gamma,h}$ in $V_{h,\gamma}$ and q_h in $V_{h,\Omega}$, we have $q_{\gamma,h} \in H^1(\gamma)$ and $q_h|_{\gamma} \in H^1(\gamma)$. Thus (16) and then (13) implies that

$$\begin{aligned} \|q_{\gamma,h} - \pi_{\mathcal{P}} q_{\gamma,h}\|_{0,\gamma} &\leq C_{\pi_{\mathcal{P}}} c_2 h \|\nabla_{\tau}(q_{\gamma,h})\|_{0,\gamma}, \\ \|q_h|_{\gamma} - \pi_{\mathcal{P}}(q_h|_{\gamma})\|_{0,\gamma} &\leq C_{\pi_{\mathcal{P}}} c_2 h \|\nabla_{\tau}(q_h|_{\gamma})\|_{0,\gamma}. \end{aligned}$$

It is obvious for a grid of triangles (when ∇q_h is piecewise constant) but also true for a grid of rectangles that there exists $C_{\sigma} > 0$ such that

$$\|\nabla_{\tau}(q_h|_{\gamma})\|_{0,\gamma} \leq C_{\sigma} h^{-\frac{1}{2}} \|\nabla_{\tau} q_h\|_{0,\mathcal{G}_{h,\gamma}} \leq C_{\sigma} h^{-\frac{1}{2}} \|\nabla q_h\|_{0,\mathcal{G}_{h,\gamma}},$$

where C_{σ} depends on the uniform regularity constant σ_{Ω} . Combining the last three inequalities we obtain

$$\begin{aligned} &\|(q_h|_{\gamma} - q_{\gamma,h}) - \pi_{\mathcal{P}}(q_h|_{\gamma} - q_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2 \\ &\leq 2h^{-1} (\|q_h|_{\gamma} - \pi_{\mathcal{P}}(q_h|_{\gamma})\|_{0,\gamma}^2 + \|q_{\gamma,h} - \pi_{\mathcal{P}} q_{\gamma,h}\|_{0,\gamma}^2) \\ &\leq 2C_{\pi_{\mathcal{P}}}^2 c_2^2 (C_{\sigma}^2 \|\nabla q_h\|_{0,\mathcal{G}_{h,\gamma}}^2 + h \|\nabla_{\tau} q_{\gamma,h}\|_{0,\gamma}^2). \end{aligned}$$

The lemma follows with $C_1 = 2C_{\pi_{\mathcal{P}}}^2 c_2^2 \max\{C_{\sigma}^2, 1\}$. ■

Lemma 2 *There is a positive constant C_2 such that if $\mu_h \in \Lambda_h$, then*

$$\|\mu_h - \pi_{\mathcal{P}}\mu_h\|_{-\frac{1}{2},h,\gamma}^2 \leq C_2 \mathcal{J}(\mu_h, \mu_h).$$

Proof As $\pi_{\mathcal{P}}$ is an L^2 -projection, it suffices to show that there is a constant C_2 such that if $\mu_h \in \Lambda_h$ there is a function $\chi_h \in \mathcal{X}_h$ such that

$$\|\mu_h - \chi_h\|_{0,\gamma}^2 \leq C_2 h^{-1} \mathcal{J}(\mu_h, \mu_h).$$

Let $\mu_h \in \Lambda_h$. We construct $\chi_h \in \mathcal{X}_h$ such that the value χ_i of χ_h on the patch $\mathcal{P}_{h,i} \in \mathcal{T}_{h,\mathcal{P}}$ is the value $\mu_{i,1}$ of μ_h on the cell $s_{i,1} \in \mathcal{T}_{h,\lambda}$, i.e. $\chi_i = \mu_{i,1}$. Then

$$\begin{aligned} \|\mu_h - \chi_h\|_{0,\gamma}^2 &= \sum_{i=1}^{n_h} \|\mu_h - \chi_i\|_{0,\mathcal{P}_{h,i}}^2 = \sum_{i=1}^{n_h} \sum_{\ell=2}^{n_i} \|\mu_h - \chi_i\|_{0,s_{i,\ell}}^2 \\ &\leq h_{\lambda} \sum_{i=1}^{n_h} \sum_{\ell=2}^{n_i} (\mu_{i,\ell} - \mu_{i,1})^2 \leq h \sum_{i=1}^{n_h} \sum_{\ell=2}^{n_i} \left(\sum_{\nu=1}^{\ell-1} j_{i,\nu} \right)^2 \\ &\leq h \sum_{i=1}^{n_h} \sum_{\ell=2}^{n_i} (\ell-1) \sum_{\nu=1}^{\ell-1} j_{i,\nu}^2 \leq h \frac{\bar{n}^2}{2} \sum_{i=1}^{n_h} \sum_{\nu=1}^{n_i-1} j_{i,\nu}^2, \end{aligned}$$

where for $\ell = 1, \dots, n_i$; $\mu_{i,\ell} = \mu_h|_{s_{i,\ell}}$; for $\nu = 1, \dots, n_i - 1$; $j_{i,\nu} = \mu_{i,\nu+1} - \mu_{i,\nu}$ and \bar{n} is an upper bound, independent of h , on the number of cells $s \in \mathcal{T}_{h,\lambda}$ contained in a patch $\mathcal{P}_h \in \mathcal{T}_{h,\mathcal{P}}$. The lemma follows with $C_2 = \frac{\bar{n}^2}{2\xi}$ since

$$\mathcal{J}(\mu_h, \mu_h) = \sum_{f \in \mathcal{F}_{h,\lambda}} \xi h^2 [\mu_h]_f^2 \geq \xi h^2 \sum_{i=1}^{n_h} \sum_{\nu=1}^{n_i-1} j_{i,\nu}^2. \quad \blacksquare$$

3.4 A stability estimate

This section is devoted to the demonstration of the stability estimate for the formulation (8) given in Theorem 1. The proof relies on Lemmas 3 and 4.

Lemma 3 *There exist positive constants C_3 , C_4 and C_5 independent of h , such that for $(p_h, p_{\gamma,h})$ in \mathbf{V}_h there exists $\eta_h \in \Lambda_h$ satisfying:*

$$\begin{aligned} \langle \eta_h, p_h|_{\gamma} - p_{\gamma,h} \rangle_{\gamma} &\geq C_3 \|\pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2, \\ \|\eta_h\|_{-\frac{1}{2},h,\gamma}^2 &\leq C_4 \|\pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2, \\ \mathcal{J}(\eta_h, \eta_h) &\leq C_5 \|\pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2. \end{aligned}$$

Proof Given $(p_h, p_{\gamma,h})$ in \mathbf{V}_h , define $\eta_h \in \mathcal{X}_h$ by $\eta_h = \frac{1}{h_{\mathcal{P}}} \pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})$. Use equations (14) and (13) to obtain the first inequality of the lemma:

$$\langle \eta_h, p_h|_{\gamma} - p_{\gamma,h} \rangle_{\gamma} = \|h_{\mathcal{P}}^{-\frac{1}{2}} \pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})\|_{0,\gamma}^2 \geq c_2^{-1} \|\pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2.$$

For the second inequality, observe that

$$\|\eta_h\|_{-\frac{1}{2},h,\gamma}^2 \leq h h_{\mathcal{P}}^{-2} \|\pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})\|_{0,\gamma}^2 \leq c_1^{-2} \|\pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2.$$

For the third inequality, using the definition (6) of \mathcal{J} , the fact that η_h is constant on patches, using (13) and the definition of η_h , one obtains

$$\begin{aligned} \mathcal{J}(\eta_h, \eta_h) &= \sum_{i=1}^{n_h-1} \xi h^2 (\eta_h|_{\mathcal{P}_{h,i}} - \eta_h|_{\mathcal{P}_{h,i+1}})^2 \leq \sum_{i=1}^{n_h} 4\xi h^2 (\eta_h|_{\mathcal{P}_{h,i}})^2 \\ &\leq 4c_1^{-2} \xi \sum_{i=1}^{n_h} \left(\pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})|_{\mathcal{P}_{h,i}} \right)^2 \leq 4c_1^{-3} \xi \|h^{-\frac{1}{2}} \pi_{\mathcal{P}}(p_h|_{\gamma} - p_{\gamma,h})\|_{0,\gamma}^2. \end{aligned}$$

Now with $C_3 = c_2^{-1}$, $C_4 = c_1^{-2}$ and $C_5 = 4c_1^{-3}\xi$, the proof is completed. \blacksquare

Before stating Lemma 4, still following Burman and Hansbo (2010), we define a subspace \mathcal{Y}_h of $V_{h,\Omega}$ consisting of certain functions having support “near” γ , (i.e. in $\mathcal{G}_{h,\gamma}$, see (17)). Toward this end we partition $\mathcal{G}_{h,\gamma}$ into a set of thickened patches $\mathcal{P}_{h,i}$, $i = 1, \dots, n_h$, where $\mathcal{P}_{h,i}$ is made up of a choice of cells $T \in \mathcal{S}_h$ such that $\mathcal{P}_{h,i} \subset \mathcal{P}_{h,i}$, see Fig. 1. The 1D patches $\mathcal{P}_{h,i}$ should be constructed in such a way that to each thick patch $\mathcal{P}_{h,i}$, we can associate a patch function $\phi_i \in V_{h,\Omega}$ such that for $i = 1, \dots, n_h$ the patch function ϕ_i satisfies the following conditions:

- $0 \leq \phi_i(x) \leq 1$, $\forall x \in \Omega$,
- ϕ_i vanishes outside $\mathcal{P}_{h,i}$,
- ϕ_i is identically equal to 1 on some face $F \in \mathcal{F}_h$ cut by γ ,
- there are constants c_3 and c_4 independent of h and of i such that

$$c_3 \leq \frac{1}{h} \int_{\mathcal{P}_{h,i}} \phi_i \quad \text{and} \quad h|\nabla \phi_i(x)| \leq c_4, \text{ for a. e. } x \in \Omega. \quad (18)$$

Because of the uniform regularity of \mathcal{T}_h , it is always possible to construct the patches in such a way: it suffices to amalgamate enough elements $s \in \mathcal{T}_{h,\lambda}$. The subspace \mathcal{Y}_h is the space generated by the functions ϕ_i ; $i = 1, \dots, n_h$. We note also that there is a constant c_5 independent of h such that

$$|\mathcal{P}_{h,i}| \leq c_5 h^2. \quad (19)$$

Lemma 4 *There exist positive constants C_6 , C_7 and C_8 , independent of h , such that for λ_h in Λ_h there is an element $r_h \in \mathcal{Y}_h \subset V_{h,\Omega}$ such that:*

$$\begin{aligned} \langle \pi_{\mathcal{P}} \lambda_h, r_h \rangle_{\gamma} &\geq C_6 \|\pi_{\mathcal{P}} \lambda_h\|_{-\frac{1}{2},h,\gamma}^2, \\ \|r_h|_{\gamma}\|_{\frac{1}{2},h,\gamma}^2 &\leq C_7 \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2, \\ \|\nabla r_h\|_{0,\Omega}^2 &\leq C_8 \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2. \end{aligned}$$

Proof Let $\lambda_h \in \Lambda_h$. We define $r_h \in \mathcal{Y}_h \subset V_{h,\Omega}$ by taking a linear combination of the patch functions as follows:

$$r_h = \sum_{i=1}^{n_h} C_{\mathcal{P}_i} \phi_i, \quad \text{where} \quad C_{\mathcal{P}_i} = \frac{\int_{\mathcal{P}_{h,i}} h_{\mathcal{P}} \lambda_h}{\int_{\mathcal{P}_{h,i}} \phi_i}. \quad (20)$$

We then have $r_h|_{\Omega \setminus \mathcal{G}_{h,\gamma}} = 0$, and recalling that ϕ_i vanishes outside of $\mathcal{P}_{h,i}$, we also have

$$\int_{\mathcal{P}_{h,i}} r_h = \int_{\mathcal{P}_{h,i}} h_{\mathcal{P}} \lambda_h, \quad \forall i = 1, \dots, n_h. \quad (21)$$

One has $\left(\int_{\mathcal{P}_{h,i}} \phi_i\right)^{-2} \leq c_3^{-2} h^{-2}$ from (18), and $\left(\int_{\mathcal{P}_{h,i}} \lambda_h\right)^2 \leq h_{\mathcal{P}_{h,i}} \int_{\mathcal{P}_{h,i}} \lambda_h^2$ by the Cauchy-Schwarz inequality. Thus, using (13), we have the estimate

$$C_{\mathcal{P}_i}^2 \leq c_2^3 c_3^{-2} \int_{\mathcal{P}_{h,i}} h \lambda_h^2 \quad \forall i = 1, \dots, n_h. \quad (22)$$

Now to check that r_h satisfies the first inequality of the lemma, since $\pi_{\mathcal{P}} \lambda_h$ is constant on $\mathcal{P}_{h,i}$, $i = 1, \dots, n_h$, we can use (21), (14) and then (13) to obtain

$$\begin{aligned} \langle \pi_{\mathcal{P}} \lambda_h, r_h \rangle_{\gamma} &= \sum_{i=1}^{n_h} (\pi_{\mathcal{P}} \lambda_h)|_{\mathcal{P}_{h,i}} \int_{\mathcal{P}_{h,i}} r_h = \sum_{i=1}^{n_h} (\pi_{\mathcal{P}} \lambda_h)|_{\mathcal{P}_{h,i}} \int_{\mathcal{P}_{h,i}} h_{\mathcal{P}} \lambda_h \\ &= h_{\mathcal{P}} \langle \pi_{\mathcal{P}} \lambda_h, \lambda_h \rangle_{\gamma} = h_{\mathcal{P}} \int_{\gamma} (\pi_{\mathcal{P}} \lambda_h)^2 \geq c_1 \|\pi_{\mathcal{P}} \lambda_h\|_{-\frac{1}{2}, h, \gamma}^2. \end{aligned}$$

For the second inequality we note that by the definition of r_h in (20), we have

$$\|r_h|_{\gamma}\|_{\frac{1}{2}, h, \gamma}^2 = h^{-1} \sum_{i=1}^{n_h} C_{\mathcal{P}_i}^2 \int_{\mathcal{P}_{h,i}} \phi_i^2 \leq c_2 \sum_{i=1}^{n_h} C_{\mathcal{P}_i}^2$$

because (13), together with the fact that $|\phi_i(x)| \leq 1$, $\forall x \in \gamma$, implies that $\int_{\mathcal{P}_{h,i}} \phi_i^2 \leq h_{\mathcal{P}_{h,i}} \leq c_2 h$. Thus using (22), one obtains

$$\|r_h|_{\gamma}\|_{\frac{1}{2}, h, \gamma}^2 \leq \sum_{i=1}^{n_h} c_2^4 c_3^{-2} \int_{\mathcal{P}_{h,i}} h \lambda_h^2 = c_2^4 c_3^{-2} \|\lambda_h\|_{-\frac{1}{2}, h, \gamma}^2.$$

For the third inequality, since the supports of the ϕ_i 's are disjoint, we have

$$\|\nabla r_h\|_{0, \Omega}^2 = \sum_{i=1}^{n_h} C_{\mathcal{P}_i}^2 \int_{\mathcal{P}_{h,i}} (\nabla \phi_i)^2 \leq c_2^2 c_4^2 c_5 \sum_{i=1}^{n_h} C_{\mathcal{P}_i}^2 \leq c_2^5 c_3^{-2} c_4^2 c_5 \sum_{i=1}^{n_h} \int_{\mathcal{P}_{h,i}} h \lambda_h^2,$$

where we have used (18), then (19) and (22). The lemma now follows with $C_6 = c_1$, $C_7 = c_2^4 c_3^{-2}$ and $C_8 = c_2^5 c_3^{-2} c_4^2 c_5$. \blacksquare

We can now state a stability theorem for the problem given by (8).

Theorem 1 *Let $\xi > 0$. There is a positive constant θ , independent of h , such that if $P_h = (p_h, p_{\gamma, h}; \lambda_h) \in \mathbf{V}_h \times \Lambda_h$, then*

$$\theta \|P_h\|_{1, h} \leq \sup_{\substack{Q_h = (q_h, q_{\gamma, h}; \mu_h) \\ Q_h \in \mathbf{V}_h \times \Lambda_h}} \frac{\mathcal{A}(P_h, Q_h) + \mathcal{J}(\lambda_h, \mu_h)}{\|Q_h\|_{1, h}}. \quad (23)$$

Proof Clearly, it suffices to show that there exist positive constants θ_1 and θ_2 such that if $P_h = (p_h, p_{\gamma,h}, \lambda_h) \in \mathbf{V}_h \times \Lambda_h$ there exists $Q_h = (q_h, q_{\gamma,h}, \mu_h) \in \mathbf{V}_h \times \Lambda_h$ such that

$$\theta_1 \|Q_h\|_{1,h} \leq \|P_h\|_{1,h} \quad \text{and} \quad \theta_2 \|P_h\|_{1,h}^2 \leq \mathcal{A}(P_h, Q_h) + \mathcal{J}(\lambda_h, \mu_h). \quad (24)$$

Let $P_h = (p_h, p_{\gamma,h}; \lambda_h) \in \mathbf{V}_h \times \Lambda_h$. The idea is to put

$$Q_h = P_h + R_h, \quad \text{with } R_h = (-c_r r_h, 0; c_\eta \eta_h) \in \mathbf{V}_h \times \Lambda_h$$

with η_h and r_h as constructed in Lemmas (3) and (4), respectively, and with c_r and c_η positive constants to be determined in such a way that both equations of (24) are satisfied with θ_1 and θ_2 independent of the choice of P_h .

To obtain the first estimate of (24), we use Lemmas 3 and 4 with (15):

$$\begin{aligned} \|Q_h\|_{1,h}^2 &= \|\nabla p_h - c_r \nabla r_h\|_{0,\Omega}^2 + \|\nabla_\tau p_{\gamma,h}\|_{0,\gamma}^2 + \|\lambda_h + c_\eta \eta_h\|_{-\frac{1}{2},h,\gamma}^2 \\ &\quad + \|p_h|_\gamma - c_r r_h|_\gamma - p_{\gamma,h}\|_{\frac{1}{2},h,\gamma}^2 + \mathcal{J}(\lambda_h + c_\eta \eta_h, \lambda_h + c_\eta \eta_h) \\ &\leq 2 \left(\|P_h\|_{1,h}^2 + c_\eta^2 (\|\eta_h\|_{-\frac{1}{2},h,\gamma}^2 + \mathcal{J}(\eta_h, \eta_h)) + c_r^2 (\|\nabla r_h\|_{0,\Omega}^2 + \|r_h\|_{\frac{1}{2},h,\gamma}^2) \right) \\ &\leq 2 \left(\|P_h\|_{1,h}^2 + c_\eta^2 (C_4 + C_5) \|p_h|_\gamma - p_{\gamma,h}\|_{\frac{1}{2},h,\gamma}^2 + c_r^2 (C_7 + C_8) \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2 \right). \end{aligned}$$

Thus putting $\theta_1 = (2(1 + \max\{c_\eta^2(C_4 + C_5), c_r^2(C_7 + C_8)\}))^{-\frac{1}{2}}$ we obtain the first inequality of (24).

For the second estimate of (24), letting $\mu_h = \lambda_h + c_\eta \eta_h$, we have

$$\mathcal{A}(P_h, Q_h) + \mathcal{J}(\lambda_h, \mu_h) = \mathcal{A}(P_h, P_h) + \mathcal{J}(\lambda_h, \lambda_h) + \mathcal{A}(P_h, R_h) + c_\eta \mathcal{J}(\lambda_h, \eta_h). \quad (25)$$

Now we bound from below each term in (25). For the first two terms,

$$\begin{aligned} \mathcal{A}(P_h, P_h) + \mathcal{J}(\lambda_h, \lambda_h) &= \|\mathbf{K}^{\frac{1}{2}} \nabla p_h\|_{0,\Omega}^2 + \|\mathbf{K}_\gamma^{\frac{1}{2}} \nabla_\tau p_{\gamma,h}\|_{0,\gamma}^2 + \mathcal{J}(\lambda_h, \lambda_h) \\ &\geq C_{\mathbf{K}}^m (\|\nabla p_h\|_{0,\Omega}^2 + \|\nabla_\tau p_{\gamma,h}\|_{0,\gamma}^2) + \mathcal{J}(\lambda_h, \lambda_h). \end{aligned} \quad (26)$$

For the fourth term, using (7), Young's inequality, then the third inequality of Lemma 3 and (15), we obtain, for each $\varepsilon_\eta > 0$,

$$\begin{aligned} c_\eta \mathcal{J}(\lambda_h, \eta_h) &\geq -c_\eta \mathcal{J}(\lambda_h, \lambda_h)^{\frac{1}{2}} \mathcal{J}(\eta_h, \eta_h)^{\frac{1}{2}} \geq -\frac{c_\eta}{\varepsilon_\eta} \mathcal{J}(\lambda_h, \lambda_h) - \frac{c_\eta \varepsilon_\eta}{4} \mathcal{J}(\eta_h, \eta_h) \\ &\geq -\frac{c_\eta}{\varepsilon_\eta} \mathcal{J}(\lambda_h, \lambda_h) - \frac{c_\eta \varepsilon_\eta}{4} C_5 \|p_h|_\gamma - p_{\gamma,h}\|_{\frac{1}{2},h,\gamma}^2. \end{aligned} \quad (27)$$

There remains to bound the third term in (25):

$$\mathcal{A}(P_h, R_h) = -c_r \int_\Omega \mathbf{K} \nabla p_h \cdot \nabla r_h + c_r \langle \lambda_h, r_h|_\gamma \rangle_\gamma + c_\eta \langle \eta_h, p_h|_\gamma - p_{\gamma,h} \rangle_\gamma. \quad (28)$$

For the first term of the right hand side of (28) we have, for each $\varepsilon_r > 0$,

$$\begin{aligned} -c_r \int_\Omega \mathbf{K} \nabla p_h \cdot \nabla r_h &\geq -\frac{c_r}{\varepsilon_r} \|\mathbf{K}^{\frac{1}{2}} \nabla p_h\|_\Omega^2 - \frac{c_r \varepsilon_r}{4} \|\mathbf{K}^{\frac{1}{2}} \nabla r_h\|_\Omega^2 \\ &\geq -\frac{c_r}{\varepsilon_r} C_{\mathbf{K}}^M \|\nabla p_h\|_\Omega^2 - \frac{c_r \varepsilon_r}{4} C_{\mathbf{K}}^M C_8 \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2. \end{aligned} \quad (29)$$

For the second term, using the Cauchy-Schwarz type inequality (11), the first inequality of Lemma 4, Young's inequality, the second inequality of Lemma 4 and Lemma 2, we obtain

$$\begin{aligned}
c_r \langle \lambda_h, r_h|_\gamma \rangle_\gamma &= c_r \langle \lambda_h - \pi_p \lambda_h, r_h|_\gamma \rangle_\gamma + c_r \langle \pi_p \lambda_h, r_h|_\gamma \rangle_\gamma \\
&\geq -\frac{c_r}{\varepsilon_r} \|\lambda_h - \pi_p \lambda_h\|_{-\frac{1}{2},h,\gamma}^2 - \frac{c_r \varepsilon_r}{4} \|r_h|_\gamma\|_{\frac{1}{2},h,\gamma}^2 + c_r C_6 \|\pi_p \lambda_h\|_{-\frac{1}{2},h,\gamma}^2 \\
&\geq -\frac{c_r}{\varepsilon_r} \|\lambda_h - \pi_p \lambda_h\|_{-\frac{1}{2},h,\gamma}^2 - \frac{c_r \varepsilon_r}{4} C_7 \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2 \\
&\quad + c_r C_6 \left(\frac{1}{2} \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2 - \|\lambda_h - \pi_p \lambda_h\|_{-\frac{1}{2},h,\gamma}^2 \right) \\
&\geq -c_r \left(C_6 + \frac{1}{\varepsilon_r} \right) \|\lambda_h - \pi_p \lambda_h\|_{-\frac{1}{2},h,\gamma}^2 + c_r \left(\frac{1}{2} C_6 - \frac{\varepsilon_r}{4} C_7 \right) \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2 \\
&\geq -c_r \left(C_6 + \frac{1}{\varepsilon_r} \right) C_2 \mathcal{J}(\lambda_h, \lambda_h) + c_r \left(\frac{1}{2} C_6 - \frac{\varepsilon_r}{4} C_7 \right) \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2,
\end{aligned} \tag{30}$$

where we have also used the inequality $\|a\|^2 \leq 2(\|a-b\|^2 + \|b\|^2)$ which gives $\|b\|^2 \geq \frac{1}{2}\|a\|^2 - \|a-b\|^2$. For the third term of the right hand side of (28) we use the first inequality of Lemma 3 and then Lemma 1 to obtain

$$\begin{aligned}
c_\eta \langle \eta_h, p_h|_\gamma - p_{\gamma,h} \rangle_\gamma &\geq c_\eta C_3 \|\pi_p(p_h|_\gamma - p_{\gamma,h})\|_{\frac{1}{2},h,\gamma}^2 \\
&\geq c_\eta C_3 \left(\tilde{C}_1 \|p_h|_\gamma - p_{\gamma,h}\|_{\frac{1}{2},h,\gamma}^2 - \|\nabla p_h\|_{0,\mathcal{G}_{h,\gamma}}^2 - h \|\nabla_\tau p_{\gamma,h}\|_{0,\gamma}^2 \right).
\end{aligned} \tag{31}$$

Thus adding equations (26), (27), (29), (30) and (31), we have

$$\begin{aligned}
\mathcal{A}(P_h, Q_h) + \mathcal{J}(\lambda_h, \mu_h) &\geq (C_{\mathbf{K}}^m - c_\eta C_3 - \frac{c_r}{\varepsilon_r} C_{\mathbf{K}}^M) \|\nabla p_h\|_{0,\Omega}^2 \\
&\quad + (C_{\mathbf{K}}^m - c_\eta C_3 h) \|\nabla_\tau p_{\gamma,h}\|_{0,\gamma}^2 + c_\eta (\tilde{C}_1 C_3 - \frac{\varepsilon_r}{4} C_5) \|p_h|_\gamma - p_{\gamma,h}\|_{\frac{1}{2},h,\gamma}^2 \\
&\quad + c_r \left(\frac{C_6}{2} - \frac{\varepsilon_r}{4} (C_7 + C_{\mathbf{K}}^M C_8) \right) \|\lambda_h\|_{-\frac{1}{2},h,\gamma}^2 + \left(1 - \frac{c_\eta}{\varepsilon_\eta} - c_r C_2 \left(C_6 + \frac{1}{\varepsilon_r} \right) \right) \mathcal{J}(\lambda_h, \lambda_h).
\end{aligned}$$

To complete the demonstration of the second estimate in (24), we have only to choose $\varepsilon_\eta, \varepsilon_r, c_r$ and c_η such that all of the constant factors above are positive.

This can be done by choosing, for instance, $\varepsilon_r = \frac{C_6}{C_7 + C_{\mathbf{K}}^M C_8}$, $\varepsilon_\eta = \frac{2\tilde{C}_1 C_3}{C_5}$, $c_r = \min\{\frac{1}{4C_2(C_6 + \frac{1}{\varepsilon_r})}, \frac{\varepsilon_r}{4} \frac{C_{\mathbf{K}}^M}{C_{\mathbf{K}}^M}\}$ and $c_\eta = \min\{\frac{C_{\mathbf{K}}^m}{2hC_3}, \frac{C_{\mathbf{K}}^m}{4C_3}, \frac{\varepsilon_\eta}{4}\}$. We can then set $\theta_2 = \min\{\frac{1}{2}, \frac{1}{2} C_{\mathbf{K}}^m, \frac{1}{2} c_\eta \tilde{C}_1 C_3, \frac{1}{4} c_r C_6\}$. \blacksquare

From Theorem 1, we deduce the following corollary.

Corollary 1 *For any $\xi > 0$, formulation (8) admits a unique solution $P_h = (p_h, p_{\gamma,h}; \lambda_h) \in \mathbf{V}_h \times \Lambda_h$.*

3.5 Convergence

Here we prove a Céa-type, best-approximation result and consider the question of convergence rates. The convergence depends on approximation results that are derived under assumptions concerning the regularity of problem (3).

Proposition 3 *Let $P = (p, p_\gamma; \lambda) \in \mathbf{V} \times \Lambda$ be the solution of (3) and let $P_h = (p_h, p_{\gamma,h}; \lambda_h) \in \mathbf{V}_h \times \Lambda_h$ be the solution of (8). Then there is a constant $\theta_c > 0$ independent of h such that for each $Q_h = (q_h, q_{\gamma,h}; \mu_h) \in \mathbf{V}_h \times \Lambda_h$,*

$$\|P - P_h\|_{0,h} + \mathcal{J}(\lambda_h, \lambda_h)^{\frac{1}{2}} \leq \theta_c \left(\|P - Q_h\|_{0,h} + \mathcal{J}(\mu_h, \mu_h)^{\frac{1}{2}} \right). \quad (32)$$

Proof Let $Q_h = (q_h, q_{\gamma,h}; \mu_h) \in \mathbf{V}_h \times \Lambda_h$. From the triangle inequality we have

$$\|P - P_h\|_{0,h} + \mathcal{J}(\lambda_h, \lambda_h)^{\frac{1}{2}} \leq \|P - Q_h\|_{0,h} + \mathcal{J}(\mu_h, \mu_h)^{\frac{1}{2}} + \sqrt{2} \|Q_h - P_h\|_{1,h}. \quad (33)$$

Because of (23) and (9), there exists $R_h = (r_h, r_{h,\gamma}; \eta_h) \in \mathbf{V}_h \times \Lambda_h$ with

$$\begin{aligned} \theta \|Q_h - P_h\|_{1,h} &\leq \frac{\mathcal{A}(Q_h - P_h, R_h) + \mathcal{J}(\mu_h - \lambda_h, \eta_h)}{\|R_h\|_{1,h}} \\ &= \frac{\mathcal{A}(Q_h - P, R_h) + \mathcal{J}(\mu_h, \eta_h)}{\|R_h\|_{1,h}}. \end{aligned}$$

Thus using the continuity (12) and inequality (7), we obtain

$$\begin{aligned} \theta \|Q_h - P_h\|_{1,h} &\leq C_c \|Q_h - P\|_{0,h} \frac{\|R_h\|_{0,h}}{\|R_h\|_{1,h}} + \mathcal{J}(\mu_h, \mu_h)^{\frac{1}{2}} \frac{\mathcal{J}(\eta_h, \eta_h)^{\frac{1}{2}}}{\|R_h\|_{1,h}} \\ &\leq C_c \|Q_h - P\|_{0,h} + \mathcal{J}(\mu_h, \mu_h)^{\frac{1}{2}}. \end{aligned} \quad (34)$$

Then (32) follows from (33) and (34) with $\theta_c = \max\{1 + \frac{\sqrt{2}C_c}{\theta}, 1 + \frac{\sqrt{2}}{\theta}\}$. \blacksquare

We now recall two trace inequalities. The proof of the first may be found in (Costabel, 1988, Lemma 3.6) (*cf.* also (Ding, 1996, Theorem 1)). For \mathcal{O} a Lipschitz domain, and $\alpha \in (\frac{1}{2}, \frac{3}{2})$, there is a constant \tilde{C}_{tr} such that

$$\|\phi|_{\partial\mathcal{O}}\|_{\alpha-\frac{1}{2},\partial\mathcal{O}} \leq \tilde{C}_{tr} \|\phi\|_{\alpha,\mathcal{O}} \quad \forall \phi \in H^\alpha(\mathcal{O}). \quad (35)$$

The second is a multiplicative trace inequality which follows from (Girault and Glowinski, 1995, Lemma 2), or from Ainsworth (2007), see also (Köppel *et al.*, 2018, Lemma 1). There is a constant $C_{tr} > 0$ such that if T a triangle or rectangle

$$\|q\|_{0,\gamma \cap T}^2 \leq C_{tr} (h^{-1} \|q\|_{0,T}^2 + h \|\nabla q\|_{0,T}^2), \quad \forall q \in H^1(T). \quad (36)$$

For approximation results we will use the Scott-Zhang interpolation operators associated with the approximation spaces $V_{h,\Omega}$ and $V_{h,\gamma}$:

$$\mathcal{I}_h^\Omega : H_0^1(\Omega) \longrightarrow V_{h,\Omega} \quad \text{and} \quad \mathcal{I}_h^\gamma : H_0^1(\gamma) \longrightarrow V_{h,\gamma}.$$

We have that if $\frac{1}{2} < \alpha \leq 2$ and $0 \leq \beta \leq \alpha$, then

$$\begin{aligned} \|\mathcal{I}_h^\Omega q - q\|_{\beta,\Omega} &\leq C_{\mathcal{I}_\Omega} h^{\alpha-\beta} |q|_{\alpha,\Omega}, \quad \forall q \in H^\alpha(\Omega), \\ \|\mathcal{I}_h^\gamma q_\gamma - q_\gamma\|_{\beta,\gamma} &\leq C_{\mathcal{I}_\gamma} h_\gamma^{\alpha-\beta} |q_\gamma|_{\alpha,\gamma}, \quad \forall q_\gamma \in H^\alpha(\gamma), \end{aligned} \quad (37)$$

where $|\cdot|_\alpha$ is an α -semi-norm; see (Ern and Guermond, 2004, Section 1.6.2).

Define π_h to be the $L^2(\Omega)$ -projection onto $\mathbb{P}^0(\mathcal{T}_h)$, the space of piecewise constant functions on Ω subordinate to \mathcal{T}_h . We have

$$\|\pi_h q - q\|_{0,\Omega} \leq C_{\pi_h} h \|\nabla q\|_{0,\Omega}, \quad \forall q \in H^1(\Omega). \quad (38)$$

We will make use of the following auxiliary problem: let Ω_1 and Ω_2 be the two subdomains of Ω obtained by splitting Ω along γ . For $\zeta \in H^{\frac{1}{2}}(\gamma)$ and for $j = 1, 2$, let $r_{\zeta,j} \in H^1(\Omega_j)$ be the solution of

$$\begin{aligned} -\Delta r_{\zeta,j} &= 0 && \text{in } \Omega_j, \\ r_{\zeta,j} &= \zeta && \text{on } \gamma, \\ \nabla r_{\zeta,j} \cdot \mathbf{n} &= 0 && \text{on } \partial\Omega_j \setminus \gamma. \end{aligned} \quad (39)$$

These problems are well posed $\forall \zeta \in H^{\frac{1}{2}}(\gamma)$ and for $j = 1, 2$, (cf. (Galvis and Sarkis, 2007, Lemma 2.1)) and r_ζ , defined by $r_\zeta|_{\Omega_j} = r_{\zeta,j}$, belongs to $H^1(\Omega)$ as $r_{\zeta,1}$ and $r_{\zeta,2}$ coincide on γ . We have

$$\|r_\zeta\|_{1,\Omega} \leq C_a \|\zeta\|_{\frac{1}{2},\gamma}. \quad (40)$$

Lemma 5 *There exists a constant C_9 such that if $\zeta \in H^{\frac{1}{2}}(\gamma)$, and $r_\zeta \in H^1(\Omega)$ is such that $r_\zeta|_{\Omega_1}$ and $r_\zeta|_{\Omega_2}$ are the solutions to (39), for $j = 1$ and 2 , then*

$$\|\zeta - (\pi_h r_\zeta)|_\gamma\|_{-\frac{1}{2},h,\gamma} \leq C_9 h \|\zeta\|_{\frac{1}{2},\gamma} \quad \text{and} \quad \mathcal{J}((\pi_h r_\zeta)|_\gamma, (\pi_h r_\zeta)|_\gamma)^{\frac{1}{2}} \leq C_9 h \|\zeta\|_{\frac{1}{2},\gamma}.$$

Proof Both of these estimates are based on the trace inequality (36) applied cell by cell. For the first estimate, inequality (36) is applied for each cell $T \in \mathcal{T}_h$ cut by γ , to $\gamma \cap T$ in relation to T : because ζ and r_ζ agree on γ and because $r_\zeta|_T$ and $(\pi_h r_\zeta)|_T$ belong to $H^1(T)$, using (10) and then using (36) for each cell cut by γ and summing over these cells and finally applying (38), we obtain

$$\begin{aligned} \|\zeta - (\pi_h r_\zeta)|_\gamma\|_{-\frac{1}{2},h,\gamma}^2 &= h \|(r_\zeta - \pi_h r_\zeta)|_\gamma\|_{0,\gamma}^2 \\ &\leq C_{tr} \left(\|r_\zeta - \pi_h r_\zeta\|_{0,\mathcal{G}_{h,\gamma}}^2 + h^2 \|\nabla r_\zeta\|_{0,\mathcal{G}_{h,\gamma}}^2 \right) \\ &\leq C_{tr} (1 + C_{\pi_h}^2) h^2 \|\nabla r_\zeta\|_{0,\mathcal{G}_{h,\gamma}}^2. \end{aligned}$$

The first estimate, with $C_9 = (C_{tr}(1 + C_{\pi_h}^2))^{\frac{1}{2}} C_a$, now follows from (40).

For the second estimate, inequality (36) is applied for each face $F \in \mathcal{F}_h$ cut by γ , to F in relation to each cell $T \in \mathcal{T}_h$ having F as a face: using the definition of \mathcal{J} , the fact that, for each face $F \in \mathcal{F}_h$, $[(\pi_h r_\zeta)]_F$ is constant and $[[r_\zeta]]_F = 0$

and $h \leq \frac{|F|}{\rho_h} h \leq \sigma_\Omega |F|$ and then using (36), (38) and (40) we obtain

$$\begin{aligned}
\mathcal{J}((\pi_h r_\zeta)|_\gamma, (\pi_h r_\zeta)|_\gamma) &= \sum_{f \in \mathcal{F}_{h,\lambda}} \xi h^2 \llbracket (\pi_h r_\zeta)|_\gamma \rrbracket_f^2 \leq \xi \sigma_\Omega h \sum_{f \in \mathcal{F}_{h,\lambda}} \int_{F_f} \llbracket \pi_h r_\zeta \rrbracket_{F_f}^2 \\
&= \xi \sigma_\Omega h \sum_{f \in \mathcal{F}_{h,\lambda}} \|\llbracket r_\zeta - \pi_h r_\zeta \rrbracket_{F_f}\|_{0,F_f}^2 \\
&\leq 2\xi \sigma_\Omega \sum_{f \in \mathcal{F}_{h,\lambda}} \sum_{i=1}^2 C_{tr} \left(\|r_\zeta - \pi_h r_\zeta\|_{0,T_{F_f}^i}^2 + h^2 \|\nabla r_\zeta\|_{0,T_{F_f}^i}^2 \right) \\
&\leq 2\xi \sigma_\Omega \sum_{f \in \mathcal{F}_{h,\lambda}} \sum_{i=1}^2 C_{tr} (1 + C_{\pi_h}^2) h^2 \|\nabla r_\zeta\|_{0,T_{F_f}^i}^2 \\
&\leq 4\xi \sigma_\Omega C_{tr} (1 + C_{\pi_h}^2) h^2 \|\nabla r_\zeta\|_{0,\Omega}^2
\end{aligned}$$

where for $f \in \mathcal{F}_{h,\lambda}$, F_f denotes the face in \mathcal{F}_h containing f , and $T_{F_f}^1$ and $T_{F_f}^2$ are the two cells in \mathcal{T}_h having F_f as a face. The second estimate now follows as above with $C_9 = 2(\xi \sigma_\Omega C_{tr} (1 + C_{\pi_h}^2))^{\frac{1}{2}} C_a$. \blacksquare

Lemma 6 Assume that $p \in H^{1+\alpha}(\Omega)$ and $p|_{\Omega_j} \in H^2(\Omega_j)$ for $j = 1, 2$, $p_\gamma \in H^{1+\tilde{\alpha}}(\gamma)$, for some $\alpha, \tilde{\alpha} \in (\frac{1}{2}, \frac{3}{2})$, and $\lambda = \llbracket \mathbf{K} \nabla p \cdot \mathbf{n}_\gamma \rrbracket \in H^{\frac{1}{2}}(\gamma)$. If $r_\lambda \in H^1(\Omega)$ is defined as in Lemma 5 with $\zeta = \lambda$, it follows that

$$\begin{aligned}
&\| (p - \mathcal{I}_h^\Omega p, p_\gamma - \mathcal{I}_h^\gamma p_\gamma; \lambda - (\pi_h r_\lambda)|_\gamma) \|_{1,h} \\
&\leq C_{10} (h^\alpha \|p\|_{1+\alpha,\Omega} + h_\gamma^{\tilde{\alpha}} \|p_\gamma\|_{1+\tilde{\alpha},\gamma} + h \sum_{j=1,2} \|p\|_{2,\Omega_j}).
\end{aligned}$$

Proof Using the definition of the norm $\|\cdot\|_{0,h}$ we have

$$\begin{aligned}
&\| (p - \mathcal{I}_h^\Omega p, p_\gamma - \mathcal{I}_h^\gamma p_\gamma; \lambda - \pi_h r_\lambda) \|_{0,h}^2 = \|\nabla(p - \mathcal{I}_h^\Omega p)\|_{0,\Omega}^2 \\
&\quad + \|\nabla_\tau(p_\gamma - \mathcal{I}_h^\gamma p_\gamma)\|_{0,\gamma}^2 + \|(p - \mathcal{I}_h^\Omega p)|_\gamma\|_{\frac{1}{2},h,\gamma}^2 \\
&\quad + \|p_\gamma - \mathcal{I}_h^\gamma p_\gamma\|_{\frac{1}{2},h,\gamma}^2 + \|\lambda - (\pi_h r_\lambda)|_\gamma\|_{-\frac{1}{2},h,\gamma}^2.
\end{aligned}$$

The first two terms can be controlled using the interpolation estimates (37). For the third term, using (36), and again (37), we obtain

$$\begin{aligned}
\|(p_h - \mathcal{I}_h^\Omega p_h)|_\gamma\|_{\frac{1}{2},h,\gamma}^2 &= \sum_{T \in \mathcal{S}_h} \|(p_h - \mathcal{I}_h^\Omega p_h)|_\gamma\|_{\frac{1}{2},h,T \cap \gamma}^2 \\
&\leq \sum_{T \in \mathcal{S}_h} C_{tr} (h^{-2} \|p_h - \mathcal{I}_h^\Omega p_h\|_{0,T}^2 + \|\nabla(p_h - \mathcal{I}_h^\Omega p_h)\|_{0,T}^2) \\
&\leq \sum_{T \in \mathcal{S}_h} 2C_{tr} C_{\mathcal{I}_\Omega}^2 h^{2\alpha} |p|_{1+\alpha,T}^2 \leq 2C_{tr} C_{\mathcal{I}_\Omega}^2 h^{2\alpha} |p|_{1+\alpha,\Omega}^2.
\end{aligned}$$

To control the fourth term we need only (37)

$$\|p_\gamma - \mathcal{I}_h^\gamma p_\gamma\|_{\frac{1}{2},h,\gamma} \leq h_\gamma^{-\frac{1}{2}} C_{\mathcal{I}_\gamma} h_\gamma^{1+\tilde{\alpha}} |p_\gamma|_{1+\tilde{\alpha},\gamma} = C_{\mathcal{I}_\gamma} h_\gamma^{\frac{1}{2}+\tilde{\alpha}} |p_\gamma|_{1+\tilde{\alpha},\gamma}.$$

For the fifth term we use Lemma 5 together with the definition of λ and (35):

$$\|\lambda\|_{\frac{1}{2},\gamma} = \|[\mathbf{K}\nabla p \cdot \mathbf{n}_\gamma]\|_{\frac{1}{2},\gamma} \leq \sum_{j=1,2} C_{\mathbf{K}}^M \tilde{C}_{tr} \|\nabla p\|_{1,\Omega_j} \leq C_{\mathbf{K}}^M \tilde{C}_{tr} \sum_{j=1,2} \|p\|_{2,\Omega_j}.$$

The stabilizing term $\mathcal{J}(\lambda_h, \lambda_h)^{\frac{1}{2}}$ is controlled similarly by the second estimate of Lemma 5. Thus the proof is completed. \blacksquare

Theorem 2 *Again, let $P = (p, p_\gamma; \lambda) \in \mathbf{V} \times \Lambda$ be the solution of (3) and let $P_h = (p_h, p_{\gamma,h}; \lambda_h) \in \mathbf{V}_h \times \Lambda_h$ be the solution of (8), and suppose the same regularity as in Lemma 6. Then there exists a constant C such that*

$$\|P - P_h\|_{0,h} + \mathcal{J}(\lambda_h, \lambda_h)^{\frac{1}{2}} \leq C(h^\alpha \|p\|_{1+\alpha,\Omega} + h_{\gamma}^{\tilde{\alpha}} \|p_\gamma\|_{1+\tilde{\alpha},\gamma} + h \sum_{j=1,2} \|p\|_{2,\Omega_j}).$$

Proof In Proposition 3 choose $q_h = \mathcal{I}_h^\Omega p$, $q_{\gamma,h} = \mathcal{I}_h^\gamma p_\gamma$ and $\mu_h = \pi_h r_\lambda$ where r_λ is defined as in Lemma 5 with $\zeta = \lambda$. Then the estimate follows directly from Lemma 6. \blacksquare

Remark 1 Generally p is expected to belong to $H^{3/2-\varepsilon}(\Omega)$ for $\varepsilon > 0$, and it is reasonable to assume that p_γ belongs to $H^2(\gamma)$ and that $p|_{\Omega_j} \in H^2(\Omega_j)$. Thus $(\mathbf{K}\nabla p|_{\Omega_j} \cdot \mathbf{n}_\gamma)|_\gamma$ belongs to $H^{\frac{1}{2}}(\gamma)$, and the jump λ is indeed in $H^{\frac{1}{2}}(\gamma)$. Thus Theorem 2 provides generally a suboptimal $\mathcal{O}(h^{\frac{1}{2}-\varepsilon})$ convergence. However a better rate of convergence of $\mathcal{O}(h)$ is frequently observed in practice.

4 Numerical results

This section is devoted to numerical experiments studying the proposed discretization (8). In particular we address accuracy, convergence and conditioning for various choices of the penalization parameter. A direct solver is used to solve the linear system.

4.1 Case 1: a vertical fracture

The first setup is a two-dimensional, square domain $\Omega := [0, 1]^2$ with homogeneous Neumann conditions on the horizontal boundaries and nonhomogeneous Dirichlet conditions on the vertical boundaries ($p = 1$ on the left and $p = 4$ on the right). A vertical fracture γ with $\mathbf{K}_\gamma = 10$, $\mathbf{K} = \mathbf{I}$, is located in the middle of the matrix domain Ω with Dirichlet boundary values $p_\gamma = 1$ on the lower tip and $p_\gamma = 4$ on the upper tip. The test case and the pressure distribution are shown in Fig. 2. The simulations are performed for various mesh sizes h , h_γ and h_λ . However, due to the high permeability in the vertical fracture, we have taken $h_\gamma = h/2$ in order to obtain high accuracy at the fracture interface. In the simulations the fracture is either located on the edges of the rectangular matrix grid, referred to as *conforming*, or in the center of the rectangular elements, referred to as *nonconforming*.

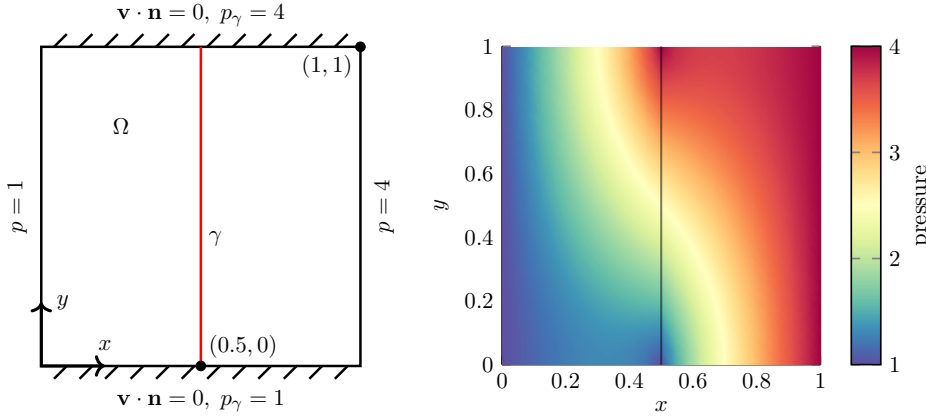


Fig. 2 Case 1 (a vertical fracture): General setting (left) and distribution of the pressures (right) of a simulation with $h = 1/24$, $h_\gamma = 1/48$, $\xi = 1$.

On this basis we study the performance of the method. As the analytical solution is not known, a fine simulation of the stabilized Lagrange multiplier method with mesh size $h = 1/384$ is used as a reference solution. The influence of the penalty value ξ on accuracy, convergence and conditioning is analyzed in the conforming as well as the nonconforming case.

Fig. 3 presents the numerical convergence analysis of the primary variables for $\xi = 0.5$ in both the cases of conforming and nonconforming meshes. As predicted by the theory and independently of the mesh configuration, the errors for p and p_γ converge linearly in the H^1 norm and the Lagrange multiplier converges linearly in the norm $\|\cdot\|_{-\frac{1}{2},\gamma,h}$. Depending on the mesh configuration the L^2 errors of the pressures converge with rates up to quadratic order: in the nonconforming case the matrix pressure converges linearly in the L^2 norm.

Figs. 4 and 5 display the approximation errors for matrix pressure, fracture pressure and the Lagrange multiplier for different penalty parameters ξ and different mesh sizes in the conforming and nonconforming cases. The plots indicate that the errors get smaller when the mesh is refined. The penalty parameter ξ has little influence on the H^1 errors for p and p_γ and seems to give slightly improved results for λ when $\xi \in [0.1, 1]$, see Fig. 4. The influence of ξ is more important for p and p_γ in the L^2 error, see Fig. 5. In the most interesting case (nonconforming), small to moderate values for ξ seem optimal for the accuracy. In each plot, looking at the different curves for fixed ξ , one can determine the convergence rate, that is shown in Fig. 3 for $\xi = 0.5$. Globally, the smaller the mesh size h , the lesser the influence of the penalty parameter ξ . This confirms the consistency of the penalty term \mathcal{J} . Furthermore an increase of the penalty parameter ξ generally leads to higher errors, which is a logical consequence of the construction of \mathcal{J} . We also observe in Fig. 5 that the nonconforming configuration of the mesh yields larger L^2 errors, errors that have a weaker dependence on ξ .

In addition to the nonconforming case in which the fracture cuts through the middle of a vertical strip of matrix mesh elements, we wish to study what

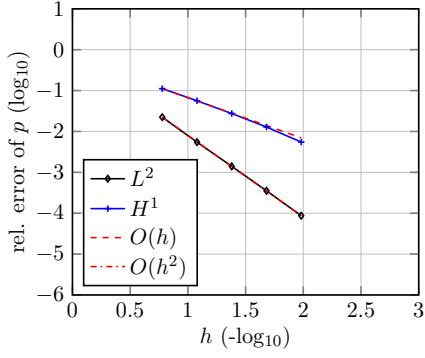
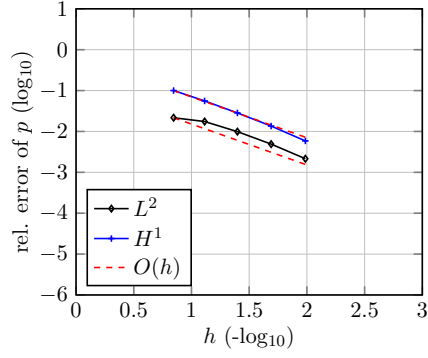
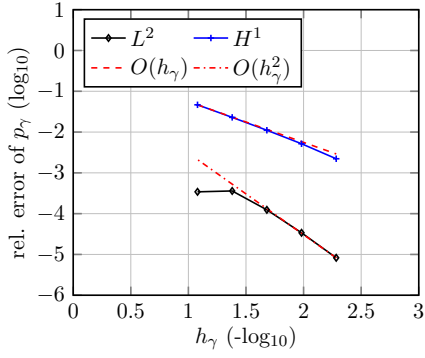
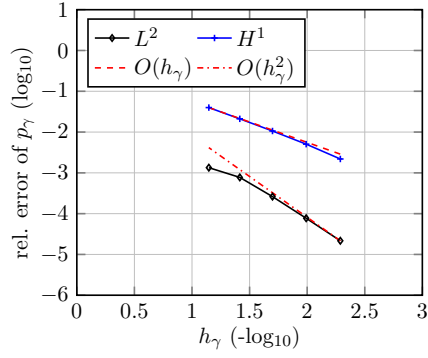
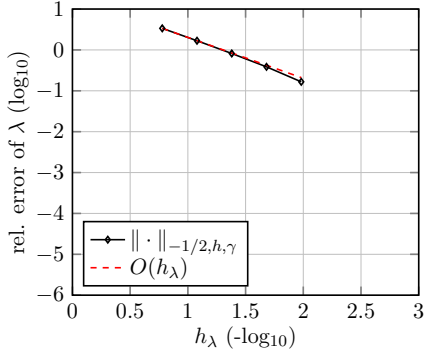
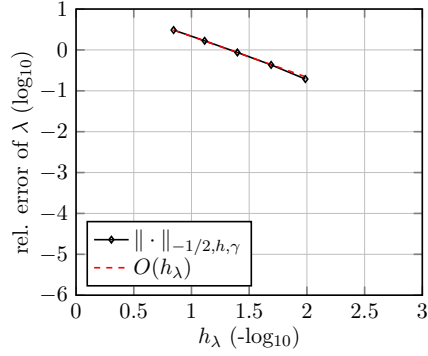
(a) Error for p (conforming)(b) Error for p (nonconforming)(c) Error for p_γ (conforming)(d) Error for p_γ (nonconforming)(e) Error for λ (conforming)(f) Error for λ (nonconforming)

Fig. 3 Case 1 (a vertical fracture): Convergence of matrix pressure p , fracture pressure p_γ and Lagrange multiplier λ for $\xi = 0.5$ in the conforming case (left) and the nonconforming case (right) depending on the mesh size.

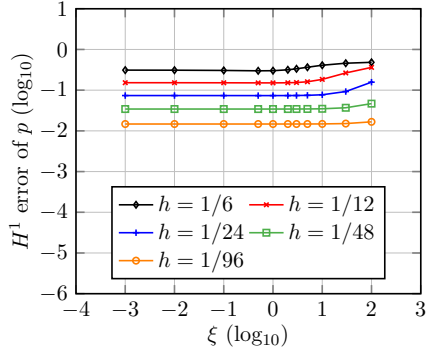
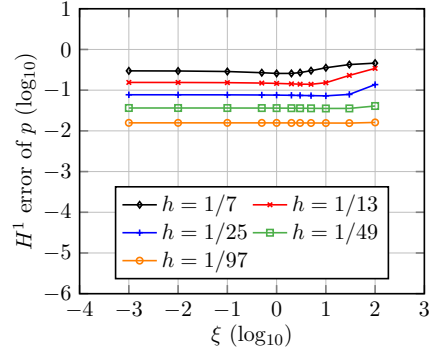
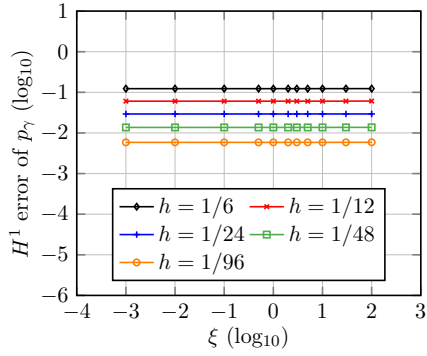
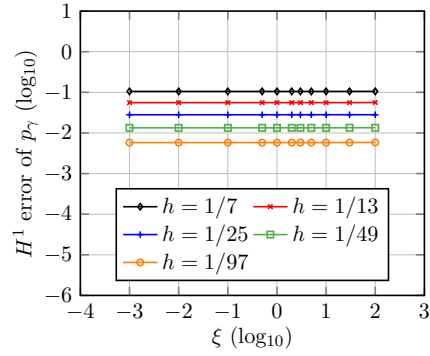
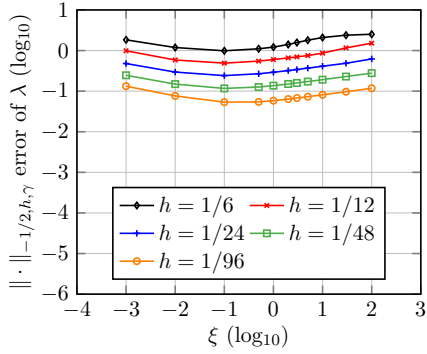
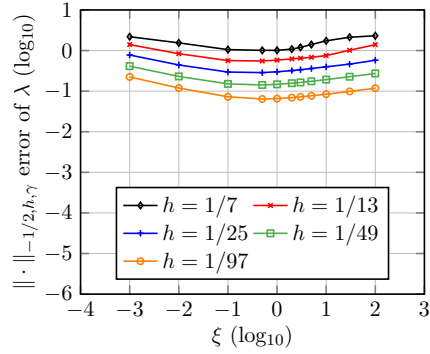
(a) H^1 Error for p (conforming)(b) H^1 Error for p (nonconforming)(c) H^1 Error for p_γ (conforming)(d) H^1 Error for p_γ (nonconforming)(e) Error for λ (conforming)(f) Error for λ (nonconforming)

Fig. 4 Case 1 (a vertical fracture): Influence of the penalty value ξ on the H^1 error for the matrix pressure p , the fracture pressure p_γ and on the $\|\cdot\|_{-\frac{1}{2}, h, \gamma}$ error for the Lagrange multiplier λ in the conforming case (left) and in the nonconforming case (right) depending on the mesh refinement index h .

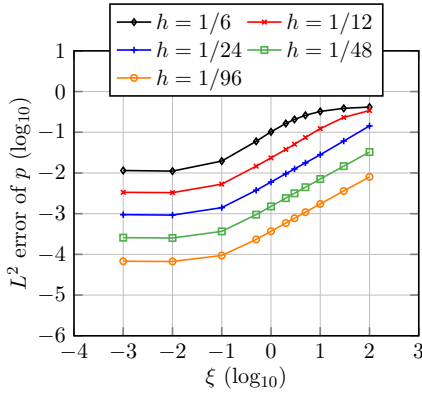
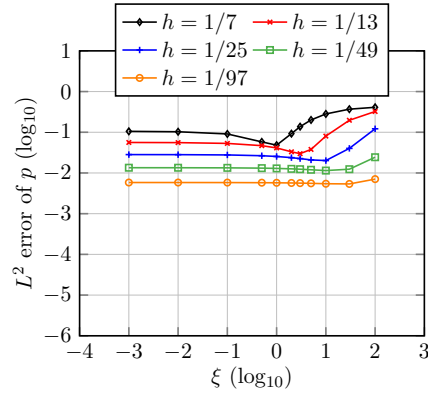
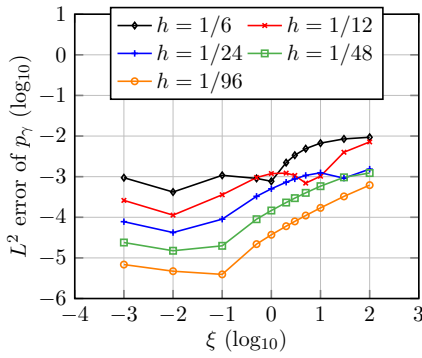
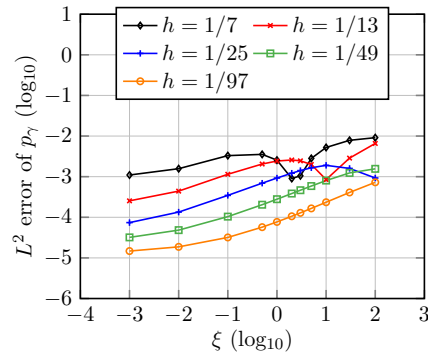
(a) L^2 Error for p (conforming)(b) L^2 Error for p (nonconforming)(c) L^2 Error for p_γ (conforming)(d) L^2 Error for p_γ (nonconforming)

Fig. 5 Case 1 (a vertical fracture): Influence of the penalty value ξ on the L^2 approximation error for the matrix pressure p and the fracture pressure p_γ in the conforming case (left) and in the nonconforming case (right) depending on the mesh refinement index h .

Distance	$\xi = 0$	$\xi = 0.001$	$\xi = 0.01$	$\xi = 0.1$	$\xi = 1$	$\xi = 10$
$h/2$	4.06e+8	9.93e+7	1.19e+7	2.35e+6	9.19e+5	5.18e+5
$h/4$	3.31e+8	9.50e+7	1.18e+7	2.25e+6	8.88e+5	5.08e+5
$h/8$	2.69e+8	8.97e+7	1.18e+7	2.14e+6	8.53e+5	4.96e+5
0	2.14e+8	8.31e+7	1.18e+7	2.01e+6	8.08e+5	4.81e+5

Table 1 Case 1 (a vertical fracture): Condition numbers as a function of ξ and the distance between the matrix mesh edges and the fracture line for $h = 1/18$, $h_\gamma = 1/36$.

happens as the matrix mesh edges approach the fracture line. Table 1 shows the condition numbers of the system matrix depending on the penalty parameter ξ and the distance between the matrix mesh edge and the fracture line for $h = 1/18$, $h_\gamma = 1/36$. The table indicates that the location of the fracture within the matrix grid does not influence significantly the conditioning of the

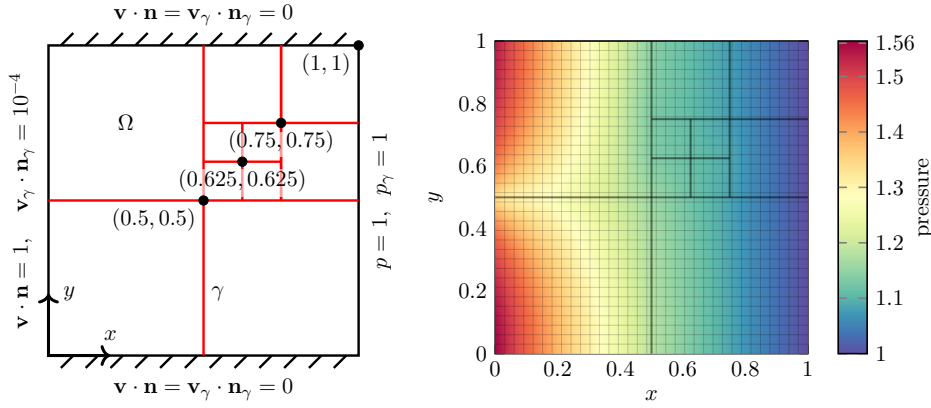


Fig. 6 Case 2 (a fracture network): General setup (left) and pressure distribution (right) of a nonconforming simulation with $h = 1/33$, $h_\gamma = 1/32$, $\xi = 1$.

system. However the condition number decreases with increasing values of the penalty parameter. This verifies the efficiency of the stabilizing term \mathcal{J} .

We conclude that the method (8) behaves as predicted by the theoretical results. The penalty parameter ξ should be chosen depending on accuracy and conditioning of the system matrix. The stabilizing term \mathcal{J} penalizes the jumps of the Lagrange multiplier. The higher the penalty parameter ξ the more the discrete multipliers tend to a constant value which affects the accuracy. However the results show clear convergence also for larger ξ . On the other hand high penalty parameters improve the conditioning.

Remark 2 We have not included comparisons with the non-penalized Lagrange multiplier method of Köppel et al (2018) for lack of space. For this comparison see Köppel (to appear, 2018).

4.2 Case 2: a fracture network

In this section a more complex test case with a regular fracture network, *cf.* (Geiger et al, 2013; Flemisch et al, 2018), is considered. The setup and the pressure distribution for a simulation with the stabilized method with nonconforming configuration and $h = 1/33$, $h_\gamma = 1/32$, $\xi = 1$, is illustrated in Fig. 6. All fractures of the test case are conductive and have a uniform permeability of $\mathbf{K}_\gamma = \mathbf{I}$. The unit square matrix domain is characterized by a permeability of $\mathbf{K} = \mathbf{I}$. Throughout this section the mesh size of the fracture will be in the same range as the mesh size of the matrix, *i.e.* $h_\gamma \approx h$.

In Table 2 we compare the method (8) with several other available methods given in the benchmark study Flemisch et al (2018) for single-phase flow in fractured porous media. The reference solution is computed with a mimetic finite difference method (Brezzi et al, 2005) with a two-dimensional grid in the fracture as well as in the matrix domain. The table shows that the stabilized Lagrange multiplier method performs well. Intermediate values of the penalty

method	d.o.f.	#-matr	#-frac	err _m	err _γ	cond
SLM-FEM: $\xi = 0$	1374	1089 quads	112	1.0e-2	6.5e-3	6.9e+8
SLM-FEM: $\xi = 0.1$	1374	1089 quads	112	1.0e-2	6.5e-3	2.0e+6
SLM-FEM: $\xi = 1$	1374	1089 quads	112	9.9e-3	6.4e-3	7.7e+5
SLM-FEM: $\xi = 1000$	1374	1089 quads	112	6.4e-2	2.9e-2	1.3e+5
Box	577	1078 trias	74	1.1e-2	1.9e-4	2.2e+3
CC-MPFA	1439	1348 trias	91	1.1e-2	4.5e-3	5.8e+4
EDFM	1501	1369 quads	132	6.5e-3	4.0e-3	5.6e+4
Mortar	3366	1280 trias	75	1.0e-2	6.9e-3	2.4e+6
P-XFEM	1650	961 quads	164	9.3e-3	7.3e-3	9.3e+9
D-XFEM	4474	1250 trias	126	9.6e-3	8.9e-3	1.2e+6

Table 2 Case 2 (a fracture network): Performance of the stabilized Lagrange multiplier method (SLM-FEM) compared to other DFM methods, cf. Flemisch et al (2018), based on the number of degrees of freedom (d.o.f.), the number of matrix elements (#-matr), the number of fracture elements (#-frac), the matrix error (err_m), the fracture error (err_γ) and the condition number (cond).

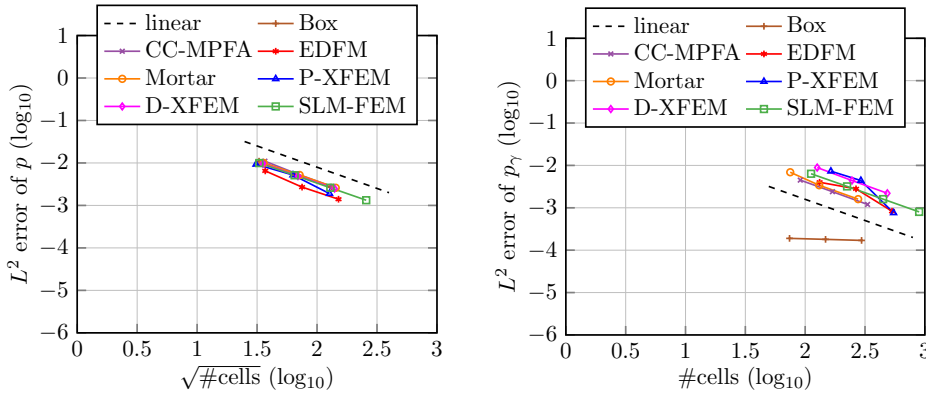


Fig. 7 Case 2 (a fracture network): Convergence of matrix pressure p (left) and fracture pressure p_γ (right) of the stabilized Lagr. multiplier method (SLM-FEM) for $\xi = 1$ depending on the number of elements ($\sqrt{\#cells}$) compared to other methods, cf. Flemisch et al (2018).

parameter, *i.e.* $\xi \in [0.1, 1]$, yield a good balance between accuracy and conditioning. Note however that this range may change for more realistic permeabilities, see Section 4.3.

To study the numerical convergence of the stabilized method the configuration is refined three times by a factor of two ($h \in \{1/33, 1/65, 1/129, 1/257\}$) similar to Flemisch et al (2018). The resulting convergence study of matrix and fracture pressure using the stabilized discretization with $\xi = 1$ is illustrated in Fig. 7. The figure shows that the stabilized method converges linearly in the matrix and in the fracture as the other methods of the benchmark study.

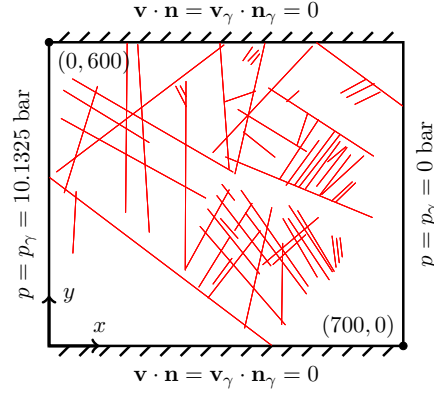


Fig. 8 Case 3 (a realistic case): Setup. The fractures are depicted as red lines.

4.3 Case 3: a realistic case

The last numerical experiment represents a real set of fractures from an interpreted outcrop in the Sotra island near Bergen in Norway of the benchmark study Flemisch et al (2018). The domain is rectangular with uniform permeability $\mathbf{K} = 10^{-14} m^2$. It contains 63 fractures grouped in several networks with $\mathbf{K}_\gamma = 10^{-10} m^3$, see Fig. 8. The size of the domain is $700 m \times 600 m$ with homogeneous Neumann boundary conditions on top and bottom, a pressure of $10.1325 bar$ on the left and a pressure of $0 bar$ on the right.

The pressure distributions for simulations with $h = 10 m$ and $\xi = 1$ and 100 are displayed in Fig. 9. A small undershoot can be observed close to the upper right fracture at the endpoint on the upper boundary. The undershoot is smaller for the larger choice of ξ . This occurs due to the weak imposition of equality of the pressure along the fracture, for more details see Köppel (to appear, 2018). Fig. 10 shows the distributions of the pressures at $y = 500 m$ and $x = 625 m$ of the stabilized Lagrange multiplier method compared to other methods of the benchmark study. The stabilized Lagrange multiplier method is in very good agreement with the pressure distributions of the other methods. A convergence analysis was not performed in this test case, as was noted in Flemisch et al (2018), since it is a really difficult task to establish a full-dimensional reference solution with the mimetic finite difference method. The comparison in terms of the conditioning and degrees of freedom is given in Table 3 and shows good performances with moderate to large values of ξ .

Remark 3 In order to improve the conditioning in this realistic test case where the permeabilities are very small, a scaling was performed prior to the computations: the duality pairings $\langle \cdot, \cdot \rangle_\gamma$ of \mathcal{A} defined in (2) and the stabilization term \mathcal{J} defined in (6) were multiplied by the scalar $k = \mathbf{K}$. Thus the actual Lagrange multiplier unknown was $\tilde{\lambda} = k\lambda$, and the stabilization term \mathcal{J} scales correctly with \mathbf{K} . It was then possible to divide the discrete system (8) by \mathbf{K}_γ , and obtain a system that is easier to solve. In the case when \mathbf{K} is a tensor or varying in space, the same idea should be considered with an average value of its norm.

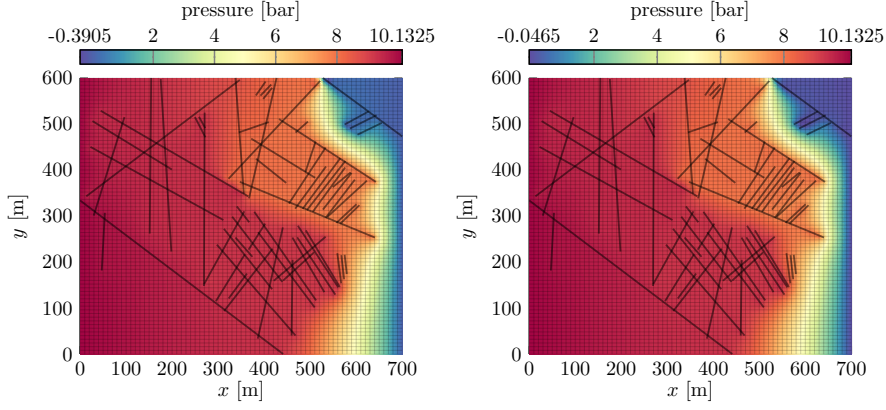


Fig. 9 Case 3 (a realistic case): Pressure distribution. Simulation with $h = 10\text{ m}$ and for $\xi = 1$ (left) and $\xi = 100$ (right). The lowest value is slightly different for the two figures.

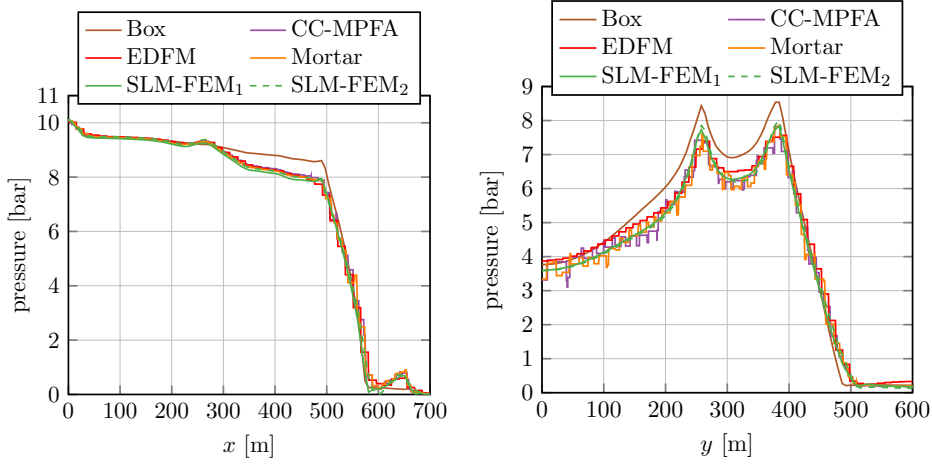


Fig. 10 Case 3 (a realistic case): Pressure distribution along the line $y = 500\text{ m}$ (left) and along the line $x = 625\text{ m}$ (right) of the stabilized Lagrange multiplier method (with $h = 10\text{ m}$) in comparison with other methods, *cf.* Flemisch et al (2018). SLM-FEM₁: $\xi = 1$. SLM-FEM₂: $\xi = 100$.

5 Conclusion

In this paper we presented a stabilized finite element discretization of a Lagrange multiplier model for single-phase Darcy flow in fractured porous media, *cf.* Köppel et al (2018), where the multiplier represents a local exchange of the fluid between fracture and matrix domain allowing for the use of a mesh in the

method	d.o.f.	#-matr	#-frac	cond
SLM-FEM: $\xi = 0$	8081	5250 quads	1372	4.8e+9
SLM-FEM: $\xi = 1e-4$	8081	5250 quads	1372	3.5e+8
SLM-FEM: $\xi = 1$	8081	5250 quads	1372	6.1e+6
SLM-FEM: $\xi = 100$	8081	5250 quads	1372	6.2e+6
Box	5563	10807 trias	1386	9.3e+5
CC-MPFA	8588	7614 trias	867	4.9e+6
EDFM	3599	2491 quads	1108	4.7e+6
Mortar	25258	8319 trias	1317	2.2e+17

Table 3 Benchmark 3 (a realistic case): Performance of the stabilized Lagrange multiplier method (SLM-FEM) compared to other DFM methods based on the number of degrees of freedom (d.o.f.), the number of matrix elements (#-matr), the number of fracture elements (#-frac) and the condition number (cond), *cf.* Flemisch et al (2018).

matrix that is not aligned with the fracture. The piecewise constant Lagrange multipliers of the stabilized discretization are defined on the intersections of the matrix elements with the fracture and, hence, are embedded on the fracture interface. A consistent stability term penalizes the jumps of the consecutive multipliers to stabilize the discrete saddle point system. We proved consistency, stability and convergence of the discrete formulation following the ideas of Burman and Hansbo (2010). The numerical experiments are consistent with the theoretical results. They confirmed that with increasing values of the penalty parameter ξ the conditioning of the discrete system can be improved. On the other hand high penalty values deteriorate the accuracy of the approximation. Hence we recommend the use of intermediate penalty values to obtain optimal results. The particular choice of ξ depends on the considered test case though. Despite the affected accuracy though the results show clear convergence also for large penalty parameters. In the numerical examples the errors of the matrix and fracture pressure converge linearly in the H^1 norm confirming the theoretical results. The Lagrange multiplier is characterized by linear rates of convergence in the discrete norm $\|\cdot\|_{-\frac{1}{2},h_\lambda,\gamma}$. The comparison with the benchmark results in Flemisch et al (2018), leads to the conclusion that the penalized discretization is a good alternative to other models for the simulation of flow in fractured porous media.

Acknowledgements The authors would like to thank the German Research Foundation (DFG) for financial support of the project within the Cluster of Excellence in Simulation Technology (EXC 310/2) at the University of Stuttgart.

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