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Estimation of spinal joint centers from external back profile and anatomical landmarks

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Abstract

Defining a subject-specific model of the human body is required for motion analysis in many fields, 1 2 such as in ergonomics and clinical applications. However, locating internal joint centers from external 3 characteristics of the body still remains a challenging issue, in particular for the spine. Current methods 4 mostly require a set of rarely accessible (3D back or trunk surface) or operator dependent inputs (large 5 number of palpated landmarks and landmarks-based anthropometrics). Therefore, there is a need to 6 provide an alternative way to estimate joint centers only using a limited number of easily palpable 7 landmarks and the external back profile. Two methods were proposed to predict the spinal joint 8 centers: one only using 6 anatomical landmarks (ALs) (2 PSIS, T8, C7, IJ and PX) and one using both 6 9 ALs and the external back profile. Regressions were established using the X-ray based 3D 10 reconstructions of 80 subjects and evaluated on 13 additional subjects of variable anthropometry. The predicted location of joint centers showed an average error 9.7 mm (±5.0) in the sagittal plane for all 11 12 joints when using the external back profile. Similar results were obtained without using external back 13 profile, 9.5 mm (±5.0). Compared to other existing methods, the proposed methods offered a more 14 accurate prediction with smaller number of palpated points. Methods have to be developed for 15 considering other postures than standing such as seated one.

16

17 Introduction

18 Accurate estimation of intervertebral joint centers is of primary importance to precisely define the 19 kinematic chain of subject-specific models for posture and motion analysis. However, few solutions have been proposed to predict joint centers using easily measurable external characteristics as inputs. 20 21 The geometric model in Snyder et al. 1972 has been widely used (Kennedy 1982, Choi et al. 2007, Reed 22 et al.1999). It provides twelve regression equations for the norm and direction of the vectors joining 23 skin markers, located on six palpated spinous processes, to six spinal joint centers. However 24 regressions were developed from only 19 male subjects' radiographic data of bones and surface 25 markers and, to our knowledge, no validation has been published yet. Other studies proposed 26 prediction equations using additional measurements such as anthropometric dimensions (body height 27 and weight), L4 skinfold and difference of L1-S1 skin distraction during maximal forward bending (Lee 28 et al. 1995, Chiou et al. 1996) in addition to palpated landmarks. However skinfold measurements 29 might show high inter-operator variability (Klipstein-Grobusch et al. 1997, Wang et al. 2000) and 30 accuracy might depend on skin thickness and skinfold compressibility (Himes et al., 1979). Palpationbased methods are also subject to inter-operator variation (Harlick et al. 2007) and could be time 31 32 consuming if there are a high number of points to be palpated. Therefore ideally, the prediction

method should require only a small number of easily palpated bony landmarks. Bryant *et al.* 1988 proposed an original geometric method aiming at predicting the distance between the internal spine curvature and the external back profile while using only two palpated landmarks (T1 and L5) as inputs. The curvilinear abscises of joint centers were estimated along the internal spinal profile. But the proposed method could not fully locate the spine in the sagittal plane. Moreover, only a small sample of 13 subjects from 13 to 17 years was used.

Recently a PCA-based method was proposed to predict internal pelvic landmarks and spine joint centers location using trunk 3D surface (Nérot *et al.* 2016). The study was based on a database of 3D reconstructions of bones and envelopes from low dose biplanar radiographs (Dubousset *et al.* 2010). The main advantage is that the proposed method requires almost no palpation. However, the full trunk skin surface is needed. A scanning device is not always a standard lab equipment. Furthermore, the whole trunk surface may not easily be scanned due to the obstruction by environmental objects for some applications, for example a seated person in a seat.

Using the existing database of 3D reconstructions of both internal skeleton and external body shape used in Nérot et al (2016), the objective of this study was to propose alternative methods for the prediction of intervertebral joint centers without using the full trunk surface scan but only a small amount of easily accessible input data.

50 Material and Methods

51 Data

52 With the approbation of the Ethics committee (CPP 06036) and signature of informed consents, 53 biplane radiographs of 93 subjects were collected with a low dose EOS system (EOS Imaging, France) 54 (46 females/47 males, age: [18, 76 years], height: [1.52, 1.97m], weight: [45, 103kg]). Participants were 55 asked to adopt a free standing position (Steffen et al. 2010). These subjects were divided into two 56 groups, a group of 80 persons for the development of the predictive methods (40 females/40 males, height: [1.52, 1.88m], weight: [48, 103kg]), and a second group of 13 subjects of variable 57 58 anthropometry for their validation (6 females/7 males, height: [1.53, 1.97 m], weight: [45, 102kg]). From these two views, 3D reconstruction of the lowers limbs, pelvis, spine and the external body 59 envelope were performed (Nérot et al. 2015). Subject-specific 3D reconstructions were based on the 60 deformation of parameterized and regionalized generic models on radiographic contours, allowing us 61 to isolate the thoracic region (Figure 1) and to automatically extract following internal and external 62 63 parameters.

- Internal parameters: Coordinates of 18 joint centers from C7/T1 to L5/S1, calculated as the
 middle points of the segments joining the barycenters of the two adjacent vertebrae end plates (Humbert et al. 2009). Internal spine profile was approximated by a cubic spline passing
 through the joint centers from C7/T1 to L5/S1.
- External parameters: anatomical landmarks (ALs) on the skin surface by virtual palpation
 including posterior (PSIS) superior iliac spines, incisura jugularis (XJ), xiphoid process (XP) and
 spinous processes. Bony landmarks were extracted from the parametrized subject-specific
 bones models and their closest points on the envelope reconstruction were considered as an
 estimation of the regular palpated landmarks. The external back curvature (or back profile)
 was also approximated by a cubic spline passing through the spinous processes from C7 to L5
 and limited at the PSIS midpoint.
- 75



- Figure 1. Definition of external back (black) and internal spinal (red) profiles which are both
 approximated by a cubic spine passing through external spinal processes and internal joint centers
 respectively. 6 palpable AL (two PSIS, T8, C7, IJ, PX) required for the methods proposed in the
 present study are also illustrated.
- 81
- 82

83 Proposed predictive methods

- 84 The predictive methods proposed in the present study were similar to that of Bryant *et al.* 1988 (Figure
- 2): first the internal spinal profile is predicted in a spine local coordinate system; secondly the two
- 86 extreme joint centers C7/T1 and L5/S1 need to be predicted; lastly the position of all other joint centers
- 87 can be located if their curvilinear coordinates are known.
- 88 The spine local coordinate system (LCS) (t₀, d, t) in the sagittal plane was defined with the origin t₀ at
- 89 C7 palpated spinous process, **t** the axis directing from C7 to the midpoint between the two palpated
- 90 PSIS (Figure 2.1). **d** was the perpendicular axis to **t** and directed forward. The internal and external
- spinal profiles were characterized by their local coordinated $[d_i^{int}, t_i]$ and $[d_i^{ext}, t_i]$ for t_i . The coordinates
- 92 along t were normalized by the distance between PSIS and C7 in order to compare individuals of
- 93 different corpulence.

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96 Using the existing database, the regression equations were obtained for all variables required for 97 predicting the internal spinal profile, two extreme joint centers C7/T1 and L5/S1 and curvilinear 98 coordinates of other joint centers. Two methods for predicting internal spinal profile were proposed, 99 one based on the distance d_i^{int} from the **t** axis, one on the distance D_i (= $d_i^{int} - I_i^{ext}$) from the external 100 back profile (Figure 2.1).

101 For the internal spine profile, best predictors were searched among anthropometric dimensions (e.g. 102 stature, weight, waist circumference etc.) and distances between ALs. Pearson tests were conducted 103 to find the most correlated variables with D_i or d_i^{int}. For instance, based on *a priori* assumption, thoracic 104 depth related measurements, such as body weight, C7-IJ distance, T8-PX distance, were considered as 105 candidate predictors. Thoracic length related parameters such as T8 to PSIS, C7 to T8 distances etc. 106 were also considered in the Pearson test (Drerup et al. 2014). A stepwise regression method was 107 performed on different combinations of 2 to 6 candidates to find the most powerful combination of 108 predictors. Using the same statistical method, the t coordinates of C7/T1 and L5/S1 along the 2D spinal 109 profile were supposed to be dependent on spine curvature descriptors (Figure 2.2). Finally, the mean 110 curvilinear coordinates of joint centers were calculated to estimate the relative position of joint 111 centers along the internal spine estimate (Figure 2.3).

112

113 Evaluation

Root mean square errors (RMSE) were calculated between estimated (regression) and reference (EOS based reconstructions) joint centers coordinates in the sagittal plane to assess the two proposed predictive methods. First, the data from 80 subjects, from which the regression equations were obtained, were used. Then an additional sample of 13 subjects was also considered for validation.

118

119 Results

120 Internal spine profile prediction

121 Up to eleven equal-distanced points along C7 to PSIS axis (t axis, Figure 2.1), with t=[0, 0.1,...,1], were

used to characterize both external and internal spine profiles. Tables 1 and 2 provide the predictors

123 for d_i^{int} and D_i. The distance D_i from the external back profile showed smaller RMS errors than the

124 distance d_i^{int} from the t axis.

- Table 1. Regression equations (and associated RMSE errors and coefficients of determination) of 127
- the distances from the external back to internal spinal profiles (D_i) for the 11 equal distanced 128
- points along the along the t axis. We recommend using points for i=[0,1,2,5,6,8,9,10] with smaller 129
- 130

RMSE.

Di	Regression equations	RMSE (mm)	R ² adj
D ₀	$0.19^*d_{C7-T8} + 0.28^*d_{C7-IJ} + 0.30^*d_{0.6}^{ext} - 10.18$	4.8	0.7
D _{0.1}	$0.48 d_{C7-IJ} + 0.86 d^{ext}_{0.1} - 6.00$	4.9	0.8
D _{0.2}	$0.40*d_{C7-IJ} + 0.23*BW+0.98*d^{ext}_{0.2} - 0.53*d^{ext}_{0.4} - 11.29$	5.7	0.6
D _{0.3}	$0.47*d_{C7-IJ} + 1.17*d^{ext}_{0.3} - 0.94*d^{ext}_{0.4} - 4.20$	6.6	0.4
D _{0.4}	0.52*BW+34.34	6.7	0.6
D _{0.5}	0.15*d _{T8-PX} + 0.34*BW + 20.45	6.4	0.6
D _{0.6}	0.17*d _{T8-PX} + 0.45*BW+14.70	6.5	0.6
D _{0.7}	0.15*d _{T8-PX} + 0.63*BW+12.00	7.0	0.7
D _{0.8}	0.12*d _{T8-PX} + 0.69*BW+19.40	6.1	0.7
D _{0.9}	0.74*BW + 44.40	6.9	0.6
D_1	0.68*BW + 44.19	9.3	0.4

Note: d_{C7-IJ} : C7 to IJ distance, d^{ext}_{i} : distance of the back profile from the C7^{ext} to PSIS^{ext} axis at t_i , d_{T8-PX} : T8 to PX distance, d_{C7-T8} : C7 to T8 distance, body weight in Kg.

131

132	Table 2. Regression equations (and associated RMSE errors and coefficients of determination) of
133	the distances from the C7 ^{ext} to PSIS ^{ext} axis to the internal spinal profiles for the 11 equal distanced
134	points along the along C7 ^{ext} to PSIS ^{ext} axis. $d^{int}_{0.3}$ is not indicated as no external predictor for $d^{int}_{0.3}$
135	was found by the Pearson test (mean value: 30.65 mm, RMSE, 11.6mm). We recommend using
136	points for i=[0,1,2,5,6,8,9,10] with smaller RMSE.

di ^{int}	Regression equations	RMSE (mm)	R^2_{adj}
d ₀	0.19*d _{C7-T8} +0.24*d _{C7-IJ} +0.13*d _{T8-PX} -25.89	5.3	0.7
$d_{0.1}$	0.45*d _{C7-IJ} -5.47	5.0	0.5
d _{0.2}	0.46*d _{C7-IJ} -0.22*d _{T8-PX} +0.28*BW +3.19	7.6	0.3
$d_{0.4}$	-0.32*d _{T8-PX} +0.53*BW +63.35	11.7	0.2
d _{0.5}	-2.50*d _{C7-T8} +-2.34*d _{T8-MidPSIS} +2.42*d _{C7-MidPSIS} +0.36*BW+24.96	6.7	0.7
d _{0.6}	-1.95*d _{C7-T8} -2.07*d _{T8-MidPSIS} + 2.01*d _{C7-MidPSIS} -0.09*d _{T8-PX} + +0.58*BW+ 54.81	6.4	0.7
d _{0.7}	-1.41*d _{C7-T8} -1.67*d _{T8-MidPSIS} + 1.52*d _{C7-MidPSIS} + 0.57*BW +65.35	7.3	0.6

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$d_{0.8}$	$-0.81^*d_{\text{C7-T8}} - 1.14^*d_{\text{T8-MidPSIS}} + 0.95^*d_{\text{C7-MidPSIS}} + 0.70^*\text{BW} + 76.41$	7.1	0.5
d _{0.9}	-0.21*d _{T8-MidPSIS} + 0.84*BW + 101.58	7.0	0.5
$d_{1.0}$	-0.16*d _{C7-MidPSIS} +1.00*BW +99.61	8.5	0.5

Note: d_{C7-IJ}: C7 to IJ distance, d_{T8-PSIS}: Distance bewteenT8 and PSIS midpoint, d_{C7-PSIS}: Distance between C7 and PSIS midpoint, d_{T8-PX}: T8 to PX distance, d_{C7-T8}: C7 to T8 distance,

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138 C7/T1 and L5/S1 prediction

- The regression equations to predict the vertical distance C7/T1 and L5/S1 from t₀ on S^{int} are listed in 139
- 140 Table 3.Estimation of L5/S1 showed a higher error than C7/T1. $d_{C7/T1}$ and $d_{L5/S1}$ were defined at the
- intersection of $t_{C7/T1}$, respectively $t_{L5/S1}$, and $S^{int.}$ 141

Table 3. Predictors and regression coefficients to predict the spine extremities C7/T1 and L5/S1 142

143

from spine shape descriptors and anthropometrics

	Regression equations	RMSE (mm)	r²
t _{C7/T1}	- (-1.02*R +0.07*Ch+0.99)*R	10.5	0.5
t _{L5/S1}	- (0.49*CL _h + 0.92)*R	18.3	0.4

Note: R, C_h and CL_h are described in Figure 3, height in mm, body weight (BW) in Kg. d_{C7-IJ} : C7 to IJ distance, d_{C7-T8} : C7 to T8 distance

144

145 Mean curvilinear coordinates of the joint centers

146 The relative positions (curvilinear abscises normalized by the curvature length) of the joint centers

along the internal spinal profile were observed quite invariant among the subjects (SD< 5 mm, Table 147

148 4).

149

Table 4. Mean position of intervertebral joint centers along S^{int}normalized by the developed length 150

151

of internal spline. Standard errors in percentage and in mm are indicated.

	Mean	SD (%)	SD (mm)
C7/T1	0	0	0

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T1/T2	4	0	1.57			
Т2/Т3	9	1	2.4			
T3/T4	13	1	3.11			
T4/T5	18	1	3.13			
T5/T6	23	1	3.54			
Т6/Т7	28	1	3.94			
Т7/Т8	33	1	4.23			
Т8/Т9	38	1	4.52			
T9/T10	43	1	4.83			
T10/T11	49	1	4.75			
T11/T12	55	1	4.76			
T12/L1	61	1	4.69			
L1/L2	69	1	4.68			
L2/L3	76	1	4.68			
L3/L4	84	1	4.46			
L4/L5	92	0	2.99			
L5/S1	100	0	1.82			

152

153

154 Evaluation

2D distance between estimated and reference joint centers using both methods showed very similar
errors, respectively 9.7 mm (±5.0) and 9.5 mm (±5.0) with or without using the external back profile
(Table 5).

158

159 Table 5. Root mean square errors (RMSE) in x (antero-posterior), y (medio-lateral) and 2D distance

160 between reference and estimated joint centers using methods with or without using the external

161

back profiles (mm) on the training group of 80 subjects. Standard deviations are provided.

	Using the external back profile			Without	using the	e externanl ba	ck profile	
		2D dis	tance RMSE		2D distance RMSE			
	х	У	mean	SD	х	У	mean	SD
C7/T1	6.8	5.5	8.7	4.5	4.0	5.5	6.8	3.5
T1/T2	4.7	5.6	7.3	3.3	4.7	5.1	6.9	3.2
T2/T3	5.1	5.7	7.7	3.3	5.5	4.8	7.4	3.6
T3/T4	5.4	5.8	7.9	3.4	6.8	4.7	8.2	4.1
T4/T5	5.8	5.7	8.2	3.6	7.7	4.5	8.9	4.5
T5/T6	6.3	6.1	8.8	3.8	8.9	4.7	10.0	4.7
T6/T7	6.7	6.4	9.3	4.1	9.8	4.9	11.0	5.1
T7/T8	6.8	6.6	9.5	4.4	9.8	5.1	11.1	5.2

Т8/Т9	6.8	6.8	9.6	4.7	8.9	5.2	10.3	5.1
T9/T10	6.8	7.0	9.8	5.0	7.5	5.5	9.3	4.7
T10/T11	6.8	7.1	9.8	5.2	6.6	5.8	8.8	4.5
T11/T12	6.9	7.2	10.0	5.4	6.2	6.1	8.8	4.5
T12/L1	7.0	7.6	10.3	5.8	6.3	6.7	9.2	4.7
L1/L2	7.2	8.2	10.9	6.1	6.9	7.4	10.2	5.4
L2/L3	6.9	9.0	11.3	6.1	7.4	8.2	11.0	6.0
L3/L4	6.0	9.3	11.1	5.4	7.4	8.2	11.0	6.0
L4/L5	6.7	9.8	11.9	5.6	6.7	9.1	11.3	5.6
L5/S1	8.0	9.9	12.7	5.9	7.2	9.5	11.9	5.3
Total			9.7	5.5			9.5	5.0

Note: Equations showing larger RMS errors $(d^{int}_{0.4}, d^{int}_{0.7})$ and respectively $D_{0.3}, D_{0.7}$ were not used for the least square estimation of internal spine.

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163	As the most precise regression equations were found with the method using the external back profile
164	(Table 1), this method was applied for predicting joint centers location over the validation cohort of 13
165	subjects. Mean error was 10.2±5.6 mm (Table 6).

167	Table 6. Mean error on 3D distance and standard error (SD) between estimated end reference joint
168	centers on the validation group of additional 13 subjects (mm) using the back profile. A third
169	orthogonal axis was added to the 2D local system and additional medio-lateral joint coordinates
170	were supposed to be aligned with the t axis so that joint i was located with respectively (d,0,t)
171	antero-posterior, medio-lateral and vertical coordinates.

	Mean	SD
C7/T1	7.0	3.9
T1/T2	9.5	5.4
T2/T3	11.5	5.9
T3/T4	10.7	6.6
T4/T5	9.6	6.2
T5/T6	9.5	5.7
T6/T7	10.0	5.8
T7/T8	10.6	5.8
Т8/Т9	10.3	5.5
T9/T10	9.5	5.1
T10/T11	8.8	5.9
T11/T12	9.7	5.7
T12/L1	10.4	5.3

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L1/L2	11.2	5.0	
L2/L3	11.5	5.3	
L3/L4	12.1	5.9	
L4/L5	10.9	6.4	
L5/S1	10.6	5.7	_
Total	10.2	5.6	_

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173

174 Discussion

Two methods requiring a small amount of easily accessible inputs to predict all thoracic and lumbar intervertebral joint centers location were compared. A focus was given on the sagittal plane where the main variation in spine shape occur for asymptomatic subjects. Only small differences were obtained between the methods either using only 6 ALS or using both 6 ALs and the external back profile.

179 Both methods were able to predict all the 18 thoracic and lumbar joint centers while most existing 180 geometrical models usually enabled to predict lumbar joint centers (Sicard et al. 1993, Lee et al. 1995, 181 Chiou et al. 1996) or a few joints, e.g. C2/C3, C7/T1, T4/T5, T8/T9, T12/L1, L2/L3 and L5/S1 (Snyder et al. 1972). The mean error of 10.2±5.6 mm was lower than the PCA-based method in Nérot et al. 2016 182 183 (12.8 ± 5.0 mm). This might be due to the pre-selection phase of candidate predictors at the areas with 184 thinner layers of soft tissues. Conversely the PCA method took into account the entire trunk surface 185 and associated shape variation, like in the belly region, which are probably independent to spine joints 186 location.

Extending Snyder et al.'s method for all joint centers was also considered. This alternative method requires the estimation of 2 unknowns for each joint: the distance to its orthogonal projection on the back profile and the curvilinear abscissa of this projection. But higher prediction errors may result from higher number of unknowns. Moreover normal vectors to the back surface were hardly reproducible depending on the quality of acquisition and the smoothing method. The advantages of the current methods are to estimate a smaller number of unknown variables and to robustly define a unique direction for calculating the spine coordinates in the sagittal plane.

194

L5/S1 estimated only using C7 and PSIS landmarks showed higher error compared to the PCA method in Nérot et al. (2016) using the whole trunk surface including the pelvic region. This might highlight the importance of considering some pelvic anatomical descriptors for L5/S1 prediction. For example, a simple method for predicting the L5/S1 from pelvic landmarks was proposed in Peng *et al.* 2015. When

199 considering our methods while imposing the true position of L5/S1, errors on joint location were

200 reduced by 1 to 5 mm on average, confirming the importance of L5/S1 accurate prediction to precisely

201 locate the rest of the spine joints.

The major limitation of this method is that it is based on a standing posture and may not be applicable to different posture involving different spinal curvatures (such as seating or supine). Furthermore, as virtual palpation was performed, the influence of palpation errors on these regression methods needs to be tested on a cohort of volunteers in future work.

206

207 Conclusion

This study proposed two geometric models allowing to predict spine joint centers form C7/T1 to L5/S1 with much less data than existing methods while improving the prediction precision. The methods are adapted to current methodology in motion analysis and compliant with minimal lab equipment. Prediction of L5/S1 using predictors from the pelvis could improve the results. Work is ongoing to change the standing position to a desired posture such as seated one in order to enlarge the possibility of applications.

214

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