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## To cite this version:

Pierre Gaillard. Rational solutions to the KPI equation of order 7 depending on 12 parameters. 2018. hal-01736228

HAL Id: hal-01736228

## https://hal.science/hal-01736228

Preprint submitted on 16 Mar 2018

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# Rational solutions to the KPI equation of order 7 depending on 12 parameters 

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January 27, 2018


#### Abstract

We construct in this paper, rational solutions as a quotient of two determinants of order $2 N=14$ and we obtain what we call solutions of order $N=7$ to the Kadomtsev-Petviashvili equation (KPI) as a quotient of 2 polynomials of degree 112 in $x, y$ and $t$ depending on 12 parameters. The maximum of modulus of these solutions at order 7 is equal to $2(2 N+$ $1)^{2}=450$. We make the study of the patterns of their modulus in the plane $(x, y)$ and their evolution according to time and parameters $a_{1}, a_{2}$, $a_{3}, a_{4}, a_{5}, a_{6}, b_{1}, b_{2}, b_{3}, b_{4}, b_{5}, b_{6}$. When all these parameters grow, triangle and ring structures are obtained.


Keywords: KPI equation; Fredholm determinants; Wronskians; rogue waves; lumps.

PACS numbers :
33Q55, 37K10, 47.10A-, 47.35.Fg, 47.54.Bd

## 1 Introduction

We consider the Kadomtsev-Petviashvili equation (KPI), first proposed in 1970 [1] in the following normalization

$$
\begin{equation*}
\left(4 u_{t}-6 u u_{x}+u_{x x x}\right)_{x}-3 u_{y y}=0 \tag{1}
\end{equation*}
$$

As usual, subscripts $x, y$ and $t$ denote partial derivatives.
The first rational solutions were constructed in 1977 by Manakov, Zakharov, Bordag and Matveev [2]. Other more general rational solutions of the KPI
equation were found by Krichever in 1978 [3, 4], Satsuma and Ablowitz in 1979 [5], Matveev in 1979 [6], in particuler among many works on this subject.
We construct rational solutions of order $N$ depending on $2 N-2$ parameters which can be written as a ratio of two polynomials in $x, y$ and $t$ of degree $2 N(N+1)$.
The maximum of the modulus of these solutions at order $N$ is equal to $2(2 N+$ $1)^{2}$. Here we construct the explicit rational solutions of order 7 , depending on 12 real parameters, and the representations of their modulus in the plane of the coordinates $(x, y)$ according to the real parameters $a_{1}, b_{1}, a_{2}, b_{2}, a_{3}, b_{3}, a_{4}, b_{4}$, $a_{5}, b_{5}, a_{6}, b_{6}$ and time $t$. When the parameters grow, we obtain $\frac{N(N+1)}{2}$ peaks in particular structures, such as triangles, rings, or concentric rings.

## 2 Rational solutions to KPI equation of order $N$ depending on $2 N-2$ parameters

The rational solutions to the KPI equation are given by the following result [38, 40]:

Theorem 2.1 The function $v$ defined by

$$
\begin{equation*}
v(x, y, t)=-2 \frac{\left|\operatorname{det}\left(\left(n_{j k}\right)_{j, k \in[1,2 N]}\right)\right|^{2}}{\operatorname{det}\left(\left(d_{j k}\right)_{j, k \in[1,2 N]}\right)^{2}} \tag{2}
\end{equation*}
$$

is a rational solution of the KPI equation (1), where

$$
\begin{align*}
& n_{j 1}=\varphi_{j, 1}(x, y, t, 0), 1 \leq j \leq 2 N \quad n_{j k}=\frac{\partial^{2 k-2} \varphi_{j, 1}}{\partial \epsilon^{2 k-2}}(x, y, t, 0) \\
& n_{j N+1}=\varphi_{j, N+1}(x, y, t, 0), 1 \leq j \leq 2 N \quad n_{j N+k}=\frac{\partial^{2 k-2} \varphi_{j, N+1}}{\partial \epsilon^{2 k-2}}(x, y, t, 0), \\
& d_{j 1}=\psi_{j, 1}(x, y, t, 0), 1 \leq j \leq 2 N \quad d_{j k}=\frac{\partial^{2 k-2} \psi_{j, 1}}{\partial \epsilon^{2 k-2}}(x, y, t, 0)  \tag{3}\\
& d_{j N+1}=\psi_{j, N+1}(x, y, t, 0), 1 \leq j \leq 2 N \quad d_{j N+k}=\frac{\partial^{2 k-2} \psi_{j, N+1}}{\partial \epsilon^{2 k-2}}(x, y, t, 0), \\
& 2 \leq k \leq N, 1 \leq j \leq 2 N
\end{align*}
$$

The functions $\varphi$ and $\psi$ are defined in (4),(5), (6), (7).

$$
\begin{align*}
& \varphi_{4 j+1, k}=\gamma_{k}^{4 j-1} \sin X_{k}, \quad \varphi_{4 j+2, k}=\gamma_{k}^{4 j} \cos X_{k} \\
& \varphi_{4 j+3, k}=-\gamma_{k}^{4 j+1} \sin X_{k}, \quad \varphi_{4 j+4, k}=-\gamma_{k}^{4 j+2} \cos X_{k} \tag{4}
\end{align*}
$$

for $1 \leq k \leq N$, and

$$
\begin{align*}
\varphi_{4 j+1, N+k} & =\gamma_{k}^{2 N-4 j-2} \cos X_{N+k}, \quad \varphi_{4 j+2, N+k}=-\gamma_{k}^{2 N-4 j-3} \sin X_{N+k} \\
\varphi_{4 j+3, N+k} & =-\gamma_{k}^{2 N-4 j-4} \cos X_{N+k}, \quad \varphi_{4 j+4, N+k}=\gamma_{k}^{2 N-4 j-5} \sin X_{N+k} \tag{5}
\end{align*}
$$

for $1 \leq k \leq N$.
The functions $\psi_{j, k}$ for $1 \leq j \leq 2 N, 1 \leq k \leq 2 N$ are defined in the same way, the term $X_{k}$ is only replaced by $Y_{k}$.

$$
X_{\nu}=\frac{\kappa_{\nu} x}{2}+i \delta_{\nu} y-i \frac{x_{3, \nu}}{2}-i \frac{\tau_{\nu}}{2} t-i \frac{e_{\nu}}{2}
$$

$$
Y_{\nu}=\frac{\kappa_{\nu} x}{2}+i \delta_{\nu} y-i \frac{x_{1, \nu}}{2}-i \frac{\tau_{\nu}}{2} t-i \frac{e_{\nu}}{2}
$$

for $1 \leq \nu \leq 2 N$, with $\kappa_{\nu}, \delta_{\nu}, x_{r, \nu}$ defined in (9) and parameters $e_{\nu}$ defined by (10).

$$
\begin{align*}
& \psi_{4 j+1, k}=\gamma_{k}^{4 j-1} \sin Y_{k}, \quad \psi_{4 j+2, k}=\gamma_{k}^{4 j} \cos Y_{k}, \\
& \psi_{4 j+3, k}=-\gamma_{k}^{4 j+1} \sin Y_{k}, \quad \psi_{4 j+4, k}=-\gamma_{k}^{4 j+2} \cos Y_{k} \tag{6}
\end{align*}
$$

for $1 \leq k \leq N$, and

$$
\begin{align*}
& \psi_{4 j+1, N+k}=\gamma_{k}^{2 N-4 j-2} \cos Y_{N+k}, \quad \psi_{4 j+2, N+k}=-\gamma_{k}^{2 N-4 j-3} \sin Y_{N+k},  \tag{7}\\
& \psi_{4 j+3, N+k}=-\gamma_{k}^{2 N-4 j-4} \cos Y_{N+k}, \quad \psi_{4 j+4, N+k}=\gamma_{k}^{2 N-4 j-5} \sin Y_{N+k}
\end{align*}
$$

Real numbers $\lambda_{j}$ are such that $-1<\lambda_{\nu}<1, \nu=1, \ldots, 2 N$ depending on a parameter $\epsilon$ which will be intended to tend towards 0 ; they can be written as

$$
\begin{equation*}
\lambda_{j}=1-2 \epsilon^{2} j^{2}, \quad \lambda_{N+j}=-\lambda_{j}, \quad 1 \leq j \leq N \tag{8}
\end{equation*}
$$

The terms $\kappa_{\nu}, \delta_{\nu}, \gamma_{\nu}, \tau_{\nu}$ and $x_{r, \nu}$ are functions of $\lambda_{\nu}, 1 \leq \nu \leq 2 N$; they are defined by the formulas:

$$
\begin{aligned}
& \kappa_{j}=2 \sqrt{1-\lambda_{j}^{2}}, \quad \delta_{j}=\kappa_{j} \lambda_{j}, \quad \gamma_{j}=\sqrt{\frac{1-\lambda_{j}}{1+\lambda_{j}}} \\
& x_{r, j}=(r-1) \ln \frac{\gamma_{j}-i}{\gamma_{j}+i}, \quad r=1,3, \quad \tau_{j}=-12 i \lambda_{j}^{2} \sqrt{1-\lambda_{j}^{2}}-4 i\left(1-\lambda_{j}^{2}\right) \sqrt{1-\lambda_{j}^{2}} \\
& \kappa_{N+j}=\kappa_{j}, \quad \delta_{N+j}=-\delta_{j}, \quad \gamma_{N+j}=\gamma_{j}^{-1} \\
& x_{r, N+j}=-x_{r, j}, \quad \tau_{N+j}=\tau_{j} \quad j=1, \ldots, N .
\end{aligned}
$$

$e_{\nu}, 1 \leq \nu \leq 2 N$ are defined in the following way:

$$
\begin{align*}
& e_{j}=2 i\left(\sum_{k=1}^{1 / 2 M-1} a_{k}(j e)^{2 k-1}-i \sum_{k=1}^{1 / 2 M-1} b_{K}(j e)^{2 k-1}\right), \\
& e_{N+j}=2 i\left(\sum_{k=1}^{1 / 2 M-1} a_{k}(j e)^{2 k-1}+i \sum_{k=1}^{1 / 2 M-1} b_{k}(j e)^{2 k-1}\right), \quad 1 \leq j \leq N,  \tag{10}\\
& a_{k}, b_{k} \in \mathbf{R}, \quad 1 \leq k \leq N-1
\end{align*}
$$

$\epsilon_{\nu}, 1 \leq \nu \leq 2 N$ are real numbers defined by :

$$
\begin{equation*}
\epsilon_{j}=1, \quad \epsilon_{N+j}=0 \quad 1 \leq j \leq N \tag{11}
\end{equation*}
$$

## 3 Explicit expression of rational solutions of order 7 depending on 12 parameters

In the the following, we explicitly construct rational solutions to the KPI equation of order 7 depending on 12 parameters.
We cannot give the complete analytic expressions of the solutions to the KPI equation of order 7 with twelve parameters because of their lengths.
The rational solutions to the KPI equation can be written as $v(x, y, t)=-2 \frac{\left|d_{3}(x, y, t)\right|^{2}}{d_{1}(x, y, t)^{2}}$,
with $d_{3}$ and $d_{1}$ polynomials of degree 112 in $x, y$ and $t$. The number of terms of the polynomials of the numerator $d_{3}$ and denominator $d_{1}$ of the solutions are shown in the table below (Table 1) when only one of the parameters $a_{i}$ and $b_{i}$ are set non equal to 0 .

| $a_{i}$ | $d_{3}$ | $d_{1}$ | $b_{i}$ | $d_{3}$ | $d_{1}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 86927 | 46383 | 1 | 86926 | 45036 |
| 2 | 55509 | 29584 | 2 | 55509 | 28790 |
| 3 | 42219 | 22489 | 3 | 42309 | 21962 |
| 4 | 34968 | 18608 | 4 | 34968 | 18167 |
| 5 | 30342 | 16132 | 5 | 30342 | 15778 |
| 6 | 26595 | 14099 | 6 | 26595 | 13846 |

Table 1: Number of terms for the polynomials $d_{3}$ and $d_{1}$ of the solutions to the KPI equation in the case $N=7$.

We give patterns of the modulus of the solutions in the plane $(x, y)$ of coordinates in functions of parameters $a_{1}, a_{2}, a_{3}, a_{4}, a_{5}, a_{6}, b_{1}, b_{2}, b_{3}, b_{4}, b_{5}, b_{6}$ and time t .
The maximum of modulus of theses solutions is checked equal in this case $N=7$ to $2(2 N+1)^{2}=2 \times 15^{2}=450$.
When all the parameters are equal to 0 , we obtain the lump $L_{7}$ with a highest amplitude of the modulus equal to 450 .


Figure 0. Solution of order 7 to KPI, for $t=0$ when all parameters equal to 0 .




Figure 1. Solution of order 7 to KPI, for $a_{1} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $a_{1}=1$; in the center for $t=0$ and $a_{1}=10^{3} ;$ on the right for $t=1$ and $a_{1}=10^{5}$.


Figure 2. Solution of order 7 to KPI, for $b_{1} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $b_{1}=1$; in the center for $t=0$ and $b_{1}=10^{3} ;$ on the right for $t=10$ and $b_{1}=10^{6}$.


Figure 3. Solution of order 7 to KPI, for $a_{2} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $a_{2}=10^{6}$; in the center for $t=0.1$ and $a_{2}=10^{6} ;$ on the right for $t=10$ and $a_{2}=10^{3}$.


Figure 4. Solution of order 7 to KPI, for $b_{2} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $b_{2}=10^{5}$; in the center for $t=0.1$ and $b_{2}=10^{3} ;$ on the right for $t=10$ and $b_{2}=10^{5}$.


Figure 5. Solution of order 7 to KPI, for $a_{3} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $a_{3}=10^{8}$; in the center for $t=0.1$ and $a_{3}=10^{5} ;$ on the right for $t=10$ and $a_{3}=10^{3}$.


Figure 6. Solution of order 7 to KPI, for $b_{3} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $b_{3}=10^{7}$; in the center for $t=0.1$ and $b_{3}=10^{4}$; on the right for $t=10$ and $b_{3}=10^{3}$.


Figure 7. Solution of order 7 to KPI, for $a_{4} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $a_{4}=10^{9}$; in the center for $t=0.1$ and $a_{4}=10^{9} ;$ on the right for $t=10$ and $a_{4}=10^{3}$.


Figure 8. Solution of order 7 to KPI, for $b_{4} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $b_{4}=10^{9}$; in the center for $t=0.1$ and $b_{4}=10^{5} ;$ on the right for $t=10$ and $b_{4}=10^{3}$.


Figure 9. Solution of order 7 to KPI, for $a_{5} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $a_{5}=10^{11}$; in the center for $t=0.1$ and $a_{5}=10^{5} ;$ on the right for $t=20$ and $a_{5}=10^{11}$.


Figure 10. Solution of order 7 to KPI, for $b_{5} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $b_{5}=10^{12}$; in the center for $t=0.1$ and $b_{5}=10^{5} ;$ on the right for $t=50$ and $b_{5}=10^{11}$.


Figure 11. Solution of order 7 to KPI, for $a_{6} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $a_{6}=10^{14}$; in the center for $t=0.1$ and $a_{6}=10^{5} ;$ on the right for $t=20$ and $a_{6}=10^{11}$.


Figure 12. Solution of order 7 to KPI, for $b_{6} \neq 0$ and all other parameters equal to 0 ; on the left for $t=0$ and $b_{6}=10^{6}$; in the center for $t=0.1$ and $b_{6}=10^{3} ;$ on the right for $t=20$ and $b_{6}=10^{11}$.

## 4 Conclusion

We construct 7 -th order rational solutions to the KPI equation depending on 12 real parameters. These solutions can be expressed in terms of a ratio of two polynomials of degree $2 N(N+1)=112$ in $x, y$ and $t$. The maximum of the modulus of these solutions is equal to $2(2 N+1)^{2}=450$; this solution which can be called lump $L_{7}$ is obtained when all parameters are equal to 0 at the instant $t=0$. Here we have given a complete description of rational solutions of order 7 with 12 parameters by constructing explicit expressions of polynomials of these solutions.
We deduce the construction of the modulus of solutions in the $(x, y)$ plane of coordinates; different structures appear. For a given $t$ close to 0 , when one parameter grows and the other ones are equal to 0 we obtain triangles, rings or concentric rings. There are six types of patterns. In the cases $a_{1} \neq 0$ or $b_{1} \neq 0$ we obtain triangles with a maximum of 28 peaks (figures 1 and 2 ); for $a_{2} \neq 0$ or $b_{2} \neq 0$, we have 3 concentric rings with two of them with 10 peaks and an another with 5 peaks (figures 3 and 4). For $a_{3} \neq 0$ or $b_{3} \neq 0$, we obtain 4 concentric rings without central peak with 7 peaks on each of them (figures 5 and 6). For $a_{4} \neq 0$ or $b_{4} \neq 0$, we have 3 concentric rings with 9 peaks, with a peak in the center(figures 7 and 8 ). For $a_{5} \neq 0$ or $b_{5} \neq 0$, we obtain 2 concentric rings without central peak with 11 peaks on each of them (figures 9 and 10). For $a_{6} \neq 0$ or $b_{6} \neq 0$, we have only one ring with 13 peaks (figures 11 and 12). But, when $t$ grows, all the structures disappear very quickly and the heights of the peaks decrease even more quickly.

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