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## Crowded Spot Estimator for Urban Cellular Networks

Sahar Hoteit · Stefano Secci · Marco Premoli

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**Abstract** The real-time detection of crowded spots in access networks is considered nowadays a necessary step in the evolution of mobile cellular networks as it can be of great benefit for many use-cases. On the one hand, a dynamic positioning of contents and computing resources in the most crowded regions can lower connection latency and data loss and can allow us to have a seamless service provided for the users, without performance degradation across the network. On the other hand, a dynamic resource allocation among access points taking into account their loads can enhance the user's quality of service and indeed network performances. In this context, using real mobile data traces from a cellular network operator in France, provided us with a temporal and spatial analysis of user content consumption habits in different French Metropolitan areas (Paris, Lyon and Nice). Furthermore, we put to use a real-time crowded spot estimator computed using two user mobility metrics, using a linear regression approach. Evaluating our estimator against more than one million user databases from a major French network operator, it appears to be an excellent crowd detection solution of cellular and backhauling network management. We show that its error count definitely decreases with the cell load, and it becomes very small for reasonable crowded spot load reaching

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S. Hoteit  
Ecole d'ingénieurs du numérique ISEP  
10 rue de Vanves, 92130 Issy les Moulineaux, France  
Tel.: +33 (0) 1 49 54 52 49  
E-mail: sahar.hoteit@isep.fr

S. Secci  
Sorbonne Universities, UPMC Univ. Paris 06, UMR 7606, LIP6  
F-75005, Paris, France  
Tel.: +33 (0) 1 44 27 36 78  
E-mail: stefano.secci@upmc.fr

M. Premoli  
Università di Milano, Milan, Italy  
E-mail: marco.premoli@unimi.it

upper thresholds. We also show that our crowded spot estimator is time and city-independent as it shows a stable behavior for different times of the day and for different cities with different topographies. Furthermore, compared to another crowded spot estimator from the literature, we show that our proposed estimator offers more suitable and accurate results in terms of crowded spot estimation for the three selected areas.

**Keywords** Mobile Data · Crowded Spot Estimation · Radius of Gyration

## 1 Introduction

As a matter of fact, we are witnessing the by-passing of a second decennial milestone in the evolution of telecommunications since the arrival of commercial Internet in 1992. After data traffic overcoming voice traffic in the beginning of the current century, we are noticing nowadays the increase of mobile data traffic at a very rapid pace. According to Cisco, mobile data traffic is expected to grow two times faster than global IP fixed traffic from 2016 to 2021 [2]. Besides, according to Mediametrie Institute [3], more than 31% of French mobile users use a smartphone, and about 71% of them connect to the Internet on a daily basis. The advent of smartphones, tablets and Internet keys, with generous processing and memory capacity, is shifting the network engineering attention from core networks and wireline local loops to the mobile cellular network. At present, techniques typically implemented in wireline network engineering are being considered for cellular access and backhauling networks. On the one hand, content delivery networks and caching protocols could go down close to backhauling gateways and base stations. On the other hand, Cloud servers could approach the user at mini data-centers connected to backhauling elements. The aim is to offload the transport network when it is congested and to improve the user's quality of experience reducing the access latency.

In order to better characterize these phenomena, in this paper we analyze user content consumption habits from the Orange cellular network in different city topographies: Paris, a large metropolitan area; Lyon a large business city with a lower population density than Paris, and Nice, the fifth most populated city in France, located on the Mediterranean coast, with a coastline topology rather than a circular one as in Paris and Lyon and a population density close to the Paris one. Moreover, we propose a real-time methodology to estimate crowded spots, based on compact and easy-to-compute user mobility metrics. Our estimator is based on linear regression of parameters computed over users' centroids and radius of gyration. We detail the performance of our estimator as a function of cell load and different regressions. We show that as a cell load estimator it has an error on median inferior to 8% for the three regions, the error is decreasing with the cell load and for crowded spot identification the load estimation and identification errors are very small. We also show that the estimator is robust and gives promising results for different time windows and as a function of the volume of data and the sample regression

window. Moreover, our estimator is time and city-independent as it shows stable behavior for different times of the day and for different cities with different topographies. Furthermore, we compare our proposed estimator to another one from the literature and we show that the former out-performs the latter in terms of crowded spot estimation accuracy.

The paper is organized as follows. Section 2 synthetically presents the dataset. Section 3 presents content consumption maps and analyzes them from a spatial distribution perspective. Section 4 presents the crowded spot estimation issue and the estimator that we propose. Section 5 presents the estimation results for Paris, Lyon and Nice Metropolitan areas for Orange network data as well as the results of comparison between our estimator and another one from the literature. Section 6 summarizes our work.

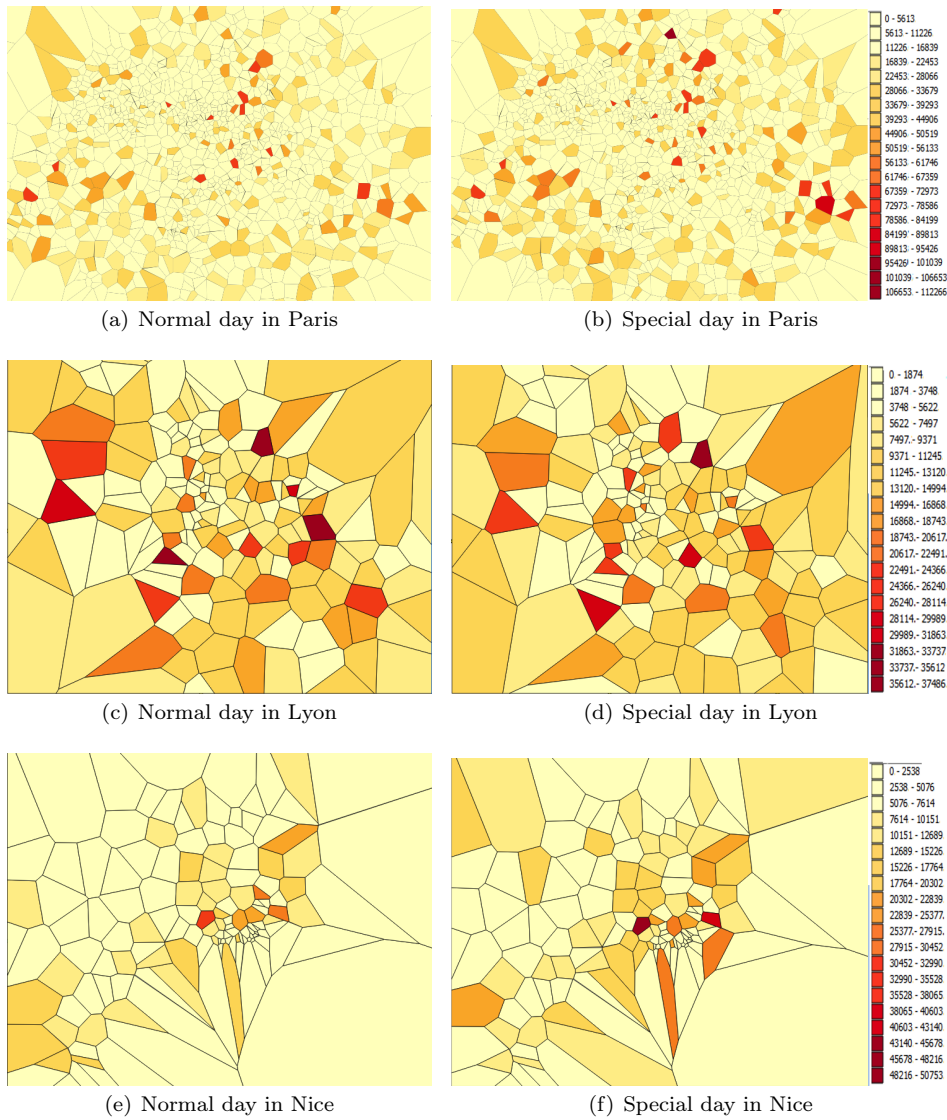
## 2 Dataset Description

The dataset used in our study consists of network probe's data, generated each time a mobile device uses wireless mobile network for Internet data exchange (not for voice calls and texts, i.e., what is commonly referred to as "mobile Internet" service). The network probe data exploited in the study provide information on the protocol used for communication. Data is individual, so all user identifiers were irreversibly anonymized before the analysis to protect user's privacy. The probe collects data with six minute interval sessions, assigning the session to the cell identifier of the last used antenna. Data is recorded on a per-user basis and covers about 1 million mobile phone users from Paris, Lyon and Nice regions (we study the mobility of around 650,000 users in Paris; 250,000 in Lyon and 100,000 in Nice). We decompose the considered regions into Voronoi cells based on tower positions, each cell being composed of a few antennas able to host up to roughly 1,200 users at the same time.

## 3 Content Consumption Temporal and Spatial Distributions

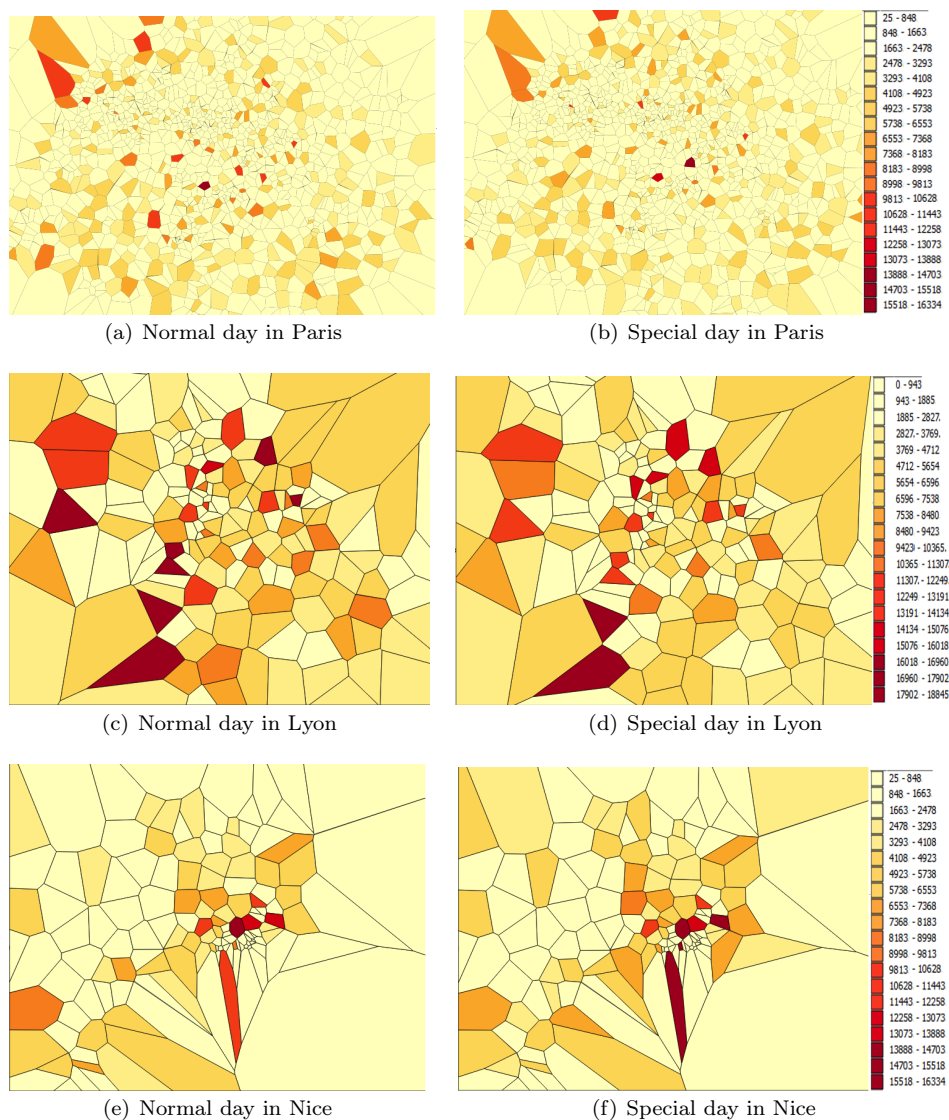
In this section, we synthetically characterize content consumptions, as a function of time and place in Paris, Lyon and Nice region respectively. We consider datasets of two different days:

- A "normal day" with standard content consumption activity (Tuesday, December 10<sup>th</sup>, 2013). We note that any other day with no special event occurring can also be chosen instead.
- A "special day" where a particular content consumption is expected (New Year's Eve on Tuesday, December 31<sup>st</sup>, 2013). We chose this day because, according to the mobile network operators [4] [5], the New Year's Eve is considered as the day with the highest cellular network load where a huge number of people use their mobile phones for sending their wishes to their friends and family.



**Fig. 1** Traffic volume distribution in different days and different cities.

Looking for differences in users' behavior in normal and special days is a key research question. Figure 1 shows the traffic volume (i.e., in bytes) for the different cells in each of the three regions during both normal and special days while Figure 2 shows user volume defined as the number of users attached to each cell in the considered regions during both days. The descriptions of the figures range from the less dense cells, represented by the clear yellow colour to the most dense cells, represented in the maps by the dark red colour.



**Fig. 2** User volume distribution for different days and different cities.

We can notice from these two figures that:

- The number of cells is not the same in all regions (i.e., Paris has the highest number of cells since it has the highest population density).
- In the same region and on the same day, a few number of cells are clearly more crowded (i.e., those represented by the dark red colour in the maps) than others presenting a large number of users and a large traffic volume;

the reason is that they clearly cover identifiable content consumption spots. They are likely, to be the public spaces where people gather together.

- The crowded spots (i.e., the dark red cells in the maps) are clearly not the same in the two considered days. While in the normal working day, the loaded cells seem to be the places where companies and businesses are located, the touristic places are the most loaded ones in terms of traffic and user volume during the New Year’s Eve.
- The crowded spots are not necessarily those with high spatial areas, these sizes are not the same in all the cases. We notice some small crowded spots in Paris region while others are bigger in the Lyon region for example.

There are therefore important differences in the geographical localization of content consumption spots. As noticed, their locations change as a function of time and the occurrence of a special event. Moreover, a detailed study in [6] shows that a large majority of the traffic volume is related to bulk transfer and web-related services whose content could be partially cached or whose Cloud server could be located close to the crowded spots to well manage the cloud and the content offloading. Users could indeed be better served if the delivery facility was located closely to the crowded spots. The backhauling network performance could also benefit from traffic offloading and traffic engineering techniques aware of user mobility and content consumption point deflections (e.g., adjusting link auto-bandwidth, path reservations and traffic offloading via D2D communications [7]).

## 4 Estimation of Crowded Spots

As explained in Section 2, the data used in our study is derived from network management tickets and generated in real-time as the user uses cellular network services. For that, it appears technically feasible to implement a crowded spot estimation technique indicating where the traffic load is going to increase closely.

### 4.1 Related Work

A limited amount of work exists in the literature on the estimation of crowded spots and rendez-vous points in access networks. E.g., in [8] vehicular data is exploited to determine accident-risk points. Authors in [9] propose a framework that discovers regions of different functions in a city using both human mobility among regions and points of interests located in a region. Many other works, such as [10], [11], [12] and [13], while assuming the availability of mobility information, focus on user-profile aware QoS provisioning, load balancing and network signaling improvement techniques. Traffic load forecasting has also been investigated from an analytical and mathematical modeling perspective. For example, authors in [14] show how under certain conditions periodic

Notation	Explanation
$i$	$i^{th}$ user
$\mathcal{I}$	Set of all users
$n^i(t)$	Number of locations recorded for user $i$ until time $t$ .
$\mathbf{r}_{cm}^i(t)$	Center of mass (centroid) of the locations recorded until time $t$ for user $i$
$\mathbf{r}_j^i(t)$	$j^{th}$ location recorded for user $i$
$r_g^i(t)$	Radius of gyration of the locations recorded until time $t$ for user $i$
$m[r_g^i(t), \mathbf{r}_{cm}^i, C_k, i, t]$	Spatial mapping counter
$C_k$	$k^{th}$ cell in the network
$RTW$	Regression Time Window
$\hat{e}(C_k, t)$	Estimation of the number of users visiting cell $C_k$ until time $t$ .
$n(C_k, t)$	Real number of users visiting cell $C_k$ until time $t$ .
$CST$	Crowd Selection Threshold

**Table 1** Summary of the general notation

sinusoidal functions can be used as cellular traffic profile. These approaches seem to fail to meet the traffic load estimation requirement of our work, as it is not possible to extrapolate an estimator from the proposed models. In the same context of modeling the spatial cell density of a mobile network, authors in [15] propose a stochastic model to compute the probability of staying in a given location for a given period of time as well as the probability of moving from a given location to another one, using a random waypoint-based mobility pattern. Also, relevant works targeting mobility pattern detection from real cellular network data have been studied e.g., [16] [17] [18]. In particular, authors in [17] categorize users with respect to their radius of gyration, allowing them to define a circle, centered at user's centroid, around which a user is expected to geographically move. Using the radius of gyration as a mobility metric, authors in [19] show that cell load can be estimated using a trajectory-based estimation technique that consists of determining the best interpolation method suitable for each user category (i.e., computed using the mobility metric). They show that, for sedentary and peri-urban users, the linear interpolation is the best one for joining user's samples between consecutive connections to the mobile phone network while the cubic interpolation fits the urban users and the commuters well. In this paper, instead of relying on user's trajectory for cell load estimation, we investigate other options not dependent on the trajectory but rather on the characterization of users' territory. We also compare both estimation techniques (i.e., trajectory and territory-bases estimation techniques) together to show the advantages of the one over the other. A summary of the notation used throughout this paper is shown in Table 1.



## 4.2 Territory-based Crowded Spot Estimator

Given a user  $i \in \mathcal{I}$  who has been located at  $n^i(t)$  locations until time  $t$ , its centroid  $\mathbf{r}_{cm}^i(t)$  can be computed as the center of mass location of all previous sampled positions.

$$\mathbf{r}_{cm}^i(t) = \frac{1}{n^i(t)} \sum_{j=1}^{n^i(t)} \mathbf{r}_j^i(t) \quad (1)$$

The radius of gyration can then be computed for each user as the deviation of the sampled positions with respect to the centroid position. It is given as follows:

$$r_g^i(t) = \sqrt{\frac{1}{n^i(t)} \sum_{j=1}^{n^i(t)} |\mathbf{r}_j^i(t) - \mathbf{r}_{cm}^i(t)|^2} \quad (2)$$

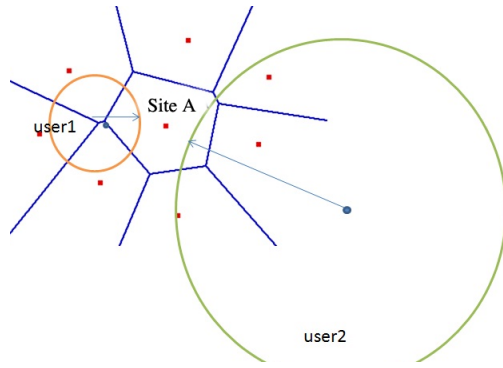
It is worth mentioning that these two metrics have been introduced in [17] to characterize the users' behavior, but they were not used to estimate the crowded spots as proposed in our paper.

Aiming at defining an adequate and implementable crowded spot estimator for cellular network management, we adopt as estimation parameters the centroid and the radius of gyration to account for the user's spatial coverage. The motivation behind such adoption is that previous research studies [20] have shown a strong repetitive tendency in human mobility (i.e., people repetitively visit the same areas) Because of this reason, these two parameters, basically, do not change much over time for each user and hence can be used for estimating the user's mobility patterns in the future.<sup>1</sup> These two parameters, the centroid and the radius of gyration, define a 'territory' of each user by the area covered by a circle centered at its centroid with a radius equal to the radius of gyration. Our proposed estimator takes into account the non-negligible intersections of different users' territories to estimate the cellular user density. For example, in Fig. 3, based on the centroid and the radius of gyration of the two users, it is reasonable to account for the possibility that the two users pass by site A. The efficiency of the estimator should be evaluated towards its capability of estimating crowded spots rather than lightly loaded cells.

For each user  $i$  given by its territory (i.e., circle with  $\mathbf{r}_{cm}^i(t)$  as a center and with  $r_g^i(t)$  as a radius) and each cell  $C_k$ , we define a spatial mapping counter  $m[r_g^i(t), \mathbf{r}_{cm}^i, C_k, i, t]$  given as follows:

$$m[r_g^i(t), \mathbf{r}_{cm}^i, C_k, i, t] = \begin{cases} 1, & \text{if the territory of } i \text{ covers at} \\ & \text{least 10\% of the area of } C_k \\ 0, & \text{in other cases} \end{cases}$$

<sup>1</sup> We note that in order to compute precisely the centroid and the radius of gyration of the users, we need sufficient location information of each one of them. This is not an issue nowadays as most of users are smartphones holders with persistent Internet connectivity (i.e., a lot of samplings can be obtained for each one of them).



**Fig. 3** Illustration of the user's territory

It is worth mentioning that other thresholds (other than 10%) could certainly be considered, depending also on the way the environment is designed architecturally. The aim of this threshold is to avoid the small overlaps since not all the cells covered by one user's radius will be visited in a reasonable manner.

Such a spatial mapping counter is the core metric of our estimator. Simply counting the number of intersections significantly covering a given cell would certainly lead to an over counting that needs to be appropriately scaled. A simple scaling could be, e.g., to divide it by the average number of users per cell during the past measurements, yet this does not prevent us from having high deviations. We propose to scale it by the scale factor that would generate a null estimation error count in an arbitrary instant  $t - RTW$  in the recent past, with a regression time window ( $RTW$ ) adequately set. Then, as an estimator of the number of users visiting cell  $C_k$ , we propose:

$$\hat{e}(C_k, t) = \frac{n(C_k, t - RTW) \sum_{i \in \mathcal{I}} m[r_g^i(t), \mathbf{r}_{cm}^i, C_k, i, t]}{\sum_{i \in \mathcal{I}} m[r_g^i(t - RTW), \mathbf{r}_{cm}^i, C_k, i, t - RTW]} \quad (3)$$

It uses therefore a linear regression over past measurements to weight the spatial mapping counter adequately. Intuitively, the smaller  $RTW$  is, the more accurate the estimation, i.e., the closer  $\hat{e}(C_k, t)$  is to the unknown  $n(C_k, t)$  that represents the real number of users per cell  $C_k$ . However,  $RTW$  should be big enough to allow the network management system to retrieve the real number of users in cell  $C_k$  at time  $t - RTW$ , i.e.,  $n(C_k, t - RTW)$ . Depending on network management tickets, session duration, network latency and network size, this parameter  $RTW$  could range from a few dozens of minutes to a few hours.

## 5 Estimator Evaluation

We evaluate our estimator using the available network management dataset of Orange's French cellular network for New Year's Eve, by computing the

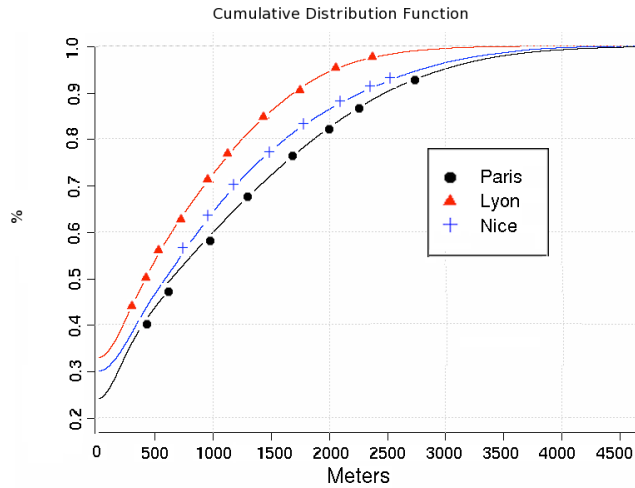


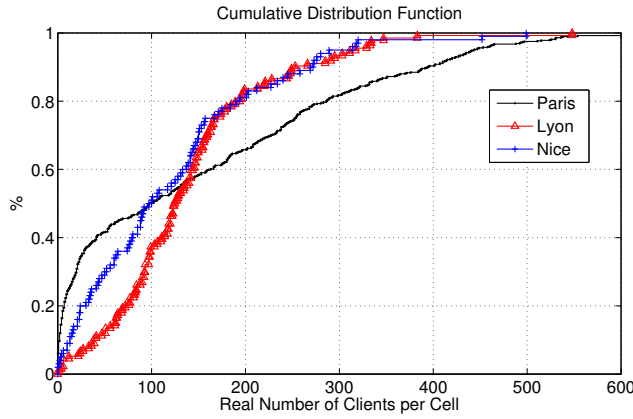
Fig. 4 CDF of the radius of gyration in different cities

centroid and the radius of gyration of all users passing by the three regions: Paris, Lyon and Nice. It is worth mentioning that we have further checked the accuracy of our estimator and verified the correctness of the results in the normal day but we show in the paper those of the special days only. We set a RTW to 1 hour, which is quite a pessimistic value (in practice, in carrier grade networks, it could even be set to a few minutes, hence allowing a higher accuracy; later we show the influence of varying the RTW on the estimator’s performance). We consider the user position samples from the whole day in the computation of users’ centroids and radius of gyration.

In order to qualify the dataset, Fig. 4 reports the CDFs of the users’ radius of gyration in the three cities, and Fig. 5 shows the CDF of the real number of users per cell in the considered day. We can appreciate that the radius of gyration adequately represents the user mobility habits and is city-dependent as it increases with the city’s geographical area (i.e., Parisian users show higher radius of gyration since the area of Paris city is larger than the other two regions; Paris:  $105.4 \text{ km}^2$ , Nice:  $71.92 \text{ km}^2$  and Lyon:  $47.95 \text{ km}^2$ ). Moreover, the cells are more loaded in Paris than Lyon and Nice (i.e., approximately 20% of the cells in Paris have more than 300 users while only about 8% in Nice and Lyon). This is interpreted by the high density of users in Paris with respect to the other two regions. It is worth noting that the distance between two neighboring cells is typically a few hundred meters.

### 5.1 Crowded Spot Estimation Accuracy

In this section, we evaluate the accuracy of the territory-based crowded spot estimator in terms of load estimation and identification errors.



**Fig. 5** CDF of the real number of customers per cell in different cities

### 5.1.1 Load Estimation Error

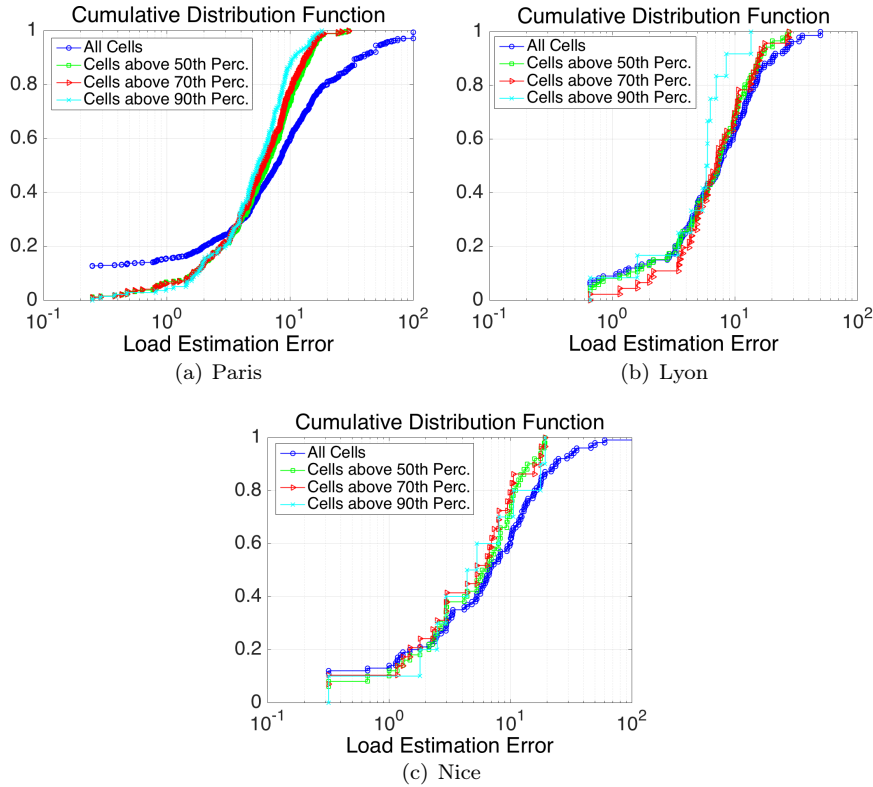
To qualify, quantitatively, the accuracy of the proposed crowded spot detection method, we analyze the load estimation error of each cell in the three selected regions. The estimation error of one cell is defined by the difference between the real and the estimated number of users of that cell. A statistical distribution plot of the obtained errors for the different cells may be useful here to better evaluate the performance of our proposed estimator. Figure 6 depicts the CDFs of the load estimation error of all cells in the three considered cities for different possible load thresholds beyond which the cell is considered as a crowded spot; from now on we refer to this threshold as Crowd Selection Threshold (CST).

The CDFs show that including all cells, and for all the considered regions, the median estimation error is lower than 8%. Including only cells having a CST of 70% (i.e., having a load higher than the load of 70% of the cells), the median estimation error is always inferior to 7%. With stricter definitions of CST (90% percentile), the median estimation error becomes inferior to 6%. It is worth stressing that the estimator's performances seem to be city-independent because it shows similar results in different regions.

Figure 7 represents the log-log scatter representations of the estimation error as a function of the real number of users per cell for each region. We can observe that, for all regions, the estimation error is high for low-loaded cells and it decreases more than linearly as the real cell load increases, which is as argued, very desirable behavior.

### 5.1.2 Identification Error

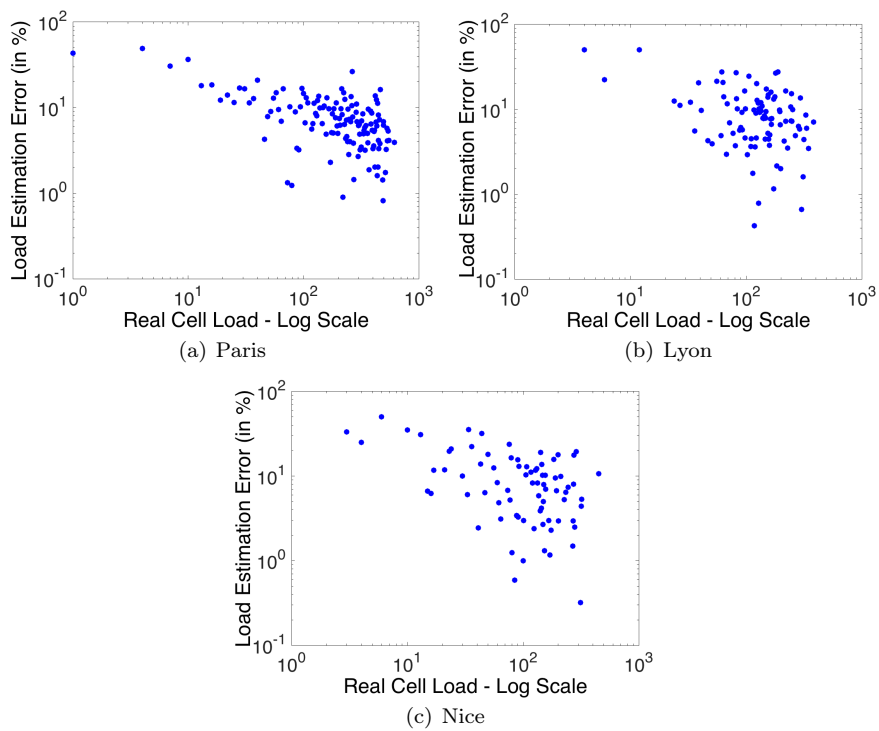
To further check the accuracy of the proposed method, we evaluate type I and II errors in crowded spot identifications, i.e., false positive (a cell is identified as a crowded spot when it is not) and false negative (a cell is not identified as a crowded spot when it is a crowded spot) errors, respectively. We choose



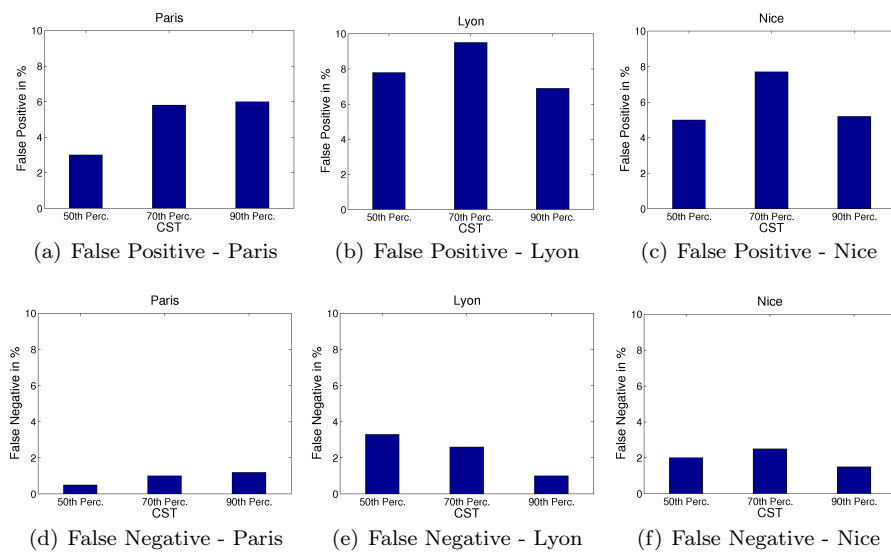
**Fig. 6** Distribution of load estimation error (in %) for the three regions

three different CST values: 50<sup>th</sup>, 70<sup>th</sup>, and 90<sup>th</sup> percentiles. We plot for each CST value the false positive and false negative ratios evaluated by directly counting from the complete dataset against those obtained through our proposed method. Fig. 8 shows the results: the identification error is clearly less than 9% for all different regions and the false negative is always lower than the false positive values meaning that our estimator is more precise in identifying the real crowded cells but has a little bit of a higher error in considering the non-crowded cells as crowded ones.

A stricter definition of crowded spots, i.e., a higher CST value, does not provide a common effect on errors Type I and Type II for all cities. This behavior could be derived from the different characteristics of data in each city: the total number of users, the density of the users, the number and location of the users' gathering spaces and the presence of clusters of neighboring cells with similar load. In the latter case, for us the most probable, according to the chosen CST value a cluster may be split resulting in an identification error. It is worth mentioning that the results of Fig. 8 do not contradict those obtained in Figure 6 as the latter shows the statistical distribution of the difference between the real and the estimated load for all the cells in the regions while



**Fig. 7** Scatter of the estimation error as a function of real cell load in the three regions



**Fig. 8** Type I and Type II errors as a function of different CST values in the three regions

the former counts only the number of times our estimator makes a wrong statement on the type of a cell, whether it is crowded or not.

In our opinion, these are extremely encouraging results. Our estimator permits us to reach an excellent level of accuracy. It can be used to feed a network management policy aiming at taking a decision when detecting a crowded spot (e.g., link auto-bandwidth bounds setting in mobile backhauling, adaptive content-delivery-network redirections, adaptive virtual machine migrations, etc.). For operational consideration, we however need to qualify its scalability.

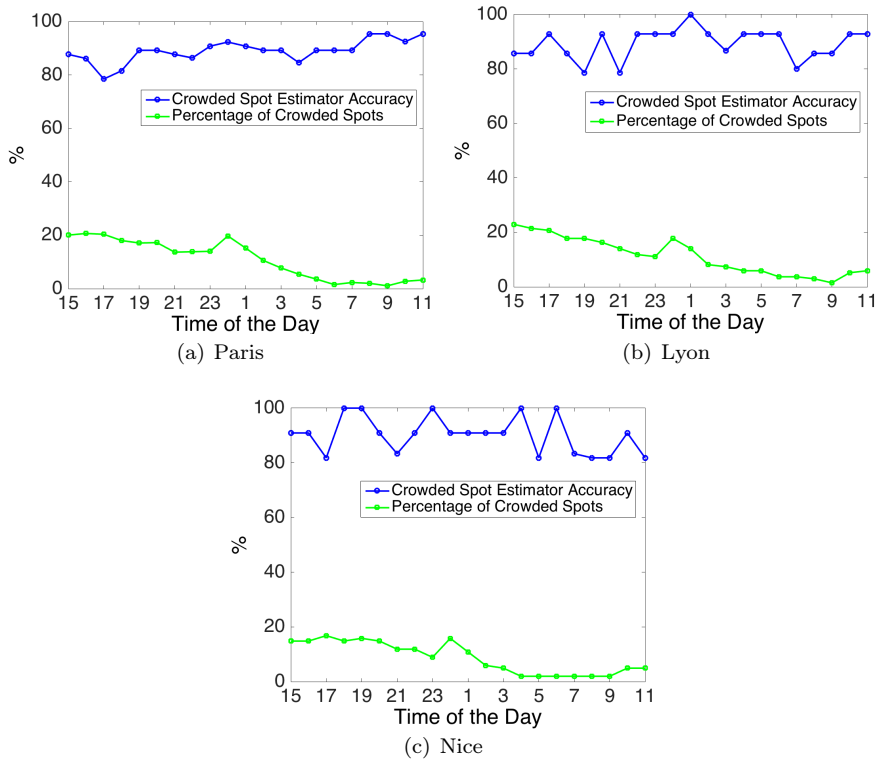
## 5.2 Implementation Complexity

Our estimator (3) is of a rather simple and intuitive nature. Certainly, a more complex estimator, e.g., weighted by a user-cell crossing probability computed using other mobility information, might be defined to reach lower errors and can be left for future work, yet the estimator computation complexity has to be as low as possible, and the utility of having a more precise estimator is a matter of discussion since the accuracy of (3) is already extremely high.

With our estimator, for each new user position, Equations (1) and (2) could be updated handling only a limited arbitrary number  $N$  of last positions, then Equation (3) can be updated. Hence, all these operations have a  $O(N * \mathcal{I}_m(t))$  time complexity,  $\mathcal{I}_m(t) \subset \mathcal{I}$  being the subset of users moving and sampled in the sampling interval  $(t - RTW, t)$ .

As already mentioned, the regression time window RTW should be chosen so that it is sufficiently higher than the computation time of the estimator. However, from a more practical perspective, in very high mobility environments, the above complexity could become quadratic, which may raise scalability concerns. Scalability concerns could also rise from the volume of the data to mine in order to extract estimator's metrics. The larger the sample temporal window is, the larger the data volume is and the higher the computation complexity is. Hence the last questions we want to answer are: does the crowded spot detection accuracy decrease with time? What happens at different times of the day? In order to answer these questions, we tested our estimator in the same period interval (between 3 pm of December 31, 2013 till 11 am of the January 1, 2014) in the three selected regions.

Figure 9 shows our evaluation results with a RTW of 1 hour and a step of 1 hour starting by 3 pm for the three considered regions. For example, when performing the crowded spot estimation at 9 pm, we exploit the data collected from 3 pm to 9 pm. These results highlight two important aspects: firstly, the accuracy of our estimator is time-independent and thus mobility-independent because it shows a constant behavior at different times of the day. Another important aspect is that the percentage of crowded spots decreases when the overall user mobility decreases, and vice versa. As a matter of fact, the maximum percentage is obtained at midnight (19% for Paris, 17% for Lyon and 15% for Nice) when people are likely to gather to celebrate New Year's



**Fig. 9** Crowded spot estimator accuracy and percentage of crowded spots as a function of time in different regions.

Eve, then this ratio decreases when people start to split up and return back to their home locations. Hence, we can conclude that the percentage of crowded spots is mobility-dependent.

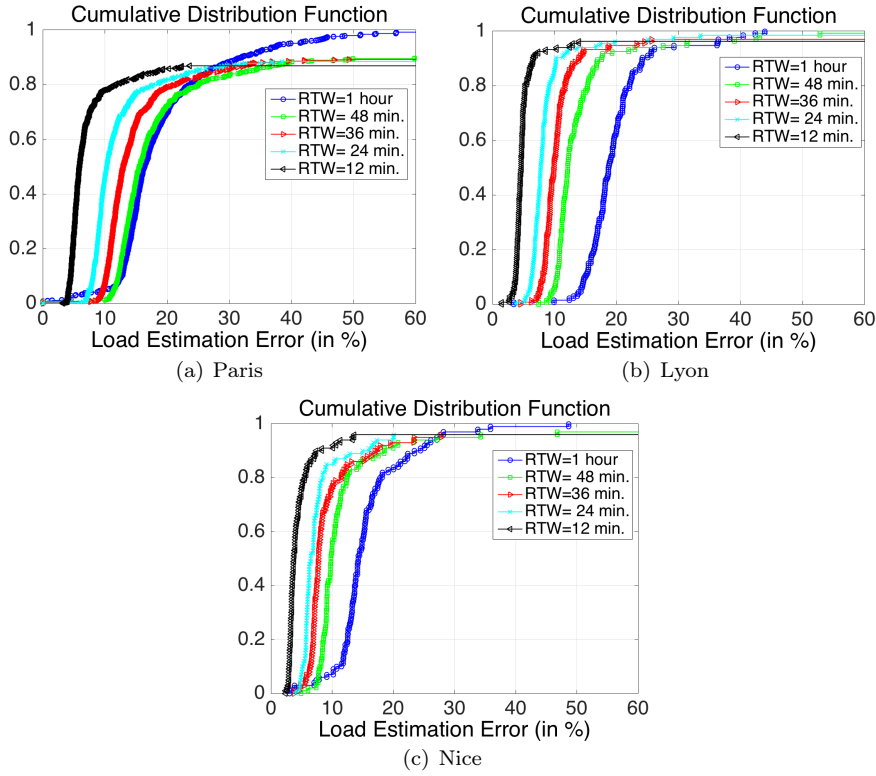
As a last analysis, we look at the influence of the regression time window on the accuracy of the estimator. For simplicity, and in order to minimize the computation time, we select 5% of the most active users in the regions and we compute the estimation error by varying the RTW as shown in Figure 10.

We clearly notice that the estimator's accuracy increases with smaller RTW (i.e., in Paris for example, the median error is 18% when RTW=1 hour, 12% for RTW=48 min and less than 5% with a RTW=12 min; we have similar results also for the other two regions).

### 5.3 Comparison between Trajectory-based Estimator and Territory-based Estimator

The trajectory-based estimator evaluated in [19] has shown quite small load estimation errors that are relatively close to those obtained through the es-

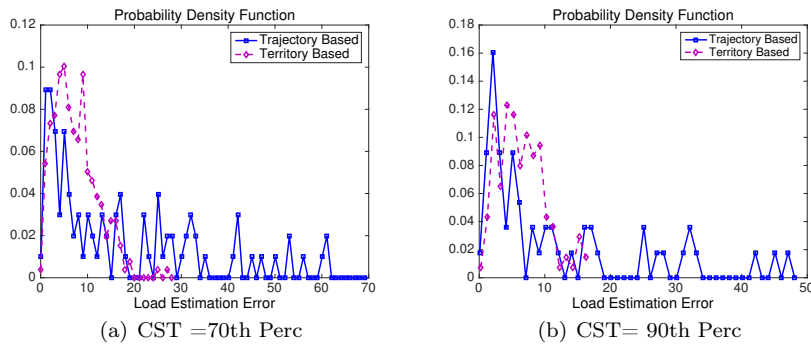




**Fig. 10** CDF of the load estimation error for different RTWs.

timator we propose in this paper (i.e., territory-based estimator). However, the advantages of the proposed estimator over the other are still not straightforward. In this section, we conduct a comparative study of the behavior of both estimators: Trajectory-based and Territory-based crowd estimators. Figure 11 shows the probability density function of the load estimation error for both estimators and for different CST values (i.e., 70% and 90%). It is easy to notice that the trajectory-based estimator has the highest load estimation errors, for both values of CST, with respect to the territory-based one (i.e., for the trajectory-based estimator, some cells have an estimation level higher than 30% while for the territory-based estimator, all cells have an error level lower than 30%).

So, as a conclusion, we can affirm that the territory-based estimator seems more suitable and more accurate in determining the load of crowded spots than the trajectory-based estimator.



**Fig. 11** Probability density function of the load estimation error for both estimators and for different CSTs.

## 6 Conclusion

An important issue in mobile access network management is to find scalable and effective ways to offload the backhauling and core network as a function of user mobility and consumption patterns. The motivation is the arising weight mobile Internet traffic taken over legacy wireline access traffic in today's Internet Service Provider networks. Different offloading techniques are currently studied which could be classified as traffic offloading (e.g., Wifi offloading [21], and femtocell offloading [22]), content offloading (e.g., ICN [23]) and Cloud (computation) offloading (e.g., CloudLet [24] [25]). In this scope, the contribution of this paper is twofold.

Firstly, working on real network probe data from the Orange cellular network of three different French metropolitan areas, we show how content consumption spots spatially move as a function of the occurrence of special events.

Secondly, motivated by the experimental findings, we propose a crowded spot estimation technique based on two compact and easy-to-compute user mobility metrics, i.e. the user's centroid and radius of gyration, and relying on linear regression. The technique basically consists of measuring the cell intersections between users' geographical 'territories' defined by users' centroids and radius of gyration, weighting it by a regression factor while accounting for the gap between estimated and real numbers in the recent past. Results on real data show that the error of our estimator exponentially decreases with the cell load, and that the crowded spot identification presents a small estimation error. We also stress our estimator for more challenging conditions with a smaller regression window and at different times of the day. We show that the estimation accuracy remains very high and it is time-independent (it shows a stable behavior at different times of the day) and it is also space-independent (it behaves similarly for cities with very different topographies). Furthermore, we prove that there is a correlation between the number of crowded spots and users' mobility. Finally, compared to another crowded spot estimator from the

literature, we show that our proposed estimator grants more accurate estimations of the most crowded spots in a region.

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