



## Flexible Electro-Active Materials

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# Flexible Electro-Active Materials

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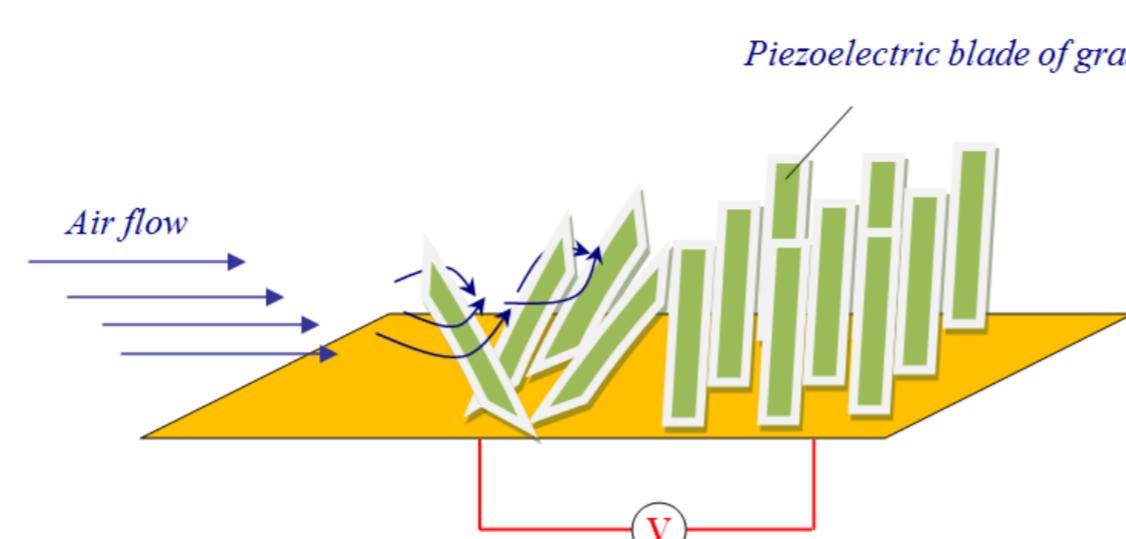
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## N-air-J and MIGAC projects

- Aim:** Synthetic blade of grass to convert wind energy into electricity
- Solution:** Use of flexible piezoelectric thin films
- Support:** Financial support provided by the french region Pays de la Loire and RFI WISE



## Flexible piezoelectric thin films

1

### Lead zirconate titanate (PZT) films



PZT on Aluminium



PZT on PET

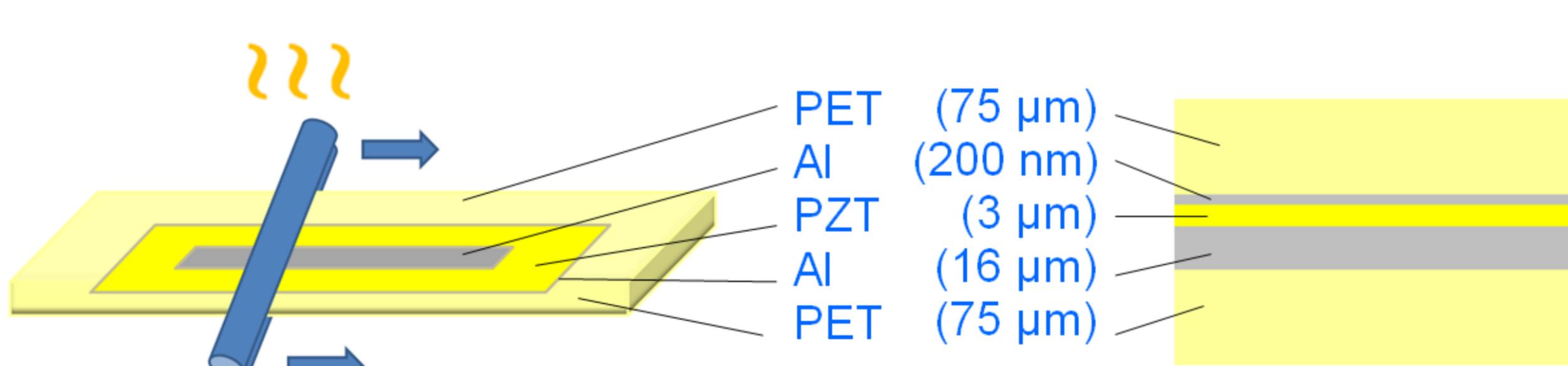


Cut able



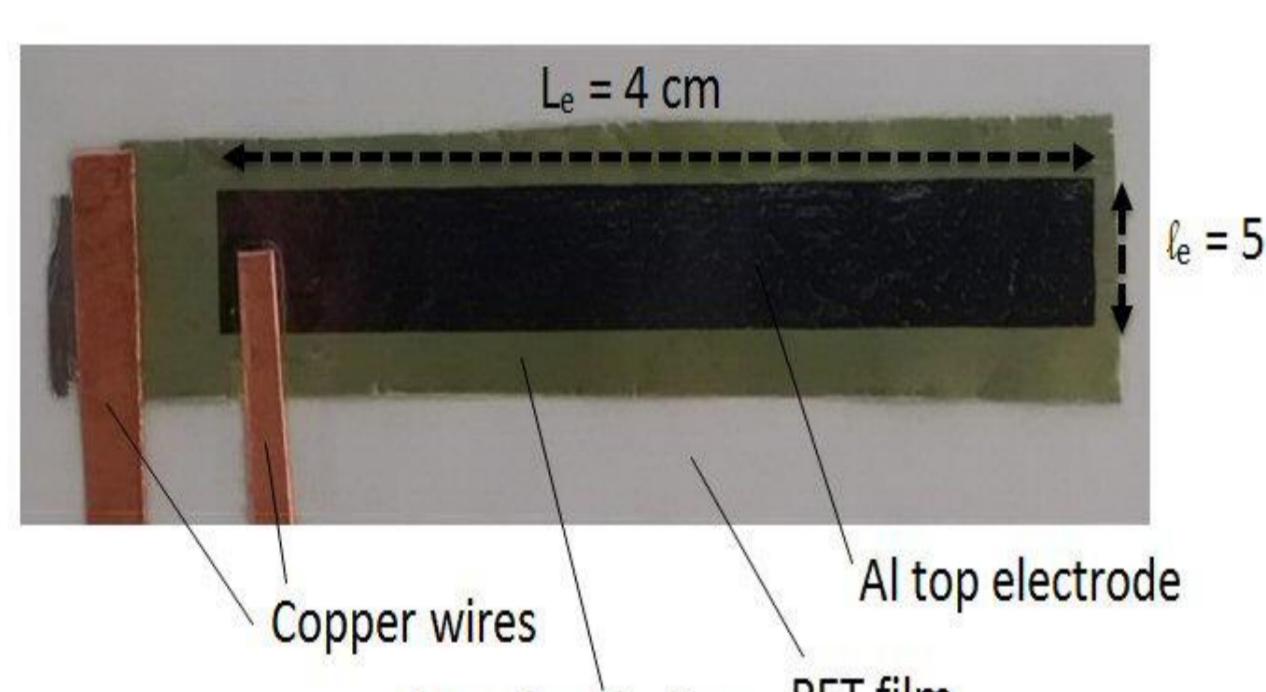
3D shape

### Non conventional shapes



Preparation of the composite by lamination of the PET

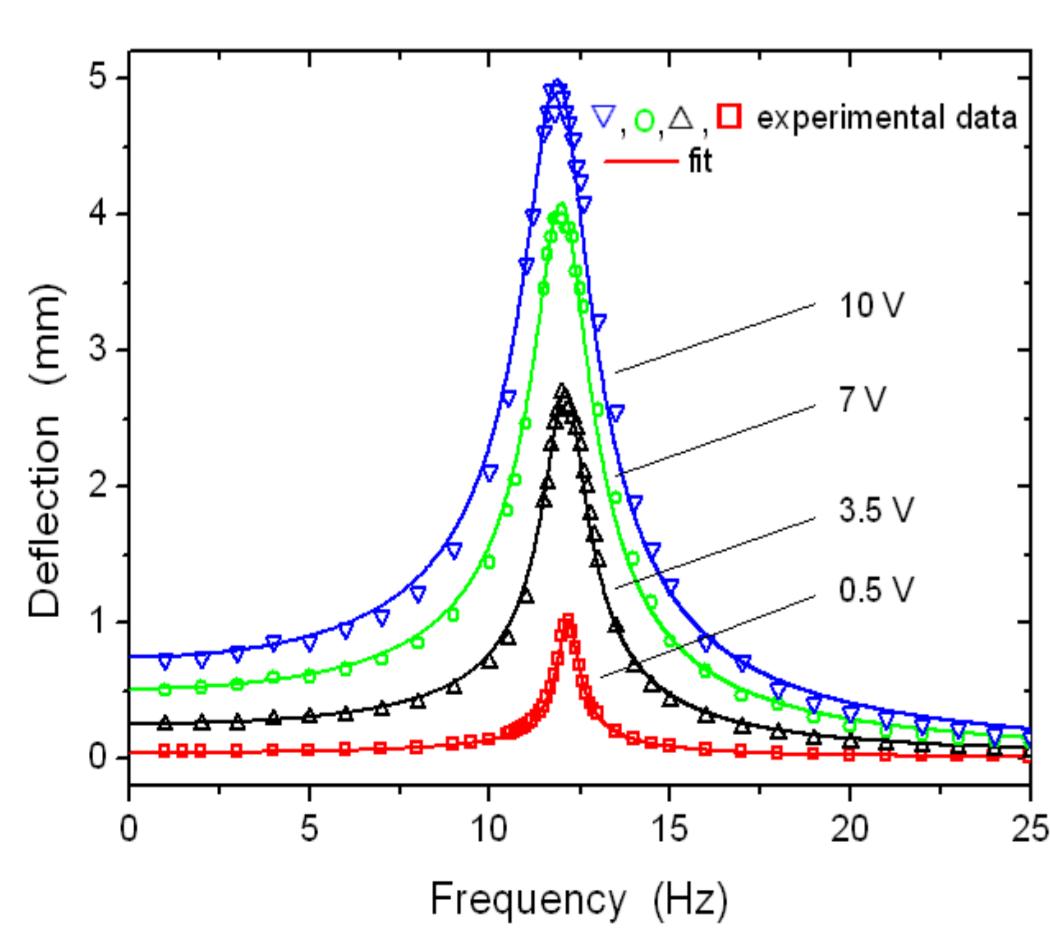
Sectional view of the composite



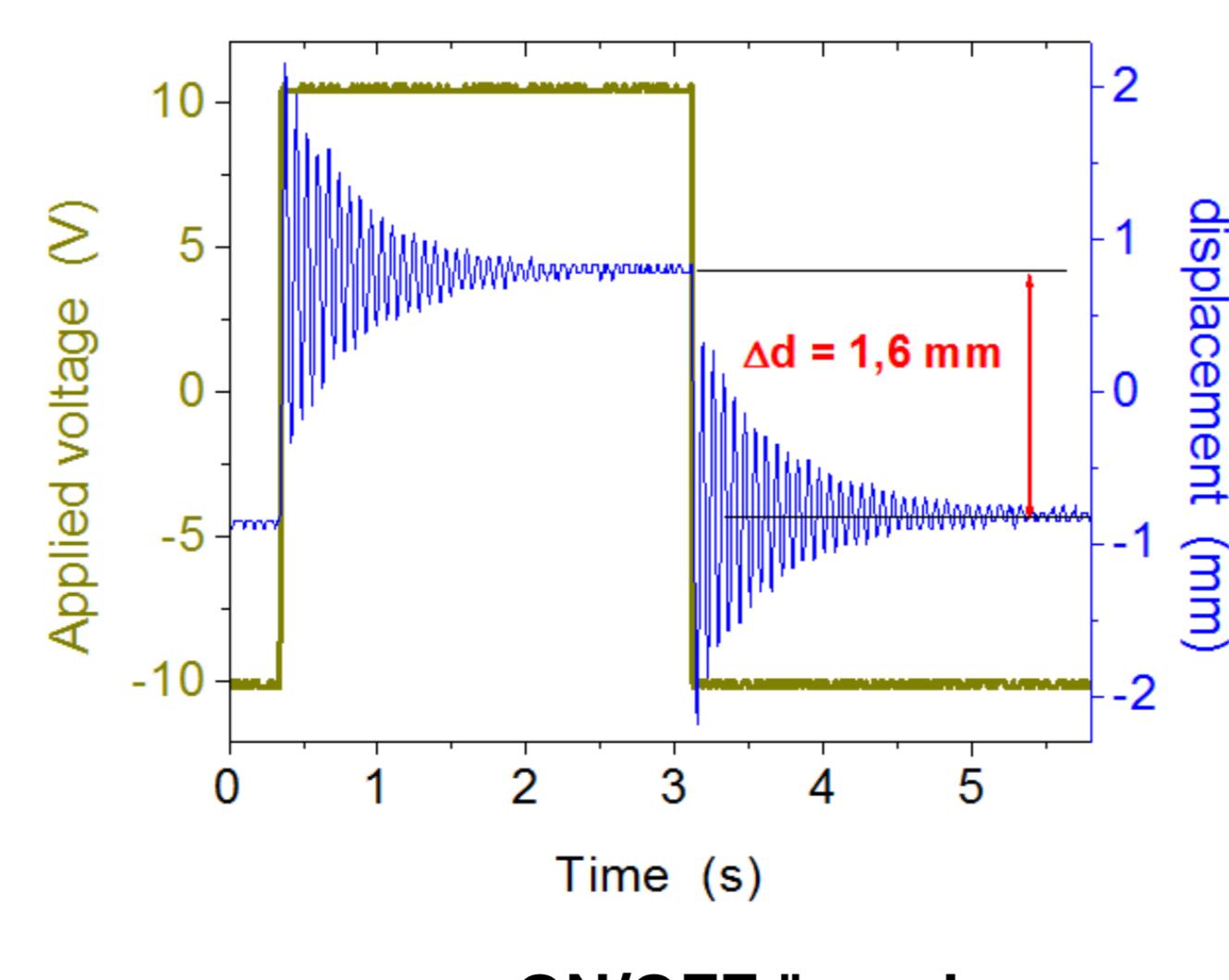
Flexible and watertight

## High bending mode actuation properties

2



Sinusoidal electrical excitations



ON/OFF " mode

milimetric deflections at low applied voltages

## Others applications

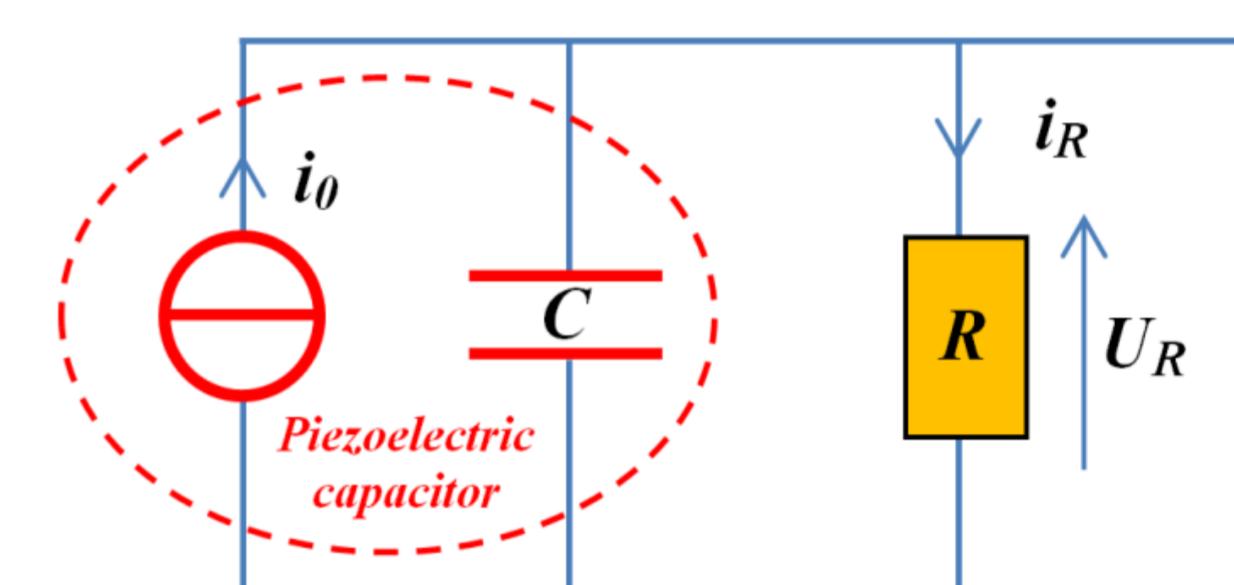
- Energy harvesting from other ambient energy sources (wave energy, body motion)
- Smart sensors (biomedical, buildings, health care, IOT, smart cities)
- Actuators showing high displacements (centimeter range)



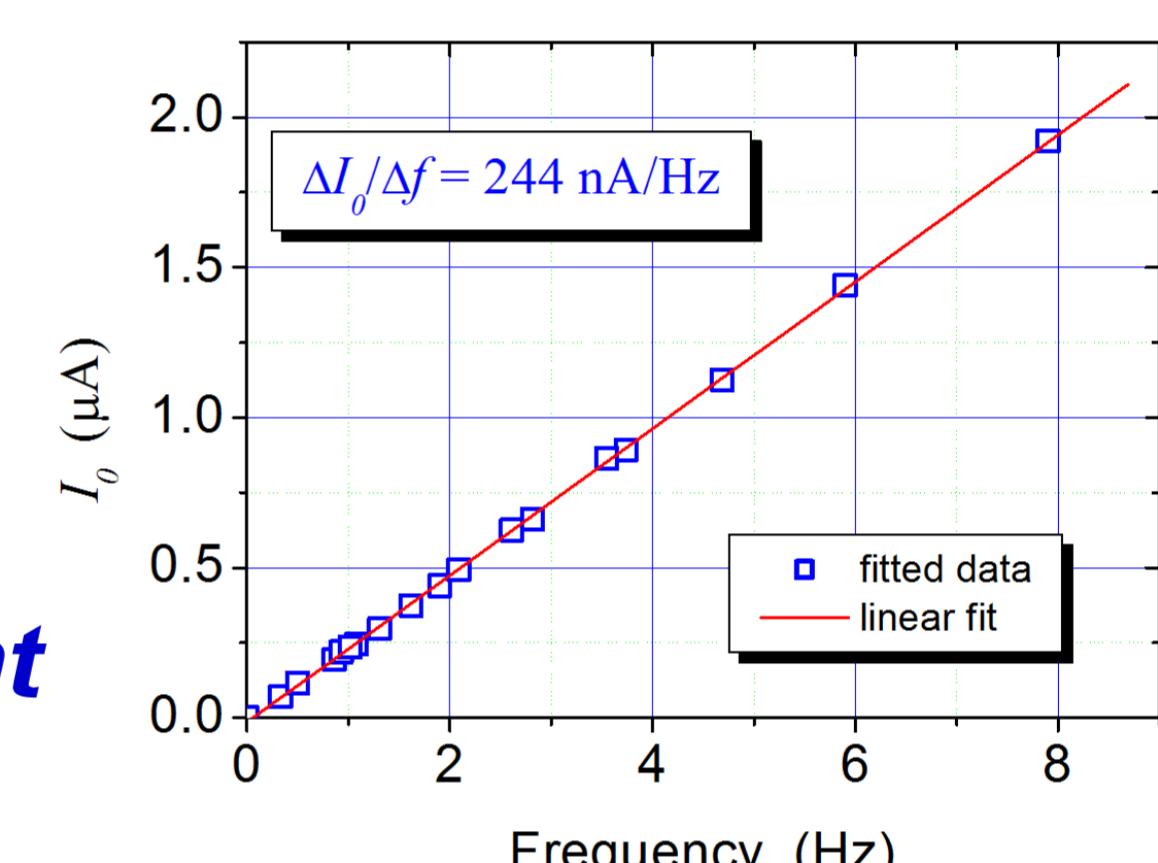
## Energy harvesting

3

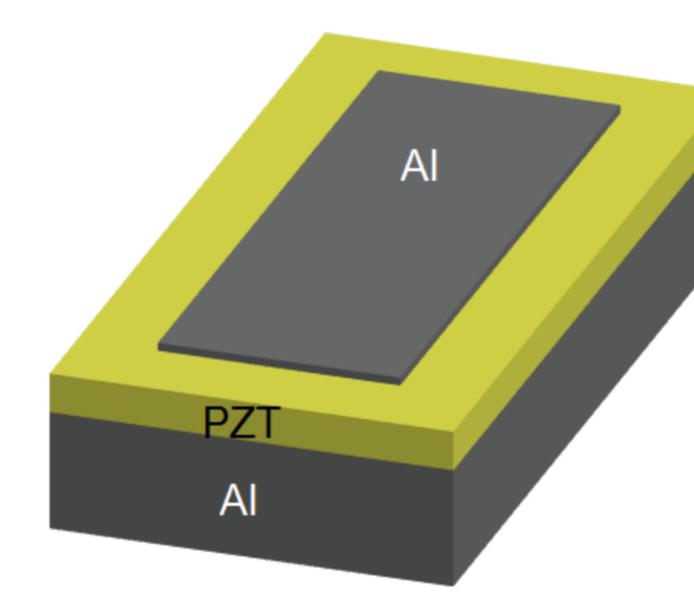
Scheme of the equivalent circuit of the energy harvesting device :



### Piezoelectric current

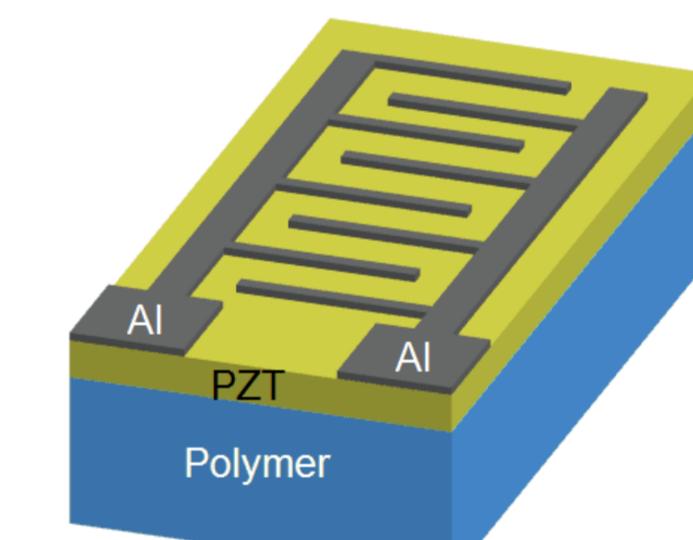


Harvesting device working at very low frequencies

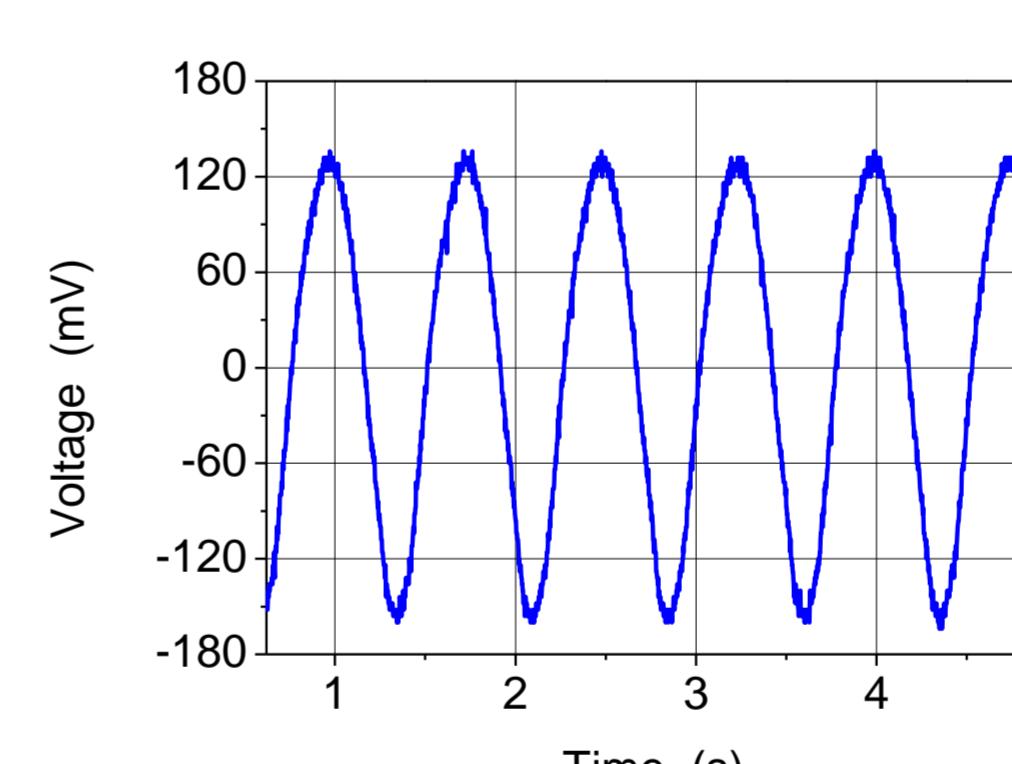


MIM structure

Output voltage X 100



IDE structure



## Flexoelectric polymers for large curvature sensing

4

Flexoelectricity: Mechanical-to-electrical coupling between strain gradient (curvature) and electrical polarization  $P_{flex}$  in every solid dielectrics → Flexoelectric effect in soft polymer films may be used for the development of low cost and easy to implement elastomer-based large curvature sensors on highly flexible metallic structures

### Strain gradient

$$P_{flex} = \mu \frac{\partial S}{\partial x} = \mu C$$

Curvature

Flexoelectric coefficient  $\mu$



Polyurethane (PU) film

PU thin films ( $e=6 \mu m$ ) deposited onto Al foil/PET flexible cantilever  
→ direct sensing of large curvature ( $80 m^{-1}$ ) = radius of curvature ( $\sim 1 cm$ )

