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Behavior of laminated shell composite with imperfect contact between the layers

David Guinovart-Sanjuán ^{a,*}, Raffaella Rizzoni ^b, Reinaldo Rodríguez-Ramos ^c, Raúl Guinovart-Díaz ^c, Julián Bravo-Castillero ^c, Ransés Alfonso-Rodríguez ^a, Frederic Lebon ^d, Serge Dumont ^e, Igor Sevostianov ^f, Federico J. Sabina ^g

The paper focuses on the calculation of the effective elastic properties of a laminated composite shell with imperfect contact between the layers. To achieve this goal, first the two-scale asymptotic homogenization method (AHM) is applied to derive the solutions for the local problems and to obtain the effective elastic properties of a two-layer spherical shell with imperfect contact between the layers. The results are compared with the numerical solution obtained by finite elements method (FEM). The limit case of a laminate shell composite with perfect contact at the interface is recovered. Second, the elastic properties of a spherical heterogeneous structure with isotropic periodic microstructure and imperfect contact is analyzed with the spherical assemblage model (SAM). The homogenized equilibrium equation for a spherical composite is solved using AHM and the results are compared with the exact analytical solution obtained with SAM.

1. Introduction

Composite materials have emerged as the materials of choice in various branches of industry – aerospace, automotive, sport, etc. – for increasing the performance and reducing the weight and cost. However, defects induced during the manufacturing process or accumulated due to environmental and operational loads lead to the reduction in the mechanical performance and material strength and are recognized as a general problem in this type of composites, [1]. Most typically, such defects can be found at the interfaces between the layers creating an imperfect contact condition, [2,3].

The effect of the contact imperfectness on elastic properties of composites attracted the attention of researchers from 1970's, [4,5]. In [6-9], the authors obtained analytical expressions for the effective elastic properties of rectangular fibrous composites with

E-mail address: davidgs1601@gmail.com (D. Guinovart-Sanjuán).

imperfect contact between the matrix and the reinforcement. On the other hand, the multilayered curvilinear shell structures have received special attention in the last years. In [10-13] several mathematical methods have been used to derive analytical expression for the elastic properties of laminated shell composites. As a particular case, in [14], the expression of the effective coefficients for a curvilinear shell composite with perfect contact at the interface is obtained.

Several mathematical models and techniques have been developed to evaluate the elastic properties of curvilinear laminated shell composites with imperfect contact at the interfaces. In papers as [10,12,15–20], the assemblage model, finite elements method and the two-scale asymptotic homogenization method are used to derive in one way or another the effective behavior of the elastic properties of particular composites with imperfect contact at the interface.

In this paper a spherical shell structure is studied. In [21] the authors considered the effect in the elastic properties of a spherical laminated shell composite under the influence of stress and strain

^a Department of Mathematics, University of Central Florida, 4393 Andromeda Loop N, Orlando, FL 32816, USA

^b Dipartimento di Ingegneria, Università di Ferrara, Via Saragat 1, 44122 Ferrara, Italy

^c Departamento de Matemática, Universidad de La Habana, San Lazaro y L, 10400 La Habana, Cuba

^d Aix-Marseille University, CNRS, Centrale Marseille, LMA, 4 Impasse Nikola Tesla, CS 40006, 13453 Marseille Cedex 13, France

^e University of Nîmes, Place Gabriel Péri, 30000 Nîmes, France

f Department of Mechanical and Aerospace Engineering, New Mexico State University, P.O. Box 30001, Las Cruces, NM 88003, USA

g Instituto de Investigaciones en Matemáticas Aplicadas y en Sistemas, Universidad Nacional Autónoma de México, Delegación Álvaro Obregón, Apartado Postal 20-726, 01000 CDMX D.F., Mexico

^{*} Corresponding author.

distributions for two composites with perfect and imperfect contact at the interface using AHM and SAM. In [21] the imperfect contact condition is modeled considering a thin interphase between the layers of the composite, i.e., a three phase composite is used in the analysis. Here the same effect in the spherical shell structure is studied except that the imperfect contact condition is modeled as a linear spring type and the FEM is used to validate the results obtained via AHM and SAM. The purpose of studying this kind of spherical structures obeys to the development and application of mathematical methods for the study of the cornea and other similar soft tissues.

In the present paper, first the AHM technique is used to evaluate the elastic properties of a two-layer laminated shell with imperfect contact of the spring type at the interface. The general analytical expressions of the effective coefficients are derived from the solution of the local problem. We focus on a two-layer spherical shell subjected to internal pressure assuming that the layers are isotropic. To validate the model, the effective coefficients of the spherical structure are compared with FEM calculations. The elastic fields (stresses, strains and displacements) are also compared with ones calculated by the method of Bufler [22] for the analysis of a spherical assemblage model (SAM). The approach is based on the transfer matrix method and yields closed form calculation of the equivalent elastic properties of a periodically laminated hollow sphere made of alternating layers of isotropic elastic materials with imperfect contact. The effective displacement, radial and hoop stresses computed via AHM are compared with the elastic fields calculated by FEM and SAM.

2. The linear elastic problem

A curvilinear elastic periodic composite is studied. The geometry of the structure is described by the curvilinear coordinates system $\mathbf{x} = (x_1, x_2, x_3) \in \Omega \subset \mathbb{R}^3$, where $\Omega = \Omega_1 \cup \Omega_2$ is the region occupied by the solid, it is bounded by the surface $\partial \Omega = \Sigma_1 \cup \Sigma_2$, where $\Sigma_1\cap\Sigma_2=\varnothing,~\Omega_\alpha~\alpha=1,2$ are the elements of the composite, separated by the interface Γ^{ε} . In Ω , the stress σ and strain ϵ are related through the Hooke's law, $\sigma^{ij} = C^{ijkl} \epsilon_{kl}$, where C^{ijkl} are the components of the elastic tensor \boldsymbol{C} . For a linear periodic solid structure, the elastic tensor $C \equiv C(x,y)$ is regular with respect to the slow variable \mathbf{x} and \mathbf{Y} -periodic with respect to the fast variable $\mathbf{y} = \mathbf{x}/\varepsilon \in \mathbf{Y}$, where $0 < \varepsilon \ll 1$ characterizes the periodicity of the composite and Y denotes the periodic cell.

The linear elastic equilibrium equation for a curvilinear laminated shell composite with imperfect contact (spring type) at the interface is

$$\sigma^{ij}_{\ j} + \Gamma^i_{jk} \sigma^{kj} + \Gamma^j_{jk} \sigma^{ik} + f^i = 0, \quad \text{in} \quad \Omega, \eqno(1)$$

subject to boundary conditions.

$$u_i = u_i^0$$
 on Σ_1 , $\sigma^{ij} n_j = S^i$ on Σ_2 , (2)

and interface contact conditions,

$$\sigma^{ij} n_j = K^{ij} \lceil [u_j] \rceil, \quad \lceil [\sigma^{ij} n_j] \rceil = 0, \quad \text{on} \quad \Gamma^{\varepsilon}, \tag{3}$$

where $\{.\}_{j} = \frac{\partial}{\partial x_{i}} \{.\}$ is the derivative with respect to the slow curvilinear coordinate, Γ^i_{ik} are the Christoffel's symbols of second type, $[[ullet]]=(ullet)^{(2)}-(ullet)^{(1)}$ denotes the jump at the interface $\Gamma^{arepsilon}$, n_j is the normal vector to the corresponding surface $(\Sigma_2, \Gamma^{\varepsilon})$, K^{ij} are the components of a matrix **K**, that characterizes the imperfect contact in Γ^{ε} and the order of **K** is $O(\varepsilon^{-1})$. Replacing the Hooke's law and considering the Cauchy's formula, $\epsilon_{ii} = (u_{i,i} + u_{i,i})/2$, the equations (1)–(3) can be rewritten for the displacement vector function [14].

3. Homogenization of two-layer laminated shell composites with imperfect contact

In order to obtain an equivalent problem to (1)–(3) with not fast oscillating coefficients, the two-scales Asymptotic Homogenization Method (AHM) is used. The general expression of the truncated expansion is given by

$$u_m^{(\varepsilon)} = \nu_m + \varepsilon \left[\hat{N}_m^p \nu_p + N_m^{lk} \nu_{l,k} \right] + o(\varepsilon), \tag{4}$$

where $v_m \equiv v_m(\mathbf{x}), N_m^{lk} \equiv N_m^{lk}(\mathbf{x}, \mathbf{y})$ is the local function for the first order approach, $N_{(1)m}^{lk}(\mathbf{x},\mathbf{y})$ is **Y**-periodic, where $\mathbf{Y}=[0,1]$ and $\hat{N}_{m}^{p} = -\Gamma_{lk}^{p} N_{m}^{lk}$ [14]. Substituting the expansion (4) into the Eqs. (1)–(3) a recurrent family of problem is obtained for different powers of the small parameter ε .

Considering a two-layer laminated shell composite with isotropic components, i.e.

$$C^{ijkl} = \lambda(y)g^{ij}g^{kl} + \mu(y)\left(g^{lj}g^{ki} + g^{il}g^{kj}\right),\tag{5}$$

where $[g^{ij}]$ is the metric tensor of the coordinates (x_1, x_2, x_3) and

$$\lambda(y) = \begin{cases} \lambda_1 & y \in [0, \gamma) \\ \lambda_2 & y \in (\gamma, 1] \end{cases}, \quad \mu(y) = \begin{cases} \mu_1 & y \in [0, \gamma) \\ \mu_2 & y \in (\gamma, 1] \end{cases}$$

where the layers are transversal to the axis x_3 , the local problem is obtained for ε^{-1}

$$\partial/\partial y \Big(C^{i3lk} + C^{i3m3} \partial N_m^{lk}/\partial y \Big) = 0 \quad \text{on} \quad \boldsymbol{Y} = [0,\gamma) \cup \{\gamma\} \cup (\gamma,1], \quad (6)$$

with interface conditions given by the expressions

$$\left[C^{i3lk} + C^{i3m3}\partial N_{(1)m}^{lk}/\partial y\right] = (-1)^{\alpha+1}K^{ij}\left[\left[N_{(1)j}^{lk}\right]\right] \quad \text{on} \quad \Gamma^{\varepsilon} = \{y = \gamma\},\tag{7}$$

$$\left[\left[C^{l3lk}+C^{l3m3}\partial N^{lk}_{(1)m}/\partial y\right]\right]=0 \qquad \qquad \text{on} \quad \Gamma^{\varepsilon}=\{y=\gamma\}, \eqno(8)$$

where the parameter $\alpha = 1,2$ denotes the layer.

Substituting (5) into the local problem (6) the following expression is obtained $\partial^2 N_{(1)m}^{lk}/\partial y^2=0$. Therefore, the local function has

$$N_{m}^{lk} = \begin{cases} A_{m}^{lk(1)} y + B_{m}^{lk(1)}, & y \in [0, \gamma), \\ A_{m}^{lk(2)} y + B_{m}^{lk(2)}, & y \in (\gamma, 1]. \end{cases}$$
 (9)

Considering the periodicity of the functions N_m^{lk} and $\partial N_m^{lk}/\partial y$ the following linear equations system is obtained from Eq. (8)

$$\begin{split} & \left[C^{i3lk(1)} + C^{i3m3(1)} A_m^{lk(1)} \right] = -K_{im} \left(A_m^{lk(1)}(\gamma) + A_m^{lk(2)}(1 - \gamma) \right), \end{split} \tag{10} \\ & \left[C^{i3lk(2)} + C^{i3m3(2)} A_m^{lk(2)} \right] = -K_{im} \left(A_m^{lk(1)}(\gamma) + A_m^{lk(2)}(1 - \gamma) \right), \tag{11} \end{split}$$

$$\left[C^{i3lk(2)} + C^{i3m3(2)}A_m^{lk(2)}\right] = -K_{im}\left(A_m^{lk(1)}(\gamma) + A_m^{lk(2)}(1-\gamma)\right),\tag{11}$$

where the supraindex (α) $\alpha = 1, 2$ refers to each layer α . The linear problem (10) and (11) related to the variables $A_m^{lk(\alpha)}$ can be solved using classical methods and therefore the local functions are obtained.

Applying the average operator to the coefficient of the parameter ε^0 , the homogenized coefficients are obtained and the general expression is given in the Eqs. (12)–(18) of [14]. The effective coefficients for a two-layer laminated shell composite with isotropic layers and imperfect contact condition at the interface have the general analytic expression

$$\widehat{h}^{ijkl} = \left\langle C^{ijkl} \right\rangle + V_1 C^{ijm3(1)} \frac{\partial N_m^{kl(1)}}{\partial v} + V_2 C^{ijm3(2)} \frac{\partial N_m^{kl(2)}}{\partial v}. \tag{12}$$

where V_{α} is the volume of the layers of the composite and the local functions $\partial N_m^{kl(\alpha)}/\partial y$ have the expression

$$\frac{\partial N_{m}^{kl(\alpha)}}{\partial y} = \frac{-C^{q3kl(\alpha)}\left(K^{qn}V_{\beta} + C^{q3n3(\beta)}\right) + C^{q3kl(\beta)}K^{qn}V_{\beta}}{C^{r3m3(1)}C^{r3n3(2)} + C^{r3m3(1)}K^{rm}V_{2} + C^{r3n3(2)}K^{rm}V_{1}},$$
(13)

for $\beta = 1, 2$ and $\beta \neq \alpha$.

The homogenized problem is obtained from the Eqs. (19) and (20) of [14].

3.1. Comparison of the effective coefficients for composites with perfect and imperfect contact

In order to illustrate the influence of the imperfect contact on the effective coefficients, a two layer rectangular laminate shell is considered (see Fig. (1)). The layers of the composite are isotropic and the materials are stainless steel (Young's modulus $E_1=206.74$ GPa, Poisson ratio, $v_1=0.3$) with volume V_1 , represented by Y_1 on Fig. (1) and aluminum (Young's modulus $E_2=72.04$ GPa, Poisson ratio, $v_2=0.35$) with volume $V_2=1-V_1$, represented by Y_2 on Fig. (1). The matrix **K** characterizes the imperfect contact at the interface Γ (see Fig. (1)) and it has nonzero components $K^{11}=K^{22}=\mu/\varepsilon$ and $K^{33}=(\mu+2\lambda)/\varepsilon$ where $\mu=\lambda=1$ and $\varepsilon=[0.001,0.01,0.05]$. The effective coefficients for the imperfect contact case are calculated using the Eq. (12) and they are compared with the coefficients obtained using Eq. (26) of [14] for perfect contact case (see Fig. (2)). The convergence of effective

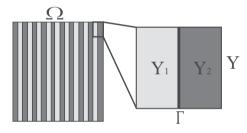


Fig. 1. Rectangular structure Ω , unit cell **Y**, the two elements **Y**₁ and **Y**₂ with the corresponding interface Γ .

coefficients for the imperfect contact case can be appreciated as $\varepsilon \to 0$, i.e. $K^{ij} \to +\infty$.

For the case of $V_1=0$ or $V_1=1$, we are in presence of a monoelement multi-layered structure, i.e. it is a structure with several layers but each layer is the same element. It can be studied the perfect and the imperfect contact between the layers of these structures. For the perfect contact case, the mono-element multi-layered structure are considered as an homogeneous structure. But a different situation is obtained for the imperfect contact case. Due to the imperfection, the structures are studied as a heterogeneous composite.

It can be seen in Fig. (2), for the perfect contact case, that the aluminum and stainless steel elastic moduli are reached for $V_1 = 0$ or $V_1 = 1$, respectively, as a whole homogeneous material. In particular, for $V_1 = 1$ the value $C^{3333} = h^{3333} = 278.3038$ GPa is attained for stainless steel. In the case of imperfect contact the imperfection is modeled as a linear spring distributed across the common interface Γ between the layers. When K^{11} takes the values 1000, 100 and 20, the elastic constant h^{3333} is equal to 254.6779. 144.3725 and 49.3587 GPa, respectively. Thus, the main effect of the imperfect contact is to degrade the composite's integrity: the value of the elastic constants diminishes accordingly, so a weakened composite is obtained. In other words, the particular case of $V_1 = 0$ ($V_1 = 1$) reports, for the imperfect contact case, the effective coefficients of the a structure Ω where the unit cell has two layers Y_1 and Y_2 made by aluminum (stainless steel), but with degrading due to the imperfection. It is very important to remark the fact that the AHM reports different values of the effective coefficients for mono-element multi-layers structures with perfect and imperfect contact at the interface; i.e. due to the imperfection, the effective coefficients of the structures with imperfect contact are weaker.

4. The spherical assemblage model with imperfect contact (SAM)

In this section, a spherical assemblage model consisting of *N* different thin elastic layers is studied using the transfer-matrix method.

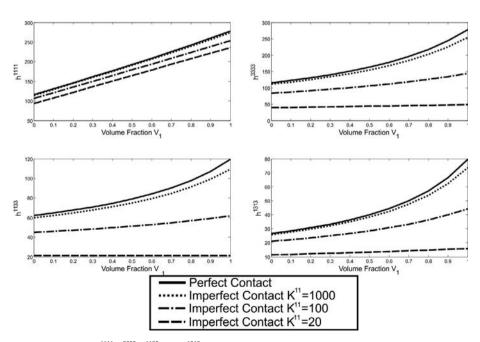


Fig. 2. Comparison of the effective coefficients h^{1111} , h^{3333} , h^{1133} and h^{1313} of a composite with perfect contact at the interface using Eq. (26) of [14] and the effective coefficients for a composite with imperfect contact using Eq. (12).

The transfer-matrix method is a classic approach [23]. Here, we first review its application to a periodic laminated hollow sphere proposed in [22] and next extend the obtained results to the case of imperfect contact between the layers.

The spherical assemblage has internal radius R_i , external radius R_e and thickness h=2t. The inner surface $r=R_i$ is loaded by a constant pressure

$$\sigma_{rr}(R_i) = +p, \tag{14}$$

whereas the external surface $r = R_e$ is traction free

$$\sigma_{rr}(R_e) = 0. (15)$$

The k-th layer comprised between the radii R_{k-1} and R_k , is characterized by the thickness h_k and it is made of linear elastic homogeneous and isotropic material with Young modulus and Poisson ratio E_k and v_k , respectively. According to the transfer-matrix method [22], the radial stress σ_{rr} and displacement u_r at radius R_{k-1} of the laminated sphere can be related to the radial stress and displacement at radius R_k through the field-transfer matrix T_k of the layer k:

$$\begin{bmatrix} \sigma_{rr}(R_k) \\ E^* u_r(R_k)/h^* \end{bmatrix} = \mathbf{T}_k \begin{bmatrix} \sigma_{rr}(R_{k-1}) \\ E^* u_r(R_{k-1})/h^* \end{bmatrix}, \tag{16}$$

$$\mathbf{T}_{k} := \begin{bmatrix} 1 - a_{k}h & b_{k}h \\ c_{k}h & 1 - d_{k}h \end{bmatrix}, \tag{17}$$

with

$$a_k := 2\left(1 - \frac{\nu_k}{(1 - \nu_k)}\right) \frac{\lambda_k}{R_i},\tag{18}$$

$$b_k := \frac{2}{(1 - \nu_k)} \frac{E_k h^*}{E^*} \frac{\lambda_k}{R_*^2},\tag{19}$$

$$c_k := \left(1 - \frac{2v_k^2}{(1 - v_k)}\right) \frac{E_k h^*}{E^*} \lambda_k, \tag{20}$$

$$d_k := \frac{2\nu_k}{(1 - \nu_k)} \frac{\lambda_k}{R_i}. \tag{21}$$

Here, $\lambda_k = h_k/h$ is the thickness ratio of the k-th layer, and E^* and h^* denote a reference modulus of elasticity and thickness, respectively. Applying (16) N-times for the layered hollow sphere made of layers in perfect contact, we have

$$\begin{bmatrix} \sigma_{rr}(R_e) \\ E^* u_r(R_e)/h^* \end{bmatrix} = \mathbf{S} \begin{bmatrix} \sigma_{rr}(R_i) \\ E^* u_r(R_i)/h^* \end{bmatrix}, \quad \mathbf{S} := \mathbf{T}_N \mathbf{T}_{N-1} \dots \mathbf{T}_1. \tag{22}$$

Here **S** is the *transfer matrix system* from radius R_i to R_e , linking the two elastic states at the boundaries of laminated sphere.

Sustituting (16) into (22) and considering only the terms of order zero and one in h, Bufler's result is obtained:

$$\mathbf{S} = \mathbf{I} - h\mathbf{M} + o(h), \quad \mathbf{M} := \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \tag{23}$$

with

$$a := \sum_{k=1}^{N} 2\left(1 - \frac{v_k}{(1 - v_k)}\right) \frac{\lambda_k}{R_i},\tag{24}$$

$$b := \sum_{k=1}^{N} \frac{2}{(1 - v_k)} \frac{E_k h^*}{E^*} \frac{\lambda_k}{R_i^2}, \tag{25}$$

$$c := \sum_{k=1}^{N} \left(1 - \frac{2v_k^2}{(1 - v_k)} \right) \frac{E_k E^*}{h^*} \lambda_k, \tag{26}$$

$$d := \sum_{k=1}^{N} \frac{2\nu_k}{(1-\nu_k)} \frac{\lambda_k}{R_i}.$$
 (27)

To extend these results to a laminated sphere with imperfect contact between the layers, an arrangement of springs is artificially considered at the spherical surface between adjacent layers. In this case, a jump of the radial displacement has to be taken into consideration, [24–27]. In particular, the continuity of radial stress is assumed and the following linear relation between the radial stress and the jump of radial displacement is imposed at the radius R_k :

$$\begin{bmatrix} \sigma_{rr}(R_k^+) \\ E^* u_r(R_k^+)/h^* \end{bmatrix} = \hat{\mathbf{K}}_k \begin{bmatrix} \sigma_{rr}(R_k^-) \\ E^* u_r(R_k^-)/h^* \end{bmatrix}, \quad \hat{\mathbf{K}}_k := \begin{bmatrix} 1 & 0 \\ E^* \varepsilon_k/(h^*(2\mu_k + \lambda_k)) & 1 \end{bmatrix}, \tag{28}$$

where the matrix $\hat{\mathbf{K}}_k$ characterizes the imperfect contact provided by the k-th layer of springs, with $k=1,2,\ldots N-1, \varepsilon_k\ll 1$ is a small length parameter accounting for its thickness and $2\mu_k+\lambda_k$ its elasticity coefficient.

Now, the presence of springs are considered, therefore the transfer matrix system **S** (cf. (23)) modifies in order to incorporate the matrices $\hat{\mathbf{K}}_{\nu}$.

$$\tilde{\mathbf{S}} = \mathbf{T}_{N} \hat{\mathbf{K}}_{N-1} \mathbf{T}_{N-1} \dots \hat{\mathbf{K}}_{1} \mathbf{T}_{1}. \tag{29}$$

Substituting (16) and (28) into (29), one obtains the new matrix system for a spherical assemblage made of N layers with imperfect contact. It can be shown that

$$\tilde{\mathbf{S}} = \mathbf{I} - h\mathbf{M} + o(h), \quad \tilde{\mathbf{M}} := \begin{bmatrix} a & b \\ \tilde{c} & d \end{bmatrix},$$
 (30)

with a, b and d given again by Eqs. (24), (25) and (27), respectively, and

$$\tilde{c} := c + \sum_{k=1}^{N-1} \frac{E^*}{h^*} \frac{\varepsilon_k}{(2\mu_k + \lambda_k)}$$

$$= \sum_{k=1}^{N} \left(1 - \frac{2\nu_k^2}{(1 - \nu_k)} \right) \frac{E_k E^*}{h^*} \lambda_k + \sum_{k=1}^{N-1} \frac{E^*}{h^*} \frac{\varepsilon_k}{(2\mu_k + \lambda_k)}.$$
(31)

The case of a periodic laminate made by repeating n times a group of N layers is now considered. As n increases, the thicknesses h_k and ε_k must decrease with n in order to keep the total thickness h of the fixed laminate. In particular, it is assumed that $h_k = \Lambda_k h/n$ and $\varepsilon_k = \xi_k h/n$, with $\Lambda_k, k = 1, 2, \dots N$, the thickness ratio of the k-th layer inside the group, and analogously $\xi_k \ll 1$, $k = 1, 2, \dots N-1$, for the k-th layer of springs. The matrix system for the hollow sphere with homogenized properties following Bufler is calculated as

$$\lim_{h\to 0} \frac{1}{h} \left(\tilde{\mathbf{S}}^n - \mathbf{I} \right) = \lim_{h\to 0} \frac{1}{h} \left(\left(\mathbf{T}_N \hat{\mathbf{K}}_{N-1} \mathbf{T}_{N-1} \dots \hat{\mathbf{K}}_1 \mathbf{T}_1 \right)^n - \mathbf{I} \right) = \langle \mathbf{M} \rangle, \tag{32}$$

with

$$\langle \mathbf{M} \rangle := \begin{bmatrix} \langle a \rangle & \langle b \rangle \\ \langle c \rangle & \langle d \rangle \end{bmatrix}, \tag{33}$$

$$\langle a \rangle := \sum_{k=1}^{N} 2 \left(1 - \frac{\nu_k}{(1 - \nu_k)} \right) \frac{\Lambda_k}{R_i}, \tag{34}$$

$$\langle b \rangle := \sum_{k=1}^{N} \frac{2}{(1 - \nu_k)} \frac{E_k h^*}{E^*} \frac{\Lambda_k}{R_i^2}, \tag{35}$$

$$\langle c \rangle := \sum_{k=1}^{N} \left(1 - \frac{2\nu_k^2}{(1 - \nu_k)} \right) \frac{E_k h^*}{E^*} \Lambda_k + \sum_{k=1}^{N-1} \frac{E^*}{h^*} \frac{\xi_k}{(2\mu_k + \lambda_k)}, \tag{36}$$

$$\langle d \rangle := \sum_{k=1}^{N} \frac{2\nu_k}{(1 - \nu_k)} \frac{\Lambda_k}{R_i}. \tag{37}$$

As an example, consider the homogenization of a periodic laminate made by repeating a group of two layers under imperfect contact. In this case, the "unit cell" of the laminate is $\mathbf{T}_+\mathbf{K}\mathbf{T}_-$, with \mathbf{T}_\pm the transfer matrices of two layers whose elasticity constants are denoted E_\pm , ν_\pm , and $\hat{\mathbf{K}}$ the matrix characterizes imperfect contact. The thickness ratios Λ_\pm are assumed to coincide $\Lambda_+=\Lambda_-=1/2$. Thus,

$$\langle a \rangle := \frac{1}{R_i} \left(\frac{(1 - 2\nu_-)}{(1 - \nu_-)} + \frac{(1 - 2\nu_+)}{(1 - \nu_+)} \right), \tag{38}$$

$$\langle b \rangle := \frac{h^*}{E^* R_i^2} \left(\frac{E_-}{(1 - \nu_-)} + \frac{E_+}{(1 - \nu_+)} \right), \tag{39}$$

$$\langle c \rangle := \frac{E^*}{h^*} \left(\frac{(1 - 2\nu_-)(1 + \nu_-)}{2E_-(1 - \nu_-)} + \frac{(1 - 2\nu_+)(1 + \nu_+)}{2E_+(1 - \nu_+)} + \frac{\xi}{(2\mu + \lambda)} \right), \tag{40}$$

$$\langle d \rangle := \frac{1}{R_i} \left(\frac{\nu_-}{(1 - \nu_-)} + \frac{\nu_+}{(1 - \nu_+)} \right). \tag{41}$$

As a final result, note that comparing the latter relations with the matrix system of a transversely isotropic homogeneous elastic sphere (cf. [22, Eqs. (17)–(19)]) one obtains the equivalent material parameters E/(1-v), E', v' of the homogenized sphere consisting of a two–layers laminate with imperfect contact,

$$\begin{split} \frac{E}{(1-\nu)} &= \left(\frac{E_{-}}{2(1-\nu_{-})} + \frac{E_{+}}{2(1-\nu_{+})}\right), \\ \frac{1}{E'} &= \frac{\left(\frac{\nu_{-}}{(1-\nu_{-})} + \frac{\nu_{+}}{(1-\nu_{+})}\right)^{2}}{\left(\frac{E_{-}}{(1-\nu_{-})} + \frac{E_{+}}{(1-\nu_{+})}\right)} \\ &+ \frac{(1-2\nu_{-})(1+\nu_{-})}{2E_{-}(1-\nu_{-})} + \frac{(1-2\nu_{+})(1+\nu_{+})}{2E_{+}(1-\nu_{+})} + \frac{\xi}{(2\mu+\lambda)}, \end{split} \tag{43}$$

$$\frac{v'}{E'} = \frac{\left(\frac{v_{-}}{(1-v_{-})} + \frac{v_{+}}{(1-v_{+})}\right)}{\left(\frac{E_{-}}{(1-v_{-})} + \frac{E_{+}}{(1-v_{+})}\right)}.$$
(44)

The state of stresses and displacements of the equivalent transversely isotropic hollow sphere subjected to the boundary conditions (14) and (15) can be obtained by substituting the relations (42)–(44) into Eq. (52) of [22], which are

$$u_{r}(r) = \frac{pR_{e}}{\left(\frac{R_{i}}{R_{e}}\right)^{\lambda_{1}-1} - \left(\frac{R_{i}}{R_{e}}\right)^{\lambda_{2}-1}} \frac{h^{*}}{E^{*}} \langle c \rangle \left[\frac{\left(\frac{r}{R_{e}}\right)^{\lambda_{2}}}{R_{i}\langle d \rangle + \lambda_{2}} - \frac{\left(\frac{r}{R_{e}}\right)^{\lambda_{1}}}{R_{i}\langle d \rangle + \lambda_{1}} \right], \tag{45}$$

$$\sigma_{rr}(r) = -\frac{p}{\left(\frac{R_i}{R_e}\right)^{\lambda_1 - 1} - \left(\frac{R_i}{R_e}\right)^{\lambda_2 - 1}} \left[\left(\frac{r}{R_e}\right)^{\lambda_1 - 1} - \left(\frac{r}{R_e}\right)^{\lambda_2 - 1} \right],\tag{46}$$

$$\sigma_{\theta\theta}(r) = -\frac{p/2}{\left(\frac{R_i}{R_e}\right)^{\lambda_1 - 1} - \left(\frac{R_i}{R_e}\right)^{\lambda_2 - 1}} \left[(1 + \lambda_1) \left(\frac{r}{R_e}\right)^{\lambda_1 - 1} - (1 + \lambda_2) \left(\frac{r}{R_e}\right)^{\lambda_2 - 1} \right],$$

with

$$\lambda_{1,2} = 1/2 \left(-1 \pm \sqrt{8\overline{C} - 1} \right), \tag{48}$$

$$\overline{C} = 1/2 \Big(R_i^2 \langle b \rangle \langle c \rangle - (1 - R_i \langle d \rangle) R_i \langle d \rangle \Big). \tag{49}$$

5. The finite element method

In this section, a numerical method based on the finite element is proposed to solve problem (6)–(8). Since this technique is quite standard, it is rapidly outlined here.

For the sake of simplicity, we denote $Y_- = [0, \gamma)$ and $Y_+ = (\gamma, 1]$. Then, choosing a test function v, which can be discontinuous across the interface Γ^ε , multiplying the equilibrium Eq. (6) by this test function and integrating among Y, one obtains after integration by parts

$$-\int_{Y_{-}} \left(C^{i3lk} + C^{i3m3} \frac{\partial N_{m}^{lk}}{\partial y} \frac{\partial v}{\partial y} \right) dy + C^{i3lk} + C^{i3m3} \frac{\partial N_{m}^{lk}}{\partial y} (\gamma^{-}) v(\gamma^{-}) = 0$$
(53)

$$-\int_{Y_{+}} C^{i3lk} + C^{i3m3} \frac{\partial N_{m}^{lk}}{\partial y} \frac{\partial v}{\partial y} dy - C^{i3lk} + C^{i3m3} \frac{\partial N_{m}^{lk}}{\partial y} (\gamma^{+}) v(\gamma^{+}) = 0.$$

$$(51)$$

Now, adding these two equations, using the continuity of $C^{i3lk} + C^{i3m3} \frac{\partial N_m^{lk}}{\partial y}$ across the interface, (see Eqs. (7) and (8)), a weak formulation of the problem can be written as follows

$$\int_{Y_{+}} C^{i3lk} + C^{i3m3} \frac{\partial N_m^{lk}}{\partial y} \frac{\partial v}{\partial y} dy + K^{im}[[N_{(1)m}^{lk}]][[v]] = 0$$

Finally, using standard finite element on each sub domain, and a "flat" finite element on Γ^{ϵ} , that have all its nodes on Γ^{ϵ} , the first ones related to Y_{-} and the other ones to Y_{+} , it is possible to write a rigidity matrix of this problem, that is invertible, with standard error estimation (see [28] or [29] for more details).

Due to finite element discretization, the integrals (see formula (12), for example) for the computation of effective coefficients are substituted by sums over element contributions.

6. Numerical results

6.1. Rectangular shell composite

Here a flat shell structure is considered in order to validate formula (12). The unit cell is composed of two layers of isotropic materials like aluminum and reinforced carbon fiber. The properties are Young's modulus equal to 150 Gpa and Poisson's ratio 0.3. The volume fraction of both materials are set to 0.5. The matrix **K** that characterizes the imperfect contact takes the same values as given in Section 3.1. In Table 1 the effective coefficients are obtained using formula (12). The same results are also attained using the formulas for perfect contact homogenized constants (1.19) [4, Chap. 5] and (9.9) [30]. As a particular case, from the model used here of imperfect contact, Eq. (12) gives the same values that formula (1.30) of [4, Chap. 5] with perfect contact (i.e. with very large K^{11}) for a flat laminated structure.

6.2. Spherical shell composite

In contrast to [21] here the imperfect condition is taken as a distribution of linear springs acting at the interface between the two isotropic materials except that now a hollow two layer spherical shell composite is considered with isotropic components.

The inner and outer radius are denoted by $R_i = R_0 - t$ and $R_e = R_0 + t$ respectively, where $t = R_0/10$. The spherical coordinate system (θ, φ, r) is used to describe the geometry of the structure, [12]. The layers of the composite are transversal to the coordinate r. The inner surface $r = R_i$ of the heterogeneous body is loaded by a constant radial stress, (14), and the external spherical surface $r = R_e$ is traction free. The materials used in the composite have the following elastic properties

$$\mu_{-} = 10\mu_{+}, \quad \mu = e^{x}\mu_{+},$$
 (52)

$$v_{-} = 0.2, \quad v_{+} = 0.35, \quad v = 0.3,$$
 (53)

where $x \in [-3,3]$, the index "-" denotes the inner layer, the index "+" the outer layer, non-indexed constants are the **K** parameters. For this particular case, the matrix **K** is diagonal and has components $K^{11} = K^{22} = \mu/\varepsilon$ and $K^{33} = (\lambda + 2\mu)/\varepsilon$.

To obtain the effective elastic properties of the presented spherical shell composite, the two above described approaches, AHM and SAM are used.

As a first step, the local functions $\partial N_m^{lk}/\partial y$ are computed via AHM (13) and FEM. The variational formulation (50) and (51) of

 Table 1

 Comparison between the effective coefficients obtained via AHM (12) for imperfect contact (I.C.) case and perfect contact (P.C.) condition using the results presented in [4].

Effective Ceoff.	P.C.	I.C. $K^{11} = 1000$	I.C. $K^{11} = 100$	I.C. $K^{11} = 20$
h ¹¹¹¹	157.843037	156.2367942	146.5355996	133.4282785
h^{1122}	73.46924781	71.86300505	62.16181048	49.05448934
h ¹¹³³	71.09793087	67.77592879	47.71209456	20.60377131
h ³³³³	147.0434479	140.1729436	98.67728648	42.61234521
h ¹³¹³	36.48801967	35.20351318	26.73349628	12.91885249
h ¹²¹²	42.18689459	42.18689459	42.18689459	42.18689459

the linear system of Eqs. (10) and (11) used to obtain the value of the local function $\partial N_m^{lk}/\partial y$ by FEM, reports the exact solution of the system due to the linearity of the system. Thus, a perfect concordance between the local function $\partial N_m^{lk}/\partial y$, computed via AHM and FEM, is obtained.

In Table 2, a comparison of the effective coefficients obtained via AHM and FEM using the parameters (52) and (53) and considering $\varepsilon=R_0/100$ is shown. Notice the perfect coincidence between the effective coefficients reported by both methods; this is an expected result since the local functions obtained through AHM and FEM also coincide.

The effective coefficients given in Table 2 are used to obtain the homogenized problem following the methodology described in [4,14]. Solving the homogenized problem with the boundary con-

ditions (14) and (15), the effective displacement and stress are computed. In order to compare the results obtained by AHM, FEM and the methodology presented in Section 4, the normalized displacement reported in Table 3 is computed using three methods AHM, FEM and SAM for the values of the parameter $x = \{-3, -2, -1, 0, 1, 2, 3\}$ at R_i , R_0 and R_e . Good concordance between the three methods is appreciated.

Considering the effective coefficients of Table 2, the radial displacement of Table 3 and the methodology described in Section 4, the effective radial σ^r and circumferential $\sigma^{\theta\theta}$ stresses are computed using the three methods.

In Table 4, the effective radial stress is computed by AHM, FEM and SAM for different values of the parameter x. The good correspondence between the three methods for $r = \{R_i, R_e\}$ is due to

Table 2 Values of the effective coefficients h^{ijkl} obtained via AHM and FEM for some values of the parameter x.

	h^{ijkl}/μ_+										
'	h ¹¹¹¹		h ¹¹³³		h ¹¹²²	h ¹¹²²		h ³³³³			
x	AHM	FEM	AHM	FEM	AHM	FEM	AHM	FEM			
-3	14.84995	14.84995	2.05841	2.05841	3.84995	3.84995	5.22134	5.22134			
-2	15.03957	15.03957	2.53939	2.53939	4.03957	4.03957	6.44138	6.44138			
-1	15.13372	15.13372	2.77821	2.77821	4.13372	4.13372	7.04716	7.04716			
0	15.17297	15.17297	2.87777	2.87777	4.17297	4.17297	7.29971	7.29971			
1	15.18812	15.18812	2.91622	2.91622	4.18812	4.18812	7.39723	7.39723			
2	15.19380	15.19380	2.93062	2.93062	4.19380	4.19380	7.43377	7.43377			
3	15.19591	15.19591	2.93595	2.93595	4.19591	4.19591	7.44730	7.44730			

Table 3 Values of the normalized effective displacement $\mu_+u_r/p(\cdot)$ obtained via AHM, FEM and SAM for some values of the parameter x.

	$\mu_+ u_r/p(R_i)$			$\mu_+ u_r/p(R_0)$			$\mu_+ u_r/p(R_e)$		
x	AHM	FEM	SAM	AHM	FEM	SAM	AHM	FEM	SAM
-3	-0.15039	-0.15191	-0.16851	-0.12612	-0.12649	-0.12857	-0.11365	-0.11433	-0.11224
-2	-0.14827	-0.14581	-0.16224	-0.12647	-0.12335	-0.13398	-0.11459	-0.11198	-0.12014
-1	-0.14749	-0.14315	-0.16218	-0.12660	-0.12182	-0.13813	-0.11494	-0.11077	-0.12510
0	-0.14721	-0.14210	-0.16310	-0.12664	-0.12119	-0.14054	-0.11507	-0.11026	-0.12775
1	-0.14710	-0.14170	-0.16367	-0.12666	-0.12094	-0.14164	-0.11511	-0.11007	-0.12893
2	-0.14706	-0.14155	-0.16393	-0.12667	-0.12085	-0.14208	-0.11513	-0.10999	-0.12939
3	-0.14705	-0.14150	-0.16403	-0.12667	-0.12082	-0.14225	-0.11514	-0.10997	-0.12957

Table 4 Values of the normalized effective radial stress $\sigma_{\pi}/p(\cdot)$ obtained via AHM, FEM and SAM for some values of the parameter x.

	$\sigma_{rr}/p(R_i)$			$\sigma_{rr}/p(R_0)$	$\sigma_{rr}/p(R_0)$			$\sigma_{rr}/p(R_e)$		
x	AHM	FEM	SAM	AHM	FEM	SAM	AHM	FEM	SAM	
-3	1	1	1	0.39194	0.40777	0.37774	0	0	0	
-2	1	1	1	0.39442	0.41001	0.38967	0	0	0	
-1	1	1	1	0.39535	0.41086	0.39422	0	0	0	
0	1	1	1	0.39569	0.41117	0.39591	0	0	0	
1	1	1	1	0.39581	0.41129	0.39654	0	0	0	
2	1	1	1	0.39586	0.41133	0.39677	0	0	0	
3	1	1	1	0.39588	0.41135	0.39685	0	0	0	

Table 5 Values of the normalized effective radial stress $\sigma_{\theta\theta}/p(\cdot)$ obtained via AHM, FEM and SAM for some values of the parameter x.

	$\sigma_{ heta heta}/p(R_i)$			$\sigma_{\theta\theta}/p(R_0)$			$\sigma_{ heta heta}/p(R_e)$		
x	AHM	FEM	SAM	AHM	FEM	SAM	AHM	FEM	SAM
-3	2.45936	2.48818	2.69206	1.99925	1.99922	1.97031	1.76450	1.77485	1.68188
-2	2.41921	2.37235	2.49624	2.00421	1.94473	1.99469	1.77900	1.73844	1.75124
-1	2.40438	2.32194	2.42263	2.00604	1.91827	2.00379	1.78437	1.71966	1.77776
0	2.39891	2.30199	2.39533	2.00672	1.90737	2.00716	1.78636	1.71178	1.78766
1	2.39690	2.29444	2.38526	2.00696	1.90319	2.00840	1.78709	1.70873	1.79132
2	2.39616	2.29163	2.38155	2.00706	1.90163	2.00886	1.78736	1.70759	1.79267
3	2.39589	2.29059	2.38019	2.00709	1.90105	2.00902	1.78746	1.70716	1.79316

the boundary conditions (14) and (15). In Table 5, the effective circumferential stress is reported for the spherical structure mentioned above. The results have similar behavior for the three methods and the same values of the parameter x.

It can be seem that the results presented in Tables 3–5 for the linear spring model, coincide with the values obtained with model where the imperfect contact condition is idealized by a thin interphase between the layers of the composite, i.e. a three phase composite as it is given in [21].

7. Conclusions

In this paper three different approaches are used to study the elastic properties of a spherical shell composite. The two-scale Asymptotic Homogenization Method is used to obtain the general expression of the local problems and the effective coefficients of elastic composites with imperfect contact at the interface. The expression of such effective coefficients is given in (12). The results are compared for different cases of imperfections and the limit case reported in [14] for perfect contact is derived, considering a particular composite. The methodology for spherical shell composites with imperfect contact at the interface is implemented. The local problems for this structure are solved analytically and via FEM. The solution of local functions are used to compute the effective coefficients, and a good coincidence between AHM and FEM is appreciated. Moreover, a third method considering the spherical assemblage model (SAM) is proposed and the general expression for the elastic properties of a spherical structure with imperfect contact at the interface is derived. The general expression, via SAM, of the displacement, radial and circumferential stresses for the spherical structure are given in the Eqs. (45)–(47). Comparison of the effective displacement, radial and circumferential stresses obtained via AHM, FEM and SAM show good results.

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