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A breakdown of injectivity for weighted ray transforms in multidimensions

F.O. Goncharov* R. G. Novikov*[†]

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Abstract

We consider weighted ray-transforms P_W (weighted Radon transforms along straight lines) in \mathbb{R}^d , $d \geq 2$, with strictly positive weights W . We construct an example of such a transform with non-trivial kernel in the space of infinitely smooth compactly supported functions on \mathbb{R}^d . In addition, the constructed weight W is rotation-invariant continuous and is infinitely smooth almost everywhere on $\mathbb{R}^d \times \mathbb{S}^{d-1}$. In particular, by this construction we give counterexamples to some well-known injectivity results for weighted ray transforms for the case when the regularity of W is slightly relaxed. We also give examples of continuous strictly positive W such that $\dim \ker P_W \geq n$ in the space of infinitely smooth compactly supported functions on \mathbb{R}^d for arbitrary $n \in \mathbb{N} \cup \{\infty\}$, where W are infinitely smooth for $d = 2$ and infinitely smooth almost everywhere for $d \geq 3$.

Keywords: Radon transforms, ray transforms, integral geometry, injectivity, non-injectivity

AMS Mathematics Subject Classification: 44A12, 53C65, 65R32

1 Introduction

We consider the weighted ray transforms P_W defined by

$$P_W f(x, \theta) = \int_{\mathbb{R}} W(x + t\theta, \theta) f(x + t\theta) dt, \quad (x, \theta) \in T\mathbb{S}^{d-1}, \quad d \geq 2, \quad (1.1)$$

$$T\mathbb{S}^{d-1} = \{(x, \theta) \in \mathbb{R}^d \times \mathbb{S}^{d-1} : x\theta = 0\}, \quad (1.2)$$

where $f = f(x)$, $W = W(x, \theta)$, $x \in \mathbb{R}^d$, $\theta \in \mathbb{S}^{d-1}$. Here, W is the weight, f is a test function on \mathbb{R}^d . In addition, we interpret $T\mathbb{S}^{d-1}$ as the set of all rays in \mathbb{R}^d . As a ray γ we understand a straight line with fixed orientation. If $\gamma = \gamma(x, \theta)$, $(x, \theta) \in T\mathbb{S}^{d-1}$, then

$$\gamma(x, \theta) = \{y \in \mathbb{R}^d : y = x + t\theta, t \in \mathbb{R}\} \text{ (up to orientation),} \quad (1.3)$$

where θ gives the orientation of γ .

We assume that

$$W = \overline{W} \geq c > 0, \quad W \in L^\infty(\mathbb{R}^d \times \mathbb{S}^{d-1}), \quad (1.4)$$

where \overline{W} denotes the complex conjugate of W , c is a constant.

Note also that

$$P_W f(x, \theta) = \int_{\gamma} W(x, \gamma) f(x) dx, \quad \gamma = \gamma(x, \theta), \quad (1.5)$$

where

$$W(x, \gamma) = W(x, \theta) \text{ for } x \in \gamma, \quad \gamma = \gamma(x, \theta), \quad (x, \theta) \in T\mathbb{S}^{d-1}. \quad (1.6)$$

The aforementioned transforms P_W arise in various domains of pure and applied mathematics; see, e.g., [Bey84], [Bom93], [BQ87], [BQ93], [Fi86], [Jollm16], [Kun92], [LB73], [MQ85], [Natt01], [Nov02], [Nov14], [Sh94], [Qui83] and references therein.

In particular, the related results are the most developed for the case when $W \equiv 1$. In this case P_W is reduced to the classical ray-transform P (Radon transform along straight lines). The transform P arises, in

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particular, in the X-ray transmission tomography. We refer to [GG82], [Natt01] and references therein in connection with basic results for this classical case.

At present, many important results on transforms P_W with other weights W satisfying (1.4) are also known; see the publications mentioned above with non-constant W and references therein.

In particular, assuming (1.4) we have the following injectivity results.

Injectivity 1 (see [Fi86]). Suppose that $d \geq 3$ and $W \in C^2(\mathbb{R}^d \times \mathbb{S}^{d-1})$. Then P_W is injective on $L_0^p(\mathbb{R}^d)$ for $p > 2$, where L_0^p denotes compactly supported functions from L^p .

Injectivity 2 (see [MQ85]). Suppose that $d = 2$, $W \in C^2(\mathbb{R}^2 \times \mathbb{S}^1)$ and

$$0 < c_0 \leq W, \|W\|_{C^2(\mathbb{R}^2 \times \mathbb{S}^1)} \leq N, \quad (1.7)$$

for some constants c_0 and N . Then, for any $p > 2$, there is $\delta = \delta(c_0, N, p) > 0$ such that P_W is injective on $L^p(B(x_0, \delta))$ for any $x_0 \in \mathbb{R}^2$, where

$$\begin{aligned} L^p(B(x_0, \delta)) &= \{f \in L^p(\mathbb{R}^2) : \text{supp } f \subset \overline{B}(x_0, \delta)\}, \\ \overline{B}(x_0, \delta) &= \{x \in \mathbb{R}^2 : |x - x_0| \leq \delta\}. \end{aligned}$$

Injectivity 3 (see [Qui83]). Suppose that $d = 2$, $W \in C^1(\mathbb{R}^2 \times \mathbb{S}^1)$ and W is rotation invariant (see formula (2.18) below). Then P_W is injective on $L_0^p(\mathbb{R}^2)$ for $p \geq 2$.

In a similar way with [Qui83], we say that W is rotation invariant if and only if

$$\begin{aligned} W(x, \gamma) &\text{ is independent of the orientation of } \gamma, \\ W(x, \gamma) &= W(Ax, A\gamma) \text{ for } x \in \gamma, \gamma \in T\mathbb{S}^{d-1}, A \in O(d), \end{aligned} \quad (1.8)$$

where $T\mathbb{S}^{d-1}$ is defined in (1.2), $O(d)$ denotes the group of orthogonal transformations of \mathbb{R}^d .

Note also that property (1.8) can be rewritten in the form (2.18), (2.19) or (2.20), (2.21); see Section 2.

Injectivity 4 (see [BQ87]). Suppose that $d = 2$, W is real-analytic on $\mathbb{R}^2 \times \mathbb{S}^1$. Then P_W is injective on $L_0^p(\mathbb{R}^2)$ for $p \geq 2$.

Injectivity 1 is a global injectivity for $d \geq 3$. Injectivity 2 is a local injectivity for $d = 2$. Injectivity 3 is a global injectivity for $d = 2$ for the rotation invariant case. Injectivity 4 is a global injectivity for $d = 2$ for the real-analytic case.

The results of Injectivity 1 and Injectivity 2 remain valid with C^α , $\alpha > 1$, in place of C^2 in the assumptions on W ; see [JoIlm16].

Injectivity 1 follows from Injectivity 2 in the framework of the layer-by-layer reconstruction approach. See [Fi86], [Novi02], [JoIlm16] and references therein in connection with the layer-by-layer reconstruction approach for weighted and non-abelian ray transforms in dimension $d \geq 3$.

The work [Bom93] gives a counterexample to Injectivity 4 for P_W in $C_0^\infty(\mathbb{R}^2)$ for the case when the assumption that W is real-analytic is relaxed to the assumption that W is infinitely smooth, where C_0^∞ denotes infinitely smooth compactly supported functions.

In somewhat similar way with [Bom93], in the present work we obtain counterexamples to Injectivity 1, Injectivity 2 and Injectivity 3 for the case when the regularity of W is slightly relaxed. In particular, by these counterexamples we continue related studies of [MQ85], [Bom93] and [GN17].

More precisely, in the present work we construct W and f such that

$$P_W f \equiv 0 \text{ on } T\mathbb{S}^{d-1}, d \geq 2, \quad (1.9)$$

where W satisfies (1.4), W is rotation-invariant (i.e., satisfies (1.8)),

$$W \text{ is infinitely smooth almost everywhere on } \mathbb{R}^d \times \mathbb{S}^{d-1} \text{ and} \quad (1.10)$$

$$W \in C^\alpha(\mathbb{R}^d \times \mathbb{S}^{d-1}), \text{ at least, for any } \alpha \in (0, \alpha_0), \text{ where } \alpha_0 = 1/16;$$

$$f \text{ is a non-zero spherically symmetric infinitely smooth compactly supported function on } \mathbb{R}^d; \quad (1.11)$$

see Theorem 1 of Section 3.

These W and f directly give the aforementioned counterexamples to Injectivity 1 and Injectivity 3.

Our counterexample to Injectivity 1 is of particular interest (and is rather surprising) in view of the fact that the problem of finding f on \mathbb{R}^d from $P_W f$ on $T\mathbb{S}^{d-1}$ is strongly overdetermined for $d \geq 3$. Indeed,

$$\begin{aligned} \dim \mathbb{R}^d &= d, \dim T\mathbb{S}^{d-1} = 2d - 2, \\ d &< 2d - 2 \text{ for } d \geq 3. \end{aligned}$$

Our counterexample to Injectivity 3 is considerably stronger than the preceding counterexample of [MQ85], where W is not yet continuous and is not yet strictly positive (i.e., is not yet separated from zero by a positive constant).

Using our W and f of (1.10), (1.11) for $d = 3$ we also obtain the aforementioned counterexample to Injectivity 2; see Corollary 1 of Section 3.

Finally, in the present work we also give examples of W satisfying (1.4) such that $\dim \ker P_W \geq n$ in $C_0^\infty(\mathbb{R}^d)$ for arbitrary $n \in \mathbb{N} \cup \{\infty\}$, where $W \in C^\infty(\mathbb{R}^2 \times \mathbb{S}^1)$ for $d = 2$ and W satisfy (1.10) for $d \geq 3$; see Theorem 2 of Section 3. To our knowledge, examples of W satisfying (1.4), where $\dim \ker P_W \geq n$ (for example in $L_0^2(\mathbb{R}^d)$) were not yet given in the literature even for $n = 1$ in dimension $d \geq 3$ and even for $n = 2$ in dimension $d = 2$.

In the present work we adopt and develop considerations of the famous work [Bom93] and of our very recent work [GN17].

In Section 2 we give some preliminaries and notations.

Main results are presented in detail in Sections 3.

Related proofs are given in Sections 4-9.

2 Some preliminaries

Notations. Let

$$\Omega = \mathbb{R}^d \times \mathbb{S}^{d-1}, \quad (2.1)$$

$$r(x, \theta) = |x - (x\theta)\theta|, \quad (x, \theta) \in \Omega, \quad (2.2)$$

$$\Omega_0(\delta) = \{(x, \theta) \in \Omega : r(x, \theta) > \delta\}, \quad (2.3)$$

$$\Omega_1(\delta) = \Omega \setminus \Omega_0(\delta) = \{(x, \theta) \in \Omega : r(x, \theta) \leq \delta\}, \quad \delta > 0, \quad (2.4)$$

$$\Omega(\Lambda) = \{(x, \theta) \in \mathbb{R}^d \times \mathbb{S}^{d-1} : r(x, \theta) \in \Lambda\}, \quad \Lambda \subset [0, +\infty), \quad (2.5)$$

$$T_0(\delta) = \{(x, \theta) \in T\mathbb{S}^{d-1} : |x| > \delta\}, \quad (2.6)$$

$$T_1(\delta) = \{(x, \theta) \in T\mathbb{S}^{d-1} : |x| \leq \delta\}, \quad \delta > 0, \quad (2.7)$$

$$T(\Lambda) = \{(x, \theta) \in T\mathbb{S}^{d-1} : |x| \in \Lambda\}, \quad \Lambda \subset [0, +\infty), \quad (2.8)$$

$$\mathcal{J}_{r,\varepsilon} = (r - \varepsilon, r + \varepsilon) \cap [0, +\infty), \quad r \in [0, +\infty), \quad \varepsilon > 0. \quad (2.9)$$

The set $T_0(\delta)$ in (2.6) is considered as the set of all rays in \mathbb{R}^d which are located at distance greater than δ from the origin.

The set $T_1(\delta)$ in (2.7) is considered as the set of all rays in \mathbb{R}^d which are located at distance less or equal than δ .

We also consider the projection

$$\pi : \Omega \rightarrow T\mathbb{S}^{d-1}, \quad (2.10)$$

$$\pi(x, \theta) = (\pi_\theta x, \theta), \quad (x, \theta) \in \Omega, \quad (2.11)$$

$$\pi_\theta x = x - (x\theta)\theta. \quad (2.12)$$

In addition, $r(x, \theta)$ of (2.2) is the distance from the origin $\{0\} \in \mathbb{R}^d$ to the ray $\gamma = \gamma(\pi(x, \theta))$ (i.e., $r(x, \theta) = |\pi_\theta x|$). The rays will be also denoted by

$$\gamma = \gamma(x, \theta) \stackrel{def}{=} \gamma(\pi(x, \theta)), \quad (x, \theta) \in \Omega. \quad (2.13)$$

We also consider

$$P_W f(x, \theta) = P_W f(\pi(x, \theta)) \text{ for } (x, \theta) \in \Omega. \quad (2.14)$$

We also define

$$B(x_0, \delta) = \{x \in \mathbb{R}^d : |x - x_0| < \delta\}, \quad \overline{B}(x_0, \delta) = \{x \in \mathbb{R}^d : |x - x_0| \leq \delta\}, \quad x_0 \in \mathbb{R}^d, \quad \delta > 0, \quad (2.15)$$

$$B = B(0, 1), \quad \overline{B} = \overline{B}(0, 1). \quad (2.16)$$

For a function f on \mathbb{R}^d we denote its restriction to a subset $\Sigma \subset \mathbb{R}^d$ by $f|_\Sigma$.

By C_0 , C_0^∞ we denote continuous compactly supported and infinitely smooth compactly supported functions, respectively.

By $C^\alpha(Y)$, $\alpha \in (0, 1)$, we denote the space of α -Hölder functions on Y with the norm:

$$\begin{aligned} \|u\|_{C^\alpha(Y)} &= \|u\|_{C(Y)} + \|u\|'_{C^\alpha(Y)}, \\ \|u\|'_{C^\alpha(Y)} &= \sup_{\substack{y_1, y_2 \in Y \\ |y_1 - y_2| \leq 1}} \frac{|u(y_1) - u(y_2)|}{|y_1 - y_2|^\alpha}, \end{aligned} \quad (2.17)$$

where $\|u\|_{C(Y)}$ denotes the maximum of $|u|$ on Y .

Rotation invariancy. Using formula (1.6), for positive and continuous W , property (1.8) can be rewritten in the following equivalent form:

$$W(x, \theta) = U(|x - (x\theta)\theta|, x\theta), \quad x \in \mathbb{R}^d, \quad \theta \in \mathbb{S}^{d-1}, \quad (2.18)$$

for some positive and continuous U such that

$$U(r, s) = U(-r, s) = U(r, -s), \quad r \in \mathbb{R}, \quad s \in \mathbb{R}. \quad (2.19)$$

In addition, symmetries (2.18), (2.19) of W can be also written as

$$W(x, \theta) = \tilde{U}(|x|, x\theta), \quad (x, \theta) \in \Omega, \quad (2.20)$$

$$\tilde{U}(r, s) = \tilde{U}(-r, s) = \tilde{U}(r, -s), \quad r \in \mathbb{R}, \quad s \in \mathbb{R}. \quad (2.21)$$

where \tilde{U} is positive and continuous on $\mathbb{R} \times \mathbb{R}$. Using the formula $|x|^2 = |x\theta|^2 + r^2(x, \theta)$, one can see that symmetries (2.18), (2.19) and symmetries (2.20), (2.21) of W are equivalent.

Partition of unity. We recall the following classical result (see, e.g., Theorem 5.6 in [MCar92]):
Let \mathcal{M} be a C^∞ -manifold, which is Hausdorff and has a countable base. Let also $\{U_i\}_{i=1}^\infty$ be an open locally-finite cover of \mathcal{M} .

Then there exists a C^∞ -smooth locally-finite partition of unity $\{\psi_i\}_{i=1}^\infty$ on \mathcal{M} , such that

$$\text{supp } \psi_i \subset U_i. \quad (2.22)$$

In particular, any open interval $(a, b) \subset \mathbb{R}$ and Ω satisfy the conditions for \mathcal{M} of this statement. It will be used in Subsection 3.1.

3 Main results

Theorem 1. *There exist a weight W satisfying (1.4) and a non-zero function $f \in C_0^\infty(\mathbb{R}^d)$, $d \geq 2$, such that*

$$P_W f \equiv 0 \text{ on } T\mathbb{S}^{d-1}, \quad (3.1)$$

where P_W is defined in (1.1). In addition, W is rotation invariant, i.e., satisfies (2.18), and f is spherically symmetric with $\text{supp } f \subseteq \overline{B}$. Moreover,

$$W \in C^\infty(\Omega \setminus \Omega(1)), \quad (3.2)$$

$$W \in C^\alpha(\mathbb{R}^d \times \mathbb{S}^{d-1}) \text{ for any } \alpha \in (0, \alpha_0), \quad \alpha_0 = 1/16, \quad (3.3)$$

$$W \geq 1/2 \text{ on } \Omega \text{ and } W \equiv 1 \text{ on } \Omega([1, +\infty)), \quad (3.4)$$

$$W(x, \theta) \equiv 1 \text{ for } |x| \geq R > 1, \quad \theta \in \mathbb{S}^{d-1}, \quad (3.5)$$

where Ω , $\Omega(1)$, $\Omega([1, +\infty))$ are defined by (2.1), (2.5), R is a constant.

The construction of W and f proving Theorem 1 is presented below in Subsections 3.1, 3.2. In addition, this construction consists of its version in dimension $d = 2$ (see Subsection 3.1) and its subsequent extension to the case of $d \geq 3$ (see Subsection 3.2).

Theorem 1 directly gives counterexamples to Injectivity 1 and Injectivity 3 of Introduction. Theorem 1 also implies the following counterexample to Injectivity 2 of Introduction:

Corollary 1. *For any $\alpha \in (0, 1/16)$ there is $N > 0$ such that for any $\delta > 0$ there are W_δ, f_δ satisfying*

$$W_\delta \geq 1/2, \quad W_\delta \in C^\alpha(\mathbb{R}^2 \times \mathbb{S}^1), \quad \|W\|_{C^\alpha(\mathbb{R}^2 \times \mathbb{S}^1)} \leq N \quad (3.6)$$

$$f_\delta \in C^\infty(\mathbb{R}^2), \quad f_\delta \not\equiv 0, \quad \text{supp } f_\delta \subseteq \overline{B}(0, \delta), \quad (3.7)$$

$$P_{W_\delta} f_\delta \equiv 0 \text{ on } T\mathbb{S}^1. \quad (3.8)$$

The construction of W_δ, f_δ proving Corollary 1 is presented in Subsection 5.1.

Theorem 2. *For any $n \in \mathbb{N} \cup \{\infty\}$ there exists a weight W_n satisfying (1.4) such that*

$$\dim \ker P_{W_n} \geq n \text{ in } C_0^\infty(\mathbb{R}^d), \quad d \geq 2, \quad (3.9)$$

where P_W is defined in (1.1). Moreover,

$$W_n \in C^\infty(\mathbb{R}^2 \times \mathbb{S}^1) \text{ for } d = 2, \quad (3.10)$$

$$W_n \text{ is infinitely smooth almost everywhere on } \mathbb{R}^d \times \mathbb{S}^{d-1} \text{ and} \quad (3.11)$$

$$W_n \in C^\alpha(\mathbb{R}^d \times \mathbb{S}^{d-1}), \quad \alpha \in (0, 1/16) \text{ for } d \geq 3,$$

$$W_n(x, \theta) \equiv 1 \text{ for } |x| \geq R > 1, \quad \theta \in \mathbb{S}^{d-1} \text{ for } n \in \mathbb{N}, \quad d \geq 2, \quad (3.12)$$

where R is a constant.

The construction of W_n proving Theorem 2 is presented in Section 4. In this construction we proceed from Theorem 1 of the present work for $d \geq 3$ and from the result of [Bom93] for $d = 2$. In addition, for this construction it is essential that $n < +\infty$ in (3.12).

3.1 Construction of f and W for $d = 2$

In dimension $d = 2$, the construction of f and W adopts and develops considerations of [Bom93] and [GN17]. In particular, we construct f , first, and then W (in this construction we use notations of Section 2 for $d = 2$). In addition, this construction is commented in Remarks 1-5 below.

Construction of f . The function f is constructed as follows:

$$f = \sum_{k=1}^{\infty} \frac{f_k}{k!}, \quad (3.13)$$

$$f_k(x) = \tilde{f}_k(|x|) = \Phi(2^k(1 - |x|)) \cos(8^k|x|^2), x \in \mathbb{R}^2, k \in \mathbb{N}, \quad (3.14)$$

for arbitrary $\Phi \in C^\infty(\mathbb{R})$ such that

$$\text{supp } \Phi = [4/5, 6/5], \quad (3.15)$$

$$0 < \Phi(t) \leq 1 \text{ for } t \in (4/5, 6/5), \quad (3.16)$$

$$\Phi(t) = 1, \text{ for } t \in [9/10, 11/10], \quad (3.17)$$

$$\begin{aligned} \Phi \text{ monotonously increases on } [4/5, 9/10] \\ \text{and monotonously decreases on } [11/10, 6/5]. \end{aligned} \quad (3.18)$$

Properties (3.15), (3.16) imply that functions \tilde{f}_k (and functions f_k) in (3.14) have disjoint supports:

$$\begin{aligned} \text{supp } \tilde{f}_i \cap \text{supp } \tilde{f}_j &= \emptyset \text{ if } i \neq j, \\ \text{supp } \tilde{f}_k &= [1 - 2^{-k}, 1 - 2^{-k} \left(\frac{6}{5}\right)], 1 - 2^{-k} \left(\frac{4}{5}\right)], i, j, k \in \mathbb{N}. \end{aligned} \quad (3.19)$$

This implies the convergence of series in (3.13) for every fixed $x \in \mathbb{R}^2$.

Lemma 1. *Let f be defined by (3.13)-(3.17). Then f is spherically symmetric, $f \in C_0^\infty(\mathbb{R}^2)$ and $\text{supp } f \subseteq \overline{B}$. In addition, if $\gamma \in T\mathbb{S}^1$, $\gamma \cap B \neq \emptyset$, then $f|_\gamma \not\equiv 0$ and $f|_\gamma$ has non-constant sign.*

Lemma 1 is similar to Lemma 1 of [GN17] and it is, actually, proved in Section 4.1 of [GN17].

Remark 1. Formulas (3.13)-(3.17) for f are similar to the formulas for f in [Bom93], where P_W was considered in \mathbb{R}^2 , and also to the formulas for f in [GN17], where the weighted Radon transform R_W along hyperplanes was considered in \mathbb{R}^3 . The only difference between (3.13)-(3.17) and the related formulas in [GN17] is the dimension $d = 2$ in (3.13)-(3.17) instead of $d = 3$ in [GN17]. At the same time, the important difference between (3.13)-(3.17) and the related formulas in [Bom93] is that in formula (3.14) the factor $\cos(8^k|x|^2)$ depends only on $|x|$, whereas in [Bom93] the corresponding factor is $\cos(3^k\phi)$ which depends only on the angle ϕ in the polar coordinates in \mathbb{R}^2 . In a similar way with [Bom93], [GN17], we use the property that the restriction of the function $\cos(8^k|x|^2)$ to an arbitrary ray γ intersecting the open ball oscillates sufficiently fast (with change of the sign) for large k .

Construction of W . In our example W is of the following form:

$$\begin{aligned} W(x, \theta) &= \phi_1(x) \left(\sum_{i=0}^N \xi_i(r(x, \theta)) W_i(x, \theta) \right) + \phi_2(x) \\ &= \phi_1(x) \left(\xi_0(r(x, \theta)) W_0(x, \theta) + \sum_{i=1}^N \xi_i(r(x, \theta)) W_i(x, \theta) \right) + \phi_2(x), (x, \theta) \in \Omega, \end{aligned} \quad (3.20)$$

where

$$\begin{aligned} \phi_1 = \phi_1(|x|), \phi_2 = \phi_2(|x|) \text{ is a } C^\infty\text{-smooth partition of unity on } \mathbb{R}^2 \text{ such that,} \\ \phi_1 \equiv 0 \text{ for } |x| \geq R > 1, \phi_1 \equiv 1 \text{ for } |x| \leq 1, \end{aligned} \quad (3.21)$$

$$\begin{aligned} \phi_2 \equiv 0 \text{ for } |x| \leq 1, \\ \{\xi_i(s), s \in \mathbb{R}\}_{i=0}^N \text{ is a } C^\infty\text{-smooth partition of unity on } \mathbb{R}, \end{aligned} \quad (3.22)$$

$$\xi_i(s) = \xi_i(-s), s \in \mathbb{R}, i = \overline{0, N}, \quad (3.23)$$

$$\begin{aligned} W_i(x, \theta) \text{ are bounded, continuous, strictly positive and rotation invariant} \\ \text{(according to (2.18)), (2.21) on the open vicinities of } \text{supp } \xi_i(r(x, \theta)), i = \overline{0, N}, \text{ respectively.} \end{aligned} \quad (3.24)$$

From the result of Lemma 1 and from (3.21) it follows that

$$P_W f(x, \theta) = \xi_0(|x|) P_{W_0} f(x, \theta) + \sum_{i=1}^N \xi_i(|x|) P_{W_i} f(x, \theta), (x, \theta) \in T\mathbb{S}^1, \quad (3.25)$$

where W is given by (3.20).

From (3.20)-(3.24) it follows that W of (3.20) satisfies the conditions (1.4), (2.20), (2.21).

The weight W_0 is constructed in next paragraph and has the following properties:

$$W_0 \text{ is bounded, continuous and rotation invariant on } \Omega(1/2, +\infty), \quad (3.26)$$

$$W_0 \in C^\infty(\Omega((1/2, 1) \cup (1, +\infty))) \text{ and } W_0 \in C^\alpha(\Omega(1/2, +\infty)) \text{ for } \alpha \in (0, 1/16), \quad (3.27)$$

there exists $\delta_0 \in (1/2, 1)$ such that:

$$W_0(x, \theta) \geq 1/2 \text{ if } r(x, \theta) > \delta_0, \quad (3.28)$$

$$W_0(x, \theta) = 1 \text{ if } r(x, \theta) \geq 1,$$

$$P_{W_0}f(x, \theta) = 0 \text{ on } \Omega((1/2, +\infty)), \quad (3.29)$$

where P_{W_0} is defined according to (1.1) for $W = W_0$, f is given by (3.13), (3.14).

In addition,

$$\text{supp } \xi_0 \subset (-\infty, -\delta_0) \cup (\delta_0, +\infty), \quad (3.30)$$

$$\xi_0(s) = 1 \text{ for } |s| \geq 1, \quad (3.31)$$

where δ_0 is the number of (3.28).

In particular, from (3.28), (3.30) it follows that

$$W_0(x, \theta)\xi_0(r(x, \theta)) > 0 \text{ if } \xi_0(r(x, \theta)) > 0. \quad (3.32)$$

In addition,

$$\xi_i(r(x, \theta))W_i(x, \theta) \text{ are bounded, rotation invariant and } C^\infty \text{ on } \Omega, \quad (3.33)$$

$$W_i(x, \theta) \geq 1/2 \text{ if } \xi_i(r(x, \theta)) \neq 0, \quad (3.34)$$

$$P_{W_i}f(x, \theta) = 0 \text{ on } (x, \theta) \in T\mathbb{S}^1, \text{ such that } \xi_i(r(x, \theta)) \neq 0, \quad (3.35)$$

$$i = \overline{1, N}, (x, \theta) \in \Omega.$$

Weights W_1, \dots, W_N of (3.20) and $\{\xi_i\}_{i=0}^N$ are constructed in Subsection 3.1.

Theorem 1 for $d = 2$ follows from Lemma 1 and formulas (3.20)-(3.29), (3.32)-(3.35).

We point out that the construction of W_0 of (3.20) is substantially different from the construction of W_1, \dots, W_N . The weight W_0 is defined for the rays $\gamma \in T\mathbb{S}^1$ which can be close to the boundary ∂B of B which results in restrictions on global smoothness of W_0 .

Remark 2. The construction of W summarized above in formulas (3.20)-(3.35) arises in the framework of finding W such that

$$P_W f \equiv 0 \text{ on } T\mathbb{S}^1 \text{ for } f \text{ defined in (3.13)-(3.18)}, \quad (3.36)$$

under the condition that W is strictly positive, sufficiently regular and rotation invariant (see formulas (1.4), (2.18), (2.19)). In addition, the weights W_i , $i = 0, \dots, N$, in (3.20) are constructed in a such a way that

$$P_{W_i}f = 0 \text{ on } V_i, i = 0, \dots, N, \quad (3.37)$$

under the condition that $W_i = W_i(x, \gamma)$ are strictly positive, sufficiently regular and rotation invariant for $x \in \gamma$, $\gamma \in V_i$, $i = 0, \dots, N$, where

$$\{V_i\}_{i=0}^N \text{ is an open cover of } T\mathbb{S}^1 \text{ and } V_0 = T_0(\delta_0), \quad (3.38)$$

$$V_i = T(\Lambda_i) \text{ for some open } \Lambda_i \subset \mathbb{R}, i = 0, \dots, N, \quad (3.39)$$

where T_0 is defined in (2.6), δ_0 is the number of (3.28), $T(\Lambda)$ is defined in (2.8). In addition, the functions ξ_i , $i = 0, \dots, N$, in (3.20) can be interpreted as a partition of unity on $T\mathbb{S}^1$ subordinated to the open cover $\{V_i\}_{i=0}^N$. The aforementioned construction of W is a two-dimensional analog of the construction developed in [GN17], where the weighted Radon transform R_W along hyperplanes was considered in \mathbb{R}^3 . At the same time, the construction of W of the present work is similar to the construction in [Bom93] with the important difference that in the present work f is spherically symmetric and W , W_i , $i = 0, \dots, N$, are rotation invariant.

Construction of W_0 . Let

$$\{\psi_k\}_{k=1}^\infty \text{ be a } C^\infty \text{ partition of unity on } (1/2, 1), \text{ such that } \text{supp } \psi_k \subset (1 - 2^{-k+1}, 1 - 2^{-k-1}), k \in \mathbb{N}, \quad (3.40)$$

$$\text{first derivatives } \psi'_k \text{ satisfy the bounds: } \sup |\psi'_k| \leq C2^k, \quad (3.41)$$

where C is a positive constant. Actually, functions $\{\psi_k\}_{k=1}^\infty$ satisfying (3.40), (3.41) were used in considerations of [Bom93].

Note that

$$1 - 2^{-(k-2)-1} < 1 - 2^{-k}(6/5), k \geq 3. \quad (3.42)$$

Therefore,

$$\text{for all } s_0, t_0 \in \mathbb{R}, s_0 \in \text{supp } \psi_{k-2}, t_0 \in \text{supp } \Phi(2^k(1-t)) \Rightarrow s_0 < t_0, k \geq 3. \quad (3.43)$$

Weight W_0 is defined by the following formulas

$$W_0(x, \theta) = \begin{cases} 1 - G(x, \theta) \sum_{k=3}^{\infty} k! f_k(x) \frac{\psi_{k-2}(r(x, \theta))}{H_k(x, \theta)}, & 1/2 < r(x, \theta) < 1, \\ 1, & r(x, \theta) \geq 1 \end{cases}, \quad (3.44)$$

$$G(x, \theta) = \int_{\gamma(x, \theta)} f(y) dy, \quad H_k(x, \theta) = \int_{\gamma(x, \theta)} f_k^2(y) dy, \quad x \in \mathbb{R}^2, \theta \in \mathbb{S}^1, \quad (3.45)$$

where f, f_k are defined in (3.13), (3.14), respectively, rays $\gamma(x, \theta)$ are given by (2.13).

Formula (3.44) implies that W_0 is defined on $\Omega_0(1/2) \subset \Omega$.

Due to (3.14)-(3.17), (3.40), (3.43), in (3.45) we have that

$$H_k(x, \theta) \neq 0 \text{ if } \psi_{k-2}(r(x, \theta)) \neq 0, (x, \theta) \in \Omega, \quad (3.46)$$

$$\frac{\psi_{k-2}(r(x, \theta))}{H_k(x, \theta)} \in C^\infty(\Omega(1/2, 1)), \quad (3.47)$$

where $r(x, \theta)$ is defined in (2.2), $\Omega, \Omega(\cdot)$ are defined in (2.1), (2.5), $d = 2$.

Also, for any fixed $(x, \theta) \in \Omega, 1/2 < r(x, \theta)$, the series in the right hand-side of (3.44) has only a finite number of non-zero terms (in fact, no more than two) and, hence, the weight W_0 is well-defined.

By the spherical symmetry of f , functions G, H_k in (3.44) are of the type (2.18) (and (2.20)). Therefore, W_0 is rotation invariant (in the sense of (2.18) and (2.20)).

Actually, formula (3.29) follows from (3.13), (3.14), (3.44), (3.45) (see Subsection 6.2 for details).

Using the construction of W_0 and the assumption that $r(x, \theta) > 1/2$ one can see that W_0 is C^∞ on its domain of definition, possibly, except points with $r(x, \theta) = 1$.

Note also that due to (3.13), (3.14), the functions f_k, G, H_k , used in (3.44), (3.45) can be considered as functions of one-dimensional arguments.

Formulas (3.26)-(3.28) are proved in Subsection 6.1.

Remark 3. Formulas (3.44), (3.45) given above for the weight W_0 are considered for the rays from $T_0(\delta_0)$ (mentioned in Remark 2) and, in particular, for rays close to the tangent rays to ∂B . These formulas are direct two-dimensional analogs of the related formulas in [GN17]. At the same time, formulas (3.44), (3.45) are similar to the related formulas in [Bom93] with the important difference that f, f_k are spherically symmetric in the present work and, as a corollary, W_0 is rotation invariant. Also, in a similar way with [Bom93], [GN17], in the present work we show that $G(x, \theta)$ tends to zero sufficiently fast as $r(x, \theta) \rightarrow 1$. This is a very essential point for continuity of W_0 and it is given in Lemma 3 of Subsection 6.1.

Construction of W_1, \dots, W_N and ξ_0, \dots, ξ_N

Lemma 2. *Let $f \in C_0^\infty(\mathbb{R}^2)$ be spherically symmetric, $(x_0, \theta_0) \in T\mathbb{S}^1, f|_{\gamma(x_0, \theta_0)} \neq 0$ and $f|_{\gamma(x_0, \theta_0)}$ changes the sign. Then there exist $\varepsilon_0 > 0$ and weight $W_{(x_0, \theta_0), \varepsilon_0}$ such that*

$$P_{W_{(x_0, \theta_0), \varepsilon_0}} f = 0 \text{ on } \Omega(\mathcal{J}_{r(x_0, \theta_0), \varepsilon_0}), \quad (3.48)$$

$$\begin{aligned} W_{(x_0, \theta_0), \varepsilon_0} &\text{ is bounded, infinitely smooth,} \\ &\text{strictly positive and rotation invariant on } \Omega(\mathcal{J}_{r(x_0, \theta_0), \varepsilon_0}), \end{aligned} \quad (3.49)$$

where $\Omega(\mathcal{J}_{r, \varepsilon_0}), \mathcal{J}_{r, \varepsilon_0}$ are defined in (2.5) and (2.9), respectively.

Lemma 2 is proved in Section 7. This lemma is a two-dimensional analog of the related lemma in [GN17].

Remark 4. In Lemma 2 the construction of $W_{(x_0, \theta_0), \varepsilon_0}$ arises from

1. finding strictly positive and regular weight $W_{(x_0, \theta_0), \varepsilon}$ on the rays $\gamma = \gamma(x, \theta)$ with fixed $\theta = \theta_0$, where $r(x, \theta_0) \in \mathcal{J}_{r(x_0, \theta_0), \varepsilon}$ for some $\varepsilon > 0$, such that (3.48) holds for $\theta = \theta_0$ and under the condition that

$$W_{(x_0, \theta_0), \varepsilon}(y, \gamma) = W_{(x_0, \theta_0), \varepsilon}(|y\theta_0|, \gamma), \quad y \in \gamma = (x, \theta_0), r(x, \theta_0) \in \mathcal{J}_{r(x_0, \theta_0), \varepsilon}; \quad (3.50)$$

2. extending $W_{r(x_0, \theta_0), \varepsilon}$ to all rays $\gamma = \gamma(x, \theta), r(x, \theta) \in \mathcal{J}_{r(x_0, \theta_0), \varepsilon}, \theta \in \mathbb{S}^1$, via formula (1.8).

We recall that $r(x, \theta)$ is defined in (2.2).

Let f be the function of (3.13), (3.14). Then, using Lemmas 1, 2 one can see that

$$\begin{aligned} \forall \delta \in (0, 1) \text{ there exist } \{J_i = \mathcal{J}_{r_i, \varepsilon_i}, W_i = W_{(x_i, \theta_i), \varepsilon_i}\}_{i=1}^N \\ \text{such that } J_i, i = \overline{1, N}, \text{ is an open cover of } [0, \delta] \text{ in } \mathbb{R}, \\ \text{and } W_i \text{ satisfy (3.48) and (3.49) on } \Omega(J_i), \text{ respectively.} \end{aligned} \quad (3.51)$$

Actually, we consider (3.51) for the case of $\delta = \delta_0$ of (3.28).

Note that in this case $\{\Omega(J_i)\}_{i=1}^N$ for J_i of (3.51) is the open cover of $\Omega_1(\delta_0)$.

To the set $\Omega_0(\delta_0)$ we associate the open set

$$J_0 = (\delta_0, +\infty) \subset \mathbb{R}. \quad (3.52)$$

Therefore, the collection of intervals $\{\pm J_i, i = \overline{0, N}\}$ is an open cover of \mathbb{R} , where $-J_i$ is the symmetrical reflection of J_i with respect to $\{0\} \in \mathbb{R}$.

We construct the partition of unity $\{\xi_i\}_{i=0}^N$ as follows:

$$\xi_i(s) = \xi_i(|s|) = \frac{1}{2}(\tilde{\xi}_i(s) + \tilde{\xi}_i(-s)), \quad s \in \mathbb{R}, \quad (3.53)$$

$$\text{supp } \xi_i \subset J_i \cup (-J_i), \quad i = \overline{0, N}, \quad (3.54)$$

where $\{\tilde{\xi}_i\}_{i=0}^N$ is a partition of unity for the open cover $\{J_i \cup (-J_i)\}_{i=0}^N$ (see Section 2, Partition of unity, for $U_i = J_i \cup (-J_i)$).

Properties (3.30), (3.54) follow from (2.22) for $\{\tilde{\xi}_i\}_{i=0}^N$ with $U_i = J_i \cup (-J_i)$, the symmetry of $J_i \cup (-J_i)$, $i = \overline{1, N}$, choice of J_0 in (3.52) and from (3.53).

In turn, (3.31) follows from (3.52) and the construction of J_i , $i = \overline{1, N}$, from (3.51) (see the proof of Lemma 2 and properties (3.51) in Section 7 for details).

Properties (3.33)-(3.35) follow from (3.51) for $\delta = \delta_0$ and from (3.52)-(3.54).

This completes the description of W_1, \dots, W_N and $\{\xi_i\}_{i=0}^N$.

Remark 5. We have that $J_i = \Lambda_i$, $i = 1, \dots, N$, where Λ_i are the intervals in formula (3.39) of Remark 2 and J_i are the intervals considered in (3.51), (3.52).

3.2 Construction of W and f for $d \geq 3$

Consider f and W of Theorem 1, for $d = 2$, constructed in Subsection 3.1. For these f and W consider \tilde{f} and \tilde{U} such that

$$f(x) = \tilde{f}(|x|), \quad W(x, \theta) = \tilde{U}(|x|, |x\theta|), \quad x \in \mathbb{R}^2, \quad \theta \in \mathbb{S}^1. \quad (3.55)$$

Proposition 1. Let W and f , for $d \geq 3$, be defined as

$$W(x, \theta) = \tilde{U}(|x|, |x\theta|), \quad (x, \theta) \in \mathbb{R}^d \times \mathbb{S}^{d-1}, \quad (3.56)$$

$$f(x) = \tilde{f}(|x|), \quad x \in \mathbb{R}^d, \quad (3.57)$$

where \tilde{U}, \tilde{f} are the functions of (3.55). Then

$$P_W f \equiv 0 \quad \text{on } T\mathbb{S}^{d-1}. \quad (3.58)$$

In addition, weight W satisfies properties (3.2)-(3.5), f is spherically symmetric infinitely smooth and compactly supported on \mathbb{R}^d , $f \neq 0$.

Proposition 1 is proved in Subsection 5.2.

This completes the proof of Theorem 1.

4 Proof of Theorem 2

4.1 Proof for $d \geq 3$

Let

$$W \text{ be the weight of Theorem 1 for } d \geq 3, \quad (4.1)$$

$$R \text{ be the number in (3.5) for } d \geq 3, \quad (4.2)$$

$$\{y_i\}_{i=1}^\infty \text{ be a sequence of vectors in } \mathbb{R}^d \text{ such that } y_1 = 0, |y_i - y_j| > 2R \text{ for } i \neq j, i, j \in \mathbb{N}, \quad (4.3)$$

$$\{\overline{B}_i\}_{i=1}^\infty \text{ be the closed balls in } \mathbb{R}^d \text{ of radius } R \text{ centered at } y_i \text{ (see (4.2), (4.3)).} \quad (4.4)$$

The weight W_n is defined as follows

$$W_n(x, \theta) = \begin{cases} 1 & \text{if } x \notin \bigcup_{i=1}^n \overline{B}_i, \\ W(x - y_1, \theta) & \text{if } x \in \overline{B}_1, \\ W(x - y_2, \theta) & \text{if } x \in \overline{B}_2, \\ \dots & \\ W(x - y_k, \theta) & \text{if } x \in \overline{B}_k, \\ \dots & \\ W(x - y_n, \theta) & \text{if } x \in \overline{B}_n, \end{cases} \quad (4.5)$$

$$\theta \in \mathbb{S}^{d-1}, \quad n \in \mathbb{N} \cup \{\infty\}, \quad d \geq 3,$$

where W is defined in (4.1), y_i and \overline{B}_i are defined in (4.3), (4.4), respectively.

Properties (1.4), (3.11) and (3.12) for W_n , defined in (4.5), for $d \geq 3$, follow from (3.2)-(3.5), (4.1), (4.2).
Let

$$f_1(x) \stackrel{\text{def}}{=} f(x), f_2(x) \stackrel{\text{def}}{=} f(x - y_2), \dots, f_n(x) \stackrel{\text{def}}{=} f(x - y_n), x \in \mathbb{R}^d, d \geq 3, \quad (4.6)$$

where y_i are defined in (4.3) and

$$f \text{ is the function of Theorem 1 for } d \geq 3. \quad (4.7)$$

One can see that

$$f_i \in C_0^\infty(\mathbb{R}^d), d \geq 3, f_i \not\equiv 0, \text{supp } f_i \subset \overline{B}_i, \overline{B}_i \cap \overline{B}_j = \emptyset \text{ for } i \neq j, \quad (4.8)$$

where \overline{B}_i are defined in (4.4), $i = 1, \dots, n$.

The point is that

$$P_{W_n} f_i \equiv 0 \text{ on } T\mathbb{S}^{d-1}, d \geq 3, i = 1, \dots, n, \quad (4.9)$$

$$f_i \text{ are linearly independent in } C_0^\infty(\mathbb{R}^d), d \geq 3, i = 1, \dots, n, \quad (4.10)$$

where W_n is defined in (4.5), f_i are defined in (4.6).

To prove (4.9) we use, in particular, the following general formula:

$$\begin{aligned} P_{W_y} f_y(x, \theta) &= \int_{\gamma(x, \theta)} W(y' - y, \theta) f(y' - y) dy' \\ &= \int_{\gamma(x - y, \theta)} W(y', \theta) f(y') dy' = P_W f(x - y, \theta), x \in \mathbb{R}^d, \theta \in \mathbb{S}^{d-1}, \end{aligned} \quad (4.11)$$

$$W_y(x, \theta) = W(x - y, \theta), f_y = f(x - y), x, y \in \mathbb{R}^d, \theta \in \mathbb{S}^{d-1}. \quad (4.12)$$

where W is an arbitrary weight satisfying (1.4), f is a test-function, $\gamma(x, \theta)$ is defined according to (2.13).

Formula (4.9) follows from formula (3.1), definitions (4.5), (4.6), (4.7), properties (4.8) and from formulas (4.11), (4.12).

Formula (4.10) follows from definitions (4.6), (4.7) and properties (4.8).

This completes the proof of Theorem 2 for $d \geq 3$.

4.2 Proof for $d = 2$

In [Bom93], there were constructed a weight W and a function f for $d = 2$, such that:

$$P_W f \equiv 0 \text{ on } T\mathbb{S}^1, \quad (4.13)$$

$$W = \overline{W} \geq c > 0, W \in C^\infty(\mathbb{R}^2 \times \mathbb{S}^1), \quad (4.14)$$

$$f \in C_0^\infty(\mathbb{R}^2), f \not\equiv 0, \text{supp } f \subset \overline{B}, \quad (4.15)$$

where c is a constant, \overline{B} is defined in (2.15).

We define

$$\widetilde{W}(x, \theta) = c^{-1} \phi_1(x) W(x, \theta) + \phi_2(x), x \in \mathbb{R}^2, \theta \in \mathbb{S}^1, \quad (4.16)$$

where W is the weight of (4.13), (4.14), c is a constant of (4.14).

$$\begin{aligned} \phi_1 = \phi_1(x), \phi_2 = \phi_2(x) \text{ is a } C^\infty\text{-smooth partition of unity on } \mathbb{R}^2 \text{ such that,} \\ \phi_1 \equiv 0 \text{ for } |x| \geq R > 1, \phi_1 \equiv 1 \text{ for } |x| \leq 1, \phi_1 \geq 0 \text{ on } \mathbb{R}^2, \\ \phi_2 \equiv 0 \text{ for } |x| \leq 1, \phi_2 \geq 0 \text{ on } \mathbb{R}^2, \end{aligned} \quad (4.17)$$

where R is a constant.

From (4.13)-(4.17) it follows that

$$P_{\widetilde{W}} f \equiv 0 \text{ on } T\mathbb{S}^1, \quad (4.18)$$

$$\begin{aligned} \widetilde{W} \geq 1, \widetilde{W} \in C^\infty(\mathbb{R}^2 \times \mathbb{S}^1), \\ \widetilde{W}(x, \theta) \equiv 1 \text{ for } |x| \geq R > 1, \theta \in \mathbb{S}^1. \end{aligned} \quad (4.19)$$

The proof of Theorem 2 for $d = 2$ proceeding from (4.15), (4.16), (4.18), (4.19) is completely similar to the proof of Theorem 2 for $d \geq 3$, proceeding from Theorem 1.

Theorem 2 is proved.

5 Proofs of Corollary 1 and Proposition 1

5.1 Proof of Corollary 1

Let

$$X_r = \{x_1 e_1 + x_2 e_2 + r e_3 : (x_1, x_2) \in \mathbb{R}^2\}, \quad 0 \leq r < 1, \quad (5.1)$$

$$S = X_0 \cap \mathbb{S}^2 = \{(\cos \phi, \sin \phi, 0) \in \mathbb{R}^3 : \phi \in [0, 2\pi)\} \simeq \mathbb{S}^1. \quad (5.2)$$

where (e_1, e_2, e_3) is the standard orthonormal basis in \mathbb{R}^3 .

Without loss of generality we assume that $0 < \delta < 1$. Choosing r so that $\sqrt{1 - \delta^2} \leq r < 1$, we have that the intersection of the three dimensional ball $B(0, 1)$ with X_r is the two-dimensional disk $B(0, \delta')$, $\delta' \leq \delta$ (with respect to the coordinates (x_1, x_2) induced by basis (e_1, e_2) on X_r).

We define N , W_δ on $\mathbb{R}^2 \times \mathbb{S}^1$ and f_δ on \mathbb{R}^2 as follows:

$$N = \|W\|_{C^\alpha(\mathbb{R}^3 \times \mathbb{S}^2)}, \quad (5.3)$$

$$W_\delta := W|_{X_r \times S}, \quad (5.4)$$

$$f_\delta := f|_{X_r}, \quad (5.5)$$

$$\text{for } r = \sqrt{1 - \delta^2},$$

where W and f are the functions of Theorem 1 for $d = 3$.

Due to (3.2)-(3.4), (5.3), (5.4) we have that

$$W_\delta \geq 1/2, \quad \|W_\delta\|_{C^\alpha(\mathbb{R}^2 \times \mathbb{S}^1)} \leq N. \quad (5.6)$$

Properties (5.6) imply (3.6).

In view of Lemma 1 for the function f of Theorem 1, we have that f_δ is spherically symmetric, $f_\delta \in C_0^\infty(B(0, \delta'))$, $f_\delta \not\equiv 0$.

Using (3.1), (5.4), (5.5) one can see that (3.8) holds.

This completes the proof of Corollary 1.

5.2 Proof of Proposition 1

Let

$$I(r) = \int_{\gamma_r} \tilde{U}(|y|, r) \tilde{f}(|y|) dy, \quad r \geq 0, \quad \gamma_r = \gamma(re_2, e_1), \quad (5.7)$$

where $\gamma(x, \theta)$ is defined by (1.3), (e_1, \dots, e_d) is the standard basis in \mathbb{R}^d .

Due to formula (3.1) of Theorem 1 for $d = 2$ and formulas (3.55), (5.7) we have that

$$I(r) = P_W f(re_2, e_1) = 0 \text{ for } r \geq 0. \quad (5.8)$$

Next, using (1.1), (3.55), (5.8) we have also that

$$P_W f(x, \theta) = \int_{\gamma(x, \theta)} \tilde{U}(|y|, |y - (y\theta)\theta|) \tilde{f}(|y|) dy = I(|x|) = 0 \text{ for } (x, \theta) \in T\mathbb{S}^{d-1}, \quad (5.9)$$

where $\gamma(x, \theta)$ is defined in (1.3).

Formula (5.9) implies (3.58). Properties of W and f mentioned in Proposition 1 follow from properties (3.2)-(3.5) of W and of f of Theorem 1 for $d = 2$.

This completes the proof of Proposition 1.

6 Proofs of formulas (3.26)-(3.29)

6.1 Proof of formulas (3.26)-(3.28)

Lemma 3. *Let W_0 be defined by (3.44), (3.45). Then W_0 admits the following representation:*

$$W_0(x, \theta) = U_0(x\theta, |x - (x\theta)\theta|), \quad (x, \theta) \in \Omega((1/2, +\infty)), \quad (6.1)$$

$$U_0(s, r) = \begin{cases} 1 - \tilde{G}(r) \sum_{k=3}^{\infty} k! \tilde{f}_k((s^2 + r^2)^{1/2}) \frac{\psi_{k-2}(r)}{\tilde{H}_k(r)}, & 1/2 < r < 1, \\ 1, & r \geq 1 \end{cases}, \quad (6.2)$$

$$\tilde{G}(r) \stackrel{def}{=} \int_{\gamma_r} \tilde{f}(|y|) dy, \quad \tilde{H}_k(r) \stackrel{def}{=} \int_{\gamma_r} \tilde{f}_k^2(|y|) dy, \quad \tilde{f} = \sum_{k=1}^{\infty} \frac{\tilde{f}_k}{k!}, \quad (6.3)$$

$$s \in \mathbb{R}, \quad x \in \mathbb{R}^2, \quad \gamma_r \text{ is an arbitrary ray in } T(r), \quad r > 1/2,$$

where $T(r)$ is defined by (2.8), $d = 2$, \tilde{f}_k are defined by (3.14). In addition:

$$U_0 \text{ is infinitely smooth on } \mathbb{R} \times \{(1/2, 1) \cup (1, +\infty)\}, \quad (6.4)$$

$$U_0(s, r) \rightarrow 1 \text{ as } r \rightarrow 1 \text{ (uniformly in } s \in \mathbb{R}), \quad (6.5)$$

$$U_0(s, r) = 1 \text{ if } s^2 + r^2 \geq 1, \quad (6.6)$$

$$|1 - U_0(s, r)| \leq C_0(1 - r)^{1/2} \log_2^4 \left(\frac{1}{1 - r} \right), \quad (6.7)$$

for $s \in \mathbb{R}$, $1/2 < r < 1$,

$$|U_0(s, r) - U_0(s', r')| \leq C_1|s - s'|^{1/\alpha} + C_1|r - r'|^{1/\alpha}, \quad (6.8)$$

for $\alpha \in (0, 1/16)$, $s, s' \in \mathbb{R}$, $r, r' > 1/2$,

where C_0, C_1 are positive constants depending on Φ of (3.15)-(3.17).

Lemma 3 is proved Section 8.

Lemma 3 implies (3.26)-(3.28) as follows.

The continuity and rotation invariance of W_0 in (3.26) follow from (2.18), (2.19), (6.1), (6.8).

Due to (3.40), (6.1), (6.2), (6.3) we have also that

$$U_0 \text{ admits a continuous extension to } \mathbb{R} \times [1/2, +\infty). \quad (6.9)$$

Properties (6.6), (6.9) imply the boundedness of W_0 on $\Omega_0(1/2)$, where $\Omega_0(\cdot)$ is defined in (2.3), $d = 2$. This completes the proof of (3.26).

Formula (3.27) follows from (6.1), (6.4), (6.8) and from the fact that $x\theta$, $|x - (x\theta)\theta|$ are infinitely smooth functions on $\Omega_0(1/2)$ and are Lipschitz in (x, θ) for $x \in \overline{B}(0, R)$, $R > 1$.

Formula (3.28) follows from (3.26), (6.1), (6.2), (6.5), (6.6).

This completes the proof of (3.26)-(3.28).

6.2 Proof of formula (3.29)

From (1.1), (3.13)-(3.16), (3.40), (3.44), (3.45) it follows that:

$$P_{W_0} f(x, \theta) = \int_{\gamma(x, \theta)} f(y) dy - G(x, \theta) \sum_{k=3}^{\infty} k! \psi_{k-2}(r(x, \theta)) \frac{\int_{\gamma(x, \theta)} f(y) f_k(y) dy}{H_k(x, \theta)} \quad (6.10)$$

$$= \int_{\gamma(x, \theta)} f(y) dy - \int_{\gamma(x, \theta)} f(y) dy \sum_{k=3}^{\infty} \psi_{k-2}(r(x, \theta)) \frac{\int_{\gamma(x, \theta)} f_k^2(y) dy}{\int_{\gamma(x, \theta)} f_k^2(y) dy} \quad (6.11)$$

$$= \int_{\gamma(x, \theta)} f(y) dy - \int_{\gamma(x, \theta)} f(y) dy \sum_{k=3}^{\infty} \psi_{k-2}(r(x, \theta)) = 0 \text{ for } (x, \theta) \in \Omega_0(1/2), \quad (6.12)$$

where $\gamma(x, \theta)$ is defined in (1.3), $\Omega_0(\cdot)$ is defined in (2.3), $d = 2$.

Formula (3.29) is proved.

7 Proof of Lemma 2

By $u \in \mathbb{R}$ we denote the coordinates on a fixed ray $\gamma(x, \theta)$, $(x, \theta) \in \Omega$, $d = 2$, taking into account the orientation, where $u = 0$ at the point $x - (x\theta)\theta \in \gamma(x, \theta)$; see notation (2.13).

Using Lemma 1, one can see that

$$f|_{\gamma(x, \theta)} \in C_0^\infty(\mathbb{R}), f|_{\gamma(x, \theta)}(u) = f|_{\gamma(x, \theta)}(|u|), u \in \mathbb{R}. \quad (7.1)$$

Using (7.1) and the assumption that $f|_{\gamma(x_0, \theta_0)}(u)$ changes the sign, one can see that there exists $\psi_{(x_0, \theta_0)}$ such that

$$\psi_{(x_0, \theta_0)} \in C_0^\infty(\mathbb{R}), \psi_{(x_0, \theta_0)} \geq 0, \psi_{(x_0, \theta_0)}(u) = \psi_{(x_0, \theta_0)}(|u|), u \in \mathbb{R}, \quad (7.2)$$

$$\int_{\gamma(x_0, \theta_0)} f \psi_{(x_0, \theta_0)} d\sigma \neq 0, \quad (7.3)$$

and if

$$\int_{\gamma(x_0, \theta_0)} f d\sigma \neq 0 \quad (7.4)$$

then also

$$\operatorname{sgn}\left(\int_{\gamma(x_0, \theta_0)} f d\sigma\right) \operatorname{sgn}\left(\int_{\gamma(x_0, \theta_0)} f \psi_{(x_0, \theta_0)} d\sigma\right) = -1, \quad (7.5)$$

where $d\sigma = du$ (i.e., σ is the standard Euclidean measure on $\gamma(x, \theta)$).

Let

$$W_{(x_0, \theta_0)}(x, \theta) = 1 - \psi_{(x_0, \theta_0)}(x\theta) \frac{\int_{\gamma(x, \theta)} f d\sigma}{\int_{\gamma(x, \theta)} f \psi_{(x_0, \theta_0)} d\sigma}, \quad x \in \mathbb{R}^2, \theta \in \mathbb{S}^1, \quad (7.6)$$

where $d\sigma = du$, where u is the coordinate on $\gamma(x, \theta)$.

Lemma 1 and property (7.2) imply that

$$\int_{\gamma(x, \theta)} f d\sigma \text{ and } \int_{\gamma(x, \theta)} f \psi_{(x_0, \theta_0)} d\sigma \text{ depend only on } r(x, \theta), \text{ where } (x, \theta) \in \Omega, \quad (7.7)$$

where $r(x, \theta)$ is defined in (2.2), Ω is defined in (2.1), $d = 2$.

From (7.2), (7.6), (7.7) it follows that $W_{(x_0, \theta_0)}$ is rotation-invariant in the sense (2.18).

Formulas (7.3), (7.6), (7.7), properties of f of Lemma 1 and properties of $\psi_{(x_0, \theta_0)}$ of (7.2) imply that

$$\exists \varepsilon_1 > 0 : \int_{\gamma(x, \theta)} f \psi_{(x_0, \theta_0)} d\sigma \neq 0 \text{ for } (x, \theta) \in \Omega(\mathcal{J}_{r(x_0, \theta_0), \varepsilon_1}), \quad (7.8)$$

where sets $\Omega(\mathcal{J}_{s, \varepsilon})$, $\mathcal{J}_{s, \varepsilon}$ are defined in (2.5), (2.9), respectively.

In addition, using properties of f of Lemma 1 and also using (3.13), (3.19), (7.2), (7.6), (7.8), one can see that

$$W_{(x_0, \theta_0)} \in C^\infty(\Omega(\mathcal{J}_{r(x_0, \theta_0), \varepsilon_1})). \quad (7.9)$$

In addition, from (7.1)-(7.7) it follows that

$$\begin{aligned} \text{if } r(x, \theta) = r(x_0, \theta_0) \text{ then } W_{(x_0, \theta_0)}(x, \theta) &= 1 - \psi_{(x_0, \theta_0)}(x\theta) \frac{\int_{\gamma(x_0, \theta_0)} f d\sigma}{\int_{\gamma(x_0, \theta_0)} f \psi_{(x_0, \theta_0)} d\sigma} \\ &= 1 - \psi_{(x_0, \theta_0)}(x\theta) \frac{\int_{\gamma(x_0, \theta_0)} f d\sigma}{\int_{\gamma(x_0, \theta_0)} f \psi_{(x_0, \theta_0)} d\sigma} \geq 1, \end{aligned} \quad (7.10)$$

where $r(x, \theta)$ is defined in (2.2), $d = 2$.

From properties of f of Lemma 1, properties of $\psi_{(x_0, \theta_0)}$ of (7.2) and from formulas (7.6), (7.8), (7.9), (7.10) it follows that

$$\exists \varepsilon_0 > 0 (\varepsilon_0 < \varepsilon_1) : W_{(x_0, \theta_0)}(x, \theta) \geq 1/2 \text{ for } (x, \theta) \in \Omega(\mathcal{J}_{r(x_0, \theta_0), \varepsilon_0}). \quad (7.11)$$

Let

$$W_{(x_0, \theta_0), \varepsilon_0} := W_{(x_0, \theta_0)} \text{ for } (x, \theta) \in \Omega(\mathcal{J}_{r(x_0, \theta_0), \varepsilon_0}), \quad (7.12)$$

where $W_{(x_0, \theta_0)}$ is defined in (7.6).

Properties (7.7), (7.9), (7.11) imply (3.49) for $W_{(x_0, \theta_0), \varepsilon_0}$ of (7.12).

Using (1.1), (7.6), (7.8), (7.12) one can see that

$$\begin{aligned} P_{W_{(x_0, \theta_0), \varepsilon_0}} f(x, \theta) &= \int_{\gamma(x, \theta)} W_{(x_0, \theta_0)}(\cdot, \theta) f d\sigma \\ &= \int_{\gamma(x, \theta)} f d\sigma - \frac{\int_{\gamma(x, \theta)} f d\sigma}{\int_{\gamma(x, \theta)} f \psi_{(x_0, \theta_0)} d\sigma} \int_{\gamma(x, \theta)} f \psi_{(x_0, \theta_0)} d\sigma = 0 \text{ for } (x, \theta) \in \Omega(\mathcal{J}_{r(x_0, \theta_0), \varepsilon_0}), \end{aligned} \quad (7.13)$$

where $\Omega(\cdot)$ is defined in (2.5), $d = 2$, $\mathcal{J}_{r, \varepsilon}$ is defined in (2.9). Formula (3.48) follows from (7.13).

Lemma 2 is proved.

8 Proof of Lemma 3

Proof of (6.1)-(6.3). Using (2.2), (3.13), (3.14), (3.45), (6.3) we obtain

$$G(x, \theta) = \tilde{G}(r(x, \theta)) = \int_{\gamma(x, \theta)} f(x) dx, \quad (8.1)$$

$$H_k(x, \theta) = \tilde{H}_k(r(x, \theta)) = \int_{\gamma(x, \theta)} f_k^2(x) dx, \quad (8.2)$$

$$\tilde{f}_k(|x|) = \tilde{f}_k((|x\theta|^2 + |x - (x\theta)\theta|^2)^{1/2}), \quad (x, \theta) \in \Omega_0(1/2), \quad (8.3)$$

where $\Omega_0(\cdot)$ is defined in (2.3), $d = 2$, $\gamma(x, \theta)$ is defined as in (2.13).

Formulas (3.44), (3.45), (8.1)-(8.3) imply (6.1)-(6.3).

Proof of (6.4). Let

$$\Lambda_k = (1 - 2^{-k+3}, 1 - 2^{-k+1}), \quad k \in \mathbb{N}, \quad k \geq 4. \quad (8.4)$$

From (3.40) it follows that, for $k \geq 4$:

$$\text{supp } \psi_{k-1} \subset (1 - 2^{-k+2}, 1 - 2^{-k}), \quad (8.5)$$

$$\text{supp } \psi_{k-2} \subset (1 - 2^{-k+3}, 1 - 2^{-k+1}) = \Lambda_k, \quad (8.6)$$

$$\text{supp } \psi_{k-3} \subset (1 - 2^{-k+4}, 1 - 2^{-k+2}). \quad (8.7)$$

Due to (6.2), (6.3), (8.5)-(8.7), we have the following formula for U_0 :

$$\begin{aligned} U_0(s, r) = 1 - \tilde{G}(r) & \left((k-1)! \tilde{f}_{k-1}((s^2 + r^2)^{1/2}) \frac{\psi_{k-3}(r)}{\tilde{H}_{k-1}(r)} \right. \\ & + k! \tilde{f}_k((s^2 + r^2)^{1/2}) \frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \\ & \left. + (k+1)! \tilde{f}_{k+1}((s^2 + r^2)^{1/2}) \frac{\psi_{k-1}(r)}{\tilde{H}_{k+1}(r)} \right) \quad \text{for } r \in \Lambda_k, \quad s \in \mathbb{R}, \quad k \geq 4. \end{aligned} \quad (8.8)$$

From (6.3), (8.8) it follows that

$$\begin{aligned} \frac{\partial^n U_0}{\partial s^n}(s, r) = -\tilde{G}(r) & \left((k-1)! \frac{\partial^n \tilde{f}_{k-1}((s^2 + r^2)^{1/2})}{\partial s^n} \frac{\psi_{k-3}(r)}{\tilde{H}_{k-1}(r)} \right. \\ & + k! \frac{\partial^n \tilde{f}_k((s^2 + r^2)^{1/2})}{\partial s^n} \frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \\ & \left. + (k+1)! \frac{\partial^n \tilde{f}_{k+1}((s^2 + r^2)^{1/2})}{\partial s^n} \frac{\psi_{k-1}(r)}{\tilde{H}_{k+1}(r)} \right), \end{aligned} \quad (8.9)$$

$$\frac{\partial^n \tilde{G}}{\partial r^n}(r) = \int_{-\infty}^{+\infty} \frac{\partial^n}{\partial r^n} \tilde{f}((s^2 + r^2)^{1/2}) ds, \quad \frac{\partial^n \tilde{H}_m}{\partial r^n}(r) = \int_{-\infty}^{+\infty} \frac{\partial^n}{\partial r^n} \tilde{f}_m^2((s^2 + r^2)^{1/2}) ds, \quad (8.10)$$

$$r \in \Lambda_k, \quad s \in \mathbb{R}, \quad m \geq 1, \quad n \geq 0, \quad k \geq 4,$$

where \tilde{G}, \tilde{H}_m are defined in (6.3).

Using Lemma 1 and formulas (3.13), (3.14), (3.40)-(3.47), (6.3) one can see that:

$$\tilde{f}, \tilde{f}_{m-2}, \tilde{G}, \tilde{H}_m \text{ belong to } C_0^\infty(\mathbb{R}), \quad \frac{\psi_{m-2}}{\tilde{H}_m} \text{ belongs to } C_0^\infty((1/2, 1)) \text{ for any } m \geq 3. \quad (8.11)$$

From (8.9)-(8.11) it follows that $U_0(s, r)$ has continuous partial derivatives of all orders with respect to $r \in \Lambda_k, s \in \mathbb{R}$. It implies that $U_0 \in C^\infty(\mathbb{R} \times \Lambda_k)$. From the fact that $\Lambda_k, k \geq 4$, is an open cover of $(1/2, 1)$ and from definition (6.2) of U_0 , it follows that $U_0 \in C^\infty(\mathbb{R} \times \{(1/2, 1) \cup (1, +\infty)\})$.

This completes the proof of (6.4).

Proof of (6.6). From (3.14)-(3.17) it follows that

$$\tilde{f}_k(|x|) = 0 \text{ if } |x| \geq 1 \text{ for } k \in \mathbb{N}. \quad (8.12)$$

Formula $|x|^2 = |x\theta|^2 + |x - (x\theta)\theta|^2, x \in \mathbb{R}^2, \theta \in \mathbb{S}^1$, and formulas (6.2), (8.12) imply (6.6).

Proofs of (6.7)-(6.8).

Lemma 4. *There are positive constants c, k_1 depending on Φ of (3.15)-(3.17), such that*

(i) *for all $k \in \mathbb{N}$ the following estimates hold:*

$$|\tilde{f}_k| \leq 1, \quad (8.13)$$

$$|\tilde{f}'_k| \leq c8^k, \quad (8.14)$$

where \tilde{f}'_k denotes the derivative of \tilde{f}_k defined in (6.3).

(ii) *for $k \geq k_1$ and $1/2 < r \leq 1$ the following estimates hold:*

$$\left| \frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \right| \leq c2^k, \quad (8.15)$$

$$\left| \frac{d}{dr} \left(\frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \right) \right| \leq c2^{5k}, \quad (8.16)$$

where ψ_k are defined in (3.40), \tilde{H}_k is defined in (6.3).

(iii) *for $k \geq 3$ and $r \geq 1 - 2^{-k}$ the following estimates hold:*

$$|\tilde{G}(r)| \leq c \frac{(2\sqrt{2})^{-k}}{k!}, \quad (8.17)$$

$$\left| \frac{d\tilde{G}}{dr}(r) \right| \leq c \frac{8^k}{k!}, \quad (8.18)$$

where \tilde{G} is defined in (6.3).

Lemma 5. *Let U_0 be defined by (6.2)-(6.3). Then the following estimates are valid:*

$$\left| \frac{\partial U_0}{\partial s}(s, r) \right| \leq \frac{C}{(1-r)^3}, \quad \left| \frac{\partial U_0}{\partial r}(s, r) \right| \leq \frac{C}{(1-r)^5} \text{ for } s \in \mathbb{R}, r \in (1/2, 1), \quad (8.19)$$

where C is a constant depending only on Φ of (3.15)-(3.17).

Lemmas 4, 5 are proved in Subsections 9.1, 9.2, respectively.

Proof of (6.7). From (8.15), (8.17) it follows that

$$|\tilde{G}(r)| \leq c(2\sqrt{2})^{-k+3}/(k-3)!, \quad (8.20)$$

$$\left| \frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \right| \leq c2^k, \quad (8.21)$$

for $r \in \Lambda_k$, $k \geq \max(4, k_1)$,

where Λ_k is defined in (8.4).

Properties (8.5)-(8.7) and estimate (8.15) imply that

$$\begin{cases} \psi_{k-1}(r) = 0, \\ \left| \frac{\psi_{k-3}(r)}{\tilde{H}_{k-1}(r)} \right| \leq c2^{k-1} \end{cases} \quad \text{if } r \in (1 - 2^{-k+3}, 1 - 2^{-k+2}), \quad (8.22)$$

$$\begin{cases} \psi_{k-2}(r) = 0, \\ \left| \frac{\psi_{k-1}(r)}{\tilde{H}_{k+1}(r)} \right| \leq c2^{k+1} \end{cases} \quad \text{if } r \in (1 - 2^{-k+2}, 1 - 2^{-k+1}), \quad (8.23)$$

$$\begin{cases} \psi_{k-1}(r) = 0, \\ \psi_{k-3}(r) = 0 \end{cases} \quad \text{if } r = 1 - 2^{-k+2}, \quad (8.24)$$

for $k \geq \max(4, k_1)$.

Note that the assumption that $r \in \Lambda_k$ is splitted into the assumptions on r of (8.22), (8.23), (8.24).

Using formulas (8.8), (8.20)-(8.24), we obtain the following estimates:

$$\begin{aligned} |1 - U_0(s, r)| &= |\tilde{G}(r)| \left| (k-1)! \tilde{f}_{k-1}((s^2 + r^2)^{1/2}) \frac{\psi_{k-3}(r)}{\tilde{H}_{k-1}(r)} + k! \tilde{f}_k((s^2 + r^2)^{1/2}) \frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \right| \\ &\leq c(2\sqrt{2})^{-k+3} (c(k-2)(k-1)2^{k-1} + c(k-2)(k-1)k2^k) \\ &\leq 2^5 \sqrt{2} c^2 2^{-k/2} k^3 \quad \text{if } r \in (1 - 2^{-k+3}, 1 - 2^{-k+2}), \end{aligned} \quad (8.25)$$

$$\begin{aligned}
|1 - U_0(s, r)| &= |\tilde{G}(r)| \left| k! \tilde{f}_k((s^2 + r^2)^{1/2}) \frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} + (k+1)! \tilde{f}_{k+1}((p^2 + r^2)^{1/2}) \frac{\psi_{k-1}(r)}{\tilde{H}_{k+1}(r)} \right| \\
&\leq c(2\sqrt{2})^{-k+3} (c2^k(k-2)(k-1)k + c2^{k+1}(k-2)(k-1)k(k+1)) \\
&\leq 2^{10} \sqrt{2} c^2 2^{-k/2} k^4 \quad \text{if } r \in (1 - 2^{-k+2}, 1 - 2^{-k+1}),
\end{aligned} \tag{8.26}$$

$$\begin{aligned}
|1 - U_0(s, r)| &= |\tilde{G}(r)| \left| k! \tilde{f}_k((s^2 + r^2)^{1/2}) \frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \right| \\
&\leq 2^4 \sqrt{2} c^2 2^{-k/2} k^3 \quad \text{if } r = 1 - 2^{-k+2},
\end{aligned} \tag{8.27}$$

for $s \in \mathbb{R}$, $k \geq \max(4, k_1)$. Estimates (8.25)-(8.27) imply that

$$|1 - U_0(s, r)| \leq C 2^{-k/2} k^4, \quad r \in \Lambda_k, \quad s \in \mathbb{R}, \quad k \geq \max(4, k_1), \tag{8.28}$$

where C is a positive constant depending on c of Lemma 4.

In addition, for $r \in \Lambda_k$ we have that $2^{-k+1} < (1-r) < 2^{-k+3}$, which together with (8.28) imply (6.7).

This completes the proof of (6.7).

Proof of (6.8). We consider the following cases of s, s', r, r' in (6.8):

1. Let

$$s, s' \in \mathbb{R} \text{ and } r, r' \geq 1. \tag{8.29}$$

Due to (6.2) we have that

$$U_0(s, r) = 1, \quad U_0(s', r') = 1. \tag{8.30}$$

Identities in (8.30) and assumption (8.29) imply (6.8) for this case.

2. Let

$$s, s' \in \mathbb{R}, \quad 1/2 < r < 1 \text{ and } r' \geq 1. \tag{8.31}$$

Then, due to (6.2), (6.7) we have that

$$|1 - U_0(s, r)| \leq C(1-r)^{1/3}, \tag{8.32}$$

$$U_0(s', r') = 1, \tag{8.33}$$

where s, s', r, r' satisfy assumption (8.31), C is a constant depending only on Φ . In particular, inequality (8.32) follows from (6.7) due to the following simple property of the logarithm:

$$\log_2^a \left(\frac{1}{1-r} \right) \leq C(a, \varepsilon)(1-r)^{-\varepsilon} \text{ for any } \varepsilon > 0, \quad r \in [0, 1), \quad a > 0, \tag{8.34}$$

where $C(a, \varepsilon)$ is some positive constant depending only on a and ε .

Due to (8.31), (8.32), (8.33) we have that

$$\begin{aligned}
|U_0(s', r') - U_0(s, r)| &= |1 - U_0(s, r)| \leq C(1-r)^{1/3} \\
&\leq C|r - r'|^{1/3} \leq C(|r - r'|^{1/3} + |s - s'|^{1/3}),
\end{aligned} \tag{8.35}$$

where C is a constant depending only on Φ .

Estimate (8.35) and assumptions (8.31) imply (6.8) for this case.

3. Let

$$s, s' \in \mathbb{R} \text{ and } r, r' \in (1/2, 1). \tag{8.36}$$

In addition, without loss of generality we assume that $r > r'$.

Next, using (6.4) one can see that

$$\begin{aligned}
|U_0(s, r) - U_0(s', r')| &= |U_0(s, r) - U_0(s', r) + U_0(s', r) - U_0(s', r')| \\
&\leq |U_0(s, r) - U_0(s', r)| + |U_0(s', r) - U_0(s', r')| \\
&\leq \left| \frac{\partial U_0}{\partial s}(\hat{s}, r) \right| |s - s'| + \left| \frac{\partial U_0}{\partial r}(s', \hat{r}) \right| |r - r'|,
\end{aligned} \tag{8.37}$$

for $s, s' \in \mathbb{R}$, $r, r' > 1/2$, and for appropriate \hat{s}, \hat{r} .

Note that \hat{s}, \hat{r} belong to open intervals $(s, s'), (r', r)$, respectively.

Using (6.7), (8.19), (8.32), (8.37) and the property that $1/2 < r' < \hat{r} < r < 1$ we obtain

$$|U_0(s, r) - U_0(s', r')| \leq C((1-r)^{1/3} + (1-r')^{1/3}), \tag{8.38}$$

$$|U_0(s, r) - U_0(s', r')| \leq \frac{C}{(1-r)^5} (|s - s'| + |r - r'|), \tag{8.39}$$

where C is a constant depending only on Φ .

We have that

$$\begin{aligned} (1-r)^{1/3} + (1-r')^{1/3} &= (1-r)^{1/3} + ((1-r) + (r-r'))^{1/3} \\ &\leq 2(1-r)^{1/3} + |r-r'|^{1/3} \\ &\leq \begin{cases} 3|r-r'|^{1/3} & \text{if } 1-r \leq |r-r'|, \\ 3(1-r)^{1/3} & \text{if } 1-r > |r-r'|, \end{cases} \end{aligned} \quad (8.40)$$

where r, r' satisfy (8.36). Note that in (8.40) we used the following inequality:

$$(a+b)^{1/m} \leq a^{1/m} + b^{1/m} \text{ for } a \geq 0, b \geq 0, m \in \mathbb{N}. \quad (8.41)$$

In particular, using (8.38), (8.40) we have that

$$|U_0(s, r) - U_0(s', r')|^{15} \leq 3^{15} C^{15} (1-r)^5 \text{ if } 1-r > |r-r'|, \quad (8.42)$$

where s, s', r, r' satisfy assumption (8.36), C is a constant of (8.38), (8.39).

Multiplying the left and the right hand-sides of (8.39), (8.42) we obtain

$$|U_0(s, r) - U_0(s', r')|^{16} \leq 3^{15} C^{16} (|s-s'| + |r-r'|), \text{ if } 1-r > |r-r'|. \quad (8.43)$$

Using (8.38), (8.40) we obtain

$$|U_0(s, r) - U_0(s', r')| \leq 3C|r-r'|^{1/3}, \text{ if } 1-r \leq |r-r'|, \quad (8.44)$$

where C is a constant of (8.38), (8.39) depending only on Φ . Using (8.43) and (8.41) for $m = 16$, $a = |s-s'|$, $b = |r-r'|$, we have that

$$|U_0(s, r) - U_0(s', r')| \leq 3C(|s-s'|^{1/16} + |r-r'|^{1/16}), \text{ if } 1-r > |r-r'|, \quad (8.45)$$

where s, s', r, r' satisfy assumption (8.36), C is a constant of (8.38), (8.39) which depends only on Φ .

Formulas (8.44), (8.45) imply (6.8) for this case.

Note that assumptions (8.29), (8.31), (8.36) for cases 1, 2, 3, respectively, cover all possible choices of s, s', r, r' in (6.8).

This completes the proof of (6.8).

This completes the proof of Lemma 3.

9 Proofs of Lemmas 4, 5

9.1 Proof of Lemma 4

Proof of (8.13), (8.14). Estimates (8.13), (8.14) follow directly from (3.14)-(3.17).

Proof of (8.17). We will use the following parametrization of the points y on $\gamma(x, \theta) \in TS^1$, $(x, \theta) \in \Omega$, $r(x, \theta) \neq 0$ (see notations (2.1), (2.2), (2.13) for $d = 2$):

$$y(\beta) = x - (x\theta)\theta + \tan(\beta)r(x, \theta)\theta, \beta \in (-\pi/2, \pi/2), \quad (9.1)$$

where β is the parameter.

We have that:

$$d\sigma(\beta) = r d(\tan(\beta)) = \frac{r d\beta}{\cos^2 \beta}, r = r(x, \theta), \quad (9.2)$$

where σ is the standard Lebesgue measure on $\gamma(x, \theta)$.

From definitions (3.13), (6.3) it follows that

$$\tilde{G}(r) = \sum_{k=1}^{\infty} \frac{\tilde{G}_k(r)}{k!}, \quad (9.3)$$

$$\tilde{G}_k(r) = \int_{\gamma_r} \tilde{f}_k(|y|) dy, \gamma_r \in T(r), r > 1/2, \quad (9.4)$$

where $T(r)$ is defined by (2.8).

Using (3.14), (9.1), (9.2), (9.4) we obtain the following formula for \tilde{G}_k :

$$\begin{aligned}
\tilde{G}_k(r) &= r \int_{-\pi/2}^{\pi/2} \Phi \left(2^k \left(1 - \frac{r}{\cos \beta} \right) \right) \cos \left(8^k \frac{r^2}{\cos^2 \beta} \right) \frac{d\beta}{\cos^2 \beta} \\
&= \{u = \tan(\beta)\} = 2r \int_0^{+\infty} \Phi \left(2^k \left(1 - r\sqrt{u^2 + 1} \right) \right) \cos \left(8^k r^2 (u^2 + 1) \right) du \\
&= \{t = u^2\} = r \int_0^{+\infty} \Phi \left(2^k \left(1 - r\sqrt{t+1} \right) \right) \cos \left(8^k r^2 (t+1) \right) \frac{dt}{\sqrt{t}} \\
&= r \cos(8^k r^2) \int_0^{+\infty} \Phi(2^k(1 - r\sqrt{t+1})) \frac{\cos(8^k r^2 t)}{\sqrt{t}} dt \\
&\quad - r \sin(8^k r^2) \int_0^{+\infty} \Phi(2^k(1 - r\sqrt{t+1})) \frac{\sin(8^k r^2 t)}{\sqrt{t}} dt \\
&= 8^{-k/2} r^{-1} \cos(8^k r^2) \int_0^{+\infty} \Phi_k(t, r) \frac{\cos(t)}{\sqrt{t}} dt \\
&\quad - 8^{-k/2} r^{-1} \sin(8^k r^2) \int_0^{+\infty} \Phi_k(t, r) \frac{\sin(t)}{\sqrt{t}} dt, \quad r > 1/2,
\end{aligned} \tag{9.5}$$

where

$$\Phi_k(t, r) = \Phi(2^k(1 - r\sqrt{8^{-k}r^{-2}t + 1})), \quad t \geq 0, \quad r > 1/2, \quad k \in \mathbb{N}. \tag{9.6}$$

For integrals arising in (9.5) the following estimates hold:

$$\left| \int_0^{+\infty} \Phi_k(t, r) \frac{\sin(t)}{\sqrt{t}} dt \right| \leq C_1 < +\infty, \tag{9.7}$$

$$\left| \int_0^{+\infty} \Phi_k(t, r) \frac{\cos(t)}{\sqrt{t}} dt \right| \leq C_2 < +\infty, \tag{9.8}$$

for $1/2 < r < 1$, $k \geq 1$.

where Φ_k is defined in (9.6), C_1, C_2 are some positive constants depending only on Φ and not depending on k and r .

Estimates (9.7), (9.8) are proved in Subsection 9.3.

From (9.5)-(9.8) it follows that

$$|\tilde{G}_k(r)| \leq 2 \cdot 8^{-k/2} (C_1 + C_2) \text{ for } r > 1/2, \quad k \in \mathbb{N}. \tag{9.9}$$

Note that for $y \in \gamma_r$, the following inequality holds:

$$2^k(1 - |y|) \leq 2^k(1 - r) \leq 2^{k-m} \leq 1/2 < 4/5 \text{ for } 1 - 2^{-m} \leq r < 1, \quad k < m, \quad m \geq 3, \tag{9.10}$$

where γ_r is a ray in $T(r)$ (see notations of (2.8), $d = 2$).

Formulas (3.14), (3.15), (6.3), (9.10) imply that

$$\gamma_r \cap \text{supp } f_k = \emptyset \text{ if } r \geq 1 - 2^{-m}, \quad k < m, \tag{9.11}$$

In turn, (9.4), (9.11) imply that

$$\tilde{G}_k(r) = 0 \text{ for } r \geq 1 - 2^{-m}, \quad k < m, \quad m \geq 3. \tag{9.12}$$

Due to (9.3), (9.4), (9.9), (9.12) we have that:

$$\begin{aligned}
|\tilde{G}(r)| &\leq \sum_{k=m}^{\infty} |\tilde{G}_k(r)|/k! \\
&\leq 2(C_1 + C_2) \frac{(2\sqrt{2})^{-m}}{m!} \sum_{k=0}^{\infty} (2\sqrt{2})^{-k} = c_1 \frac{(2\sqrt{2})^{-m}}{m!}, \quad c_1 = (C_1 + C_2) \frac{4\sqrt{2}}{2\sqrt{2} - 1}, \\
&\text{for } r \geq 1 - 2^{-m}, \quad m \geq 3.
\end{aligned} \tag{9.13}$$

This completes the proof of estimate (8.17).

Proof of (8.18). Using (9.3), (9.4) we have that:

$$\left| \frac{d\tilde{G}}{dr}(r) \right| \leq \sum_{k=1}^{\infty} \frac{1}{k!} \left| \frac{d\tilde{G}_k(r)}{dr} \right|. \quad (9.14)$$

Formulas (3.14), (8.10) for $n = 1$, (8.14), (9.4) imply that

$$\begin{aligned} \left| \frac{d\tilde{G}_k}{dr}(r) \right| &= \left| \int_{-\infty}^{+\infty} \frac{r \tilde{f}'_k((s^2 + r^2)^{1/2})}{\sqrt{r^2 + s^2}} ds \right| \\ &\leq \int_{-\infty}^{+\infty} |\tilde{f}'_k((s^2 + r^2)^{1/2})| ds = \int_{\gamma_r} |\tilde{f}'_k(|y|)| dy \leq c 8^k \int_{\gamma_r \cap B(0,1)} dy \leq 2c 8^k, \end{aligned} \quad (9.15)$$

where $B(0, 1)$ is defined in (2.15), $d = 2$.

At the same time, formula (9.12) implies that

$$\frac{d\tilde{G}_k(r)}{dr} = 0 \text{ for } r \geq 1 - 2^{-m}, k < m, m \geq 3. \quad (9.16)$$

Formulas (9.14), (9.15), (9.16) imply the following sequence of inequalities:

$$\left| \frac{d\tilde{G}(r)}{dr} \right| \leq \sum_{k=m}^{\infty} \frac{1}{k!} \left| \frac{d\tilde{G}_k(r)}{dr} \right| \leq c \frac{8^m}{m!} \sum_{k=0}^{\infty} \frac{m! 8^k}{(k+m)!}, r \geq 1 - 2^{-m}, m \geq 3. \quad (9.17)$$

The series in the right hand-side in (9.17) admits the following estimate:

$$\sum_{k=0}^{\infty} \frac{m! 8^k}{(k+m)!} \leq \sum_{k=0}^{\infty} \frac{8^k}{k!} = e^8 \text{ and the estimate does not depend on } m. \quad (9.18)$$

Formulas (9.17), (9.18) imply (8.18).

Proof of (8.15). For each ψ_k from (3.40) we have that

$$|\psi_k| \leq 1. \quad (9.19)$$

Therefore, it is sufficient to show that

$$\tilde{H}_k \geq C 2^{-k} \text{ for } k \geq k_1, C = c^{-1}. \quad (9.20)$$

Proceeding from (6.3) and in a similar way with (9.5) we obtain the formulas

$$\tilde{H}_k(r) = r \int_0^{+\infty} \frac{\Phi^2(2^k(1 - r\sqrt{t+1}))}{\sqrt{t}} \cos^2(8^k r^2(t+1)) dt = \tilde{H}_{k,1}(r) + \tilde{H}_{k,2}(r), r > 1/2, \quad (9.21)$$

$$\tilde{H}_{k,1}(r) = \frac{r}{2} \int_0^{+\infty} \frac{\Phi^2(2^k(1 - r\sqrt{t+1}))}{\sqrt{t}} dt, \quad (9.22)$$

$$\tilde{H}_{k,2}(r) = \frac{r}{2} \int_0^{+\infty} \frac{\Phi^2(2^k(1 - r\sqrt{t+1}))}{\sqrt{t}} \cos(2 \cdot 8^k r^2(t+1)) dt. \quad (9.23)$$

In addition, we have that:

$$\text{supp}_t \Phi^2(2^k(1 - r\sqrt{t+1})) \subset [0, 3] \text{ for } 1/2 < r \leq 1 - 2^{-k+1}, k \geq 3, \quad (9.24)$$

where supp_t denotes the support of the function in variable t . Property (9.24) is proved below in this paragraph (see formulas (9.26)-(9.29)).

Note that

$$2^k(1 - r) \geq 2^k \cdot 2^{-k+1} \geq 2 > 6/5 \text{ for } 1/2 < r \leq 1 - 2^{-k+1}, k \geq 3. \quad (9.25)$$

From (3.15), (3.16) and from (9.25) we have that:

$$\text{supp}_t \Phi^2(2^k(1 - r\sqrt{t+1})) \subset [0, +\infty) \text{ for } 1/2 < r \leq 1 - 2^{-k+1}, k \geq 3. \quad (9.26)$$

We have that

$$\exists t_1^{(k)} = t_1^{(k)}(r) \geq 0, t_2^{(k)} = t_2^{(k)}(r) \geq 0, t_2^{(k)} > t_1^{(k)}, \text{ such that } \begin{cases} 2^k(1 - r\sqrt{t_1^{(k)} + 1}) = 11/10, \\ 2^k(1 - r\sqrt{t_2^{(k)} + 1}) = 9/10, \end{cases} \quad (9.27)$$

$$|t_2^{(k)} - t_1^{(k)}| \geq \left(\sqrt{t_2^{(k)} + 1} - \sqrt{t_1^{(k)} + 1} \right) = \frac{2^{-k}}{5} r^{-1} \geq \frac{2^{-k}}{5}, \quad (9.28)$$

for $1/2 < r \leq 1 - 2^{-k+1}$, $k \geq 3$.

In addition, from (9.27) it follows that

$$\begin{aligned} t_1^{(k)} &= \frac{(1 - 2^{-k} \frac{11}{10})^2}{r^2} - 1 \leq 4(1 - 2^{-k} \frac{11}{10})^2 - 1 \leq 3, \\ t_2^{(k)} &= \frac{(1 - 2^{-k} \frac{9}{10})^2}{r^2} - 1 \leq 4(1 - 2^{-k} \frac{11}{10})^2 - 1 \leq 3, \\ &\text{for } 1/2 < r \leq 1 - 2^{-k+1}, k \geq 3. \end{aligned} \quad (9.29)$$

Using (3.15)-(3.17), (9.22), (9.24), (9.27)-(9.29) we have that

$$\begin{aligned} \tilde{H}_{k,1}(r) &\geq \frac{r}{2} \int_{t_1^{(k)}}^{t_2^{(k)}} \frac{dt}{\sqrt{t}} \geq \frac{r}{2} \int_3^{3+|t_2^{(k)} - t_1^{(k)}|} \frac{dt}{\sqrt{t}} \\ &\geq \frac{r}{6} \int_3^{3+|t_2^{(k)} - t_1^{(k)}|} dt = \frac{r}{6} |t_2^{(k)} - t_1^{(k)}| \geq \frac{2^{-k}}{30} \text{ for } 1/2 < r \leq 1 - 2^{-k+1}, k \geq 3. \end{aligned} \quad (9.30)$$

On the other hand, proceeding from using (9.23) and, in a similar way with (9.5)-(9.9), we have

$$\begin{aligned} |\tilde{H}_{k,2}(r)| &= \frac{r}{2} \left| \int_0^{+\infty} \frac{\Phi^2(2^k(1 - r\sqrt{t+1}))}{\sqrt{t}} \cos(2 \cdot 8^k r^2(t+1)) dt \right| \\ &\leq \frac{r}{2} |\cos(2 \cdot 8^k r^2)| \left| \int_0^{+\infty} \Phi^2(2^k(1 - r\sqrt{t+1})) \frac{\cos(2 \cdot 8^k r^2 t)}{\sqrt{t}} dt \right| \\ &\quad + \frac{r}{2} |\sin(2 \cdot 8^k r^2)| \left| \int_0^{+\infty} \Phi^2(2^k(1 - r\sqrt{t+1})) \frac{\sin(2 \cdot 8^k r^2 t)}{\sqrt{t}} dt \right| \\ &\leq 8^{-k/2} \frac{r^{-1}}{2} \left| \int_0^{+\infty} \Phi_k^2(t, r) \frac{\cos(2t)}{\sqrt{t}} dt \right| + 8^{-k/2} \frac{r^{-1}}{2} \left| \int_0^{+\infty} \Phi_k^2(t, r) \frac{\sin(2t)}{\sqrt{t}} dt \right| \\ &\leq 8^{-k/2} C, \text{ for } 1/2 < r < 1 - 2^{-k+1}, k \geq 3, \end{aligned} \quad (9.31)$$

where $\Phi_k(t, r)$ is defined in (9.6), C is some constant depending only on Φ and not depending on k, r . In (9.31) we have also used that $\Phi^2(t)$ satisfies assumptions (3.15)-(3.17).

Note also that $\Phi^2(t)$ satisfies assumptions (3.15)-(3.17) for $\Phi(t)$.

Using (9.21)-(9.23), (9.30), (9.31) we obtain

$$\begin{aligned} |\tilde{H}_k(r)| &\geq |\tilde{H}_{k,1}(r)| - |\tilde{H}_{k,2}(r)| \\ &\geq \frac{2^{-k}}{30} - C' \cdot 8^{-k/2} \\ &\geq 2^{-k} \left(\frac{1}{30} - \frac{C'}{(\sqrt{2})^k} \right) \\ &\geq C 2^{-k} \text{ for } 1/2 < r < 1 - 2^{-k+1}, k \geq k_1 \geq 3, \\ C &= \frac{1}{30} - C'(\sqrt{2})^{-k_1}, \end{aligned} \quad (9.32)$$

where C' depends only on Φ , k_1 is arbitrary constant such that $k_1 \geq 3$ and C is positive.

Formulas (8.15) follows from (3.40), (9.32).

This completes the proof (8.15).

Proof of (8.16). The following formula holds:

$$\frac{d}{dr} \left(\frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \right) = - \frac{\tilde{H}'_k(r)\psi_{k-2}(r) - \tilde{H}_k(r)\psi'_{k-2}(r)}{\tilde{H}_k^2(r)}, \quad 1/2 < r < 1, \quad (9.33)$$

where $\tilde{H}'_k, \psi'_{k-2}$ denote the derivatives of \tilde{H}_k, ψ_k , defined in (6.3), (3.40), respectively.

Using (3.14), (6.3), (8.10), $n = 1$, (8.13), (8.14) we have that

$$\begin{aligned} |\tilde{H}'_k(r)| &= 2 \left| \int_{-\infty}^{+\infty} \frac{r}{\sqrt{r^2+s^2}} \tilde{f}_k(\sqrt{r^2+s^2}) \tilde{f}'_k(\sqrt{r^2+s^2}) ds \right| \\ &\leq 2 \int_{-\infty}^{+\infty} |\tilde{f}_k(\sqrt{r^2+s^2}) \tilde{f}'_k(\sqrt{r^2+s^2})| ds = 2 \int_{\gamma_r} |\tilde{f}_k(|y|) \tilde{f}'_k(|y|)| dy \\ &\leq 2c8^k \int_{\gamma_r \cap B(0,1)} dy \leq 4c8^k, \quad \gamma_r \in T(r), \quad k \geq 3, \quad r > 1/2, \end{aligned} \quad (9.34)$$

where we use notations (2.8), (2.15), $d=2$.

Using (3.40), (3.41), (8.15), (9.32)-(9.34) we have that

$$\begin{aligned} \left| \frac{d}{dr} \left(\frac{\psi_{k-2}(r)}{\tilde{H}_k(r)} \right) \right| &\leq C2^{2k} (|\tilde{H}'_k(r)| + |\tilde{H}_k(r)| \cdot |\psi'_{k-2}(r)|) \leq C'2^{5k}, \\ &\text{for } 1/2 < r < 1 - 2^{-k+1}, \quad k \geq k_1 \geq 3, \end{aligned} \quad (9.35)$$

where C' is a constant not depending on k and r and depending only on Φ .

This completes the proof of Lemma 4.

9.2 Proof of Lemma 5

It is sufficient to show that

$$\left| \frac{\partial U_0(s, r)}{\partial s} \right| \leq \frac{C}{(1-r)^3}, \quad (9.36)$$

$$\left| \frac{\partial U_0(s, r)}{\partial r} \right| \leq \frac{C}{(1-r)^5}, \quad (9.37)$$

for $s \in \mathbb{R}, r \in \Lambda_k, k \geq \max(4, k_1)$,

where C is a positive constant depending only on Φ of (3.14), Λ_k is defined in (8.4), k_1 is a constant arising in Lemma 4 and depending only on Φ .

Indeed, estimates (8.19) follow from (6.4), (9.36), (9.37) and the fact that $\Lambda_k, k \geq 4$, is an open cover of $(1/2, 1)$.

In turn, estimates (9.36), (9.37) follow from the estimates

$$\left| \frac{\partial U_0(s, r)}{\partial s} \right| \leq C \cdot 8^k, \quad (9.38)$$

$$\left| \frac{\partial U_0(s, r)}{\partial r} \right| \leq C \cdot (32)^k, \quad (9.39)$$

for $s \in \mathbb{R}, r \in \Lambda_k$,

and from the fact that $2^{-k+1} < 1-r < 2^{-k+3}, k \geq \max(4, k_1)$, for $r \in \Lambda_k$, where C is a positive constant depending only on Φ .

Estimate (9.38) follows from formula (8.9) for $n = 1$ and estimates (8.14), (8.15), (8.20)-(8.24).

Estimate (9.39) follows from (8.8), (8.13)-(8.16), (8.20)-(8.24) and from the estimates:

$$\left| \frac{d}{dr} \left(\frac{\psi_{k-i}(r)}{\tilde{H}_{k-i+2}(r)} \right) \right| \leq c2^{5(k+1)}, \quad (9.40)$$

$$\left| \frac{d\tilde{G}(r)}{dr} \right| \leq c \frac{8^{-k+3}}{(k-3)!}, \quad (9.41)$$

for $r \in \Lambda_k, i \in \{1, 2, 3\}$,

where c is a constant arising in Lemma 4.

Estimate (9.40) follows from (8.16) (used with $k-1, k, k+1$ in place of k). Estimate (9.41) follows from (8.18) (used with $k-3$ in place of k).

This completes the proof of Lemma 5.

9.3 Proof of estimates (9.7), (9.8)

We use the following Bonnet's integration formulas (see, e.g., [Fich59], Chapter 2):

$$\int_a^b f_1(t)h(t) dt = f_1(a) \int_a^{\xi_1} h(t) dt, \quad (9.42)$$

$$\int_a^b f_2(t)h(t) dt = f_2(b) \int_{\xi_2}^b h(t) dt, \quad (9.43)$$

for some appropriate $\xi_1, \xi_2 \in [a, b]$, where

$$\begin{aligned} f_1 & \text{ is monotonously decreasing on } [a, b], f_1 \geq 0, \\ f_2 & \text{ is monotonously increasing on } [a, b], f_2 \geq 0, \\ h(t) & \text{ is integrable on } [a, b]. \end{aligned} \quad (9.44)$$

Let

$$g_1(t) = \frac{\sin(t)}{\sqrt{t}}, g_2(t) = \frac{\cos(t)}{\sqrt{t}}, t > 0, \quad (9.45)$$

$$G_1(s) = \int_0^s \frac{\sin(t)}{\sqrt{t}} dt, G_2(s) = \int_0^s \frac{\cos(t)}{\sqrt{t}} dt, s \geq 0. \quad (9.46)$$

We recall that

$$\lim_{s \rightarrow +\infty} G_1(s) = \lim_{s \rightarrow +\infty} G_2(s) = \sqrt{\frac{\pi}{2}}. \quad (9.47)$$

From (9.45), (9.46), (9.47) it follows that

$$G_1, G_2 \text{ are continuous and bounded on } [0, +\infty). \quad (9.48)$$

Due to (3.15)-(3.18), (9.6) and monotonicity of the function $2^k(1 - r\sqrt{8^{-k}r^{-2}t + 1})$ in t on $[0, +\infty)$ it follows that

$$\Phi_k(t, r) \text{ is monotonously decreasing on } [0, +\infty), \text{ if } 2^k(1 - r) \leq 11/10, \quad (9.49)$$

$$\begin{aligned} \Phi_k(t, r) & \text{ is monotonously increasing on } [0, t_0] \text{ for some } t_0 > 0 \\ & \text{ and is monotonously decreasing on } [t_0, +\infty), \text{ if } 2^k(1 - r) > 11/10. \end{aligned} \quad (9.50)$$

for $r > 1/2, k \in \mathbb{N}$,

Moreover, due to (3.15)-(3.17), (9.6), for $T_k = 8^k, k \in \mathbb{N}$, we have that

$$\Phi_k(T_k, r) = \Phi(2^k(1 - r\sqrt{r^{-2} + 1})) = \Phi(2^k(1 - \sqrt{1 + r^{-2}})) = 0, \quad (9.51)$$

$$\Phi_k(t, r) = 0 \text{ for } t \geq T_k, \quad (9.52)$$

$$|\Phi_k(t, r)| \leq 1 \text{ for } t \geq 0, \quad (9.53)$$

$r > 1/2, k \in \mathbb{N}$.

Using (9.6), (9.45)-(9.50), (9.52) and (9.42)-(9.44) we obtain

$$\begin{aligned} \int_0^{+\infty} \Phi_k(t, r)g_i(t) dt &= \int_0^{T_k} \Phi_k(t, r)g_i(t) dt = \Phi_k(0, r) \int_0^{\xi} g_i(t) dt \\ &= \Phi_k(0, r)G_i(\xi) \text{ for appropriate } \xi \in [0, T_k], \text{ if } 2^k(1 - r) \leq 11/10, \end{aligned} \quad (9.54)$$

$$\begin{aligned} \int_0^{\infty} \Phi_k(t, r)g_i(t) dt &= \int_0^{T_k} \Phi_k(t, r)g_i(t) dt = \int_0^{t_0} \Phi_k(t, r)g_i(t) dt + \int_{t_0}^{T_k} \Phi_k(t, r)g_i(t) dt \\ &= \Phi_k(t_0, r) \int_{\xi'}^{t_0} g_i(t) dt + \Phi_k(t_0, r) \int_{t_0}^{\xi''} g_i(t) dt \\ &= \Phi_k(t_0, r)(G_i(\xi'') - G_i(\xi')) \text{ for appropriate } \xi' \in [0, t_0], \xi'' \in [t_0, T_k], \\ & \text{ if } 2^k(1 - r) > 11/10, \end{aligned} \quad (9.55)$$

where $i = \overline{1, 2}$.

Estimates (9.7), (9.8) follow from (9.45), (9.46), (9.48), (9.53)-(9.55).

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