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# POINCARÉ AND SOBOLEV INEQUALITIES FOR DIFFERENTIAL FORMS IN HEISENBERG GROUPS 

ANNALISA BALDI<br>BRUNO FRANCHI<br>PIERRE PANSU

## 1. Introduction

1.1. Sobolev and Poincaré inequalities for differential forms. Sobolev inequality in $\mathbb{R}^{n}$ deals with compactly supported 0 -forms, i.e. functions $u$ on $\mathbb{R}^{n}$, and 1 -forms, their differentials $d u$. It states that

$$
\|u\|_{q} \leq C_{p, q, n}\|d u\|_{p}
$$

whenever

$$
1 \leq p, q<+\infty, \quad \frac{1}{p}-\frac{1}{q}=\frac{1}{n} .
$$

A local version, for functions supported in the unit ball, holds under the weaker assumption

$$
1 \leq p, q<+\infty, \quad \frac{1}{p}-\frac{1}{q} \leq \frac{1}{n} .
$$

Poincare's inequality is a variant for functions $u$ defined on but not necessarily compactly supported in the unit ball $B$. It states that there exists a real number $c_{u}$ such that

$$
\left\|u-c_{u}\right\|_{q} \leq C_{p, q, n}\|d u\|_{p}
$$

Alternatively, given a closed 1-form $\omega$ on $B$, there exists a function $u$ on $B$ such that $d u=\omega$ on $B$, and such that

$$
\|u\|_{q} \leq C_{p, q, n}\|\omega\|_{p} .
$$

This suggests the following generalization for higher degree differential forms.
Let $M$ be a Riemannian manifold. We say that a strong Poincaré inequality $(p, q)$-Poincaré $(k)$ holds on $M$, if there exists a positive constant $C=C(M, p, q)$ such that for every closed $k$-form $\omega$ on $M$, belonging to $L^{p}$, there exists a $k-1$-form $\phi$ such that $d \phi=\omega$ and

$$
\|\phi\|_{q} \leq C\|\omega\|_{p} .
$$

A strong Sobolev inequality $(p, q)$-Sobolev $(k)$ holds on $M$, if for every closed compactly supported $k$-form $\omega$ on $M$, belonging to $L^{p}$, there exists a compactly supported $k-1$-form $\phi$ such that $d \phi=\omega$ and

$$
\|\phi\|_{q} \leq C\|\omega\|_{p} .
$$

[^0]Both statements should be thought of as quantitative versions of the statement that every closed $k$-form is exact.

For Euclidean domains, the validity of Poincaré inequality is sensitive to irregularity of boundaries. One way to eliminate such a dependance is to allow a loss on domain. Say an interior Poincaré inequality $(p, q)$-Poincaré $(k)$ holds on $M$ if for every small enough $r>0$ and large enough $\lambda \geq 1$, there exists a constant $C=C(M, p, q, r, \lambda)$ such that for every $x \in M$ and every closed $k$-form $\omega$ on $B(x, \lambda r)$, belonging to $L^{p}$, there exists a $(k-1)$-form $\phi$ on $B(x, r)$ such that $d \phi=\omega$ on $B(x, r)$ and

$$
\|\phi\|_{L^{q}(B(x, r))} \leq C\|\omega\|_{L^{p}(B(x, \lambda r))} .
$$

For interior Sobolev inequalities, merely add the word compactly supported. Both properties should be thought of as quantitative versions of the statement that, locally, every closed $k$-form is exact.

It turns out that in several situations, the loss on domain is harmless. This is the case for $L^{q, p}$-cohomological applications, see $\frac{1}{11]}$.
1.2. Contact manifolds. A contact structure on a manifold $M$ is a smooth distribution of hyperplanes $H$ which is maximally nonintegrable in the following sense: if $\theta$ is a locally defined smooth 1-form such that $H=\operatorname{ker}(\theta)$, then $d \theta$ restricts to a nondegenerate 2 -form on $H$. A contact manifold is the data of a smooth manifold $M$ and a contact structure $H$ on $M . M$ must be odd-dimensional. Contactomorphisms are contact structure preserving diffeomorphisms between contact manifolds. The prototype of a contact manifold is the Heisenberg group $\mathbb{H}^{n}$, the simply connected Lie group whose Lie algebra is the central extension $\mathfrak{h}=\mathfrak{h}_{1} \oplus \mathfrak{h}_{2}, \mathfrak{h}_{2}=\mathbb{R}=Z(\mathfrak{h})$, with bracket $\mathfrak{h}_{1} \otimes \mathfrak{h}_{1} \rightarrow \mathfrak{h}_{2}=\mathbb{R}$ being a non-degenerate skew-symmetric 2-form. The contact structure is obtained by left-translating $\mathfrak{h}_{1}$. According to Darboux, every contact manifold is locally contactomorphic to $\mathbb{H}^{n}$. The Heisenberg Lie algebra admits a one parameter group of automorphisms $\delta_{t}$,

$$
\delta_{t}=t \text { on } \mathfrak{h}_{1}, \quad \delta_{t}=t^{2} \text { on } \mathfrak{h}_{2},
$$

which are analogues of Euclidean homotheties. However, differential forms on $\mathfrak{h}$ split into 2 eigenspaces under $\delta_{t}$, therefore de Rham complex lacks scale invariance under these anisotropic dilations.

A substitute for de Rham's complex, that recovers scale invariance under $\delta_{t}$ has been defined by M. Rumin, 18$]$. It makes sense for arbitrary contact manifolds $(M, H)$. Let $\Omega^{\bullet}$ denote the space of smooth differential forms on $M$, let $\mathcal{I}^{\bullet}$ denote the differential ideal generated by 1-forms that vanish on $H$, let $\mathcal{J}^{\bullet}$ denote its annihilator. Exterior differential $d: \Omega^{\bullet} \rightarrow \Omega^{\bullet}$ descends to first order differential operators $d_{c}: \Omega^{\bullet} / \mathcal{I}^{\bullet} \rightarrow \Omega^{\bullet} / \mathcal{I}^{\bullet}$ and $d_{c}: \mathcal{J}^{\bullet} \rightarrow \mathcal{J}^{\bullet}$. It turns out that $\Omega^{h} / \mathcal{I}^{h}=0$ for $h \geq n+1$ and $\mathcal{J}^{h}=0$ for $h \leq n$. If $\omega \in \Omega^{n} / \mathcal{I}^{n}$, there is a unique lift $\tilde{\omega} \in \Omega^{n}$ such that $d \tilde{\omega} \in \mathcal{J}^{n+1}$. Set $d_{c} \omega=d \tilde{\omega}$. This defines a linear second order differential operator $\Omega^{n} / \mathcal{I}^{n+1} \rightarrow \mathcal{J}^{n+1}$ which completes Rumin's complex, which is homotopic to de Rham's complex. The homotopy is a first order differential operator.

Elements of $\Omega^{\bullet} / \mathcal{I}^{\bullet}$ and $\mathcal{J}^{\bullet}$ can be viewed as smooth sections of sub-bundles $\mathcal{E}_{0}^{\bullet}$ of $\Lambda^{\bullet} H^{*}$ and $\Lambda^{\bullet} H^{*} \otimes(T M / H)$ respectively. A Euclidean norm on $H$ determines Euclidean norms on $\Lambda^{\bullet} H^{*}$. Locally, a 1-form $\theta$ vanishing on $H$ such that $\left|d \theta_{\mid H}\right|=1$ is uniquely determined up to sign, hence a norm on $T M / H$. The measure on $M$
defined by the locally defined top degree form $\theta \wedge(d \theta)^{n}$ only depends on the norm on $H$ as well. Whence $L^{p}$-norms on spaces of sections of bundles $\mathcal{E}_{0}^{\bullet}$.

The data of $(M, H)$ equipped with a Euclidean norm defined on sub-bundle $H$ only is called a sub-Riemannian contact manifold. Poincaré and Sobolev inequalities for differential forms make sense on contact sub-Riemannian manifolds: merely replace $d$ with $d_{c}$. All left-invariant sub-Riemannian metrics on Heisenberg group are bi-Lipschitz equivalent, hence we may refer to sub-Riemannian Heisenberg group without referring to a specific left-invariant metric. On the other hand, in absence of symmetry assumptions, large scale behaviours of sub-Riemannian contact manifolds are diverse.
1.3. Results on Poincaré and Sobolev inequalities. In this paper, we prove strong contact Poincaré and Sobolev inequalities and interior contact Poincaré and Sobolev inequalities in Heisenberg groups, where the word "contact" is meant to stress that the exterior differential is replaced by Rumin's $d_{c}$. The range of parameters differs slightly from the Euclidean case, due to the fact that $d_{c}$ has order 2 in middle dimension. Let $h \in\{0, \ldots, 2 n+1\}$. Say that assumption $E(h, p, q, n)$ holds if $1<p \leq q<\infty$ satisfy

$$
\frac{1}{p}-\frac{1}{q}= \begin{cases}\frac{1}{2 n+2} & \text { if } h \neq n+1 \\ \frac{2}{2 n+2} & \text { if } h=n+1\end{cases}
$$

Say that assumption $I(h, p, q, n)$ holds if $1<p \leq q<\infty$ satisfy

$$
\frac{1}{p}-\frac{1}{q} \leq \begin{cases}\frac{1}{2 n+2} & \text { if } h \neq n+1 \\ \frac{2}{2 n+2} & \text { if } h=n+1\end{cases}
$$

strongglobal Theorem 1.1. Under assumption $E(h, p, q, n)$, strong $(p, q)$-Poincaré and $(p, q)$ Sobolev inequalities hold for $h$-forms on $\mathbb{H}^{n}$.

Theorem 1.2. Under assumption $I(h, p, q, n)$, interior $(p, q)$-Poincaré and $(p, q)$ Sobolev inequalities hold for $h$-forms on $\mathbb{H}^{n}$.

Precise formulations of interior Poincaré and Sobolev inequalities are given in section ${ }^{\text {po }}$.

Here is a sample consequence of these results. Combining both theorems with results from ${ }^{[17]^{2}}$, we get
Corollary 1.3. Under assumption $E(h, p, q, n)$, the $\ell^{q, p}$-cohomology in degree $h$ of $\mathbb{H}^{n}$ vanishes.
1.4. Bounded geometry and smoothing. Along the way, we construct local smoothing operators for differential forms. They can be combined to yield a global smoothing operator on sub-Riemannian contact manifolds, which has independent interest (see Theorem $\frac{1.5}{1.5}$ below). This operator is bounded on $L^{p}$ provided the sub-Riemannian metric has bounded geometry in the following sense.
contact Definition 1.4. Let $k \geq 2$. Let $B(e, 1)$ denote the unit sub-Riemannian ball in $\mathbb{H}^{n}$. We say that a sub-Riemannian contact manifold $(M, H, g)$ has bounded $C^{k}$ geometry is there exist constants $r>0, C$ such that, for every $x \in M$, if we denote by $B(x, r)$ the sub-Riemannian ball for $(M, H, g)$ centered at $x$ and of radius $r$, there exists a contactomorphism (i.e. a diffeomorphism preserving the contact forms) $\phi_{x}: B(e, 1) \rightarrow M$
(1) $B(x, r) \subset \phi_{x}(B(e, 1))$.
(2) $\phi_{x}$ is $C$-bi-Lipschitz.
(3) Coordinate changes $\phi_{x} \circ \phi_{y}^{-1}$ and their first $k$ derivatives with respect to unit left-invariant horizontal vectorfields are bounded by $C$.

On sub-Riemannian Heisenberg balls, Sobolev spaces can be defined as follows. Fix an orthonormal basis of left-invariant vector fields $W_{i}$. Express forms in this frame, and differentiate along these vector-fields only. Let $\ell=0, \ldots, k$. Say that a differential form on unit ball $B$ belongs to $W^{\ell, p}$ if all derivatives up to order $k$ of its components belong to $L^{p}(B)$. Using $C^{k}$-bounded charts, this local notion extends to $C^{k}$-bounded geometry sub-Riemannian contact manifolds $M$, and the global $W^{k, p}$ norm on globally defined differential forms is defined by

$$
\left(\sum_{j}\left\|\omega_{\mid B\left(x_{j}, r\right)}\right\|_{W^{k, p}\left(B\left(x_{j}, r\right)\right)}\right)^{1 / p}
$$

where $x_{i}$ is an $r$-dense uniformly discrete subset of $M$ (it will be shown in section 5 that this norm does not depend on choices, up to multiplicative constants). By duality, Sobolev spaces with negative $\ell=-k+1, \ldots,-1$ can be defined.
1.5 Theorem 1.5. Let $(M, H, g)$ be a sub-Riemannian contact manifold of bounded $C^{k}$-geometry. Under assumption $I(h, p, q, n)$, there exist operators $S$ and $T$ on $h$ forms on $M$ which are bounded from $W^{j-1, p}$ to $W^{j, q}$ for all $0 \leq j \leq k$, and such that $1=S+d_{c} T+T d_{c}$.

Iterating $S$ yields an operator which is bounded from $L^{p}$ to $W^{k, q}$, and still acts trivially on cohomology. For instance, this allows to replace a closed form, up to adding a controlled exact form, with a much more regular differential form.
1.5. Questions. Keeping in mind the analogous inequalities in the scalar case, the following questions naturally arise.

1. Do balls is Heisenberg group satisfy strong $(p, q)$-Poincaré and $(p, q)$-Sobolev inequalities? In other words, do Poincaré and Sobolev inequalities hold without lack on domain?
2. Do interior $(p, q)$-Poincaré and $(p, q)$-Sobolev inequalities hold for limiting values, i.e. for $p=1$ or $q=\infty$ ?
3. How much of these results does extend to more general Carnot groups?

## 2. SCheme of proof

2.1. Global homotopy operators. The most efficient way to prove a Poincaré inequality is to find a homotopy between identity and 0 on the complex of differential forms, i.e. a linear operator $K$ that raises the degree by 1 and satisfies

$$
1=d K+K d
$$

More generally, we shall deal with homotopies between identity and other operators $P$, i.e. of the form

$$
1-P=d K+K d
$$

In Euclidean space, the Laplacian provides us with such a homotopy. Write $\Delta=d \delta+\delta d$. Denote by $\Delta^{-1}$ the operator of convolution with the fundamental solution of the Laplacian. Then $\Delta^{-1}$ commutes with $d$ and its adjoint $\delta$, hence
$K_{e}=\delta \Delta^{-1}$ satisfies $1=d K_{e}+K_{e} d$ on globally defined $L^{p}$ differential forms. Furthermore, $K_{e}$ is bounded $L^{p} \rightarrow W^{1, q}$ provided $\frac{1}{p}-\frac{1}{q}=\frac{1}{n}$. This proves the strong $(p, q)$-Poincaré inequality for Euclidean space. Rumin defines a Laplacian $\Delta_{c}$ by $\Delta_{c}=d_{c} \delta_{c}+\delta_{c} d_{c}$ when both $d_{c}$ 's are first order, and by $\Delta_{c}=\left(d_{c} \delta_{c}\right)^{2}+\delta_{c} d_{c}$ or $\Delta_{c}=d_{c} \delta_{c}+\left(\delta_{c} d_{c}\right)^{2}$ near middle dimension, when one of them has order 2. This leads to a homotopy of the form $K_{0}=\delta_{c} \Delta_{c}^{-1}$ or $K_{0}=\delta_{c} d_{c} \delta_{c} \Delta_{c}^{-1}$ depending on degree. Again, $K_{0}$ is bounded $L^{p} \rightarrow W^{1, q}$ under assumption $E(h, p, q, n)$. This proves the strong contact $(p, q)$-Poincaré $(h)$ inequality for Heisenberg group, Theorem I.1.
2.2. Local homotopy operators. We pass to local results. In Euclidean space, Poincaré's Lemma asserts that every closed form on a ball is exact. We need a quantitative version of this statement. The standard proof of Poincaré's Lemma relies on a homotopy operator which depends on the choice of an origin. Averaging over origins yields a bounded operator $K: L^{p} \rightarrow L^{q}$, as was observed by Iwaniec and Lutoborski, $[\stackrel{[1}{[3]}$. This proves the strong Euclidean $(p, q)$-Poincaré $(h)$ inequality for convex Euclidean domains, A support preserving variant $J: L^{p} \rightarrow L^{q}$ appears in Mitrea-Mitrea-Monniaux, $[16]$ and this proves the strong Euclidean $(p, q)$-Sobolev inequality for bounded convex Euclidean domains. Incidentally, since, for balls, constants do not depend on the radius of the ball, this reproves the strong Euclidean $(p, q)$-Sobolev inequality for Euclidean space.

In this paper a sub-Riemannian counterpart is obtained using the homotopy of de Rham's and Rumin's complexes. Since this homotopy is a differential operator, a preliminary smoothing operation is needed. This is obtained by localizing (multiplying the kernel with cut-offs) the global homotopy $K_{0}$ provided by the inverse of Rumin's (modified) Laplacian.

Hence the proof goes as follows (see Section $\frac{\text { poincare }}{6}$ :
(1) Show that the inverse $K_{0}$ of Rumin's modified Laplacian on all of $\mathbb{H}^{n}$ is given by a homogeneous kernel $k_{0}$. Deduce bounds $L^{p} \rightarrow W^{1, q}$. Conclude that $K_{0}$ is an exact homotopy for globally defined $L^{p}$ forms.
(2) Split $k_{0}=k_{1}+k_{2}$ where $k_{1}$ has small support and $k_{2}$ is smooth. Hence $T=K_{1}$ is a homotopy on balls (with a loss on domain) of identity to $S=d_{c} K_{2}+K_{2} d_{c}$ which is smoothing. This provides the required local smoothing operation.
(3) Compose Iwaniec and Lutoborski's averaged Poincaré homotopy for the de Rham complex and Rumin's homotopy, and apply the result to smoothed forms. This proves an interior Poincaré inequality in Heisenberg group. Replacing Iwaniec and Lutoborski's homotopy with Mitrea-Mitrea-Monniaux's homotopy leads to an interior Sobolev inequality.
2.3. Global smoothing. Let $(M, H, g)$ be a bounded $C^{k}$-geometry sub-Riemannian contact manifold. Pick a uniform covering by equal radius balls. Let $\chi_{j}$ be a partition of unity subordinate to this covering. Let $\phi_{j}$ be the corresponding charts from the unit Heisenberg ball. Let $S_{j}$ and $T_{j}$ denote the smoothing and homotopy operators transported by $\phi_{j}$. Set

$$
T=\sum_{j} T_{j} \chi_{j}, \quad S=\sum_{j} S_{j} \chi_{j}+T_{j}\left[\chi_{j}, d_{c}\right]
$$

When $d_{c}$ is first order, the commutator $\left[\chi_{j}, d_{c}\right]$ is an order 0 differential operator, hence $T_{j}\left[\chi_{j}, d_{c}\right]$ gains 1 derivative. When $d_{c}$ is second order, $\left[\chi_{j}, d_{c}\right]$ is a first order
differential operator. It turns out that precisely in this case, $T_{j}$ gains 2 derivatives, hence $T_{j}\left[\chi_{j}, d_{c}\right]$ gains 1 derivative in this case as well.

This is detailed in section 17 .

## 3. Heisenberg groups and Rumin's complex $\left(E_{0}^{\bullet}, d_{c}\right)$

3.1. Differential forms on Heisenberg group. We denote by $\mathbb{H}^{n}$ the $n$-dimensional Heisenberg group, identified with $\mathbb{R}^{2 n+1}$ through exponential coordinates. A point $p \in \mathbb{H}^{n}$ is denoted by $p=(x, y, t)$, with both $x, y \in \mathbb{R}^{n}$ and $t \in \mathbb{R}$. If $p$ and $p^{\prime} \in \mathbb{H}^{n}$, the group operation is defined by

$$
p \cdot p^{\prime}=\left(x+x^{\prime}, y+y^{\prime}, t+t^{\prime}+\frac{1}{2} \sum_{j=1}^{n}\left(x_{j} y_{j}^{\prime}-y_{j} x_{j}^{\prime}\right)\right)
$$

The unit element of $\mathbb{H}^{n}$ is the origin, that will be denote by $e$.
For [II] and to [20]. We limit ourselves to fix some notations, following lij].

The Heisenberg group $\mathbb{H}^{n}$ can be endowed with the homogeneous norm (Korányi norm)

$$
\begin{equation*}
\varrho(p)=\left(\left|p^{\prime}\right|^{4}+p_{2 n+1}^{2}\right)^{1 / 4} \tag{1}
\end{equation*}
$$

and we define the gauge distance (a true distance, see $\frac{\{\text { Stein }}{[9], \text { p. }}$. 638 , that is equivalent to Carnot-Carathéodory distance) as

$$
\begin{equation*}
d(p, q):=\varrho\left(p^{-1} \cdot q\right) \tag{2}
\end{equation*}
$$

Finally, set $B_{\rho}(p, r)=\left\{q \in \mathbb{H}^{n} ; d(p, q)<r\right\}$.
A straightforward computation shows that there exists $c_{0}>1$ such that

$$
\begin{equation*}
c_{0}^{-2}|p| \leq \rho(p) \leq|p|^{1 / 2} \tag{3}
\end{equation*}
$$

provided $p$ is close to $e$. In particular, for $r>0$ small, if we denote by $B_{\text {Euc }}(e, r)$ the Euclidean ball centred ad $e$ of radius $r$,

$$
\begin{equation*}
B_{\mathrm{Euc}}\left(e, r^{2}\right) \subset B_{\rho}(e, r) \subset B_{\mathrm{Euc}}\left(e, c_{0}^{2} r\right) \tag{4}
\end{equation*}
$$

It is well known that the topological dimension of $\mathbb{H}^{n}$ is $2 n+1$, since as a smooth manifold it coincides with $\mathbb{R}^{2 n+1}$, whereas the Hausdorff dimension of $\left(\mathbb{H}^{n}, d\right)$ is $Q:=2 n+2$.

We denote by $\mathfrak{h}$ the Lie algebra of the left invariant vector fields of $\mathbb{H}^{n}$. The standard basis of $\mathfrak{h}$ is given, for $i=1, \ldots, n$, by

$$
X_{i}:=\partial_{x_{i}}-\frac{1}{2} y_{i} \partial_{t}, \quad Y_{i}:=\partial_{y_{i}}+\frac{1}{2} x_{i} \partial_{t}, \quad T:=\partial_{t}
$$

The only non-trivial commutation relations are $\left[X_{j}, Y_{j}\right]=T$, for $j=1, \ldots, n$. The horizontal subspace $\mathfrak{h}_{1}$ is the subspace of $\mathfrak{h}$ spanned by $X_{1}, \ldots, X_{n}$ and $Y_{1}, \ldots, Y_{n}$. Coherently, from now on, we refer to $X_{1}, \ldots, X_{n}, Y_{1}, \ldots, Y_{n}$ (identified with first order differential operators) as to the horizontal derivatives. Denoting by $\mathfrak{h}_{2}$ the linear span of $T$, the 2-step stratification of $\mathfrak{h}$ is expressed by

$$
\mathfrak{h}=\mathfrak{h}_{1} \oplus \mathfrak{h}_{2} .
$$

The stratification of the Lie algebra $\mathfrak{h}$ induces a family of non-isotropic dilations $\delta_{\lambda}, \lambda>0$ in $\mathbb{H}^{n}$. The homogeneous dimension of $\mathbb{H}^{n}$ with respect to $\delta_{\lambda}, \lambda>0$ equals $Q$.

The vector space $\mathfrak{h}$ can be endowed with an inner product, indicated by $\langle\cdot, \cdot\rangle$, making $X_{1}, \ldots, X_{n}, Y_{1}, \ldots, Y_{n}$ and $T$ orthonormal.

Throughout this paper, we write also

$$
\begin{equation*}
W_{i}:=X_{i}, \quad W_{i+n}:=Y_{i}, \quad W_{2 n+1}:=T, \quad \text { for } i=1, \cdots, n \tag{5}
\end{equation*}
$$

The dual space of $\mathfrak{h}$ is denoted by $\bigwedge^{1} \mathfrak{h}$. The basis of $\Lambda^{1} \mathfrak{h}$, dual to the basis $\left\{X_{1}, \ldots, Y_{n}, T\right\}$, is the family of covectors $\left\{d x_{1}, \ldots, d x_{n}, d y_{1}, \ldots, d y_{n}, \theta\right\}$ where

$$
\theta:=d t-\frac{1}{2} \sum_{j=1}^{n}\left(x_{j} d y_{j}-y_{j} d x_{j}\right)
$$

is called the contact form in $\mathbb{H}^{n}$.
We indicate as $\langle\cdot, \cdot\rangle$ also the inner product in $\bigwedge^{1} \mathfrak{h}$ that makes $\left(d x_{1}, \ldots, d y_{n}, \theta\right)$ an orthonormal basis.

Coherently with the previous notation $\left(\frac{\text { campi }}{b}\right)$, we set

$$
\omega_{i}:=d x_{i}, \quad \omega_{i+n}:=d y_{i}, \quad \omega_{2 n+1}:=\theta, \quad \text { for } i=1, \cdots, n
$$

We put $\bigwedge_{0} \mathfrak{h}:=\bigwedge^{0} \mathfrak{h}=\mathbb{R}$ and, for $1 \leq k \leq 2 n+1$,

$$
\bigwedge^{k} \mathfrak{h}:=\operatorname{span}\left\{\omega_{i_{1}} \wedge \cdots \wedge \omega_{i_{k}}: 1 \leq i_{1}<\cdots<i_{k} \leq 2 n+1\right\}
$$

The volume $(2 n+1)$-form $\theta_{1} \wedge \cdots \wedge \theta_{2 n+1}$ will be also written as $d V$.
The same construction can be performed starting from the vector subspace $\mathfrak{h}_{1} \subset$ $\mathfrak{h}$, obtaining the horizontal $k$-covectors

$$
\bigwedge^{k} \mathfrak{h}_{1}:=\operatorname{span}\left\{\omega_{i_{1}} \wedge \cdots \wedge \omega_{i_{k}}: 1 \leq i_{1}<\cdots<i_{k} \leq 2 n\right\}
$$

weight Definition 3.1. If $\eta \neq 0, \eta \in \bigwedge^{1} \mathfrak{h}_{1}$, we say that $\eta$ has weight 1 , and we write $w(\eta)=1$. If $\eta=\theta$, we say $w(\eta)=2$. More generally, if $\eta \in \bigwedge^{h} \mathfrak{h}$, we say that $\eta$ has pure weight $k$ if $\eta$ is a linear combination of covectors $\omega_{i_{1}} \wedge \cdots \wedge \omega_{i_{h}}$ with $w\left(\omega_{i_{1}}\right)+\cdots+w\left(\omega_{i_{h}}\right)=k$.

Notice that, if $\eta, \zeta \in \bigwedge^{h} \mathfrak{h}$ and $w(\eta) \neq w(\zeta)$, then $\langle\eta, \zeta\rangle=0$.
3.2. Rumin's complex on Heisenberg groups. The exterior differential $d$ does not preserve weights. It splits into

$$
d=d_{0}+d_{1}+d_{2}
$$

where $d_{0}$ preserves weight, $d_{1}$ increases weight by 1 unit and $d_{2}$ increases weight by 2 units. $d_{0}$ is a differential operator of order 0 ; in degree $k$, it vanishes on forms of weight $k$ and if $\beta$ is a $k-1$-form of weight $k-1, d_{0}(\theta \wedge \beta)=d \theta \wedge \beta$. A first attempt in trying to invert $d$ is to invert $d_{0}$. For this, let us pick a complement $\mathcal{W}$ to $\operatorname{ker}\left(d_{0}\right)$ in $\Lambda^{\bullet} \mathfrak{h}$ and a complement $\mathcal{V}$ to $\operatorname{Im}\left(d_{0}\right)$ in $\Lambda^{\bullet} \mathfrak{h}$ containing $\mathcal{W}$. This allows to define $d_{0}^{-1}$ to be 0 on $\mathcal{V}$ and the inverse of $d_{0}: \mathcal{W} \rightarrow \operatorname{Im}\left(d_{0}\right)$. This defines a left-invariant order 0 operator on smooth forms on $\mathbb{H}^{n}$. Denote by $V$ (resp. W) the space of smooth sections of $\mathcal{V}($ resp. $\mathcal{W})$.

Rumin shows that

$$
r=1-d_{0}^{-1} d-d d_{0}^{-1}
$$

is the projector onto the subspace

$$
E=V \cap d^{-1} V
$$

along the subspace

$$
F=W+d W
$$

Hence, in the sequel, it will be denoted by $\Pi_{E}$. The weight-preserving part of $r$,

$$
r_{0}=1-d_{0}^{-1} d_{0}-d_{0} d_{0}^{-1}
$$

has order 0 , it is the projector onto $\mathcal{E}_{0}:=\mathcal{V} \cap \operatorname{ker}\left(d_{0}\right)$ along $\mathcal{W} \oplus \operatorname{Im}\left(d_{0}\right)$. Hence, in the sequel, it will be denoted by $\Pi_{E_{0}}$, where $E_{0}$ is the space of smooth sections of $\mathcal{E}_{0} . \Pi_{E_{0} \mid E}$ and $\Pi_{E \mid E_{0}}$ are inverses of each other. We use them to conjugate $d_{\mid E}$ to an operator

$$
d_{c}=\Pi_{E_{0}} d \Pi_{E} \Pi_{E_{0}}
$$

on $E_{0}$. By construction, the complex $\left(E_{0}, d_{c}\right)$ is isomorphic to $(E, d)$, which is homotopic to the full de Rham complex.
3.3. Contact manifolds. We now sketch Rumin's construction of the intrinsic complex for general contact manifolds $(M, H)$. Locally, $H$ is the kernel of a smooth contact 1-form $\theta$. Let $L: \Lambda^{\bullet} H^{*} \rightarrow \Lambda^{\bullet} H^{*}$ denote multiplication by $d \theta_{\mid H}$.

It is well known that, for every $h \leq n-1, L^{n-h}: \bigwedge^{h} H^{*} \rightarrow \bigwedge^{2 n-h} H^{*}$ is an isomorphism. It follows that $\operatorname{ker}\left(L^{n-h+1}\right)$ is a complement of $\operatorname{Im}(L)$ in $\bigwedge^{h} H^{*}$, if $h \leq n$, and that $\operatorname{Im}(L)=\bigwedge^{h} H^{*}$ if $h \geq n+1$. Therefore we set

$$
\mathcal{V}^{h}= \begin{cases}\left\{\alpha \in T^{*} M ; L^{n-h+1}\left(\alpha_{\mid H}\right)=0\right\} & \text { if } h \leq n \\ \left\{\alpha \in T^{*} M ; \alpha_{\mid H}=0\right\} & \text { otherwise }\end{cases}
$$

Similarly, $\operatorname{Im}\left(L^{h-n+1}\right)$ is a complement of $\operatorname{ker}(L)$ in $\bigwedge^{h} H^{*}$ if $h \geq n$, and $\operatorname{ker}(L)=$ $\{0\}$ in $\bigwedge^{h} H^{*}$ if $h \leq n-1$. Therefore we set

$$
\mathcal{W}^{h}= \begin{cases}\left\{\alpha \in T^{*} M ; \alpha_{\mid H}=0\right\} & \text { if } h \leq n-1, \\ \left\{\alpha \in T^{*} M ; \alpha \in \theta \wedge \operatorname{Im}\left(L^{h-n+1}\right)\right\} & \text { otherwise }\end{cases}
$$

Changing $\theta$ to an other smooth 1-form $\theta^{\prime}=f \theta$ with kernel $H$ does not change $\mathcal{V}$ and $\mathcal{W}$. With these choices, spaces of smooth sections $V$ and $W$ depend only on the plane field $H$. We can define subspaces of smooth differential forms $E=V \cap d^{-1} V$ and $F=W+d W$ and the projector $\Pi_{E}$. Since no extra choices are involved, $E, F$ and $\Pi_{E}$ are invariant under contactomorphisms.

In degrees $h \geq n+1, \mathcal{E}_{0}=\theta \wedge\left(\bigwedge^{h} H^{*} \cap \operatorname{ker}(L)\right)$ is a contact invariant. Since

$$
\left(\Pi_{E_{0}}\right)_{\mid E}=\left(\left(\Pi_{E}\right)_{\mid E_{0}}\right)^{-1}
$$

the operator $d_{c}=\left(\left(\Pi_{E}\right)_{\mid E_{0}}\right)^{-1} \circ d \circ\left(\Pi_{E}\right)_{\mid E_{0}}$ is a contact invariant.
In degrees $h \leq n$, the restriction of differential forms to $H$ is an isomorphism of $\mathcal{E}_{0}$ to $\mathcal{E}_{0}^{\prime}:=\bigwedge^{h} H^{*} \cap \operatorname{ker}\left(L^{n-h+1}\right)$. We note that for a differential form $\omega$ such that $\omega_{\mid H} \in \mathcal{E}_{0}^{\prime}, \Pi_{E}(\omega)$ only depends on $\omega_{\mid H}$. Indeed, $d_{0}^{-1} \omega=0$. Furthermore, if $\omega=\theta \wedge \beta, d_{0}^{-1} d \omega=d_{0}^{-1}(d \theta \wedge \beta)=\omega$, hence $\Pi_{E}(\omega)=\omega-d d_{0}^{-1} \omega=0$. It follows that $\left(\Pi_{E}\right)_{\mid E_{0}}$ can be viewed as defined on the space $E_{0}^{\prime}$ of sections of $\mathcal{E}_{0}^{\prime}$, which is a contact invariant. Since

$$
\left(\Pi_{E_{0}}\right)_{\mid E}=\left(\left(\Pi_{E}\right)_{\mid E_{0}}\right)^{-1}, \quad \text { it follows that }\left(\Pi_{E_{0}^{\prime}}\right)_{\mid E}=\left(\left(\Pi_{E}\right)_{\mid E_{0}^{\prime}}\right)^{-1}
$$

and $d_{c}$ viewed as an operator on $E_{0}^{\prime}$,

$$
\left(\left(\Pi_{E}\right)_{\mid E_{0}^{\prime}}\right)^{-1} \circ d \circ\left(\Pi_{E}\right)_{\mid E_{0}^{\prime}}
$$

is a contact invariant. In the sequel, we shall ignore the distinction between $E_{0}$ and $E_{0}^{\prime}$. The connection with the description provided in the introduction is easy.

Ale and BEGN.

By construction,
i) $d_{c}^{2}=0$;
ii) the complex $\mathcal{E}_{0}:=\left(E_{0}^{\bullet}, d_{c}\right)$ is homotopically equivalent to the de Rham complex $\Omega:=\left(\Omega^{\bullet}, d\right)$. Thus, if $D \subset \mathbb{H}^{n}$ is an open set, unambiguously we write $H^{h}(D)$ for the $h$-th cohomology group;
iii) $d_{c}: E_{0}^{h} \rightarrow E_{0}^{h+1}$ is a homogeneous differential operator in the horizontal derivatives of order 1 if $h \neq n$, whereas $d_{c}: E_{0}^{n} \rightarrow E_{0}^{n+1}$ is an homogeneous differential operator in the horizontal derivatives of order 2 .
Since the exterior differential $d_{c}$ on $E_{0}^{h}$ can be written in coordinates as a leftinvariant homogeneous differential operator in the horizontal variables of order 1 if $h \neq n$ and of order 2 if $h=n$, the proof of the following Leibniz' formula is easy.
leibniz Lemma 3.2. If $\zeta$ is a smooth real function, then

- if $h \neq n$, then on $E_{0}^{h}$ we have:

$$
\left[d_{c}, \zeta\right]=P_{0}^{h}(W \zeta)
$$

where $P_{0}^{h}(W \zeta): E_{0}^{h} \rightarrow E_{0}^{h+1}$ is a homogeneous differential operator of degree zero with coefficients depending only on the horizontal derivatives of $\zeta$;

- if $h=n$, then on $E_{0}^{n}$ we have

$$
\left[d_{c}, \zeta\right]=P_{1}^{n}(W \zeta)+P_{0}^{n}\left(W^{2} \zeta\right)
$$

where $P_{1}^{n}(W \zeta): E_{0}^{n} \rightarrow E_{0}^{n+1}$ is a homogeneous differential operator of degree 1 with coefficients depending only on the horizontal derivatives of $\zeta$, and where $P_{0}^{h}\left(W^{2} \zeta\right): E_{0}^{n} \rightarrow E_{0}^{n+1}$ is a homogeneous differential operator in the horizontal derivatives of degree 0 with coefficients depending only on second order horizontal derivatives of $\zeta$.

## 4. Kernels

If $f$ is a real function defined in $\mathbb{H}^{n}$, we denote by ${ }^{\mathrm{v}} f$ the function defined by ${ }^{\mathrm{v}} f(p):=f\left(p^{-1}\right)$, and, if $T \in \mathcal{D}^{\prime}\left(\mathbb{H}^{n}\right)$, then ${ }^{\mathrm{v}} T$ is the distribution defined by $\left\langle{ }^{\mathrm{v}} T \mid \phi\right\rangle:=\left\langle\left. T\right|^{\mathrm{v}} \phi\right\rangle$ for any test function $\phi$.

Following e.g. [8], we can define a group convolution in $\mathbb{H}^{n}$ : if, for instance, $f \in \mathcal{D}\left(\mathbb{H}^{n}\right)$ and $g \in L_{\mathrm{loc}}^{1}\left(\mathbb{H}^{n}\right)$, we set

$$
\begin{equation*}
f * g(p):=\int f(q) g\left(q^{-1} \cdot p\right) d q \quad \text { for } q \in \mathbb{H}^{n} \tag{6}
\end{equation*}
$$

We remind that, if (say) $g$ is a smooth function and $P$ is a left invariant differential operator, then

$$
P(f * g)=f * P g
$$

We remind also that the convolution is again well defined when $f, g \in \mathcal{D}^{\prime}\left(\mathbb{H}^{n}\right)$, provided at least one of them has compact support. In this case the following identities hold

$$
\begin{equation*}
\langle f * g \mid \phi\rangle=\left\langle\left. g\right|^{\mathrm{v}} f * \phi\right\rangle \quad \text { and } \quad\langle f * g \mid \phi\rangle=\left\langle f \mid \phi *^{\mathrm{v}} g\right\rangle \tag{7}
\end{equation*}
$$

for any test function $\phi$.
As in [8], we also adopt the following multi-index notation for higher-order derivatives. If $I=\left(i_{1}, \ldots, i_{2 n+1}\right)$ is a multi-index, we set $W^{I}=W_{1}^{i_{1}} \cdots W_{2 n}^{i_{2 n}} T^{i_{2 n+1}}$. By the Poincaré-Birkhoff-Witt theorem, the differential operators $W^{I}$ form a basis for the algebra of left invariant differential operators in $\mathbb{H}^{n}$. Furthermore, we set $|I|:=i_{1}+\cdots+i_{2 n}+i_{2 n+1}$ the order of the differential operator $W^{I}$, and $d(I):=i_{1}+\cdots+i_{2 n}+2 i_{2 n+1}$ its degree of homogeneity with respect to group dilations.

Suppose now $f \in \mathcal{E}^{\prime}\left(\mathbb{H}^{n}\right)$ and $g \in \mathcal{D}^{\prime}\left(\mathbb{H}^{n}\right)$. Then, if $\psi \in \mathcal{D}\left(\mathbb{H}^{n}\right)$, we have

$$
\begin{align*}
\left\langle\left(W^{I} f\right) * g \mid \psi\right\rangle & =\left\langle W^{I} f \mid \psi *{ }^{\mathrm{v}} g\right\rangle=(-1)^{|I|}\left\langle f \mid \psi *\left(W^{I} \mathrm{v} g\right)\right\rangle \\
& =(-1)^{|I|}\left\langle f *^{\mathrm{v}} W^{I \mathrm{v}} g \mid \psi\right\rangle \tag{8}
\end{align*}
$$

folland
Following $\frac{f 0 l l}{[7] \text {, we }}$ remind now the notion of kernel of type $\mu$.
Definition 4.1. A kernel of type $\mu$ is a homogeneous distribution of degree $\mu-Q$ (with respect to group dilations $\delta_{r}$ ), that is smooth outside of the origin.

The convolution operator with a kernel of type $\mu$ is still called an operator of type $\mu$.
kernel Proposition 4.2. Let $K \in \mathcal{D}^{\prime}\left(\mathbb{H}^{n}\right)$ be a kernel of type $\mu$.
i) ${ }^{\mathrm{v}} K$ is again a kernel of type $\mu$;
ii) $W K$ and $K W$ are associated with kernels of type $\mu-1$ for any horizontal derivative $W$;
iii) If $\mu>0$, then $K \in L_{\mathrm{loc}}^{1}\left(\mathbb{H}^{n}\right)$.

Theorem 4.3. Suppose $0<\alpha<Q$, and let $K$ be a kernel of type $\alpha$. Then
i) if $1<p<Q / \alpha$, and $1 / q:=1 / p-\alpha / Q$, then

$$
\|u * K\|_{L^{q}\left(\mathbb{H}^{n}\right)} \leq C\|u\|_{L^{p}\left(\mathbb{H}^{n}\right)}
$$

for all $u \in L^{p}\left(\mathbb{H}^{n}\right)$.
ii) If $p \geq Q / \alpha$ and $B, B^{\prime} \subset \mathbb{H}^{n}$ are fixed balls, then for any $q \geq p$

$$
\|u * K\|_{L^{q}\left(B^{\prime}\right)} \leq C\|u\|_{L^{p}\left(\mathbb{H}^{n}\right)}
$$

for all $u \in L^{p}\left(\mathbb{H}^{n}\right)$ with $\operatorname{supp} u \subset B$.
iii) If $K$ is a kernel of type 0 and $1<p<\infty$, then

$$
\|u * K\|_{L^{p}\left(\mathbb{H}^{n}\right)} \leq C\|u\|_{L^{p}\left(\mathbb{H}^{n}\right)}
$$

Proof. For statements i) and iii), we refer to $\frac{\| f 011 \text { and }}{[7]}$, Propositions 1.11 and 1.9. As for ii), if $p \geq Q / \alpha$, we choose $1<\tilde{p}<Q / \alpha$ such that $1 / \tilde{p} \leq 1 / q+\alpha / Q$. If we set $1 / \tilde{q}:=1 / \tilde{p}-\alpha / Q<1 / q$, then

$$
\begin{gathered}
\|u * K\|_{L^{q}\left(B^{\prime}\right)} \leq C_{B^{\prime}}\|u * K\|_{L^{\tilde{q}}\left(B^{\prime}\right)} \leq C_{B^{\prime}}\|u * K\|_{L^{\tilde{q}\left(\mathbb{H}^{n}\right)}} \\
\leq C^{\prime}\left(B^{\prime}\right)\|u\|_{L^{\tilde{p}}\left(\mathbb{H}^{n}\right)} \leq C^{\prime}\left(B, B^{\prime}\right)\|u\|_{L^{p}(B)}
\end{gathered}
$$

truncation Lemma 4.4. Suppose $0<\alpha<Q$. If $K$ is a kernel of type $\alpha$ and $\psi \in \mathcal{D}\left(\mathbb{H}^{n}\right)$,作忈folinand neighborhood of the origin, then the statements i) and ii) of Proposition 4.3 still hold if we replace $K$ by $(1-\psi) K$.

Analogously if $K_{0}$ is a kernel of type 0 and $\psi \in \mathcal{D}\left(\mathbb{H}^{n}\right)$, then statement iii) of


Proof. As in $\left\lvert\, \frac{f 01 l}{}\right.$ and Proposition 1.11, we have only notice that $|(1-\psi) K(x)| \leq$ $C_{\psi}|x|^{\alpha-Q}$, so that $(1-\psi) K \in L^{Q /(Q-\alpha), \infty}\left(\mathbb{H}^{n}\right)$, and thereforet i) and ii) hold true.

Suppose now $\alpha=0$. Notice that $(\psi-1) K \in L^{1, \infty}\left(\mathbb{H}^{n}\right)$, and therefore also $u \rightarrow((\psi-1) K) * u$ is $L^{p}-L^{p}$ continuous by Hausdorff-Young Theorem. This proves that iii) holds true.
truncation rem
Remark 4.5. By Theorem $\frac{\text { h1s folland }}{4.3, \text { Lemma }} \frac{\text { truncation }}{4.4 \text { stall holds if we replace }(1-\psi) K \text { by }}$ $\psi K$.

The following (well known) estimate will be useful in the sequel.
pointwise Lemma 4.6. Let $g$ be a a kernel of type $\mu>0$. Then, if $f \in \mathcal{D}\left(\mathbb{H}^{n}\right)$ and $R$ is an homogeneous polynomial of degree $\ell \geq 0$ in the horizontal derivatives, we have

$$
R(f * g)(p)=O\left(|p|^{\mu-Q-\ell}\right) \quad \text { as } p \rightarrow \infty
$$

On the other hand, if $g$ is a smooth function in $\mathbb{H}^{n} \backslash\{0\}$ that satisfies the logarithmic estimate $|g(p)| \leq C(1+|\ln | p| |)$ and in addition its horizontal derivatives are homogeneous of degree -1 with respect to group dilations, then, if $f \in \mathcal{D}\left(\mathbb{H}^{n}\right)$ and $R$ is an homogeneous polynomial of degree $\ell \geq 0$ in the horizontal derivatives, we have

$$
\begin{array}{lll}
R(f * g)(p) & =O\left(|p|^{-\ell}\right) & \text { as } p \rightarrow \infty
\end{array} \quad \text { if } \ell>0 ; ~ 子 O(\ln |p|) \quad \text { as } p \rightarrow \infty \quad \text { if } \ell=0 .
$$

Since we have fixed a left-invariant moving frame for $E_{0}^{\bullet}$, a $\left(N_{h} \times N_{k}\right)$-matrix whose entries are kernels of type $\alpha$ defines in a natural way an operator from $E_{0}^{h}$ to $E_{0}^{k}$. We still refer to this operator as to an operator associated with a (matrixvalued) kernel of type $\alpha$.
rumin laplacian
 ting

$$
\Delta_{\mathbb{H}, h}= \begin{cases}d_{c} \delta_{c}+\delta_{c} d_{c} & \text { if } \quad h \neq n, n+1 ; \\ \left(d_{c} \delta_{c}\right)^{2}+\delta_{c} d_{c} & \text { if } h=n ; \\ d_{c} \delta_{c}+\left(\delta_{c} d_{c}\right)^{2} & \text { if } \quad h=n+1 .\end{cases}
$$

Notice that $-\Delta_{\mathbb{H}, 0}=\sum_{j=1}^{2 n}\left(W_{j}^{2}\right)$ is the usual sub-Laplacian of $\mathbb{H}^{n}$.
For sake of simplicity, since a basis of $E_{0}^{h}$ is fixed, the operator $\Delta_{\mathbb{H}, h}$ can be identified with a matrix-valued map, still denoted by $\Delta_{\mathbb{H}, h}$

$$
\begin{equation*}
\Delta_{\mathbb{H}, h}=\left(\Delta_{\mathbb{H}, h}^{i j}\right)_{i, j=1, \ldots, N_{h}}: \mathcal{D}^{\prime}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right) \rightarrow \mathcal{D}^{\prime}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right) \tag{9}
\end{equation*}
$$

where $\mathcal{D}^{\prime}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right)$ is the space of vector-valued distributions on $\mathbb{H}^{n}$.
This identification makes possible to avoid the notion of currents: we refer to BFTT for a more elegant presentation.

It is proved in $\frac{18 \text { that } n_{\mathbb{H}}, h \text { is hypoelliptic and maximal hypoelliptic in the }}{}$ sense of $[2]$. In general, if $\mathcal{L}$ is a differential operator on $\mathcal{D}^{\prime}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right)$, then $\mathcal{L}$ is said hypoelliptic if for any open set $\mathcal{V} \subset \mathbb{H}^{n}$ where $\mathcal{L} \alpha$ is smooth, then $\alpha$ is smooth in $\mathcal{V}$. In addition, if $\mathcal{L}$ is homogeneous of degree $a \in \mathbb{N}$, we say that $\mathcal{L}$ is maximal hypoelliptic if for any $\delta>0$ there exists $C=C(\delta)>0$ such that for any homogeneous polynomial $P$ in $W_{1}, \ldots, W_{2 n}$ of degree $a$ we have

$$
\|P \alpha\|_{L^{2}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right)} \leq C\left(\|\mathcal{L} \alpha\|_{L^{2}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right)}+\|\alpha\|_{L^{2}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right)}\right) .
$$

for any $\alpha \in \mathcal{D}\left(B B_{\text {furfin }}\left(0, \delta_{d}\right), \mathbb{R}^{N_{h}}\right)$.
Combining [18], Section 3, and [3], Theorems 3.1 and 4.1, we obtain the following result.
Theorem 4.8 (see I IFP, Theorem 4.6). If $0 \leq h \leq 2 n+1$, then the differential operator $\Delta_{\mathbb{H}, h}$ is hypoelliptic of order $a$, where $a=2$ if $h \neq n, n+1$ and $a=4$ if $h=n, n+1$ with respect to group dilations. Then
i) for $j=1, \ldots, N_{h}$ there exists

$$
\begin{equation*}
K_{j}=\left(K_{1 j}, \ldots, K_{N_{h} j}\right), \quad j=1, \ldots N_{h} \tag{10}
\end{equation*}
$$

with $K_{i j} \in \mathcal{D}^{\prime}\left(\mathbb{H}^{n}\right) \cap \mathcal{E}\left(\mathbb{H}^{n} \backslash\{0\}\right), i, j=1, \ldots, N$;
ii) if $a<Q$, then the $K_{i j}$ 's are kernels of type a for $i, j=1, \ldots, N_{h}$

If $a=Q$, then the $K_{i j}$ 's satisfy the logarithmic estimate $\left|K_{i j}(p)\right| \leq$ $C(1+|\ln \rho(p)|)$ and hence belong to $L_{\mathrm{loc}}^{1}\left(\mathbb{H}^{n}\right)$. Moreover, their horizontal derivatives $W_{\ell} K_{i j}, \ell=1, \ldots, 2 n$, are kernels of type $Q-1$;
iii) when $\alpha \in \mathcal{D}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right)$, if we set

$$
\begin{equation*}
\mathcal{K} \alpha:=\left(\sum_{j} \alpha_{j} * K_{1 j}, \ldots, \sum_{j} \alpha_{j} * K_{N_{h} j}\right) \tag{11}
\end{equation*}
$$

then $\Delta_{\mathbb{H}, h} \mathcal{K} \alpha=\alpha$. Moreover, if $a<Q$, also $\mathcal{K} \Delta_{\mathbb{H}, h} \alpha=\alpha$.
iv) if $a=Q$, then for any $\alpha \in \mathcal{D}\left(\mathbb{H}^{n}, \mathbb{R}^{N_{h}}\right)$ there exists $\beta_{\alpha}:=\left(\beta_{1}, \ldots, \beta_{N_{h}}\right) \in$ $\mathbb{R}^{N_{h}}$, such that

$$
\mathcal{K} \Delta_{\mathbb{H}, h} \alpha-\alpha=\beta_{\alpha} .
$$

K Remark 4.9. Coherently with formula ( $\frac{(\mathrm{matrix} \text { form }}{\boldsymbol{9}) \text {, the operator } \mathcal{K} \text { can be identified with }}$ an operator (still denoted by $\mathcal{K}$ ) acting on smooth compactly supported differential forms in $\mathcal{D}\left(\mathbb{H}^{n}, E_{0}^{h}\right)$. Moreover, when the notation will not be misleading, we shall denote by $\alpha \rightarrow \Delta_{\mathbb{H}, h}^{-1} \alpha$ the convolution with $\mathcal{K}$ acting on forms of degree $h$.
comm
Lemma 4.10. If $\alpha \in \mathcal{D}\left(\mathbb{H}^{n}, E_{0}^{h}\right)$
i) $d_{c} \Delta_{\mathbb{H}, h}^{-1} \alpha=\Delta_{\mathbb{H}, h+1}^{-1} d_{c} \alpha, \quad h=0,1, \ldots, 2 n, \quad h \neq n-1, n+1$.
ii) $d_{c} \Delta_{\mathbb{H}, n-1}^{-1} \alpha=d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1} d_{c} \alpha \quad(h=n-1)$.
iii) $d_{c} \delta_{c} d_{c} \Delta_{\mathbb{H}, n+1}^{-1} \alpha=\Delta_{\mathbb{H}, n+2}^{-1} d_{c} \alpha$, $\quad(h=n+1)$.
iv) $\delta_{c} \Delta_{\mathbb{H}, h}^{-1} \alpha=\Delta_{\mathbb{H}, h-1}^{-1} \delta_{c} \alpha \quad h=1, \ldots, 2 n+1, \quad h \neq n, n+2$.
v) $\delta_{c} \Delta_{\mathbb{H}, n+2}^{-1} \alpha=\delta_{c} d_{c} \Delta_{\mathbb{H}, n+1}^{-1} \delta_{c} \alpha \quad(h=n+2)$.
vi) $\delta_{c} d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1} \alpha=\Delta_{\mathbb{H}, n-1}^{-1} \delta_{c} \alpha, \quad(h=n)$.

Proof. Let us prove i), ii), iii). The remaining assertions will follow by Hodge duality. Put

$$
\begin{aligned}
& \omega_{h}:=d_{c} \Delta_{\mathbb{H}, h}^{-1} \alpha-\Delta_{\mathbb{H}, h+1}^{-1} d_{c} \alpha \quad \text { if } h \neq n-1, n+1, \\
& \omega_{n-1}:=d_{c} \Delta_{\mathbb{H}, n-1}^{-1} \alpha-d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1} d_{c} \alpha \\
& \omega_{n+1}:=d_{c} \delta_{c} d_{c} \Delta_{\mathbb{H}, n+1}^{-1} \alpha-\Delta_{\mathbb{H}}^{-1}, n+2 \\
& c_{c} \alpha .
\end{aligned}
$$

 $\omega_{h}=M_{h} * \alpha$, where $M_{h}$ is a kernel of type 1 . Thus, by Lemma 4.6

$$
\omega_{h}(x)=O\left(|x|^{1-Q}\right) \quad \text { as } x \rightarrow \infty
$$

We want to show now that

$$
\begin{equation*}
\Delta_{\mathbb{H}, h+1}^{-1} \omega_{h}=0 \quad \text { for } h=1, \ldots, 2 n \tag{13}
\end{equation*}
$$

Suppose first $h \neq n-1, n, n+1$. By Theorem $\frac{g l o b a l ~ s o l u t i o n ~}{4.8, \text { we have: }}$

$$
\begin{aligned}
\Delta_{\mathbb{H}, h+1} \omega_{h} & =d_{c} \delta_{c} d_{c} \Delta_{\mathbb{H}, h}^{-1} \alpha-d_{c} \alpha \\
& =d_{c} \Delta_{\mathbb{H}, h} \Delta_{\mathbb{H}, h}^{-1} \alpha-d_{c} \alpha=0 .
\end{aligned}
$$

If $h=n-1$, then

$$
\begin{aligned}
\Delta_{\mathbb{H}, n} \omega_{n-1} & =d_{c} \delta_{c} d_{c} \delta_{c}\left(d_{c} \Delta_{\mathbb{H}, n-1}^{-1} \alpha-d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1} d_{c} \alpha\right) \\
& =d_{c} \delta_{c} d_{c} \Delta_{\mathbb{H}, n-1} \Delta_{\mathbb{H}, n-1}^{-1} \alpha-d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1} \Delta_{\mathbb{H}, n}^{-1} d_{c} \alpha=0 .
\end{aligned}
$$

If $h=n$, then (keeping in mind that $d_{c} \Delta_{\mathbb{H}, n}^{-1} \alpha$ is a form of degree $n+1$ and $\Delta_{\mathbb{H}, n}^{-1} \alpha$ is a form of degree $n$ )

$$
\begin{aligned}
\Delta_{\mathbb{H}, n+1} \omega_{n} & =\left(\left(\delta_{c} d_{c}\right)^{2}+d_{c} \delta_{c}\right) d_{c} \Delta_{\mathbb{H}, n}^{-1} \alpha-d_{c} \alpha \\
& =d_{c}\left(\delta_{c} d_{c}+\left(d_{c} \delta_{c}\right)^{2}\right) \Delta_{\mathbb{H}, n}^{-1} \alpha-d_{c} \alpha \\
& =d_{c} \Delta_{\mathbb{H}, n} \Delta_{\mathbb{H}, n}^{-1} \alpha-d_{c} \alpha=0 .
\end{aligned}
$$

Finally, if $h=n+1$, then

$$
\begin{aligned}
\Delta_{\mathbb{H}, n+2} \omega_{n+1} & =d_{c} \delta_{c} d_{c} \delta_{c} d_{c} \Delta_{\mathbb{H}, n+1}^{-1} \alpha-d_{c} \alpha \\
& =d_{c} \Delta_{\mathbb{H}, n+1} \Delta_{\mathbb{H}, n+1}^{-1} \alpha-d_{c} \alpha=0
\end{aligned}
$$

This proves (harmonic
Thus, by $\left[\frac{B E T 3}{}\right]$, Proposition $3.2, \omega$ is a polynomial coefficient form. Then, by (inf) necessarily $\omega \equiv 0$.

This proves i), ii), iii).
5.1. Sobolev spaces. Since here we are dealing only with integer order FollandStein function spaces, we can give this simpler definition (for a general presentation, see e.g. [7].
integer spaces
Definition 5.1. If $U \subset \mathbb{H}^{n}$ is an open set, $1 \leq p \leq \infty$ and $m \in \mathbb{N}$, then the space $W^{m, p}(U)$ is the space of all $u \in L^{p}(U)$ such that
$W^{I} u \in L^{p}(U) \quad$ for all multi-indices $I$ with $d(I)=m$,
endowed with the natural norm.
Theorem 5.2. If $U \subset \mathbb{H}^{n}, 1 \leq p<\infty$, and $k \in \mathbb{N}$, then
i) $W^{k, p}(U)$ is a Banach space;
ii) $W^{k, p}(U) \cap C^{\infty}(U)$ is dense in $W^{k, p}(U)$;
iii) if $U=\mathbb{H}^{n}$, then $\mathcal{D}\left(\mathbb{H}^{n}\right)$ is dense in $W^{k, p}(U)$.

Definition 5.3. If $1 \leq p<\infty$, we denote by $\stackrel{\circ}{W}^{k, p}(U)$ the completion of $\mathcal{P}\left({ }_{j}(U)\right.$ isison $W^{k, p}(U)$. If $U$ is bounded, then by (iterated) Poincaré inequality (see e.g. [14]), it follows that the norms

$$
\|u\|_{W^{k, p}(U)} \quad \text { and } \quad \sum_{d(I)=k}\left\|W^{I} u\right\|_{L^{p}(U)}
$$

are equivalent on $\stackrel{\circ}{W}^{k, p}(U)$ when $1 \leq p<\infty$.

Finally, $W_{\text {Euc }}^{k, p}(U)$ denotes the usual Sobolev space.

### 5.2. Negative spaces.

negative spaces
Definition 5.4. If $U \subset \mathbb{H}^{n}$ is an open set and $1<p<\infty, W^{-k, p}(U)$ is the dual space of ${ }^{\circ}{ }^{k, p^{\prime}}(U)$, where $1 / p+1 / p^{\prime}=1$. It is well known that

$$
W^{-k, p}(U)=\left\{f_{0}+\sum_{d(I)=k} W^{I} f_{I}, f_{0}, f_{I} \in L^{p}(U) \text { for any } I \text { such that } d(I)=k\right\}
$$

and

$$
\|u\|_{W^{-k, p}(U)} \approx \inf \left\{\left\|f_{0}\right\|_{L^{p}(U)}+\sum_{I}\left\|f_{I}\right\|_{L^{p}(U)} ; d(I)=k, f_{0}+\sum_{d(I)=k} W^{I} f_{I}=u\right\} .
$$

If $U$ is bounded, then we can take $f_{0}=0$.
Finally, we stress that

$$
\left\{f_{0}+\sum_{d(I)=k} W^{I} f_{I}, f_{0}, f_{I} \in \mathcal{D}(U) \text { for any } I \text { such that } d(I)=k\right\}
$$

is dense in $W^{-k, p}(U)$.
dual spaces forms
Definition 5.5. If $U \subset \mathbb{H}^{n}$ is an open set, $0 \leq h \leq 2 n+1,1 \leq p \leq \infty$ and $m \geq 0$, we denote by $W^{m, p}\left(U, \bigwedge^{h} \mathfrak{h}\right)\left(b y \stackrel{\circ}{W}^{m, p}\left(U, \bigwedge^{h} \mathfrak{h}\right)\right)$ the space of all sections of $\bigwedge^{h} \mathfrak{h}$ such that their components with respect to a given left-invariant frame belong to $W^{m, p}(U)\left(\right.$ to $\stackrel{\circ}{W}^{m, p}(U)$, respectively), endowed with its natural norm. Clearly, this definition is independent of the choice of the frame itself.

The spaces $W^{m, p}\left(U, E_{0}^{h}\right)$ and $\stackrel{\circ}{W}^{m, p}\left(U, E_{0}^{h}\right)$ are defined in the same way.
On the other hand, the spaces

$$
W^{-m, p}\left(U, E_{0}^{h}\right):=\left(\stackrel{\circ}{W}^{m, p^{\prime}}\left(U, E_{0}^{h}\right)\right)^{*}
$$

canhe viewed as spaces of currents on $\left(E_{0}^{\bullet}, d_{c}\right)$ as in $\frac{\text { BFTT }}{[2]}$, Proposition 3.14. Again as in $\frac{\beta 21 \mathrm{~L}}{[2],}$ Proposition 3.14, an element of $W^{-m, p}\left(U, E_{0}^{h}\right)$ can be identified (with respect to our basis) with a $N_{h}$-ple

$$
\left(T_{1}, \ldots, T_{N_{h}}\right) \in\left(W^{-m, p}\left(U, E_{0}^{h}\right)\right)^{N_{h}}
$$

(this is nothing but the intuitive notion of "currents as differential form with distributional coefficients"). The action of $u \in W^{-m, p}\left(U, E_{0}^{h}\right)$ associated with $\left(T_{1}, \ldots, T_{N_{h}}\right)$ on the form $\sum_{j} \alpha_{j} \xi_{j}^{h} \in \stackrel{\circ}{W}^{m, p^{\prime}}\left(U, E_{0}^{h}\right)$ is given by

$$
\langle u \mid \alpha\rangle:=\sum_{j}\left\langle T_{j} \mid \alpha_{j}\right\rangle
$$

On the other hand, suppose for sake of simplicity that $U$ is bounded, then by Definition 5.4 there exvst $f_{I}^{j} \in L^{p}(U), j=1, \ldots, N_{h}, i=1, \ldots, 2 n+1$ such that

$$
\begin{equation*}
\langle u \mid \alpha\rangle=\sum_{j} \sum_{d(I)=m} \int_{U} f_{I}^{j}(x) W^{I} \alpha_{j}(x) d x \tag{14}
\end{equation*}
$$

Alternatively, one can express duality in spaces of differential forms using the pairing between $h$-forms and $2 n+1-h$-forms defined by

$$
\alpha, \beta \mapsto \int_{U} \alpha \wedge \beta
$$

Note that this makes sense for Rumin forms and is a nondegenerate pairing. In this manner, the dual of $L^{p}\left(U, E_{0}^{h}\right)$ is $L^{p^{\prime}}\left(U, E_{0}^{2 n+1-h}\right)$. Hence $W^{-m, p}\left(U, E_{0}^{h}\right)$ consists of differential forms of degree $2 n+1-h$ whose coefficients are distributions belonging to $W^{-m, p}(U)$.

### 5.3. Contact invariance.

Lemma 5.6. Let $U$, $V$ be open subsets of $\mathbb{H}^{n}$. Let $\phi: U \rightarrow V$ be a $C^{k}$-bounded contact diffeomorphism. Let $\ell=-k+1, \ldots, k-1$. Then the pull-back operator $\phi^{\sharp}$ from $W^{\ell, p}$ forms on $V$ to $W^{\ell, p}$ forms on $U$ is bounded, and its norm depends only on the $C^{k}$ norms of $\phi$ and $\phi^{-1}$.

When $\ell \geq 0$, this follows from the chain rule and the change of variables formula. According to the change of variables formula

$$
\int_{U} \phi^{\sharp} \alpha \wedge \phi^{\sharp} \beta=\int_{V} \alpha \wedge \beta,
$$

the adjoint of $\phi^{\sharp}$ with respect to the above pairing is $\left(\phi^{-1}\right)^{\sharp}$. Hence $\phi^{\sharp}$ is bounded on negative Sobolev spaces of differential forms as well.
5.4. Sobolev spaces on contact sub-Riemannian manifolds. We define Sobolev spaces (involving a positive or negative number of derivatives) on bounded geometry contact sub-Riemannian manifolds.

Let $(M, H, g)$ be a bounded $C^{k}$-geometry sub-Riemannian contact manifold. Pick a uniform covering $\mathcal{U}$ by equal radius balls (uniform means that distances between centers are bounded below). Let $\phi_{j}: B \rightarrow U_{j}$ be $C^{k}$-bounded contact charts from the unit Heisenberg ball. Given a differential form $\omega$ on $M$, let $\omega_{j}=\phi_{j}^{\sharp} \omega$. Let $-k+1 \leq \ell \leq k-1$ be an integer. Define

$$
\|\omega\|_{\mathcal{U}, \ell, p}=\left(\sum_{j}\left\|\omega_{j}\right\|_{W^{\ell, p}(B)}^{p}\right)^{1 / p}
$$

Let us show that an other uniform covering $\mathcal{U}^{\prime}$ and other choices of controlled charts lead to an equivalent norm. Every piece $U$ of $\mathcal{U}$ is covered with boundedly many pieces $U_{i}^{\prime}$ of $\mathcal{U}^{\prime}$. Thus

$$
\left\|\omega_{j}\right\|_{W^{\ell, p}}^{p} \leq \sum\left\|\omega_{j \mid \phi_{j}-1}\left(U_{i}^{\prime}\right)\right\|_{W^{\ell, p}\left(\phi_{j}-1\left(U_{i}^{\prime}\right)\right)}^{p}
$$

Since $\omega_{j \mid \phi_{j}-1\left(U_{i}^{\prime}\right)}$ is the pull-back by the contactomorphism $\phi=\phi_{j} \circ \phi_{i}^{\prime-1}$ of $\omega_{i \mid \phi_{i}^{\prime-1}\left(U_{j}\right)}$, Lemma 5.6 implies that

$$
\left\|\omega_{j \mid \phi_{j}-1\left(U_{i}^{\prime}\right)}\right\|_{W^{\ell, p}\left(\phi_{j}^{-1}\left(U_{i}^{\prime}\right)\right)} \leq C\left\|\omega_{i \mid \phi_{i}^{\prime}-1}\left(U_{j}\right)\right\|_{W^{\ell, p}\left(\phi_{i}^{\prime-1}\left(U_{j}\right)\right)}
$$

where the constant only depends on the uniform bound on horizontal derivatives of order $\leq k$ of $\phi$. Thus

$$
\left\|\omega_{j}\right\|_{W^{\ell, p}}^{p} \leq \sum\left\|\omega_{i}^{\prime}\right\|_{W^{\ell, p}(B)}^{p}
$$

When summing over $j$, each term $\left\|\omega_{i}^{\prime}\right\|$ on the right hand side occurs only a bounded number $N$ of times. This yields

$$
\|\omega\|_{\mathcal{U}, \ell, p} \leq C N^{1 / p}\|\omega\|_{\mathcal{U}^{\prime}, \ell, p} .
$$

## 6. Номotopy formulae and Poincaré and Sobolev inequalities

In this paper we are mainly interested to obtain functional inequalities for differential forms that are the counterparts of the classical $(p, q)$-Sobolev and Poincaré inequalities on a ball $B \subset \mathbb{R}^{n}$ with sharp exponents of the form

$$
\left\|u-u_{B}\right\|_{L^{q}}(B) \leq C(r)\|\nabla u\|_{L^{p}}(B)
$$

(as well as of its counterpart for compactly supported functions). In this case, we can choose $q=p n /(n-p)$, provided $p<n$.

Definition 6.1. Take $\lambda>1$ and set $B=B(e, 1)$ and $B^{\prime}=B(e, \lambda)$, where the $B(x, r)$ 's are the Korányi balls in $\mathbb{H}^{n}$ (in particular the balls centered at $x=e$, and then all balls, are convex). If $1 \leq k \leq 2 n+1$ and $q \geq p \geq 1$, we say that the interior $(p, q)$-Poincaré inequality holds in $E_{0}^{k}$ if there exists a constant $C$ such that, for every $d_{c}$-closed differential $k$-form $\omega$ in $L^{p}\left(B^{\prime} ; E_{0}^{k}\right)$ there exists a differential $k-1$-form $\phi$ in $L^{q}\left(B, E_{0}^{k-1}\right)$ such that $d_{c} \phi=\omega$ and

$$
\left.\|\phi\|_{L^{q}\left(B, E_{0}^{k-1}\right)} \leq C\|\omega\|_{L^{p}\left(B^{\prime}, E_{0}^{k}\right)} \quad \text { interior } \mathbb{H} \text {-Poincaré } e_{p, q}(k)\right) .
$$

Remark 6.2. If $k=1$ and $Q>p \geq 1$, then ( $\mathbb{H}$-Poincaré ${ }_{p, q}(1)$ ) is nothing but the


Remark 6.3. If we replace Rumin's complex $\left(E_{0}^{\mathbf{0}}, d_{c}\right)$ by the usual de Rham's complex $\left(\Omega^{\bullet}, d\right)$ in $\mathbb{R}^{2 n+1}$, then the $(p, q)$-Poincaré inequality holds on Euclidean balls for $k=1$ and $n>p \geq 1$. If $k>1$, then the $(p, q)$-Poincaré inequality for $2 n+1>p>1$ and $\frac{1}{p}-\frac{1}{q}=\frac{1}{2 n+1}$ is proved by Iwaniec \&3 Lutoborski (see $[3]$, Corollary 4.2).

The $\mathbb{H}$-Poincaré ${ }_{p, q}(k)$ inequality (as well as its Euclidean counterpart) can be formulated by duality as follows.
equiv Sobolev Definition 6.4. Take $\lambda>1$ and set $B=B(e, 1)$ and $B^{\prime}=B(e, \lambda)$. If $1 \leq k \leq 2 n$, $1 \leq p \leq q<\infty$ and $q \geq p$, we say that the (local) $\mathbb{H}-\operatorname{Sobolev}_{p, q}(k)$ inequality holds if there exists a constant $C$ such that for every compactly supported smooth $d_{c}$ closed differential $k$-form $\omega$ in $L^{p}\left(B ; E_{0}^{k}\right)$ there exists a smooth compactly supported differential $(k-1)$-form $\phi$ in $L^{q}\left(B^{\prime}, E_{0}^{k-1}\right)$ such that $d_{c} \phi=\omega$ in $B^{\prime}$ and

H Sobolev

$$
\begin{equation*}
\|\phi\|_{L^{q}\left(B^{\prime}, E_{0}^{k-1}\right)} \leq C\|\omega\|_{L^{p}\left(B, E_{0}^{k}\right)} . \tag{15}
\end{equation*}
$$

Notice that, in this case, we do not distinguish interior inequalities (in other words, we can always assume $B=B^{\prime}$ ), basically since, when dealing with compactly supported forms, the structure of the boundary does not affect the estimates.
sobolev k=1
Remark 6.5. If $k=1$ and $Q>p \geq 1$, then $\left(\mathbb{H}-\operatorname{Sobolev}_{p, q}(1)\right)$ is nothing but the usual Sobolev inequality with $\frac{1}{p}-\frac{1}{q}=\frac{1}{Q}$.

In $\left[\frac{\mathrm{L}}{[3]}\right]$, starting from Cartan's homotopy formula, the authors proved that, if $D \subset \mathbb{R}^{N}$ is a convex set, $1<p<\infty, 1<k<N$, then there exists a linear bounded map:

$$
\begin{equation*}
K_{\mathrm{Euc}, k}: L^{p}\left(D, \bigwedge^{k}\right) \rightarrow W^{1, p}\left(D, \bigwedge^{k-1}\right) \tag{16}
\end{equation*}
$$

that is a homotopy operator, i.e.

## may 4 eq:1

10 maggio eq:1

10 maggio eq:2
$\left.\left.\left.\left.\left\langle K_{y} \omega(x)\right| \xi_{1} \wedge \cdots \wedge \xi_{k-1}\right)\right\rangle:=\int_{0}^{1} t^{k-1}\langle\omega(t x+(1-t) y)|(x-y) \wedge \xi_{1} \wedge \cdots \wedge \xi_{k-1}\right)\right\rangle$.
Starting from $\frac{\mathbb{L} 13]}{13}$, in $\frac{\text { mitrea_mitrea_monniaux }}{16] \text {, Section } 4, \text { the authors define a compact homotopy op- }}$ erator $J_{\text {Euc }, k}$ in Lipschitz star-shaped domains in the Euclidean space $\mathbb{R}^{N}$, providing an explicit representation formulas for $J_{\mathrm{Euc}, k}$, together with continuity properties among Sobolev spaces. More precisely, if $D \subset \mathbb{R}^{N}$ is a star-shaped Lipschitz domain and $1<k<N$, then there exists

$$
J_{\mathrm{Euc}, k}: L^{p}\left(D, \bigwedge^{k}\right) \rightarrow W_{0}^{1, p}\left(D, \bigwedge^{k-1}\right)
$$

such that

$$
\omega=d J_{\mathrm{Euc}, k} \omega+J_{\mathrm{Euc}, k+1} d \omega \quad \text { for all } \omega \in \mathcal{D}\left(D, \bigwedge^{k}\right)
$$

Take now $D=B(e, 1)=: B$ and $N=2 n+1$. If $\omega \in C^{\infty}\left(B, E_{0}^{k}\right)$, then we set

$$
K=\Pi_{E_{0}} \circ \Pi_{E} \circ K_{\mathrm{Euc}} \circ \Pi_{E}
$$

(for sake of simplicity, from now on we drop the index $k$ - the degree of the form writing, e.g., $K_{\text {Euc }}$ instead of $K_{\text {Euc }, k}$.

Analogously, we can define

$$
J=\Pi_{E_{0}} \circ \Pi_{E} \circ J_{\mathrm{Euc}} \circ \Pi_{E} .
$$

Then $K$ and $J$ invert Rumin's differential $d_{c}$ on closed forms of the same degree. More precisely, we have:
Lemma 6.6. If $\omega$ is $d_{c}$-closed, then

$$
\begin{equation*}
\omega=d_{c} K \omega \quad \text { if } 1 \leq k \leq 2 n+1 \quad \text { and } \quad \omega=d_{c} J \omega \quad \text { if } 1 \leq k \leq 2 n \tag{22}
\end{equation*}
$$

In addition, if $\omega$ is compactly supported in $B$, then $J \omega$ is still compactly supported in $B$.
Proof. Consider for instance $d_{c} K \omega$. If $d_{c} \omega=0$, then $d\left(\Pi_{E} \omega\right)=0$, and hence

$$
\Pi_{E} \omega=d K_{\text {Euc }}\left(\Pi_{E} \omega\right)
$$

by (117). By (20) (and recalling that $d \Pi_{E}=\Pi_{E} d$ and $\Pi_{E} \Pi_{E_{0}} \Pi_{E}=\Pi_{E}$ ),

$$
\begin{aligned}
d_{c} K \omega & =\Pi_{E_{0}} d \Pi_{E} \Pi_{E_{0}} \Pi_{E} K_{E u c} \Pi_{E} \omega=\Pi_{E_{0}} d \Pi_{E} K_{E u c} \Pi_{E} \omega \\
& =\Pi_{E_{0}} \Pi_{E} d K_{E u c} \Pi_{E} \omega=\Pi_{E_{0}} \Pi_{E} \Pi_{E} \omega=\Pi_{E_{0}} \Pi_{E} \Pi_{E_{0}} \omega=\omega
\end{aligned}
$$

Finally, if $\operatorname{supp} \omega \subset B$, then $\operatorname{supp} J \omega \subset B$ since both $\Pi_{E}$ and $\Pi_{E_{0}}$ preserve the support.
senza nome
Lemma 6.7. Put $B=B(e, 1)$. Then:
i) if $1<p<\infty$ and $k=1, \ldots, 2 n+1$, then $K: W^{1, p}\left(B, E_{0}^{k}\right) \rightarrow L^{p}\left(B, E_{0}^{k-1}\right)$ is bounded;
ii) if $1 \leq p \leq \infty$ and $n+1<k \leq 2 n+1$, then $K: L^{p}\left(B, E_{0}^{k}\right) \rightarrow L^{p}\left(B, E_{0}^{k-1}\right)$ is compact;
iii) if $1<p<\infty$ and $k=n+1$, then $K: L^{p}\left(B, E_{0}^{n+1}\right) \rightarrow L^{p}\left(B, E_{0}^{n}\right)$ is bounded.
Analogous assertions hold for $1 \leq k \leq 2 n$ when we replace $K$ by J. In addition, $\operatorname{supp} J \omega \subset B$.
Proof. By its very definition, $\Pi_{E}: W^{1, p}\left(B, E_{0}^{k}\right) \rightarrow L^{p}\left(B, E_{0}^{k}\right)$ is bounded. By $\left(\frac{\text { Keuc }}{16}\right)$, $K_{\text {Euc }}$ is continuous from $L^{p}\left(B, E_{0}^{k}\right)$ to $W^{1, p}\left(B, E_{0}^{k-1}\right)$ and hence, in particular, from $L^{p}\left(B, E_{0}^{k}\right)$ to $W^{1, p}\left(B, E_{0}^{k-1}\right)$. Then we can conclude the proof of i), keeping again into account that $\Pi_{E}$ is a differential operator of order $\leq 1$ in the horizontal derivatives.

To prove ii) it is enough to remind that $K=\Pi_{E_{0}} K_{\text {Euc }}$ of forms of degree $h>n$, together with Remark 4.1 in [13].

As for iii), the statement can be proved similarly to i), noticing that $K=$ $\Pi_{E_{0}} \Pi_{E} K_{\text {Euc }}$ on forms of degree $n+1$.

Finally, $\operatorname{supp} J \omega \subset B$ since both $\Pi_{E}$ and $\Pi_{E_{0}}$ preserve the support.

The operators $K$ and $J$ provide a local homotopy in Rumin's complex, but fail to yield the Sobolev and Poincaré inequalities we are looking for, since, because of the presence of the projection operator $\Pi_{E}$ (that on forms of low degree is a senza nome first order differential operator) they loose regularity as is stated in Lemma $\frac{\text { s.nza }}{6.7}$, 11) above. In order to build "good" local homotopy operators with the desired gain of regularity, we have to combine them with homotopy operators which, though not local, in fact provide the "good" gain of regularity.
homotopy formulas Proposition 6.8. If $\alpha \in \mathcal{D}\left(\mathbb{H}^{n}, E_{0}^{h}\right)$ for $p>1$ and $h=1, \ldots, 2 n$, then the following homotopy formulas hold:

- if $h \neq n, n+1$, then $\alpha=d_{c} K_{1} \alpha+\tilde{K}_{1} d_{c} \alpha$, where $K_{1}$ and $\tilde{K}_{1}$ are associated with kernels $k_{1}, \tilde{k}_{1}$ of type 1 ;
- if $h=n$, then $\alpha=d_{c} K_{1} \alpha+\tilde{K}_{2} d_{c} \alpha$, where $K_{1}$ and $\tilde{K}_{2}$ are associated with kernels $k_{1}, \tilde{k}_{2}$ of type 1 and 2, respectively;
- if $h=n+1$, then $\alpha=d_{c} K_{2} \alpha+\tilde{K}_{1} d_{c} \alpha$, where $K_{2}$ and $\tilde{K}_{1}$ are associated with kernels $k_{2}, \tilde{k}_{1}$ of type 2 and 1 , respectively.
Proof. Suppose $h \neq n-1, n, n+1$. By Lemma $\frac{\text { comm }}{4.10}$, we have:

$$
\begin{aligned}
\alpha & =\Delta_{\mathbb{H}, h} \Delta_{\mathbb{H}, h}^{-1} \alpha=d_{c}\left(\delta_{c} \Delta_{\mathbb{H}, h}^{-1}\right) \alpha+\delta_{c}\left(d_{c} \Delta_{\mathbb{H}, h}^{-1}\right) \alpha \\
& =d_{c}\left(\delta_{c} \Delta_{\mathbb{H}, h}^{-1}\right) \alpha+\left(\delta_{c} \Delta_{\mathbb{H}, h+1}^{-1}\right) d_{c} \alpha .
\end{aligned}
$$

where $\delta_{c} \Delta_{\mathbb{H}, h}^{-1}$ and $\delta_{c} \Delta_{\text {whe }}^{-1}$, are associated with a kernel of type 1 (by Proposition $\frac{\text { kernel }}{4.2 \text { and }}$ Theorem $\frac{\text { globa }}{4.8)}$.

Analogously, if $h=n-1$

$$
\begin{aligned}
\alpha & =\Delta_{\mathbb{H}, n-1} \Delta_{\mathbb{H}, n-1}^{-1} \alpha=d_{c}\left(\delta_{c} \Delta_{\mathbb{H}, n-1}^{-1}\right) \alpha+\delta_{c}\left(d_{c} \Delta_{\mathbb{H}, n-1}^{-1}\right) \alpha \\
& =d_{c}\left(\delta_{c} \Delta_{\mathbb{H}, n-1}^{-1}\right) \alpha+\left(\delta_{c} d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1}\right) d_{c} \alpha .
\end{aligned}
$$

Again $\delta_{c} \Delta_{\mathbb{H}, n-1}^{-1}$ and $\delta_{c} d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1}$ are associated with kernels of type 1.
Take now $h=n$. Then

$$
\begin{aligned}
\alpha & =\Delta_{\mathbb{H}, n} \Delta_{\mathbb{H}, n}^{-1} \alpha=\left(d_{c} \delta_{c}\right)^{2} \Delta_{\mathbb{H}, n}^{-1} \alpha+\delta_{c}\left(d_{c} \Delta_{\mathbb{H}, n}^{-1}\right) \alpha \\
& =d_{c}\left(\delta_{c} d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1}\right) \alpha+\delta_{c} \Delta_{\mathbb{H}, n+1}^{-1} d_{c} \alpha
\end{aligned}
$$

where $\delta_{c} d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1}$ and $\delta_{c} \Delta_{\mathbb{H}, n+1}^{-1}$ are associated with a kernel of type 1 and 2 , respectively).

Finally, take $h=n+1$. Then

$$
\begin{aligned}
\alpha & =\Delta_{\mathbb{H}, n+1} \Delta_{\mathbb{H}, n+1}^{-1} \alpha=d_{c} \delta_{c} \Delta_{\mathbb{H}, n+1}^{-1} \alpha+\left(\delta_{c} d_{c}\right)^{2} \Delta_{\mathbb{H}, n+1}^{-1} \alpha \\
& =d_{c} \delta_{c} \Delta_{\mathbb{H}, n+1}^{-1} \alpha+\delta_{c} \Delta_{\mathbb{H}, n+2}^{-1} d_{c} \alpha
\end{aligned}
$$

where $\delta_{c} \Delta_{\mathbb{H}, n+1}^{-1}$ and $\delta_{c} \Delta_{\mathbb{H}, n+2}^{-1}$ associated with kernels of type 2 and 1 , respectively.

The $L^{p}-L^{q}$ continuity properties of convolution operators associated with Folland's kernels yields the following strong $\mathbb{H}$-Poincaré $p$, ( $h$ ) inequality in $\mathbb{H}^{n}$ (the strong $\mathbb{H}$-Sobolev $p_{p, q}(h)$ is obtained in Corollary 6.17).
strong poincare Corollary 6.9. Take $1 \leq h \leq 2 n+1$. Suppose $1<p<Q$ if $h \neq n+1$ and $1<p<Q / 2$ if $h=n+1$. Let $q \geq p$ defined by

$$
\frac{1}{p}-\frac{1}{q}:= \begin{cases}\frac{1}{Q} & \text { if } h \neq n+1  \tag{23}\\ \frac{2}{Q} & \text { if } h=n+1\end{cases}
$$

Then for any $d_{c}$-closed form $\alpha \in \mathcal{D}\left(\mathbb{H}^{n}, E_{0}^{h}\right)$ there exists $\phi \in L^{q}\left(\mathbb{H}^{\prime}, E_{0}^{h-1}\right)$ such that $d_{c} \phi=\alpha$ and

$$
\|\phi\|_{L^{q}\left(\mathbb{H}^{n}, E_{0}^{h-1}\right)} \leq C\|\alpha\|_{L^{p}\left(\mathbb{H}^{n}, E_{0}^{h-1}\right)}
$$

(i.e., the strong $\mathbb{H}$-Poincaré ${ }_{p, q}(h)$ inequality holds for $1 \leq h \leq 2 n+1$ ).
smoothing
approx homotopy tilde

Theorem 6.10. Let $B=B(e, 1)$ and $B^{\prime}=B(e, \lambda), \lambda>1$, be concentric balls of $\mathbb{H}^{n}$. If $1 \leq h \leq 2 n+1$, there exist operators $T$ and $\tilde{T}$ from $C^{\infty}\left(B^{\prime}, E_{0}^{\bullet}\right)$ to $C^{\infty}\left(B, E_{0}^{\bullet-1}\right)$ and $S$ from $C^{\infty}\left(B^{\prime}, E_{0}^{\bullet}\right)$ to $C^{\infty}\left(B, E_{0}^{\bullet}\right)$ satisfying

$$
\begin{equation*}
d_{c} T+\tilde{T} d_{c}+S=I \quad \text { on } B \tag{24}
\end{equation*}
$$

In addition
i) $\tilde{T}: W^{-1, p}\left(B^{\prime}, E_{0}^{h+1}\right) \rightarrow L^{p}\left(B, E_{0}^{h}\right)$ if $h \neq n$, and $\tilde{T}: W^{-2, p}\left(B, E_{0}^{n+1}\right) \rightarrow$ $L^{p}\left(B, E_{0}^{n}\right)$;
ii) $T: L^{p}\left(B^{\prime}, E_{0}^{h}\right) \rightarrow W^{1, p}\left(B, E_{0}^{h-1}\right), h \neq n+1, T: T: L^{p}\left(B^{\prime}, E_{0}^{n+1}\right) \rightarrow$ $W^{2, p}\left(B, E_{0}^{n}\right)$ if $h=n+1$,
iii) $S: L^{p}\left(B^{\prime}, E_{0}^{h}\right) \rightarrow W^{s, p}\left(B, E_{0}^{h}\right)$,
so that (Eaprox homotopy tilde still holds in $L^{p}\left(B, E_{0}^{\bullet}\right)$. In addition, for every $(h, p, q)$ satisfying inequalities

$$
1<p \leq q<\infty, \quad \frac{1}{p}-\frac{1}{q} \leq \begin{cases}\frac{1}{Q} & \text { if } h \neq n+1  \tag{25}\\ \frac{2}{Q} & \text { if } h=n+1\end{cases}
$$

we have:
iv) $T: L^{p}\left(B^{\prime}, E_{0}^{h}\right) \rightarrow L^{q}\left(B, E_{0}^{h-1}\right)$;
v) $S: L^{p}\left(B^{\prime}, E_{0}^{h}\right) \rightarrow W^{s, q}\left(B, E_{0}^{h}\right)$;
vi) $W^{1, p}\left(B^{\prime}, E_{0}^{h}\right) \rightarrow W^{s, q}\left(B, E_{0}^{h-1}\right)$ for any $s>0$.

Proof. Suppose first $h \neq n, n+1$. We consider a cut-off function $\psi_{R}$ supported in a $R$-neighborhood of the origin, such that $\psi_{R} \equiv 1$ near the origin. With the notations of Proposition $\frac{\text { homotopy }}{6.8, \text { we can write }} k_{1}=k_{1} \psi_{R}+\left(1-\psi_{R}\right) k_{1}$ and $\tilde{k}_{1}=\tilde{k}_{1} \psi_{R}+\left(1-\psi_{R}\right) \tilde{k}_{1}$. Let us denote by $K_{1, R}, \tilde{K}_{1, R}$ the convolution operators associated with $\psi_{R} k_{1}, \psi_{R} \tilde{k}_{1}$, respectively. Le us fix two balls $B_{0}, B_{1}$ with

$$
\begin{equation*}
B \Subset B_{0} \Subset B_{1} \Subset B^{\prime} \tag{26}
\end{equation*}
$$

and a cut-off function $\chi \in \mathcal{D}\left(B_{1}\right)$, $\chi \equiv 1$ on $B_{0}$. If $\alpha \in C^{\infty}\left(B^{\prime}, E_{0}^{\bullet}\right)$, we set $\alpha_{0}=\chi \alpha$, continued by zero outside $B_{1}$

Keeping in mind (8) and Proposition 4.2 , we have

$$
\begin{equation*}
\alpha_{0}=d_{c} K_{1, R} \alpha_{0}+\tilde{K}_{1, R} d_{c} \alpha_{0}+S_{0} \alpha_{0} \tag{27}
\end{equation*}
$$

where $S_{0}$ is

$$
S_{0} \alpha_{0}:=d_{c}\left(\left(1-\psi_{R}\right) k_{1} * \alpha_{0}\right)+\left(1-\psi_{R}\right) \tilde{k}_{1} * d_{c} \alpha_{0}
$$

We set

$$
T \alpha:=K_{1, R} \alpha_{0}, \quad \tilde{T} \alpha:=\tilde{K}_{1, R} d_{c} \alpha_{0}, \quad S \alpha:=S_{0} \alpha_{0}
$$

We notice that, provided $R>0$ is small enough, the definition of $T$ and $\tilde{T}$ does not depend on the continuation of $\alpha$ outside $B_{0}$. By ( $\overline{Z T}$ ) we have

$$
\alpha=d_{c} T \alpha+\tilde{T} d_{c} \alpha+S \alpha \quad \text { in } B
$$

If $h=n$ we can carry out the same construction, replacing $\tilde{k}_{1}$ by $\tilde{k}_{2}$ (keep in mind that $\tilde{k}_{2}$ is a kernel of type 2). Analogously, if $h=n+1$ we can carry out the same construction, replacing $k_{1}$ by $k_{2}$ (again a kernel of type 2 ).

Let us prove i). Suppose $h \neq n$, and take $\beta \in W^{-1, p}\left(B^{\prime}, E_{0}^{h}\right)$. The operator $\tilde{K}_{1, R}$ is associated with a matrix-valued kernel $\psi_{R}\left(\tilde{k}_{1}\right)_{\ell, \lambda}$ and $\beta$ is identified with a vector-valued distribution $\left(\beta_{1}, \ldots, \beta_{N_{h}}\right)$, with $\beta_{j}=\sum_{i} W_{i} f_{i}^{j}$ as in Definition $\frac{\text { dual }}{5.5}$ with

$$
\sum_{j} \sum_{i}\left\|f_{i}^{j}\right\|_{L^{p}\left(B^{\prime}\right)} \leq C\|\beta\|_{W^{-1, p}\left(B^{\prime}, E_{0}^{h}\right)} .
$$

Thus $\left(\beta_{0}\right)_{j}$, the $j$-th component of $\beta_{0}=\chi \beta$ has the form

$$
\left(\beta_{0}\right)_{j}=\sum_{i} W_{i}\left(\chi f_{i}^{j}\right)-\sum_{i}\left(W_{i} \chi\right) f_{i}^{j}=: \sum_{i} W_{i}\left(f_{i}^{j}\right)_{0}-\sum_{i}\left(W_{i} \chi\right) f_{i}^{j}
$$

In order to estimate the norm of $\tilde{T} \beta$ in $L^{p}\left(B, E_{0}^{h}\right)$, we take

$$
\phi=\sum_{j} \phi_{j} \xi_{j}^{h} \in \mathcal{D}\left(B, E_{0}^{h}\right), \quad \text { with } \quad \sum_{j}\left\|\phi_{j}\right\|_{L^{p^{\prime}}\left(B^{\prime}\right)} \leq 1,
$$

and we estimate $\langle T \beta \mid \phi\rangle$, that, by ( $\frac{\text { dual spaces forms eq:1 }}{14) \text {, is a sum of terms }}$ of the form

## caso 1

$$
\begin{equation*}
\int_{B}\left(\psi_{R} \kappa * f_{0}\right)(x) W_{i} \phi(x) d x=\left\langle\psi_{R} \kappa * W_{i} f_{0} \mid \phi\right\rangle \tag{28}
\end{equation*}
$$

or of the form

$$
\begin{equation*}
\int_{B}\left(\psi_{R} \kappa *\left(W_{i} \chi\right) f\right)(x) \phi(x) d x \tag{29}
\end{equation*}
$$

where $\kappa$ denotes one of the kernels $\left(\tilde{k}_{1}\right)_{\ell, \lambda}$ of type 1 associated with $\tilde{k}_{1}, f$ is one of the $f_{i}^{j}$ 's and $\phi$ one of the $\phi_{j}$ 's,

As for $\left(\frac{\text { caso }}{(28), ~} \frac{1}{\text { by }}\left(\frac{\text { convolution by parts }}{(8),}\right.\right.$

$$
\begin{aligned}
& \left\langle\psi_{R} \kappa * W_{i} f_{0} \mid \phi\right\rangle=\left\langle{ }^{\mathrm{v}} W^{I \mathrm{v}}\left[\psi_{R} \kappa\right] * f_{0} \mid \phi\right\rangle \\
& \quad=\left\langle\psi_{R}{ }^{\mathrm{v}} W^{I \mathrm{v}} \kappa * f_{0} \mid \phi\right\rangle-\left\langle\left({ }^{\mathrm{v}} W^{I \mathrm{v}} \psi_{R}\right) \kappa * f_{0} \mid \phi\right\rangle
\end{aligned}
$$

We notice now that ${ }^{\mathrm{v}} W^{I}{ }^{\mathrm{v}} \kappa$ is a kernel of type 0 . Therefore, by Lemma $\frac{1 \text { trun }}{4.4}$

$$
\begin{aligned}
\left\langle\psi_{R}{ }^{\mathrm{v}} W^{I \mathrm{v}}\right. & \kappa * f_{0}|\phi\rangle \leq\left\|\psi_{R}{ }^{\mathrm{v}} W^{I \mathrm{v}} \kappa * f_{0}\right\|_{L^{p}(B)}\|\phi\|_{L^{p^{\prime}}(B)} \\
& \leq\left\|\psi_{R}{ }^{\mathrm{v}} W^{I \mathrm{v}} \kappa * f_{0}\right\|_{L^{p}(B)} \leq C\left\|f_{0}\right\|_{L^{p}\left(B^{\prime}\right)} \\
& \leq C\|\beta\|_{W^{-1, p}\left(B^{\prime}, E_{0}^{h}\right)}
\end{aligned}
$$

 (4.5). Eventually, combining (L28) and (EQ) we obtain that

$$
\|\tilde{T} \beta\|_{L^{p}(B)} \leq C\|\beta\|_{W^{-1, p}\left(B^{\prime}, E_{0}^{h}\right)} .
$$

The assertion for $h=n$ can be proved in the same way, taking into account that $\tilde{T}$ is built from a kernel of type 2 , and that the space $W^{-2, p}\left(B, E_{0}^{n+1}\right)$ is characterized by "second order divergences".

Let us prove now ii). Suppose $h \neq n+1$ and take $\alpha=\sum_{j} \alpha_{j} \xi_{j}^{h} \in \mathcal{D}\left(B^{\prime}, E_{0}^{h}\right)$. Arguing as above, in order to estimate $\|T \alpha\|_{W^{1, p}\left(B, E_{0}^{h-1}\right)}$ we have to consider terms of the form

$$
\begin{equation*}
W_{\ell}\left(\psi_{R} \kappa *\left(\chi \alpha_{j}\right)\right)=\psi_{R} \kappa *\left(W_{\ell}\left(\chi \alpha_{j}\right)\right) \tag{30}
\end{equation*}
$$

(when we want to estimate the the $L^{p}$-norm of the horizontal derivatives of $T \alpha$ ), or of the form

$$
\begin{equation*}
\psi_{R} \kappa *\left(\chi \alpha_{j}\right) \tag{31}
\end{equation*}
$$

(when we want to estimate the $L^{p}$-norm of $T \alpha$ ). Both ( $\frac{\text { caso } 3}{30}$ and ( $\frac{\text { caso } 4}{31 \text { ) can }}$ be handled as in the case i) (no need here of the duality argument).

We point out that ( $\mathbf{3 1}$ ) yields a $L^{p}-L^{q}$ estimates (since, unlike ( $\begin{aligned} & \text { caso } 3 \\ & 30), ~ i n v o l v e s ~\end{aligned}$ only kernels of type 1) and then assertion iv) follows.

Let us prove v). Then also iii) will follow straightforwardly.
It is easy to check that $S_{0}$ can be written as a convolution operator with matrixvalued kernel $s_{0}$. In turn, each entry of $s_{0}$ (that we still denote by $s_{0}$ ) is a sum of terms of the form

$$
\left(1-\psi_{R}\right) W_{\ell} \kappa-\left(W_{\ell} \psi_{R}\right) \kappa
$$

Thus, the kernels are smooth and then regularizing from $\mathcal{E}^{\prime}\left(B^{\prime}\right)$ to $C^{\infty}$ of a neighborhood of $B$. Thus

$$
\left\|W^{I} s_{0} * \alpha_{j}\right\|_{L^{q}(B)} \leq C\left\|\alpha_{j}\right\|_{L^{p}(B)}
$$

for all $p, q$.
tenda Remark 6.11. Apparently, in previous theorem, two different homotopy operators $T$ and $\tilde{T}$ appear. In fact, they coincide when acting on form of the same degree.

More precisely, in Proposition 6.8 the homotopy formulas involve four operators $K_{1}, \tilde{K}_{1}, K_{2}, \tilde{K}_{2}$, where the notation is meant to distinguish operators acting on $d_{c} \alpha$ (the operators with tilde) from those on which the differential acts (the operators without tilde), whereas the lower index 1 or 2 denotes the type of the associated
kernels. Alternatively, a different notation could be used: if $\alpha \in \mathcal{D}\left(\mathbb{H}^{n}, E_{0}^{h}\right)$ we can write

$$
\alpha=d_{c} K_{h}+\tilde{K}_{h+1} d_{c} \alpha
$$

where the tilde has the same previous meaning, whereas the lower index refers now to the degree of the forms on which the operator acts.

It is important to notice that

$$
K_{h+1}=\tilde{K}_{h+1}, \quad h=1, \ldots, 2 n
$$

Indeed, take $h<n-1$. Then $\tilde{K}_{h+1}=\delta_{c} \Delta_{\mathbb{H}, h+1}^{-1}$ (as it appears in the homotopy formula at the degree $h$ ), that equals $K_{h+1}$ (as it appears in the homotopy formula at the degree $h+1 \leq n-1$ ). Take now $h=n-1$. Then $\tilde{K}_{n}=\delta_{c} d_{c} \delta_{c} \Delta_{\mathbb{H}, n}^{-1}$ (as it appears in the homotopy formula at the degree $n$ ), that equals $K_{n}$ (as it appears in the homotopy formula at the degree $n$ ). If $h=n$, then $\tilde{K}_{n+1}=\delta_{c} \Delta_{\mathbb{H}, n+1}^{-1}$ (as it appears in the homotopy formula at the degree $n$ ), that equals $K_{n+1}$ (as it appears in the homotopy formula at the degree $n+1$ ). Finally, if $h>n$, then $\tilde{K}_{h+1}=\delta_{c} \Delta_{\mathbb{H}, h+1}^{-1}$ (as it appears in the homotopy formula at the degree $h$ ), that equals $K_{h+1}$ (as it appears in the homotopy formula at the degree $h+1$ ).

Once this point is established, from now on we shall write

$$
K:=K_{h}=\tilde{K}_{h}
$$

without ambiguity.
Therefore $T=\tilde{T}$ and the homotopy formula ( $\frac{\text { approx homotopy tilde }}{(24) \text { reads as }}$

$$
\begin{equation*}
d_{c} T+T d_{c}+S=I \quad \text { on } B \tag{32}
\end{equation*}
$$

Remark 6.12. By the arguments used in the proof of Theorem $\frac{\text { smoothing }}{(6.10, \imath) \text { the proof of }}$ the $L^{p}-W^{s, q}$ continuity of $S$ can be adapted to prove that $S$ is a smoothing operator, $i_{\text {i e for }}$ fory $m, s \in \mathbb{N} \cup\{0\}, S$ is bounded from $W^{-m, p}\left(B^{\prime}, E_{0}^{\bullet}\right)$ to $W^{s, q}\left(B, E_{0}^{\bullet}\right)$ when (L25) holds. In particular, if $\alpha \in W^{-m, p}\left(B^{\prime}, E_{0}^{\bullet}\right)$ then $S \alpha \in C^{\infty}\left(B, E_{0}^{\bullet}\right)$.
locality Remark 6.13. It is worth pointing out the followipg fact: take $\alpha, \beta \in L^{p}\left(B^{\prime}, E_{0}^{\bullet}\right)$, $\alpha \equiv \beta$ on $B_{1}$ ( $B_{1}$ has been introduced in (衣). . Then $\alpha_{0} \equiv \beta_{0}$ in $B_{0}$, so that
 $\left(d_{c} T+T d_{c}\right) \beta$ in $B$. Thus, by $(32), S \alpha=S \beta$ in $B$.

The following commutation lemma will be helpful in the sequel.
S-commuta-d Lemma 6.14. We have:

$$
\left[S, d_{c}\right]=0 \quad \text { in } L^{p}\left(\mathbb{H}^{n}, E_{0}^{\bullet}\right)
$$

Proof. Take first $\alpha \in C^{\infty}\left(B^{\prime}, E_{0}^{h}\right), 1 \leq h \leq 2 n+1$. By ( $\frac{\text { approx homotopy }}{=} S d_{c} S$ on $\mathcal{D}\left(B^{\prime}, E_{0}^{h}\right)$.

Take now $\alpha \in L^{p}\left(B^{\prime}, E_{0}^{h}\right)$, and let let $_{\text {, }} \chi_{1}$ be a cut-off function supported in $B^{\prime}, \chi_{1} \equiv$ 1 on $B_{1}$ ( $B_{1}$ has been defined in ( 26$)$ ). By convolution with usual Friedrichs' mollifiers, we can find a sequence $\left(\alpha_{k}\right)_{k \in \mathbb{N}}$ in $\mathcal{D}\left(B^{\prime}, E_{0}^{h}\right)$ converging to $\chi_{1} \alpha$ in $L^{p}\left(B^{\prime}, E_{0}^{h}\right)$. By Theorem $\frac{\text { smoothing }}{6.10, S \alpha_{k}} \rightarrow S\left(\chi_{1} \alpha\right)$ in $W^{2, p}\left(B, E_{0}^{h+1}\right)$, and hence $d_{c} S \alpha_{k} \rightarrow d_{c} S\left(\chi_{\alpha}\right)$ in $L^{p}\left(B, E_{0}^{h}\right)$ as $k \rightarrow \infty$ (obviously, if $h \neq n-1$, it would have been enough to have $S \alpha_{k} \rightarrow S\left(\chi_{\text {p } \alpha} \alpha \operatorname{inn}_{n+1} W^{1, p}\left(B, E_{0}^{h+1}\right)\right)$. On the other hand, $\chi_{1} \alpha \equiv \alpha$ in $B_{1}$, and then by Remark $\frac{10 c a l}{6.13} S\left(\chi_{1} \alpha\right)=S \alpha$ in $B$, so that $d_{c} S \alpha_{k} \rightarrow d_{c} S \alpha$ in $L^{p}\left(B, E_{0}^{h}\right)$ as
$k \rightarrow \infty$. Moreover $d_{c} \alpha_{k} \rightarrow d_{c}\left(\chi_{\operatorname{smodth} \alpha} \operatorname{ing}^{-1, p}\left(B^{\prime}, E_{0}^{h}\right)\left(\right.\right.$ in $W^{-2, p}\left(B^{\prime}, E_{0}^{h}\right)$ if $\left.h=n\right)$ and hence, again by Theorem $\overline{6.10, S d_{c}} \alpha_{k} \overrightarrow{o c a} S_{i} d_{c y}\left(\chi_{1} \alpha\right)$ in $B$ as $n \rightarrow \infty$. Again $d_{c}\left(\chi_{1} \alpha\right) \equiv d_{c} \alpha$ in $B_{1}$ and then, by Remark $\overline{0.13,} S d_{c} \alpha_{k} \rightarrow S d_{c} \alpha$ in $B$ as $k \rightarrow \infty$.

Finally, since $d_{c} S \alpha_{k}=S d_{c} \alpha_{k}$ for all $k \in \mathbb{N}$, we can take the limits as $k \rightarrow \infty$ and the assertion follows.

$1<p<\infty$, then both an interior $\mathbb{H}$-Poincaré ${ }_{p, q}(h)$ and an interior $\mathbb{H}-\operatorname{Sobolev}_{p, q}(h)$ inequalities hold for $1 \leq h \leq 2 n$.
 ${ }_{\text {S-conmutad }}$ Be can write $\omega=d_{c} T \omega+S \omega$ in $B$. By Remark $\delta .14, S \omega \in \mathcal{E}\left(B, E_{0}^{h}\right)$, and $d_{c} S \omega=0$. Thus we can apply ( $\frac{\text { nomotopy }}{(22) \text { to } S \omega \text { and }}$ we get $S \omega=d_{c} K S \omega$, where $K$ is defined in $(20) . \operatorname{In} \dot{B}$, put now

$$
\phi:=(K S+T) \omega .
$$

Trivially $d_{c} \phi=d_{c} K S \omega+d_{c} T \omega=S \omega+\omega-S \omega=\omega$. By Theorem $\frac{\text { smoothing }}{6.10,}$

$$
\begin{align*}
& \|\phi\|_{L^{q}\left(B, E_{0}^{h-1}\right)} \leq\|K S \omega\|_{L^{q}\left(B, E_{0}^{h-1}\right)}+\|T \omega\|_{L^{q}\left(B, E_{0}^{h-1}\right)} \\
& \quad \leq\|K S \omega\|_{L^{q}\left(B, E_{0}^{h-1}\right)}+C\|\omega\|_{L^{p}\left(B^{\prime}, E_{0}^{h-1}\right)} \\
& \quad \leq C\left\{\|S \omega\|_{W^{1, q}\left(B, E_{0}^{h-1}\right)}+\|\omega\|_{L^{p}\left(B^{\prime}, E_{0}^{h-1}\right)}\right\} \quad \text { (by Lemma senza nome }  \tag{33}\\
& \quad \leq C\|\omega\|_{L^{p}\left(B^{\prime}, E_{0}^{h-1}\right)} .
\end{align*}
$$

$\mathbb{H}$-Sobolev ${ }_{p, q}(h)$ inequality: let $\omega \in L^{p}\left(B, E_{0}^{h}\right)$ be a compactly supported form such that $d_{c} \omega=0$. Since $\omega$ vanishes in a neighborhood of $\partial B$, without loss of generality we can assume that it is continued by zero on $B^{\prime}$. In addition, $\omega=\chi \omega$. By ( ${ }^{(32)}$ ) we have $\omega=d_{c} T \omega+S \omega$. On the other hand, $T \omega$ is supported in $B_{0}$ (since $R$ is small), so that also $S \omega$ is supported in $B_{\text {homotopy }}$. Again as above $S \omega \in C^{\infty}\left(B, E_{0}^{h}\right)$, and $d_{c} S \omega=0$ may 31 eq:2 Thus we can apply (homotopy, ciosed we get $S \omega=d_{c} J S \omega$, where $J$ is defined in $\left(\frac{\text { may }}{21}\right)$. By Lemma $\frac{10}{6} .6, J S \omega$ is supported in $B_{0} \subset B^{\prime}$. Thus, if we set $\phi:=(J S+T) \omega$, then $\phi$ is supported in $B^{\prime}$. Moreover $d_{c} \phi=d_{c} d_{\text {estimates }} \operatorname{Sin}_{c} d_{c} T \omega=S \omega+\omega-S \omega=\omega$. At this point, we can repeat the estimates (33) and we get eventually

$$
\|\phi\|_{L^{q}\left(B^{\prime}, E_{0}^{h-1}\right)} \leq C\|\omega\|_{L^{p}\left(B, E_{0}^{h-1}\right)}
$$

This completes the proof of the theorem.
Let $B(p, r)$ a Korányi ball of center $p \in \mathbb{H}^{n}$ and radius $r>0$. The map $x \rightarrow$ $f(x):=\tau_{p} \delta_{r}(x)$ provides a contact diffeomorphism from $B(e, \rho)$ to $B(p, r \rho)$ for $\rho>0$. Therefore the pull-back $f^{\#}: E_{0}^{\bullet} \rightarrow E_{0}^{\bullet}$. In addition, if $\alpha \in E_{0}^{h}$, then

$$
f^{\#} \alpha=r^{h} \alpha \circ f \quad \text { if } h \leq n \quad \text { and } \quad f^{\#} \alpha=r^{h+1} \alpha \circ f \quad \text { if } h>n
$$

Theorem 6.16. Take $1 \leq h \leq 2 n+1$. Suppose $1<p<Q$ if $h \neq n+1$ and $1<p<Q / 2$ if $h=n+1$. Let $q \geq p$ such that

$$
\frac{1}{p}-\frac{1}{q} \leq \begin{cases}\frac{1}{Q} & \text { if } h \neq n+1 \\ \frac{2}{Q} & \text { if } h=n+1\end{cases}
$$

Then there exists a constant $C$ such that, for every $d_{c}$-closed differential $h$-form $\omega$ in $L^{p}\left(B(p, \lambda r) ; E_{0}^{h}\right)$ there exists a $h-1$-form $\phi$ in $L^{q}\left(B(p, r), E_{0}^{h-1}\right)$ such that $d_{c} \phi=\omega$ and

$$
\|\phi\|_{L^{q}\left(B(p, r), E_{0}^{h-1}\right)} \leq C r^{Q / q-Q / p+1}\|\omega\|_{L^{p}\left(B(p, \lambda r), E_{0}^{h}\right)} \quad \text { if } h \neq n+1
$$

and

$$
\|\phi\|_{L^{q}\left(B(p, r), E_{0}^{n}\right)} \leq C r^{Q / q-Q / p+2}\|\omega\|_{L^{p}\left(B(p, \lambda r), E_{0}^{n+1}\right)}
$$

Analogously there exists a constant $C$ such that, for every compactly supported $d_{c^{-}}$ closed $h$-form $\omega$ in $L^{p}\left(B(p, r) ; E_{0}^{h}\right)$ there exists a compactly supported $(h-1)$-form $\phi$ in $L^{q}\left(B(p, \lambda r), E_{0}^{h-1}\right)$ such that $d_{c} \phi=\omega$ in $B(p, \lambda r)$ and

$$
\begin{equation*}
\|\phi\|_{L^{q}\left(B(p, \lambda r), E_{0}^{k-1}\right)} \leq C\|\omega\|_{L^{p}\left(B(p, r), E_{0}^{k}\right)} \tag{35}
\end{equation*}
$$

Proof. We have just to take the pull-back $f^{\#} \omega$ and then apply Theorem ${ }^{\mathrm{pq} .15 \text { poincare }}$

If the choice of $q$ is sharp (i.e. in ( ${ }^{k p g} 2$ the right hand side of (55) is independent of the radius of the ball, so that a global $\mathbb{H}$-Sobolev $p_{p, q}(h)$ inequality holds.
strong sobolev Corollary 6.17. Take $1 \leq h \leq 2 n+1$. Suppose $1<p<Q$ if $h \neq n+1$ and $1<p<Q / 2$ if $h=n+1$. Let $q \geq p$ defined by

$$
\frac{1}{p}-\frac{1}{q}:= \begin{cases}\frac{1}{Q} & \text { if } h \neq n+1  \tag{36}\\ \frac{2}{Q} & \text { if } h=n+1\end{cases}
$$

Then $\mathbb{H}$-Sobolev ${ }_{p, q}(h)$ inequality holds for $1 \leq h \leq 2 n+1$.

## 7. Contact manifolds and global smoothing

Throughout this section, $(M, H, g)$ will be a sub-Riemannian contact manifold
 Rumin's complex in $(M, H, g)$ and in the Heisenberg group.
memory Proposition 7.1. If $\phi$ is a contactomorphism from an open set $\mathcal{U} \subset \mathbb{H}^{n}$ to $M$, and we set $\mathcal{V}:=\phi(\mathcal{U})$, we have
i) $\phi^{\#} E_{0}^{\bullet}(\mathcal{V})=E_{0}^{\bullet}(\mathcal{U})$;
ii) $d_{c} \phi^{\#}=\phi^{\#} d_{c}$;
iii) if $\zeta$ is a smooth function in $M$, then the differential operator in $\mathcal{U} \subset \mathbb{H}^{n}$ defined by $v \rightarrow \phi^{\#}\left[d_{c}, \zeta\right]\left(\phi^{-1}\right)^{\#} v$ is a differential operator of order zero if $v \in E_{0}^{h}(\mathcal{U}), h \neq n$ and a differential operator of order 1 if $v \in E_{0}^{n}(\mathcal{U})$.

Proof. Assertions i) and ii) follow straightforwardly since $\phi$ is a contact map. Assertion iii) follows from Lemma $\sqrt{3.2}$, since, by definition,

$$
\phi^{\#}\left[d_{c}, \zeta\right]\left(\phi^{-1}\right)^{\#} v=\left[d_{c}, \zeta \circ \phi\right] v .
$$

carte Remark 7.2. Let $\left\{\phi_{x_{j}}(B(e, 1))\right\}$ a countable locally finite subcovering of $\left\{\phi_{x}(B(e, 1)), x \in\right.$ $M\}$. From now on, for sake of simplicity, we shall write $\phi_{j}:=\phi_{x_{j}}$. Without loss of generality, we can replace $B(e, 1)$ by $B(e, \lambda)$, where $\lambda>1$ is fixed (just to be congruent in the sequel with the notations of previous sections).

Let $\left\{\chi_{j}\right\}$ be a partition of the unity subordinated to the covering $\left\{\phi_{j}(B(e, \lambda))\right\}$ of $M$. As above, without loss of generality, we can assume $\phi_{j}^{-1}\left(\operatorname{supp} \chi_{j}\right) \subset B(e, 1)$.

If $u \in L^{p}\left(M, E_{0}^{\bullet}\right)$, we write

$$
u=\sum_{j} \chi_{j} u
$$

We can write

$$
\chi_{j} u=\left(\phi_{j}^{-1}\right)^{\#} \phi_{j}^{\#}\left(\chi_{j} u\right)=:\left(\phi_{j}^{-1}\right)^{\#} v_{j} .
$$

We use now the homotopy formula in $\mathbb{H}^{n}$ (see Theorem $\overline{6} .10$ ):

$$
v_{j}=d_{c} T v_{j}+T d_{c} v_{j}+S v_{j} \quad \text { in } B(e, 1)
$$

Without loss of generality, we can assume that $R>0$ in the definition of the kernel of $T$ has been chosen in such a way that the $R$-neighborood of $\phi_{j}^{-1}\left(\operatorname{supp} \chi_{j}\right) \subset$ $B(e, 1)$. In particular $v_{j}-d_{c} T v_{j}-T d_{c} v_{j}$ is supported in $B(0,1)$ and therefore also $S v_{j}$ is supported in $B(0,1)$.

In particular, $\left(\phi_{j}^{-1}\right)^{\#}\left(d_{c} T v_{j}+T d_{c} v_{j}+S v_{j}\right)$ is supported in $\phi_{j}(B(e, 1))$ so that it can be continued by zero on $M$.

Thus

$$
\begin{aligned}
u & =\sum_{j}\left(\phi_{j}^{-1}\right)^{\#}\left(d_{c} T v_{j}+T d_{c} v_{j}+S v_{j}\right) \\
& =d_{c} \sum_{j}\left(\phi_{j}^{-1}\right)^{\#} T \phi_{j}^{\#}\left(\chi_{j} u\right) \\
& +\sum_{j}\left(\left(\phi_{j}^{-1}\right)^{\#} T \phi_{j}^{\#} \chi_{j}\right) d_{c} u-\sum_{j}\left(\phi_{j}^{-1}\right)^{\#} T \phi_{j}^{\#}\left(\left[\chi_{j}, d_{c}\right] u\right) \\
& +\sum_{j}\left(\left(\phi_{j}^{-1}\right)^{\#}\left(S \phi_{j}^{\#} \chi_{j}\right) u .\right.
\end{aligned}
$$

We set
T

$$
\begin{equation*}
T u:=\sum_{j}\left(\phi_{j}^{-1}\right)^{\#} T \phi_{j}^{\#}\left(\chi_{j} u\right) \tag{37}
\end{equation*}
$$

and
S

$$
\begin{equation*}
S u:=\sum_{j}\left(\phi_{j}^{-1}\right)^{\#} S \phi_{j}^{\#}\left(\chi_{j} u\right)-\sum_{j}\left(\phi_{j}^{-1}\right)^{\#} T \phi_{j}^{\#}\left(\left[\chi_{j}, d_{c}\right] u\right) . \tag{38}
\end{equation*}
$$

The core of this section consists in the following approximate homotopy formula, where the "error term" $S_{M}$ has the maximal regularising property compatible with the regularity of $M$.
homotopy manifold
homotopy M

$$
\begin{equation*}
I=d_{c} T_{M}+T_{M} d_{c}+S_{M} \tag{39}
\end{equation*}
$$

where

$$
T_{M}:=\left(\sum_{i=0}^{k-1} S^{i}\right) T, \quad S_{M}:=S^{k}
$$


By definition
Theorem 7.3. Let $(M, H, g)$ be a bounded $C^{k}$-geometry sub-Riemannian contact manifold, $k \geq 2$. Then

$$
\begin{equation*}
d_{c} S u=S d_{c} u \tag{40}
\end{equation*}
$$

In addition, the following maps are continuous:
i) $T_{M}: W^{-1, p}\left(M, E_{0}^{h+1}\right) \rightarrow L^{p}\left(M, E_{0}^{h}\right)$ if $h \neq n$, and $T_{M}: W^{-2, p}\left(M, E_{0}^{n+1}\right) \rightarrow$ $L^{p}\left(M, E_{0}^{n}\right) ;$
ii) $T_{M}: L^{p}\left(M, E_{0}^{h}\right) \rightarrow W^{1, p}\left(M, E_{0}^{h-1}\right), h \neq n+1, T_{M}: L^{p}\left(M, E_{0}^{n+1}\right) \rightarrow$ $W^{2, p}\left(M, E_{0}^{n}\right)$ if $h=n+1$,
iii) $S_{M}: L^{p}\left(M, E_{0}^{h}\right) \rightarrow W^{k, p}\left(M, E_{0}^{h}\right)$.

In order to prove Theorem $\frac{\text { homotopy manifold }}{7.3 \text {, let us prove the following preliminary result: }}$
homotopy manifold lemma
homotopy MO

Lemma 7.4. Let $(M, H, g)$ be a bounded $C^{k}$-geometry sub-Riemannian contact manifold. If $2 \leq \ell \leq k-1$ and $T$ and $S$ are defined in (B7) and (58), then

$$
\begin{equation*}
I=d_{c} T+T d_{c}+S \tag{41}
\end{equation*}
$$

In addition, the following maps are continuous:
i) $T: W^{-1, p}\left(M, E_{0}^{h+1}\right) \rightarrow L^{p}\left(M, E_{0}^{h}\right)$ if $h \neq n$, and $T: W^{-2, p}\left(M, E_{0}^{n+1}\right) \rightarrow$ $L^{p}\left(M, E_{0}^{n}\right)$;
ii) $T: L^{p}\left(M, E_{0}^{h}\right) \rightarrow W^{1, p}\left(M, E_{0}^{h-1}\right), h \neq n+1, T: L^{p}\left(M, E_{0}^{n+1}\right) \rightarrow$ $W^{2, p}\left(M, E_{0}^{n}\right)$ if $h=n+1$,
iii) if $1 \leq \ell \leq k$, then $S: W^{\ell-1, p}\left(M, E_{0}^{h}\right) \longrightarrow W^{\ell, p}\left(M, E_{0}^{h}\right)$.

Proof. ${ }_{\text {constact }}^{\text {First }}$ of all, we notice that, if $\alpha$ is supported in $\phi_{j}(B(e, \lambda))$, then, by Definition 1.4 the norms

$$
\|\alpha\|_{W^{m, p}\left(M, E_{0}^{\bullet}\right)} \quad \text { and } \quad\left\|\phi_{j}^{\#} \alpha\right\|_{W^{m, p}\left(\mathbb{H}^{n}, E_{0}^{\bullet}\right)}
$$

are equivalent for $-k \leq m \leq k$, with equivalence constants independent of $j$. Thus, assertions i) and ii) follow straightforwardly from Theorem $\overline{6} .10$.

To get iii) we only need to note that the operators $\left(\phi_{j}^{-1}\right)^{\#} T \phi_{j}^{\#}\left[\chi_{j}, d_{c}\right]$ are bounded from $W^{\ell-1, p}\left(M, E_{0}^{\bullet}\right) \rightarrow W^{\ell, p}\left(M, E_{0}^{\bullet}\right)$ in every degree. Indeed, by Lemma $\frac{\text { Reibniz }}{3.2}$ above, the differential operator in $\mathbb{H}^{n} \phi_{j}^{\#}\left[\chi_{j}, d_{c}\right]\left(\phi_{j}^{-1}\right)^{\#}$ has order 1 if $h=n$, and order 0 if $h \neq n$. Since the kernel of $T$ can be estimated by kernel of type 2 if acts on forms of degree $h=n$, and of type 1 if acts on forms of degree $h \neq n$, the assertion follows straightforwardly

Summing up in $j$ and keeping into account that the sum is locally finite, we obtain:

$$
\begin{aligned}
& \left\|\sum_{j} \phi_{j}^{\#} T_{j}\left(\phi_{j}^{-1}\right)^{\#}\left[\chi_{j}, d_{c}\right]\right\|_{W^{\ell, p}(M)} \leq \sum_{j}\left\|\phi_{j}^{\#} T_{j}\left(\phi_{j}^{-1}\right)^{\#}\left[\chi_{j}, d_{c}\right]\right\|_{W^{\ell, p}\left(\phi\left(\mathcal{U}_{j}\right)\right)} \\
& \quad \leq C \sum_{j}\left\|T_{j} \phi_{j}^{\#}\left[\chi_{j}, d_{c}\right]\right\|_{W^{\ell, p}\left(\mathcal{U}_{j}\right)} \leq C \sum_{j}\left\|\phi_{j}^{\#} u\right\|_{W^{\ell-1, p}\left(U_{j}\right)} \\
& \quad \leq C\|u\|_{W^{\ell-1, p}(M)}
\end{aligned}
$$

Proof of Theorem homotopy nemadimatata su M

$$
\begin{aligned}
d_{c} T_{M} & +T_{M} d_{c}+S_{M} \\
& =d_{c}\left(\sum_{i=0}^{k-1} S^{i}\right) T+\left(\sum_{i=0}^{k-1} S^{i}\right) \tilde{T} d_{c}+S^{k} \\
& =\sum_{i=0}^{k-1} S^{i}\left(d_{c} T+T d_{c}\right)+S^{k} \\
& =\sum_{i=0}^{k-1} S^{i}(I-S)+S^{k}=I
\end{aligned}
$$

Then statements i) ii) and iii) follow straightforwardly from i), ii) and iii) of Lemma
homotopy manifold 7.4.

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