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# Spatially localized radiating diffusion flames

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## A B S T R A C T

A simple model of radiating diffusion flames considered by Kavousanakis et al. (2013) [1] is extended to two spatial dimensions. A large variety of stationary spatially localized states representing the breakup of the flame front near extinction is computed using numerical continuation. These states are organized by a global bifurcation in space that takes place at a particular value of the Damköhler number and their existence is consistent with current understanding of spatial localization in driven dissipative systems.

**Keywords:**  
Diffusion flames  
Localized states  
Instabilities

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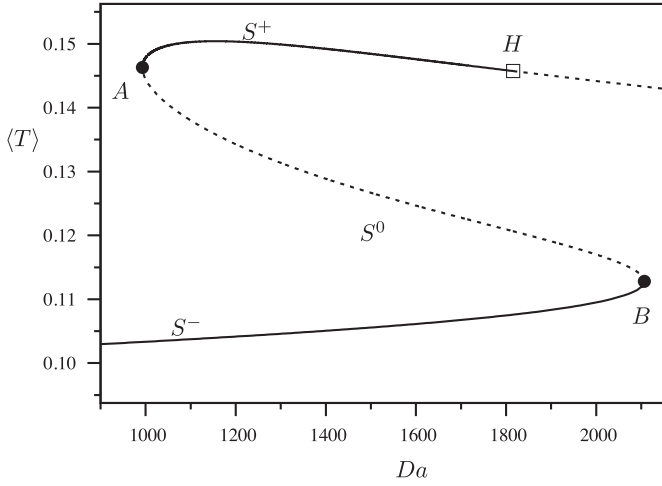
## 1. Introduction

In premixed flames, strong coupling between aerodynamics and reaction/diffusion processes arising from strong thermal expansion gives rise to Darrieus–Landau instabilities [2]. In diffusion flames, in contrast, thermal expansion plays a minor role in the thermal-diffusive processes that are behind the presence of instabilities in non-premixed flames [3]. The origin of these instabilities, which can lead to spatially uniform pulsation or to stationary or oscillating cellular structures, has been reviewed by Matalon [4,5]. Models of non-premixed flames that neglect aerodynamic effects have proved particularly useful in studies of turbulent partially premixed combustion. A well-known example is provided by the turbulent flamelet model of Peters [6] whose dynamics are dominated by diffusive processes, and not advection. The now classical flat unstrained flame introduced by Kirkbey and Schmitz [7] has been extensively studied, and numerous stability analyses [8–11] have shown that the Lewis numbers of both reactants play an essential role in selecting the nature of the possible thermal-diffusive instabilities that appear when approaching extinction (here necessarily via lean mixtures). Examples of these instabilities can be found in axisymmetric jet configurations, both experimentally [12–14] and numerically [15], as well as in tubular flames [16,17] and in unstrained flames [18,19].

The present paper is devoted to shedding additional light on the properties and dynamics of diffusion flames near flame ex-

tingtion. Of particular interest in this connection is the dynamical behavior preceding extinction, including intermittency, breakup, hopping, and other types of time dependence. Diffusion flames typically exhibit cellular structures, often accompanied by temporal oscillations. Existing studies range from detailed simulations of models that retain as many of the basic processes as possible to highly simplified model systems, designed to exhibit an understanding of the qualitative properties of such flames, usually through the use of linear stability analysis in time, e.g., [20]. Such model studies are useful in developing both physical intuition and a mathematical understanding of the observed transitions. The latter often relies on bifurcation theory and relevant dynamical systems theory [1].

This paper focuses on the spatial structure of diffusion flames in the extinction regime, but goes much beyond linear stability analysis. Specifically, we show that a well-known mechanism responsible for the presence of spatially localized structures in continuous systems described by partial differential equations applies to simple models of radiating diffusion flames, and explore its consequences for the predictions of the model. This mechanism is mathematical in nature, and employs an understanding of this type of model developed using ideas based on the notion of spatial dynamics: treating the spatial profile of a stationary solution of the equations as a consequence of evolution in the spatial variable, in other words, as if space were like time [21]. This is a powerful idea that makes most sense in systems with one unbounded direction. Of course, real systems are defined by boundary-valued problems whereas time-like problems are solved with initial conditions. It turns that this difference is not crucial, and that much can be deduced based on this approach even when the domain is finite, provided it is sufficiently large. This approach is extended here to



**Fig. 1.** The S-shaped branch of one-dimensional equilibria in terms of the average temperature  $\langle T \rangle \equiv (1/2) \int_{-1}^1 \tilde{T}(x) dx$  as a function of the Damköhler number  $Da$  for  $Le_o = Le_f = 1$ ,  $T_b = 0.1$ ,  $T_a = 1$  and  $R = 0.2$ , showing the folds A and B (solid dots) and a Hopf bifurcation at  $Da \approx 1800$  (H, open square symbol) on the upper branch  $S^+$ . The labels  $S^0$  and  $S^-$  indicate the middle and lower branches. Stable (unstable) branches are shown in solid (broken) lines.

two spatial dimensions and used to compute a large variety of stationary spatially localized states representing the breakup of the flame front near extinction. These states are organized by a global bifurcation in space that takes place at a particular value of the Damköhler number and their existence is consistent with current understanding of spatial localization in driven dissipative systems.

We consider a simple model of a radiating diffusion flame studied in [1]. Specifically, we consider a one-dimensional flame between a pair of porous walls that allow fuel (mass fraction  $Y_f$ ) to diffuse in from the left ( $x = -1$ ) and oxidizer (mass fraction  $Y_o$ ) to diffuse in from the right ( $x = 1$ ), both assumed to have the same temperature  $T_b$ . The burning process is described by a binary one step process of Arrhenius type with reaction term  $w = Da Y_o Y_f \exp(-T_a/T)$ , where  $T$  is the instantaneous temperature and the constant  $T_a$  represents the activation temperature. This temperature-activated process releases heat that is redistributed via radiation. Convection is ignored. The system is described by the nondimensional equations

$$\frac{\partial T}{\partial t} = \frac{\partial^2 T}{\partial x^2} + w - RDa(T^4 - T_b^4), \quad (1)$$

$$Le_o \frac{\partial Y_o}{\partial t} = \frac{\partial^2 Y_o}{\partial x^2} - w, \quad (2)$$

$$Le_f \frac{\partial Y_f}{\partial t} = \frac{\partial^2 Y_f}{\partial x^2} - w \quad (3)$$

with the boundary conditions

$$T = T_b, \quad Y_f = 1, \quad Y_o = 0 \quad \text{at} \quad x = -1, \quad (4)$$

$$T = T_b, \quad Y_f = 0, \quad Y_o = 1 \quad \text{at} \quad x = +1. \quad (5)$$

Here  $Le_o$  and  $Le_f$  are the Lewis numbers of the oxidizer and fuel, respectively,  $R$  is a parameter, and  $Da$  is the Damköhler number.

Steady solutions  $(\tilde{T}(x), \tilde{Y}_o(x), \tilde{Y}_f(x))$  of this boundary value problem are independent of  $Le_o$ ,  $Le_f$  and reveal the presence of the classic S-shaped response curve as a function of the Damköhler number first identified by Liñán [22] and Peters [23]. Figure 1 shows a typical result in terms of the spatial average of the temperature,  $\langle T \rangle \equiv (1/2) \int_{-1}^1 \tilde{T}(x) dx$ , plotted as a function of  $Da$ . In the following we refer to the states on the upper branch of the curve as  $S^+$  while those on the lower branch are labeled  $S^-$ ; the states

in between are labeled  $S^0$  (Fig. 1). The stability of this solution was examined in [1] for  $Le_o = Le_f = 1$ . The middle segment  $S^0$  of the S-shaped response was found to be unstable, with a real eigenvalue passing through zero at both the left and right folds, labeled A and B in Fig. 1 and represented as solid circles, as expected on the basis of standard bifurcation theory. In addition, the authors identified a sequence of Hopf bifurcations on the  $S^+$  branch, the first of which destabilizes  $S^+$  as  $Da$  increases (square symbol in Fig. 1), leading to temporal oscillations. Other Hopf bifurcations restabilize  $S^+$  at larger  $Da$  (not shown), so that in all cases the large  $Da$  part of  $S^+$  was found to be stable. This is of course the ignited state. Thus the results of [1] can be interpreted as showing that, within this model at least and for appropriate parameter values, the flame undergoes oscillations prior to extinction as  $Da$  decreases.

In this paper, we are interested in the steady solutions that bifurcate from the folds A and B on the S-shaped branch when the problem is extended to the  $(x, y)$  plane,  $-\infty < y < \infty$ . We refer to the  $y$  direction as the transverse direction. In other words, we study steady solutions of the problem

$$\frac{\partial T}{\partial t} = \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + w - RDa(T^4 - T_b^4), \quad (6)$$

$$Le_o \frac{\partial Y_o}{\partial t} = \frac{\partial^2 Y_o}{\partial x^2} + \frac{\partial^2 Y_o}{\partial y^2} - w, \quad (7)$$

$$Le_f \frac{\partial Y_f}{\partial t} = \frac{\partial^2 Y_f}{\partial x^2} + \frac{\partial^2 Y_f}{\partial y^2} - w \quad (8)$$

with the  $y$ -independent boundary conditions (4)–(5) on  $x = \pm 1$  and periodic boundary conditions in  $y$  with a large spatial period  $L_y \gg 1$ . The resulting system is spatially reversible, i.e., it is invariant under the transformation  $y \rightarrow -y$ . This is an important property of the model that has important consequences for the spatial eigenvalues of the base ( $y$ -invariant) state [21].

As in the one-dimensional case steady solutions of this problem are necessarily independent of the Lewis numbers  $Le_o$ ,  $Le_f$ . Moreover, one class of solutions consists of those found in [1], extended uniformly in  $y$ . However, when the stability of these solutions is examined with respect to  $y$ -dependent perturbations one finds that other,  $y$ -dependent, solutions may be present. This is so despite the fact that there is no bifurcation to periodic states in the  $y$  direction, the so-called striped flames. This fact can be established by examining the linear problem for an infinitesimal perturbation  $(a'(x, y, t), b'(x, y, t), c'(x, y, t))$  of the one-dimensional time-independent solution  $(\tilde{T}(x), \tilde{Y}_o(x), \tilde{Y}_f(x))$ . This linear problem can be separated by writing  $(a'(x, y, t), b'(x, y, t), c'(x, y, t)) = (a(x), b(x), c(x)) \exp(\sigma t +iky)$ . The resulting  $k$ -dependent linear problem has no solutions with zero growth rate  $\sigma$  when  $k \neq 0$ , indicating the absence of a pattern-forming Turing instability. However, when  $k = 0$  the linear problem does have two locations where  $\sigma = 0$ . These are precisely the folds A and B on the S-shaped branch, where – as already mentioned – the stability problem for the one-dimensional solution  $(\tilde{T}(x), \tilde{Y}_o(x), \tilde{Y}_f(x))$  necessarily has a zero eigenvalue.

The paper is organized as follows. In Section 2, we provide a brief summary of the essential input from dynamical systems theory that guides our study. Detailed results are presented in Section 3 and these confirm the bifurcation structure anticipated in Section 2. The paper concludes with a brief discussion and conclusions. The numerical procedure used to compute localized structures in the present system is described in the Appendix.

## 2. A brief review of the theory

The theory summarized below applies to systems with a single unbounded direction such as the  $y$  direction in the present problem. We suppose that the system exhibits an S-shaped branch

of  $y$ -independent states. In this case it is known [24–26] that a branch of  $y$ -dependent solutions bifurcates from each fold, and that in both cases it does so in the inward direction. An explicit example of a weakly nonlinear calculation demonstrating this fact can be found in Appendix C of Ref. [24] or in the Appendix of Ref. [26]. The solutions that bifurcate from the folds are not periodic, but take the form of a gentle dip in  $S^+$  (fold A) or gentle bump on top of  $S^-$  (fold B), both with  $y$ -dependent profiles of the form  $a \operatorname{sech}^2 by$ . Here  $a \propto |Da - Da_{sn}|^{1/2}$  and  $b \propto |Da - Da_{sn}|^{1/4}$ , where  $Da_{sn}$  is the Damköhler number corresponding to fold A or B (and hence the location of the saddle-node bifurcation). Both states are reflection-symmetric with respect to the reflection  $y \rightarrow -y$ . With increasing distance from the fold A the dip deepens and the solution localizes in the  $y$  direction forming a state that has been called a hole: the solution connects the upper branch state  $S^+$  to the lower branch state  $S^-$  and back again. The shape of the fronts connecting these states is determined by the value of  $Da$  and is highly nonlinear. As one follows this branch, using numerical continuation, for example, one finds that the hole broadens as the  $S^-$  state invades the domain and displaces the fronts to either side away from the center. Following the solution branch further one observes that the peak amplitude begins to decrease while the solution continues to broaden, thereby forming a peak on top of the  $S^-$  state. This process continues as one follows the branch yet further until the solution branch terminates at fold B on the branch of  $y$ -independent states. Thus the folds A and B are in fact connected by a branch of  $y$ -dependent steady solutions of problem. We refer to the resulting  $y$ -dependent solutions as localized states, and label the associated branch with the letter  $L$ . When periodic boundary conditions with a large spatial period are imposed in the  $y$  direction, as typically done in numerical computations, the above situation persists, although the bifurcations to the  $y$ -dependent states shift from the folds to nearby values of the Damköhler number. All of these transitions can be clearly seen in recent work on the Lugiato–Lefever equation arising in nonlinear optics [26]; this equation also exhibits an S-shaped response curve but the calculations are simpler since the equation as posed in [26] is one-dimensional.

The detailed behavior of the  $L$  branch depends on the nature of the spatial eigenvalues  $\lambda$  of  $S^\pm$ . These eigenvalues are obtained by linearizing the time-independent Eqs. (6)–(8) about the steady state  $(\bar{T}(x), \bar{Y}_0(x), \bar{Y}_f(x))$  and looking for steady solutions of the form  $(a'(x, y), b'(x, y), c'(x, y)) = (a(x), b(x), c(x)) \exp(\lambda y)$ . Because of the symmetry  $y \rightarrow -y$  if  $\lambda$  is an eigenvalue so is  $-\lambda$ ; if  $\lambda$  is complex  $\lambda^*$ ,  $-\lambda$  and  $-\lambda^*$  are also eigenvalues. Thus generically spatial eigenvalues come in quartets. In particular, when the leading spatial eigenvalues (the eigenvalues whose real part is closest to zero) of  $S^\pm$  are both real the front connecting  $S^+$  to  $S^-$  will be monotonic, leaving  $S^+$  along the  $\lambda^+ > 0$  direction in phase space and approaching  $S^-$  along the corresponding  $-\lambda^- < 0$  direction; the front at the other end of the hole will also be monotonic, leaving  $S^-$  along the  $\lambda^- > 0$  direction and approaching  $S^+$  along the  $-\lambda^+ < 0$  direction. In this case the  $L$  branch is also monotonic: it extends to the right from the left fold at A and to the left from the right fold at B, becoming vertical at an intermediate  $Da$  value, hereafter  $Da_M$ , corresponding to the formation of a front between  $S^+$  and  $S^-$ ; owing to the symmetry  $y \rightarrow -y$  this solution in fact corresponds to the formation of a heteroclinic cycle, when the system is viewed as evolving in  $y$  from  $-\infty$  to  $+\infty$ . This cycle connects  $S^+$  to  $S^-$  and back to  $S^+$ , or equivalently  $S^-$  to  $S^+$  and back to  $S^-$ . Unfortunately all these solutions are unstable with respect to infinitesimal perturbations growing in time.

If, however, the spatial eigenvalues  $\lambda^+$  of  $S^+$  are complex the fronts will no longer be monotonic, and will exhibit growing oscillations as they depart from  $S^+$  before approaching  $S^-$  along the  $-\lambda^-$  direction. The presence of these oscillations is reflected in

growing oscillations in the branch  $L$  as the hole deepens and fills with  $S^-$ . These oscillations are important because the  $L$  segments with a positive slope (i.e., between a fold on the left and the next fold on the right) in the bifurcation diagram will be stable with respect to infinitesimal perturbations in time [26]; the rest of the  $L$  branch, and in particular the segments near A and B remain unstable. Thus in this case one finds temporally stable spatially localized solutions lying on portions of the branch  $L$  – a new type of stable diffusion flame. Since the intervals of stable solutions on  $L$  lie below  $S^+$  (see below) these spatially localized flames will be cooler than the spatially homogeneous flame  $S^+$ . Note, in particular, that these stable localized solutions are present despite the absence of spatially periodic  $y$ -dependent states. In the literature this type of behavior is known as collapsed snaking [25,27].

The above statements are consequences of the theory of spatial dynamics applied to problems of this type [21,28] and hence are not specific to the problem under discussion. In the next section, we demonstrate that these conclusions indeed apply to Eqs. (6)–(8) with the boundary conditions (4)–(5), and discuss the additional features that come about when the problem is posed on a periodic domain in the  $y$  direction with period  $L_y < \infty$ .

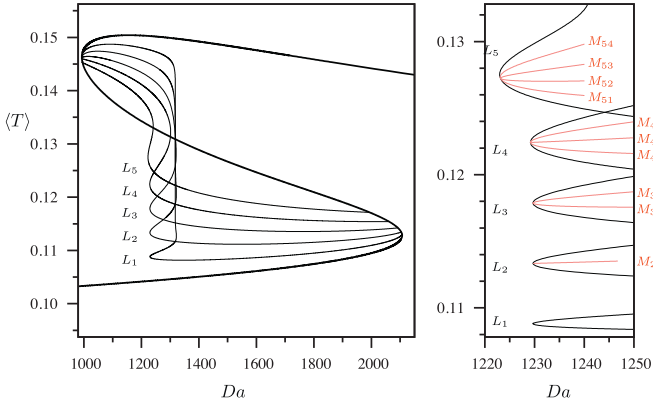
In fact the situation is yet more complex as we show in explicit computations, also in the next section.

### 3. Results

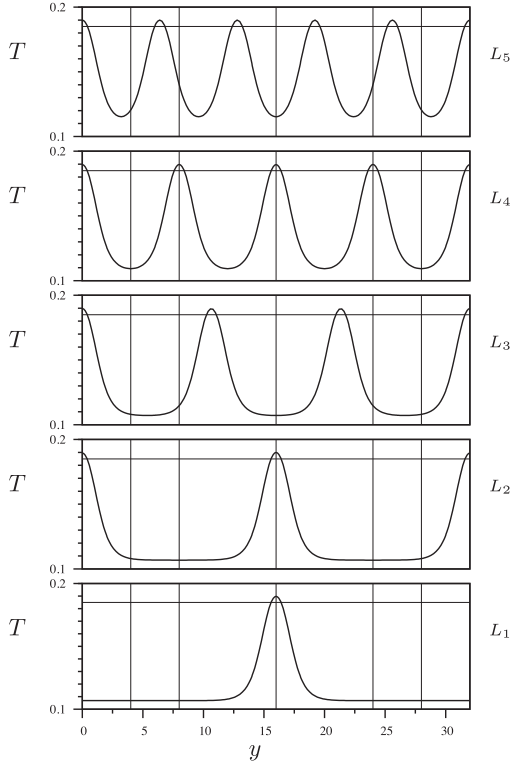
Our numerical results employ the same parameter values as used in [1], viz.  $Le_o = Le_f = 1$ ,  $T_b = 0.1$ ,  $T_a = 1$  and  $R = 0.2$ . All calculations are performed in a domain of area  $S \equiv 2 \times L_y$  with periodic boundary conditions at  $y = 0, L_y$  and  $L_y = 32$ . We represent our results in bifurcation diagrams showing  $\langle T \rangle \equiv S^{-1} \int_S T(x, y) dS$ , i.e., the average temperature in the domain. This representation of the solution is preferred since it is capable of distinguishing between solutions with temperature peaks of different heights, unlike diagrams showing, for example, the maximum temperature along the center line  $x = 0$ . Stability properties of the solutions are determined using the Arnoldi method which is used to track the dominant temporal eigenvalues of the solutions as a function of the Damköhler number. The fact that the domain in  $y$  is finite modifies in certain respects the predictions of the general theory summarized in the preceding section, as also explained below.

#### 3.1. Primary branches

The finite domain size  $L_y < \infty$  has two main effects: (i) it forces the wavenumber  $k$  to take on integer values, and (ii) it limits, for example, the width of the  $S^-$  hole that can develop within the  $S^+$  state. The former implies that the bifurcations at the left and right folds break up into a series of successive bifurcations generating solutions with  $k = 1, 2, 3, \dots$ , with  $k = 1$  representing one wavelength within the  $y$  domain,  $k = 2$  representing two wavelengths etc. Since modulation of  $(\bar{T}(x), \bar{Y}_0(x), \bar{Y}_f(x))$  with wavenumber  $0 < k \ll 1$  is no longer possible these bifurcations will be displaced from the folds, with the bifurcation generating  $k = 1$  closest to the fold,  $k = 2$  further from the fold, etc. Figure 2(a) shows the S-shaped branch of  $y$ -independent solutions computed in [1] (Fig. 1) together with five branches of  $y$ -dependent states connecting the region near fold A with the region near fold B. All of these branches, hereafter  $L_k$ , behave in a similar way, with the  $k = 1$  closest to the theoretically predicted behavior. Near the primary bifurcation point near B the solution corresponds to the slowly varying peak state; by the time one reaches the first fold on the left this peak state has grown in amplitude to the amplitude of the  $S^+$  state and has self-focused into a single spatially localized pulse whose shape is determined by the value of the Damköhler number at this fold (Fig. 3, lowest panel). At this



**Fig. 2.** (a) Bifurcation diagram showing the quantity  $\langle T \rangle \equiv S^{-1} \int_S T(x, y) dS$  as a function of the Damköhler number  $Da$  for  $Le_o = Le_f = 1$ ,  $T_b = 0.1$ ,  $T_a = 1$ ,  $R = 0.2$  and  $L_y = 32$ . The branches of  $k$ -pulse localized states are denoted  $L_k$ . Stable (unstable) branches are indicated in solid (broken) lines. (b) A close-up of the left folds on each of the  $L_k$  branches shown in (a) showing the presence of tertiary branches of multipulse states of unequal height (stability not indicated).



**Fig. 3.** Solutions  $T(0, y)$  at the left folds on the  $L_k$  branches for the parameter values of Fig. 2 and appropriate values of the Damköhler number  $Da$ . The horizontal lines indicate the amplitude of the plateau corresponding to  $Da = Da_M$ ; the vertical lines indicate the axes of symmetry of the different solutions.

fold the branch acquires stability and the pulse remains stable until the next fold on the right where it loses stability again. Since there is in fact an infinite number of oscillations in the branch as  $\langle T \rangle$  increases (impossible to see on the scale of the figure) this process repeats, generating an exponentially decreasing sequence of intervals in  $Da$  with stable pulses. These successive pulses differ in the width of the plateau at amplitude  $S^+$  that is enclosed by the oscillating fronts on either side, whose profile is fixed by the Damköhler number  $Da \approx Da_M = 1318$ . The other branches behave similarly, except that  $L_2$  self-focuses into two identical equidistant pulses,  $L_3$  self-focuses into three identical equidistant pulses, etc. The pulses comprising the  $L_1, L_2, L_3, \dots$  solutions at the first folds on the left

differ only very slightly, owing to the slightly different values of  $Da$  at these folds, and this remains so provided they remain sufficiently separated. Of course, since the pulse width is determined by  $Da$  only a finite number of pulses can fit into the available  $y$ -domain. For this reason the solution branches with  $k > 3$  depart from the theoretically predicted behavior: the corresponding solutions can no longer be considered to be spatially localized and significant interaction between pulses takes place. For these reasons the  $L_k$  branches with  $k > 3$  no longer oscillate, and indeed do not undergo the abrupt growth in the pulse width predicted to take place near  $Da_M$ .

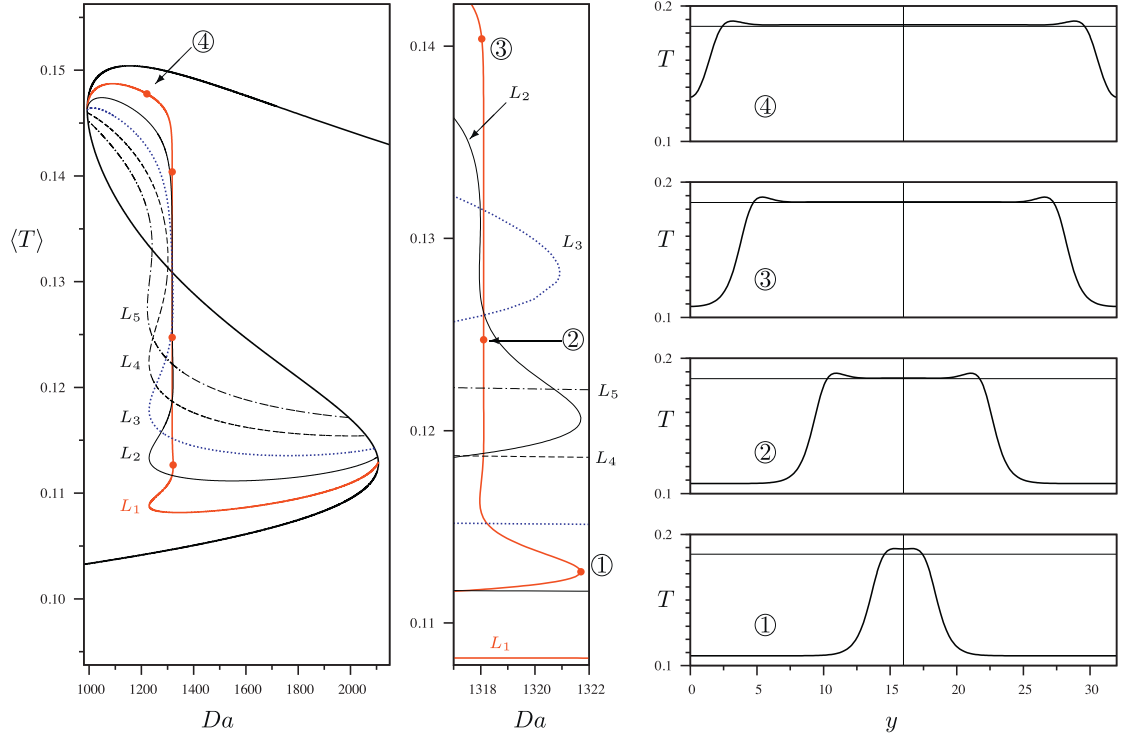
The value  $Da = Da_M$  corresponds to the formation of a heteroclinic cycle connecting the homogeneous states  $S^+$  and  $S^-$  at this value of  $Da$ , and plays the role of a Maxwell point familiar from systems exhibiting gradient dynamics [21]. Figure 4 shows several profiles at  $Da \approx Da_M$  with increasing values of  $\langle T \rangle$ . At the first right fold at the lower end of the near-vertical segment of the  $L_1$  branch the one-pulse state shown in Fig. 3 (bottom panel) starts to develop a dimple in the center (Fig. 4, profile 1). This is a consequence of the complex spatial eigenvalues of  $S^+$ . As  $\langle T \rangle$  increases the pulse broadens (Fig. 4, profiles 2 and 3). In an infinite system this process continues indefinitely, resulting in the formation of the heteroclinic cycle connecting  $S^+$  and  $S^-$ . In a domain of finite period this process inevitably terminates and the branch turns at the top towards lower Damköhler numbers. Figure 4, profile 4, shows that in this regime the minima at either end start to lift up, creating a hole-like modulation of the high temperature state  $S^+$ . With decreasing  $Da$  this hole becomes shallower and shallower and at the termination point near fold A the hole disappears and the state  $S^+$  is recovered. Of course, because of translation invariance, the hole can be moved to the center of the periodic domain. One sees that such a state therefore represents an “anti-pulse”. Thus on a finite domain the branch of pulses bifurcating from B connects to the branch of holes or anti-pulses that bifurcates from A [26]. Analogous evolution takes place along branches  $L_k$ ,  $k > 1$ , with the same value of  $Da_M$ .

We emphasize that the oscillatory approach of the solution branches in Fig. 2(a) to  $Da = Da_M$  and hence the presence of the folds on the  $L_k$  branches is a direct consequence of the fact that the leading spatial eigenvalues of the state  $S^+$  at  $Da = Da_M$  are complex. These oscillations in turn stabilize the portions of the  $L_k$  branches with positive slope and hence lead to multistability of different localized states in the vicinity of  $Da_M$ .

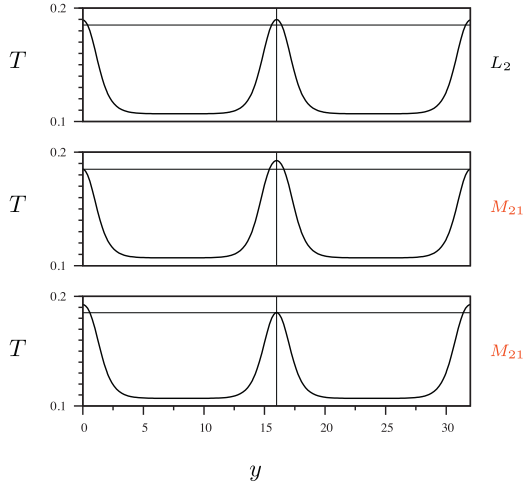
### 3.2. Secondary branches

For  $k > 1$  the primary states produced by the above process resemble periodic arrays of pulses. It is therefore not surprising that the folds on these branches generate a secondary family of hole-like states, i.e., spatially modulated arrays of pulses. The mechanism is essentially the same, except that this time the stability problem is of Floquet type and the computation of the modulated states near the folds cannot be accomplished analytically even in one spatial dimension. Figure 2(b) shows the secondary branches near the left folds on the primary branches  $L_k$  of localized states. The modulational instability generates solutions consisting of a certain number of higher and lower peaks taken from the upper and lower branches on either side of the  $L_k$  fold. We use the integer  $\ell$ ,  $\ell < k$ , to denote the number of higher peaks in the solution ( $k - \ell$  is then the number of lower peaks), and label the resulting modulated solutions using the notation  $M_{k\ell}$ . In each case we observe the presence of  $k - 1$  secondary branches. In particular, when  $k = 1$  there is no possible modulation, and indeed no secondary bifurcation is observed. When  $k = 2$  a modulation centered on  $y = 0$  can either increase or decrease the height of the central peak (Fig. 5). However, translation invariance of the system in the  $y$



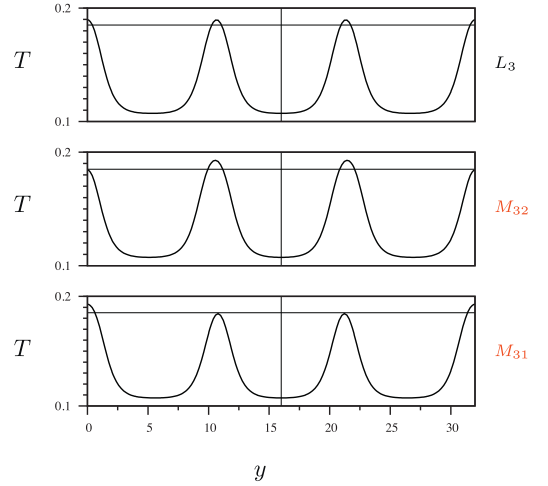


**Fig. 4.** Detail of Fig. 2 in the vicinity of  $Da = Da_M$  showing the abrupt evolution of the solution profile that takes place in this regime. The profiles  $T(0, y)$  shown on the right correspond to the numbered locations: ①:  $Da = 1321.6974$ , ②:  $Da = 1318.1069$ , ③:  $Da = 1318.0387$ , ④:  $Da = 1221.3835$ . The horizontal lines in the right panels indicate the plateau corresponding to  $Da = Da_M$ ; the vertical lines indicate the axis of symmetry of the solutions.



**Fig. 5.** Comparison of the  $L_2$  solution (top panel) with the  $M_{21}$  solution (lower panels) at  $x = 0$ . The solutions in the lower panels are related by translation through  $L_y/2$ . The thin horizontal line connects the peaks with the smaller amplitude and is drawn to emphasize the height differences arising from spatial modulation of the  $L_2$  state in the top panel. The Damköhler numbers are ( $L_2$ ) 1229.7331, ( $M_{21}$ ) 1245.8670, and ( $M_{21}$ ) 1244.0886.

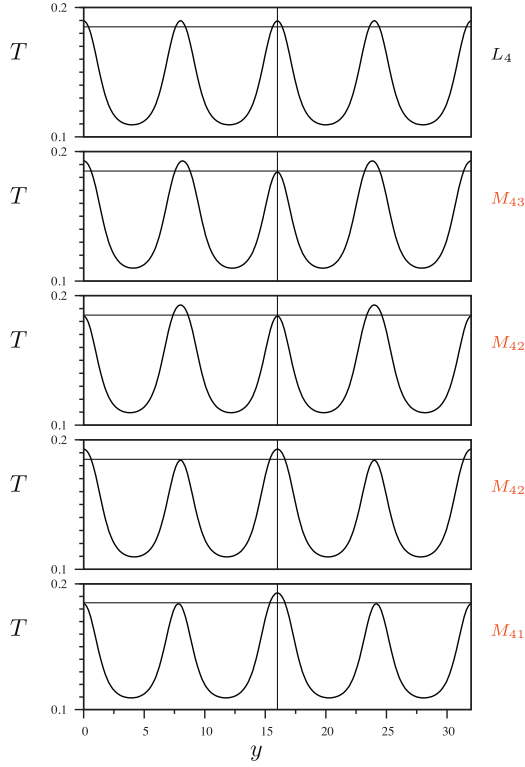
direction shows that the resulting two states are in fact equivalent; thus only one branch of modulated pulses, hereafter  $M_{21}$ , bifurcates from the vicinity of the left fold of the  $L_2$  branch (Fig. 2(b)). When  $k = 3$  a modulation centered on  $y = 0$  can either decrease the amplitude of the two middle peaks or increase it. The resulting states are now distinct and hence two branches of secondary modulated solutions bifurcate from the vicinity of the lowest fold on the  $L_k$  branch (Fig. 6). When  $k = 4$  there are three distinct secondary branches labeled  $M_{43}$ ,  $M_{42}$  and  $M_{41}$  (Fig. 7), and similarly for  $k = 5$  (Fig. 8). As each of these branches is followed from their



**Fig. 6.** Comparison of the  $L_3$  solution (top panel) with the  $M_{31}$  and  $M_{32}$  solutions (lower panels) at  $x = 0$ . The Damköhler numbers are ( $L_3$ ) 1229.6859, ( $M_{32}$ ) 1249.4207 and ( $M_{31}$ ) 1250.0697.

birth in the direction of increasing  $Da$ , all replicate the same type of snaking in the vicinity of  $Da_M$  as the primary branches. Moreover, similar tertiary bifurcations take place at all the other folds on the  $L_k$  branches. For a similar construction in a different two-dimensional system, see [29].

The above analysis is important for the stability of the  $L_k$  states. We have already noted that the  $L_1$  branch is initially unstable with a single unstable eigenvalue. This is because it bifurcates from  $S^0$  above the right fold, where  $S^0$  is once unstable. This bifurcation is supercritical, in the sense that it is in the direction of increasing instability of  $S^0$  (decreasing Damköhler number). Consequently  $L_1$  is once unstable. If no additional bifurcations take place  $L_1$  will restabilize at the first fold since its eigenvalue behaves like that of

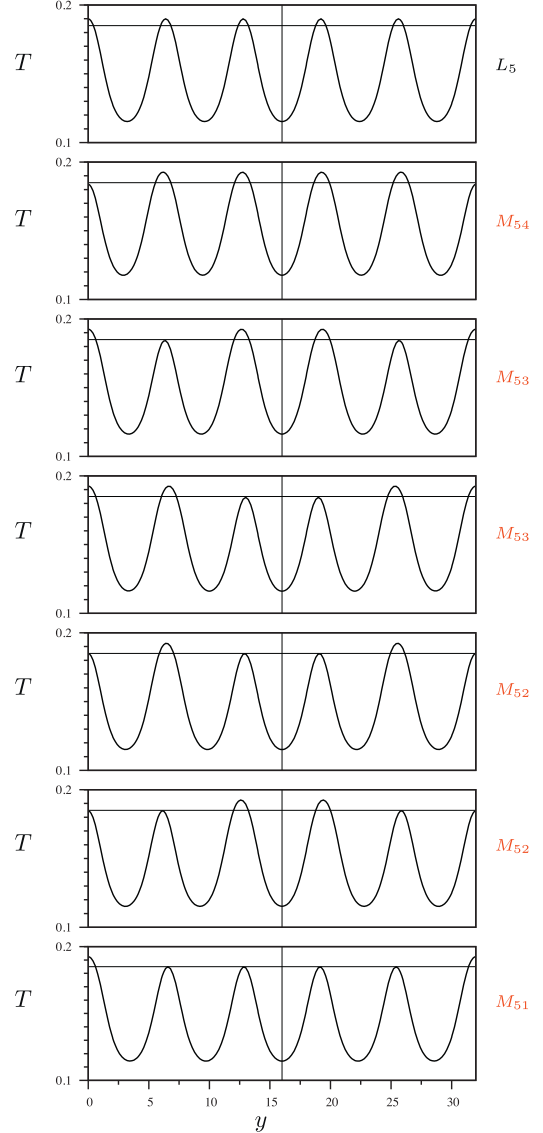


**Fig. 7.** Comparison of the  $L_4$  solution (top panel) with the  $M_{43}$  solution (second panel), the  $M_{42}$  solutions (panels three and four) and the  $M_{41}$  solution (last panel), all at  $x = 0$ . The solutions in panels three and four are related by translation by  $L_y/4$ . The Damköhler numbers are ( $L_4$ ) 1229.1817, ( $M_{43}$ ) 1249.7594, ( $M_{42}$ ) 1249.6024, ( $M_{42}$ ) 1249.6946 and ( $M_{41}$ ) 1249.7307.

$S^0$  which also restabilizes at a left fold (fold A). Thus one expects the single pulse state to be stable above the first left fold of  $L_1$ ; this state is destabilized by the same eigenvalue at the next fold on the right, and so on all the way up the  $L_1$  branch. Similarly, the branch  $L_2$  is twice unstable near the bifurcation that creates it (it is unstable with respect to a spatially uniform eigenfunction and also with respect to single-pulse perturbations). The first of these eigenvalues restabilizes at the left fold of  $L_2$  while the other is involved in the bifurcation to the modulated state  $M_{21}$  that takes place near this fold. Thus after these two bifurcations at or near the left fold the two-pulse state acquires stability. At the same time we see that the secondary bifurcation to the  $M_{21}$  state is subcritical, and hence this state is unstable near the bifurcation that creates it (Fig. 2(b)). By the same argument the three-pulse state  $L_3$  also acquires stability after the left fold on  $L_3$  and the two successive bifurcations creating  $M_{31}$  and  $M_{32}$ , etc. These results are completely consistent with our numerical continuation results.

#### 4. Discussion and conclusions

In this paper, we have examined a simple model of diffusive flames with radiative temperature redistribution, focusing on its properties near the extinction regime (fold labeled A). Despite its simplicity the model exhibits interesting properties. Using numerical branch-following methods, motivated by a theoretical understanding of the origin of spatially localized structures [21], we identified a sequence of branches consisting of  $k$  equidistant temperature peaks along the flame front. These solutions represent states generated by the breakup of the front, and correspond to cooler structures centered on the middle of the channel ( $x = 0$ ) and localized in the transverse direction. We have seen that these states are located near the “Maxwell” point  $Da = Da_M$  correspond-



**Fig. 8.** Comparison of the  $L_5$  solution (top panel) with the  $M_{54}$  solution (second panel), two distinct  $M_{53}$  solutions (panels three and four), two distinct  $M_{52}$  solutions (panels five and six), and one  $M_{51}$  solution (panel seven). The branches of the  $M_{52}$  and of the  $M_{53}$  solutions are distinct but coincide in the representation used to plot them, to within numerical error. The Damköhler numbers are ( $L_5$ ) 1222.9785, ( $M_{54}$ ) 1239.7467, ( $M_{53}$ ) 1239.7574, ( $M_{53}$ ) 1239.3069, ( $M_{52}$ ) 1238.0365, ( $M_{52}$ ) 1239.8294 and ( $M_{51}$ ) 1239.7314.

ing to the appearance of a heteroclinic connection between the cold homogeneous state and the homogeneous flame, and that they can be stable provided the spatial eigenvalues of the hot homogeneous state are complex. We have confirmed that this is indeed the case for the parameter values considered in [1].<sup>1</sup> Applying the same ideas to the localized states  $L_k$ , now viewed as periodic states with period  $L_y$ , we discovered the presence of multiple tertiary branches originating from the vicinity of all folds on the  $L_k$  branches, and consisting of  $k$  peaks of different heights. Although we did not determine the stability properties of these tertiary states we have argued that their presence is in fact key for the stability of the multipulse states  $L_k$ ,  $k > 1$ , since bifurcations to these states are required to stabilize the multipulse states near

<sup>1</sup> These eigenvalues become pure imaginary at and beyond the Hopf bifurcation identified in [1] since  $S^+$  is then unstable in time, cf. [25].



$Da = Da_M$ . These results suggest a simple procedure for identifying the location in parameter space where localized flames are present – it suffices to compute the dependence of  $Da_M$  on the model parameters and use the result to track  $Da_M$  through parameter space.

We remark that each of our  $L_k$  solutions corresponds to a periodic state on the real line,  $-\infty < y < \infty$ , each with a different basic wavelength. Each of these periodic states undergoes a fold on the left much like the much-studied Swift–Hohenberg equation with a quadratic-cubic nonlinearity [30]. It follows that a pair of branches of spatially localized *pulse trains* necessarily bifurcates from the left fold of such replicated  $L_k$  states and that these undergo homoclinic snaking as described in [21,28], in contrast to the collapsed snaking exhibited by  $L_k$ . Thus on large domains, admitting modulation extending over many wavelengths, a yet greater variety of localized structures, consisting of coexisting groups of pulses with different numbers of pulses, can be found. However, the corresponding calculations appear prohibitive and we have not pursued this direction further.

The model studied here, despite its simplicity, captures the essential qualitative properties of “real” diffusive flames seen in experiments. To demonstrate that this is so a movie is presented as supplemental material. This movie records an experiment in the first version of a novel one-dimensional burner [18]. The experiment consists of a closed square combustion chamber with the reactants and products positioned in a counterflow configuration. This is done using 625 injection needles (1 mm O.D.) through which the reactant is fed in while the hot air/products exit the chamber inbetween the needles. The oxidizer mixture ( $O_2$ – $CO_2$ ) for this movie was fixed at 70%  $O_2$  by volume (62.92% mass), with the reactant mixture ( $H_2$ – $CO_2$ ) slowly decreasing from 24% to 12%  $H_2$  by volume (1.41% to 0.73% mass). The flow rate was maintained at  $Q_0 = 3.33 \times 10^{-5} \text{ m}^3/\text{s}$  (33.3 ml/s),  $Q_f = 3.00 \times 10^{-5} \text{ m}^3/\text{s}$  (30 ml/s) with a cross-sectional area of 46 mm<sup>2</sup>. The movie was captured by a digital camcorder (Sony, DSR 300P), at an oblique angle of about 45° with respect to the flat and horizontal flame. Frames from this movie are shown as still pictures in [18]. The movie illustrates the transition process from a flat flame to a fully cellular flame all the way to spatially localized flamelets. The movie begins with a flat flame, and as the reactant mixture becomes poorer in  $H_2$  cell formation starts at the flame edges adjacent to the chamber walls. We note the cells are not spatially locked to the tube grid. As the  $H_2$  concentration is reduced further, the cellular region grows towards the center of the flame. After some time (around 1 min), the entire flame consists of cells and the transition to the fully cellular regime is considered complete. At this point, the cell structures (flame “patches”) are not stationary. As the  $H_2$  concentration is reduced even further, the number of cells progressively decreases until the extinction limit is reached. We believe that the flame undergoes breakup into spatially localized structures in the time interval 1.0–1.5 min. It is in this region that our insight into the presence of a large multiplicity of localized structures with a specific characteristic size becomes particularly relevant.

The key new observation for near-extinction flame dynamics is the observation that the fold  $A$  representing extinction of the uniform ( $y$ -invariant) flame is responsible for the presence of a large number of simultaneously stable spatially localized flames at nearby values of the Damköhler number. We believe that this property carries over to more sophisticated models and hence has broad relevance to diffusion flames in general. This new class of states becomes particularly relevant when the uniform flame  $S^+$  becomes unstable to oscillations already near  $A$ , for example, by moving the Hopf bifurcation  $H$  in Fig. 1 to lower values (by changing the value of the parameter  $R$  or the Lewis numbers  $Le_o$ ,  $Le_f$ ) so that the localized flames are also time-dependent.

Given the success of our approach it is now of considerable interest to explore extensions of the model to more realistic configura-

tions. In future work we shall explore the effects of different fuel and oxidizer Lewis numbers on the dynamical properties of the localized states we have found (which are independent of  $Le_o$ ,  $Le_f$ ), as well as including the effects of hydrodynamic flow (cf. [20]), and extending the calculations to three dimensions in order to identify spot-like flames in the extinction region. More realistic models should also include density dependence of the model parameters.

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## Appendix

In order to compute steady solutions of Eqs. (6)–(8) with the boundary conditions (4)–(5) as a function of the Damköhler number  $Da$ , we use a standard numerical arclength continuation method [31] based on a Newton solver for the time-independent version of the equations [32]. This method allows one to follow branches of stable or unstable steady states, compute their linear stability, locate secondary bifurcations and follow the resulting secondary solution branches.

To do so, the equations are spatially discretized using a spectral element method in which the domain  $[0, 2] \times [0, L_y]$  is decomposed into  $N_e$  spectral elements of size  $[0, 2] \times [kl_y, (k+1)l_y]$  with  $N_e l_y = L_y$  and  $0 \leq k \leq N_e - 1$ . In each element, the fields  $(T, Y_o, Y_f)$  are approximated by a high-order interpolant through  $n_x \times n_y$  Gauss–Lobatto–Legendre points. In the continuation procedure, the solutions are calculated as a function of the branch arclength. Each point of this branch corresponds to a steady state that includes the values  $\bar{Y} \equiv (\bar{T}_j, \bar{Y}_{oj}, \bar{Y}_{fj})_{1 \leq j \leq N}$  of  $(T, Y_o, Y_f)$  at the  $N = N_e n_x n_y$  discretization points and the corresponding Damköhler number  $Da$ . The unknowns  $\bar{X} \equiv (\bar{Y}, Da)$  are obtained by solving the discretized steady state equations by a Newton method. The arclength is then incremented and the procedure repeated.

The Newton solver that we use derives from a first-order time integration scheme for the time-dependent problem [33,34] and we use a scheme in which the diffusive linear part of the equations is treated implicitly while the nonlinear part is treated explicitly. Each time step requires the inversion of three Helmholtz problems. The discrete version of the weak form of each Helmholtz problem is first transformed into a set of  $n_x$  one-dimensional problems after a partial diagonalization of the operator, each of which is solved using a Schur decomposition method.

Once a steady state is obtained, its linear stability properties are studied by means of Arnoldi’s method. This method allows one to compute the most unstable eigenvalues and the corresponding eigenvectors, and these can be used to locate secondary bifurcations. Once a steady bifurcation is located, the corresponding unstable eigenvector and associated steady state are used to build a predictor for a solution along the emerging branch; the code then uses continuation to follow the new branch. Again, the implementation of the Arnoldi procedure uses the first order time-stepping code following the procedure originally proposed by Tuckerman [33].

The technique has been used with success to compute time-independent localized structures in several systems arising in fluid mechanics [35–38].

## Supplementary material

Supplementary material associated with this article can be found, in the online version, at [10.1016/j.combustflame.2016.10.002](https://doi.org/10.1016/j.combustflame.2016.10.002).

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