



HAL
open science

Optimal location of sensors and actuators for wave and heat processes

Yannick Privat, Emmanuel Trélat, Enrique Zuazua

► **To cite this version:**

Yannick Privat, Emmanuel Trélat, Enrique Zuazua. Optimal location of sensors and actuators for wave and heat processes. Pde's, Dispersion, Scattering theory and Control theory, Jun 2013, Monastir, Tunisia. pp.123–139. hal-01582648

HAL Id: hal-01582648

<https://hal.science/hal-01582648>

Submitted on 7 Sep 2017

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

OPTIMAL LOCATION OF SENSORS AND ACTUATORS FOR WAVE AND HEAT PROCESSES

par

Yannick Privat, Emmanuel Trélat & Enrique Zuazua

Résumé. — We investigate the problem of optimizing the shape and location of sensors and actuators for evolution systems driven by distributed parameter systems or partial differential equations (PDE). We consider wave, Schrödinger and heat equations on an arbitrary domain Ω , in any space dimension, and with suitable boundary conditions (if there is a boundary) which can be of Dirichlet, Neumann, mixed or Robin type. This kind of problem is frequently encountered in applications where one aims, for instance, at maximizing the quality of reconstruction of the solution, using only a partial observation. From the mathematical point of view, using probabilistic considerations we model this problem as that of maximizing the so-called randomized observability constant, over all possible subdomains of Ω having a prescribed measure. The spectral analysis of this problem reveals intimate connections with the theory of quantum chaos. More precisely, we provide a solution to this problem when the domain Ω satisfies suitable quantum ergodicity assumptions.

This proceedings paper is a short exposition and survey of results published in a series of works [17, 18, 19, 20, 21], in which we solved the above issues. The second author gave a talk on that subject in a workshop organized in Monastir in 2013.

1. Introduction

Our objective is to model and solve the problem of optimizing the shape and location of sensors and actuators for processes modeled by a PDE on any open bounded connected subset of a Riemannian manifold, with various possible boundary conditions. Our results reveal intimate connections with quantum ergodicity issues. They strongly depend on the nature of the PDE under consideration.

1.1. The context. — The literature on optimal observation or sensor location problems is abundant in engineering applications (see, e.g., [3, 10, 13, 14, 23, 25, 26, 27] and references therein), where the aim is often to optimize the number, the place and the type of sensors in order to improve the estimation of the state of the system. Fields of applications are very numerous and concern for example active structural acoustics, piezoelectric actuators, vibration control in mechanical

structures, damage detection and chemical reactions, just to name a few of them. In most of these applications the method consists in approximating appropriately the problem by selecting a finite number of possible optimal candidates and of recasting the problem as a finite-dimensional combinatorial optimization problem. In many of these contributions the sensors have a prescribed shape (for instance, balls with a prescribed radius) and then the problem consists of placing optimally a finite number of points (the centers of the balls) and thus is finite-dimensional, since the class of optimal designs is replaced with a compact finite-dimensional set.

In the present paper our objective is to run the search over *all* possible subsets, in other words we optimize not only the placement but also the shape of the sensors or actuators.

Among the existing approaches, the closest one to ours consists of considering truncations of Fourier expansion representations. Adopting such a Fourier point of view, the authors of [11, 12] studied optimal stabilization issues of the one-dimensional wave equation and, up to our knowledge, these are the first articles in which one can find characterizations of the optimal set whenever it exists, for the problem of determining the best possible shape and position of the damping subdomain of a given measure. In [5] the authors investigate the problem modeled in [23] of finding the best possible distributions of two materials (with different elastic Young modulus and different density) in a rod in order to minimize the vibration energy in the structure. For this optimal design problem in wave propagation, the authors of [5] prove existence results and provide convexification and optimality conditions. The authors of [1] also propose a convexification formulation of eigenfrequency optimization problems applied to optimal design. In [8] the authors discuss several possible criteria for optimizing the damping of abstract wave equations and derive optimality conditions for a certain criterion related to a Lyapunov equation.

From the mathematical point of view, the issue of studying a relaxed version of optimal design problems for the shape and position of sensors or actuators has been investigated in a series of articles. In [16], the authors study a convexified version of the optimal location of controllers for the heat equation problem, noticing that such problems are often ill-posed. In [2], the authors consider a similar problem and study the asymptotic behavior as the final time T goes to infinity of the solutions of the relaxed problem; they prove that optimal designs converge to an optimal relaxed design of the corresponding two-phase optimization problem for the stationary heat equation. We also mention [15] where, for fixed initial data, numerical investigations are used to provide evidence that the optimal location of null-controllers of the heat equation problem is an ill-posed problem. In [20] we proved that, for fixed initial data as well, the problem of optimal shape and location of sensors is always well-posed for heat, wave or Schrödinger equations, and we solved it, showing that the complexity of the optimal set depends on the regularity of the initial data; in particular we showed that, even for smooth initial data the optimal set can be fractal.

A huge difference between these works and the approach developed here is in the fact that all criteria introduced in the sequel take into consideration all possible initial

data, and moreover the optimization will run over all possible measurable subsets in \mathcal{U}_L . It is the idea developed in [18, 17, 19, 21] where the problem of the optimal location of an observation subset ω among all possible subsets of a given measure or volume fraction of Ω was addressed and solved for wave and Schrödinger equations and also for general parabolic equations. A relevant spectral criterion, viewed as a measure of eigenfunction concentration and not depending on the initial conditions was considered, in order to design an optimal observation or control set in an uniform way, independent of the data and solutions under consideration, as explained next. Such a kind of uniform criterion was earlier introduced for the one-dimensional wave equation in [11, 12] in view of investigating optimal stabilization issues.

1.2. Problem formulation. — To begin with, let us focus on a particular case of our study, starting from a practical problem. Assume that Ω is a given bounded open subset of \mathbb{R}^n , representing for instance a cavity in which some signals are propagating according to the wave equation

$$(1) \quad \partial_{tt}y = \Delta y,$$

with Dirichlet boundary conditions. Having for example in mind some reconstruction inverse problem, assume that one is allowed to place some sensors in the cavity, in order to make some measurements of the signals propagating in Ω over a certain horizon of time. We assume that we have the choice not only of the placement of the sensors but also of their shape. Let us address the question of knowing what is the best possible shape and location of sensors, achieving the best possible observation, in some sense to be made precise. This problem of optimal observability, inspired by control theoretical considerations, is intimately related to those of optimal controllability and stabilization.

At this step, the question is too much informal and a first challenge is to settle it properly in the mathematical world, so that the resulting problem will be both mathematically solvable and relevant in view of practical issues.

A first obvious but important remark is that, for any problem consisting of optimizing the observation, certainly the best policy consists of observing the solutions over the whole domain Ω . This is however clearly not reasonable and in practice the domain covered by sensors is limited, due for instance to cost considerations. From the mathematical point of view, we model this basic limitation by considering as the set of unknowns, the set of all possible measurable subsets ω of Ω that are of Lebesgue measure $|\omega| = L|\Omega|$, where $L \in (0, 1)$ is some fixed real number. Any such subset represents the sensors put in Ω , and we assume that we are able to measure the restrictions of the solutions of (1) to ω .

2. Modeling and problem formulation

Let us model the notion of best observation. For all $(y^0, y^1) \in L^2(\Omega, \mathbb{C}) \times H^{-1}(\Omega, \mathbb{C})$, there exists a unique solution $y \in C^0(0, T; L^2(\Omega, \mathbb{C})) \cap C^1(0, T; H^{-1}(\Omega, \mathbb{C}))$

of (1) such that $y(0, \cdot) = y^0(\cdot)$ and $y_t(0, \cdot) = y^1(\cdot)$. Let $T > 0$. We say that (1) is observable on ω in time T if there exists $C > 0$ such that

$$(2) \quad C \|(y^0, y^1)\|_{L^2 \times H^{-1}}^2 \leq \int_0^T \int_{\omega} |y(t, x)|^2 dx dt,$$

for all $(y^0, y^1) \in L^2(\Omega, \mathbb{C}) \times H^{-1}(\Omega, \mathbb{C})$. This inequality is called an *observability inequality*, and is of great importance in view of showing the well-posedness of some inverse problems. It is well known that within the class of \mathcal{C}^∞ domains Ω , this observability property holds if the pair (ω, T) satisfies the *Geometric Control Condition* in Ω (see [4]), according to which every ray of geometrical optics that propagates in the cavity Ω and is reflected on its boundary $\partial\Omega$ intersects ω within time T . The observability constant $C_T(\chi_\omega)$ is defined as the infimum of the quantities

$$\frac{\int_0^T \int_{\Omega} \chi_\omega(x) |y(t, x)|^2 dx dt}{\|(y^0, y^1)\|_{L^2 \times H^{-1}}^2}$$

over all initial data $(y^0, y^1) \in L^2(\Omega, \mathbb{C}) \times H^{-1}(\Omega, \mathbb{C}) \setminus \{(0, 0)\}$. It is the largest possible constant for which (2) holds. It depends both on the time T (the horizon time of observation) and on the subset ω on which the measurements are done. Here, the notation χ_ω stands for the characteristic function of ω .

A priori, it might appear natural to model the problem of best observability as that of maximizing the functional $\chi_\omega \mapsto C_T(\chi_\omega)$ over the set

$$(3) \quad \mathcal{U}_L = \{\chi_\omega \mid \omega \subset \Omega \text{ measurable, } |\omega| = L|\Omega|\}.$$

However, this choice of model leads to a mathematical problem that is difficult to handle from the theoretical point of view, and more importantly, it is not relevant in view of practical issues. Let us explain these two difficulties.

First of all, a spectral expansion of the solutions shows the emergence of crossed terms that are difficult to treat. Indeed, let $(\phi_j)_{j \in \mathbb{N}^*}$ be a Hilbert basis of $L^2(\Omega)$ consisting of eigenfunctions of the Dirichlet-Laplacian operator on Ω , associated with the negative eigenvalues $(-\lambda_j^2)_{j \in \mathbb{N}^*}$. Then any solution y of (1) can be expanded as

$$(4) \quad y(t, x) = \sum_{j=1}^{+\infty} (a_j e^{i\lambda_j t} + b_j e^{-i\lambda_j t}) \phi_j(x),$$

where the coefficients a_j and b_j account for initial data. It follows that $2C_T^{(W)}(\chi_\omega)$ is the infimum of the quantities

$$\int_0^T \int_{\omega} \left| \sum_{j=1}^{+\infty} (a_j e^{i\lambda_j t} + b_j e^{-i\lambda_j t}) \phi_j(x) \right|^2 dx dt$$

over all possible sequences (a_j) and (b_j) of $\ell^2(\mathbb{C})$ such that $\sum_{j=1}^{+\infty} (|a_j|^2 + |b_j|^2) = 1$. Then, maximizing this functional over \mathcal{U}_L appears to be very difficult from the theoretical point of view, due to the crossed terms $\int_{\omega} \phi_j \phi_k dx$ measuring the interaction over ω between distinct eigenfunctions.

The second difficulty with this model is its lack of relevance in practice. Indeed, the observability constant $C_T(\chi_\omega)$ is *deterministic* and provides an account for the *worst possible case*. Hence, in this sense, it is a *pessimistic* constant. In practice when realizing a large number of measures, it may be expected that this worst case does not occur so often, and one would like that the observation be optimal for most of experiments. This leads us to consider rather an averaged version of the observability inequality over random initial data. In few words, we define what we call the *randomized observability constant* $2C_{T,\text{rand}}(\chi_\omega)$ as the infimum of the quantities

$$\mathbb{E} \int_0^T \int_\omega \left| \sum_{j=1}^{+\infty} (\beta_{1,j}^\nu a_j e^{i\lambda_j t} + \beta_{2,j}^\nu b_j e^{-i\lambda_j t}) \phi_j(x) \right|^2 dx dt$$

over all possible sequences (a_j) and (b_j) of $\ell^2(\mathbb{C})$ such that $\sum_{j=1}^{+\infty} (|a_j|^2 + |b_j|^2) = 1$, where $(\beta_{1,j}^\nu)_{j \in \mathbb{N}^*}$ and $(\beta_{2,j}^\nu)_{j \in \mathbb{N}^*}$ are two sequences of (for example) i.i.d. Bernoulli random laws on a probability space $(\mathcal{X}, \mathcal{A}, \mathbb{P})$, and \mathbb{E} is the expectation over the \mathcal{X} with respect to the probability measure \mathbb{P} . It corresponds to an averaged version of the observability inequality over random initial data. We refer to [19] for more details and properties of the randomization procedure. The following result gives a characterization of the randomized observability constant.

Theorem 1 ([19]). — *For every measurable subset ω of Ω , there holds*

$$2C_{T,\text{rand}}(\chi_\omega) = T \inf_{j \in \mathbb{N}^*} \int_\omega \phi_j(x)^2 dx.$$

It is interesting to note that there always holds

$$C_T(\chi_\omega) \leq C_{T,\text{rand}}(\chi_\omega),$$

and that the inequality is strict for instance in any of the following cases:

- in 1D, with $\Omega = (0, \pi)$ and Dirichlet boundary conditions, whenever T is not an integer multiple of π ;
- in multi-D, with Ω stadium-shaped, whenever ω contains an open neighborhood of the wings (in that case there even holds $C_T^{(W)}(\chi_\omega) = 0$).

Taking into account the fact that, in practice, it is expected that a large number of measurements is to be done, we finally model the problem of best observability in the following more relevant way:

Maximize the functional

$$(5) \quad J(\chi_\omega) = \inf_{j \in \mathbb{N}^*} \int_\omega \phi_j(x)^2 dx$$

over the set \mathcal{U}_L .

The functional J appears as a criterion giving an account for *eigenfunctions concentration properties*.

It can be noted that J can be as well recovered by considering, instead of an averaged version of the observability inequality over random initial data, a time-asymptotic version of it. More precisely, we claim that, if the eigenvalues of the

Dirichlet-Laplacian are simple (which is a generic property), then $J(\chi_\omega)$ is the largest possible constant such that

$$C\|(y^0, y^1)\|_{L^2 \times H^{-1}}^2 \leq \lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T \int_\omega |y(t, x)|^2 dx dt,$$

for all $(y^0, y^1) \in L^2(\Omega, \mathbb{C}) \times H^{-1}(\Omega, \mathbb{C})$ (see [19]).

3. Solving the problem

In view of solving the uniform optimal design problem

$$\sup_{\chi_\omega \in \mathcal{U}_L} J(\chi_\omega),$$

we first consider a convexified version, by considering the convex closure of the set \mathcal{U}_L for the L^∞ weak star topology, that is

$$\bar{\mathcal{U}}_L = \{a \in L^\infty(\Omega, [0, 1]) \mid \int_\Omega a(x) dx = L|\Omega|\}.$$

The convexified problem then consists of maximizing the (relaxed) functional

$$J(a) = \inf_{j \in \mathbb{N}^*} \int_\Omega a(x) \phi_j(x)^2 dx$$

over $\bar{\mathcal{U}}_L$. Clearly there exists a maximizer, but since the functional J is not lower semi-continuous it is not clear whether or not there may be a *gap* between the problem (5) and its convexified version. The following result shows that, under appropriate spectral assumptions, there is no gap. Note that $\mu_j = \phi_j^2 dx$ is a probability measure, for every integer j .

Theorem 2 (No-gap and optimal value of J [19]). — *We make the following assumptions:*

- $\partial\Omega$ is Lipschitz.
- **Quantum Unique Ergodicity (QUE) on the base.** *The whole sequence of probability measures $\mu_j = \phi_j^2 dx$ converges vaguely to the uniform measure $\frac{1}{|\Omega|} dx$.*
- **Uniform L^p -boundedness.** *There exist $p \in (1, +\infty]$ and $A > 0$ such that $\|\phi_j\|_{L^{2p}(\Omega)} \leq A$, for every $j \in \mathbb{N}^*$.*

Then

$$\sup_{\chi_\omega \in \mathcal{U}_L} \inf_{j \in \mathbb{N}^*} \int_\omega \phi_j(x)^2 dx = L,$$

for every $L \in (0, 1)$.

At this step, it follows from Theorems 1 and 2 that, under appropriate spectral assumptions, the maximal possible value of $C_{T, \text{rand}}(\chi_\omega)$ (over the set \mathcal{U}_L) is equal to $TL/2$.

The question of knowing whether the supremum is reached (existence of an optimal set) is investigated in the next section.

Remark 1. — Actually, this statement holds true as well whenever the set \mathcal{U}_L is replaced with the set of all measurable subsets ω of Ω , of measure $|\omega| = L|\Omega|$, that are moreover either open with a Lipschitz boundary, or open with a bounded perimeter, or Jordan measurable (i.e., whose boundary is of measure zero).

Remark 2. — The assumptions of Theorem 2 hold true in dimension one. Indeed, the eigenfunctions of the Dirichlet-Laplacian operator on $\Omega = (0, \pi)$ are given by $\phi_j(x) = \sqrt{\frac{2}{\pi}} \sin(jx)$, for every $j \in \mathbb{N}^*$. Therefore, clearly, the whole sequence (not only a subsequence) $(\phi_j^2)_{j \in \mathbb{N}^*}$ converges weakly to $1/\pi$ for the weak star topology of $L^\infty(0, \pi)$.

In dimension greater than one the situation is widely open. Our assumptions are related with ergodicity properties of Ω . We recall the definition:

Quantum Ergodicity (QE) on the base property. There exists a subsequence of the sequence of probability measures $\mu_j = \phi_j^2 dx$ of density one converging vaguely to the uniform measure $\frac{1}{|\Omega|} dx$.

Here, density one means that there exists $\mathcal{I} \subset \mathbb{N}^*$ such that $\#\{j \in \mathcal{I} \mid j \leq N\}/N$ converges to 1 as N tends to $+\infty$. It is well known that, if the domain Ω (seen as a billiard where the geodesic flow moves at unit speed and bounces at the boundary according to the Geometric Optics laws) is ergodic, then QE is satisfied. This is the contents of Shnirelman's Theorem, proved in [7, 9, 22, 28] in various contexts (manifolds with or without boundary, with a certain regularity), and which is actually stronger because it is established in the framework of pseudodifferential operators, whereas, here, we are concerned with a version of the statement restricted to the configuration space Ω (whence the wording “on the base”).

To the best of our knowledge, nothing seems to be known on the uniform L^p -boundedness property.

Remark 3. — The assumptions made in Theorem 2 are sufficient conditions implying the no-gap, but they are however not sharp. Indeed, we have (see [19]):

1. Assume that $\Omega = (0, \pi)^2$ is a square of \mathbb{R}^2 , and consider the usual Hilbert basis of eigenfunctions of Δ made of products of sine functions. Then QUE on the base is not satisfied. However, the no-gap holds true.
2. Assume that Ω is the unit disk of \mathbb{R}^2 , and consider the usual basis of eigenfunctions of Δ defined in terms of Bessel functions. Then, for every $p \in (1, +\infty]$, the uniform L^p -boundedness property is not satisfied, and QUE on the base is not satisfied as well. However, the no-gap holds true.

The result on the square could be expected, since the square is nothing else but a tensorised version of the one-dimensional case. The result in the disk is more surprising, having in mind that, among the quantum limits in the disk, one can find the Dirac measure along the boundary which causes the well known phenomenon of whispering galleries. This strong concentration feature could have led to the intuition that there exists an optimal set, concentrating around the boundary; the calculations show that it is however not the case, and the no-gap is proved to hold.

Remark 4. — *We are not aware of any example in which there is a gap between the problem (5) and its convexified version.*

Our results eventually show intimate connections between domain optimization and fine spectral properties or quantum ergodicity properties of Ω . Such a relation was suggested in the early work [6] concerning the exponential decay properties of dissipative wave equations.

4. Nonexistence of an optimal set and remedies

The maximum of J over $\overline{\mathcal{U}}_L$ is clearly reached (in general, in an infinite number of ways). The question of the reachability of the supremum of J over \mathcal{U}_L , that is, the existence of an optimal classical set, is a difficult question in general. In particular cases it can however be addressed using harmonic analysis.

For instance in dimension one, we can prove that the supremum is reached if and only if $L = 1/2$ (and there is an infinite number of optimal sets).

Other (partial) results are given in [19].

In larger dimension, the question is completely open, and we conjecture that, for generic domains Ω and generic values of L , the supremum is not reached and hence there does not exist any optimal set. It can however be noted that, in the two-dimensional Euclidean square, if we restrict the search of optimal sets to Cartesian products of 1D subsets, then the supremum is reached if and only if $L \in \{1/4, 1/2, 3/4\}$ (see [19]).

In view of that, it is then natural to study a finite-dimensional spectral approximation of the problem, namely:

<p>Maximize the functional</p> $J_N(\chi_\omega) = \min_{1 \leq j \leq N} \int_{\omega} \phi_j(x)^2 dx$ <p>over the set \mathcal{U}_L.</p>

The existence and uniqueness of an optimal set ω^N is then not difficult to prove, as well as a Γ -convergence property of J_N towards J for the weak star topology of L^∞ . Moreover, the sets ω^N have a finite number of connected components, expected to increase in function of N . In particular, the sets ω^N constitute a maximizing sequence for the (convexified) problem of maximizing J over $\overline{\mathcal{U}}_L$, and this, without geometric or ergodicity assumptions on Ω . Of course, then, under the assumptions of Theorem 2, these sets constitute a maximizing sequence for the problem of maximizing J over \mathcal{U}_L .

The numerical simulations of Fig. 1 show the shapes of these sets; their increasing complexity which can be observed as N increases is in accordance with the conjecture of the nonexistence of an optimal set maximizing J . On this figure, we have taken $\Omega = (0, \pi)^2$, with the normalized eigenfunctions of the Dirichlet-Laplacian given by $\phi_{j,k}(x_1, x_2) = \frac{2}{\pi} \sin(jx_1) \sin(kx_2)$, for all $(x_1, x_2) \in (0, \pi)^2$.

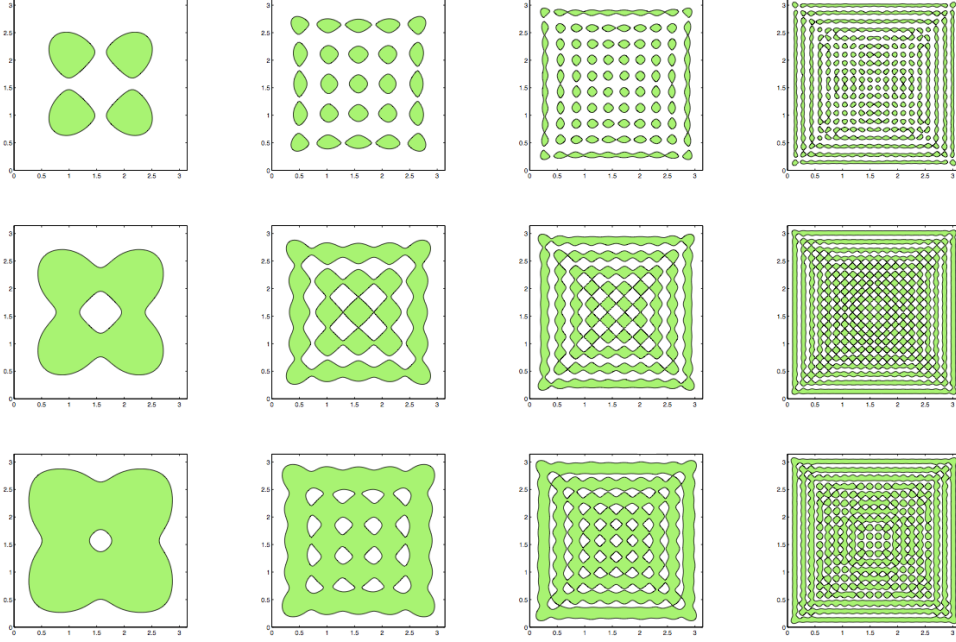


FIGURE 1. $\Omega = (0, \pi)^2$. Row 1: $L = 0.2$; row 2: $L = 0.4$; row 3: $L = 0.6$. From left to right: $N = 2$ (4 eigenmodes), $N = 5$ (25 eigenmodes), $N = 10$ (100 eigenmodes), $N = 20$ (400 eigenmodes). The optimal domain is in green.

It can be noted that, in the one-dimensional case, for L sufficiently small, loosely speaking, the optimal domain ω^N for N modes is the worst possible one when considering the truncated problem with $N + 1$ modes (spillover phenomenon; see [12, 17]).

This intrinsic instability is in some sense due to the fact that in the definition of the spectral criterion (5) all modes have the same weight, and the same criticism can be made on the observability inequality (2). Due to the increasing complexity of the geometry of highfrequency eigenfunctions, it could indeed be expected that the optimal shape and placement problem would be complicated. This leads to the intuition that lower frequencies should be more weighted than the higher ones, and then it seems relevant to introduce a weighted version of the observability inequality (2), by considering the (equivalent) inequality

$$C_{T,\sigma}(\chi_\omega) (\|(y^0, y^1)\|_{L^2 \times H^{-1}}^2 + \sigma \|y^0\|_{H^{-1}}^2) \leq \int_0^T \int_\omega |y(t, x)|^2 dx dt,$$

where $\sigma \geq 0$ is some weight. There holds $C_{T,\sigma}(\chi_\omega) \leq C_T(\chi_\omega)$, and considering as before an averaged version of this weighted observability inequality over random initial data leads to $2C_{T,\sigma,\text{rand}}^{(W)}(\chi_\omega) = TJ_\sigma(\chi_\omega)$, where the weighted spectral criterion J_σ is

defined by

$$J_\sigma(\chi_\omega) = \inf_{j \in \mathbb{N}^*} \sigma_j \int_\omega \phi_j(x)^2 dx,$$

with $\sigma_j = \lambda_j^2 / (\sigma + \lambda_j^2)$ (increasing sequence of positive real numbers converging to 1; see [19] for details). The truncated criterion $J_{\sigma,N}$ is then defined accordingly, by keeping only the N first modes. We then have the following result.

Theorem 3 ([19]). — *Assume that the whole sequence of probability measures $\mu_j = \phi_j^2(x) dx$ converges vaguely to the uniform measure $\frac{1}{|\Omega|} dx$ (Quantum Unique Ergodicity assumption), and that the sequence of eigenfunctions ϕ_j is uniformly bounded in $L^\infty(\Omega)$. Then, for every $L \in (\sigma_1, 1)$, there exists $N_0 \in \mathbb{N}^*$ such that*

$$\max_{\chi_\omega \in \mathcal{U}_L} J_\sigma(\chi_\omega) = \max_{\chi_\omega \in \mathcal{U}_L} J_{\sigma,N}(\chi_\omega) \leq \sigma_1 < L,$$

for every $N \geq N_0$. In particular, the problem of maximizing J_σ over \mathcal{U}_L has a unique solution $\chi_{\omega^{N_0}}$, and moreover the set ω^{N_0} has a finite number of connected components.

Note that the conclusion of Theorem 3 holds true as well in a hypercube with Dirichlet boundary conditions when one considers the usual Hilbert basis made of products of sine functions, although QUE is not satisfied in such a domain (see [19]).

The theorem says that, for the problem of maximizing $J_{\sigma,N}$ over \mathcal{U}_L , the sequence of optimal sets ω^N is stationary whenever L is large enough, and ω^{N_0} is then the (unique) optimal set, solution of the problem of maximizing J_σ . It can be noted that the lower threshold in L depends on the chosen weights, and the numerical simulations that we will provide indicate that this threshold is sharp in the sense that, if $L < \sigma_1$ then the sequence of maximizing sets loses its stationarity feature.

As a conclusion, this weighted version of our spectral criterion can be viewed as a remedy for the spillover phenomenon. Note that, of course, other more evident remedies can be discussed, such as the search of an optimal domain among a set of subdomains sharing nice compactness properties (such as having a uniform perimeter or BV norm), however our aim is here to investigate domains as general as possible (only measurable) and rather to discuss the mathematical, physical and practical relevance of the criterion encoding the notion of optimal observability.

Let us finally note that all our results hold for wave and Schrödinger equations on any open bounded connected subset of a Riemannian manifold (then replacing Δ with the Laplace-Beltrami operator), with various possible boundary conditions (Dirichlet, Neumann, mixed, Robin) or no boundary conditions in case the manifold is compact without boundary. The abstract framework and generalizations are described in details in [19].

5. THE CASE OF PARABOLIC PDE'S

We report here on results of [21]. Instead of dealing with a general parabolic model, for the sake of simplicity we consider the heat equation

$$(6) \quad \partial_t y - \Delta y = 0, \quad (t, x) \in (0, T) \times \Omega,$$

with Dirichlet boundary conditions. For any measurable subset ω of Ω , we observe the solutions of (6) restricted to ω over the horizon of time $[0, T]$, that is, we consider the observable $z(t, x) = \chi_\omega(x)y(t, x)$, where χ_ω denotes the characteristic function of the subset ω .

For a given measurable subset ω of Ω , the heat equation (6) is said observable on ω in time T whenever there exists $C > 0$ such that

$$(7) \quad C \int_{\Omega} y(T, x)^2 dx \leq \int_0^T \int_{\omega} y(t, x)^2 dx dt,$$

for every solution of (6) such that $y(0, \cdot) \in \mathcal{D}(\Omega)$. It is well known that, if Ω is C^2 or rectangular then this observability inequality holds (see [24]). The observability constant $C_T(\chi_\omega)$ is defined as the largest possible constant such that (7) holds, that is the infimum of the quantities

$$\frac{\int_0^T \int_{\omega} y(t, x)^2 dx dt}{\int_{\Omega} y(T, x)^2 dx}$$

over all $y(0, \cdot) \in \mathcal{D}(\Omega) \setminus \{0\}$. As before, randomizing the initial data leads to the definition of the *randomized observability constant*

$$(8) \quad C_{T, \text{rand}}(\chi_\omega) = \inf_{j \in \mathbb{N}^*} \frac{e^{2\lambda_j T} - 1}{2\lambda_j} \int_{\omega} \phi_j(x)^2 dx,$$

with the significant difference that every integral is multiplied by the weight $\frac{e^{2\lambda_j T} - 1}{2\lambda_j}$. This implies completely different results. As before, instead of considering as a criterion the deterministic observability constant, we find more relevant to model the problem of best observation domain as that of maximizing the functional $C_{T, \text{rand}}(\chi_\omega)$ over the set \mathcal{U}_L .

Theorem 4 ([21]). — *Assume that $\partial\Omega$ is piecewise C^1 . There exists a unique optimal observation set ω^* , solution of the problem of maximizing the functional $C_{T, \text{rand}}(\chi_\omega)$ over the set \mathcal{U}_L . Moreover, we have*

$$C_T(\chi_{\omega^*}) < C_{T, \text{rand}}(\chi_{\omega^*}).$$

Here, it is understood that the optimal set ω^* is unique within the class of all measurable subsets of Ω quotiented by the set of all measurable subsets of Ω of zero measure.

Note that this existence and uniqueness result holds for every orthonormal basis of eigenfunctions of the Dirichlet-Laplacian, but the optimal set depends on the specific choice of the Hilbert basis.

It is remarkable that the optimal observation set ω^* can be built from a finite-dimensional spectral approximation, by keeping only a finite number of modes. The precise result is the following.

Theorem 5 ([21]). — For every $N \in \mathbb{N}^*$, there exists a unique set ω^N such that $\chi_{\omega^N} \in \mathcal{U}_L$ maximizes the functional

$$\chi_{\omega} \mapsto \inf_{1 \leq j \leq N} \frac{e^{2\lambda_j T} - 1}{2\lambda_j} \int_{\omega} \phi_j(x)^2 dx$$

over \mathcal{U}_L . Moreover ω^N is semi-analytic, and thus, in particular, it has a finite number of connected components. Furthermore, the sequence of optimal sets ω^N is stationary, and there exists $N_0 \in \mathbb{N}^*$ such that $\omega^N = \omega^*$ if $N \geq N_0$.

In particular, it follows that the optimal set ω^* of Theorem 4 is semi-analytic as well and hence has a finite number of connected components. This property is in strong contrast with the results established for wave and Schrödinger equations. For the latter equations, the fact that all frequencies have the same weight causes a strong instability of the optimal sets ω^N , in particular the spillover phenomenon mentioned previously. For parabolic equations this instability phenomenon does not occur, and the sequence of maximizers ω^N is constant as soon as N is large enough, equal to ω^* . This property is of particular interest in view of designing the best observation set ω^* in practice.

On Figure 2, we compute the optimal domain ω^N in the case $\Omega = (0, \pi)^2$, $L = 0.2$ and $T = 0.05$, for $N = 1, \dots, 6$. We can observe the expected stationarity property of the sequence of optimal domains ω^N from $N = 4$ on (i.e., 16 eigenmodes).

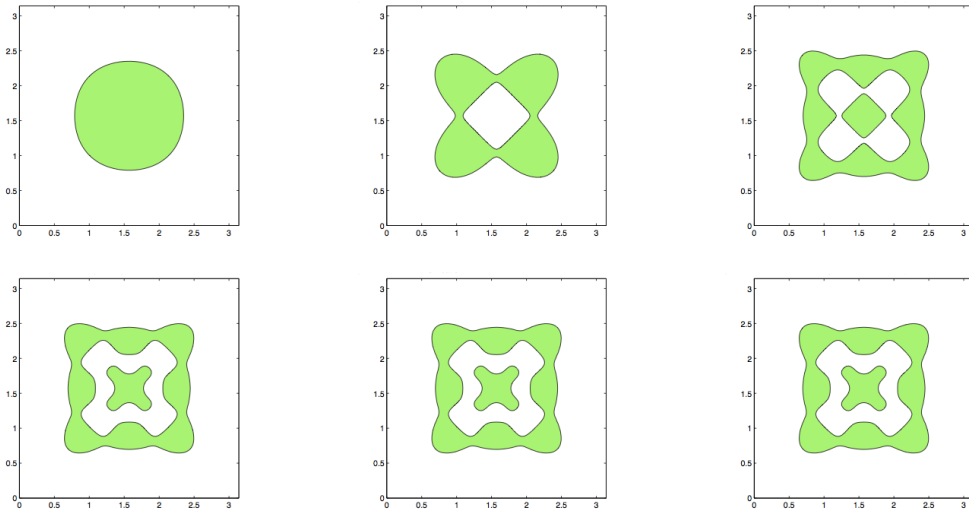


FIGURE 2. Optimal thermometer in the square. On this figure, $\Omega = (0, \pi)^2$, $L = 0.2$, $T = 0.05$, and A_0 is the Dirichlet Laplacian. Row 1, from left to right: optimal domain ω^N (in green) for $N = 1, 2, 3$. Row 2, from left to right: optimal domain ω^N (in green) for $N = 4, 5, 6$.

These results can be established as well for more general parabolic equations (see [21]), involving in particular anomalous diffusion equations and Stokes equations. Let us mention in particular an interesting feature occurring for the anomalous diffusion equation

$$\partial_t y + (-\Delta)^\alpha y = 0$$

in Ω , where $(-\Delta)^\alpha$ is some positive power of the Dirichlet-Laplacian, with arbitrary boundary conditions implying $y|_{\partial\Omega} = 0$. It is proved in [21] that:

- in the Euclidean square $\Omega = (0, \pi)^2$, when considering the usual Hilbert basis of eigenfunctions consisting of products of sine functions, for every $\alpha > 0$ there exists a unique optimal set (as in Theorem 4), which is moreover open and semi-analytic;
- in the Euclidean disk $\Omega = \{x \in \mathbb{R}^2 \mid \|x\| < 1\}$, when considering the usual Hilbert basis of eigenfunctions parametrized in terms of Bessel functions, for every $\alpha > 0$ there exists a unique optimal measurable set ω^* (as in Theorem 4), which is moreover open, radial, with the following additional surprising property:
 - if $\alpha > 1/2$ then ω^* consists of a finite number of concentric rings that are at a positive distance from the boundary;
 - if $\alpha < 1/2$ (or if $\alpha = 1/2$ and T is small enough) then ω^* consists of an infinite number of concentric rings accumulating at the boundary!

These surprising results show that the complexity does not only depend on the operator under consideration but also on the geometry of the domain Ω .

6. CONCLUSION

We have surveyed our results for the optimal shape and placement of sensors. Similar results can be derived for actuators (see [18, 19, 21]), using, in particular, duality arguments. Our main contribution is to have highlighted a precise relation between those kinds of shape optimization problems and concentration properties of eigenfunctions (quantum ergodicity issues). Many interesting open questions remain to be investigated, such as:

- Generic nonexistence of an optimal set.
- Other relevant shape optimization problems avoiding the spillover phenomenon.
- Control consequences for random initial data.
- Optimal stabilization and optimal choice of dampers.
- Optimization of the deterministic observability constant.
- Discrete versions of optimization problems above.

The latter issue might be particularly important in applications both because discrete models are often employed, and also because numerical approximation schemes necessarily end up becoming of discrete nature. In particular, the following type of questions arise as discrete versions of those we have considered in this paper in the continuous setting. Let A be a real symmetric matrix. The problem of the optimal

choice of an observation operator B over a certain class \mathcal{B} can be formulated as

$$\sup_{B \in \mathcal{B}} \inf \left\{ \frac{\langle Bx, x \rangle}{\|x\|^2} \mid \exists \lambda, Ax = \lambda x \right\}.$$

In the context of our paper, B is the (infinite-dimensional) Gramian of observation over ω . But the problem can be generalized in the above more abstract form, allowing us in particular to formulate in an appropriate context the following open question: under which assumptions do the optimal designs commute with discretization schemes?

Acknowledgment. The work of the third author was supported by the Advanced Grant NUMERIWAVES/FP7-246775 of the European Research Council Executive Agency, PI2010-04 and the BERC 2014-2017 program of the Basque Government, the MTM2011-29306-C02-00 and SEV-2013-0323 Grants of the MINECO, the CIMI - Toulouse and a Humboldt Research Award (University of Erlangen-Nürnberg).

The second and the third authors were partially supported by the Grant FA9550-14-1-0214 of the EOARD-AFOSR.

Références

- [1] G. Allaire, S. Aubry, F. Jouve, *Eigenfrequency optimization in optimal design*, Comput. Methods Appl. Mech. Engrg. **190** (2001), 3565–3579.
- [2] G. Allaire, A. Münch, F. Periago, *Long time behavior of a two-phase optimal design for the heat equation*, SIAM J. Control Optim. **48** (2010), no. 8, 5333–5356.
- [3] A. Armaoua, M. Demetriou, *Optimal actuator/sensor placement for linear parabolic PDEs using spatial H^2 norm*, Chemical Engineering Science **61** (2006), 7351–7367.
- [4] C. Bardos, G. Lebeau, J. Rauch, *Sharp sufficient conditions for the observation, control, and stabilization of waves from the boundary*, SIAM J. Control Optim. **30** (1992), no. 5, 1024–1065.
- [5] J.C. Bellido, A. Donoso, *An optimal design problem in wave propagation*, J. Optim. Theory Appl. **134** (2007), 339–352.
- [6] G. Chen, S.A. Fulling, F.J. Narcowich, S. Sun, *Exponential decay of energy of evolution equations with locally distributed damping*, SIAM J. Appl. Math. **51** (1991), no. 1, 266–301.
- [7] Y. Colin de Verdière, *Ergodicité et fonctions propres du Laplacien*, Comm. Math. Phys. **102** (1985), 497–502.
- [8] F. Fahroo, K. Ito, *Optimum damping design for an abstract wave equation*, New directions in control and automation, I (Limassol, 1995), Kybernetika (Prague) 32 (1996), no. 6, 557–574.
- [9] P. Gérard, E. Leichtnam, *Ergodic properties of eigenfunctions for the Dirichlet problem*, Duke Math. J. **71** (1993), 559–607.
- [10] T.J. Harris, J.F. Macgregor, J.D. Wright, *Optimal sensor location with an application to a packed bed tubular reactor*, AIChE Journal **26** (1980), no. 6, 910–916.
- [11] P. Hébrard, A. Henrot, *Optimal shape and position of the actuators for the stabilization of a string*, Syst. Cont. Letters **48** (2003), 199–209.
- [12] P. Hébrard, A. Henrot, *A spillover phenomenon in the optimal location of actuators*, SIAM J. Control Optim. **44** 2005, 349–366.

- [13] S. Kumar, J.H. Seinfeld, *Optimal location of measurements for distributed parameter estimation*, IEEE Trans. Autom. Contr. **23** (1978), 690–698.
- [14] K. Morris, *Linear-quadratic optimal actuator location*, IEEE Trans. Automat. Control **56** (2011), no. 1, 113–124.
- [15] A. Münch, P. Pedregal, *Numerical null controllability of semi-linear 1D heat equations : fixed point, least squares and Newton methods*, Math. Control Relat. Fields **3** (2012) , no. 2, 217–246.
- [16] A. Münch, F. Periago, *Optimal distribution of the internal null control for the 1D heat equation*, J. Diff. Equations **250**, 95–111 (2011).
- [17] Y. Privat, E. Trélat, E. Zuazua, *Optimal observation of the one-dimensional wave equation*, J. Fourier Anal. Appl. **19** (2013), no. 3, 514–544.
- [18] Y. Privat, E. Trélat, E. Zuazua, *Optimal location of controllers for the one-dimensional wave equation*, Ann. Inst. H. Poincaré Anal. Non Linéaire **30** (2013), no. 6, 1097–1126.
- [19] Y. Privat, E. Trélat, E. Zuazua, *Optimal observability of the multi-dimensional wave and Schrödinger equations in quantum ergodic domains*, Preprint Hal (2013), to appear in J. Europ. Math. Soc.
- [20] Y. Privat, E. Trélat, E. Zuazua, *Complexity and regularity of maximal energy domains for the wave equation with fixed initial data*, Preprint Hal (2013), to appear in Discrete Cont. Dynam. Syst. (2015).
- [21] Y. Privat, E. Trélat, E. Zuazua, *Optimal shape and location of sensors for parabolic equations with random initial data*, Preprint Hal (2014).
- [22] A. Shnirelman, *Ergodic properties of eigenfunctions*, Uspehi Mat. Nauk **29** (1974), no. 6(180), 181–182.
- [23] O. Sigmund, J.S. Jensen, *Systematic design of phononic band-gap materials and structures by topology optimization*, R. Soc. Lond. Philos. Trans. Ser. A Math. Phys. Eng. Sci. **361** (2003), no. 1806, 1001–1019.
- [24] M. Tucsnak, G. Weiss, *Observation and control for operator semigroups*, Birkhäuser Verlag, Basel (2009).
- [25] D. Ucinski, M. Patan, *Sensor network design fo the estimation of spatially distributed processes*, Int. J. Appl. Math. Comput. Sci. **20** (2010), no. 3, 459–481.
- [26] M. van de Wal, B. Jager, *A review of methods for input/output selection*, Automatica **37** (2001), no. 4, 487–510.
- [27] A. Vande Wouwer, N. Point, S. Porteman, M. Remy, *An approach to the selection of optimal sensor locations in distributed parameter systems*, Journal of Process Control **10** (2000), 291–300.
- [28] S. Zelditch, M. Zworski, *Ergodicity of eigenfunctions for ergodic billiards*, Comm. Math. Phys. **175** (1996), no. 3, 673–682.

YANNICK PRIVAT⁽¹⁾ & EMMANUEL TRÉLAT⁽²⁾ & ENRIQUE ZUAZUA^{(3) (4)}

⁽¹⁾CNRS, Sorbonne Universités, UPMC Univ Paris 06, UMR 7598, Laboratoire Jacques-Louis Lions, F-75005, Paris, France (yannick.privat@upmc.fr).

⁽²⁾Sorbonne Universités, UPMC Univ Paris 06, CNRS UMR 7598, Laboratoire Jacques-Louis Lions, Institut Universitaire de France, F-75005, Paris, France (emmanuel.trelat@upmc.fr).

⁽³⁾BCAM - Basque Center for Applied Mathematics, Mazarredo, 14 E-48009 Bilbao-Basque Country-Spain

⁽⁴⁾Ikerbasque, Basque Foundation for Science, María Diaz de Haro 3, E-48013 Bilbao-Basque Country-Spain (zuazua@bcamath.org).