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Bare Soil HYdrological Balance Model “MHYSAN”: Calibration and Validation Using SAR Moisture Products and Continuous Thetaprobe Network Measurements over bare agricultural soils (Tunisia)

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Abstract. The present study highlights the potential of multi-temporal X-band Synthetic Aperture Radar (SAR) moisture products to be used for the calibration of a model reproducing soil moisture (SM) variations. We propose the MHYSAN model (Modèle de bilan HYdrique des Sols Agricoles Nus) for simulating soil water balance of bare soils. This model was used to simulate surface evaporation fluxes and SM content at daily time scale over a semi-arid, bare agricultural site in Tunisia (North Africa). Two main approaches are considered in this study. Firstly, the MHYSAN model was successfully calibrated for seven sites using continuous thetaprobe measurements at two depths. Then the possibility to extrapolate local SM simulations at distant sites, based on soil texture similarity only, was tested. This extrapolation was assessed using SAR estimates and manual thetaprobe measurements of SM recorded at these distant sites. The results reveal a bias of approximately 0.63% and 3.04%, and an RMSE equal to 6.11% and 4.5%, for the SAR volumetric SM and manual thetaprobe measurements, respectively. In a second approach, the MHYSAN model was calibrated using seven very high-resolution SAR (TerraSAR-X) SM outputs ranging over only two months. The simulated SM were validated using continuous thetaprobe measurements during 15 months. Although the SM was measured

on only seven different dates for the purposes of calibration, satisfactory results were obtained as a result of the wide range of SM values recorded in these seven images. This led to good overall calibration of the soil parameters, thus demonstrating the considerable potential of Sentinel-1 images for daily soil moisture monitoring using simple models.

Keywords: Bare soil hydrological model, satellite soil moisture products, semi-arid area, continuous soil moisture measurements.

1 Introduction

The conservation of water and soil resources is one of the main missions for sustainable agricultural management. These natural resources are threatened by various types of degradation, such as water and wind erosion, floods, drought and deforestation, all of which impede agricultural development. In recent decades, the long periods of drought, especially in semi-arid regions, had a negative impact on available water resources. In addition, most of the intercepted water is lost through evaporation, or by drainage, deep percolation and subsurface runoff. Therefore, knowledge of water fluxes within the soil-atmosphere system is a major issue for the improvement of water use efficiency. Many studies have been carried out to quantify these fluxes, and various tools have been developed to estimate the soil-water regime. These efforts can thus be expected to contribute to the sustainable management of natural resources (Er-Raki et al., 2007; Gowda et al., 2008; Simonneaux et al., 2008; Zhang et al., 2010; Li et al., 2009; Sutanto et al., 2012 and Saadi et al., 2015).

The amount of water stored in the soil is a crucial parameter, in situations where energy and mass fluxes at the land surface-atmosphere boundary need to be determined, and is of fundamental importance to many agricultural, hydrological, and meteorological processes (Koster et al., 2004; Seneviratne et al., 2010). Many soil water balance models have been developed, highlighting in particular the influence of surface soil moisture conditions on the hydrological response of a watershed (Famiglietti and Wood, 1994; Entekhabi and Rodriguez-Iturbe, 1994 ; Zehe and Blöschl, 2004; Brocca et al., 2005 and 2008; Manfreda et al., 2005; Tramblay et al., 2012). Spatio-temporal soil moisture (SM) information is also of

55 primary importance for the simulation of surface evaporation fluxes and vertical water circulation such
56 as surface water displacement via capillarity, and underground percolation. It is important for the
57 management of water resources, irrigation scheduling decisions, as well as the estimation of runoff and
58 soil erosion potential (Chen and Hu, 2004; Koster et al., 2004; Pandey et al., 2010; Bezerra et al., 2013;
59 Zhang et al., 2015). The spatial distribution of the soil's water content varies both vertically and
60 horizontally, as a consequence of variations in precipitation and evaporation, and the influences of
61 topography, soil texture, and vegetation.

62 As SM plays an important role in the hydrologic response, as well as land surface inputs to the
63 atmosphere, large spatio-temporal databases of moisture observation data need to be maintained, and
64 methodologies for the estimation of this key hydraulic property must be developed. This can be
65 achieved through the use of SM monitoring networks, providing frequent temporal observations at a
66 high spatial density. In situ station networks can be efficiently used as tools for the calibration of
67 hydrological models, and their interest has been demonstrated in various studies using different remote
68 sensing satellites and techniques (Wagner et al., 2008; Albergel et al., 2011; Gorraeb et al., 2015b).

69 Considerable progress has been made in recent decades with the development of SM retrieval
70 techniques, based on the analysis of remotely sensed radar data. The high spatial resolution and regular
71 coverage provided by Imaging Synthetic Aperture Radar (SAR) sensors make these instruments a
72 promising additional source of data for the measurement of seasonal and long-term variations in surface
73 SM content, and could potentially improve hydrologic modeling applications (Baghdadi et al., 2008;
74 Barrett et al., 2009). Several algorithms have been developed to retrieve soil moisture from radar data
75 (Baghdadi et al., 2008; Zribi et al., 2011). In particular, the use of multi-temporal SAR acquisitions
76 allows SM to be effectively estimated, using a small number of assumptions, by analyzing changes in
77 radar backscattering over time (Zribi et al., 2005; Pathe et al., 2009; Gorraeb et al., 2015b).

78 Subsequently, the integration of SM SAR products into hydrological balance models would be of
79 considerable interest, since it could provide scientists with the opportunity to improve hydrological
80 forecasting. Many recent studies have shown that the SM retrieved from SAR data generally agrees

81 very well with that predicted by hydrological models (Baghdadi et al., 2007; Doubková et al., 2012;
82 Iacobellis et al., 2013; Santi et al., 2013; Pierdicca et al., 2014). Baghdadi et al., 2007, showed that the
83 monitoring of SM from SAR images was possible in operational phase. In fact, they compared
84 moistures simulated by the operational Météo-France ISBA soil-vegetation-atmosphere transfer model
85 with radar SM estimates to validate its pertinence. This comparison has shown an acceptable difference
86 between ISBA simulations and radar estimates. Pierdicca et al., 2014 compared SM values generated by
87 a soil water balance model with multi-temporal retrievals from ERS-1 images acquired over central
88 Italy. Very good results were obtained at the scale of the watershed, showing that the short three-day
89 revisit periodicity of ERS/SAR data can be used to compute relatively accurate estimations of the
90 temporal variations in SM.

91 SM remote sensing outputs can also be used for data assimilation and calibration in hydrological
92 transfer models, in order to evaluate their reliability (Weisse et al., 2003; Aubert et al., 2003; Qui et al.,
93 2009; Brocca et al., 2010 and 2012; Draper et al., 2011; Renzullo et al., 2014; Massari et al., 2015;
94 Lievens et al., 2015; López López et al., 2016). For example, Aubert et al., 2003, integrated remotely
95 sensed SM data into their hydrological model, to improve the accuracy of their hydrological forecasts.
96 Their methodology involved the implementation of a sequential assimilation procedure, allowing step-
97 by-step control of the model's successive outputs, thereby avoiding any divergence with respect to the
98 remotely sensed SM data. In a study published by (Brocca et al., 2010), a SM product derived from the
99 Advanced SCATterometer (ASCAT) sensor was introduced into a rainfall-runoff model (MISDc) and
100 applied to many sub-catchments of the Upper Tiber River in central Italy. The results reveal that even
101 with a coarse spatial resolution, remote sensing data can considerably improve the accuracy of runoff
102 predictions.

103 The growing availability of remote sensing SAR SM products, combined with the relatively large
104 number of parameters involved in soil water processes, means that moisture satellite data can now be
105 used for the calibration of distributed SM models. However, relatively few published studies have dealt
106 with the calibration of hydrological models using SAR SM products (François et al., 2003, Pauwels et

107 al., 2002; Matgen et al., 2006; Montanari et al., 2009). In this context, the present study focuses mainly
108 on the effectiveness of high-resolution TerraSAR-X SM products to be used as calibration data in a
109 hydrological model. We propose a new, simple soil hydrological model called MHYSAN
110 (“Modelisation de Bilan HYdrique des Sols Agricoles Nus” in French, or "Water balance model for
111 bare agricultural soils") which was used to compute surface evaporation and water balance in central
112 Tunisia, thereby simulating soil moisture time series. Modeling bare soil behavior should be considered
113 as a first step toward agricultural soil moisture monitoring, but is all the more as bare soils represent the
114 majority of surface in our study area, like in most semi-arid areas. Our paper is organized in five
115 sections. The following section presents the database and ground station measurements used in this
116 study. Then, section 3 explains the functioning of the MHYSAN model and the calibration and
117 validation method. The results of the calibration and validation processes are presented and discussed in
118 Section 4, and then our conclusions and perspectives are provided in section 5.

119 **2 Database description**

120 **2.1 Study Area Description**

121 The experimental site is situated on the Kairouan plain (9°30'E to 10°15'E, 35°N to 35°45'N), a semi-
122 arid region in central Tunisia (see Fig. 1) with an area of more than 3000 km². In this region, the annual
123 rainfall records are of approximately 300 mm/year, with the two rainiest months being October and
124 March and the mean daily temperature is about 19.2 °C. The mean annual reference evapotranspiration
125 estimated using the Penman-Monteith method is equal to 1600 mm (Zribi et al., 2011). Water
126 management in the Merguellil basin is characteristic of semi-arid regions, with an upstream sub-basin
127 collecting surface and subsurface flows to the El Haouareb dam, and a downstream plain supporting
128 irrigated agriculture. Agriculture consumes more than 80% of the water extracted from the Kairouan
129 aquifer.

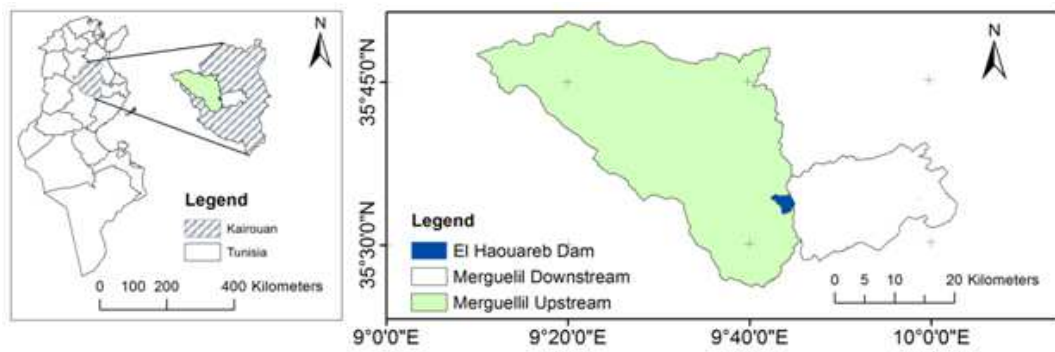


Figure 1: Localization of the study site.

2.2 Ground and remote sensing database

2.2.1 Continuous in situ SM and meteorological data

Ground-based SM measurements were obtained from a Continuous Soil Moisture Network (CSMN) which has been operated over the studied area since 2009. The CSMN network includes the following seven stations: Bouhajla, Hmidate, Sidi Heni, Chebika, Barrouta, Barrage and P12, as shown in Fig. 2. SM measurements were made with permanently installed Theta-Probe ML2X instruments, aligned horizontally at depths of 5 and 40 cm. For each continuous probe, SM values were recorded at 4h intervals and expressed in volumetric units (m^3/m^3). Thetaprobe calibrations were performed during the commissioning phase through the use of several different gravimetric measurements (Amri et al., 2012). Table 1 provides the geographic coordinates and soil characteristics of each station, in terms of their bulk density and soil texture classes.

Table 1. Geographic coordinates and physical soil properties of the seven continuous thetaprobe stations (da: bulk density)

Name	Lat(DD)	Long(DD)	da _{5cm}	da _{40cm}	% Sand	% Clay	% Silt	Texture
Bouhajla	N35.3888	E10.0477	1.69	1.63	71.9	16.5	11.6	sandy loam
Sidi Heni	N35.6630	E10.3404	1.35	1.6	48.5	28.1	23.4	sandy clay loam
Barrage	N35.5702	E9.7635	1.60	1.69	58.1		11.9	sandy clay loam
Barrouta	N35.5778	E10.0480	1.56	1.59	65.4	27.7	6.9	sandy clay loam
Chebika	N35.5504	E9.9216	1.32		32	36.2	31.8	clay loam

P12	N35.5563	E9.8716	1.47		69	18.5	13.5	sandy loam
Hmidate	N35.4757	E9.8449	1.67		81.1	12.7	6.2	sandy loam

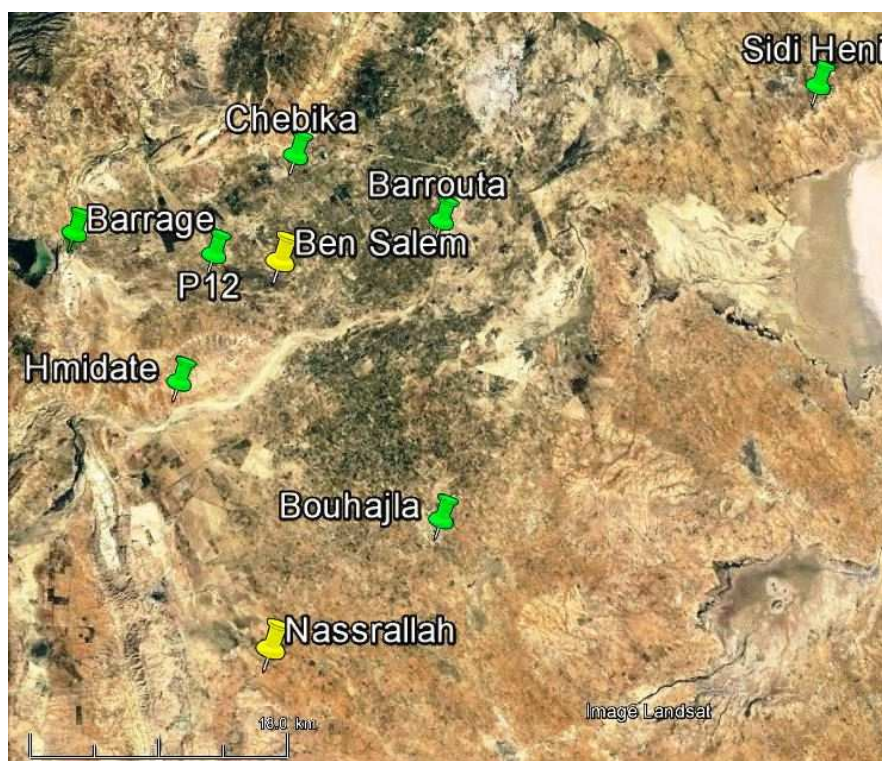
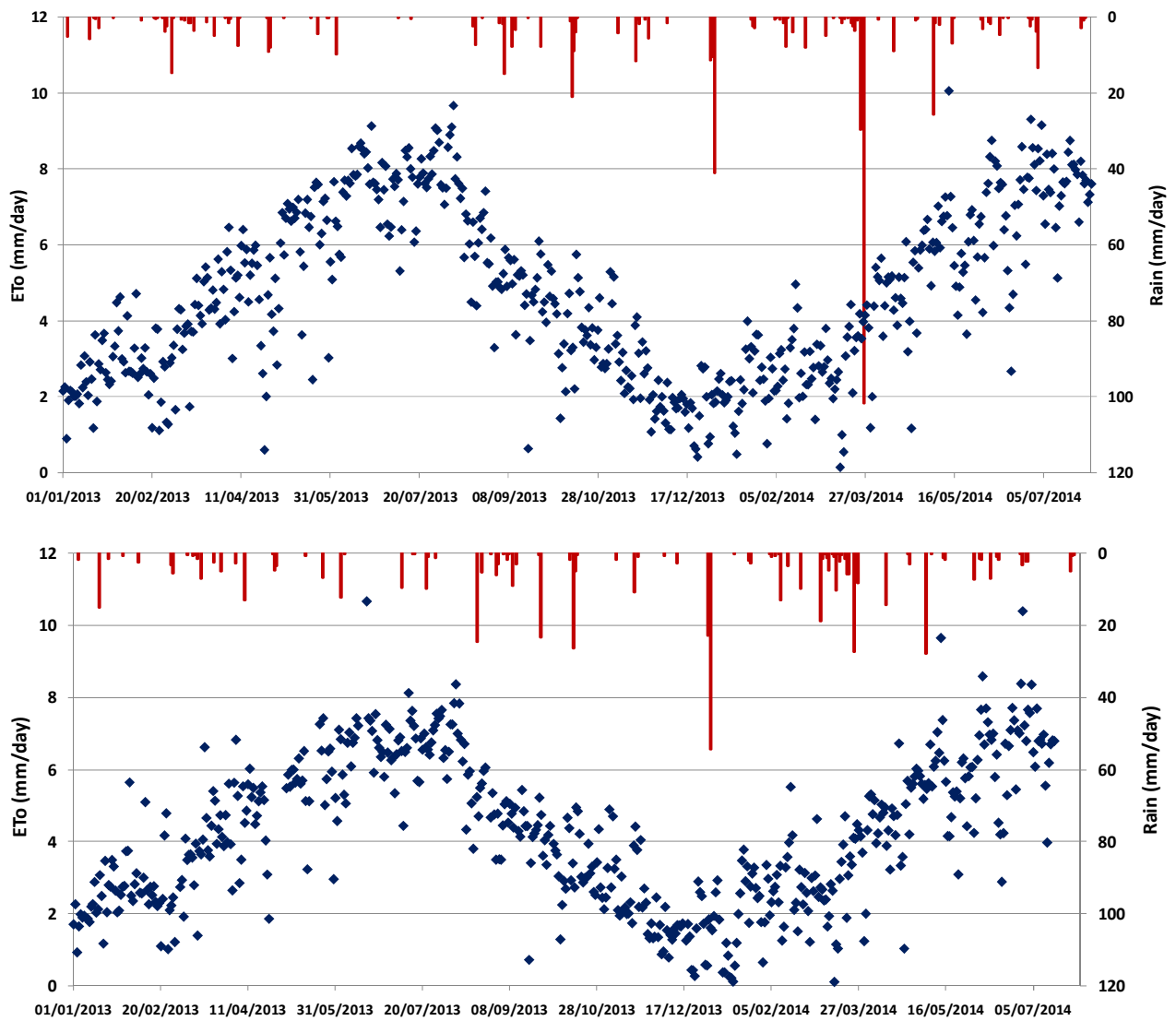


Figure 2: Locations of the continuous thetaprobe (green pins) and meteorological (yellow pins) stations (courtesy of Google Earth).

Fig. 3 shows the daily precipitation and reference evapotranspiration (ET_o) time series obtained using this meteorological data between January 2013 and August 2014 at the Ben Salem and Nassrallah stations, respectively. In this study, we used the SM and meteorological measurements recorded during the hydrological year of 2013-2014.



156 (a)

157 (b)

158 Figure 3: Mean daily rainfall (red bars at the top) and reference evapotranspiration “ETo” (blue points)

159 recorded at two meteorological stations: (a) Nassrallah and (b) Ben Salem, for the hydrological year of

160 (2013-2014).

161 2.2.2 Analysis of SM and rainfall time series

162 The daily rainfall and SM variations for the 2013-2014 season were analyzed in order to check the

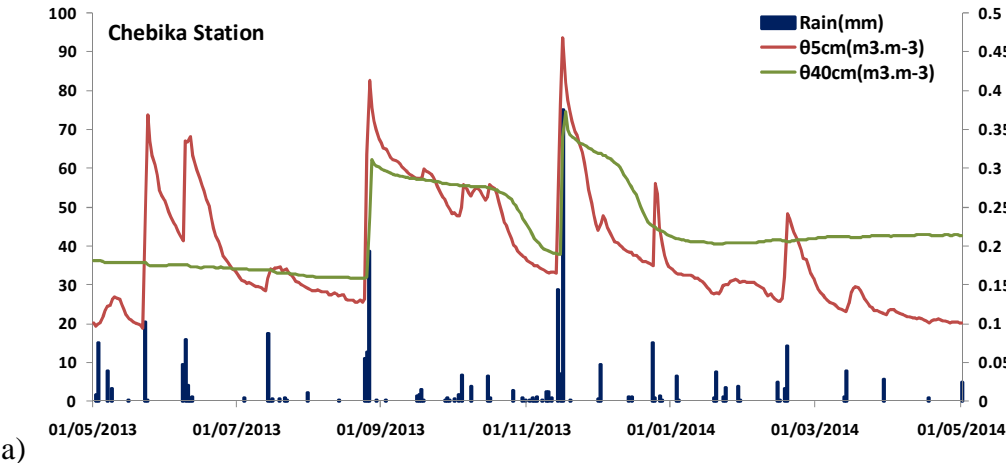
163 correlation between rainfall and soil moisture. Fig. 4 shows the example of the Chebika and Hmidate

164 probes. The rainfall gauges selected for each SM site were the closest to each of the continuous probe

stations. The rainfall time series should be consistent with the temporal variations in SM recorded at the depths of 5 cm and 40 cm.

From Fig. 4, it can be seen that SM variations in the shallow layer (5 cm) are very different to those observed in the deep layer (40 cm). The soil moisture content in both of these layers can be attributed mainly to the influence of the soil's texture and pore size distribution (Bezerra et al., 2013; Zhang et al., 2015; Shabou et al., 2015). We also note that the deeper the probes are, the smoother the recorded response. According to (Famiglietti et al., 1998; Amri et al., 2012), the amount of water stored in the first centimeter of top soil increases rapidly in the presence rainfall, and can decrease significantly within a few hours, due to atmospheric influences (evaporation ...). This is the reason for which, as shown in Fig. 4, the SM estimated at 40 cm is affected by considerably small variations than those measured at the surface (5 cm). A large water content in the deep soil layers maintains an upward vertical SM gradient, thereby contributing to the SM and evaporation observed in the shallow surface layers (Chen and Hu, 2004).

Overall, the precipitation inputs are quite well correlated with the observed SM variations, in particular the surface SM (θ_{5cm}). For the 2013-2014 period, small discrepancies are occasionally observed between SM and precipitation, since rainfall events are not always accompanied by an increase in SM, and some SM variations are not correlated with any rainfall event.



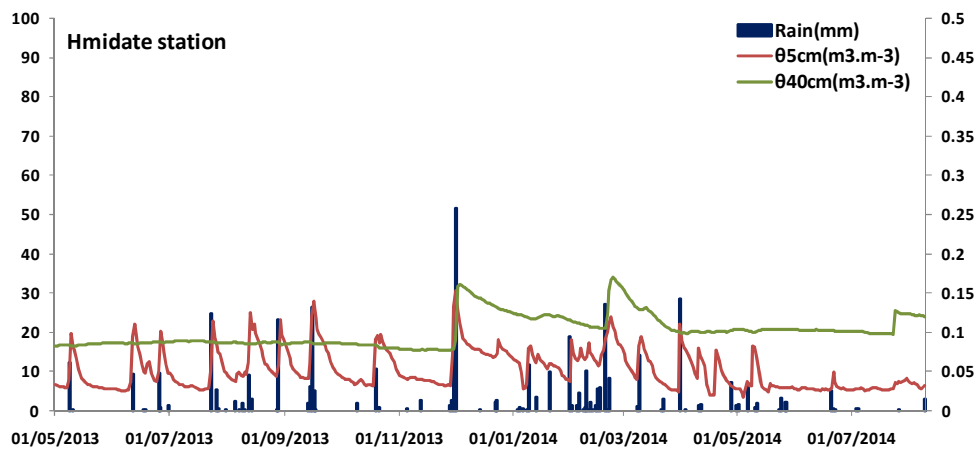


Figure 4: Correlation between daily precipitation data (blue bars) and SM time series recorded during the 2013-2014 season, using: a) the Chebika thetaprobe station b) the Hmidate thetaprobe station, at depths of 5 cm and 40 cm.

2.2.3 Soil moisture control plots

SM measurements were collected from a set of 15 control plots on bare soil fields distributed over the study area, having different types of roughness ranging from smooth to ploughed surfaces (Fig.6). Ground campaigns were carried out from November 2013 to January 2014, simultaneously with SAR image acquisitions. The surface areas of these study fields ranged between 1.6 and 17 ha. Handheld thetaprobe measurements were made at a depth of 5 cm, at approximately 20 points distributed over the entire surface area of each control plot, within a two-hour time frame between 3:40 p.m. and 5:40 p.m., coinciding with the time of each overhead satellite acquisition.

The manual thetaprobe measurements were calibrated using gravimetric measurements recorded during previous campaigns (Zribi et al., 2011). The ground-measured volumetric moisture “mv” values ranged between 4.7% to 31.6 %, for all manual thetaprobe measurements. For each control plot, three soil samples were collected, and the soil's texture was determined by measuring the percentages of sand, silt and clay particles in the laboratory (Gorrah et al., 2015a). These fractions were then classified according to the USDA textural triangle (Fig. 5). In our control plots, the observed variability of the soil's

composition, which is dominated by a high proportion of fine particles, could have a significant influence on its water retention capacity.

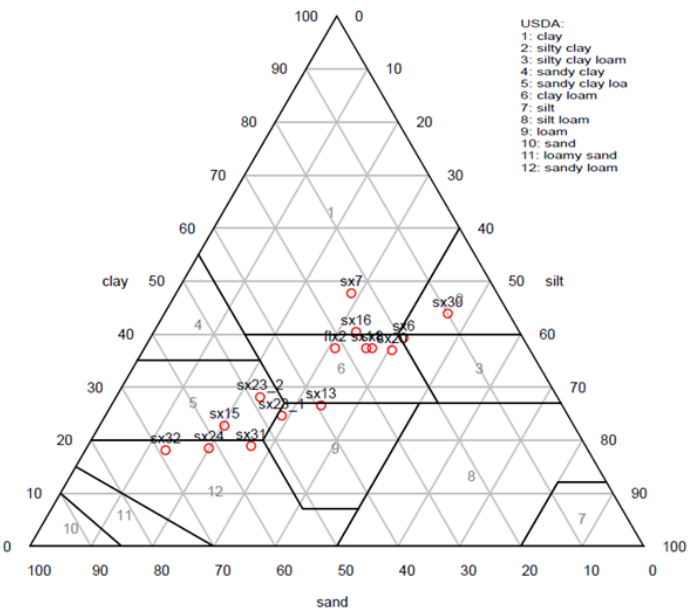
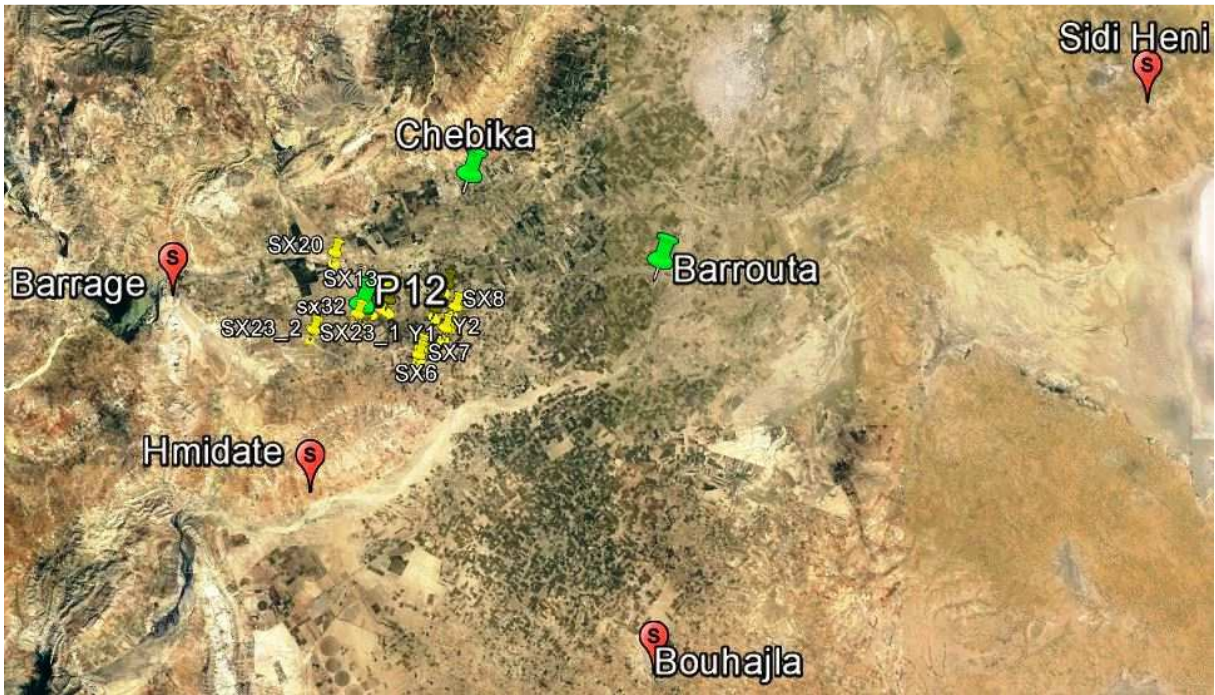


Figure 5: Textural triangle (USDA classification) of the soil in the control plots: each red circle corresponds to a single field.

2.2.4 SAR data and SM products

Seven TerraSAR-X images (X-Band ~9.65 GHz, 36° incidence angle and HH polarization) were acquired over the Kairouan plain between November 2013 and January 2014. All of the TSX images correspond to a “Single-look Slant Range Complex: SSC” TSX product, with a Single-look complex format, having a ground pixel spacing of approximately 2 m. The SAR images were initially multi-looked using the NEST software (<https://earth.esa.int/web/nest/home/>) to reduce speckle effects. For all images, five looks were used in the azimuth and range directions (resulting pixel size ~ 9 × 9 m²). The images were then radiometrically calibrated to derive their backscattering coefficients σ° , and then geo-referenced using the SRTM 3Sec DEM (Auto download with the NEST software). The mean radar signals were computed for each control plot.

216 The SM maps were produced using the multi-temporal TerraSAR-X data acquired at high spatial
 217 resolution scale. For the estimation of bare surface SM, we propose an algorithm based on an empirical
 218 change detection approach combining TerraSAR-X images with ground CSMN measurements. It is
 219 important to note that we used only three continuous Thetaprobe stations from the CSMN, to calibrate
 220 the SAR moisture products. In the following, we note these stations as (CSMN₃), as shown in Fig.6.



221
 222 Figure 6. Location of the control plots (yellow pins) and the CSMN₃ (green pins).

223 The methodology adopted in this study to estimate the spatial variability of SM is described in (Gorrah
 224 et al., 2015b). Our analysis is based on the seven radar images acquired over the study site.
 225 The proposed approach takes advantage of the approximately linear dependence (in decibels) of radar
 226 backscattering signals on soil moisture. This linear relationship is modeled as:

227
$$\sigma_{dB}^0 = S_0 m v + f(R) \tag{1}$$

228 where S_0 is the radar signal's sensitivity to soil moisture (mv), and $f(R)$ is a function of the roughness R .
 229 The change in soil moisture Δm_v between two successive TerraSAR-X image acquisitions (11 day
 230 period in the case of the present study), can be expressed as:

$$231 \quad \Delta m_v = \frac{\Delta \sigma^\circ - \Delta f(R)}{S_0} \quad (2)$$

232 where $\Delta \sigma^\circ$ is the radar signal difference, obtained by subtracting consecutive radar backscatter images
 233 acquired over a given area (i.e. the change in signal strength between two acquisition dates), and $\Delta f(R)$ is
 234 the difference in radar signal resulting from roughness contributions, between two successive radar
 235 images.

236 The proposed algorithms are validated by comparing the radar estimations with ground-truth
 237 measurements made in control plots, characterized by soil moistures ranging between dry and wet
 238 conditions. Since a small improvement in the soil moisture estimation accuracy is observed when the
 239 roughness variations are taken into account, the resulting soil moisture maps are computed for each date
 240 d_t and each pixel (i, j) , as:

$$241 \quad m_v(i, j, d_t) = \Delta m_v(i, j, d_t, d_{t-1}) + m_v(i, j, d_{t-1}) \quad (3)$$

242 where $m_v(i, j, d_t)$ is the SM at pixel (i, j) and date d_t , $m_v(i, j, d_{t-1})$ is the SM at pixel (i, j) and date d_{t-1} ,
 243 and $\Delta m_v(i, j, d_t, d_{t-1})$ is the change in SM at pixel (i, j) , between the dates d_t, d_{t-1} .

244 Fig. 7 shows three bare soil moisture maps computed using the above algorithm on three different dates:
 245 *12/12/2013: was a dry date, and the spatial variations in soil moisture can be seen to be low.
 246 *23/12/2013: was the wettest day (the recorded precipitation was approximately 38.6 mm), and the
 247 spatial variations in soil moisture are relatively homogenous (dark blue)
 248 *14/01/2014: was characterized by medium values of soil moisture and highly heterogeneous levels of
 249 soil moisture (dark blue to light).

250 The TerraSAR-X SM maps provided data representing the volumetric soil moisture content expressed
 251 in volumetric percentage units (vol. %).

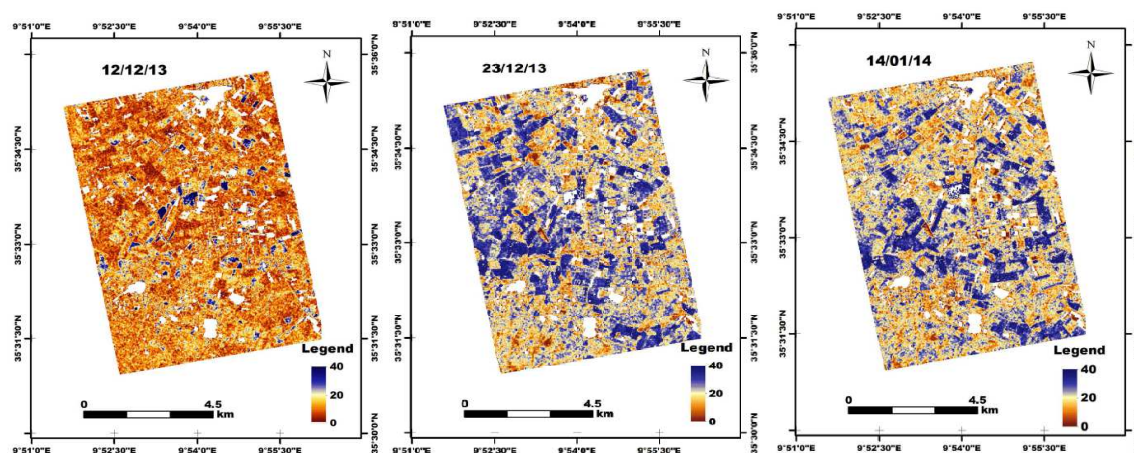


Figure 7: Three surface SM TerraSAR-X products.

3 Bare soil hydrological balance estimation

3.1 MHYSAN model description

The “MHYSAN” model simulates the soil water balance at 24-hour intervals, using daily precipitation and meteorological data as inputs for the estimation of evaporation. The model considers a dual soil layer structure: a surface layer from which moisture can evaporate, and a deep layer where water is stored (fig.8). During rainfall events, the gravity makes water successively fill the soils’ compartments from top to bottom. In this model, lateral circulation of water (overland and subsurface runoff) is assumed to be negligible. When all compartments are full, any excess water flows out of the system by means of deep drainage (Simonneaux et al., 2009, Saadi et al., 2015).

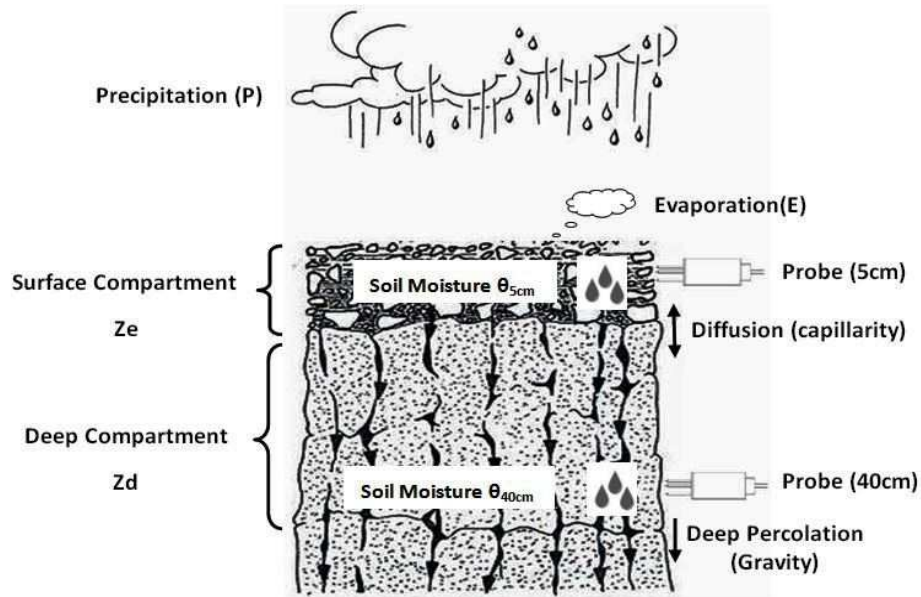


Figure 8: Schematic representation of the conceptual bare soil hydrological model “MHYSAN”.

Z_e [mm] is the height of the evaporative layer. Below this surface layer, a deep layer of height Z_d [mm] is modeled. TEW is the water column [mm] representing the difference between the moisture content at field capacity and the residual water content that cannot be evaporated from the soil, and is described by the following expression Eq. (1):

$$TEW = (\theta_{fc} - \theta_{res}) * Z_e, \quad (1)$$

The evaporative capacity of the deep compartment (TDW) is computed in a similar manner to the TEW, using the following expression Eq. (2):

$$TDW = (\theta_{fc} - \theta_{res}) * Z_d \quad (2)$$

Capillary processes are also modeled in MHYSAN, either upwards or downwards, between the evaporative layer and the deep compartment, on the basis of their relative water contents. In particular, this allows evaporation to continue long after a rainfall event, since the deeper layers can sustain low evaporation fluxes at the surface. The daily amount of water diffusing between the two layers, Dif_{ed} , is computed following Eq. (3):

$$Dif_{ed} = cdif * \left(\frac{\frac{(TDW - D_{d,i})}{Z_d} - \frac{(TEW - D_{e,i})}{Z_e}}{\theta_{fc}} \right), \quad (3)$$

where $D_{e,i}$ and $D_{d,i}$ represent the depletion of water in the evaporation and deep layers for day i (i.e. the volume of voids as compared to soil at field capacity), and $cdif$ is the diffusion coefficient [$\text{mm} \cdot \text{day}^{-1}$]. The MHYSAN model balances the soil's daily water budget by ensuring that water inputs and outputs are conserved, in accordance with the following expression Eq. (4):

$$E_i + DP_i + \Delta SW_i = P_i \quad (4)$$

with:

E_i Evaporation

DP_i Deep Percolation (drainage)

ΔSW_i Variation of the soil's water content

P_i Precipitation

The evaporation (E_i) from a bare soil surface is defined as the volume of water vapor removed from the soil's surface and transferred to the atmosphere and is estimated using the FAO-56 formalism (Allen et al., 1998) using equation 5:

$$E_i = K_{e,i} * ET_0, \quad (5)$$

Where

ET_0 is the grass reference evapotranspiration (mm/day). This term was computed using the expressions proposed by Allen et al. (1998), where $K_{e,i}$ is the evaporation coefficient, related to the volume of water in the surface layer, obtained with equation 6:

$$K_{e,i} = \frac{(TEW - D_{e,i})}{(TEW - R_E)} \leq 1, \quad (6)$$

and R_E is the coefficient of resistance to evaporation.

The depletion ($D_{e,i}$) is updated every day from the soil water balance as follows:

$$\begin{cases} D_{e,i} = D_{e,i-1} - P_i + E_i - Dif_{ed} \\ 0 \leq D_{e,i} \leq TEW \end{cases}, \quad (7)$$

If $D_{e,i} < 0$ then:

$$DP = -D_{e,i}$$

$$D_{e,i} = 0$$

Depletion in the deep layer ($D_{d,i}$) is computed as follows:

$$\begin{cases} D_{d,i} = D_{d,i-1} - DP_{d,i} + Dif_{ed} \\ 0 \leq D_{d,i} \leq TDW \end{cases}, \quad (8)$$

If $D_d < 0$, then:

$$DP_{d,i} = -D_{d,i}$$

$$D_{d,i} = 0$$

where $DP_{d,i}$ is the assumed value of deep percolation on day i [mm].

The volumetric soil moisture contents θ [m^3m^{-3}] at depths of 5 and 40 cm are determined by the

MHYSAN model from the following relationships:

$$\theta_{5cm} = \theta_{res} + (\theta_{fc} - \theta_{res}) * (TEW - D_{e,i}) / TEW, \quad (9)$$

and

$$\theta_{40cm} = \theta_{res} + (\theta_{fc} - \theta_{res}) * (TDW - D_{d,i}) / TDW, \quad (10)$$

3.2 Model calibration and validation

We choose to calibrate some parameters of the MHYSAN as shown in Table 2. These parameters are related to the soil's hydraulic properties, and are specific to each type of soil, depending on the size distribution and structure of its pore spaces. Some of the model parameters were fixed from ground moisture profiles measured at depths of 5 cm and 40 cm (e.g. the initial soil moisture content H_{Init} and the residual soil moisture content θ_{res}). The other parameters were calibrated using the observed soil moisture data. We choose to fix θ_{res} but not θ_{fc} because the water holding capacity is not related to

absolute values of these parameters but only to their difference. The soil parameters retained after calibration of the MHYSAN model are summarized in Table 3. The calibration involves maximizing the Nash–Sutcliffe efficiency computed between observed and modeled values of soil moisture, at depths of 5 and 40 cm. This is written as:

$$NASH = \left[1 - \frac{\sum_{i=1}^n (\theta_i^{obs} - \theta_i^{sim})^2}{\sum_{i=1}^n (\theta_i^{obs} - \overline{\theta^{obs}})^2} \right] * 100, \tag{11}$$

where θ_i^{obs} is the observed value of soil moisture on day i, θ_i^{sim} is the modeled value of soil moisture on day i, and $\overline{\theta^{obs}}$ is the observed mean value of soil moisture over the entire period under consideration. The Nash efficiency varies between 100 and $-\infty$, with an efficiency of 100 indicating a perfect fit between the modeled outputs and observations. A negative Nash efficiency indicates that the mean value of the observed time series would have been a better predictor than the model. In the present study, the NASH efficiency coefficients were used for the calibration and validation of the MHYSAN model. The discrepancies observed between the SM observations and MHYSAN simulations are expressed also in the form of two statistical indices: root mean square error (RMSE) and bias.

Table 2. Model parameters used for the evaporation and moisture simulations

Soil parameters	Description	Data Sources
$\theta_{fc} [m^3 m^{-3}]$	Volumetric water content at field capacity [0-1]	Derived from the MHYSAN calibration
$\theta_{res} [m^3 m^{-3}]$	Residual moisture content [0-1]	Derived from ground moisture profiles
$R_E [mm]$	Coefficient of resistance to evaporation	Derived from the MHYSAN calibration
$cdif [mm \cdot day^{-1}]$.	Diffusion coefficient for the hydraulic gradients between the deep and surface compartments	Derived from the MHYSAN calibration
$H_Init [m^3 m^{-3}]$	Initial soil moisture content at depths of 5 cm and 40 cm	Derived from ground moisture profiles
$Ze [mm]$	Height of the surface layer	Derived from the MHYSAN calibration
$Zd[mm]$	Height of the deep layer	Derived from the MHYSAN

In this work, SM data derived from either CSMN stations or SAR moisture products were used to calibrate the model and independent SM data were used to validate the model (Fig.9). In fact, two approaches were considered for calibration of the MHYSAN model. In the first approach, model calibration was carried out using the CSMN data. The purpose of this step was to assess the intrinsic ability of MHYSAN to simulate soil moisture. Then, we tested the possibility to spatially extrapolate the local MHYSAN SM simulations based on the texture similarity of distant sites, assuming meteorological forcing are the same. This extrapolation was assessed using punctual thetaprobe SM measurements and SAR SM estimates available for independent control plots.

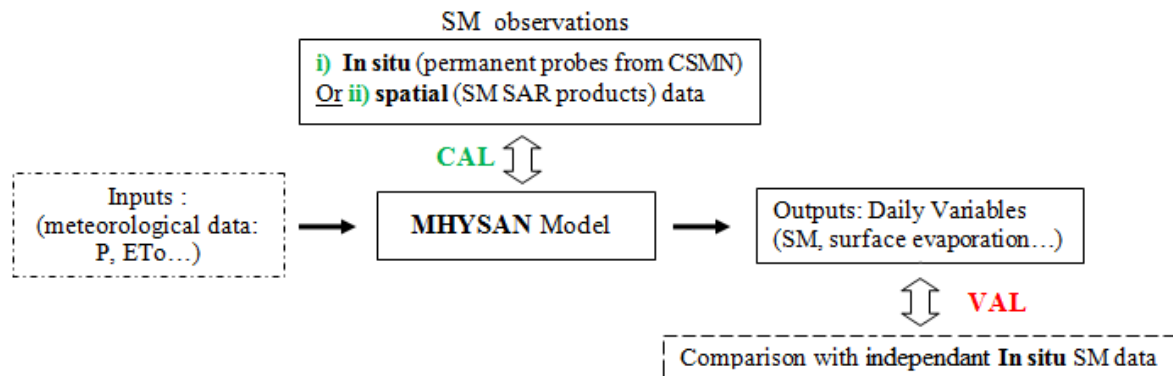


Figure 9: Use of soil moisture data (in situ continuous probes or radar images) in the MHYSAN model

In the second approach, the objective was to test the use of remotely sensed data alone (SAR) to calibrate the model. Calibration was performed using the SM TerraSAR-X products retrieved on seven different dates ranging between November and January. The validation was achieved by comparing model predictions with measurements collected for the four CSMN sites (Bouhajla, Sidi Heni, Barrage and Hmidate) that were not used for SAR SM calculation. Because the knowledge of texture was necessary to derive SM from SAR data, it was calculated only for the control plots. The selection of the control plots for which SAR SM estimates will be used for MHYSAN calibration was achieved based on texture similarities between CSMN stations used for validation and the control plots. The similarity

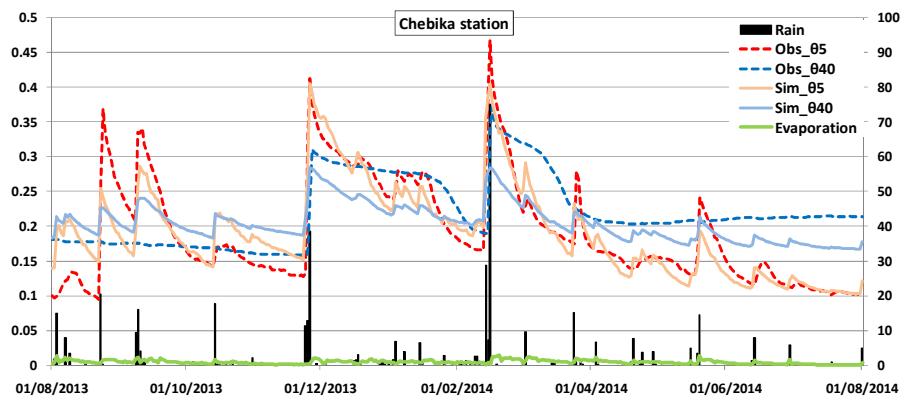
354 was based on the the euclidean distances between texture components, namely percentage of clay, silt
355 and sand.

356 **4 Results and Discussion**

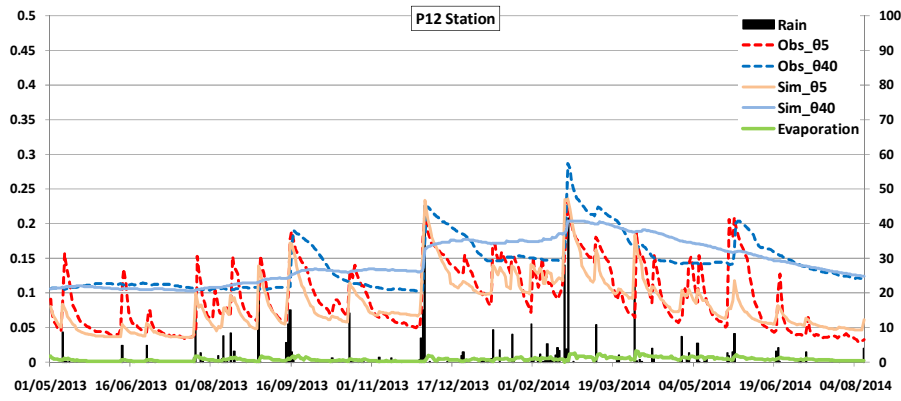
357 **4.1 MHYSAN model calibration using SM measurements**

358 In the present step, the MHYSAN model was implemented for the seven continuous probe stations, in
359 an attempt to reproduce the SM time series observed by each continuous thetaprobe at depths of 5 and
360 40 cm. Fig. 10 provides a plot of the estimated values of the main water balance components, in
361 particular soil moisture and evaporation time series, for three CSMN stations (2013-2014 period).

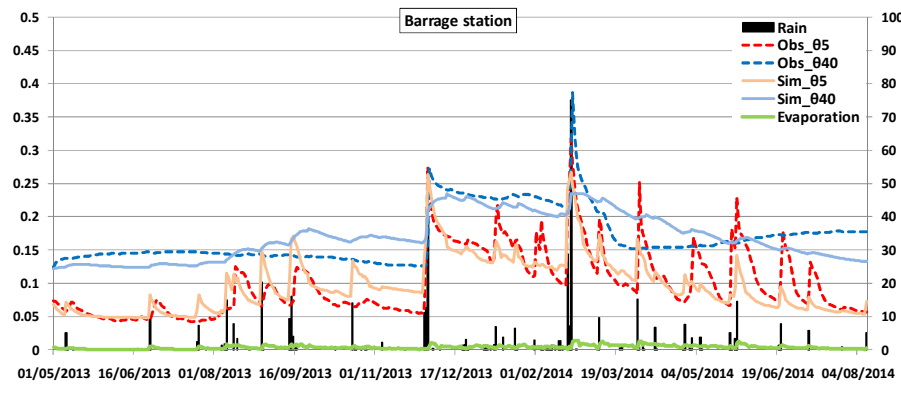
362 Table 3 lists the MHYSAN parameters which were established as described in the table 2 (section 3.2)
363 and retained for each continuous thetaprobe station. The time-dependent agreement between the observed
364 and simulated SM time series is characterized by the NASH efficiency coefficients at depths of 5 cm and 40
365 cm. Following calibration, the NASH efficiency coefficients ranged between 81.2 and 52 % for
366 $NASH_{5cm}$ and between 76.3 and 11% for $NASH_{40cm}$. Overall, the results for the surface horizon at a
367 depth of 5 cm (θ_{5cm}) are better than those corresponding to the layer located at a depth of 40 cm (θ_{40cm}).
368 Discrepancies are occasionally observed for the period from 2013-2014, when the simulated MHYSAN
369 SM responses are higher or lower than the SM continuous probes measurements. In addition, we note
370 that the agreement between simulations and observations is not as good in the case of the Sidi Heni
371 station. This can be explained by the poor representativity of the rainfall data considered for this station,
372 which is more remote than the other stations (situated at approximately 39 km from the Ben Salem
373 meteorological station).



(a)



(b)



(c)

Figure 10: Evaporation and soil moisture simulations using observed moisture measurements from (a) Chebika (b) P12 (c) Barrage. “Obs 05” and “Obs 040” correspond to the SM time series observed using continuous probes at depths of 5 cm and 40 cm respectively. “Sim 05” and “Sim 040” correspond to the volumetric water content simulated by the MHYSAN model, at depths of 5 cm and 40 cm respectively.

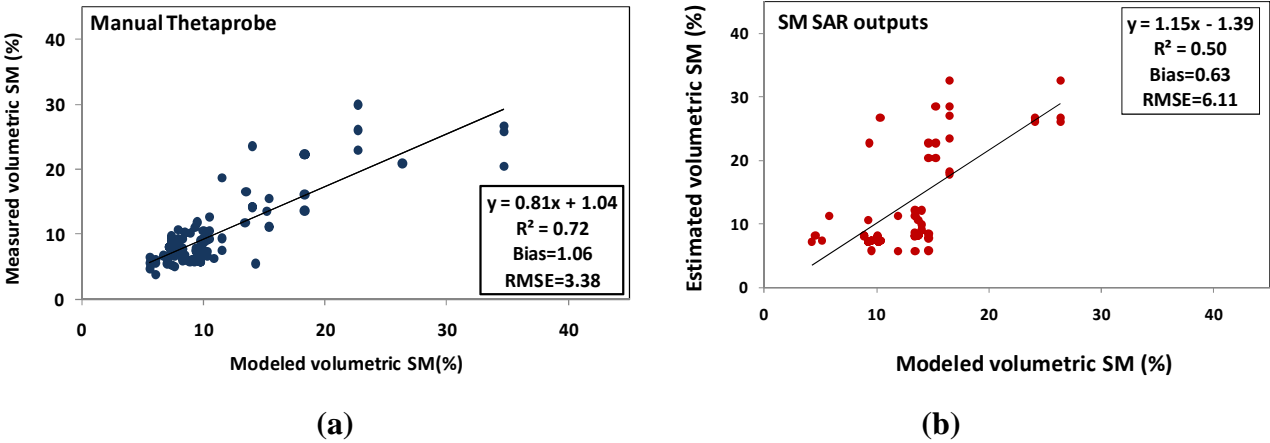
Table 3. Soil Parameters retained after calibrating MHYSAN with measured values of moisture.

Ze (mm)	Zd (mm)	$\theta_{fc} 5cm$ [m ³ m ⁻³]	$\theta_{res} 5cm$ [m ³ m ⁻³]	$\theta_{fc} 40cm$ [m ³ m ⁻³]	$\theta_{res} 40cm$ [m ³ m ⁻³]	R _E [mm]	cdif [mm.day ⁻¹]	NASH _{5cm}	NASH _{40cm}
Chebika station									
194.5	500	0.37	0.04	0.27	0.1	-5.57	6.23	81.2	26.2
P12 station									
188	866	0.24	0.03	0.2	0.09	-21.7	3.47	66	63.2
Hmidate station									
225	500	0.1	0.03	0.11	0.06	-25.1	0.31	62.4	50.8
Barrage station									
225	679	0.28	0.05	0.23	0.12	-15.1	5.98	68	49
Barroua station									
225	680	0.21	0.04	0.11	0.03	-1.13	3.36	63	76.3
Bouhajla station									
225	280	0.16	0.01	0.11	0.01	-10	3.05	58	39.1
Sidi Heni station									
225	318	0.27	0.07	0.14	0.1	-84.8	2.34	52	11

382

383 Then, we propose a comparison of calibrated MHYSAN SM outputs at plot scale with in situ SM data
384 and SAR moisture estimations. These comparisons take into account texture similarities, as well as the
385 location between continuous probe stations and control plots for 2013-2014 season (only stations close
386 to the control plots were used). In Fig. 11, we compare the MHYSAN surface SM at 5cm depth with
387 plot scale estimations made using: a) manual thetaprobe, and b) SAR moisture. In the last case, the
388 CSMN₃ used to calibrate the SAR moisture products, were removed from these comparisons. At plot
389 scale, the results are characterized by a volumetric moisture bias and RMSE equal to 1.06 and 3.38%
390 respectively, when the MHYSAN SM simulations are compared to the SM manual thetaprobe
391 measurements. Similarly, the comparison between MHYSAN SM and SM SAR outputs leads to a
392 volumetric moisture bias and an RMSE equal to 0.63 and 6.11%, respectively. Baghdadi et al., 2007

393 compared SM SAR estimates over bare soils with SM ISBA simulations and obtained a mean difference
 394 between 0.4 and 10% ($RMSE \leq 5\%$ for 12 dates among the 18 examined dates and between 5% and
 395 10% for the 6 remaining dates). The results are good indicators of the suitability of local SM datasets
 396 for the determination of soil moisture dynamics at the regional scale, on the basis of soil texture
 397 similarities.



398
 399 (a) (b)
 400 Figure 11: Comparisons from the 2013-2014 ground campaign, between Modeled volumetric SM
 401 values (5 cm depth) and: (a) SM Manual thetaprobe measurements and (b) SM SAR products, at plot
 402 scale.

403 **4.2 MHYSAN model calibration using satellite SM products**

404 In this section, the MHYSAN model was calibrated using SAR products only (from radar images
 405 acquired on seven different dates). As SAR SM estimates are related to the surface of the soil, the
 406 calibration was achieved only for this surface layer, although we computed performance criteria for
 407 both surface and deep layers. Following this calibration, the model was validated using daily SM
 408 observations derived from long-term data provided by the CSMN stations between 2013 and 2014. In
 409 the latter case, we used only those CSMN (4 stations) that were not used to calibrate the SAR moisture
 410 products.

411 As no SAR SM estimations were available for the areas corresponding to the four CSMN stations used
412 to validate MHYSAN, the SAR SM corresponding to control plots with textures similar to that of each
413 respective station were used. Four different control-plot groups were thus selected, on the basis of the
414 Euclidean distance between their texture and that of their respective stations. Only distances of less than
415 10 were retained. For each texture group, the relevant SAR SM value was computed as the mean of the
416 SM values determined for the corresponding control plots.

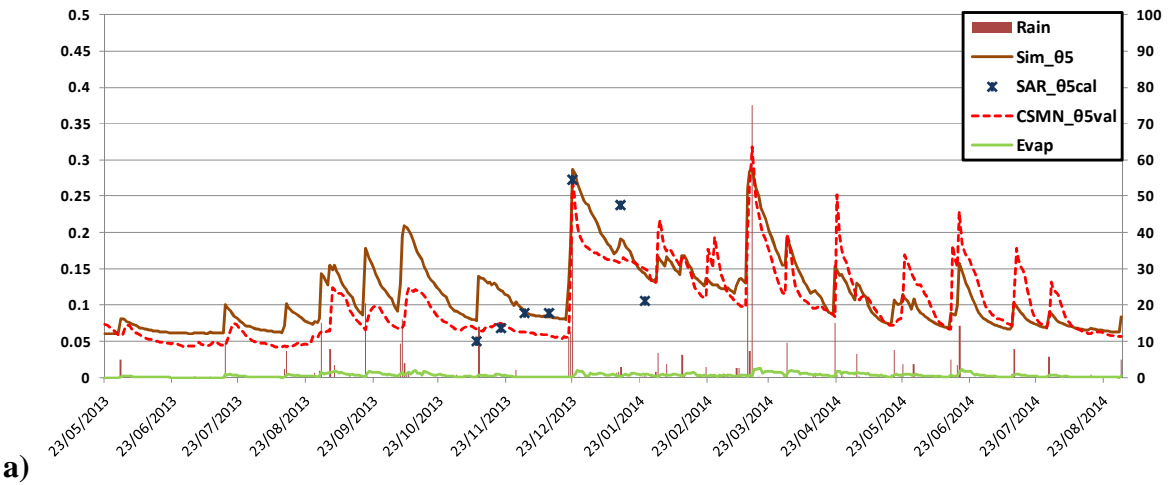
417 Fig. 12 shows the resulting estimated water balance variables, surface SM and evaporation, computed
418 by the MHYSAN model using seven SAR SM products for the four different plots corresponding to
419 each of the validation stations. The discrepancies between the estimated SM SAR products and the
420 simulated SM MHYSAN outputs are presented in Table 4, showing that globally satisfactory
421 simulations are achieved. The use of just seven SAR SM estimations leads to good model performance.
422 Brocca et al., 2008 reported the calibration of a conceptual model for soil water content balance, using a
423 small number of isolated SM measurements. In this study, variations in RMSE and NASH values were
424 determined as a function of the number of SM measurements (ranging from 3 to 15) used to calibrate
425 the model. The results revealed that just seven SM measurements were sufficient to obtain good RMSE
426 and NASH values, and to correctly calibrate the tested soil hydrological balance model.

427 We see on fig. 12 that although the seven satellite acquisition were achieved in a short time range as
428 compared to the simulation length, the SAR moisture values vary considerably over time, due to
429 important rainfall occurring during this period, which may have influenced positively our results.

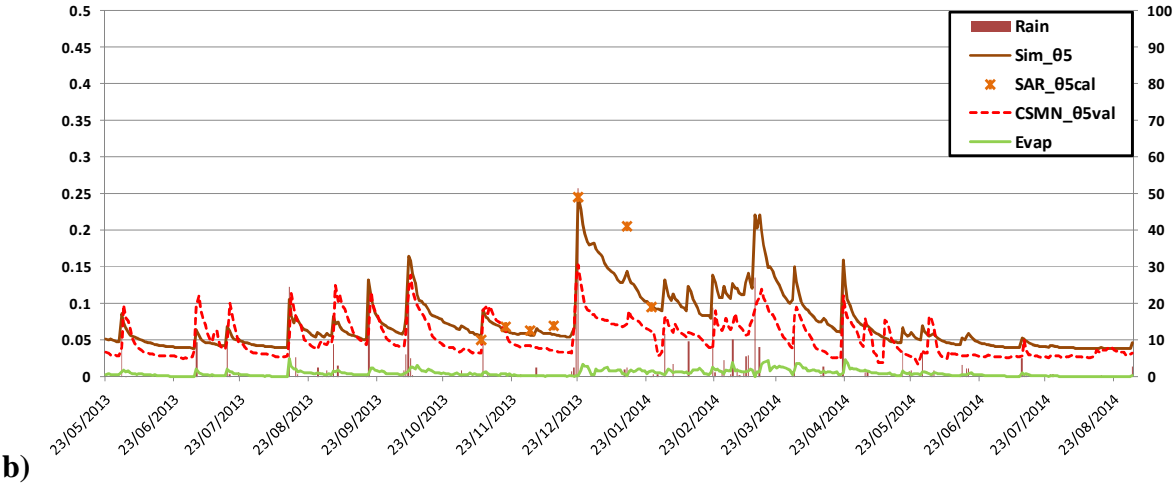
430 Fig. 12 plots the calibrated MHYSAN SM outputs, together with the continuous thetaprobe SM
431 observations. The Nash efficiency and statistical performance of these outputs are provided in Table 4.
432 The validated version of the calibrated MHYSAN model is generally found to be in good agreement
433 with the continuous probe observations and the MHYSAN simulations (Fig. 12 and Table 4). The
434 performances shown in this table also indicate that there is a poor agreement between the simulations and
435 observations in the case of the Sidi Heni and Hmidate stations. For the Sidi Heni station, this outcome
436 can be explained mainly by the poorly representative rainfall data used for this station. Indeed, an

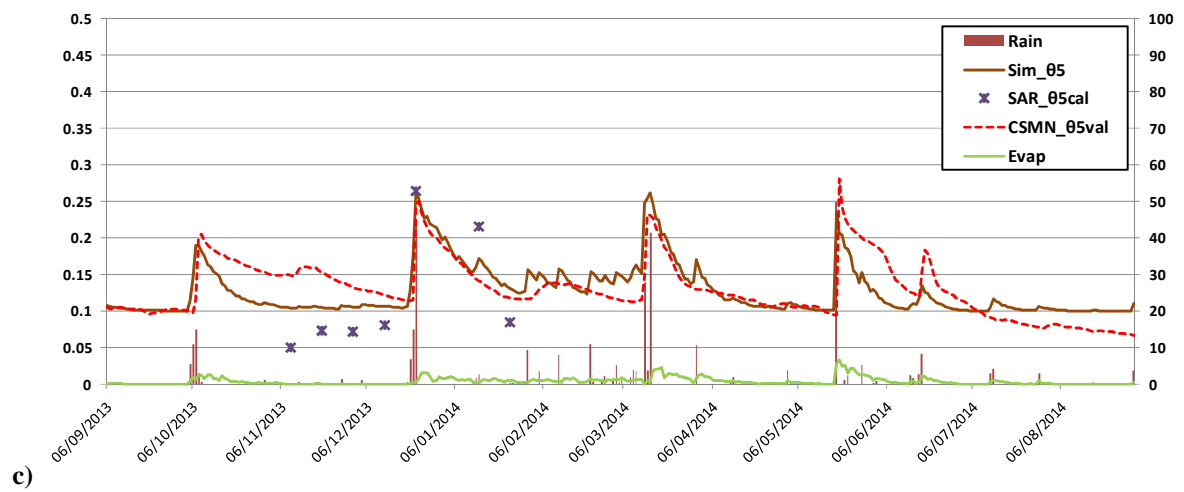
437 increase in SM was measured in May without rainfall event recorded. For the Hmidate station, after the
 438 important SM raise in December, a lower SM is observed compared to simulations. This result can be
 439 related to the soil at the Hmidate station which has a very high percentage of sand (81%), and just one
 440 corresponding control plot (selected according to the distance between its texture and that of the
 441 Hmidate station), which could lead to larger errors in the model.

442

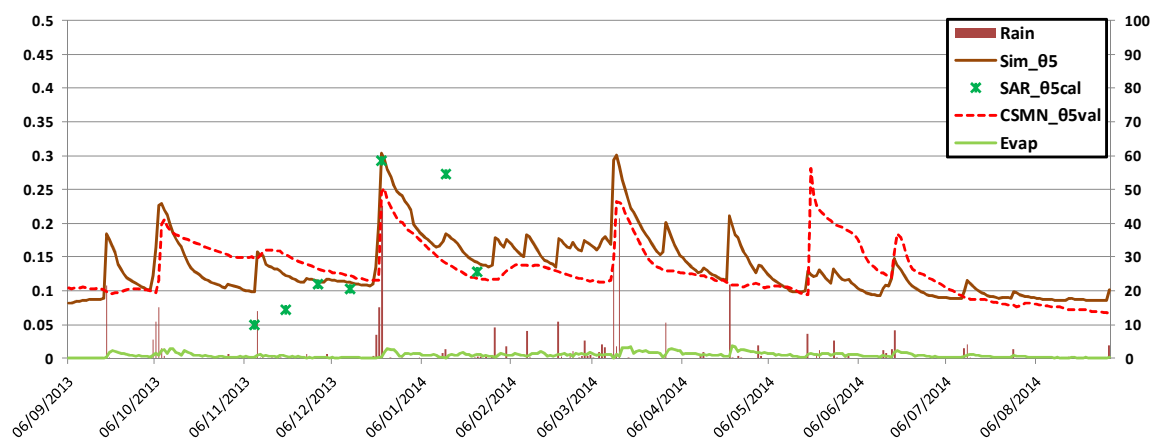


443





c)



d)

Figure 12: Estimation of times series of water balance variables, using calibrated MHYSAN SAR data and validation results from different texture groups: (a) "Barrage" station; (b) "Hmidate" station; (c) "Bouhajla" station and (d) "Sidi Heni" station

Table 4. Quality parameters of the MHYSAN "Calibration-Validation" process. The criteria for the calibration phase are computed only for the seven SAR dates. Validation criteria are computed for the full CSMN measurement period.

	NASH (%)		RMSE (%)		Bias (%)	
	CAL	VAL	CAL	VAL	CAL	VAL
Barrage station	87.6	57.5	2.84	3.16	-0.43	-0.18
Hmidate station	89	-88	2.4	3.4	-1.06	2.23
Bouhajla station	77	44.1	3.7	2.89	2.07	-0.31
Sidi Heni station	76.7	2.8	4.29	3.81	0.72	0.41

453 Finally, the MHYSAN simulations using SAR SM products for calibration were compared with
 454 MHYSAN outputs obtained using bibliographic FAO parameters only. The Ze and Zsol depth were
 455 fixed respectively at 100 and 700 mm in order to fit with the SM probe depth. The soil resistance to
 456 evaporation R_E was determined using the REW values proposed by FAO for various soils textures
 457 (table 19 of the FAO 56 paper), as well as the soil moisture values θ_{res} and θ_{fc} . Finally, the diffusion
 458 coefficient was arbitrary fixed to the medium value of 2 as observed for several calibrations achieved in
 459 previous studies (not shown here). The Nash efficiency and statistical performance of these simulations
 460 are listed in Table 5, showing that the MHYSAN model performs better when SAR SM products are
 461 used. These results confirm the effectiveness of TerraSAR-X SM retrieval for the calibration of a bare
 462 soil hydrological model.

463 Table 5. Quality parameters of the MHYSAN model using FAO parameters only

	NASH (%)	RMSE (%)	Bias (%)
Barrage station	-151	12.84	9.96
Hmidate station	-259	13.69	11.63
Bouhajla station	70.2	4.22	1.42
Sidi Heni station	-423	20.36	18.31

464 **5 Conclusions**

465 This study was designed to investigate the potential of high-resolution TerraSAR-X soil moisture (SM)
 466 products for the calibration of a soil water balance model. We used MHYSAN, a bare soil hydrological
 467 balance model, which simulates soil evaporation and moisture content over bare soil using as
 468 input meteorological data. The model was first calibrated using time series of daily SM continuously
 469 measured for some sites. The results had good NASH efficiencies ranged between 81.2 and 52 % for
 470 $NASH_{5cm}$ and between 76.3 and 11% for $NASH_{40 cm}$, thus showing that the MHYSAN model is able to
 471 correctly reproduce the SM. Validation of calibrated output SM was based on comparison over control
 472 plots with manual thetaprobe measurements and SM products obtained by SAR image processing.
 473 These comparisons were made on the basis of texture similarities between continuous probes and
 474 control plots. The results have a bias of approximately 1.06 and 0.63, and an RMSE equal to 3.38% and

475 6.11%, for the ground volumetric SM determined using manual thetaprobe and SAR moisture maps,
476 respectively.

477 The model was then calibrated using SAR SM maps retrieved on seven different dates ranging over two
478 months and was then validated using moisture data recorded at continuous probe stations during 15
479 months. We show that the model performs well with NASH efficiencies ranged between 76.7 and 89%,
480 thus demonstrating that SAR data can actually be used to calibrate SM models without requiring
481 ground data. High agreement is observed between calibrated model and continuous thetaprobe
482 measurements. These results show that a simple SM model combined this SAR images acquired
483 for contrasted moisture condition may allow estimates of daily SM. An optimal use of this
484 approach could be achieved by using moisture data collected at different times of the year, during the
485 rainy season and the dry season, since the model's performance will necessarily vary for different types
486 of case study. The study presented here should be extended to other areas, in particular those
487 presenting other soil types (covered soils, degraded soils ...). Moreover, progress in the
488 parameterization of this model could benefit from a more varied range of SAR data.

489 The main limitation relies in the representativity of the meteorological forcing used. Indeed, if
490 rainfall data is not reliable, a frequent configuration in semi arid areas, then the model although
491 locally well calibrated will not be able to work correctly. In this case the solution would be to use
492 remote sensing not only to calibrate the model, but to monitor rainfall and the SM themselves.
493 This opportunity is about to be offered in the coming month thanks to the Sentinel-1 mission
494 which represent a considerable breakthrough providing frequent and free high resolution SAR
495 data all over the world. In future research, we plan to optimize and apply this approach to the case of
496 Sentinel1 SAR data, allowing moisture estimations to be made at a higher repeat rate, over longer
497 periods of time.

498 **Author Contributions**

499 Azza Gorrab and Vincent Simonneaux: data processing; data analysis and interpretation of results.

500 Mehrez Zribi: SAR data analysis and interpretation of results.
501 Sameh Saadi: data processing.
502 Nicolas Baghdadi: SAR data analysis.
503 Zohra Lili-Chabaane: organization of experimental campaigns.
504 Pascal Fanise: site instrumentation.

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