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- 1
- 2 Effect of coupling excess pore pressure and soil deformation on nonlinear SSI in liquefiable
- 3 soil deposits
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- 10
- 11
- 12 Abstract
- 13 The current seismic design philosophy is based on nonlinear behavior of structures where the
- 14 foundation soil is often simplified by a modification of the input acceleration depending on
- 15 the expected site effects. The latter are generally limited to depend on the shear-wave
- 16 velocity profile or a classification of the site. Findings presented in this work illustrate the
- 17 importance of accounting for both soil nonlinearity due to seismic liquefaction and for soil-
- 18 structure interaction when dealing with liquefiable soil deposits.
- 19 This paper concerns the assessment of the effect of excess pore pressure (Δp_w) and
- 20 deformation for the nonlinear response of liquefiable soils on the structure's performance.
- 21 For this purpose a coupled Δp_w and soil deformation (CPD) analysis is used to represent the
- soil behavior. A mechanical-equivalent fully drained decoupled (DPD) analysis is also
- 23 performed. The differences between the analyses on different engineering demand parameters
- are evaluated. The results allow to identify and to quantify the differences between the
- analyses. Thus, it is possible to establish the situations for which the fully drained analysis
- 26 might tend to overestimate or underestimate the structure's demand.
- 27
- 28 Keywords: Seismic liquefaction ; Effective stress analysis ; Soil-structure interaction ;
- 29 Nonlinearity
- 30

31 1 INTRODUCTION

- 32 Sufficient evidence has been identified to proof the importance of site effects on the surface
- 33 ground motion. Still, in the earthquake engineering practice, the effects of nonlinear soil
- 34 behavior on the dynamic soil-structure interaction (SSI) are either neglected or simplified.
- 35 Moreover, when these effects are taken into account, in most cases the nonlinear soil
- 36 response is modeled with fully drained analysis that do not account for the excess pore
- 37 pressure (Δp_w) generation which controls the behavior of liquefiable soils. In contrast,
- 38 coupled analysis allows the modeling of the generation, redistribution and eventual
- 39 dissipation of Δp_w during and after earthquake shaking. While small or no volume change
- 40 associated with shear strain is presented, use of fully drained analysis may be justified. For
- 41 typical liquefiable soils at relatively shallow depths, a threshold shear strain below which no
- 42 Δp_w will develop has been identified at about 10 $^{\$4}$ (Drenevich and Richart 1970; Dobry and
- 43 Swiger 1979; Dobry et al. 1982). Above this threshold effective mean stress changes which
- 44 will affect the material properties. In such situations, coupled effective stress analysis seem
- 45 more appropriate (Yoshida and Iai 1998).
- 46
- 47 Recent studies, performed by Hartvigsen (2007), Yoshida (2013) and Montoya-Nougera and
- 48 Lopez-Caballero (2016) have evaluated the effects of coupling Δp_w and deformation on the
- soil behavior. In these studies, focus was given mainly to the effects on the ground motion
- 50 amplitude and frequency content. A summary of this research is briefly presented in the

- 51 following section. Concerning peak ground acceleration (PGA), all studies agree that
- 52 accounting for Δp_w will in general incur in lower values; thus without it the results will be
- 53 conservative. However, regarding the response spectra of acceleration (PSA), higher values
- 54 could be presented for long periods; which will be prejudicial for flexible buildings. All of
- these analyses have been performed in free-field 1D conditions and these effects have not
- 56 been analyzed on the performance of structures founded on cohesionless soils.
- 57
- 58 The aim of this work is to assess the effects of Δp_w generation on the performance of a
- 59 structure founded on liquefiable soil. For this purpose a nonlinear 2D soil-structure
- 60 interaction (SSI) model is analyzed under a wide range of unscaled earthquake signals. Two
- 61 structures with different predominant periods are used in order to account for different cases
- 62 of SSI. In the interest of quantifying the effects, two mechanically-equivalent models -one 63 with coupled Δp_w and soil deformation (CPD) and one fully drained (DPD) - were performed
- 64 with the same effective-stress analysis. Three aspects were evaluated on the structure: i) the
- response spectra of acceleration, ii) the relative settlement and iii) the inter-story drift.
- 66
- 67 1.1 Summary of previous findings
- In this work, the comparison is made between analyses with and without Δp_w in the interest
- 69 of evaluating solely the effect of coupling Δp_w and deformation. To address this subject, only
- a limited number of studies have been published. Each study used a different technique but in
- all, the fundamental variation is in the presence or lack of Δp_w . For clarity the two analyses
- 72 will be referred to as CPD and DPD.
- 73

74 Hartvigsen (2007) performed a series of CPD and DPD analyses of 1D wave propagation in 75 different soil columns and subjected to a variety of earthquake motions. The main 76 conclusions of the parametric study were also published by Kramer et al. (2011). In total, 77 nine 20-m thick soil profiles with varying depths of liquefiable soil were subjected to 139 78 input motions. The model used is written in effective stresses but for the DPD analysis, the 79 bulk modulus of the pore fluid was reduced to a very low value. Thus, while the weight of the 80 water contributes to the dynamic soil response (i.e. the inertial effect), there is no generation 81 of Δp_w . As a result, they presented a correction function for the surface PSA obtained by the ratio of CPD and DPD analyses. This correction, called the response spectra ratio (RSR =82 PSA^{CPD}/PSA^{DPD}), is a function of period and of the loading parameter (L) that is the inverse 83 84 of the factor of safety (FS) defined by the cyclic stress approach (Seed and Idriss 1971). RSR 85 can then be applied to the PSA values obtained with a total stress analysis to obtain a more 86 accurate response spectrum for liquefiable soils. Among the main features of this factor is 87 that even for very high FS, an amplification is evidenced -i.e. RSR > 1 - above a certain 88 period that increases as FS decreases. Interestingly, as FS decreases a peak of amplification 89 and of deamplification evolves. The combination of the mid-period deamplification trough 90 and long period amplification evidences the shift to low frequencies that occurs as a result of 91 soft-site amplification (Beresnev and Wen 1996). For the lowest liquefaction resistance 92 shown (FS=0.5), maximum RSR is approximately 1.3 at T \approx 10s and the minimum is 0.3 at 93 T \approx 0.5s. A regression analysis was used to obtain RSR but the correlation between the 94 residuals was low, hence the applicability of the function is unlikely. Additionally, the use of 95 a loading parameter reduces the analysis to a simplified procedure where the input motion 96 variability is only expressed by PGA and the magnitude scaling factor while the soil response 97 is only described by the SPT blow count and the reduction factor. 98

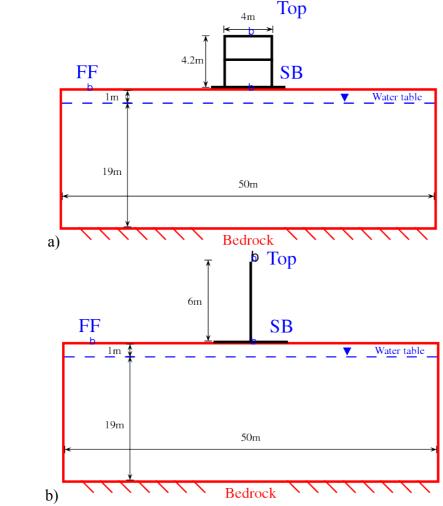
99 Similarly, Yoshida (2013) compared the CPD and DPD analyses. A total of 268 sites were 100 subjected to 11 earthquake motions. Again the only difference between the analyses is the

- 101 consideration of excess pore water pressure generation or not; however, no information on
- 102 how this was performed was stated. The comparison was focused on five frequently used
- 103 intensity measures of the surface time history: the peak acceleration (PGA), peak velocity
- 104 (PGV), peak displacement (PGD), instrumental seismic intensity (I_{JMA}) and spectral intensity 105 (SI). The PCA results from the CPD analysis many equal to the selection of the second secon
- 105 (SI). The PGA results from the CPD analysis were consistently smaller than the ones
- 106 obtained by the DPD one. Whereas for PGD, the CPD results were greater, which could
- 107 affect the design of underground structures such as piles and pipelines. The differences
- 108 between the analyses were smaller for the other intensity measures. Again, the program used 109 for these analyses only took into account the SPT blow count to describe the soil behavior. In
- 107 for mese analyses only took into account the SFT blow count to describe the soft behavior. If 110 contrast with Hartvigsen results, no clear trend between the two analyses was identified.
- 111 possibly due to the great variability of sites tested, some of those with no liquefiable soil.
- 112
- 113 Gingery et al. (2014) followed a similar procedure as that of Hartvigsen (2007) but applied to
- 114 ground motion prediction equations (GMPEs) that do not account for liquefaction. The four
- 115 GMPEs used were the updated attenuation relationships for the western U.S. from the Next
- 116 Generation Attenuation (NGA) project (Chiou et al. 2008) that accounted for soil conditions.
- 117 An amplification function (AF) for each GMPE was calculated from the logarithmic ratio of
- 118 PSA of recorded motions in 19 liquefiable soil deposits and the evaluated NGA GMPE, i.e.
- 119 $\ln(AF) = \ln(PSA^{\text{rec}}/PSA^{\text{NGA}})$. The correction functions presented in general a similar trend
- 120 as the RSR proposed by Hartvigsen (2007) but with higher maximums and minimums;
- although these factors are hard to compare, as they are applied to different analyses (i.e. CPD
 vs DPD and measured vs. GMPEs). However, an interesting aspect of these results is that
- 123 added to the known long period amplification, a second amplification was observed for short
- 124 periods (around T \leq 0.05 seconds) which could be the result of acceleration spikes that occur
- 125 in association with the dilatational part of liquefaction phase transformation behavior.
- 126
- 127 Finally, the work presented by Montoya-Noguera and Lopez-Caballero (2016) also analyzed 128 the effect of coupling Δp_w and soil deformation on 1D wave propagation. Besides evaluating 129 PSA and other intensity measures at the surface; a detailed analyses of time evolution and 130 maximum profiles was also presented. Concerning PSA, the CPD results present an amplification in long periods and also at periods around 0.05s, as evidenced by Hartvigsen 131 132 (2007). The differences between CPD and DPD response spectra increase with the amount of 133 liquefied soil in the deposit. One interesting finding was that although for most motions 134 tested PGA is greater for the DPD analysis, some cases present lower values, even down to 135 40% smaller. In contrast, for the Arias intensity of surface acceleration and the co-seismic 136 settlement, DPD values were up to six times greater than CPD ones. Regarding the soil 137 profile, clear relations were found between acceleration, shear strain and liquefaction ratio for 138 the CPD analysis; however, shear strains evolution with depth do not relate with acceleration 139 in the DPD analysis. It should be mentioned that this paper was the first phase of a larger 140 study and that the present work is the scale up to a 2D more complex model. To the best 141 knowledge of authors, no study has been published that accounts for the effects of coupling Δp_w and soil deformation on SSI. While PGA and other intensity measures can be lower with 142 143 CPD analysis in 1D soil profiles, the added effect of the 2D pore pressure's migration and 144 distribution, and of the structure's load and seismic performance, it could be prejudicial for 145 the analysis.
- 146

147 2 NUMERICAL MODEL

- 148 Two soil-structure models are considered in this work. They consist of reinforced concrete
- 149 (RC) buildings with a shallow rigid foundation, standing on saturated cohesionless soil. A
- 150 schema of the models is shown in Figure 1. One structure is modeled as an RC frame of one

- 151 span and two stories and the other is a single-degree-of-freedom (SDOF). The dynamic
- 152 performance of the structures is different as they have different height, weight and
- 153 predominant periods. Both structures lay on a 6m rigid foundation. All structural elements are
- elasto-plastic. Concerning the soil model, a 50m wide and 20m thick deposit of loose-tomedium (LMS) sand is overlaying an elastic bedrock. The shear modulus increases with
- medium (LMS) sand is overlaying an elastic bedrock. The shear modulus increases v depth and the equivalent shear wave velocity of the first 20m ($V_{s,20}$) is 200 m/s. The
- fundamental elastic frequency (f_0) of the soil profile, calculated with a low-strain frequency
- 158 analysis, is equal to 2.63Hz. An elastoplastic multi-mechanism model is used to represent the
- 159 soil behavior. Under the deposit, an engineering bedrock representing a half-space medium is
- 160 modeled with an isotropic linear elastic behavior and a shear wave velocity (V_s) equal to
- 161 550m/s. The ground water table is located 1m below the surface.
- 162





- 165 Figure 1: Schema of the numerical model for a) B01 and b) T040
- 166
- 167 2.1 Finite element model
- 168 As the soil is assumed to be horizontally homogeneous, a 2D finite element computation was
- 169 performed. The general purpose finite element code GEFDyn (Aubry and Modaressi 1996)
- 170 was used. The saturated soil was modeled using quadrilateral isoparametric elements with
- 171 eight nodes for both solid displacements and fluid pressures. The soil model is 20m depth,
- 172 50m wide. The size of the elements is $0.5 \times 0.5 \text{m}^2$, which is in agreement with the suggestions
- 173 made by Foerster and Modaressi (2007) to prevent numerical dispersion even for strong
- 174 motion excitations. For a maximum frequency of 15Hz (of engineering interest in this study)
- and a minimum initial V_s of 135m/s (at the surface), a minimum of 36 points per wavelength

176 is allowed in the elastic domain. The number of points is high, although it will decrease as the

- soil softens and the V_s decreases. For the time discretization in the dynamic analysis, an
- 178 implicit Newmark numerical integration scheme is used with parameters $\gamma_N = 0.611$ and $\beta_N = 0.301$. This induces a minimal numerical damping that affects principally the elastic response
- 0.301. This induces a minimal numerical damping that affects principally the elastic responseof the model, but allows an optimal high-frequency dissipation with minimal low-frequency
- 181 impact (Hughes, 2000; Montova-Noguera and Lopez-Caballero 2016). To take into account
- the interaction effects between the structure and the soil, a modified width plain-strain
- 183 condition was asumed in the model. This approach was developed and verified with 3D
- 184 models by Saez et al. (2013). In this case an out-of-plane dimension of 4m is used for the soil 185 profile.
- 186

187 2.1.1 Coupled and Decoupled dynamic approach

188 A coupled dynamic approach derived from the $u - p_w$ formulation of the Biot's generalized 189 consolidation theory (Zienkiewicz and Shiomi 1984; Zienkiewicz and Taylor 1991) was

introduced in the code by Modaressi (1987). This formulation consists of neglecting fluid

acceleration terms and its convective terms so that the unknown variables remain the

displacement of the solid \boldsymbol{u} and the pore water pressure $p_{\boldsymbol{w}}$. As further simplifications, soil

193 grain compressibility is assumed to be null and thermal effects are ignored. The behavior of

the solid skeleton is derived assuming the principle of effective stress as proposed by

195 Terzaghi (1943), where the total stress tensor ($\boldsymbol{\sigma}$) is separated into two components: the 196 effective stress tensor ($\boldsymbol{\sigma}'$) and the pore pressure (p_w). Which reads: $\boldsymbol{\sigma} = \boldsymbol{\sigma}' - p_w \boldsymbol{I}$ with \boldsymbol{I} the 197 identity second order tensor. Under such hypotheses the set of governing equations is:

- identity second order tensor. Under such hypotheses the set of governing equations is:
- 199

Overall equilibrium for the soil-fluid mixture

- 200
- 201 202

 $\operatorname{div}\boldsymbol{\sigma}' - \operatorname{grad}(p_w) + \rho \boldsymbol{g} = \rho \ddot{\boldsymbol{u}} \qquad (1)$

where ρ is the total average unit mass ($\rho = n\rho_w + (1 - n)\rho_s$); *n* is the soil porosity; ρ_w , the fluid mass; ρ_s , the soil particle mass; *g*, the gravity acceleration vector and *u*, the solid skeleton displacement.

Equilibrium of water and flow conservation equation using generalized Darcy's law.
 Assuming each phase as homogeneous:

210

$$\operatorname{div} \dot{\boldsymbol{u}} - \operatorname{div}(\boldsymbol{K}(\operatorname{grad}(p_w) - \rho_w \boldsymbol{g})) - \operatorname{div}(\boldsymbol{K}\rho_w \ddot{\boldsymbol{u}}) + \frac{p_w}{Q} = 0 \quad (2)$$

211 where **K** is the permeability tensor defined by $\mathbf{K} = \mathbf{\kappa} / \rho_w \mathbf{g}$, $\mathbf{\kappa}$ being the kinematic

212 permeability tensor, and Q is the compressibility parameter $(Q^{-1} = n/K_w + (1 - n)/K_s)$,

213 K_w and K_s being the fluid and solid compressibility, respectively.

214

215 Note that the pore water pressure generation and dissipation will depend on the permeability 216 tensor and the compressibility parameter. Hence, the DPD analysis can be done by either 217 reducing the compressibility to nearly zero as was done by Hartvigsen (2007), or by increasing the permeability to infinity. In this study another approach was chosen. It consists 218 219 in keeping the same inertial effects, while no excess pore pressure is generated. For the 220 inertial effects, the DPD analysis has a total unit mass equal to the coupled model, so the 221 weight of the water contributes to the dynamic soil response (equation 1). Thus, in the DPD 222 analysis the pore water pressures are computed based on a fixed water table level. It is worth 223 noting that both CPD and DPD are performed with effective-stress analysis and with the 224 same constitutive model.

- 225
- 226 2.1.2 Boundary conditions

227 Concerning boundary conditions, as the signal propagation is one-dimensional and as the

- response of an infinite semi-space is modeled, equivalent boundaries have been imposed on
- the lateral nodes (i.e. the normal stress on these boundaries remains constant and the
- displacements of nodes at the same depth in two opposite sides are the same in all directions)(Lopez-Caballero and Modaressi 2011). As the lateral limits of the problem are considered to
- (Lopez-Caballero and Modaressi 2011). As the lateral limits of the problem are considered to
 be far enough from the structure in the middle of the model, periodic conditions are verified.
- For the bedrock's boundary condition, paraxial elements simulating "deformable unbounded
- elastic bedrock" have been used (Modaressi and Benzenati 1994). The paraxial elements
- efficiently evacuate outgoing (diffracting) waves in a local domain. While the vertically
- incident shear waves, defined at the outcropping bedrock, are introduced into the base of the
- model after deconvolution. Thus, the obtained movement at the bedrock is composed of bothincident and reflected waves.
- 239
- For the CPD analysis, during the dynamic loading, p_w are allowed to change below the
- groundwater table as a result of soil contraction and dilation due to shear strains. For the
- bedrock's boundary, the pore pressure conditions are assumed to be impervious. Therefore,
- no flux occurs across the interface boundary between the studied domain and the underlying
- semi-infinite space.
- 245
- 246 2.2 Soil Model
- 247 The soil deposit of cohesionless sand presents a maximum shear modulus (G_{max}) profile
- 248 dependent on the mean effective stress (p'), as follows:
- 249

$$G_{max} = G_{ref} \left(\frac{p'}{p'_{ref}}\right)^{n_e} (3)$$

250

251 where G_{ref} is the shear modulus at the reference stress (p'_{ref}) and n_e is the degree of

nonlinearity. In this case, G_{ref} equals to 290MPa, p'_{ref} to 1MPa and n_e to 0.5. Thus, at free field G_{max} increases with depth as shown in Figure 2. The ground water table is placed 1m below the surface and for this superficial layer, G_{max} is constant (i.e. $n_e = 0$). The engineering bedrock is assumed to be deformable. It has an isotropic linear elastic behavior with a shearwave velocity (V_s) equal to 1700m/s and a shear modulus (G) of 5.8 GPa. The impedance ratio between the bedrock and the deposit (I) is 7.8, evaluated as $I = (V_s^r \rho^r)/(V_s^s \rho^s)$, where

superscripts r and s denote bedrock and bottom of the soil deposit. This value is sufficiently

259 large to assume an elastic behavior of the engineering bedrock compared to the soil deposit.

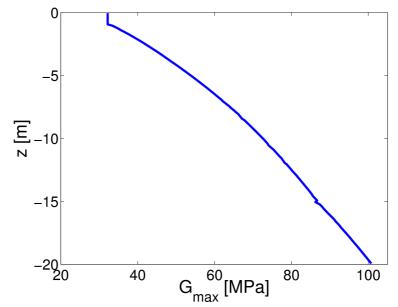


Figure 2: Initial shear modulus profile at free-field

263

264 2.2.1 Soil constitutive model

The elastoplastic multi-mechanism model used was developed at CentraleSupélec, formerly called École Centrale Paris (ECP), in the early 80s (Aubry et al. 1985; Modaressi 1987) and has been improved thereafter. The family of ECP models has been validated in a number of studies to simulate different kinds of loadings: seismic soil response of vertical arrays (Foerster and Modaressi 2007b; Regnier et al. 2015b), seismic response of soil structures (Sica et al. 2008) and pile installation (Berenguer 2014) among others.

271 The model uses a Coulomb type failure criterion and follows the critical-state concept. It can 272 take into account a large range of deformations due to the decomposition into three domains 273 (pseudo-elastic, hysteretic and mobilized) and the evolution of hardening based on the plastic 274 strain. To model the cyclic behavior it uses a kinematic hardening which relies on the state 275 variables at the last load reversal. For a complete description of the model refer to Aubry et 276 al. (1982), Hujeux (1985), and Lopez-Caballero and Modaressi-Farahmand-Razavi (2010) 277 among others. The soil model parameters were determined with the procedure defined by 278 Lopez-Caballero et al. (2007) and are found in Montoya-Noguera and Lopez-Caballero 279 (2016).

279

281 2.3 Structural model

282 Two models were used in order to analyze the effect of the coupling Δp_w and soil

283 deformation for different predominant periods. The structures used will be called B01 and

T040 and are reinforced concrete buildings with different size, weight and stiffness. In order

to simulate the B01 structure, plastic hinge beam-column elements are used which take into

account axial force (*P*) and bending moment (*M*) interaction (Prakash et al. 1993). This structure is a large-scale, one-span, two-story frame model proposed by Vechio and Emara

288 (1992). In contrast, the T040 is a single-degree-of-freedom (SDOF) modeled with an elastic

perfectly plastic behavior and is equivalent to a one-span, three-story building (Saez et al.

290 2013). It is a simplified model of a moment frame mid-rise structure according to the

building type classification of HAZUS-MH MR3 (2003). This additional structure is used in

this study to highlight the effects of the soil behavior in the structure performance near

resonance. The main characteristics of both structures are shown in Table 1.

Property	B01	T040
Total height [m]	4.2	6
Width [m]	4	N/A
Mass [ton]	45	120
Fundamental fixed-base period T_0 [s]	0.24	0.40

297 Table 1: Structures' properties

298

299 The structure foundation is modeled as a rigid block of 10cm thick and 6m wide. Between the 300 foundation and the soil, interface elements are used to allow relative movement of the 301 structure with respect to the soil, in order to avoid the traction effect. These elements follow a

302 Coulomb-type plastic criterion.

303

304 The building's weight affects the stress state (horizontal, vertical and shear) and also the

305 volumetric deformations, hence it affects the maximum shear modulus (G_{max}) defined

previously by equation (3). Thus, the effect of the structure's inertial load on the soil behavior 306 307

is seen on the differences in G_{max} along the horizontal axis which is shown in Figure 3 for 308 both structures. Note how the soil under the building presents higher values compared to free-

309 field for shallow depths until around 6m but for deeper soil, the G_{max} values are decreased.

310 Additionally, because T040 is heavier, this increase and decrease are greater and affect lower

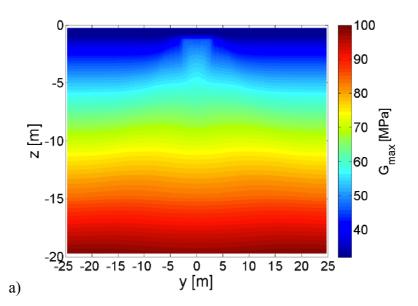
311 depths. As the coefficient of earth pressure at rest (k_0) also increases with the building load,

312 the surrounding soil is stiffened but without the effect of the shear stress. Thus, a slight

313 increase in G_{max} is visible in the soil on this region, specially visible below 10m in T040 model (Figure 3b). It is worth noting that areas where the G_{max} increased might present

314 315 higher liquefaction resistance.

316



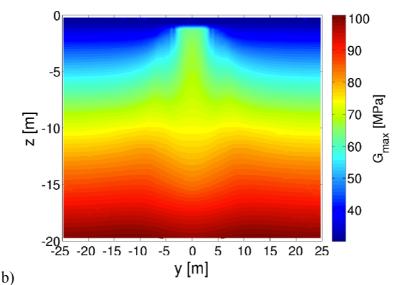


Figure 3: Shear modulus G_{max} distribution in the deposit before shaking for a) B01 and b) T040

321

318

Concerning the initial seismic behavior, a scaled motion with a very low amplitude (i.e. 322 323 PHA $\approx 10^{-5} g$) was used to evaluate the pseudo-elastic behavior of both soil and structure. Figure 4 shows the transfer functions (|TF|) - with fixed base and with soil-structure 324 interaction (SSI) effects (top/FF) for the two structures. In addition, |TF| of the soil deposit 325 326 (FF/bedrock) is also shown. Firstly, it is interesting to note that, even if B01 has two stories, only one resonant frequency (f_{str}^{FB}) is observed - as the other one is above 15Hz. Hence both structures behave as SDOFs. The SSI effects consist of a shift to lower frequencies due to the 327 328 329 flexibility of the foundation soil and a deamplification due to the material and radiation 330 damping added by the soil (Mylonakis and Gazetas 2000). As expected, structure B01 being 331 more rigid presents a higher interaction with the soil foundation; hence, the deamplification 332 and the frequency shift are greater. Hence, the relative position of the fundamental frequency 333 of the soil with respect to that of the structure and the frequency content of the input motion 334 is very important for the inelastic dynamic SSI effects (Saez et al. 2013). Thus, as T040 main 335 frequency is lower than that of the soil, higher SSI effects are expected when nonlinear soil 336 degradation causes a shift of the soil frequency to lower values.

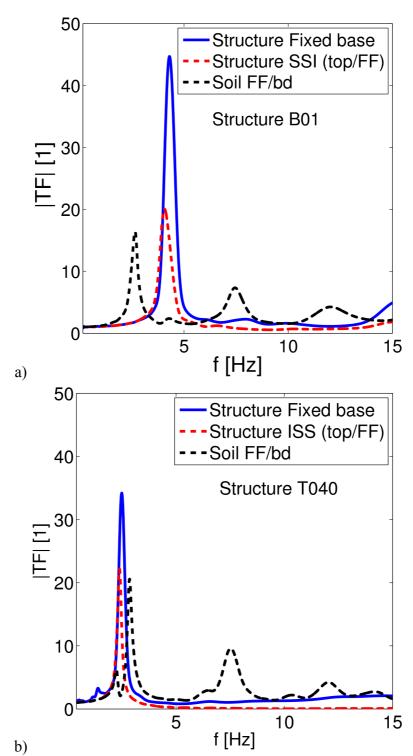






Figure 4: Transfer function of the free-field and the structure for a) B01 and b) T040

342 2.4 Input earthquake motions

343 Ninety unscaled records were chosen from the Pacific Earthquake Engineering Research

344 Center (PEER) database. The signals used were recorded near the source - with a site-to-

source distance below 70km- and in dense soil conditions - i.e. 30m averaged shear-wave

346 velocity $(V_{s 30})$ above 600m/s. These signals are supposed to have minimal noise and are

347 appropriate for an outcropping bedrock condition. The events range between 6.2 and 7.7 in

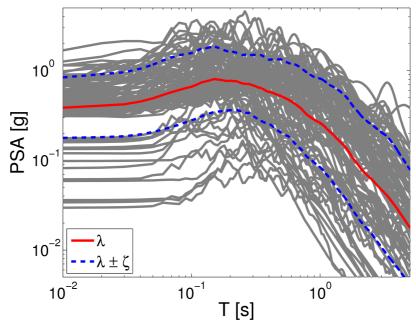
- 348 moment magnitude.
- 349

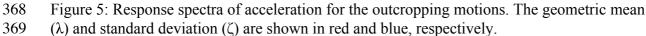
- 350 The statistics of some earthquake parameters calculated at outcropping conditions are shown in Table 2. These intensity measures are peak horizontal acceleration (PHA), peak ground 351 velocity (PGV), mean period (T_m) , predominant period (T_p) , period of equivalent harmonic 352 wave $(T_{V/A})$, Arias intensity (I_A) , significant duration (D_{5-95}) , root-mean-square intensity 353 (I_{RMS}) , spectral intensity (SI) and specific energy density (SED). The coefficient of variation (CV) is high for all parameters and it is about 130% for I_A . A high variation in I_A is of great 354 355 356 importance given that after the sensitivity analysis performed by Lopez-Caballero and 357 Modaressi-Farahmand-Razavi (2010), it was proved to be the most influential input variable on the average liquefaction developed on the upper 10m of the deposit, known as $Q_{H=10m}$. 358 Figure 5 shows the response spectra of all the input earthquake motions; accelerations were 359 360 filtered to 20Hz and the spectral amplitude has a 5% structural damping. Similarly, a great 361 variation is presented on the response spectra.
- 362

363 Table 2: Earthquake characteristics

Parameter	Range	Mean	CV [%]	Median
PHA [g]	0.03 % 1.16	0.34	85	0.26
PGV [cm/s]	3.15 % 121	30.52	92	21.80
T_m [s]	0.22 & 0.87	0.49	31	0.47
$T_p[s]$	0.09 % 0.65	0.30	51	0.25
$T_{V/A}$ [s]	0.21 % 0.85	0.48	35	0.48
I_A [m/s]	0.02 % 11.8	2.17	136	0.64
D ₅₋₉₅ [s]	4.12 8 36.47	17.04	58	14.59
I_{RMS} [m/s ²]	0.04 \$ 1.48	0.46	79	0.41
<i>SI</i> [m]	0.04 % 1.16	0.37	80	0.30
$SED [cm^2/s]$	28.7 \$ 34098	2705	241	499

365 366





371 3 ANALYSIS AND RESULTS

The effect of coupling Δp_w and soil deformations on a soil-structure model is highly complex and will affect several aspects of the response. First the analysis for one input motion will be shown and then some results concerning all the motions will be addressed.

375

As recalled before, Montoya-Noguera and Lopez-Caballero (2016) have already analyzed the effects of such coupling on the nonlinear seismic soil response. In that study, a 1D model of the same soil deposit was used and compared to a denser soil deposit. As differences in the response are given by the liquefaction apparition and the pore pressure generation, in this

- 380 study, only the more liquefiable soil is used for the SSI model.
- 381
- 382 As explained in section

383 2.1.1, the main difference in the analyses will be given by the strains due to pore pressure

- 384 generation. As the latter increases, the difference in the soil deposit in terms of acceleration,
- 385 shear strain and settlement increases. Figure 6 and Figure 7 show the time histories of these 386 parameters for one motion tested.
- 386 parameters f 387
- 388 First, in Figure 6 the evolution of the liquefaction ratio $(r_u = \Delta p_w / \sigma'_0)$ is shown for a profile 389 far from the structure -i.e. in free field. In this analysis, liquefaction is described as the 390 significant reduction of the effective stress and therefore accounts for both phenomena: true 391 *liquefaction* (when $r_u = 1.0$) and *cyclic mobility* (i.e. $0.8 < r_u < 1.0$ with development of 392 large strains) (Koutsourelakis et al. 2002; Popescu et al. 2006). Thus, liquefaction is said to 393 be triggered when r_{μ} equals 0.8. The location of liquefaction is dependent on the frequency 394 content and the soil stiffness evolution. In general, high frecuency accelerations tend to 395 liquefy shallow soil while low frequency ones tend to liquefy deeper soil (Popescu, 2002; 396 Lopez-Caballero and Modaressi-Farahmand-Razavi, 2008). Real motions have complex 397 frequency content that varies in time thus liquefaction can be triggered at different locations. 398 For the case shown in Figure 6, liquefaction is first triggered at shallow soil as initially the 399 motion contains primarily high frequency amplitudes, and then liquefaction appears in deeper 400 soil when the motion contains low frequency content. The pore pressure generation and 401 dissipation through depth evolves as the motion's frequency content as well as the soil 402 stiffness changes. The frequency content of the motion is modified due to pore-pressure generation as has been shown in previous studies (Kramer et al., 2015; Montova-Noguera and 403 404 Lopez-Caballero, 2016). Additionally, the soil stiffness is reduced in zones where 405 liquefaction is triggered first and pore-pressure might migrate to deeper aswell as shallower 406 depths. It can be noted that although the same soil properties are used throughout the deposit, 407 due to the increase in mean stress and the stress ratio difference, pore pressure generation 408 does not increase simultaneously through depth. Additionally, the time evolution of the 409 frequency content of the motion causes liquefaction at different depths in different instants. 410 For this motion, liquefaction first appears between 6 and 7m depth at around 8s, then it starts in two other deeper zones. After the predominant duration of the motion, i.e. at around 15s, 411 the pore pressure migrates to other depths. At the end of shaking, r_{μ} is almost evenly 412 413 distributed and it is still above 0.8 for depths between 5 and 15m.

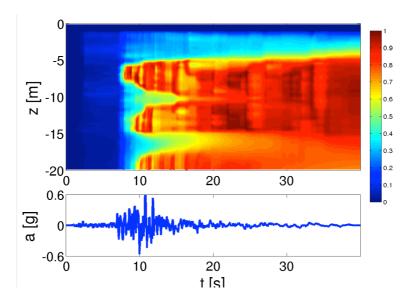
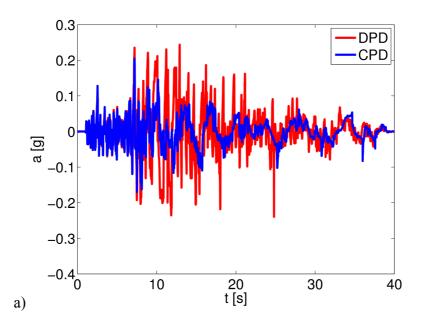


Figure 6: Time history liquefaction ratio at free field for one motion tested. The outcroppingacceleration time history is shown below.

419

420 The time history of the acceleration at the structure's base is shown in Figure 7 for both 421 analyses. With respect to the outcropping motion shown in the previous figure, the peak 422 amplitude is almost one third for the DPD model and is slightly lower for the CPD one. The 423 differences in time between the analyses is easily related to the liquefaction evolution with 424 time also shown previously. After the first liquefaction triggering at 8s, the responses start to 425 differ. The CPD model presents a shift towards low frequencies after approximately 10s, 426 while the DPD shows higher spikes at higher frequencies. Similarly, the relative settlement of 427 the structure with respect to free field $(|u_z|)$, shown in Figure 7, evolves differently starting from 8s. Due to the pore pressure migration, evidenced in Figure 6, differences in $|u_z|$ are 428 greater after the predominant duration of the motion and by the end of the shaking, the CPD 429 430 model presents results more than 4 times higher than the DPD.

431



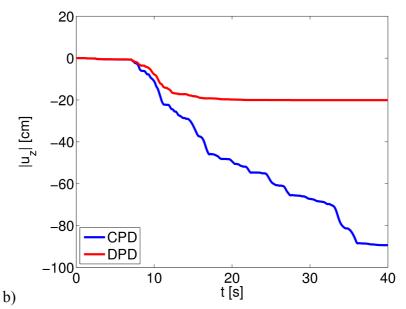
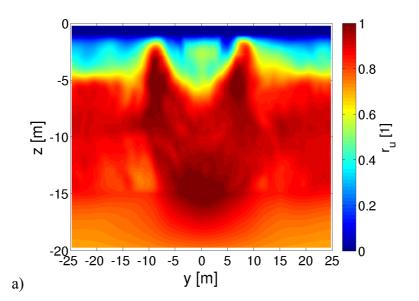


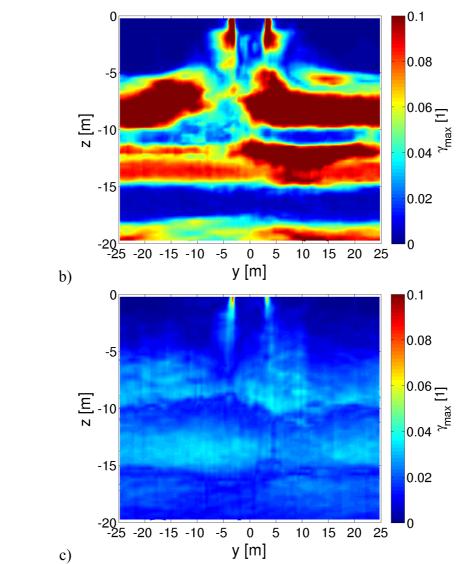
Figure 7: Time history analysis for one motion tested: a) Surface acceleration at structure's
base and b) relative settlement of the structure with respect to free field

436

437 Concerning the entire deposit an important issue is the building load and the effects on the 438 soil behavior. Figure 8 shows the liquefaction ratio at the end of shaking and the maximum 439 shear strain for all the deposit. As the soil under the structure is stiffened, liquefaction is not 440 presented there; however, around this area and because of the differences in the stress state, high r_u values appear beyond the structure's influence. On that account, the maximum shear 441 strains are higher for the CPD model; often twice the value of the DPD one. Furthermore, 442 443 while for the CPD model, the maximum values appear to be related to the places where 444 maximum r_u values are located; for DPD, the maximum values are more evenly distributed 445 through the deposit.

446





4	49
	-

Figure 8: Soil deposit analysis for one motion tested: a) Liquefaction ratio at the end of shaking and maximum shear strain for b) CPD and c) DPD models.

452

In terms of time history and in the entire deposit, the response for each motion varies greatly,
due to the differences in frequency, energy and duration content of the motion. Hence to
analyze all the motions tested, focus will be given to three engineering demand parameters:

456 (1) peak ground acceleration (PGA) at the structure's base, (2) co-seismic relative settlement

457 of the structure with respect to free field $(|u_z|)$ and (3) maximum inter-story drift (ISD).

458 These parameters are often used for seismic structure performance when SSI effects are taken

459 into account and are often used for numerical analysis.

460

461 To relate the differences between the CPD and DPD analyses with the level of liquefaction, 462 results are ranged by the liquefaction index $(Q_{H \cdot L})$. This parameter was firstly introduced in 463 1D by Shinozuka and Ohtomo (1989) and it is extended to a 2D model as:

464 465

$$Q_{H:L} = \frac{1}{H:L} \int_0^H \int_0^L r_{u, \text{ end}}(y, z) \mathrm{d}y \mathrm{d}z \tag{4}$$

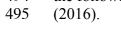
466 467

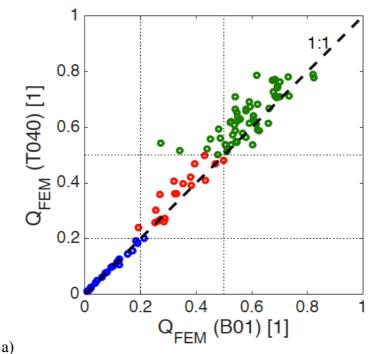
468 where $r_{u, \text{ end}}$ is the liquefaction ratio, previously defined, evaluated at the end of shaking.

469 When $Q_{H \cdot L}$ is equal to unity, it means that liquefaction is present throughout the thickness H

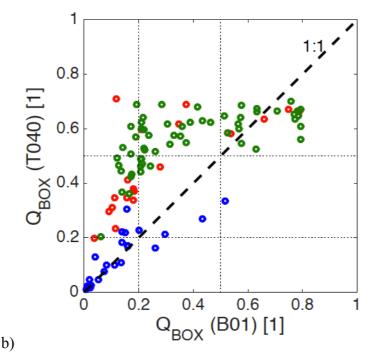
- 470 and the length L and thus gives information of the liquefaction ratio as well as the total 471 liquefactor L and L are a set of the structure L is the structure L is the structure L is the structure L and L are structure L is the structure L and L are structure L and L and L are structure at the structure L and L are structure at the structure L and L are structure at the st
- 471 liquefied area. As was seen previously, the structure has a significant effect on the
- 472 liquefaction distribution in the soil deposit. Hence different values of *H* and *L* were used to 473 evaluate $Q_{H \cdot L}$. Figure 9 compares the $Q_{H \cdot L}$ values between the models of the B01 and that of
- 474 the T040 structures for two sets of H and L values : a) H=20m and L=50m, which is the size
- 475 of the entire finite element model (FEM) and b) H=4m and L=20m, a box under the structure
- and below the water table level. Note that the results are divided in three groups by
- 477 liquefaction levels: low (for Q_{FEM} below 0.2), moderate (between 0.2 and 0.5) and high
- 478 (above 0.5). When the liquefaction index is evaluated throughout FEM, in Figure 9a, results
- are slightly higher with T040 but in average are fairly similar. This is to be expected since the
- 480 motions energy is the same and, while under the structure the soil has been modified, other
 481 areas will be affected, as was observed in Figure 8a. In general, the differences between the
- 482 Q_{FEM} results for the two models generally increase for higher Q_{FEM} . However, in average this
- 483 difference is less than 8%.
- 484

485 In contrast, the Q_{BOX} results shown in Figure 9b differ greatly between the two models. In 486 most cases, the area tested presented higher levels of liquefaction when the T040 structure is 487 used. Note that for the model with B01 structure, several cases present a Q_{BOX} value about 488 0.2, while for the same cases, Q_{BOX} in the T040 model range between 0.2 to 0.7. On the other 489 hand, in the T040 model, cases that presented Q_{BOX} values about 0.6, can present values 490 ranging from 0.1 to 0.8 in the B01 model. In other words, in the same area, three motions can 491 produce the same level of liquefaction in one model and on the other model, produce either 492 low, moderate or high levels. In order to have a better relation with the motions energy and 493 less influence on the structure used, the liquefaction levels defined by Q_{FEM} will be used in 494 the following section. For further details on this analysis please refer to Montoya-Noguera





496



498 Figure 9: Effect of the structure on the Liquefaction index $(Q_{H \cdot L})$ evaluated at: (a) the entire 499 deposit (Q_{FEM}) and at (b) a box below the structure of size $4x20 (Q_{BOX})$

500 501

502 3.1 Effect on the surface acceleration

503 The amplification (or deamplification) of an earthquake motion due to site effects has been 504 studied for many decades. Some researchers as Trifunac and Brady (1975) and Seed et al.

505 (1976), among others, focused on the correlations between distance from source, earthquake

506 magnitude and site conditions. In engineering practice, site amplification factors are often

507 used to take into account these effects. An example of these factors, is the pioneering work of

508 Idriss (1990) and Dickenson and Seed (1996) based on empirical measurements and

509 engineering judgment of ratios between the peak surface acceleration of a soft deposit (PGA)

510 and the peak horizontal acceleration at outcropping rock (PHA). Advanced numerical models

511 of seismic soil behavior are useful to analyze the nonlinear effects on the ground motion;

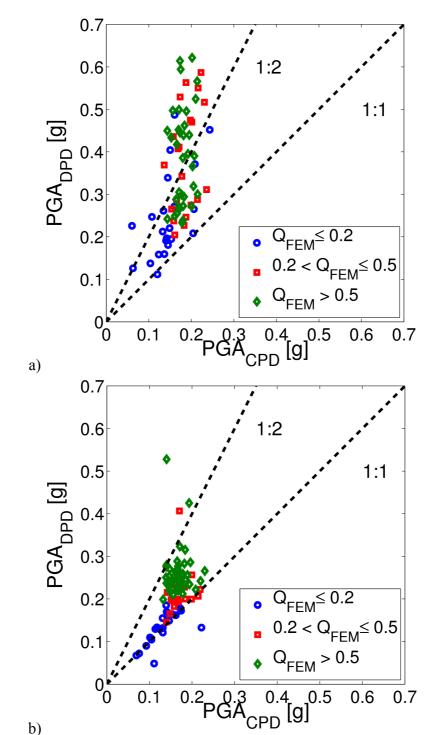
bowever if the site is susceptible to liquefaction, when no coupling of Δp_w and soil

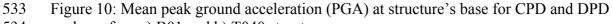
513 deformation is present, the model might largely overestimate the peak accelerations at 514 surface.

515

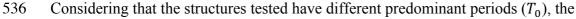
516 Concerning the peak ground acceleration (PGA) at the structure's base, Figure 10 shows the 517 comparison between the CPD and DPD values for both structures. For most motions tested 518 the coupling produces a deamplification on the acceleration as it accounts for soil softening 519 due to the pore pressure increase. However, for two motions with T040, where the value of 520 Q_{FEM} is low, the CPD results are greater. These values correspond to high frequency peaks related to the dilatation phase. In general, the differences between the analyses are higher and 521 more dispersive with the B01 structure, specially results for the DPD analysis are doubled for 522 523 this structure. CPD results of PGA are similar for both structures and appear to be limited by 524 the liquefaction triggering to a maximum value of about 0.25g. The structure weight has an 525 influence on the liquefaction susceptibility but does not seem to affect the PGA value with 526 CPD analysis. In contrast, DPD results of PGA are twice as big with B01 structure which is 527 lighter. As shown in Figure 7a, in the DPD analysis the acceleration at the structure base 528 presents high amplitude spikes at high frequencies which are controlled in the T040 model

- 529 because of the structure weight.
- 530





- 534 analyses for : a) B01 and b) T040 structures
- 535



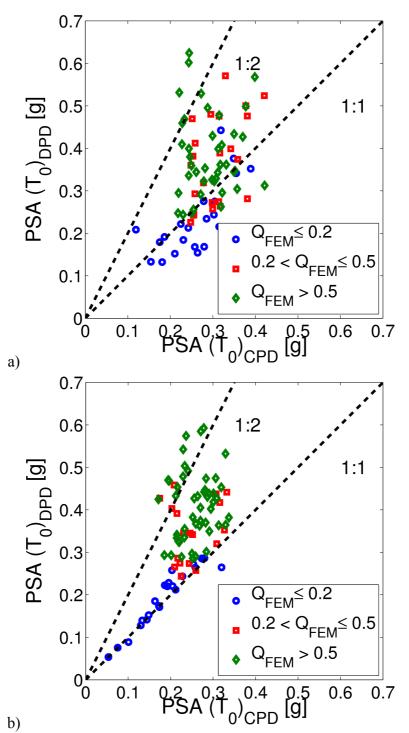
- 537 acceleration response spectra (*PSA*) is evaluated at each T_0 value and the comparison
- between CPD and DPD is shown in Figure Error! Reference source not found. As the T_0
- 539 value of T040 is near the fundamental elastic period of the soil, the behavior presents less
- 540 dispersion and higher *PSA* values for the decoupled model. On the contrary, with B01 higher
- 541 dispersion is evidenced specially for the CPD analysis. The combined effect of SSI and

542 liquefaction is highly variable. With this structure, for almost all cases with low levels of 543 liquefaction and even for some cases with intermediate and high levels, CPD results are

higher. Although with the majority of the motions, the results where greater with DPD

analysis. Hence, in general, as surface acceleration is concerned, the lack of coupling will

- 546 produce a conservative analysis.
- 547



548

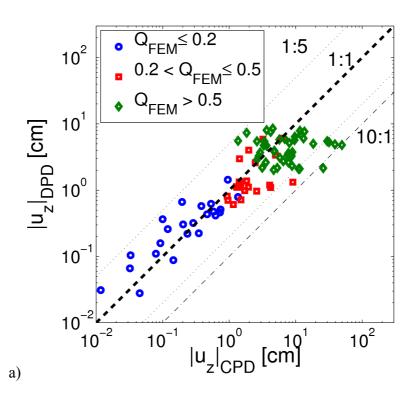
550 Figure 11: Comparison of CPD and DPD results for the response spectra of acceleration at

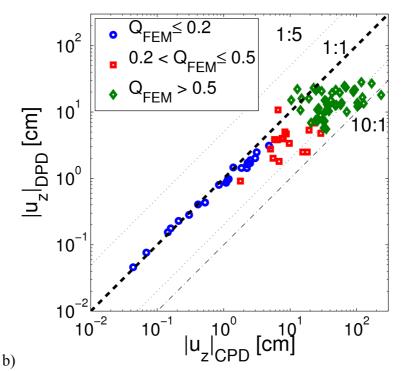
- structure's base evaluated at the predominant structure period: a) B01 and b) T040
- 552
- 553 3.2 Effect on the structure settlement
- 554 In contrast, regarding the relative settlement of the structure with respect to free-field ($|u_z|$),

- shown in Figure Error! Reference source not found., taking into account the effect of coupling in most cases will result in higher values. This could be prejudicial for the structure's performance. However, as for PSA, some motions presented lower values when CPD is used. Specially for low levels of liquefaction and with the B01 structure. In contract, when liquefaction levels are high and $|u_z|$ is the greatest, the differences between the analyses increase. Note that for some cases, the CPD results are about 10 times greater than the DPD ones.
- 562

As T040 is heavier, $|u_z|$ are more important and with CPD results are above 10cm for approximately half of the motions tested. This value corresponds to the limit for slight damage state of reinforced concrete frame buildings given by Bird et al. (2006). Above it, cracks in structural elements appear and damage has to be repaired. If no coupling was present, this fundamental aspect would be overseen and results will be unconservative or even dangerous for the structure.

569





571

572 Figure 12: Comparison of CPD and DPD results for the relative settlement with respect to

- 573 free-field: a) B01 and b) T040
- 574

575 3.3 Effect on the structure seismic demand

576 Regarding the seismic demand on the structure, the comparison of CPD and DPD results of

577 the maximum inter-story drift (ISD) is shown in Figure Error! Reference source not

578 **found.** This parameter is appropriate to show the effect on the drift in structures with

579 different height as it normalizes the maximum horizontal displacement evaluated at each

580 level by its corresponding height. It is interesting to note how the two structures present very

different results. For B01, the CPD values are greater than the DPD ones for almost all cases;while for T040, it is the contrary.

583

Recall that the SSI effect for the quasi-elastic behavior is more important for B01, as shown

585 in Figure 4. Hence, with this structure and for low levels of liquefaction the SSI effect is

586 greater than the coupling effect and ISD is higher with CPD analysis. But when the 587 liquefaction level increases, the coupling effect is more important as the soil will attenuate

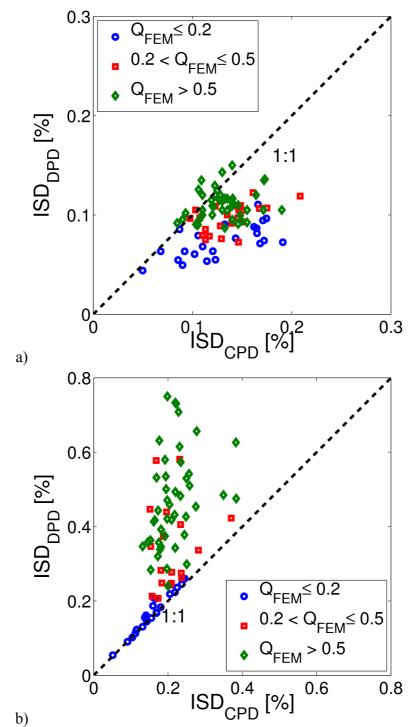
the motion and the structure drift with CPD will be reduced. Concerning T040, the values

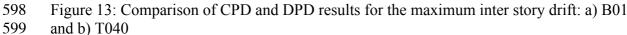
with the DPD analysis are more than doubled when Q_{FEM} is above 0.5, even four times

507 with the Dr D analysis are more than doubled when Q_{FEM} is above 0.5, even four times 590 greater for some cases. Additionally, a high dispersion is evidenced for these values. For

591 models of liquefiable soil where structure nonlinearity is taken into account but there is no

- 592 coupling of Δp_w with soil deformation, the response could be largely overestimated. This
- would lead to a conservative design. In contrast, when SSI effects are important, the lack of
- 594 coupling of Δp_w will lead to an unconservative or prejudicial conception.
- 595





599 600

597

Figure 14 shows the nonlinearity evolution of the soil - structure system by analyzing the (177) - (17

transfer function (|TF|) between the top floor and the free field (FF) for B01. This function takes into account the structure's performance as well as the SSL effects. Pagulta are represent

takes into account the structure's performance as well as the SSI effects. Results are ranged

by the peak horizontal acceleration (PHA) recorded at the outcropping rock. Additionally, the functional dependence of the scale dependence of the state of the structure in fine dependence of the scale dependence of the structure in fine dependence of the structure in fine dependence of the scale dependence of the s

fundamental elastic frequency of the soil deposit (f_0) and that of the structure in fixed

base condition (f_{str}^{FB}) are shown as reference. With DPD analysis, a lower amplitude of the

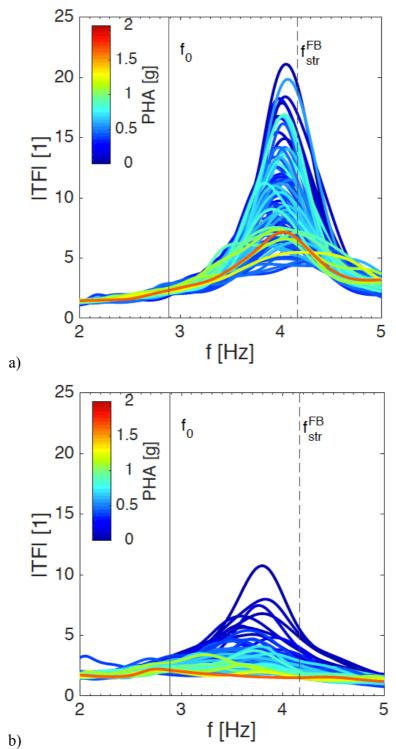
607 predominant frequency even for low PHA values. This deamplification drops drastically after

609 with CPD analysis the deamplification is smaller and almost no frequency shift is evidenced.

610 This can be explained by the liquefaction presented in the deposit that can isolate the SSI

611 effect between the surficial soil and the structure.

612



613

- Figure 14: Nonlinearity evolution at the structure's |*TF*| (Top/FF) for B01 with a) CPD and b)
 DPD analyses
- 617

- 618 3.4 Comparison with 1D models
- 619 Finally the effect of pore pressure generation on the surface acceleration is compared
- 620 between a 1D FF model and the 2D soil-structure model. When no soil-structure interaction

621 (SSI) is present, the wave propagation is evaluated on a soil column and the altered spectra of 622 acceleration is used on the structure's model. In Figure 15 the response spectra ratio (RSR) evaluated at the surface of a 1D model is compared to that of the base of each structure. In 623 this figure the effects of both the SSI and the coupling of Δp_w and soil deformation can be 624 625 analyzed. RSR is defined by:

626 627

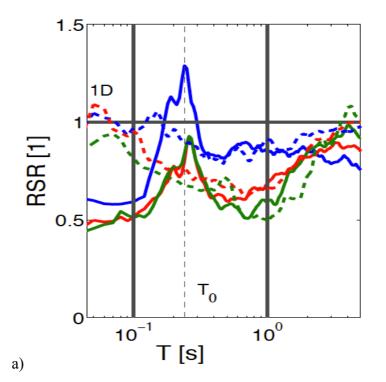
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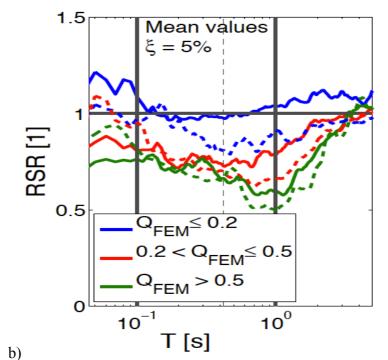
$$RSR(T) = PSA_{CPD}(T)/PSA_{DPD}(T)$$
(5)

629 The mean values for each liquefaction index level are shown in Figure 15. The results for the 1D model are shown in dashed lines and are the same in both figures, as no structure is 630 631 present. However, the results with the structures vary greatly. It seems that the SSI effect is 632 important for B01 while it is almost negligible for T040 - as 1D and 2D results are roughly 633 similar. Specially, at the structure's predominant period, RSR is affected for B01 (T_0 =0.24s) 634 where with low liquefaction levels the CPD amplification is even 25% higher than the DPD one; while for T040 no change is visible at this period ($T_0=0.4$ s). Differences between 1D and 635 2D results are greater for short periods, below 0.2s and more important for B01. Which 636 637 means that the coupling effects are greater when SSI effects are more important. However, even if RSR appears to be related to the liquefaction level, the mean values for high and 638 639 intermediate levels are similar in all the period range used and specially for B01 results. This 640 aspect is worth mentioning as it means that although liquefaction is not triggered, the pore 641 pressure migration due to the structure's effect on the soil modifies the acceleration response at the structure's base. Hence, a CPD analysis is preferred when modeling 2D SSI even if 642

643 liquefaction potential is low.

644





647 Figure 15: RSR at 1D model and at structure's base for: a) B01 and b) T040

648

649 4 CONCLUSIONS

650 A finite element analysis was used to investigate the effect of coupling excess pore pressure 651 and soil deformation on a soil-structure model. Two mechanically-equivalent analyses were 652 performed with 90 unscaled earthquake motions: one taking into account coupling (CPD) and 653 one fully-drained (DPD). The same effective-stress model was used for the calculations and 654 the initial elastic behavior was proved to be the same. The present study aimed to highlight the importance of accurately model liquefiable soils in order to improve performance-based 655 earthquake engineering (PBEE). One of the main findings of this study is that when models 656 657 are fully drained, less shear strains are developed hence the relative settlement of the structure is underestimated for most motions and both structures tested. Even if in free-field 658 659 (FF), DPD analysis presented higher settlement, the structure's weight affects the soil 660 behavior and hence the structure's settlement with respect to FF is in general underestimated with DPD models. Additionally, if the SSI effects are significant, i.e. when the predominant 661 662 period of the structure is near to that of the soil, the maximum ISD is consistently 663 underestimated by the DPD analysis. In this regard, the use of DPD models will not be recommended for a PBEE design. Two main effects are involved in this analysis: the 664 coupling of excess pore pressure and soil deformation and the interactions between the soil 665 666 deposit and the structure. These can be beneficial or detrimental for different EDPs but the 667 analysis should include both as it seems that the complex relation between them will vary for 668 each motion, soil and structure tested. 669

670 The relation of both SSI and CPD effects was shown to be highly complex. Thus, the effects

of CPD could be further evaluated for other soil deposits and other structures in order to
 increase the reliability of the results. In addition to the nonlinearity of the soil, the structure's

nonlinearity could be further enriched comprehending the evaluation of damage and failure.

674 The present study focused on the comparison between drained and coupled analyses,

however, it would be interesting to also compare the response of perfectly undrained analysis

available on several commercial softwares and performed by practitioners. More on this topic

677 will be analyzed in a future work Furthermore, some challenges are still to be acknowledged.

- 678 Comparisons of CPD and DPD models with vertical array data in liquefiable soils could be
- 679 helpful to better understand the importance of coupling excess pore pressure and
- 680 deformations. Additionally, physical modeling of structures founded on liquefiable soil could
- 681 be performed in shaking tables and centrifuge tests to further validate the relation between
- 682 both SSI and CPD effects.
- 683
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- 687
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