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► **To cite this version:**

Souleymane Kadri Harouna, Valérie Perrier. Homogeneous Dirichlet wavelets on the interval diagonalizing the derivative operator, and related applications. 2018. hal-01568431v2

**HAL Id: hal-01568431**

**<https://hal.science/hal-01568431v2>**

Preprint submitted on 12 Mar 2018 (v2), last revised 15 Feb 2019 (v3)

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# Wavelets linked by differentiation-integration on the unit interval and related applications

Kadri Harouna Souleymane · Perrier Valérie

**Abstract** This paper presents a new construction of biorthogonal multiresolution analyses of  $L^2(0, 1)$  linked by differentiation and integration. The arising wavelet basis is set to satisfy homogeneous Dirichlet boundary conditions, while this requirement is not necessary for the scaling function basis. This new wavelet basis allows to compute the solution of the Poisson equation only by a wavelet coefficient renormalization - like in Fourier domain - , which yields a linear complexity  $\mathcal{O}(N)$  for this problem. Fast algorithms are provided and illustrated by numerical examples.

**Keywords** Wavelet on the interval · Boundary condition · Poisson equation

## 1 Introduction

Since the pioneering work of Lemarié-Rieusset [15], due to their important role in the construction of divergence-free or curl-free wavelets, biorthogonal multiresolution analyses linked by differentiation and integration have been widely studied [14, 20, 22, 23]. The main purpose was to construct two multiresolution analyses of  $L^2(0, 1)$  provided by spaces  $V_j^1$  and  $V_j^0$  such that

$$\forall j, \quad \frac{d}{dx} V_j^1 = V_j^0. \quad (1)$$

Relation (1) should be interpreted as:  $\forall f \in V_j^1, f' \in V_j^0$  and  $\forall g \in V_j^0$ , there exists  $f \in V_j^1$  such that  $f' = g$ .

On the unit interval  $[0, 1]$ , with non periodic boundary conditions, such a construction was firstly introduced by Jouini and Lemarié-Rieusset [14]. They started

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with  $V_j^1$  as a *regular* multiresolution analysis reproducing polynomial at boundaries [1, 5, 12], with the scaling function  $\varphi^1$  and wavelet  $\psi^1$  generators that satisfy [15]:

$$(\varphi^1)'(x) = \varphi^0(x) - \varphi^0(x-1) \quad \text{and} \quad (\psi^1)' = 4\psi^0. \quad (2)$$

Jouini and Lemarié-Rieusset [14] used the orthogonal construction of [5] for the space  $V_j^1$ . They show that, from relation (2) and properly setting the integers parameters in the construction of  $V_j^1$ , one can deduce the space  $V_j^0$  that satisfies (1). In this case, the wavelet space  $W_j^0$  is defined by differentiating the wavelet basis of  $W_j^1$ :

$$W_j^0 = \text{span}\{\psi_{j,k}^0 := 2^{-j}(\psi_{j,k}^1)'\}.$$

The corresponding biorthogonal spaces  $(\tilde{V}_j^1, \tilde{V}_j^0)$  are respectively constructed again using integration by part [6]. However, the construction of [14] remains theoretical, for instance it is not easy to compute numerically the wavelet filter of  $\psi_{j,k}^0$  and  $\tilde{\psi}_{j,k}^0$ :

$$\psi_{j,k}^0 = \sum_n H_{k,n}^0 \varphi_{j+1,n}^0 \quad \text{and} \quad \tilde{\psi}_{j,k}^0 = \sum_n \tilde{H}_{k,n}^0 \tilde{\varphi}_{j+1,n}^0. \quad (3)$$

This point was relieved by Kadri-Harouna and Perrier [20], they extend the construction of [14] to any *regular* scaling function generator  $\varphi^1$  and provided a numerical algorithm and examples for the fast wavelet transform.

One advantage of the construction [14, 20] is that the associated multiscale projectors commute with differentiation in  $H^1(0, 1)$ . This fundamental property enables to demonstrate the Ladysenskaya-Babuska-Brezzi (LBB) condition for a wavelet based method in the numerical discretization of mixed problem such as Stokes problem [3, 7]. The key ingredient is that, commutation with derivation allows to get easily the condition of Fortin's lemma [11], see [7].

Ensuring the commutation of multiscale projectors with differentiation imposes to the biorthogonal space  $\tilde{V}_j^0$  to satisfy homogeneous Dirichlet boundary condition. In this case,  $\tilde{V}_j^0 \subset H_0^1(0, 1)$  cannot be a multiresolution analysis of  $L^2(0, 1)$ . Moreover, relation (2) remains valid only for internal scaling functions and wavelets. Nonetheless, the edge functions did not satisfy this relation: a change of basis is introduced [21].

Recently, Stevenson [22] has proposed another construction which differs from the existing constructions by the choice of the boundary conditions for the dual spaces  $\tilde{V}_j^0$  and  $\tilde{V}_j^1$ . Precisely, let us suppose that  $\psi_{j,k}^1$  and  $\tilde{\psi}_{j,k}^0$  are the wavelets constructed from scaling function generators satisfying (2). Then, integration by part shows that:

$$\psi_{j,k}^1(1)\tilde{\psi}_{j,k}^0(1) - \psi_{j,k}^1(0)\tilde{\psi}_{j,k}^0(0) = \langle \psi_{j,k}^0, \tilde{\psi}_{j,k}^0 \rangle - \langle \psi_{j,k}^1, \tilde{\psi}_{j,k}^1 \rangle. \quad (4)$$

If the two systems  $(\psi_{j,k}^1, \tilde{\psi}_{j,k}^1)$  and  $(\psi_{j,k}^0, \tilde{\psi}_{j,k}^0)$  are biorthogonal, the boundary terms of (4) should vanish. Instead of taking  $\tilde{\psi}_{j,k}^0 \in H_0^1(0, 1)$  like in [14], the construction of [22] sets  $\psi_{j,k}^1(1) = 0$  and  $\tilde{\psi}_{j,k}^0(0) = 0$ . This choice of boundary condition is more general and leads to  $\tilde{V}_j^0$  as a multiresolution analysis of  $L^2(0, 1)$ : however the commutation of multiscale projectors with differentiation is lost.

The focal point of this work is the construction of wavelet bases for biorthogonal multiresolution analyses of  $L^2(0, 1)$  linked by differentiation and integration [14, 20, 22]. As for the internal wavelets (2), emphasis is made on the construction of edge wavelets in order to get a diagonal differentiation relation:

$$\psi_{j,k}^1(x) = 2^j \int_0^x \psi_{j,k}^0(t) dt \quad \text{and} \quad (\psi_{j,k}^1)'(x) = 2^j \psi_{j,k}^0(x). \quad (5)$$

We start with the construction of wavelets  $\psi_{j,k}^0$  and  $\tilde{\psi}_{j,k}^0$ : for this step, we will use a classical biorthogonal or orthogonal wavelet basis on the interval  $[0, 1]$ . Since  $\int_0^1 \psi_{j,k}^0(t) dt = 0$ , relation (5) leads to  $\psi_{j,k}^1 \in H_0^1(0, 1)$  instead of  $\psi_{j,k}^1 \in H^1(0, 1)$  and  $\tilde{\psi}_{j,k}^0 \in H_0^1(0, 1)$  as in [14, 20, 22, 23]. Moreover, from the multiscale decomposition:

$$V_j^1 = V_{j_{min}}^1 \oplus W_{j_{min}}^1 \oplus \dots \oplus W_{j-1}^1, \quad (6)$$

we see that incorporating homogeneous Dirichlet boundary condition in  $V_j^1$  is reduced to the treatment of this boundary condition only at the coarse scale  $j_{min}$ . Considering the particular case  $\psi_{j,k}^0 = \tilde{\psi}_{j,k}^0$ , which corresponds to the orthogonal setting, gives:

$$\langle (\psi_{j,k}^1)', (\psi_{\ell,n}^1)' \rangle = 2^{j+\ell} \langle \psi_{j,k}^0, \psi_{\ell,n}^0 \rangle = 2^{j+\ell} \delta_{j,\ell} \delta_{k,n}. \quad (7)$$

Then, from (7) we infer that the 1D Poisson equation with homogeneous Dirichlet boundary can be solved with a linear numerical complexity in the multiresolution analysis provided by spaces  $V_j^1$ . Furthermore, this new construction still maintains the properties of Fortin's lemma [11] in the numerical discretization of Stokes problem and allows to get a fast divergence-free wavelet transform algorithm similar to this of the periodic case [10]. The main difficulty of such a construction is the numerical implementation of the decomposition (6), this point will be well documented in the present work.

In Section 2 we recall the construction of biorthogonal multiresolution analysis of  $L^2(0, 1)$  with polynomial reproduction and how to impose homogeneous boundary conditions in such context. Section 3 reminds the principle of the construction of BMRA linked by differentiation / integration and its main properties needed for a numerical implementation. The new construction of BMRA linked by differentiation / integration is detailed in Section 4, while the associated fast wavelet transform algorithms are provided in Section 5. Finally, Section 6 presents numerical examples showing the potentiality of these new bases.

## 2 Biorthogonal multiresolution analyses of $L^2(0, 1)$ reproducing polynomial

The construction of biorthogonal multiresolution analyses  $(V_j, \tilde{V}_j)$  of  $L^2(0, 1)$  with polynomial reproduction  $(r, \tilde{r})$  is classical [4, 8, 12]: the principle is to start with generators  $(\varphi, \tilde{\varphi})$ , that are biorthogonal scaling functions of a BMRA on  $\mathbb{R}$ . We

suppose that  $\varphi$  is compactly supported on  $[n_{min}, n_{max}]$  and reproduces polynomials up to degree  $r - 1$ :

$$0 \leq \ell \leq r - 1, \quad \frac{x^\ell}{\ell!} = \sum_{k=-\infty}^{+\infty} \tilde{p}_\ell(k) \varphi(x - k), \quad \forall x \in \mathbb{R}, \quad (8)$$

with  $\tilde{p}_\ell(k) = \langle \frac{x^\ell}{\ell!}, \tilde{\varphi}(x - k) \rangle$ . Similarly,  $\tilde{\varphi}$  reproduces polynomials up to degree  $\tilde{r} - 1$  and we note  $p_\ell(k) = \langle \frac{x^\ell}{\ell!}, \varphi(x - k) \rangle$ . For  $j$  sufficiently large, the spaces  $V_j$  on  $[0, 1]$  have the structure:

$$V_j = V_j^b \oplus V_j^{int} \oplus V_j^\sharp, \quad (9)$$

where  $V_j^{int} = \text{span}\{\varphi_{j,k}(x) = 2^{j/2}\varphi(2^j x - k); k = k_b, 2^j - k_\sharp\}$  is the space generated by *interior scaling functions* whose supports are included into  $[\frac{\delta_b}{2^j}, 1 - \frac{\delta_\sharp}{2^j}] \subset [0, 1]$  ( $\delta_b, \delta_\sharp \in \mathbb{N}$  be two fixed parameters), and  $k_b = \delta_b - n_{min}$  and  $k_\sharp = \delta_\sharp + n_{max}$ . Moreover

$$\begin{aligned} V_j^b &= \text{span}\{\Phi_{j,\ell}^b(x) = 2^{j/2}\Phi_\ell^b(2^j x); \ell = 0, \dots, r - 1\}, \\ V_j^\sharp &= \text{span}\{\Phi_{j,\ell}^\sharp(1 - x) = 2^{j/2}\Phi_\ell^\sharp(2^j(1 - x)); \ell = 0, \dots, r - 1\}, \end{aligned}$$

are the *edge spaces*, the *edge scaling functions* at the edge 0 being defined in order to preserve the polynomial reproduction (8) on the interval  $[0, 1]$ :

$$0 \leq \ell \leq r - 1, \quad \Phi_\ell^b(x) = \sum_{k=1-n_{max}}^{k_b-1} \tilde{p}_\ell(k) \varphi(x - k) \chi_{[0, +\infty[}. \quad (10)$$

At the edge 1, the edge scaling functions  $\Phi_{j,\ell}^\sharp$  are constructed on  $] - \infty, 1]$  by symmetry, using the transform  $Tf(x) = f(1 - x)$ . In practice we have to choose  $j \geq j_{min}$  where  $j_{min}$  is the smallest integer which verifies  $j_{min} > \log_2[n_{max} - n_{min} + \delta_\sharp + \delta_b]$  to ensure that the supports of edge scaling functions at 0 do not intersect the supports of edge scaling functions at 1.

The polynomial reproduction in  $V_j$  is then satisfied since, for  $0 \leq \ell \leq r - 1$  and  $x \in [0, 1]$  we have:

$$\frac{2^{j/2}(2^j x)^\ell}{\ell!} = 2^{j/2}\Phi_\ell^b(2^j x) + \sum_{k=k_b}^{2^j - k_\sharp} \tilde{p}_\ell(k) \varphi_{j,k}(x) + 2^{j/2}\Phi_\ell^\sharp(2^j(1 - x)). \quad (11)$$

Similarly, the biorthogonal spaces  $\tilde{V}_j$  are defined with the same structure, allowing the polynomial reproduction up to degree  $\tilde{r} - 1$ :

$$\tilde{V}_j = \text{span}\{\tilde{\Phi}_{j,\ell}^b\}_{\ell=0, \tilde{r}-1} \oplus \tilde{V}_j^{int} \oplus \text{span}\{\tilde{\Phi}_{j,\ell}^\sharp\}_{\ell=0, \tilde{r}-1}, \quad (12)$$

where  $\tilde{V}_j^{int} = \text{span}\{\tilde{\varphi}_{j,k}; k = \tilde{k}_b, 2^j - \tilde{k}_\sharp\}$  is the space generated by interior scaling functions  $\tilde{\varphi}_{j,k}(x) = 2^{j/2}\tilde{\varphi}^1(2^j x - k)$ , whose supports are included into  $[\frac{\tilde{\delta}_b}{2^j}, 1 - \frac{\tilde{\delta}_\sharp}{2^j}]$  ( $\tilde{\delta}_b, \tilde{\delta}_\sharp \in \mathbb{N}$  be two parameters). The edge scaling functions at 0 are defined by:

$$0 \leq \ell \leq \tilde{r} - 1, \quad \tilde{\Phi}_\ell^b(x) = \sum_{k=1-\tilde{n}_{max}}^{\tilde{k}_b-1} p_\ell(k) \tilde{\varphi}(x - k) \chi_{[0, +\infty[}.$$

The equality between dimensions of  $V_j$  and  $\tilde{V}_j$  is obtained by adjusting the parameters  $\tilde{\delta}_b = \tilde{k}_b - \tilde{n}_{max}$  and  $\tilde{\delta}_\# = \tilde{k}_\# + \tilde{n}_{min}$  (with  $[\tilde{n}_{min}, \tilde{n}_{max}] = \text{supp } \tilde{\varphi}$ ) such that:  $\Delta_j = \dim(V_j) = \dim(\tilde{V}_j) = 2^j - (\delta_b + \delta_\#) - (n_{max} - n_{min}) + 2r + 1$ . Remark that  $(\delta_b, \delta_\#)$  remain "free" parameters of the construction (often chosen equal to 0 or 1). The last step of the construction lies in the biorthogonalization process of the basis functions, since edge scaling functions of  $V_j$  and  $\tilde{V}_j$  are no more biorthogonal [1, 8, 12, 17]. Finally, the spaces  $(V_j, \tilde{V}_j)$  form a biorthogonal MRA of  $L^2(0, 1)$ .

*Boundary conditions* A multiresolution analyses of

$$H_0^m(0, 1) = \{f \in H^m(0, 1) : f^{(p)}(0) = f^{(p)}(1) = 0, \quad 0 \leq p \leq m - 1\}$$

can be defined from  $V_j$  by taking  $V_j^{m,0} = V_j \cap H_0^m(0, 1)$ . For instance, if  $m = 1$ , as described in [16, 17], it suffices to remove the edge scaling functions  $\Phi_0^b$  at edge 0 and  $\Phi_0^\#$  at edge 1 which leads to:

$$V_j^{1,0} = \text{span}\{\Phi_{j,\ell}^b; \ell = 1, r - 1\} \oplus V_j^{int} \oplus \text{span}\{\Phi_{j,\ell}^\#; \ell = 1, r - 1\}.$$

In such case, we also remove the edge functions  $\tilde{\Phi}_0^b$  and  $\tilde{\Phi}_0^\#$  from  $\tilde{V}_j$  prior to biorthogonalization, to adjust the dimension of the biorthogonal space. Then, the spaces  $(V_j^{1,0}, \tilde{V}_j^{1,0})$  constitute a biorthogonal multiresolution analyses of  $H_0^1(0, 1)$ .

### 3 Existing construction of $(V_j^0, \tilde{V}_j^0)$ linked by differentiation / integration with $(V_j^1, \tilde{V}_j^1)$

In this section, we recall briefly the earlier construction of the multiresolution analysis linked differentiation / integration. Then, we will mention their limitations in some applications that we intend to take up with our new construction below.

All the construction of biorthogonal multiresolution analysis of  $L^2(0, 1)$  linked by differentiation/ integration are based on the following proposition [15]:

**Proposition 1** *Let  $(V_j^1(\mathbb{R}))$  be a MRA of  $L^2(\mathbb{R})$ , with differentiable and compactly supported scaling function  $\varphi^1 \in C^{1+\epsilon}$ ,  $\epsilon > 0$  and wavelet  $\psi^1$ . Then there exists a MRA  $(V_j^0(\mathbb{R}))$ , with associated scaling function  $\varphi^0$  and wavelet  $\psi^0$ , such that:*

$$(\varphi^1)'(x) = \varphi^0(x) - \varphi^0(x - 1) \text{ and } (\psi^1)' = 4 \psi^0.$$

*The biorthogonal functions verify:  $\int_x^{x+1} \tilde{\varphi}^1(t) dt = \tilde{\varphi}^0(x)$  and  $(\tilde{\psi}^0)' = -4 \tilde{\psi}^1$ .*

Proposition 1 provides biorthogonal multiresolution analysis of  $L^2(\mathbb{R})$  linked by differentiation/ integration [15]. For the space  $L^2(0, 1)$ , again based on Proposition 1, the first construction was done by Jouini and Lemarié-Rieusset [14]: they prove the existence of two biorthogonal multiresolution analyses of  $L^2(0, 1)$ , denoted  $(V_j^1)$  and  $(V_j^0)$  linked by differentiation such that:

$$\frac{d}{dx} V_j^1 = V_j^0. \quad (13)$$

The construction of [14] allows to study divergence-free vector functions on hypercube  $[0, 1]^d$ , thus to get commutation of multiscale projector with the derivation operator, the biorthogonal spaces  $\tilde{V}_j^0$  should satisfy:

$$\tilde{V}_j^0 = H_0^1(0, 1) \cap \int_0^x \tilde{V}_j^1 = \left\{ f : f' \in \tilde{V}_j^1 \text{ and } f(0) = f(1) = 0 \right\}. \quad (14)$$

Then, as mentioned before,  $\tilde{V}_j^0$  can not be a multiresolution analysis of  $L^2(\mathbb{R})$  since  $\tilde{V}_j^0 \subset H_0^1(0, 1)$ . Furthermore, if  $(\mathcal{P}_j^1, \tilde{\mathcal{P}}_j^1)$  are the biorthogonal projectors of  $(V_j^1, \tilde{V}_j^1)$  and  $(\mathcal{P}_j^0, \tilde{\mathcal{P}}_j^0)$  those of  $(V_j^0, \tilde{V}_j^0)$  respectively, we have [14]:

**Proposition 2**

- (i)  $\forall f \in H^1(0, 1), \quad \frac{d}{dx} \circ \mathcal{P}_j^1 f = \mathcal{P}_j^0 \circ \frac{d}{dx} f,$
- (ii)  $\forall f \in H_0^1(0, 1), \quad \frac{d}{dx} \circ \tilde{\mathcal{P}}_j^0 f = \tilde{\mathcal{P}}_j^1 \circ \frac{d}{dx} f.$

Despite of satisfying Proposition 2, the construction of Jouini and Lemarié-Rieusset [14] remains in a theoretical setting based on the use of Daubechies compactly supported orthogonal generators [9]. A construction that uses classical biorthogonal multiresolution analyses on the interval [4, 8, 12], with polynomial reproduction at boundaries, was done and implemented by Kadri-Harouna and Perrier [20]. In such a construction, the choice of integer parameters  $(\delta_b, \delta_\sharp)$  and  $(\tilde{\delta}_b, \tilde{\delta}_\sharp)$  is very important: they must be identical for the two multiresolution analyses to satisfy (13,14) and to provide the commutation of multiscale projector with the differentiation operator.

### 3.1 Wavelet spaces

For  $j \geq j_{min}$ , the biorthogonal wavelet spaces associated to  $V_j^1$  are defined by  $W_j^1 = V_{j+1}^1 \cap (\tilde{V}_j^1)^\perp$ . As for the scaling function spaces, these spaces have the following structure:

$$W_j^1 = W_j^{1,b} \oplus W_j^{1,int} \oplus W_j^{1,\sharp},$$

where  $W_j^{1,b}$  is spanned by the edge wavelets at 0,  $W_j^{1,int}$  is spanned by the interior wavelets and  $W_j^{1,\sharp}$  is spanned by the edge wavelets at 1, see [1, 4, 8, 12, 17] and references therein. The biorthogonal spaces  $\tilde{W}_j^1 = \tilde{V}_{j+1}^1 \cap (V_j^1)^\perp$  are constructed in the same way, finally the wavelet bases of the two spaces must to be biorthogonalized identically as the scaling functions. The resulting wavelet bases are denoted by  $\{\psi_{j,k}^1\}_{k=1,2^j}$  and  $\{\tilde{\psi}_{j,k}^1\}_{k=1,2^j}$  without distinction.

The biorthogonal wavelets of  $W_j^0$  and  $\tilde{W}_j^0$ , linked to  $\psi_{j,k}^1$  and  $\tilde{\psi}_{j,k}^1$  by differentiation/integration are defined by the following proposition, established in the general framework by [14]:

**Proposition 3** *Let  $(V_j^1, \tilde{V}_j^1)$  and  $(V_j^0, \tilde{V}_j^0)$  BMRA's satisfying (13,14). The wavelet spaces  $W_j^0 = V_{j+1}^0 \cap (\tilde{V}_j^0)^\perp$  and  $\tilde{W}_j^0 = \tilde{V}_{j+1}^0 \cap (V_j^0)^\perp$  are linked to the biorthogonal wavelet spaces associated to  $(V_j^1, \tilde{V}_j^1)$  by:*

$$W_j^0 = \frac{d}{dx} W_j^1 \quad \text{and} \quad \tilde{W}_j^0 = \int_0^x \tilde{W}_j^1. \quad (15)$$

Moreover, let  $\{\psi_{j,k}^1\}_{k=1,2^j}$  and  $\{\tilde{\psi}_{j,k}^1\}_{k=1,2^j}$  be two biorthogonal wavelet bases of  $W_j^1$  and  $\tilde{W}_j^1$ . Biorthogonal wavelet bases of  $W_j^0$  and  $\tilde{W}_j^0$  are directly defined by:

$$\psi_{j,k}^0 = 2^{-j}(\psi_{j,k}^1)' \quad \text{and} \quad \tilde{\psi}_{j,k}^0 = -2^j \int_0^x \tilde{\psi}_{j,k}^1. \quad (16)$$

This new edge wavelets preserve fast algorithms since they satisfy two-scale equations [20]:

**Proposition 4** Let  $\{\psi_{j,k}^1\}_{k=1,2^j}$  and  $\{\tilde{\psi}_{j,k}^1\}_{k=1,2^j}$  be two biorthogonal wavelet bases of  $W_j^1$  and  $\tilde{W}_j^1$  associated respectively to filters  $G_j^1$  and  $\tilde{G}_j^1$ :

$$\psi_{j,k}^1 = \sum_n (G_j^1)_{k,n} \varphi_{j+1,n}^1 \quad \text{and} \quad \tilde{\psi}_{j,k}^1 = \sum_n (\tilde{G}_j^1)_{k,n} \tilde{\varphi}_{j+1,n}^1.$$

Then there exist sparse matrices  $G_j^0$  and  $\tilde{G}_j^0$  defined by:

$$G_j^0 = 2^{-j} G_j^1 L_{j+1}^1 \quad \text{and} \quad \tilde{G}_j^0 = -2^j \tilde{G}_j^1 L_{j+1}^{0T}, \quad (17)$$

such that the wavelets  $\psi_{j,k}^0$  and  $\tilde{\psi}_{j,k}^0$  satisfy:

$$\psi_{j,k}^0 = \sum_n (G_j^0)_{k,n} \varphi_{j+1,n}^0 \quad \text{and} \quad \tilde{\psi}_{j,k}^0 = \sum_n (\tilde{G}_j^0)_{k,n} \tilde{\varphi}_{j+1,n}^0.$$

The matrices  $L_j^1$  and  $L_j^0$  correspond to the change of basis between  $(\frac{d}{dx} V_j^1, V_j^0)$  and  $(\int_0^x V_j^0, V_j^1)$ , respectively:

$$\frac{d}{dx} \varphi_{j,k}^1 = \sum_{n=1}^{\Delta_j-1} (L_j^1)_{k,n} \varphi_{j,n}^0 \quad \text{and} \quad - \int_0^x \varphi_{j,k}^0 = \sum_{m=1}^{\Delta_j} (L_j^0)_{k,m} \varphi_{j,m}^1. \quad (18)$$

Interior wavelets  $\psi_{j,k}^0(x) = 2^{j/2} \psi^0(2^j x - k)$  in Proposition 3 correspond to classical wavelets,  $\psi^0$  being a wavelet on  $\mathbb{R}$  associated to the scaling function  $\varphi^0$  as in Proposition 1. On the other hand, in the standard constructions [4, 8, 17, 12], the edge wavelets of  $W_j^0$  and  $\tilde{W}_j^0$  do not verify the diagonal differentiation relations (16). Moreover, to construct divergence-free wavelet satisfying *free slip* boundary condition [20, 22], one needs to differentiate wavelet of  $V_{j+1}^1 \cap H_0^1(0, 1)$ , which derivatives differ from the wavelets defined in (16). In this case, for instance the numerical computation of the Helmholtz-Hodge decomposition or the numerical simulation of the incompressible Navier-Stokes equations should required the use of four different kind of edge wavelet filters, see [19, 21]. The new construction detailed in the next section will lead to edge wavelets that satisfy (16) even if with Dirichlet homogeneous boundary condition.



#### 4 New construction of $(V_j^1, \tilde{V}_j^1)$ linked to $(V_j^0, \tilde{V}_j^0)$ by differentiation / integration

In this section we present our new construction of biorthogonal multiresolution analyses linked by differentiation and integration. The construction of the primal spaces  $(V_j^1, V_j^0)$  remains the same as in the classical construction [14, 20]. However, the construction of the biorthogonal spaces  $(\tilde{V}_j^1, \tilde{V}_j^0)$  and the wavelet bases will be different.

The construction starts with  $(V_j^0, \tilde{V}_j^0)$  as a standard biorthogonal multiresolution analyses of  $L^2(0, 1)$  [1, 4, 5], where the scaling function generators  $(\varphi^0, \tilde{\varphi}^0)$  satisfy Proposition 1. Again, we denote by  $(\delta_b, \delta_\#)$  and  $(\tilde{\delta}_b, \tilde{\delta}_\#)$  the integer parameters used in the construction of  $(V_j^0, \tilde{V}_j^0)$ . Following [14, 20], the classical multiresolution spaces  $V_j^1$  constructed from the scaling function  $\varphi^1$  with the same integer parameters  $(\delta_b, \delta_\#)$  satisfy:

$$\frac{d}{dx}V_j^1 = V_j^0 \quad \text{and} \quad \Delta_j^1 - 1 = \Delta_j^0.$$

In this case, for the biorthogonal space  $\tilde{V}_j^0$ , since  $\Delta_j^0 = \dim(\tilde{V}_j^0)$ , we see that:

$$\Delta_j^1 - 2 = \dim\left(\frac{d}{dx}\tilde{V}_j^0\right).$$

The construction of  $\tilde{V}_j^1$  follows similar approach. To get equality between dimensions of spaces  $V_j^1$  and  $\tilde{V}_j^1$ :

$$\Delta_j^1 = \tilde{\Delta}_j^1,$$

the integer parameters to be used for the construction of  $\tilde{V}_j^1$  must be fixed to  $(\tilde{\delta}_b - 1, \tilde{\delta}_\# - 1)$ . It follows therefore that:

$$\frac{d}{dx}\tilde{V}_j^0 \not\subset \tilde{V}_j^1.$$

This is another difference compared to the existing construction.

The construction of the wavelet basis associated to  $V_j^1$  is the major contribution of the present work. In the classical construction, one defines the wavelet space as:

$$V_{j+1}^1 = V_j^1 \oplus W_j^1, \quad \text{where} \quad W_j^1 = V_{j+1}^1 \cap (\tilde{V}_j^1)^\perp.$$

Then, the space  $W_j^1$  does not necessarily satisfy homogeneous Dirichlet boundary condition. To compensate for that, in this work the wavelet space is defined as:

$$\overline{W}_j^1 = \int_0^x W_j^0,$$

where  $W_j^0$  is the wavelet space associated to  $V_j^0$  [1, 4, 8, 12, 17]:

$$W_j^0 = V_{j+1}^0 \cap (\tilde{V}_j^0)^\perp.$$

*Remark 1*

From the zero mean value property of the wavelet  $\psi_{j,k}^0$ , by construction the space  $\overline{W}_j^1$  satisfies:

$$\overline{W}_j^1 \subset H_0^1(0, 1).$$

In the previous section, the wavelet space  $W_j^0$  was defined as  $W_j^0 = \frac{d}{dx}W_j^1$  and this choice of  $W_j^0$  led in general to:

$$W_j^1 \neq \int_0^x W_j^0.$$

For all  $j \geq j_{min}$ , the spaces  $\overline{W}_j^1$  verify the following proposition.

**Proposition 5**

Let  $W_j^0$  be the wavelet space associated to  $V_j^0$ , where  $V_j^0 = \frac{d}{dx}V_j^1$ . Then the space  $V_{j+1}^1$  can be decomposed as follows:

$$V_{j+1}^1 = V_j^1 \oplus \overline{W}_j^1, \quad \text{with } \overline{W}_j^1 = \int_0^x W_j^0, \quad (19)$$

and

$$V_{j+1}^1 = V_{j_{min}}^1 \oplus \overline{W}_{j_{min}}^1 \oplus \cdots \oplus \overline{W}_j^1. \quad (20)$$

*Proof* As  $\frac{d}{dx}V_j^1 = V_j^0$ , we get:

$$\overline{W}_j^1 = \int_0^x W_j^0 \subset \int_0^x \frac{d}{dt}V_{j+1}^1 \subset V_{j+1}^1 \quad \text{and} \quad \int_0^x W_j^0 \subset H_0^1(0, 1).$$

Moreover, let  $u_j$  be a function of  $V_j^1 \cap \overline{W}_j^1$ :

$$u_j = \sum_k c_k \varphi_{j,k}^1 = \sum_n d_n \int_0^x \psi_{j,n}^0,$$

we deduce that:

$$\frac{d}{dx}u_j \in V_j^0 \cap W_j^0 \Rightarrow \frac{d}{dx}u_j = 0 \Rightarrow u_j = C \in \mathbb{R}.$$

Since

$$\langle 1, \int_0^x \psi_{j,n}^0 \rangle = -\langle x, \psi_{j,n}^0 \rangle = 0,$$

we get  $u_j = 0$ , which implies  $V_j^1 \cap \overline{W}_j^1 = \{0\}$ . Let  $f_{j+1} \in V_{j+1}^1$ , then:

$$\frac{d}{dx}f_{j+1} \in V_{j+1}^0 = V_j^0 \oplus W_j^0.$$

Since  $f_{j+1}(0) \in V_j^1$  (the constants are in  $V_j^1$ ), integration gives:

$$f_{j+1}(x) = f_{j+1}(0) + \int_0^x \mathcal{P}_j^0\left(\frac{d}{dx}f_{j+1}\right) + \int_0^x \mathcal{Q}_j^0\left(\frac{d}{dx}f_{j+1}\right) \in V_j^1 + \overline{W}_j^1,$$

and this ends the proof.

The interest of such a wavelet space construction is that homogeneous Dirichlet boundary conditions can be handled easily. Indeed, by construction the space  $\overline{W}_j^1 \subset H_0^1(0, 1)$  and relation (20) allow to get the following decomposition:

$$V_{j+1}^{1,0} = V_{j+1}^1 \cap H_0^1(0, 1) = V_{j_{min}}^1 \cap H_0^1(0, 1) \oplus \overline{W}_{j_{min}}^1 \oplus \cdots \oplus \overline{W}_j^1.$$

Moreover, if we define  $\tilde{V}_j^{1,0}$  as  $\tilde{V}_j^{1,0} = \frac{d}{dx} \tilde{V}_j^0$ , we have:

**Proposition 6**

Let  $(V_j^1, \tilde{V}_j^1)$  and  $(V_j^0, \tilde{V}_j^0)$  be two BMRA's of  $L^2(0, 1)$  linked by differentiation and integration such that:

$$\frac{d}{dx} V_j^1 = V_j^0 \quad \text{and} \quad \frac{d}{dx} \tilde{V}_j^0 = \tilde{V}_j^{1,0} \subset L^2(0, 1), \quad (21)$$

where  $V_j^{1,0}$  is the multiresolution analysis of  $H_0^1(0, 1)$  provided by  $V_j^{1,0} = V_j^1 \cap H_0^1(0, 1)$ . Then, the wavelet space  $\int_0^x W_j^0$  is the classical wavelet space associated to  $V_j^{1,0}$ :

$$V_{j+1}^{1,0} = V_{j+1}^1 \cap H_0^1(0, 1) = V_j^{1,0} \oplus \int_0^x W_j^0 \quad \text{and} \quad \int_0^x W_j^0 = V_{j+1}^{1,0} \cap (\tilde{V}_j^{1,0})^\perp. \quad (22)$$

*Proof*

From the vanishing moment condition of the wavelet basis of  $W_j^0$  we get:

$$\int_0^1 W_j^0 = 0 \quad \Rightarrow \quad \int_0^x W_j^0 \subset H_0^1(0, 1).$$

The differentiation relation gives:

$$\frac{d}{dx} V_{j+1}^1 = V_{j+1}^0 \quad \Rightarrow \quad \int_0^x V_{j+1}^0 \subset V_{j+1}^1,$$

thus

$$\int_0^x W_j^0 \subset V_{j+1}^1 \cap H_0^1(0, 1) = V_{j+1}^{1,0}.$$

The differentiation relation:

$$\frac{d}{dx} \tilde{V}_j^0 = \tilde{V}_j^{1,0}$$

states that for any  $\tilde{f}_j^{1,0} \in \tilde{V}_j^{1,0}$ , there exists  $\tilde{f}_j^0 \in \tilde{V}_j^0$  such that  $(\tilde{f}_j^0)' = \tilde{f}_j^{1,0}$ , then:

$$\left\langle \int_0^x \psi_{j,k}^0, \tilde{f}_j^{1,0} \right\rangle = \left\langle \int_0^x \psi_{j,k}^0, \frac{d}{dx} \tilde{f}_j^0 \right\rangle = -\langle \psi_{j,k}^0, \tilde{f}_j^0 \rangle = 0 \quad \Rightarrow \quad \int_0^x W_j^0 \subset (\tilde{V}_j^{1,0})^\perp.$$

Then we deduce that  $\int_0^x W_j^0 \subset V_{j+1}^{1,0} \cap (\tilde{V}_j^{1,0})^\perp$  and since the two spaces have the same dimension, we get:

$$\int_0^x W_j^0 = V_{j+1}^{1,0} \cap (\tilde{V}_j^{1,0})^\perp.$$

We recall that the integer parameters used in the construction of  $\tilde{V}_j^1$  and  $\tilde{V}_j^0$  are not the same, thus one can not expect to get commutation between multiscale projectors and derivation as in Proposition 2. However, for the oblique multiscale projectors of  $(V_j^{1,0}, V_j^0)$  and  $(\tilde{V}_j^0, \tilde{V}_j^{1,0})$ , we can prove the following proposition:

**Proposition 7**

Let  $(\mathcal{P}_j^{1,0}, \mathcal{P}_j^0)$  be the biorthogonal projectors associated with  $(V_j^{1,0}, V_j^0)$  and  $(\tilde{\mathcal{P}}_j^0, \tilde{\mathcal{P}}_j^{1,0})$  the biorthogonal projectors associated with  $(\tilde{V}_j^0, \tilde{V}_j^{1,0})$ . Then, we have:

- (i)  $\forall f \in H_0^1(0, 1), \quad \frac{d}{dx} \circ \mathcal{P}_j^{1,0} f = \mathcal{P}_j^0 \circ \frac{d}{dx} f.$   
(ii)  $\forall f \in H^1(0, 1), \quad \frac{d}{dx} \circ \tilde{\mathcal{P}}_j^0 f = \tilde{\mathcal{P}}_j^{1,0} \circ \frac{d}{dx} f.$

*Proof*

From proposition 6, there are two matrices denoted  $L_j^{1,0}$  and  $\tilde{L}_j^{1,0}$  of size  $(\Delta_j^1 - 2) \times (\Delta_j^1 - 1)$ , such that:

$$\varphi_{j,k}^{1,0} = \sum_{n=1}^{\Delta_j^1-1} (L_j^{1,0})_{k,n} \int_0^x \varphi_{j,n}^0 \quad \text{and} \quad \tilde{\varphi}_{j,k}^{1,0} = \sum_{n=1}^{\Delta_j^1-1} (\tilde{L}_j^{1,0})_{k,n} \frac{d}{dx} \tilde{\varphi}_{j,n}^0.$$

The biorthogonality of the basis functions  $\varphi_{j,k}^{1,0}$  and  $\tilde{\varphi}_{j,k}^{1,0}$ , with an integration by part give:

$$\begin{aligned} \delta_{k,m} &= \langle \varphi_{j,k}^{1,0}, \tilde{\varphi}_{j,m}^{1,0} \rangle = \sum_{\ell} (\tilde{L}_j^{1,0})_{m,\ell} \langle \varphi_{j,k}^{1,0}, \frac{d}{dx} \tilde{\varphi}_{j,\ell}^0 \rangle = \sum_{\ell} (\tilde{L}_j^{1,0})_{m,\ell} \langle -\frac{d}{dx} \varphi_{j,k}^{1,0}, \tilde{\varphi}_{j,\ell}^0 \rangle \\ &= - \sum_n \sum_{\ell} (L_j^{1,0})_{k,n} (\tilde{L}_j^{1,0})_{m,\ell} \langle \varphi_{j,n}^0, \tilde{\varphi}_{j,\ell}^0 \rangle = - \sum_n (L_j^{1,0})_{k,n} (\tilde{L}_j^{1,0})_{m,n}, \end{aligned}$$

which means that:

$$I_{\Delta_j-2} = -L_j^{1,0} {}^t \tilde{L}_j^{1,0}.$$

Thus, the proof of the point (i) becomes a change of basis. Indeed, for  $f \in H_0^1(0, 1)$ , we have:

$$\begin{aligned} \frac{d}{dx} \mathcal{P}_j^{1,0}(f) &= \sum_k \langle f, \tilde{\varphi}_{j,k}^{1,0} \rangle \frac{d}{dx} \varphi_{j,k}^{1,0} = \sum_k \sum_n (L_j^{1,0})_{k,n} \langle f, \tilde{\varphi}_{j,k}^{1,0} \rangle \varphi_{j,n}^0 \\ &= \sum_n \langle f, \sum_k (L_j^{1,0})_{k,n} \tilde{\varphi}_{j,k}^{1,0} \rangle \varphi_{j,n}^0 = \sum_n \langle f, \sum_k \sum_m (L_j^{1,0})_{k,n} (\tilde{L}_j^{1,0})_{k,m} \frac{d}{dx} \tilde{\varphi}_{j,m}^0 \rangle \varphi_{j,n}^0 \\ &= \sum_n \langle f, -\frac{d}{dx} \tilde{\varphi}_{j,n}^0 \rangle \varphi_{j,n}^0 = \sum_n \langle \frac{d}{dx} f, \tilde{\varphi}_{j,n}^0 \rangle \varphi_{j,n}^0 = \mathcal{P}_j^0 \left( \frac{d}{dx} f \right). \end{aligned}$$

For the second point (ii), let us consider the matrix  $\tilde{L}_j^0$  defined by:

$$\frac{d}{dx} \tilde{\varphi}_{j,k}^0 = \sum_{n=1}^{\Delta_j^0-1} (\tilde{L}_j^0)_{k,n} \tilde{\varphi}_{j,n}^{1,0}.$$

Again, the duality of the basis and integration by part give:

$$\langle \frac{d}{dx} \varphi_{j,k}^{1,0}, \tilde{\varphi}_{j,m}^0 \rangle = (L_j^{1,0})_{k,m} = \langle \varphi_{j,k}^{1,0}, -\frac{d}{dx} \tilde{\varphi}_{j,m}^0 \rangle = -(\tilde{L}_j^0)_{m,k},$$

then

$$\begin{aligned} \frac{d}{dx} \tilde{\mathcal{P}}_j^0(f) &= \sum_k \langle f, \varphi_{j,k}^0 \rangle \frac{d}{dx} \tilde{\varphi}_{j,k}^0 = \sum_k \sum_n (\tilde{L}_j^0)_{k,n} \langle f, \varphi_{j,k}^0 \rangle \tilde{\varphi}_{j,n}^{1,0} \\ &= \sum_n \langle f, \sum_k (\tilde{L}_j^0)_{k,n} \varphi_{j,k}^0 \rangle \tilde{\varphi}_{j,n}^{1,0} = \sum_n \langle f, -\sum_k (\tilde{L}_j^{1,0})_{n,k} \varphi_{j,k}^0 \rangle \tilde{\varphi}_{j,n}^{1,0} \\ &= \sum_n \langle f, -\frac{d}{dx} \varphi_{j,n}^{1,0} \rangle \tilde{\varphi}_{j,n}^{1,0} = \sum_n \langle \frac{d}{dx} f, \varphi_{j,n}^{1,0} \rangle \tilde{\varphi}_{j,n}^{1,0} = \tilde{\mathcal{P}}_j^{1,0} \left( \frac{d}{dx} f \right). \end{aligned}$$

## 5 Fast decomposition algorithms

In this section we provide numerical algorithms for the computation of the projection of  $f_{j+1} \in V_{j+1}^1$  onto  $V_j^1$  and  $\overline{W}_j^1$  respectively. Precisely, starting with:

$$f_{j+1} = \sum_{k=1}^{\Delta_{j+1}^1} c_{j+1,k} \varphi_{j+1,k}^1,$$

we want to compute the coefficients  $c_{j,k}$  and  $d_{j,k}$  from  $c_{j+1,k}$  such that:

$$f_{j+1} = \sum_{k=1}^{\Delta_{j+1}^1} c_{j+1,k} \varphi_{j+1,k}^1 = \sum_{k=1}^{\Delta_j^1} c_{j,k} \varphi_{j,k}^1 + \sum_{m=1}^{2^j} d_{j,m} \int_0^x \psi_{j,m}^0.$$

Firstly, we notice that  $f_{j+1}$  can be split as

$$f_{j+1} = \sum_{k=1}^{\Delta_{j+1}^1} c_{j+1,k} \varphi_{j+1,k}^1 = f_{j+1}^0 + f_{j+1}^{1,0} + f_{j+1}^1,$$

with

$$f_{j+1}^0 = c_{j+1,1} \varphi_{j+1,1}^1 \Rightarrow f_{j+1}^0(0) \neq 0 \text{ and } f_{j+1}^0(1) = 0,$$

$$f_{j+1}^1 = c_{j+1,\Delta_{j+1}^1} \varphi_{j+1,\Delta_{j+1}^1}^1 \Rightarrow f_{j+1}^1(0) = 0 \text{ and } f_{j+1}^1(1) \neq 0,$$

and

$$f_{j+1}^{1,0} = \sum_{k=2}^{\Delta_{j+1}^1-1} c_{j+1,k} \varphi_{j+1,k}^1 \in H_0^1(0,1).$$

Then, the function  $f_{j+1}^{1,0}$  belongs to  $V_{j+1}^{1,0}$  and this space corresponds to:

$$V_{j+1}^{1,0} = V_j^{1,0} \oplus W_j^{1,0}, \text{ with } W_j^{1,0} = \overline{W}_j^1.$$

Thus, the two scale decomposition of  $f_{j+1}^{1,0}$  is a classical decomposition in the multiresolution analysis of  $H_0^1(0,1)$  provided by the scaling function filter of  $V_j^{1,0}$  and wavelet filter of  $W_j^{1,0}$ . The projection of  $f_{j+1}^0$  is based on the following two scale relations satisfied by the scaling function  $\varphi_{j+1,1}^1$ :

$$\varphi_{j+1,1}^1 = \sum_{n=1}^{\tilde{\Delta}_j^1} \tilde{H}_{n,1}^1 \varphi_{j,n}^1 + \sum_{m=1}^{2^j} \tilde{G}_{m,1}^1 \psi_{j,m}^1 = \sum_{n=1}^{\tilde{\Delta}_j^1} \tilde{H}_{n,1}^1 \varphi_{j,n}^1 + \sum_{m=1}^{2^j} \tilde{G}_{m,1}^1 \int_0^x \psi_{j,m}^0,$$

where the first decomposition corresponds to  $V_{j+1}^1 = V_j^1 \oplus W_j^1$  and the second one corresponds to  $V_{j+1}^1 = V_j^1 \oplus \overline{W}_j^1$ . To get the new filters  $\tilde{H}_{n,1}^1$  and  $\tilde{G}_{m,1}^1$ , according to the biorthogonalization procedure that we adopted, where only the dual basis are modified, we have:

$$\tilde{G}_{k,1}^1 = \sum_{m=1}^{2^j} \tilde{G}_{m,1}^1 \langle \int_0^x \psi_{j,m}^0, \tilde{\psi}_{j,k}^1 \rangle, \quad (23)$$

and

$$\tilde{H}_{k,1}^1 = \tilde{H}_{k,1}^1 + \sum_{m=1}^{2^j} \tilde{G}_{m,1}^1 \langle \int_0^x \psi_{j,m}^0, \tilde{\varphi}_{j,k}^1 \rangle. \quad (24)$$

Equations (23) and (23) define two linear systems with respect to the edge scaling function and wavelet filters  $\tilde{G}_{n,1}^1$  and  $\tilde{H}_{n,1}^1$ . From [2, 21], the computation of coefficients  $\langle \int_0^x \psi_{j,m}^0, \tilde{\psi}_{j,k}^1 \rangle$  and  $\langle \int_0^x \psi_{j,m}^0, \tilde{\varphi}_{j,k}^1 \rangle$  is straightforward and this is done only for functions whose support intersect the edge function support, due to the compactly support properties of the generators. Then, solving these linear systems, with similar relations at the boundary 1, allows to get the new edge filters. Then, the main steps of the decomposition algorithm are summarized as:

$$\begin{aligned} c_{j,1} &= c_{j+1,1} \tilde{H}_{1,1}^1, \\ c_{j,k} &= \sum_{n=2}^{\Delta_{j+1}-1} c_{j+1,n} \tilde{H}_{n,k}^{1,0} + c_{j+1,1} \tilde{H}_{k,1}^1 + c_{j+1,\Delta_{j+1}} \tilde{H}_{k,\Delta_{j+1}}^1, \quad 2 \leq k \leq \Delta_j - 1, \\ c_{j,\Delta_j} &= c_{j+1,\Delta_{j+1}} \tilde{H}_{\Delta_j,\Delta_{j+1}}^1, \end{aligned}$$

and

$$d_{j,k} = \sum_{n=2}^{\Delta_{j+1}-1} c_{j+1,n} \tilde{G}_{n,k}^{1,0} + c_{j+1,1} \tilde{G}_{k,1}^1 + c_{j+1,\Delta_{j+1}} \tilde{G}_{k,\Delta_{j+1}}^1, \quad 1 \leq k \leq 2^j.$$

*Fast reconstruction algorithm* For  $f_{j+1} \in V_{j+1}^1$ , let us suppose that we know its projection onto  $V_j^1 \oplus \overline{W}_j^1$  in terms of:

$$f_{j+1} = \sum_{k=1}^{\Delta_j^1} c_{j,k} \varphi_{j,k}^1 + \sum_{m=1}^{2^j} d_{j,m} \int_0^x \psi_{j,m}^0,$$

and we want to compute its projection onto  $V_{j+1}^1$  in terms of:

$$f_{j+1} = \sum_{k=1}^{\Delta_{j+1}^1} c_{j+1,k} \varphi_{j+1,k}^1.$$

Setting

$$\sum_{k=1}^{\Delta_j^1} c_{j,k} \varphi_{j,k}^1 = f_j^0 + f_j^{1,0} + f_j^1, \quad \text{with } f_j^0 = c_{j,1} \varphi_{j,1}^1 \quad \text{and } f_j^1 = c_{j,\Delta_j^1} \varphi_{j,\Delta_j^1}^1,$$

it is easy to see that

$$f_j^{1,0} + \sum_{m=1}^{2^j} d_{j,m} \int_0^x \psi_{j,m}^0 \in V_{j+1}^1,$$

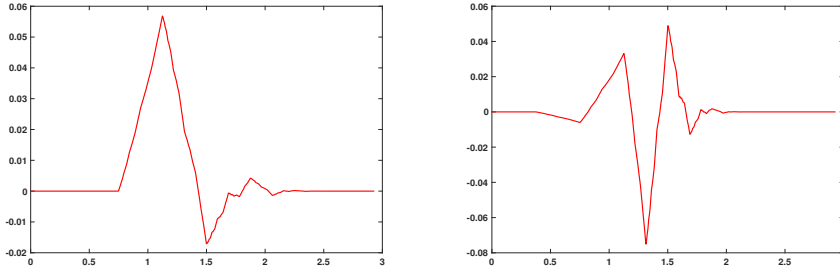


Fig. 1: Plot of the internal scaling function  $\varphi^0$  (left) and the internal wavelet  $\psi^0$  (right). Daubechies orthogonal generator with  $r = 3$ .

thus we get:

$$c_{j+1,k} = \sum_{n=1}^{\Delta_j^1} c_{j,n} H_{n,k}^1 + \sum_{m=1}^{2^j} d_{j,m} \bar{G}_{m,k}^1, \quad 2 \leq k \leq \Delta_{j+1}^1 - 1,$$

and

$$c_{j+1,1} = \sum_{n=1}^{\Delta_j^1} c_{j,n} H_{n,1}^1, \quad c_{j+1,\Delta_{j+1}^1} = \sum_{n=1}^{\Delta_j^1} c_{j,n} H_{n,\Delta_{j+1}^1}^1.$$

## 6 Numerical examples

We present in this section numerical examples to illustrate the potential application of this new construction of multiresolution analysis of  $L^2(0,1)$  linked by differentiation and integration. We remind that our construction starts with the construction of  $V_j^0$ . Here, for the different examples, the scaling function and wavelet generators ( $\varphi^0, \psi^0$ ) considered are Daubechies orthogonal generators, with three vanishing moments for the wavelet [9]. The integer parameters of the construction of  $V_j^0$  thus are:

$$r = 3, \quad \delta_b = \delta_{\sharp} = 1, \quad n_{min} = -r + 1 \quad \text{and} \quad n_{max} = r.$$

On Figure 1, we show the plot of the internal scaling function  $\varphi^0$  and the wavelet  $\psi^0$ . The edge orthogonal scaling functions and wavelets are plotted on Figure 2 and Figure 3 respectively. The generators ( $\varphi^1, \psi^1$ ) are computed from ( $\varphi^0, \psi^0$ ) using the formula:

$$\varphi^1(x) = \int_{x-1}^x \varphi^0(t) dt \quad \text{and} \quad \psi^1(x) = 4 \int_{-\infty}^x \psi^0(t) dt. \quad (25)$$

The graphs of  $\varphi^1$  and  $\psi^1$  are plotted on Figure 4, Figure 5 and Figure 6 show the plot of the edge scaling function graphs. The edge wavelet graphs are plotted on Figure 7 and Figure 8. We notice that these edge wavelets satisfy homogeneous Dirichlet boundary condition while this boundary condition is not required for all the edge scaling functions.

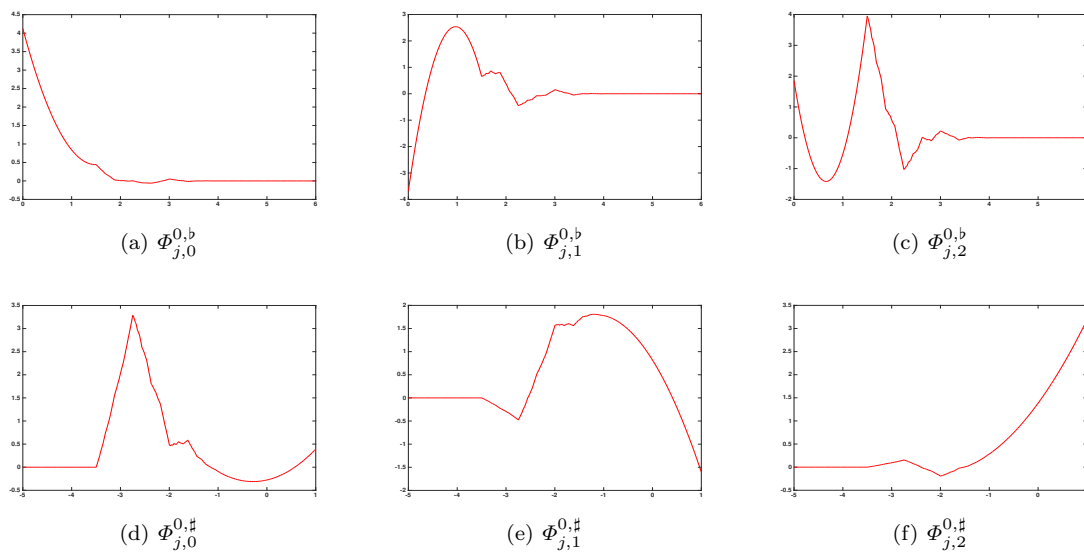


Fig. 2: Plot of the edge orthogonal scaling functions. Daubechies orthogonal generator with  $r = 3$ .

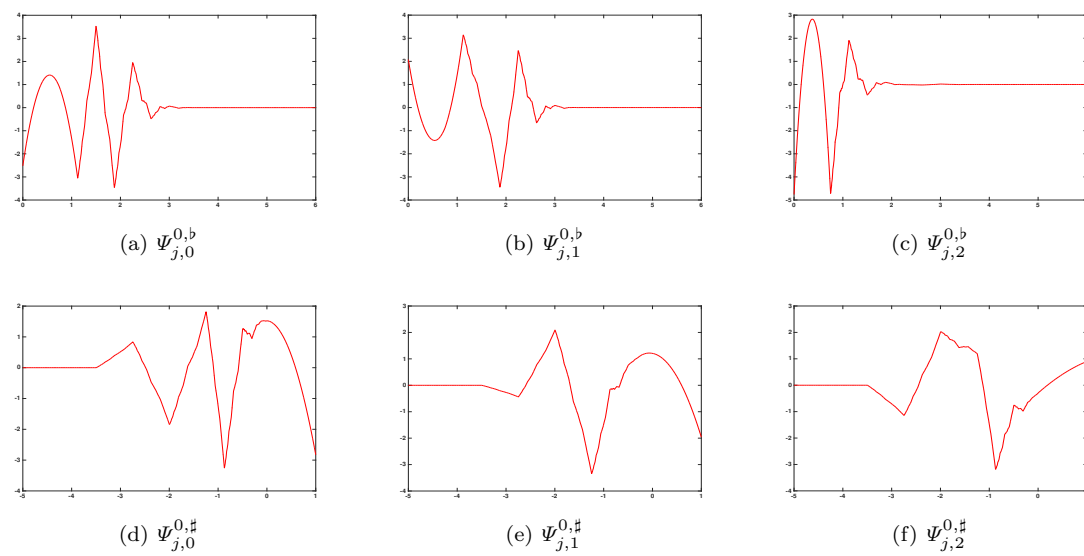


Fig. 3: Plot of the edge orthogonal wavelet functions. Daubechies orthogonal generator with  $r = 3$ .



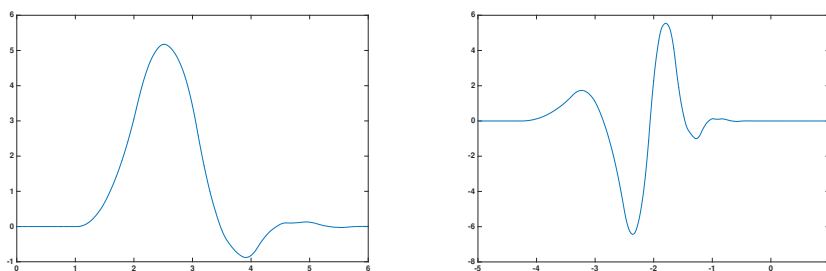


Fig. 4: Plot of the internal scaling function  $\varphi^1(x) = \int_{x-1}^x \varphi^0(t)dt$  (left) and the internal wavelet  $\psi^1(x) = 4 \int_{-\infty}^x \psi^0(t)dt$  (right), where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

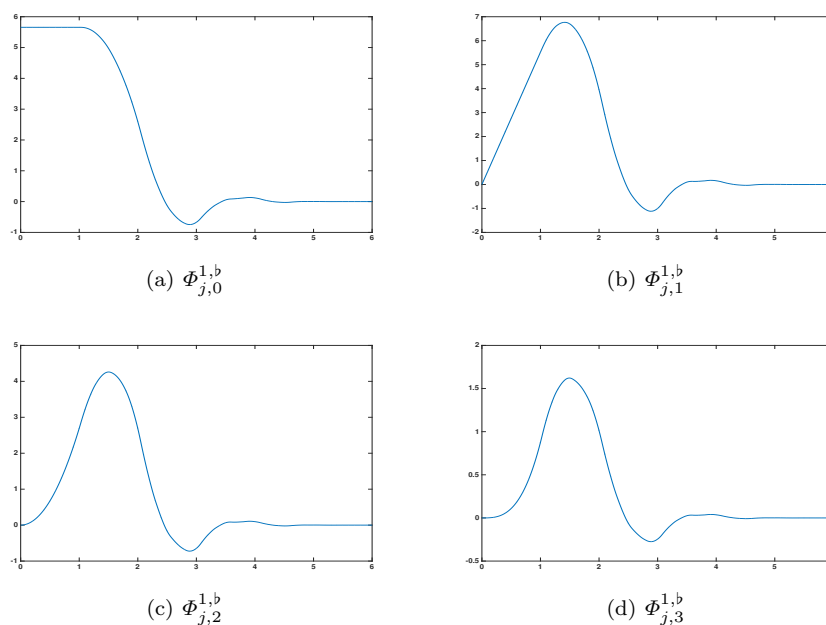


Fig. 5: Plot of the edge scaling functions at edge 0, computed from generator  $\varphi^1(x) = \int_{x-1}^x \varphi^0(t)dt$ , where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

Similarly, the generators  $(\tilde{\varphi}^1, \tilde{\psi}^1)$  biorthogonal to  $(\varphi^1, \psi^1)$  are computed using the formula:

$$\varphi^0(x) = \int_x^{x+1} \tilde{\varphi}^1(t)dt \quad \text{and} \quad \psi^0(x) = -4 \int_{-\infty}^x \tilde{\psi}^1(t)dt. \quad (26)$$

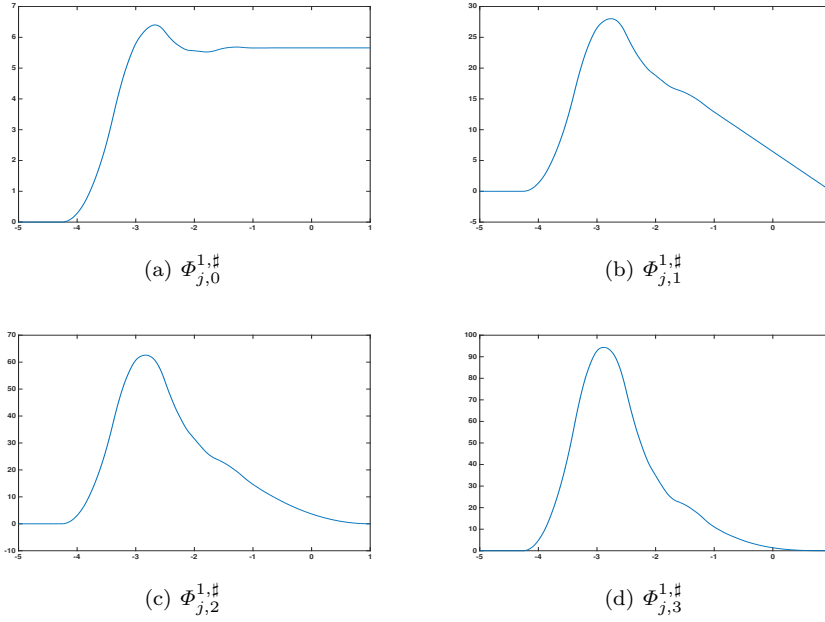


Fig. 6: Plot of the edge scaling functions at edge 1, computed from generator  $\varphi^1(x) = \int_{x-1}^x \varphi^0(t)dt$ , where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

The graphs of  $\tilde{\varphi}^1$  and  $\tilde{\psi}^1$  are plotted on Figure 9, Figure 10 and Figure 11 show the plot of the edge biorthogonal scaling functions. The edge biorthogonal wavelet graphs are plotted on Figure 12 and Figure 13.

We also study the interpolation error of the multiresolution analysis  $(V_j^1, \tilde{V}_j^1)$ . For a given function  $f$ , whose values are known at grid points  $x_k = k/2^{j_{max}}$ ,  $0 \leq k \leq 2^{j_{max}}$ , the interpolation step consists of computing the projection

$$\mathcal{P}_{j_{max}}^1(f) = \sum_{k=0}^{\Delta_{j_{max}}^1 - 1} \langle f, \tilde{\varphi}_{j_{max},k}^1 \rangle \varphi_{j_{max},k}^1. \quad (27)$$

We adapted the quadrature formula and algorithms of [17] to the biorthogonal case to compute numerically the inner product  $\langle f, \tilde{\varphi}_{j_{max},k}^1 \rangle$ . For the function  $f$  defined by:

$$f(x) = \sin(2\pi x) \sin(50x) + 1, \quad (28)$$

we show on Figure 14 the snapshot of the interpolation error  $\|f - \mathcal{P}_{j_{max}}^1(f)\|$  according to the different values of  $j_{max}$ . Again, from  $\tilde{f}_{j_{max}} = \mathcal{P}_{j_{max}}^1(f)$  we study the projection error

$$\|\tilde{f}_{j_{max}} - \mathcal{P}_j^1(\tilde{f}_{j_{max}})\|, \quad j_{min} \leq j \leq j_{max} - 1,$$

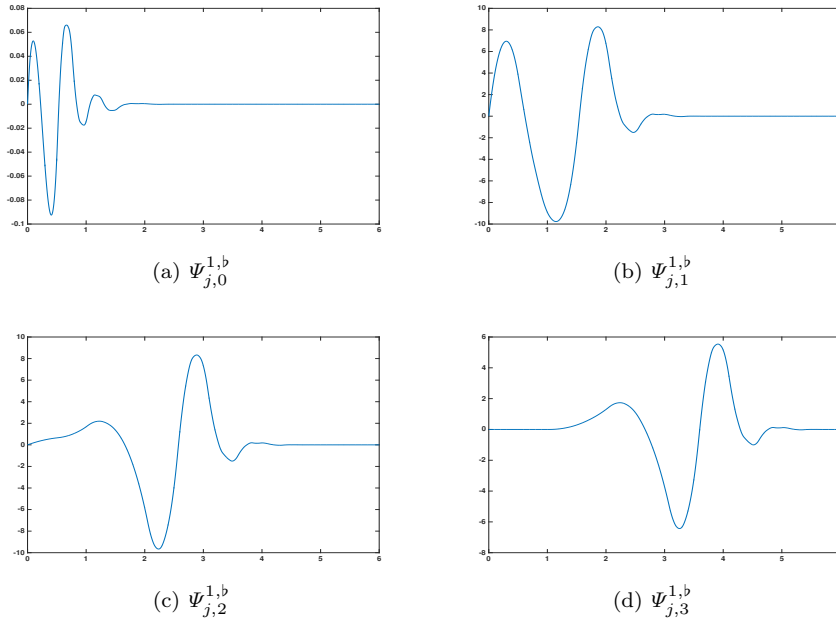


Fig. 7: Plot of the edge wavelet at edge 0, computed from generator  $\psi^1(x) = 4 \int_{-\infty}^x \psi^0(t) dt$ , where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

involved in the fast wavelet transform algorithm. Figure 15 shows the plot of the projection error in a loglog scale with respect to the resolutions  $j$ . The Figure 16 shows the plot of this error at grid points for  $j_{max} = 16$  and  $j = 9$  or  $j = 13$ .

To prove the sparse approximation property of the wavelet basis  $\psi_{j,k}^1$ , we studied the non-linear approximation error of  $f$  defined in (28). On Figure 17 we plot the evolution of this error according the ratio of wavelet coefficients retained.

In each of these experiences, the errors decay order obtained is about  $s \approx -4$ . Since  $f$  is very smooth, this is in accordance with the theoretical order which is the polynomial approximation order of the space  $V_j^1$ .

### 6.1 One dimensional laplacian operator

In this section, we evaluate the performance of our new wavelet basis construction, in the numerical resolution of one dimension poisson equation with homogeneous Dirichlet boundary condition:

$$\begin{cases} -u''(x) = f(x), & x \in ]0, 1[, \\ u(0) = u(1) = 0. \end{cases} \quad (29)$$

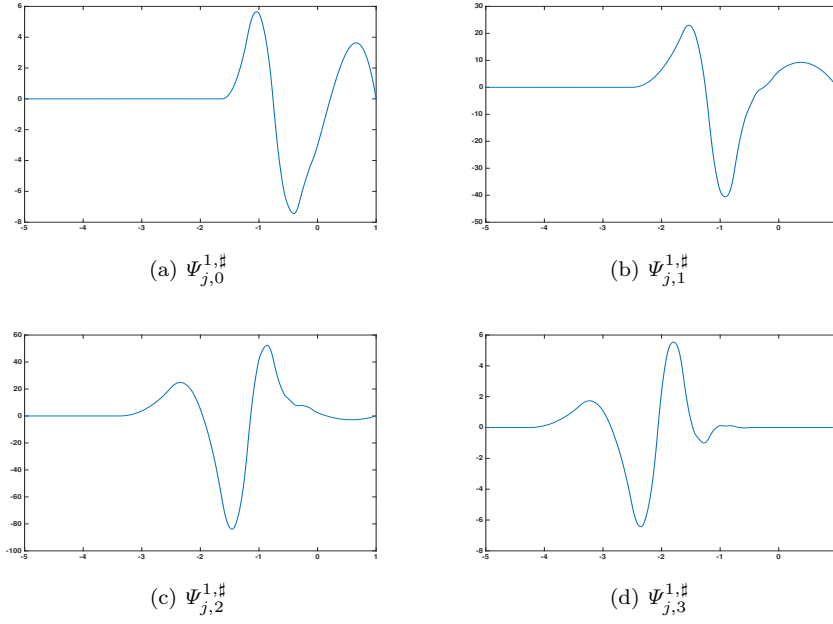


Fig. 8: Plot of the edge wavelet at edge 1, computed from generator  $\psi^1(x) = 4 \int_{-\infty}^x \psi^0(t) dt$ , where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

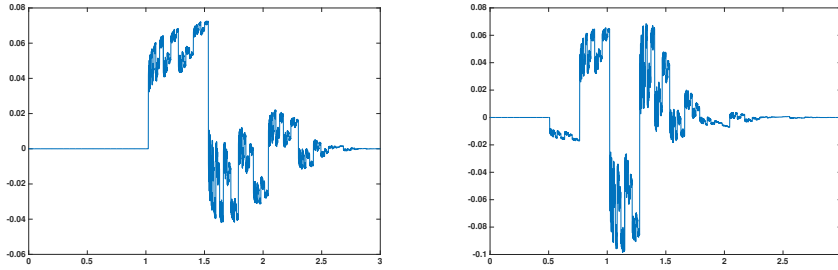


Fig. 9: Plot of the internal scaling function  $\tilde{\varphi}^1$  (left) and the internal wavelet  $\tilde{\psi}^1(t)$  (right), where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

Usually, the numerical resolution of problem (29) with a wavelet based method is done using a Galerkin (or Petrov-Galerkin) method. This leads to the resolution of a linear algebraic system with the stiffness matrix of the considered wavelet basis [2, 7]. In our construction, the wavelet basis  $\psi_{j,k}^0$  can be chosen as an orthogonal basis. In this case, it is easy to see that the stiffness matrix of the wavelet basis  $\psi_{j,k}^1$  constructed by integrating  $\psi_{j,k}^0$  is a diagonal matrix:

$$\langle -(\psi_{j,k}^1)''', \psi_{\ell,n}^1 \rangle = \langle (\psi_{j,k}^1)', (\psi_{\ell,n}^1)' \rangle = 2^{j+\ell} \langle \psi_{j,k}^0, \psi_{\ell,n}^0 \rangle = 2^{j+\ell} \delta_{j,\ell} \delta_{k,n}. \quad (30)$$

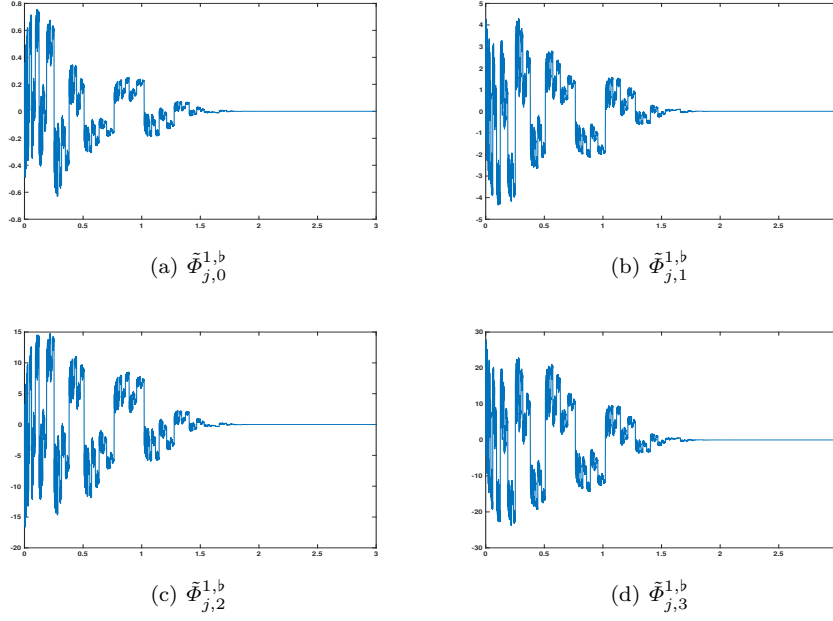


Fig. 10: Plot of the edge biorthogonal scaling functions, where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

Then, if the solution  $u$  is searched in terms of its wavelet series:

$$u = \sum_{j,k} u_{j,k} \psi_{j,k}^1, \quad (31)$$

the coefficients  $u_{j,k}$  are given by:

$$u_{j,k} = 2^{-2j-4} f_{j,k}, \quad \text{where} \quad f = \sum_{j,k} f_{j,k} \tilde{\psi}_{j,k}^1. \quad (32)$$

Thus, the resolution of (29) is reduced to a wavelet coefficient normalization, with a linear numerical complexity. We notice that, at the coarse scale  $j_{min}$  we also have to invert the stiffness matrix of the scaling function  $\varphi_{j_{min},k}^1$ . The size of this matrix is very small compared to the size of the whole system.

To see the efficiency of this approach, we firstly compare its numerical complexity to the complexity of a finite difference method and the multi-grid method of [13]. The main criterion we took is the real computational time of the MATLAB code [18] that encodes the method. For this purpose, two numerical experiences have been conducted. The first experience is done with the exact solution:

$$u(x) = x^3 - x^4. \quad (33)$$

The source term  $f$  is appropriately computed from the solution  $u$ . On Tab. 1, we provide the different mean real computational time according to the space

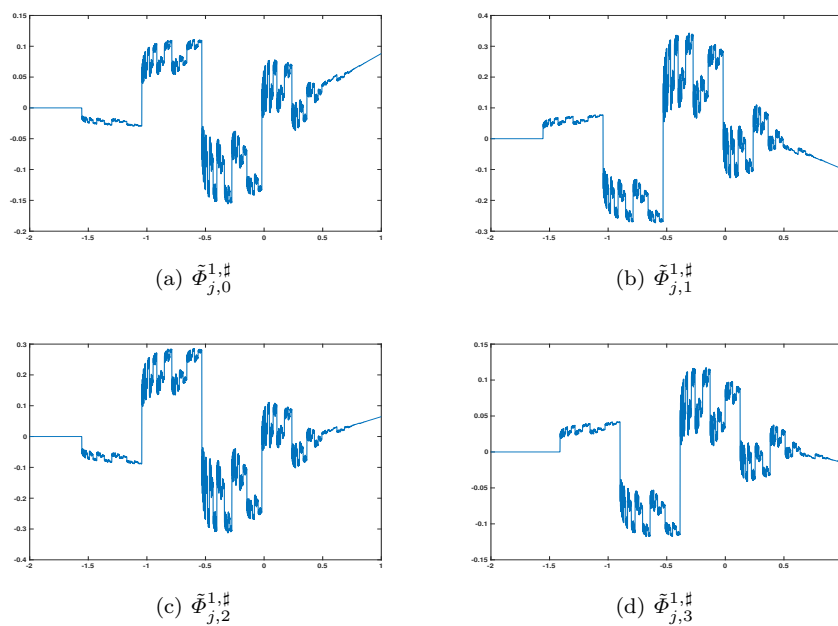


Fig. 11: Plot of the edge biorthogonal scaling functions, where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

resolution  $j$ . It can be observed that the present method performs better than these two methods when the resolution  $j$  increases, with a good accuracy on the relative  $L_2$ -error.

Computational time			
Method	resolution $j$	t (seconds)	$L_2$ -error
Multi-grid	8	0.010705	$4.4184E^{-5}$
Present	8	0.000625	$1.3302E^{-9}$
Finite difference	8	0.000205	$4.4341E^{-5}$
Multi-grid	10	0.019202	$2.7255E^{-6}$
Present	10	0.000835	$3.1552E^{-11}$
Finite difference	10	0.000389	$2.7640E^{-6}$
Multi-grid	16	0.089770	$2.0575E^{-7}$
Present	16	0.007712	$5.6942E^{-11}$
Finite difference	16	0.018695	$9.2095E^{-10}$

Table 1: Comparison of the real computational time and the relative  $L^2$ -error for the exact solution:  $u(x) = x^3 - x^4$ .

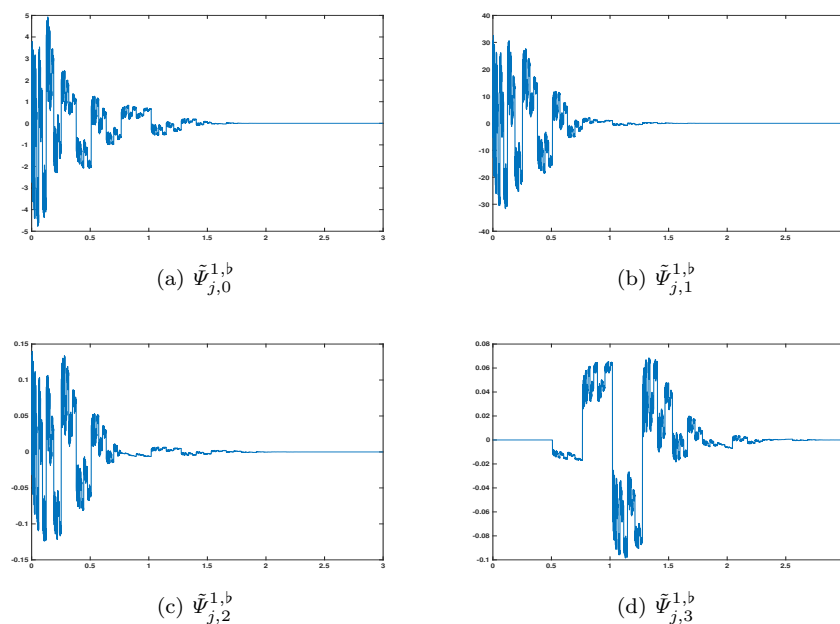


Fig. 12: Plot of the edge biorthogonal wavelets, where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

The second experience concerns the source term  $f$  defined by:

$$f(x) = \begin{cases} 0, & 0 \leq x < 3/8, \\ 2, & 3/8 \leq x \leq 5/8, \\ 0, & 5/8 < x \leq 1, \end{cases} \quad (34)$$

and this corresponds to an exact solution  $u$  of (29) defined by:

$$u(x) = \begin{cases} \frac{1}{4}x, & 0 \leq x < 3/8, \\ -x^2 + x - \frac{9}{64}, & 3/8 \leq x \leq 5/8, \\ -\frac{1}{4}x + \frac{1}{4}, & 5/8 < x \leq 1. \end{cases} \quad (35)$$

The function  $f$  has discontinuities at  $x = 3/8$  and  $x = 5/8$ . Then, the motivation for this experience is to highlight the adaptativity of the wavelet basis  $\psi_{j,k}^1$ .

## 7 Conclusion

In this paper we have presented a new construction of biorthogonal wavelet bases linked by differentiation and integration. In opposite to the existing constructions, the differentiation relation between the wavelet basis  $\psi_{j,k}^1$  and  $\psi_{j,k}^0$  remains

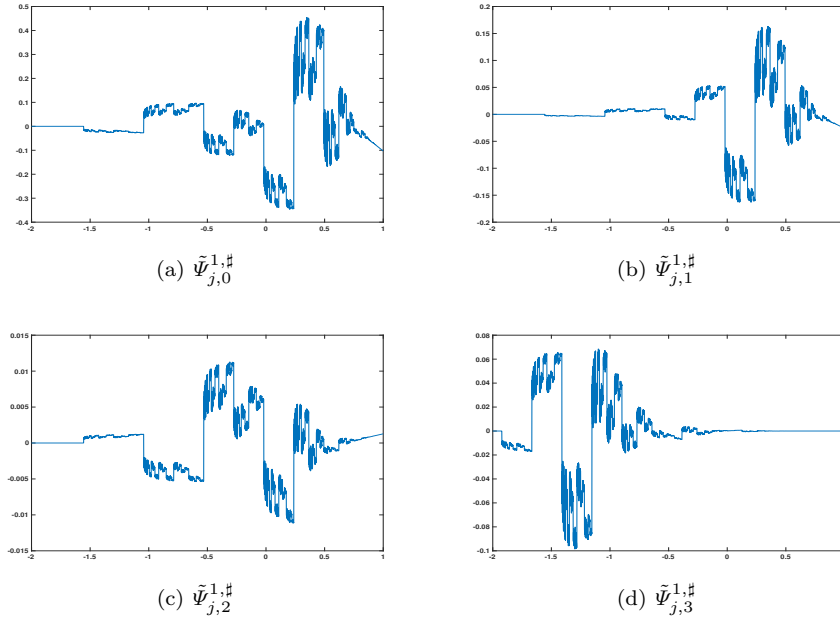


Fig. 13: Plot of the edge biorthogonal wavelets, where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

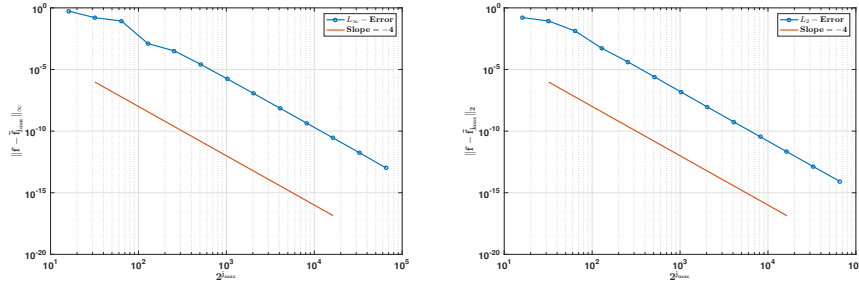


Fig. 14: Plot of the interpolation error  $\|f - \tilde{f}_{j_{max}}\|_\infty$  (left) and  $\|f - \tilde{f}_{j_{max}}\|_2$  (right) in loglog scale, where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

diagonal as for the internal wavelet. To get this point, we have constructed a multiresolution analysis of  $L^2(0, 1)$  for which the wavelet basis satisfies homogeneous Dirichlet boundary condition. Many experiments have demonstrated the potential applications of this new construction in signal compression and in the numerical resolution of the Poisson equation in one dimensional space. Note also that, the diagonal relation between the wavelet bases can improve the fast divergence-free and curl-free wavelet transform algorithms and we leave that for future works.



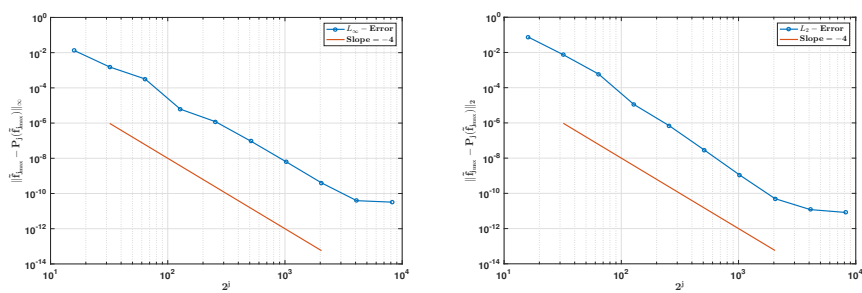


Fig. 15: Plot of the projection error  $\|\tilde{f}_{j_{max}} - \mathcal{P}_j^1(\tilde{f}_{j_{max}})\|_\infty$  (left) and  $\|\tilde{f}_{j_{max}} - \mathcal{P}_j^1(\tilde{f}_{j_{max}})\|_2$  (right) in loglog scale, where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$

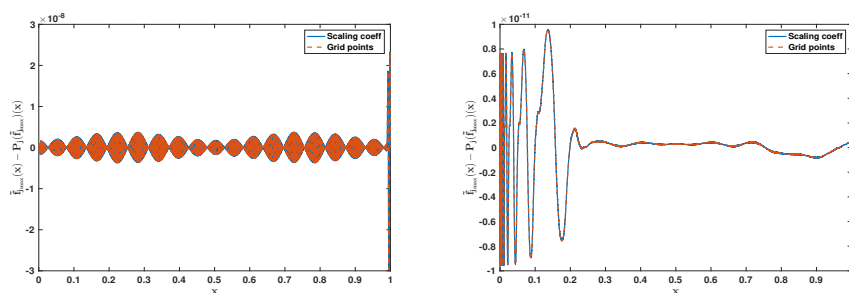


Fig. 16: Plot of the projection error  $\tilde{f}_{j_{max}} - \mathcal{P}_j^1(\tilde{f}_{j_{max}})$  at grid points for  $j_{max} = 16$  and  $j = 9$  (left) and for  $j = 13$  (right), where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

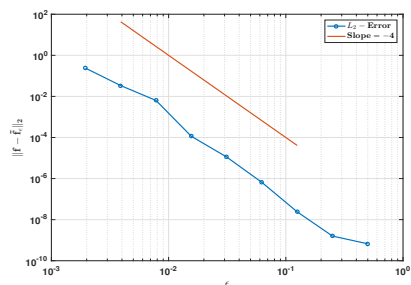


Fig. 17: Plot of the non linear approximation  $L_2$ -error. Daubechies orthogonal generator with  $r = 3$ .

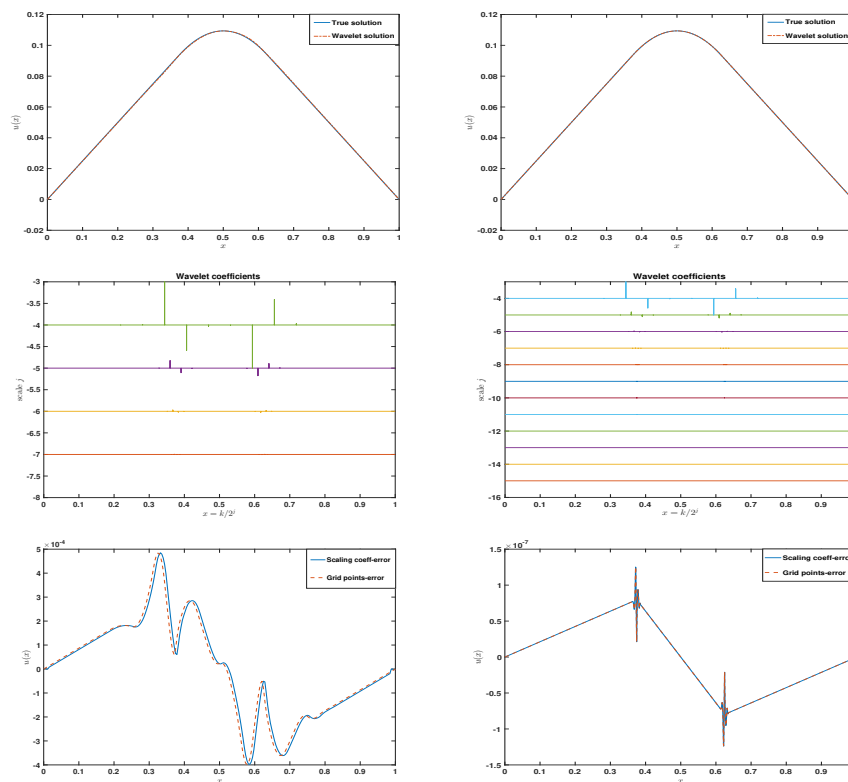


Fig. 18: From top to bottom, plot of the computed solution, its wavelet coefficients and the residual error (first column  $j = 8$  and second column  $j = 16$ ). Where  $(\varphi^0, \psi^0)$  are Daubechies orthogonal generators with  $r = 3$ .

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